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U.S. NAVAL POSTGRADUATE SCHOOL

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Moxtexey, Cat.....im CIRCULAR CYIINDRICAI SHELLS SUBJECTED TO HYDROSTATIC PRESSURE

A Thesis<br>Submitted to the Faculty of Hebb Institute of Naval Architecture In Partial Fulfillment Of the Requirements for the Degree of Master of Science In Naval Architecture

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## ABSTRACT

Experimental investigations were undertaken to determine the collapse pressures of relatively thick circular cylindrical shells subjected to hydrostatic pressure. A total of twenty-three fiber glass reinforced plastic cylinders with thickness to diameter ratios ranging from 0.05 to 0.09 was tested to determine collapse pressures and the effective modulus of elasticity of the material. The length to diameter ratio was kept constant. Results were plotted non-dimensionally with $\mathrm{P} / \mathrm{E}$ as the ordinate and $h / D$ as the abscissa. The results were compared with available theoretical instability formulas and were in very good agreement with theory for ratios of $h / D$ up to about 0.07 . Above this value of $h / D$, experimental collapse pressures were lower than those predicted by theory.

It was concluded that the von Mises equation [equation (6), Ref. 22] is the best instability equation for cylinders with ratios of $h / D$ greater than 0.05. It was also concluded that for almost all practical cases, the thin shell theory is sufficiently accurate for predicting instability fallures.

Derivations for the following are included: (1)Expressions for calculation of the moduli of elasticity in the circumferential and longitudinal directions; (2)An expression for the shear modulus and for the effective modulus of elasticity of an orthotropic material; (3)A determinant expressing the critical pressure of simply supported, orthotropic, circular cylinders subjected to hydrostatic pressure; and (4) An expression for calculating the bending stress in a simply supported circular cylinder subjected to hydrostatic pressure.
Page
ABSTRACT ..... ii
ACKNOWLFDGEMENT ..... 111
NOTATION ..... iv
INTRODUCTION ..... 1
CONCFPTS AND ASSUMPTIONS IN '?HE THFORY OF THIN SHELIS ..... 3
LITERATURE SURVEY ..... 7
TEST APPARATUS, MODELS, AND TEST PROCEDURE ..... 19
EXPERIMENTAL DATA ..... 40
ANALYSIS OF EXPERIMENTAL DATA ..... 4
PRESENTATION AND DISCUSSION OF RESULTS ..... 58
CONCLUSIONS ..... 64
RECOMMENDATIONS ..... 65
BIBLIOGRAPHY ..... 67
APPENDICES
RECORD OF STRAIN DATA ..... Al
PLOTS OF PRESSURE VS. STRAIN ..... Bl
THEORY FOR CALCULATION OF Ex AND Eø FROM STRAIN DATA ..... Cl
DERIVATION OF SHEAR MODULUS FOR AN ORTHOTROPIC MATERIAL ..... D1
DERIVATION OF DETERMINANT FOR THE CRITICAL PRESSURE OF A SIMPLY SUPPORTED, ORTHOTROPIC, CIRCULAR CYLINDER SUBJECTED TO HYDROSTATIC PRESSURE ..... El
DEPIVATION OF AN EYPRESSION FOR THE LONGITUDINAL BENDING STRESS IN A SIMPIY SUPPORTED CIRCULAR CYLINDER SUBJECTED TO EXTFRNAL HYDPOSTATIC PRESSURE ..... F1
SOLUTION OF VON MISFS' EQUATION (6) ..... G1

## LIST OF TABLES

TABLE SUAJECT ..... PAGE
1 SUMMARY OF EXPERIMENTAL INVESTIGATIONS IN THE LITERATURE ..... 12THEORETICAL BUCKLING FORMULAS FORUNSTIFFFNED CYIINDERS UNDER HYDROSTATICLOAD13
34CALCULATION OF EFFECTIVE YOUNG'S MODULUS, E $E^{\circ}$53
12CALCULATION FOR NON-DIMENSIONALBUCKI.ING PRESSURE60

## LIST OF FIGURES

FIGURE TITLE ..... PAGE
A SHELI ELEMENT ..... vii
1 DRAWING OF PRFSSURE VESSEL ..... 22
2 DETAILS OF "O" RING, GROOVE, \& CIACULAR PLATE ..... 233 ARRANGEMENT OF FITTINGS IN PRESSUREVESSEL24
4 ARRANGFMENT OF TEST APPARATUS ..... 25
5 PHOTOGRAPH OF ASSEMRIED APPARATUS ..... 26
6
BUCKLING CUDVES BASED ON FORMULA 9 ..... 29
7
DRAWING OF MODEL \& END PIUGS ..... 31
8 MODEL PRFPARFD FOR TESTING ..... 37
9 GAGE CALIBRATION, 15,000 PSI GAGE ..... 38
10 GAGE CALIBRATION, 5000 PSI GAGE ..... 39
11 PHOTOGRAPH OF COLIAPSED MODELS ..... 56
12 PHOTOGRAPH OF COLLAPSED MODELS ..... 57
13 PLOT OF EXPERIMENTAL RTSULTS AND THEORFTICAL BUCKLING EQUATIONS ..... 61
14
NONDIMENSIONAL BUCKLING PRESSURE FORSIMPIY SUPPORTED CIRCULAR CYIINDERSSUBJECTED TO HYDROSTATIC PRESSURE --VON MISES' EQ. (6)62
15 NUMBER OF LOBFS FOR CIRCULAR CYLINDER UNDER HYDROSTATIC PRESSURE ..... 63

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## NOTATION

D Flexural rigidity, $D=\frac{E h^{3}}{12\left(1-2^{2}\right)}$
D Mean diameter
$D_{1} \quad$ Inside diameter
$D_{2}$ Outside diameter
E Modulus of elasticity
$E_{e} \quad$ Effective modulus of elasticity for anisotropic material
Ex Modulus of elasticity in the longitudinal direction
Ee, Ed Modulus of elasticity in the circumferential direction
$G$ Shear modulus, $G=\frac{E}{2(1+2)}$
h Thickness of shell
$\mathrm{K}_{1} \quad$ Non-dimensional term from thick cylinder stress formula,

$$
K_{1}=\frac{2 R_{2}^{2}}{R_{2}^{2}-R_{1}^{2}}
$$

$\mathrm{K}_{2}$ Non-dimensional term from thick cylinder stress formula,

$$
K_{2}=\frac{R_{2}^{2}+R_{1}^{2}}{R_{2}^{2}-R_{1}^{2}}=K_{1}-1
$$

L Effective length
$L_{\text {oa }}$ Actual length
$m$ Number of waves or lobes along effective length of cylinder at time of collapse

四 $\varnothing$ Strain-pressure ratio, circumferential strain gage
${ }^{m} \times \quad$ Strain-pressure ratio, longitudinal strain gage.
$M_{x} \quad$ Axial bending moment per unit of circumference
$M_{\phi} \quad$ Circumferential bending moment per unit of length
$M_{x \phi} \quad$ Twisting moment per unit of length on element cut out by generators
Mox Twisting moment per unit of circumference on element cut out by plane perpendicular to axis


In the notation used in this paper, the subscript "I" refers to the inside of the cylinder, and the subscript "2" refers to the outside of the cylinder.
n Number of lobes or waves in a complete circumferential belt around cylinder at time of collapse
$N_{x} \quad$ Normal force per unit of circumference in axial direction
$N_{\phi} \quad$ Normal force per unit of length in circumferential direction
$N_{x} \neq$ Shear force per unit length on elements cut by generators
$N_{\phi x} \quad$ Shear force per unit of circumference on elements cut by planes perpendicular to axis
p Pressure
$Q_{\phi} \quad$ Radial shear in the $x z$ plane
$Q_{x} \quad$ Radial shear in the $y z$ plane
r Radial coordinate
R Mean radius
$R_{1} \quad$ Inside radius
$\mathrm{R}_{2}$ Outside radius
u Axial displacement
v Circumferential displacement
w Radial displacement
$z$ Perpendicular distance from mid-surface of shell, positive inward
$\alpha \quad$ Non-dimensional term in buckling equations, $\alpha=\frac{1}{3} \cdot \frac{h^{2}}{D^{2}}$
$\gamma$ Shearing strain
$\gamma_{\text {if }}$ Shearing strain along i-plane in $j$-direction
$\epsilon_{x} \quad$ Normal strain in axial direction
$\epsilon_{\varnothing} \quad$ Normal strain in circumferential direction
$\epsilon_{r} \quad$ Normal strain in radial direction
$\theta \quad$ Cylindrical (angular) coordinate
$\lambda$ Non-dimensional term in buckling equations, $\lambda=m \frac{\pi D}{2 L}$
$\nu$ Poisson's ratio
$\sigma_{x} \quad$ Normal stress in axial direction
$\sigma_{\phi} \quad$ Normal stress in circumferential direction
$\tau_{i j}$ Shear stress along 1 -plane in j-direction
$\phi \quad$ Cylindrical (angular) coordinate
$\chi_{x}$ Change of curvature of generator
$\chi_{\neq}$Change of curvature of circumference
$\chi_{x \phi}$ Twist of element due to $M_{x \phi}$


SHELL ELEMENT

The absence of experimental results and elastic instability analyses for thick cylinders has been pointed out by Wenk ${ }^{l}$. On the basis of this information and consultation with Mr. John Pulos of the Structural Mechanics Laboratory, David Taylor Model Basin, the authors decided to undertake an experimental investigation of the elastic instability of relatively thick cylinders subjected to external hydrostatic pressure. Thus, the primary purpose of this thesis evolved; which is the experimental evaluation of available theoretical instability formulas as applied to cylinders with thickness to diameter ratios greater than those heretofore tested. From the results of the proposed experiments it was anticipated that the following question posed by Dr. Wenk (see "Discussion" of Ref. l) could be answered:
"At what ratio of thickness to diameter are errors in the thin-shell approximation unacceptable?"

A prime requisite prior to undertaking the thesis was the making of a careful survey of the literature to determine the extent of theoretical and experimental work. The authors conducted such a survey both prior to beginning the experiments and on a continuing basis throughout the period of the thesis work. The reaults of this search are presented in the section entitled "Literature Survey."

It was also necessary to design and construct the experimental apparatus and the models. The materials and methods of design, together with the procedures employed, are indicated in the body of this parer. Since the models were fabricated from glass-reinforced plastic, the elastic formulas required in analyzing the data were modified to account for the difference in the values of the principal moduli of elasticity. Derivationsfor the expressions used are presented in the appendix.

References are listed beginning on page 67.

The thesis begins with a section on concepts and assumptions employed in the theory of thin shells. This study was made in order to gain an insight into the differences between a thick and a thin shell theory.

A thin shell may be defined as one for which the ratio of the thickness of the shell to the principal radil of curvature is small compared to unity. The problem of classifying a shell as thick or thin therefore reduces to the determination of a value of $h / R$ below which solution errors wll be within a prescribed limit. Novozhilov ${ }^{2}$ has stated that for ordinary technical calculations it is admissable to have a relative error of $5 \%$, and that for thin shells this corresponds to a maximum $h / R=0.05$. Timoshenko ${ }^{3}$ ( p .354 ) has suggested a value of $h / R=0.10$ as the dividing point for thin curved bars.

There are three principal assumptions employed in the theory of thin shells in addition to those made for most problems in elasticity. They are
(1) The normal stresses acting on planes parallel to the middle surface may be neglected in comparison with the other stresses.
(2) The normals to the undeformed middle surface are deformed without change of length into the normals to the deformed middle surface.
(3) The thickness $h$ is very small compared to the least radif of curvature (i.e. $h / R \ll 1$ ).

Assumptions (1) and (2) essentially reduce the problem to the case of plane stress. Consider the generalized matrix form of Hooke's law (see Borg ${ }^{4}$, p. 59).

$$
T=\lambda I_{1} E_{3}+2 \mu \eta
$$

where

$$
\begin{aligned}
& T=\text { the stress tensor } \\
& \eta=\text { the strain tensor } \\
& I_{1}=\text { the trace of the strain tensor } \\
& E_{3}=\text { the unit, } 3 \times 3, \text { matrix } \\
& \lambda, \mu=\text { constants } \\
& \lambda=\frac{\nu E}{(1+\nu)(1-2 \nu)} \quad \mu=G=\frac{E}{2(1+\nu)}
\end{aligned}
$$

Now at the inside surface of the cylinder (i.e. at $z=h / 2$ ) the stress component $\sigma_{z}$ is zero. Then, if the shell is thin, this component can be assumed to be zero throughout the thickness of the shell since it is small compared to the stresses $\sigma_{0}$ and $\sigma_{x}$.

Assumption (2) is equivalent to assuming that the shearing strains $Y_{x z}$ and $V_{\theta z}$ are zero, for the definition of shearing strain is the change in value of an originally right angle from the unstrained state. The assumption is that this right angle is preserved during deformation.

$$
\text { Therefore, letting } \sigma_{z}=V_{x z}=\gamma_{\theta z} \text { be zero, the tensor equation }
$$ becomes

$$
\left(\begin{array}{ccc}
\sigma_{x} & \sigma_{x \theta} & \sigma_{x z} \\
\sigma_{x \theta} & \sigma_{\theta} & \sigma_{\theta z} \\
\sigma_{x z} & \sigma_{\theta z} & 0
\end{array}\right)=\lambda\left(\epsilon_{x}+\epsilon_{\theta}+\epsilon_{z}\right)\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right)+2 \mu\left(\begin{array}{ccc}
\epsilon_{x} & 1 / 2 \gamma_{x \theta} & 0 \\
1 / 2 \gamma_{x \theta} & \epsilon_{\theta} & 0 \\
0 & 0 & \epsilon_{z}
\end{array}\right)
$$

Expanding the equation gives

$$
\begin{aligned}
& \sigma_{x}=\lambda\left(\epsilon_{x}+\epsilon_{\theta}+\epsilon_{z}\right)+2 \mu \epsilon_{x} \\
& \sigma_{\theta}=\lambda\left(\epsilon_{x}+\epsilon_{\theta}+\epsilon_{z}\right)+2 \mu \epsilon_{\theta} \\
& \sigma_{z}=0=\lambda\left(\epsilon_{x}+\epsilon_{\theta}+\epsilon_{z}\right)+2 \mu \epsilon_{z} \\
& \sigma_{x \theta}=\mu \gamma_{x \theta} \\
& \sigma_{x z}=\sigma_{\theta z}=0
\end{aligned}
$$

Eliminating $\epsilon_{z}$ from the first two equations by use of the third gives the desired stress-strain relations

$$
\begin{aligned}
\sigma_{x} & =\frac{E}{1-\nu^{2}}\left(\epsilon_{x}+\nu \epsilon_{\theta}\right) \\
\sigma_{\theta} & =\frac{E}{1-\nu^{2}}\left(\epsilon_{\theta}+\nu \epsilon_{x}\right) \\
\sigma_{x \theta} & =\frac{E}{2(1-\nu)} \gamma_{x \theta}
\end{aligned}
$$

Furthermore, assumptions (1) and (3) are utilized in reducing the strain components to a usable form (see Wang ${ }^{5}$, pp. 335-340). When this
is done, the equation for $\sigma_{x}$ becomes

$$
\sigma_{x}=\frac{E}{1-\nu^{2}}\left[\epsilon_{x_{0}}+\nu \epsilon_{\theta 0}-z\left(x_{x}+\nu x_{\theta}\right)\right]
$$

where

$$
\begin{array}{ll}
\epsilon_{x 0}=\frac{\partial u}{\partial x} & x_{x}=\frac{\partial^{2} w}{\partial x^{2}} \\
\epsilon_{\theta 0}=\frac{1}{a} \frac{\partial v}{\partial \theta}-\frac{w}{a} & x_{\theta}=\frac{1}{a} \frac{\partial}{\partial \theta}\left(\frac{v}{a}+\frac{1}{a} \frac{\partial w}{\partial \theta}\right)
\end{array}
$$

The expressions for the other stress components are similar in degree of complexity.

Finally, to obtain the relations between the stress resultants and couples, the following expressions must be integrated.

$$
\left\{\begin{array}{l}
N_{\theta} \\
M_{\theta} \\
Q_{\theta} \\
N_{\theta x} \\
M_{\theta x}
\end{array}\right\}=\int_{-n / 2}^{+n / 2}\left\{\begin{array}{c}
\sigma_{\theta} \\
z \sigma_{\theta} \\
\tau_{\theta z} \\
\tau_{\theta x} \\
z \tau_{\theta x}
\end{array}\right\} d z \quad\left\{\begin{array}{c}
N_{x} \\
M_{x} \\
Q_{x} \\
N_{x \theta} \\
M_{x}
\end{array}\right\}=\int_{-n / 2}^{+n / 2} \quad\left\{\begin{array}{c}
\sigma_{x} \\
z \sigma_{x} \\
\tau_{x z} \\
\tau_{x \theta} \\
z \tau_{x \theta}
\end{array}\right\}\left(1+z / R_{\theta}\right) d z
$$

Again, assumption (3) is used and $z / R_{\theta}$ is neglected. Then, $N_{X \theta}=N_{\theta x}$, $M_{x \theta}=M_{\theta x}$, and the expressions may be integrated without difficulty. For example, the expression for $N_{X}$ becomes

$$
N_{x}=\frac{E h}{1-\nu \nu^{2}}\left[\frac{\partial u}{\partial x}+\nu\left(\frac{1}{a} \frac{\partial v}{\partial \theta}-\frac{w}{\omega}\right)\right]
$$

This equation and the remaining ones obtained in a similar manner are known as Love's first approximation.

It is possible to derive expressions for the stress resultants and couples without resorting to the use of assumptions (1) - (3). Naghdi ${ }^{6}$, using a variational method due to $\operatorname{Reissner}{ }^{7}$, has made such a derivation. In order to gain an appreciation for the simplicity of the above expression and of the complexities involved in a thick shell theory, the more exact expression for $N_{x}$ is given below.
$N_{x}=\left\{\frac{E h}{1-\nu^{2}}\left[\epsilon_{x_{0}}+\nu \epsilon_{\theta 0}\right]\right\}+\left\{D \frac{x_{x}}{R_{\theta}}\right\}+\left\{-\frac{\nu}{1-\nu} \frac{h^{2}}{12}\left[\frac{\nu}{2 R_{\theta}}\left(x_{x}+x_{\theta}\right)\right.\right.$

$$
\left.\left.+\frac{x_{\theta}+2 x_{x}}{R_{\theta}}\right]+\frac{\nu}{1-2} \frac{h}{2}\left[\left(\sigma_{z}\right)_{2=+\frac{h}{2}}+\left(\sigma_{2}\right)_{2}=-\frac{h}{2}\right]\right\}
$$

Presumably, these more exact relations could be introduced into the equilibrium equations, and, provided a solution could be effected, a thick shell analysis for the instability problem would become available. An analytical approach to a thick shell instability analysis has not been attempted in this thesis, however.

## LITERATURE SURVEY

The theoretical and experimental analysis of the buckling of cylindrical shells subjected to hydrostatic pressure has attracted the attention of numerous investigators dating from experiments conducted by Fairbairn ${ }^{8}$ in 1858. All investigators employed the theory of thin shells in arriving at theoretical formulas and most experiments were carried out on models with relatively thin walls. Tables and descriptive information are presented in this section to indicate the extent of previous theoretical and experimental investigations. Particularly helpful in the making of the literature survey were two reports by Nash ${ }^{9}$ which contain a listing of 2339 papers and books relevant to experimental and theoretical work on shells and shell-like structures from 1828 through 1956.

## Results of Previous Bxperimental Investigations

Table 1 is a chronological listing of various investigators together with the range of geometries involved and other pertinent data. Since the first analytical solution to the instability problem was not available until 1913, all investigations prior to this time were made principally to determine empirical design formulas. Those investigations made in later years were carried out to test the validity of analytical solutions either in general or as applied to a particular problem.

With the exception of Southwell, all experimental investigators prior to 1929 restricted the loading on the cylinder to a radial pressure only. The axial thrust was eliminated by the use of a relatively stiff rod which connected the end plugs. The use of radial pressure only resulted from the
absence of anslytical formulas based on combined loading, and irom the fact that one of the principal applications of the results was to the study of boiler flues. Southwell did use a combined loading to simplify the apparatus. He neglected the effect of axial loading, however, in comparing test results with his analytical approach.

Most investigators after 1929 employed models subjected to hydrostatic (combined radial and axial) loads. An analytical solution to the problem of the cylinder under hydrostatic pressure was available by this time, and the submarine presented an immediate application.

From columns 4,5, and 6 of Table 1 the following is noted: Most of the models were relatively small in diameter, as was the $h / D$ ratio. In those cases where the $h / D$ ratio was greater than 0.05 the model was either so long that the values of the critical pressure approached that of an infinite tube, or they were in the range where yielding of the material occurred rather than an instability failure.

The type of support used by the various investigators is indicated in column 7. In general, this information was procured from sketches of the models as prepared for testing. A clamped type of support is indicated only where the author concerned specifically labelled the test condition as such. It is again noteworthy that no attempt was made to clamp the ends until $1941^{10}$ when an analytical solution became available. Also, as indicated by Cook, ${ }^{11}$ simply supported ends can be approached experimentally much more closely than fixed ends.

Column 8 indicates the maximum collapse pressures achieved by the various investigators; column 9 the number of models tested; and column 10 the variety of materials which have been utilized in the construction of models.

Several general observations can be made based on the survey of experimental results found in the literature:
(1) Scale effect is not important provided reasonable care is taken in fabricating the models. After testing 100 models representing the strength hull of a submarine, Windenburg ${ }^{12}$ concluded that scale effect was not evident. Some the earlier experiments have not given good results when compared to theory because of the inadequacy of materials and unsound fabrication techniques. Most of the results obtained in the last two decades have given very good correlation.
(2) Although the assumed end condition is taken as either simply supported or as clamped, neither condition can be precisely obtained in practice. Based on tests of 258 brass models, Cornell 13 concluded that the end plugs inserted into the ends of the tubes offered a restraint that tended to reduce the effective length. He found that to get close agreement of his test results with theory, it was necessary to use an effective free length which differed from the actual free length by $\frac{1}{2} \%$ to $2 \%$. (Because of the small value of such a correction, the authors assume the measured free length to be the same as the effective free length for the tests reported in this thesis.)
(3) Several investigators have conducted carefully controlled experiments to determine the influence of other factors, such as eccentricity, on the collapse pressure. Sturm 10 was probably the first to investigate the problem of out-of-roundness from an experimental and analytical point of view. In recent years, Cleaver ${ }^{14}$ has conducted very thorough, extensive, and carefully controlled tests on 530 models subjected to radial pressure. He lists the
following factors as affecting the collapse pressure:
a. Fccentricity of bore relative to the external surface.
b. Variations from true circular shape (out-of-roundness).
c. Ovality of the specimen (the difference in the maximum and minimum diameters divided by the nominal diameter).
d. Variation of material properties.

From the results of his tests Sturm concludes that eccentricity of bore is the predominant manufacturing variable affecting collapse strength, but for eccentricities within the limits imposed by current specifications, its effects are small and can be neglected for practical purposes. Variations in circularity exert no measurable systematic influence, and provided they are within current specifications (i.e. for commercial tubes), they too may be neglected.

The althors point out in passing that for a well-made, simply supported model the above effocts tend to cancel the effect of any end restraint that might be present. Therefore, neglecting these effects may be justified when attempting to correlate experimental and theoretical results.

## Results of Analytical Investigations

Table 2 presents a summary of results of principal theoretical investigations. The method of approach to the problem is indicated.

The differences in the various formulas can be accounted for by the inclusion or omission of certain higher order terms in the differential equations of equilibrium, by the mothod of approach (i.e. equil-
ibrium, energy, kinetic), and by the degree of simplification of the ifnal result.

All of the more exact formulas are found to have the form

$$
p / E=F_{1}(h / D)^{3}+F_{2}(h / D)
$$

where $F_{1}$ and $F_{2}$ are functions of
(a) The length to diameter ratio.
(b) Poisson's ratio.
(0) The number of lobes in a complete cicumferential belt at the time of collapse.
(d) The number of lobes along a generator of the cylinder at the time of collapse. Von Mises ${ }^{15}$ has shown this quantity to be unity for minimum buakling pressure.

In order to facilitate comparison of the buckling equations with test results, values of $F_{1}$ and $F_{2}$ for the model geometry and material under consideration in this paper have been calculated for the various buckling formulas. These values are given in Table 3. Curves for $\mathrm{p} / \mathrm{E}$ versus $h / D$ are also included for these cases. (See Fig. 13).

In addition to the formulas for the buckling pressure of cylinders under hydrostatic load, it is of interest to examine formulas for buckling pressure under uniform radial load only. Table 4 gives some of the principal radial load buckling equations. A comparison of the radial load formulas with the hydrostatic load counterparts indicates that the following relationship is approximately true

$$
\frac{\text { bucking pressure under hydrostatic load }}{\text { buckling pressure under radial load }}=\frac{n^{2}-1}{n^{2}-1+\frac{\lambda^{2}}{2}}
$$

Thus as $\lambda$ approaches zero $(L / D \rightarrow \infty)$, the formulas for hydrostatic load should yield the same results as the formulas for radial lad. For the case where $\lambda=0, n$ becomes two, and all of the more exact hydrostatic and radial load buckling pressure equations reduce to the Bresse equation (Table 4) for a tube of infinite length.

SUMMARY OF EXPERIMENTAL INVESTIGATIONS
in the literature

TABLE 2
THEORETICAL GUCKLIVG FORMULAS FOR UNSTIFFENED CYLINDERS
UNDER HVOROSTATIC LOAD

| No | DATE | INVESTIGATOR | METHOD OF APPROACH | BUCKLING FORMULA | REMARKS | REF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 1924 | PRESCOTT | EQUILIBRIUM | $\frac{P}{E}=\frac{2}{3}\left[\frac{\left(m^{2}-1\right)^{2}}{m^{2}-1+\frac{\lambda^{2}}{2}\left(1+\frac{1}{m}\right)}\right]\left(\frac{h}{D}\right)^{3}+\left[\frac{2 n^{4} / n^{4}}{m^{2}-1+\frac{n^{2}}{2}\left(1+\frac{1}{n^{2}}\right)}\right]\left(\frac{h}{D}\right)$ |  | 35 |
| 2 | 1929 | VON MISES | EQUIIIBRIUM | $\begin{gathered} \frac{P}{E}=\frac{2}{3}\left[\frac{\left(m^{2}+\lambda^{2}\right)^{2}-2 \mu_{1} n^{2}+\mu_{2}}{\left(n^{2}-1+\lambda^{2} / 2\right)\left(1-2^{2}\right)}\right]\left(\frac{h}{D}\right)^{3}+\left[\frac{2 \lambda^{4}}{\left(n^{2}-1+\lambda^{2} / 2\right)\left(m^{2}+\lambda^{2}\right)^{2}}\right]\left(\frac{h}{D}\right) \\ 2 \mu_{1}=2+\rho\left[3+\nu+\left(1-\nu^{2}\right) \rho\right] \\ \mu_{2}=(1-\rho \nu)\left[1+(1+2 \nu) \rho-\left(1-\nu^{2}\right)\left(1+\frac{1+\nu}{1-\nu} \rho\right) \rho^{2}\right] \\ \rho=\frac{\lambda_{1}^{2}}{\lambda^{2}+n^{2}} \end{gathered}$ | VON MISES EQUATION (6) | 22 |
| 3 | 1429 | TOAUGAWA | EquLIBRIUM | $\frac{P}{E}=\frac{2}{3}\left[\frac{\left(m^{2}+n^{2}\right)^{2}-\frac{n^{4}\left(2 n^{2}-1\right)}{\left(n^{2}+n^{2}\right)^{2}}}{\left(m^{2}-1+\lambda^{2} / 2\right)\left(1-2^{2}\right)}\right]\left(\frac{h}{D}\right)^{3}+\left[\frac{2 \lambda^{4}}{\left(n^{2}-1+\lambda^{2} / 2\right)\left(m^{2}+n^{2}\right)^{2}}\right]\left(\frac{h}{D}\right)$ | DERIVED FOR RING-STIFEHED CYLINDERS, WHERE $\begin{aligned} & \lambda=K \frac{\pi D}{2}, A N D \\ & K=1 F C R N_{O} \end{aligned}$ | 23 |

TABLE 2 (continued)

table 2 (continued)

| No. | DATE | investigator | METHOD OF APPROACH | BUCKLING FORMULA | REMARKS | REF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8 | 1947 | BATDORF |  | $\frac{P}{E}=\frac{2.42}{\left(1-2^{2}\right)} \cdot \frac{(-h / D)^{5 / 2}}{L / D}$ | an approximation cf THE MORG EXACT FURMULA | 34 |
| 9 | $\begin{aligned} & 1950 \\ & 1954 \end{aligned}$ | Salerno \& LEVINE NASH | ENERGY <br> ENERGY | $\frac{P}{E}=\frac{2}{3}\left[\frac{\left(n^{2}+n^{2}\right)^{2}}{\left(i n^{2}-1+\lambda^{2} / 2\right)\left(1-v^{2}\right)}\right]\left(\frac{h}{D}\right)^{3}+\left[\frac{2 \lambda^{4}}{\left(m^{2}-1+n^{2} / 2\right)\left(\lambda^{2}+n^{2}\right)^{2}}\right]\left(\frac{h}{D}\right)$ | THIS FORMULH IS ALSO GIVEN BY VON MISES ${ }^{22}$ <br> AS A SIMPLIFIED <br> EXPRESSION FOR HIS <br> MORE EXACT EQUATION, <br> EXCEDT THAT <br> $\left(n^{2}-1+\lambda^{2} / 2\right) \quad 15$ <br> REPLACED BY $\left(m^{2}+\lambda^{2} / 2\right)$ <br> IN VON MISES? | 32 |
|  |  |  |  |  |  |  |

$$
\begin{gathered}
\text { CONSTANTS FOR BUCKLING EQUATIONS } \\
P / E=F_{1}(h / D)^{3}+F_{2}(h / D) \\
F O R \quad L / D=2.53, n=2, \quad \nu=0.15
\end{gathered}
$$


TABLE

| $\begin{aligned} & \hline 4 \\ & w_{2} \end{aligned}$ | $\underline{n}$ | $m_{m}^{m}$ | $n$ | $\underline{6}$ | 9 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \tilde{v} \\ & \alpha \\ & k_{\alpha}^{\alpha} \\ & k_{2} \end{aligned}$ |  |  |  |  |  |
| $\begin{aligned} & d \\ & j \\ & j \\ & s \\ & d \\ & 0 \\ & u \\ & \\ & 0 \\ & 2 \\ & j \\ & \vdots \\ & \vdots \\ & 0 \\ & 0 \end{aligned}$ |  |  |  |  |  |
|  | $\begin{aligned} & \lambda \\ & \stackrel{y}{b} \\ & 2 \\ & \stackrel{\omega}{2} \\ & \langle \end{aligned}$ |  |  |  |  |
|  | $\begin{aligned} & w_{1} \\ & n \\ & \hat{n} \\ & u_{1} \\ & k \\ & k \\ & 0 \end{aligned}$ |  |  |  | $\sum$ $\alpha$ $\vdots$ 3 |
| $\begin{aligned} & 4 \\ & k \\ & 0 \end{aligned}$ | $\begin{array}{ll} \infty & \infty \\ \alpha_{0} \\ \infty & \infty \\ \infty \end{array}$ | $\cdots$ | $\stackrel{\downarrow}{*}$ | $\pm \stackrel{\text { n }}{\sim}$ | $\begin{aligned} & \text { j} \\ & \text { a } \end{aligned}$ |
| $\stackrel{\circ}{2}$ | - | $\checkmark$ | m | 7 | b |

## TEST APPARATUS, MODELS, AND TFST PROCEDURE

## Test Apparatus

The test apparatus consists of a pressure vessel, pump, tubing, pressure gages, and equipment required for the taking of strain gage data. The arrangement and details of the apparatus are shown in Figures 1 through 5. Specifications which were drawn up for the test apparatus are given below.

Size of chamber: $5^{\prime \prime}$ I.D., $13^{\prime \prime}$ depth Working pressure: $10,000 \mathrm{psi}$

Penetrations: One fitting for pressure tubing, one fitting for four wires from strain gages on the external surface of the model, one fitting for $1 / 4^{n}$ tube to vent model to the atmosphere and to lead out internal strain gage wires.

Pump: Hand operated pump with self-contained check valve and reservoir--the type commonly used with hydraulic jacks. Pressure gages: One $5000 \mathrm{psi} \mathrm{g}^{\prime \prime}$ Bourdon gage graduated in increments of 50 psi , and one 15,000 psi 6" Bourdon gage, graduated in increments of 100 psi .

Strain Indicator: Baldwin, Type N
The pressure vessel was constructed in accordance with a basic design drawn up by Mr. Kenneth Hom of the David Taylor Model Basin. The design was modified slightly by the authors, to suit the purpose required. The following calculations show the factors of safety, for a working pressure of 10,000 psi. The material is low carbon steel, the yield strength of which was assumed to be 30,000 psi. Formulas used are given in reference (39).
$t=$ wall thickness, inches, $=\left\{\begin{array}{l}2.25 \text { for walls } \\ 2.125 \text { for bottom }\end{array}\right\}$
$\mathrm{d}=$ inside diameter of chamber, inches, $=5.00$
$P=$ chamber pressure, psi
$\mathrm{S}=$ maximum stress, $\mathrm{psi},=30,000$
$R=$ inside radius of chamber, inches, $=2.50$
F.S. = factor of safety based on yield strength of $30,000 \mathrm{psi}$

Based on circumferential stress in wall:
$P=\frac{S t}{R+0.6 t}=\frac{(30,000)(2.25)}{2.50+(0.6)(2.25)}=17,532 \mathrm{psi}$
F.S. $=\frac{17,532}{10,000} \cong 1.75$

Based on longitudinal stress in wall:
$P=\frac{2 S t}{R-0.4 t}=\frac{(2)(30,000)(2.25)}{2.50-(0.4)(2.25)}=84,375 \mathrm{psi}$
F.S. $=\frac{84,375}{10,000} \cong 8.44$

Based on stress in bottom:
$P=\frac{S t^{2}}{d^{2}(0.162)}=\frac{(30,000)(2.125)^{2}}{(5.00)^{2}(0.162)}=33,449 \mathrm{psi}$
F.S. $=\frac{33,449}{10,000} \cong 3.34$

* Ref. (39), para. UG-27(c)(1)
** Ref. (39), Section VIII, para. UG-34(1).
Para. UG-36(3) states:
"Single openings in vessels not subject to rapid fluctuations in pressure do not require reinforcement other than that inherent in the construction under the following conditions:
....(b) Threaded, studded, or expanded connections in which the hole cut in the shell or head is not greater than two-inch pipe size."

The pressure vessel was proof tested to $11,000 \mathrm{psi}$ on 30 August, 1960. It was raised to this pressure three times, and strain data were taken on the outside surface using a circumferential strain gage. This test was made prior to the making of the penetrations for fittings "A" and "B" (Fig. 4). The strain data taken plotted linearly from zero to 11,000 psi.

This apparatus should not be used with a working pressure in excess of $10,000 \mathrm{psi}$, unless the pressure vessel is again proof tested at the higher pressure with strain gage measurements taken in regions of high stress. In any case, it is recommended that a pressure of $15,000 \mathrm{psi}$ not be exceeded, and that for working pressures in excess of $10,000 \mathrm{psi}$ the pressure vessel be placed in a pit or behind a suitable barrier. All tubing and fittings used should be rated at the maximum working pressure employed.

Persons making further use of this apparatus are warned that valve ${ }^{\mathrm{M}} \mathrm{G}^{\mathrm{n}}, \mathrm{Fig}$. 4, is rated at 3000 psi . It is recommended that this valve be replaced by one rated at $10,000 \mathrm{psi}$ or higher. As a safety precaution in performing the tests for this thesis, a $1 / 8^{\prime \prime}$ steel plate was attached to the table between the onerators and fittings "D" through "H" (Fig. 4). The plate can be seen in the photograph, Fig. 5.


DETAILS OF "O"-RING, GROOVE, \& CIRCULAR PLATE

## FIGURE 3

## ARRANGEMENT OF FITTINGS IN PRESSURE VESSEL

$$
1 / 2^{\prime \prime}=1^{\prime \prime}
$$





FIGURE 5
Photograph of Assembled Apparatus

## Model Design

Design of the models was based on the following considerations:
(1) Maximum working pressure of test apparatus: 10,000 psi
(2) Dimensions of test chamber: $5^{\prime \prime}$ I.D. and $13^{\prime \prime}$ depth

Since the purpose of the thesis is to evaluate the instability formulas for relatively thick-walled cylinders, it was necessary to design the models to fail by instability, and to have a relatively large thickness-diameter ratio. Mr. John Pulos of the David Taylor Model Basin recommended a range of $h / D$ from 0.05 to 0.10 . Also, Timoshenko ${ }^{3}$ ( p .354 ) has given a value of $h / D=0.05$ as an estimated division point between thick and thin curved bars. Accordingly, the range of values for $h / D$ was selected as 0.05 to 0.10.

A calculation revealed that a material with a relatively low modulus of elasticity was required in order to cause instability failures in the range of $h / D$ greater than 0.05 , and, at the same time, remain within the upper limit of test pressure of $10,000 \mathrm{psi}$. Captain Hinners suggested the possible use of glass-reinforced plastic, especially in view of the current interest in this material because of its favorable strength-weight ratio.

The David Taylor Model Basin had published a report ${ }^{38}$ (No. 1413) on the hydrostatic pressure tests of a cylindrical shell of a glass fiber reinforced epoxy resin fabricated by the Zenith Plastics Co. of Gardena, California. The circumferential modulus of this material was reported to be $4.8 \times 10^{6} \mathrm{psi}$, and the plot of pressure vs. strain was linear with but a slight departure from linearity near the collapse pressure. This material seemed to meet the requirements well. It had disadvantages, however, in that it was neither homogeneous nor isotropic, thus violating two basic assumptions in the usual approach to the theory of elasticity.

It was felt, nevertheless, that these disadvantages would be overcome by computing an "effective modulus of elasticity" from strain data, and by using models fabricated in such a way as to give maximum dispersion of the glass in the resin. Correspondence with the Zenith Plastics Co. was initiated to obtain information regarding the procurement of the nedessary models. Zenith very generously offered to supply the models at no cost.

At this point specifications were drawn ur: for the model geometries. Using DTMB formula (9) [Formula No. 5, Table 2], a set of curves was drawn for various values of $L / D$, with buckling pressure as the ordinate and $h / D$ as the abscissa. These curves are show. in Fig. 6. The hoop stress failure pressure was also plotted on these curves using a nominal value of compressive strength of 70,000 psi as obtained from DTMB Report 1413.38 These curves were then used to select appropriate values for $L / D$ and $h / D$. It was decided to keep the value of $L / D$ constant at about 2.5 and vary the value of $h / D$ from about 0.05 to 0.09 . It was also decided to test a minimum of three models of each geometry in order to determine that test results could be reproduced. Table 5 lists the models received from Zenith and gives their measured average dimensions. Fig. 7 is a sketch of the model showing the end closure plugs. The plugs, made from medium steel stock, were designed to give simple support of the model ends, the condition for the von Mises buckling equation. The effective length, $L$, is as shown. The inside diameter was chosen as $3.195^{\prime \prime}$ because of the availability at the Zenith plant of a mandrel of that diameter.


## Model Fabrication

The models were built up using layers of glass fiber reinforced epoxy resin tape. The glass fibers ran in one direction, along the length of the tape strip, and the tape was applied to the mandrel both by circumferential winding under tension (circumferential plies) and by laying on strips parallel to the axis of the mandrel (longitudinal plies). The process was started and ended with two circumferential plies and was continued using alternate layers in a ratio of two circumferential plies to one longitudinal ply. This $2: 1$ ratio of circumferential to longitudinal plies results in the allowable stresses in the longitudinal and circumferential directions being in close agreement with the induced stresses in these directions. The resulting structure is of course anisotropic. The thickness was varied by varying the number of layers of tape. Five tubes were fabricated, each about $60^{\prime \prime}$ in length and each of a different thickness (see Table 5). Upon completion of the curing process, most of the models were cut from the tube to proper length while still on the mandrel at the plant. Some of the models were cut from the remaining portions of tubes after delivery, using a band-saw, and grinding or machining the ends until smooth and normal to the cylinder axis. By weighing and measuring some of the models, the density of the material was determined to be about 0.07 pounds/cubic inch. Values of resin content for the model material were provided by Zenith, and are given in Table 11.


TABLE 5


$$
\text { * } D=1 / 2\left(3.195+D_{2}\right)
$$

## Instrumentation of Models

Strain data were taken to provide a means for calculating an effective modulus of elasticity for the models. As shown in Appendix C, values of the strain-pressure ratios, taken in the directions of principal stresses, can be used in conjunction with Hooke's law and thick shell theory to solve for $E_{\phi}$ and $E_{x}$. A value for Poisson's ratio must be known or assumed.

In order to determine average values for $\epsilon_{p}$ and $\epsilon_{x}$, strain gages were applied to a number of the models, oriented both circumferentially and longitudinally. The number of gages used was limited both by financial considerations and by the number of leads that could be fed through the pressure fittings in the tank. In general, four gages were applied to each instrumented model. These gages were located at the midlength of the model to avoid end effects, and were oriented two in a circumferential direction and two in a longitudinal direction. The two circumferential gages were placed "back to back", inside and outside, as were the two longitudinal gages.

The choice of gage types was governed by:
(1) the need to have non-pressure-sensitive gages;
(2) the necessity for measuring strains up to 15,000 microinches/inch;
(3) the desire to use a gage length long enough to reduce the effect of local variations in strain; and
(4) the cost of gages.

On the basis of these considerations, two types of gages were selected. For use on the inside of the model, where the gage would not be subject to the pressure of the fluid, the SR-4, A-5-1 wire gage was used. This gage has a $1 / 2^{n}$ gage length, is relatively inexpensive, and is suitable for the
measurement of strains up to $1 \frac{1}{2}$ to $2 \%$. For use on the outside of the model, where the gage would be subject to external pressure of the fluid, the SR-4, paper-backed constantan foil gage FAP-50-12 was selected. This gage, with a $1 / 2^{n}$ gage length, is not as pressure-sensitive as the A-5-1 gage. It also is suitable for measurements of strain up to $1 \frac{1}{2}$ to $2 \%$.

Compensating gages of the same type and lot number were used in conjunction with the active gages.

The gages were applied using Duco cement, and the gage manufacturer's Instructions were followed. After the cement had dried, all gages were connected in the strain indicator circuit and pressed with a pencil eraser tip while watching the strain indicator to check for excessive deflections of the needle.

## Test Procedure

Strain gages were applied to the inside of the model by using a "harness"-a sheet of graph paper to which the gages were attached. This sheet was trimmed to exact dimensions, rolled into a cylinder, and positioned inside the model with glue applied to the gages. Leads of \#28 stranded wire were attached to the strain gages.

The ends of the model were propared by thorough cleaning with acetone. PR-1321 Class A sealant *as then applied to the ends, and the end plugs inserted, leading the wires from the inside of the model out through the $1 / 4^{\prime \prime}$ tube ** screwed into the lower end plug. After the sealant set up, the model was ready for installation in the tank. Fig. 8 shows a model ready for installation and $\operatorname{Flg} .5$ shows a model in the tank and partially lowered into testing position. Flg. 3 shows a model'inside the chamber.

The model was positioned in the open tank by first leading the wires from the $1 / 4^{n}$ end plug tube through the "A" fitting in the center of the tank bottom, then connecting the external strain gage leads to the leads inside the tank from the "B" fitting. The model was then lowered, allowing the $1 / 4$ " tube to slide through the "A" fitting until the lower end plug rested on a steel "spool" support about 2 " high located in the bottom of the chamber. The lock nut of the "A" fitting was then tightened, taking care not to over-tighten.***

* Manufactured by the Products Research Co., 410 Jersey Ave., Gloucester City, New Jersey
** This tube is a semi-permanent attachment to the end plug, its threaded end having been coated with sealant prior to screwing into the tapped end plug.
*** It was observed that excessive tightening of the lock nut permanently deformed the ferrule and tube, making it impossible to slide the tube back out of the fitting after the test.

With the model in place, the strain gage leads coming from the $1 / 4^{\prime \prime}$ tube and from the "B" fitting underneath the pressure vessel were connected to the strain indicator or switching unit. The chamber was filled with transformer oil * to a level slightly above the sealing surface. The circular plate was inserted, causing the excess oil to be squeezed into the plug recess. This precaution was taken to insure that the oil was relatively air-free. The screw plug was then positioned and tightened. Tapping the screw plug wrench handle with a hammer insured firm seating of the circular plate.

Pressure was raised by operating the hand pump. The valve "G" in the line to the 5000 psi gage was shut at 4500 psi . This valve, although rated at 3000 psi , performed satisfactorily.

In some cases, only one strain gage was measured per run, using the strain indicator directly. In most of these tests, at least two runs were made per gage, and the readings for the two runs were found to vary very little. For other tests, the switching unit was employed and a number of gages were read per run.

Upon completion of a test, the screw plug was removed, and the "A" fitting lock nut was loosened to permit removal of the model. As the model was removed, the $1 / 4$ " tube slipped out of the "A" fitting, allowing the oil in the tank to drain into a receptacle below.

The two pressure gages used during the tests were calibrated at the Material Laboratory before beginning the tests and at DTMB toward the end of testing. Both calibrations were made using dead-weight gage

* WEMCO Class C transformer ofl was used as the pressurizing fluid, making it unnecessary to waterproof strain gages exposed to the fluid.
testers. No differences were noted in the gage calibrations. The 5000 psi gage was adjusted after the second calibration to give gage readings closer to the actual pressure. The gage calibration curves are shown in Figures 9 and 10.



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## EXPERIMENTAL DATA

A total of twenty-three models was tested, twenty-one of which were tested to failure. Seven of the models were instrumented to measure strains in order to determine the moduli of elasticity. Three models were designed to fail by yielding of the material. This was done in order to calculate the maximum compressive stress which the material would sustain and to determine the appearance of models after yield failure. Since the calculated circumferential stress for the "D" and "E" models was close to the nominal strength of the material, this information was used to ascertain whether these models did, in fact, fail by instability alone, or whether some yielding might have taken place.

A summary of the models tested, with the respective collapse pressures, is presented in Table 6. The recorded strain data are in Appendix $A$, and the pressure-strain plots are in Appendix B. Table 7 summarizes the measured strain-pressure ratios as obtained from the plots. The first models instrumented were tested with the compensating gage located inside the model for inside active gages, and with the compensating gage located in the pressurized fluid for external active gages. As shown in Appendix $C$, it is theoretically possible to cancel the effect of radial strain on the outside active gage by having the compensating gage mounted on a block which is subject to the hydrostatic pressure. Furthermore, any effect of pressure on the active gage in the fluid would be compensated for, as well as more accurate temperature compensation provided. The later models tested, however, had all gages--inside and outside--balanced against a single dummy gage inside the model. This latter procedure was followed because it had been determined that the error caused by neglecting the Poisson effect of the radial strain on the outside gages was negligible, and therefore the additional complication to the testing procedure was unjustified.

In order to be able to compare and average the strain data taken under the two different methods of compensation, the strain-pressure ratios of active gages read with the dummy under pressure were corrected to values equivalent to those taken with the dummy gage inside the model. This was accomplished by simply adding the value of strain-pressure ratio of a gage mounted on a dummy block under pressure, balanced against a dummy gage inside a model. All the strain-pressure ratios used in computations, therefore, have values which would result from active gages being read against a dummy located on the inside of the model, not under pressure.

LAMÉ STRESS IN MODELS AT COLLAPSE PRESSURE

| MODEL | $K$, | COLLAOSE PRESSURE P (PSI) | $\sigma_{o_{1}}=P K_{1}$ | $\sigma_{x}=\frac{1}{2} P K_{1}$ | $\sigma_{\phi_{2}}=P\left(K_{1}-1\right)$ | REMARKS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A-1 | 10.978 | 3090 | 33,922 | 16,961 | 30,832 |  |
| A. 2 |  | 3180 | 34,910 | 17,455 | 31,730 |  |
| A 3 |  | 3130 | 34,361 | 17,180 | 31, 231 |  |
| A-4 |  | $\stackrel{-}{-}$ | - | - | -- | STRAIN DATA ONLY - SEE <br> TABLE 7 |
| A -5 |  | 4720 | 51,816 | 25,908 | 47,096 |  |
| A-6 |  | 5760 | 63,233 | 31,616 | 57,473 | YIELD MODEL |
| B-1 | 9.323 | 4360 | 40,648 | 20,324 | 36,288 |  |
| B-2 |  | 2300 | 21,443 | 10,722 | 19,143 | PREMATURE FAILURE |
| B-3 |  | 4330 | 40,369 | 20,184 | 36,038 |  |
| $B-4$ | $Y$ | 3155 | 29,414 | 14,707 | 26,259 | PREMATURE FAILURE |
| C-1 | 8.191 | 5520 | 45,214 | 22,607 | 39,694 |  |
| c-2 |  | 5480 | 44,887 | 22,444 | 39,407 |  |
| C-3 |  | 5430 | 44,477 | 22,238 | 39,047 |  |
| $c-4$ |  | 7760 | 63,562 | 31,781 | 55,802 | YIELD MODEL |
| $D-1$ | 7. 225 | 6870 | 49,636 | 24,8/8 | 42,766 |  |
| D. 2 |  | 7230 | 52,237 | 26,118 | 45,007 |  |
| $D-3$ |  | 7710 | 55,705 | 27,852 | 47,945 |  |
| D-4 |  | 6920 | 49,997 | 24,998 | 43,077 |  |
| D-5 | 1 | 9650 | 69,721 | 34,860 | 60,071 | YIELO MODEL |
| E-1 | 6.714 | 8460 | 56,800 | 28,400 | 48,340 |  |
| $E-2$ |  | 8830 | 59,285 | 29,642 | 50,455 |  |
| $E-3$ |  | 8770 | 58,882 | 29,441 | 50,112 |  |
| E. 4 | $Y$ | - | - | - | - | $\begin{aligned} & \text { STRAIN DATA } \\ & \text { ONLY - SEE } \\ & \text { TAGLE T } \end{aligned}$ |

TABLE 7

MEASURED STRAIN-PRESSURE RATIOS


## Strain Data Analysis

The moduli of elasticity were calculated from the strain-pressure ratios using the formulas presented in Table 8. The theoretical basis for these formulas is shown in Appendix C. A summary for the calculations for $E_{\phi}$ and $E_{x}$ is given in Tables 9 and 10. No values were calculated for the $B$-model because premature fallure of the instrumented model in this series prevented the taking of sufficient strain data. The values of $E_{\phi}$ and $E_{x}$ used for the B-models are averages of the values for the other models.

Since available instability formulas apply to isotropic materials, it was necessary to develop a method for converting the principal moduli $E_{\phi}$ and $E_{x}$ into an effective modulus $E_{e}$. This was accomplished by first deriving an expression for the shear modulus of an orthotropic material. The derivation followed a method used by Timoshenko ${ }^{40}$ (pp. 54-57) in deriving the expression for the isotropic case and is presented in Appendix D. The shear modulus thus found is

$$
G=\frac{E_{x} E_{\phi}}{\left(E_{x}+E_{\phi}\right)(1+\nu)}
$$

Note that for $E_{x}=E_{\phi}$ this expression reduces to the isotropic case

$$
G=\frac{E}{2(1+\nu)}
$$

In the derivation, Poisson's ratio was assumed to be constant. As noted later, this assumption does not lead to an appreciable error. Then, to obtain an effective modulus, the orthotropic expression for $G$ was equated to that for the isotropic case as follows:

Let $E_{X}=k E_{\phi}$, then $G=\frac{E_{\phi}}{\frac{1+k}{k}(1+\nu)}$. Equating this to $G=\frac{E_{\Theta}}{2(I+\nu)} \quad$ gives

$$
E_{\theta}=2 E_{\phi} \frac{k}{l+k}
$$

The calculated effective values for the modulus are summarized in Table 11. In addition, the authors undertook the derivation of an expression for the bucking pressure of an orthotropic cylinder. This derivation is shown in Appendix $E$, and the buckling pressure is given in the form of a determinant. The calculation of buckling pressure using this determinant is very cumbersoma. Since the expression was derived shortly before the completion of the thesis, no evaluation of the determinant was made with respect to the experimental results contained herein. It is believed, however, that it may have merit in computing buckling pressures for orthotropic cylinders. Also, it might be used to verify the assumption of an effective modulus for use with the isotropic equations. It is noted that the determinant derived for the orthotropic case reduces to the expression for the infinite tube, with $\mathrm{E}_{\phi}$ the only modulus, when $L$ is made to approach infinity. This suggests that, in reality, an effective modulus for use in the buckling equation should depend on the length of the cylinder. It is also noted that the determinant reduces to that given by Timoshenko ${ }^{30}$ (p. 449) when $E_{X}$ is made equal to $E_{\phi}$ and $G$ is put equal to $\frac{E}{2(1+\nu)}$, except that the term $-\frac{\mathrm{pa}}{\mathrm{h}} \frac{\lambda^{2}}{2}$ is added to the last term in row 3 , column $C$ to take care of the end thrust.

Details of the assumptions employed in the calculation of an effective modulus follow.
(1) As previously stated, Poisson's ratio was assumed to be constant.

On the basis of data provided by the David Taylor Model Basin and the Zenith Plastics Company, this value was assumed to be 0.15. The effect of the variation in Poisson's ratio on the value of the calculated modulus is small. For example, using $\nu=0.10$ instead of 0.15 in the calculation for $E_{\phi}$ raises the calculated value about $3 \%$ for both the $A$ models and the $E$ models.
(2) The stress field in the model was assumed to be in accordance with the Lame thick shell theory, and the strain-pressure curves were assumed to be Iinear up to the point of collapse. As a consequence of this assumption the bending stress due to the simply supported tube of finite length is neglected. As will be shown later, the bending stress prior to buckling is a very small quantity.
(3) The effect of radial strain was neglected in calculating $E_{\phi_{z}}$ and $E_{x_{i}}$. This effect is small as is shown below: The radial strain on the outer surface is given by: (see Appendix C)

$$
\epsilon_{r_{2}}=p\left[\frac{1}{E_{r}}-\nu\left(\frac{K_{1} / 2}{E_{x}}+\frac{K_{2}}{E_{\phi}}\right)\right]
$$

Thus,

$$
m_{r_{2}}=\frac{1}{E_{r}}-\nu\left(\frac{k_{1} / 2}{E_{x}}+\frac{k_{2}}{E_{\phi}}\right)
$$

It is seen that the greatest error would occur for the largest value of $m_{r_{2}}$, which value would correspond to the thickest cylinder, i.e., the cylinder with the least value of $\mathrm{K}_{1}$. For the E-model, $\mathrm{K}_{1} \cong 6.5 ; \mathrm{K}_{2}=\mathrm{K}_{1}-1 \cong 5.5 ; \mathrm{E}_{\phi} \cong 5.5 \times 10^{6}$; $E_{x} \cong 4 \times 10^{6} ; \nu \cong 0.15$; then assuming a nominal value for $E_{\mathrm{r}}=3 \times 10^{6}, \quad \mathrm{~m}_{\mathrm{r}_{2}} \cong 1 / 3-(0.15)\left(\frac{3.25}{4}+\frac{5.5}{5}\right) \cong 0.046$ Now the exact formula for computing $E$ using outside strain gage data is:

$$
E_{\phi}=\frac{K_{2}(1+\nu)(1-2 \nu)}{m_{\phi_{2}}(1-\nu)+\nu m_{x_{2}}+\nu m_{n_{2}}}
$$

It was found that the difference between the value of $E_{\phi}$ calculated by using this equation with $m_{r_{2}}=0.046$ and that calculated by neglecting $m_{r_{2}}$ entirely was less than $1 \%$. It was further noted that the longitudinal compressive strain was greater on the outside than on the inside of the models. This difference is attributed to the fact that some bending of the shell undoubtedly occurs even for the lower pressures. That this difference is not inherent in the strain relations can be show by the following development: From Appendix C,

$$
\begin{array}{ll}
\epsilon_{x_{2}}=\frac{\rho K_{1}}{2 E_{x}}-\nu\left(\frac{p K_{2}}{E_{\phi}}+\frac{p}{E_{r}}\right) & \text { (radial stress }=p) \\
\epsilon_{x_{1}}=\frac{\rho K_{1}}{2 E_{x}}-\nu\left(\frac{p K_{1}}{E_{\phi}}\right) & \text { (radial stress }=0 \text { ) }
\end{array}
$$

$$
\text { Since } K_{2}=K_{1}-1 \text {, }
$$

$$
\begin{aligned}
& \epsilon_{x_{2}}-\epsilon_{x_{1}}=\frac{\rho K_{1}}{2 E_{x}}-\frac{\nu \rho K_{1}}{E_{\phi}}+\frac{\nu \rho}{E_{\phi}}-\frac{\nu \rho}{E_{r}}-\frac{\rho K_{1}}{2 E_{x}}+\frac{\nu \rho K_{1}}{E_{\phi}} \\
& \epsilon_{x_{2}}-\epsilon_{x_{1}}=\frac{\nu \rho}{E_{\phi}}-\frac{\nu \rho}{E_{r}}
\end{aligned}
$$

from which,

$$
m_{x_{2}}-m_{x_{1}}=\nu\left(\frac{1}{E_{\phi}}-\frac{1}{E_{r}}\right)
$$

Since $\quad E_{\phi} \cong 5 \times 10^{6} \quad E_{r} \cong 3 \times 10^{6} \quad$ and $\nu=0.15$,

$$
m_{x_{2}}-m_{x_{1}} \cong(0.15)(1 / 5-1 / 3) \cong-0.02
$$

This difference is small in comparison with the differences actually messured and is of opposite sign. It is concluded, therefore, that the measured difference results from bending of the generators. In order to reduce the errors arising from this effect, an average of $m_{x_{1}}$ and $m_{x_{2}}$ was used in all calculations which called for either value.

Table 7 shows that even for identical models there were considerable differences in measured values of strain-pressure ratios. These differences may be attributed to two causes:
(1) The properties of the individual models may vary slightly, even though cut from the same tube.
(2) Even on the same model, the strain-pressure ratios will vary from point to point around the circumference, as shown in reference (38).

The most accurate data for use in computing moduli would he that taken from a number of strain gages spaced around the circumference of each model, using the average values of strain-pressure ratios. Due to limitations discussed previously, this procedure could not be followed. Instead, the averaging process was accomplished by using inside and outside strain data, and averaging the moduli thus calculated. Where circumferential variations in strain-pressure ratios are caused by the tendency to lobe formation, the use of inside and outside data from "back-to-back" gages tends to cancel the variation. In the case of the $A, D$, and E geometries, two instrumented models of each were tested in order to provide more data for averaging.

Since the tubes were fabricated using the same techniques and material, one would expect the moduli to be about the same for all the models. Such is the case, except that the A models were found to have a slightly higher modulus. (See Tables 10 and 11). As previously noted, the effective modulus for the B models was taken as the average of that of the other models, due to insufficient strain data. The small differences in resin content for the models (Table ll) are not sufficient to account for the differences in moduli.

## TABLE 8

SUMMARY OF THICK SHELL FORMULAS FOR CALCULATING
MODULI OF ELASTICITY

Inside gages, dummy block not subject to pressure:

$$
E_{\phi}=\frac{K_{1}\left(1-\nu^{2}\right)}{m_{\phi_{1}}+\nu m_{x_{1}}} \quad E_{x}=\frac{K_{1}\left(1-\nu^{2}\right)}{2\left(m_{x_{1}}+\nu m_{\phi_{1}}\right)}
$$

Outside gages, dummy block not subject to pressure:

$$
E_{\phi}=\frac{k_{2}(1+\nu)(1-2 \nu)}{m_{\phi_{2}}(1-\nu)+\nu\left(m_{x_{2}}+m_{r}\right)} \quad E_{x}=\frac{k_{1}(1+\nu)(1-\nu)}{2\left[m_{x_{2}}(1-\nu)+\nu\left(m_{\phi_{2}}+m_{r}\right)\right]}
$$

Outside gages, dummy block subject to hydrostatic pressure ${ }^{*}$ :

$$
E_{\phi}=\frac{\left(k_{2}-1\right)\left(1-v^{2}\right)}{m_{\phi_{2}}^{\prime}+v m_{x_{2}}^{\prime}} \quad E_{x}=\frac{\left(\frac{k_{1}}{2}-1\right)\left(1-v^{2}\right)}{m_{x_{2}}^{\prime}+\nu m_{\phi_{2}}^{\prime}}
$$

* Dummy block assumed to be of same material as model; circumferential active gages balanced against circumferential dummy and longitudinal active gages balanced against longitudinal dummy.

SUMMARY OF THICK SHELL FORMULAS FOR CALCULATING

## MODULI OF ELASTICITY



$$
\left.\begin{array}{rl}
E_{\phi}= & \text { Circumferential modulus of elasticity } \\
E_{x}= & \text { Longitudinal modulus of elasticity } \\
R= & \text { Mean radius, } 1 / 2\left(R_{1}+R_{2}\right) \\
h= & \text { Wall thickness, }\left(R_{2}-R_{1}\right) \\
K_{1}=\frac{2 R_{2}^{2}}{R_{2}^{2}-R_{1}^{2}} \\
K_{2}=\frac{R_{2}^{2}+R_{1}^{2}}{R_{2}^{2}-R_{1}^{2}} \\
m_{\phi_{1}}= & \text { Avg. strain-pressure ratio, inside circumferential gages, } \\
\text { dummy not under pressure. }
\end{array}\right] \begin{aligned}
& m_{x_{1}}= \text { Avg. strain-pressure ratio, inside longitudinal gages, } \\
& m_{\phi_{2}}= \text { Avg. strain-pressure ratio, outside circumferential gages, } \\
& \text { dummy not under pressure. }
\end{aligned}, \begin{aligned}
& \text { dummy not under pressure. }
\end{aligned}
$$

AND CALCULATION FOR K,

| TUBE | A | B | C | D | $E$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| AVG INSIDE DIA (IN) | 3.195 | 3.145 | 3.195 | 3.195 | 3.195 |
| AVG. WALL THICKNESS (IN) | 0.169 | 0.205 | 0.240 | 0.281 | 0.309 |
| AVG. MEAN OIA. (IN) | 3.364 | 3.400 | 3.435 | 3.476 | 3.504 |
| /D | 0.05024 | 0.06029 | 0.06987 | C. 08084 | 0.08818 |
| AVG. INSIOE RADIUS (IN)' | 1.5975 | 1.5975 | 1.5975 | 1.5975 | 1.5975 |
| AVG. OUTSIDE RADIUS (IN.) | 1.7665 | 1.8025 | 1.8375 | 1.8785 | 1.9065 |
| $R_{2}^{2}$ | 3.1205 | 3.2490 | 3.3764 | 3. 5288 | 3.6347 |
| $R^{2}$ | 2.5520 | 2.5520 | 2.5520 | 2.5520 | 2.5520 |
| $R_{2}^{2}-R_{1}^{2}$ | 0.5685 | 0.6970 | 0.8244 | 0.9768 | 1.0827 |
| $K_{1}=\frac{2 R_{2}^{2}}{R_{2}^{2}-R_{1}^{2}}$ | 10.978 | 9.323 | 8.191 | 7. 225 | 6.714 |

TABLE 10

CALCULATION FOR Eq AND EX

| $E_{\phi}=\frac{k_{1}\left(1-\nu^{2}\right)}{m_{x_{1}}+2 m_{x}}$ |  |  |  | $E_{x}=\frac{\left(k_{1} / 2\right)\left(1-v^{2}\right)}{m_{x}+v_{1} / m_{1}}$ |  |  |  | $\begin{aligned} & 1-z^{2}=0.9775 \\ & m_{x}=(1 / 2)\left(m_{x}+m_{x 2}\right) \end{aligned}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | (1) | (2) | (3) | (4) | 5 | 6 | C | (8) | (9) | (10) |
| MODEL | K, | $\begin{aligned} & \text { AVE } \\ & M_{\phi} \\ & \times 10^{6} \\ & \hline \end{aligned}$ | $\begin{gathered} \text { AVE } \\ \mathrm{MA}^{6} \\ \times 10^{6} \end{gathered}$ | (1) $\times\left(1-\nu^{2}\right)$ | $2 / 178$ <br> $\times 10^{6}$ | $\begin{aligned} & >m_{\phi_{1}} \\ & \times 10 \end{aligned}$ | (3) + (6) | (2) + (5) | $\begin{gathered} E_{\oplus} \times 10^{-6} \\ (4) \div(8) \end{gathered}$ | $\begin{aligned} & E_{x} \times 10^{-6} \\ & \frac{1}{2}[(4 \div(7)] \end{aligned}$ |
| A | 10.978 | 1.800 | 0.132 | 10.731 | 0.1098 | 0.2700 | 1.002 | 1.910 | 5.62 | 5.35 |
| B | 9.323 |  |  |  |  |  |  |  |  |  |
| c | 8.191 | 1.469 | 0.813 | 8.007 | 0.1219 | 0.2204 | 1.0334 | 1.5909 | 5.03 | 3.87 |
| D | 7.225 | 1.262 | 0.674 | 7.062 | 0.1011 | 0.1893 | 0.8633 | 1.3631 | 5.18 | 4.09 |
| $E$ | 6.7/4 | 1.200 | 0.589 | 6.563 | 0.0884 | 0.1800 | 0.769 | 1.2884 | 5.09 | 4.27 |
| $\begin{array}{lll}  & \text { DUTSIDE GAGE DATA } & \nu=0.15 \\ E_{\varnothing}=\frac{K_{2}(1+2)(1-22)}{m_{\phi_{2}}(1-2)+2 m_{x}} & E_{x}=\frac{\left(k_{1} / 2\right)(1+2)(1-2 \nu)}{m_{x}(1-2)+2 m_{\alpha_{2}}} & (1+\nu)(1-2.8)=(1.15)(0.70)=0.805 \\ & & K_{2}=K_{1}-1 \end{array}$ |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |
|  | (11) | (12) | (13) | (14) | (15) | (16) | (17) | (18) | (19) | (20) |
| MCOE, | $\begin{gathered} 1 \times \\ (1+2)(1-22) \end{gathered}$ | $\begin{aligned} & A V E E_{1} \\ & M_{\phi_{2}} \times 10^{6} \end{aligned}$ | $(1-\nu) \times(12)$ | $\left[\begin{array}{l} {[1-1] x} \\ (1+2)(1-22) \end{array}\right.$ | $(1-2) \times(3,$ | $\nu \times(2)$ | (13) + (5) | (15) +16 | $\begin{gathered} E_{\Phi} \times 10^{-6} \\ (14) \div(17) \end{gathered}$ | $\begin{aligned} & E_{x} \times 10^{-6} \\ & \frac{1}{2}[(11) \div(16)] \end{aligned}$ |
| A | 8.837 | 1.430 | 1.2155 | 8.0323 | 0.6222 | 0.2145 | 1.3253 | 0.8367 | 6.06 | 5.28 |
| B |  |  |  |  |  |  |  |  |  |  |
| $c$ | 6594 | 1.131 | 0.9613 | 5.7888 | 0.6910 | 0.1696 | 1.0832 | 0.8606 | 5.34 | 3. 83 |
| D | 5.816 | 0.999 | 0.8492 | 5.0111 | 0.5729 | 0.1498 | 0.9503 | 0.7227 | 5.27 | 4.02 |
| $E$ | 5.405 | 0.930 | 0.7905 | 4.5998 | 0.5007 | 0.1395 | 0.8789 | 0.6402 | 5.23 | 4.22 |

CALCULATION OF EFFECTIVE YOUNG'S MODULUS, EC

AND RESIN CONTENT OF MATERIAL


$$
\begin{aligned}
& E_{e}=2 E_{\phi}\left(\frac{k}{1+k}\right) \text { WHERE } k=E_{x} / E_{\phi} \\
& \text { (SEE PAGES } 44 \$ 45 \text { FOR DERIVATION.) }
\end{aligned}
$$

n

* VALUES OF RESIN CONTENT WERE PROVIDED BY ZENITH PLASTICS CO.
* b. model Eg taken as average of El for $A, C, d$, fe models

In order to properly evaluate experimental results, it was necessary to verify the mode of failure for each model. Although all models were designed to fail by instability, the predicted instability failure pressure for the $D$ and E models was fairly close to the corresponding compressive yield failure pressure predicted using the thick-shell theory and a nominal value for the yield strength of the material. Also, the thick-shell formulas used to calculate the stress do not take into account the bending effects. Because of these considerations, the following steps were taken in order to make an evaluation for the mode of failure.
(1) In order to evaluate the effects of bending, a formula was derived to calculate the longitudinal bending stress for a simply supported cylinder. The method of derivation was suggested by Mr. John Pulos of DTMB and is presented in Appendix F. The expression for the bending stress at midbay 1s:

$$
\left[\sigma_{b}\right]_{x=0}=\left[\frac{\rho R^{2}(1-2 / 2)}{\left(1-2^{2}\right)}\right]\left(\frac{\theta}{L}\right)^{2}\left[\frac{\left(\eta_{1}^{2}-\eta_{2}^{2}\right)^{2}}{\eta_{1} \eta_{2}^{2}}\right]\left[\frac{\sin \theta \theta \eta_{1} \sin \theta \eta_{2}}{\cosh ^{2} \theta \eta_{1} \cos ^{2} \theta \eta_{2}+\sin ^{2} \theta \eta_{1} \sin ^{2} \theta \eta_{e}}\right]
$$

Substituting values for the E, model, the theoretical longitudinal bending stress at midbay was found to be only 75 psi .
(2) The Lame (thick-shell) stress corresponding to the failure pressure was calculated for each of the models and compared both Wth a nominal compressive strength*of 70,000 psi as obtained from DTMB Report $1413^{33}$, and with the lowest calculated value obtained from a yield model $(63,233$ psi). For the E model, the highest calculated stress was $59,285 \mathrm{psi}$ (see Table 6). This value is 10,715 psi below the value for nominal strength but only $3,948 \mathrm{psi}$ below that obtained from the yield model. It

[^0]should be noted, however, that application of the Hencky-von Mises failure criterion would cause the differences to be greater.
(3) Finally, the physical appearance of the collapsed models was compared to that of the thinnest model, for which a pure instability failure was certain, and with that of a short model which definitely failed by yielding of the material. Figures 11 and 12 show collapsed $C, D$, and $E$ models together with a short model which failed by yielding. It is noted that the longer models pictured failed along a longitudinal line parallel to the model axis by buckling inward, whereas the short model tended toward failure throughout most of its wall area.

On the basis of these considerations it was determined that the $A$, $B$, and $C$ models failed purely in the instability mode. Since the compressive stress for the $E$ models was within about 4000 psi of the value obtained from a yield model, there still may be reason to question whether or not some yielding took place. Also, there was scatter in the points for the D and E models (See Fig. 13) which may be a result of local yielding caused by stress concentrations due to the heterogeneous nature of the material.



## PRESENTATION AND DISCUSSION OF RESULTS

Results of the experiments are show graphically in Figure 13. The critical pressures determined from tests were converted to the non-dimensional form $p / s_{e}$. These values were plotted against the thickness-diameter ratio. Calculations for $p / E_{e}$ are shown in Table 12.

Also plotted on Figure 13 are curves representing various theoretical buckling formulas, using an average value of $L / D$ for the models tested. (Average $L / D=2.53$ ).

In spite of the anisotropic nature of the model material and the inaccuracies inherent in the computation for an effective modulus, very good agreement with theory was obtained except for the thicker models. The fact that the points for the $D$ and $E$ models fall below the curves may indicate that the thin shell buckling theory is not adequate for ratios of $h / D$ in this range. As previously noted, however, some yielding may have occurred in these models.

It appears that the von Mises equation is the best one to use in the range of $h / D>0.05$ since, in general, it yields conservative values for the collapse pressure. Design curves for the buckling of simply supported cylinders were therefore drawn up for the von Mises equation. (See Fig. 14). Data for these curves were calculated using the IBM 7090 computer at DTMB. These data are reproduced in Appendix G.

Since curves were not available for determining the number of circumferential lobes into which a relatively thick oylinder would fail, curves were dram. (See Fig. 15). These curves were calculated using data in Appendix $G$ by putting the buckling equation in the form

$$
p / E=F_{1}(h / D)^{3}+F_{2}(h / D)
$$

for each $n$ and $L / D$ and then solving for the desired intersections. These curves are for $\nu=0.15$.

For values of $n$ with $\nu=0.3$, in the range $h / D \leqslant 0.02$, see reference (33).

As far as is known by the authors, these curves for the von Mises equation and for the number of lobes are the only ones available in the range of $h / D$ greater than 0.05 .

CALCULATIONS FOR NON-DIMENSIONAL GUCKLING DRESSURE, PCR/E





## CONCLUSIONS

Based on the results of these experiments the following conclusions are drawn:
(1) The von Mises equation, equation (6), Ref. 22 is the best instability equation for cylinders with ratios of $h / D$ greater than 0.05. It gives conservative values for the buckling pressure up to an $h / D$ of about 0.07 . Use of presently available simplified forms of buckling equations cannot be expected to give conservative values for the buckling pressure in this range of $h / D$. It is noted that Windenburg and Trilling ${ }^{33}$ had previously reached the conclusion that the von Mises formula was probably the best one; however, their conclusion was based on an analysis of experimental and theoretical results for cylinders with ratios of $h / D$ less than 0.007 in contrast with the much thicker range of 0.05 to 0.088 investigated in this thesis.
(2) For practical cases, the use of stiffening ringe, heavy webs, and bulkheads would result in smaller ratios of $h / D$ and $L / D$ for a given weight of structural material. It is concluded, then, that for most practical cases, the thin shell theory is sufficiently accurate for predicting instability fallures.
(3) For cylinders built up of fiber glass reinforced plastic laters, the methods employed in this thesis are sufficiently accurate to predict instability failure pressures.
(4) For an orthotropic cylinder, the effective modulus, as used in the buckling equation, is probably a function of the length between supports.

## RECOMMENDATIONS

## Further Investigations.

The experimental apparatus designed and assembled for this thesis provides a means for the undertaking of a variety of experimental investigations in the field of hydrostatically loaded shells. Some investigations which might be undertaken are:
(1) Investigate the stresses in short, relatively thick, fiberglass reinforced cylindrical shells. Measure the strain distribution along a generator and determine the effects of bending. Verify the formula for bending stress which is derived in Appendix $F$.
(2) Using fiber-glass reinforced plastic models, verify the orthotropic buckling determinant as derived in Appendix E. In conjunction with this, evaluate the determinant to arrive at a general expression for buckling pressure similar to the von Mises equation for the isotropic case. Using the result, develop a method of computing an "effective modulus" for use in isotropic buckling formulas.
(3) Perform experiments on models of unusual form, such as:
a. Stiffened spheres
b. Ellipsoids
c. Sphere-cylinder intersections

## RECOMMENDATIONS (Continued)

Improvement of Apparatus.
Replace valve (G), (F1g. 4) with one rated at $10,000 \mathrm{psi}$ or higher, such as American Instrument Company valve, Cat. No. 44-1505.

Install a fitting in the line to each gage to damp out the sudden drop in pressure when a model breaks, thus protecting the gage pointer. There are commercial fittings available for this purpose.

If a greater number of strain gage leads are required to be run for the gages mounted on the outside of the model, it is recommended that a CONAX Corporation thermocouple fitting, Cat. No. TG-20-B8, be installed in place of the fitting " $A$ " now installed. The $T G-20-B 8$ will take eight \#20 wires.

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## APPENDIX A

## RECORD OF STRAIN GAGE DATA

The following tables consist of the recorded strains corresponding to the gage pressures and corrected pressures. The model number, gage type, gage factor, date of test, gage location, cycle number, run number, and pertinent remarks are also indicated.

Three types of Baldwin-Lima-Hamilton gages were used for the strain measurements:

Gage Type

## Nominal Gage Length

A-5-1

$$
1 / 2^{n}
$$

FAP-50-12
$1 / 2^{n}$
FA-100-121"

The type A-5-1 gage was used on the inside of the model only, since the wre gage is particularly sensitive to hydrostatic pressure. The FAP-50-12, a foll gage, was used both inside and outside the models. The FA-100-12 was used on the outside of model A-4 only. All three types appeared to give reliable data. No particular difficulty was experienced in handling and applying the gages.

In the row entitled Gage Location, "L" stands for a longitudinally mounted gage, "C" for a circumferentially mounted gage, "l" for an inside gage, and "2" for an outside gage.

In some cases the gages were read one at a time requiring a different pressure cycle for each gage. A record was kept of the total number of cycles for each model and the number of runs for a particular gage. These data were taken in order to ascertain the effects of creep, if any. It appeared from the results, however, that creep was not an important factor for these short term tests.
v
$Y$
$Y$ $m$

4
$k$
$<$

| MODEL NO. A-4.\|GAGE TYPE |  |  |  |  |  |  |  | GAGE FACTOR INSIDE |  |  |  |  | 2.11 <br> 2.12 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GAGE LOCATION |  | $L-2$ |  |  | C-2 |  |  | $\angle-1$ |  |  | $C-1$ |  |  |
| CCYCLE | NO. |  | 2 |  |  | 2 |  |  | 2 |  |  | 2 |  |
| RUN NO |  |  | 2 |  |  | 2 |  |  | 2 |  |  | 2 |  |
| $P-G A G E$ | \|P-CORR, | $R$ | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ | $\Sigma$ |
| 0 | 0 | 9000 | - | - | 9000. | - | - | 9000 | - | - | 9000 | - |  |
| 500 | 550 | 8520 | 480 | 480 | 8130 | 870 | 870 | 8650 | 350 | 350 | 8080 | 920 | 920 |
| 1000 | 1030 | 8085 | 435 | 915 | $73 / 5^{\circ}$ | 815 | 1685 | 8360 | 290 | 640 | 7240 | 840 | 1760 |
| 1500 | 1520 | 7675 | 410 | 1325 | 6520 | 785 | 2480 | 8070 | 290 | 930 | 6360 | 880 | 2640 |
| 2000 | 2010 | 7270 | 405 | 1730 | 5640 | 880 | 3260 | 7790 | 280 | 1210 | 5330 | 1030 | 3670 |
| -2100 | 2105 | 7200 | - 70 | 1800 | 5450 | 190 | 3550 | 7740 | 50 | 1260 | 5120 | 210 | 3880 |
| 2200 | 2200 | 7120 | 80 | 1880 | 5250. | 200 | 3750 | 7685 | 55 | 1315 | 4900 | 220 | 4100 |
| 2300 | 2300 | - 2085 | 35 | 1915 | 5070 | 180 | 3930 | 7610 | 75 | 1390 | 4660 | 240 | 4340 |
| 2400 | - 2400 | 7030 | 55 | 1970 | 4800 | 270 | 4200 | 7535 | 75 | 1465 | 4370 | 290 | 4630 |
| 2500 | 2500 | 7030 | 0 | 1970 | 4575 | 225 | 4425 | 7480 | 55 | 1520 | 4105 | 265 | 4895 |
| 2600 | 2600 | 7010 | 20 | 1980 | 4170 | 405 | 4830 | 7425 | 55 | 1575 | 3630 | 475 | 5370 |
| 2700 | 2700 | 7150 | $-140$ | 1850 | 3740 | 430 | 5260 | 7390 | 35 | 1610 | 3280 | 350 | 5720 |
| 2750 | 2750 | 7205 | $-55$ | 1795 | 3245 | 449 | 5755 | 7380 | 10 | 1620 | 2650 | 630 | 6350 |
| 2800 | 2800 | 7420 | $-215$ | 1580 | 2500 | 745 | 6500 | 7395 | $-15$ | 1605 | 1850 | 800 | 1iso |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  | $\stackrel{\rightharpoonup}{*}$ |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |



W 1 i 00 o










| WICJEL | NCETION |  | $c-2$ | - | $\angle-1$ |  |  |  |  |  |  |  |  | $c-2$ |  |  | $22-61$$c-2$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CrCLENO. |  |  | / |  |  | , |  |  | 1 |  |  | 2 |  |  |  |  |  |  |
| RIUNNO. |  |  | / |  |  | / |  |  | , |  |  | 2 |  |  | 2 |  |  |  |
| O-GAGE | P-CORR | R | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ | $\Sigma$ | R | $\triangle$ | $\Sigma$ | R | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ | $\Sigma$ | R | $\triangle$ |
| 0 | 0 | 11800 | - | - | 11800 | - | - | IIf00 | - | - | 11800 | - | - | 11800 | - | - | 11790 | - |
| 250 | 300 | 11540 | 260 | 260 | 11665 | 135 | 135 | 11780 | 20 | 20 |  |  |  | 15555 | 245 | 245 | 1570 | 220 |
| 500 | 550 | 11310 | 230 | 490 | 11540 | 125 | 260 | 11760 | 20 | 40 | 11760 | 40 | 40 |  |  |  | 11350 | 220 |
| 750 | 790 | 11070 | 240 | 730 | /1430 | 110 | 370 | 11740 | 20. | 60 |  |  |  | $1 / 30$ | 425 | 670 | II125 | 225 |
| 1000 | 1030 | 10850 | 220 | 950 | /1310 | 120 | 490 | $1 / 720$ | 20 | 80 | 11730 | 30 | 70 |  |  |  | 10915 | 210 |
| 1250 | 1280 | 10630 | 220 | 1170 | (1190 | 120 | 610 | $1 / 1710$ | 10 | 90 |  |  |  | 10720 | 410 | 1080 | 10710 | 205 |
| 1500 | 1520 | 10420 | 210 | 1380 | 11080 | 110 | 720 | 1/1/80 | 30 | 120 | 11700 | 30 | 100 | 10520 | 200 | 1280 | 110505 | 205128 |
| 1750 | 1770 | 10180 | 240 | 1620 | 10960 | 120 | 840 | $1 / 680$ | 0 | 120 |  |  |  | 10300 | 220 | 1500 | 10290 | 21515 |
| 2000 | 2010 | 9950 | 230 | 1850 | 10850 | 110 | . 950 | 11665 | 15 | 135 | 11675 | 25 | 125 | 10090 | 210 | 1710 | 10080 | 210 |
| 2250 | 2250 | 9730 | 220 | 2070 | 10740 | 110 | 1060 | $1 / 660$ | 5 | 140 |  |  |  | 9880 | 210 | 1920 | 9870 | 210 |
| 2500 | 2500 | 9515 | 215 | 2285 | 10620 | 120 | 1180 | $1 / 650$ | 10. | 150 | 11650 | 25 | 150 | 9670 | 210 | 2130 | 9670 | 200 |
| 2750 | 2750 | 9290 | 225 | 2510 | 1 asoo | 120 | 1300 | $1 / 640$ | 10 | 160 |  |  |  | 9450 | 220 | 2350 | 9440 | 230 |
| 3000 | 3000 | 9075 | 215 | 2725 | 10380 | 120 | 1420 | $1 / 630$ | 10 | 170 | 11630 | 20 | 170 | 9250 | 200 | 2550 |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  | AGAL | HNST | Insin | PE D | dumm |  |  |  |  | AGA | AINST | outs | E | ummy |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |


| MOLEL | $N$ E-4 | GAGE YPE FAP-50-12 |  |  |  |  |  | = $F E F A C T O F 2.11$ |  |  |  |  |  | UHTE 3-22 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $G A G E \angle C$ | ATION | $\angle-2$ |  |  | $<-2$ |  |  | $c-2$ |  |  | $<-2$ |  |  | L-1 |  |  |
| C YCLE | NO. |  | 1 |  | READ WN/LE | $G_{D E C}$ | CEN |  | 3 |  |  | 3 |  |  | 3 |  |
| RUN NO. |  |  | 1 |  | PRESSURE |  |  |  | 2 |  |  | 1 |  |  | 2 | $\Sigma$ |
| $P-G A G E$ | P-CIORR | $R$ | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ | $\Sigma$ | $R$ | $\triangle$ |  |
| 0 | 0 | 11800 | - | - | $1 / 860$ | - | - | $1 / 800$ | - | - | 11800 | - | - | 11800 | - |  |
| 250 | 300 | $1 / 660$ | 140 | 140 |  |  |  | $1 / 530$ | 270 | 270 | 11625 | 175 | 175 | $1 / 680$ | 120 | 120 |
| 500 | 550 | 11530 | 130 | 270 | $1 / 595$ | 265 | 265 | 11295 | 235 | 505 | 11475 | 150 | 325 | 11560 | 120 | 240 |
| 750 | 790 | 11410 | 120 | 390 | $1 / 470$ | 125 | 390 | 11065 | 230 | 735 | 11320 | 155 | 480 | 11450 | 110 | 350 |
| 1000 | 1030 | 11280 | 130 | 520 | $1 / 345$ | 125 | 515 | 10840 | 225 | 960 | 11170 | 150 | 630 | 11330 | 120 | 470 |
| 1250 | 1280 | $1 / 160$ | 120 | 640 | 11225 | 120 | 635 | 10615 | 225 | 1185 | 11030. | 140 | 770 | $1 / 210$ | 120 | 590 |
| 1500 | 1520 | $1 / 050$ | 110 | 750 | 11005 | 220 | 855 | 10405 | 210 | 1395 | 10880 | 150 | 920 | 11110 | 100 | 690 |
| 1750 | 1770 | 10925 | 125 | 875 | 10980 | 25 | 880 | 10165 | 240 | 1635 | 10725 | 155 | 1075 | 10990 | 120 | 810 |
| 2000 | 2010 | 10815 | 110 | 985 | 10855 | 125 | 1005 | 9930 | 235 | 1870 | 10580 | 145 | 1220 | 10880 | $1 / 0$ | 920 |
| 2250 | 2250 | 10690 | 125 | $1 / 10$ | 10740 | 115 | 1120 | 9700 | 230 | 2100 | 10430 | 150 | 1370 | 10760 | 120 | 1040 |
| 2500 | 2500 | 10580 | 110 | 1220 | 10620 | 120 | 1240 | 9480 | 220 | 2320 | 10295 | 135 | 1505 | 10650. | 110 | 1150 |
| 2750 | 2750 | 10480 | 100 | 1320 | 10490. | 130 | 1370 | 9260 | 220 | 2540 | 10155 | 140 | 1645 | 10530 | 120 | 1270 |
| 3000 | 3000 | 10370 | 110 | 1430 |  |  |  | 9045 | 215 | 2755 | 10025 | 130 | 1715 | 10420 | $1 / 0$ | 1380 |
| 3250 | 3250 |  |  |  |  |  |  | 8790 | 255 | 3010 | 9880 | 145 | 1920 | 10290 | 130 | 1510 |
| 3500* | 3580 | AGAN | $5 T$ | siom | Dumen |  |  | 8555 | 235 | 3245 | 9750 | 130 | 2050 | 10160 | 130 | 1640 |
| 4000 | 4100 |  |  |  |  |  |  | 8090 | 465 | 3710 | 9510 | 240 | 2290 | 9900 | 260 | 1900 |
| 4500 | 4600 |  |  |  |  |  |  | 7650 | 440 | 4150 | 9325 | 185 | 2475 | 9670 | 230 | 2130 |
| 5000 | 5100 |  |  |  |  |  |  | 7205 | 445 | 4595 | 9175 | 150 | 2625 | 9415 | 255 | 2385 |
| 6000 | 6130 |  |  |  |  |  |  | 6320 | 885 | 5480 |  |  |  | 8890 | 525 | 2910 |
| 6500 | 6615 |  |  |  |  |  |  | 5820 | 500 | 5980 |  |  |  |  |  |  |
| 7000 | 7140 |  |  |  |  |  |  | 5340 | 480 | 6460 |  |  |  |  |  |  |
| PE MARKS: * SHIFTED TO 15000 PSi GAGE |  |  |  |  |  |  |  | AGAINST INSIDE DUMMY |  |  |  |  |  |  |  |  |

## APPENDIX B

## PLOTS OF PRESSURE VERSUS STRAIN

This section contains plots of the measured strains. The resulting slopes, designated by the letter $m$ with appropriate subscripts are indicated on the plots.

It is noted that all plots are very nearly linear until the collapse pressure is approached. The reversed slope for gage L-2, model A-4 indicates the development of a tensile stress as a result of bending near the collapse pressure.








## APPENDIX C

## THEORY FOR CALCULATION OF E AND Ex FROM STRAIN DATA

The circumferential stress in a thick-walled cylinder under external hydrostatic pressure, p , is given by:

$$
\begin{equation*}
\sigma_{\phi}=\frac{\rho R_{2}^{2}+\rho \frac{R_{1}^{2} R_{2}^{2}}{r^{2}}}{R_{2}^{2}-R_{1}^{2}} \tag{REF}
\end{equation*}
$$

where $r$ is the distance from the center at which the stress is measured. If $r$ is given values of $r=R_{1}$ and $r=R_{2}$, the following expressions evolve for the circumferential stress on the inner and outer walls of the cylinder:

$$
\begin{aligned}
& \sigma_{\phi_{1}}=p\left(\frac{2 R_{2}^{2}}{R_{2}^{2}-R_{1}^{2}}\right) \\
& \sigma_{\phi_{2}}=p\left(\frac{R_{2}^{2}+R_{1}^{2}}{R_{2}^{2}-R_{1}^{2}}\right)=p\left(\frac{2 R_{2}^{2}}{R_{2}^{2}-R_{1}^{2}}-1\right)
\end{aligned}
$$

( $\sigma_{\phi_{1}}$ and $\sigma_{\phi_{2}}$ are positive if compressive.)
The longitudinal stress is constant over the cross section, and is given by:

$$
\begin{equation*}
\sigma_{x}=\rho \frac{R_{2}^{2}}{R_{2}^{2}-R_{1}^{2}} \tag{Ref.42}
\end{equation*}
$$

Letting $\quad K_{1}=\frac{2 R_{2}^{2}}{R_{2}^{2}-R_{1}^{2}}, \quad$ we have

$$
\left.\begin{array}{l}
\sigma_{\phi}=p K_{1} \\
\sigma_{\phi_{2}}=p\left(K_{1}-1\right)=p K_{2} \\
\sigma_{x}=p K_{1} / 2
\end{array}\right\}
$$

If we assume a material which has three principal values of Young's Modulus and a single value of $\nu$, then from Hooke's Law:

$$
\left.\begin{array}{l}
\epsilon_{\phi}=\frac{\sigma_{\phi}}{E_{\phi}}-\frac{\nu \sigma_{r}}{E_{r}}-\frac{\nu \sigma_{x}}{E_{x}} \\
\epsilon_{x}=\frac{\sigma_{x}}{E_{x}}-\frac{\nu \sigma_{r}}{E_{r}}-\frac{\nu \sigma_{\phi}}{E_{\phi}}  \tag{2}\\
\epsilon_{r}=\frac{\sigma_{r}}{E_{r}}-\frac{\nu \sigma_{x}}{E_{x}}-\frac{\nu \sigma_{\phi}}{E_{\phi}}
\end{array}\right\}
$$

Combining Hooke's Law and thick shell theory, we have strains in the inside and outside surfaces of a thick-walled cylinder subject to external hydrostatic pressure:

$$
\begin{align*}
& \epsilon_{\phi_{2}}=p\left(\frac{K_{2}}{E_{\phi}}-\frac{\nu}{E_{r}}-\frac{\nu K_{1}}{2 E_{x}}\right) \\
& \epsilon_{x_{2}}=p\left(\frac{K_{1}}{2 E_{x}}-\frac{\nu}{E_{r}}-\frac{\nu K_{2}}{E_{\phi}}\right)  \tag{3}\\
& \epsilon_{r 2}=p\left(\frac{1}{E_{r}}-\frac{\nu K_{1}}{2 E_{x}}-\frac{v K_{2}}{E_{\phi}}\right)
\end{align*}
$$

(outside)
(Note that $\sigma_{r}=p$ on the outside surface)

$$
\begin{align*}
& \epsilon_{\phi_{1}}=\rho\left(\frac{K_{1}}{E_{\phi}}-\frac{\nu K_{1}}{2 E_{x}}\right) \\
& \epsilon_{x_{1}}=\rho\left(\frac{K_{1}}{2 E_{x}}-\frac{\nu K_{1}}{E_{\phi}}\right)  \tag{4}\\
& \epsilon_{r}=-\nu \rho\left(\frac{K_{1}}{2 E_{x}}+\frac{K_{1}}{E_{\phi}}\right)
\end{align*}
$$

(Note that $\sigma_{r}=0$ on the inside surface)

The stresses in the surfaces of a block of material subject to external pressure, $p$, are given by:

$$
\sigma_{\phi}=\sigma_{x}=\sigma_{r}=p
$$

From Hooke's Law, the strains on the outside surface of the block are given by:

$$
\left.\begin{array}{l}
\epsilon_{\phi D}=p\left(\frac{1}{E_{\phi D}}-\frac{\nu}{E_{r D}}-\frac{\nu}{E_{X D}}\right)  \tag{5}\\
\epsilon_{\times D}=p\left(\frac{1}{E_{X D}}-\frac{\nu}{E_{r D}}-\frac{\nu}{E_{\phi D}}\right) \\
\epsilon_{r D}=p\left(\frac{1}{E_{r D}}-\frac{\nu}{E_{\times D}}-\frac{\nu}{E_{\phi D}}\right)
\end{array}\right\}
$$

The $D$ subscript on a term indicates that it refers to the block rather than to the cylinder.

Consider the case of strain measurements made with strain gage on the inside surface of the cylinder, using a dummy gage not subject to pressure. The strains as read are given by:

$$
\begin{align*}
& \epsilon_{\phi_{1}}=p k_{1}\left(\frac{1}{E_{\phi}}-\frac{\nu}{2 E_{x}}\right) \\
& \epsilon_{x_{1}}=p K_{1}\left(\frac{1}{2 E_{x}}-\frac{\nu}{E_{\phi}}\right)  \tag{6}\\
& \epsilon_{r_{1}}=-p \nu K_{1}\left(\frac{1}{2 E_{x}}+\frac{1}{E_{\phi}}\right)
\end{align*}
$$

Solving the first two of these equations:

$$
\left.\begin{array}{l}
E_{\phi}=\frac{k_{1}\left(1-v^{2}\right)}{m_{\phi_{1}}+v m x_{1}}  \tag{7}\\
E_{x}=\frac{k_{1}\left(1-v^{2}\right)}{2\left(m_{x_{1}}+\nu m_{\phi_{1}}\right)}
\end{array}\right\}
$$

Where

$$
\begin{aligned}
& m_{x_{1}}=\epsilon_{x_{1}} / p \\
& m_{\phi_{1}}=\epsilon_{\phi_{1}} / p
\end{aligned}
$$

Therefore a model instrumented thus can be subjected to hydrostatic pressure and the measured strain-pressure ratios, $m_{x_{1}}$ and $m_{\phi_{1}}$, with an assumed or known value of $\nu$ can be substituted to solve for $E_{x}$ and $E_{\phi}$. The radial strain does not enter the solution, and the radial stress is zero.

Consider the case of strain measurements made with strain gages on the outside surface of the cylinder, using a dummy gage not subject to pressure. The strains as read are given by:

$$
\begin{align*}
& \epsilon_{\phi_{2}}=p\left(\frac{K_{2}}{E_{\phi}}-\frac{\nu}{E_{r}}-\frac{\nu K_{1}}{2 E_{x}}\right) \\
& \epsilon_{x_{2}}=p\left(\frac{K_{1}}{2 E_{x}}-\frac{\nu}{E_{r}}-\frac{\nu K_{2}}{E_{\phi}}\right)  \tag{8}\\
& \epsilon_{r_{2}}=p\left(\frac{1}{E_{r}}-\frac{\nu K_{1}}{2 E_{x}}-\frac{\nu K_{2}}{E_{\phi}}\right)
\end{align*}
$$

Solving this system of equations simultaneously gives:

$$
\begin{align*}
& E_{\phi}=\frac{n_{2}(1+v)(1-2 v)}{m_{\phi_{2}}(1-v)+v\left(m_{x_{2}}+m_{r_{2}}\right)}  \tag{9}\\
& E_{x}=\frac{K_{1}(1+v)(1-2 v)}{2\left[m_{x_{2}}(1-v)+v\left(m_{\phi_{2}}+m_{r_{2}}\right)\right]}
\end{align*}
$$

Consider the case of strain measurements made with strain ages on the outside surface of the cylinder, using dummy gages mounted on a block subject to the hydrostatic pressure, the longitudinal active gage being balanced against a longitudinally oriented dummy, and the circumferential active gage being balanced against a circumferentially oriented dummy. Assume the dummy block to be of the same material as the cylinder. The indicated strain readings are:

$$
\begin{aligned}
& \epsilon_{\phi_{2}}^{\prime}=\epsilon_{\phi_{2}}-\epsilon_{\phi_{D}} \\
& \epsilon_{x_{2}}^{\prime}=\epsilon_{x_{2}}-\epsilon_{\phi D} \\
& \epsilon_{r_{2}}^{\prime}=\epsilon_{r_{2}}-\epsilon_{r D}
\end{aligned}
$$

where the primes indicate that the strains are the indicated values rather than the actual strains. From (3) and (5):

$$
\left.\begin{array}{l}
\epsilon_{\phi_{2}}^{\prime}=p\left(\frac{K_{2}}{E_{\phi}}-\frac{\nu}{E_{r}}-\frac{\nu K_{1}}{2 E_{x}}\right)-p\left(\frac{1}{E_{\phi}}-\frac{\nu}{E_{r}}-\frac{\nu}{E_{x}}\right) \\
\epsilon_{x_{2}}^{\prime}=p\left(\frac{K_{1}}{2 E_{x}}-\frac{\nu}{E_{r}}-\frac{\nu K_{2}}{E_{\phi}}\right)-p\left(\frac{1}{E_{x}}-\frac{\nu}{E_{r}}-\frac{\nu}{E_{\phi}}\right) \\
\epsilon_{r}^{\prime}=p\left(\frac{1}{E_{r}}-\frac{\nu K_{1}}{2 E_{x}}-\frac{\nu K_{2}}{E_{\phi}}\right)-p\left(\frac{1}{E_{r}}-\frac{\nu}{E_{x}}-\frac{\nu}{E_{\phi}}\right) \\
\epsilon_{\phi_{2}}^{\prime}=p\left[\frac{\left(K_{2}-1\right)}{E_{\phi}}-\frac{\nu\left(K_{1} / 2\right.}{E_{x}}-1\right) \\
\epsilon_{x_{2}}^{\prime}=p\left[\frac{\left(K_{1} / 2-1\right)}{E_{x}}-\frac{\nu\left(K_{2}-1\right)}{E_{\phi}}\right] \\
\epsilon_{r}^{\prime}=0
\end{array}\right\} \begin{aligned}
& \text { (10) }
\end{aligned}
$$

The terms involving radial strain drop out. A comparison of (10) with (3) shows that they are identical, except that in (10) the radial terms are missing, and $K_{2}-1$ and $K_{1} / 2-1$ appear in place of $K_{2}$ and $\mathrm{K}_{1} / 2$, respectively. Thus by having the compensating gages arranged as in this case, the values of $E_{\phi}$ and $E_{x}$ may be computed from the indicated strains $\epsilon_{\phi_{2}}^{\prime}$ and $\epsilon_{x_{2}}^{\prime}$, and the radial strains do not enter the solution.

Solving (10):

$$
\begin{align*}
& E_{\phi}=\frac{\left(k_{2}-1\right)\left(1-v^{2}\right)}{m_{\phi_{2}}^{\prime}+\nu m_{x_{2}}^{\prime}}  \tag{11}\\
& E_{x}=\frac{\left(k_{1} / 2-1\right)\left(1-v^{2}\right)}{m_{x_{2}}^{\prime}+\nu m_{\phi_{2}}^{\prime}}
\end{align*}
$$

$$
\}
$$

$$
\text { WHERE: } \begin{aligned}
m_{\phi_{2}}^{\prime} & =\epsilon_{\phi_{2}}^{\prime} / \varphi \\
m_{x_{2}}^{\prime} & =\epsilon_{x_{2}}^{\prime} / \varphi
\end{aligned}
$$

## APPENDIX D

## DERIVATION OF SHEAR MODULUS FOR AN ORTHOTROPIC MATERIAL

Following a method similar to that used by Timoshenko (Ref. 40, pp. 54-57) for developing the shear modulus for the isotripic case, a formula is derived for the shear modulus of an orthotropic material by assuming two principal moduli of elasticity and a constant value for Poisson's ratio.

Consider an element in pure shear. For this condition $\sigma_{x}=-\sigma_{\theta}=\tau_{x} \theta$, as is readily apparent from Mohr's circle. The element can be represented as shown below:

(The deformed element is represented by dotted lines.) The deformed angle at $A$ is $\frac{\pi}{2}-Y$; that at $B$ is $\frac{\pi}{2}+V$, where $V$ is the shearing strain. Now $\overline{O A}^{\prime}=\overline{O A}\left(1+\epsilon_{x}\right)$ and $\overline{O B}^{\prime}=\overline{O B}\left(1+\epsilon_{\theta}\right)$

$$
\epsilon_{x}=\frac{\sigma_{x}}{E_{x}}-\frac{\nu \sigma_{\theta}}{E_{\theta}} \quad \epsilon_{\theta}=\frac{\sigma_{\theta}}{E_{\theta}}-\frac{\nu \sigma_{x}}{E_{x}}
$$

but $\sigma_{x}=\tau_{x \theta}$ and $\sigma_{\theta}=-\tau_{x \theta}$, Then

$$
\overline{O A}^{\prime}=\overline{O A}\left[1+\frac{\tau_{x \theta}}{E_{x}}+\frac{\nu \tau_{x \theta}}{E_{\theta}}\right] \quad \overline{O B}^{\prime}=\overline{O B}\left[1-\frac{\tau_{x \theta}}{E_{\theta}}-\frac{2 \tau_{x \theta}}{E_{x}}\right]
$$

Since $\overline{O A}=\overline{O B}$

$$
\operatorname{TAN} O A^{\prime} B^{\prime}=\operatorname{TAN}(\pi / 4-r / 2)=\frac{\overline{O B}^{\prime}}{\overline{O A}}=\frac{\left[1-\frac{\tau_{x \theta}}{E_{\theta}}-\frac{2 \tau_{x \theta}}{E_{x}}\right]}{\left[1+\frac{\tau_{x \theta}}{E_{x}}+\frac{2 \tau_{x \theta}}{E_{\theta}}\right]}
$$

From trigonometry

$$
\operatorname{TAN}(\pi / 4-r / 2)=\frac{\operatorname{TAN} \pi / 4-\operatorname{TAN} r / 2}{1+\operatorname{TAN} \pi / 4 \operatorname{TAN} r / 2} \simeq \frac{1-r / 2}{1+r / 2}
$$

Solving for $r$ gives

$$
r=\frac{2\left(E_{x}+E_{\theta}\right)(1+\nu)}{\frac{2 E_{x} E_{\theta}}{\tau_{x \theta}}-\left(E_{x}-E_{\theta}\right)(1-\nu)}
$$

Neglecting the second term in the denominator and solving for The

$$
\tau_{x \theta}=\frac{E_{x} E_{\theta}}{\left(E_{x}+E_{\theta}\right)(1+\tau)} Y
$$

Then, the orthotropic expression for $G$ becomes

$$
G=\frac{E_{x} E_{\theta}}{\left(E_{x}+E_{\theta}\right)(1+2)}
$$

Conway ${ }^{41}$ arrived at a similar expression using an energy analysis.

APPENDIX E

DERIVATION OF EQUATION FOR THE CRITICAL PRESSURE
OF A SIMPLY SUPPORTED, ORTHOTROPIC, CIRCULAR CYLINDER SUBJECTED TO HYDROSTATIC PRESSURE

Stress-strain relations.
For isotropic shells, the relation between the stress resultants and couples and the corresponding strains is:

$$
\begin{array}{ll}
N_{x}=\frac{E h}{1-\nu^{2}}\left(\epsilon_{x 0}+\nu \epsilon_{\theta 0}\right) & M_{x}=-D\left(x_{x}+\nu x_{\theta}\right) \\
N_{\theta}=\frac{E h}{1-\nu^{2}}\left(\epsilon_{\theta 0}+\nu \epsilon_{x 0}\right) & M_{\theta}=-D\left(x_{\theta}+\nu x_{x}\right) \\
N_{x \theta}=G \gamma_{0} & M_{x \theta}=D(1-\nu) x_{x \theta}
\end{array}
$$

where the subscript "o "refers to strains in the middle surface.
If is is assumed that the cylinder is orthotropic with principal moduli $E_{X}$ and $E_{\theta}$ and with a constant value of Poisson's ratio, these equations may be written:

$$
\begin{array}{ll}
N_{x}=\frac{h}{1-\nu^{2}}\left(E_{x} \epsilon_{x 0}+\nu E_{\theta} \epsilon_{\theta 0}\right) & M_{x}=-\frac{h^{3}}{12\left(1-\nu^{2}\right)}\left(E_{x} x_{x}+\nu E_{\theta} x_{\theta}\right) \\
N_{\theta}=\frac{h}{1-\nu^{2}}\left(E_{\theta} \epsilon_{\theta 0}+\nu E_{x} \epsilon_{x 0}\right) & M_{\theta}=-\frac{h^{3}}{12\left(1-\nu^{2}\right)}\left(E_{\theta} x_{\theta}+\nu E_{x} x_{x}\right) \\
N_{x \theta}=G \gamma_{0} & M_{x \theta}=G \frac{h^{3}}{6 a} x_{x \theta}
\end{array}
$$

The strains and changes of curvature in terms of the displacements are:

$$
\begin{array}{ll}
\epsilon_{x 0}=\frac{\partial u}{\partial x} & x_{x}=\frac{\partial^{2} w}{\partial x^{2}} \\
\epsilon_{\theta 0}=\frac{1}{a} \frac{\partial w}{\partial \theta}-\frac{w}{a} & x_{\theta}=\frac{1}{a} \frac{\partial}{\partial \theta}\left(\frac{w}{a}+\frac{1}{a} \frac{\partial w}{\partial \theta}\right) \\
Y_{0}=\frac{\partial w}{\partial x}+\frac{1}{a} \frac{\partial u}{\partial \theta} & x_{x \theta}=\frac{1}{a}\left(\frac{\partial w}{\partial x}+\frac{\partial^{2} w}{\partial x \partial \theta}\right)
\end{array}
$$

The stress resultants and couples can then be written in terms of the displacements:

$$
\begin{aligned}
& N_{x}=\frac{h}{1-\nu^{2}}\left[E_{x} \frac{\partial u}{\partial x}+\nu E_{\theta}\left(\frac{1}{a} \frac{\partial v}{\partial \theta}-\frac{w}{a}\right)\right] \\
& N_{\theta}=\frac{h}{1-\nu^{2}}\left[\frac{E_{\theta}}{a} \frac{\partial v}{\partial \theta}-\frac{E_{\theta}}{a} w+\nu E_{x} \frac{\partial u}{\partial x}\right] \\
& M_{x}=-\frac{h^{3}}{12\left(1-\nu^{2}\right)}\left[E_{x} \frac{\partial^{2} w}{\partial x^{2}}+\frac{\nu E_{\theta}}{a^{2}}\left(\frac{\partial w}{\partial \theta}+\frac{\partial^{2} w}{\partial \theta^{2}}\right)\right] \\
& M_{\theta}=-\frac{h^{3}}{12\left(1-\nu^{2}\right)}\left[\frac{E_{\theta}}{a^{2}}\left(\frac{\partial w}{\partial \theta}+\frac{\partial^{2} w}{\partial \theta^{2}}\right)+\nu E_{x} \frac{\partial^{2} w}{\partial x^{2}}\right] \\
& N_{x \theta}=G h\left[\frac{\partial w^{2}}{\partial x}+\frac{1}{a} \frac{\partial u}{\partial \theta}\right] \\
& M_{x \theta}=G \frac{h^{3}}{6 a}\left[\frac{\partial w}{\partial x}+\frac{\partial^{2} w}{\partial x \partial \theta}\right]
\end{aligned}
$$

## The Equilibrium Equations.

The equilibrium equations for a circular cylinder under radial load only are:

$$
\begin{aligned}
& a^{2} \frac{\partial N_{x}}{\partial x}+a \frac{\partial N_{x \theta}}{\partial \theta}=0 \\
& \frac{\partial N_{\theta}}{\partial \theta}+a \frac{\partial N_{x \theta}}{\partial x}-\frac{\partial M_{\theta}}{a \partial \theta}+\frac{\partial M_{x \theta}}{\partial x}=0 \\
& a \frac{\partial^{2} M_{x}}{\partial x^{2}}-2 \frac{\partial^{2} M_{x \theta}}{\partial x \partial \theta}+\frac{1}{a} \frac{\partial^{2} M_{\theta}}{\partial \theta^{2}}+N_{\theta}-p\left(w+\frac{\partial^{2} W^{2}}{\partial \theta^{2}}\right)=0
\end{aligned}
$$

[See Timoshenko, Ref. 30, p.447; note that the term $q a\left(\frac{\partial^{2} v}{\partial x \partial \theta}-\frac{\partial w}{\partial x}\right)$ has been neglected, as was done by vol Mises ${ }^{22}$.]

These equations may be modified to include the effect of axial load as follows. This procedure was used by vo Mises.

The total axial force on the ends of the cylinder is equal to $\pi a^{2} p$. This force is transmitted to the ends of the cylinder of area $2 \pi a h$. Hence the pressure in the cylinder walls is

$$
P^{\prime}=\frac{\pi a^{2} P}{2 \pi a h}=\frac{a P}{2 h}
$$

Now consider an element of the shell in the longitudinal plane.


After deformation, the curvature of the generatrix (neglecting higher order terms) is

$$
\frac{\partial^{2} w}{\partial x^{2}}
$$

The force per unit length, $p^{\prime} h$, thus has a component in the z-direction of

$$
P^{\prime} h \frac{\partial^{2} w}{\partial x^{2}}=\frac{p a}{2} \frac{\partial^{2} w}{\partial x^{2}}
$$

Since the radius, $a$, had been divided out of the original equilibrium equation, this term is written as

$$
\frac{p}{a}\left(\frac{a^{2}}{2} \cdot \frac{\partial^{2} w}{\partial x^{2}}\right)
$$

In order to include the effect of the axial load, this term is added to the term in parenthesis in equation (3) to get:

$$
a \frac{\partial^{2} M_{x}}{\partial x^{2}}-2 \frac{\partial^{2} M_{x \theta}}{\partial x \partial \theta}+\frac{1}{a} \frac{\partial^{2} M_{\theta}}{\partial \theta^{2}}+N_{\theta}-p\left(w+\frac{\partial^{2} w}{\partial \theta^{2}}+\frac{a^{2}}{2} \frac{\partial^{2} w}{\partial x^{2}}\right)=0
$$

## Boundary conditions.

The transverse and longitudinal cross sections of the cylinder assume the following shapes after buckling:

$n=2$


At $x=0$, the displacements may be written:

$$
\left.\begin{array}{l}
u=A \sin n \theta \\
w=B \cos n \theta \\
w=C \sin n \theta
\end{array}\right\} v \text { is } 90^{\circ} \text { out of phase with u and w. }
$$

At $x=0, u=0$ and $v$ and $w$ are maximum; hence, the displacements for any value of $x$ become:

$$
\begin{aligned}
& u=A \sin n \theta \sin \frac{\pi x}{l} \\
& w=B \cos n \theta \cos \frac{\pi x}{l} \\
& w=C \sin n \theta \cos \frac{\pi x}{l} \\
& \text { Let } \lambda=\frac{\pi a}{l}, t h e n \\
& u=A \sin n \theta \sin 1 / a x \\
& w=B \cos n \theta \cos 1 / a x \\
& w=C \sin n \theta \cos 1 / a x
\end{aligned}
$$

Determinant for the Critical Pressure.
By substituting the boundary conditions into the relations for the stress resultants and couples, and substituting the resulting expressions into the equilibrium equations, a system of three equations in $A, B$, and $C$ is determined. In order that an instability condition exist, the constants $A, B$, and $C$, which determine the magnitudes of the displacements, must have values other than zero. This condition requires that the determinant of the coefficients of $A, B$, and $C$ be zero. The determinant for this case is given on the next page. Evaluation of the determinant for a given geometry and material yields the critical buckling pressure.

| $\stackrel{\square}{4}$ |  |  |
| :---: | :---: | :---: |
|  |  |  |
| $\left[\supset\left(r^{x-1}\right)_{z} u+{ }^{x} \exists_{r} Y\right]$ |  | $\stackrel{H}{4}_{\substack{x \\ ~}}$ |

## APPENDIX $P$

DERIVATION OF AN EXPRESSION FOR THE LONGITUDINAL BENDING STRESS

## IN A

SIMPLY SUPPORTED CIRCULAR CYLINDER SUBJECTED TO EXTERNAL HYDROSTATIC PRESSURE

Salerno and Pulos 43 have derived expressions for the stresses in a circular cylindrical shell supported by uniformly spaced circular rings of constant cross section. By using the displacement function obtained in their paper with the appropriate boundary conditions for simple support, an expression for the longitudinal bending stress at midbay is derived.

The longitudinal bending stress is given by:

$$
\sigma_{b}=\frac{E h}{2\left(1-\nu^{2}\right)} \frac{d^{2} w}{d x^{2}}
$$

The displacement function, $w$, as derived by Salerno and Pulos for deflection in the radial direction, is

$$
\omega=B \cos H(\lambda, x)+F \cos H\left(\lambda_{3} x\right)-\frac{P R^{2}[1-\Sigma / 2]}{E h}
$$

where $B$ and $F$ are constants depending on the boundary conditions, $\lambda_{1} \neq \lambda_{3}$, and

$$
\begin{aligned}
& \lambda_{1}=\left[-\frac{P R}{4 D}+\sqrt{\left(-\frac{P R}{4 D}\right)^{2}-\left(\frac{E h}{D R^{2}}\right)}\right]^{1 / 2} \\
& \lambda_{3}=-\left[\frac{P R}{4 D}-\sqrt{\left(-\frac{P R}{4 D}\right)^{2}-\left(\frac{E h}{D R^{2}}\right)}\right]^{1 / 2} \\
& D=\frac{E h^{3}}{12\left(1-2^{2}\right)} \quad \text { (Flexural rigidity of shell) } \\
& R=\text { Mean radius of shell. }
\end{aligned}
$$

Taking the $x$-axis along the axis of the cylinder, with the origin at the mid-length, the boundary conditions for simply-supported ends require that

$$
\begin{array}{lll}
w=0 & \text { at } & x=L / 2 \\
\frac{d^{2} w}{d x^{2}}=0 & \text { at } & x=L / 2
\end{array}
$$

from which,

$$
\begin{aligned}
& 0=B \cos H \lambda_{1} L / 2+F \cos H \lambda_{3} L / 2-\frac{P R^{2}}{E h}\left(1-\frac{2}{2}\right) \\
& 0=B \lambda_{1}^{2} \cos H \lambda_{1} L / 2+F \lambda_{3}^{2} \cos H \lambda_{3} L / 2
\end{aligned}
$$

Solving simultaneously,

$$
\begin{aligned}
& B=\left(\frac{\lambda_{3}^{2}}{\lambda_{3}^{2}-\lambda_{1}^{2}}\right)\left(\frac{1}{\cos H \lambda_{1} L / 2}\right)\left[\frac{P R^{2}}{E h}(1-\nu / 2)\right] \\
& F=\left(\frac{\lambda_{1}^{2}}{\lambda_{1}^{2}-\lambda_{3}^{2}}\right)\left(\frac{1}{\cos H \lambda_{3} L / 2}\right)\left[\frac{P R^{2}}{E h}(1-2 / 2)\right]
\end{aligned}
$$

Krenzke and Short 44 have presented a graphical method for calculating the stresses obtained by the analysis of Salerno and Pulos. In this reference, different parameters were employed as a simplification. These parameters, defined below, are used for the remainder of this derivation.

$$
\begin{gathered}
\lambda_{1}=\frac{2 \theta}{L}\left(\eta_{1}+i \eta_{2}\right) \quad \lambda_{3}=\frac{2 \theta}{L}\left(\eta_{1}-i \eta_{2}\right) \\
\eta_{1}=\frac{1}{2} \sqrt{1-r} \quad \eta_{2}=\frac{1}{2} \sqrt{1+r} \\
r=\frac{P}{2 E}\left(\frac{R}{h}\right)^{2} \sqrt{3\left(1-\nu^{2}\right)} \\
\theta=\frac{\sqrt[4]{3\left(1-\nu^{2}\right)}}{\sqrt{R h}} L
\end{gathered}
$$

Using the Krenzke and Short parameters,

$$
\begin{aligned}
\frac{\lambda_{1}^{2}}{\lambda_{1}^{2}-\lambda_{3}^{2}} & =\frac{\left(\eta_{1}+i \eta_{2}\right)^{2}}{4 i \eta_{1} \eta_{2}} \quad \frac{\lambda_{3}^{2}}{\lambda_{1}^{2}-\lambda_{3}^{2}}=\frac{\left(\eta_{1}-i \eta_{2}\right)^{2}}{4 i \eta_{1} \eta_{2}} \\
B & =-\left[\frac{\left(\eta_{1}-i \eta_{2}\right)^{2}}{4 i \eta_{1} \eta_{2}}\right] \frac{\frac{P R^{2}}{E h}(1-\eta / 2)}{\cos H\left(\eta_{1} \theta+i \eta_{2} \theta\right)} \\
F & =\left[\frac{\left(\eta_{1}+i \eta_{2}\right)^{2}}{4 i \eta_{1} \eta_{2}}\right] \frac{\frac{P R^{2}}{E h}(1-\eta / 2)}{\cos H\left(\eta_{1} \theta-i \eta_{2} \theta\right)}
\end{aligned}
$$

Then,

$$
\begin{gathered}
w=\left[\frac{\left(\eta_{1}+i \eta_{2}\right)^{2}}{4 i \eta_{1} \eta_{2}}\right] \frac{P R^{2}}{E h}(1-2 / 2) \cos H \frac{2 \theta x}{L}\left(\eta_{1}-i \eta_{2}\right) \\
\cos H\left(\eta_{1} \theta-i \eta_{2} \theta\right)
\end{gathered}\left[\frac{\left(\eta_{1}-i \eta_{2}\right)^{2}}{4 i \eta_{1} \eta_{2}}\right] \frac{\frac{P R^{2}}{E h}\left(1-\frac{2}{2}\right) \cos H \frac{2 \theta x}{L}\left(\eta_{1}+i \eta_{2}\right)}{\cos H\left(\eta_{1} \theta+i \eta_{2} \theta\right)}, ~\left(1-\frac{P R^{2}(1 / 2)}{E h}\right.
$$

Taking the second derivative of this expression, simplifying, and substituting into the expression for the longitudinal bending stress gives:

$$
\begin{aligned}
\sigma_{b}=\left[\frac{\rho R^{2}(1-\nu / 2)}{\left(1-\nu^{2}\right)}\right]\left(\frac{\theta}{L}\right)^{2}[ & {\left[\frac{\left(\eta_{1}^{2}+\eta_{2}^{2}\right)^{2}}{\eta_{1} \eta_{2}}\right] \times } \\
& {\left[\frac{\sin H \theta \eta_{1} \sin \theta \eta_{2} \cos \mu \frac{2 \theta x}{L} \eta_{1} \cos H \frac{2 \theta x}{L} \eta_{2}}{\cos H^{2} \theta \eta_{1} \cos ^{2} \theta \eta_{2}+\sinh ^{2} \theta \eta_{1} \sin ^{2} \theta \eta_{2}}-\right.} \\
& \left.\frac{\cos H \theta \eta_{1} \cos \theta \eta_{2} \sin H \frac{2 \theta x}{L} \eta_{1} \sin \frac{2 \theta x}{L} \eta_{2}}{\cosh ^{2} \theta \eta_{1} \cos ^{2} \theta \eta_{2}+\sinh ^{2} \theta \eta_{1} \sin ^{2} \theta \eta_{2}}\right]
\end{aligned}
$$

At midday $x=0$, and

$$
\left[\sigma_{b}\right]_{x=0}=\left[\frac{\rho R^{2}(1-\nu / 2)}{\left(1-\nu^{2}\right)}\right]\left(\frac{\theta}{L}\right)^{2}\left[\frac{\left(\eta_{1}^{2}+\eta_{2}^{2}\right)^{2}}{\eta_{1} \eta_{2}}\right]\left[\frac{\sin \theta \eta_{1} \sin \theta \eta_{2}}{\cosh ^{2} \theta \eta_{1} \cos ^{2} \theta \eta_{2}+\sin ^{2} \theta \eta_{1} \sin ^{2} \theta \eta_{2}}\right]
$$

## APPENDIX G

## SOLUTION OF VON MISES' EQUATION (6)

This appendix contains solutions of the von Mises equation (6) ${ }^{22}$ as computed by the IBM 7090 computer at DTMB. Values of $\mathrm{p} / \mathrm{E}$ were computed for a range of $L / D$ from 0.50 to 3.00 in increments of 0.25 , and for a range of $h / D$ from 0.01 to 0.10 in increments of 0.01 . The solution for a particular $h / D$ was started with a value of $n=2$. The value of $n$ was then incremented by one until a minimum value for $p / E$ was obtained. Columns 3, 4, and 5 give the auxiliary quantities $\rho, \mu_{1}$, and $\mu_{2}$ for use in the von Mises equation.





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$\therefore 15$



#  

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## LI 2.




## thesB202

Elastic instability of relatively thick


[^0]:    * Yield strength in circumferential direction, $\sigma \phi$

