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THESIS

POWER-DENSITY DISTRIBUTION BELOW THE OCEAN SURFACE DUE TO INCIDENT LASER RADIATION

by

Michael John Milchanowski

March 1977

Thesis Advisor:

D. J. Collins

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POWER-DENSITY DISTRIBUTION BELOW THE OCEAN SURFACE DUE TO INCIDENT LASER RADIATION

by

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Submitted in partial fulfillment of the requirements for the degree of

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from the NAVAL POSTGRADUATE SCHOOL March 1977



ABSTRACT

The time-averaged power-density distribution below the ocean surface due to incident laser radiation is examined by means of computer simulation of the geometrical optics involved with the air/sea interface and subsequent ocean penetration by the laser beam. The effects over the entire spectra of incidence angles, wind velocities, wind directions, beam spot sizes and depths of penetration are analyzed.

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I. <u>INTRODUCTION</u>

The time-averaged power-density distribution below the ocean surface due to incident laser radiation is examined over the entire spectra of incidence angles, wind velocities and wind directions by means of geometrical optics.

Current interest in using laser systems for communications through the air-sea interface and for detecting submerged objects necessitates the development of prediction methods for determining the subsurface power-distribution of radiation from a laser source above the ocean. A mathematical model for the optical-communications application done by Karp in Ref. 1 is developed in terms of a radiance function related to the coherence function with accurate results mutual for incidence angles out to 45 degrees. A more general model developed by Swennen in Refs. 2-4 examines the power-density distribution below the ocean surface through a rigorous assessment of the ocean surface geometry allowing for theoretically accurate results over the entire incidence angle spectrum.

The computer code developed for this analysis of the power-density distribution below the ocean surface is an expansion of Swennen's theory[Refs. 2-4].

II. DESCRIPTION OF PHYSICAL PARAMETERS

A. OCEAN SURFACE

A geometrical representation of the ocean surface in terms of local slopes developed by Cox and Munk[Ref. 5] is the basis for the analysis of the power probability distribution below the ocean, as it is in Refs. 2-4. A review of this representation follows.

The center of symmetry of the incident laser beam on the ocean surface facet is the center of a right-handed cartesian coordinate system, point "O" in Fig. 1. The z-axis points vertically upward. The y-axis is in the horizontal plane, colinear with the projection of the center of the incident laser beam onto that plane and pointing in the direction of the laser source.

The slopes of the ocean surface facet are defined by angular parameters Alpha and Beta. The angle Beta is the angle between the line of steepest ascent of the facet and the x-y plane; Alpha is the angle between the projection of the line of steepest ascent onto the x-y plane and the y-axis.

A second cartesian coordinate system at the surface is used, as explained in Ref. 2, to simplify the computation of the slope probability function. This coordinate system is designated by primes with the y'-axis pointing towards the wind source and rotated an angle Chi from the y-axis. The

z'-axis coincides with the z-axis. The slope parameters are also primed with their transformations given by:

> Beta' = Beta Alpha' = Alpha - Chi

Below the ocean surface a depth Z at the point of observation, O', is centered a translational transformation of the surface coordinate system. Angles Mu and Nu define the laser beam refracted to O' by any surface facet. The first angle, Mu, is the angle between the refracted ray and the z-axis; the second, Nu, is the angle between the y-axis and the vertical plane of the refracted ray.

B. LASER BEAM

A cylindrical laser beam of radius a is incident on the ocean surface wave facet at an angle Psi measured from the z-axis. The intersection of the beam and the facet is a flat elliptical surface as illustrated in Fig. 2. The semi-minor axis of the ellipse is equal to the beam radius and the semi-major axis, b, is defined by:

b = a * sec Psi

The analytical development, as in Refs. 2-4, begins at the ocean surface facet. The laser source, aiming, atmospheric propagation, etc. are extraneous to this analysis. Power density values at the surface are not quoted because the analysis deals with the ratio of the

power density at the depth of interest, P_d , and the power density at the surface, P_d .

C. MAXIMUM ANGLE OF INCIDENCE

The angle of incidence with respect to the z-axis, Psi, of the laser beam is analyzed from zero degrees to a maximum of 84 degrees. At greater angles the beam will not be able to strike all the wave facets within a wavelength of the wave due to the wave height. There is also the possibility, as illustrated in Fig. 3, that a ray incident at Psi > 84 degrees could pass through the wave, re-enter the atmosphere and then re-enter the ocean; or, depending on the local slopes, the ray could undergo a total internal reflection if the Critical Angle were exceeded. The mathematical model of Swennen[Refs. 2-4] and this thesis do not address this situation.

This limitation on the maximum angle of incidence, Psi , is derived from Fig. 4 and defined by:

$$Psi = tan (L/2H)$$

The significant wave height, H, and the average period, T, of the wave are given by equations (1) and (2) as defined by Pierson[Ref. 7]. The average wavelength of the wave is given by equation (3) as defined by Hill[Ref. 8].

$$H = 2.14 \times 10^{-2} \times W^2$$
 (1)

$$T = 0.81 * (2W/g)$$
 (2)

$$L = gT^2/2$$
(3)

where

W = wind velocity
g = gravitational constant

For wind velocities of 1 to 14 m/sec the maximum angle of incidence is 84.2 degrees (±0.4 degrees) for all wind velocities; therefore, Psi is limited to 84 degrees. max

III. POWER-DENSITY PROABILITY INTEGRAL

A. GENERAL FQUATION

The power-density probability distribution (P_d) at the point of observation below the ocean surface (0°) due to the entire beam is given by the integral of dP over all of the d contributing surface facets. As a function of the angular parameters (Mu,Nu) the integral as defined in Refs. 2-4 is given by:

$$P_{d} = \iint_{\mu \mathcal{V}} F(Mu, Nu) dMu dNu$$
(4)

where

*[cos(Mu)*cos(Mu)+sin(Mu)*sin(Mu)*cos[Nu-Nu]] *P(Z',Z')*tan(Beta)*sec²(Beta)*J⁻¹

and

F = power density at the surface facet
ds
T = Fresnel's transmittance coefficient
DIF = diffuse transmittance function
WI = angle of incidence

WR = angle of refraction
Mu = first quadrant angle the refracted center
 ray of the beam makes with the positive
 z-axis
Nu = positive angle the projection of the
 refracted center ray of the beam onto the
 xy-plane makes with the y-axis measured
 from the latter to the former
F(Z',Z') = time-average slope distribution
 x y
 function

The development of equation (4) is described in great detail in Refs. 2-4 and will not be repeated here; however, for clarity the major components of equation (4) will be discussed.

B. FRESNEL'S TRANSMITTANCE FUNCTION

Fresnel's transmittance coefficient (T) is defined as the intensity ratio of the transmitted to the incident beam energy.

The collimated incident laser beam is composed of two polarization components, a transverse magnetic or parallel polarization (T) and a transverse electric or normal /// polarization (T). Resolving the refracted beam into its i components (T ,T) is a complex task due to rotation of the i // plane of incidence about all three coordinate axis over the range of integration. In order to deal with this complexity the beam is assumed to be rendered diffuse and unpolarized below the ocean surface due to scattering, propagation

direction variations and phase changes. This assumption allows for the averaging of T and T to obtain the value $\frac{1}{1}$ // of T.

$$T = (T + T) / 2$$

The equations for T and T used by Swennen[Refs. 2-4]

$$T = [\sin(WI) * \sin(WR) / \sin(WI + WR)]^{2}$$
(5)

$$T = [\sin(WI) * \sin(WR) / \sin(WI + WR) * \cos(WI - WR)]^{2}$$
(6)

Equations (5) and (6) are in disagreement with those developed by Ecrn[Ref. 9] and Fowles[Ref. 10], given by:

$$T = [2 \times \cos(WI) \times \sin(WR) / \sin(WI + WR)]^{2}$$
(7)

$$T = [2 \times \cos(WI) \times \sin(WR) / \sin(WI + WR) \times \cos(WI - WR)]^{2}$$
(8)

The gecmetry of the ray refraction through the ocean surface is illustrated in Fig. 5.

C. DIFFUSE IRANSMITTANCE FUNCTION

The diffuse transmittance function (DTF) accounts for beam attenuation below the ocean surface due to scattering and absorbtion.

The six-constant DTF developed by Duntley in Ref. 11 is simplified to a function of two constants; the backward scattering coefficient (BS) and the total absorbtion coefficient (AC). This simplification is valid because of the random scattering particle orientation in the ocean. The DTF is defined by:

DTF = K/[(AC+BS) * sinh(K*Z) + K* cosh(K*Z)]

where

 $K = [AC*(AC+2BS)]^{1/2}$

Z = depth of the point of observation

In current terminolgy this method of accounting for attenuation is a zero-angle forward scattering technique.

Typical values for BS and AC were used from measurements by Tyler[Ref. 12] and Duntley[Ref. 13]. These represent an average between cool and warm ocean waters in the blue-green spectrum (4800 angstrom).

BS = 0.065 percent AC = 0.044 m⁻¹
The time-average slope probability function, $P(Z_{,,Z_{,,X_{,X_{,Y}}})$, is a statistical distribution of the ocean surface slopes developed by Cox and Munk[Ref. 5]. The distribution derived from the surface geometry is Gaussian, which is then altered by a Gram-Charlier series in order to account for slope skewness and peakedness caused by the wind.

$$P(Z',Z') = f(Xi,Eta,W)$$

x y

where

Xi = standardized crosswind slope component
Eta = standardized upwind slope component
W = wind velocity

The development and the equation for the slope probability function are covered in detail in Refs. 2,4, and 5. A clean ocean surface is assumed and the limits of applicability placed on the functional parameters are adhered to, namely:

```
|Xi| \le 2.5|Eta| \le 2.5W \le 14 \text{ m/sec}
```

E. JACOEIAN

The power-density probability integral, equation (4),

was first developed over the slope components (Z', Z'). It was then transformed to a function of the angular parameters (Alpha,Beta) and then by the Jacobian (J) to a function of (Mu,Nu).

$$P_{d} = \iint_{Z'_{x}Z'_{y}} dP_{d}$$

=
$$\iint_{A} F (Alpha, Beta) dAlpha dBeta$$

=
$$\iint_{\mu V} F (Mu, Nu) J^{-1} dMu dNu$$

where

 $J = \partial(Mu, Nu) / \partial(Alpha, Beta)$

IV. METHODS OF SOLUTION

A. FAR ZCNE

Swennen[Refs. 2-4] observed that when the depth (Z) of the point of observation is large compared to the beam cross-sectional radius at the surface (Z/a>100) the integrand of equation (4) remains essentially constant during the integration. The integral can then be approximated by:

$$P_{d} = \iint_{\mu \nu} F(Mu, Nu) * J^{-1} dMu dNu$$

$$\simeq F(Mu, Nu) * J^{-1} \Delta Mu \Delta Nu ; with Mu=Mu & Nu=Nu$$

The area $\Delta Mu \Delta Nu$ in the (Mu, Nu) plane is approximated by an ellipse of area ΔA , whose development is covered in detail in Ref. 3.

This is the Far Zone approximation and equation (4) becomes:

$$P_{d} = P_{ds} *T*tan (Beta) *sec^{2} *cos (WI)$$
$$*sec (WR) *P (Z', P') *J^{-1} *\Delta A$$

The basic Far Zone computer program developed in FORTRAN language and run on the IBM 360 system solves for the ratio of the power density at the point of observation to the power density at the surface facet, P_{d}/P_{ds} . The main d ds portion of the program allows for the entry of any combination of variables (wind, depth, beam radius, Psi, Chi, Nu, backward scattering coefficient, absorbtion coefficient) and also computes the diffuse transmittance function, Fresnsl's transmittance function and the slope probability function. Subroutines common to all variable entries are used to compute the angles (Alpha, Beta, WI, WR), the Jaccbian and A.

It is possible to investigate the power-density probability distribution over a wide range of variables with a minimal cf storage requirements and computation time due to the use of an IBM System/360 Source Library subroutine, NLNSYS, in solving for the coupled (Alpha, Beta) and (Mu, Nu) angle pairs from the simultaneous non-linear equations:

 $\cos (Mu_0) = [\cos (Psi) + K*\cos (Beta)]/n \qquad (9)$ $\cot (Nu_0) = \cot (Alpha) - \sin (Psi)/K$ $*sin (Alpha) *sin (Beta) \qquad (10)$

where

K = K(Psi, Alpha, Beta, n)

B. NEAR ZCNE

When the depth of the point of observation is not large compared to the beam cross-sectional radius at the surface (Z/a<100) the Far Zone approximation does not hold and the double integration of equation (4) must be carried out.

Swennen[Ref. 2] used Simpson's method of numerical integration to approximate equation (4). The method was subject to singularity points in the integration limits which increased the complexity and time required for the computation.

The double integration can be more accurately and relatively simply approximated by using the Gauss Quadrature system of solution, Refs. 14 and 15. The Two-Point Gauss-Legendre Quadrature method was used. This method, valid for polynomials up to degree three (equation (4) is of degree two), consists of first transforming the function F(Mu,Nu) into a function F(s,t) whose interval is $-1 \le s \le 1$ and $-1 \le t \le 1$ by letting:

$$Mu = [(Mu - Mu) * s + Mu + Mu]/2$$
(11)

$$Nu = [(Nu - Nu) * t + Nu + Nu]/2$$
(12)

and

$$dMu = \left[\left(Mu - Mu \right) / 2 \right] ds$$
(13)

$$dNu = [(Nu - Nu)/2]dt$$
(14)

The power-density integral

is transformed into

$$P_{d} = [(Mu_{u} - Mu_{u}) (Nu_{u} - Nu_{u}) / 4] * \iint_{-1}^{11} F(s,t) ds dt$$
(15)

The Twc-Point Gauss-Legendre Quadrature approximation of equation (13) is given by:

$$P_{d} = [(Mu - Mu) (Nu - Nu) / 4] * \underbrace{\stackrel{I}{\underset{i=0}{\overset{i=0}{\atop}}} \overset{I}{\underset{j=0}{\overset{i=0}{\atop}}} W * P(s, t) (16)$$

where

W = 1.0 = Gauss weight factors
i
$$s_{i}, t_{j} = \pm (3)^{-2}$$
 = Gauss roots

The basic Near Zone computer program developed uses this Gauss-Legendre Quadrature method in solving the power-density integral coupled with the same subroutines as the Far Zone program. The main program computes the integration limits (Mu ,Mu) and (Nu ,Nu) after determining u 1 u 1 whether the surface projection of the point of observation is inside or outside the beam's horizontal cross-sectional area. The equations for the integration limits are well defined in Refs. 2-4.

The transformations described by equations (11) - (15) are then performed and the power-density is solved for using equation (16). As in the Far Zone program, the Near Zone



program can take any combination of variables as entries.

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V. <u>RESULTS</u>

Results for oblique incidence angles (0<Psi \leq 84 degrees) were obtained for vertical plane cuts at Nu = 0 degrees over the entire range of variables; however, valid data for vertical planar sections at Nu \neq 0 degrees could not be obtained due to values of the standardized crosswind and

upwind slope components being out of the range of applicability for the slope probability function. This problem is believed to be inherent in the method of mathematical analysis of the ccean surface used. Results for normal incidence (Psi = 0 degrees) over the entire range of variables, including Nu planar variations, were 0 obtained.

The validity check carried out on the slope probability function, as discussed in Section III.D, clearly identified invalid data. Another source of invalid data occurred at higher incidence angles (Psi) where the simultaneous solution of non-linear equations (9) and (10) resulted in an angle of incidence (WI) greater than 90 degrees while the slope probability function still indicated valid. This output was also easily identified and eliminated.

Computations with the Near Zone solution method used more computer time and storage than did the Far Zone solution method. For a computer solution using one value for each variable entry, the Near Zone used 36 per cent more computer time and 8 per cent more computer storage than did

an equivalent Far Zone solution. The higher time requirement for the Near Zone solution was due mainly to a greater compiling time requirement. The time difference between the two solution methods decreased as the number of variables that were incremented during one computer run increased.

A sample computer run with output is presented in Appendix E.

A. PRESENTATION OF RESULTS

Results are presented graphically to simplify comparisons of the wide range of variables. Vertical-planar sections of the power density probability distribution below the ocean surface out through the center of the beam cross-section at the horizontal ocean surface at an angle Nu are used for the majority of the results presented.

This presentation is in rectangular coordinates with ncrmalized power density in decibels on the ordinate and the angle Mu in degrees on the abscissa. The normalized power

density is equal to $10*\log \left[(P * Z^2) / P \right]$. This 10 d ds

normalization with respect to P / Z should produce a ds

distribution function that is independent of depth in the Far Zone regime, according to Swennen[Ref. 2-4], because the multiple slopes seen in a beam cross-section at the surface tend to render the radiation diffuse. The power density of diffuse radiation at large depths decreases as the square of the depth. When the effects of scattering and absorption

are included this independence does not occur, as will be discussed later; however, the normalization of the power density is used in all regimes for continuity and for comparisons with Refs. 2-4.

E. EFFECTS CF WIND VELOCITY

As wind velocity increases, the power density distribution spreads out and the maximum power density decreases slightly. This effect is presented in Figs. 6-11 for various angles of beam incidence with respect to the vertical (Psi = 0,30,60 and 84 degrees). Figures 10 and 11 also show the close correlation between results obtained from the Near Zone and the Far Zone solution methods for Psi = 0 and 40 degrees, respectively.

The spreading effect on the power density distribution is due to larger refraction angles (WR) caused by higher wave facet slopes that occur at higher wind velocities. The maximum power density decrease is caused by the spreading.

For an optical communication or detection system an increase in wind velocity would mean that the maximum intensity of the beam that could be focused to a point beneath the ocean surface would be reduced, but the width of receivable signal radiation or the search width would be increased.

C. EFFECTS OF INCIDENCE ANGLE

As the angle of incidence with respect to the vertical (Psi) is increased the maximum power density decreases and

the distribution shifts away from the vertical. This effect can be seen in Figs. 6-11 and more clearly in Figs. 12 and 13. Figure 12 is a Far Zone solution at a depth of 50 meters for Psi = 0,30,60 and 84 degrees while Fig. 13 is a Near Zone solution at a depth of 10 meters for the same values of Psi.

The decrease in maximum power density is a result of greater reflectance at the surface facet as the angles of incidence (WI) increase with increases in Psi. The shift in the center of the distributions away from the vertical is caused by the higher angles of refraction (WR) that occur as WI increases.

For an optical communication or detection system an increase in Psi would be expected to lower the maximum beam intensity below the ocean surface and to shift the point of maximum intensity away from the point of water entry.

D. EFFECTS CF WIND DIRECTION

The effects of wind direction are small compared to the wind velocity effects. When the wind direction (Chi) is perpendicular to the beam (Chi = 90 degrees) there is slightly less spreading of the power density distribution compared to Chi = 0 or 180 degrees. The maximum power density is essentially unaffected by variations in Chi.

Figure 14 shows the effect of variations in Chi for normal incidence and Fig. 15 for oblique incidence (Psi = 40 degrees).

Wind direction appears to be of little concern to an optical communication or detection system as related to the

power density distribution below the ocean surface.

E. EFFECIS OF SPOT SIZE

Figures 16 and 17 show the effect of increasing the incident beam spot radius from 0.1 to 0.5 meters for Fsi = 0 and 40 degrees, respectively. This is done with the assumption that the energy per unit area remains constant; therefore, the total energy must increase. The power density spreads out and increases in intensity uniformly over the distribution as the spot size is increased.

Since the equations used in this solution method deal with the ratio of P_{d}/P_{d} , these results simply mean that more power in a larger beam will produce a more intense and more widely distributed pattern below the ocean surface.

F. EFFECTS OF DEPTH

The decrease of power density with increases in depth is illustrated in Figs. 18 and 19 for Psi equal to 0 and 40 degrees, respectively. The decrease is linear for the normalized power density as can be seen in Fig. 20.

Scattering and absorption cause this decrease in the power density. As the depth increases the diffuse transmittance function (DTF) rapidly becomes an inverse function of the sum of the hyperbolic sine of the depth and the hyperbolic cosine of the depth,



$$DTF = f[(sinhZ+coshZ)]$$

which means the DTF decreases rapidly with increases in depth and approaches zero in the limit. This agrees with the theory of Preisendorfer[Ref. 16].

Swennen's prediction of a constant normalized power density distribution in the Far Zone regime due to the diffusing effects of the ocean in Refs. 2-4 holds only when the effects of scattering and absorption are ignored. One computer run was made with the DTF set equal to one to illustrate this effect in Fig. 20.

Figures 21 and 22 illustrate the decrease in power density with depth, non-dimensionalized with respect to spot size, Z/a, again for Psi equal to 0 and 40 degrees, respectively.

An optical communication or detection system will be limited greatly by the power density decrease associated with depth.

G. MAXIMUM FOWER DENSITY

The maximum obtainable power density available over the spectrum of incidence angles (Psi = 0 - 84 degrees) for a given set of conditions is presented in Figs. 23 and 24. The maximum power density obtainable does not occur for normal incidence, but for a small value of Psi, because of the fact that as the wind increases the most probable slope is not zero but a small angle. The maximum obtainable power density then drops continuously with increases in Psi after the peak that occurs around Psi = 10 - 15 degrees.

· 27

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Figure 23 illustrates the decrease in the maximum obtainable power density for all values of Psi as the wind velocity increases. This is due to the spreading effect on the power density distribution caused by the wind that was described previously.

Figure 24 illustrates the independence of the maximum power density on the wind direction (Chi) for all values of Psi. Chi equal to 270 degrees is not plotted but is equivalent to the condition at 90 degrees because of the symmetry of the slope probability function about the wind direction.

The angle with respect to the vertical from the point of observation below the ocean surface (Mu₀) at which the maximum power density occurs for each value of Psi is plotted in Fig. 25. The plot is independent of wind velocity and direction. Examining Figs. 16 - 19 it can be seen that Fig. 25 is also independent of depth and spot size. Mu₀ for maximum power density increases nearly 0 linearly from approximately 1 to 56 degrees as Psi goes from 0 to 84 degrees. The increase in Mu₀ is due to the power density distribution shifting away from the vertical for increasing values of Psi as discussed earlier and illustrated in Figs. 12 and 13.

1

The obvious consideration with an optical communication or detection system is the decrease in maximum power density that accompanies higher incidence angles and wind velocities. The strong independence of the angle Mu at 0which the maximum power density occurs with respect to the wind velocity, wind direction, depth and spot size indicates

that a satellite based laser navigation system for submarine usage may be a possibility.

VI. CONCLUSIONS

The time-averaged power-density distribution below the ocean surface due to incident laser radiation has been examined through computer simulations in both the Near Zone and the Far Zone regimes. The effects of altering incidence angles, wind velocities, wind directions, beam spot sizes and depths of penetration have been presented.

The power-density distribution was found to be highly dependent on the angle of beam incidence, the wind velocity and the attenuation associated with depth of penetration of the laser beam. The fact that the location of the maximum power density was found to be fundamentally dependent on only the angle of beam incidence indicates a possibility of direction finding capabilities by a submerged receiver.

Improvements in computer systems and analysis techniques have allowed an examination of a much broader range of variables than were possible heretofore. Angles of beam incidence up to 84 degrees were considered within the range of validity for restrictions placed on the simulation. Above 84 degrees incidence angle the possible interactions at the air/sea interface make an analysis of the power-density distribution extremely complex, and experimentation will be necessary to give indications of the feasibility of laser operations in this area.

This simulation could be extended to an analysis of much larger spot sizes that would be expected from a satellite based transmitter. Prettyman and Cermak[Ref. 17] suggested that the effects of larger spots could be approximated by

assuming each wave facet independent of its neighbors and then integrating over the larger spot area, since the small spot represents the outer limit of the effects of the ocean surface on a laser beam of greater spot size. There would have to be a large number of surface facets contained in the spot to insure facet independence and accurate approximations, hence a strong dependence on the wavelength of the wave associated with wind velocity.

An extension of the simulation to pulsed laser radiation is also warrented, since this mode of operation may be required for air-to-subsurface laser systems. The effects of pulsed radiation occur nearly instantaneously as compared to the time-averaged analysis performed in this simulation.

A further refinement of the simulation would involve a more complex modeling of the beam attenuation due to scattering and absorption in the ocean through the use of a diffusion or a multiple forward scattering method, both described by Bucher[Ref. 18] and Preisendorfer[Ref. 16].

APPENDIX A

FIGURES








Figure 2: Intersection of laser beam with ocean wave facet









Figure 4: Maximum angle of incidence wave geometry





Figure 5: Ray refraction geometry





















Figure 10

40
















































Figure 21

















Figure 25



APPENDIX B

COMPUTER PROGRAM USAGE

To use the computer programs listed following this Appendix, first compute the ratio of the depth of the point of observation below the ocean surface to the beam radius at the surface facet, Z/a. Use the Near Zone program for $Z/a \le 100$ and the Far Zone program for Z/a > 100. The Near Zone program may be used for any value of Z/a, but a slight computation time and computer storage increase will result.

The only other basic requirement is the selection of eight input variables. The variables are listed below along with the line from the respective program in which they appear.

VARIABLE	<u>NEAR</u> ZONE	<u>FAR</u> ZONE
Depth, Z (m)	470	440
Beam radius, RAD (m)	480	450
Angle Nu, NUORUN (deg)	490	480
Backward scattering coefficient, BS	560	530
Absorpticn coefficient, AC (m)	570	540
Beam incidence angle, PSIRUN (deg)	630	590
Wind direction, CHI (rad)	680	640
Wind velccity, W (m/sec)	710	6 7 0

Z, RAD, NUORUN, BS and AC are direct program inputs



made on the indicated lines. PSI, CHI and W are selected from DATA statements 430 and 440 in the Near Zone program and 420 and 430 in the Far Zone program. The variable locations in DATA statements were used for multiple variations of the parameters in a slightly different form of the program than presented which is easily set up with DO LOOPS. The entry variables may also be varied in this same manner.

Both programs must be combined with the common package of subroutines that are listed following the basic program listings.

The cutput from both listed programs appear on the next two pages.

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NEAR ZONE COMPUTER PROGRAM

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= 1.-(24.)*C40*(XI**2-L.)*ETA-(1./6.)*C03*(ETA**3-)
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R = (2.*COS(WI)*SIN(WR))

R = (2.*COS(WI)*SIN(WR))
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AXI = ABS(XI)

AETA = ABS(ETA)

VALID = 1

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CETERMINE IF THE SURFACE PROJECTION OF THE POINT OF OBSERVATION
Is inside or outside the beam:
    ref a: EqnS 68-70 75-77
    ref a: EquS 68-70 95 60 70 130
    ref a: EquS 71.0U-74
    ref a: EquS 710.001 750
    ref a: EquS 710.001
    ref a: EquS 710
    ref a: EquS 70
    ref a: Equ
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             UELIQUE INCIDENCE, OUTSIDE BEAM:

XI = -(2*TAN(MUO))*TAN(NUO))/SQRT(1.+TAN(NUO)**2)

INTERMECIATE EQNS: ABX,AYS,BXAY

INTERMECIATE EQNS: ABX,AYS,BXAY

AFS = (RAD**2)*(BB**2)*X1

AYS = (RAD**2)*Y1*SQRT((BB**2)*(X1**2)-(RAD**2)*(BB**2)+(RAD**2)*(

1/1**2)

E>AY = (BB**2)*(1**2)+(RAD**2)*(Y1**2)

E>AY = (ABX-AYS)/BXAY

X22 = (ABX-AYS)/BXAY

IF (X1 + 7 + 45)/BXAY
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      ALCULATION OF INTEGRATION LIMITS FOR THE SURFACE FRCJECTION
F THE POINT OF OBSERVATION OUTSIDE THE BEAM:
EF 3: EQNS 13,14,21-26,34-39,60-70
F (PSIRUN.EQ.0.) GO TO 155
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   E & A Y = ( BB **2 ) * ( X I **2 ) + ( RAD **2 ) * ( Y I **2 )
E & A Y = ( AB X - A Y S) / B X A Y
X Z = ( AB X + A Y S) / B X A Y
Y Z = ( AB X + A Y S) / B X A Y
Y Z = ( AB X + A Y S) / B X A Y
Y Z = B B * S GR T ( I - - X 2 I ** 2 / R A D ** 2 )
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Y4 = -BB
Y5 = BB
GC TO 165
CTNU = COTAN(NU0)
CA = CTNU*(X1*CTNU-Y1)
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CE = SQRT(BE**2*CTNU**2-(BB**2/RAD**2)*(Y1**2-BB**2+X1*CTNU*(X4*CT NU-2.*Y1)) CC = CTNU**2+BB**2/RAD**2 X4 = (CA-(SIN(NU0)/ABS(SIN(NU0)))*CB)/CC Y4 = BB*SCRT(1X4**2/RAD**2) Y4 S5 = (X4+X1)*CTNU+Y1 Y4 S5 = (X4+X1)*CTNU+Y1 Y4 S5 = BB*SCRT(1X5**2/RAD**2) Y5 S6 = (X5-X1)*CTNU+Y1 Y5 S7 S7 S6 = (X5-X1)*CTNU+Y1 Y5 S7	<pre>55 NGRMAL INCIDENCE, OUTSIDE BEAM:</pre>	<pre>Ŷ4 = -RAD Y5 = RAD C CTNL = COTAN(NUO) CNA = -Y1*CTNU CNB = SCRT(RAD**2*CTNU**2-Y1**2+RAD**2) CNC = CTNU**2+1 CNC = CTNU**2+1 X5 = (CNA-(SIN(NUO)/ABS(SIN(NUO)))*CNB)/CNC</pre>	YY4 = BB*SQRT(1X4**2/RAD**2) Y45GN = X4*CTNU+Y1 Y5 = BB*SQRT(1X5**2/RAD**2) Y55GN = X5*CTNU+Y1 Y5 = S1GN(YY5,Y55GN) Y5 = S1GN(YY5,Y55GN) Y5 = SQRT((Y4-Y1)**2+(X4-X1)**2) B1 = SQRT((Y5-Y1)**2+(X4-X1)**2) D1 = ARCOS((Y1+(Y1-Y21)+X1*(X1-X21))/SQRT((X1**2+Y1**2)*((Y1-Y21)))/SQRT((X1**2+Y1**2)))/SQRT((Y1-Y2))/SQRT((Y1-Y2)))/SQRT((Y1-Y2)))/SQRT((Y1-Y2))/SQRT((Y1-Y2)))/SQRT((Y1-Y2)))/SQRT((Y1-Y2))/SQRT((Y1-Y2)))/SQRT((Y1-Y2))/SQRT((Y1-Y2)))/SQRT((Y1-Y2))/SQRT((Y1-Y2))/SQRT((Y1-Y2)))/SQRT((Y1-Y2))/SQRT((Y1-Y1-Y2))/SQRT((Y1-Y1-Y2))/SQRT((Y1-Y1-Y1-Y2))/SQRT((Y1-Y1-Y1-Y1-Y2))/SQRT((Y1-Y1-Y1-Y1-Y1-Y1-Y1-Y1-Y1-Y1-Y1-Y1-Y1-Y	<pre>Chuc2 = ARCC5((Y1*(Y1-Y22)+X1*(X1-X22))/SQRT((X1**2+Y1**2)*((Y1-Y22)) 1)**2+(X1-X22)**3))) MLL = ATAN(B2/2) WLL = ATAN(B1/2) NLL = ATAN(B1/2) NLL = NU0+DNU1 NLL = NU0-DNU2</pre>
		-	-1	



NTEGRATION CS(WR))*PSLOPE*TAN(B)*(1./COS(B))**2*(1./JAC UL))/4.)*CTF COS(ETAMU1)*COS(MU0)+SIN(ETAMU1)*SIN(MU0)*CCS(ABS(XINL2-NU0 COS(ETAMU2)*COS(MU0)+SIN(ETAMU2)*SIN(MU0)*CCS(ABS(XINU2-NU0 COS(ETAMU2)*COS(MU0)+SIN(ETAMU2)*SIN(MU0)*CGS(ABS(XINU1-NU0 PRATIO=POWER DENSITY RATIO CCMPUTED USING A TWO-POINT GAUSS-LEGENDRE QLADRATURE NUMERICAL INTEGRATICN SCHEME REF 3: EQN 53 REF 3: EQN 53 REF 3: 4615 CINT=CONSTANT DURING INTEGRATION CINT=CONSTANT DURING INTEGRATION CINT=T*COS(WI)*(1./COS(WR))*PSLOPE*TAN(B)*(1./COS(F CINT=T*COS(WI)*(1./COS(WR))*PSLOPE*TAN(B)*(1./COS(F CINT=T*COS(WI)*(1./COS(WR))*PSLOPE*TAN(B)*(1./COS(F CINT=T*COS(WI)*(1./COS(WR))*PSLOPE*TAN(B)*(1./COS(F CINT=T*COS(WI)*(1./COS(WR))*PSLOPE*TAN(B)*(1./COS(F CINT=T*COS(WI)*(1./COS(WR))*PSLOPE*TAN(B)*(1./COS(F CINT=T*COS(WI)*(1./COS(WR))*PSLOPE*TAN(B)*(1./COS(F CINT=T*COS(WI)*(1./COS(WR))/4.)*COS(F FAMU1=((NUU-MUL)*ETA2+MUU+MUL)/2. XINU2=((NUU-NUL)*XI1+NUU+NUL)/2. ABS(CINT*(FXT1+FXT2+FXT3+FXT4) PWRDEN(J) = 10.*ALOGIO(PRATIO*2**2) REF 2: PGS 65-67; FIG 34 CUTPUT INSTRUCTIONS S 11 18 ļį H II FRATIC 10 FX14 1)) FXT2 FXT3 FXT3 LCL CLC XZZ רישהר כישהר 5 2 85 175 16C 17C -----ပပပပ 0000000 C

, ALPHAD, BD, WIC, WRC, T, JACOB, P SLCPE, PRATIO, FWRDEN(J), X F7.2,1X,F7.2,1X,F7.2,1X,F7.2,1X,F7.2,1X,F7.4,1X,F7.4,1X,1 .4,1X,0PF8.2,2X,12,5X,12,3X,F4.1,1X,F4.1) LCCP EXIT FOR LOW SLCPE PROBABILITY IF ((PSLOPE.LT.1.E-20).AND.(PWRDEN(J).LT.PWRDEN(JJ)).AND.(J.GT.5)) CCNVERT ALPHA, B, WI, WR FROM RADIANS TO DEGREES RCEG = 57,2958 ALPHAD = ALPHA*RDEG BC = B*RDEG WIC = WI*RDEG WRD = WR*RDEG WRD = WR*RDEG WRTE (6,190) J,ALPHAD,BD,WIC,WRC,T,JACOB,PSLC J'VALIC AX I, AETA FCRMAT (1X,12,1X,F7 PE11.4,1X,1PE11.4,1 , AET 200 1200 155 CC 150 C C ပပ

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FAR ZONE SOLUTION OF THE TIME-AVERAGE POWER PROBABILITY DISTRIBUTION BELOW THE OCEAN OF A LASER BEAM INCIDENT CN THE SURFACE	NCMENCLATURE: PSI=ANGLE OF INCIDENT BEAM WITH RESPECT TO VERTICAL AXIS CHI=ANGLE OF WIND WITH RESPECT TO THE INCIDENT BEAM IN THE XY-PLANE	ALPHA = ANGLE OF MAX WAVE SLOPE WITH RESFECT TO THE INCIDENT BEAM IN THE XY-PLANE B=MAX SLOPE OF WAVE FACET NU=NU0=ANGLE BETWEEN REFRACTEC RAY PRCJECTED CNTO XY-PLANE	MU=MUO=ANGLE BETWEEN REFRACTEE RAY AND THE Z AXIS Z=DEPTH BELOW OCEAN SURFACE (METERS) RAD=INCIDENT RAY SPOT RADIUS AT WAVE FACET (MINOR AXIS CF FILIPSE WHEN PST IS NON-ZERO)	BB=MAJOR AXISOF SPOT INCIDENT ON WAVE FACET W=WIND VELOCITY (M/SEC) WI=RAY INCIDENCE ANGLE WR=RAY REFRACTION ANGLE	CTF=DIFFUSE TRANSMITTANCE FUNCTION BS=BACKWARD SCATTERING COEFFICIENT AC=ABSORBTION COEFFICIENT T=FRESNEL'S TRANSMITTANCE FUNCTION	ÁN = INDEX OF REFRACTIÓN PSLOPE=SLOPE PROBABILITY FUNCTIÓN DAREA=AREA INCREMENT	JACOB=JACOBIAN Pwrden=power density (decibels)	INTEGER VALID REAL NUO,JMUO,JACOB,MLO,NUORUN CCMMGN MUO,NUO,PSIAN,PSIRUN,NUORUN,PI,Z,RAC,8B,JK DIMENSICN W(3), CHI(3), NCHI(3), RG(4), JMUC(90), PMRDEN(90), PSIN 1(10)	INFUT PARAMETERS: CATA W.CHI,NCHI/14.10.5.00.1.5708.3.14159.0.90.180/ CATA PSIN/0.10.20.30.40.50.50.60.70.80.84./ Z = 50.	RAC = 2 PI = 3.141592654 AN = 1.33 NUCRUN = 0.

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LACOB 5X, DAREA', 6X, PSLOPE', 7X, PRATIC', 5X, PWRDER
'PUC', 2X, VALIDITY', 1X, XI', 3X, 'ETA'/)
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GREA
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H1, 10X, FAR ZONE SOLUTION, 5X, CEPTH=
8.5, 5X, WIND=, F4, 1, M/SEC, /11X, PSI=
5.1, M, 8X, VALID=1,/11X, NUO=, F4, 1,
                                                                                                                                                                                                             PSI
           DIFFUSE TRANSMITTANCE FUNCTION (DTF)

REF 11: PG 65

ES = .065

AC = .044

FK = SQRT (AC*(AC+2.*BS))

CTF = FK/((AC+BS)*SINH(FK*Z)+FK*COSH(FK*Z))
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EQNS 50,54,55,82
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= PSIN(5)
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NLORUN/57.295
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PWRCEN(J) = 0
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FCRMAT (1H
CTF=, F8
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FSLCPE = SLOPE PROBIBILITY FUNCTION
REF 5: EQNS 5-9:12-18
SIGC = SQRT(:003+1:92E-03*W(I))
SIGC = SQRT(3.16E-03*W(I))
C22 = 04-.033*W(I)
C22 = 04-.033*W(I))
C22 = 12
C24 = 225
C24 = 12
C24 FROBABILITY N RESNEL'S TRANSMITTANCE 5 9610 R = (2.*COS(WI)*SIN(WR)/SIN(WI+WR))**2 R = (2.*COS(WI)*SIN(WR)/SIN(WI+WR)*COS(WI-WR))**2 (TPAR+TPER)/2. 4 ш AR ANGLES REA INCREMENT (DAREA) COMPUTED IN SUBROUTINE EF 3: EQNS 13, 14, 21-24, 38, 39, 79, 80 ALL AREA (DAREA) SLCPE SUBROUTINE NO JACOBIAN COMPUTED IN SUBROUTINE JACO REF 3: EQNS 48-52 CALL JACO (ALPHA, B, JACOB) (VALID=1; INVALIC=0) N ALFHA,B,WI,WR ARE COMPUTED Refs 2,364 Call Angles (Alpha,b,wI,wr) JMLO(J) = FLOAT(J) MLC = JMUO(J)/57.2558 JK = J VALIDITY CHECK AXI = ABS(XI) AETA = ABS(ETA) V/LID = 1 J-6 II II , Fare ARO 2002

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PSI,NU0,MU0£AN B LUTION FOR PSIENUO NON-ZERO: PHA & B FOR A GIVEN MUO & NUO ARE OBTAINEC BY SGLVING PULTANEOUS NON-LINEAR EQNS 82&83 OF REF 3 USING IBM SOURCE B SUBROUTINE (NLNSYS) 205 220 SCLUTICN FOR PSI NON-ZERO & NUO=0.0: ALPHA = 0. B SOLVED FROM NJN-LINEAR EQN 82 OF REF 3 USING IBM SOURCE SUBROUTINE (NLNSYS); FIRST ESTABLISH INITIAL B GUESS IF ((JK.EQ.I).OR.((JK.EQ.I5).AND.(PSIRUN.GT.30.))) GG TO 2 Y(1) = B GC TO 225 10 00 Q(1) = ALPHA C(2) = B GC TO 210 C(1) = .1 O(2) = .1 CALL NLNSYS (2,10,4,ISING,1,FINDAB,Q) ALPHA = Q(1) B = Q(2) WI = ARCOS(COS(PSI)*COS(B)-SIN(PSI)*COS(ALPFA)*SIN(B) WR = ARCOS((1./AN)*SQRT(COS(WI)**2+AN**2-1.)) GC TO 235 FIRST ESTABLISH INITIAL GUESS FOR NLNSYS
IF ((JK.EQ.I).OR.((JK.EQ.15).AND.(PSIRUN.GT.30.)))
Q(1) = ALPHA
Q(2) = B
G(2) = B
G(2) = B
G(1) = .1
Q(2) = .1 ¥ EXTERNAL FINDAB, FINDB REAL NUC, MUO, NUORUN CCMMON MUO, NUO, PSI, AN, PSIRUN, NUORUN, PI, Z, RAC, EB, JI DIMENSIGN Q(2), Y(1) IF (PSIRUN-EQ.0.) GO TO 230 IF (NUORUN-EQ.0.) GO TO 215 GIVEN (1) = 1 ALL NLNSYS (1,10,4,1SING,1,FINCB,Y) = Y(1) MI = ARCOS(COS(PSI)*COS(B)-SIN(PSI)*SIN(B)) MR = ARCOS((1./AN)*SQRT(COS(WI)**2+AN**2-1.)) GC TO 235 ALPHA, B, WI EWR SCLUTION FOR PSI=0.0: ALPHA = NUO B = ATAN((AN*SIN(MUO))/(AN*COS(MUO)-1.)) MI = B (ALPHA, B, WI, WR) FOR SOL VES ANGLES ANGLES SLEROUT INE SUBROUT INE SCI UFUERIA O 210 25 25 25 S 0 S 21 20 3 NN N 000 ပပ ပပ 0000000 ပပ





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310 F = -COTAN(NUO)+COTAN(Q(1))-SIN(PSI)/(SIN(Q(1))*SIN(Q(2))*(SIN(PSI) 1)*COS(Q(1))*SIN(Q(2))-COS(PSI)*CCS(Q(2))+SQRT((SIN(PSI)*COS(Q(1))* 2SIN(Q(2))-COS(PSI)*COS(Q(2)))**2+AN**2-1.))) Ľ PAI (ALPHAEB) REAL MLO,NUO,NUORUN CCMPON MUO,NUO,PSI,AN,PSIRUN,NUORUN,PI,Z,RAC,BB,JK DIMENSION G(2) IF (K.EG.I) GO TO 305 GC TO 310 THE FCR COMPUTING USED BY NLNSYS FINDAB (Q,F,K) Q(1)=ALPHA Q(2)=B SLEROUTINE SLEROUTINE RETURN END 315 305 ں C 000000 C

F = -COS(MU0)+(1./AN)*(CPSI+(SPSI*SIN(Y(1))-CPSI*COS(Y(1))+SQRT((S 1PSI*SIN(Y(1))-CPSI*COS(Y(1)))**2+AN**2-1))*COS(Y(1))) B=Y(1)REAL MLO, NUO, NUORUN CCMMON MUO, NUO, PSI, AN, PSIRUN, NUORUN, PI, Z, RAC, BB, JK DIMENSICN Y(1) SPSI = SIN(PSI) CFSI = COS(PSI) SLBROUTINE FINDB USED BY NLNSYS FCR COMPUTING B; SLEROUTINE FINDB (Y,F,K) RETURN END ပပပ S

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EAREA FOR GBLIQUE INCIDENCE: X1 = -(2*TAN(MU0)*TAN(NU0))/SQRT(1.+TAN(NU0)**2) Y1 = -(2*TAN(MU0))/SQRT(1.+TAN(NU0)**2) INTERMECIATE EQNS: ABX,AYS,BXAY AEX = (RAD**2)*(BB**2)*X1 AFY = (RAD**2)*Y1*SQRT((BB**2)*(X1**2)-(RAD**2)*(BB**2)+(RAD**2)*(Y1**2)) = (BB**2)*Y1*SQRT((BB**2)*(Y1**2)-(RAD**2)*(BB**2)*(RAD**2)*(Y1**2)) = (BB**2)*(X1**2)+(RAD**2)*(Y1**2) Y1**2) = (ABX-AYS)/BXAY X21 = (ABX-AYS)/BXAY IF (X1.LT.RAD) GO TO 605 FOR (DAREA) REAL MLO, NUO, NUORUN CCCMMON MUO, NUO, PSI, AN, PSIRUN, NUORUN, PI, Z, RAC, BB, JK CALL ERRSET (251,500,-1,1) If (PSIRUN.EQ.0.) GO TO 625 AREA INCREMENT SLEROUTINE AREA COMPUTES THE NCRMAL & OBLIQUE INCIDENCE. (DAREA) AREA SLEROUTINE 62C 605 61C 615 ပပ S



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63C CTNU = CAN(NUO)

74 = -RAD

75 = 0.

75 = 0.

75 = CAN

76 = CTNU = COTAN(NUO)

COR = -YINUO

COR = CERT(ABS(RAD*2*CTNU**2-YI**2+RAD**2))

COR = CCNU+*2+1.

74 = BB*SGRT(1-x4**2)RAD**2)

74 = SIGN(YY5+Y5KAD**2)

75 = SIGN(YY5+Y5KAD**2)

75 = SIGN(YY5+Y5KAD**2)

75 = SIGN(YY5+Y5KAD**2)

75 = CCNU+1.

75 = C
1-x21)**2)
C4 = (Y1*(Y1-Y22)+X1*(X1-X22))/SQRT((X1**2+Y1**2)*((Y1-Y21)**2+(X1
1-X21)**2))
IF (C3.6T.1.0) C3 = 1.0
IF (C4.6T.1.0) C4 = 1.0
CAREA = ((P1/4.)*(ATAN(C1)-ATAN(C2)))*(ARCOS(C3)+ARCOS(C4))
GC T0 640
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           CG = (YI*(YI-Y22)+XI*(XI-X22))/SQRT((XI**2+YI**2)*((YI-Y21)**2+(XI

1-X21)**2))

IF (C3.GT.1.0) C3 = 1.0

IF (C4.GT.1.0) C4 = 1.0

CAREA = ((PI/4.)*(ATAN(CI)-ATAN(C2)))*(ARCCS(C3)+ARCCS(C4))
                                                                                                                                                                                                                                                                                                                                        # REA FCR NORMAL INCIDENCE:

1 = 0.

21 = -(RAD*Y1*SQRT(Y1**2-RAD**2))/Y1**2

22 = -X21

21 = -RAD*SQRT(1.-X21**2/RAD**2)

22 = -RAD*SQRT(1.-X22**2/RAD**2)

60 T0 630
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NLNS1430		NLNS1450 NLNS1460 NLNS1460 NLNS1470 NLNS1490 NLNS1490	NLNS1500 NLNS15100 NLNS1520		/ NLNS15600	T NLNS1620	NLNS1660	NLNS16/0 NLNS1680 NLNS1690 NLNS1700	NLNS1720 NLNS1720 NLNS1730	NLNS1780	NLNSI 790 NLNSI 800 NLNSI 8100 NLNSI 8100	
SLEROUTINE NLNSYS (N, MAXIT, NUMSIG, ISING, IPRINT, EVALUT, X)	NLNSYS SOLVES A SYSTEM OF SIMULTANEOUS NCN-LINEAR EQUATIONS NLNSYS IS FROM THE IBM SYSTEM 360 SUBROUTINE LIBRARY	DIMENSION X(1) INTEGER CONVRG,TALLY,PONTER CCMMON/SS SS/ISUB(19),COE(20,21),PCNTER(20,20) EXTERNAL EVALUT DIMENSION TEMP(20),PART(20)	CCNVRG=1 INITIALIZE CONVERGENCE AND TOLERANCE DETERMINERS.	ŘĚĽČONEIO.**(-NUMSIG) ITERATION LOOP. DC 55 MEI,MAXIT PROGRAM WILL PRINT OUT SUCCESSIVE APPROXIMATICNS EF X IF	IOOO, FORMAT(1X,1240), MRITE (6,1000) M,(X(I),I=1/N) 1000, FORMAT(1X,1240), ITERATION,14,17HTFE X ESTIMATE IS,5F15.7/7F15.7	THROUGH THE VARIABLES WITHOUT INTERCHANGING ROWS CR COLUMNS.	5 PCNTER(1, J)=J CNE K FOR EACH EQUATION.	IF K IS GREATER THAN 1 BACK-SUBSTITUTION IS NECESSARY. IF (K.GT.1) CALL BAKSUB(K,N,X) CALL EVALUT(X,F,K)	7 TALLY=0 DC 10 I=K.N ITEMP=PCNTER(K,I)	HELDEXCREMENT TO OBTAIN ITEMP'TH PARTIAL. H=FACTOR*HOLD I F (H.FQ.O.) H=.001	X(ITEMP)=HOLD+H IF K IS GREATER THAN 1, A NEW X(ITEMP) VALUE WILL AFFECT X'S WHICH ARE EXPRESSED IN TERMS OF IT AS A RESULT OF PREVIOUS FOUNTION STEPS	IF (K.GT.I) CALL BAKSUB(K,N,X) CALL EVALUT(X,FPLUS,K) GET ITEMP'TH PARTIAL PART(ITEMP)=(FPLUS-F)/H
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ل ر	DIMENSIGN X(1) IN TEGER PCNTER CCMMON/SS SS/ISUB(19),COE(20,21),PCNTER(20,20)		BK SB2630 BK SB26430 BK SB2650 BK SB2650
ر	CC 10 KMM=2.K KP=K+2-KMM KPAX=I SUB(KM-1) X(KMAX)=0.		BKS8826900000000000000000000000000000000000
Ĺ	DC 5 J=KM,N JSUB=PONTÉR(KM,J) SFF (3) FOR THF FXPRFSSION FOR X(KMAX).		BK 5B2710 BK 5B2720 BK 5B2730
	5 X (KMAX) = X (KMAX) + COE (KM-1, JSUB) * X (JSUB) 0 X (KMAX) = X (KMAX) + COE (KM-1, N+1) RETURN END	-	BK SB2740 BK SB2750 BK SB2750 BK SB2750



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