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Monterey, California: U.S. Naval Postgraduate School

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A TACTICAL DATA SIMULATION PROGRAM
FOR THE CONTROL DATA 1604 COMPUTER
AND THE dd65 DISPLAY CONSOLE

EDWARD L. BORDEN
and
ANTHONY C. CASCIATO

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A TACTICAL DATA SIMULATION PROGRAM FOR THE CONTROL DATA
1604 COMPUTER AND THE dd65 DISPLAY CONSOLE

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Edward L. Borden
and
Anthony C. Casciato

A TACTICAL DATA SIMULATION PROGRAM FOR THE CONTROL DATA
1604 COMPUTER AND THE dd65 DISPLAY CONSOLE

by

Edward L. Borden

Lieutenant, United States Navy

and

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Lieutenant, United States Navy

Submitted in partial fulfillment of
the requirements for the degree of

MASTER OF SCIENCE
IN
ENGINEERING ELECTRONICS

United States Naval Postgraduate School

Monterey, California

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A TACTICAL DATA SIMULATION PROGRAM FOR THE CONTROL DATA

1604 COMPUTER AND THE dd65 DISPLAY CONSOLE

by

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This work is accepted as fulfilling
the thesis requirements for the degree of

MASTER OF SCIENCE

IN

ENGINEERING ELECTRONICS

from the

United States Naval Postgraduate School

ABSTRACT

There exists a need for a simulation program that will enable a programmer to simulate systems such as the Naval Tactical Data System (NTDS), Marine Corps Tactical Data System (MTDS), Airborne Tactical Data System (ATDS), or any other system that uses radar or sonar information for operation. A programming project was undertaken using the Control Data 1604 Computer (CDC 1604) and the Data Display Incorporated model dd65 Display Console (DD65) as the basic hardware. The program developed features on-line control of the CDC 1604 by the DD65, display of simulated targets and messages on the DD65, control of tracks by operating personnel from the DD65, continuous graph output for permanent record purposes, and real time or double real time operation. This program can be expanded to provide more features of any of the tactical data systems by the addition of the appropriate subroutines.

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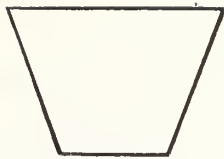
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TABLE OF SYMBOLS

Basic Symbols



Input/Output



Processing



Annotation

Specialized Input/Output Symbols

Punched Card



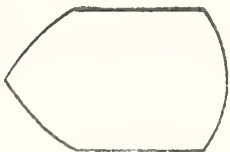
Document



Manual Input

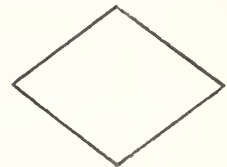


Display



Specialized Processing Symbols

Decision



Predefined Process



Additional Symbols

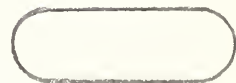
Entry/Exit



Connector



Statement Tag



Off-page connector



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1. Introduction.

1.1 Background. With the development of new weapons systems, there has been a renewed interest in the study of tactical methods and the importance of command decisions. This first manifested itself in studies of abstract mathematical models which later provided the basis for pure computer simulation. By a thorough analysis of the results of the simulation, much valuable data on expected system performance was obtained; however, these models did not allow for the man made command decision, nor did they operate in real time with a realistic environment. There must be a more flexible man-machine interface to allow the tactician to construct controlled situations at will, to observe directly the effect of one or more command decision links, to modify parameters assumed for system components, and to provide hard-copy records for a later critique of the situation.

1.2 Proposed Approach. The objective of the thesis project to be described in this paper was to undertake, within the constraints of currently available equipment, the implementation of a simulation system that would be used as a test vehicle to study any problem that involve trajectories. The salient characteristics of the system were to be:

- (1) A flexible, fine grain, three dimensional track generator.
- (2) A direct man-computer interaction capability (i.e. "on-line" control).
- (3) A language independent approach to setting up simulated tactical situations.
- (4) A modular approach to inserting sub-systems for testing.
- (5) A real time approach to the simulation problem.

A flexible track generator was felt to be a basic necessity in order to provide realistic problem inputs to replace the classical step and ramp input functions. The track generator should have the capability of duplicating the actual position information available to a surveillance system.

In order to take maximum advantage of man-computer interaction capability, it was felt there was a need for direct man-computer communication as well as pre-programmed communication. To this end, an executive routine, that would act as the coordinating routine between the track generator, man communication, display, etc., would be developed. The executive routine would operate in real time in order to provide realistic simulation.

1.3 User Capabilities.

1.3.1 Tactical Data Simulator. A typical tactical data problem (NTDS type) would be one of pre-programmed hostile tracks, one or more surface ships on station, and one or more friendly aircraft, each under computer (pre-programmed) or console control. Then either a canned problem or an actual problem could be run using the console for track modification.

By use of the hard-copy critique output, the user may examine one or more of the following:

- (1) The quality of the position information generated by his systems equations.
- (2) The effects of various noise environments upon the quality of position information.
- (3) The results of tactical decisions made and a comparison of the results, of rerunning the problem, with different tactical decisions being made.

1.3.2 Control System Test Vehicle. An example of a control system test vehicle would be a test of a Carrier Automatic Landing System. The track generator would furnish the fine grain aircraft position data and would receive orders from the landing system computers. The stability of the Carrier Automatic Landing System, as well as its accuracy, versus changing parameters could readily be studied. Using the same approach, many different types of control systems could be studied, such as:

- (1) Air to Surface missile systems.
- (2) Surface to Surface missile systems.
- (3) Surface to Air missile systems.
- (4) Subsurface to Air missile systems.

2. Programming.

2.1 Programming Language. The following languages were readily available to the authors:

- (1) FORTRAN 60.
- (2) FORTRAN SYMBOLIC.
- (3) FORTRAN 63.
- (4) ALGOL.
- (5) SCRAP.
- (6) CODAP.

In choosing a language, several criteria must be met:

- (1) Ease of manipulating individual bits.
- (2) Flexible input/output routines.
- (3) Availability of diversified library subroutines.
- (4) Flexibility of operation.
- (5) Ease of programming.

Some of the available languages satisfied several of the desired criteria, however, it was felt that only FORTRAN SYMBOLIC met all of the requirements. In addition, the FORTBIN compiler associated with FORTRAN SYMBOLIC is very reliable and libraries may be manipulated at will. For these reasons FORTRAN SYMBOLIC was chosen.

2.2 Initial Programming. Initially, it was decided to divide the programming into two areas. These areas were:

- (1) Executive Control Routine.
- (2) Track Generator.

It was felt that each of these areas were independent enough to allow for separate work. A general outline of the interface was set down,

	EXECUTIVE FLAG TABLE (EFT)	EXECUTIVE TIME TABLE (ETT)	EXECUTIVE JUMP TABLE (EJT)
1	_____	<u>1 second</u>	<u>A</u>
2	_____	<u>6 seconds</u>	<u>B</u>
3	_____	<u>6 seconds</u>	<u>C</u>
4	_____	<u>10 minutes</u>	<u>D</u>
5	_____	<u>2 hours</u>	<u>A</u>
6	_____	<u>1 minute</u>	<u>E</u>
7	_____	<u>30 seconds</u>	<u>F</u>
8	_____	<u>4 seconds</u>	<u>H</u>
9	_____	<u>1 hour</u>	<u>D</u>
M = 10	_____	_____	_____

Figure 1. Example of Executive Table Structure

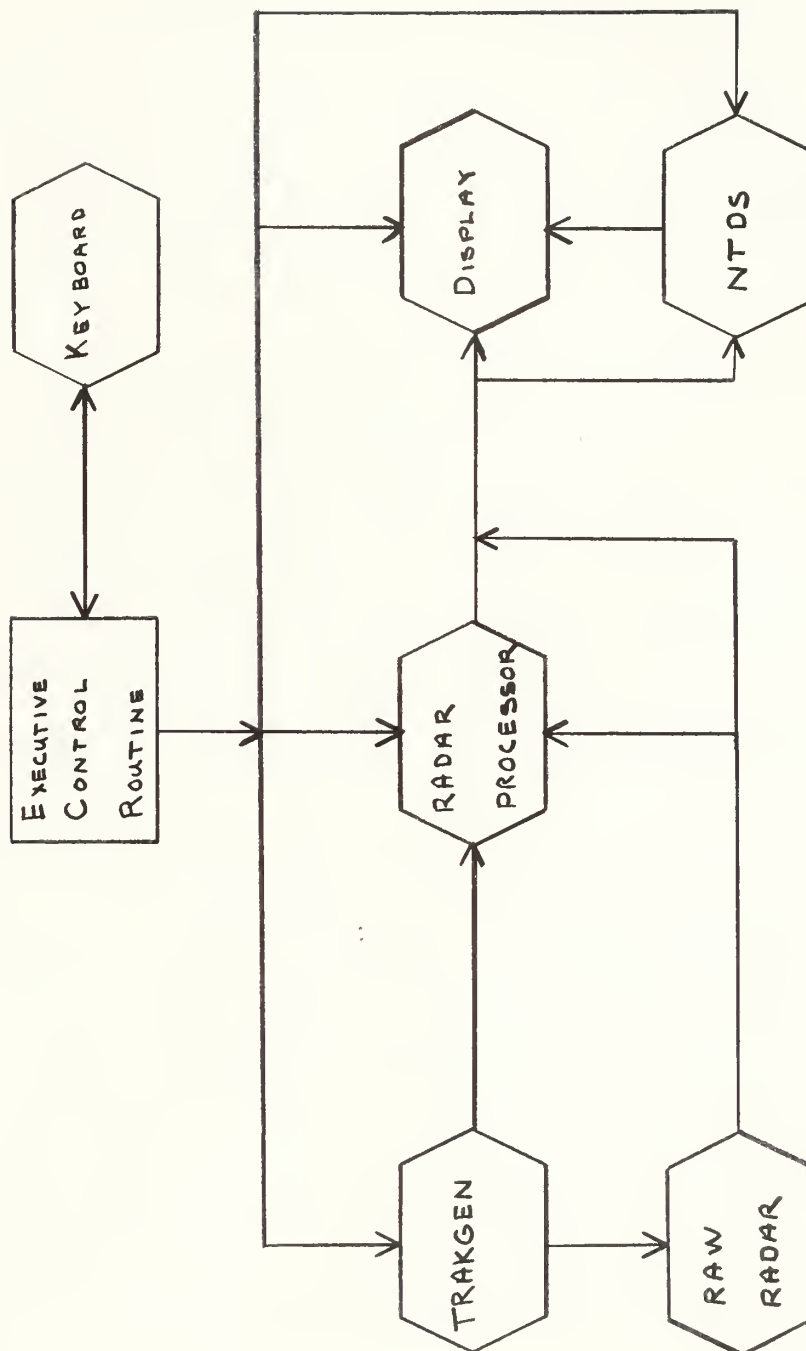


Figure 2. Original Concept of SIMONE

with the final details left to be established as the programs developed. This worked very satisfactorily.

2.2.1 SIMONE.

2.2.1.1. Basic Philosophy. Upon analysis of the problem, the initial frame work was set down as represented by Fig. 2. The system was to operate in real-time, therefore, an executive routine would be needed and would be the heart of the system. The philosophy of the executive routine is found in [14]. Briefly this philosophy is:

- (1) Subprograms are considered for execution on the basis of their priorities as system components.
- (2) Subprograms would be listed by priority and this list would be scanned sequentially, executing subprograms as they are needed.
- (3) After each execution, the scanning process would be resumed starting with the highest priority entry.
- (4) Assumption is made that sufficient computational capability exists to perform all assigned tasks.
- (5) A subprogram is executed only when its "flag" is set.

The executive control philosophy is implemented through a method of table control. Three tables, Executive Flag Table (EFT), Executive Time Table (ETT), and Executive Jump Table (EJT), contain the necessary information for executive control. See Fig. 1. There is a one-to-one correspondence between these tables. Fig. 3 is a flow chart of the Executive Control Program. Starting with this basic routine and the functions of the following subprograms, the initial programming was undertaken:

- (1) Keyboard Processor
- (2) Radar Processor
- (3) Track Generator
- (4) Display Routine
- (5) Raw Data Routine
- (6) NTDS Routine

2.2.1.2 Programming and Problems. The implementation of Fig. 3 was accomplished with very little difficulty. The executive tables were implemented as arrays with the exception of the EJT. The EJT was programmed as the addresses of jump instructions in the program. By using the philosophy of the computed GO TO of FORTRAN, the appropriate jump will be executed based on the EJT index.

With the basic control routine working, the next step was to determine the method by which the DD 65 would communicate with the main computer. There are two basic methods by which the DD 65 may communicate with the CDC 1604. The first is via the CDC 160 and the second is via Channel 7. The first method involves the use of the CDC 160 to interrogate the DD 65 and then to transfer the information from the DD 65 to a buffer in the CDC 160 and then finally to transfer this stored information to the CDC 1604. This method is similar to that used in satellite operations. [12] The second method provides for direct communications between the CDC 1604 and the DD 65 via Channel 7. The latter method has two modes of operations with respect to the DD 65, active and passive. The active mode involves the use of the interrupt features of the DD 65 while the passive mode involves an interrogation similar to that used by the CDC 160. The first method using the CDC 160 was not

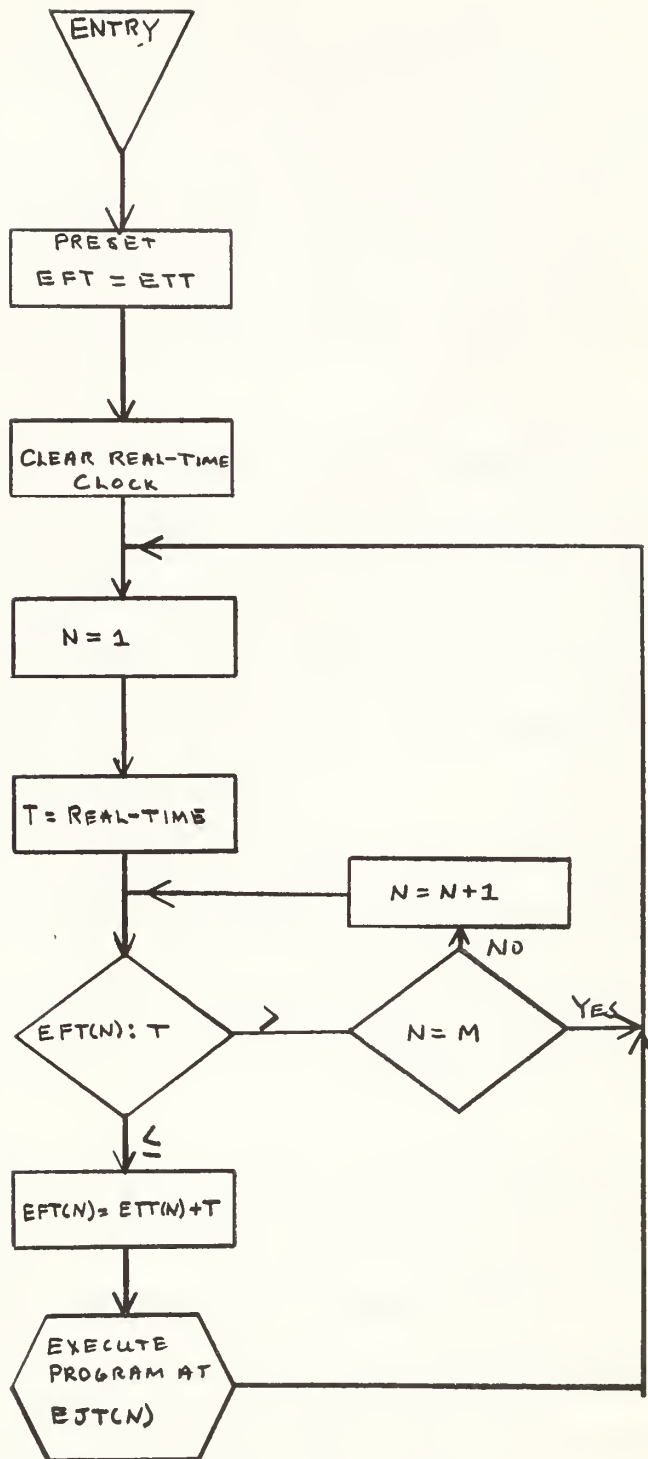


Figure 3. An Executive Control Program

chosen due to the desire to keep the programming as simple as possible. The active mode of the second method was chosen because of its ability to provide continuous control of the CDC 1604. In the passive mode, control of the CDC 1604 would occur only at predetermined times. This may or may not be desirable. In the active mode, the desired control information is transferred to the CDC 1604 instantaneously. This instantaneous transfer allows for the fastest response to the commands originated at the DD 65 console. With these decisions made, the major programming was started.

To program the interrupts, a copy of the MACHINE RESIDENT was used to determine the actual address in memory of the clock processor. By substituting the address of SIMONE's interrupt routine in lower cell 7, and by jumping to the clock processor after checking for interrupts from the DD 65, the interrupt tests were ready to run. This arrangement proved to be satisfactory for the time being.

As the program developed, changes were made to RESIDENT and consequently the program had to change. In order to make SIMONE independent of any address in RESIDENT, the clock processor was incorporated in SIMONE's interrupt processing routine. At this time the double real-time feature was also added.

The next problem was that of how to handle the input functions. The first approach was to use a very complicated jump table and flags within the subroutines. This approach proved very cumbersome, therefore, a new solution was sought. This solution came in the form of a 30 x 3 matrix, which composed a control table for Keyboard 2, and a buffer for storage of both Keyboard 1 and 2 information. See Fig. 5 for Keyboard 2

Control Table. Each row in the matrix corresponds to one of the switches on Keyboard 2. The columns provide information that enables the computer to process the command.

The problem of display was solved with the development of subroutine PRINT. For a complete explanation see Appendix III. For the display, symbols had to be developed by using the vector mode of the DD 65. These symbols are shown in Fig. 6. The results were not entirely satisfactory. The raw radar symbol was changed to just two vectors end to end with the X and Y position located at the junction of the two vectors. The remaining symbols are fine for the smaller scales, however, they are too large when the display scale is set for 256 miles. These symbols are, however, the smallest available with present equipment and logic.

As the philosophy of the program expanded, it became evident that there must be some type of hard-copy record of each problem run. This was the beginning of the critique routine. The initial thoughts centered around the use of scratch tapes to have all information and then at the end of the problem to provide a graph output. The basic idea was to plot one graph that would show all tracks in the xy plane. The critique routine was programmed and tested. The results of the test showed this method to be feasible, however, some difficulty was encountered. When trying to read the scratch tape, parity errors occurred. To eliminate this problem, memory was chosen to be the scratch pad. This proved quite satisfactory, however, due to the limited size of the scratch pad, only 10 minutes of information could be stored. The solution to this problem was another subprogram that would plot a

graph every 10 minutes. During the reprogramming, a second graph was added that would provide for an altitude profile vs. time plot. The last modification included the point plotting of both the smoothed position and the actual position at time intervals to be specified by the user.

The radar processor was made very simple. It included the smoothing equations normally associated with the "Alpha-Beta" tracker. [1]. It is in this routine where there is much to be done. Several types of smoothing and predicting equations are available. Both the NTDS and the MTDS systems were studied.

As the programming continued, the basic frame work was expanded to include many routines. These routines are explained in detail in Appendix I and an explanation of their use is found in Section 4.4.2.

See Fig. 4 for final Block Diagram.

2.2.1.3 Future Expansions. There are many areas for expansion. Some of these would be:

- (1) On-line graph plotting on an XY plotter.
- (2) New smoothing equations.
- (3) A more complete intercept routine.
- (4) A more sophisticated display routine.
- (5) Integration of program with FORTSHARE [12] .
- (6) Incorporation of a radar characteristic table.
- (7) A more complete aircraft characteristic table.

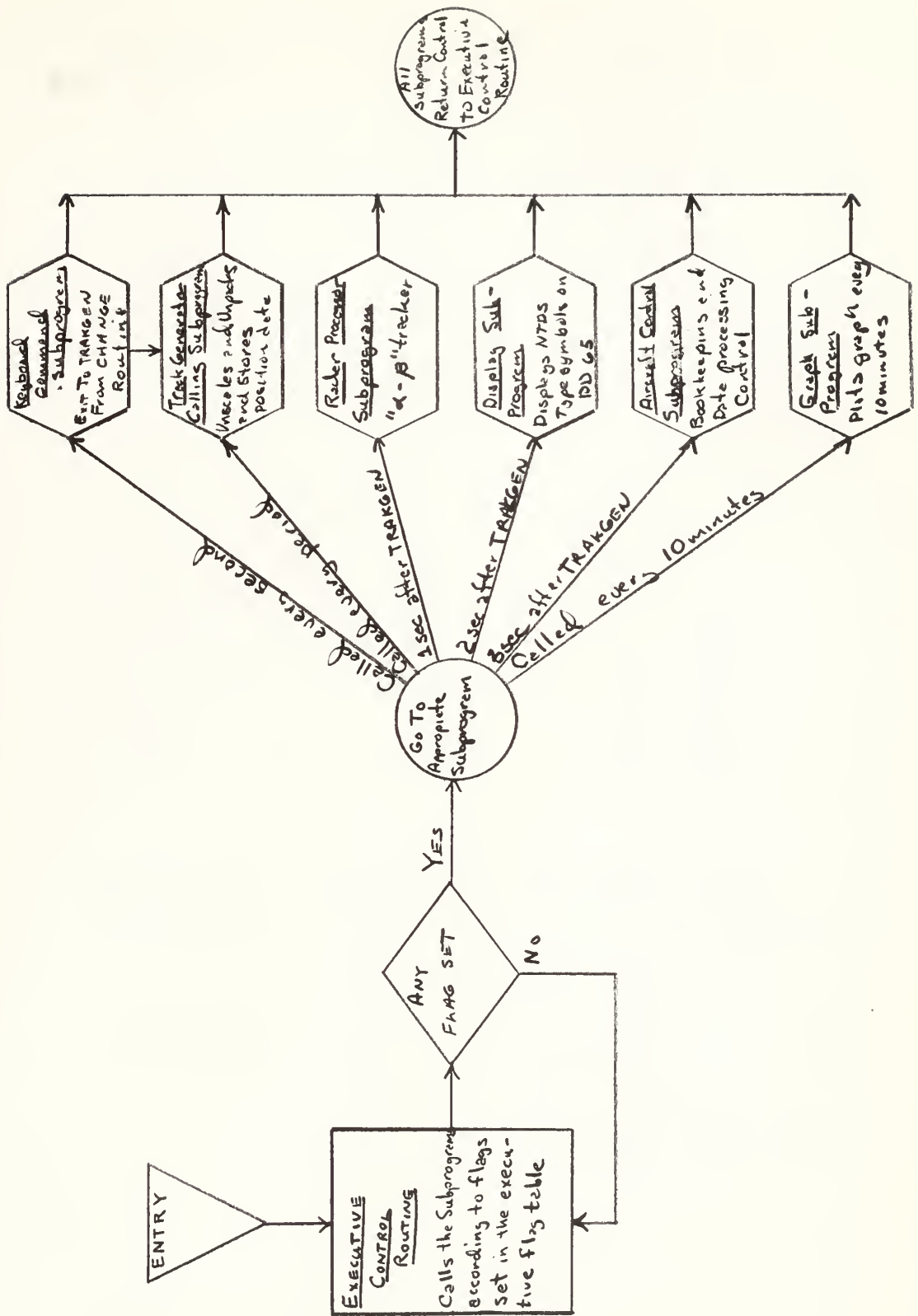


Figure 4. Final Block Diagram of SIMONE

BUTTON TABLE	LIGHT TABLE	TRANSFER TABLE
01	77202	5 P0
02	77204	6 P1
03	77210	6 P2
04	77220	7 P3
05	77240	5 P4
11	77302	4 P5
12	77304	4 P6
↓	↓	↓
53	77710	5 P27
54	77720	8 P28
55	77740	8 P29

BUTTON TABLE = Code from DD 65 Keyboard 2 switch.

LIGHT TABLE = External Function Code for turning on
Computer Controlled light indicator.

TRANSFER TABLE = Number of Characters in the name of the
program called and the address of the
name. (Used to transfer program name to
the buffer.)

Figure 5. Keyboard 2 Control Table














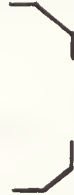
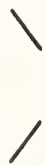
	Hostile Aircraft		Friendly Aircraft		Unidentified Aircraft
	Hostile Submarine		Friendly Submarine		Unidentified Submarine
	Hostile Surface		Friendly Surface		Unidentified Surface
	Own Ship				
	Task Force Center				
		Original Radar Symbols (By Quadrants)		Final Radar Symbols (By Quadrants)	

Figure 6. Display Symbols for DD 65

2.2.2 Subroutine TRAKGEN.

2.2.2.1 Early Philosophy. The track generator should be able to generate several tracks, each of which could be maneuvered in three dimensions at the will of the user. It should be able to produce tracks which could simulate aircraft, ships, and submarines. This placed a requirement for a very wide speed range capability on the track generator. The track generator should be capable of being coupled with a track parameter program which would give each track the characteristics of a particular aircraft or vessel.

It was decided to program the track generator as a very fine grain "actual" track generator. This would mean very high resolution capability in three dimensions. The user could then feed this data through a radar simulator program which would deteriorate the data to simulate a specific radar system in a particular environment.

The subroutine should be able to accept preprogrammed track commands and on-line commands from the user. It should then be expanded to allow track control from the tactical data system in the calling program.

2.2.2.2 Initial Programming. The first decision faced in programming the track generator was to determine the number of tracks to be generated. This number would be dependent on user need, available memory space, and program running time. It was felt that there should be a minimum of ten tracks available in order to provide reasonable flexibility. The number 15 was finally chosen mainly because it was convertible to a convenient power of two in binary form.

The first block diagram for TRAKGEN is shown in Fig. 7. Since the subroutine would be generating and storing information on several tracks

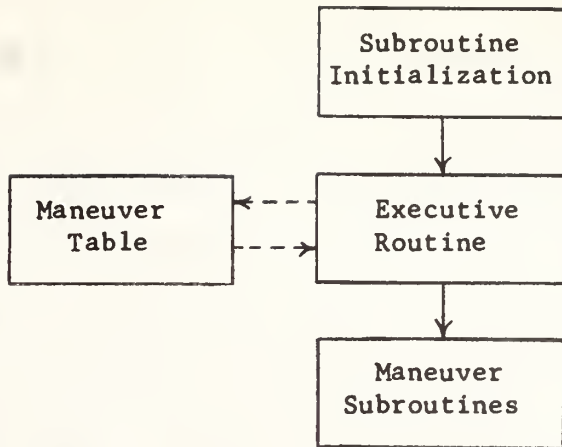


Figure 7. Initial Block Diagram for TRAKGEN

according to a maneuver (command) table, some initialization of matrices and flags would be necessary. It was decided to store the initial position, course, and speed for each track during this phase of the subroutine. Some signal was necessary from the calling program to allow initialization at the proper time. The real-time for the problem would have to be transferred with each call anyway, so a search was made for a way to utilize this as a flag. If the subroutine could be called initially with the real-time equal to zero, the initialization could be accomplished without fear of the flag reappearing later in the program and without the need for a separate flag word.

All track information is stored in a 15 x 6 matrix composed of 48 bit computer words. The track number corresponds to the row number in the matrix. The columns are arranged as shown in Fig. 8. Since the memory requirements for the program were unknown, it was felt necessary that track information be packed into the matrix words rather than stored in individual words. The number of bits assigned to each variable was arrived at by trial and error once the maneuver routines were programmed. The final size was determined by a requirement for slow speed tracking at an angle close to the cardinal compass points. Since the computation is done in part in fixed point arithmetic, a slow track would have to move far enough to change by one bit in order to maintain proper course. This was accomplished by balancing the overall range, the minimum track speed, and the calling period and arriving at the necessary bit resolution. The tracking criterion was that a one or two knot track should be able to track at an angle of five degrees off of a cardinal compass heading with a calling period of one second. At the same time, an overall range capability of ± 250 miles was desired. With the number of bits allotted, a two knot track can meet the five degree requirement with a one second calling period. A calling period of greater than one second allows a one knot track to meet the requirement. Similar reasoning was used to arrive at the altitude packing. The same number of bits were allotted to altitude as to X and Y position for the sake of symmetry. The track course was stored in tenths of degrees to allow turning rates of less than one degree per second with fixed point computation. Since a floating point capability was available in the computer, all quantities were stored in their original units; i.e., course is stored in tenths of

IPOSIT, IPOSIT1 Arrays:

X Position 24 bits	Y Position 24 bits
--------------------	--------------------

IPOSIT contains the X and Y position information for active tracks.

IPOSIT1 initially contains the initial X and Y position for pre-programmed tracks. After the track is started, IPOSIT1 is used to store position information for faded tracks.

IHEAD Array:

Turn Rate 8 bits	Ordered Crs. 9 bits	Course 12 bits	Speed 12 bits
---------------------	------------------------	-------------------	------------------

FFLAG (fade command flag) 1 bit
 IFADE (fade flag) 1 bit
 ISKIP (keyboard control flag) 1 bit
 Maneuver Code 4 bits

JHEAD, JHEAD1 Arrays:

Ordered Altitude 24 bits	Altitude 24 bits
--------------------------	------------------

JHEAD contains altitude information for active tracks.

JHEAD1 initially contains the initial altitude for preprogrammed tracks. After the track is started, JHEAD1 is used to store altitude information for faded tracks.

KHEAD Array:

Spare 12 bits	Acceleration Rate 8 bits	Climb Rate 16 bits	Ordered Speed 12 bits
------------------	-----------------------------	-----------------------	--------------------------

LHEAD Array:

Maneuver Limit 18 bits	X Position 9 bits	Y Position 9 bits
---------------------------	----------------------	----------------------

Track Number 4 bits
 Maneuver Code 5 bits
 Spare 2 bits
 LFLAG 1 bit (a 1 indicates LHEAD command present)

Figure 8. Subroutine TRAKGEN Array Formats

degrees rather than an artificial unit such as BAMS (Binary Angular Measure).

The executive routine divides non-initial calls of the subroutine into two parts:

- (1) Update maneuver codes.
- (2) Update positions.

The first section checks the maneuver table to see if any tracks are due to be maneuvered at this time. If there are maneuver commands, the proper changes are made in the maneuver code stored in the track matrix. Maneuver limits and rates are also stored in proper portions of the matrix.

The second section updates all 15 tracks according to the maneuver code stored in the track matrix. Initially, a print statement would print out what maneuver had been scheduled for each track. After the executive routine was functioning properly, the maneuver routines were inserted in place of the print statements.

The first maneuver routines were:

- (1) Constant course routine.
- (2) Turn routine.
- (3) Climb routine.
- (4) Speed routine.

No provision was made to perform more than one maneuver at a time in the initial programming of TRAKGEN.

The constant course routine takes the track speed per second times the calling period in seconds and computes incremental X and Y distances and adds these to the original position of the track.

The climb and speed routines are similar and simply increment altitude or speed linearly for the number of seconds in the calling period.

The turn routine was the last maneuver section programmed and was the most complicated due to the fact that a track can arrive at a given course by turning in either direction. Two methods of generating a curved track were studied. The first was a computation based on turning radius, bank angle, speed, and turn center position. [18]. The second method was a straight line approximation based on speed and turn rate only. After trying both methods, it was decided that the straight line approximation gave satisfactory results with less computation. The turn routine geometry is shown in Fig. 9. In order to insure stability and uniformity regardless of the calling period, the track is incremented in one second segments. Only the positions corresponding to a calling period time are transmitted to the calling program. If a turn will be completed in less than the number of seconds available in the calling period, the track is incremented in one second segments until just short of the ordered course. Then the track is set to the ordered course for the final increment. See Fig. 10.

Tests were run on the turn routine to check the validity of the approximation. A 1000 knot track was programmed to perform repeated 360 degree turns with a calling period of six seconds. A total of eight revolutions was made and a graph output showed that the track accurately retraced its path on each revolution. This indicates that the approximation results in stable arcs and that circles do not degenerate into logarithmic spirals.

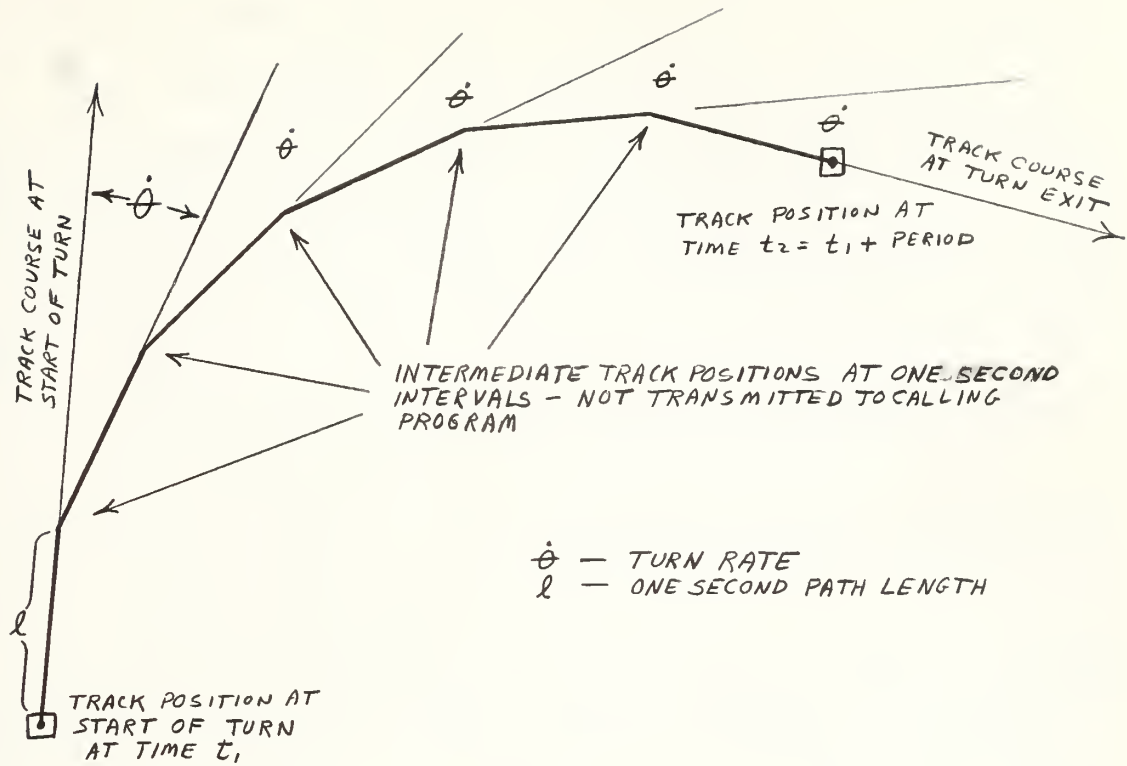


Figure 9. Unfinished Turn

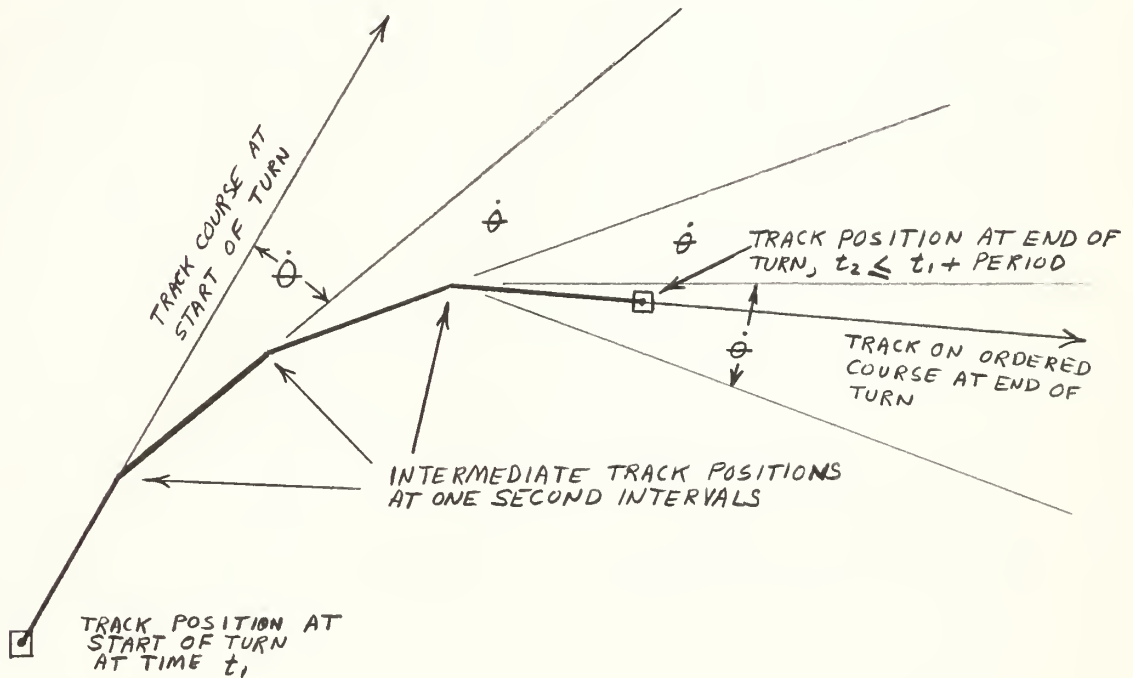


Figure 10. Completed Turn

2.2.2.3 Expanding the Program. At this point, the track generator was capable of generating tracks which could perform only one maneuver at a time. Some method had to be devised to allow multiple maneuvers such as a climbing turn. It was felt that a proper choice of maneuver code table and maneuver sequencing could solve this problem.

There are two possible methods of controlling the tracks by maneuver codes.

- (1) Insert a code to initiate the maneuver and insert a separate code to stop the maneuver.
- (2) Insert a code to initiate the maneuver along with the desired maneuver limit and rate.

The second method was chosen since it reduces the number of maneuver table entries by a factor of two. It also corresponds to the normal method of giving commands to operating units in the fleet. Many forms of maneuver code table were tried and discarded as being too cumbersome. There are three basic maneuvers, turn, climb, and accelerate. If these are equated to maneuver codes of two, three, and four, the simple addition of desired maneuvers will result in a distinct maneuver code for all possible combinations of maneuvers. These are shown below:

- 2 Turn (basic command).
- 3 Climb (basic command).
- 4 Accelerate (basic command).
- 5 Climbing turn.
- 6 Accelerate in a turn.
- 7 Accelerate in a climb.
- 9 Accelerate in a climbing turn.

To fit in with the addition or subtraction of maneuver codes, the code of zero was assigned to a constant course, speed, and altitude track.

These maneuver codes are internal to the program; the external codes being turn, climb, and accelerate only.

Since the only external codes being used were two, three, and four, this left all other unused numbers available for other functions. The external maneuver code decided upon is:

- 1 Start track.
- 2 Turn.
- 3 Climb/dive.
- 4 Change speed.
- 5 Fade.
- 6 Unfade.
- 8 Scrub track.

The fade command allows a track to disappear from the position array while still being capable of performing all maneuvers. The unfade command returns the track to the position array for normal display. The maneuver code seven is unused.

In the initial program, the maneuver table was read in during the initial call and stored in memory. This severely limited the size of the maneuver table. For this reason, the maneuver table was changed to a data deck table and only one maneuver entry at a time is stored in memory. Each maneuver table entry contains:

- (1) Maneuver execution time.
- (2) Track number.
- (3) Maneuver code.
- (4) Maneuver limit.
- (5) Maneuver rate.

Besides being controlled from the programmed maneuver table, it was desired that tracks be able to maneuver according to the dictates of the user or according to the computations in the data process section

of the calling program. In order to avoid redundancy, it was decided to convert the necessary commands into the same form as that read from a maneuver table data card and to insert these into the program in place of data card information. From this point on, the information is processed the same as a maneuver table entry.

Two sections in the program were developed to handle the interface between the input command and the main subroutine. The Keyboard Control Section is designed to handle commands from the DD 65 console keyboard. It performs checks on the command information to determine if the track called for is available for control. It also sets a flag in the track matrix to disallow further preprogrammed commands since they will be meaningless once the track has been displaced from its preprogrammed track. The one exception to this is the keyboard fade or unfade commands which do not alter the track path and, hence, do not disallow maneuver table commands. All tracks are available for keyboard control with the exception of preprogrammed tracks which have not yet been started by the maneuver table command.

The Data Process Section can control any number of tracks simultaneously. It processes the information from the tactical data section of the calling program into a form suitable to be fed directly into the Keyboard Command Section. Input command information flow is shown in Fig. 11.

2.2.2.4 Future Expansion. Subroutine TRAKGEN can be expanded in several areas. The input maneuver code could be changed so that input commands are inserted in plain language for convenience. The Hollerith word then would select the internal numerical maneuver code.

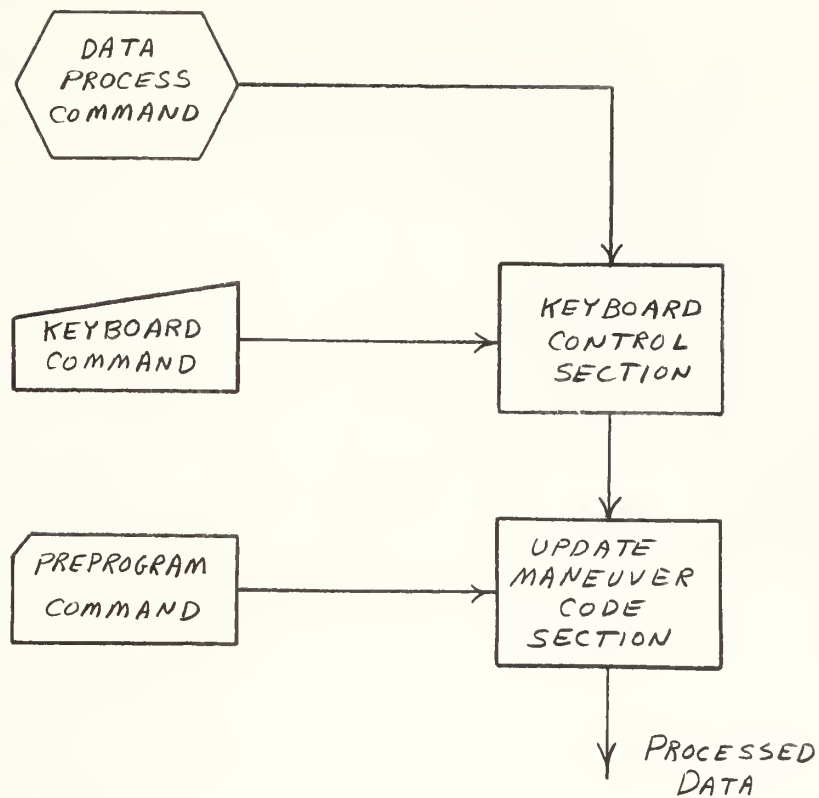


Figure 11. Command Flow Paths

Since the memory capacity of the 1604 has not been fully utilized, it is possible to expand the capability of TRAKGEN to handle more tracks or to have greater range capability. Trakgen requires an additional nine words for each track and the calling program SIMONE requires another 70 cells to allow expanded scratch pad space for each track. The range capability can be expanded by eliminating X, Y, and Z packing and using a complete word for each quantity. This would also allow greater resolution and consequently slower speeds and slower accelerations.

Another expansion of TRAKGEN would be the provision for negative track speeds to allow ships and submarines to back down. This would entail a reworking of the IHEAD array and the pack/unpack sections pertaining to speed and ordered speed.

To keep up with today's high speed aircraft, it would be well if the subroutine could accept maneuver rates in terms of maximum allowable g-forces on the aircraft and pilot. A section could be programmed which would compute these forces as functions of speed and altitude. In this context it would be well to make provision for entering aircraft speeds in mach number as well as well as knots. The g-force section would also prevent aircraft from performing maneuvers which in real life would be physically impossible. It is advisable when doing this to avoid including any classified aircraft parameters to avoid the necessity of classifying the program.

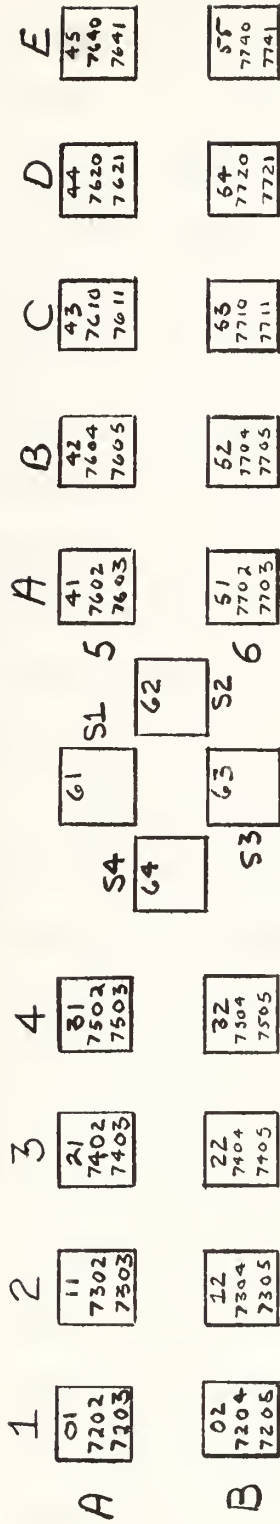
3. EQUIPMENT.

3.1 CDC 1604. The CDC 1604 is a stored-program, general-purpose digital computer, with a storage capacity of 32,768 48 bit words, designed to solve large scale scientific problems and to handle large volume data processing.

The input-output section of the computer handles the flow of information to and from the computer. The computer communicates with external equipment on one of seven channels. Six of these channels are independent buffer channels which provide for the normal input-output exchange of data. The input-output channels are paired, channels 1 and 2, channels 3 and 4, and channels 5 and 6. Channel 7 is a high-speed (4.8 usec per word) transfer channel on which up to eight different equipments may be connected. All communications between the CDC 1604 and the DD 65 were on this channel. By use of the CDC 160 computer as a buffer, communications can be established with the DD 65 using channels 5 and 6. This latter method is similar to that used in the Satellite System. 12 .

3.2 DD 65. The DD 65 consists to two units, the display console and the logic unit. The display console consists of two 12-inch electrostatically deflected tubes. Each tube has a usable display area of 8.5 x 8.5 inches. The left hand tube is normally used to display raw video from one of several radar inputs. The right hand tube is a non-radar tube used to display messages, symbols, etc.

There are several methods of inputting operator commands into the computer. They are by use of an alphanumeric keyboard, a general purpose keyboard, a track-ball controller, and a range switch.



Each of the squares represents a switch on Keyboard #2; the outer characters are switch designators. Depressing any switch generates the 2-digit code shown within the corresponding square. The 4-digit codes inside the squares are computer codes that control the corresponding indicator lights. Even codes turn the indicators ON; the odd codes turn them OFF.

Figure 12. Switch Designations and Input/Output Codes for Keyboard 2

The logic unit consists of a 1024 24 bit word core memory. Each word is paired to give an effective 512 48 bit word memory. This memory can display data at very high refresh rates. There is a switch inside the logic cabinet that enables one to use only the lower half of memory, thus giving less flicker on the tubes. However, it was found that the flicker was not bad and the advantage of extra memory far out weighed the slight discomfort of the flicker.

3.2.1 Command Inputting Devices. The command inputting devices are designated as Keyboard 1, Keyboard 2, Track Ball, and Range Switch. Keyboard 1 is an alphanumeric typewriter keyboard. There are 64 keys on Keyboard 1 of which 60 represent different symbols and three editing keys, i.e., carriage return, space, and tab, and one unassigned key, (code 00).

Keyboard 2 is divided into three functional sections. See Fig. 12. The first section consists of 20 switch units arranged in a 4 x 5 matrix. This group has computer selected light indicators and provisions for insertion of separately coded switch matrix overlays. By use of these overlays, many different functions may be programmed. The second consists of 4 special switch units. These units are grounded to the 60 cps power supply. This enables the switch code to be sent to the computer 60 times a second without having to hit the key but one time. This enables this group of keys to move an editing symbol over the display surface. The third section is a group of 10 switches located over the alphanumeric keyboard. These have associated computer controlled light indicators, also. This set of switches is designed to perform functions common to all overlay programs.

The Track Ball is located to the right of the display tubes on the monitor table top. The X and Y coordinate information is available at all times to the computer and need only be selected.

The last command inputting device is not really a command inputting device, however, it was used for this purpose. This is the Radar Range Switch. This is an 8-position switch which is used to select the range of the display. The 8 positions, ranges and associated codes are shown in Fig. 13.

<u>Switch Position</u>	<u>Code</u>	<u>Switch Position</u>	<u>Code</u>
OFF	0	32	4
4	1	64	5
8	2	128	6
16	3	256	7

Figure 13. Range Switch Coding.

4. Usage.

4.1 General. This routine is intended for use with the normal library currently used by the Computer Facility. Complete compatibility has been maintained.

4.2 Program Format. This routine will normally be called from a reserve library tape. However, if the user wants to modify the program in order to use his own subroutines, the program will be operated under card control. In this case, the following is an example of the normal run using the CDC 405 card reader:

```
SET,5000,66.                (Memory scratch pad)
CALL,1,FORTBIN.             (Compiler)
FORTBIN,C,1.                (Compiler program)
        PROGRAM SIMONE      (Program)
        -
        -
        -
        -
        END
        END
        (Blank card)
        (Blank card needed for card reader)
SIMONE.
* Data
        -
        -
        -
        -
        ..
CONTROL,0.
```

To execute this program, load the card reader with the above cards and then type on the typewriter, "control,c,p.". This will start the card reader and all control statements will be printed on the CDC 1612 printer.

After the user has checked out his program, the following methods are suggested:


```

CALL,1,FORTBIN.
FORTBIN,C,1,4.
    PROGRAM SIMONE
        -
        -
        -
        -
    END
    END
(Blank card)
CONTROL,0.

```

This will cause SIMONE to be compiled and placed in library format on tape 4. A pre-compiled program is ready to run. Due to the fact that cells 5000₈ to 20300₈ are used as a scratch pad, SIMONE cannot be called and run. The following program will allow for the proper space being left for the scratch pad:

```

SET,5000,66.
CALL,1,FORTBIN.
FORTBIN,C,4.
    PROGRAM SIMTWO
    CALL SIMONE
    END
    END
(Blank card)
(Blank card)
SIMTWO.
*Data
    -
    -
    -
..
CONTROL,0.

```

This program reduces the recompile time from about eight minutes to approximately 18 seconds.

4.3 The Data Cards.

4.3.1 The first data card contains job identification. It will be reproduced on the graph output. Use columns 1 through 8. This identification could be in the form of a date, run number, etc.

4.3.2 The second and third data cards contain the necessary arguments for the graph outputs:

- (1) XSCALE: Columns 6 through 11. X-scale in units per inch. The units are miles for the second data card and minutes for the third data card. The format is E6.0.
- (2) YSCALE: Columns 13 through 18. Y-scale in units per inch. The units are miles for the second data card and feet for the third data card. The format is E6.0.
- (3) IXUP: Columns 20 and 21. Distance in inches, of the X-axis from the bottom of the graph. Format I2.
- (4) IYRIGHT: Column 23. Distance in inches, of the Y-axis from the left of the graph. Format I1.
- (5) MODEXAX: Column 25. Determine the mode of the X-axis location 20 . Format I1.
- (6) MODEYAX: Column 27. Determines the mode of the Y-axis location 20 . Format I1.
- (7) IWIDE: Column 29. Width of graph in inches. Format I1.
- (8) IHIGH: Columns 31 and 32. Height of graph in inches. Format I2.
- (9) IGRID: Column 34. If IGRID = 1, a 1" x 1" will be superimposed on the graph. Format I1.

The second card furnishes the information for the X - Y position graph and the third card the information for the altitude vs. time graph.

4.3.3 The fourth data card contains SCALE. Use columns 1 through 10. Format F10.0. Due to the variation in altitude capabilities, provision has been made to scale the depth information. Any negative

altitude will be multiplied by SCALE. This will allow for easier interpretation of negative altitudes.

4.3.4 The fifth data card contains IP and IPP. Use columns 1 and 2 for IP and columns 5 through 10 for IPP. Format I2 and I6. IP is the period in seconds for calling TRAKGEN. All other executive routines are called at times based on this period. IPP is the number of seconds between points on the point plot. If IPP is zero, the point plot will not be plotted.

4.3.5 The sixth data card contains the number of preprogrammed tracks, NTRACKS. $0 \leq NTRACKS \leq 15$. Right justify in columns 1 and 2.

4.3.6 The seventh data card starts the initial position data. There must be one initial position data card for each preprogrammed track. The position data cards correspond to tracks numbered in consecutive increasing number with the last position being for track number 15. e.g., if three tracks are preprogrammed, the initial position cards are for tracks 13, 14, and 15 in that order.

- (1) X-position in miles in columns 1 through 10. X-position may have up to four decimal places. Maximum X is ± 279 miles.
- (2) Y-position in miles in columns 11 through 20. The same comments apply as for X-position.
- (3) Altitude in integer feet right justified in columns 25 through 30. Maximum altitude is ± 98689 feet.
- (4) Course in integer degrees right justified in columns 38 through 40.

- (5) Speed in integer knots right justified in columns 47 through 50. Maximum speed is 4095 knots. If a zero speed is assigned, a non-zero course must be given or the track will fail to start when ordered.

4.3.7 This data card begins the maneuver table. There must be one data card for each maneuver. The last card in the table must be a non-executable card with a zero in column ten. There is no limit to the length of the maneuver table data deck. Entries are:

- (1) Maneuver execution time in seconds right justified in columns 1 through 10. This time need not agree with a calling time since the maneuver will be executed as soon as real-time is equal to or greater than execution time.
- (2) Track number right justified in columns 19 and 20.
- (3) Maneuver code in column 30:
 - 1 Start track.
 - 2 Turn.
 - 3 Climb/dive.
 - 4 Change speed.
 - 5 Fade.
 - 6 Unfade.
 - 8 Scrub track.

The first code for any track must be a start track command.

- (4) Ordered course in integer degrees, ordered speed in integer knots, or ordered altitude in integer feet as appropriate. Right justify in columns 35 through 40.
- (5) Maneuver rate right justified in columns 43 through 50.

Insert turn rate in degrees per second with up to one decimal place.

$0.1 \leq \text{turn rate} \leq 25.5$.

Insert climb/dive rate in integer feet per minute. $43 \leq \text{climb rate} \leq$

65535. Insert acceleration rate in integer knots per second, maximum

255.

Any number of maneuvers can be scheduled for the same execution time. A track can be ordered to perform more than one maneuver at the same time by inserting each maneuver on succeeding cards, e.g.:

265	12	2	180	1.5
265	12	3	5000	1000

This orders track number 12 to start a climbing turn to 180 degrees at a 1.5 degree per second turn rate and to an altitude of 5000 feet at a climb rate of 1000 feet per minute starting at a time of 265 seconds.

4.4 DD 65 Operations.

4.4.1 Hardware. Before starting operations on the CDC 1604, the DD 65 must be ready in all respects to accept information from the CDC 1604.

The following check off list is provided to aid in setting up the DD 65.

1. Check for interrupt/sense relay in place.
2. Check for cables in place.
3. Check for memory switch in WHOLE position.
4. Check for mode switch in 1604 only position.
5. Check for Power ON.
6. If the CDC 160 output/input cables are connected, insure that the CDC 160 is on. If the CDC 160 is not on or is inoperative, disconnect cables.

4.4.1.1 Interrupt/sense Relay. Several years ago, because of some logic problems, a modification to the logic cabinet was undertaken. This modification consisted of putting in series with the interrupt lines a relay, that was actuated by the power supply. It was customarily removed when not needed. This year the sense lines were also run through this relay. With the advent of the routine of the sense lines through this relay, it is possible to leave the switch in the OFF position without loading down the sense lines of the 1604. For this reason, the relay may now be left in permanently. However, before running for the first time it will be wise to check this relay. It is located on the inside bottom of logic chassis 2.

4.4.1.2 Cable Connections. Fig. 15 shows the proper connections for the cables. These cables are located at the base of the logic cabinet just below logic chassis 2.

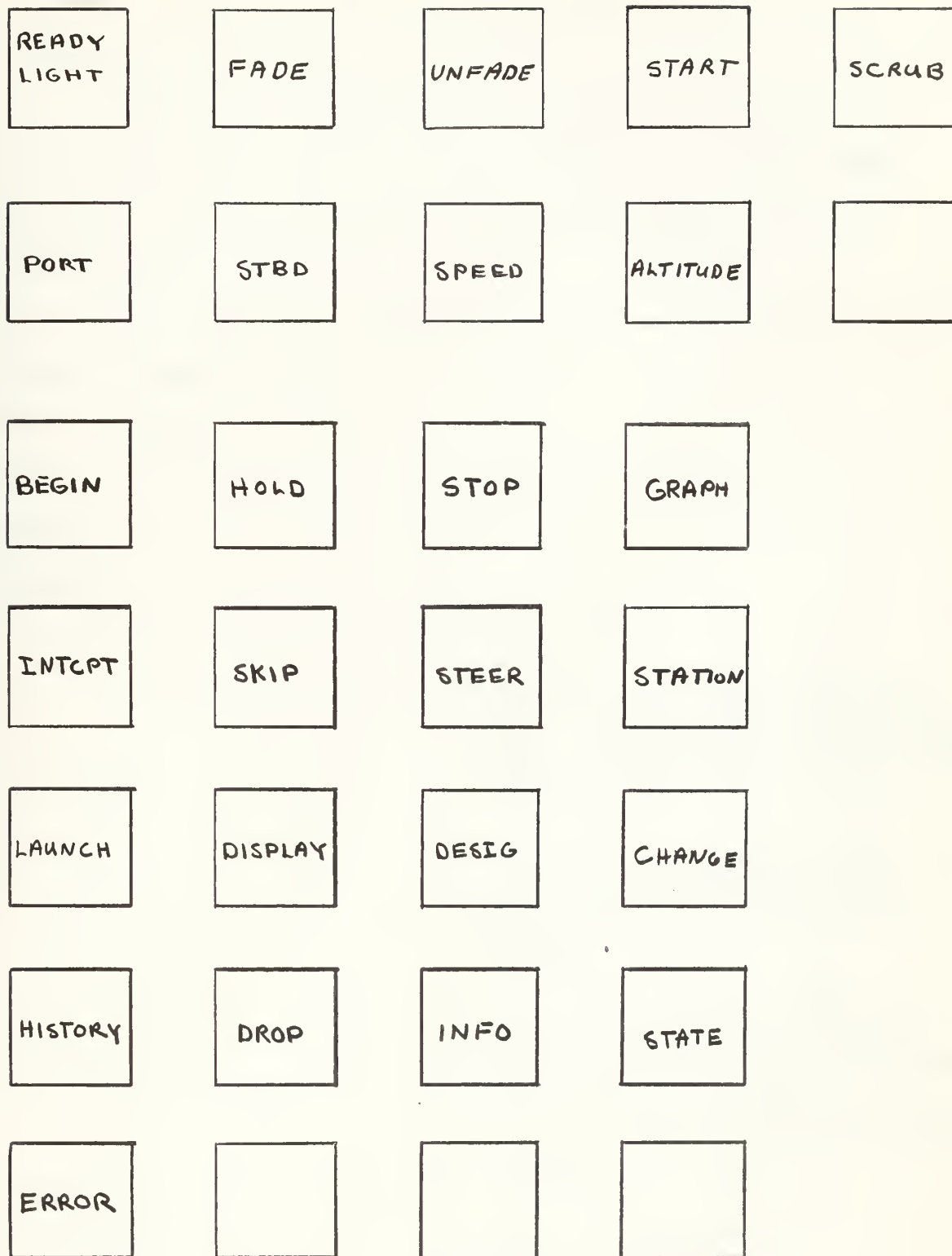


Figure 14. Keyboard 2 Functions

4.4.1.3 Memory Switch. A miniature toggle switch located on the inside edge of logic chassis 1 enables/disables the upper half of memory. Under normal use this switch is in the WHOLE or "down" position, to make maximum use of the memory.

4.4.1.4 Mode Switch. The Mode Switch is located on the front panel of the logic cabinet. This switch has three positions, "160", "Both", and "1604". The normal position for operation of SIMONE is in the "1604" position.

4.4.2 Console Operations. The following Sections deal with the callable routines available to the user.

4.4.2.1 CHANGE.

TASK

To maneuver one of the tracks,

EXAMPLE

CHANGE, N, M, L, R, X, Y, Z. \$

ARGUMENTS

7

N = Track number

M = Maneuver called--START, SCRUB, PORT, STBD, SPEED, ALTITUDE, FADE, OR UNFADE. If the Maneuver called is SCRUB, FADE, or UNFADE, then a period and \$ follow M.

L = Limit--initial course for START and desired course for PORT or STBD. This argument is desired speed for SPEED and desired altitude for ALTITUDE.

R = Rate--initial speed for START, ten times the rate of turn for PORT or STBD, rate of climb/dive for ALTITUDE, and acceleration/deceleration for SPEED. If omitted when interpreted as a rate, then standard rates will be assumed.

X = Initial X position for START only.

Y = Initial Y position for START only.

Z = Initial Z position for START only.

4.4.2.2 DESIG.

TASK

To designate a track.

EXAMPLE

DESIG,TYPE.\$

ARGUMENTS

2

TYPE = Type of target-- F will assign friendly symbol, H will assign hostile symbol, and if omitted, ownship symbol will be assigned.

HOOK = Target under hook will be assigned symbol designated by TYPE.

4.4.2.3 DISPLAY.

TASK

To change the tube on which raw radar data displayed.

EXAMPLE

DISPLAY.\$

ARGUMENTS

0

This routine will cause the raw data to be displayed on the opposite tube from which it is now displayed.

4.4.2.4 DROP.

TASK

To cause a history track to be erased.

EXAMPLE

DROP.\$

ARGUMENTS

1

HOOK = Target under hook will have its history track erased.

4.4.2.5 GRAPH.

TASK

To cause a graph to be plotted.

EXAMPLE

GRAPH.\$

ARGUMENTS

0

This routine will cause a graph to be plotted that will cover the period from the last regular plot to the present time. The next regular plot will cover the time from now till then.

4.4.2.6 HISTORY.

TASK

To cause history points to be displayed.

EXAMPLE

HISTORY,A,M.\$

ARGUMENTS

3

A = Number of points desired. This must be between 0 and 24. A number over 24 will be reduced to 24. If omitted, 12 points will be plotted.

M = Point mode indicator. If omitted, points will be plotted every period. M will cause points to be plotted every minute.

HOOK = Target under hook will have its history plotted.

4.4.2.7 HOLD.

TASK

To cause the problem to pause.

EXAMPLE

HOLD.\$

ARGUMENTS

0

This routine puts the program into a wait loop. This wait loop is terminated upon the second striking of the HOLD switch.

4.4.2.8 INFO.

TASK

To provide information on targets.

EXAMPLE

INFO.\$

ARGUMENTS

1

HOOK = Information about target under hook will be displayed. See Appendix I for format.

4.4.2.9 INTCPT.

TASK

To initiate an intercept.

EXAMPLE

INTCPT,C.\$

ARGUMENTS

2

C = CAP number of interceptor

HOOK = Target under hook will be intercepted
by CAP

4.4.2.10 LAUNCH.

TASK

To launch a CAP.

EXAMPLE

LAUNCH,C,R,B,T.\$

ARGUMENTS

4

C = CAP number of CAP to be launched

R = Range from the TASK FORCE center of
CAP station

B = Bearing from the TASK FORCE center of
CAP station

T = Type of CAP (2 through 7)

If arguments R and B are omitted,
Station will be assumed to be under
hook. If argument T is omitted,
type 7 interceptor is assumed. To
designate type and use hook for sta-
tion, zeros must be placed in R and B.

4.4.2.11 SKIP.

TASK

To cause an intercept to be skipped.

EXAMPLE

SKIP,C.\$

ARGUMENTS

1

C = CAP number of intercepting CAP

4.4.2.12 STATE.

TASK To display the State of the CAP.

EXAMPLE STATE,C.\$

ARGUMENTS 1

C = Cap number. State format in Appendix I.

4.4.2.13 STATION.

TASK To Station a CAP.

EXAMPLE STATION, C,R,B.\$

ARGUMENTS 3

C = CAP number

R = Range from TASK FORCE center of CAP station

B = Bearing from TASK FORCE center of CAP station

If R = 0, then station will be assumed to be under the hook.

4.4.2.14 STEER.

TASK To cause a CAP to be sent to TASK FORCE center.

EXAMPLE STEER,C.\$

ARGUMENTS 1

C = CAP number

4.4.2.15 STOP.

TASK To terminate the problem.

EXAMPLE STOP.\$

ARGUMENTS 0

4.4.2.16 BEGIN.

TASK

To start the problem.

EXAMPLE

BEGIN.\$

ARGUMENTS

0

This routine starts the problem and the number of tracks under user control is displayed on the DD 65.

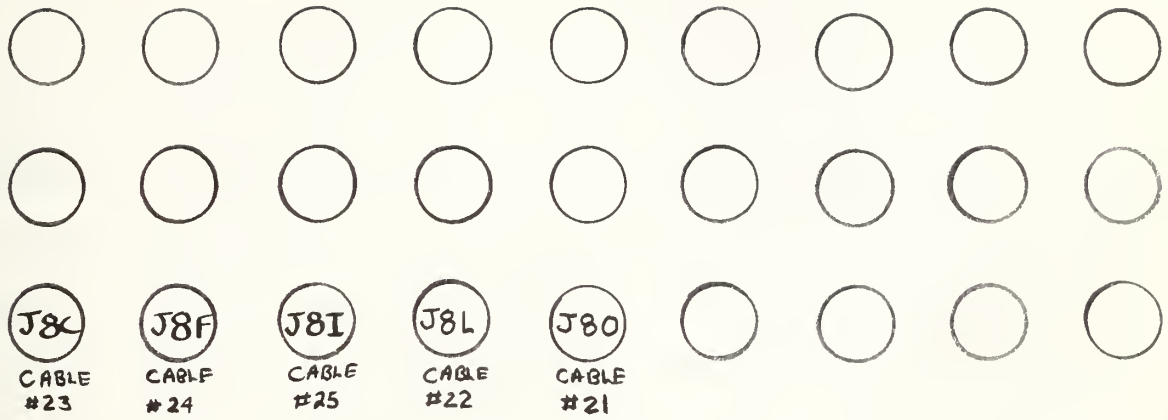


Figure 15. Cable Connections

5. Equipment and Logical Difficulties.

Some difficulties were encountered which were the result of both equipment logical shortcomings and equipment interaction.

5.1 DD 65 Display Console. Keyboard 1, the alphanumeric keyboard, when selected for input remains selected even after the input has been completed. If the keyboard were again selected for input, the processor is indefinitely delayed when the input is attempted. This limitation is the result of the cumbersome electromechanical keying system used, and has been previously avoided by selecting another display unit external function code. The deselect code previously used was SELECT RADAR TARGET DATA TO AUXILIARY EQUIPMENT. This code seemed to work well and was used to positively deselect both Keyboards 1 and 2.

It was also found that when one used the code SELECT RADAR RANGE SWITCH followed by SELECT TRACK BALL "X" that on some occasions the computer would be delayed indefinitely trying to input the X-coordinate. On the time the 1604 was not delayed, the next time an input from Keyboard 1 was attempted the code 760 was transferred to the computer. To correct for this the code for SELECT RADAR TARGET DATA TO AUXILIARY EQUIPMENT was used to deselect again. It appears that whenever an input code is selected it takes an output code to deselect the input code and vice versa. This points out the fact that there is no single code that deselects previously set selects.

5.2 CDC 1604. At this time there still remains an interaction between the 1604 and the DD 65 that has not been explained. Occasionally, during an update of the DD 65's memory or during an erasing of the DD 65's memory, the 1604 ends up with a 00007 in the upper address portion of

cell 00007. Since the upper instruction is an unconditional jump, the computer just sits there looping on the same cell. The logic prints show this to be impossible and the logic cards that actuate the interrupt lockout have been changed to no avail. At this time there is no answer.

6. Conclusions and Acknowledgments.

6.1 **Conclusions.** A general purpose track generator has been implemented based on the following concepts:

- (1) Suitable for on-line simulation as well as system analysis studies.
- (2) Applicable to both anti-air and anti-submarine warfare operations.
- (3) Provision for operator interaction made available for exercising "console control" in gaming situations.

The tracking package provided is intended to be used as a basic tool in:

- (1) Computer simulation analysis of weapons systems performance, e.g., interceptor-missile mission.
- (2) Illustration and evaluation of combat direction system functions, e.g., NTDS, ATDS.
- (3) Any system studies requiring complex track motion data on multiple targets, e.g., track-while-scan radar system performance.

The following major routines have been fully checked out under operating conditions:

- (1) Subroutine TRAKGEN (Track Generator).
- (2) Executive Control Routine.
- (3) Display Subprogram.
- (4) Radar Processor Subprogram.
- (5) Keyboard Command Routine (Program Control Routine).
- (6) Graph Output Routine.
- (7) All keyboard callable routines except the HISTORY Routine.

In addition, an Aircraft Control Subprogram has been incorporated into the program listing. While reasonably close to final form, it has not yet been successfully tested with the system.

In the course of the work several interface problems on the 1604 - DD 65 channel 7 hookup were brought to light and corrected.

These problems were:

- (1) The DD 65, when turned off, loading the sense lines of the CDC 1604.
- (2) The CDC 1604 being unable to input information from the track ball without first positively deselecting any previous input selection made by the CDC 1604.
- (3) Incorrect cable listings in [10] for channel 7 hookup.

In addition, the following engineering difficulties have appeared but have not been corrected:

- (1) An apparent random failure of the interrupt lockout feature of the CDC 1604 resulting in the computer remaining in a loop executing the instruction "SLJ (7)" while PAR equals 00007.
- (2) Apparent incomplete decoding of certain external function codes or "leaking" of other signals into the external function lines of the DD 65 resulting in random selects of the computer controlled light indicators.
- (3) Sensitivity of data transfer to timing adjustments in the CDC 1607 tape units resulting in parity errors if they are out of tolerance (Not corrected, but bypassed by use of memory as a scratch pad).

Upon analysis of the data obtained over the past five months, the duty cycle has been calculated to range from 0.18 to 0.26. The smaller duty cycle occurred during a 15 track problem. These figures were a result of the duty cycle routine embedded in the program. They closely correlate with theoretical data. The duty cycle indicates that the only constraint on expanding the program is that of computer memory size.

6.2 Acknowledgments. The authors wish to express their appreciation to Professor Mitchell L. Cotton for his aid and encouragement in the preparation of this thesis. In addition, the authors would like to thank Major Thomas Kauffman, USMC for his liason with Litton Systems, Inc., Data Systems Division who provided us with much information concerning simulation and smoothing systems; Lieutenant Commander J. V. Reynolds, USN, Fleet Computer Programming Center Pacific, who provided us with data concerning the Naval Tactical Data System and their approach to the simulation problem; Mr. Leon Spors and Mr. John Plesac of Control Data Corporation for their assistance in studying the interface problem; and Mr. Walter Landaker for his excellent maintenance of the DD 65.

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APPENDIX I - A

1. Identification.

Title: SIMONE

Category: Control Routine

Programmer: E. L. Borden

Organization: U. S. Naval Postgraduate School

Date: April 1965

2. Purpose.

This control routine provides a means to control a simulated tactical data system from the DD 65.

3. Executive Called Subprograms.

3.1 1F-Display Subprogram. This program calls PRINT and causes both raw and smoothed data to be displayed on the DD 65.

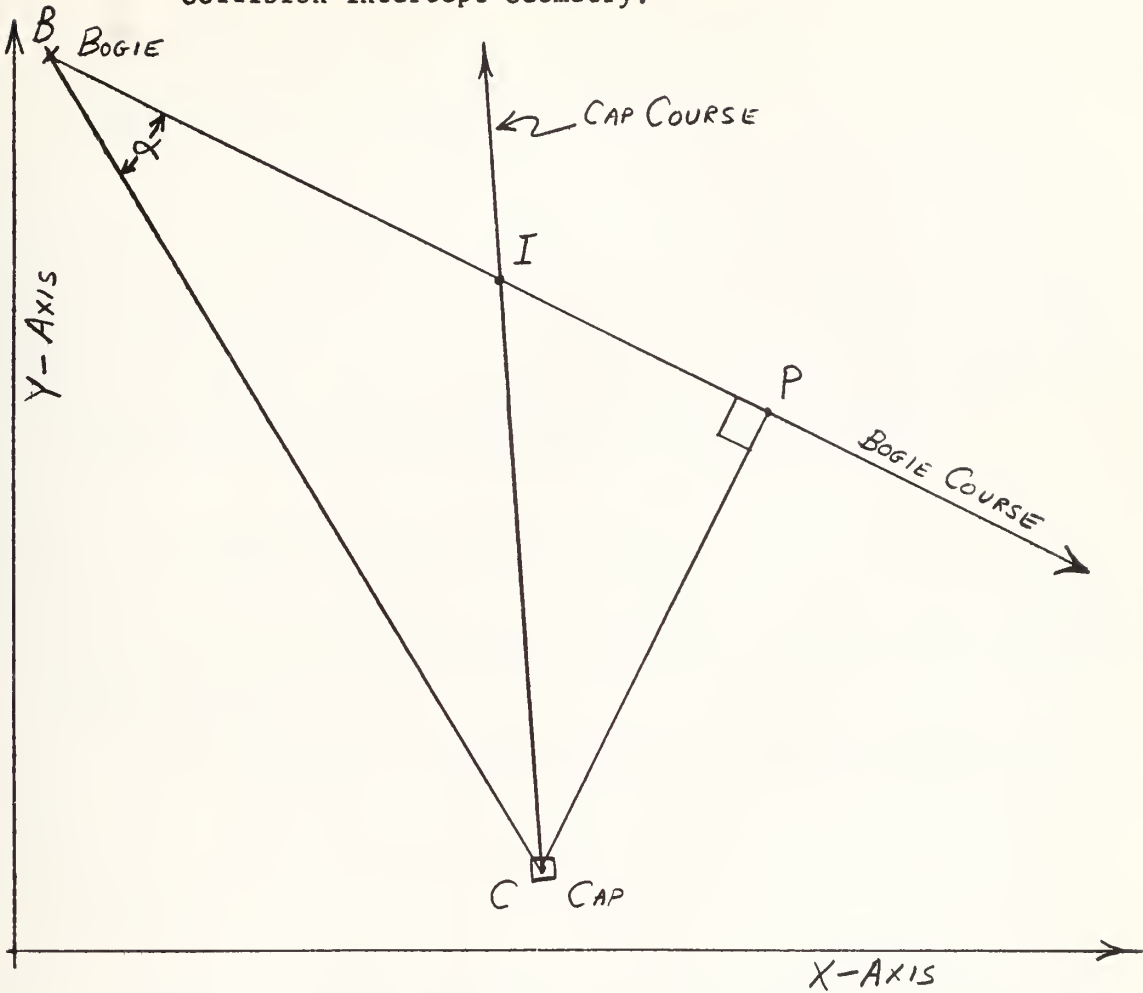
3.2 1G-Radar Processor. This subprogram uses the basic "alpha-beta" smoothing equations to process the radar data. The equations can be found in [1].

3.3 1GR-10 Minute Graph Subprogram. This program reads from the memory scratch pad and processes the data for calling DRAW to output the permanent graph record.

3.4 1INT-Aircraft Control Subprogram. This program performs the bookkeeping on fuel and ammunition loading for friendly aircraft and allows for control of these aircraft by the data process section. See Fig. I-1 for the collision intercept geometry.

APPENDIX I

Collision Intercept Geometry.



Alfa = Absolute value of Bogie Course minus Cap Bearing from bogie.

I = Point of intercept.

CP = N (Perpendicular distance from Cap to Bogie track).

BP = M (Distance from Bogie to point P).

V_b = Velocity of Bogie.

V_c = Velocity of Cap.

Figure I-1

APPENDIX I

In order for the Cap to intercept the Bogie at point I, the following equations must be true:

$$BI = V_b t \quad \& \quad CI = V_c t$$

We assume the following equation to be true. If it is not the case, BI will be negative and a collision intercept will be impossible since the intercept will take place somewhere to the right of P.

$$(CI)^2 = (M - BI)^2 + N^2$$

Solving the above equation simultaneously we end up with a quadratic equation in BI.

$$(V_c - V_b)^2 \cdot (BI)^2 + (2MV_b^2) \cdot (BI) - V_b^2(M^2 + N^2) = 0$$

Solution:

$$(BI)^2 + \frac{2MV_b^2}{(V_c^2 - V_b^2)^2} \cdot (BI) - \frac{V_b^2}{(V_c^2 - V_b^2)^2} \cdot (M^2 + N^2) = 0$$

$$BI = \frac{V_b^2 M}{(V_c^2 - V_b^2)} \cdot \left[-1 \pm \sqrt{1 + \left(1 + \left[\frac{N}{M}\right]^2\right) \left(\left[\frac{V_c}{V_b}\right]^2 - 1\right)} \right]$$

This is the basic equation that must be solved in order to determine if an intercept can be made. If two positive values of BI exist, the smaller of the two will be the shortest intercept.

APPENDIX I

3.5 1K-Keyboard Command Subprogram. This program sets the range scale factor and positions the hook on the right hand tube of the DD 65. This routine also checks to see if there are any commands from the DD 65 to be executed. If there are commands to be executed then control is passed to the 1P-Program Control Routine.

3.6 1TG-Track Generator Calling Subprogram. This program calls TRAKGEN, unscales and unpacks the X, Y, and Z positions and records these values on the memory scratch pad for future graphs.

4. DD 65 Called Routines.

4.1 1C-Change Routine. This is a seven argument routine, which is used to control tracks.

4.1.1 Arguments.

1A	Track Number
2A	Maneuver Called
3A	Variable Argument (Limit)
4A	Variable Argument (Rate)
5A	X Position
6A	Y Position
7A	Z Position

The variable arguments are interpreted according to the maneuver called. The interpretations are:

Maneuver	3A	4A
START	Course Desired	Speed Desired
SCRUB	Ignored	Ignored
PORT	Course Desired	10 x Turn Rate
STBD	Course Desired	10 x Turn Rate
SPEED	Speed Desired	Acceleration
ALTITUDE	Altitude Desired	Dive/Climb Rate
FADE	Ignored	Ignored
UNFADE	Ignored	Ignored

APPENDIX I

Arguments 5A, 6A, and 7A are used only when the maneuver START is called, at all other times they are ignored.

When the argument is a rate (4A with PORT, STBD, SPEED, and ALTITUDE), omitting the argument will cause standard rates to be entered. These rates are:

PORT	1.5 Degrees per second
STBD	1.5 Degrees per second
SPEED	10 knots per second
ALTITUDE	5000 feet per minute

4.2 1D-Display Routine. This is a zero argument routine that complements the D-Flag. The Display Subprogram uses the D-Flag to determine on which tube the raw data is to be displayed. A negative D-Flag will cause the raw data to be displayed on the right hand tube while a positive D-Flag will display the data on the left hand tube.

4.3 1J-Designate Target Routine. This routine is a two argument routine that calls the 3J0 routine to determine the second argument. The target under the hook will be designated according to the following:

Argument	Designation
0(zero)	Own Ship
H	Hostile Track
F	Friendly Track

When a track is designated friendly and it is an aircraft, its interceptor type is determined by the condition of the least significant bit in cell 50 (Job time clock). A 0 assigns a type 7 and a 1 assigns a type 3.

APPENDIX I

4.4 1L-History Routine. This routine is a three argument routine. The first argument is the number of points desired. This argument may be any number between 1 and 24. Any number greater than 24 will be reduced to 24. If the argument is omitted, then 12 points will be plotted. If the second argument is anything other than zero, then the first argument will be interpreted as the number of minutes of past history with one point for each minute. The third argument, the track number, is filled by the Hook Routine. Up to two tracks may have past history plotted. If a third track is requested, the first track will be dropped.

4.5 1PQ-Hold Routine. This is a zero argument routine that places the program in a wait loop. The second hitting of the hold switch will resume the program.

4.6 1Q-Intercept Command Routine. This is a two argument routine that calls the Hook Routine to fill the second argument, the BOGEY track number. The first argument is the CAP number of the interceptor. This routine sets the necessary flags which signal the Aircraft Control Subprogram to initiate an intercept.

4.7 1R-Drop History Routine. This is a one argument routine that has its argument, the track number, filled by the Hook Routine. The history being displayed on the hooked track will be dropped upon execution of this routine.

APPENDIX I

4.8 1S-Stop and Critique Routine. This is a zero argument routine that causes the problem to be terminated and the final graph to be plotted.

4.9 1ST-State Routine. This is a one argument routine which causes one of the following messages to be displayed on the DD 65 depending upon the actual state of the interceptor.

STATE REPORT ON CAP xx

PLUS
AMMO MINUS / OXYGEN PLUS / FUEL xxxx POUNDS / TIME xxxz.
ZERO

TYPE x

4.10 1TT-Information Routine. This is a one argument routine that has its argument filled by the Hook Routine. The following are examples of the types of information messages that appear:

INFORMATION
TRACK NR 14
BOGEY E3
COURSE 350, SPEED 450, ALTITUDE 35000.
RANGE: 120 MILES.
BEARING: 80 DEGREES.
FROM TASK FORCE CENTER

INFORMATION
TRACK NR 13
SKUNK D
COURSE 35, SPEED 13.
RANGE: 12000 YARDS.
BEARING 270 DEGREES.
FROM OWN SHIP

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INFORMATION

TRACK NR 3
GOBLIN E
COURSE 270, SPEED 4, DEPTH 200.
RANGE: 3000 YARDS.
BEARING: 5 Degrees
FROM OWN SHIP

Speeds are in knots and depth is in feet.

4.11 1U-Steer Command Routine. This is a one argument routine which sets the necessary flags which signal the Aircraft Control Subprogram to steer the CAP specified by the argument.

4.12 1V-Station Command Routine. This is a three argument routine. The arguments are:

1A	CAP number
2A	Range of Station from TF Center
3A	Bearing of Station from TF Center

If argument 2A is zero or omitted, then the station will be assumed to be under the hook. This routine sets the necessary flags which signal the Aircraft Control Subprogram to station the CAP.

4.13 1W-Skip Command Routine. This is a one argument routine that sets the necessary flags which signal the Aircraft Control Subprogram to cause the CAP listed in the argument to disengage and return to station.

4.14 1X-Launch CAP Command Routine. This is a four argument routine. The arguments are:

1A	CAP number
2A	Range of Station from TF Center
3A	Bearing of Station from TF Center
4A	Type of interceptor

APPENDIX I

If argument 2A is zero or omitted, then the hook is assumed to be over the station. This routine sets the necessary flags which signal the Aircraft Control Subprogram to launch a CAP and send him to the designated station.

4.15 1Z-Begin Routine. This is a zero argument routine that starts the program and calls TRAKGEN with time equal to zero. This routine also causes the number of tracks under Keyboard control to be displayed on the DD 65. The format of the message is:

07 TRACKS UNDER YOUR CONTROL.

5. Control Routines.

5.1 1T Executive Control Routine. This routine follows the basic philosophy of the executive control routine described in Section 2.2.1.1 of the main body and in [14] .

5.2 1P-Program Control Routine. This routine functions as the basic operator-computer communications link, decodes control statements, packs arguments for routines; then passes control to the routine designated.

6. Miscellaneous Routines.

6.1 3JO-Hook Routine. This routine is used by many other routines and cannot be called separately. It hooks any track within the range acquisition gate. The range acquisition gate is variable and changes depending upon the range scale setting. The gate sizes are:

APPENDIX I

Range Scale (miles)	Gate
256	8.0 x 8.0
128	4.0 x 4.0
64	2.0 x 2.0
32	1.0 x 1.0
16	.5 x .5
8	.25 x .25
4	.125 x .125

There is no acquisition gate for altitude. If two or more targets are within the X and Y gates but at different altitudes, the target with the lowest track number will be hooked. If there is no target within the gate, the error message "TRACK NOT HOOKED" will be displayed and control will return to the Executive Control Routine.

6.2 1Y-Find CAP Number Routine. This routine is used in conjunction with any routine that uses CAP number instead of track number as an argument. This routine searches the TRACK array to determine the track number of the CAP. If the result of the search is negative, the message "CAP xx NOT AIRBORNE" is displayed on the DD 65.

6.3 1ZZ-CAP Number and Station Routine. This routine calls the CAP Number Routine to determine track number and then computes the X and Y coordinates of the designated station.

7. Error Stops.

An incorrect number of tracks, i.e. number greater than 15, on the sixth data card will cause the program to execute a selective stop. The following error message will be displayed.

NTRACKS \geq 16 CHECK DATA DECK AND TRY AGAIN

APPENDIX I

The program may be started again after correcting the data deck by hitting RUN on the CDC 1604.

8. Error Messages.

Message	Meaning
PROGRAM NOT CALLED	The program called was not listed in the Program Name Table.
TOO MANY ARGUMENTS	Too many arguments were listed for the program called or an unauthorized argument was used (i.e. ≥, :, A, etc.)
2ND ARGUMENT ILLEGAL	An illegal maneuver was called for or the argument for the Desig Routine was not on H, P, or O (zero).
TARGET NOT HOOKED	No target was within the range acquisition gate.
NTRACKS ≥ 16 CHECK DATA DECK AND TRY AGAIN	

See 7.

9. Information Messages from Aircraft Control Subprogram.

Message	Meaning
CAP xx UNABLE TO INTERCEPT - FUEL	CAP does not have enough fuel to reach the intercept point
CAP xx UNABLE TO INTERCEPT - AMMO	CAP does not have any ammunition left aboard
CAP xx LOW STATE	CAP has just enough fuel to return to carrier
CAP xx MAYDAY...MAYDAY...	CAP out of fuel, Ditching
CAP xx INTERCEPTING - UNABLE TO RETURN	CAP does not have sufficient fuel to return to the carrier after making an intercept

APPENDIX I

CAP xx FAMISHED

CAP has no station assigned

CAP xx POOR INTERCEPT

CAP unable to make collision
intercept and is in a pursuit
intercept

SPLASH BOGEY Exx

CAP destroyed BOGEY Exx

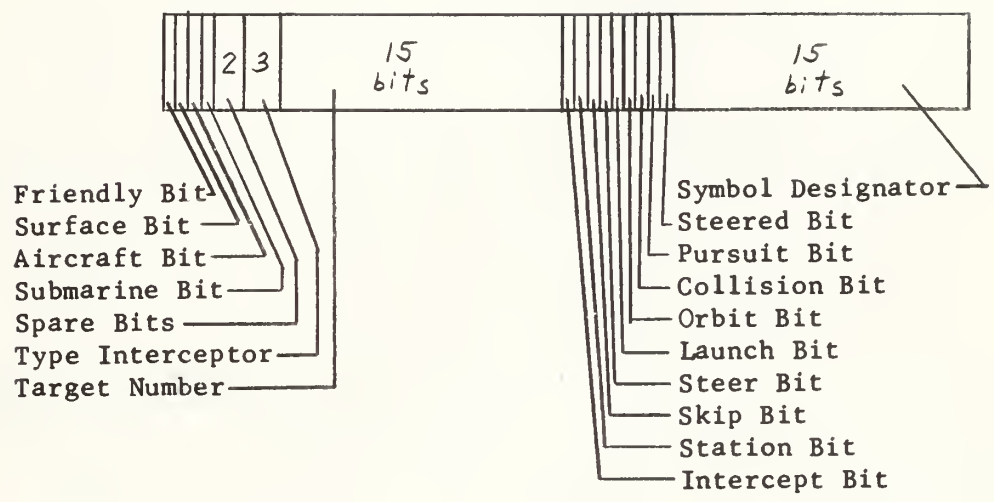
HEADS UP BOGEY Exx

CAP unable to destroy BOGEY
Exx

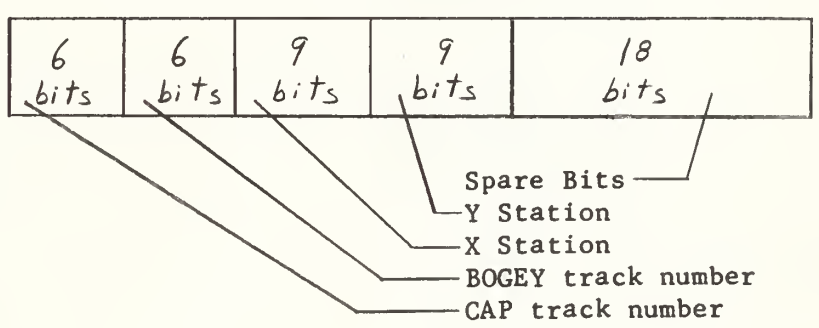
APPENDIX I

10. Array Formats.

10.1 TRACK Array.

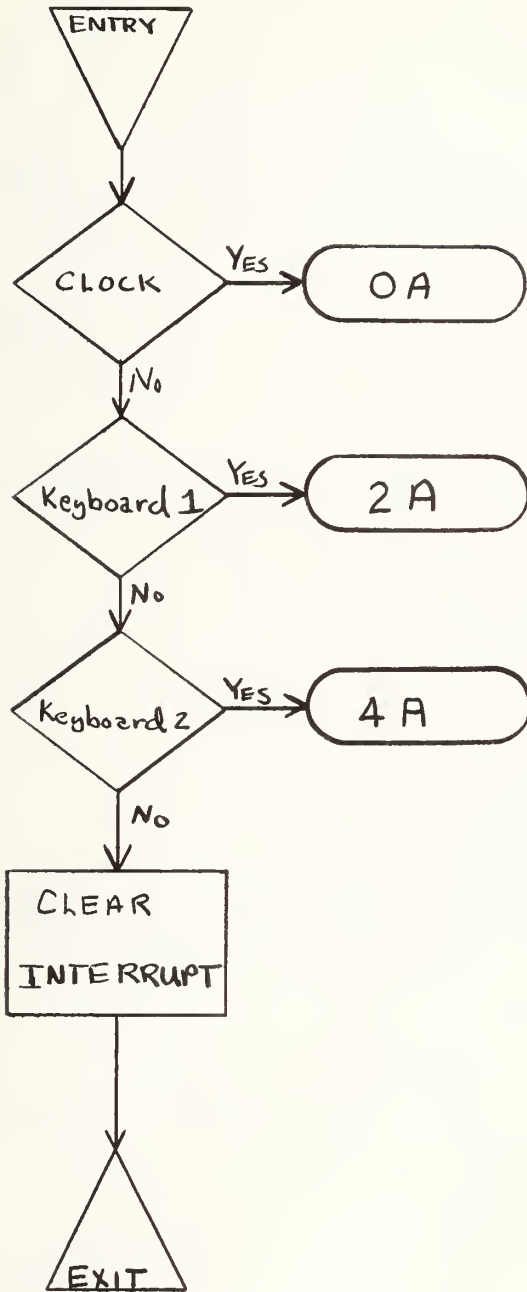


10.2 TRACK1 Array.



Interrupt Routine

Interrupt Processor



Clock Processor

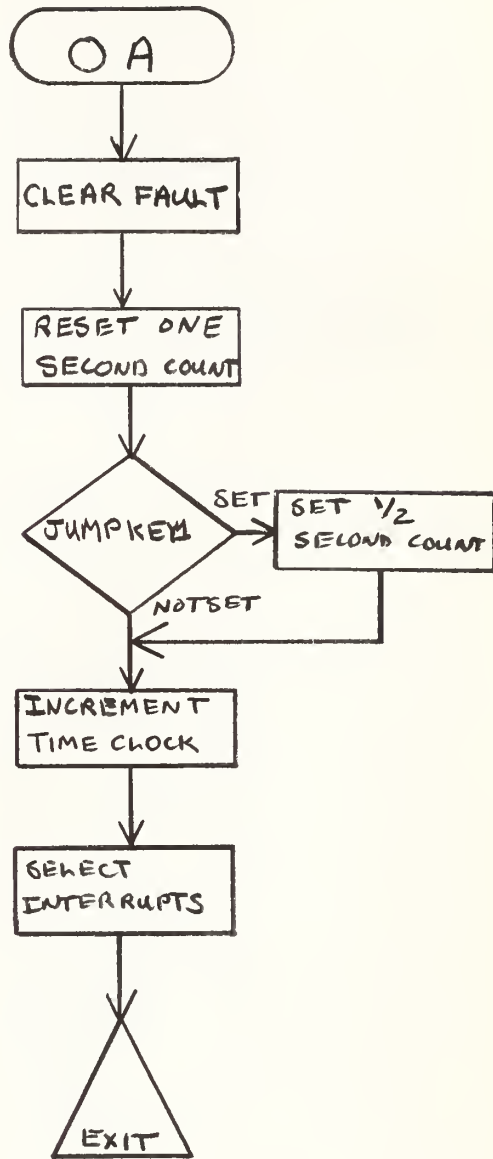
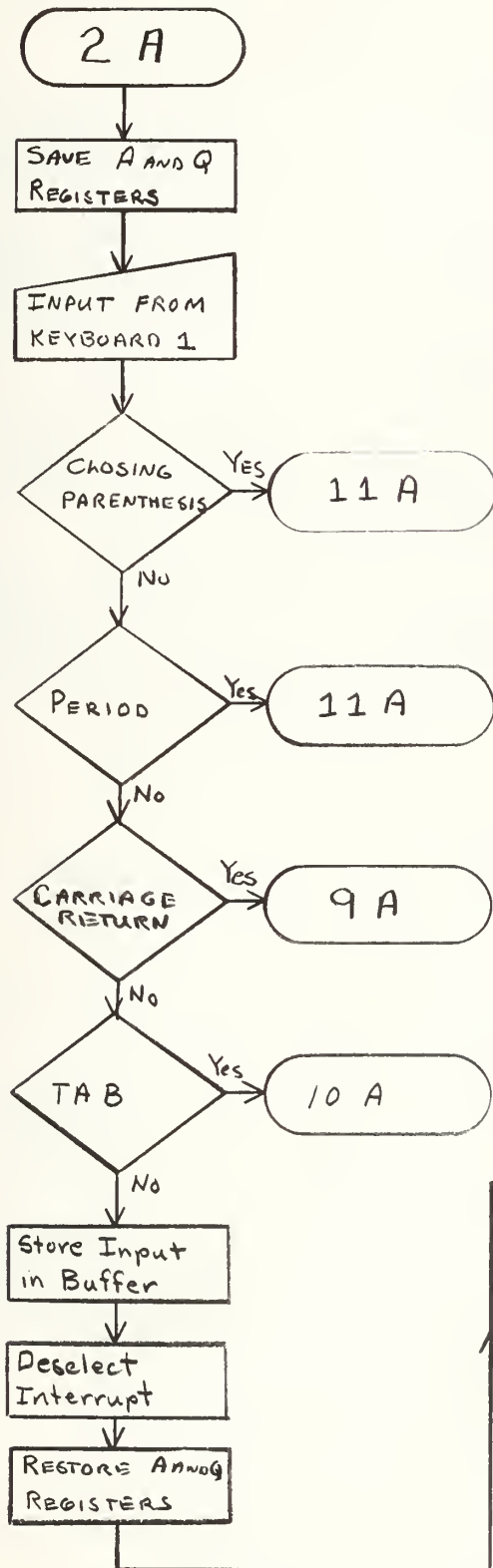


Figure I-2

Keyboard 1 Processor



Keyboard 2 Processor

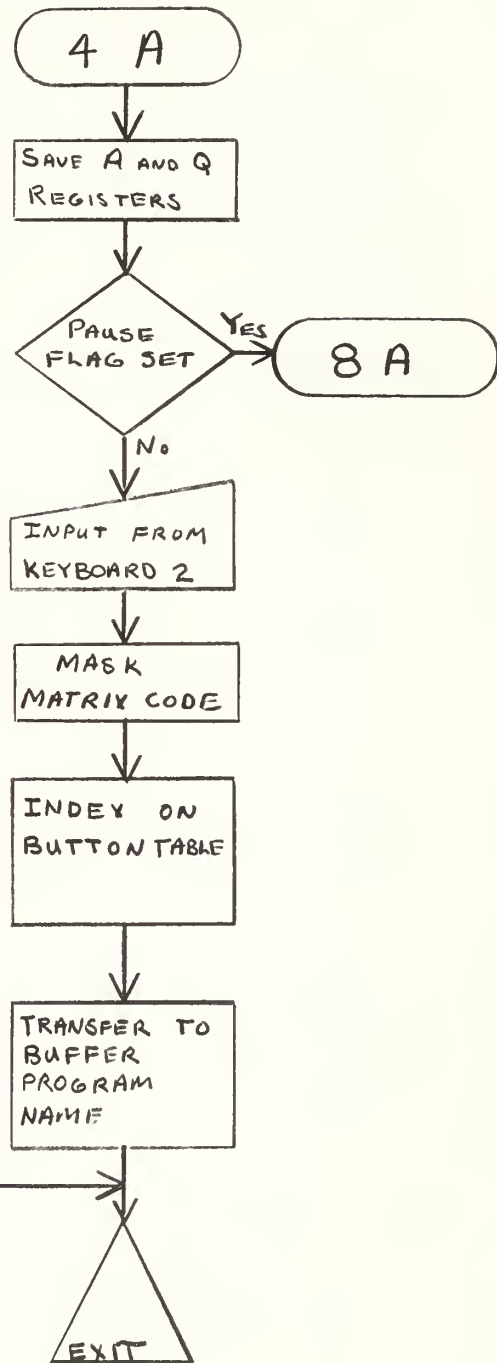
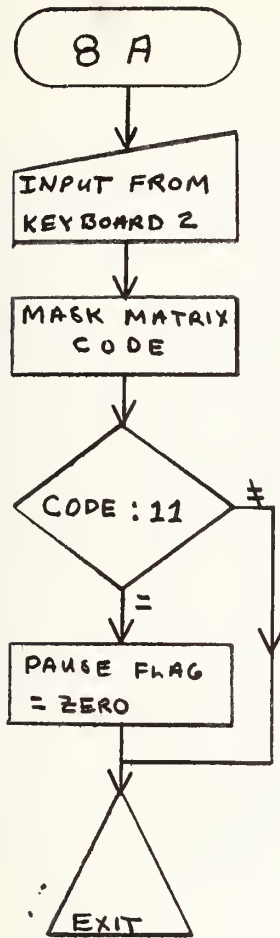
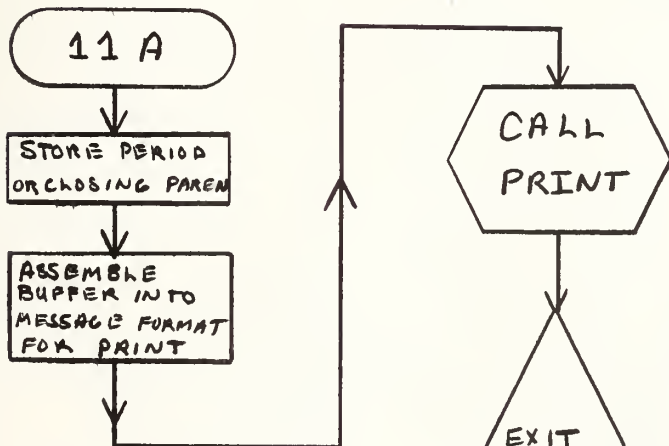


Figure I-3

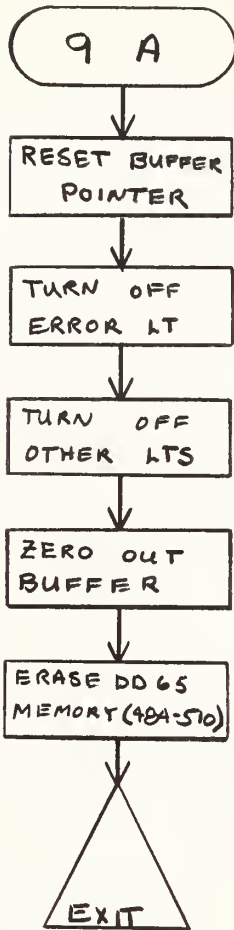
Pause Check Routine



Print



Erase on CR



Erase on TAB

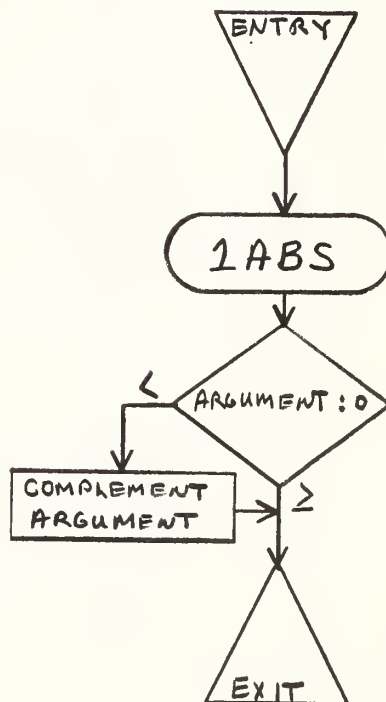
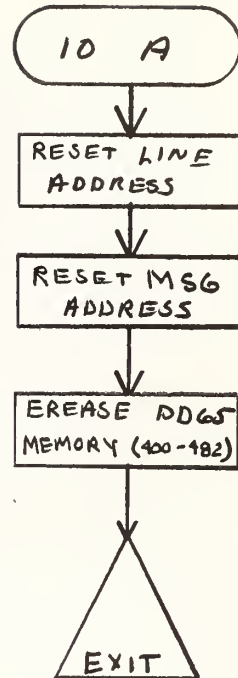


Figure I-4

Change Routine

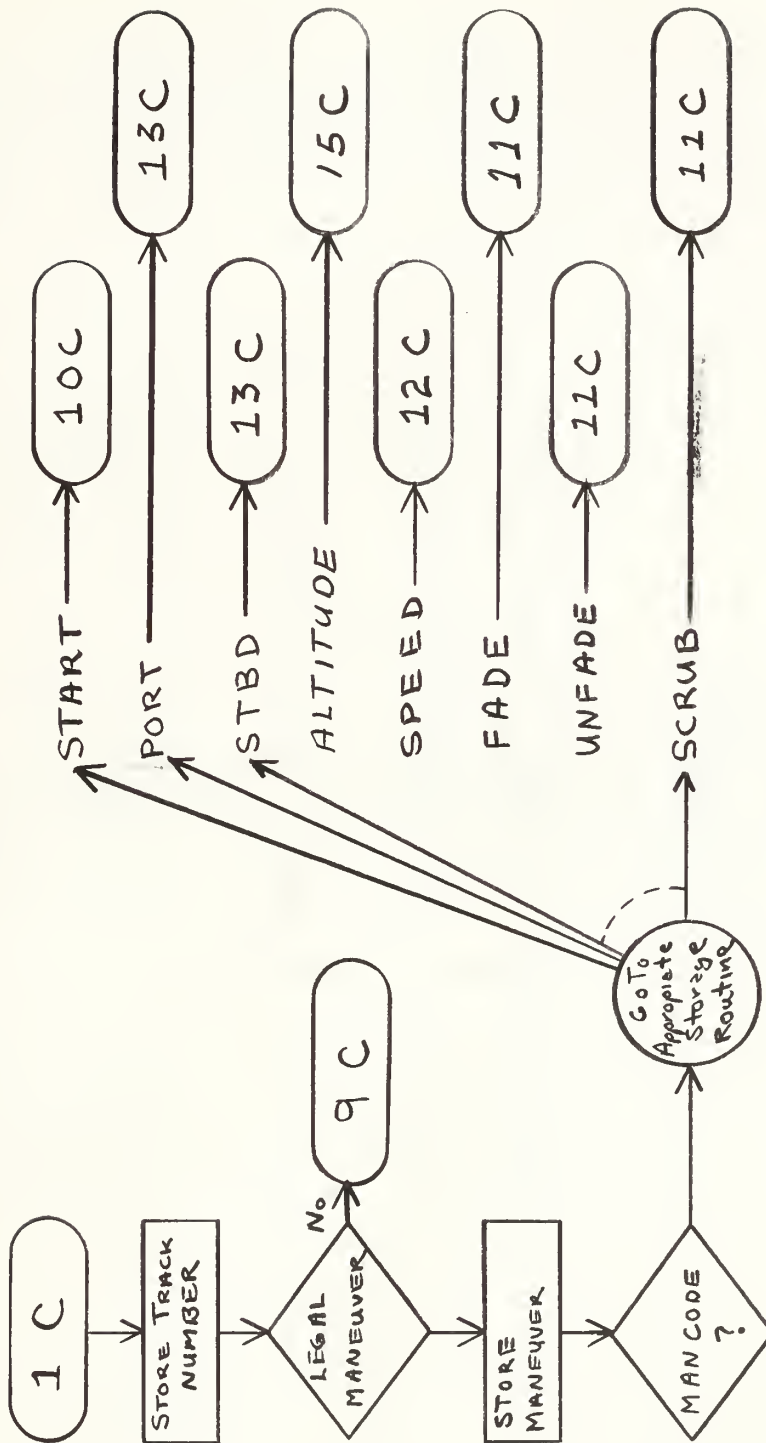


Figure I-5

Storage Routines

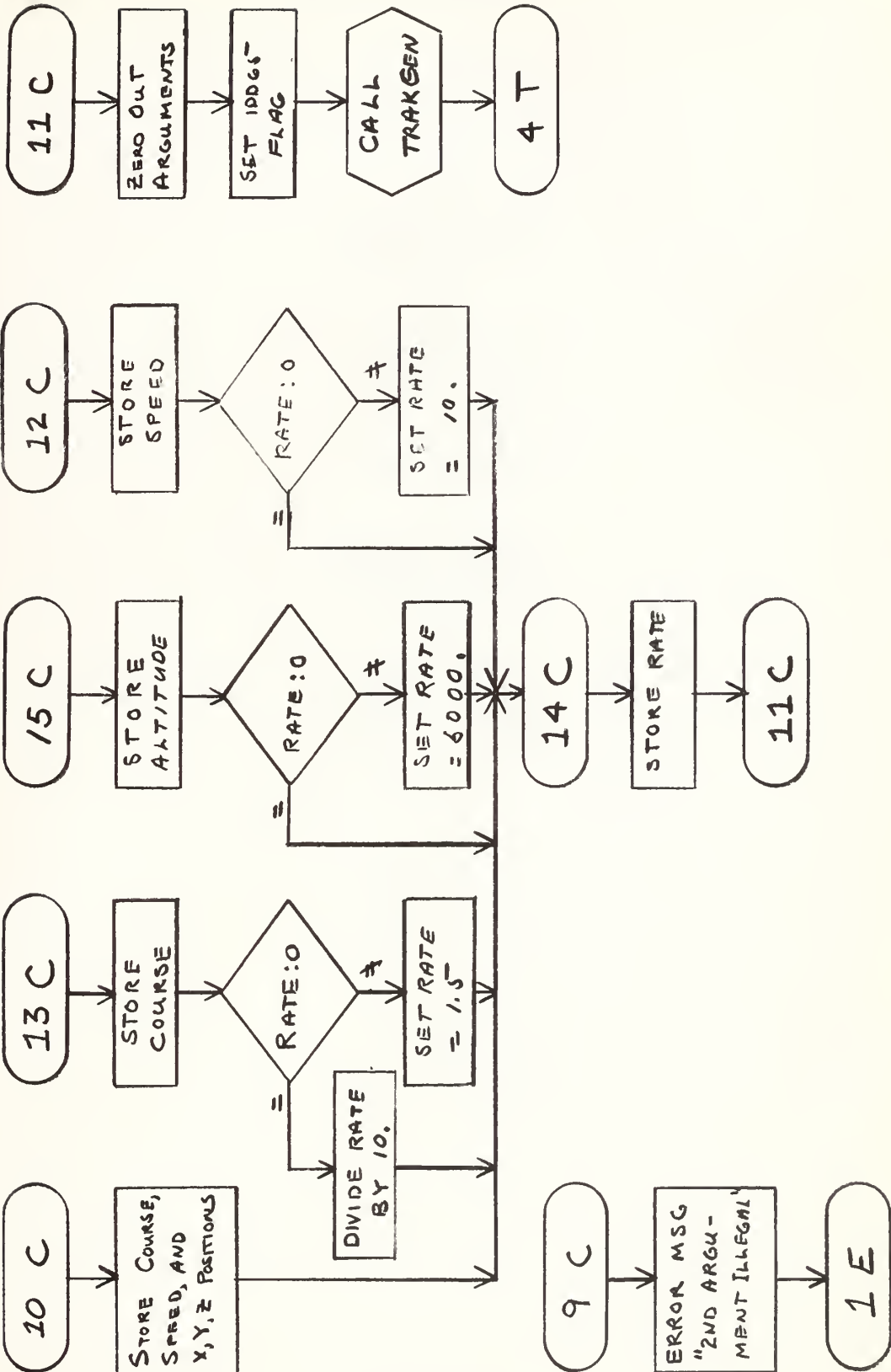


Figure I-6

Error Message Routine

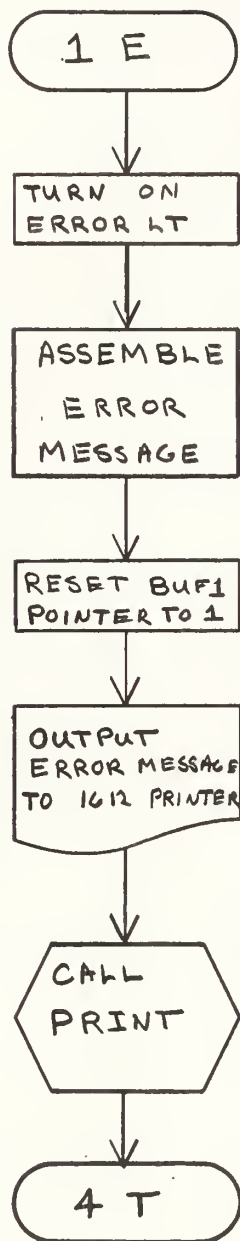


Figure I-7

Display Subprogram

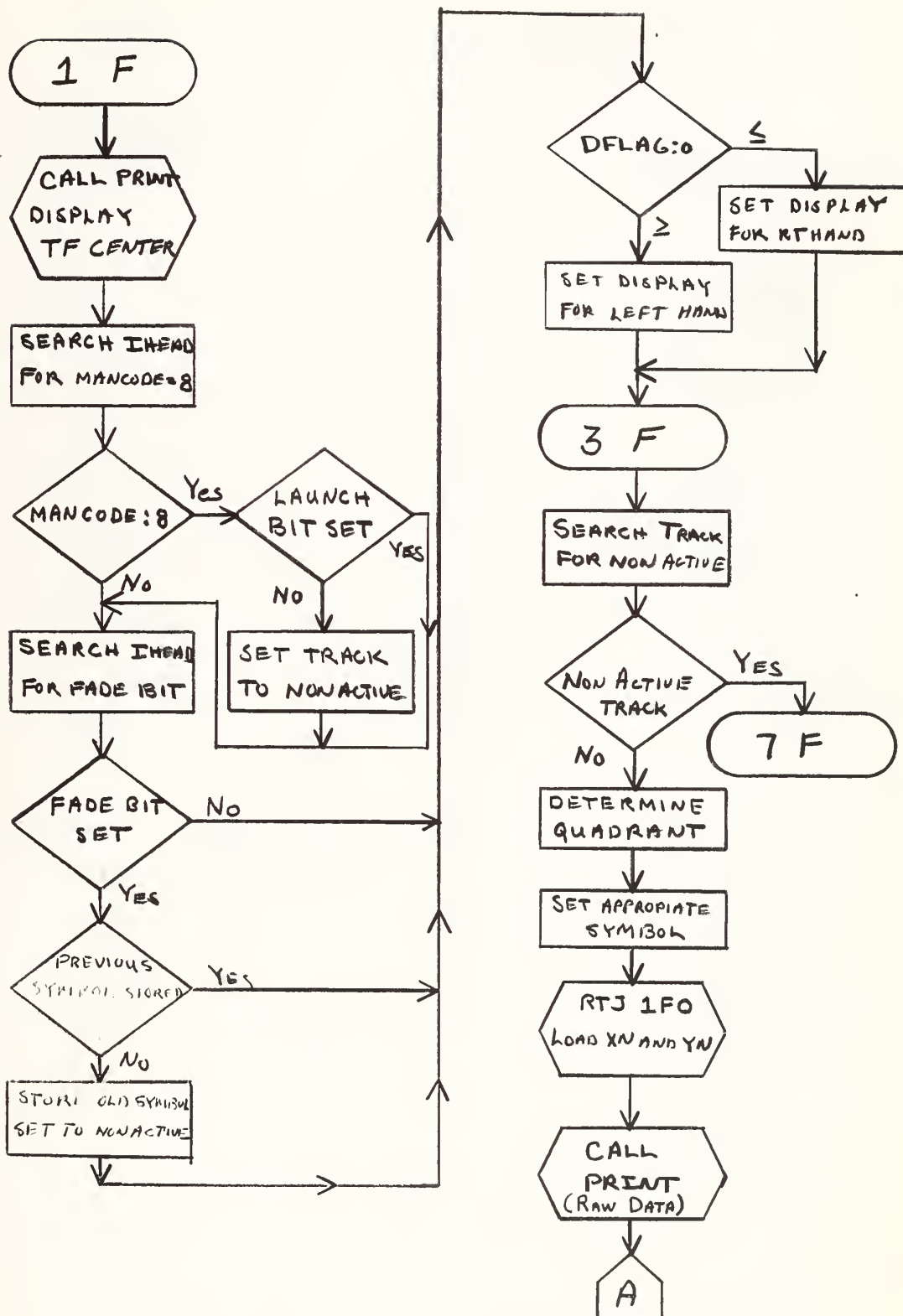


Figure I-8

Display Subprogram (cont)

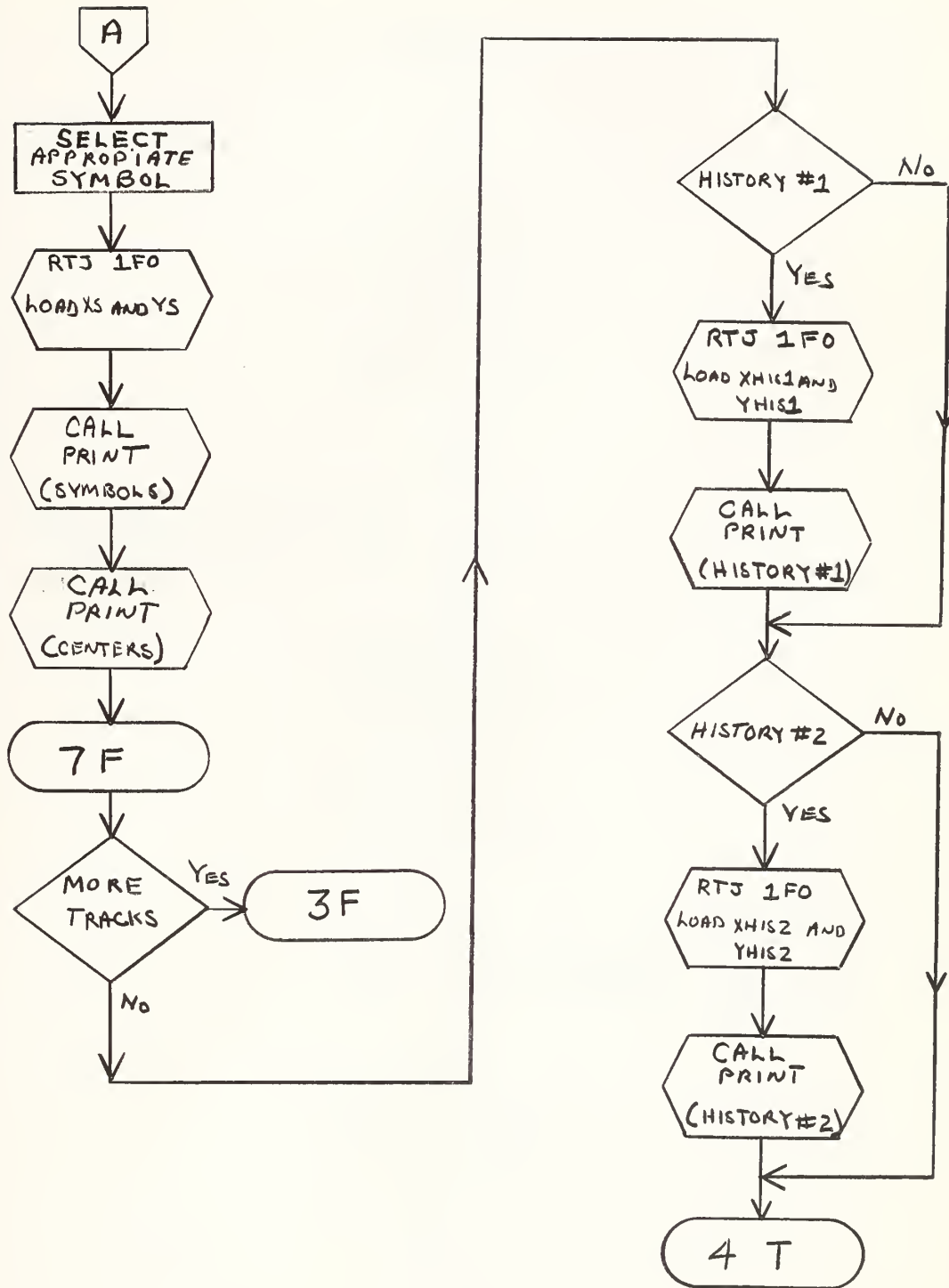


Figure I-9

Load X and Y Routine

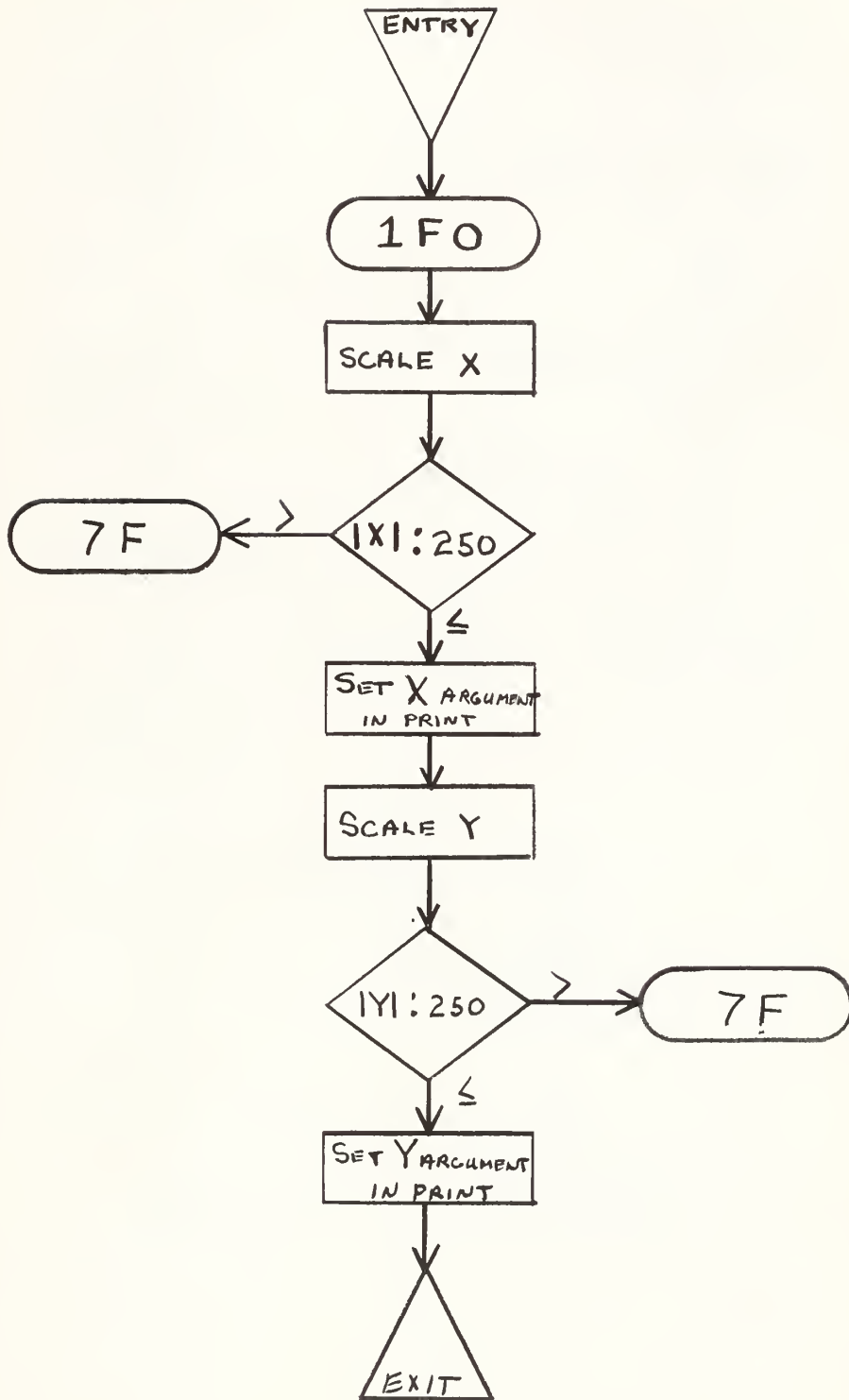


Figure I-10

Radar Processor Subprogram

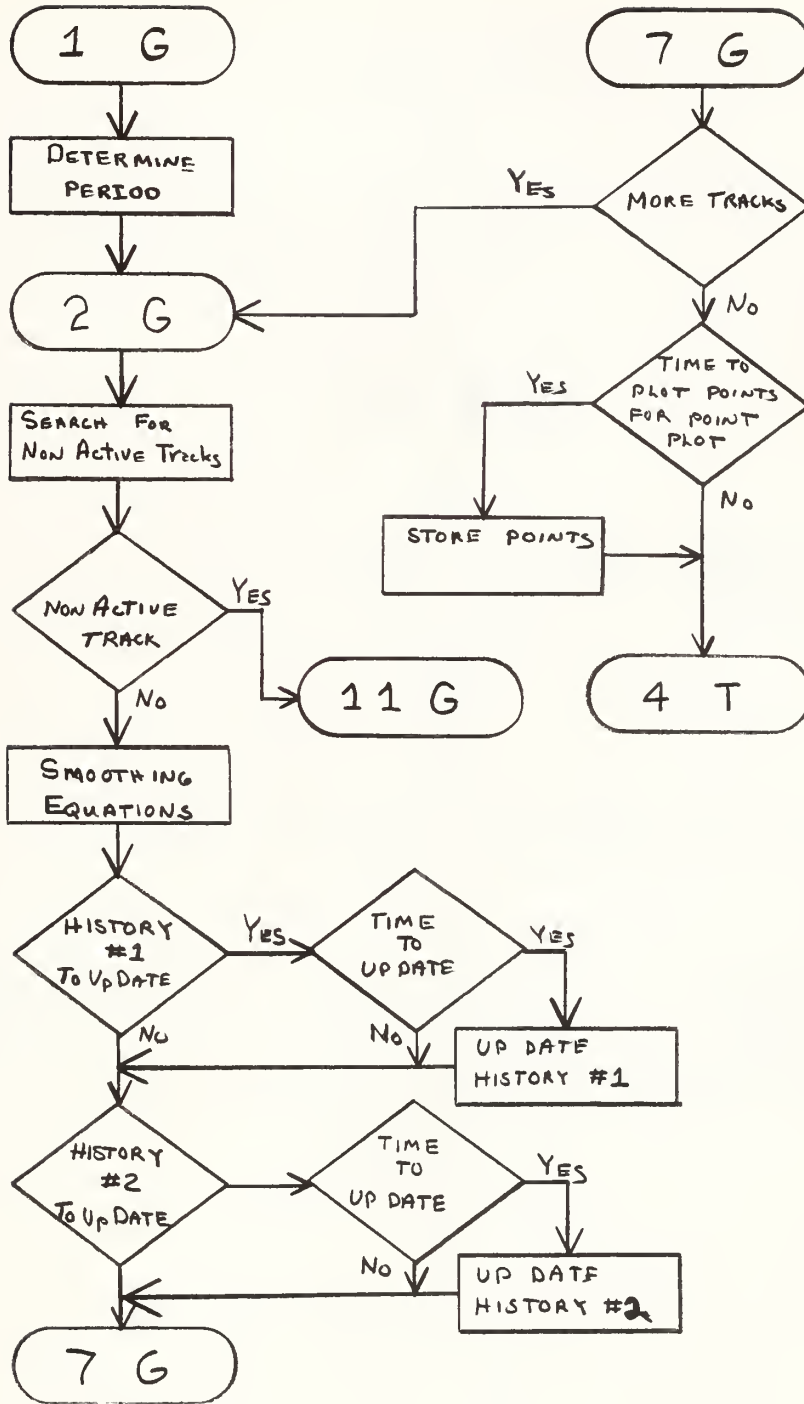


Figure I-11

Radar Processor Subprogram (cont)

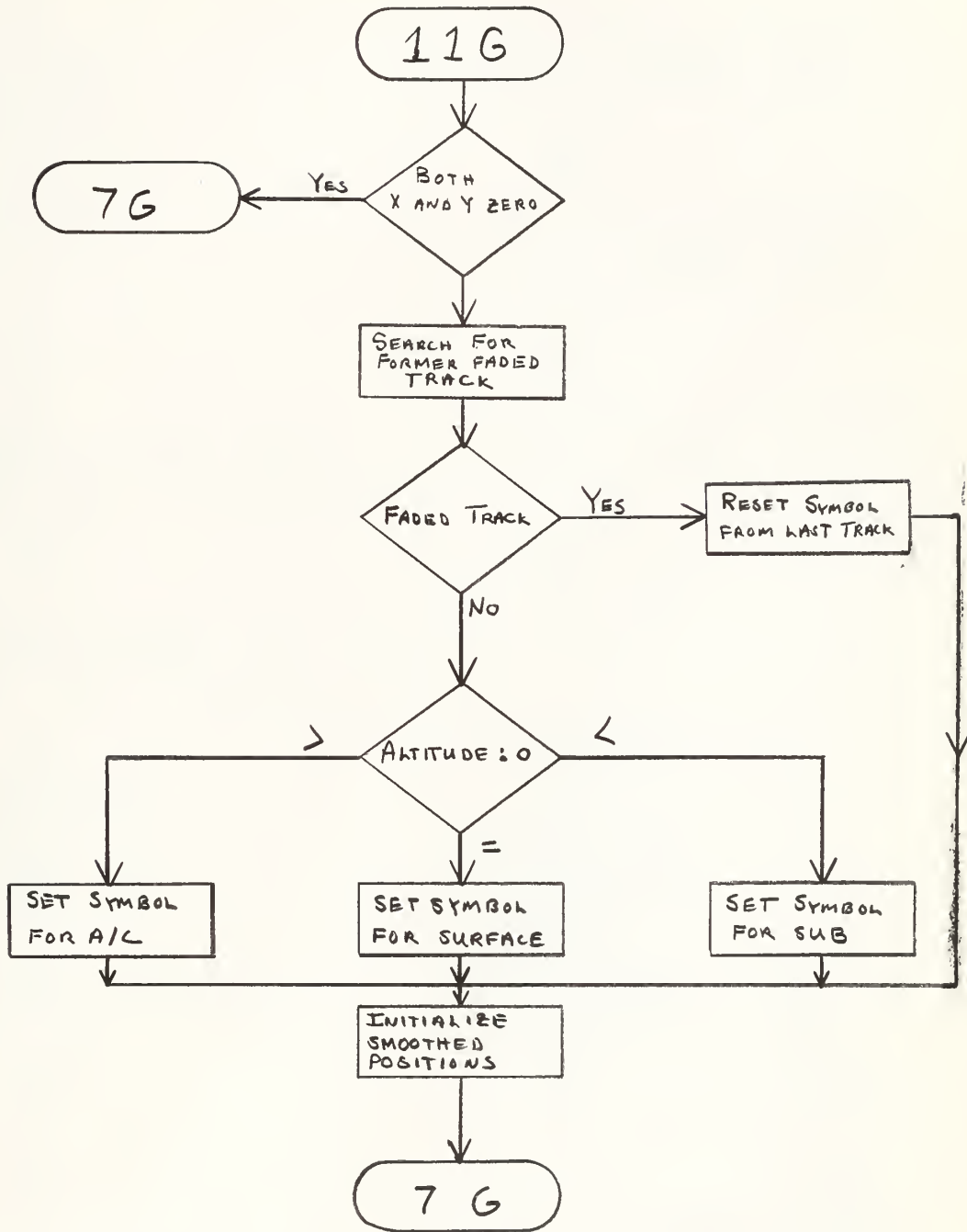


Figure I-12

Aircraft Control Subprogram

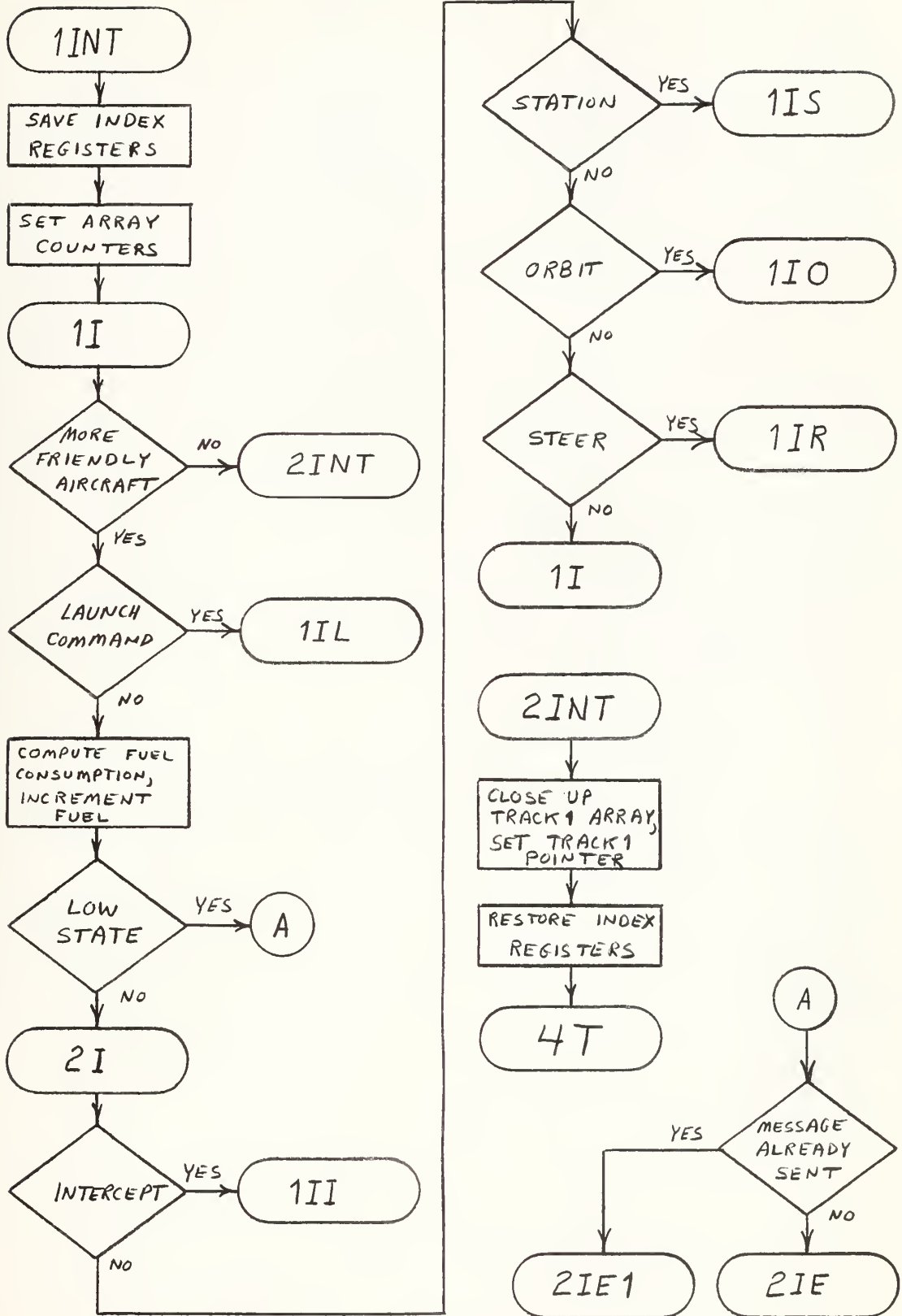


Figure I-13

Send Message Routine

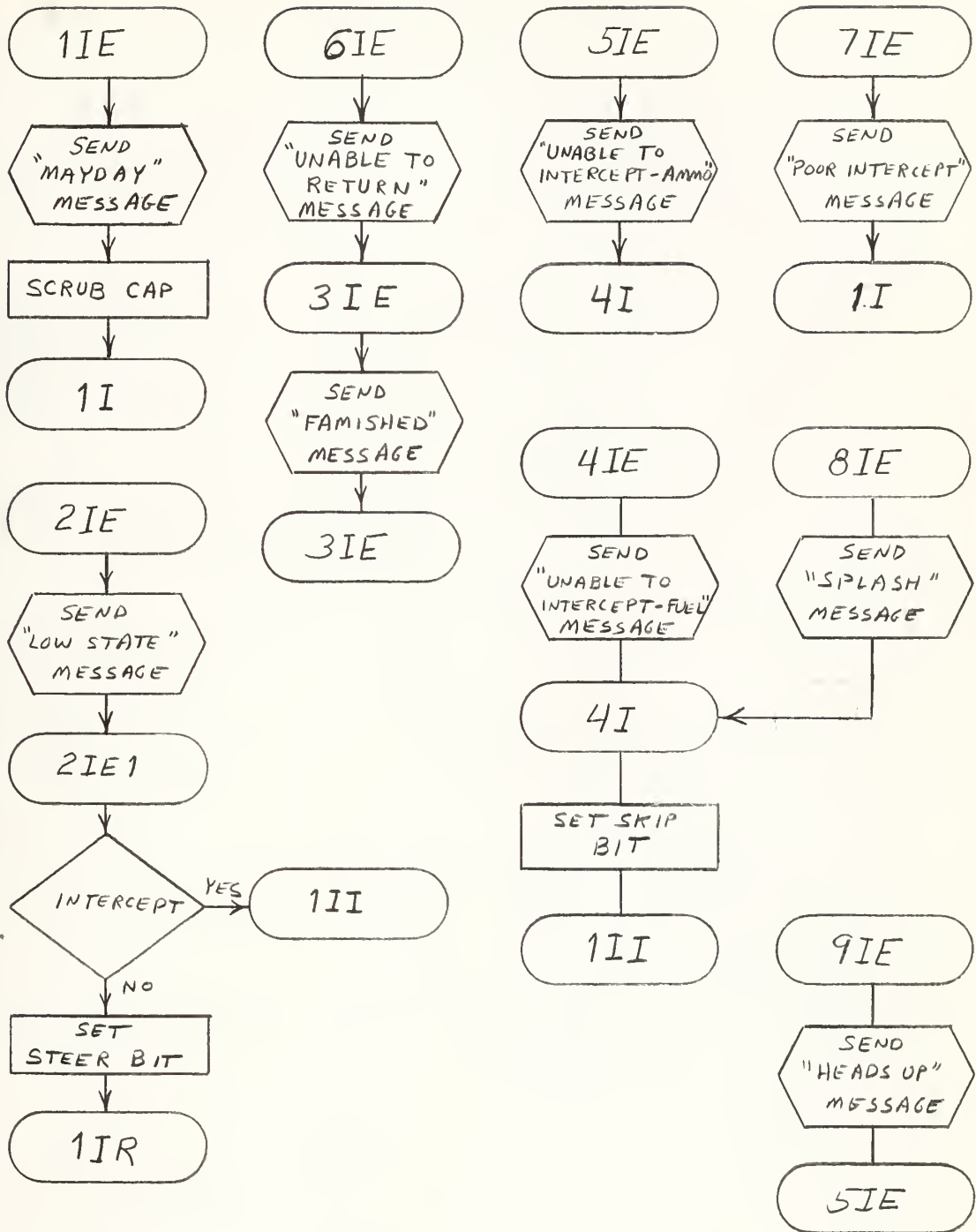


Figure I-14

Intercept and Skip Routines

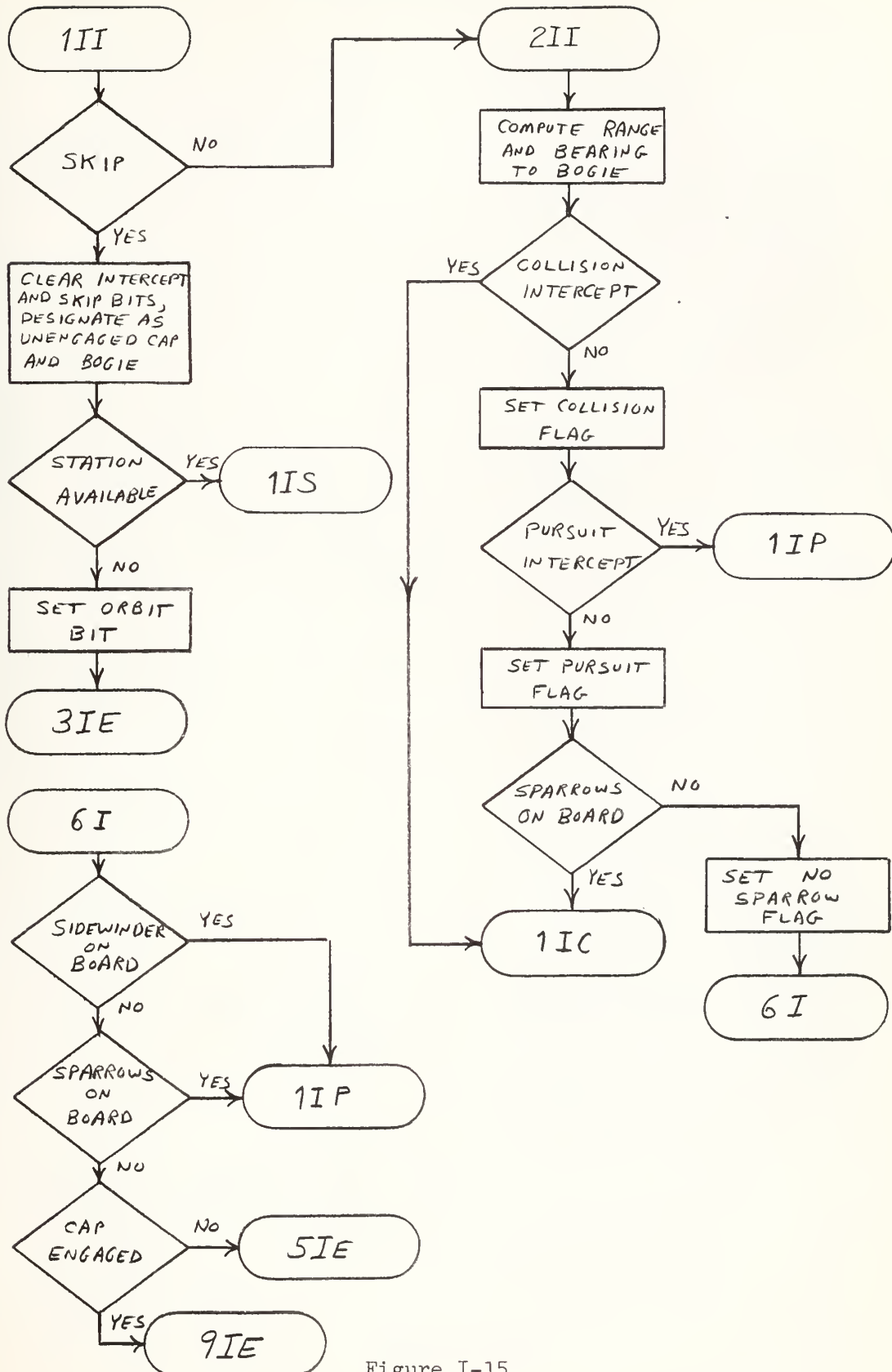


Figure I-15

Collision Intercept and Station Routines

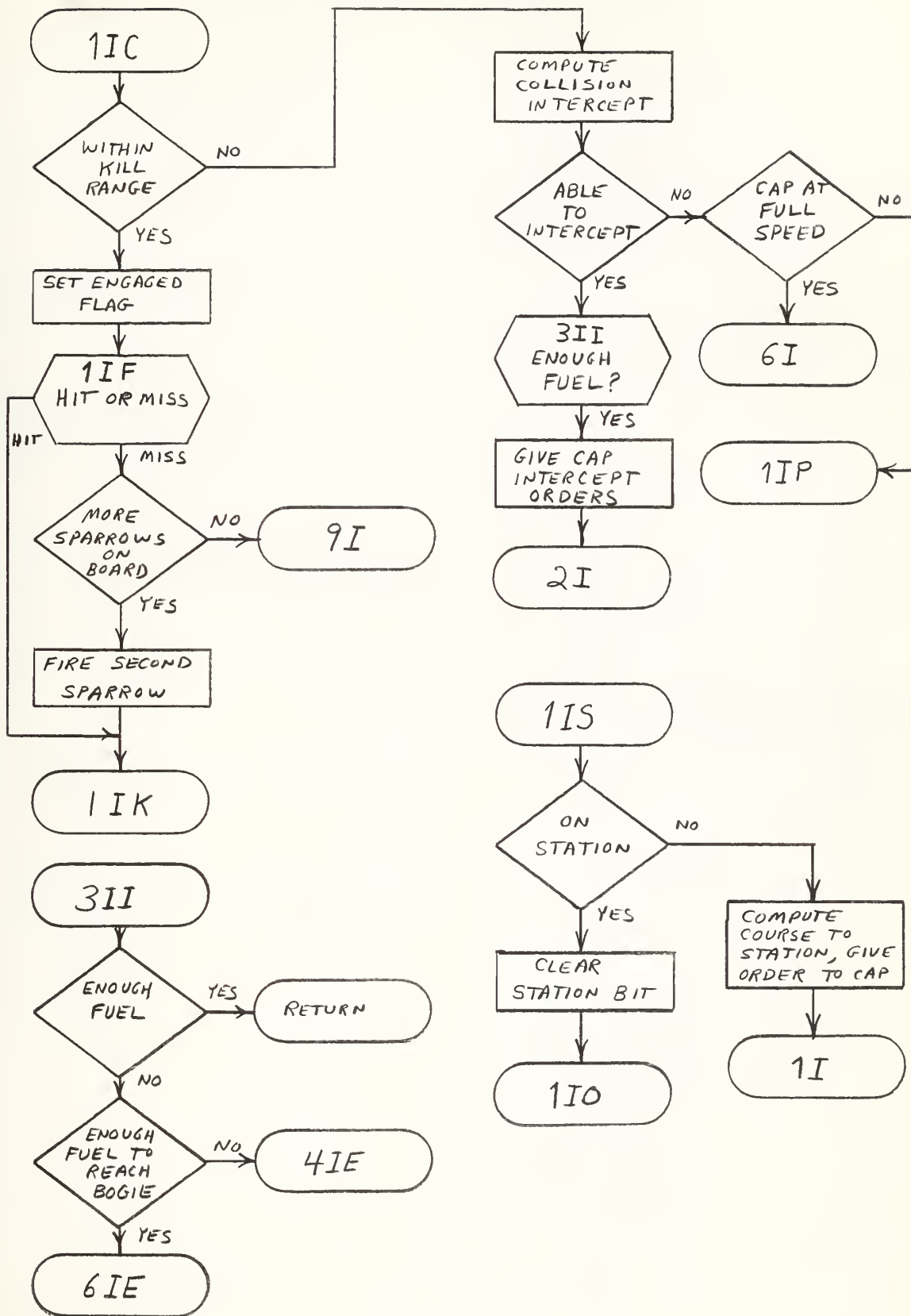


Figure I-16

Pursuit Intercept and Steer Routines

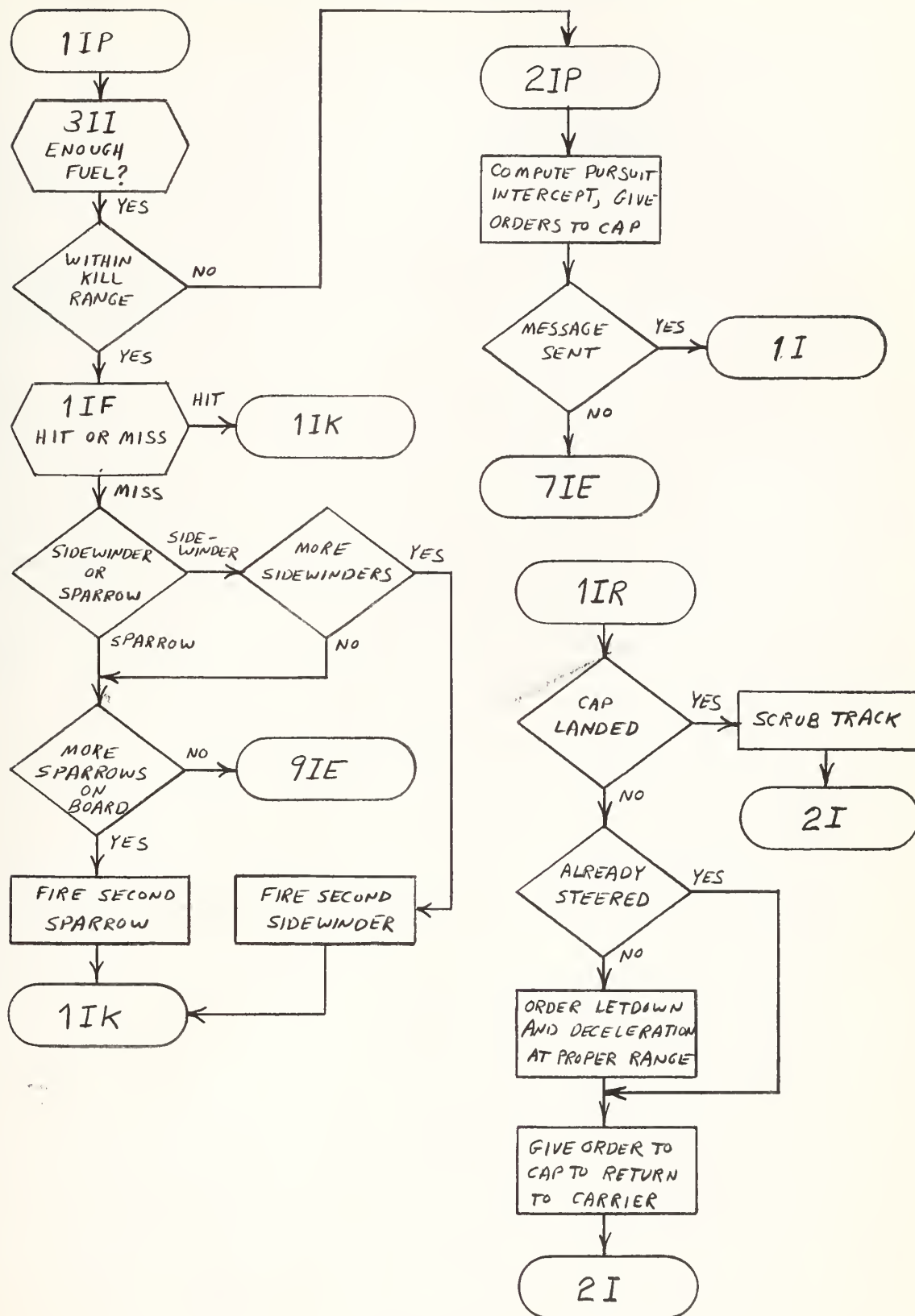
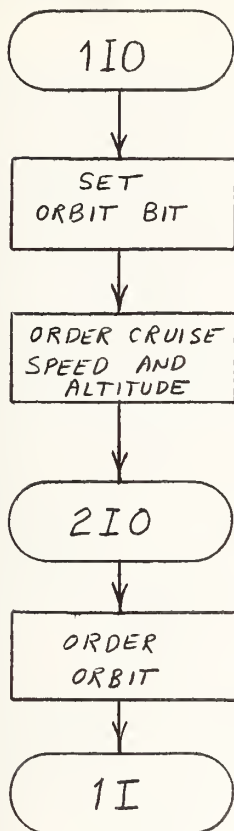


Figure I-17

APPENDIX I-B

Orbit Routine



Launch Routine

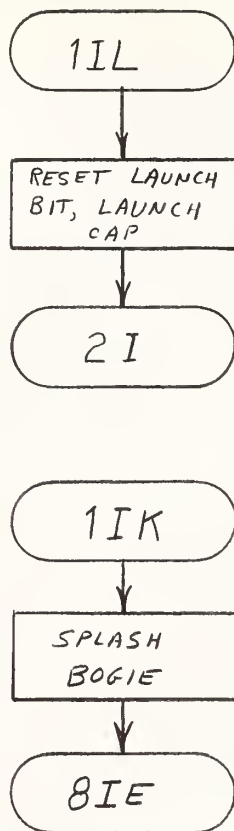


Figure I-18

Designate Track Routine

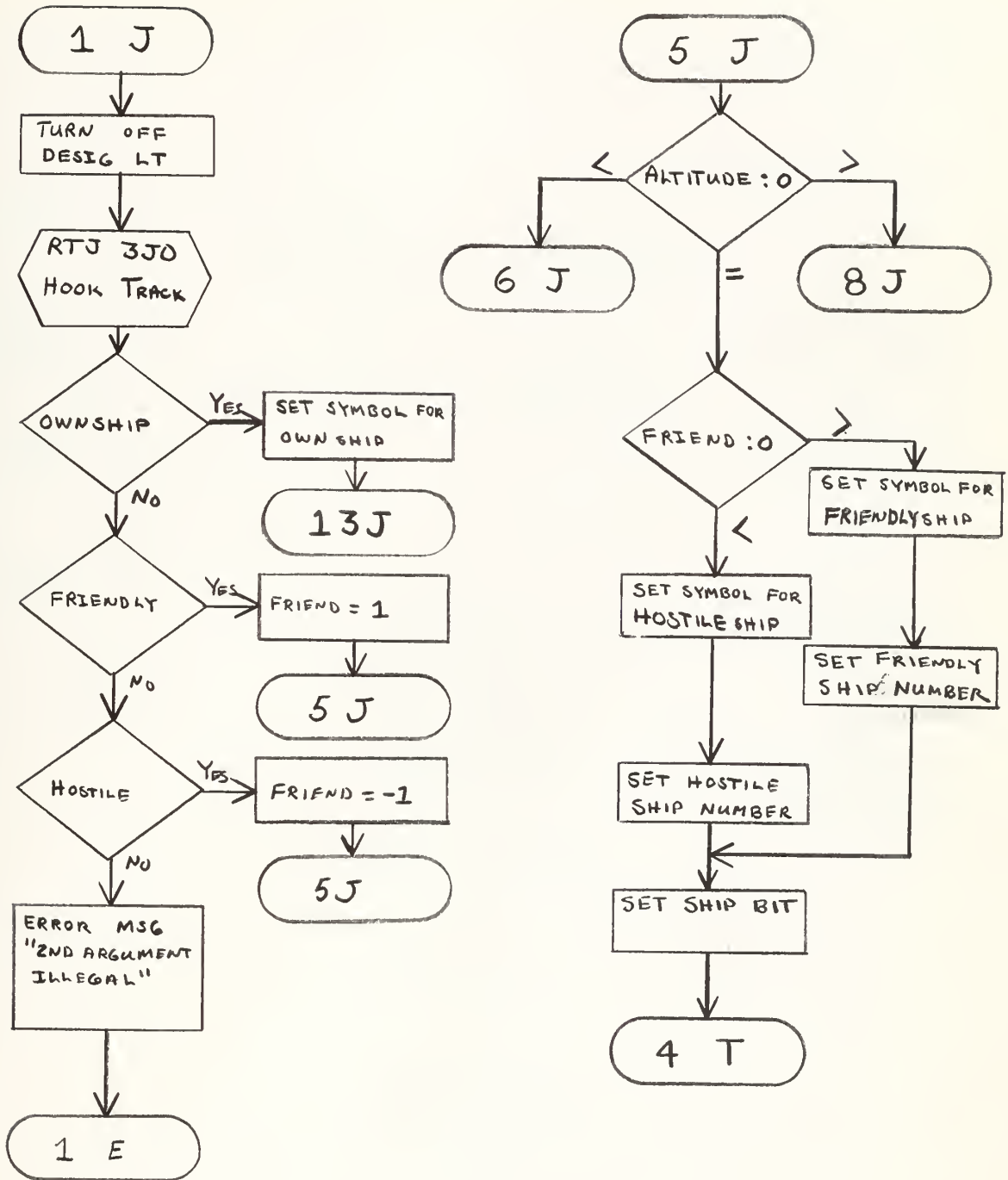


Figure I-19

Designate Track Routine (cont)

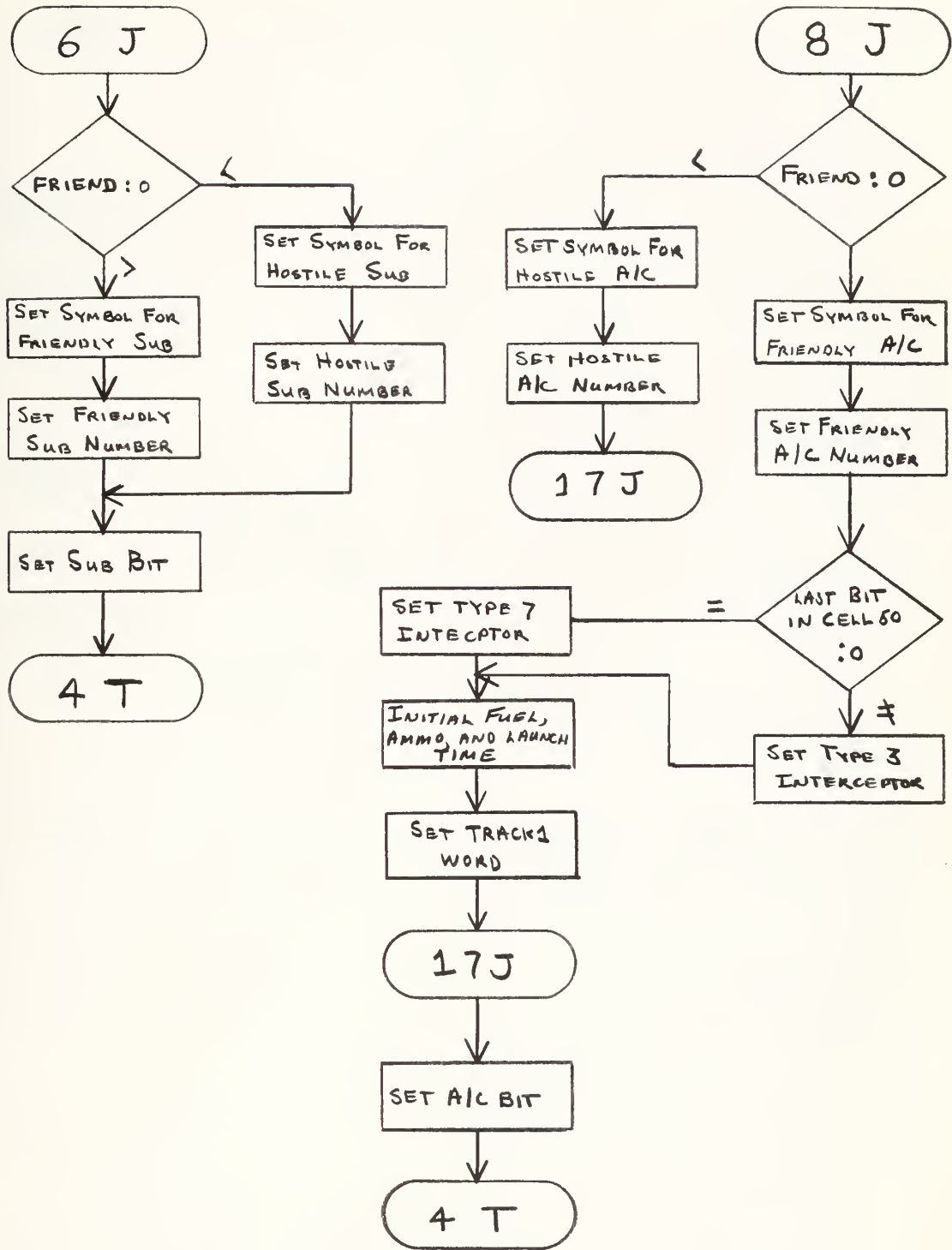


Figure I-20

Hook Track Routine

Keyboard Command Subprogram

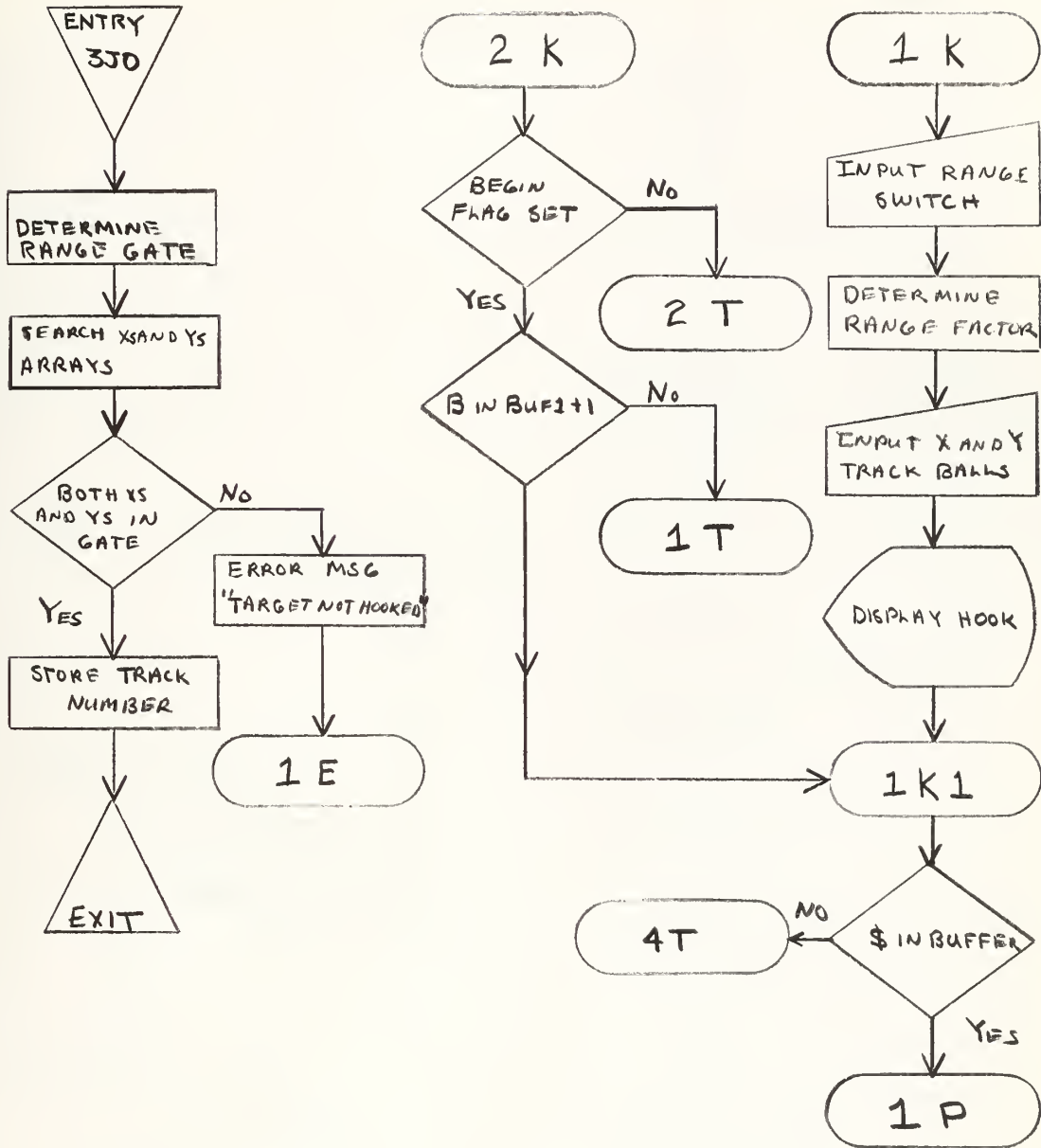


Figure I-21

History Routine

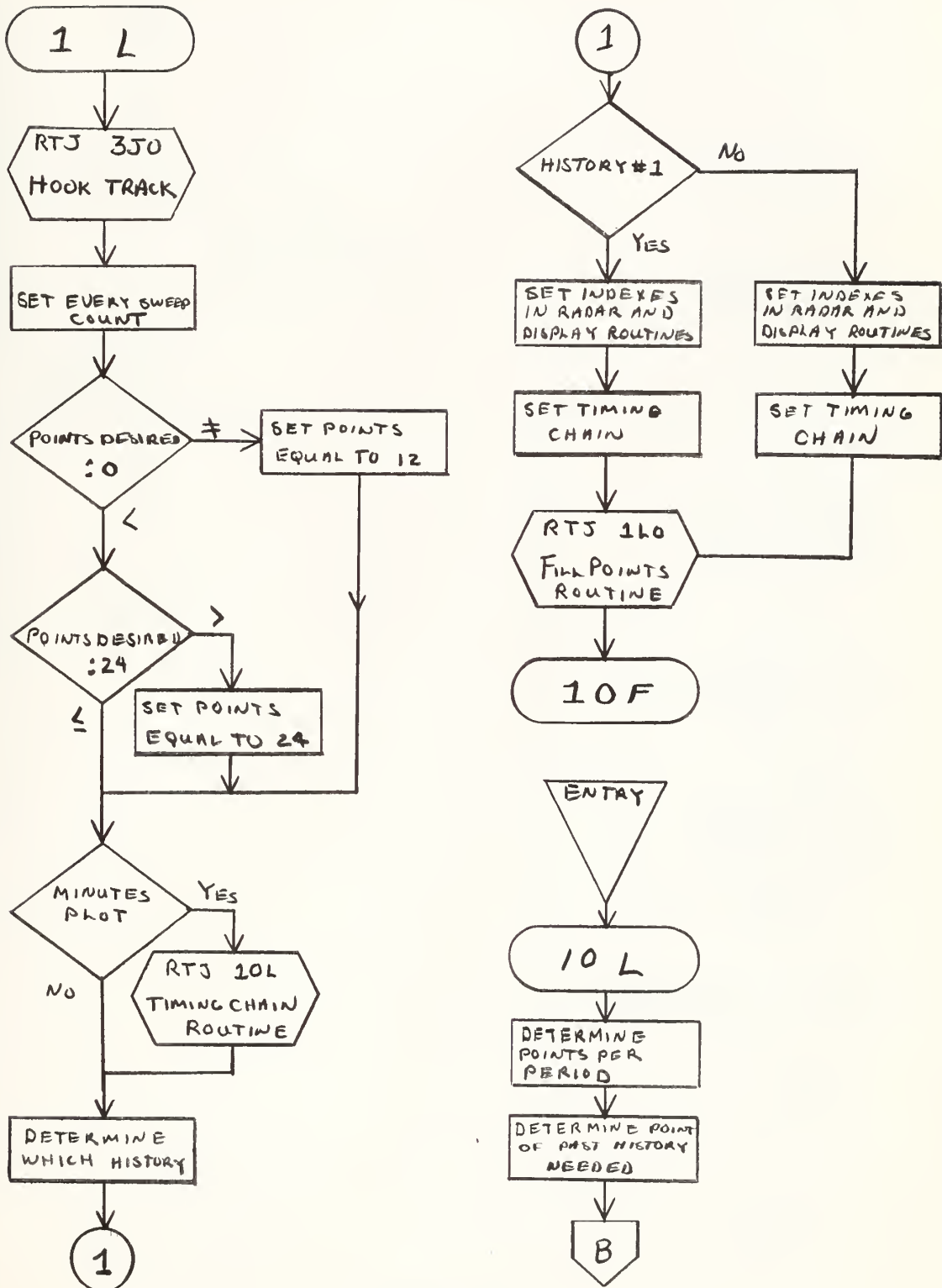


Figure I-22

History Routine (cont)

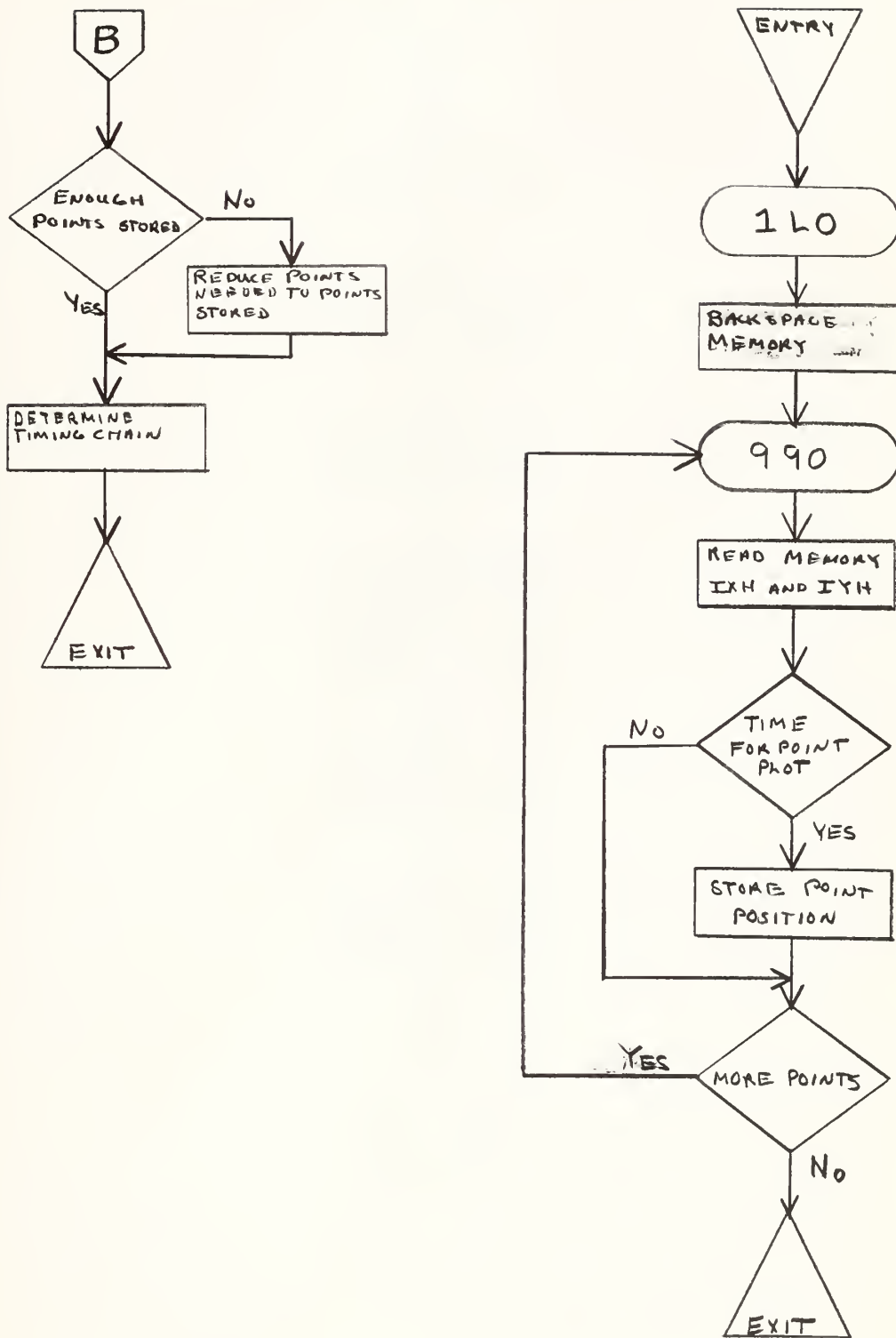


Figure I-23

Erase Routine

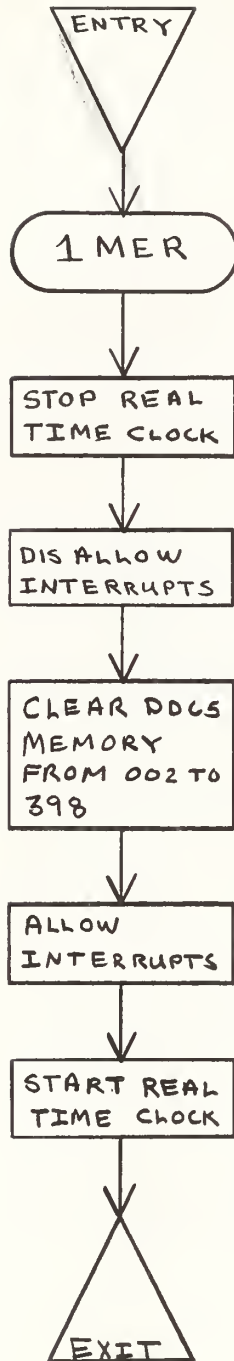
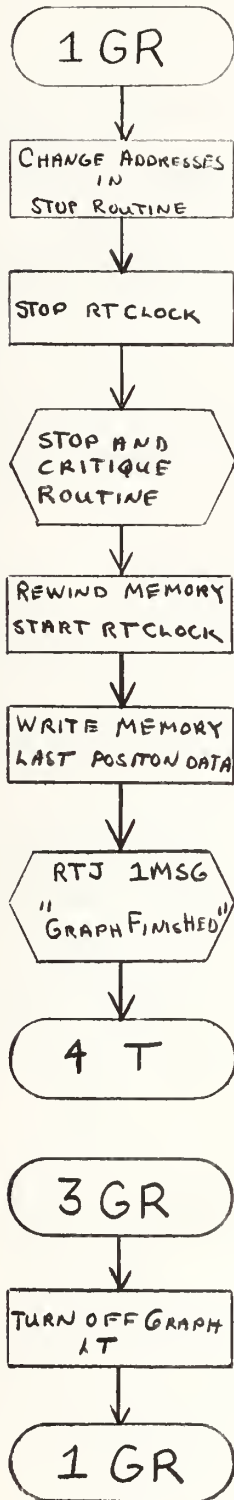
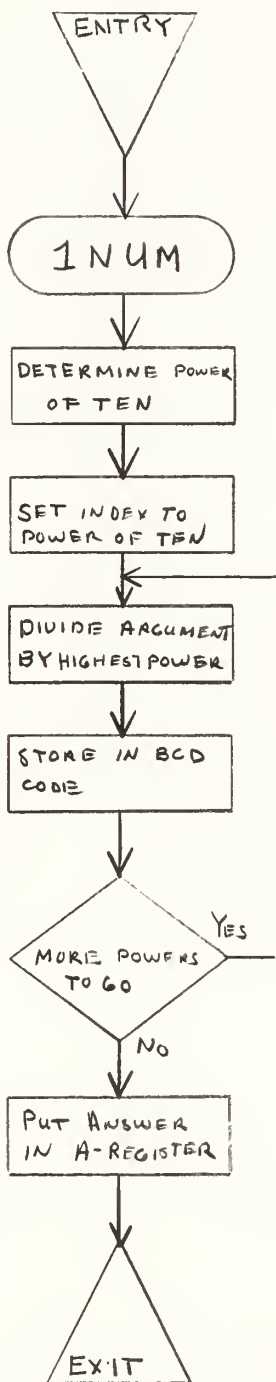


Figure I-24

Graph Subprogram



Octal to BCD Converter



Graph Title Update

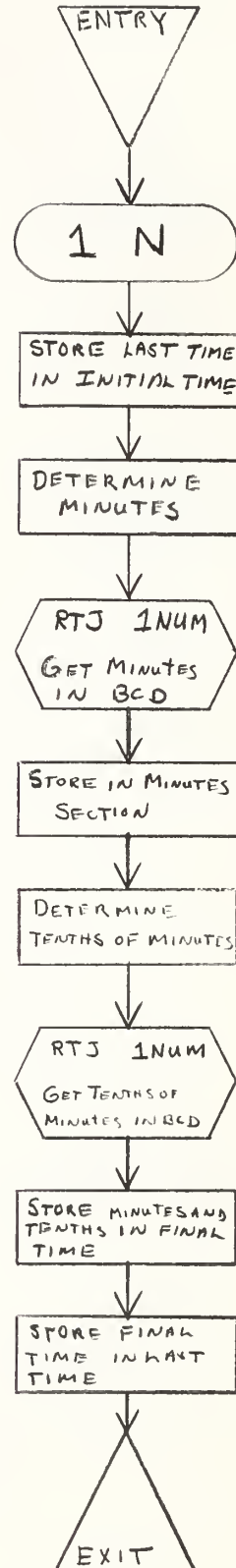
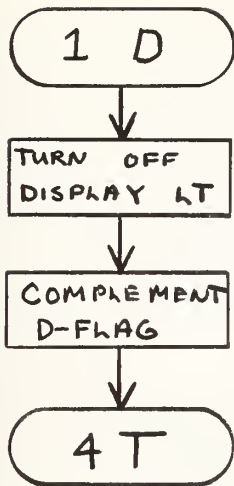
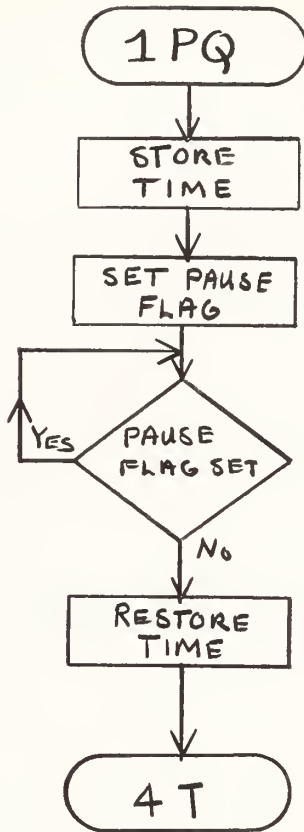


Figure I-25

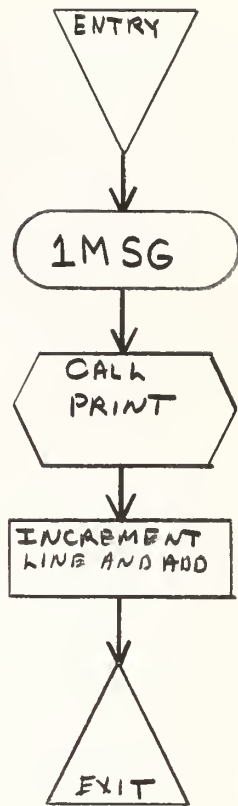
Display Routine



Hold or Pause Routine



Message Routine



Drop History Routine

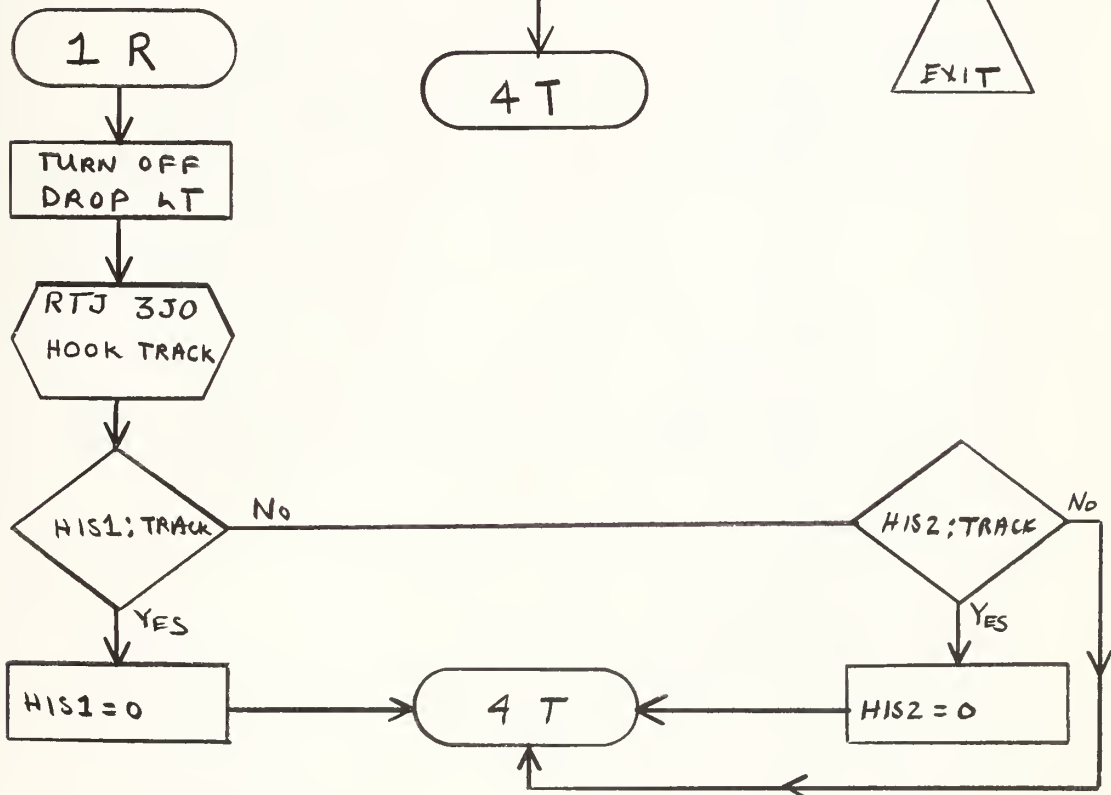


Figure I-26

Program Control Routine

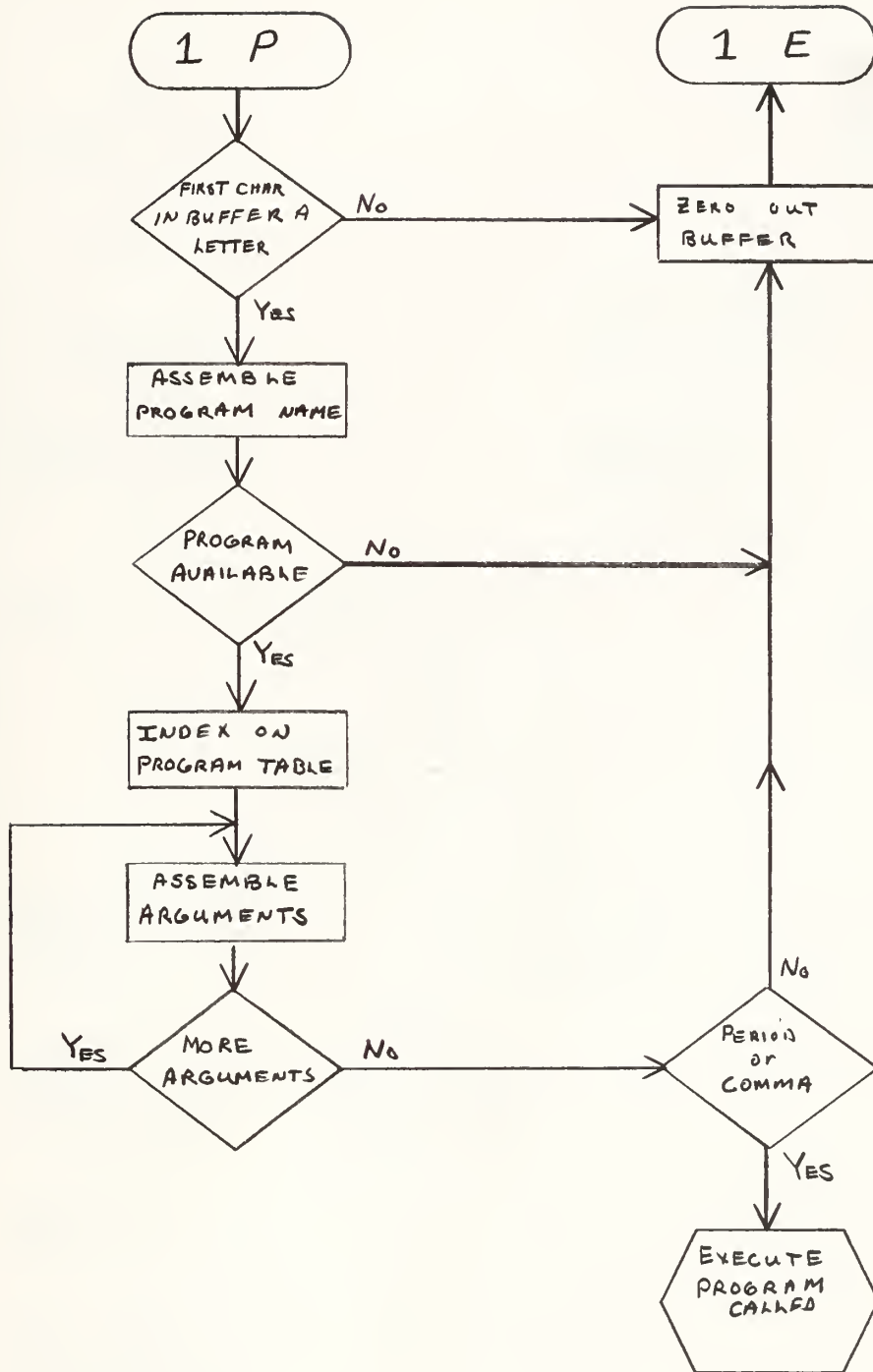


Figure I-27

Intercept Command Routine

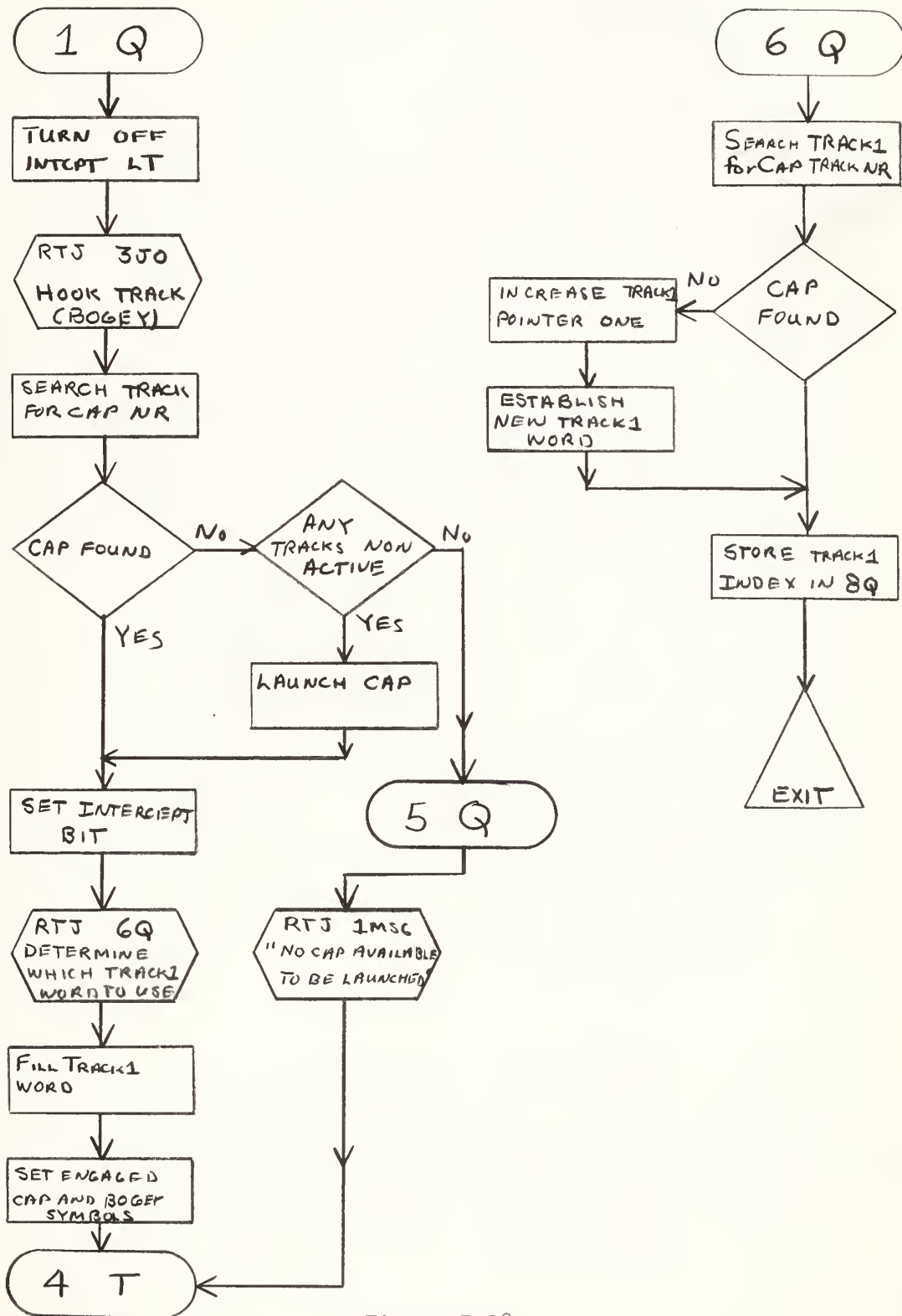


Figure I-28

Stop and Critique Routine

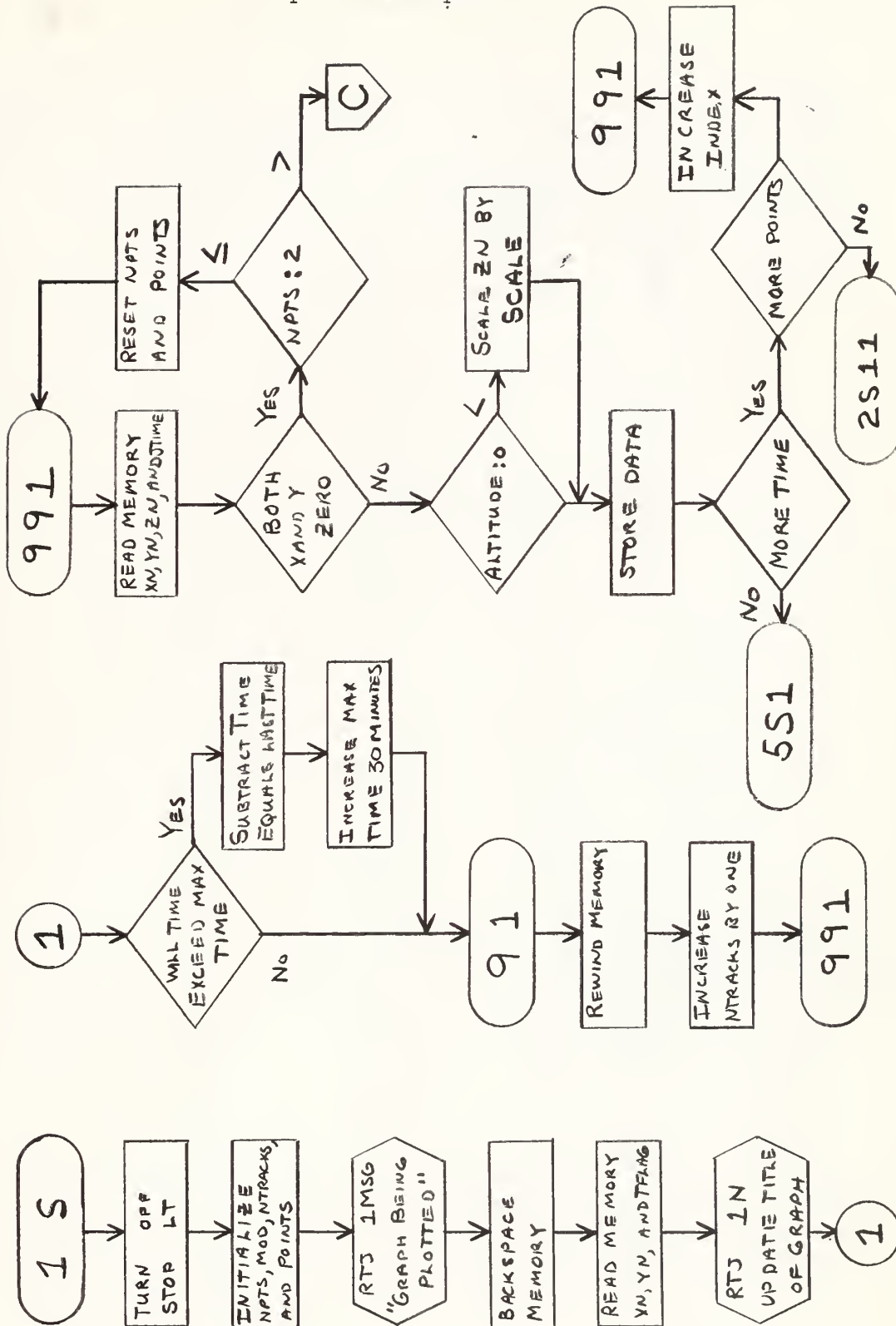


Figure I-29

Stop and Critique Routine (cont)

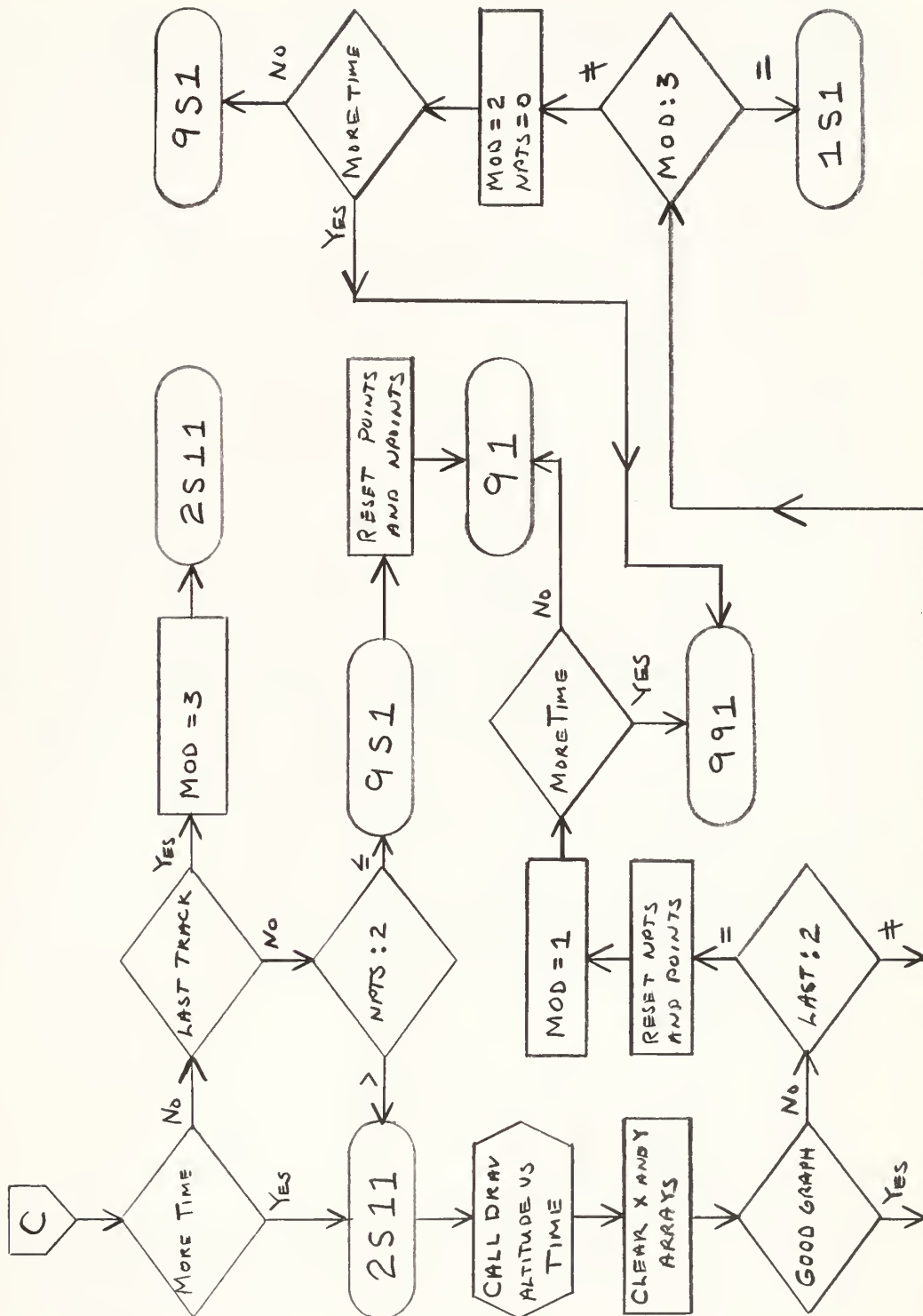


Figure I-30

Stop and Critique Routine (cont)

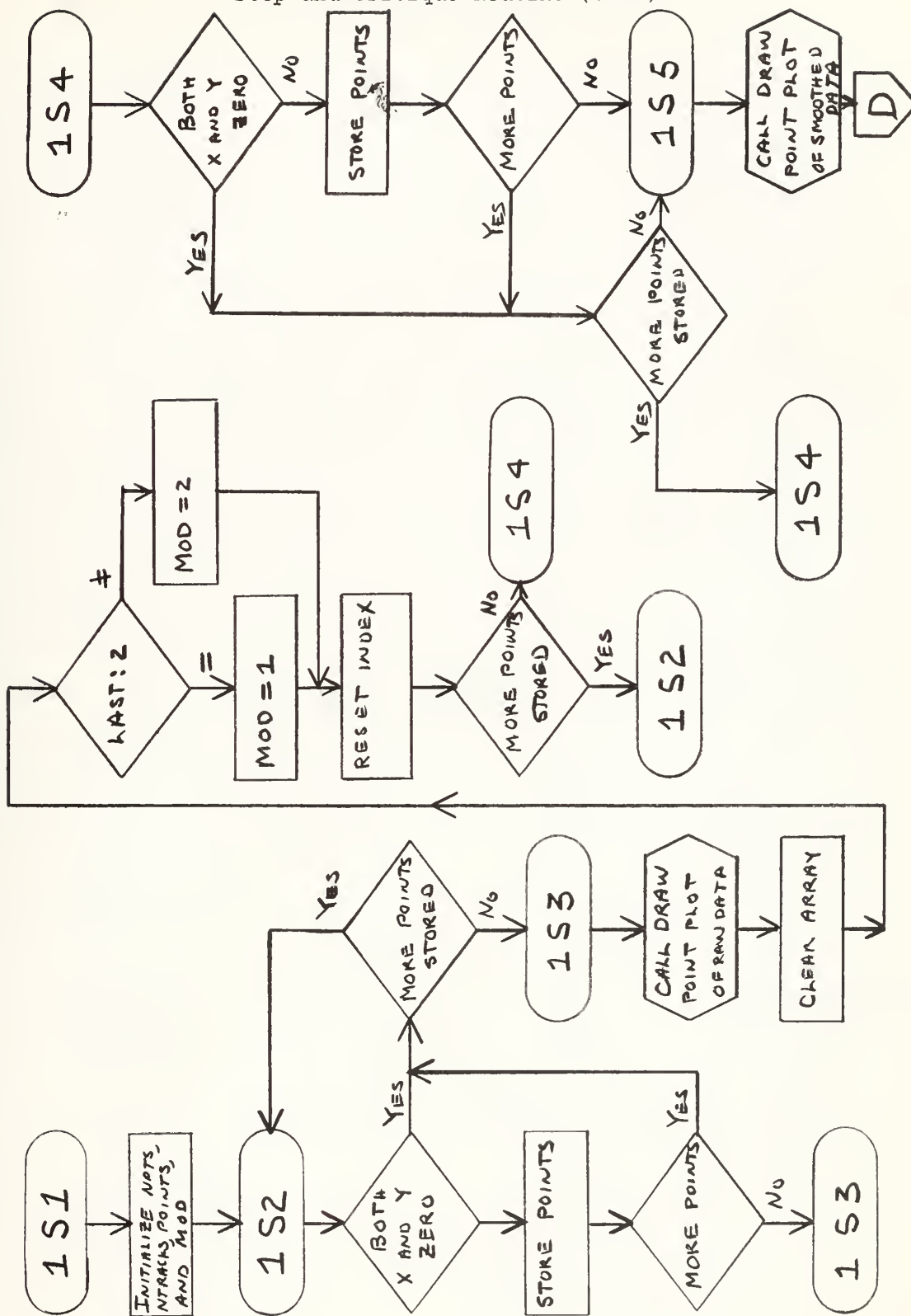


Figure I-31

Stop and Critique Routine (cont)

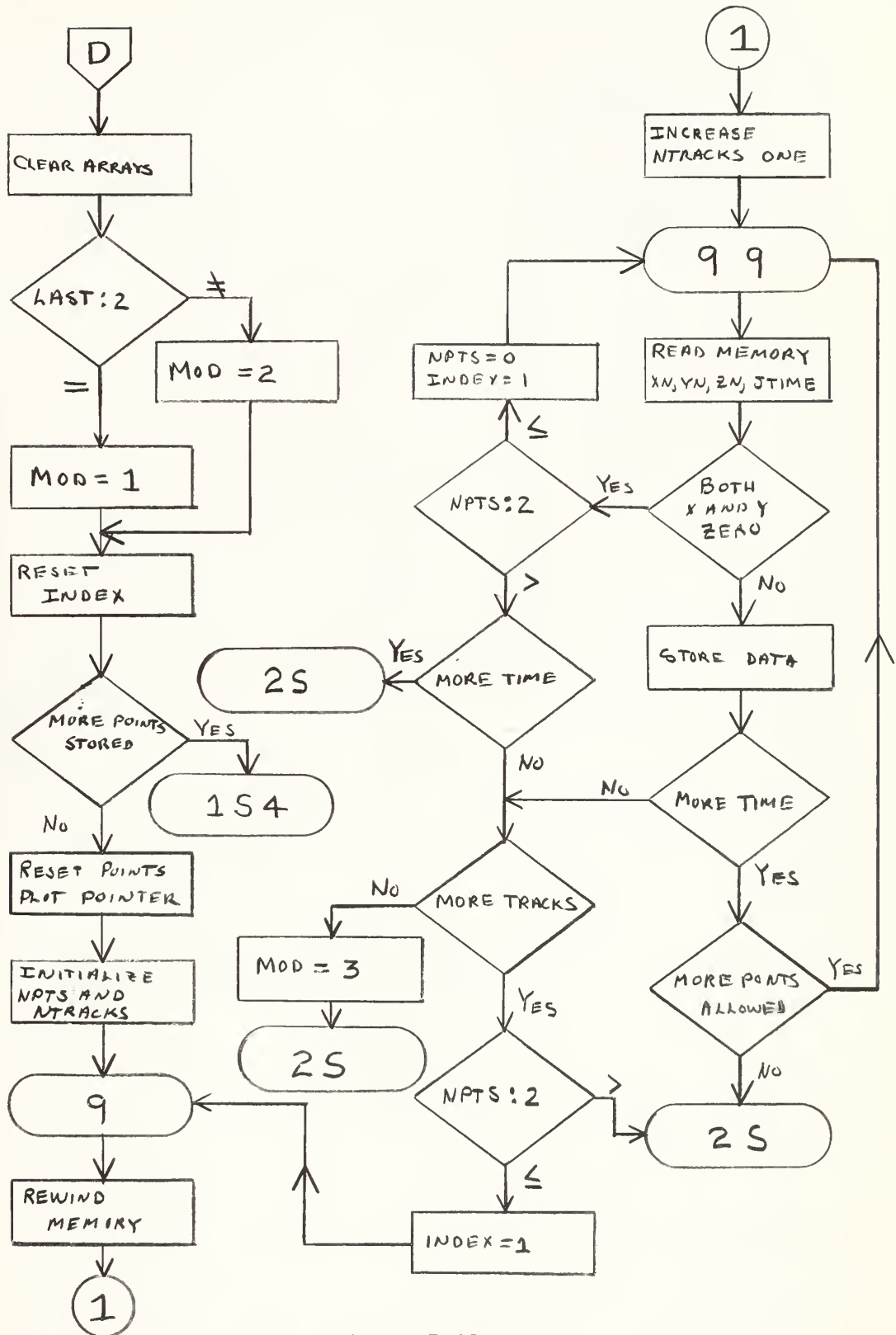


Figure I-32

Stop and Critique Routine (cont)

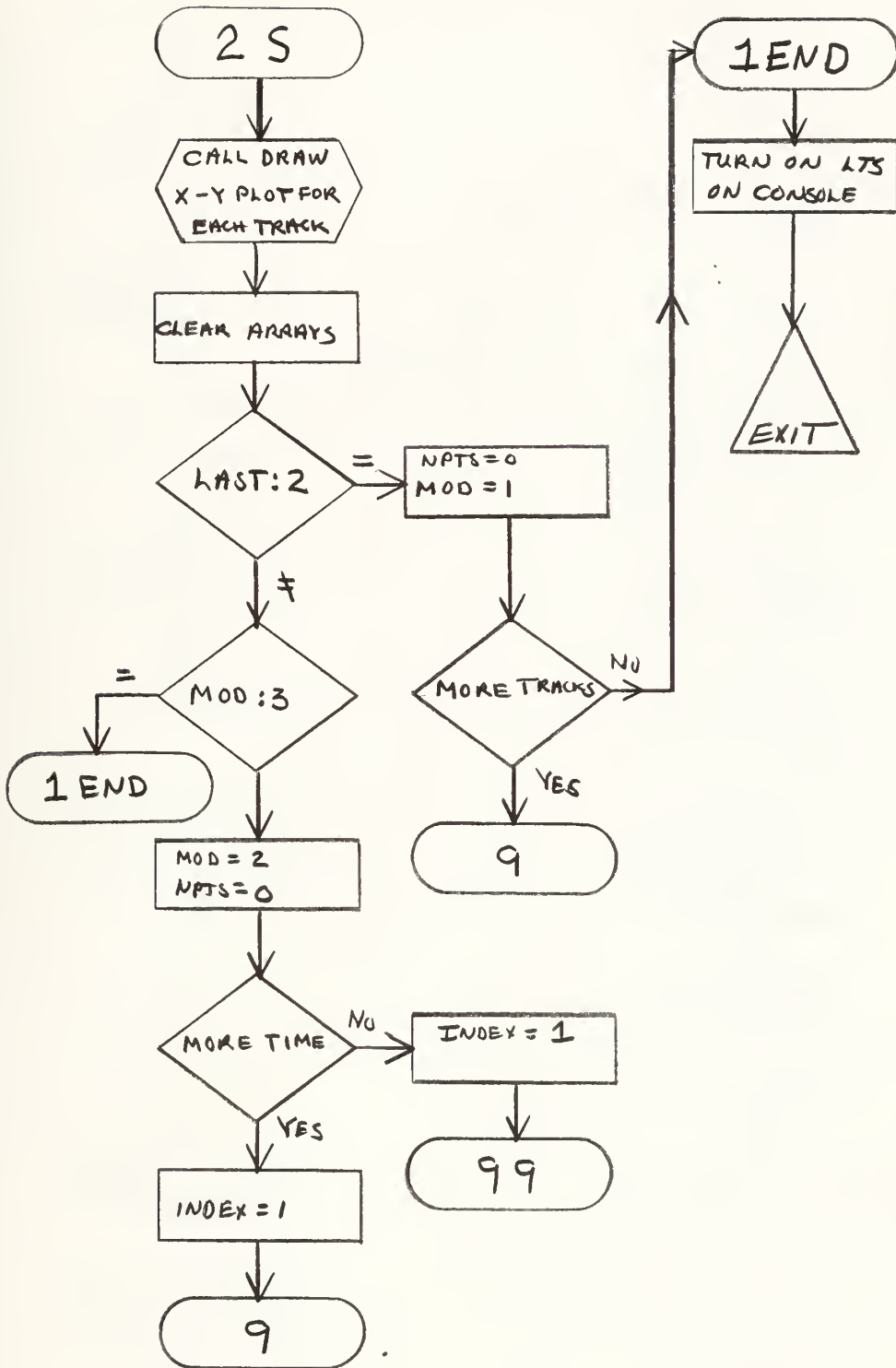


Figure I-33

State Routine

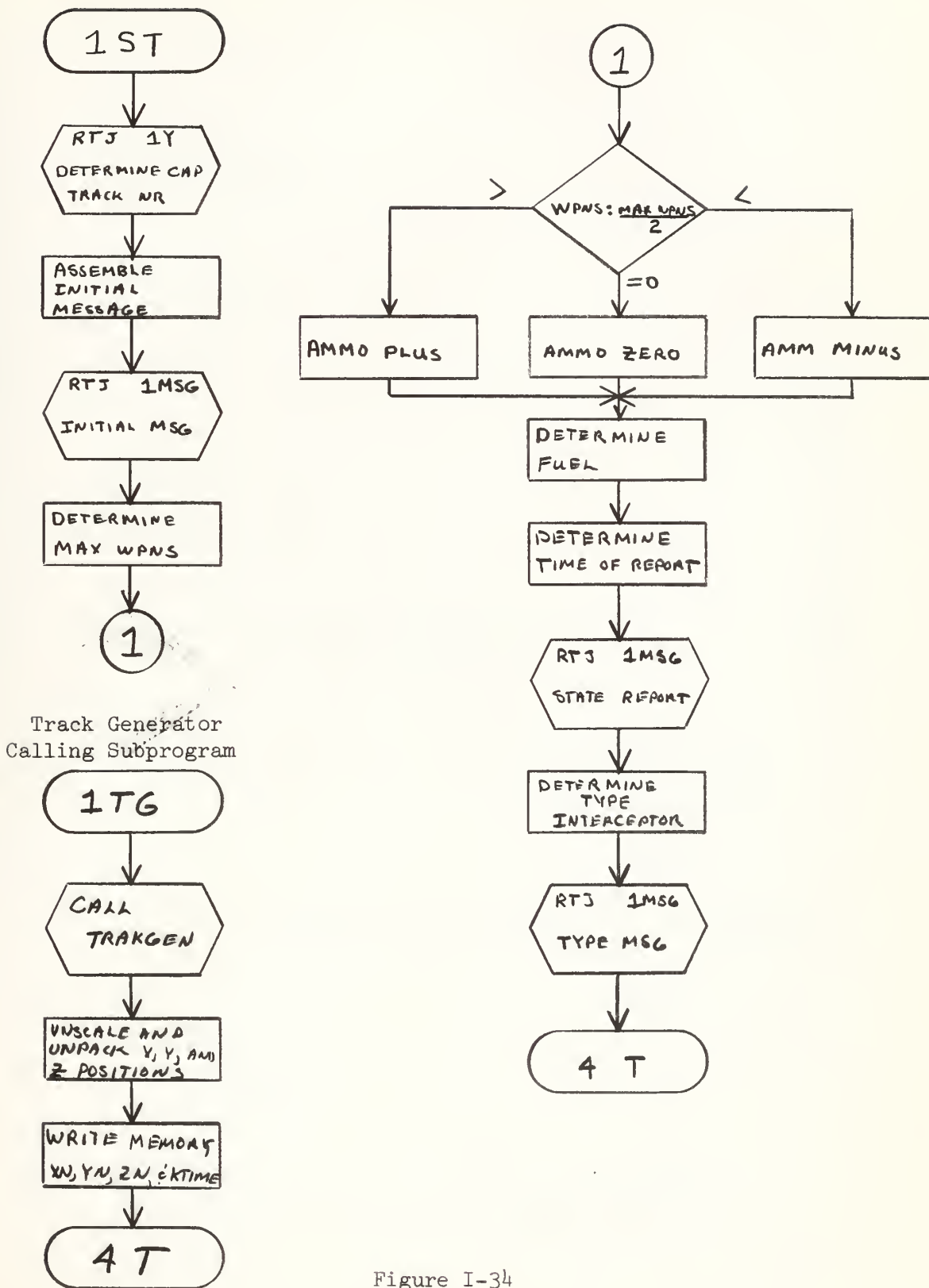


Figure I-34

Executive Routine

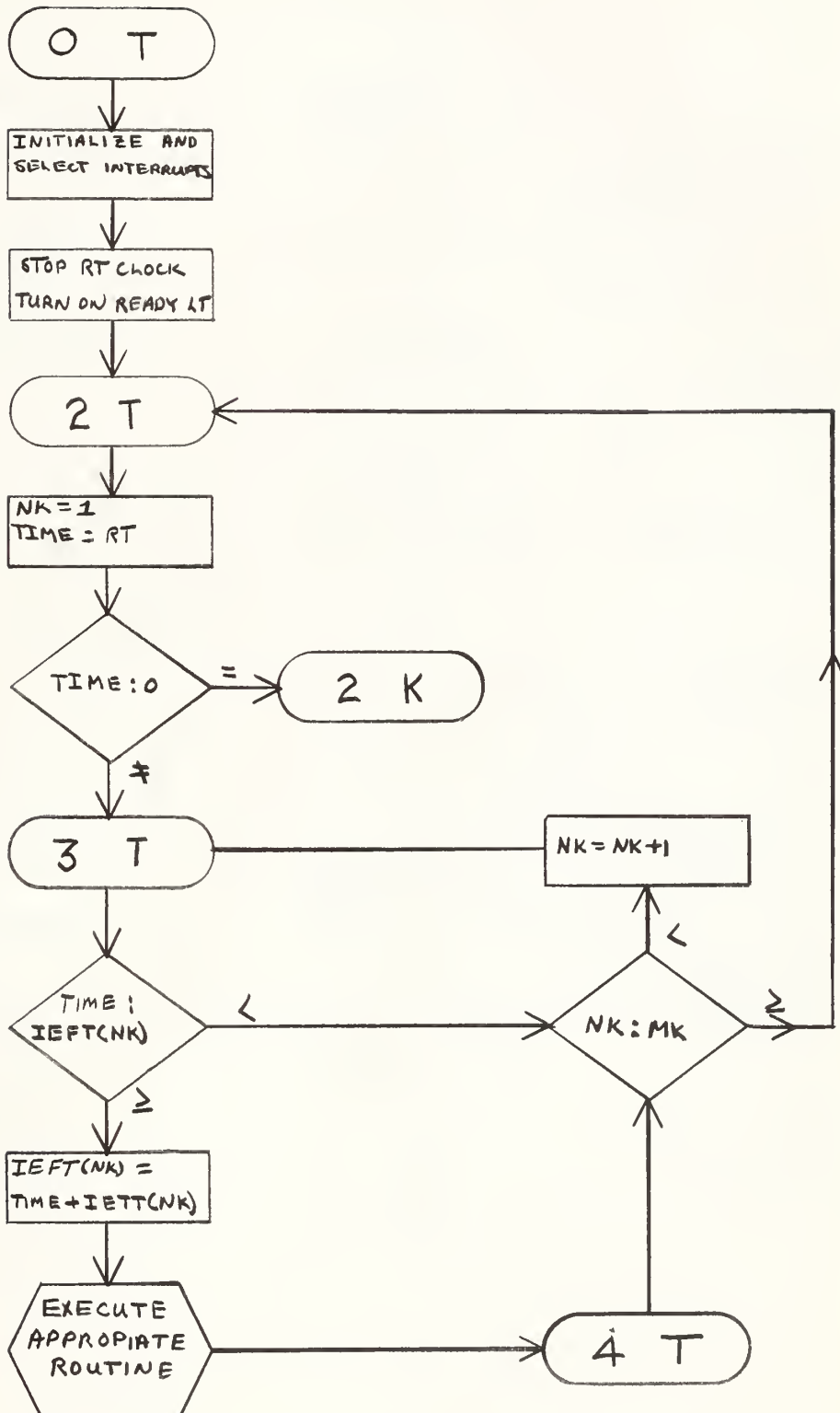


Figure I-35

INFO Routine

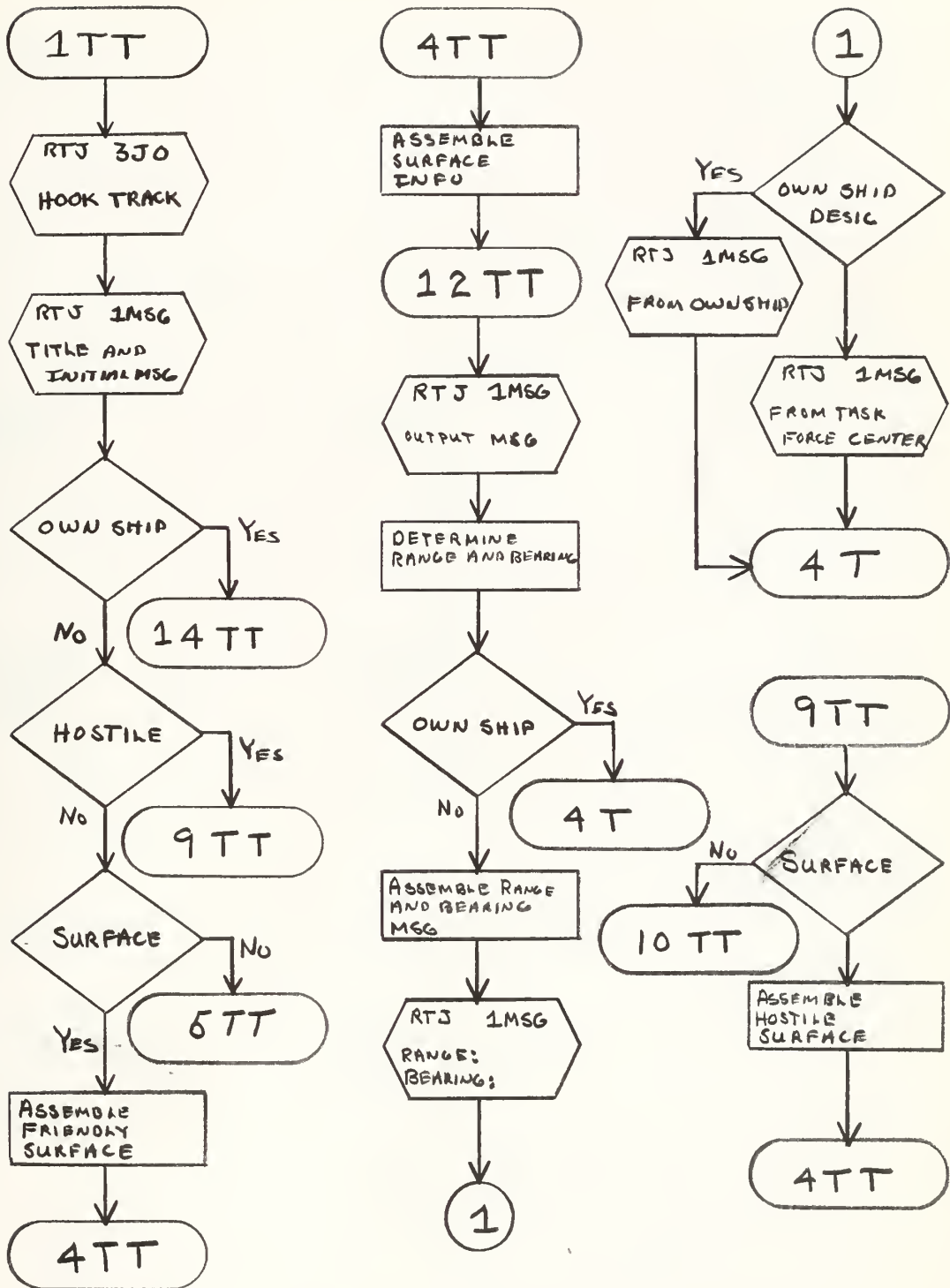


Figure I-36

INFO Routine (cont)

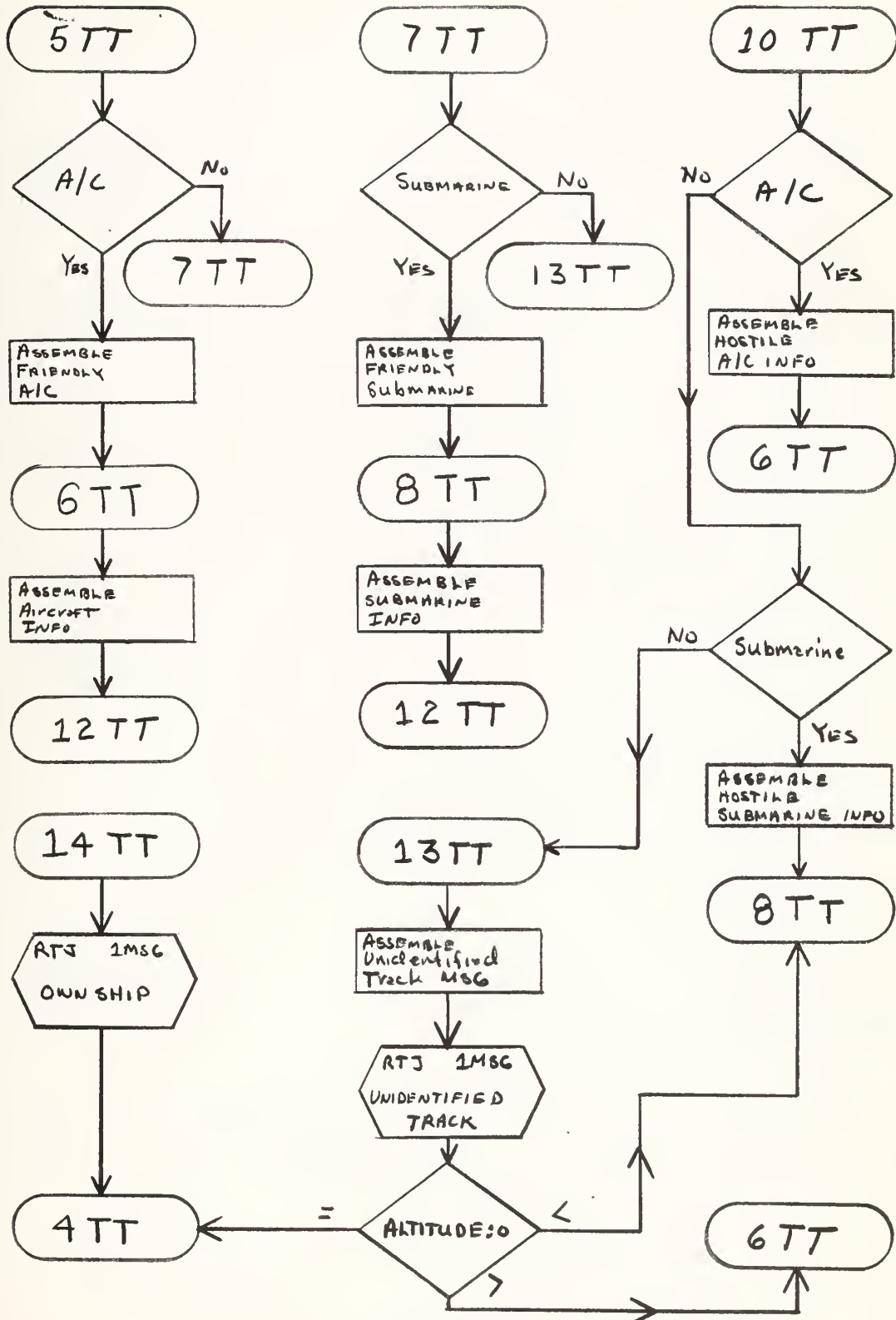


Figure I-37

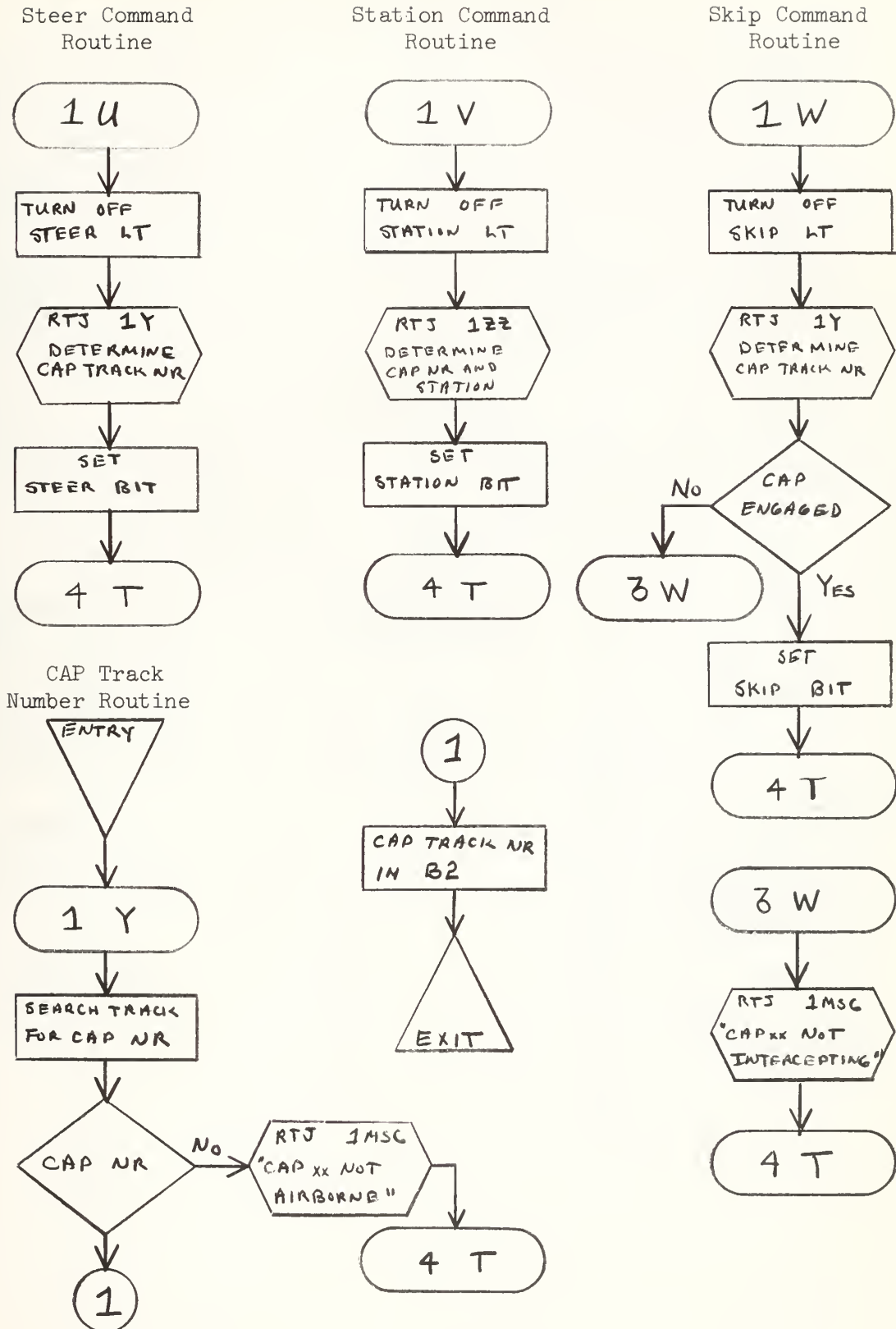


Figure I-38

Launch Command Routine

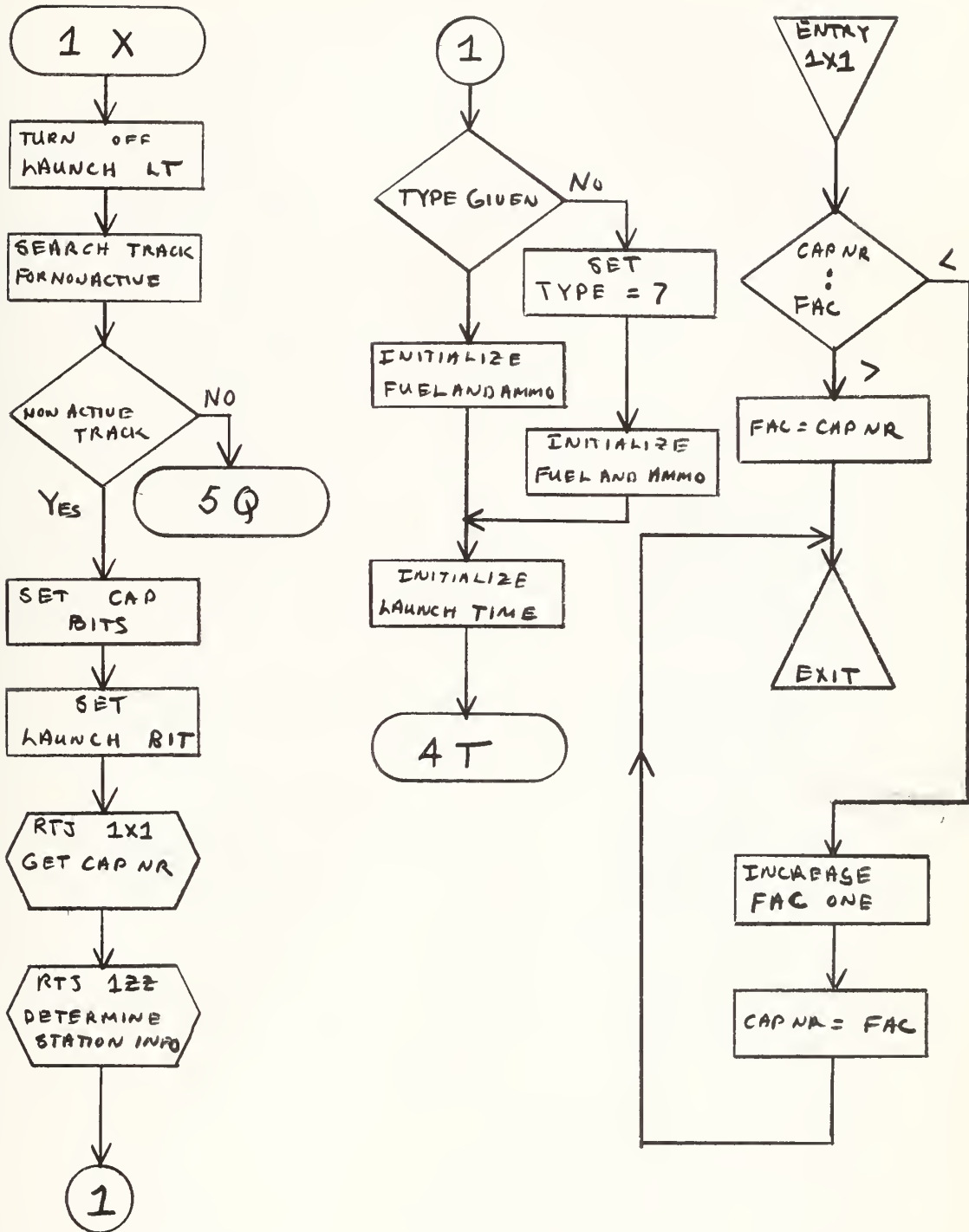


Figure I-39

Begin Routine

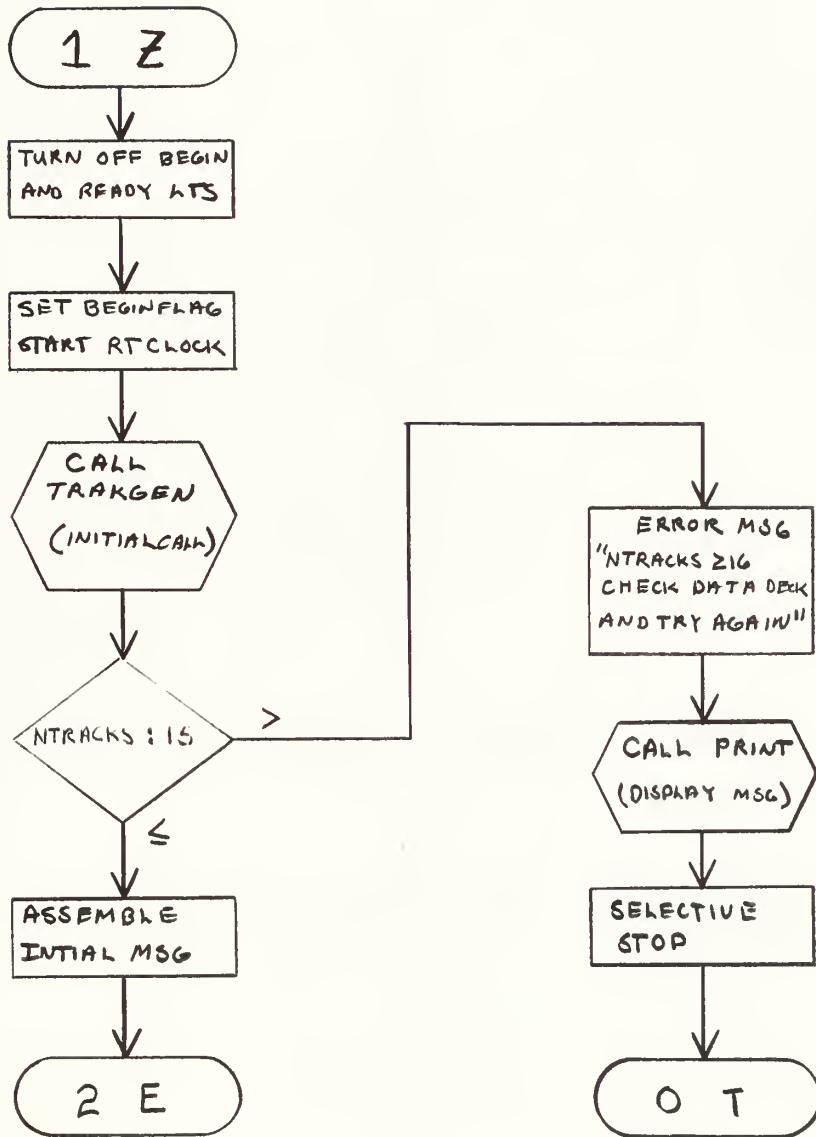


Figure I-40

CAP Track Number and Station Routine

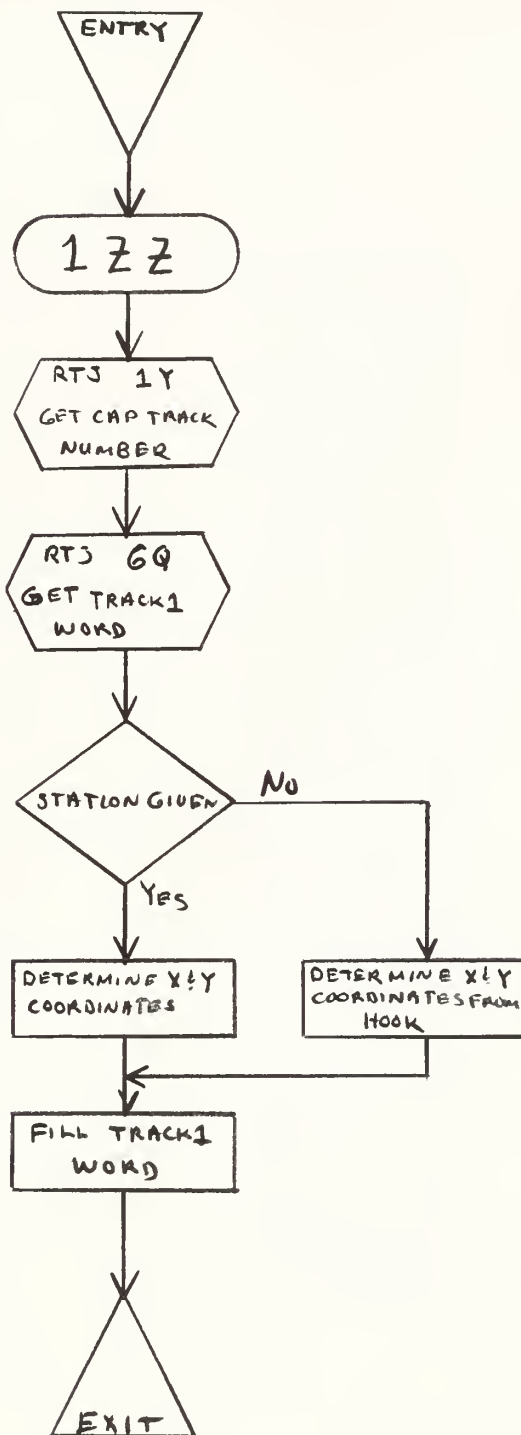


Figure I-41

APPENDIX I-C

SIMONE PROGRAM LISTING

```

MACHINE SIMONE
RSV(IPOSIT=15,IHEAD=15,JHEAD=15,IDD65=10,IETT=6,IETF=6,BUFI=120)
RSV(T=11,ERRMSG=4,R=4,D=15,F=15,TRACK=15,TRACK1=15,TRACK2=15)
RSV(SPD=15,CRS=15,KTIME=4,MACH=15)
RSV(XHISI1=24,YHISI1=24,XHISI2=24,YHISI2=24,IXH=15,IYH=15)
RSV(XN=15,YN=15,ZN=15,XP=15,YP=15,ZP=15,XS=15,YS=15,ZS=15,
*   VXS=15,VYS=15,VZS=15,LHEAD=60,KFIG=15)
RSV(X=299,X1=299,X2=299,Y=299,Y1=299,Y2=299)

LIB(TRAKGEN,PRINT,DRAW,FLOATFIX=FLOAT,FIXFLOAT=FIX,COURSE)
LIB(SQRTF=SQ,COSF,SINF)

COMMON IPOSIT,IHEAD,JHEAD,LHEAD,IDD65,ISCALE1,ISCALE2,SCALE1,
*   SCALE2,TIME

LOC(Z=0,ITIME=50)

* BCD CODE TABLE

CON(F0 =12B,F1 =01B,F2 =02B,F3 =03B,F4 =04B,F5 =05B,F6 =06B,
*   F7 =07B,F10=10B,F11=11B,F12=61B,F13=62B,F14=63B,F15=64B,
*   F16=65B,F17=66B,F20=67B,F21=70B,F22=71B,F23=41B,F24=42B,
*   F25=43B,F26=44B,F27=45B,F30=46B,F31=47B,F32=50B,F33=51B,
*   F34=22B,F35=23B,F36=24B,F37=25B,F40=26B,F41=27B,F42=30B,
*   F43=31B,F44=73B,F45=53B,F46=34B,F47=13B,F50=54B,F51=21B,
*   F52=60B,F53=40B,F54=74B,F55=33B,F56=20B,F57=14B,F60=52B)

* SPECIAL SYMBOLS FOR DD-65 DISPLAY

CON(S1 = 0700524354455647B, S1A = 5041010454540401B,
*   S1B = 0001565677000000B, S1C = 0000000000000000B,
*   S2 = 1046455443427700B, S2A = 0000000000000000B,
*   S2B = 0000000000000000B, S2C = 00000000,
*   S3 = 0700524354455647B, S3A = 5041770000000000B,
*   S3B = 0000000000000000B, S3C = 00000000B,

```



```

* S4 = 1042435445467700B, S4A = 0000000000000000B,
* S4B = 0000000000000000B, S4C = 0000000B,
* S5 = 1012141416565050B, S5A = 5277000000000000B,
* S5B = 0000000000000000B, S5C = 0000000B)
CON(S6 = 1052545456565050B, S6A = 5277000000000000B,
* S6B = 0000000000000000B, S6C = 0000000B,
* S7 = 1052545456770000B, S7A = 0000000000000000B,
* S7B = 0000000000000000B, S7C = 0000000B,
* S8 = 1053557700000000B, S8A = 0000000000000000B,
* S8B = 0000000000000000B, S8C = 0000000B,
* S9 = 1013155751770000B, S9A = 0000000000000000B,
* S9B = 0000000000000000B, S9C = 0000000B,
* S10 = 1053555751770000B, S10A = 0000000000000000B,
* S10B = 0000000000000000B, S10C = 0000000B)
CON(S11 = 50161552525215B, S11A = 1657700000000000B,
* S11B = 000077777777777B, S11C = 7300000000000000B,
* S12 = 5053555077000000B, S13 = 5052545456507700B)

```

* RAW DATA DISPLAY SYMBOLS

```

CON(C360 = 4310164377000000B, C090 = 4116144177000000B,
* C180 = 4310164377000000B, C270 = 4116147700000000B)

```

* MASK FOR LOADING AND UNPACKING

```

CON(MASK4B = 0070000000000000B, MASK8U = 0030000000000000B,
* MASK9 = 000000077777777B, MASK9L = 5000000002000030B)
CON(MASK10 = 777777777777700B, MASK11 = 000000000000077B,
* MASK12 = 000000000000070B, MASK13 = 740000000000000B,
* MASK14 = 400000000000000B, MASKX = 777777700000000B,
* MASKY = 00000007777777B, MASK15 = 7777777777777B,
* MASK16 = 100000000000000B, MASK17 = 200000000000000B,
* MASK18 = 040000000000000B, MASK19 = 000000040000000B,
* MASK20 = 000000020000000B, MASK21 = 000000010000000B,
* MASK22 = 000000004000000B, MASK23 = 000000002000000B,
* MASK24 = 000000001000000B, MASK25 = 000000000400000B,

```


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```

*   MASK26 = 0000000002000000B, MASK27 = 0000000001000000B)
CON(MASK30 = 0070000000000000B, MASK31 = 0000000770000000B,
*   MASK32 = 0000007700000000B, MASK33 = 0000000050600000B,
*   MASK34 = 0000000077000000B, MASK35 = 0000077000000000B)
CON(MASK36 = 7700000000000000B, MASK37 = 0000077777777777B,
*   MASK38 = 7777777007777777B, MASK39 = 0000077007777777B)
CON(MASK40 = 0100000000000000B)

```

* PROGRAM NAMES

```

CON(P0 = 6265677145000000B, P1 = 7145236347230000B,
*   P2 = 4361244563700000B, P3 = 7071222346513000B,
*   P4 = 6551514651000000B, P5 = 7046436400000000B,
*   P6 = 2242714700000000B, P7 = 6471224743613000B,
*   P8 = 6451464700000000B, P9 = 4546232024226564B,
*   P10 = 2223464700000000B, P11 = 2223656551000000B,
*   P12 = 6465227167000000B, P13 = 7145664600000000B,
*   P14 = 4546232024226564B, P15 = 6751614770000000B,
*   P16 = 2223612371464500B, P17 = 6370614567650000B,
*   P18 = 2223612365000000B, P19 = 4546232024226564B)
CON(P20 = 5165616430204323B, P21 = 6661646500000000B,
*   P22 = 2445666164650000B, P23 = 2223615123000000B,
*   P24 = 2263512462000000B, P25 = 4746512300000000B,
*   P26 = 2223626400000000B, P27 = 2247656564000000B,
*   P28 = 6143237123246465B, P29 = 4546232024226564B)

```

* BCD MESSAGE CODE TABLE

```

CON(E0 =4751466751614420B, E1 =4546232063614343B,
*   E2 =6564000000000000B, E3 =2346462044614530B,
*   E4 =2061516724446545B, E5 =2322000000000000B,
*   E6 =0245642061516724B, E7 =4465452320714343B,
*   E8 =6567614373000000B, E9 =0000202351616342B,
*   E10=2220244564655120B, E11=3046245120634645B,
*   E12=2351464373000000B, E13=2361516765232045B,
*   E14=4623207046464265B, E15=6400000000000000B)

```


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```

CON(E16=0000000000000000B,
* E18=4620714523655163B,
* E20=6543000000000000B,
* E22=2445616243654023B,
* E24=6547232040206144B,
* E26=0000000000000000B,
* E28=6500000000000000B,
* E30=4461306461307373B,
* E32=7373000000000000B,
* E34=6661447122706564B,
* CON(E36=0000000000000000B,
* E38=2371456720402024B,
* E40=2051652324514500B,
* E42=4746465120714523B,
* E44=2247436122702020B,
* E46=0000000000000000B,
* E48=2062466765302065B,
* CON(E50=4523516163422220B,
* E52=6370656342206461B,
* E54=6145642023513020B,
* CON(E56=4546206361472061B,
* E58=2023462062652043B,
* E60=0000000000000000B,
* E62=5162465145650000B,
* E64=2020454623204461B,
* E66=7145236551636547B,
* CON(E68=6751614770206265B,
* E70=2365647300000000B,
* E72=4571227073000000B,
* E74=5144612371464500B,
* E76=2351616342204551B,
* E78=2020202020202020B,
* E80=0000000000000000B,
* E82=0000000000000000B,
* CON(E84=2223612365205165B,
* E86=0000000000000000B,
E17=2445616243652023B,
E19=6547232040206624B,
E21=0000000000000000B,
E23=4620714523655163B,
E25=4460000000000000B,
E27=4346262022236123B,
E29=0000000000000000B,
E31=7344613064613073B,
E33=0000000000000000B,
E35=0000000000000000B,
E37=7145226551636547B,
E39=4561624365202346B,
E41=0000000000000000B,
E43=6551636547230000B,
E45=2062466765302065B,
E47=7065616422202447B,
E49=0000000000000000B,
E51=3720010620202020B,
E53=2361206465634220B,
E55=6167617145730000B,
E57=2561714361624365B,
E59=6124456370656400B,
E61=2020454623206171B,
E63=0000000000000000B,
E65=4271456720614520B,
E67=2373000000000000B,
E69=7145672047434623B,
E71=6751614770206671B,
E73=2020202071456646B,
E75=2020202020202020B,
E77=0000000000000000B,
E79=0000000000000000B,
E81=0000000000000000B,
E83=0*0000000000000000B,
E85=4746512320464520B,
E87=2020206144444620B,

```


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```
* E88=00000000000000000000B,  
* E89=4627306765452047B,  
* E90=4324222021206624B,  
* E91=00000000000000000000B,  
* E92=2047462445642220B,  
* E93=2120237144652020B,  
* E94=00000000000000000000B)  
CON(E95=4626452022707147B,  
* E96=5161456765152020B,  
* E97=2030615164220000B,  
* E98=6265615171456715B,  
* E99=2064656751656522B,  
* E100=6651464420462645B,  
* E101=2022707147000000B,  
* E102=6651464420236122B,  
* E103=4266465163652063B,  
* E104=6545236551000000B,  
* E105=20447143652200000B)
```

* GRAPH TITLES

```
CON(TITLE = 0)  
CON(TITLE1 = 2271442046456520B, TITLE2 = 2020202020614323B,  
* TITLE3 = 7123246465202522B, TITLE4 = 7320237144652020B,  
* TITLE5 = 20202020202020B, TITLE6 = 20202020202020B,  
* TITLE7 = 0000000000000000B, TITLE8 = 2023714465202020B,  
* TITLE9 = 0000000000000000B, TITLE10 = 0000000000000000B,  
* TITLE11 = 4524236522202020B, TITLE12 = 2020202020202020B)  
CON(KTITLE = 0)
```

```
CON(TITLE13 = 2271442046456520B, TITLE14 = 2020202020274030B,  
* TITLE15 = 2047462271237146B, TITLE16 = 4520474346232020B,  
* TITLE17 = 20202020202020B, TITLE18 = 20202020202020B,  
* TITLE19 = 0000000000000000B, TITLE20 = 2023714465202020B,  
* TITLE21 = 0000000000000000B, TITLE22 = 0000000000000000B,  
* TITLE23 = 4524236522202020B, TITLE24 = 2020202020202020B)
```

* PTABLE

```
CON(PTABLE = 0, P1 = 48, P2 = 24, P3 = 12, P4 = 8, P5 = 6, P6 = 4,  
* P7 = 3, P8 = 2, P9 = 1)
```

* TIMING CONSTANTS FOR DISPLAY AND READBACK

```
CON(PP0 = 0000000000000000B, PP1 = 4000000000000000B,
```


* PP2 = 4000000040000000B, PP3 = 4000400040004000B,
 * PP4 = 4010020040100200B, PP5 = 4040404040404040B,
 * PP6 = 4210421042104210B, PP7 = 4444444444444444B,
 * PP8 = 5252525252525252B, PP9 = 7777777777777777B)

* AIRCRAFT CONTROL CONSTANTS

CON(LHEAD1 = 4020000000000000B, LHEAD2 = 404000000000000036B,
 * LHEAD3 = 40600000000024000B, LHEAD4 = 410000000000000012B,
 * LHEAD5 = 40400000003000017B, LHEAD6 = 472000000000000036B,
 * LHEAD7 = 4060000120024000B, LHEAD8 = 420000000000000000B,
 * LHEAD9 = 41000001700000012B)

* INITIAL INTERCEPTOR INFORMATION

CON(IFIG0 = 0000000000000000B, IFIG1 = 0000000000000000B,
 * IFIG2 = 2064002317404301B, IFIG3 = 2064004317404301B,
 * IFIG4 = 3260440437644300B, IFIG5 = 3260444437644300B,
 * IFIG6 = 3506440437644300B, IFIG7 = 3506444437644300B)

* SECOND WORD INTERCEPTOR INFORMATION

CON(FIG = 0.00, FIG1 = 0.00, FIG2 = 0.67, FIG3 = 0.67,
 * FIG4 = 1.18, FIG5 = 1.15, FIG6 = 1.15, FIG7 = 1.30)

* MANEUVER CODE TABLE

CON(MAN1 = 05B, MAN2 = 06B, MAN3 = 01B, MAN4 = 10B, MAN5 = -2B,
 * MAN6 = 02B, MAN7 = 04B, MAN8 = 03B)

* BUTTON TABLE

CON(T0 = 01B, T1 = 02B, T2 = 03B, T3 = 04B, T4 = 05B,
 * T5 = 11B, T6 = 12B, T7 = 13B, T8 = 14B, T9 = 15B,
 * T10 = 21B, T11 = 22B, T12 = 23B, T13 = 24B, T14 = 25B,
 * T15 = 31B, T16 = 32B, T17 = 33B, T18 = 34B, T19 = 35B,

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* T20 = 41B, T21 = 42B, T22 = 43B, T23 = 44B, T24 = 45B,
 * T25 = 51B, T26 = 52B, T27 = 53B, T28 = 54B, T29 = 55B)

* LIGHT TABLE

CON(LT0 = 77202B, LT1 = 77204B, LT2 = 77210B, LT3 = 77220B,
 * LT4 = 77240B, LT5 = 77302B, LT6 = 77304B, LT7 = 77310B,
 * LT8 = 77320B, LT9 = 77340B, LT10 = 77402B, LT11 = 77404B,
 * LT12 = 77410B, LT13 = 77420B, LT14 = 77440B, LT15 = 77502B,
 * LT16 = 77504B, LT17 = 77510B, LT18 = 77520B, LT19 = 77540B,
 * LT20 = 77602B, LT21 = 77604B, LT22 = 77610B, LT23 = 77620B,
 * LT24 = 77640B, LT25 = 77702B, LT26 = 77704B, LT27 = 77710B,
 * LT28 = 77720B, LT29 = 77740B)

* TURN OFF LIGHT CONSTANTS

CON(OFF0 = 77203B, OFF1 = 77205B, OFF2 = 77211B, OFF3 = 77221B,
 * OFF4 = 77241B, OFF5 = 77303B, OFF6 = 77305B, OFF7 = 77311B,
 * OFF8 = 77321B, OFF9 = 77341B, OFF10 = 77403B, OFF11 = 77405B,
 * OFF12 = 77411B, OFF13 = 77421B, OFF14 = 77441B, OFF15 = 77503B,
 * OFF16 = 77505B, OFF17 = 77511B, OFF18 = 77521B, OFF19 = 77541B,
 * OFF20 = 77603B, OFF21 = 77605B, OFF22 = 77611B, OFF23 = 77621B,
 * OFF24 = 77641B, OFF25 = 77703B, OFF26 = 77705B, OFF27 = 77711B,
 * OFF28 = 77721B, OFF29 = 77741B)

* OCTAL TO BCD CONVERSION FOR NUMBERS 0-15

CON(OB0 = 4546B, OB1 = 1201B, OB2 = 1202B, OB3 = 1203B,
 * OB4 = 1204B, OB5 = 1205B, OB6 = 1206B, OB7 = 1207B,
 * OB8 = 1210B, OB9 = 1211B, OB10 = 0112B, OB11 = 0101B,
 * OB12 = 0102B, OB13 = 0103B, OB14 = 0104B, OB15 = 0105B)

* ASSORTED CONSTANTS

CON(R0 = 01, R1 = 10, R2 = 100, R2A = 1000, R2B = 10000,
 * R2C = 100000, R2D = 1000000, R3 = 0000007300204020B,

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```

* R4 = 0000007300204471B, R5 = 434127000000000000B,
* R6 = 7777777777777757B, R7 = 43310200000000013B,
* R8 = 000227440000000000B, R9 = 0033206143232020B,
* R10= 000000005300000000B, R11= 6246676530202065B,
* R12= 6651716545644330B, R13= 2022224520070600B,
* R14= 0023206465472370B, R15= 007300000000000000B,
* R16= 022204252200000000B, R17= 6746624271452000B,
* R18= 2064436745201000B, R19= 4546454064652271B)
CON(R20= 6745612365647300B, R21= 4471452422202120B,
R22= 3165514620202120B, R23= 4743242220202120B,
R24= 452300000000000000B, R25= 0000 0011530000B)
CON(R26= 031027450000000000B, R27= 202012001200000000B)
CON(RH0 = 0., RH1 = 64., RH2 = 32., RH3 = 16., RH4 = 8., RH5 = 4.,
RH6 = 2., RH7 = 1.)
CON(PIP = 3000350000005000B, CLK = 3777777777777704B)
CON(CLK5 = 3777777777777742B)
CON(ERASE = 000000000041000B, ERASE1 = 0000000017101000B)
CON(ERASE2 = 0000000014405000B)
CON(XIP = -377B, YIP = -377B)
CON(ALPHA=.085,BETA=.009)
CON(AXIS = 450., RADIAN5 = 0.01745)
CON(ZERO = 0.0, EIGHT = 8.0)
CON(BUTTONS = 30)
CON(ZTIME= 1800)

```

I RET SLJ (N) SLJ (OT) . EXIT/ENTRY 00000

* FORMATS USED IN PROGRAM

```

1 FORMAT(4A8) 00001
100 FORMAT(6A8) 00002
101 FORMAT(A4,IX,E6.0,IX,E6.0,IX,I2,IX,I1,IX,I1,IX,I1,IX,I2,IX,
* I1,IX) 00003
102 FORMAT(A8) 00004
103 FORMAT(F10.0) 00005
104 FORMAT(I2,2X,I6) 00006

```


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200 FORMAT(17H1 DUTY CYCLE = F7.5, 16H FOR THIS RUN.) 00007

* INTERRUPT ROUTINE

1A	EXF 7 (00131B)	SLJ (0A)	• TIME ADVANCE	00010
	EXF 7 (77173B)	SLJ (2A)	• KBD 1 INTER ROUTINE	00011
	EXF 7 (77174B)	SLJ (4A)	• KBD 2 INTER ROUTINE	00012
1AA	EXF (00070B)	EXF (77111B)	• CLEAR BOTH ARITHMETIC AND	00013
	SLJ (Z+7B)	ZRO (0)	• DD65 INTERRUPTS	00014

* TIME ADVANCE ROUTINE

0A	EXF (00070B)	STA (ASAVE)	• CLEAR FAULT	00015
	SSK (Z)	SLJ (Z+7B)	• SENSE ZERO OVERFLOW	00016
	LDA (CLK)	STA (Z)	• RESET ONE-SECOND COUNT	00017
	SLJ 5 (L+4)	ENI (0)	• DOUBLE TIME ROUTINE	00020
	RAO (Z+50B)	EXF (77105B)	• INCREMENT TIME AT 50	00021
	EXF (77103B)	LDA (ASAVE)	• SELECT INTERRUPTS	00022
	SLJ (Z+7B)	ZRO (0)	• EXIT THROUGH 7	00023
	SLJ (N)	LDA (CLK5)	• RESET ONE HALF SECONUD COUNT	00024
	STA (Z)	SLJ (L-1)	•	00025

* KEYBOARD PROCESSOR

2A	SIU 4 (3A)	NUMBER 1	• SAVE INDEX B4	00026
	STQ (QSAVE)	STA (ASAVE)	• SAVE A AND Q REGISTERS	00027
	EXF (77140B)	LIL 4 (KNR1)	• B4 = KNR1 SELECT KBD1	00030
	LIL 4 (KNR1)	EXF 7 (77140B)	• B4 = KNR1 SELECT KBD1	00031
	INT (BUF1)	EXF (77140B)	• INPUT CHARACTER	00032
	EQS (74B)	LDA (BUF1)	• CHECK FOR CLOSING PAREN	00033
	SLJ (11A)	SLJ (L+2)	• YES JUMP TO PRINT ROUTINE	00034
	EQS (73B)	ZRO (0)	• CHECK FOR PERIOD	00035
	SLJ (11A)	SLJ (L+2)	• YES JUMP TO PRINT ROUTINE	00036
	EQS (76B)	ZRO (0)	• CHECK FOR CR	00037
	SLJ (9A)	SLJ (L+2)	• YES JUMP TO 9A	00040
	EQS (36B)	ZRO (0)	• CHECK FOR TAB	00041
	SLJ (10A)	SLJ (L+2)	• YES JUMP TO 10A	00042

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3A STA 4 (BUF1) RAO (KNR1) INCREASE POINTER 00043
 ENI 4 (N) EXF (77001B) RESTORE B4 DESELECT 00044
 LDA (ASAVE) LDQ (QSAVE) RESTORE A AND Q REGISTERS 00045
 EXF (77111B) SLJ (Z+7B) EXIT THRU CELL 7 00046

* KEYBOARD PROCESSOR NUMBER 2

4A SIU 3 (6A) SIL 4 (6A) SAVE INDESES 00047
 SIU 5 (7A) SIL 6 (7A) 3, 4, 5, 6 00050
 STA (ASAVE) STQ (QSAVE) SAVE A AND Q REGISTERS 00051
 LDA (PFLAG) AJP 1 (8A) CHECK P-FLAG 00052
 LDQ (MASK11) EXF (77120B) SELECT KBD2 00053
 INT (KBD2WD) LDL (KBD2WD) INPUT 00054
 STA (KBD2WD) LIL 3 (BUTTONS) WHICH BUTTON HIT 00055
 EQS 3 (T0) SLJ (6A) TURN ON CORRECT LT 00056
 LDA 3 (LT0) SAU (L+1) 00057
 EXF (N) LDA 3 (OTAB) 00060
 SAU (5A) ARS (24) 00061
 STA (T+1) LIL 5 (T+1) STORE NUMBER OF LETTERS 00062
 LIL 6 (KNR1) LDA (KNR1) IN THE NAME 00063
 INA 5 (0) STA (KNR1) INCREASES KNR1 BY NR LETTERS 00064
 LDA (N) ENI (0) 00065
 ENQ (0) LLS (6) TRANSFER WORD TO BUF1 00066
 STQ 6 (BUF1) INI 6 (1) 00067
 IJP 5 (L-2) ENI (0) LOOP 00070
 ENI 3 (N) ENI 4 (N) RESTORE INDEXES 00071
 ENI 5 (N) ENI 6 (N) 3, 4, 5, 6 00072
 LDA (ASAVE) LDQ (QSAVE) DESELECT AND CLEAR 00073
 EXF (77001B) EXF (77111B) EXIT THRU CELL 7 00074
 SLJ (Z+7B) ZRO (0) INPUT 00075
 EXF (77120B) INT (KBD2WD) MASK MATRIX CODE 00076
 LDQ (MASK11) LDL (KBD2WD) CHECK FOR PAUSE 00077
 EQS (F11) SLJ (6A) 00100
 ENA (0) STA (PFLAG) RESET P-FLAG 00101
 SLJ (6A) ZRO (0) RETURN 00102

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* ERASE ON CARRIAGE RETURN

9A	ENA	(1)	STA	(KNR1)	•	RESET POINTERS	00103
	EXF	(77241B)	LIL	4 (BUTTONS)	•	TURN OFF ERROR LT	00104
	LDA	4 (OFFO)	SAU	(L+1)	•		00105
	EXF	(N)	IJP	4 (L-1)	•	TURN OFF ALL LTS	00106
	ENA	(0)	ENI	4 (120)	•	ZERO OUT BUFFER	00107
	STA	4 (BUF1)	IJP	4 (L)	•		00110
	EXF	(02000B)	EXF	(04001B)	•	STOP RT CLOCK AND DISALLOW	00111
	ENI	4 (484)	ENI	(0)	•	ERRASE DD65 MEMORY	00112
	EXF	(77010B)	OUT	(ERASE1)	•	FROM ADDRESS	00113
	EXF	(77010B)	OUT	(S6C)	•	484 TO 510	00114
	ISK	4 (510)	SLJ	(L-1)	•	LOOP	00115
	EXF	(04000B)	EXF	(01000B)	•	ALLOW AND START RT CLOCK	00116
	SLJ	(3A)	ZRO	(0)	•	RETURN	00117

* ERASE ON TAB

10A	ENA	(353B)	STA	(YMSG)	•	RESET LINE	00120
	ENA	(400)	STA	(ADD)	•	RESET MSG ADDRESS IN DD65	00121
	ENI	4 (400)	ENI	(0)	•		00122
	EXF	(02000B)	EXF	(04001B)	•	STOP RT CLOCK AND DISALLOW	00123
	EXF	(77010B)	EXF	7 (77010B)	•	ERRASE DD65 MEMORY	00124
	OUT	(ERASE2)	ENI	(0)	•	FROM ADDRESS	00125
	EXF	(77010B)	OUT	(S6C)	•	400 TO 482	00126
	ISK	4 (482)	SLJ	(L-1)	•	LOOP	00127
	EXF	(04000B)	EXF	(01000B)	•	ALLOW AND START RT CLOCK	00130
	SLJ	(3A)	ZRO	(0)	•	RETURN	00131

* PRINT ROUTINE FOR BUFFER

11A	STA	4 (BUF1)	RAO	(KNR1)	•	STORE CLOSING PAREN. OR PERIOD	00132
	SIU	2 (15A)	SIL	3 (15A)	•	SAVE NEEDED INDEXES	00133
	SIU	5 (16A)	SIL	6 (16A)	•	2, 3, 4, 5, 6	00134
	SIU	4 (L+5)	SIL	4 (13A)	•		00135
	ENI	3 (1)	ENI	2 (0)	•	ASSEMBLE MESSAGE FOR PRINT	00136

APPENDIX I-C

ENG	(0)	STQ	(T+1)	00137
LDA	(T+1)	ENI	5 (1)	00140
ALS	(6)	ADD	3 (BUF1)	00141
ISK	3 (N)	SLJ	(L+2)	00142
SLJ	(L+4)	ZRO	(0)	00143
ISK	5 (8)	SLJ	(L-3)	00144
STA	2 (D)	INI	2 (1)	00145
SLJ	(L-6)	ZRO	(0)	00146
ISK	5 (8)	SLJ	(L+2)	00147
STA	2 (D)	SLJ	(L+2)	00150
ALS	(6)	SLJ	(L-2)	00151
ENA	(XP1)	SAL	(PRINT+1)	00152
ENA	(YP1)	SAL	(PRINT+2)	00153
LIL	5 (PRINT+4)	SIL	5 (T+1)	00154
LIL	5 (PRO)	SIL	5 (PRINT+3)	00155
ENI	5 (484)	SIL	5 (PRINT+4)	00156
ENA	(D)	ENI	(0)	00157
ENQ	(OB)	SLJ	4 (PRINT)	00160
LIL	5 (T+1)	SIL	5 (PRINT+4)	00161
ENA	(0)	STA	2 (D)	00162
IJP	2 (L-1)	ENI	4 (N)	00163
ENI	2 (N)	ENI	3 (N)	00164
ENI	5 (N)	ENI	6 (N)	00165
SLJ	(3A)	ZRO	(0)	00166

• CHECK FOR END OF LETTERS
 • CHECK FOR 8 CHARACTERS
 • STORE WORD IN D ARRAY
 • LOOP
 • CHECK FOR POSITION OF LAST WORD
 • POSITON LAST WORD
 • SET UP ARGUMENTS FOR PRINT
 • JUMP TO PRINT
 • RESTORE MEMOY ADDRESS IN PRINT
 • ERASE D ARRAY
 • LOOP
 • RESTORE INDEXES
 • 2, 3, 4, 5, 6
 • RETURN THRU CELL 7

* ABSOLUTE VALUE ROUTINE

IABS	SLJ	(N)	SLJ	(L+2)	00167
2ABS	ZRO	(0)	ZRO	(0)	00170
	LDA	7 (2ABS)	AJP	2 (IABS)	00171
	LAC	7 (2ABS)	SLJ	(IABS)	00172
	LDL	(MASK24)	AJP	(L+3)	00173
	LDA	1 (TRACK)	SST	(MASK20)	00174
	SCL	(MASK24)	STA	1 (TRACK)	00175
	LDO	2 (TRACK)	LDL	(MASK10)	00176
	STA	2 (TRACK)	ENA	(34B)	00177

• EXIT/ENTRY
 • ARGUMENT
 • A POSITIVE RETURN
 • COMPLEMENT RETURN
 • CAP HAS ASSIGNED STATION, SET STATION BIT, CLEAR ORBIT BIT
 • REDESIGNATE AS UNENGAGED

APPENDIX I-C

```

RAD 2 (TRACK)
LDQ 1 (TRACK)
STA 1 (TRACK)
RAD 1 (TRACK)
AJP (L+1)
LDA 1 (TRACK)
SLJ (3IE)
ENI (0)
LDL (MASK10)
ENA (30B)
LDL (MASK20)
SLJ (1IS)
SST (MASK24)
ZRO (0)
BOGIE
REDESIGNATE AS
UNENGAGED CAP
RETURN TO STATION
SET ORBIT BIT, NO
STATION ASSIGNED
00200
00201
00202
00203
00204
00205
00206

```

* CHANGE ROUTINE

```

1C SLJ (L+8)
2C ZRO (0)
3C ZRO (0)
4C ZRO (0)
5C ZRO (0)
6C ZRO (0)
7C ZRO (0)
8C ZRO (0)
LDA (2C)
LDA (3C)
EQS 4 (P21)
LDA 4 (OFF21)
EXF (N)
LDA 4 (MAN1)
LDA 4 (OZ10)
SLJ (N)
ENA (E6)
LDA (4C)
LDA (5C)
LDA (6C)
LDA (7C)
LDA (8C)
ENI 4 (6)
STA 4 (2C)
ENA (1)
SLJ 4 (TRAKGEN)
ENTRY
TRACK NUMBER
MANEUVER CALLED
3RD ARGUMENT
4TH ARGUMENT
5TH ARGUMENT
6TH ARGUMENT
7TH ARGUMENT
STORE TRACK NUMBER
SEARCH FOR MANEUVER
TURN OFF CHANGE AND MAN LTS
STORE MANCODE
SET ENTRY ADDRESS
JUMP TO PROPER ENTRY
ENTRY TO ERROR ROUTINE
STORE CRS
STORE SPD
STORE X POSIT
STORE Y POSIT
STORE Z POSIT
BEGIN EXIT ROUTINE
ZERO ALL ARGUMENTS
SET PERIOD FLAG
CALL TRAKGEN
00207
00210
00211
00212
00213
00214
00215
00216
00217
00220
00221
00222
00223
00224
00225
00226
00227
00230
00231
00232
00233
00234
00235
00236
00237
00240
9C
10C
11C

```


APPENDIX I-C

12C	SLJ (4T)	ZRO (0)	RETURN	00241
	LDA (4C)	STA (IDD65+4)	• STORE SPD	00242
	LDA (5C)	AJP (18C)	•	00243
	SLJ (16C)	ZRO (0)	•	00244
13C	LDA (4C)	STA (IDD65+3)	• STORE CRS	00245
	LDA (5C)	AJP (17C)	•	00246
	SLJ 4 (FLOAT)	ZRO (0)	• FLOAT RATE	00247
	FDV (10.)	STA (5C)	•	00250
14C	LDA (5C)	STA (IDD65+10)	• STORE RATE	00251
	SLJ (11C)	ZRO (0)	•	00252
15C	LDA (4C)	STA (IDD65+5)	• STORE ALTITUDE	00253
	LDA (5C)	AJP (19C)	•	00254
16C	LDA (5C)	SLJ 4 (FLOAT)	• FLOAT RATE	00255
	STA (5C)	SLJ (14C)	•	00256
17C	LDA (1.5)	STA (5C)	• SET STD RATE TURN	00257
	SLJ (14C)	ZRO (0)	•	00260
18C	LDA (10.)	STA (5C)	• SET STD SPEED RATE	00261
	SLJ (14C)	ZRO (0)	•	00262
19C	LDA (5000.)	STA (5C)	• SET STD CLIMB/DIVE RATE	00263
	SLJ (14C)	ZRO (0)	• STORE RATE	00264

* DATA DISPLAY ROUTINE

1D	EXF (77311B)	LAC (DFLAG)	• TURN OFF DISPALY LT	00265
	STA (DFLAG)	SLJ (4T)	• COMPLEMENT D-FLAG	00266

* ERROR MESSAGE ROUTINE

1E	SAL (2E)	SAU (6E)	•	00267
	EXF (77240B)	ENI 5 (1)	• TURN ON ERROR LT	00270
2E	ENI 4 (7)	LDQ (N)	• SET LETTER COUNT	00271
	ENA (0)	ENI (0)	• ZERO ACCUMLATOR	00272
3E	LLS (6)	QJP (5E)	• ASSEMBLE ERROR MSG	00273
	IJP 4 (L-1)	ENI (0)	• END WORD CHECK	00274
	ISK 5 (4)	SLJ (2E)	• CHECK WORD COUNT	00275
	SLJ (5E1)	ZRO (0)	•	00276

APPENDIX I-C

4E	LDA (T+9)	INI 4 (-1)	•		00277
	ALS (6)	ADD (20B)	•	FILL OUT WORD WITH BLANKS	00300
	IJP 4 (L-1)	STA 5 (ERRMSG)	•	STORE WHEN FILLED	00301
	ISK 5 (4)	SLJ (4E1)	•	4-WORDS NO JUMP TO 4E1	00302
	SLJ (5E1)	ZRO (0)	•	YES - JUMP TO 5E1	00303
4E1	ENA (0)	ENI 4 (8)	•	SET INDEX + 1	00304
	STA (T+9)	SLJ (4E)	•		00305
5E	STA (T+9)	ENI (0)	•	STORE MESSAGE	00306
	SIL 4 (T+10)	LDA (T+10)	•	NATURAL END OF WORD	00307
	AJP 1 (4E)	LDA (T+9)	•	NO JUMP TO FILL OUT ROUTINE	00310
	STA 5 (ERRMSG)	RAO (2E)	•		00311
5E1	ISK 5 (4)	SLJ (2E)	•	4-WORDS NO JUMP TO 2E	00312
	ENA (1)	STA (KNR1)	•	SET POINTER TO 1	00313
6E	PRINT 1, ERRMSG		•		00314
	ENA (N)	STA (T+8)	•	DISPLAY MSG USING	00315
	ENA (XP1)	SAL (PRINT+1)	•	PRINT ROUTINE	00316
	ENA (YP2)	SAL (PRINT+2)	•		00317
	LDA (T+8)	LIL 5 (PRINT+4)	•		00320
	SIL 5 (T+6)	LIL 5 (PRO)	•		00321
	SIL 5 (PRINT+3)	ENI 5 (502)	•		00322
	SIL 5 (PRINT+4)	ENQ (0B)	•		00323
	SLJ 4 (PRINT)	ZRO (0)	•		00324
	LIL 5 (T+6)	SIL 5 (PRINT+4)	•	RESTORE ORIGINAL ADDRESS	00325
	SLJ (4T)	ZRO (0)	•	RETURN	00326
* EXIT PROGRAM					
IEND	EXF (77202B)	EXF (77302B)	•	X X X X	00327
	EXF (77402B)	EXF (77502B)	•	X	00330
	EXF (77204B)	EXF (77210B)	•	X	00331
	EXF (77310B)	EXF (77410B)	•	X X X X	00332
	EXF (77510B)	EXF (77520B)	•	X	00333
	EXF (77540B)	EXF (77440B)	•	X	00334
	EXF (77340B)	EXF (77240B)	•	X X X X	00335
	LDA (COUNTER)	SLJ 4 (FLOAT)	•	DUTY CYCLE CARD	00336
	ENI (0)	STA (COUNTER)	•	DUTY CYCLE CARD	00337

APPENDIX I-C

```

LDA (TIME)
STA (TIME)
FDV (PERIOD)
STA (TEMP)
FSB (TEMP)
FDV (TIME)
LDA (1.0)
STA (TEMP)
PRINT 200, TEMP
SLJ (IRET)
SLJ 4 (FLOAT)
ENI (0)
FMU (5.)
LDA (COUNTER)
FMU (797.2E-6)
STA (TEMP)
FSB (TEMP)
ENI (0)
ZRO (0)
DUTY CYCLE CARD
DUTY CYCLE CARD
DUTY CYCLE CARD
DUTY CYCLE CARD
DUTY CYCLE CARD
DUTY CYCLE CARD
DUTY CYCLE CARD
DUTY CYCLE CARD
DUTY CYCLE CARD
DUTY CYCLE CARD
EXIT MAIN PROGRAM
00340
00341
00342
00343
00344
00345
00346
00347
00350
00351

```

* DISPLAY ROUTINE

```

1F
SIU 4 (10F1)
SIU 6 (11F)
ENA (2)
ENA (S6C)
SAL (PRINT+2)
SAL (PRINT+3)
ENA (S11)
ENI 4 (16)
LDA (MASK14)
MEQ 4 (IHEAD)
LDA 4 (TRACK)
LDA (MASK23)
MEQ (T+10)
LDQ (MASK13)
LDQ (MASK13)
SAL 4 (TRACK)
ENI 4 (16)
LDA (MASK40)
MEQ 4 (IHEAD)
LDQ 4 (TRACK)
EQS (52B)
SLJ (L+5)
STA 4 (F)
2F
SIL 5 (10F1)
SLJ 4 (1MER)
SAL (PRINT+4)
SAL (PRINT+1)
ENA (1)
ENQ (-0B)
SLJ 4 (PRINT)
LDQ (MASK13)
ENI 5 (0)
SLJ (L+7)
STA (T+10)
LDQ (MASK23)
SLJ (L+2)
SLJ (2F)
ENA (52B)
SLJ (2F)
LDQ (MASK40)
ENI (0)
SLJ (L+8)
LDL (77B)
SLJ (L+2)
ZRO (0)
LDQ (MASK40)
SAVE INDEXES
ERASE
TASK
FORCE
CENTER
SET SEARCH INDEX
MANCODE = 8
NO JUMP
YES CHECK LAUNCH BIT
LAUNCH BIT NOT SET
DESTROY TRACK WORD
SET INDEX FOR SEARCH
SET A FOR SEARCH
CHECK FOR FADE BIT
SAVE TRACK SYMBOL
PREVIOUS SYMBOL STORED
YES JUMP
00352
00353
00354
00355
00356
00357
00360
00361
00362
00363
00364
00365
00366
00367
00370
00371
00372
00373
00374
00375
00376
00377
00400

```


APPENDIX I-C

LDA 4 (TRACK)	SCL (MASK11)	•	CLEAR OLD SYMBOL	00401
ADD (52B)	STA 4 (TRACK)	•	SET SYMBOL TO NON ACTIVE	00402
SLJ (L-8)	ZRO (0)	•		00403
LDA (DFLAG)	AJP 3 (L+3)	•	CHECK TUBE FOR	00404
ENA (0)	STA (RAW)	•	DISPLAY OF RAW DATA	00405
SLJ (3F)	ZRO (0)	•		00406
ENA (1)	STA (RAW)	•		00407
3F ENI 4 (1)	ENI (0)	•	RAW DATA DISPLAY	00410
3FF ENQ (77B)	LDL 4 (TRACK)	•		00411
SUB (52B)	AJP (7F)	•		00412
LDL 4 (TRACK)	ENI (0)	•		00413
STA (T+3)	LIL 5 (T+3)	•		00414
ENA 4 (XN)	STA (XD)	•	SET DISPLAY ROUTINE	00415
ENA 4 (YN)	STA (YD)	•	ADDRESS	00416
ENI (0)	SLJ 4 (1F0)	•	LOAD X AND Y	00417
LDA 4 (XN)	AJP 3 (4F)	•	JUMP IF X NEG	00420
LDA 4 (YN)	AJP 3 (5F)	•	JUMP IF X POS Y NEG	00421
ENA (C360)	SLJ (L+5)	•	000 - 090	00422
4F LDA 4 (YN)	AJP 3 (6F)	•	JUMP IF X NEG Y NEG	00423
ENA (C270)	SLJ (L+3)	•	270 - 360	00424
ENA (C090)	SLJ (L+2)	•	090 - 180	00425
6F ENA (C180)	ENI (0)	•	180 - 270	00426
ENQ (-0B)	LIL 5 (RAW)	•		00427
SIL 5 (PRINT+3)	SLJ 4 (PRINT)	•	DISPLAY RAW DATA	00430
ENA 4 (XS)	STA (XD)	•	SET DISPLAY ROUTINE	00431
ENA 4 (YS)	STA (YD)	•	ADDRESS	00432
SLJ 4 (1F0)	ZRO (0)	•		00433
LIL 6 (PRINT+2)	SIL 6 (T+5)	•		00434
LIL 6 (PRINT+1)	SIL 6 (T+4)	•		00435
LDA (PRO)	ENQ (-0B)	•		00436
SAL (PRINT+3)	LIL 5 (T+3)	•		00437
ENA 5 (S1)	SLJ 4 (PRINT)	•	PRINT SYMBOLS	00440
LIL 6 (T+4)	SIL 6 (PRINT+1)	•		00441
LIL 6 (T+5)	SIL 6 (PRINT+2)	•		00442
LDA (PRO)	SAL (PRINT+3)	•		00443
ENA (S11C)	ENQ (0B)	•		00444

APPENDIX I-C

7F	SLJ 4 (PRINT)	ZRO (0)	•	PRINT PERIODS	00445
10F	ISK 4 (15)	SLJ (3FF)	•	LOOP	00446
12F	LDA (HIS1)	AJP 1 (13F)	•	HIS1 TO BE PRINTED YES JUMP	00447
13F	LDA (HIS2)	AJP 1 (15F)	•	HIS2 TO BE PRINTED YES JUMP	00450
14F	SLJ (10F1)	ZRO (0)	•	RETURN	00451
	ENI 4 (N)	ENI (0)	•	DISPLAY HIS1	00452
	ENA 4 (XHIS1)	STA (XD)	•	SET DISPLAY ROUTINE	00453
	ENA 4 (YHIS1)	STA (YD)	•	ADDRESS	00454
	SLJ 4 (1F0)	ZRO (0)	•		00455
	LDA (PRO)	SAL (PRINT+3)	•		00456
	ENA (S11C)	ENQ (0B)	•		00457
14F1	SLJ 4 (PRINT)	ZRO (0)	•	LOOP	00460
15F	IJP 4 (14F)	SLJ (12F)	•	DISPLAY HIS2	00461
16F	ENI 4 (N)	ENI (0)	•	SET DISPLAY ROUTINE	00462
	ENA 4 (XHIS2)	STA (XD)	•	ADDRESS	00463
	ENA 4 (YHIS2)	STA (YD)	•		00464
	SLJ 4 (1F0)	ZRO (0)	•		00465
	LDA (PRO)	SAL (PRINT+3)	•		00466
	ENA (S11C)	ENQ (0B)	•		00467
	SLJ 4 (PRINT)	ZRO (0)	•	LOOP	00470
16F1	IJP 4 (16F)	SLJ (10F1)	•	RETURN	00471
10F1	ENI 4 (N)	ENI 5 (N)	•		00472
11F	ENI 6 (N)	SLJ (4T)	•		00473

* LOAD X AND Y ROUTINE

1F0	SLJ (N)	LDA 7 (XD)	•	EXIT/ENTRY	00474
	FMU (RHO)	SLJ 4 (FIX)	•	SCALE X	00475
	STA (XD)	ENA (XD)	•		00476
	SAL (2ABS)	SLJ 4 (1ABS)	•	CHECK X FOR MAX	00477
	THS (250)	SLJ (7F)	•		00500
	ENA (XD)	SAL (PRINT+1)	•	SCALE Y	00501
	LDA 7 (YD)	FMU (RHO)	•		00502
	SLJ 4 (FIX)	ZRO (0)	•		00503
	STA (YD)	ENA (YD)	•		00504
	SAL (2ABS)	SLJ 4 (1ABS)	•		00505

APPENDIX I-C

THS (250) SLJ (7F) • CHECK Y FOR MAX 00506
 ENA (YD) SAL (PRINT+2) • • 00507
 SLJ (1F0) ZRO (0) • RETURN 00510

* RADAR PROCESSOR ROUTINE

1G SIL 2 (8G) SIU 3 (9G) • SAVE INDEXES 00511
 SIL 4 (9G) SIU 5 (10G) • 2,3,4,5 00512
 LDA (KTIME) SUB (KTIME+1) • DETERMINE PERIOD 00513
 STA (IP) SLJ 4 (FLOAT) • FLOAT PERIOD 00514
 STA (PERIOD) FDV (3600.) • 00515
 STA (PERIOD2) ENI 4 (1) • SET TRACK INDEX 00516
 2G ENQ (77B) LDL 4 (TRACK) • PUT TRACK DESIGNATION IN A 00517
 EQS (F60) SLJ (3G) • 00520
 3G SLJ (11G) ZRO (0) • NON DESIGNATED TRACK JUMP 00521
 ENA (0) STA (J1) • CLEAR J1 00522
 SIL 4 (J1) LDA 4 (XN) • 00523
 FSB 4 (XP) FMU (BETA) • 00524
 FDV (PERIOD2) FAD 4 (VXS) • VXS = VXS(N-1) 00525
 STA 4 (VXS) LDA 4 (XN) • + BETA*(XN-XP)/PERIOD2 00526
 FSB 4 (XP) FMU (ALPHA) • XS = XP + ALPHA*(XN-XP) 00527
 FAD 4 (XP) STA 4 (XS) • 00530
 LDA 4 (VXS) FMU (PERIOD2) • XP = XS + PERIOD2*VXS 00531
 FAD 4 (XS) STA 4 (XP) • 00532
 LDA 4 (YN) FSB 4 (YP) • 00533
 FMU (BETA) FDV (PERIOD2) • VYS = VYS(N-1) 00534
 FAD 4 (VYS) STA 4 (VYS) • + BETA*(YN-YP)/PERIOD2 00535
 LDA 4 (YN) FSB 4 (YP) • 00536
 FMU (ALPHA) FAD 4 (YP) • YS = YP + ALPHA*(YN-YP) 00537
 STA 4 (YS) LDA 4 (VYS) • 00540
 FMU (PERIOD2) FAD 4 (YS) • YP = YS + PERIOD2*VYS 00541
 STA 4 (YP) ENA 4 (VXS) • 00542
 SAL (COURSE+1) ENA 4 (VYS) • DETERMINE 00543
 SAL (COURSE+2) ENA 4 (CRS) • COURSE IN DEGREES TRUE 00544
 SAL (COURSE+3) ENA 4 (SPD) • SPEED IN MACH NUMBER 00545
 SAL (COURSE+6) ENA 4 (MACH) • 00546

APPENDIX I-C

	SAL	(COURSE+4)	ENA	4	(ZN)	•	M = SPD(KNTS)/(661-2.5*ALT)	00547
	SAL	(COURSE+5)	SLJ	4	(COURSE)	•		00550
	LDA	(ZN)	STA	4	(ZS)	•	STORE Z DATA	00551
	STA	(ZP)	LDA		(J1)	•		00552
	EQS	(HIS1)	SLJ		(5G)	•	HIS1 TO BE UPDATED NO JUMP	00553
	SSH	(PPMC1)	SLJ		(7G)	•		00554
4G	ENI	(24)	INI	2	(-1)	•	UPDATE HIS1	00555
	LDA	(XHIS1)	STA	2	(XHIS1+1)	•		00556
	LDA	(YHIS1)	STA	2	(YHIS1+1)	•		00557
	IJP	(L-2)	LDA	4	(XN)	•		00560
	STA	(YHIS1+1)	LDA	4	(YN)	•		00561
	STA	(YHIS1+1)	SLJ		(7G)	•		00562
5G	EQS	(HIS2)	SLJ		(7G)	•	HIS2 TO BE UPDATED NO JUMP	00563
	SSH	(PPMC2)	SLJ		(7G)	•		00564
6G	ENI	(24)	INI	2	(-1)	•	UPDATE HIS2	00565
	LDA	(XHIS2)	STA	2	(XHIS2+1)	•		00566
	LDA	(YHIS2)	STA	2	(YHIS2+1)	•		00567
	IJP	(L-2)	LDA	4	(XN)	•		00570
	STA	(XHIS2+1)	LDA	4	(YN)	•		00571
	STA	(YHIS2+1)	ENI		(0)	•	LOOP	00572
7G	ISK	(15)	SLJ		(2G)	•		00573
7G1	LDA	(KTIME)	SLJ		(L+1)	•		00574
	SUB	(IPP)	AJP	3	(L+9)	•		00575
7G11	ENA	(60)	RAD		(IPP)	•	INCREMENT IPP BY 60	00576
	LIL	(PPI)	ENI	4	(14)	•		00577
	LDA	(XS+1)	STA	3	(X1)	•	STORE X-SMOOTHED POINT	00600
	LDA	(YS+1)	STA	3	(Y1)	•	Y-SMOOTHED POINT	00601
	LDA	(XN+1)	STA	3	(X2)	•	X-ACTUAL POINT	00602
	LDA	(YN+1)	STA	3	(Y2)	•	Y-ACTUAL POINT	00603
	INI	(1)	IJP	4	(L-4)	•	LOOP	00604
	SIL	(PPI)	ENI		(0)	•		00605
7G2	ENI	(3)	ENI		(0)	•		00606
	LDA	(KTIME)	STA	4	(KTIME+1)	•		00607
8G	IJP	(L-1)	ENI	2	(N)	•	LOOP RESTORE INDEXES	00610
9G	ENI	(N)	ENI	4	(N)	•	RESTORE INDEXES	00611
10G	ENI	(N)	SLJ		(4T)	•	RETURN	00612

APPENDIX I-C

11G	LDA 4 (XN)	AJP 1 (L+2)	•	00613
	LDA 4 (YN)	AJP (7G)	•	00614
	LDA 4 (F)	AJP (L+4)	•	00615
	LDQ 4 (TRACK)	QRS (6)	•	00616
	QLS (6)	ADL (MASK10)	•	00617
	STA 4 (TRACK)	SLJ (14G)	•	00620
	LDA 4 (ZN)	AJP (12G)	•	00621
	AJP 3 (13G)	ENA (-36B)	•	00622
	RAD 4 (TRACK)	SLJ (14G)	•	00623
12G	ENA (-42B)	SLJ (L-1)	•	00624
13G	ENA (-46B)	SLJ (L-2)	•	00625
14G	LDA 4 (XN)	STA 4 (XS)	•	00626
	STA 4 (XP)	LDA 4 (YN)	•	00627
	STA 4 (YS)	STA 4 (YP)	•	00630
	ENA (0)	STA 4 (F)	•	00631
	SLJ (7G)	ZRO (0)	•	00632

• CHECK FOR PREVIOUS TRACK FADE
 • CLEAR OLD SYMBOL
 • RESTORE PREVIOUS SYMBOL
 • JUMP ACCORDING TO ALTITUDE
 • UNIDENTIFIED A/C
 • UNIDENTIFIED SURFACE
 • UNIDENTIFIED SUBMARINE
 • SET XP AND XS = XN
 • SET YP AND YS = YN
 • RESET F TO ZERO

* 10 MIN GRAPH ROUTINE

1GR	ENA (2GR)	SAU (3S)	•	00633
	SAU (8S)	EXF (2000B)	•	00634
	SLJ (1S)	ZRO (0)	•	00635
2GR	ENA (1END)	SAU (3S)	•	00636
	SAU (8S)	EXF (01000B)	•	00637
	REWIND MM		•	00640
	WRITE TAPE MM, XN, YN, JTIME		•	00641
	ENA (E71)	SLJ 4 (1MSG)	•	00642
	SLJ (4T)	ZRO (0)	•	00643
3GR	EXF (77503B)	SLJ (1GR)	•	00644

• CHANGE ADDRESSES
 • STOP THE REAL TIME CLOCK
 • JUMP TO STOP AND CRIT ROUTINE
 • SEND GRAPH FINISHED MSG
 • RETURN
 • TURN OFF GRAPH LT

* AIRCRAFT CONTROL ROUTINE

1INT	SIU 1 (1ISV)	SIL 2 (1ISV)	•	00645
	SIU 3 (2ISV)	SIL 4 (2ISV)	•	00646
	SIU 5 (3ISV)	SIL 6 (3ISV)	•	00647
	ENI 3 (1)	ENI 5 (0)	•	00650

• SAVE INDEX
 • REGISTERS
 • SET ARRAY COUNTERS

APPENDIX I-C

11	ISK 5 (15)	SLJ	(L+2)	•	CHECK FOR LOOP END	00651
	SLJ (2INT)	ZRO	(0)	•	JUMP IF TRACK1 ARRAY FINISHED	00652
	LDA 5 (TRACK1)	AJP	(2INT)	•	JUMP IF NO FRIENDLY AIRCRAFT	00653
	ENQ (0)	STQ	(ISFLAG)	•	SET FLAGS TO ZERO	00654
	STQ (ICFLAG)	STQ	(IPFLAG)	•		00655
	STQ (IEFLAG)	LLS	(6)	•		00656
	STQ (ICNR)	QLS	(36)	•	UNPACK CAP TRACK NUMBER	00657
	STQ (KCNR)	LIL 1 (ICNR)		•		00660
	LDQ 1 (TRACK)	LDL (MASK32)		•		00661
	ARS (24)	STA (JCNR)		•	UNPACK CAP NUMBER	00662
	LDL (MASK23)	AJP 1 (1IL)		•	JUMP TO LAUNCH CAP	00663
	LDL (MASK30)	ARS (39)		•		00664
	STA (ITYPE)	LIL 4 (ITYPE)		•	UNPACK A/C TYPE	00665
	LDA 4 (FIG)	STA (FLOW)		•	UNPACK FUEL RATE	00666
	FMU (PERIOD)	SLJ 4 (FIX)		•	COMPUTE FUEL CONSUMPTION	00667
	STA (T+2)	LDQ 1 (KFIG)		•	INCREMENT	00670
	ENA (0)	LLS (15)		•	FUEL ON BOARD	00671
	SUB (T+2)	AJP 3 (1IE)		•	JUMP IF FUEL EXHAUSTED	00672
	STA (T+11)	LRs (15)		•		00673
	STQ 1 (KFIG)	ENA 1 (XP)		•	STORE NEW FUEL QUANTITY	00674
	SAL (2ID)	ENA 1 (YP)		•	COMPUTE	00675
	SAL (3ID)	ENA (0)		•	RANGE	00676
	STA (T+2)	ENA (T+2)		•	FROM	00677
	SAL (4ID)	SAL (5ID)		•	CARRIER	00700
	SLJ 4 (1ID)	ZRO (0)		•		00701
	STA (DME)	ENI (0)		•		00702
	LDQ 4 (IFIG0)	LDL (MASK31)		•		00703
	ARS (21)	SLJ 4 (FLOAT)		•		00704
	STA (RECOVER)	LDQ 4 (IFIG0)		•		00705
	LDL (77700B)	ARS (6)		•		00706
	STA (ICRUISE)	SLJ 4 (FLOAT)		•		00707
	FDV (3600.)	STA (CRUISE)		•	UNPACK CRUISE SPEED	00710
	LDQ 4 (IFIG0)	LDL (MASK34)		•		00711
	ARS (15)	STA (LEVEL)		•	UNPACK CRUISE ALTITUDE	00712
	LDL (1B)	AJP 1 (L+3)		•		00713
	ENA (1800)	STA (INTSPD)		•	MAX SPEED+IS 1800 KNOTS	00714

SLJ	(L+2)	ZRO	(0)	•	MAX SPEED IS 1200 KNOTS	00715
ENA	(1200)	STA	(INTSPD)	•		00716
SLJ 4	(FLOAT)	ZRO	(0)	•		00717
STA	(SPDINT)	ENI	(0)	•		00720
LDA	(T+11)	SLJ 4	(FLOAT)	•		00721
STA	(FUEL)	LDA	(DME)	•	COMPUTE	00722
FDV	(CRUISE)	FMU	(FLOW)	•	STEER	00723
FAD	(RECOVER)	FSB	(FUEL)	•	STATE	00724
AJP 3	(2I)	LDQ 1	(TRACK2)	•	JUMP IF NOT LOW STATE	00725
LDL	(MASK19)	AJP 1	(2IE1)	•	JUMP IF MESSAGE ALREADY SENT	00726
SLJ	(2IE)	ZRO	(0)	•	SEND LOW STATE MESSAGE	00727
LDQ 1	(TRACK)	LDL	(MASK19)	•		00730
AJP 1	(1II)	ENI	(0)	•	JUMP TO INTERCEPT	00731
LDL	(MASK20)	AJP 1	(1IS)	•	JUMP TO STATION	00732
LDL	(MASK24)	AJP 1	(2IO)	•	JUMP TO ORBIT	00733
LDL	(MASK22)	AJP 1	(1IR)	•	JUMP TO STEER	00734
SLJ	(1I)	ZRO	(0)	•	END OF MAIN LOOP	00735

* EXIT FROM AIRCRAFT CONTROL ROUTINE

2INT	ENI 5 (1)	ENI 6 (1)	•	REARRANGE	00736
LDA 6	(TRACK1)	AJP 1 (L+3)	•	T TRACK1	00737
ISK 6	(15)	SLJ (L-1)	•	ARRAY	00740
SLJ	(L+3)	ZRO (0)	•		00741
STA 5	(TRACK1)	INI 5 (1)	•		00742
ISK 6	(15)	SLJ (L-4)	•		00743
SIL 5	(KNR2)	ENI (0)	•	SET TRACK1 POINTER	00744
ENI 1 (*)		ENI 2 (*)	•	RESTORE	00745
ENI 3 (*)		ENI 4 (*)	•	INDEX	00746
ENI 5 (*)		ENI 6 (*)	•	REGISTERS	00747
SLJ	(4T)	ZRO (0)	•	END AIRCRAFT CONTROL ROUTINE	00750

* COMPUTE SQUARE ROOT OF (A-C) SQUARED MINUS (B-D) SQUARED

1ID	SLJ (*)	SLJ (L+5)	•	00751
2ID	ZRO (0)	ZRO (0)	•	00752

3ID	ZRO	(0)	ZRO	(0)	B	00753
4ID	ZRO	(0)	ZRO	(0)	C	00754
5ID	ZRO	(0)	ZRO	(0)	D	00755
	LDA	7 (2ID)	FSB	7 (4ID)	A-C	00756
	STA	(T+7)	FMU	(T+7)	(A-C) SQUARED	00757
	STA	(T+7)	LDA	7 (3ID)		00760
	FSB	7 (5ID)	STA	(T+8)	R-D	00761
	FMU	(T+8)	FAD	(T+7)	(3-D) SQUARED + (A-C) SQUARED	00762
	STA	(T+7)	ENA	(T+7)		00763
	SAL	(SQ+1)	SLJ	4 (SQ)	TAKE SQUARE ROOT	00764
	SLJ	(1ID)	ZRO	(0)	RESULT IN A REGISTER	00765

* COIN FLIPPER

1IF	SLJ	(*)	LDW	(Z)	RETURN WITH A REGISTER	00768
	LDL	(1B)	AJP	1 (L-1)	+, HEADS	00769
	ENA	(-1)	SLJ	(L-2)	-, TAILS	00770

* DETERMINE SHORTEST DIRECTION OF TURN TO A GIVEN COURSE

1IT	SLJ	(*)	SLJ	(L+3)		00771
2IT	ZRO	(0)	ZRO	(0)	ORDERED COURSE	00772
3IT	ZRO	(0)	ZRO	(0)	PRESENT COURSE	00773
	LDW	7 (2IT)	FSB	7 (3IT)	THE SIGN OF A REGISTER	00774
	SLJ	4 (FIX)	ZRO	(0)	DETERMINES DIRECTION OF TURN	00775
	AJP	(1IT)	ENI	(0)		00776
	STA	(T+7)	ENA	(T+7)		00777
	SAL	(2ABS)	SLJ	4 (1ABS)	+ STANDBOARD TURN	01000
	SUB	(160)	AJP	2 (L+2)	- PORT TURN	01001
	LDA	(T+7)	SLJ	(1IT)	0 0 COURSE	01002
	LAC	(T+7)	SLJ	(1IT)		01003

* SEND MESSAGE TO DISPLAY UNIT

1IE	ENA	(E29)	SLJ	4 (10IE)	MAYDAY MESSAGE	01005
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APPENDIX I-C

LDA	(KCNR)	ADD	(LHEAD8)	•	01006
STA 3	(LHEAD)	ENI	(0)	•	01007
ENA	(0)	STA 5	(TRACK1)	•	01010
STA 5	(TRACK2)	ENI	(0)	•	01011
ENA	(52B)	STA 1	(TRACK)	•	01012
ISK 3	(60)	SLJ	(L+2)	•	01013
ENI 3	(60)	ENI	(0)	•	01014
SLJ	(11)	ZRO	(0)	•	01015
ENA	(E26)	SLJ 4	(10IE)	•	01016
LDA 1	(TRACK2)	SST	(MASK19)	•	01017
STA 1	(TRACK2)	ENI	(0)	•	01020
LDQ 1	(TRACK)	LDL	(MASK19)	•	01021
AJP 1	(11I)	LDA 1	(TRACK)	•	01022
SST	(MASK22)	STA 1	(TRACK)	•	01023
SLJ	(11R)	ZRO	(0)	•	01024
ENA	(E33)	SLJ 4	(10IE)	•	01025
SLJ	(11O)	ZRO	(0)	•	01026
ENA	(E16)	SLJ 4	(10IE)	•	01027
LDA 1	(TRACK)	SST	(MASK21)	•	01030
STA 1	(TRACK)	SLJ	(11I)	•	01031
ENA	(E21)	SLJ 4	(10IE)	•	01032
SLJ	(4I)	ZRO	(0)	•	01033
ENA	(E36)	SLJ 4	(10IE)	•	01034
LDA 1	(TRACK2)	SST	(MASK23)	•	01035
STA 1	(TRACK2)	SLJ	(31I)	•	01036
ENA	(E41)	SLJ 4	(10IE)	•	01037
SLJ	(11)	ZRO	(0)	•	01040
ENA	(E44)	SAL	(12IE)	•	01041
ENA	(E46)	SLJ 4	(11IE)	•	01042
SLJ	(4I)	ZRO	(0)	•	01043
ENA	(E47)	SAL	(12IE)	•	01044
ENA	(49)	SLJ 4	(11IE)	•	01045
SLJ	(5IE)	ZRO	(0)	•	01046
SLJ	(*)	STA	(T+11)	•	01047
LDA	(JCNR)	SLJ 4	(1NUM)	•	01050
ALS	(6)	ADD	(R5)	•	01051
2IE					
2IE1					
3IE					
4IE					
4I					
5IE					
6IE					
7IE					
8IE					
9IE					
10IE					

APPENDIX I-C

01052
01053
01054
01055
01056
01057
01060
01061
01062

STA 7 (T+11) .
SLJ 4 (1MSG) .
SLJ (10IE) .
SLJ (*) .
LDA (JBNR) .
ALS (39) .
STA 7 (T+11) .
SLJ 4 (1MSG) .
SLJ (11IE) .

LDA (T+11)
ZRO (0)
ZRO (0)
STA (T+11)
SLJ 4 (1NUM)
SCL (77B)
ENA (*)
ZRO (0)
ZRO (0)

* SKIP INTERCEPT

01063
01064
01065

111 LDL (MASK21) . JUMP TO INTERCEPT
LDA 1 (TRACK) . CLEAR INTERCEPT
STA 1 (TRACK) . AND SKIP BIT

AJP (2II)
SCL (MASK33)
LDQ 1 (TRACK)

* INTERCEPT ROUTINE

2II LDQ 1 (TRACK) . IF CAP HAS ASSIGNED STATION,
AJP (L+3) . SET ORBIT BIT AS A FLAG,
SST (MASK24) . CLEAR STATION BIT
STA 1 (TRACK)
LDQ 1 (KFIG)
ENA (0)
STA (SP)
LLS (3)
LDQ 5 (TRACK1)
ENA (0)
STA (IBNR)
ALS (36)
LDQ 2 (TRACK)
ARS (24)
LDA 2 (XP)
STA (XDIS)
FSB 1 (YP)
FMU (YDIS)

LDL (MASK20) .
LDA 1 (TRACK) .
SCL (MASK20) .
ENI (0) .
LLS (15) .
LLS (3) .
ENA (0) .
STA (SW) .
LLS (6) .
LLS (6) .
LIL 2 (IBNR) .
STA (KBNR) .
LDL (MASK32) .
STA (JBNR) .
FSB 1 (XP) .
LDA 2 (YP) .
STA (YDIS) .
STA (T+2) .

01066
01067
01070
01071
01072
01073
01074
01075
01076
01077
01100
01101
01102
01103
01104
01105
01106
01107

APPENDIX I-C

LDA	(XDIS)	FMU	(XDIS)	•	CAP	01110
FAD	(T+2)	STA	(T+2)	•		01111
ENA	(T+2)	SLJ 4	(SQ)	•		01112
STA	(BC)	ENI	(0)	•		01113
ENA	(XDIS)	SAL	(COURSE+1)	•	COMPUTE	01114
ENA	(YDIS)	SAL	(COURSE+2)	•	BEARING	01115
ENA	(CAPB)	SAL	(COURSE+3)	•	OF	01116
ENA	(0)	STA	(T+2)	•	BOGIE	01117
ENA	(T+2)	SAL	(COURSE+4)	•	FROM	01120
SAL	(COURSE+5)	SLJ 4	(COURSE)	•	CAP	01121
SLJ	(7I)	ZRO	(0)	•		01122

* DOES CAP HAVE ENOUGH FUEL FOR INTERCEPT

3II	SLJ	(*)	ENI	(0)	•	01123
	LDA	(YBI)	FMU	(YBI)	•	01124
	STA	(T+2)	LDA	(XBI)	•	01125
	FMU	(XBI)	FAD	(T+2)	•	01126
	STA	(T+2)	ENA	(T+2)	•	01127
	SAL	(SQ+1)	SLJ 4	(SQ)	•	01130
	STA	(T+2)	ENA	(XBI)	•	01131
	SAL	(2ID)	ENA	(YBI)	•	01132
	SAL	(3ID)	ENA 1	(XP)	•	01133
	SAL	(4ID)	ENA 1	(YP)	•	01134
	SAL	(5ID)	SLJ 4	(IID)	•	01135
	STA	(T+3)	FAD	(T+2)	•	01136
	FDV	(CRUISE)	FMU	(FLOW)	•	01137
	FAD	(600.)	FSB	(FUEL)	•	01140
	AJP 2	(L+1)	SLJ	(3II)	•	01141
	LDA	(T+3)	FDV	(CRUISE)	•	01142
	FMU	(FLOW)	FSB	(FUEL)	•	01143
	AJP 2	(4IE)	LDQ 1	(TRACK2)	•	01144
	LDL	(MASK23)	AJP 1	(3II)	•	01145
	SLJ	(6IE)	ZRO	(0)	•	01146
7I	LDQ 1	(TRACK)	LDL	(MASK25)	•	01147
	AJP 1	(IIC)	ENA	(I)	•	01150

• COMPUTE AMOUNT OF FUEL NEEDED
 • TO TRAVEL FROM PRESENT POSITION
 • TO COLLISION INTERCEPT POINT AND THEN TO CARRIER TO ARRIVE WITH 600 POUNDS OF FUEL
 • A JUMP IF SHORT OF FUEL
 • COMPUTE AMOUNT OF FUEL TO REACH BOGIE
 • JUMP IF UNABLE TO INTERCEPT
 • JUMP IF UNABLE TO RETURN
 • JUMP IF COLLISION INTERCEPT

APPENDIX I-C

STA	(ICFLAG)	LDL	(MASK26)	• SET INITIAL COLLISION FLAG	01151
AJP 1	(IIP)	ENA	(1)	•	01152
STA	(IPFLAG)	LDA	(SP)	• SET INITIAL PURSUIT FLAG	01153
AJP 1	(IIC)	ENI	(0)	• JUMP IF SPARROWS ON BOARD	01154
ENA	(1)	STA	(ISFLAG)	•	01155
SLJ	(6I)	ZRO	(0)	• JUMP IF NO SPARROWS	01156

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* COLLISION INTERCEPT

IIC	LDA	(BC)	FSB	(10•)	•	01157
AJP 2	(L+5)	ENA	(1)	• JUMP IF OUTSIDE KILL RANGE	•	01160
STA	(IEFLAG)	SLJ 4	(IIF)	• SET ENGAGED FLAG	•	01161
AJP 2	(L+2)	RSO	(SP)	• MISS WITH SPARROW	•	01162
AJP	(9I)	ENI	(0)	• JUMP IF NO SPARROWS	•	01163
RSO	(SP)	SLJ	(IIK)	• HIT WITH SPARROW	•	01164
LDA 2	(CRS)	FSB	(CAPB)	•	•	01165
STA	(T+2)	ENA	(T+2)	•	•	01166
SAL	(2ABS)	SLJ 4	(IABS)	•	•	01167
FMU	(.0174533)	STA	(ALFA)	•	•	01170
ENA	(ALFA)	ENI	(0)	•	•	01171
SAL	(COSF+1)	SLJ 4	(COSF)	•	•	01172
FMU	(BC)	STA	(BP)	•	•	01173
ENA	(ALFA)	SAL	(SINF+1)	•	•	01174
SLJ 4	(SINF)	ZRO	(0)	•	•	01175
FMU	(BC)	STA	(CP)	•	•	01176
LDA 1	(SPD)	FDV 2	(SPD)	•	•	01177
STA	(T+2)	FMU	(T+2)	•	•	01200
FSB	(1•)	STA	(T+2)	•	•	01201
LDA	(CP)	FDV	(BP)	•	•	01202
STA	(T+3)	FMU	(T+3)	•	•	01203
FAD	(1•)	FMU	(T+2)	•	•	01204
FAD	(1•)	STA	(ARG)	• CHECK IF CAP ACCELERATING	•	01205
AJP 2	(L+4)	LDA	(SPDINT)	•	•	01206
FSB	(10•)	FSB 1	(SPD)	•	•	01207
AJP 2	(L+3)	LDA 1	(TRACK)	• JUMP IF UNABLE TO INTERCEPT	•	01210
SCL	(MASK25)	STA 1	(TRACK)	• CLEAR COLLISION BIT	•	01211

APPENDIX I-C

SLJ	(6I)	ZRO	(0)	•	JUMP IF UNABLE TO INTERCEPT	01212
LDA 1	(TRACK)	SST	(MASK25)	•	SET COLLISION BIT	01213
STA 1	(TRACK)	SLJ	(1IP)	•	TEMPORARY PURSUIT INTERCEPT	01214
LDA 1	(SPD)	FMU 1	(SPD)	•		01215
STA	(T+2)	LDA 2	(SPD)	•		01216
FMU 2	(SPD)	FAD	(T+2)	•		01217
STA	(T+2)	LDA 2	(SPD)	•		01220
FMU 2	(SPD)	FMU	(BP)	•		01221
FDV	(T+2)	STA	(A)	•		01222
ENA	(ARG)	SAL	(SQ+1)	•		01223
SLJ 4	(SQ)	ZRO	(0)	•		01224
STA	(SQARG)	LDA	(-1.)	•		01225
FSB	(SQARG)	STA	(B1)	•		01226
FMU	(A)	STA	(B3)	•		01227
LDA	(-1.)	FAD	(SQARG)	•		01230
STA	(B2)	FMU	(A)	•		01231
STA	(B4)	LDA	(B3)	•		01232
AJP	(L+9)	AJP 2	(L+9)	•		01233
LDA	(B4)	AJP 3	(L+2)	•		01234
SLJ	(L+5)	ZRO	(0)	•		01235
LDA	(SPDINT)	FSB	(10.)	•		01236
FSB 1	(SPD)	AJP 2	(L+3)	•	JUMP IF UNABLE TO INTERCEPT	01237
LDA 1	(TRACK)	SCL	(MASK25)	•	CLEAR COLLISION BIT	01240
STA 1	(TRACK)	SLJ	(6I)	•	JUMP IF UNABLE TO INTERCEPT	01241
LDA 1	(TRACK)	SST	(MASK25)	•	SET COLLISION BIT	01242
STA 1	(TRACK)	SLJ	(1IP)	•	TEMPORARY PURSUIT INTERCEPT	01243
LDA	(B4)	STA	(BI)	•	BI = B4	01244
SLJ	(L+8)	ZRO	(0)	•		01245
LDA	(B4)	AJP	(L+4)	•		01246
AJP 2	(L+3)	ENI	(0)	•		01247
LDA	(B3)	STA	(BI)	•	BI = B3	01250
SLJ	(L+4)	ZRO	(0)	•		01251
LDA	(B3)	FSB	(B4)	•		01252
AJP	(L-3)	AJP 3	(L-3)	•		01253
AJP 2	(L-8)	ZRO	(0)	•		01254
LDA 2	(CRS)	FMU	(.0174533)	•	CONVERT COURSE	01255

APPENDIX I-C

ADD (T+2)	STA 3 (LHEAD)	ORDER TURN	01322
ISK 3 (60)	SLJ (L+2)		01323
ENI 3 (60)	ENI (0)		01324
LDA 2 (ZP)	FSB (2500.)	SET CAP ALTITUDE	01325
AJP 2 (L+2)	LDA (I750B)	TO BOGIE ALTITUDE	01326
STA (T+2)	SLJ (L+3)	LESS 2000 FEET OR	01327
LDA 2 (ZP)	FSB (2000.)	TO 1000 FEET IF	01330
STA (T+2)	SLJ 4 (FIX)	BOGIE IS BELOW	01331
ALS (18)	ADD (LHEAD3)	2500 FEET	01332
ADD (KCNR)	STA 3 (LHEAD)		01333
ISK 3 (60)	SLJ (L+2)		01334
ENI 3 (60)	ENI (0)		01335
LDQ 1 (IHEAD)	LDL (7777B)	UNPACK CAP SPEED	01336
STA (T+2)	SUB (INTSPD)		01337
AJP (L+5)	LDA (LHEAD4)	JUMP IF INTERCEPTOR AT SPEED	01340
ADD (KCNR)	STA (T+3)		01341
LDA (T+2)	ALS (18)		01342
ADD (T+3)	STA 3 (LHEAD)	ORDER SPEED	01343
ISK 3 (60)	SLJ (L+2)		01344
ENI 3 (60)	ENI (0)		01345
LDA 1 (TRACK)	SST (MASK25)	SET COLLISION BIT	01346
STA 1 (TRACK)	SLJ (2I)		01347
LDA (SW)	AJP 1 (IIP)	JUMP IF SIDEWINDERS ON BOARD	01350
LDA (ISFLAG)	AJP (IIP)	JUMP IF AMMO NOT EXHAUSTED	01351
LDA (IEFLAG)	AJP 1 (9IE)	JUMP IF CAP ENGAGED, NO AMMO	01352
AJP (5IE)	ENI (0)	JUMP IF AMMO EXHAUSTED	01353
6I			
* PURSUIT INTERCEPT			
IIP LDA (ICFLAG)	AJP (L+4)	CHECK FOR ENOUGH	01354
LDA 2 (XP)	STA (XBI)	FUEL FOR	01355
LDA 2 (YP)	STA (YBI)	INTERCEPT	01356
SLJ 4 (3II)	ZRO (0)		01357
LDA (BC)	FSB (2.5)		01360
AJP 2 (2IP)	SLJ 4 (IIF)	JUMP IF OUTSIDE KILL RANGE	01361
AJP 3 (L+4)	LDA (SW)	JUMP IF MISS	01362

APPENDIX I-C

AJP	(L+2)	RSO	(SW)	HIT WITH SIDEWINDER	01363
SLJ	(1IK)	ZRO	(0)		01364
RSO	(SP)	SLJ	(1IK)	HIT WITH SPARROW	01365
LDA	(SW)	AJP	(L+3)	JUMP IF NO SIDEWINDERS	01366
RSO	(SW)	AJP	(L+5)	JUMP IF NO SECOND SIDEWINDER	01367
RSO	(SW)	SLJ	(1IK)	HIT WITH SECOND SIDEWINDER	01370
LDA	(ISFLAG)	AJP 1	(9IE)	JUMP IF NO SPARROWS	01371
RSO	(SP)	AJP	(9IE)	MISS WITH SPARROW	01372
RSO	(SP)	SLJ	(1IK)	HIT WITH SPARROW	01373
LDA	(ISFLAG)	AJP 1	(9IE)	JUMP IF NO SPARROWS	01374
RSO	(SP)	SLJ	(1IK)	HIT WITH SPARROW	01375
ENA	(CAPB)	SAL	(2IT)	DÉTERMINE BEST	01376
LDQ 1	(IHEAD)	LDL	(7777B)	DIRECTION TO TURN	01377
ARS	(12)	ENG	(0)		01400
DVI	(10)	STA	(T+3)		01401
ENA	(T+3)	SAL	(3IT)		01402
SLJ 4	(1IT)	ZRO	(0)		01403
AJP	(L+8)	AJP 3	(L+2)	ON COURSE	01404
LDA	(LHEAD2)	SLJ	(L+2)	STARBOARD TURN	01405
LDA	(LHEAD6)	ENI	(0)	PORT TURN	01406
STA	(T+2)	LDA	(CAPB)		01407
SLJ 4	(FIX)	ZRO	(0)		01410
ALS	(18)	ADD	(KCNR)		01411
ADD	(T+2)	STA 3	(LHEAD)	ORDER TURN TO COURSE	01412
ISK 3	(60)	SLJ	(L+2)		01413
ENI 3	(60)	ENI	(0)		01414
LDA 2	(ZP)	SLJ 4	(FIX)		01415
ALS	(18)	ADD	(KCNR)		01416
ADD	(LHEAD3)	STA 3	(LHEAD)	ORDER ALTITUDE EQUAL BOGIE ALT	01417
ISK 3	(60)	SLJ	(L+2)		01420
ENI 3	(60)	ENI	(0)		01421
ENI	(0)	LDA 2	(SPD)		01422
FMU	(1.15)	STA	(T+2)	ORDER SPEED EQUAL	01423
FSB	(SPDINT)	AJP 3	(L+2)	TO BOGIE SPEED	01424
LDA	(INTSPD)	SLJ	(L+2)	PLUS 15 PERCENT	01425
LDA	(T+2)	SLJ 4	(FIX)		01426

2IP

APPENDIX I-C

01427
01430
01431
01432
01433
01434
01435
01436

```

ALS      (18)
ADD      (LHEAD4)
ISK 3    (60)
ENI 3    (60)
LDQ 1    (TRACK)
AJP 1    (11)
SST      (MASK26)
SLJ      (7IE)

ADD      (KCNR)
STA 3    (LHEAD)
SLJ      (L+2)
ENI      (0)
LDL      (MASK26)
LDA 1    (TRACK)
STA 1    (TRACK)
ZRO      (0)

      JUMP IF MESSAGE ALREADY SENT
    
```

* INTERCEPTOR KILL, SPLASH BOGIE

```

1IK  LDA  (LHEAD8)
      STA 3 (LHEAD)
      ENA  (0)
      STA 5 (TRACK2)
      ENA  (52B)
      ISK 3 (60)
      ENI 3 (60)
      SLJ  (8IE)

      ADD  (KBNR)
      ENI  (0)
      STA 5 (TRACK1)
      ENI  (0)
      STA 2 (TRACK)
      SLJ  (L+2)
      ENI  (0)
      ZRO  (0)

      SPLASH BOGIE

      ERASE TRACK2 WORD
      RESET TRACK WORD
    
```

* LAUNCH CAP FROM CARRIER

```

1IL  LDA 1 (TRACK)
      STA 1 (TRACK)
      LDA (KCNR)
      STA 3 (LHEAD)
      ISK 3 (60)
      ENI 3 (60)
      SLJ (2I)

      SCL (MASK23)
      LDQ 1 (TRACK)
      ADD (LHEAD1)
      ENI (0)
      SLJ (L+2)
      ENI (0)
      ZRO (0)

      RESET
      LAUNCH BIT
      INSERT CAP NUMBER
      INTO LAUNCH
      COMMAND WORD
      COMMAND WORD
    
```

* ORBIT ROUTINE

```

1IO  LDA 1 (TRACK)
      ENA (52B)
      STA 1 (TRACK)
      LDA (ICRUISE)
      ALS (18)

      SST (MASK24)
      STA 1 (TRACK)
      ENI (0)
      ALS (18)

      SET ORBIT BIT
      RESET TRACK WORD
    
```


APPENDIX I-C

ADD	(LHEAD4)	ADD	(KCNR)	•	01462
STA 3	(LHEAD)	ENI	(0)	•	01463
ISK 3	(60)	SLJ	(L+2)	•	01464
ENI 3	(60)	ENI	(0)	•	01465
LDA	(LEVEL)	ALS	(18)	•	01466
ADD	(LHEAD3)	ADD	(KCNR)	•	01467
STA 3	(LHEAD)	ENI	(0)	•	01470
ISK 3	(60)	SLJ	(L+2)	•	01471
ENI 3	(60)	ENI	(0)	•	01472
LDA	(LHEAD5)	ADD	(KCNR)	•	01473
STA 3	(LHEAD)	ENI	(0)	•	01474
ISK 3	(60)	SLJ	(L+2)	•	01475
ENI 3	(60)	ENI	(0)	•	01476
SLJ	(11)	ZRO	(0)	•	01477

210

* STEER ROUTINE

11R	LDA	(DME)	FSB	(1.)	•	01500
AJP 2	(L+8)	LDA	(LHEAD8)	•	01501	
ADD	(KCNR)	STA 3	(LHEAD)	•	01502	
ENA	(0)	STA 5	(TRACK1)	•	01503	
STA 5	(TRACK2)	ENI	(0)	•	01504	
ISK 3	(60)	SLJ	(L+2)	•	01505	
ENI 3	(60)	ENI	(0)	•	01506	
SLJ	(21)	ZRO	(0)	•	01507	
LDQ 1	(TRACK)	LDL	(MASK27)	•	01510	
AJP 1	(81)	ENI	(0)	•	01511	
LDA 1	(ZP)	FSB	(80.)	•	01512	
FMU	(.006)	FMU	(CRUISE)	•	01513	
FSB	(DME)	AJP 3	(L+3)	•	01514	
LDA	(LHEAD7)	ENQ	(1)	•	01515	
STQ	(T+4)	SLJ-	(L+3)	•	01516	
LDA	(LEVEL)	ALS	(18)	•	01517	
ADD	(LHEAD3)	ENI	(0)	•	01520	
ADD	(KCNR)	STA 3	(LHEAD)	•	01521	
ISK 3	(60)	SLJ	(L+2)	•	01522	

• ORDER CRUISE SPEED

• ORDER CRUISE ALTITUDE

• ORDER ORBIT

• ORDER CRUISE ALTITUDE

• JUMP IF NOT LANDED YET

• CAP LANDED,

• ERASE TRACK2 WORD

• SCRUB TRACK

• SCRUB TRACK

• JUMP IF ALREADY STEERED

• COMPUTE RANGE

• AT WHICH TO

• BEGIN LET DOWN

• ORDER LET DOWN

• ORDER CRUISE ALTITUDE

APPENDIX I-C

01523	ENI 3 (60)	ENI (0)	ENI (0)	ENI (0)	•		01523
01524	ENI (0)	LDA 1 (SPD)	LDA 1 (SPD)	LDA 1 (SPD)	•	• COMPUTE RANGE	01524
01525	FSB (120.)	STA (T+2)	STA (T+2)	STA (T+2)	•	• AT WHICH TO	01525
01526	FDV (20.)	FMU (T+2)	FMU (T+2)	FMU (T+2)	•	• BEGIN DECELERATION	01526
01527	FSB (DME)	AJP 3 (L+5)	AJP 3 (L+5)	AJP 3 (L+5)	•		01527
01530	LDQ (T+4)	QJP (L+3)	QJP (L+3)	QJP (L+3)	•		01530
01531	LDA 1 (TRACK)	SST (MASK27)	SST (MASK27)	SST (MASK27)	•	• SET STEERED BIT	01531
01532	STA 1 (TRACK)	ENI (0)	ENI (0)	ENI (0)	•		01532
01533	LDA (LHEAD9)	SLJ (L+3)	SLJ (L+3)	SLJ (L+3)	•	• ORDER DECELERATION	01533
01534	LDA (ICRUISE)	ALS (18)	ALS (18)	ALS (18)	•		01534
01535	ADD (LHEAD4)	ENI (0)	ENI (0)	ENI (0)	•	• ORDER CRUISE SPEED	01535
01536	ADD (KCNR)	STA 3 (LHEAD)	STA 3 (LHEAD)	STA 3 (LHEAD)	•		01536
01537	ISK 3 (60)	SLJ (L+2)	SLJ (L+2)	SLJ (L+2)	•		01537
01540	ENI 3 (60)	ENI (0)	ENI (0)	ENI (0)	•		01540
01541	ENA 1 (XP)	SAL (COURSE+1)	SAL (COURSE+1)	SAL (COURSE+1)	•		01541
01542	ENA 1 (YP)	SAL (COURSE+2)	SAL (COURSE+2)	SAL (COURSE+2)	•		01542
01543	ENA (T+2)	SAL (COURSE+3)	SAL (COURSE+3)	SAL (COURSE+3)	•		01543
01544	ENA (0)	STA (T+3)	STA (T+3)	STA (T+3)	•		01544
01545	ENA (T+3)	SAL (COURSE+4)	SAL (COURSE+4)	SAL (COURSE+4)	•		01545
01546	SAL (COURSE+5)	SLJ 4 (COURSE)	SLJ 4 (COURSE)	SLJ 4 (COURSE)	•		01546
01547	ENA (T+2)	SAL (2IT)	SAL (2IT)	SAL (2IT)	•	• DETERMINE BEST	01547
01550	LDQ 1 (IHEAD)	LDL (7777B)	LDL (7777B)	LDL (7777B)	•	• DIRECTION TO TURN	01550
01551	ARS (12)	ENQ (0)	ENQ (0)	ENQ (0)	•		01551
01552	DVI (10)	STA (T+3)	STA (T+3)	STA (T+3)	•		01552
01553	ENA (T+3)	SAL (3IT)	SAL (3IT)	SAL (3IT)	•		01553
01554	SLJ 4 (1IT)	ZRO (0)	ZRO (0)	ZRO (0)	•		01554
01555	AJP (2I)	AJP 3 (L+2)	AJP 3 (L+2)	AJP 3 (L+2)	•	• ON COURSE	01555
01556	LDA (LHEAD2)	SLJ (L+2)	SLJ (L+2)	SLJ (L+2)	•	• STARBOARD TURN	01556
01557	LDA (LHEAD6)	ENI (0)	ENI (0)	ENI (0)	•	• PORT TURN	01557
01560	STA (T+3)	LDA (T+2)	LDA (T+2)	LDA (T+2)	•		01560
01561	SLJ 4 (FIX)	ZRO (0)	ZRO (0)	ZRO (0)	•		01561
01562	ALS (18)	ADD (KCNR)	ADD (KCNR)	ADD (KCNR)	•		01562
01563	ADD (T+3)	STA 3 (LHEAD)	STA 3 (LHEAD)	STA 3 (LHEAD)	•	• ORDER TURN	01563
01564	ISK 3 (60)	SLJ (L+2)	SLJ (L+2)	SLJ (L+2)	•		01564
01565	ENI 3 (60)	ENI (0)	ENI (0)	ENI (0)	•		01565
01566	SLJ (2I)	ZRO (0)	ZRO (0)	ZRO (0)	•		01566

APPENDIX I-C

* STATION ROUTINE

11S	LDQ 5 (TRACK1)	LLS (21)			01567
	QRS (39)	STQ (IYSTA)		UNPACK STATION Y POSITION	01570
	ENQ (0)	LRS (9)			01571
	QRS (39)	STQ (IXSTA)		UNPACK STATION X POSITION	01572
	LDA (IXSTA)	SLJ 4 (FLOAT)			01573
	STA (XSTA)	ENI (0)			01574
	LDA (IYSTA)	SLJ 4 (FLOAT)			01575
	STA (YSTA)	LDA 1 (YP)		IS	01576
	FSB (YSTA)	STA (T+2)		CAP	01577
	ENA (T+2)	SAL (2ABS)		ON	01600
	SLJ 4 (IABS)	ZRO (0)		STATION	01601
	ENA (6)	STA (T+3)			01602
	THS (T+3)	SLJ (L+6)			01603
	LDA 1 (XP)	FSB (XSTA)			01604
	STA (T+2)	ENA (T+2)			01605
	SAL (2ABS)	SLJ 4 (IABS)			01606
	THS (T+3)	SLJ (L+3)		JUMP IF NOT ON STATION	01607
	LDA 1 (TRACK)	SCL (MASK20)		CLEAR STATION BIT	01610
	STA 1 (TRACK)	SLJ (IIO)		ON STATION	01611
	LDA (KCNR)	ADD (LHEAD4)		NOT ON STATION	01612
	STA (T+2)	LDA (ICRUISE)			01613
	ALS (18)	ADD (T+2)			01614
	STA 3 (LHEAD)	ENI (0)		ORDER CRUISE SPEED	01615
	ISK 3 (60)	SLJ (L+2)			01616
	ENI 3 (60)	ENI (0)			01617
	LDA (KCNR)	ADD (LHEAD3)			01620
	STA (T+2)	LDA (LEVEL)			01621
	ALS (18)	ADD (T+2)			01622
	STA 3 (LHEAD)	ENI (0)		ORDER CRUISE ALTITUDE	01623
	ISK 3 (60)	SLJ (L+2)			01624
	ENI 3 (60)	ENI (0)			01625
	LDA 1 (XP)	FSB (XSTA)			01626
	STA (T+2)	LDA 1 (YP)			01627

APPENDIX I-C

FSB	(YSTA)	STA	(T+3)	•	•	01630
ENA	(T+2)	SAL	(COURSE+1)	•	•	01631
ENA	(T+3)	SAL	(COURSE+2)	•	•	01632
ENA	(T+4)	SAL	(COURSE+3)	•	•	01633
ENA	(0)	STA	(T+5)	•	•	01634
ENA	(T+5)	SAL	(COURSE+4)	•	•	01635
SAL	(COURSE+5)	SLJ	4 (COURSE)	•	•	01636
LDA	(T+4)	SLJ	4 (FIX)	•	•	01637
ALS	(18)	STA	(T+4)	•	•	01640
LDQ	1 (IHEAD)	LDL	(7777B)	•	•	01641
ARS	(12)	ENQ	(0)	•	•	01642
DVI	(10)	STA	(T+3)	•	•	01643
ENA	(T+3)	SAL	(3IT)	•	•	01644
ENA	(T+4)	SAL	(2IT)	•	•	01645
SLJ	4 (1IT)	ZRO	(0)	•	•	01646
AJP	(11)	AJP	2 (L+2)	•	•	01647
LDA	(LHEAD6)	SLJ	(L+2)	•	•	01650
LDA	(LHEAD2)	ENI	(0)	•	•	01651
STA	(T+2)	LDA	(KCNR)	•	•	01652
RAD	(T+2)	LDA	(T+4)	•	•	01653
ALS	(18)	ADD	(T+2)	•	•	01654
STA	3 (LHEAD)	ENI	(0)	•	•	01655
ISK	3 (60)	SLJ	(L+2)	•	•	01656
ENI	3 (60)	ENI	(0)	•	•	01657
SLJ	(11)	ZRO	(0)	•	•	01660

*DESIGNATE TRACK ROUTINE

1J	EXF	(77411B)	SLJ	(L+3)	•	01661
2J	ZRO	(0)	ZRO	(0)	•	01662
3J	ZRO	(0)	ZRO	(0)	•	01663
	LDA	(2J)	LLS	(6)	•	01664
	LDL	(77B)	STA	(2J)	•	01665
	ENA	(3J)	SLJ	4 (3J0)	•	01666
	LDA	(2J)	AJP	(19J)	•	01667
	INA	(-66B)	AJP	(4J)	•	01670

APPENDIX I-C

4J	INA	(-2B)	AJP	(9J)	•	SENSE HOSTILE	01671
5J	ENA	(E6)	SLJ	(1E)	•	ERROR EXIT	01672
	ENA	(1)	STA	(FRIEND)	•	SET FRIEND	01673
	ENA	(ZN)	ADD	(3J)	•	FRIEND = 1 / FRIENDLY	01674
	STA	(T+6)	LDQ	7 (T+6)	•	FRIEND = -1 / HOSTILE	01675
	ENA	(TRACK)	ADD	(3J)	•	JUMP ACCORDING TO	01676
	STA	(T+6)	QJP	3 (6J)	•	ALTITUDE	01677
	QJP	(7J)	QJP	2 (8J)	•		01700
6J	LDA	(FRIEND)	AJP	2 (L+3)	•		01701
	ENA	(40B)	STA	7 (T+6)	•	HOSTILE SUB	01702
	SLJ	(12J)	ZRO	(0)	•		01703
	ENA	(20B)	STA	7 (T+6)	•	FRIENDLY SUB	01704
	SLJ	(10J)	ZRO	(0)	•		01705
	LDA	(FRIEND)	AJP	2 (L+3)	•		01706
7J	ENA	(44B)	STA	7 (T+6)	•	HOSTILE SURFACE	01707
	SLJ	(15J)	ZRO	(0)	•		01710
	ENA	(24B)	STA	7 (T+6)	•	FRIENDLY SURFACE	01711
	SLJ	(13J)	ZRO	(0)	•		01712
8J	LDA	(FRIEND)	AJP	2 (L+3)	•		01713
	ENA	(34B)	STA	7 (T+6)	•	HOSTILE A/C	01714
	SLJ	(18J)	ZRO	(0)	•		01715
	ENA	(30B)	STA	7 (T+6)	•	FRIENDLY A/C	01716
	SLJ	(16J)	ZRO	(0)	•		01717
9J	ENA	(-1)	STA	(FRIEND)	•	SET HOSTILE	01720
	SLJ	(5J)	ZRO	(0)	•		01721
10J	LDA	(MASK14)	RAD	7 (T+6)	•	SET FRIENDLY	01722
	RAO	(FSUB)	SAU	7 (T+6)	•	SET TARGET NUMBER	01723
11J	LDA	(MASK18)	RAD	7 (T+6)	•	SET SUB BIT	01724
	SLJ	(4T)	ZRO	(0)	•	RETURN	01725
12J	RAO	(HSUB)	SAU	7 (T+6)	•	SET TARGET NUMBER	01726
	SLJ	(11J)	ZRO	(0)	•		01727
13J	LDA	(MASK14)	RAD	7 (T+6)	•	SET FRIENDLY	01730
	RAO	(FSUR)	SAU	7 (T+6)	•	SET TARGET NUMBER	01731
14J	LDA	(MASK17)	RAD	7 (T+6)	•	SET SURFACE BIT	01732
	SLJ	(4T)	ZRO	(0)	•	RETURN	01733
15J	RAO	(HSUR)	SAU	7 (T+6)	•		01734

APPENDIX I-C

16J	SLJ (14J)	ZRO (0)	•	SET FRIENDLY	01735
	LDA (MASK14)	RAD 7 (T+6)	•	DETERMINE TYPE INTERCEPTOR	01736
	LIL 2 (3J)	LDQ (ITIME)	•	ZERO JUMP TO F4	01737
	LDL (1B)	AJP (L+9)	•	F8 TYPE	01740
	LDA (MASK8U)	RAD 7 (T+6)	•	SET INITIAL	01741
	RAO (FAC)	LDA (IFIG3)	•	FUEL AND	01742
	SCL (MASK9)	STA 2 (KFIG)	•	TIME	01743
	LDA (ITIME)	RAD 2 (KFIG)	•		01744
	LDA (3J)	ALS (42)	•		01745
	LIL 2 (KNR2)	STA 2 (TRACK1)	•	SET UP TRACK1 WORD	01746
	RAO (KNR2)	LDA (FAC)	•		01747
	SAU 7 (T+6)	SLJ (L+4)	•	SET CAP NUMBER	01750
	LDA (MASK4B)	RAD 7 (T+6)	•	F4 TYPE	01751
	RAO (FAC)	LDA (IFIG7)	•		01752
17J	SLJ (L-8)	ZRO (0)	•	JUMP TO INITIALIZE	01753
	LDA (MASK16)	RAD 7 (T+6)	•	SET A/C BIT	01754
	SLJ (4T)	ZRO (0)	•	RETURN	01755
18J	RAO (HAC)	SAU 7 (T+6)	•	SET TARGET NUMBER	01756
	SLJ (17J)	ZRO (0)	•		01757
19J	ENA (TRACK)	ADD (3J)	•		01760
	STA (T+6)	ENA (0)	•		01761
	STA 7 (T+6)	LDA (3J)	•	OWN SHIP SYMBOL SET	01762
	STA (OWN)	SLJ (13J)	•		01763

* HOOK ROUTINE

3J0	SLJ (N)	STA (TAR)	•	STORE ADDRESS OF ANSWER	01764
	LDA (EIGHT)	FDV (RHO)	•	DETERMINE RANGE GATE	01765
	STA (INC)	FAD (XPIP)	•		01766
	STA (XDESIG)	LDA (INC)	•	DETERMINE X POSITION	01767
	FAD (YPIP)	STA (YDESIG)	•	DETERMINE Y POSITION	01770
	ENI 3 (1)	ENI (0)	•		01771
3J1	LDA 3 (YS)	FSB (YDESIG)	•	CHECK FOR TARGET IN Y GATE	01772
	STA (T+2)	ENA (T+2)	•		01773
	SAL (2ABS)	SLJ 4 (1ABS)	•		01774
	EOS (INC)	SLJ (L+2)	•		01775

APPENDIX I-C

SLJ	(L+2)	ZRO	(0)				01776
THS	(INC)	SLJ	(3J2)				01777
LDA	3 (XS)	FSB	(XDESIG)				02000
STA	(T+2)	ENA	(T+2)				02001
SAL	(2ABS)	SLJ	4 (1ABS)				02002
EQS	(INC)	SLJ	(L+2)				02003
SLJ	(L+2)	ZRO	(0)				02004
THS	(INC)	SLJ	(3J2)				02005
SIL	3 (3J)	LDA	(3J)				02006
STA	7 (TAR)	SLJ	(3J0)				02007
ISK	3 (15)	SLJ	(3J1)				02010
ENA	(E13)	SLJ	(1E)				02011

3J2

* KEYBOARD ROUTINE ENTRY AND CHECK

1K	EXF	(77110B)	INT	(RANGE)			02012
	EXF	(77001B)	LIL	5 (RANGE)			02013
	LDA	5 (RHO)	STA	(RHO)			02014
	EXF	(77102B)	INT	(XBALL)			02015
	EXF	(77001B)	LDA	(XBALL)			02016
	ALS	(39)	ARS	(39)			02017
	SLJ	4 (FLOAT)	ZRO	(0)			02020
	FDV	(RHO)	STA	(XPIP)			02021
	EXF	(77104B)	INT	(YBALL)			02022
	EXF	(77001B)	LDA	(YBALL)			02023
	ALS	(39)	ARS	(39)			02024
	SLJ	4 (FLOAT)	ZRO	(0)			02025
	FDV	(RHO)	STA	(YPIP)			02026
	LDA	(XBALL)	ALS	(36)			02027
	ADD	(PIP)	STA	(HOOK)			02030
	LDA	(YBALL)	RAD	(HOOK)			02031
	EXF	(77010B)	EXF	7 (77010B)			02032
	OUT	(HOOK)	ENI	(0)			02033
1K1	ENI	4 (120)	ENA	(53B)			02034
	EQS	4 (BUF1)	SLJ	(4T)			02035
	SLJ	(1P)	ZRO	(0)			02036

APPENDIX I-C

2K LDA (IFLAG) AJP 1 (2T) 02037
 LDA (BUF1+1) AJP (L+2) 02040
 EQS (F13) SLJ (IT) 02041
 SLJ (IK1) ZRO (0) 02042

• CHECK FOR BEGIN FLAG
 • NOTHING IN BUF1 JUMP TO 2T
 • CHECK FOR B IN BUFF+1
 • YES JUMP TO IK1

* HISTORY ROUTINE

1L EXF (77221B) SLJ (4L) 02043
 2L ZRO (0) ZRO (0) 02044
 3L1 ZRO (0) ZRO (0) 02045
 3L ZRO (0) ZRO (0) 02046
 4L ENA (3L) SLJ 4 (3J0) 02047
 ENA (9) STA (PPM) 02050
 LDA (2L) AJP (8L) 02051
 THS (30B) SLJ (L+2) 02052
 SLJ (9L) ZRO (0) 02053
 LDA (3L1) AJP 5 (10L) 02054

• TURN OFF HISTORY LT
 • NUMBER OF POINTS DESIRED
 • MINUTES INSTEAD OF POINTS
 • TRACK DESIRED
 • HOOK TRACK
 • SET EVERY SWEEP COUNT
 • JUMP IF NR POINTS = ZERO
 • JUMP IF NR POINTS .GT. 24

5L LAC (HISTORY) AJP 2 (7L) 02055
 LIL 2 (3L1) LIL 4 (2L) 02056
 SIU 4 (13F) SIU 4 (4G) 02057
 LIL 3 (3L) SIL 3 (HIS1) 02060
 LIL 4 (PPM) LDA 4 (PP0) 02061
 STA (PPMC1) STA (PPMC) 02062
 ENA (XHIS1) SLJ 4 (1L0) 02063
 SIU 4 (10F1) SIL 5 (10F1) 02064
 SIU 6 (11F) ENA (0) 02065

• DETERMINE WHICH ARRAYS TO USE
 • HIS1 ARRAYS
 • SET INDEXES
 • SET TIMING CHAINS
 • JUMP TO FILL ROUTINE
 • SAVE INDEXES
 • 4, 5, 6

6L STA (3L1) STA (2L) 02066
 SLJ (10F) ZRO (0) 02067
 LIL 2 (3L1) LIL 4 (2L) 02070
 SIU 4 (15F) SIU 4 (6G) 02071
 LIL 3 (3L) SIL 3 (HIS2) 02072
 LIL 4 (PPM) LDA 4 (PP0) 02073
 STA (PPMC2) STA (PPMC) 02074
 ENA (XHIS2) SLJ 4 (1L0) 02075
 SLJ (6L) ZRO (0) 02076
 ENA (12) STA (2L) 02077

• ZERO ARGUMENTS
 • JUMP TO DISPLAY
 • HIS2 ARRAYS
 • SET INDEXES
 • SET TIMING CHAINS
 • JUMP TO FILL ROUTINE
 • PUT 12 IN 2L

APPENDIX I-C

9L SLJ (5L) ZRO (0) 02100
 ENA (24) STA (2L) 02101
 SLJ (5L) ZRO (0) 02102
 • PUT 24 IN 2L
 •

* TIMING CHAIN ROUTINE

10L SLJ (N) ENI (0) 02103
 ENA (60) ENQ (0) 02104
 DVI (IP) STA (PPM) 02105
 ENQ (0) MUI (2L) 02106
 STA (3L1) LDA (TIME) 02107
 SUB (TFLAG) ENQ (0) 02110
 DVI (IP) ENQ (0) 02111
 THS (3L1) SLJ (L+2) 02112
 STA (3L1) ENI (0) 02113
 LDA (PPM) ENI 2 (10) 02114
 EQS 2 (PTABLE) SLJ (L+3) 02115
 LDA 2 (PPO) STA (PPMC) 02116
 SIL 2 (PPM) SLJ (5L) 02117
 LDA (PPM) ENI 2 (10) 02120
 THS 2 (PTABLE) SLJ (4T) 02121
 LDA 2 (PPO) STA (PPMC) 02122
 SIL 2 (PPM) SLJ (10L) 02123
 • EXIT/ENTRY
 • DETERMINE PERIODS
 • PER MIN
 • POINTS NEEDED
 •
 • ENOUGH POINTS STORED
 • NO REDUCE 3L1
 •
 • DETERMINE TIMING CHAIN
 •
 •
 • RETURN
 • RETURN

* FILL ARRAYS ROUTINE

110 SLJ (N) SAL (1L1) 02124
 INA (25) SAL (1L2) 02125
 BACKSPACE MM 02126
 90 IJP 2 (90) LIL 2 (3L1) 02127
 LIL 5 (2L) ENI (0) 02130
 990 READ TAPE MM, IXH,IYH SLJ (1L3) 02131
 SSH (PPMC1) STA 5 (N) 02132
 111 LDA 3 (IXH) STA 5 (N) 02133
 112 LDA 3 (IYH) STA 5 (N) 02134
 • EXIT/ENTRY
 • BACK UP MEMORY
 •
 • LOOP
 •
 • FILL ARRAY
 •

APPENDIX I-C

1L3 INI 5 (-1) ENI (0) 02135
 IJP. 2 (990) SLJ (1L0) 02136
 * ERASE ROUTINE

1MER SLJ (N) SIU 4 (2MER) * EXIT/ENTRY 02137
 ENI 4 (2) ENI (0) * SET INDEX FOR LOOP 02140
 EXF (02000B) EXF (04001B) * STOP RT CLOCK DISALLOW 02141
 EXF (77010B) OUT (ERASE) * FIRST ERASE WORD 02142
 EXF (77010B) OUT (S6C) * STRING ERASE WORDS 02143
 ISK 4 (398) SLJ (L-1) * LOOP 02144
 EXF (04000B) EXF (01000B) * ALLOW START RT CLOCK 02145
 ENI 4 (N) SLJ (1MER) * RETURN 02146

* MESSAGE ROUTINE
 1MSG SLJ (N) STA (T+8) * EXIT/ENTRY 02147
 ENA (XP1) SAL (PRINT+1) * SET UP ARGUMENTS FOR PRINT 02150
 ENA (YMSG) SAL (PRINT+2) * 02151
 SIU 5 (2MSG) LIL 5 (PRO) * 02152
 SIL 5 (PRINT+3) LIL 5 (ADD) * 02153
 SIL 5 (PRINT+4) ENQ (OB) * 02154
 LDA (T+8) SLJ 4 (PRINT) * JUMP TO PRINT 02155
 LIL 5 (PRINT+4) SIL 5 (ADD) * RESET ADD 02156
 ENA (-12B) RAD (YMSG) * DECREASE YMSG 02157
 2MSG ENI 5 (N) SLJ (1MSG) * RETURN 02160

* GRAPH TITLE UPDATE
 IN SLJ (*) LDA (GTIME) * 02161
 ADD (R3) STA (TITLE9) * STORE 02162
 STA (TITLE21) LDA (TFLAG) * INITIAL TIME 02163
 ENQ (0) DVI (60) * 02164
 STQ (T+10) SLJ 4 (1NUM) * 02165
 ALS (30) SCL (MASK37) * 02166
 ADD (R4) STA (T+9) * STORE FINAL 02167

APPENDIX I-C

```

LDA (T+10)
MUI (10)
DVI (60)
ALS (18)
RAD (T+9)
STA (TITLE22)
STA (GTIME)

ENQ (0)
ENQ (0)
SLJ 4 (1NUM)
SCL (MASK38)
STA (TITLE10)
SCL (MASK39)
SLJ (1N)

INTEGER TIME
STORE FINAL
DECIMAL TIME
    
```

```

02170
02171
02172
02173
02174
02175
02176
    
```

* OCTAL TO BCD NUMBER CONVERTER 0 TO 9,999,999

```

INUM SLJ (N)
ENI 2 (N)
THS (1000000)
THS (100000)
THS (10000)
THS (1000)
THS (100)
THS (10)
LDQ (TITLE6)
ENQ (0)
SAL (2NUM)
LDA (T)
SCL (77B)
STA (T)
IJP 2 (L-5)
ENI 2 (N)
ZRO (0)

SIU 2 (3NUM)
ENI (0)
INI 2 (1)
INI 2 (1)
INI 2 (1)
INI 2 (1)
INI 2 (1)
INI 2 (1)
INI 2 (1)
STQ (T)
DVI 2 (RO)
LIL 1 (2NUM)
ALS (6)
ADD 1 (FO)
LLS (48)
LDA (T)
SLJ (1NUM)
ZRO (0)

EXIT/ENTRY
TAKES OCTAL NUMBER
CONVERTS IT TO BCD
AND PACKS IT IN THE
LOWER 36 BITS OF
T WITH THE REST
OF THE WORD BLANKS

I. E.
2020NNNNNNNNNNNN
LOOP
RETURN
    
```

```

02177
02200
02201
02202
02203
02204
02205
02206
02207
02210
02211
02212
02213
02214
02215
02216
02217
    
```

* PROGRAM CONTROL ROUTINE

```

IP LIL 4 (KNR)
LDA 4 (BUF1)
EGS 1 (F12)
ENA (0)
LDA 4 (BUF1)
EGS 1 (FO)

ENI (0)
ENI 1 (26)
SLJ (2P)
STA (T)
ENI 1 (36)
SLJ (L+4)

SET B4 = KNR
CHECK TO SEE IF FIRST
CHARACTER IS LETTER
ASSEMBLE NAME
    
```

```

02220
02221
02222
02223
02224
02225
    
```


APPENDIX I-C

Address	Instruction	Position Name
02226	LDA (T)	ALS (6)
02227	ADD 4 (BUF1)	STA (T)
02230	INI 4 (1)	SLJ (L-4)
02231	SUB (F56)	AJP (L-1)
02232	LDA (T)	ENQ (0)
02233	LRS (6)	AJP 1 (L)
02234	LDL (-0B)	LIL 3 (NPROG)
02235	EQS 3 (P0)	SLJ (2P)
02236	LDA 3 (0Z)	SAU (L+7)
02237	SAL (4P)	ARS (24)
02240	STA (5P)	SLJ 4 (3P)
02241	ENA (1)	STA (KNR)
02242	STA (KNR1)	ENI (0)
02243	ENA (0)	ENI 4 (120)
02244	STA 4 (BUF1)	IJP 4 (L)
02245	SLJ (N)	ZRO (0)
02246	SLJ 4 (13P)	ZRO (0)
02247	ENA (EO)	SLJ (1E)
02250	SLJ (N)	SLJ (L+3)
02251	ZRO (0)	ZRO (0)
02252	ZRO (0)	ZRO (0)
02253	LDA 4 (BUF1)	AJP (8P)
02254	INA (-33B)	AJP (L+5)
02255	INA (-1B)	AJP (L+4)
02256	INA (-37B)	AJP (3P)
02257	INA (-1)	AJP (3P)
02260	SLJ (8P)	ZRO (0)
02261	INI 4 (1)	LDA 4 (BUF1)
02262	SUB (F56)	AJP (L-1)
02263	ENA (0)	STA (T)
02264	LDA 4 (BUF1)	ENI 1 (10)
02265	EQS (F53)	SLJ (L+3)
02266	STA (NEG)	INI 4 (1)
02267	LDA 4 (BUF1)	SLJ (L+3)
02270	EQS (60B)	SLJ (L+2)
02271	INI 4 (1)	LDA 4 (BUF1)

2P
3P
4P
5P
6P

APPENDIX I-C

EQS 1 (F0)	SLJ (L+2)	•	SENSE OCTAL NUMBER	02272
SLJ (9P)	ZRO (0)	•	ASSEMBLE NUMBER	02273
LDA 4 (BUF1)	ENI 1 (36)	•		02274
EQS 1 (F0)	SLJ (L+4)	•		02275
LDA (T)	ALS (6)	•	ASSEMBLE NAME	02276
ADD 4 (BUF1)	STA (T)	•		02277
INI 4 (1)	SLJ (L-4)	•	LOOP	02300
SUB (F56)	AJP (L-1)	•	POSITION ARGUMENT	02301
LDA (T)	ENQ (0)	•		02302
LRS (6)	AJP 1 (L)	•		02303
STQ (T)	ENI (0)	•		02304
RAO (4P)	RSO (5P)	•		02305
AJP 3 (8P)	LDA (T)	•	SENSE ARGUMENT LIMIT	02306
LDQ (NEG)	QJP (L+3)	•	CHECK NEGATIVE FLAG	02307
LAC (T)	ENQ (0)	•		02310
STQ (NEG)	ENI (0)	•		02311
STA 7 (4P)	SLJ (6P)	•	LOOP	02312
SLJ 4 (13P)	ZRO (0)	•		02313
ENA (E3)	SLJ (1E)	•	TOO MANY ARGUMENTS	02314
SIL 4 (10P)	SLJ (L+2)	•		02315
ZRO (0)	ZRO (0)	•	PRESENT POSITION IN ARRAY	02316
LIL 2 (10P)	ENI 5 (0)	•	DETERMINE WIDTH OF NUMBER	02317
LDA 2 (BUF1)	ENI (0)	•		02320
INA (-33B)	AJP (11P)	•	SENSE COMMA	02321
INA (-01B)	AJP (11P)	•	SENSE OPEN PAREN	02322
INA (-37B)	AJP (11P)	•	SENSE PERIOD	02323
INA (-01B)	AJP (11P)	•	SENSE CLOSING PAREN	02324
INI 2 (1)	INI 5 (1)	•	B5 NOW HAS WIDTH OF NUMBER	02325
SLJ (L-6)	ZRO (0)	•		02326
ENA (0)	STA (T)	•		02327
ENI 1 (10)	SLJ 4 (12P)	•		02330
EQS 1 (F0)	SLJ (2P)	•	SENSE OCTAL NUMBER	02331
LDA (T)	MUI (F0)	•	MULTIPLY BY TEN	02332
INA 1 (0)	STA (T)	•	INCREASE BY NEXT DIGIT	02333
SLJ (L-4)	ZRO (0)	•	LOOP	02334

APPENDIX I-C

* DETERMINE OCTAL NUMBER ROUTINE

12P	SLJ	(N)	IJP	5	(L+2)	•	EXIT/ENTRY	02335
	SLJ	(7P)	ZRO	(0)		•		02336
	LDA	4	SAL	(L+3)		•		02337
	EQS	(F56)	SLJ	(L+2)		•	CHECK FOR SPACES	02340
	LDA	(F0)	SAL	(L+1)		•	PUT ZEROS IN FOR SPACES	02341
	INI	4	ENA	(N)		•		02342
	SLJ	(12P)	ZRO	(0)		•	RETURN	02343

* ZERO OUT BUF1 UPON ERROR ROUTINE

13P	SLJ	(N)	LIL	4	(KNR1)	•	EXIT/ENTRY	02344
	ENA	(0)	STA	4	(BUF1)	•	ZERO OUT BUF1	02345
	IJP	4	SLJ	(13P)		•	RETURN	02346

* HOLD OR PAUSE ROUTINE

1PQ	LDA	(TIME)	STA	(PAUSE)	•	STORE TIME	02347	
	ENA	(1)	STA	(PFLAG)	•	SET P-FLAG	02350	
	LDA	(PFLAG)	AJP	1	(L)	•	WAIT LOOP	02351
	EXF	(77303B)	LDA	(PAUSE)	•	TURN OFF PAUSE LIGHT	02352	
	STA	(TIME)	STA	(ITIME)	•	RESTORE TIME	02353	
	SLJ	(4T)	ZRO	(0)	•	RETURN	02354	

* INTERCEPT COMMAND ROUTINE

1Q	EXF	(77321B)	SLJ	(L+3)	•	TURN OFF INT LIGHT	02355	
2Q	ZRO	(0)	ZRO	(0)	•	CAP NR OF INTECTOR	02356	
3Q	ZRO	(0)	ZRO	(0)	•	BOGEY HOOKED	02357	
	ENA	(3Q)	SLJ	4	(3J0)	•	HOOK BOGEY	02360
	ENI	2	ENI	(0)	•	SET INDEX FOR LOOP	02361	
	SSK	2	SLJ	(L+6)	•	SENSE FRIENDLY	02362	
	LDA	(MASK16)	LDQ	2	(TRACK)	•		02363
	MEQ	(MASK16)	SLJ	(L+5)	•	CHECK FOR A/C BIT	02364	
	QRS	(24)	LDL	(77B)	•		02365	

APPENDIX I-C

EQS	(2Q)	SLJ	(L+2)	•	IS CAP CALLED FOR AIRBORNE	02366
SIU	2 (2Q)	SLJ	(4Q)	•	YES JUMP TO 4Q	02367
ISK	2 (15)	SLJ	(L-6)	•	LOOP	02370
ENI	2 (16)	LDQ	(MASK11)	•	LAUNCH CAP ROUTINE	02371
ENA	(52B)	ENI	(0)	•		02372
MEQ	2 (TRACK)	SLJ	(5Q)	•	CHECK FOR NON ACTIVE TRACKS	02373
ENA	(2Q)	SLJ	4 (1X1)	•	GET CAP NUMBER	02374
LDA	(2Q)	ALS	(24)	•		02375
RAD	2 (TRACK)	ENI	(0)	•	SET CAP NUMBER	02376
LDA	(MASK14)	RAD	2 (TRACK)	•	SET FRIENDLY SYMBOL	02377
LDA	(MASK4B)	RAD	2 (TRACK)	•	SET TYPE INTERCEPTOR	02400
LDA	(MASK23)	RAD	2 (TRACK)	•	SET LAUNCH BIT	02401
SIU	2 (2Q)	LDA	(IFIG7)	•	STORE CAP TRACK NR	02402
SCL	(MASK9)	STA	2 (KFIG)	•	INITIALIZE FUEL	02403
LDA	(ITIME)	RAD	2 (KFIG)	•	AND LAUNCH TIME	02404
LDA	(MASK19)	RAD	2 (TRACK)	•	SET INTERCEPT BIT	02405
LDQ	(2Q)	QRS	(24)	•		02406
LDL	(77B)	ALS	(42)	•		02407
SLJ	4 (6Q)	ZRO	(0)	•	JUMP TO DETERMINE TRACK1 WORD	02410
LIL	3 (8Q)	STA	(T+2)	•		02411
LDA	3 (TRACK1)	SCL	(MASK36)	•		02412
ADD	(T+2)	STA	3 (TRACK1)	•	SET UP TRACK1 WORD	02413
LDQ	2 (TRACK)	LDL	(MASK10)	•		02414
STA	2 (TRACK)	ENA	(55B)	•	SET ENAGAGED CAP SYMBOL	02415
RAD	2 (TRACK)	LIL	2 (3Q)	•		02416
LDQ	2 (TRACK)	LDL	(MASK10)	•		02417
STA	2 (TRACK)	ENA	(54B)	•	SET ENGAGED BOGEY SYMBOL	02420
RAD	2 (TRACK)	ENI	(0)	•		02421
LDA	(3Q)	ALS	(36)	•		02422
RAD	3 (TRACK1)	ENA	(0)	•		02423
STA	(2Q)	SLJ	(4T)	•		02424
ENA	(E56)	SLJ	4 (1MSG)	•	NO CAP AVAILABLE	02425
ENA	(0)	STA	(2Q)	•	TO BE LAUNCHED	02426
SLJ	(4T)	ZRO	(0)	•		02427

4Q

5Q

APPENDIX I-C

* DETERMINE WHICH TRACK1 WORD TO USE

6Q	SLJ (N)	SIL 4 (7Q)	• EXIT/ENTRY	02430
	LIL 4 (KNR2)	LDQ (MASK36)	•	02431
	MEQ 4 (TRACK1)	SLJ (L+3)	• CHECK FOR CAP TRACK NR	02432
7Q	SIL 4 (8Q)	ENI 4 (N)	• SAVE TRACK1 INDEX	02433
8Q	SLJ (6Q)	ZRO (0)	• RETURN	02434
	LIL 4 (KNR2)	SIL 4 (8Q)	• USE NEXT TRACK1 WORD	02435
	STA (9Q)	RAO (KNR2)	• INCREASE KNR2	02436
	LDA (9Q)	SLJ (7Q)	• RETURN	02437
9Q	ZRO (0)	ZRO (0)	•	02440

* DROP HISTORY ROUTINE

1R	EXF (77321B)	SLJ (3R)	• TURN OFF DROP LT	02441
2R	ZRO (0)	ZRO (0)	• TRACK TO BE DROPPED	02442
3R	ENA (2R)	SLJ 4 (3J0)	• HOOK TRACK	02443
	EQS (HIS1)	SLJ (4R)	• HIS1 NO --JUMP 4R	02444
	ENA (0)	STA (HIS1)	• RESET HIS1	02445
	ENA (-0B)	STA (HISTORY)	• RESET HISTORY	02446
	SLJ (4T)	ZRO (0)	• RETURN	02447
4R	EQS (HIS2)	SLJ (4T)	• HIS2 NO --JUMP 4T	02450
	ENA (0)	STA (HIS2)	• RESET HS12	02451
	STA (HISTORY)	SLJ (4T)	• RESET HISTORY RETURN	02452

* STOP AND CRITIQUE ROUTINE

1S	EXF (77403B)	ENA (0)	• TURN OFF STOP LT	02453
	STA (NPTS)	STA (NTRACKS)	• SET NPTS AND NTRACKS	02454
	ENA (1)	STA (MOD)	• SET MOD	02455
	ENI 6 (1)	LIL 3 (NTRACKS)	• SET INDEXES	02456
	ENA (E68)	SLJ 4 (1MSG)	• GRAPH BEING PLOTTED MSG	02457
9991	BACKSPACE MM			02460
	READ TAPE MM, XN,YN,ZN,	TFLAG		02461
	SLJ 4 (1N)	ZRO (0)	• UPDATE GRAPH TITLE	02462
	LDA (TFLAG)	SUB (MTIME)	• DETERMINE IF THIS GRAPH	02463

APPENDIX I-C

91	AJP 6 (12S1)	ENI (0)	•	WILL EXCEED MAX TIME	02464
	REWIND MM				02465
	RAO (NTRACKS)	LIL 3 (NTRACKS)	•	INCREASE NTRACKS	02466
991	READ TAPE MM, XN,YN,ZN,JTIME				02467
	LDA 3 (XN)	AJP 1 (L+3)	•	IS X ZERO NO JUMP	02470
	LDA 3 (YN)	AJP 1 (L+2)	•	IS Y ZERO NO JUMP	02471
	SLJ (4S1)	ZRO (0)	•	BOTH X AND Y ZERO JUMP	02472
	LDA 3 (ZN)	AJP 7 (13S1)	•	JUMP IF SUBMARINE	02473
	STA 6 (Y)	LDA (JTIME)	•	STORE Z DATA	02474
	SUB (FTIME)	SLJ 4 (FLOAT)	•	CHANGE TIME TO MIN	02475
	FDV (60.)	STA 6 (X)	•	STORE TIME	02476
	RAO (NPTS)	LDA (JTIME)	•	INCREASE NPTS	02477
	SUB (TFLAG)	AJP (5S1)	•	MORE TIME NO JUMP	02500
	AJP 2 (5S1)	ENA (1603B)	•	MORE POINTS YES JUMP	02501
	THS (NPTS)	SLJ (6S1)	•		02502
2S11	ENA (NPTS)	SAL (DRAW+1)	•	FILL DRAW ARGUMENTS	02503
	ENA (X)	SAL (DRAW+2)	•		02504
	ENA (Y)	SAL (DRAW+3)	•		02505
	ENA (MOD)	SAL (DRAW+4)	•		02506
	ENA (SIC)	SAL (DRAW+5)	•		02507
	ENA (LABEL)	SAL (DRAW+6)	•		02510
	ENA (ITITLE)	SAL (DRAW+7)	•		02511
	ENA (XSCALE1)	SAL (DRAW+8)	•		02512
	ENA (YSCALE1)	SAL (DRAW+9)	•		02513
	ENA (IXUP1)	SAL (DRAW+10)	•		02514
	ENA (IYRT1)	SAL (DRAW+11)	•		02515
	ENA (MODXAX1)	SAL (DRAW+12)	•		02516
	ENA (MODYAX1)	SAL (DRAW+13)	•		02517
	ENA (IWIDE1)	SAL (DRAW+14)	•		02520
	ENA (IHIGH1)	SAL (DRAW+15)	•		02521
	ENA (IGRID)	SAL (DRAW+16)	•		02522
	ENA (LAST)	SAL (DRAW+17)	•		02523
	SLJ 4 (DRAW)	ZRO (0)	•	JUMP TO DRAW	02524
	ENI 5 (300)	ENA (0)	•	CLEAR ARRAY	02525
	STA 5 (X)	STA 5 (Y)	•		02526
	IJP 5 (L-1)	ENI (0)	•	LOOP	02527

APPENDIX I-C

2S12	LDA (LAST)	AJP 1 (7S1)	• CHECK TO SEE IF GOOD GRAPH	02530
	ENA (3)	ENI (0)	• IS MOD = 3	02531
	EGS (MOD)	SLJ (L+2)		02532
3S1	SLJ (1S1)	ZRO (0)	• YES JUMP TO X-Y PLOT	02533
	ENA (2)	STA (MOD)	• SET MOD = 2	02534
	ENA (0)	STA (NPTS)	• SET NPTS TO ZERO	02535
	LDA (JTIME)	SUB (TFLAG)	• MORE TIME	02536
	AJP (9S1)	AJP 2 (9S1)	• NO JUMP TO REWIND	02537
4S1	ENI 6 (1)	SLJ (991)	• YES JUMP TO READ	02540
	ENA (2)	ENI (0)	• IS NPTS .GT. 2	02541
	THS (NPTS)	SLJ (10S1)	• NO - IGNORE GRAPH	02542
	LDA (JTIME)	SUB (TFLAG)	• AND JUMP TO READ	02543
	AJP (5S1)	AJP 2 (5S1)	• MORE TIME NO JUMP	02544
5S1	SLJ (2S11)	ZRO (0)	• YES JUMP TO GRAPH	02545
	ENA (15)	ENI (0)	• CHECK FOR LAST TRACK	02546
	EGS (NTRACKS)	SLJ (11S1)	• LAST TRACK NO JUMP	02547
	ENA (3)	STA (MOD)	• YES SET MOD = 3	02550
6S1	SLJ (2S11)	ZRO (0)	• JUMP TO GRAPH	02551
7S1	INI 6 (1)	SLJ (991)	• INCREASE INDEX JUMP TO READ	02552
	LDA (LAST)	SUB (2B)	• LAST = 2	02553
	AJP 1 (2S12)	STA (NPTS)	• NO JUMP TO MOD CHECK	02554
	ENA (1)	STA (MOD)	• RESET NPTS AND MOD	02555
	ENI 6 (1)	LDA (JTIME)	• AND INDEX	02556
	SUB (TFLAG)	AJP (991)	• MORE TIME	02557
8S1	AJP 2 (991)	SLJ (91)	• YES JUMP TO REWIND	02560
9S1	SLJ (1S1)	ZRO (0)	• NO JUMP TO X-Y POSIT PLOT	02561
	ENA (0)	STA (NPTS)	• RESET NPTS	02562
10S1	ENI 6 (1)	SLJ (91)	• RESET INDEX JUMP TO REWIND	02563
	ENA (0)	STA (NPTS)	• RESET NPTS AND INDEX	02564
11S1	ENI 6 (1)	SLJ (991)	• JUMP TO READ	02565
	ENA (2)	ENI (0)	• NPTS .GT. TWO	02566
	THS (NPTS)	SLJ (9S1)	• NO JUMP TO GRAPH	02567
	SLJ (2S11)	ZRO (0)	• YES JUMP TO GRAPH	02570

APPENDIX I-C

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* RESET BASE TIME ROUTINE
12S1  SLJ  (N)          LDA  (JTIME)      • EXIT/ENTRY      02571
      STA  (FTIME)     ENA  (1800)      • SET FTIME TO LAST JTIME 02572
      RAD  (MTIME)     SLJ  (12S1)      • INCREASE MAX TIME RETURN 02573

*SCALE SUBMARINE DEPTH ROUTINE
13S1  SLJ  (N)          FMU  (SCALE)      • EXIT/ENTRY      02574
      SLJ  (13S1)     ZRO  (0)        • SCALE RETURN     02575

* X-Y PLOT ROUTINE
1S1   LIL 3 (PPI)      ENI 6 (1)      • SET INDEXES     02576
      ENA  (0)         STA  (NPTS)    • SET NPTS        02577
      ENA  (1)         STA  (MOD)     • RESET MOD TO ONE =0 02600
1S2   LDA 3 (X1)      AJP 1 (L+3)    • IS X ZERO NO JUMP 02601
      LDA 3 (Y1)      AJP 1 (L+2)    • IS Y ZERO NO JUMP 02602
      SLJ  (L+5)      ZRO  (0)       • BOTH X AND Y ZERO JUMP 02603
      LDA 3 (X1)      STA 6 (X)     • STORE X DATA   02604
      LDA 3 (Y1)      STA 6 (Y)     • STORE Y DATA   02605
      ISK 6 (30)      SLJ  (L+2)    • CHECK FOR NPTS = 30 02606
      SLJ  (1S3)      ZRO  (0)       • JUMP TO GRAPH   02607
      IJP 3 (1S2)     SIL 6 (NPTS)   •
      SLJ  (L+2)      ZRO  (0)       •
1S3   ENA  (30)       STA  (NPTS)    • SET NPTS EQUAL TO THIRTY 02610
      ENA  (NPTS)     SAL  (DRAW+1)  • FILL DRAW ARGUMENTS 02611
      ENA  (X)        SAL  (DRAW+2)  •
      ENA  (Y)        SAL  (DRAW+3)  •
      ENA  (MOD)      SAL  (DRAW+4)  •
      ENA  (F5)       SAL  (DRAW+5)  •
      ENA  (LABLE)    SAL  (DRAW+6)  •
      ENA  (KTITLE)   STA  (DRAW+7)  •
      ENA  (XSCALE)   SAL  (DRAW+8)  •
      ENA  (YSCALE)   SAL  (DRAW+9)  •
      ENA  (IXUP)     SAL  (DRAW+10) •
  
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APPENDIX I-C

ENA	(YSCALE)	SAL	(DRAW+9)	•	02671
ENA	(IXUP)	SAL	(DRAW+10)	•	02672
ENA	(IYRIGHT)	SAL	(DRAW+11)	•	02673
ENA	(MODEXAX)	SAL	(DRAW+12)	•	02674
ENA	(MODEYAX)	SAL	(DRAW+13)	•	02675
ENA	(IWIDE)	SAL	(DRAW+14)	•	02676
ENA	(IHIGH)	SAL	(DRAW+15)	•	02677
ENA	(IGRID)	SAL	(DRAW+16)	•	02700
ENA	(LAST)	SAL	(DRAW+17)	•	02701
SLJ	4 (DRAW)	ZRO	(0)	•	02702
ENI	5 (50)	ENA	(0)	•	02703
STA	5 (X)	STA	5 (Y)	•	02704
IJP	5 (L-1)	LDA	(LAST)	•	02705
EQS	(2B)	SLJ	(L+5)	•	02706
ENA	(1)	STA	(MOD)	•	02707
ENI	6 (1)	IJP	3 (1S4)	•	02710
ENA	(1)	STA	(PPI)	•	02711
SLJ	(L+4)	ZRO	(0)	•	02712
ENA	(1)	STA	(MOD)	•	02713
ENI	6 (1)	IJP	3 (1S4)	•	02714
SLJ	(L-4)	ZRO	(0)	•	02715
ENA	(0)	STA	(NPTS)	•	02716
STA	(NTRACKS)	LIL	3 (NTRACKS)	•	02717
REWIND	MM				02720
RAO	(NTRACKS)	LIL	3 (NTRACKS)	•	02721
READ	TAPE MM, XN, YN, ZN, JTIME				02722
LDA	3 (XN)	AJP	1 (L+3)	•	02723
LDA	3 (YN)	AJP	1 (L+2)	•	02724
SLJ	(4S)	ZRO	(0)	•	02725
LDA	3 (XN)	STA	6 (X)	•	02726
LDA	3 (YN)	STA	6 (Y)	•	02727
RAO	(NPTS)	LDA	(JTIME)	•	02730
SUB	(TFLAG)	AJP	(5S)	•	02731
AJP	2 (5S)	ENA	(1603B)	•	02732
THS	(NPTS)	SLJ	(6S)	•	02733
ENA	(NPTS)	SAL	(DRAW+1)	•	02734

•	JUMP TO DRAW	
•	CLEAR ARRAY	
•	LOOP	
•	CHECK FOR LAST EQUAL TWO	
•	RESET MOD EQUAL ONE	
•	CHECK FOR MORE POINTS	
•	RESET PPI TO ONE	
•	SET MOD	
•	CHECK FOR MORE POINTS	
•	INCREASE NTRACKS	
•	IS X ZERO NO JUMP	
•	IS Y ZERO NO JUMP	
•	BOTH X AND Y ZERO JUMP	
•	STORE X DATA	
•	STORE Y DATA	
•	INCREASE NPTS	
•	MORE TIME NO JUMP	
•	MORE POINTS YES JUMP	
•	FILL DRAW ARGUMENTS	

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APPENDIX I-C

6S	ENA (3)	STA (MOD)	• YES SET MOD = 3	03001
	SLJ (2S)	ZRO (0)	• JUMP TO GRAPH	03002
7S	INI 6 (1)	SLJ (99)	• INCREASE INDEX JUMP TO READ	03003
	LDA (LAST)	SUB (2B)	• LAST = 2	03004
	AJP 1 (2S1)	STA (NPTS)	• NO JUMP TO MOD CHECK	03005
	ENA (1)	STA (MOD)	• RESET NPTS AND MOD	03006
	ENI 6 (1)	LDA (JTIME)	• AND INDEX	03007
	SUB (TFLAG)	AJP (L+2)	• MORE TIME	03010
	AJP 2 (L+1)	SLJ (9)	• YES JUMP TO REWIND	03011
8S	SLJ (LEND)	ZRO (0)	• NO JUMP TO X-Y POSIT PLOT	03012
9S	ENI 6 (1)	SLJ (9)	• RESET INDEX JUMP TO REWIND	03013
10S	ENA (0)	STA (NPTS)	• RESET NPTS AND INDEX	03014
	ENI 6 (1)	SLJ (99)	• JUMP TO READ	03015
11S	ENA (2)	ENI (0)	• NPTS .GT. TWO	03016
	THS (NPTS)	SLJ (9S)	• NO JUMP TO GRAPH	03017
	SLJ (2S)	ZRO (0)	• YES JUMP TO GRAPH	03020

* STATE ROUTINE

1ST	EXF (77521B)	SLJ (L+4)	• TURN OFF STATE LT	03021
2ST	ZRO (0)	ZRO (0)	• CAP NUMBER	03022
3ST	ZRO (0)	ZRO (0)	• TRACK NUMBER	03023
4ST	ZRO (0)	ZRO (0)	• TYPE OF INTERCEPTOR	03024
	LDA (2ST)	SLJ 4 (1Y)	• DETERMINE CAP TRACK NR	03025
	SIL 2 (3ST)	SLJ 4 (INUM)	• STROE CAP TRACK NR	03026
	ALS (6)	ADD (R5)	• ASSEMBLE INITIAL MSG	03027
	SCL (77B)	STA (E86)	• SEND INITIAL MSG	03030
	ENA (E84)	SLJ 4 (IMSG)	• DETERMINE MAX WPNS	03031
	LDQ 2 (TRACK)	LDL (MASK4B)		03032
	ARS (39)	STA (4ST)		03033
	LIL 2 (4ST)	LDQ 2 (IFIG0)		03034
	LDL (MASK35)	ARS (27)		03035
	STA (T+9)	ARS (3)		03036
	ENQ (7B)	ADL (T+9)		03037
	ARS (1)	STA (WPNS)	• DIVIDE MAX WPNS BY 2 AND STORE	03040
	LIL 3 (3ST)	LDQ 3 (KFIG)		03041

LDL	(MASK35)	ARS	(27)	•		03042
STA	(T+9)	ARS	(3)	•		03043
ENQ	(7B)	ADL	(T+9)	•		03044
AJP	(5ST)	ENI	(0)	•	AMMO ZERO	03045
THS	(WPNS)	SLJ	(6ST)	•	AMMO PLUS	03046
LDA	(R21)	STA	(E88)	•	AMMO MINUS	03047
SLJ	(7ST)	ZRO	(0)	•		03050
LDA	(R22)	STA	(E88)	•	AMMO ZERO	03051
SLJ	(7ST)	ZRO	(0)	•		03052
LDA	(R23)	STA	(E88)	•	AMMO PLUS	03053
LDA	3 (KFIG)	ARS	(33)	•	DETERMINE TIME OF REPORT	03054
SLJ	4 (INUM)	ZRO	(0)	•		03055
ADD	(R24)	STA	(E91)	•		03056
LDA	(ITIME)	ENQ	(0)	•		03057
DVI	(60)	ENI	2 (0)	•		03060
THS	(59)	SLJ	(L+2)	•	CHECK HOURS	03061
SLJ	(L+3)	ZRO	(0)	•		03062
SUB	(60)	INI	2 (100)	•		03063
SLJ	(L-3)	ZRO	(0)	•		03064
ADD	(ZTIME)	INA	2 (0)	•		03065
SLJ	4 (INUM)	ZRO	(0)	•		03066
ALS	(24)	ADD	(R25)	•		03067
SCL	(77B)	STA	(E94)	•		03070
ENA	(E87)	SLJ	4 (1MSG)	•	SEND REPORT	03071
LDA	(45T)	SLJ	4 (1NUM)	•	DETERMINE TYPE	03072
ADD	(R26)	STA	(E82)	•		03073
ENA	(E82)	SLJ	4 (1MSG)	•	SEND TYPE MSG	03074
SLJ	(4T)	ZRO	(0)	•	RETURN	03075
* SELECT INTERRUPTS AND INITIALIZING						
OT	EXF (04000B)	EXF	(77105B)	•	ALLOW SELECTED INTERRUPTS	03076
	EXF (77103B)	EXF	(00100B)	•	KEYBD1, KEYBD2, AND ARITHMETIC	03077
	ENA (1A)	SAL	(Z+7B)	•	RESET INTERRUPT ADDRESS	03100
	ENA (400)	STA	(ADD)	•	MEMORY ADDRESS DD65 FOR MSG	03101
	ENA (-377B)	STA	(XPI)	•	LEFT SIDE OF PAGE	03102

ENA	(377B)	STA	(YP1)	• FIRST LINE OF PRINT	03103
ENA	(365B)	STA	(YP2)	• SECOND LINE OF PRINT	03104
ENA	(353B)	STA	(YMSG)	• FIRST LINE OF PRINT FOR MSG	03105
ENA	(44B)	STA	(MM)	• MEMORY INDICATOR	03106
ENA	(0)	STA	(IFLAG)	• SET I-FLAG =0	03107
STA	(NEG)	STA	(DFLAG)	• SET NEG AND D-FLAG =0	03110
STA	(RAW)	STA	(PFLAG)	• SET RAW AND P-FLAG =0	03111
STA	(HSUB)	STA	(HSUR)	• SET HSUB AND HSUR =0	03112
STA	(HAC)	STA	(FAC)	• SET HAC AND FAC =0	03113
STA	(FSUB)	STA	(FSUR)	• SET FSUB AND FSUR =0	03114
STA	(FTIME)	ENA	(1)	• SET SUBTRACT TIME =0	03115
STA	(KNR2)	STA	(PRO)	• SET KNR2 AND PRO =1	03116
STA	(KNR1)	STA	(KNR)	• SET KNR1 AND KNR =1	03117
ENA	(20)	STA	(NPROG)	• NUMBER OF CALLABLE PROGRAMS	03120
ENA	(6)	STA	(MK)	• NUMBER OF EXECUTIVE ROUTINES	03121
ENA	(1800)	STA	(MTIME)	• SET MAX TIME FOR GRAPH	03122
ENA	(0)	STA	(COUNTER)	• DUTY CYCLE CARD	03123
LDA	(R27)	STA	(GTIME)	• INITIALIZE GTIME	03124
ENI	4 (15)	ENA	(52B)	• SET ALL TRACKS TO NON ACTIVE	03125
STA	4 (TRACK)	IJP	4 (L)	• LOOP	03126
READ	102, JTITLE				03127
LDA	(JTITLE)	STA	(TITLE7)	• SET DATE IN GRAPH TITLE	03130
STA	(TITLE19)	ENI	(0)		03131
READ	101, LABEL, XSCALE, YSCALE, IXUP, IYRIGHT, MODEXAX, MODEYAX, IWIDE, IHIGH, IGRID				03132
*	READ 101, LABEL, XSCALE1, YSCALE1, IXUP1, IYRT1, MODXAX1, MODYAX1, IWIDE1, IHIGH1, IGRID				03133
READ	103, SCALE				03134
READ	104, IP, IPP				03135
ENA	(1)	STA	(IETT+1)	• INITIALIZE ---	03136
ENA	(1)	STA	(ILEFT+1)	• EXECUTIVE	03137
ENA	(600)	STA	(ILEFT+5)	• TABLES	03140
LDA	(IP)	STA	(ILEFT+2)		03141
STA	(IETT+2)	STA	(IETT+3)		03142
STA	(IETT+4)	STA	(IETT+6)		03143
INA	(1)	STA	(ILEFT+6)		03144

APPENDIX I-C

ZRO	(5)	ZRO	(P4)	• ERROR	03203
ZRO	(4)	ZRO	(P5)	• HOLD	03204
ZRO	(4)	ZRO	(P6)	• SKIP	03205
ZRO	(7)	ZRO	(P7)	• DISPLAY	03206
ZRO	(4)	ZRO	(P8)	• DROP	03207
ZRO	(8)	ZRO	(P9)	• NOT USED	03210
ZRO	(4)	ZRO	(P10)	• STOP	03211
ZRO	(5)	ZRO	(P11)	• STEER	03212
ZRO	(5)	ZRO	(P12)	• DESIG	03213
ZRO	(4)	ZRO	(P13)	• INFO	03214
ZRO	(8)	ZRO	(P14)	• NOT USED	03215
ZRO	(5)	ZRO	(P15)	• GRAPH	03216
ZRO	(7)	ZRO	(P16)	• STATION	03217
ZRO	(6)	ZRO	(P17)	• CHANGE	03220
ZRO	(5)	ZRO	(P18)	• STATE	03221
ZRO	(8)	ZRO	(P19)	• NOT USED	03222
ZRO	(8)	ZRO	(P20)	• READY LT	03223
ZRO	(4)	ZRO	(P21)	• FADE	03224
ZRO	(6)	ZRO	(P22)	• UNFADE	03225
ZRO	(5)	ZRO	(P23)	• START	03226
ZRO	(5)	ZRO	(P24)	• SCRUB	03227
ZRO	(4)	ZRO	(P25)	• PORT	03230
ZRO	(4)	ZRO	(P26)	• STBD	03231
ZRO	(5)	ZRO	(P27)	• SPEED	03232
ZRO	(8)	ZRO	(P28)	• ALTITUDE	03233
ZRO	(8)	ZRO	(P29)	• NOT USED	03234

* TRACK GENERATOR CALLING ROUTINE

1TG	SIU 4 (3TG)	SIL 5 (3TG)	• SAVE INDEXES	03235
	SLJ 4 (TRAKGEN)	ZRO (0)	• CALL TRAKGEN	03236
	ENI 4 (1)	ENI (0)	•	03237
2TG	LDQ 4 (IPOSIT)	LDL (MASKX)	• UNPACK IPOSIT	03240
	ARS (24)	SLJ 4 (FLOAT)	• UNSCALE X-POSITION	03241
	FDV (SCALE1)	STA 4 (XN)	• STORE IN XN	03242
	LDQ 4 (IPOSIT)	ENI (0)	•	03243

APPENDIX I-C

LDL	(MASKY)	ALS	(24)	UNSCALE Y-POSITION	03244
ARS	(24)	SLJ	4 (FLOAT)	• STORE IN YN	03245
FDV	(SCALE1)	STA	4 (YN)	•	03246
LDQ	4 (JHEAD)	ENI	(0)	• UNPACK JHEAD	03247
LDL	(MASKY)	ALS	(24)	• UNSCALE Z-POSITION	03250
ARS	(24)	SLJ	4 (FLOAT)	• STORE IN ZN	03251
FDV	(SCALE2)	STA	4 (ZN)	•	03252
ISK	4 (15)	SLJ	(2TG)	• LOOP	03253
LDA	(TIME)	STA	(KTIME)	•	03254
WRITE	TAPE MM, XN,YN,ZN,TIME			•	03255

* ADD NOISE ROUTINE HERE OR BEFORE WRITE TAPE

3TG	ENI	4 (N)	ENI	5 (N)	• RESTORE INDEXES	03256
	SLJ	(4T)	ZRO	(0)	• RETURN	03257

* INFO ROUTINE

1TT	EXF	(77421B)	SLJ	(L+2)	• TURN OFF INFO LT	03260
2TT	ZRO	(0)	ZRO	(0)	• TRACK FOR INFO	03261
	ENA	(2TT)	SLJ	4 (3J0)	• HOOK TRACK	03262
	ENA	(E73)	SLJ	4 (1MSG)	• OUTPUT TITLE	03263
	LDA	(2TT)	SLJ	4 (1NUM)	•	03264
	ALS	(36)	SCL	(MASKY)	•	03265
	STA	(E77)	ENA	(E75)	•	03266
3TT	SLJ	4 (1MSG)	ZRO	(0)	• OUTPUT TRACK NUMBER	03267
	LDA	(2TT)	ENI	(0)	• CHECK FOR OWN SHIP	03270
	EQS	(OWN)	SLJ	(L+2)	•	03271
	SLJ	(14TT)	ZRO	(0)	• OWN SHIP JUMP	03272
	LIL	3 (2TT)	LDA	3 (TRACK)	•	03273
	STA	(2TT)	ENI	(0)	•	03274
	SSH	(2TT)	SLJ	(9TT)	• JUMP ON HOSTILE	03275
	SSH	(2TT)	SLJ	(5TT)	• JUMP ON NOT SURFACE	03276
	LDA	3 (TRACK)	STA	(2TT)	• SURFACE TRACK	03277
	LDA	(R12)	STA	(E79)	•	03300
	LDQ	(2TT)	GRS	(24)	•	03301

APPENDIX I-C

4TT	LDL (777B)	SLJ 4 (1NUM)	•	03302
	SAL (3TT)	LDQ (3TT)	•	03303
	LDL (77B)	ADD (R18)	•	03304
	STA (E80)	ENA (0)	•	03305
	STA (E81)	ENA (E78)	•	03306
	SLJ 4 (1MSG)	ZRO (0)	•	03307
	LDA 3 (CRS)	SLJ 4 (FIX)	•	03310
	SLJ 4 (1NUM)	ZRO (0)	•	03311
	ALS (6)	ADD (R7)	•	03312
	STA (E79)	LDA 3 (SPD)	•	03313
	SLJ 4 (FIX)	ZRO (0)	•	03314
	SLJ 4 (1NUM)	ZRO (0)	•	03315
	LRS (6)	ADD (MASK17)	•	03316
	ADD (R8)	STA (E80)	•	03317
	ENA (0)	LLS (6)	•	03320
	ALS (42)	ADD (R15)	•	03321
	STA (E81)	ENA (0)	•	03322
	STA (E82)	ENA (E78)	•	03323
	SLJ (12TT)	ZRO (0)	•	03324
5TT	SSH (2TT)	SLJ (7TT)	•	03325
	LDA 3 (TRACK)	STA (2TT)	•	03326
	LDQ (2TT)	QRS (24)	•	03327
	LDL (777B)	SLJ 4 (1NUM)	•	03330
	ADD (R5)	STA (E79)	•	03331
	ENA (0)	STA (E80)	•	03332
	ENA (E78)	SLJ 4 (1MSG)	•	03333
6TT	LDA 3 (CRS)	SLJ 4 (FIX)	•	03334
	SLJ 4 (1NUM)	ZRO (0)	•	03335
	ALS (6)	ADD (R7)	•	03336
	STA (E79)	LDA 3 (SPD)	•	03337
	SLJ 4 (FIX)	ZRO (0)	•	03340
	SLJ 4 (1NUM)	ZRO (0)	•	03341
	LRS (6)	ADD (MASK17)	•	03342
	ADD (R8)	STA (E80)	•	03343
	ENA (0)	LLS (6)	•	03344
	ALS (42)	ADD (R9)	•	03345

•

SURFACE INFO

•

OUTPUT SURFACE INFO

•

JUMP ON NO A/C

•

A/C TRACK

•

A/C INFO

•

APPENDIX I-C

10TT	SUB	(20B)	ADD	(E78)	•	03412
	ADD	(R16)	STA	(E79)	•	03413
	ENA	(0)	STA	(E80)	•	03414
	ENA	(E78)	SLJ 4	(IMSG)	•	03415
	SLJ	(4TT)	ZRO	(0)	•	03416
	SSH	(2TT)	SLJ	(11TT)	•	03417
	LDA 3	(TRACK)	STA	(2TT)	•	03420
	LDQ	(2TT)	QRS	(24)	•	03421
	LDL	(777B)	SLJ 4	(INUM)	•	03422
	ALS	(36)	SCL	(77B)	•	03423
	STA	(E80)	LDA	(R11)	•	03424
	STA	(E79)	ENA	(0)	•	03425
	STA	(E81)	ENA	(E78)	•	03426
	SLJ 4	(IMSG)	ZRO	(0)	•	03427
	SLJ	(6TT)	ZRO	(0)	•	03430
11TT	SSH	(2TT)	SLJ	(13TT)	•	03431
	LDA 3	(TRACK)	STA	(2TT)	•	03432
	LIU 5	(2TT)	LDA 5	(F11)	•	03433
	SUB	(20B)	ADD	(E78)	•	03434
	ADD	(R17)	STA	(E79)	•	03435
	ENA	(0)	STA	(E80)	•	03436
	ENA	(E78)	SLJ 4	(IMSG)	•	03437
	SLJ	(8TT)	ZRO	(0)	•	03440
12TT	SLJ 4	(IMSG)	ZRO	(0)	•	03441
	LDA 3	(ZN)	STA	(ZTAR)	•	03442
	LDA 3	(XN)	STA	(XTAR)	•	03443
	LDA 3	(YN)	STA	(YTAR)	•	03444
	LIL 3	(OWN)	LAC 3	(XN)	•	03445
	FAD	(XTAR)	STA	(XTAR)	•	03446
	LAC 3	(YN)	FAD	(YTAR)	•	03447
	STA	(YTAR)	ENA	(XTAR)	•	03450
	SAL	(COURSE+1)	ENA	(YTAR)	•	03451
	SAL	(COURSE+2)	ENA	(DTAR)	•	03452
	SAL	(COURSE+3)	ENA	(S6C)	•	03453
	SAL	(COURSE+5)	ENA	(RTAR)	•	03454
	SAL	(COURSE+6)	SLJ 4	(COURSE)	•	03455

• JUMP TO SURFACE INFO

• JUMP ON NOT A/C

• HOSTILE A/C TRACK

• JUMP-TP A/C INFO

• JUMP ON NON DESIGNATED TRACK

• HOSTILE SUBMARINE TRACK

• JUMP TO SUBMARINE INFO

• OUTPUT ALL MSG ROUTINE

• JUMP TO COURSE

APPENDIX I-C

LDA	(DTAR)	AJP	(4T)	•	RETURN OWN SHIP	03456
LDA	(E96)	STA	(E79)	•	FORM RANGE MSG	03457
LDA	(ZTAR)	AJP	(L+2)	•		03460
AJP	2 (L+6)	ENI	(0)	•		03461
LDA	(RTAR)	FMU	(2000.)	•		03462
SLJ	4 (FIX)	ZRO	(0)	•		03463
SLJ	4 (INUM)	ZRO	(0)	•		03464
STA	(E80)	LDA	(E105)	•		03465
SLJ	(L+4)	ZRO	(0)	•		03466
LDA	(RTAR)	SLJ	4 (FIX)	•		03467
SLJ	4 (INUM)	ZRO	(0)	•		03470
STA	(E80)	LDA	(E97)	•		03471
STA	(E81)	ENA	(E78)	•		03472
SLJ	4 (1MSG)	ZRO	(0)	•	OUTPUT RANGE MSG	03473
LDA	(E98)	STA	(E79)	•		03474
LDA	(DTAR)	SLJ	4 (FIX)	•		03475
SLJ	4 (INUM)	ZRO	(0)	•		03476
STA	(E80)	LDA	(E99)	•		03477
STA	(E81)	ENA	(0)	•		03500
STA	(E82)	ENA	(E78)	•		03501
SLJ	4 (1MSG)	ZRO	(0)	•	OUTPUT BEARING MESSAGE	03502
LDA	(OWN)	AJP	1 (L+6)	•	JUMP IF OWN SHIP REFERENCE	03503
LDA	(E102)	STA	(E79)	•		03504
LDA	(E103)	STA	(E80)	•		03505
LDA	(E104)	STA	(E81)	•		03506
ENA	(E78)	SLJ	4 (1MSG)	•	OUTPUT REFERENCE MESSAGE	03507
SLJ	(4T)	ZRO	(0)	•	RETURN	03510
LDA	(E100)	STA	(E79)	•		03511
LDA	(E101)	STA	(E80)	•		03512
SLJ	(L-4)	ZRO	(0)	•		03513
LDA	(R19)	STA	(E79)	•	UNIDENTIFIED TRACK	03514
LDA	(R20)	STA	(E80)	•		03515
ENA	(0)	STA	(E81)	•		03516
ENA	(E78)	SLJ	4 (1MSG)	•		03517
LDA	3 (ZN)	AJP	(4TT)	•	JUMP ACCORDING TO ALTITUDE	03520
AJP	2 (6TT)	AJP	3 (8TT)	•		03521

13TT

APPENDIX I-C

14TT	ENA	(E95)	STA	(E79)	•	03522
	ENA	(0)	STA	(E80)	•	03523
	SLJ	4 (1MSG)	ZRO	(0)	•	03524
	SLJ	(4TT)	ZRO	(0)	•	03525

• OUTPUT OWN SHIP INFO
• JUMP TO SURFACE INFO

* STEER COMMAND ROUTINE

1U	EXF	(77405B)	SLJ	(L+2)	•	03526
2U	ZRO	(0)	ZRO	(0)	•	03527
	LDA	(2U)	SLJ	4 (1Y)	•	03530
	LDA	(MASK22)	RAD	2 (TRACK)	•	03531
	SLJ	(4T)	ZRO	(0)	•	03532

• TURN OFF STEER LT
• CAP NUMBER
• DETERMINE CAP TRACK NR
• SET STEER BIT
• RETURN

* STATION COMMAND ROUTINE

1V	EXF	(77505B)	SLJ	(L+4)	•	03533
2V	ZRO	(0)	ZRO	(0)	•	03534
3V	ZRO	(0)	ZRO	(0)	•	03535
4V	ZRO	(0)	ZRO	(0)	•	03536
	ENA	(2V)	SLJ	4 (1ZZ)	•	03537
	LDA	(MASK20)	RAD	2 (TRACK)	•	03540
	SLJ	(4T)	ZRO	(0)	•	03541

• TURN OFF STATION LT
• CAP NUMBER
• RANGE FROM CARRIER
• BEARING DEGREES TRUE
• DETERMINE CAP TRACK NR
• SET STATION BIT
• RETURN

* SKIP INTERCEPT COMMAND ROUTINE

1W	EXF	(77205B)	SLJ	(L+2)	•	03542
2W	ZRO	(0)	ZRO	(0)	•	03543
	LDA	(2W)	SLJ	4 (1Y)	•	03544
	LDQ	(MASK19)	LDL	2 (TRACK)	•	03545
	AJP	(3W)	LDA	(MASK21)	•	03546
	RAD	2 (TRACK)	SLJ	(4T)	•	03547
3W	LDA	(2W)	SLJ	4 (1NUM)	•	03550
	STA	(T+1)	LDA	(R5)	•	03551
	RAD	(T+1)	STA	(E63)	•	03552
	ENA	(E63)	SLJ	4 (1MSG)	•	03553
	SLJ	(4T)	ZRO	(0)	•	03554

• TURN OFF INTcpt LT
• CAP TO SKIP
• DETERMINE CAP TRACK NR
• IS CAP MAKING AN INTERCEPT
• NO JUP -- YES SET SKIP BIT
• RETURN
• SEND MSG
• CAP XX NOT
• MAKING
• INTERCEPT
• RETURN

* LAUNCH COMMAND ROUTINE

1X	EXF	(77211B)	SLJ	(L+5)	•	TURN OFF LAUNCH LT	03555
2X	ZRO	(0)	ZRO	(0)	•	CAP NUMBER	03556
3X	ZRO	(0)	ZRO	(0)	•	RANGE	03557
4X	ZRO	(0)	ZRO	(0)	•	BEARING DEGREES TRUE	03560
5X	ZRO	(0)	ZRO	(0)	•	TYPE OF INTERCEPTOR	03561
	ENI	2 (16)	LDQ	(MASK11)	•		03562
	ENA	(52B)	ENI	(0)	•		03563
	MEQ	2 (TRACK)	SLJ	(5Q)	•	SEARCH FOR NON ACTIVE TRACK	03564
	LDA	(MASK9L)	STA	2 (TRACK)	•	SET CAP BITS	03565
	LDA	(MASK20)	RAD	2 (TRACK)	•		03566
	ENA	(2X)	SLJ	4 (1X1)	•	GET CAP NUMBER	03567
	LDA	(2X)	ALS	(24)	•		03570
	RAD	2 (TRACK)	ENI	(0)	•	SET CAP NUMBER	03571
	ENA	(2X)	SLJ	4 (1ZZ)	•	DETERMINE STATION INFO	03572
	LDA	(5X)	AJP	(7X)	•	JUMP IF NO TYPE GIVEN	03573
	INA	(-1)	AJP	(7X)	•	INITIALIZE	03574
	INA	(1)	ENI	(0)	•	INTERCEPTOR TYPE	03575
	ALS	(39)	RAD	2 (TRACK)	•	FUEL	03576
	LIL	5 (5X)	LDA	5 (IFIG0)	•	AND	03577
6X	STA	2 (KFIG)	LDA	(ITIME)	•	LAUNCH TIME	03600
	RAD	2 (KFIG)	SLJ	(4T)	•		03601
7X	LDA	(MASK4B)	RAD	2 (TRACK)	•	MAKE INTECEPTOR F4	03602
	LDA	(IFIG7)	SLJ	(6X)	•		03603

* DETERMINE FRIENDLY A/C NUMBER ROUTINE

1X1	SLJ	(N)	STA	(T+8)	•	EXIT/ENTRY	03604
	LDA	7 (T+8)	ENI	(0)	•	CHECK TO SEE IF NUMBER .GT.	03605
	THS	(FAC)	SLJ	(L+3)	•	FAC YES JUMP NO USE FAC	03606
	RAO	(FAC)	STA	7 (T+8)	•		03607
	SLJ	(1X1)	ZRO	(0)	•	RETURN	03610
	STA	(FAC)	SLJ	(1X1)	•	SET NEW FAC RETURN	03611

* FIND CAP NUMBER ROUTINE

1Y	SLJ (N)	STA (2Y)	EXIT/ENTRY	03612
	ENI 2 (1)	ENI (0)		03613
	SSK 2 (TRACK)	SLJ (L+7)	CHECK FOR FRIENDLY	03614
	LDQ 2 (TRACK)	LDA (MASK16)	CHECK FOR A/C BIT	03615
	MEQ (MASK16)	SLJ (L+5)		03616
	LDQ 2 (TRACK)	QRS (24)		03617
	LDL (77B)	ENI (0)		03620
	EQS (2Y)	SLJ (L+2)	CHECK FOR CAP NUMBER	03621
	SLJ (1Y)	ZRO (0)	RETURN WITH TRACK NUMBER IN B2	03622
	ISK 2 (15)	SLJ (L-7)	LOOP	03623
	LDA (2Y)	SLJ 4 (1NUM)	ERROR EXIT	03624
	ALS (6)	STA (T+1)	CAP XX NOT AIRBORNE	03625
	LDA (R5)	RAD (T+1)	MSG TO BE SENT	03626
	STA (E60)	ENA (E60)		03627
	SLJ 4 (1MSG)	ZRO (0)		03630
	SLJ (4T)	ZRO (0)	RETURN	03631
2Y	ZRO (0)	ZRO (0)	CAP NUMBER	03632

* PROGRAM ARGUMENT AND ADDRESS TABLE

0Z	ZRO (0)	ZRO (1Z)	BEGIN	03633
	ZRO (1)	ZRO (1Q)	INTCPT (INTERCEPT)	03634
	ZRO (4)	ZRO (1X)	LAUNCH	03635
	ZRO (2)	ZRO (1L)	HISTORY	03636
	ZRO (0)	ZRO (4T)	ERROR	03637
	ZRO (0)	ZRO (1PQ)	HOLD/PAUSE	03640
	ZRO (1)	ZRO (1W)	SKIP	03641
	ZRO (0)	ZRO (1D)	DISPLAY	03642
	ZRO (0)	ZRO (1R)	DROP	03643
	ZRO (0)	ZRO (2P)	NOT USED.	03644
	ZRO (0)	ZRO (1S)	STOP	03645
	ZRO (1)	ZRO (1U)	STEER	03646
	ZRO (2)	ZRO (1J)	DESIG	03647
	ZRO (0)	ZRO (1TT)	INFO	03650

APPENDIX I-C

ZRO	(0)	ZRO	(2P)	•	NOT USED	03651
ZRO	(0)	ZRO	(3GR)	•	GRAPH	03652
ZRO	(3)	ZRO	(1V)	•	STATION	03653
ZRO	(7)	ZRO	(1C)	•	CHANGE	03654
ZRO	(1)	ZRO	(1ST)	•	STATE	03655
ZRO	(0)	ZRO	(2P)	•	NOT USED	03656
ZRO	(0)	ZRO	(4T)	•	READY	03657
ZRO	(0)	ZRO	(11C)	•	FADE	03660
ZRO	(0)	ZRO	(11C)	•	UNFADE	03661
ZRO	(0)	ZRO	(10C)	•	START	03662
ZRO	(0)	ZRO	(11C)	•	SCRUB	03663
ZRO	(0)	ZRO	(13C)	•	PORT	03664
ZRO	(0)	ZRO	(13C)	•	STBD	03665
ZRO	(0)	ZRO	(12C)	•	SPEED	03666
ZRO	(0)	ZRO	(15C)	•	ALTITUDE	03667
ZRO	(0)	ZRO	(2P)	•	NOT USED	03670

OZ10

* BEGIN ROUTINE

1Z	EXF	(77203B)	EXF	(77603B)	•	TURN OFF BEGIN AND READY LTS	03671
	ENA	(1)	STA	(IFLAG)	•	SET IFLAG	03672
	LDA	(CLK)	STA	(Z)	•	RESET CLOCK	03673
	EXF	(1000B)	SLJ	4 (TRAKGEN)	•	INITIAL CALL OF TRAKGEN	03674
	AJP	3 (2Z)	ENI	(0)	•	NTRACKS GREATER THAN 16 JUMP	03675
	STA	(T+11)	LIL	4 (T+11)	•		03676
	LDA	4 (OB0)	ALS	(36)	•		03677
	STA	(R)	LDA	(E9)	•		03700
	RAD	(R)	LDA	(E10)	•	INITIAL	03701
	STA	(R+1)	LDA	(E11)	•	MESSAGE	03702
	STA	(R+2)	LDA	(E12)	•		03703
	STA	(R+3)	ENA	(R)	•		03704
	SAL	(2E)	SAU	(6E)	•		03705
	ENI	5 (1)	SLJ	(2E)	•		03706
2Z	ENA	(XP1)	SAL	(PRINT+1)	•	ERRO MSG -- NTRACKS .GT. OR	03707
	ENA	(YP2)	SAL	(PRINT+2)	•	.EO. 16 CHECK DATA DECK	03710


```

03711 ENA (1) SAL (PRINT+3) . TRY AGAIN
03712 ENA (E50) ENQ (0B) .
03713 SLJ 4 (PRINT) ZRO (0) .
03714 SLS (0T) ZRO (0) . RESTART
    
```

* CAP NUMBER AND STATION INFORMATION ROUTINE

```

1ZZ SLJ (N) SLJ (L+4) . EXIT/ENTRY 03715
2ZZ ZRO (0) ZRO (0) . CAP NUMBER 03716
3ZZ ZRO (0) ZRO (0) . RANGE FROM CARRIER 03717
4ZZ ZRO (0) ZRO (0) . BEARING DEGREES TRUE 03720
STA (T+1) LDA 7 (T+1) . TRANSFER 03721
STA (2ZZ) RAO (T+1) . ARGUMENTS 03722
LDA 7 (T+1) STA (3ZZ) . TO THIS ROUTINE 03723
RAO (T+1) LDA 7 (T+1) . GET CAP TRACK NR 03724
STA (4ZZ) LDA (2ZZ) . 03725
SLJ 4 (1Y) ZRO (0) . 03726
SIL 2 (2ZZ) LDA (2ZZ) . 03727
ALS (42) SLJ 4 (6Q) . DETERMINE TRACK1 WORD 03730
LIL 3 (8Q) STA (T+2) . 03731
LDA 3 (TRACK1) SCL (MASK36) . 03732
ADD (T+2) STA 3 (TRACK1) . SET UP TRACK1 WORD 03733
LDA (3ZZ) AJP (5ZZ) . STATION GIVEN NO JUMP TO 03734
SLJ 4 (FLOAT) ZRO (0) . HOOK STATION 03735
STA (3ZZ) ENI (0) . FLOAT 03736
LDA (4ZZ) SLJ 4 (FLOAT) . ARGUMENTS 03737
STA (4ZZ) LDA (AXIS) . CONVERT TO RADIAN 03740
FSB (4ZZ) FMU (RADIAN) . 03741
STA (4ZZ) ENA (4ZZ) . 03742
SAL (COSF+1) SAL (SINF+1) . 03743
SLJ 4 (COSF) ZRO (0) . DETERMINE X AND Y 03744
FMU (3ZZ) SLJ 4 (FIX) . POSITION 03745
SCL (-777B) ALS (27) . OF 03746
RAD 3 (TRACK1) SLJ 4 (SINF) . STATION 03747
FMU (3ZZ) SLJ 4 (FIX) . 03750
SCL (-777B) ALS (18) . SET TRACK1 WORD 03751
    
```


03752
 03753
 03754
 03755
 03756
 03757
 03760
 03761
 03762
 03763

• RETURN
 • DETERMINE
 • X AND Y
 • POSITION
 • OF

(1ZZ)
 (RHO)
 (XPIP)
 (INC)
 (FIX)
 (25)
 (XPIP)
 (0)
 (34)
 (1ZZ)

RAD 3 (TRACK1)
 LDA (EIGHT)
 STA (INC)
 STA (XDESIG)
 FAD (YPIP)
 SCL (-777B)
 RAD 3 (TRACK1)
 SLJ 4 (FIX)
 SCL (-777B)
 RAD 3 (TRACK1)

5ZZ

SLJ
 FDV
 FAD
 LDA
 SLJ 4
 ALS
 LDA
 ZRO
 ALS
 SLJ

END

APPENDIX II-A

1. Identification.

Title: TRAKGEN

Category: Track Generator

Programmer: A. C. Casciato

Organization: U. S. Naval Postgraduate School

Date: April 1965

2. Purpose.

This subroutine is designed to generate fine grain, three dimensional position information in order to simulate radar or sonar track information. The subroutine generates up to 15 tracks simultaneously.

3. Program Sections.

3.1 IRET - Subroutine Entry, Initial Call. This section checks for the initial call and initializes all arrays and flags, reads in the initial position data for preprogrammed tracks, and sets all tracks to standby.

3.2 ITRAK - Process Maneuver Table Entries. This section reads in maneuver command data from the Data Process Section, the Keyboard Command Section, and the Maneuver Table and updates the maneuver code in the track matrix. It selects the proper maneuver section for track processing.

3.3 IWAIT - Utility Section. This section contains several small sections used by other portions of the subroutine.

3.4 IMOVE - Update Tracks. This section unpacks the track matrix information and routes the data through the proper maneuver routines

APPENDIX II-A

in the necessary order. After processing, the data is repacked into the track matrix.

3.5 IEXIT - Exit From Subroutine. This section restores the index information and returns control to the calling program.

3.6 IGO - Constant Course Section. This section increments X and Y position information when the track is not in a turn.

3.7 ITURN - Turn Section. This section processes the X and Y position information when the track is in a turn.

3.8 IDIVE - Climb Section. This section increments the altitude information when the track is climbing/diving.

3.9 ISPD - Speed Change Section. This section increments the speed information when the track is changing speed.

3.10 ICT - Multiple Maneuver Section. This section sets the proper flags to route the track information through the necessary maneuver sections when performing more than one maneuver.

3.11 IKEY - Keyboard Command Section. This section processes keyboard command information into a form similar to that of a maneuver table data card.

3.12 7KEY - Data Process Command Section. This section converts tactical data command information into the form of keyboard command information.

4. Limitations on Subroutine Quantities.

4.1 The maximum and minimum values for subroutine TRACKGEN input quantities are:

APPENDIX II-A

X and Y position:	+ 279 miles.
Altitude	+ 98,689 feet.
Course:	0 to 360 degrees.
Speed:	0 to 4095 knots.
Turn Rate:	0.1 to 25.5 degrees per second.
Climb Rate:	43* to 65,535 feet per minute.
Acceleration:	1 to 255 knots per second.

* The climb rate has a minimum of 43 feet per minute with a calling period of one second. With the six second calling period, a minimum climb rate of eight feet per minute is possible.

5. Rules Governing Track Commands.

- 5.1 The first command for a preprogrammed track must be a "Start Track" command.
- 5.2 More than one command may be given to the same track at the same time.
- 5.3 Normal maneuver commands may be given to a track even if it has been faded.
- 5.4 Once a track has been maneuvered by the keyboard console or by the data process section, further preprogrammed commands are ignored. This does not apply to the keyboard "Fade" or "Unfade" commands.
- 5.5 A track which has been scrubbed by any means cannot be restarted from the preprogrammed data deck.
- 5.6 Any maneuver may be continued to a new assigned limit by inserting a maneuver command with the new limit. The previous maneuver does not have to be completed before ordering the new limit.

SUBROUTINE TRAKGEN FLOW DIAGRAMS

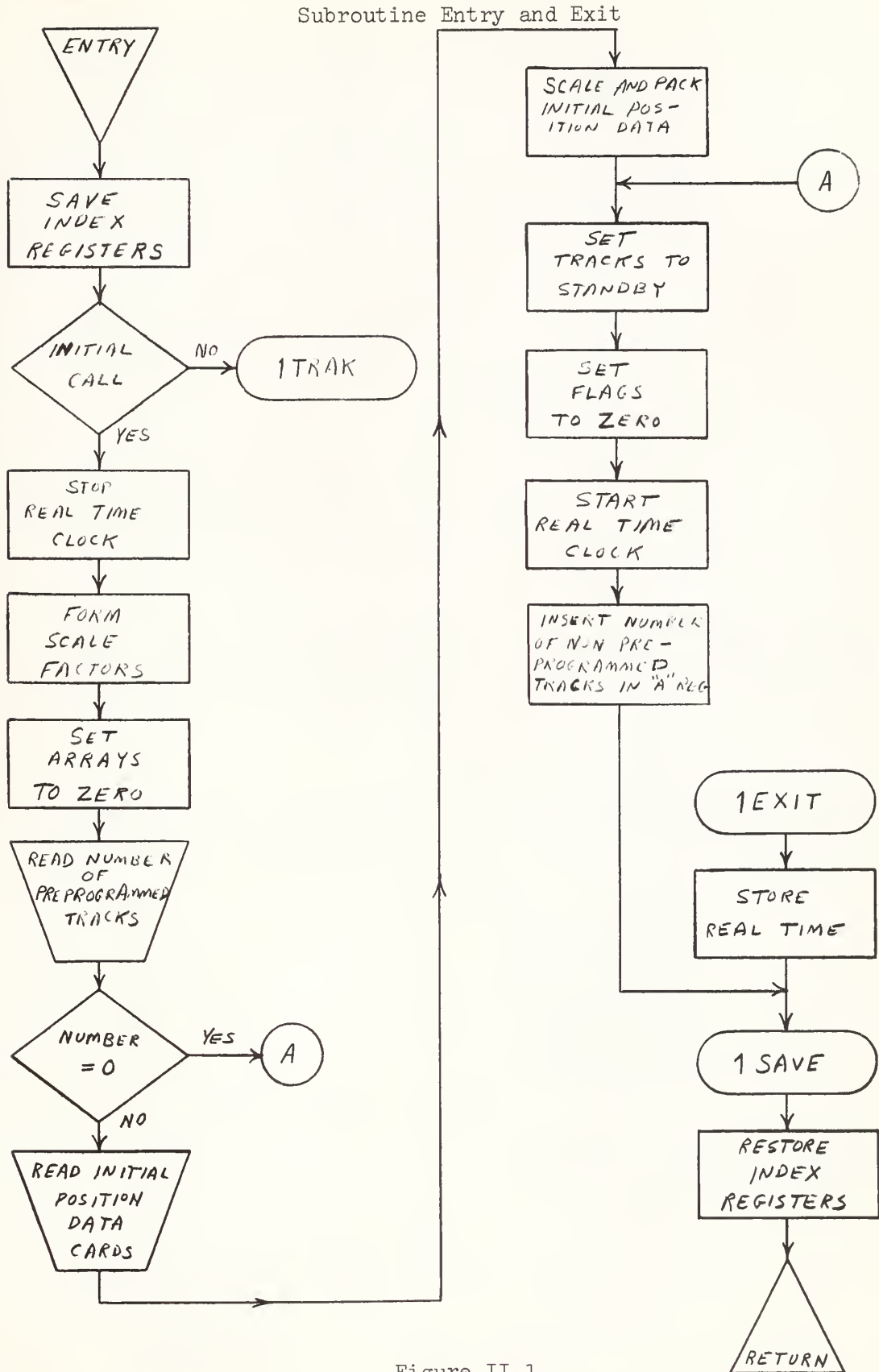


Figure II-1

Update Maneuver Codes

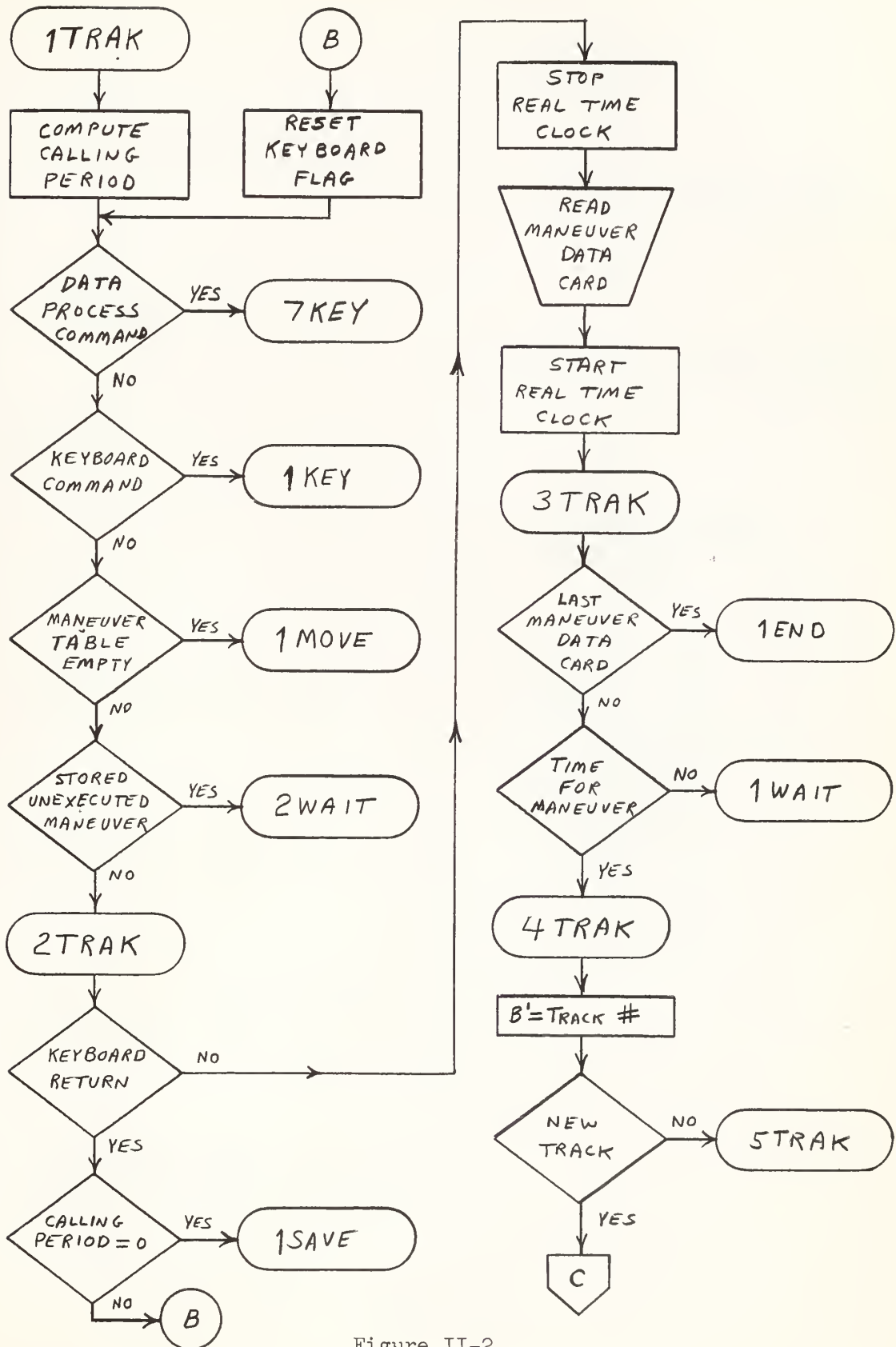


Figure II-2

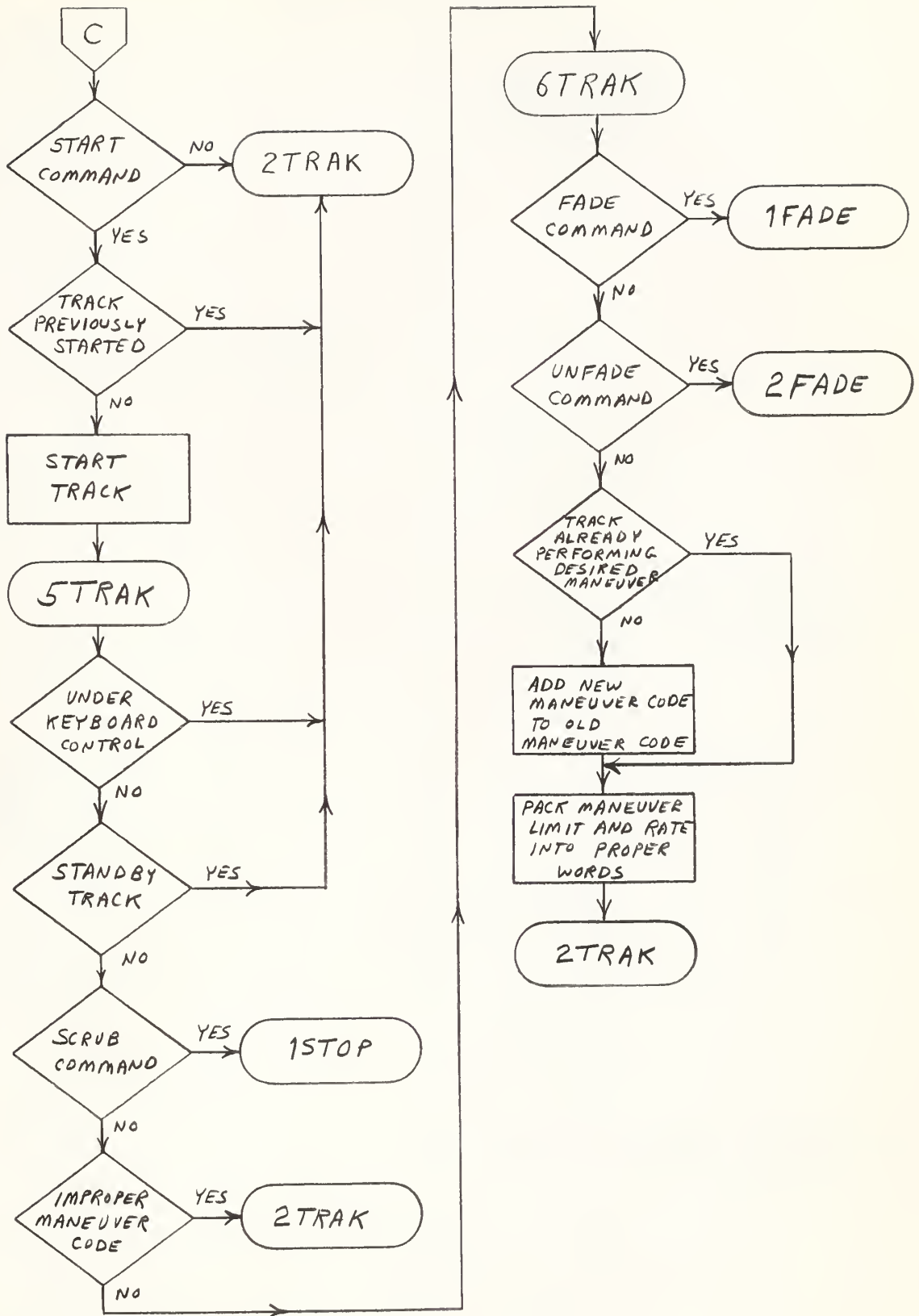


Figure II-3

Update Track Positions

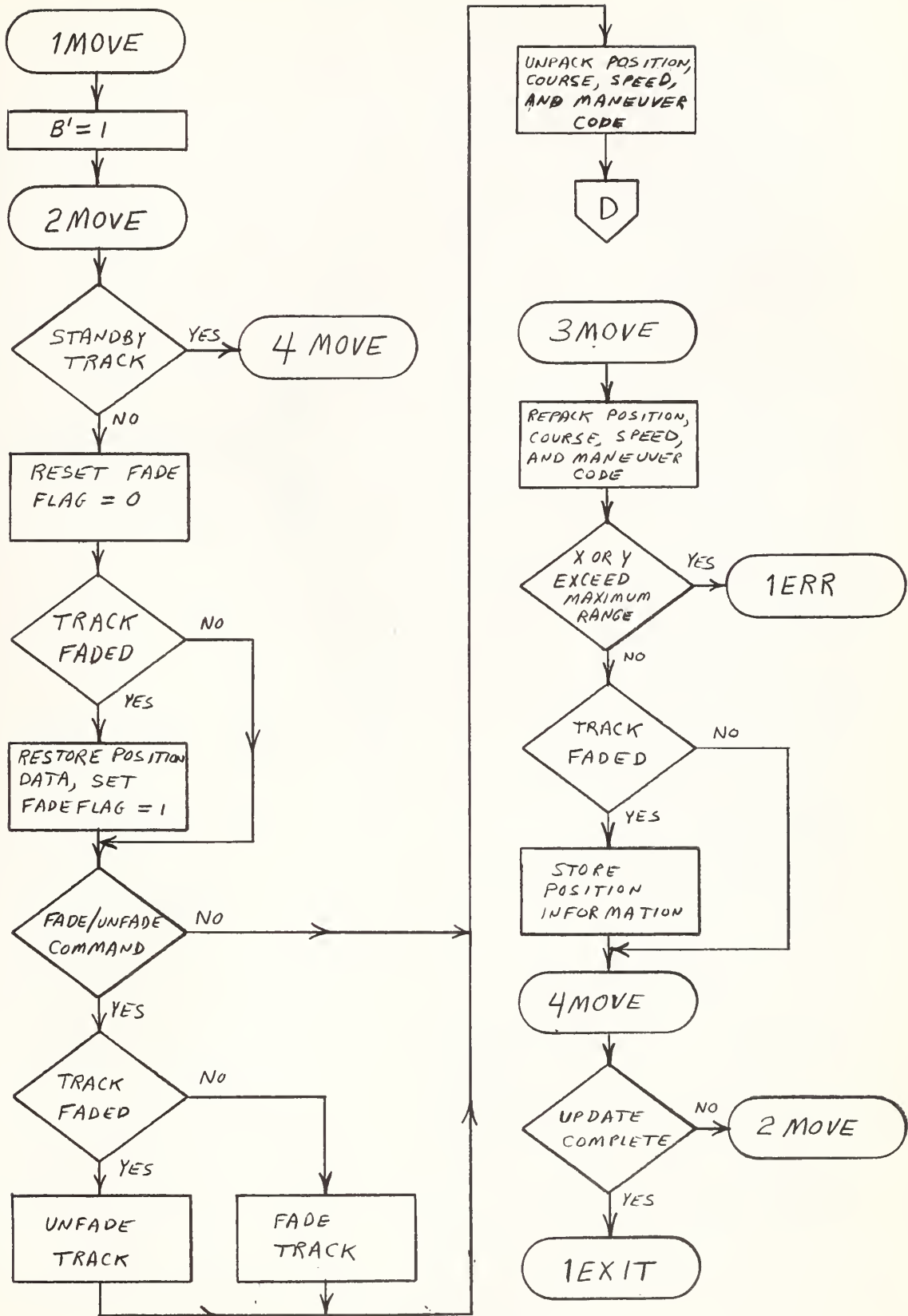


Figure II-4

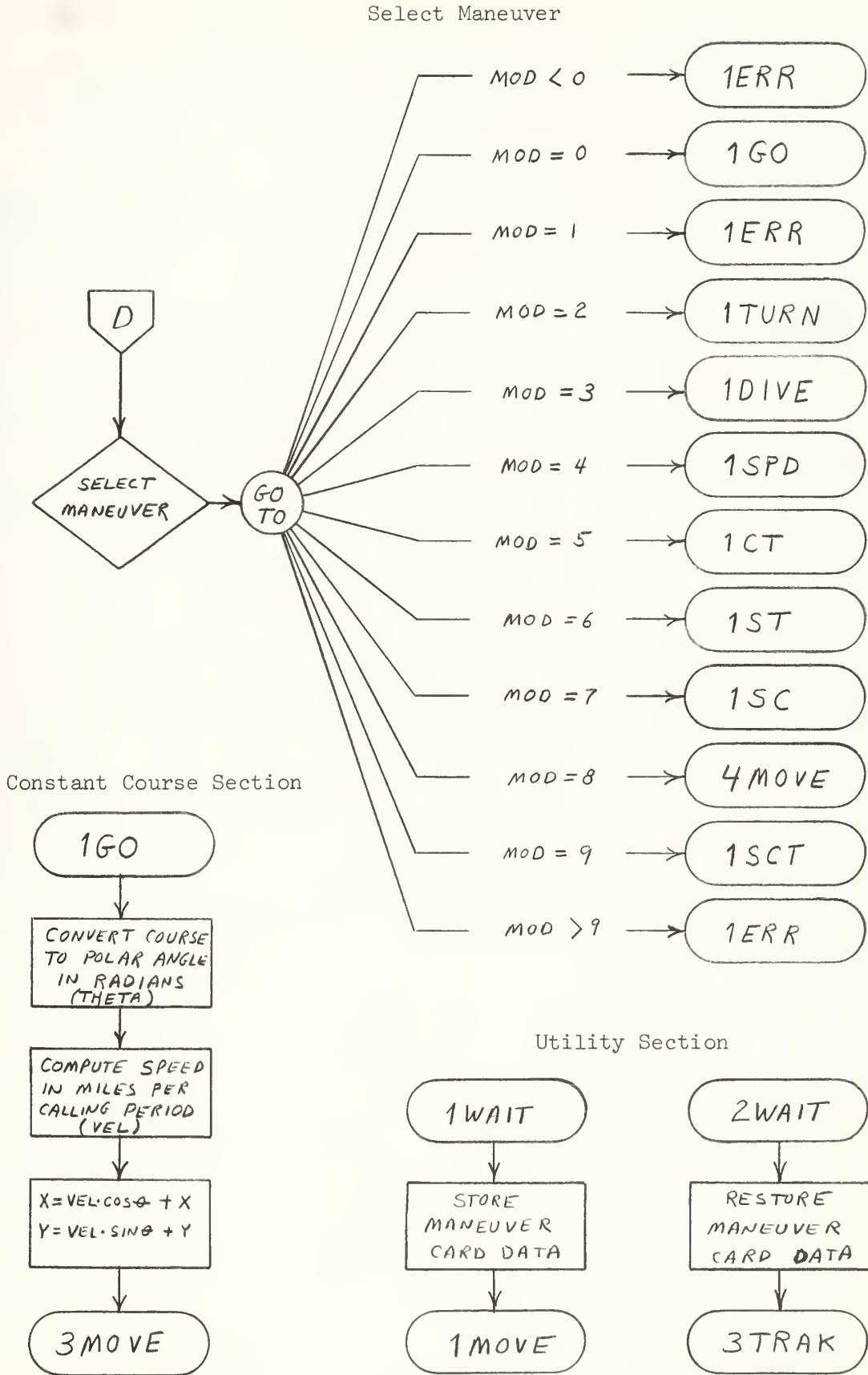


Figure II-5

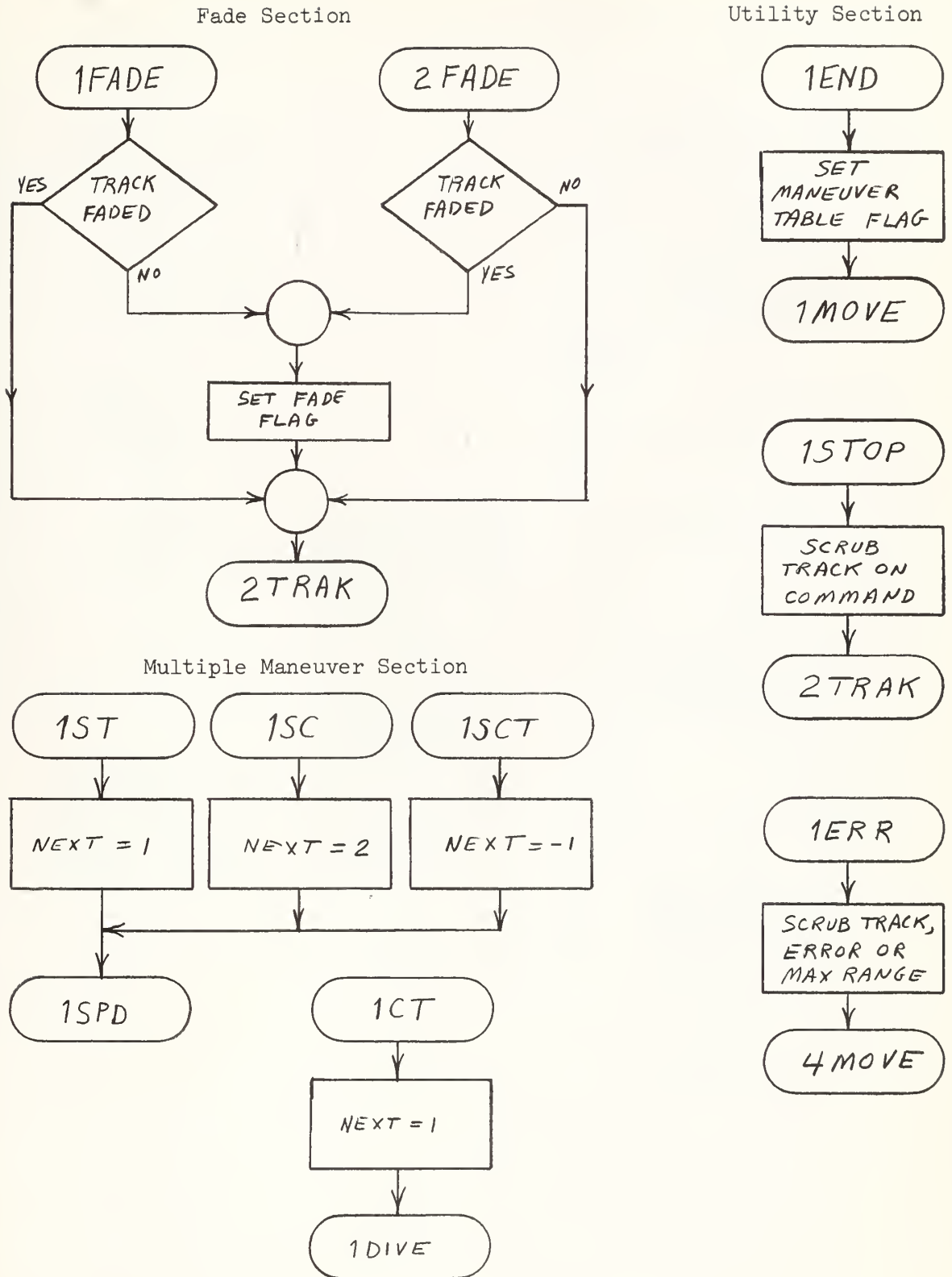


Figure II-6

Turn Section

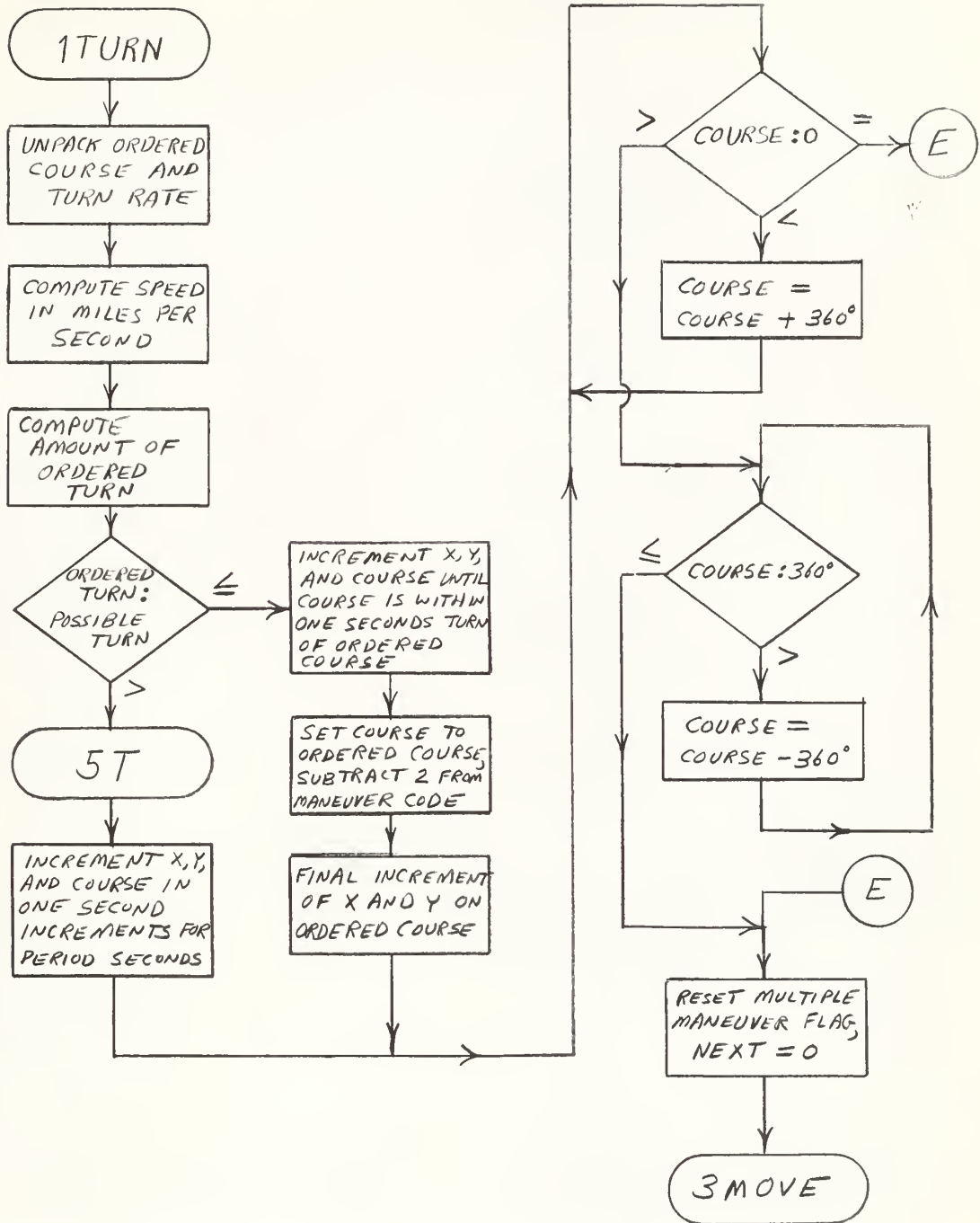


Figure II-7

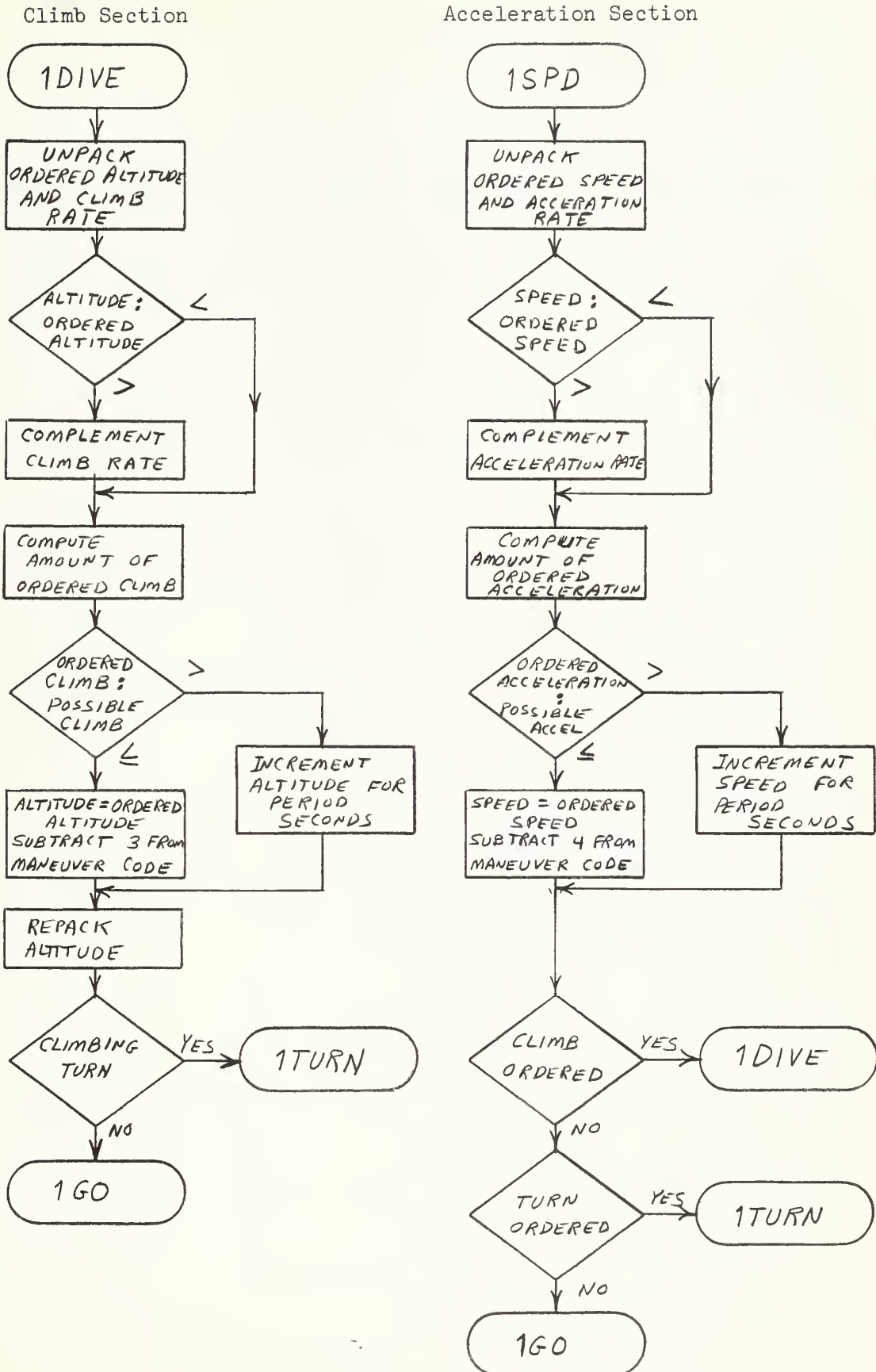


Figure II-8

Keyboard Command Section

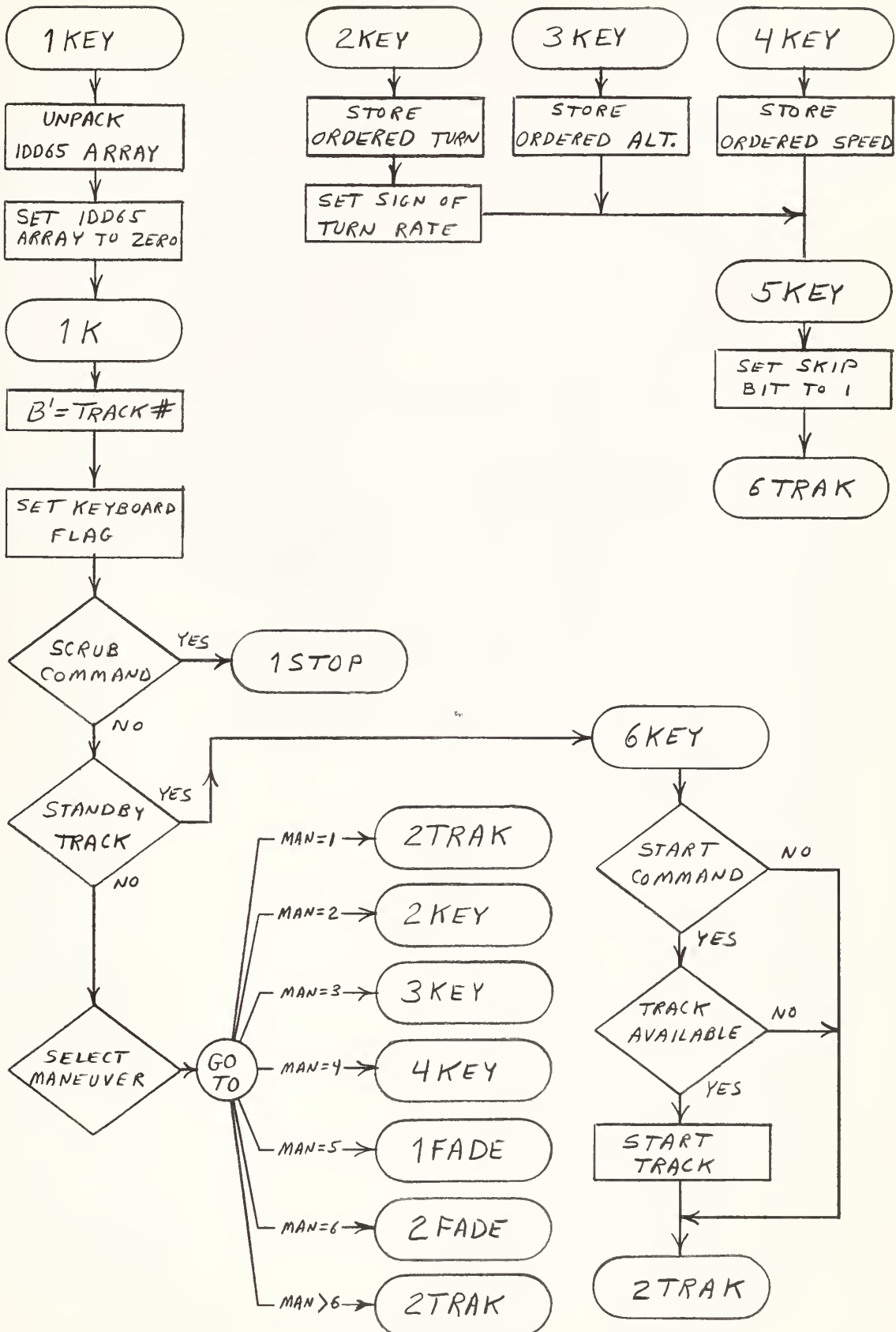


Figure II-9

Data Process Command Section

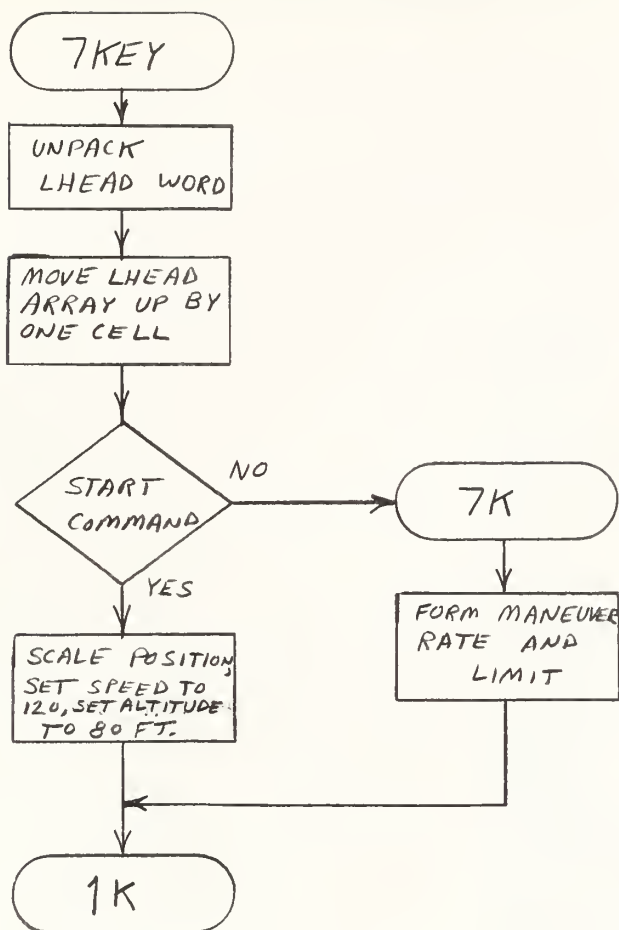


Figure II-10

APPENDIX II-C

SUBROUTINE TRAKGEN PROGRAM LISTING

MACHINE TRAKGEN

* DATA CARDS - EACH ENTRY MUST BE RIGHT JUSTIFIED IN SPECIFIED COLUMNS

- * 1. NUMBER OF PREPROGRAMMED TRACKS, 15 MAXIMUM, COLUMNS 1-2
- * 2. INITIAL POSITION CARDS, ONE FOR EACH PREPROGRAMMED TRACK IN
- * ORDER OF INCREASING TRACK NUMBER WITH THE LAST ONE BEING 15
- * A. X POSITION IN MILES, +- 279 MILES MAXIMUM, COLUMNS 1-10
- * B. Y POSITION IN MILES, +- 279 MILES MAXIMUM, COLUMNS 11-20
- * NOTE - X AND Y POSITIONS MAY HAVE UP TO 4 DECIMAL PLACES
- * C. ALTITUDE IN FEET, +- 98689 FEET MAXIMUM, COLUMNS 25-30
- * D. COURSE IN DEGREES, COLUMNS 38-40
- * E. SPEED IN KNOTS, 4095 KNOTS MAXIMUM, COLUMNS 47-50

* 3. MANEUVER CARDS, ONE FOR EACH MANEUVER

- * A. TIME FOR MANEUVER IN SECONDS, COLUMNS 1-10
- * B. TRACK NUMBER, COLUMNS 19-20
- * C. MANEUVER CODE, COLUMN 30

* 1 START TRACK

* 2 TURN

* 3 CLIMB/DIVE

* 4 CHANGE SPEED

* 5 FADE TRACK

* 6 UNFADE TRACK

* 8 SCRUB TRACK

* D. ORDERED COURSE IN DEGREES, ORDERED SPEED IN KNOTS, OR

* ORDERED ALTITUDE IN FEET, COLUMNS 35-40

* E. MANEUVER RATE, COLUMNS 43-50, THIS ENTRY MAY HAVE ONE.

* DECIMAL PLACE FOR TURN RATE

* POSITIVE TURN RATE SIGNIFIES A STARBOARD TURN,

* NEGATIVE TURN RATE SIGNIFIES A PORT TURN

* INSERT TURN RATE IN DEGREES PER SECOND, 25.5 MAXIMUM,

* INSERT CLIMB RATE IN FEET PER MINUTE, 65535 MAXIMUM, 43

* MINIMUM, INSERT ACCELERATION RATE IN KNOTS PER SECOND,

* 255 MAXIMUM.

* LAST MANEUVER CARD MUST HAVE MANEUVER TIME EQUAL TO ZERO

APPENDIX II-C

TRAKGEN VARIABLES AND CONSTANTS

*	AXIS	CONVERSION FACTOR - DEGREES TO RADIANS
*	CRS	TRACK COURSE
*	DEGREES	360 DEGREES SCALED BY TEN
*	DPS	TURN RATE, TENTHS OF DEGREES PER SECOND
*	FFLAG	FADE/UNFADE COMMAND BIT
*	IALT	ORDERED ALTITUDE
*	ICHECK	ABSOLUTE VALUE OF TURN RATE
*	ICRS	TRACK COURSE
*	IDD65	KEYBOARD COMMAND ARRAY
*	IDPS	TURN RATE, TENTHS OF DEGREES PER SECOND
*	IFADE	FADE BIT, 1 - TRACK FADED
*	IFPS	CLIMB RATE, FEET PER SECOND
*	IHEAD	COURSE, SPEED, AND MANEUVER CODE ARRAY
*	IKPS	ACCELERATION RATE, KNOTS PER SECOND
*	IPERIOD	TIME BETWEEN SUBROUTINE CALLS
*	IPOSIT	X AND Y POSITION ARRAY
*	IPOSIT1	INITIAL X AND Y POSITION ARRAY, FADE ARRAY
*	IRATE	SCRATCH WORK CELL FOR MANEUVER RATE
*	ISCALE1	SCALE FACTOR FOR X AND Y POSITION
*	ISCALE2	SCALE FACTOR FOR ALTITUDE
*	ISKIP	KEYBOARD CONTROLLED BIT, 1 - KEYBOARD CONTROLLED
*	ISPD	TRACK SPEED
*	ITER	NUMBER OF ITERATIONS IN TURN ROUTINE
*	IVEL	ORDERED SPEED
*	IX	TRACK X POSITION
*	IY	TRACK Y POSITION
*	IZ	TRACK ALTITUDE
*	JCHECK	ICHECK * IPERIOD
*	JCRS	ORDERED COURSE IN DEGREES
*	JFPS	ABSOLUTE VALUE OF CLIMB RATE
*	JHEAD	ALTITUDE ARRAY
*	JHEAD1	INITIAL ALTITUDE ARRAY, FADE ARRAY
*	JUMP	SCRATCH WORK CELL FOR AMOUNT OF MANEUVER
*	KCRS	ORDERED COURSE IN TENTHS OF DEGREES

APPENDIX II-C

*	KEY	KEYBOARD RETURN FLAG
*	KHEAD	ORDERED SPEED ARRAY
*	KMAN	KEYBOARD MANEUVER CODE
*	KPS	ABSOLUTE VALUE OF ACCELERATION RATE
*	LAST	MANEUVER TABLE FLAG, 1 - MANEUVER TABLE EMPTY
*	LEFT	STORE MANEUVER DATA FLAG
*	LHEAD	DATA PROCESS COMMAND ARRAY
*	LIMIT	DESIRED MANEUVER LIMIT
*	LIMITH	MANEUVER LIMIT FOR DELAYED MANEUVER
*	LTIME	TIME OF LAST SUBROUTINE CALL IN SECONDS
*	MAN	MANEUVER CODE
*	MANH	MANEUVER CODE FOR DELAYED MANEUVER
*	MAX	MAXIMUM X OR Y RANGE BEFORE OVERFLOW
*	MOD	MANEUVER CODE
*	MODPOS	CURRENT TRACK MANEUVER CODE, LEFT JUSTIFIED
*	MOD8	MANEUVER CODE FOR STANDBY TRACK
*	MTIME	EXECUTION TIME FOR MANEUVER
*	MTIMEH	DELAYED EXECUTION TIME FOR MANEUVER
*	NACTIVE	NUMBER OF NON PREPROGRAMMED TRACKS
*	NEXT	MULTIPLE MANEUVER FLAG
*	NORTH	360 DEGREES SCALED BY TEN
*	NR	TRACK NUMBER
*	NRH	TRACK NUMBER FOR DELAYED MANEUVER
*	NTIME	TIME OF PRESENT SUBROUTINE CALL IN SECONDS
*	NTRACKS	NUMBER OF PREPROGRAMMED TRACKS
*	PERIOD	TIME BETWEEN SUBROUTINE CALLS
*	RATE	MANEUVER RATE
*	RATEH	MANEUVER RATE FOR DELAYED MANEUVER
*	SCALE1	SCALE FACTOR FOR X AND Y POSITION
*	SCALE2	SCALE FACTOR FOR ALTITUDE
*	SPD	TRACK SPEED
*	TEMP	SCRATCH WORK CELL
*	THETA	COURSE POLAR ANGLE IN RADIAN
*	VEL	TRACK SPEED IN MILES/SECOND OR MILES/PERIOD
*	X	TRACK X POSITION
*	Y	TRACK Y POSITION

APPENDIX II-C

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RSV(IPOSIT=15,IPOSIT1=15,IHEAD=15,JHEAD=15,JHEAD1=15,KHEAD=15,
*   LHEAD=60,IDD65=10)
COMMON IPOSIT,IHEAD,JHEAD,LHEAD,IDD65,ISCALE1,ISCALE2,SCALE1,
*   SCALE2,NTIME
LIB(FLOATFIX = FLOAT, FIXFLOAT = FIX, COSF, SINP, XABSF, SIGNF)

1000 FORMAT(I2)
1001 FORMAT(2F10.0,4X,I6,7X,I3,6X,I4)
1002 FORMAT(I10,8X,I2,9X,I1,4X,I6,2X,F8.0)

CON(MASK1 = 7777777700000000B, MASK2 = 7577777777777777B,
*   MASK3 = 7777777777770000B, MASK4 = 0377777777777777B,
*   MASK5 = 777777777777000B, MASK6 = 7400000000000000B,
*   MASK7 = 777777777777760B, MASK8 = 0037777700000000B,
*   MASK9 = 777777777777400B, MASK10 = 7777777700007777B,
*   MASK11 = 00000007777777B, MASK12 = 777770007777777B,
*   MASK13 = 77400777777777B, MASK14 = 74000007777777B,
*   MASK15 = 7437777700000000B, MASK16 = 7777777777600000B,
*   MASK17 = 77777600000777B, MASK18 = 77770017777777B,
*   MASK19 = 00000177777000B, MASK20 = 0000776000007777B)
CON(MT1 = 4400000000000000B, MT2 = 3000000000000000B,
*   MT3 = 2400000000000000B, MT4 = 1000000000000000B,
*   MC1 = 4400000000000000B, MC2 = 3400000000000000B,
*   MC3 = 2400000000000000B, MC4 = 1400000000000000B,
*   MS1 = 4400000000000000B, MS2 = 3400000000000000B,
*   MS3 = 3000000000000000B, MS4 = 2000000000000000B)
CON(IZERO = 0, IONE = 1, ITWO = 2, ITHREE = 3, IFOUR = 4,
*   IFIVE = 5, ISIX = 6, ISEVEN = 7, IEIGHT = 8, ININE = 9,
*   ITEN = 10, I15 = 15)
CON(ISKIP = 0200000000000000B, MOD8 = 4000000000000000B, I85 = 85,
*   I30000 = 30000, AXIS = 4500., RADIANS = .0017453293,
*   DEGREES = 3600., MAX = 3777777B, IFADE = 0100000000000000B,
*   FFLAG = 0040000000000000B, SIXTY = 60., NORTH = 3600,
*   TEN = 10.)
00000
00001
00002

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APPENDIX II-C

* ENTRY TO SUBROUTINE

IRET	SLJ	(*)	ENI	(0)	•	RETURN JUMP	00000
	SIU	1 (1SAVE)	SIL	2 (1SAVE)	•	SAVE	00001
	SIU	3 (2SAVE)	SIL	4 (2SAVE)	•	INDEX	00002
	SIU	5 (3SAVE)	SIL	6 (3SAVE)	•	REGISTERS	00003
	LDA	(NTIME)	AJP	1 (1TRAK)	•	JUMP IF NOT INITIAL CALL	00004
	EXF	(2000B)	ENI	(0)	•	STOP REAL TIME CLOCK	00005
	LDA	(I30000)	STA	(ISCALE1)	•	FORM ISCALE1	00006
	LDA	(I85)	STA	(ISCALE2)	•	FORM ISCALE2	00007
	LDA	(ISCALE1)	SLJ	4 (FLOAT)	•	FORM SCALE1	00010
	STA	(SCALE1)	ENI	(0)	•	FORM SCALE1	00011
	LDA	(ISCALE2)	SLJ	4 (FLOAT)	•	FORM SCALE2	00012
	STA	(SCALE2)	ENI	1 (1)	•	FORM SCALE2	00013
	ENA	(0)	ENI	(0)	•	SET IPOBIT, IHEAD,	00014
	STA	1 (IPOSIT)	STA	1 (IHEAD)	•	JHEAD, AND KHEAD	00015
	STA	1 (JHEAD)	STA	1 (KHEAD)	•	ARRAYS TO ZERO	00016
	ISK	1 (15)	SLJ	(L-2)	•	SET LHEAD	00017
	ENI	1 (1)	ENA	(0)	•	ARRAY TO	00020
	STA	1 (LHEAD)	ENI	(0)	•	ZERO	00021
	ISK	1 (60)	SLJ	(L-1)	•	SET IDD65	00022
	ENI	1 (1)	ENA	(0)	•	ARRAY TO	00023
	STA	1 (IDD65)	ENI	(0)	•	ZERO	00024
	ISK	1 (10)	SLJ	(L-1)	•		00025

* READ, SCALE, AND PACK INITIAL POSITION DATA

IREAD	SLJ	1 (TEMP)	LDA	(TEMP)	•	FORM	00030
	ADD	(I15)	SUB	(NTRACKS)	•	ARRAY	00031
	STA	(TEMP)	LIL	2 (TEMP)	•	SUBSCRIPT	00032
	READ	1001, X, Y, IZ, ICRS, ISPD			•		00033
	LDA	(X)	FMU	(SCALE1)	•		00034
	SLJ	4 (FIX)	ZRO	(0)	•		00035
					•		00036

READ	1000, NTRACKS				•	JUMP IF NO PREPROGRAM TRACKS	00026
LDA	(NTRACKS)	AJP	(2EXIT)		•		00027
SAU	(2READ)	ENI	1 (1)		•		00030

APPENDIX II-C

SCL (MASK1) ALS (24) •
 STA 2 (IPOSIT1) LDA (Y) • PACK INITIAL X POSITION
 FMU (SCALE1) SLJ 4 (FIX) •
 SCL (MASK1) RAD 2 (IPOSIT1) • PACK INITIAL Y POSITION
 LDA (IZ) MUI (ISCALE2) •
 STA 2 (JHEAD1) LDA (ICRS) • PACK INITIAL ALTITUDE
 MUI (ITEN) ALS (I2) •
 STA 2 (IHEAD) LDA (ISPD) • PACK INITIAL COURSE
 SCL (MASK3) RAD 2 (IHEAD) • PACK INITIAL SPEED
 2READ ISK 1 (*) SLJ (IREAD) •

00037
 00040
 00041
 00042
 00043
 00044
 00045
 00046
 00047
 00050

* SET UNUSED TRACKS TO STANDBY, SET FLAGS TO ZERO

2EXIT ENA (I5) SUB (NTRACKS) •
 STA (NACTIVE) ENI 1 (I1) •
 LDA 1 (IHEAD) SST (MOD8) • SET TRACKS
 STA 1 (IHEAD) ENI (0) • TO STANDBY
 ISK 1 (I5) SLJ (L-2) •
 ENA (0) STA (LTIME) • SET FLAGS
 STA (LAST) STA (LEFT) • TO ZERO
 STA (NEXT) EXF (I000B) • START REAL TIME CLOCK
 LDA (NACTIVE) SLJ (ISAVE) • END OF INITIAL CALL

00051
 00052
 00053
 00054
 00055
 00056
 00057
 00060
 00061

* NON INITIAL CALL, PROCESS MANEUVER TABLE ENTRIES

1TRAK LDA (NTIME) SUB (LTIME) • COMPUTE CALLING PERIOD
 STA (IPERIOD) SLJ 4 (FLOAT) • STORE IPERIOD
 STA (PERIOD) ENI (0) • STORE PERIOD
 LDA (LHEAD+1) AJP 3 (7KEY) • JUMP IF DATA PROCESS COMMAND
 LDA (IDDD65+9) AJP 1 (IKEY) • JUMP IF KEYBOARD COMMAND
 LDA (LAST) AJP 1 (IMOVE) • JUMP IF MANEUVER TABLE EMPTY
 LDA (LEFT) AJP 1 (2WAIT) • JUMP IF HOLDING A MANEUVER
 LDA (KEY) AJP (L+3) • JUMP TO READ NEXT DATA CARD
 AJP 3 (ISAVE) ENA (0) • JUMP IF PERIOD EQUALS ZERO
 STA (KEY) SLJ (L-6) • RESET KEYBOARD FLAG
 EXF (2000B) ENI (0) • STOP REAL TIME CLOCK

00062
 00063
 00064
 00065
 00066
 00067
 00070
 00071
 00072
 00073
 00074

APPENDIX II-C

3TRAK	EXF	(1000B)	ENI	(0)	START REAL TIME CLOCK	00075
	LDA	(MTIME)	AJP	(1END)	JUMP IF MANEUVER TABLE TO END	00076
	SUB	(NTIME)	AJP	(4TRAK)	JUMP IF TIME FOR MANEUVER	00077
4TRAK	AJP	2 (1WAIT)	ENI	(0)	JUMP IF NOT TIME FOR MANEUVER	00100
	LIL	1 (NR)	LDA	1 (IHEAD)	SET INDEX ONE TO TRACK NUMBER	00101
	SCL	(MASK4)	SUB	(MOD8)	UNPACK OLD MANEUVER CODE	00102
	AJP	1 (5TRAK)	ENA	(1)	JUMP IF OLD TRACK	00103
	SUB	(MAN)	AJP	1 (2TRAK)	JUMP IF NOT START COMMAND	00104
	LDA	1 (IHEAD)	SCL	(MOD8)	CLEAR OLD MANEUVER CODE	00105
	AJP	(2TRAK)	STA	1 (IHEAD)	JUMP IF PREVIOUSLY STARTED	00106
	LDA	1 (IPOSIT1)	STA	1 (IPOSIT)	START	00107
	LDA	1 (JHEAD1)	STA	1 (JHEAD)	NEW	00110
	SLJ	(2TRAK)	ZRO	(0)	TRACK	00111
5TRAK	LIL	1 (NR)	LDA	1 (IHEAD)	UPDATE MANEUVER CODES	00112
	SCL	(MASK2)	SUB	(ISKIP)	UNPACK ISKIP BIT	00113
	AJP	(2TRAK)	LDA	1 (IHEAD)	JUMP IF KEYBOARD CONTROLLED	00114
	SCL	(MASK4)	STA	(MODPOS)	UNPACK OLD MANEUVER CODE	00115
	SUB	(MOD8)	AJP	(2TRAK)	JUMP IF STANDBY TRACK	00116
	LDA	(MAN)	SUB	(IEIGHT)	CHECK FOR SCRUB COMMAND	00117
	AJP	(1STOP)	LDA	(MAN)	JUMP IF TRACK TO BE SCRUBBED	00120
	AJP	(2TRAK)	ENI	(0)	JUMP IF MAN IS ZERO (ERROR)	00121
6TRAK	LDA	(MAN)	ENI	(0)	SELECT MANEUVER	00122
	INA	(-1)	AJP	(2TRAK)	MAN ERROR	00123
	INA	(-1)	AJP	(L+6)	TURN	00124
	INA	(-1)	AJP	(L+8)	CLIMB/DIVE	00125
	INA	(-1)	AJP	(L+10)	CHANGE SPEED	00126
	INA	(-1)	AJP	(1FADE)	FADE	00127
	INA	(-1)	AJP	(2FADE)	UNFADE	00130
	SLJ	(2TRAK)	ZRO	(0)	JUMP IF MAN GT SIX (ERROR)	00131
	ENI	2 (4)	LDA	(MODPOS)	SEARCH FOR TURN	00132
	EQS	2 (MT1)	SLJ	(L+8)	JUMP IF TRACK NOT TURNING	00133
	SLJ	(1PACK)	ZRO	(0)	JUMP IF TRACK ALREADY TURNING	00134
	ENI	2 (4)	LDA	(MODPOS)	SEARCH FOR CLIMB	00135
	EQS	2 (MC1)	SLJ	(L+5)	JUMP IF TRACK NOT CLIMBING	00136
	SLJ	(1PACK)	ZRO	(0)	JUMP IF TRACK ALREADY CLIMBING	00137
						00140

APPENDIX II-C

ENI 2 (4)	LDA	(MODPOS)	SEARCH FOR ACCELERATION	00141
EQS 2 (MS1)	SLJ	(L+2)	JUMP IF TRACK NOT ACCELERATING	00142
SLJ (1PACK)	ZRO	(0)	JUMP IF TRACK ACCELERATING	00143
LDA (MAN)	SCL	(MASK7)	MASK MANEUVER CODE	00144
ALS (44)	RAD	(MODPOS)	ADD NEW MANEUVER CODE	00145
LDA 1 (IHEAD)	SCL	(MASK6)	CLEAR OLD MANEUVER CODE	00146
ADD (MODPOS)	STA 1	(IHEAD)	REPLACE MANEUVER CODE	00147
SLJ (1PACK)	ZRO	(0)		00150
1FADE LDQ 1 (IHEAD)	LDL	(IFADE)	CHECK FOR FADE	00151
AJP 1 (2TRAK)	SLJ	(L+3)	A-JUMP IF ALREADY FADED	00152
2FADE LDQ 1 (IHEAD)	LDL	(IFADE)	CHECK FOR FADE	00153
AJP (2TRAK)	ENI	(0)	JUMP IF NOT FADED	00154
LDA 1 (IHEAD)	SST	(FFLAG)	VALID FADE/UNFADE COMMAND,	00155
STA 1 (IHEAD)	SLJ	(2TRAK)	SET FADE FLAG	00156
1PACK LDA (MAN)	ENI	(0)	SELECT PACK ROUTINE	00157
INA (-2)	AJP	(2PACK)	TURN	00160
INA (-1)	AJP	(3PACK)	CLIMB/DIVE	00161
INA (-1)	AJP	(4PACK)	ACCELERATE	00162
2PACK LDA (RATE)	FMU	(TEN)	TURN	00163
ENI (0)	SLJ 4	(FIX)	CALLED	00164
STA (IRATE)	LDA 1	(IHEAD)	FOR,	00165
SCL (MASK8)	STA 1	(IHEAD)	PACK	00166
LDA (LIMIT)	SCL	(MASK5)	INTO	00167
ALS (24)	RAD 1	(IHEAD)	ORDERED COURSE	00170
LDA (IRATE)	SCL	(MASK9)	AND	00171
ALS (33)	RAD 1	(IHEAD)	TURN RATE	00172
SLJ (2TRAK)	ZRO	(0)		00173
3PACK LDA (LIMIT)	MUI	(ISCALE2)	CLIMB	00174
STA (LIMIT)	ENI	(0)	CALLED	00175
LDA (RATE)	FMU	(SCALE2)	FOR,	00176
FDV (SIXTY)	SLJ 4	(FIX)	PACK	00177
STA (IRATE)	LDA 1	(JHEAD)	INTO	00200
SCL (MASK1)	STA 1	(JHEAD)	ORDERED ALTITUDE	00201
LDA (LIMIT)	SCL	(MASK1)	AND	00202
ALS (24)	RAD 1	(JHEAD)	CLIMB RATE	00203
LDA 1 (KHEAD)	SCL	(MASK19)		00204

APPENDIX II-C

STA 1 (KHEAD)	LDA	(IRATE)	•	00205
SCL (MASK16)	ALS	(12)	•	00206
RAD 1 (KHEAD)	SLJ	(2TRAK)	•	00207
4PACK LDA (RATE)	SLJ 4	(FIX)	•	00210
STA (IRATE)	LDA 1	(KHEAD)	•	00211
SCL (MASK20)	STA 1	(KHEAD)	•	00212
LDA (LIMIT)	SCL	(MASK3)	•	00213
RAD 1 (KHEAD)	LDA	(IRATE)	•	00214
SCL (MASK9)	ALS	(28)	•	00215
RAD 1 (KHEAD)	SLJ	(2TRAK)	•	00216

ACCELERATION
CALLED FOR,
PACK
INTO
ORDERED SPEED
AND
ACCELERATION RATE

* UTILITY SECTION

1WAIT ENA (1)	STA	(LEFT)	•	00217
LDA (MTIME)	STA	(MTIMEH)	•	00220
LDA (LIMIT)	STA	(LIMITH)	•	00221
LDA (RATE)	STA	(RATEH)	•	00222
LDA (MAN)	STA	(MANH)	•	00223
LDA (NR)	STA	(NRH)	•	00224
SLJ (MOVE)	ZRO	(0)	•	00225
2WAIT ENA (0)	STA	(LEFT)	•	00226
LDA (MTIMEH)	STA	(MTIME)	•	00227
LDA (LIMITH)	STA	(LIMIT)	•	00230
LDA (RATEH)	STA	(RATE)	•	00231
LDA (MANH)	STA	(MAN)	•	00232
LDA (NRH)	STA	(NR)	•	00233
SLJ (3TRAK)	ZRO	(0)	•	00234
1END ENA (1)	STA	(LAST)	•	00235
SLJ (MOVE)	ZRO	(0)	•	00236
1STOP LDA (MOD8)	STA 1	(IHEAD)	•	00237
ENA (0)	STA 1	(IPOSIT)	•	00240
STA 1 (JHEAD)	STA 1	(KHEAD)	•	00241
SLJ (2TRAK)	ZRO	(0)	•	00242
LDA (MOD8)	STA 1	(IHEAD)	•	00243
ENA (0)	STA 1	(IPOSIT)	•	00244
STA 1 (JHEAD)	STA 1	(KHEAD)	•	00245

STORE
MANEUVER
CARD
DATA FOR
MANEUVER
BEING
HELD
RESTORE
MANEUVER
CARD
DATA FOR
MANEUVER
BEING
HELD
MANEUVER TABLE EMPTY
SCRUB TRACK
SCRUB TRACK,
MOD ERROR, OR
MAX RANGE EXCEEDED

APPENDIX II-C

00246	SLJ (4MOVE)	ZRO (0)	•	
	* UPDATE TRACKS			
00247	1MOVE ENI 1 (1)	ENI (0)	•	INITIALIZE TRACK NUMBER INDEX
00250	2MOVE LDA 1 (IHEAD)	SCL (MASK4)	•	UNPACK MANEUVER CODE
00251	SUB (MOD8)	AJP (4MOVE)	•	JUMP IF STANDBY TRACK
00252	ENA (0)	STA (TEMP)	•	RESET TEMP FADE FLAG
00253	LDQ 1 (IHEAD)	LDL (IFADE)	•	CHECK FOR FADE
00254	AJP (L+4)	LDA 1 (IPOSIT1)	•	JUMP IF NOT FADED
00255	STA 1 (IPOSIT)	LDA 1 (JHEAD1)	•	TRACK PREVIOUSLY FADED,
00256	STA 1 (JHEAD)	ENA (1)	•	RESTORE POSITION INFORMATION
00257	STA (TEMP)	ENI (0)	•	SET FADED FLAG
00260	LDQ 1 (IHEAD)	LDL (FFLAG)	•	CHECK FOR FADE COMMAND
00261	AJP (L+6)	LDA (TEMP)	•	JUMP IF NO COMMAND
00262	AJP (L+3)	LDA 1 (IHEAD)	•	JUMP IF NOT FADED
00263	SCL (IFADE)	SCL (FFLAG)	•	UNFADE TRACK,
00264	STA 1 (IHEAD)	SLJ (L+3)	•	RESET FADE BITS
00265	LDA 1 (IHEAD)	SST (IFADE)	•	FADE TRACK,
00266	SCL (FFLAG)	STA 1 (IHEAD)	•	SET FADE BIT
00267	LDA 1 (IHEAD)	SCL (MASK4)	•	UNPACK
00270	ARS (44)	SCL (MASK7)	•	MANEUVER MODE,
00271	STA (MOD)	LDA 1 (IHEAD)	•	COURSE,
00272	SCL (MASK10)	ARS (12)	•	SPEED,
00273	STA (ICRS)	LDA 1 (IHEAD)	•	X POSITION
00274	SCL (MASK3)	STA (ISPD)	•	AND
00275	LDA 1 (IPOSIT)	SCL (MASK11)	•	Y POSITION
00276	ARS (24)	ENI (0)	•	
00277	STA (IX)	LDA 1 (IPOSIT)	•	
00300	SCL (MASK1)	ALS (24)	•	
00301	ARS (24)	STA (IY)	•	
00302	LDA (ICRS)	SLJ 4 (FLOAT)	•	
00303	STA (CRS)	ENI (0)	•	
00304	LDA (ISPD)	SLJ 4 (FLOAT)	•	
00305	STA (SPD)	ENI (0)	•	
00306	LDA (IX)	SLJ 4 (FLOAT)	•	

APPENDIX II-C

STA	(X)	ENI	(0)	00307
LDA	(IY)	SLJ	4 (FLOAT)	00310
STA	(Y)	LDA	(MOD)	00311
AJP	3 (IERR)	AJP	(LGO)	00312
INA	(-1)	AJP	(IERR)	00313
INA	(-1)	AJP	(LTURN)	00314
INA	(-1)	AJP	(LDIVE)	00315
INA	(-1)	AJP	(LSPD)	00316
INA	(-1)	AJP	(LCT)	00317
INA	(-1)	AJP	(LST)	00320
INA	(-1)	AJP	(LSC)	00321
INA	(-1)	AJP	(4MOVE)	00322
INA	(-1)	AJP	(LSCT)	00323
SLJ	(IERR)	ZRO	(0)	00324

SELECT MANEUVER
 MANEUVER CODE ERROR
 TURN
 CLIMB/DIVE
 ACCELERATION
 CLIMBING TURN
 ACCELERATION IN TURN
 ACCELERATION IN CLIMB
 SCRUBBED TRACK
 ACCELERATION IN CLIMB--TURN
 MANEUVER CODE ERROR

* REPACK SECTION

3MOVE	LDA	(IX)	AJP	(L+4)	00325
	AJP	3 (L+2)	SUB	(MAX)	00326
	AJP	3 (L+2)	SLJ	(IERR)	00327
	LAC	(IX)	SLJ	(L-2)	00330
	LDA	(IX)	SCL	(MASK1)	00331
	ALS	(24)	STA	1 (IPOSIT)	00332
	LDA	(IY)	AJP	(L+4)	00333
	AJP	3 (L+2)	SUB	(MAX)	00334
	AJP	3 (L+2)	SLJ	(IERR)	00335
	LAC	(IY)	SLJ	(L-2)	00336
	LDA	(IY)	SCL	(MASK1)	00337
	RAD	1 (IPOSIT)	LDA	1 (IHEAD)	00340
	SCL	(MASK14)	STA	1 (IHEAD)	00341
	LDA	(ICRS)	SCL	(MASK3)	00342
	ALS	(12)	RAD	1 (IHEAD)	00343
	LDA	(ISPD)	SCL	(MASK3)	00344
	RAD	1 (IHEAD)	LDA	(MOD)	00345
	SCL	(MASK7)	ALS	(44)	00346
	RAD	1 (IHEAD)	ENI	(0)	00347

REPACK
 X POSITION,
 Y POSITION,
 COURSE,
 SPEED,
 AND
 MANEUVER MODE
 IF EITHER
 X OR Y IS
 GREATER
 THAN MAXIMUM
 RANGE,
 SCRUB
 TRACK

APPENDIX II-C

LDQ 1 (IHEAD)	LDL (IFADE)	•	CHECK FOR FADE	00350
AJP (4MOVE)	LDA 1 (IPOSIT)	•	JUMP IF NOT FADED	00351
STA 1 (IPOSIT1)	LDA 1 (JHEAD)	•	TRACK FADED, SAVE	00352
STA 1 (JHEAD1)	ENA (0)	•	POSITION INFORMATION,	00353
STA 1 (IPOSIT)	STA 1 (JHEAD)	•	SET POSITION TO ZERO	00354
4MOVE ISK 1 (15)	SLJ (2MOVE)	•	END OF UPDATE LOOP	00355

* EXIT-FROM SUBROUTINE

1EXIT LDA (NTIME)	STA (LTIME)	•	STORE REAL TIME	00356
1SAVE ENI 1 (*)	ENI 2 (*)	•	RESTORE INDEX	00357
2SAVE ENI 3 (*)	ENI 4 (*)	•	REGISTERS, RETURN	00360
3SAVE ENI 5 (*)	ENI 6 (*)	•	TO CALLING PROGRAM	00361
SLJ (IRET)	ZRO (0)	•	RETURN	00362

* CONSTANT COURSE SECTION

1GO LDA (AXIS)	FSB (CRS)	•	CONVERT COURSE TO POLAR	00363
FMU (RADIANS)	STA (THETA)	•	ANGLE IN RADIAN	00364
LDA (SPD)	FMU (SCALE1)	•	COMPUTE SPEED IN	00365
FMU (PERIOD)	FDV (DEGREES)	•	MILES PER CALLING PERIOD	00366
STA (VEL)	ENA (THETA)	•	INCREMENT X	00367
SAL (COSF+1)	SLJ 4 (COSF)	•		00370
FMU (VEL)	FAD (X)	•		00371
ENI (0)	SLJ 4 (FIX)	•		00372
STA (IX)	ENA (THETA)	•	INCREMENT Y	00373
SAL (SINF+1)	SLJ 4 (SINF)	•		00374
FMU (VEL)	FAD (Y)	•		00375
ENI (0)	SLJ 4 (FIX)	•		00376
STA (IY)	SLJ (3MOVE)	•		00377

* TURN SECTION

1TURN LDA 1 (IHEAD)	SCL (MASK12)	•	UNPACK	00400
ARS (24)	STA (JCRS)	•	ORDERED COURSE	00401
LDA 1 (IHEAD)	SCL (MASK13)	•	UNPACK TURN RATE	00402

APPENDIX II-C

ALS	(7)	ARS	(40)	•	EXTEND SIGN BIT	00403
STA	(IDPS)	LDA	(SPD)	•	COMPUTE SPEED	00404
FMU	(SCALE1)	FDV	(DEGREES)	•	IN MILES	00405
STA	(VEL)	ENI	(0)	•	PER SECOND	00406
LDA	(IDPS)	SLJ	4 (FLOAT)	•	FLOAT TURN RATE	00407
STA	(DPS)	LDA	(JCRS)	•	CONVERT ORDERED COURSE	00410
MUI	(ITEN)	STA	(KCRS)	•	TO TENTHS OF DEGREES	00411
SUB	(ICRS)	STA	(JUMP)	•		00412
LDA	(IDPS)	AJP	2 (L+3)	•	JUMP IF STARBOARD TURN	00413
LDA	(JUMP)	AJP	3 (1T)	•	COMPUTE	00414
AJP	(2T)	AJP	2 (L+3)	•	AMOUNT	00415
LDA	(JUMP)	AJP	3 (L+2)	•	OF ORDERED	00416
AJP	(2T)	AJP	2 (3T)	•	TURN	00417
ENA	(JUMP)	SAL	(XABSF+1)	•		00420
ENI	(0)	SLJ	4 (XABSF)	•	PASSES	00421
STA	(TEMP)	LDA	(NORTH)	•	THROUGH	00422
SUB	(TEMP)	STA	(JUMP)	•	NORTH	00423
SLJ	(L+5)	ZRO	(0)	•		00424
ENA	(JUMP)	SAL	(XABSF+1)	•	TURN DOES	00425
ENI	(0)	SLJ	4 (XABSF)	•	NOT PASS	00426
STA	(JUMP)	SLJ	(L+2)	•	THROUGH NORTH	00427
LDA	(NORTH)	STA	(JUMP)	•	360 DEGREE TURN	00430
ENA	(IDPS)	SAL	(XABSF+1)	•	REMOVE SIGN	00431
ENI	(0)	SLJ	4 (XABSF)	•	OF TURN RATE	00432
STA	(ICHECK)	MUI	(IPERIOD)	•	COMPUTE AMOUNT OF TURN	00433
STA	(JCHECK)	LDA	(JUMP)	•	POSSIBLE THIS PERIOD	00434
SUB	(JCHECK)	AJP	(L+2)	•	ORDERED TURN = POSSIBLE TURN	00435
AJP	2 (5T)	ENI	(0)	•	ORDERED TURN GT POSSIBLE TURN	00436
ENQ	(0)	LDA	(JUMP)	•	ORDERED TURN LT POSSIBLE TURN	00437
DVI	(ICHECK)	STA	(ITER)	•	DETERMINE NUMBER OF	00440
LDA	(ITER)	SUB	(IONE)	•	ONE SECOND ITERATIONS	00441
AJP	3 (4T)	AJP	(4T)	•	ONE OR LESS ITERATIONS	00442
ENI	2 (1)	LDA	(ITER)	•	INITIALIZE	00443
SAU	(3TURN)	ENI	(0)	•	ITERATION INDEX	00444
LDA	(CRS)	FAD	(DPS)	•	INCREMENT	00445
STA	(CRS)	LDA	(AXIS)	•	X	00446

1T

2T

3T

2TURN

APPENDIX II-C

AJP 2 (L+3)	LDA (CRS)	JUMP IF COURSE POSITIVE	00510
FAD (DEGREES)	STA (CRS)	COURSE NEGATIVE, ADD 360 DEG	00511
SLJ (L-3)	ZRO (0)	JUMP TO RECHECK	00512
LDA (CRS)	FSB (DEGREES)	CHECK FOR COURSE	00513
AJP (L+1)	AJP 3 (L+3)	GREATER THAN 360 DEGREES	00514
LDA (CRS)	FSB (DEGREES)	COURSE GT 360, SUBTRACT 360	00515
STA (CRS)	SLJ (L-3)	JUMP TO RECHECK	00516
LDA (CRS)	SLJ 4 (FIX)	CONVERT COURSE	00517
STA (ICRS)	ENA (0)	TO FIXED POINT	00520
STA (NEXT)	SLJ (3MOVE)	RESET MULTIPLE MANEUVER FLAG	00521

* CLIMB SECTION

IDIVE LDA 1 (JHEAD)	SCL (MASK1)	UNPACK ALTITUDE	00522
ALS (24)	ARS (24)	EXTEND SIGN BIT	00523
STA (IZ)	LDA 1 (JHEAD)	STORE ALTITUDE	00524
SCL (MASK11)	ARS (24)	UNPACK	00525
STA (IALT)	LDA 1 (KHEAD)	ORDERED ALTITUDE	00526
SCL (MASK17)	ARS (12)	UNPACK	00527
STA (IFPS)	LDA (IALT)	CLIMB RATE	00530
SUB (IZ)	AJP 2 (L+2)	JUMP IF CLIMB CALLED FOR	00531
LAC (IFPS)	STA (IFPS)	DIVE CALLED FOR	00532
LDA (IALT)	SUB (IZ)	COMPUTE	00533
STA (TEMP)	ENA (TEMP)	AMOUNT	00534
SAL (XABSF+1)	SLJ 4 (XABSF)	OF ORDERED	00535
STA (JUMP)	ENA (IFPS)	CLIMB/DIVE	00536
SAL (XABSF+1)	SLJ 4 (XABSF)	COMPUTE ABSOLUTE CLIMB RATE	00537
STA (JFPS)	MUI (IPERIOD)	COMPUTE AMOUNT OF CLIMB	00540
STA (TEMP)	LDA (JUMP)	POSSIBLE THIS PERIOD	00541
SUB (TEMP)	AJP (L+2)	JUMP IF CLIMB = POSSIBLE CLIMB	00542
AJP 2 (L+4)	ENI (0)	JUMP, CLIMB GT POSSIBLE CLIMB	00543
LDA (IALT)	STA (IZ)	CLIMB COMPLETE,	00544
LDA (MOD)	SUB (ITHREE)	SET ALTITUDE TO	00545
STA (MOD)	SLJ (L+3)	ORDERED ALTITUDE	00546
LDA (IPERIOD)	MUI (IFPS)	INCREMENT	00547
ADD (IZ)	STA (IZ)	ALTITUDE	00550

APPENDIX II-C

LDA 1 (JHEAD) SCL (MASK11) • CLEAR AND 00551
 STA 1 (JHEAD) LDA (IZ) • REPLACE 00552
 SCL (MASK1) RAD 1 (JHEAD) • ALTITUDE 00553
 LDA (NEXT) AJP (1GO) • CHECK MULTIPLE MANEUVER FLAG 00554
 SLJ (1TURN) ZRO (0) • JUMP IF CLIMBING TURN 00555

* SPEED CHANGE SECTION

1SPD LDA 1 (KHEAD) SCL (MASK3) • UNPACK 00556
 STA (IVEL) LDA 1 (KHEAD) • ORDERED SPEED 00557
 SCL (MASK18) ARS (28) • AND 00560
 STA (IKPS) LDA (IVEL) • ACCELERATION RATE 00561
 SUB (ISPD) AJP 2 (L+2) • JUMP IF SPEED INCREASE 00562
 LAC (IKPS) STA (IKPS) • SPEED DECREASE CALLED FOR 00563
 LDA (IVEL) SUB (ISPD) • COMPUTE 00564
 STA (TEMP) ENA (TEMP) • AMOUNT 00565
 SAL (XABSF+1) SLJ 4 (XABSF) • OF ORDERED 00566
 STA (JUMP) ENA (IKPS) • ACCELERATION AND 00567
 SAL (XABSF+1) SLJ 4 (XABSF) • MAXIMUM POSSIBLE 00570
 STA (KPS) MUI (IPERIOD) • ACCELERATION THIS PERIOD 00571
 STA (TEMP) LDA (JUMP) • 00572
 SUB (TEMP) AJP (L+2) • JUMP IF ACCELERATION TO END 00573
 AJP 2 (L+4) ENI (0) • ACCELERATION WILL NOT END 00574
 LDA (IVEL) STA (ISPD) • ACCELERATION COMPLETE, 00575
 LDA (MOD) SUB (IFOUR) • SET SPEED TO 00576
 STA (MOD) SLJ (L+3) • ORDERED SPEED 00577
 LDA (IPERIOD) MUI (IKPS) • INCREMENT 00600
 ADD (ISPD) STA (ISPD) • SPEED 00601
 LDA (ISPD) SLJ 4 (FLOAT) • 00602
 STA (SPD) LDA (NEXT) • CHECK FOR SPEED 00603
 AJP (1GO) AJP 3 (1DIVE) • CHANGE DURING CLIMB 00604
 SUB (IONE) AJP (1TURN) • CHECK FOR 00605
 AJP 3 (1TURN) ENA (0) • TURN DURING CLIMB 00606
 STA (NEXT) SLJ (1DIVE) • RESET MULTIPLE MANEUVER FLAG 00607

APPENDIX II-C

* MULTIPLE MANEUVER SECTION

1CT	ENA (1)	STA (NEXT)	• CLIMBING TURN	00610
	SLJ (LDIVE)	ZRO (0)	•	00611
1ST	ENA (1)	STA (NEXT)	• SPEED CHANGE IN TURN	00612
	SLJ (1SPD)	ZRO (0)	•	00613
1SC	ENA (2)	STA (NEXT)	• SPEED CHANGE IN CLIMB	00614
	SLJ (1SPD)	ZRO (0)	•	00615
1SCT	ENA (-1)	STA (NEXT)	• SPEED CHANGE IN CLIMBING TURN	00616
	SLJ (1SPD)	ZRO (0)	•	00617

* KEYBOARD COMMAND SECTION

IKEY	LDA (IDD65+1)	STA (NR)	• STORE TRACK NUMBER	00620
	LDA (IDD65+2)	STA (KMAN)	• STORE MANEUVER CODE	00621
	LDA (IDD65+3)	STA (ICRS)	• STORE COURSE	00622
	LDA (IDD65+4)	STA (ISPD)	• STORE SPEED	00623
	LDA (IDD65+5)	STA (IALT)	• STORE ORDERED ALTITUDE	00624
	LDA (IDD65+6)	MUI (ISCALE1)	• SCALE X POSITION	00625
	STA (IX)	LDA (IDD65+7)	• STORE X POSITION	00626
	MUI (ISCALE1)	STA (IY)	• STORE Y POSITION	00627
	LDA (IDD65+8)	MUI (ISCALE2)	• SCALE ALTITUDE POSITION	00630
	STA (IZ)	LDA (IDD65+10)	• STORE ALTITUDE POSITION	00631
	STA (RATE)	ENI 2 (1)	• STORE MANEUVER RATE	00632
	ENA (0)	ENI (0)	• SET IDD65	00633
	STA 2 (IDD65)	ENI (0)	• ARRAY	00634
1K	ISK 2 (12B)	SLJ (L-1)	• TO ZERO	00635
	LIL 1 (NR)	ENA (KMAN)	• SET INDEX ONE TO TRACK NUMBER	00636
	SAL (XABSF+1)	SLJ 4 (XABSF)	• SET MANEUVER CODE EQUAL TO	00637
	STA (MAN)	LDA (IPERIOD)	• ABSOLUTE VALUE OF KMAN	00640
	AJP 1 (L+2)	ENA (-1)	• SET	00641
	STA (KEY)	SLJ (L+2)	• KEYBOARD	00642
	ENA (1)	STA (KEY)	• FLAG	00643
	LDA (MAN)	AJP (2TRAK)	• JUMP IF MAN ERROR	00644
	SUB (IEIGHT)	AJP (1STOP)	• JUMP TO SCRUB TRACK	00645
	LDA 1 (IHEAD)	SCL (MASK4)	• UNPACK OLD MANEUVER CODE	00646

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STA	(MODPOS)	SUB	(MOD8)	•	SELECT KEYBOARD MANEUVER	00647
AJP	(6KEY)	LDA	(MAN)	•	START TRACK	00650
INA	(-1)	AJP	(2TRAK)	•	ERROR	00651
INA	(-1)	AJP	(2KEY)	•	TURN	00652
INA	(-1)	AJP	(3KEY)	•	CLIMB/DIVE	00653
INA	(-1)	AJP	(4KEY)	•	CHANGE SPEED	00654
INA	(-1)	AJP	(1FADE)	•	FADE	00655
INA	(-1)	AJP	(2FADE)	•	UNFADE	00656
SLJ	(2TRAK)	ZRO	(0)	•	ERROR	00657

* KEYBOARD TURN SECTION

2KEY	LDA	(ICRS)	STA	(LIMIT)	•	STORE ORDERED COURSE	00660
ENA	(RATE)	SAL	(SIGNF+1)	•	INSERT PROPER	00661	
ENA	(KMAN)	SAL	(SIGNF+2)	•	SIGN INTO	00662	
ENI	(0)	SLJ	4 (SIGNF)	•	TURN RATE	00663	
STA	(RATE)	SLJ	(5KEY)	•	END KEYBOARD TURN SECTION	00664	

* KEYBOARD CLIMB SECTION

3KEY	LDA	(IALT)	STA	(LIMIT)	•	STORE ORDERED ALTITUDE	00665
SLJ	(5KEY)	ZRO	(0)	•		00666	

* KEYBOARD SPEED CHANGE SECTION

4KEY	LDA	(ISPD)	STA	(LIMIT)	•	STORE ORDERED SPEED	00667
------	-----	--------	-----	---------	---	---------------------	-------

* EXIT FROM KEYBOARD ROUTINE

5KEY	LDA	1 (IHEAD)	SST	(ISKIP)	•	SET ISKIP	00670
STA	1 (IHEAD)	SLJ	(6TRAK)	•	TO ONE	00671	

* START TRACK FROM KEYBOARD

6KEY	LDA	(MAN)	SUB	(IONE)	•	CHECK FOR START COMMAND	00672
AJP	1 (2TRAK)	LDA	1 (IHEAD)	•	JUMP IF NOT START (ERROR)	00673	

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SCL (MOD8)	AJP 1 (2TRAK)	JUMP IF NOT PREVIOUSLY STARTED	00674
LDA (IX)	SCL (MASK1)		00675
ALS (24)	STA 1 (IPOSIT)	PACK X POSITION	00676
LDA (IY)	SCL (MASK1)		00677
RAD 1 (IPOSIT)	LDA (IZ)	PACK Y POSITION	00700
SCL (MASK1)	STA 1 (JHEAD)	PACK ALTITUDE	00701
LDA (ICRS)	MUI (I2B)	CONVERT COURSE TO	00702
SCL (MASK3)	ALS (I2)	TENTHS OF DEGREES	00703
STA 1 (IHEAD)	LDA (ISPD)	PACK COURSE	00704
SCL (MASK3)	SST (ISKIP)	SET SKIP BIT	00705
RAD 1 (IHEAD)	SLJ (2TRAK)	PACK SPEED	00706

* DATA PROCESS COMMAND SECTION

7KEY	LDQ (LHEAD+1)	LDL (777777B)	UNPACK MANEUVER RATE	00707
STA (TEMP)	LDA (LHEAD+1)	LDA (LHEAD+1)	STORE MANEUVER RATE	00710
LRS (9)	QRS (39)	QRS (39)	UNPACK Y POSITION	00711
STQ (IY)	LRS (9)	LRS (9)	STORE Y POSITION	00712
QRS (39)	STQ (IX)	STQ (IX)	STORE X POSITION	00713
LRS (18)	QRS (30)	QRS (30)	UNPACK MANEUVER LIMIT	00714
STQ (LIMIT)	LRS (4)	LRS (4)	STORE MANEUVER LIMIT	00715
QRS (44)	STQ (NR)	STQ (NR)	STORE TRACK NUMBER	00716
LRS (5)	QRS (43)	QRS (43)	UNPACK MANEUVER CODE	00717
STQ (KMAN)	LDA (NR)	LDA (NR)	STORE MANEUVER CODE	00720
SCL (MASK7)	STA (NR)	STA (NR)	MASK TRACK NUMBER	00721
ENI 1 (1)	ENI 2 (1)	ENI 2 (1)	SHIFT	00722
INI 2 (1)	LDA 2 (LHEAD)	LDA 2 (LHEAD)	LHEAD	00723
STA 1 (LHEAD)	ENI (0)	ENI (0)	ARRAY	00724
ISK 1 (59)	SLJ (L-2)	SLJ (L-2)	UP BY	00725
ENA (0)	STA (LHEAD+60)	STA (LHEAD+60)	ONE CELL	00726
LDA (KMAN)	INA (-1)	INA (-1)	SELECT MANEUVER	00727
AJP 1 (7K)	LDA (IX)	LDA (IX)	START TRACK	00730
MUI (ISCALE1)	STA (IX)	STA (IX)	SCALE X POSITION	00731
LDA (IY)	MUI (ISCALE1)	MUI (ISCALE1)		00732
STA (IY)	ENA (I20B)	ENA (I20B)	SCALE Y POSITION	00733
MUI (ISCALE2)	STA (IZ)	STA (IZ)	SET ALTITUDE TO 80 FEET	00734

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ENA	(170B)	STA	(ISPD)	•	SET SPEED TO 120 KNOTS	00735
LDA	(LIMIT)	STA	(ICRS)	•	STORE ORDERED CPURSE	00736
SLJ	(1K)	ZRO	(0)	•		00737
INA	(-1)	AJP	(L+3)	•	STARBOARD TURN	00740
INA	(-1)	AJP	(L+6)	•	CLIMB/DIVE	00741
INA	(-1)	AJP	(L+7)	•	CHANGE SPEED	00742
LDA	(LIMIT)	STA	(ICRS)	•	TURN OR ERROR	00743
LDA	(TEMP)	SLJ 4	(FLOAT)	•	FORM	00744
FDV	(10.)	STA	(RATE)	•	MANEUVER RATE	00745
SLJ	(1K)	ZRO	(0)	•		00746
LDA	(LIMIT)	STA	(IALT)	•	CLIMB/DIVE	00747
SLJ	(L+2)	ZRO	(0)	•		00750
LDA	(LIMIT)	STA	(ISPD)	•	CHANGE SPEED	00751
LDA	(TEMP)	SLJ 4	(FLOAT)	•	FORM MANEUVER RATE	00752
STA	(RATE)	SLJ	(1K)	•		00753

7K

END

APPENDIX III-A

1. Identification.

Title: PRINT

Category: On Line Display

Programmer: E. L. Borden

Organization: U. S. Naval Postgraduate School

Date: April 1965

2. Purpose.

This subroutine is designed to allow users to display characters and/or vectors on the Data Display model dd 65. The routine enables the user to display data without the trouble of packing special words for the dd 65.

3. Usage.

3.1 Normal Operation.

3.1.1 PRINT provides for entry of the medium size characters. Vectors of any size allowed will be entered by PRINT.

3.1.2 In order to illustrate the usage of PRINT, assume that you wanted to output to the dd 65 the following message:

"NO TRACKS UNDER YOUR CONTROL."

In the memory of the 1604 you would have the following stored:

<u>Address</u>	<u>Contents of cell</u>
22222	4546202351616342
22223	2220244564655120
22224	3046245120634645
22225	2351464373000000

PRO = 1 - right hand tube
0 - left hand tube

ADD = Address in dd 65 memory where message to be stored

APPENDIX III-A

X = X position of First Character/Vector

Y = Y position of First Character/Vector

To display the message on the dd 65 the following set of coding is necessary:

ENA	(X)	SAL	(PRINT+1)	.
ENA	(Y)	SAL	(PRINT+2)	.
ENA	(PRO)	SAL	(PRINT+3)	.
ENA	(ADD)	SAL	(PRINT+4)	.
ENA	(22222B)	ENQ	(0)	.
SLJ	4 (PRINT)	ZRO	(0)	.

The address of the message to be displayed is entered in the Accumulator and the Q-Register is set to zero for character mode or to minus zero for vector mode. If the argument PRINT+4 is deleted the address will be the next available cell in the dd 65 memory.

3.1.3 When the main program executes the subroutine, the subroutine assembles the message and packs it into a designator word and subsequent string words. The packing ends when the end of the message is sensed. To sense the end of the message, PRINT uses two codes. The code 00 is used to sense the end of a character message since this code is illegal. The code 77 is used to sense the end of a vector message since this code is an illegal vector code.

3.1.4 PRINT has a built in sense for end of line and end of page. Before any character or vector is assembled into a word the end of line is sensed. If the end of the line has been reached, the subroutine will reset the X position to an initial position of 400₈ and the Y position will then be checked for end of page. If the end of page has not been reached, the Y position will be decreased by 12₈ and a new designator word will begin with the new X and Y positions. If the end of page is sensed, then the Y

APPENDIX III-A

position will be reset to an initial value of 377_8 . At this time the new designator word will be formed. The routine also checks to insure that memory is not overflowed. Before packing any word, a memory check is made and if it is found that memory has overflowed, then the memory address is reset to 002_8 and a new designator word is started.

Subroutine PRINT

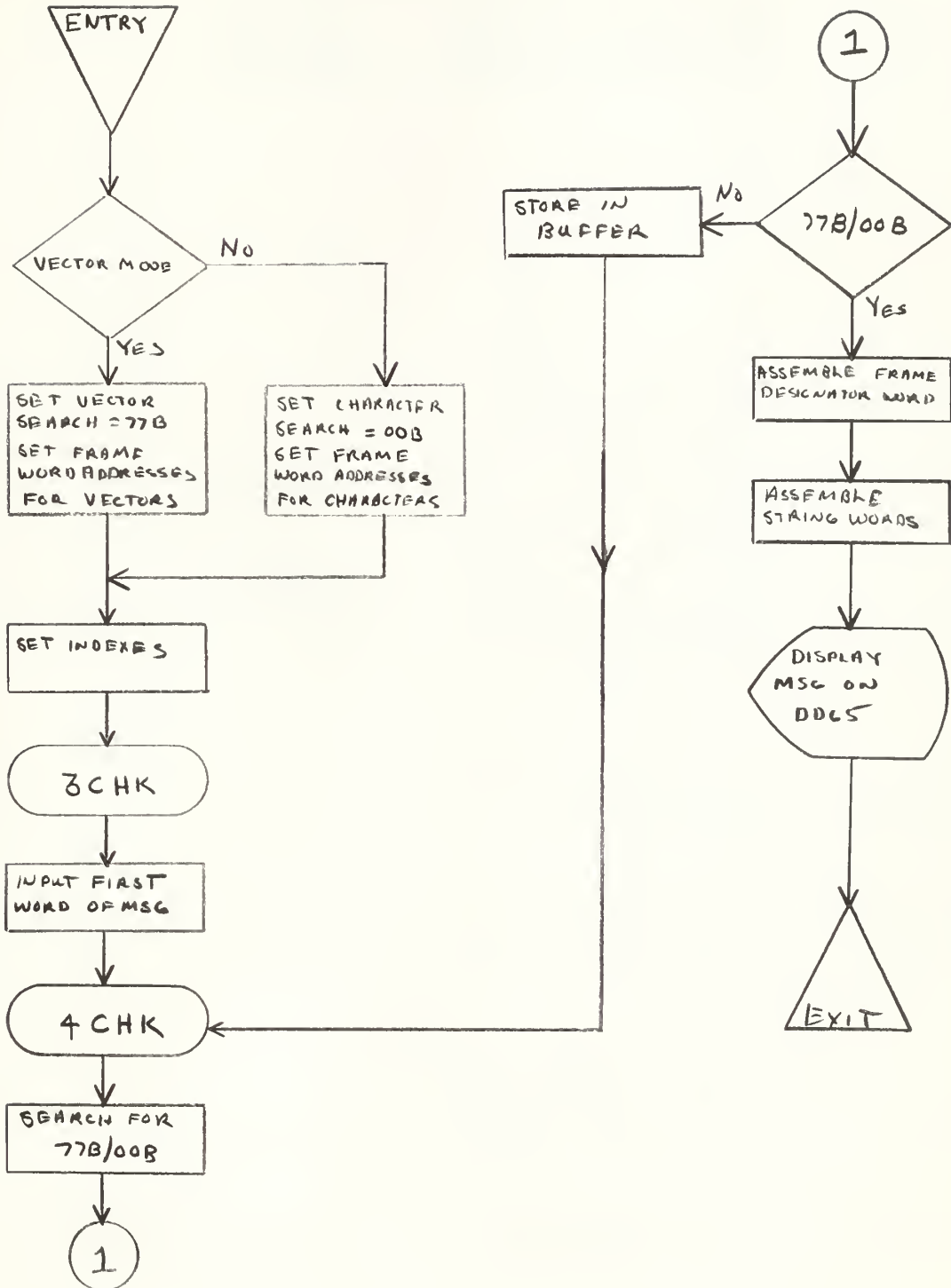


Figure III-1

APPENDIX III-C

SUBROUTINE PRINT PROGRAM LISTING

MACHINE PRINT (1A,2A,3A,4A)

RSV(BUF=121,OUTPUT=18)

CON(DW= 3000000000000000, LTFWC = 1000B, RTFWC = 5000B,VI = 776B,
 * LTFWV = 3000B, RTFWV = 7000B, LTSWC = 0B, RTSWC = 4000B,
 * LTSWV = 2000B, RTSWV = 6000B, XI = -377B, YI = 377B, V = 77B,
 * MASK1 = 777777777777000B, DX = 10B, DY=12B)

IRET	SLJ	(N)	SLJ	(1CHK)	• EXIT / ENTRY	00000
1A	ZRO	(0)	ZRO	(0)	• X-POSITION	00001
2A	ZRO	(0)	ZRO	(0)	• Y-POSITION	00002
3A	ZRO	(0)	ZRO	(0)	• 0-LEFT TUBE 1-RT TUBE	00003
4A	ZRO	(0)	ZRO	(0)	• MEMORY ADDRESS	00004

* SET UP SEARCH WORDS

1CHK	SIU 2	(1SAVE)	SIL 3	(1SAVE)	• SAVE INDEXES	00005
	SIU 4	(2SAVE)	SIL 5	(2SAVE)	• 2,3,4,5	00006
	STA	(TEMP)	QJP 3	(2CHK)	• VECTOR OR CHARACTER MODE	00007
	ENA	(LTSWC)	SAU	(5CHK)	• SET SEARCH = ZERO	00010
	ENA	(LTFWC)	SAL	(1C1)	• SET FIRST WORD	00011
	ENA	(LTSWC)	SAU	(2C1)	• SET STRING WORD	00012
	SLJ	(L+4)	ZRO	(0)	•	00013
2CHK	ENA	(V)	SAU	(5CHK)	• SET SEARCH = 77B	00014
	ENA	(LTFWV)	SAL	(1C1)	• SET FIRST WORD	00015
	ENA	(LTSWV)	SAU	(2C1)	• SET STRING WORD	00016
	ENI 2	(1)	ENI 3	(7)	• B2 = BUFFER INDEX, B3 = LETTER	00017

* FILL BUFFER SECTION

3CHK	LDQ 7	(TEMP)	ENA	(0)	•	00020
4CHK	LLS	(6)	ENI	(0)	•	00021
5CHK	EQS	(N)	SLJ	(6CHK)	• SEARCH FOR 00/77	00022
	SLJ	(7CHK)	ZRO	(0)	•	00023
6CHK	STA 2	(BUF)	ENA	(0)	• STORE IN BUFFER	00024

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ISK 2 (121)	SLJ (L+2)	• CHECK FOR FULL BUFFER	00025
SLJ (7CHK)	ZRO (0)	• JUMP IF BUFFER FILLED	00026
IJP 3 (4CHK)	ENI (0)	• LOOP FOR 8 CHARACTERS	00027
RAO (TEMP)	ENI 3 (7)	• INCREASE WORD ONE ADDRESS	00030
ENA (0)	SLJ (3CHK)	•	00031
INI 2 (-1)	LDA (4A)	•	00032

* ASSEMBLY OF DESIGNATOR WORD

8CHK	SUB (V1)	AJP 6 (1MEM)	• CHCEK FOR MEMORY OVERFLOW	00033
	ENI 4 (18)	LDA (DW)	• ASSEMBLE FIRST WORD FRAME	00034
	STA 4 (OUTPUT)	LDA 7 (1A)	•	00035
	STA (X)	SCL (MASK1)	•	00036
	ALS (36)	RAD 4 (OUTPUT)	• PACK INITIAL X POSITION	00037
	LDA 7 (2A)	STA (Y)	•	00040
	SCL (MASK1)	RAD 4 (OUTPUT)	• PACK INITIAL Y POSITION	00041
	LDA (4A)	ALS (13)	•	00042
	RAD 4 (OUTPUT)	ENI 5 (1)	•	00043
	SIL 2 (CHECK)	SLJ (1C)	• SET CHECK	00044

*RESET MEMORY TO 002 SECTION

1MEM	SLJ (N)	ENA (2)	• RESET MEMORY	00045
	STA (4A)	SLJ (1MEM)	•	00046

* ASSEMBLY OF STRING WORDS

1C	LDA 5 (BUF)	ALS (30)	•	00047
	RAD 4 (OUTPUT)	SLJ 4 (1XY)	•	00050
	INI 5 (1)	LDA 5 (BUF)	•	00051
	ALS (24)	RAD 4 (OUTPUT)	• CHECK X-Y POSITION	00052
1C1	INI 5 (1)	ENA (N)	•	00053
	ADD (3A)	STA (TEMP)	• ASSEMBLE STRING WORD FRAME	00054
	LDA 7 (TEMP)	RAD 4 (OUTPUT)	• PACK MODE, TUBE, AND STRING BIT	00055
	INI 4 (-1)	ENA (2)	•	00056
	RAD (4A)	ENA (-2B)	•	00057

APPENDIX III-C

00060
00061
00062
00063

• CHECK FOR END OF MSG
•
• CHECK FOR MEMORY OVERFLOW

AJP (IOUT)
ENI (0)
SUB (V1)
ENI (0)

RAD (CHECK)
AJP 3 (IOUT)
LDA (4A)
AJP 6 (IMEM)

2C

* FILL STRING WORDS

00064
00065
00066
00067
00070
00071
00072
00073
00074
00075
00076
00077
00100
00101
00102
00103
00104
00105
00106
00107
00110
00111
00112
00113
00114

• FIRST CHARACTER
• SECOND CHARACTER
• THIRD CHARACTER
• FOURTH CHARACTER
• FIFTH CHARACTER
• SIXTH CHARACTER
• SEVENTH CHARACTER

ENI (0)
STA (TEMP)
STA 4 (OUTPUT)
SLJ 4 (IXY)
ALS (42)
INI 5 (1)
SLJ 4 (IXY)
ALS (36)
INI 5 (1)
SLJ 4 (IXY)
ALS (30)
INI 5 (1)
SLJ 4 (IXY)
ALS (24)
INI 5 (1)
SLJ 4 (IXY)
ALS (18)
INI 5 (1)
SLJ 4 (IXY)
ALS (12)
INI 5 (1)
SLJ 4 (IXY)
RAD 4 (OUTPUT)
IJP 4 (3C)
ZRO (0)

ENI (N)
ADD (3A)
LDA 7 (TEMP)
RSD (CHECK)
LDA 5 (BUF)
RAD 4 (OUTPUT)
RSD (CHECK)
LDA 5 (BUF)
RAD 4 (OUTPUT)
RSD (CHECK)
LDA 5 (BUF)
RAD 4 (OUTPUT)
RSD (CHECK)
LDA 5 (BUF)
RAD 4 (OUTPUT)
RSD (CHECK)
LDA 5 (BUF)
INI 5 (1)
SLJ (IOUT)

2C1

* INCREMENT MEMORY ADDRESS

00115

RAD (4A)

3C ENA (2)

APPENDIX III-C

LDA (CHECK) INI 4 (1) • CHECK FOR END OF MSG 00116
 AJP 3 (IOUT) AJP (IOUT) • 00117
 INI 4 (-1) SLJ (2C) • LOOP FOR STRING WORDS 00120

* X-Y POSITION CHECK

IXY SLJ (N) LDA (CHECK) • 00121
 AJP 3 (IOUT) LDA (DX) • CHECK FOR END OF MSG 00122
 RAD (X) SUB (377B) • INCREASE X 00123
 AJP 2 (L+1) SLJ (IXY) • X OVERFLOW NO-RETURN 00124
 LDA (XI) STA (X) • YES - INCREASE Y 00125
 LAC (DY) RAD (Y) • 00126
 ADD (400B) AJP 3 (IXY2) • Y OVERFLOW JUMP IF YES 00127

* NEW DESIGNATOR WORD SECTION

IXY1 IJP 4 (IX) SLJ (IOUT) • 00130
 IX LDA (DW) ENI (0) • ASSEMBLE DESIGNATOR WORD 00131
 STA 4 (OUTPUT) ENQ (777B) • 00132
 LDL (X) ALS (36) • 00133
 RAD 4 (OUTPUT) LDL (Y) • PACK X POSITION 00134
 RAD 4 (OUTPUT) ENA (2) • PACK Y POSITION 00135
 RAD (4A) SUB (V1) • 00136
 AJP 6 (IMEM) LDA (4A) • CHECK FOR MEMORY OVERFLOW 00137
 ALS (13) RAD 4 (OUTPUT) • INCREMENT MEMORY ADDRESS 00140
 SLJ (IC) ZRO (0) • 00141

* RESET Y TO Y-INITIAL SECTION

IXY2 LDA (YI) STA (Y) • 00142
 SLJ (IXY1) ZRO (0) • 00143

* OUTPUT TO DD65 SECTION

IOUT ENI 5 (1) ENI (0) • 00144
 ZOUT LDA 4 (OUTPUT) STA 5 (OUTPUT) • 00145

APPENDIX IV-A

1. Identification.

Title: COURSE

Category: Course and Velocity determination

Programmer: E. L. Borden

Organization: U. S. Naval Postgraduate School

Date: April 1965

2. Purpose.

This subroutine is designed to take an x-velocity, a y velocity, and a z-position and determines a course in degrees true, a velocity in knots, and a velocity in mach number for any z-position greater than zero.

3. Usage.

3.1 Normal Operation

3.1.1 The normal calling sequence of COURSE is as follows:

VX = X-velocity in knots
VY = Y-velocity in knots
CRS = Course in degrees true
SPD = Speed in knots
MACH = Mach number
Z = Z-position in feet

ENA	(VX)	SAL	(COURSE+1)	.
ENA	(VY)	SAL	(COURSE+2)	.
ENA	(CRS)	SAL	(COURSE+3)	.
ENA	(MACH)	SAL	(COURSE+4)	.
ENA	(Z)	SAL	(COURSE+5)	.
ENA	(SPD)	SAL	(COURSE+6)	.
SLJ	4 (COURSE)	ZRO	(0)	.

3.1.2 COURSE determines course and speed in the normal manner.

Mach number is determined by the following formula:

APPENDIX IV-A

$$\text{MACH} = \frac{\text{SPD(knots)}}{661 - 2.5 \times \text{ALT(Kft)}}$$

The above formula is valid for ALT less than 35,000 feet. If ALT is greater than 35,000 feet, it is reduced to 35,000 feet.

Subroutine COURSE Chart 1

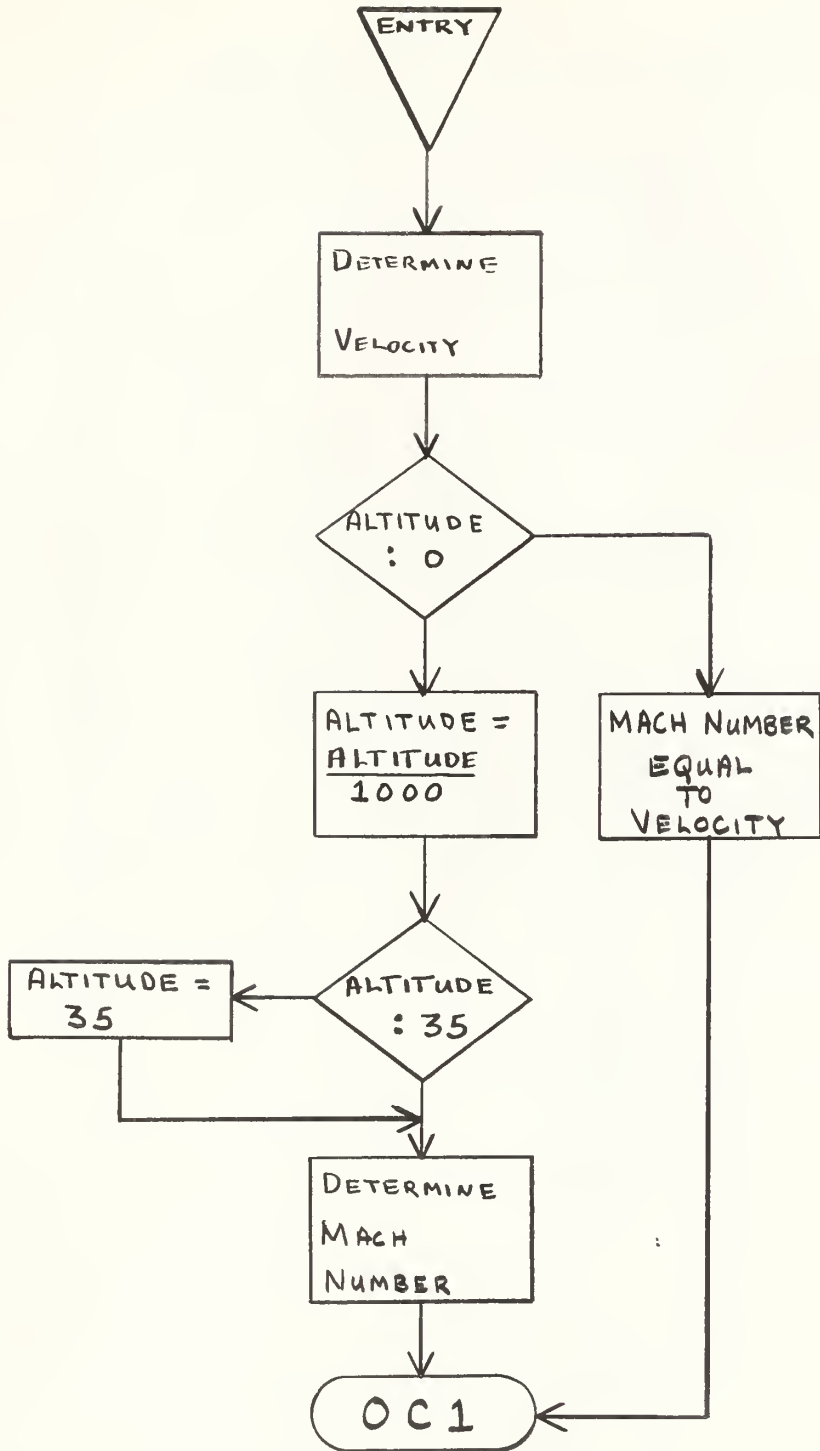


Figure IV-1

Subroutine COURSE Chart 2

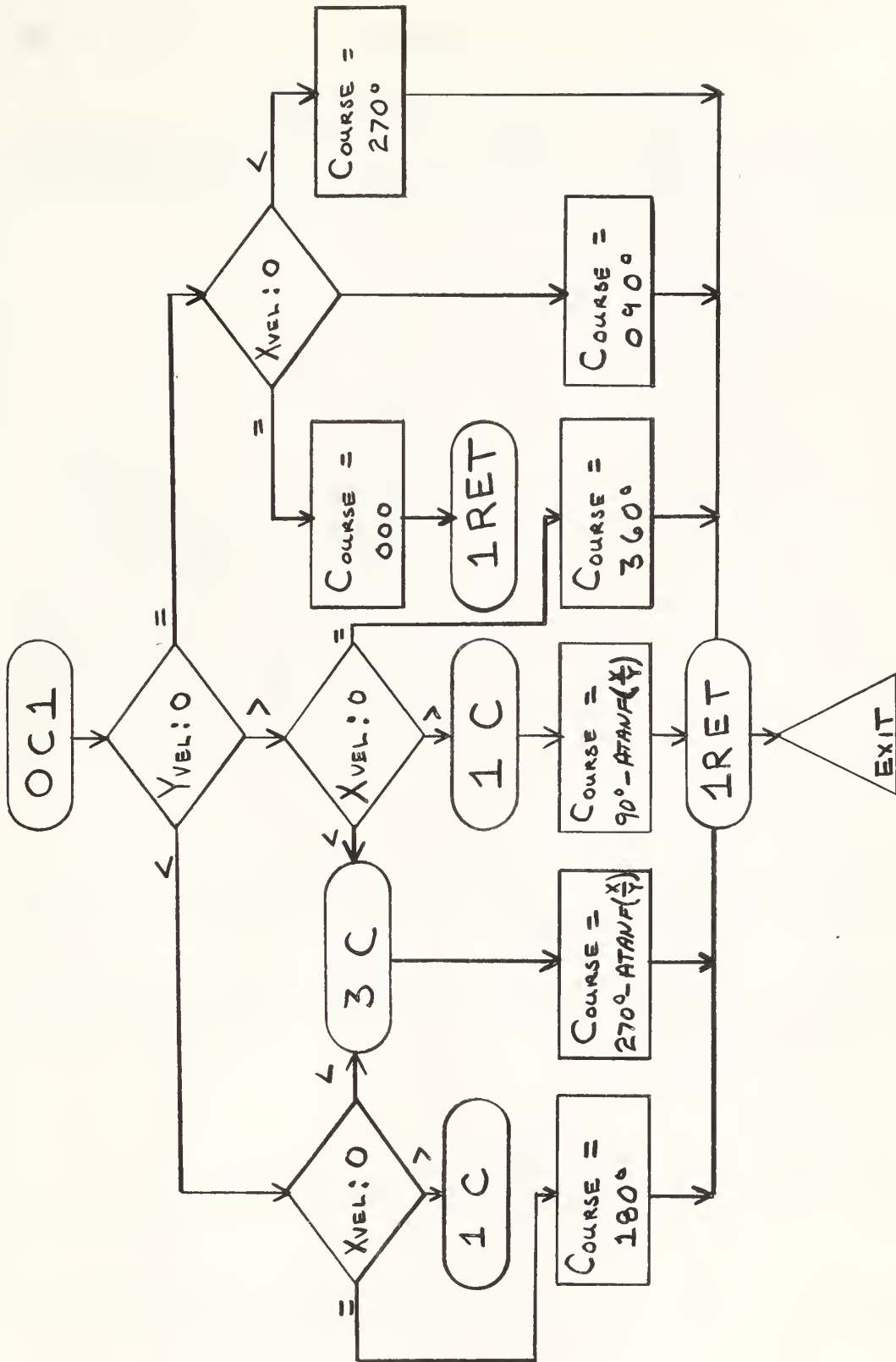


Figure IV-2

APPENDIX IV-C

STA 7 (3A)	SLJ (IRET)	•	00034
* 360 DEGREES			
2C LDA (360•)	STA 7 (3A)	•	00035
SLJ (IRET)	ZRO (0)	•	00036
* 180-270 DEGREES			
3C LDA 7 (2A)	FDV 7 (1A)	•	00037
STA (TEMP)	ENA (TEMP)	•	00040
SAL (AT+1)	SLJ 4 (AT)	•	00041
FMU (57•3)	STA (TEMP)	•	00042
LDA (270•)	FSB (TEMP)	•	00043
STA 7 (3A)	SLJ (IRET)	•	00044
* 090 -180 DEGREES			
4C LDA 7 (1A)	AJP (5C)	•	00045
AJP 3 (3C)	SLJ (1C)	•	00046
* 180 DEGREES			
5C LDA (180•)	STA 7 (3A)	•	00047
SLJ (IRET)	ZRO (0)	•	00050
* 270-360 DEGREES			
6C LDA 7 (1A)	AJP (8C)	•	00051
AJP 3 (7C)	LDA (90•)	•	00052
STA 7 (3A)	SLJ (IRET)	•	00053
* 270 DEGREES			
7C LDA (270•)	STA 7 (3A)	•	00054
SLJ (IRET)	ZRO (0)	•	00055

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