# Learning of Variability for al Pattern Report Statistics of the Statistics of Alexander Report Statistics of Alexander Report Statistics o

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Abstract. In many applications, modelling techniques are necessary which take into account the inherent variability of given data. In this paper, we present an approach to model class specific pattern variation based on tangent distance within a statistical framework for classification. The model is an effective means to explicitly incorporate invariance with respect to transformations that do not change class-membership like e.g. small affine transformations in the case of image objects. If no prior knowledge about the type of variability is available, it is desirable to learn the model parameters from the data. The probabilisti interpretation presented here allows us to view learning of the variational derivatives in terms of a maximum likelihood estimation problem. We present experimental results from two different real-world pattern recognition tasks, namely image ob je
t re
ognition and automati spee
h re
ognition. On the US Postal Service handwritten digit recognition task, learning of variability achieves results well comparable to those obtained using specific domain knowledge. On the SieTill orpus for ontinuously spoken telephone line recorded German digit strings the method shows a significant improvement in omparison with a ommon mixture density approa
h using a omparable amount of parameters. The probabilisti model is well-suited to be used in the field of statistical pattern recognition and an be extended to other domains like luster analysis.

### 1 **Introduction**

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In many applications, it is important to carefully consider the inherent variability of data. In the field of pattern recognition it is desired to construct classification algorithms whi
h tolerate variation of the input patterns that leaves the lassmembership unchanged. For example, image objects are usually subject to affine transformations of the image grid like rotation, s
aling and translation. Conventional distan
e measures like the Eu
lidean distan
e or the Mahalanobis distan
e [3] do not take into account such transformations or do so only if the training data contains a large number of transformed patterns, respectively. One method to incorporate *invariance* whith respect to such transformations into a classifier is to use invariant distan
e measures like the tangent distan
e, whi
h has been successfully applied in image object recognition during the last years  $[9, 14, 15]$ .

Tangent distance (TD) is usually applied by explicitly modelling the derivative of transformations which are known a priori. This is especially effective in cases where the training set is small. But not in all domains such specific knowledge is available. For example, the transformation effects on the feature vectors of a speech signal that are used in automatic speech recognition are generally difficult to obtain or unknown.

In this paper we present a method to automatically *learn* the derivative of the variability present in the data within a statisti
al framework, thus leading to an increased robustness of the classifier. To show the practical value of the approach we present results from experiments in two real-world application areas, namely optical character recognition (OCR) and automatic speech recognition (ASR).

To classify an observation  $x \in \mathbb{R}$ , we use the Bayesian decision rule

$$
x \longmapsto r(x) = \operatorname{argmax}_{x} \{ p(k) \cdot p(x|k) \}.
$$
 (1)

Here,  $p(k)$  is the *a priori* probability of class k,  $p(x|k)$  is the *class conditional* probability for the observation x given class k and  $r(x)$  is the decision of the classifier. This decision rule is known to be optimal with respect to the expected number of classification errors if the required distributions are known [3]. However, as neither  $p(k)$  nor  $p(x|k)$  are known in practical situations, it is necessary to hoose models for the respe
tive distributions and estimate their parameters using the training data. The lass onditional probabilities are modelled using Gaussian mixture densities (GMD) or kernel densities (KD) in the experiments. The latter can be regarded as an extreme case of the mixture density model, where ea
h training sample is interpreted as the enter of a Gaussian distribution. A Gaussian mixture is defined as a linear combination of Gaussian component densities, which can approximate any density function with arbitrary pre
ision, even if only omponent densities with diagonal ovarian
e matri
es are used. This restri
tion is often imposed in order to redu
e the number of parameters that must be estimated. The ne
essary parameters for the GMD an be estimated using the Expectation-Maximization (EM) algorithm [3].

#### 2Invarian
e and Tangent Distan
e

There exists a variety of ways to a
hieve invarian
e or transformation toleran
e of a lassier, in
luding normalization, extra
tion of invariant features and invariant distance measures [19]. Distance measures are used for classification as dissimilarity measures, i.e. the distan
es should ideally be small for members of the same class and large for members of different classes. An invariant distance measure ideally takes into account transformations of the patterns, yielding small values for patterns which mostly differ by a transformation that does not change lass-membership. In the following, we will give a brief overview of one invariant distance measure called *tangent distance*, which was introduced in [15, 16].

Let  $x \in \mathbb{R}^-$  be a pattern and  $t(x, \alpha)$  denote a transformation of  $x$  that depends on a parameter L-tuple <sup>2</sup> IR<sup>L</sup> , where we assume that <sup>t</sup> does not



Fig. 1. Illustration of the Euclidean distance between an observation  $x$  and a reference  $\mu$  (dashed line) in comparison to the distance between the corresponding manifolds (dotted line). The tangent approximation of the manifold of the referen
e and the orresponding (one-sided) tangent distance is depicted by the light gray lines.

affect class membership (for small  $\alpha$ ). The set of all transformed patterns now omprises a manifold manifold  $\mathbf{v}$  $\{t(x, \alpha) : \alpha \in \mathbb{R}^L\} \subset \mathbb{R}^D$  in pattern space. The distance between two patterns can then be defined as the minimum distance between the manifold  $\mathcal{M}_x$  of the pattern x and the manifold  $\mathcal{M}_\mu$  of a class specific prototype pattern  $\mu$ , which is truly invariant with respect to the regarded transformations (
f. Fig. 1):

$$
d(x,\mu) = \min_{\alpha,\beta \in \mathbb{R}^L} \{ ||t(x,\alpha) - t(\mu,\beta)||^2 \}
$$
 (2)

However, the resulting distance calculation between manifolds is a hard nonlinear optimization problem in general. Moreover, the manifolds usually cannot be handled analytically. To overcome these problems, the manifolds can be approximated by a *tangent subspace*  $\widehat{\mathcal{M}}$ . The *tangent vectors*  $x_l$  that span the subspace are the partial *derivatives* of the transformation  $t$  with respect to the parameters  $\alpha_l$   $(l = 1, \ldots, L)$ , i.e.  $x_l = \partial t(x, \alpha) / \partial \alpha_l$ . Thus, the transformation  $t(x, \alpha)$  can be approximated using a Taylor expansion around  $\alpha = 0$ :

$$
t(x,\alpha) = x + \sum_{l=1}^{L} \alpha_l x_l + \sum_{l=1}^{L} \mathcal{O}(\alpha_l^2)
$$
\n(3)

The set of points consisting of all linear combinations of the pattern  $x$  with the tangent vectors  $x_l$  forms the tangent subspace  $\widehat{\mathcal{M}}_x$ , which is a first-order approximation of  $\mathcal{M}_x$ :

$$
\widehat{\mathcal{M}}_x = \left\{ x + \sum_{l=1}^L \alpha_l x_l \; : \; \alpha \in \mathbb{R}^L \right\} \subset \mathbb{R}^D \tag{4}
$$

Using the linear approximation  $\widehat{\mathcal{M}}_x$  has the advantage that distance calculations are equivalent to the solution of linear least square problems or equivalently



Fig. 2. Example of first-order approximation of affine transformations and line thickness. (Left to right: original image, diagonal deformation, s
ale, line thi
kness in
rease, shift left, axis deformation, line thickness decrease)

projections into subspaces, which are computationally inexpensive operations. The approximation is valid for small values of  $\alpha$ , which nevertheless is sufficient in many appli
ations, as Fig. 2 shows for examples of OCR data. These examples illustrate the advantage of TD over other distance measures, as the depicted patterns all lie in the same subspa
e. The TD between the original image and any of the transformations is therefore zero, while the Eu
lidean distan
e is significantly greater than zero. Using the squared Euclidean norm, the TD is defined as:

$$
d_{2S}(x,\mu) = \min_{\alpha,\beta \in \mathbb{R}^L} \{ ||(x + \sum_{l=1}^L \alpha_l x_l) - (\mu + \sum_{l=1}^L \beta_l \mu_l)||^2 \}
$$
(5)

Eq.  $(5)$  is also known as *two-sided* tangent distance  $(2S)$  [3]. In order to reduce the effort for determining  $d_{2S}(x, \mu)$  it may be convenient to restrict the calculation of the tangent subspa
es to the prototype (or the referen
e) ve
tors. The resulting distance measure is called *one-sided* tangent distance (1S):

$$
d_{1S}(x,\mu) = \min_{\alpha \in \mathbb{R}^L} \{ ||x - (\mu + \sum_{l=1}^L \alpha_l \mu_l)||^2 \}
$$
(6)

The presented onsiderations are based on the Eu
lidean distan
e, but equally apply when using the Mahalanobis distance [3] in a statistical framework. They show that a suitable first-order model of variability is a subspace model based on the derivatives of transformations that respe
t lass-membership, where the variation is modelled by the tangent vectors or subspace components, respectively. In the following we will on
entrate on properties of the model and the estimation of subspa
e omponents if the transformations are not known.

#### 3Learning of Variability

We first discuss a probabilistic framework for TD and then show, how learning of the tangent ve
tors an be onsidered as the solution of a maximum likelihood estimation problem. This estimation is espe
ially useful for ases where no prior knowledge about the transformations present in the data is available.

#### $3.1$ Tangent Distance in a Probabilistic Framework

To embed the TD into a statisti
al framework we will fo
us on the one-sided TD, assuming that the references are subject to variations. A more detailed presentation in
luding the remaining ases of variation of the observations and the two-sided  $TD$  can be found in  $[8]$ .

We restrict our considerations here to the case where the observations  $x$  are normally distributed with expectation  $\mu$  and covariance matrix  $\Sigma$ . The extension to Gaussian mixtures or kernel densities is straightforward using maximum approximation or the EM algorithm. In order to simplify the notation, class indices are omitted. Using the first-order approximation of the manifold  $\mathcal{M}_{\mu}$  for a mean vector  $\mu$ , we obtain the probability density function (pdf) for the observations:

$$
p(x | \mu, \alpha, \Sigma) = \mathcal{N}(x | \mu + \sum_{l=1}^{L} \alpha_l \mu_l, \Sigma)
$$
 (7)

The integral of the joint distribution  $p(x, \alpha | \mu, \Sigma)$  over the unknown transformation parameters  $\alpha$  then leads to the following distribution:

$$
p(x | \mu, \Sigma) = \int p(x, \alpha | \mu, \Sigma) d\alpha
$$
  
= 
$$
\int p(\alpha | \mu, \Sigma) \cdot p(x | \mu, \alpha, \Sigma) d\alpha
$$
  
= 
$$
\int p(\alpha) \cdot p(x | \mu, \alpha, \Sigma) d\alpha
$$
 (8)

Without loss of generality, the tangent vectors of the pdf in Eq. (7) can be assumed orthonormal with respect to  $\Sigma$ , as only the spanned subspace determines the modelled variation. Hen
e, it is always possible to a
hieve the ondition

$$
\mu_l^T \Sigma^{-1} \mu_m = \delta_{l,m} \tag{9}
$$

using e.g. a singular value decomposition, where  $\delta_{l,m}$  denotes the Kronecker delta. Note that we assume that  $\alpha$  is independent of  $\mu$  and  $\Sigma$ , i.e.  $p(\alpha | \mu, \Sigma) \equiv$  $p(\alpha)$ . Furthermore,  $\alpha \in \rm I\!R^-$  is assumed to be normally distributed with mean U and a covariance matrix  $\gamma$  , i.e.  $p(\alpha) = \mathcal{N}(\alpha|0,\gamma$  i), where I denotes the identity matrix and  $\gamma$  is a hyperparameter describing the standard deviation of the transformation parameters. These assumptions redu
e the omplexity of the calculations but do not affect the general result. The evaluation of the integral in Eq. (8) leads to the following expression:

$$
p(x|\mu, \Sigma) = \mathcal{N}(x|\mu, \Sigma') = \det(2\pi\Sigma')^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\left[(x-\mu)^T\Sigma'^{-1}(x-\mu)\right]\right) \tag{10}
$$

$$
\Sigma' = \Sigma + \gamma^2 \sum_{l=1}^{L} \mu_l \mu_l^T, \qquad \Sigma'^{-1} = \Sigma^{-1} - \frac{1}{1 + \frac{1}{\gamma^2}} \Sigma^{-1} \sum_{l=1}^{L} \mu_l \mu_l^T \Sigma^{-1} \tag{11}
$$

Note that the exponent in Eq. (10) leads to the onventional Mahalanobis distance for  $\gamma \to 0$  and to TD for  $\gamma \to \infty$ . Thus, the incorporation of tangent vectors adds a corrective term to the Mahalanobis distance that only affects the covariance matrix which can be interpreted as structuring  $\Sigma$  [8]. For the limiting case  $\Sigma = I$ , a similar result was derived in [6]. The probabilistic interpretation of TD an also be used for a more reliable estimation of the parameters of the distribution  $[2, 8]$ . Note furthermore that det $(\geq) = (1 + \gamma^{-})^{-}$ det $(\geq)$   $[5, pp.$  38. L which is independent of the tangent vectors and can therefore be neglected in the following maximum likelihood estimation.

### 3.2 Estimation of Subspa
e Components

In order to circumvent the restriction that the applicable transformations must be known a priori, the tangent ve
tors an be learned from the training data. This estimation can be formulated within a maximum likelihood approach.

Let the training data be given by  $x_{n,k}$ ,  $n = 1, \ldots, N_k$  training patterns of  $k = 1, \ldots, K$  classes. Assuming that the number L of tangent vectors is known

(note that L can be determined automatically  $[1]$ ) we consider the log-likelihood as a function of the unknown tangent vectors  $\{\mu_{kl}\}$  (for each class k):

$$
F(\{\mu_{kl}\}) := \sum_{k=1}^{K} \sum_{n=1}^{N_k} \log \mathcal{N}(x_{n,k} | \mu_k, \Sigma'_k)
$$
  
= 
$$
\frac{1}{1 + \frac{1}{\gamma^2}} \sum_{k=1}^{K} \sum_{n=1}^{N_k} \sum_{l=1}^{L} ((x_{n,k} - \mu_k)^T \Sigma^{-1} \mu_{kl})^2 + \text{const}
$$
  
= 
$$
\frac{1}{1 + \frac{1}{\gamma^2}} \sum_{k=1}^{K} \sum_{l=1}^{L} \mu_{kl}^T \Sigma^{-1} S_k \Sigma^{-1} \mu_{kl} + \text{const}
$$
(12)

with  $S_k = \sum_{n=1}^{N_k} (x_{n,k} - \mu_k)(x_{n,k} - \mu_k)^T$  as the class specific scatter matrix.  $\Sigma$ and Sk an be regarded as ovarian
e matri
es of two ompeting models. Taking the constraints of orthonormality of the tangent vectors with respect to  $\Sigma^{-1}$ into account, we obtain the following result [5, pp. 400ff.]: The class specific tangent versions and that the versions  $\alpha$  in the versions of the versions and versions to be versions  $2^{-1/2} \mu_{kl}$  are those eigenvectors of the matrix  $2^{-1/2} \lambda_k (2^{-1/2})^{-1}$  with the largest orresponding eigenvalues.

As the above considerations show, two different models have to be determined for the covariance matrices  $\Sigma$  and  $S_k$ . While  $S_k$  is defined as a class specific scatter matrix, a globally pooled covariance matrix is a suitable choice for  $\Sigma$  in many cases. Using these models, the effect of incorporating the tangent distan
e into the Mahalanobis distan
e is equivalent to performing a global whitening transformation of the feature space and then using the  $L$  class specific eigenvectors with the largest eigenvalues as tangent vectors for each class. This reduces the effect of those directions of class specific variability that contribute the most variance to  $\Sigma$ . While the maximum likelihood estimate leads to results similar to conventional principal component analysis (PCA), the estimated components are used in a completely different manner here. In conventional PCA, the principal components are chosen to minimize the reconstruction error. In ontrast to that, these omponents span the subspa
e with minor importan
e in the distan
e al
ulation in the approa
h presented here. This an be interpreted as reducing the effect of specific variability, motivated by the fact that it does not hange lass membership of the patterns. The tangent distan
e has the property that it also works very well in ombination with global feature transformations as for instance a linear discriminant analysis (LDA), since  $\Sigma$  can be assumed as a global ovarian
e matrix of an LDA-transformed feature spa
e.

#### 4Experimental Results

To show the appli
ability of the proposed learning approa
h, we present results obtained on two real-world classification tasks. The performance of a classifier is measured by the obtained *error rate*  $(ER)$ , i.e. the ratio of misclassifications to the total number of classifications. For speech recognition a suitable measure is the *word error rate* (WER), which is defined as the ratio of the number of in
orre
tly re
ognized words to the total number of words to be re
ognized. The difference to the correct sentence is measured using the Levenshtein or edit distance, defined as the minimal number of insertions (ins), deletions (del) or replacements of words necessary to transform the correct sentence to the recognized sentence. The *sentence error rate* (SER) is defined as the fraction of in
orre
tly re
ognized senten
es.

### 4.1 Image Object Recognition

Results for the domain of image object recognition were obtained on the well known US Postal Servi
e handwritten digit re
ognition task (USPS). It ontains normalized greys
ale images of size 16-16 pixels, divided into a training set of 7,291 images and a test set of 2,007 images. Reported re
ognition error rates for this database are summarized in Table 1. In our preliminary experiments, we used kernel densities to model the distributions in Bayes' decision rule and we applied *appearance based* classification, i.e. no feature extraction was applied. The use of tangent distan
e based on derivatives (6 aÆne derivatives plus line thi
kness) and virtual training and testing data (by shifting the images 1 pixel into 8 dire
tions, keeping training and test set separated) improved the error rate to  $2.4\%$ . This shows the effectivity of the tangent distance approach in combination with prior knowledge. Finally, using classifier combination, where different test results were combined using the sum rule, we obtained an error rate of  $2.2\%$  [9].

For our experiments on learning of variability, we used two different settings. First, we used a single Gaussian density, i.e. one referen
e per lass, and varied the number of estimated tangents. As shown in Table 2, the error rate can

method		$ER[\%]$
human performance	SIMARD et al. 1993] $\lceil 15 \rceil$	2.5
relevance vector machine	TIPPING et al. 2000 [17]	5.1
neural net (LeNet1)	LECUN et al. $1990$ [14]	4.2
invariant support vectors	SCHÖLKOPF et al. 1998 [13]	3.0
neural net $+$ boosting	DRUCKER et al. 1993 [14]	$*2.6$
tangent distance	SIMARD et al. 1993 [15]	$*2.5$
nearest neighbor classifier	$\lceil 9 \rceil$	5.6
mixture densities	baseline  2	7.2
	$+$ LDA $+$ virtual data	$3.4\,$
kernel densities	[9] tangent distance, derivative, one-sided $(\mu)$	3.7
	one-sided $(x)$	3.3
	two-sided	3.0
	+ virtual data	2.4
	$+$ classifier combination	2.2
kernel densities	tangent distance, learned, one-sided $(\mu)$ , $L = 12$	3.7

Table 1. Summary of results for the USPS corpus (error rates, [%]). : training set extended with 2,400 ma
hine-printed digits

Table 2. Results for learning of tangent vectors (ER [%], USPS, KD)

			$\#$ references/class $\vert L = 0 \vert L = 7 \vert L = 12 \vert L = 20$ derivative tangent vectors $(L = 7)$
	18.6		
$\approx 700$	5.5	3.9	

be reduced from 18.6% to 5.5% with the estimation of tangent vectors from class specific covariance matrices as proposed above. Using only  $L = 7$  tangent vectors, the result of 6.4% compares favorably to the use of the derivative, here with  $11.8\%$  error rate. This is probably due to the fact that the means of the single densities are the average of a large number of images and therefore very blurred, whi
h is a disadvantage for the derivative tangent ve
tors. Here, the estimated tangent ve
tors outperform those based on the derivative.

Interestingly, when using all 7,291 training patterns in a kernel density based classifier, the result obtained without tangent model is the same as for a single density model with 12 estimated tangents. In this case, the single densities with estimated tangent subspa
e obtain the same result using about 50 times fewer parameters. In the se
ond setting with about 700 referen
es per lass (KD), the error rate can be reduced to  $3.7\%$  for 20 estimated tangents. Fig. 3(a) shows the evolution of the error rate for different number of tangent vectors. Here, the tangent vectors were estimated using a local, class specific covariance matrix obtained from the set of lo
al nearest neighbors for ea
h training pattern. Therefore, the method is only applied to the one-sided tangent distan
e with tangents on the side of the referen
e. The obtained error rate is the same as for the derivative tangents, although somewhat higher for the same number of tangents. This shows that the presented method can be effectively used to learn the class specific variability on this dataset. Note that using the tangents on the side of the observations resp. on both sides, the obtained error rate is significantly lower (cf. Table 1).

Fig. 3(b) shows the error rate with respect to the subspace standard deviation  $\gamma$  for derivative tangents and estimated tangents using  $L = 7$  each. It can be seen that, on this data, no significant improvement can be obtained by restricting the value of  $\gamma$ , while there may be improvements for other pattern recognition tasks.

So far we have not discussed the computational complexity of the tangent method. Due to the structure of the resulting model, the computational cost of the distance calculation is increased approximately by a factor of  $(L + 1)$ , in omparison with the baseline model that orresponds to the Eu
lidean distan
e.

### 4.2 Automati Spee
h Re
ognition

Experiments for the domain of speech recognition were performed on the  $SieTill$ corpus [4] for telephone line recorded German continuous digit strings. The corpus onsists of approximately 43k spoken digits in 13k senten
es for both training and test set. In Table 3 some information on orpus statisti
s is summarized.

The re
ognition system is based on whole-word Hidden Markov Models (HMMs) using ontinuous emission densities. The baseline system is hara
 terized as follows:



Fig. 3. (a) ER w.r.t. number of estimated tangents (USPS, KD). (b) ER w.r.t. subspa
e standard deviation  $\gamma$  for  $L = 7$  derivative and estimated tangent vectors (USPS, KD).

- $-$  vocabulary of 11 German digits including the pronunciation variant 'zwo',
- gender-dependent whole-word HMMs, with every two subsequent states being identi
al,
- $=$  for each gender 214 distinct states plus one for silence,
- { Gaussian mixture emission distributions,
- one globally pooled diagonal covariance matrix  $\Sigma$ ,
- 12 cepstral features plus first derivatives and the second derivative of the first feature component.

The baseline re
ognizer applies maximum likelihood training using the Viterbi approximation in ombination with an optional LDA. A detailed des
ription of the baseline system can be found in [18]. The word error rates obtained with the baseline system for the ombined re
ognition of both genders are summarized in Table 4 (in the lines with 0 tangent ve
tors (tv) per mixture (mix)). In this domain, all densities of the mixtures for the states of the HMMs are regarded as separate *classes* for the application of learning of variability. The  $S_k$  were trained as state specific full covariance matrices. Note that the  $S_k$  are only necessary in the training phase.

For single densities, the in
orporation of TD improved the word error rate by 18.1% relative for one tangent vector and 21.6% relative using four tangent ve
tors per state. In ombination with LDA transformed features the relative improvement was 13.8% for the incorporation of one tangent vector and increased to  $28.6\%$  for five tangent vectors per state. Fig.  $4(a)$  depicts the evolution of the word error rates on the  $SieTill$  test corpus for different numbers of tangent ve
tors using single densities that were trained on LDA transformed features.

Table 3. Corpus statisti
s for the SieTill orpus.

corpus	female	male			
	sent. digits sent. digits				
test	6176 20205 6938 22881				
train 6113 20115 6835 22463					

For this setting the optimal hoi
e for gender dependent trained referen
es was five tangent vectors per state.

Using mixture densities, the performance gain in word error rate decreased but was still significant. Thus the relative improvement between the baseline result and tangent distan
e was 6:7% (16 densities plus one tangent ve
tor per mixture) for untransformed features and 13:6% for LDA transformed features (16 dns/mix, 1 tv/mix). The same applies for the optimal number of tangent ve
tors whi
h was found at one tangent ve
tor per mixture. Consequently, a larger number of densities is able to partially ompensate for the error that is made in the case that the covariance matrix is estimated using the conventional method. The best result was obtained using 128 densities per mixture in ombination with LDA transformed features and the in
orporation of one tangent vector per state. Using this setting, the word error rate decreased from 1.85% to 1.67% which is a relative improvement of  $5\%$ . Fig. 4(b) depicts the evolution of word error rates for onventional training in omparison with TD using equal numbers of parameters. Even though the incorporation of tangent vectors into the Mahalanobis distan
e in
reases the number of parameters, the overall gain in performan
e justies the higher expense.

## $\overline{5}$

In this paper we presented an approa
h for modelling and learning variability for statisti
al pattern re
ognition, embedding tangent distan
e into a probabilisti framework. In contrast to principal component analysis based methods like [12] the model disregards the specific variability of the patterns when determining the distan
e or the log-likelihood, respe
tively, whi
h leads to an in
orporation of transformation tolerance and therefore improves the classification performance. This is due to the basic difference between the *distance in feature space* and the

Table 4. Word error rates (WER) and senten
e error rates (SER) on the SieTill orpus obtained with the tangent distance. In column 'tv/mix' the number of used tangent ve
tors per mixture is given. A value of 0 means that the onventional Mahalanobis distan
e is used. 'dns/mix' gives the average number of densities per mixture.

without LDA				with LDA					
$\frac{dn}{m}$ tv/mix		[%] error rates			$\frac{dn}{m}$ $\frac{dv}{m}$		error rates $[\%]$		
		del - ins  WER SER					del - ins  WER SER		
	$\theta$	1.17-0.83 4.59		11.34		0	$0.71 - 0.63$ 3.78		9.74
		$1.17 - 0.5213.76$		9.22			$0.97 - 0.49$ 3.26		8.46
	4	$[0.69 - 1.07]3.60$		9.10		5	$ 0.48 - 0.88 2.70$		7.18
16	$\theta$	$[0.59 - 0.83]2.67$		6.92	16	$\theta$	$0.44 - 0.68$   2.28		5.92
		10.54-0.5812.49		6.56			$0.58 - 0.40$   1.97		5.06
	$\overline{4}$	$[0.46 - 0.80] 2.60$		6.76		4	$0.38 - 0.55$   1.97		5.35
128	$\theta$	$[0.52 - 0.54]$ 2.24		5.87	128	$\theta$	$0.45 - 0.39$   1.85		4.94
		0.50 - 0.48   2.12		5.75			$ 0.42 \text{-} 0.34   1.67$		4.50
	4	$\vert 0.55$ - $0.49 \vert 2.13$		5.71		4	$0.39 - 0.41$   1.76		4.81



Fig. 4. (a) Word error rates as a function of the number of tangent vectors on the SieTill test orpus for single densities using ML training on LDA transformed features. (b) Comparison of WER for mixture densities on the SieTill test orpus using equal overall model parameter numbers.

distances from feature space, which control is an extra space propriate for the control of the complete  $\alpha$ tion [11]. The presented model in its local version is adaptive to specific local variability and therefore similar to  $[7]$ . Note that the presented model assigns to the subspace components a weight  $\gamma$  that was found to be usually larger than the corresponding eigenvalue, which is a main difference to subspace approximations to the full covariance matrix based on eigenvalue decomposition like e.g. [10]. The overrepresentation of estimated variational subspa
e omponents may lead to an increased transformation tolerance. The new model proved to be very effective for pattern re
ognition, in
luding the ombination with globally operating feature transformations as the linear discriminant analysis. Thus, theoretical ndings are supported by the experimental results. Comparative experiments were performed on the USPS corpus for image object recognition and on the orpus for an extra communication or processes for an extended for an extra specific strings for a specific nition. On the USPS orpus, single density and kernel density error rates ould be significantly improved, and the obtained results were well comparable to the use of tangents based on prior knowledge. Using the one-sided TD, a relative improvement in word error rate of approximately 20% was a
hieved for single densities on the  $SieTill$  corpus. For mixture densities we could gain a relative improvement of up to 13.6% in word error rate. Incorporating the TD we were able to redu
e the word error rate of our best re
ognition result based on maximum likelihood trained references from 1.85% to 1.67%. Note that the probabilistic modelling technique may also be used for other tasks like clustering, where first results show that the formed clusters respect the transformations.

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