RATIONAL MAPS WITH FATOU COMPONENTS OF ARBITRARILY LARGE CONNECTIVITY

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ABSTRACT. We study the family of singular perturbations of Blaschke products $B_{a,\lambda}(z)=z^3\frac{z-a}{1-\overline{a}z}+\frac{\lambda}{z^2}$. We analyse how the connectivity of the Fatou components varies as we move continuously the parameter λ . We prove that all possible escaping configurations of the critical point $c_-(a,\lambda)$ take place within the parameter space. In particular, we prove that there are maps $B_{a,\lambda}$ which have Fatou components of arbitrarily large finite connectivity within their dynamical planes.

1. Introduction

Given a rational map $f: \widehat{\mathbb{C}} \to \widehat{\mathbb{C}}$, where $\widehat{\mathbb{C}} = \mathbb{C} \cup \{\infty\}$ denotes the Riemann Sphere, we consider the discrete dynamical system provided by the iterates of f. This dynamical system splits $\widehat{\mathbb{C}}$ into two totally invariant sets, the Fatou set $\mathcal{F}(f)$, which is defined as the set of points $z \in \widehat{\mathbb{C}}$ such that the family $\{f^n, n \in \mathbb{C}\}$ is normal in some neighbourhood of z, and its complement, the Julia set $\mathcal{J}(f)$. The dynamics of the points $z \in \mathcal{F}(f)$ is stable in the sense of normality whereas the dynamics of the points $z \in \mathcal{J}(f)$ presents a chaotic behaviour. The Fatou set $\mathcal{F}(f)$ is open and, hence, $\mathcal{J}(f)$ is closed. The connected components of $\mathcal{F}(f)$ are called Fatou components and are mapped under f among themselves. A Fatou component U is called periodic if there exists $q \in \mathbb{N}$ with $f^q(U) = U$ and preperiodic if there exists $q \in \mathbb{N}$ such that $f^q(U)$ is periodic. All Fatou components of rational maps are either periodic or preperiodic (see [21]). Moreover, any cycle of periodic Fatou components of a rational map has at least a critical point, i.e. a point $z \in \widehat{\mathbb{C}}$ such that f'(z) = 0, related to it. For a more detailed introduction to the dynamics of rational maps we refer to [4] and [14].

The connectivity of a domain $D \subset \mathbb{C}$ is given by the number of connected components of its boundary ∂D . It is well known that periodic Fatou components have connectivity 1, 2 or ∞ (see [4]). However, preperiodic Fatou components may have finite connectivity greater than 2. Beardon [4] introduced an example suggested by Shishikura of a family of rational

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maps with Fatou components of finite connectivity greater than 2. Baker, Kotus and Lü [3] proved that, given any $n \in \mathbb{N}$, there exists rational and meromorphic transcendental maps with preperiodic Fatou components of connectivity n by means of a quasiconformal surgery procedure. Later on, Qiao and Gao [16], and Stiemer [20] provided explicit examples of families of rational maps with such dynamical properties. However, the examples presented in [3], [16] and [20] use an increasing number of critical points. Consequently, the degree of these rational maps grows with n.

In [7] we introduced a family of singularly perturbed Blaschke products (see Equation (3)) whose maps have, under certain dynamical conditions, Fatou components of arbitrarily large finite connectivity (see Theorem 1.1). We also provided numerical evidence showing that parameters satisfying these conditions actually exist. The main goal in this paper is to give a rigorous proof of this fact, that is, to show that this family of perturbations of Blaschke products contains examples of rational maps having Fatou components of arbitrarily large finite connectivity (in the same dynamical plane). To our knowledge, there are no previous examples known to show this phenomenon.

The study of singular perturbations in holomorphic dynamics was introduced by McMullen [13] to prove the existence of Julia sets with buried components, i.e. connected components of $\mathcal{J}(f)$ which do not lie in the boundary of any Fatou component, that are Jordan curves. He considered the singular perturbations of z^n given by

$$Q_{\lambda,n,d}(z) = z^n + \frac{\lambda}{z^d},\tag{1}$$

where $\lambda \in \mathbb{C}^* = \mathbb{C} \setminus \{0\}$ and $n, d \in \mathbb{N}$. These maps have $z = \infty$ as a superattracting fixed point. Moreover, they have n+d critical points which appear symmetrically around the pole z = 0. McMullen showed that, if 1/n + 1/d < 1 and $|\lambda|$ is small enough, then the Julia set consists of a Cantor set of quasicircles. A quasicircle is a Jordan curve which is the image of the unit circle under a quasiconformal map (see e.g. [6]). Devaney, Look and Uminsky [9] studied the Julia sets of the maps $Q_{\lambda,n,d}$ from a more general point of view. They showed that if the critical orbits converge to ∞ then $\mathcal{J}(Q_{\lambda,n,d})$ is either a Cantor set of points, or a Cantor set of quasicircles, or a Sierpinski curve (a homeomorphic image of a Sierpinski carpet). Afterwards, the family $Q_{\lambda,n,d}$ (see e.g. [15], [18], [17]) and singular perturbations of polynomials other than z^d (see e.g. [5] and [11]) have been the object of study of several papers.

In [7] we investigate singular perturbations of the Blaschke products

$$B_a(z) = z^3 \frac{z - a}{1 - \overline{a}z} \tag{2}$$

where $a \in \mathbb{D}^* = \mathbb{D} \setminus \{0\}$. These Blaschke products have z = 0 and $z = \infty$ as superattracting fixed points of local degree 3. Moreover, their Julia set, which is the common boundary of the basins of attraction of z = 0 and $z = \infty$, is given by $\mathcal{J}(B_a) = \mathbb{S}^1$. In this sense, the dynamics of B_a is very similar to the one of the polynomials z^3 . However, the maps B_a have two extra critical points $c_-(a) \in \mathbb{D}$ and $c_+(a) \in \mathbb{C} \setminus \overline{\mathbb{D}}$. We consider the singular perturbations given by

$$B_{a,\lambda}(z) = z^3 \frac{z-a}{1-\overline{a}z} + \frac{\lambda}{z^2}$$
(3)

where $a \in \mathbb{D}^*$ and $\lambda \in \mathbb{C}^*$. These singularly perturbed maps have two critical points $c_-(a,\lambda)$ and $c_+(a,\lambda)$ which are analytic continuation of the ones of B_a . If $|\lambda|$ is small, the dynamics of $B_{a,\lambda}$ is similar to the one of $Q_{\lambda,3,2}$ in a neighbourhood of z=0 and we obtain a McMullen-like Julia set. However, the extra critical point c_- allows the maps $B_{a,\lambda}$ to have richer dynamics than the maps $Q_{\lambda,3,2}$. The main theorem in [7] describes the connectivity of the Fatou components of $B_{a,\lambda}$ in the case that $|\lambda|$ is small enough and $c_-(a,\lambda)$ belongs to the basin of attraction of $z=\infty$, $A_{a,\lambda}(\infty)$. We denote the immediate basin of attraction of ∞ , i.e. the connected component of $A_{a,\lambda}(\infty)$ which contains ∞ , by $A_{a,\lambda}^*(\infty)$. We denote by \mathbb{D}_R the disk centred at 0 with radius R and by \mathbb{D}_R^* the punctured disk $\mathbb{D}_R \setminus \{0\}$.

Theorem 1.1 ([7, Theorem A]). Fix $a \in \mathbb{D}^*$. Then, there exists a constant C(a) such that if $\lambda \in \mathbb{D}^*_{C(a)}$ and $c_-(a,\lambda) \in A_{a,\lambda}(\infty)$, then $c_-(a,\lambda)$ belongs to a connected component U_c of $A_{a,\lambda}(\infty) \setminus A^*_{a,\lambda}(\infty)$ and exactly one of the following holds.

- a) The Fatou component U_c is simply connected. All Fatou components of $B_{a,\lambda}$ have connectivity 1 or 2. (see Figure 1 (a) and (b)).
- b) The Fatou component U_c is multiply connected and does not surround z = 0. All Fatou components of $B_{a,\lambda}$ have connectivity 1, 2 or 3. (see Figure 1 (c) and (d)).
- c) The Fatou component U_c is multiply connected and surrounds z = 0. All Fatou components of $B_{a,\lambda}$ have finite connectivity but there are components of arbitrarily large connectivity. (see Figure 1 (e) and (f)).

It follows from Theorem 1.1 that there may be parameters for which the maps $B_{a,\lambda}$ have Fatou components of arbitrarily large finite connectivity (within a single dynamical plane). The main goal of this paper is to prove the existence of parameters $(a,\lambda) \in \mathbb{D}^* \times \mathbb{C}^*$ such that $|\lambda| < \mathcal{C}(a)$ and $c_-(a,\lambda) \in A_{a,\lambda}(\infty)$, realizing each of the three statements of Theorem 1.1. This is the content of Theorem A.

Theorem A. There exists parameters $(a_i, \lambda_i) \in \mathbb{D}^* \times \mathbb{C}^*$, i = 1, 2, 3, such that $|\lambda_i| < C(a_i)$, $c_-(a_i, \lambda_i) \in A_{a_i, \lambda_i}(\infty)$, and each of the following hold.

- a) All Fatou components of B_{a_1,λ_1} have connectivity 1 or 2.
- b) All Fatou components of B_{a_2,λ_2} have connectivity 1, 2 or 3.
- c) All Fatou components of B_{a_3,λ_3} have finite connectivity but there are components of arbitrarily large connectivity.

The rational maps $B_{a,\lambda}$ have 7 free critical orbits which are not related by any kind of symmetry. Because of this, it is very difficult to investigate the parameter space of $B_{a,\lambda}$ from a global point of view. However, if $\lambda \in \mathbb{D}_{C(a)}^*$ then all critical points but, maybe, $c_-(a,\lambda)$ belong to the basin of attraction of ∞ (see Theorem 2.2). Hence, for fixed $a_0 \in \mathbb{D}^*$, we can draw the parameter plane of $B_{a_0,\lambda}$ for $|\lambda|$ small using the orbit of $c_-(a_0,\lambda)$ (see Figure 2). These numerical experiments show annular hyperbolic components of parameters which surround $\lambda = 0$ and accumulate on it (see Figure 2 (left)). These hyperbolic components correspond to parameters for which statement c) of Theorem A holds. In our next result, Theorem B, we show that there are multiply connected hyperbolic components which surround $\lambda = 0$ and accumulate on it. We conjecture that these hyperbolic components are annuli.

Theorem B. For fixed $a \in \mathbb{D}^*$, there are multiply connected hyperbolic components which surround $\lambda = 0$ and accumulate on it. The corresponding maps $B_{a,\lambda}$ have Fatou components of arbitrarily large finite connectivity.

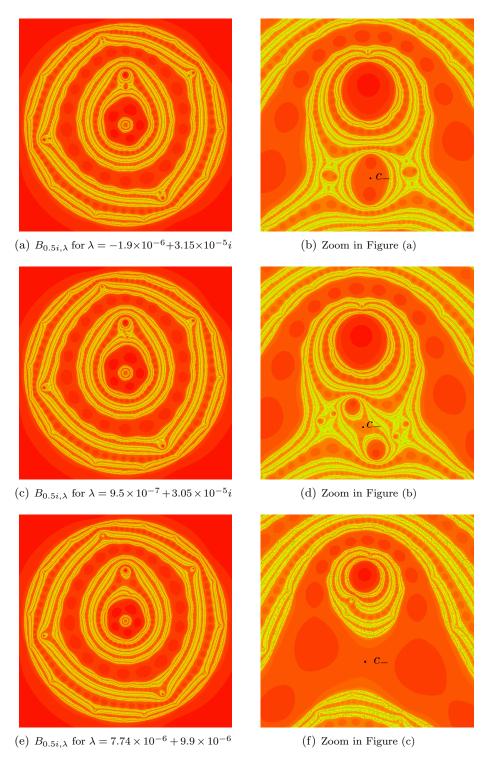


FIGURE 1. Dynamical planes of 3 maps $B_{a,\lambda}$ with a=0.5i for which the 3 statements of Theorem 1.1 hold. We use a scaling from yellow to red to plot the basin of attraction of $z=\infty$. We may observe an approximation of the Julia set in yellow.

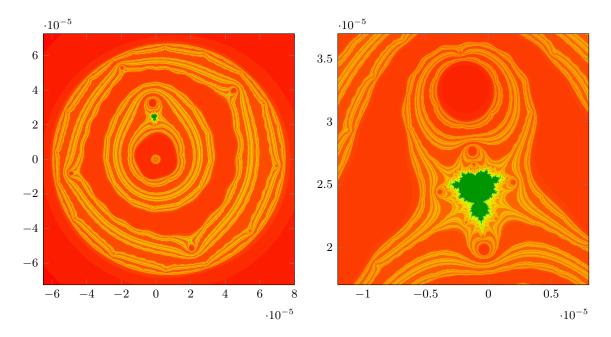


FIGURE 2. Parameter plane of $B_{a,\lambda}$ for a=0.5i fixed. The x-axis corresponds to $\operatorname{Re}(\lambda)$ and the y-axis to $\operatorname{Im}(\lambda)$. The parameters for the left figure corresponds to $\operatorname{Re}(\lambda) \in (-6.5 \times 10^{-5}, 8 \times 10^{-5})$ and $\operatorname{Im}(\lambda) \in (-7.25 \times 10^{-5}, 7.25 \times 10^{-5})$. The right figure is a zoom in the left one. Colours are as follows. We use a scaling from yellow to red to draw the parameters for which $c_- \in A(\infty)$ and green for $c_- \notin A(\infty)$.

These numerical experiments also show simply connected hyperbolic components which correspond to parameters for which statement a) of Theorem A holds. They are surrounded by annular hyperbolic components which correspond to parameters for which statement b) of Theorem A holds (see Figure 2 (right)). In Theorem 4.5 we prove that any parameter λ for which statement a) holds is surrounded by multiply connected hyperbolic components of parameters for which statement b) holds.

The paper is structured as follows. In Section 2 we introduce the main dynamical properties of the maps $B_{a,\lambda}$. Afterwards, in Section 3 we study the dynamics of the preimages of the annular Fatou component which contains the 5 critical points and zeros which appear after the singular perturbation, and analyse their dependence on λ . Finally, in Section 4 we prove Theorem A and Theorem B.

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2. Preliminaries on the dynamics of the singular perturbations

The goal of this section is to describe the dynamics of the singularly perturbed Blaschke products $B_{a,\lambda}(z)$ (Equation (3)). We introduce the results proven in [7] which are used along the paper. We first explain the dynamics of the unperturbed Blaschke products

$$B_a(z) = z^3 \frac{z - a}{1 - \overline{a}z}$$

for $a \in \mathbb{D}^*$. The maps B_a have z = 0 and $z = \infty$ as superattracting fixed points of local degree 3. If $a \in \mathbb{D}^*$, then they have a single zero, $z_0(a) = a \in \mathbb{D}^*$, and a single pole $z_{\infty}(a) = 1/\overline{a} \in \mathbb{C} \setminus \mathbb{D}$. Consequently, if $a \in \mathbb{D}^*$ the unit disk is invariant. Therefore, the basin of attraction of $z = \infty$ is $A_a(\infty) = \widehat{\mathbb{C}} \setminus \overline{\mathbb{D}}$ and the basin of attraction of z = 0 is $A_a(0) = \mathbb{D}$. Moreover, the maps B_a have two free critical points $c_+(a) \in \mathbb{C} \setminus \mathbb{D}$ and $c_-(a) \in \mathbb{D}^*$ given by

$$c_{\pm}(a) := a \cdot \frac{1}{3|a|^2} \left(2 + |a|^2 \pm \sqrt{(|a|^2 - 4)(|a|^2 - 1)} \right).$$

We refer to [8] for a more detailed introduction to the dynamics of the Blaschke products B_a . After the singular perturbation, the previously described critical points, zero and pole move continuously with respect to λ . We obtain from them the critical points $c_{\pm}(a,\lambda)$, the zero $z_0(a,\lambda)$ and the pole $z_{\infty}(a,\lambda)=1/\overline{a}$ of the maps $B_{a,\lambda}$. The point $z=\infty$ is a permanent superattracting fixed point of $B_{a,\lambda}$ of local degree 3 for all λ and, therefore, it is a double critical point. We denote by $A_{a,\lambda}(\infty)$ its basin of attraction and by $A_{a,\lambda}^*(\infty)$ its immediate basin of attraction, i.e. the connected component of $A_{a,\lambda}(\infty)$ which contains $z=\infty$. On the other hand, the point z=0 becomes a double preimage of $z=\infty$ after the singular perturbation. Hence, it is a simple critical point.

So far we have described the position of 5 critical points and one zero of the maps $B_{a,\lambda}$, which have degree 6. However, every rational map of degree 6 has $2 \cdot 6 - 2 = 10$ critical points and 6 preimages of z = 0. The following proposition describes how the remaining 5 critical points and zeros appear in an almost symmetrical position around z = 0 after the singular perturbation.

Proposition 2.1 ([7, Proposition 2.3]). If we fix $a \in \mathbb{D}^*$, then $B_{a,\lambda}(z)$ has 5 zeros of the form $\xi(\lambda/a)^{1/5} + o(\lambda^{1/5})$, where ξ denotes a fifth root of the unity and $o(\lambda^{1/5})$ is such that $\lim_{\lambda \to 0} |o(\lambda^{1/5})|/|\lambda^{1/5}| = 0$. Moreover, $B_{a,\lambda}(z)$ has 5 critical points of $B_{a,\lambda}(z)$ of the form $-\xi(2\lambda/3a)^{1/5} + o(\lambda^{1/5})$.

We are particularly interested on the dynamics of the maps $B_{a,\lambda}$ for small parameters λ . The following theorem describes their dynamics near z=0 and in the immediate basin of attraction of $z=\infty$ (see Figure 3).

Theorem 2.2 ([7, Theorem 2.5]). Fix $a \in \mathbb{D}^*$. Then, there is a constant C(a) such that if $\lambda \in \mathbb{D}^*_{C(a)}$ the following hold.

- a) The immediate basin of attraction of ∞ , $A_{a,\lambda}^*(\infty)$, is simply connected and $\partial A_{a,\lambda}^*(\infty)$ is a quasicircle. Moreover, $A_{a,\lambda}^*(\infty)$ is mapped with degree 4 onto itself and contains only a pole z_{∞} and a critical point $c_{+}(a,\lambda)$ other than the superattracting fixed point $z=\infty$.
- b) There is a simply connected Fatou component $T_0(a, \lambda)$ which contains z = 0 and is mapped 2 to 1 onto $A_{a,\lambda}^*(\infty)$.
- c) There is an annular Fatou component $A_0(a,\lambda)$ which contains 5 critical points and 5 preimages of z=0 and is mapped 5 to 1 onto $T_0(a,\lambda)$.
- d) The annular region in between $A_0(a,\lambda)$ and $A_{a,\lambda}^*(\infty)$ contains a critical point $c_-(a,\lambda)$ and a zero $z_0(a,\lambda)$. Moreover, the connected component $D_0(a,\lambda)$ of $B_{a,\lambda}^{-1}(T_0(a,\lambda))$ in which

 $z_0(a,\lambda)$ lies is simply connected and is mapped with degree 1 onto $T_0(a,\lambda)$. Consequently, it does not contain the critical point $c_-(a,\lambda)$.

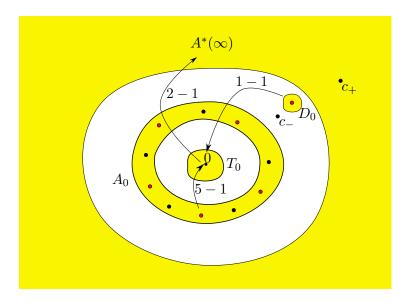


FIGURE 3. Summary of the dynamics described in Theorem 2.2. We draw in red the preimages of zero and in black the critical points.

Whenever it is clear from the context, we drop the dependence on the parameters a and λ of the different sets and points introduced in Theorem 2.2. It follows from this theorem that if $\lambda \in \mathbb{D}_{C(a)}^*$, where $\mathcal{C}(a)$ depends on a, then the dynamics of the maps $B_{a,\lambda}$ is essentially unicritical: all critical orbits but, maybe, the orbit of the point c_- accumulate on the superattracting fixed point $z = \infty$. Since z = 0 is the only pole outside $A^*(\infty)$, we have that if a point w belongs to $A(\infty) \setminus \{A^*(\infty) \cup T_0\}$, then w is eventually mapped under iteration of $B_{a,\lambda}$ into the the annular domain A_0 or the disk D_0 . In Lemma 2.4 we show how the connectivity of a Fatou component U depends on whether U is eventually mapped onto A_0 or D_0 . In the proof of Lemma 2.4 we use the Riemann-Hurwitz formula (c.f. [14, 19]), which can be stated as follows.

Theorem 2.3 (Riemann-Hurwitz formula). Let U and V be two connected domains of $\widehat{\mathbb{C}}$ of finite connectivity m_U and m_V and let $f: U \to V$ be a degree k proper map branched over r critical points counted with multiplicity. Then

$$m_U - 2 = k(m_V - 2) + r.$$

Lemma 2.4. Fix $a \in \mathbb{D}^*$ and $\lambda \in \mathbb{D}^*_{C(a)}$. Let $U \subset A(\infty)$ be a Fatou component of $B_{a,\lambda}$ other than $A^*(\infty)$, T_0 , A_0 , or D_0 . Then, exactly one of the following holds.

- The set U is simply connected and is eventually mapped under iteration onto D_0 .
- The set U is multiply connected and is eventually mapped under iteration onto A_0 . If c_- belongs to U, then U is triply connected. Moreover, if U surrounds z=0 then $B_{a,\lambda}(U)$ also does.

Proof. The Fatou component U is eventually mapped under iteration onto D_0 or A_0 since those are the only preimages of T_0 , and T_0 is the only preimage of $A^*(\infty)$ other than itself.

It follows from the Riemann-Hurwitz formula (see Theorem 2.3) that at least two critical points are required to map a multiply connected domain onto a simply connected domain. Since D_0 is simply connected and c_- is the only free critical point, we can conclude that all iterated preimages of D_0 are simply connected.

Assume that U is eventually mapped onto A_0 . Since A_0 has connectivity 2, it follows that U has, at least, connectivity 2 and, hence, it is multiply connected. Indeed, it follows from the Riemann-Hurwitz formula that if a preimage of a doubly connected domain contains no critical point, then it is also doubly connected. Hence, all preimages of A_0 are doubly connected until one of them, say U_c , contains the critical point c_- . It follows again from the Riemann-Hurwitz formula that U_c has connectivity 3. Moreover, it can be proven that if U_c surrounds z = 0, then it has iterated preimages of arbitrarily large connectivity (see [7, Proposition 3.1], c.f. Theorem 1.1).

To finish the proof of the lemma it is enough to show that if U does not surround z = 0, then none of its preimages does. Let Bdd(U) denote the set of all points bounded by U (including U). Then Bdd(U) is a simply connected domain which can contain at most the critical value $B_{a,\lambda}(c_-)$. It follows from the Riemann-Hurwitz formula that all preimages of Bdd(U) are simply connected. Moreover, none of them can contain the point z = 0. Consequently, no preimage of U can surround z = 0.

We finish the preliminaries with the following result. It shows that, if $\lambda \in \mathbb{D}^*_{C(a)}$, then there is a straight annulus inside A_0 . Within the paper [7] this is presented as one of the conditions to obtain the constant $\mathcal{C}(a)$ in the proof of Theorem 2.5. Even if we could avoid using it in this paper, it helps us understand how the annulus A_0 shrinks when λ tends to 0.

Lemma 2.5. Let $a \in \mathbb{D}^*$. If $\lambda \in \mathbb{D}^*_{C(a)}$, then A_0 contains the straight annulus of inner radius $\left(\frac{|\lambda|}{2|a|}\right)^{1/5}$ and outer radius $\left(\frac{2|\lambda|}{|a|}\right)^{1/5}$.

3. Annular dynamics of the singular perturbations

The goal of this section is to study the dynamics of the preimages of the annulus $A_0(a,\lambda)$ (see Theorem 2.2), to analyse how they move when we modify the parameter λ and to label the preimages of $A_0(a,\lambda)$ which surround z=0. To do so we first study how much the singular perturbation changes the dynamics (see Proposition 3.1). Afterwards we study how the maps $B_{a,\lambda}$ act on Jordan curves surrounding z=0 (see Proposition3.3) and analyse the continuity of $\partial A_{a,\lambda}^*(\infty)$ with respect to λ (see Proposition 3.7). Finally, we introduce a labelling of the preimages of $A_0(a,\lambda)$ which is induced by the dynamics of the maps $B_{a,\lambda}$ and allows us to order them depending on their position with respect to z=0 (see Definition 3.13 and Lemma 3.15).

Hereafter we will use the following notation. Given a Jordan curve $\eta \subset \mathbb{C}$, we denote by $\operatorname{Int}(\eta)$ the bounded component of $\mathbb{C} \setminus \eta$ and by $\operatorname{Ext}(\eta)$ the unbounded component of $\mathbb{C} \setminus \eta$. The following proposition tells us that the singular perturbation only modifies significantly the dynamics in the region bounded by the annulus $A_0(a,\lambda)$.

Proposition 3.1. Let $a \in \mathbb{D}^*$ and let $\lambda \in \mathbb{D}^*_{C(a)}$. Then, there exist analytic Jordan curves $\Gamma \subset A_0(a,\lambda)$ and $B_{a,\lambda}(\Gamma) \subset T_0(a,\lambda)$, both of them surrounding z=0, such that the following hold.

- Γ is mapped three-to-one onto $B_{a,\lambda}(\Gamma)$.
- There are a quasiconformal homeomorphism $\Psi: \operatorname{Int}(\partial A_{a,\lambda}^*(\infty)) \to \mathbb{D}$ and a Blaschke product $R_{b,t}(z) = e^{2\pi i t} z^3(z-b)/(1-\bar{b}z)$, where $b \in \mathbb{D}^*$ and $|e^{2\pi i t}| = 1$, such that $\Psi(B_{a,\lambda}(z)) = R_{b,t}(\Psi(z))$ for all z in the open annular domain A_{Γ} bounded by Γ and $\partial A_{a,\lambda}^*(\infty)$.

Proof. The main idea of the proof is to perform a quasiconformal surgery which erases the extra dynamics which appear after the singular perturbation near z = 0 and keeps the dynamics of the Blaschke products within the unbounded region delimited by an analytic curve $\Gamma \subset A_0$. We refer to [1] and [6] for an introduction to quasiconformal mappings and the tools used in quasiconformal surgery.

We first show how to obtain the curve Γ . Let γ be an analytic Jordan curve in the Fatou component T_0 (see Theorem 2.2) such that it surrounds z=0 and the images of all critical points contained in A_0 . Then, the annulus \mathcal{A} bounded by γ and ∂T_0 contains no critical values and all components of $B_{a,\lambda}^{-1}(\mathcal{A})$ are annuli bounded by preimages of γ and ∂T_0 . Since $\partial B_{a,\lambda}^{-1}(T_0)$ consists of three connected components (notice that $\partial B_{a,\lambda}^{-1}(T_0) = \partial D_0 \cup \partial A_0$), we conclude that $\partial B_{a,\lambda}^{-1}(\mathcal{A})$ consists of three annular connected components. Two of them are in A_0 . Since \mathcal{A} does neither contain z=0 nor any critical value, one of the connected components of $\partial B_{a,\lambda}^{-1}(\mathcal{A})$, say \mathcal{A}_o^{-1} , surrounds all critical points and preimages of z=0 in A_0 . The other component of $\partial B_{a,\lambda}^{-1}(\mathcal{A})$ in A_0 , say \mathcal{A}_i^{-1} , does not surround any zero or critical point in A_0 . We denote by γ_i^{-1} and γ_o^{-1} the connected components of $\partial \mathcal{A}_i^{-1}$ and $\partial \mathcal{A}_o^{-1}$ contained in A_0 (see Figure 4). The curves γ_i^{-1} and γ_o^{-1} are mapped under $B_{a,\lambda}$ onto γ . Since γ is an analytic Jordan curve which contains no critical value, the curves γ_i^{-1} and γ_o^{-1} are also analytic Jordan curves.

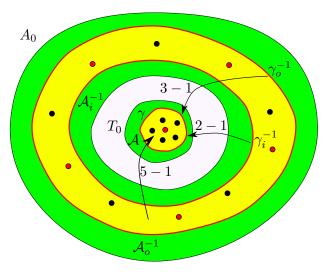


FIGURE 4. Scheme of the dynamics described in the proof of Proposition 3.1. We draw as red dots z = 0 and its preimages in A_0 . We draw as black dots the critical points in A_0 and its images in T_0 .

Now we want to show that γ_o^{-1} is mapped 3 to 1 onto γ . Since A_0 is mapped 5 to 1 onto T_0 (see Theorem 2.2), it is enough to show that γ_i^{-1} is mapped 2 to 1 onto γ . Consider the annulus \mathcal{A}' bounded by ∂T_0 and γ_i^{-1} . It is mapped under $B_{a,\lambda}$ onto the annulus \mathcal{A}'' bounded

by $\partial A^*(\infty)$ and γ . It is not difficult to see that \mathcal{A}' is a connected component of $B_{a,\lambda}^{-1}(\mathcal{A}'')$ and, hence, $B_{a,\lambda}|_{\mathcal{A}'}$ is proper. In particular, $B_{a,\lambda}|_{\mathcal{A}'}$ has a degree k which is also achieved on the boundaries. Since T_0 is mapped onto $A^*(\infty)$ 2 to 1 (see Theorem 2.2), we conclude that this degree is 2 and γ_i^{-1} is mapped 2 to 1 onto γ .

Let $\Gamma := \gamma_o^{-1}$. We have proven that Γ is an analytic Jordan curve which is mapped 3 to 1 onto the analytic Jordan curve γ . Moreover, $\gamma \subset \operatorname{Int}(\Gamma)$. It is an standard procedure of quasiconformal surgery used in complex dynamics to 'glue' z^3 in $\operatorname{Int}(\Gamma)$ under these circumstances (c.f. [6, proof of Theorem 7.4]). We include the details of the surgery construction in sake of completeness.

Pick $0 < \rho < 1$. Let $\mathcal{R} : \operatorname{Int}(\gamma) \to \mathbb{D}_{\rho^3}$ be a Riemann map fixing z = 0. Then, \mathcal{R} extends to the boundary as an analytic map. Indeed, it extends continuously to the boundary by Carathéodory's Theorem. Since γ is an analytic curve, this continuation is analytic (see [6, Thm. 2.9]). Let $\psi_1 : \gamma \to \mathbb{S}^1_{\rho^3}$ be the extension map, where $\mathbb{S}^1_{\rho^3} := \partial \mathbb{D}_{\rho^3}$. Since $\psi_1 \circ B_{a,\lambda} : \Gamma \to \mathbb{S}^1_{\rho^3}$ is an analytic map of degree 3, we can choose a C^1 (or real analytic) lift $\psi_2 : \Gamma \to \mathbb{S}^1_{\rho}$ so that $\psi_1(B_{a,\lambda}(z)) = \psi_2(z)^3$.

Let A be the annulus bounded by γ and Γ and define $\mathbb{A}_{\rho,\rho^3} = \{z; \rho < |z| < \rho^3\}$. Then, there exists a quasiconformal map $\psi : A \to \mathbb{A}_{\rho,\rho^3}$ which extends continuously to $\psi : \overline{A} \to \overline{\mathbb{A}_{\rho,\rho^3}}$ and such that $\psi|_{\Gamma} = \psi_2$ and $\psi|_{\gamma} = \psi_1$ (see e.g. [1] or [6]). Now we define a model map F as

$$F(z) = \begin{cases} B_{a,\lambda}(z) & \text{for} \quad z \in \text{Ext}(\Gamma) \\ \mathcal{R}^{-1} \left(\psi(z)^3 \right) & \text{for} \quad z \in \text{Ext}(\gamma) \setminus \text{Ext}(\Gamma) \\ \mathcal{R}^{-1} \left(\mathcal{R}(z)^3 \right) & \text{for} \quad z \in \text{Int}(\gamma). \end{cases}$$

The map F(z) is quasiregular and has topological degree 4 by construction. Indeed, since A_0 is mapped with degree 5 onto T_0 , $\operatorname{Int}(\Gamma)$ contains 5 preimages of every point of $\operatorname{Int}(\gamma)$. Moreover, since $B_{a,\lambda}|_{\operatorname{Int}(\gamma_i^{-1})}:\operatorname{Int}(\gamma_i^{-1})\to\operatorname{Ext}(\gamma)$ is proper of degree 2 (notice that $T_0\subset\operatorname{Int}(\gamma_i^{-1})$ and $B_{a,\lambda}|_{T_0}$ has degree 2), $\operatorname{Int}(\Gamma)$ contains 2 preimages of every point in $\operatorname{Ext}(\gamma)$ under $B_{a,\lambda}$. Instead, F maps $\operatorname{Int}(\Gamma)$ onto $\operatorname{Int}(\gamma)$ with degree 3. Hence, the surgery construction erases two preimages of every point in $\widehat{\mathbb{C}}$ and we can conclude that F has topological degree 4 since $B_{a,\lambda}$ has degree 6. We continue by defining an F-invariant Beltrami coefficient μ . Observe that F is a holomorphic map everywhere except on the annulus A bounded by γ and Γ . Notice also that the orbit of a point z can go at most once through A. Let $A^n = \{z \mid B_{a,\lambda}^n(z) \in A\}$. Thus, if $\mu_0 \equiv 0$ denotes the Beltrami coefficient of the standard complex structure, we can define

$$\mu(z) = \begin{cases} \psi^* \mu_0(z) & \text{for } z \in A \\ (B_{a,\lambda})^* \mu(z) & \text{for } z \in A^n \setminus A^{n-1} \\ \mu_0(z) & elsewhere, \end{cases}$$

where * denotes the pullback operation. By construction, $F^*\mu = \mu$. Moreover, since $B_{a,\lambda}$ is a holomorphic function and hence preserves dilatation, we have that the dilatation of μ is given by $K_{\mu} = K_{\psi^*\mu_0}$. Thus, μ has bounded dilatation. Let ϕ be an integrating map given by the Measurable Riemann Mapping Theorem (see [2]) fixing z = 0 and $z = \infty$. Then, $\phi^*\mu_0 = \mu$. Define $f = \phi \circ F \circ \phi^{-1}$. By construction, $f^*\mu_0 = \mu_0$. Then, by Weyl's Lemma (see [1, p. 16]),

f is a holomorphic map. Moreover, since F has topological degree 4, we conclude that f is a rational map of degree 4.

Summarizing, with the quasiconformal surgery procedure we have obtained a rational map f such that the following hold.

- The maps $B_{a,\lambda}$ and f are conjugate on $\operatorname{Ext}(\Gamma)$.
- The map f is conjugate to z^3 on $Int(\phi(\gamma))$. In particular, it has z=0 as superattracting fixed point of local degree 3.
- The only pole of f is given by $\phi(z_{\infty})$, where $z_{\infty} = 1/\overline{a}$ is the only pole of $B_{a,\lambda}$ in $\operatorname{Ext}(\Gamma)$. Moreover, $\phi(z_{\infty})$ belongs to the basin of attraction of $z = \infty$ under f.

Let $\mathcal{D} = \phi(\mathbb{C}\backslash \overline{A^*(\infty)})$. Then, since f has no pole in \mathcal{D} we conclude that f maps \mathcal{D} onto itself with degree 4 (it is a fully invariant set under f). Consider the Riemann map Φ sending \mathcal{D} onto \mathbb{D} and 0 onto 0. Then $f|_{\mathcal{D}}$ is conjugate to the map $\tilde{f}: \mathbb{D} \to \mathbb{D}$ defined as $\tilde{f} = \Phi \circ f \circ \Phi^{-1}$. Since $f|_D$ has degree 4 and z=0 is a superattracting fixed point of local degree 3, it follows that \tilde{f} is necessarily a Blaschke product of the form $R_{b,t}(z) = e^{2\pi i t} z^3 (z-b)/(1-\bar{b}z)$, where $b \in \mathbb{D} \setminus \{0\}$ and $|e^{2\pi i t}| = 1$ (see [14, Lemma 15.5]). Finally, the quasiconformal map $\Psi := \Phi \circ \phi: \operatorname{Int}(\partial A^*(\infty)) \to \mathbb{D}$ satisfies $\Psi(B_{a,\lambda}(z)) = R_{b,t}(\Psi(z))$ for all z in the annulus A_{Γ} bounded by Γ and $\partial A^*(\infty)$.

Given a Jordan curve γ which surrounds z=0, we want to analyse the structure of $B_{a,\lambda}^{-1}(\gamma)$. This is done in Proposition 3.3, which uses the previous result. Before stating this proposition we introduce notation which is used in the remaining parts of this section.

Definition 3.2. We define $\mathcal{A}_{0,\infty}(a,\lambda)$ to be the annulus bounded by $\partial T_0(a,\lambda)$ and $\partial A_{a,\lambda}^*(\infty)$, $\mathcal{A}_{in}(a,\lambda)$ to be the annulus bounded by ∂T_0 and $\overline{A_0(a,\lambda)}$, and $\mathcal{A}_{out}(a,\lambda)$ to be the annulus bounded by $\overline{A_0(a,\lambda)}$ and $\partial A_{a,\lambda}^*(\infty)$.

As before, we should drop the dependence on a and λ of the annulus introduced in Definition 3.2 whenever it is clear from the context. In Figure 3, \mathcal{A}_{in} corresponds to the interior white annulus, while \mathcal{A}_{out} corresponds to the union of the exterior white region together with the yellow disk D_0 .

Proposition 3.3. Let γ be a Jordan curve which surrounds z = 0 and is contained in the annulus $A_{0,\infty}$. Then $B_{a,\lambda}^{-1}(\gamma)$ has a connected component contained in A_{in} which is a Jordan curve that surrounds z = 0 and is mapped 2-1 onto γ . The other connected components of $B_{a,\lambda}^{-1}(\gamma)$ belong to A_{out} and exactly one of the following holds.

- If $B_{a,\lambda}(c_-) \in \text{Int}(\gamma)$, then $B_{a,\lambda}^{-1}(\gamma)$ has a single connected component in \mathcal{A}_{out} , which is a Jordan curve that surrounds z = 0 and is mapped 4-1 onto γ .
- If $B_{a,\lambda}(c_-) \in \gamma$, then $B_{a,\lambda}^{-1}(\gamma)$ has a single connected component in \mathcal{A}_{out} , which consists of the union of 2 Jordan curves which intersect at the critical point c_- . One of them surrounds z=0 and is mapped 3-1 onto γ . The other one surrounds the zero z_0 but not z=0 and is mapped 1-1 onto γ .
- If $B_{a,\lambda}(c_-) \in \operatorname{Ext}(\gamma)$, then $B_{a,\lambda}^{-1}(\gamma)$ has two disjoint connected components in \mathcal{A}_{out} , which are Jordan curves. One of them surrounds z=0 and is mapped 3-1 onto γ . The other one surrounds the zero z_0 but not z=0 and is mapped 1-1 onto γ .

Proof. Given that $B_{a,\lambda}(A_0) = T_0$ and $B_{a,\lambda}(T_0) = A^*(\infty)$, we have $B_{a,\lambda}^{-1}(\mathcal{A}_{0,\infty}) \subset \mathcal{A}_{in} \cup \mathcal{A}_{out}$. We first analyse the set $B_{a,\lambda}^{-1}(\gamma)$ in \mathcal{A}_{in} . Since there is no zero and no pole in \mathcal{A}_{in} , we have that \mathcal{A}_{in} is mapped onto $\mathcal{A}_{0,\infty}$ under $B_{a,\lambda}$. Moreover, $B_{a,\lambda}|_{\mathcal{A}_{in}}$ is proper of degree 2 since $B_{a,\lambda}|_{\partial T_0}$ has degree 2. A connected component γ' of $B_{a,\lambda}^{-1}(\gamma)$ in \mathcal{A}_{in} surrounds z=0. Otherwise, since there is no zero and no pole in \mathcal{A}_{in} , it could not be mapped to a curve surrounding z=0. As before, $B_{a,\lambda}$ is proper of degree 2 on the annulus bounded by ∂T_0 and γ' . In particular, γ' is mapped 2 to 1 onto γ and there is no other connected component of $B_{a,\lambda}^{-1}(\gamma)$ in \mathcal{A}_{in} .

The set \mathcal{A}_{out} belongs to the annular region where the dynamics of $B_{a,\lambda}$ is conjugate to the dynamics of a Blaschke product of the form $R_{b,t}(z) = e^{2\pi i t} z^3 (z-b)/(1-\bar{b}z)$, where $b \in \mathbb{D}^* = \mathbb{D} \setminus \{0\}$ and $|e^{2\pi i t}| = 1$, as in Proposition 3.1. Hence, to finish the proof of the result it is enough to prove that the last three statements of the proposition hold for $R_{b,t}$ in \mathbb{D}^* .

The Blaschke products $R_{b,t}$ map the unit disk \mathbb{D} into itself. Since $b \in \mathbb{D}^*$, they have z = 0 as superattracting fixed point of local degree 3, which has \mathbb{D} as its basin of attraction. Moreover, there is a unique non-zero critical point $c_{b,t} \in \mathbb{D}^*$ and a unique zero in \mathbb{D}^* , given by z = b. Notice that the map $R_{b,t}|_{\mathbb{D}}$ has degree 4. Let $\eta \subset \mathbb{D}$ be a Jordan curve surrounding z = 0. Since there is only a critical point, any connected component η' of $R_{b,t}^{-1}(\eta)$ is either a Jordan curve or the union of two Jordan curves which intersect at the critical point. Since $R_{b,t}|_{\mathbb{D}}$ has no poles, any bounded connected component of $\mathbb{C} \setminus \eta'$ is mapped into $\mathrm{Int}(\eta)$. Moreover, exactly one of the three following cases holds.

If $R_{b,t}(c_{b,t}) \in \operatorname{Ext}(\eta)$ then there is a connected component η' of $R_{b,t}^{-1}(\eta)$ which is a Jordan curve that surrounds z = 0 but not the critical point. Then $\operatorname{Int}(\eta')$ is mapped onto $\operatorname{Int}(\eta)$ with degree 3. Consequently, η' is mapped onto η with degree 3. There is an extra preimage η'' which is a Jordan curve that does not surround z = 0, is mapped 1 to 1 onto η and such that $b \in \operatorname{Int}(\eta'')$.

If $R_{b,t}(c_{b,t}) \in \eta$ then $R_{b,t}^{-1}(\eta)$ is the union of two Jordan curves η' and η'' such that $\eta' \cap \eta'' = \{c_{b,t}\}$. As in the previous case we have that $0 \in \text{Int}(\eta')$, that $b \in \text{Int}(\eta'')$, and that η' and η'' are mapped into η with degree 3 and 1, respectively.

If $R_{b,t}(c_{b,t}) \in \operatorname{Int}(\eta)$ then there is a component of $R_{b,t}^{-1}(\eta)$ which surrounds both z=0 and the critical point $c_{b,t}$. If not, there would be two connected components of $R_{b,t}^{-1}(\eta)$, one surrounding z=0 and the other surrounding the critical point. The interior of these connected components would be mapped into $\operatorname{Int}(\eta)$ with degree 3 and 2, respectively, which is not possible since $R_{b,t}|_{\mathbb{D}}$ has degree 4. Let η' be the connected component of $R_{b,t}^{-1}(\eta)$ surrounding z=0 and the critical point. Then, $R_{b,t}|_{\operatorname{Int}(\eta')}$ is a proper map from a simply connected domain onto a simply connected domain with 3 critical points counted with multiplicity (recall that z=0 is a double critical point). It follows from the Riemann-Hurwitz formula (see Theorem 2.3) that $R_{b,t}|_{\operatorname{Int}(\eta')}$ has degree 4. Hence, η' is mapped onto η with degree 4 and there is no other connected component of $R_{b,t}^{-1}(\eta)$.

The following result is a direct corollary of Proposition 3.1. It describes how preimages of $A_0(a,\lambda)$ accumulate on $\partial A_{a,\lambda}^*(\infty)$. It also provides a first ordering in a subset of the Fatou components which are eventually mapped onto $A_0(a,\lambda)$.

Corollary 3.4. Let $a \in \mathbb{D}^*$ and let $\lambda \in \mathbb{D}^*_{\mathcal{C}(a)}$. Then, there is a sequence $\{A_n(a,\lambda)\}_{n\in\mathbb{N}}$ of connected components of $B_{a,\lambda}^{-n}(A_0(a,\lambda))$ such that the following hold.

- Every $A_n(a, \lambda)$ surrounds z = 0.
- For every $n \in \mathbb{N}$, $B_{a,\lambda}(A_n(a,\lambda)) = A_{n-1}(a,\lambda)$ and A_{n-1} is a subset of the bounded connected component of $\widehat{\mathbb{C}} \setminus A_n$ which contains z = 0.
- The sets $A_n(a,\lambda)$ accumulate on $\partial A_{a,\lambda}^*(\infty)$.

Proof. Let $R_{b,t}(z) = e^{2\pi i t} z^3(z-b)/(1-\bar{b}z)$ where $b \in \mathbb{D}^*$ and $|e^{2\pi i t}| = 1$ as in Proposition 3.1. Then, the preimage of any Jordan curve $\eta \subset \mathbb{D} \setminus \{0\}$ surrounding 0 under $R_{b,t}$ has one connected component, say η_{-1} , which also surrounds z = 0. If $\eta \cap \eta_{-1} = \emptyset$ then $\eta \subset \text{Bdd}(\eta_{-1})$, where $\text{Bdd}(\eta_{-1})$ denotes the closed region bounded by η_{-1} (notice that η_{-1} may not be a Jordan curve). Moreover, the iterated preimages of this curve accumulate on \mathbb{S}^1 , which is the boundary of the basin of attraction of z = 0.

We know from Proposition 3.1 that there is a Jordan curve $\Gamma \subset A_0(a,\lambda)$ surrounding z=0 such that $B_{a,\lambda}$ is conjugate to a Blaschke product $R_{b,t}(z)$ on the annular domain A_{Γ} bounded by Γ and $A_{a,\lambda}^*(\infty)$. To finish the proof of the corollary we take a Jordan curve $\zeta_0 \subset A_0(a,\lambda) \cap A_{\Gamma}$ surrounding z=0. By Proposition 3.3, there is exactly one connected component of $B_{a,\lambda}^{-1}(\zeta_0)$, say ζ_1 , which is a curve that surrounds z=0 and is contained in the annular domain $A_{out}(a,\lambda)$ bounded by $\overline{A_0(a,\lambda)}$ and $\partial A_{a,\lambda}^*(\infty)$. The curve ζ_1 belongs to a Fatou component $A_1(a,\lambda)$ that surrounds z=0 and satisfies $B_{a,\lambda}(A_1(a,\lambda))=A_0(a,\lambda)$. In particular, $\zeta_1 \cap \zeta_0 = \emptyset$. Since $A_{out}(a,\lambda) \subset A_{\Gamma}$, we can conclude that $\zeta_0 \subset \operatorname{Bdd}(\zeta_1)$ using the conjugacy Ψ between $B_{a,\lambda}$ and the Blaschke products $R_{b,t}$ (see Proposition 3.1). In particular, the Fatou component $A_1(a,\lambda)$ surrounds $A_0(a,\lambda)$. Repeating the process, we obtain a sequence of curves $\{\zeta_n\}$, $B_{a,\lambda}(\zeta_n) = \zeta_{n-1}$, that surround z=0 and satisfy $\zeta_{n-1} \subset \operatorname{Bdd}(\zeta_n)$. We also obtain a corresponding sequence of Fatou components $\{A_n(a,\lambda)\}$, $B_{a,\lambda}(A_n(a,\lambda)) = A_{n-1}(a,\lambda)$, such that $A_{n-1}(a,\lambda)$ is a subset of the bounded connected component of $\widehat{\mathbb{C}} \setminus A_n(a,\lambda)$ which contains z=0, for all $n\geq 1$. The last claim holds since, again by the conjugacy Ψ , the curves ζ_n accumulate on $\partial A_{a,\lambda}^*(\infty)$.

In Corollary 3.4 we have introduced a sequence of preimages A_n of A_0 with prescribed dynamics. However, it is convenient to label all the preimages of A_0 which surround z = 0. We do this in the next lemma.

Lemma 3.5. Given any finite sequence $\Delta = \{i_0, \dots, i_{p_{\Delta}-1}\}$, where p_{Δ} is a non-zero natural number and $i_n \in \{0,1\}$ for all integer $0 \le n < p_{\Delta}$, there exists a unique Fatou component $A_{\Delta}(a,\lambda)$ which surrounds z = 0, is mapped onto $A_0(a,\lambda)$ in p_{Δ} iterations of $B_{a,\lambda}$ and satisfies the following.

- If $i_n = 0$, then $B^n_{a,\lambda}(A_{\Delta}(a,\lambda)) \subset \mathcal{A}_{out}$. In particular, if $i_0 = 0$ then $A_{\Delta}(a,\lambda) \subset \mathcal{A}_{out}$.
- If $i_n = 1$, then $B_{a,\lambda}^{n}(A_{\Delta}(a,\lambda)) \subset A_{in}$. In particular, if $i_0 = 1$ then $A_{\Delta}(a,\lambda) \subset A_{in}$.

Proof. The result follows directly from Lemma 2.4 and Proposition 3.3. From Lemma 2.4 we know that if U is a Fatou component that surrounds z = 0 then $B_{a,\lambda}(U)$ also surrounds z = 0. Therefore, it is enough to analyse the preimages of any Fatou component surrounding

z=0. From Proposition 3.3 we know that any Fatou component U which surrounds z=0 has exactly two preimages which surround z=0, one in A_{in} and the other in A_{out} .

Remark 3.6. Along the paper we keep the notation $A_n(a,\lambda)$ for the Fatou components introduced in Corollary 3.4. The Fatou component $A_n(a,\lambda)$ corresponds to $A_{\Delta}(a,\lambda)$ where Δ consists of a sequence of n symbols 0. Since we keep the notation A_n , we avoid the confusion between $A_1(a,\lambda) = A_{\{0\}}(a,\lambda) \subset \mathcal{A}_{out}$ and $A_{\{1\}}(a,\lambda) \subset \mathcal{A}_{in}$, or the original annulus $A_0(a,\lambda)$.

Notice that if $c_{-}(a, \lambda) \in U_{c}(a, \lambda)$, where $U_{c}(a, \lambda)$ is a preimage of $A_{0}(a, \lambda)$, then $U_{c}(a, \lambda)$ has connectivity 3 (see Lemma 2.4). If $U_{c}(a, \lambda)$ surrounds z = 0, the subsequent preimages of $U_{c}(a, \lambda)$ which also surround z = 0 have greater connectivity (see [7]). Because of this, when we talk about the sets $A_{\Delta}(a, \lambda)$ we refer to them as multiply connected preimages of A_{0} surrounding z = 0.

The goal of the rest of this section is to study how the Fatou components $A_{\Delta}(a,\lambda)$ depend on the parameters. It will be convenient to denote them keeping their dependence with respect to a and λ . Since their boundaries are eventually mapped under iteration onto $\partial A_{a,\lambda}^*(\infty)$, we first analyse how this set depends on λ . It follows from Proposition 3.7 that $\partial A_{a,\lambda}^*(\infty)$ depends continuously on λ . This proposition uses the theory of \mathcal{J} -stable rational maps (see [12]) applied to polynomial-like maps (see [10]), to obtain a result which is much stronger than we actually need. However, we decided to include it since, by using [10, Proposition 10], the proof of the result is not very technical.

Proposition 3.7. Let $a \in \mathbb{D}^*$. Then, for all $\lambda_0 \in \mathbb{D}_{\mathcal{C}(a)}$, there exist a neighbourhood Λ of λ_0 , a neighbourhood W of $\partial A_{a,\lambda_0}^*(\infty)$ and a map $\tau_a(\lambda,z)$, $\tau_a: \Lambda \times W \to \widehat{\mathbb{C}}$, such that the following hold.

- $\tau_a(\lambda, z)$ is holomorphic in λ and quasiconformal on z.
- For fixed $\lambda' \in \Lambda$, the set $\tau_a(\lambda', W)$ is an open neighbourhood of $\partial A_{a,\lambda'}^*(\infty)$ and $\tau_a(\lambda',\cdot): W \to \tau_a(\lambda',W)$ is a homeomorphism. Moreover, $\tau_a(\lambda_0,z)$ is the identity map on W.
- For all $\lambda \in \Lambda$ and all $z \in W$ we have $B_{a,\lambda}(\tau_a(\lambda,z)) = \tau_a(\lambda, B_{a,\lambda_0}(z))$.

In particular, $\tau_a(\lambda, \partial A_{a,\lambda_0}^*(\infty)) = \partial A_{a,\lambda}^*(\infty)$ and $\tau_a(\lambda, z)$ conjugates B_{a,λ_0} and $B_{a,\lambda}$ on $\partial A_{a,\lambda_0}^*(\infty)$, for all $\lambda \in \Lambda$.

Proof. The idea of this proof is to build a holomorphic family of polynomial-like mappings for which the dynamics on $A_{a,\lambda}^*(\infty)$ is preserved. A polynomial-like map is a triple $\{f,U,V\}$ where U and V are simply connected domains bounded by analytic curves, U is compactly contained in V, and $f:U\to V$ is holomorphic and proper of a given degree k (see [10]). The filled Julia set \mathcal{K}_f of a polynomial-like map is defined as the set of points which never escape U under iteration of f, i.e. $\mathcal{K}_f = \{z \in U \mid f^n(z) \in U \ \forall n \in \mathbb{N}\}$. Its Julia set is defined as $\mathcal{J}_f = \partial \mathcal{K}_f$.

We begin by building a family of polynomial-like mappings $\{f_{\lambda}, U_{\lambda}, V\}$ depending holomorphically on λ and such that $\mathcal{J}_{f_{\lambda}} = \partial A_{a,\lambda}^*(\infty)$. Fix $\lambda_0 \in \mathbb{D}_{\mathcal{C}(a)}^*$. By Corollary 3.4, we know that there are multiply connected Fatou components $A_n(a, \lambda_0)$ which accumulate on $\partial A_{a,\lambda_0}^*(\infty)$ and surround z = 0. Hence, we can fix n such that $A_n(a,\lambda_0)$ surrounds z = 0 and the critical value $v_-(a,\lambda_0) = B_{a,\lambda_0}(c_-(a,\lambda_0))$. We can take an analytic Jordan curve $\gamma \subset A_n(a,\lambda_0)$ surrounding z = 0 and the critical value $v_-(a,\lambda_0)$. By proposition 3.3 we know

that there is a preimage $\gamma_{\lambda_0}^{-1} \subset A_{n+1}(a,\lambda_0)$ of γ which surrounds z=0 and is mapped with degree 4 onto γ . The curve $\gamma_{\lambda_0}^{-1}$ also surrounds the critical point $c_-(a,\lambda_0)$.

The triple $\{f_{\lambda_0} = B_{a,\lambda_0}, \operatorname{Ext}(\gamma_{\lambda_0}^{-1}), \operatorname{Ext}(\gamma)\}$ is a polynomial-like map of degree 4. Moreover, we have that $\mathcal{K}_{f_{\lambda_0}} = \overline{A}_{a,\lambda_0}^*(\infty)$ and that $\mathcal{J}_{f_{\lambda_0}} = \partial A_{a,\lambda_0}^*(\infty)$. If we fix γ and take λ in a neighbourhood Λ of λ_0 , then there is a connected component γ_{λ}^{-1} of $B_{a,\lambda}^{-1}(\gamma)$ which surrounds z = 0, moves holomorphically with respect to λ and coincides with $\gamma_{\lambda_0}^{-1}$ for $\lambda = \lambda_0$. If the neighbourhood of Λ is small enough, then γ_{λ}^{-1} is an analytic Jordan curve, $\gamma \in \operatorname{Int}(\gamma_{\lambda}^{-1})$, γ_{λ}^{-1} surrounds the critical point $c_{-}(a,\lambda)$ and γ_{λ}^{-1} is mapped onto γ with degree 4 under $B_{a,\lambda}$. Hence, we have a family of polynomial-like maps $\{f_{\lambda} = B_{a,\lambda}, \operatorname{Ext}(\gamma_{\lambda}^{-1}), \operatorname{Ext}(\gamma)\}_{\lambda \in \Lambda}$ which depend holomorphically on λ and such that $\mathcal{J}_{f_{\lambda}} = \partial A_{a,\lambda}^*(\infty)$. Moreover, since the only critical points of $B_{a,\lambda}$ in $\operatorname{Ext}(\gamma_{\lambda}^{-1})$ are $c_{+}(a,\lambda)$ and $z = \infty$ and both of them belong to $A_{a,\lambda}^*(\infty)$, it follows that the family of polynomial-like maps is \mathcal{J} -stable and the claims of the proposition hold for all $\lambda_0 \in \mathbb{D}_{\mathcal{C}(a)}^*$ (see [10, Proposition 10]).

To finish the proof we need to show that the same construction can be made in a neighbourhood of the parameter $\lambda_0 = 0$. To do so, it is enough to find analytic Jordan curves $\gamma, \gamma_0^{-1} \subset \mathbb{D}$ such that γ surrounds z = 0 and the critical value $v_-(a)$, that γ_0^{-1} surrounds z = 0 and the critical point $c_-(a)$ and is mapped with degree 4 onto γ under $B_{a,0} = B_a$, and that $\gamma \subset \text{Int}(\gamma_0^{-1})$. The existence of the curves γ and γ_0^{-1} for B_a is shown in [7, Proposition 2.2]. Using the curve γ we can build a family of \mathcal{J} -stable polynomial-like maps $\{f_{\lambda} = B_{a,\lambda}, \operatorname{Ext}(\gamma_{\lambda}^{-1}), \operatorname{Ext}(\gamma)\}_{\lambda \in \Lambda}$. As before, we conclude that the claims of the proposition hold for all λ in a neighbourhood of $\lambda_0 = 0$.

Remark 3.8. It follows from Proposition 3.7 that the quasicircles $\partial A_{a,\lambda}^*(\infty)$ are continuous deformations of the unit circle $\mathbb{S}^1 = \partial A_{a,0}^*(\infty)$.

Remark 3.9. The conjugacy τ_a introduced in Proposition 3.7 can be extended to a neighbourhood of any connected component of $B_{a,\lambda_0}^{-n}(\partial A_{a,\lambda_0}^*(\infty))$, n>0, that does not contain a precritical point. In particular, any such curve moves continuously with respect to λ .

The next result is a direct corollary of Proposition 3.7. The proof is straightforward using that $\partial A_0(a,\lambda) \subset B_{a,\lambda}^{-2}(\partial A_{a,\lambda}^*(\infty))$ and that there is no critical point on $\partial T_0(a,\lambda) \cup \partial A_0(a,\lambda)$.

Corollary 3.10. The annulus $A_0(a, \lambda)$ moves continuously with respect to λ for all $\lambda \in \mathbb{D}^*_{\mathcal{C}(a)}$. Moreover, for any fixed $n \in \mathbb{N}$, the set $B_{a,\lambda}^{-n}(A_0(a,\lambda))$ moves continuously with respect to λ .

The previous corollary applies to the union of all Fatou components which are mapped under n iterations onto $A_0(a,\lambda)$. However, we have to be more careful when talking about the continuity of a concrete preimage $A(a,\lambda)$ of $A_0(a,\lambda)$ with respect to λ . It follows from the Riemann-Hurwitz formula (see Theorem 2.3) that all preimages of the annulus $A_0(a,\lambda)$ are doubly connected until one of them, say $U_c(a,\lambda)$, contains the critical point $c_-(a,\lambda)$ (compare with the proof of Lemma 2.4). In Lemma 2.4 we show that, if such $U_c(a,\lambda)$ exists, it has connectivity 3. The following proposition describes how is the transition from double to triple connectivity when $c_-(a,\lambda) \in \partial U_c(a,\lambda)$ (see Figure 5).

Proposition 3.11. Assume that there is a preimage $U_c(a, \lambda)$ of the annulus $A_0(a, \lambda)$ such that $c_-(a, \lambda) \in \partial U_c(a, \lambda)$. Then $U_c(a, \lambda)$ is doubly connected and exactly one of the following holds.

- One connected component of $\partial U_c(a,\lambda)$ is a Jordan curve. The other connected component of $\partial U_c(a,\lambda)$ consists of the union of two Jordan curves attached at the critical point $c_-(a,\lambda)$.
- Both connected components of $\partial U_c(a,\lambda)$ are Jordan curves. There is an extra preimage $U'_c(a,\lambda)$ of $A_0(a,\lambda)$ such that $\partial U_c(a,\lambda) \cap \partial U'_c(a,\lambda) = c_-(a,\lambda)$. Moreover, if $U_c(a,\lambda)$ surrounds z=0, then $U'_c(a,\lambda)$ cannot surround z=0.

Proof. Since $c_{-}(a,\lambda)$ is not mapped under iteration into $A_{0}(a,\lambda)$, it follows from the Riemann-Hurwitz formula (see Theorem 2.3) that all preimages of $A_{0}(a,\lambda)$ are doubly connected, and so is $U_{c}(a,\lambda)$. Moreover, all connected components of $\partial B_{a,\lambda}^{-n}(A_{0}(a,\lambda))$ are Jordan curves until we find some n>0 such that $B_{a,\lambda}^{n}(c_{-}(a,\lambda))\in\partial A_{0}(a,\lambda)$. In particular, $\partial B_{a,\lambda}(U_{c}(a,\lambda))$ is the union of two Jordan curves, say β_{1} and β_{2} . We may assume, without lost of generality, that $B_{a,\lambda}(c_{-}(a,\lambda))\in\beta_{1}$. Let β'_{1} and β'_{2} be the connected components of the preimages of β_{1} and β_{2} , respectively, which have no-empty intersection with $\partial U_{c}(a,\lambda)$. Then β'_{1} consists of the union of two Jordan curves which intersect at $c_{-}(a,\lambda)$ while β'_{2} is a Jordan curve. By Proposition 3.3, at most one of the two Jordan curves which form β'_{1} can surround z=0. We conclude that only the two possibilities of the statement can take place.

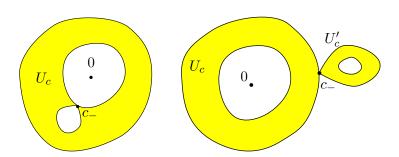


FIGURE 5. Scheme of the two possible configurations for a preimage U_c of A_0 such that $c_- \in \partial U_c$.

Remark 3.12. It follows from the two possible configurations described in Proposition 3.11 that if a preimage $A_{\Delta}(a,\lambda)$ surrounds z=0, then it will permanently surround z=0 when we move the parameter λ . Indeed, the possible problems can only occur when the critical point $c_{-}(a,\lambda)$ crosses it (or an iterated image of it). If we move λ close to a parameter which corresponds to the second case of Proposition 3.11, an extra preimage $A'(a,\lambda)$, which does not surround z=0, may separate from $A_{\Delta}(a,\lambda)$ or merge with it. However, the set $A_{\Delta}(a,\lambda)$ surrounds continuously z=0 when we move λ .

We finish this section investigating the ordering of the sets $A_{\Delta}(a,\lambda)$ as in Lemma 3.5. A sequence Δ denotes a unique multiply connected preimage A_{Δ} of A_0 with dynamics described by Δ . We can establish an order between these sets which relates their sequences and their relative position in the dynamical plane. This ordering is introduced in the following

definition. To simplify notation, it also takes into consideration the case $A_{\Delta} = A_n$ as in Corollary 3.4.

Definition 3.13. We say that $\Delta_1 \prec \Delta_2$ if the Fatou component A_{Δ_2} surrounds A_{Δ_1} . We say that $\Delta \prec n$ (or $n \prec \Delta$) if A_n surrounds A_{Δ} (or if A_{Δ} surrounds A_n). We say that $n \prec m$ if A_m surrounds A_n .

Remark 3.14. From Corollary 3.4 we know that A_{n+1} surrounds A_n . Therefore, $n \prec m$ if and only if n < m.

It follows from Proposition 3.11 that the order introduced in Definition 3.13 is consistent and cannot vary with λ (c.f. Remark 3.12). It can also be proven that it does neither depend on a. We can order the different sequences using their 0's and 1's. The next lemma explains how the number of 0's at the beginning of the sequence influences the order, which is the only thing that we use in this paper (see Theorem 4.3). The general case is more complicated.

Lemma 3.15. Let Δ be a finite sequence of 0's and 1's which contains, at least, one symbol 1. Assume that Δ begins with n_{Δ} symbols 0 followed by a 1 (if $\Delta = \{1, \dots\}$, then $n_{\Delta} = 0$). Then, the following hold.

- If $n_{\Delta} = 0$, then $\Delta \prec 0$. If $n_{\Delta} > 0$, then $n_{\Delta} 1 \prec \Delta \prec n_{\Delta}$.

Proof. Let $\Delta = \{i_0, \dots, i_{p_{\Delta}-1}\}$. If $n_{\Delta} = 0$ then, by definition, $i_0 = 1$ and A_{Δ} belongs to the annulus A_{in} , which is surrounded by A_0 . Hence, we have that $\Delta \prec 0$. Let $\Delta_1 = 0$ $\{0, i_0, \dots, i_{p_{\Delta}-1}\}$, where $i_0 = 1$. Then $n_{\Delta_1} = 1$, $A_{\Delta_1} \subset \mathcal{A}_{out}$, and $B_{a,\lambda}(A_{\Delta_1}) = A_{\Delta}$. Let A be the doubly connected region bounded by bounded by A_0 and A_1 . Then, $B_{a,\lambda}^{-1}(\mathcal{A}_{in}) \cap \mathcal{A}_{out} \subset A$. We can conclude that $A_{\Delta_1} \subset A$ and, hence, $0 \prec \{0, i_0, \cdots, i_{p_{\Delta}-1}\} \prec 1$. Analogously, we can conclude that for any sequence Δ' with $n_{\Delta'} > 0$ we have $n_{\Delta'} - 1 \prec \Delta' \prec n_{\Delta'}$.

4. Escaping dynamics: Proof of Theorems A and B

The goal of this section is to study the case where the critical point c_- belongs to $A(\infty)$, to show that all possibilities described in Theorem 1.1 can take place, and to prove Theorem A and Theorem B. If c_{-} belongs to $A(\infty)$ then it is eventually mapped onto D_0 or A_0 (see Lemma 2.4). If it is eventually mapped into D_0 then it belongs to a simply connected Fatou component and statement a) of Theorem 1.1 holds. On the other hand, if c_{-} is eventually mapped under iteration into A_0 then it belongs to a triply connected Fatou component (see Lemma 2.4), which may surround z=0 or not. Theorem A is a direct corollary of Theorem 4.3, Theorem 4.4, and Theorem 4.5, which establish the existence of parameters for which statements c), a), and b) of Theorem A hold, respectively. Theorem B follows almost directly from Theorem 4.3, which establishes the existence of multiply connected hyperbolic components of parameters λ for which $c_{-}(a,\lambda) \in A_{\Delta}(a,\lambda)$ for every finite sequence Δ of 0's and 1's such that $s \prec \Delta$, where s is a natural number which depends on a. The set $A_{\Delta}(a,\lambda)$ denotes the preimage of $A_0(a,\lambda)$ introduced in Lemma 3.5. Notice that here we consider the order of sequences Δ as in Definition 3.13. Before proving Theorem 4.3, Theorem 4.4 and Theorem 4.5 we introduce the number s.

For fixed $a \in \mathbb{D}^*$, we can associate a natural number $r(a, \lambda)$ to each $\lambda \in \mathbb{D}^*_{\mathcal{C}(a)}$. This number $r(a, \lambda)$ is given by the minimal n such that $c_-(a, \lambda) \in \operatorname{Bdd}(A_n(a, \lambda))$, where $\operatorname{Bdd}(A_n(a, \lambda))$ denotes the open region bounded by $A_n(a, \lambda)$ (including $A_n(a, \lambda)$). Since the $A_n(a, \lambda)$ accumulate on $\partial A^*_{a,\lambda}(\infty)$ (see Corollary 3.4), we know that $r(a,\lambda)$ is finite for all $\lambda \in \mathbb{D}^*_{\mathcal{C}(a)}$.

Definition 4.1. For fixed $a \in \mathbb{D}^*$ and $\lambda \in \mathbb{D}^*_{\mathcal{C}(a)}$, we define $r(a,\lambda)$ as the minimal n such that $c_-(a,\lambda) \in \operatorname{Bdd}(A_n(a,\lambda))$. For fixed $a \in \mathbb{D}^*$ and given $0 < \rho < \mathcal{C}(a)$ we define $s(a,\rho) := \max\{r(a,\lambda) \mid |\lambda| = \rho\}$ and $t(a,\rho) := \min\{r(a,\lambda) \mid |\lambda| \le \rho, \lambda \ne 0\}$.

Notice that $s(a, \rho)$ is well defined and finite since the set of parameters λ such that $|\lambda| = \rho$ is closed. On the other hand $t(a, \rho)$ is well defined since we are taking a minimum on the set of natural numbers.

Lemma 4.2. If $\rho \to 0$, then $s(a, \rho) \to \infty$ and $t(a, \rho) \to \infty$.

Proof. The result follows directly from the fact that, as $\lambda \to 0$, the maps $B_{a,\lambda}(z)$ converge uniformly to $B_a(z)$ (Equation (2)) on compact subsets of $\mathbb{C} \setminus \mathbb{D}_{\epsilon}$, where ϵ is arbitrarily small. Hence, as $\lambda \to 0$ the critical point $c_{-}(a,\lambda)$ of $B_{a,\lambda}$ converges to the critical point $c_{-}(a)$ of B_a . The critical point $c_{-}(a)$ belongs to the boundary of the maximal domain of definition of the Böttcher coordinate of the superattracting fixed point z=0 of B_a (see e.g. [14]). In particular, the orbit of $c_{-}(a)$ converges to z=0 but $B_a^n(c_{-}(a)) \neq 0$ for every natural number n. Moreover, no point of the maximal domain of definition of the Böttcher coordinate is eventually mapped under iteration of B_a onto z=0. It follows from this and the uniform convergence of $B_{a,\lambda}$ to B_a on compact subsets of $\mathbb{C} \setminus \mathbb{D}_{\epsilon}$ that the annulus $A_0(a,\lambda)$ shrinks to z=0 as $\lambda \to 0$. We conclude that, as $\lambda \to 0$, the critical point $c_{-}(a,\lambda)$ requires an increasing number of iterates to be mapped into the region $\operatorname{Bdd}(A_0(a,\lambda))$. Consequently, for all $\epsilon > 0$ there is a natural number $n(\epsilon)$ such that if $|\lambda| \leq \epsilon$ then $r(a,\epsilon) \geq n(\epsilon)$. Moreover, $n(\epsilon) \to \infty$ as $\epsilon \to 0$. This implies that $s(a,\rho)$ and $t(a,\rho)$ converge to ∞ as $\rho \to 0$.

We can now start the proof of Theorem A and Theorem B. Statement c) of Theorem A follows directly from Theorem 4.3. We study the parameters for which the critical point $c_{-}(a,\lambda)$ belongs to a preimage of $A_{0}(a,\lambda)$ surrounding z=0. It follows from Theorem 1.1 that these parameters are precisely the ones for which the singular perturbations $B_{a,\lambda}$ have Fatou components of arbitrarily large finite connectivity. Let $A_{\Delta}(a,\lambda)$ denote the preimage of $A_{0}(a,\lambda)$ surrounding z=0 with dynamics described by the sequence $\Delta=\{i_{0},\cdots,i_{p_{\Delta}-1}\}$ as introduced in Lemma 3.5. We consider the order of sequences Δ introduced in Definition 3.13. By definition of $t(a,\rho)$, there can be no parameter λ with $|\lambda| \leq \rho$ such that $c_{-}(a,\lambda) \in A_{\Delta}(a,\lambda)$ if $\Delta \prec t(a,\rho)$. In the following theorem we prove that if $s(a,\rho) \prec \Delta$ then there is a multiply connected hyperbolic component Ω_{Δ} of parameters such that $c_{-}(a,\lambda) \in A_{\Delta}(a,\lambda)$. Moreover, Ω_{Δ} is contained in the disk of parameters \mathbb{D}_{ρ} .

Theorem 4.3. Let $0 < \rho < C(a)$. Then, for every sequence Δ such that $s(a, \rho) \prec \Delta$, there is a multiply connected hyperbolic component $\Omega_{\Delta} \subset \mathbb{D}_{\rho}^*$ which surrounds the parameter $\lambda = 0$ and such that if $\lambda \in \Omega_{\Delta}$ then $c_{-}(a, \lambda) \in A_{\Delta}(a, \lambda)$.

Proof. Fix $\rho < \mathcal{C}(a)$ and $\lambda \in \mathbb{C}$ with $|\lambda| = \rho$. Let Δ be a finite sequence of 0's and 1's such that $s(a,\rho) \prec \Delta$. By definition of $s(a,\rho)$ we have that $c_{-}(a,\lambda) \in \operatorname{Bdd}(A_{s(a,\rho)}(a,\lambda))$. Moreover, by definition of the ordering of the sequences Δ (see Definition 3.13) we have that the multiply connected domain $A_{\Delta}(a,\lambda)$ is not contained in $\operatorname{Bdd}(A_{s(a,\rho)}(a,\lambda))$. Indeed $A_{\Delta}(a,\lambda)$ surrounds

Bdd($A_{s(a,\rho)}(a,\lambda)$). The idea of the proof is the following. We decrease continuously λ . Then, the set $A_{\Delta}(a,\lambda)$ shrinks with λ , obtaining parameters for which $c_{-}(a,\lambda) \notin Bdd(A_{\Delta}(a,\lambda))$. Finally, by continuity, there is some parameter λ for which $c_{-}(a,\lambda) \in A_{\Delta}(a,\lambda)$.

Let p_{Δ} be such that $B_{a,\lambda}^{p_{\Delta}}(A_{\Delta}(a,\lambda)) = A_0(a,\lambda)$. The arguments that we use are based on the fact $A_{\Delta}(a,\lambda)$ moves continuously with respect to λ except at the parameters for which there is an $n \leq p_{\Delta}$ such that $c_{-}(a,\lambda) \in \partial B_{a,\lambda}^{n}(A_{\Delta}(a,\lambda))$ (see Corollary 3.10, Proposition 3.11 and Remark 3.12). At these parameters, either one of the connected components of the boundary of $A_{\Delta}(a,\lambda)$ is pinched or there are extra connected components of $B_{a,\lambda}^{-p_{\Delta}}(A_0(a,\lambda))$ which share boundary points with $A_{\Delta}(a,\lambda)$ (see Proposition 3.11 and Figure 5). To simplify the arguments it will be convenient to work with a curve surrounding z=0 contained in $A_{\Delta}(a,\lambda)$. The annulus $A_0(a,\lambda)$ moves continuously with respect to λ by Corollary 3.10. Hence, we can take a family of Jordan curves $\gamma_{\lambda} \subset A_0(a,\lambda)$ which surrounds z=0 and depends continuously on λ . Indeed, it follows from Lemma 2.5 that we can take γ_{λ} to be the circle centred at z=0 with radius $\left(\frac{|\lambda|}{|a|}\right)^{1/5}$. Let $\gamma_{\lambda}^{\Delta}$ be the unique connected component of $B_{a,\lambda}^{-p_{\Delta}}(\gamma_{\lambda})$ which surrounds z=0 and is contained in $A_{\Delta}(a,\lambda)$ (see Proposition 3.3). Then, $\gamma_{\lambda}^{\Delta}$ moves continuously with respect to λ except at the parameters λ_n such that there is an n, $0 \le n < p_{\Delta}$, for which $c_{-}(a, \lambda_{n}) \in B_{a, \lambda_{n}}^{n}(\gamma_{\lambda_{n}}^{\Delta})$. However, this is not a problem for the proof. Indeed, the set $B_{a,\lambda}^{-p_{\Delta}}(\gamma_{\lambda})$ moves continuously with respect to λ for all $\lambda \in \mathbb{D}_{\mathcal{C}(a)}^*$. Moreover, if the points z=0 and $c_{-}(a,\lambda_{n})$ belong to the same connected component of $\mathbb{C}\setminus\gamma_{\lambda_{n}}^{\Delta}$, then they belong to the same connected component of $\mathbb{C} \setminus \gamma_{\lambda}^{\Delta}$ for all λ in a neighbourhood of λ_n . In the remaining part of the proof we modify continuously λ to find parameters λ_{Δ} for which $c_{-}(a,\lambda_{\Delta}) \in \gamma_{\lambda_{\Delta}}^{\Delta}$.

If $|\lambda| = \rho$ and $s(a, \rho) \prec \Delta$ then, by definition of $s(a, \rho)$, we have that $c_{-}(a, \lambda)$ belongs to the connected component of $\mathbb{C}\setminus\gamma_{\lambda}^{\Delta}$ which contains z=0. On the other hand, we have by Lemma 4.2 that there is an $\epsilon > 0$ such that $\Delta \prec t(a, \epsilon)$ and, therefore, if $|\lambda| \leq \epsilon$ then $c_{-}(a, \lambda)$ belongs to the unbounded component of $\mathbb{C} \setminus \gamma_{\lambda}^{\Delta}$. The set $B_{a,\lambda}^{-p_{\Delta}}(\gamma_{\lambda})$ depends continuously on λ and contains the curve $\gamma_{\lambda}^{\Delta}$. Moreover, for fixed λ_0 with $|\lambda_0| < C(a)$, we know that if a connected component of $\mathbb{C} \setminus \gamma_{\lambda_0}^{\Delta}$ contains both z=0 and $c_-(a,\lambda_0)$, then for all λ in a neighbourhood of λ_0 we have that a connected component of $\mathbb{C} \setminus \gamma_{\lambda}^{\Delta}$ contains both z=0 and $c_{-}(a,\lambda)$. Since $c_{-}(a,\lambda)$ depends continuously on λ , if we take any continuous path η in the parameter plane joining a parameter λ_{ρ} with $|\lambda_{\rho}| = \rho$ and a parameter λ_{ϵ} with $|\lambda_{\epsilon}| \leq \epsilon$, then there is a parameter $\lambda_{\Delta} \in \eta$ such that $c_{-}(a, \lambda_{\Delta}) \in \gamma_{\lambda_{\Delta}}^{\Delta}$. Let Λ_{Δ} be the set of parameters λ such that $c_{-}(a,\lambda) \in \gamma_{\lambda}^{\Delta}$. Then Λ_{Δ} is closed (its complement is open) and separates the set of parameters λ with $|\lambda| = \rho$ and the set of parameters λ with $|\lambda| \leq \epsilon$. We can conclude that the complement of Λ_{Δ} in the parameter plane is disconnected. Finally, since Λ_{Δ} is a subset of the set of parameters Ω'_{Δ} for which $c_{-}(a,\lambda) \in A_{\Delta}(a,\lambda)$, we conclude that there is (at least) a connected component Ω_{Δ} of Ω'_{Δ} which is multiply connected, is contained in \mathbb{D}_{ρ}^* , and separates $\lambda = 0$ from the set λ with $|\lambda| = \rho$. This finishes the proof of the theorem.

Now we can prove Theorem B. It is a direct corollary of Lemma 4.2 and Theorem 4.3.

Proof of Theorem B. Fix $0 < \rho < C(a)$. Then, it follows from Theorem 4.3 that, for every finite sequence Δ of 0's and 1's as in Lemma 3.5 such that $s(a, \rho) \prec \Delta$, there is a hyperbolic

component Ω_{Δ} which surrounds the parameter $\lambda = 0$, is contained in the disk of parameters λ with $|\lambda| < \rho$, and such that for all $\lambda \in \Omega_{\Delta}$ we have $c_{-}(a,\lambda) \in A_{\Delta}(a,\lambda)$. These hyperbolic components accumulate on $\lambda = 0$ since, by Lemma 4.2, as we decrease ρ to 0 the natural number $s(a,\rho)$ tends to ∞ .

We continue with the proof of the existence of parameters for which statement a) of Theorem 1.1 holds.

Theorem 4.4. Let $a \in (0,1)$. Then there exists $\lambda \in \mathbb{R}^+$, $\lambda < C(a)$, such that $c_- \in A(\infty)$ and $B_{a,\lambda}$ has only Fatou components of connectivity 1 and 2.

Proof. It is enough to prove that, given $a \in (0,1)$, there exists $\lambda \in \mathbb{R}^+$ with $\lambda < \mathcal{C}(a)$ such that $B_{a,\lambda}^n(c_-) \in D_0$ for some n > 1. Then, it follows from the Riemann-Hurwitz formula (see Theorem 2.3) that $c_-(a,\lambda)$ belongs to a simply connected preimage of D_0 and statement a) of Theorem 1.1 holds.

The proof of the result is similar to the one of Theorem 4.3. However, in this case we restrict to real parameters to ensure that c_- is eventually mapped into D_0 . We begin the proof of the result analysing the real dynamics of the maps $B_{a,\lambda}$ for $a \in (0,1)$ and $\lambda \in \mathbb{R}^+$, $\lambda < C(a)$. We focus on the dynamics within the interval $(-\infty, z_{\infty})$, where $z_{\infty} = 1/\overline{a}$ denotes the only pole of $B_{a,\lambda}$ other than z = 0. We have that

$$\lim_{z \to -\infty} B_{a,\lambda}(z) = \lim_{z \to 0^-} B_{a,\lambda}(z) = \lim_{z \to 0^+} B_{a,\lambda}(z) = \lim_{z \to (z_{\infty})^-} B_{a,\lambda}(z) = +\infty.$$

We know from Proposition 2.1 that $B_{a,\lambda}(z)$ has 5 preimages of z=0 of the form $\xi(\lambda/a)^{1/5}+$ $o(\lambda^{1/5})$ and 5 critical points of $B_{a,\lambda}(z)$ of the form $-\xi(2\lambda/3a)^{1/5} + o(\lambda^{1/5})$, where ξ denotes a fifth root of the unity and $o(\lambda^{1/5})$ is such that $\lim_{\lambda\to 0} |o(\lambda^{1/5})|/|\lambda^{1/5}| = 0$. Due to the symmetry with respect to the real line we know that a zero $z_5 = (\lambda/a)^{1/5} + o(\lambda^{1/5}) \in (0, z_{\infty})$ and a critical point $c_5 = -(2\lambda/3a)^{1/5} + o(\lambda^{1/5}) \in (-\infty, 0)$ belong to the real line while the other 4 zeros and critical points which appear near z=0 are in $\mathbb{C}\setminus\mathbb{R}$ for λ small. We can conclude that the map is decreasing in the intervals $(-\infty, c_5)$ and $(0, c_-)$ and increasing in the intervals $(c_5,0)$ and (c_-,z_∞) (see Figure 6). There is no zero in the interval $(-\infty,0)$, while $z_5 \in (0, c_-)$ and $z_0 \in (c_-, z_\infty)$. Moreover, there is a fixed point $x_1(a, \lambda) \in (z_0, z_\infty)$ which comes from analytic continuation of the repelling fixed point $x_1(a) = 1$ of the unperturbed Blaschke products B_a . It follows from the uniform convergence of $B_{a,\lambda}$ to B_a when $\lambda \to 0$ on compact subsets of $\mathbb{C} \setminus \mathbb{D}_{\epsilon}$ that, for λ small enough, the point $x_1(a,\lambda)$ is repelling and is the only fixed point in the segment (c_-, z_∞) since this is also true for the Blaschke products B_a . Moreover, every point in $(c_-, x_1(a, \lambda))$ converges monotonously onto $x_1(a, \lambda)$ under backwards iteration of $B_{a,\lambda}$. Even if it is not necessary to complete the proof of this result, we want to point out that the previous description holds for all λ positive such that $\lambda < \mathcal{C}(a)$. Indeed, in this case it is possible to adapt the construction of Proposition 3.1 so that the conjugation $\Phi \circ \phi$ with a Blaschke product $R_{b,t}$ obtained in the construction preserves the real line.

Now consider the zero $z_0(a,\lambda)$ of $B_{a,\lambda}$. Then, it has a sequence of preimages $z_{-n}(a,\lambda)$ such that $B_{a,\lambda}^n(z_{-n}(a,\lambda)) = z_0(a,\lambda)$ and the $z_{-n}(a,\lambda)$ accumulate monotonically on $x_1(a,\lambda)$. Moreover, as $\lambda \to 0$ the zero $z_0(a,\lambda)$ depends continuously on λ and converges to the zero $z_0(a)$ of B_a . Analogously, its preimages $z_{-n}(a,\lambda)$ depend continuously on λ and converge uniformly onto preimages $z_{-n}(a)$ of $z_0(a)$ under B_a , which accumulate monotonically on the

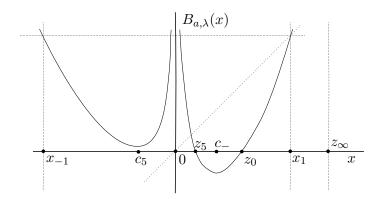


FIGURE 6. Summary of the real dynamics described in Theorem 4.4.

repelling fixed point $x_1(a)$. This allows us to control the sequence $\{z_{-n}(a,\lambda)\}_{n\in\mathbb{N}}$ of preimages of $z_0(a,\lambda)$ as we move continuously λ to 0.

To finish the proof we will find an $m \in \mathbb{N}$ and an interval of parameters $[\Lambda_2, \Lambda_1] \subset \mathbb{R}^+$ such that if $\lambda = \Lambda_2$ then $B_{a,\lambda}^{m+2}(c_-(a,\lambda)) = x_1(a,\lambda)$, if $\lambda = \Lambda_1$ then $B_{a,\lambda}^{m+2}(c_-(a,\lambda)) < x_1(a,\lambda)$ and if $\lambda \in (\Lambda_2, \Lambda_1]$ then $0 < B_{a,\lambda}^{m+2}(c_-(a,\lambda))$. It would then follow from the fact that the points $z_{-n}(a,\lambda)$ accumulate on $x_1(a,\lambda)$ and depend continuously on λ that for some parameters $\lambda \in (\Lambda_2, \Lambda_1)$ (indeed, infinitely many) the point $c_-(a,\lambda)$ is mapped under $B_{a,\lambda}^{m+2}$ onto a preimage $z_{-n}(a,\lambda)$ of z_0 . For these parameters the critical point $c_-(a,\lambda)$ belongs to a simply connected Fatou component which is a preimage of D_0 and we are done.

Before proving this we comment very briefly on the dynamics on the boundary of A_0 and its preimages. It follows from the real dynamics described previously (see Figure 6) that $B_{a,\lambda}(\partial T_0 \cap \mathbb{R}) = x_1(a,\lambda)$. In particular, $\partial A_0 \cap \mathbb{R}$ and all its preimages are also eventually mapped onto $x_1(a,\lambda)$ and move continuously with respect to λ .

Let $\lambda_0 \in \mathbb{R}^+$, $\lambda_0 < \mathcal{C}(a)$. Then, there exists an $m \in \mathbb{N}$ such that $B^m_{a,\lambda_0}(c_-(a,\lambda_0)) \notin A_0(a,\lambda_0)$ and for some $\lambda_m < \lambda_0$ we have $B^m_{a,\lambda_m}(c_-(a,\lambda_m)) \in A_0(a,\lambda_m)$. Indeed, it is enough to consider an m such that the set $A_m(a,\lambda_0)$, as introduced in Corollary 3.4, surrounds $c_-(a,\lambda_0)$. Then we can decrease λ continuously until we find a parameter λ_m such that $c_-(a,\lambda_m) \in A_m(a,\lambda_n)$ as in the proof of Theorem 4.3. We can now take a maximal parameter Λ_2 , $\lambda_m < \Lambda_2 < \lambda_0$, such that if $\lambda = \Lambda_2$ then $c_-(a,\lambda) \in \partial A_m(a,\lambda)$ and, therefore, $B^{m+2}_{a,\Lambda_2}(c_-(a,\Lambda_2)) = x_1(a,\Lambda_2)$.

We now need to find a Λ_1 such that $B_{a,\Lambda_1}^{m+2}(c_-(a,\Lambda_1)) < x_1(a,\Lambda_1)$ and if $\lambda \in (\Lambda_2,\Lambda_1]$ then $0 < B_{a,\lambda}^{m+2}(c_-(a,\lambda))$. Since $0 < B_{a,\Lambda_2}^{m+2}(c_-(a,\Lambda_2))$, to ensure that $0 < B_{a,\lambda}^{m+2}(c_-(a,\lambda))$ if $\lambda \in (\Lambda_2,\Lambda_1]$, it suffices to take Λ_1 close enough to Λ_2 . By Corollary 3.4, we know that the Fatou components $A_n(a,\lambda)$ accumulate on $\partial A_{a,\lambda}^*(\infty)$ as n tends to ∞ . Since $\partial A_m(a,\lambda)$ is mapped under m+2 iterations of $B_{a,\lambda}$ onto $\partial A_{a,\lambda}^*(\infty)$, it follows that $\partial A_m(a,\lambda)$ is the accumulation set of Fatou components $\tilde{A}_{m,n}(a,\lambda)$ which are mapped under m+2 iterations of $B_{a,\lambda}$ onto the $A_n(a,\lambda)$ that accumulate at $\partial A_{a,\lambda}^*(\infty)$. It is enough to take $\Lambda_1 \in (\Lambda_2,\lambda_0)$ close enough to Λ_2 such that $c_-(a,\Lambda_1) \in \tilde{A}_{m,n}(a,\Lambda_1)$, for some $\tilde{A}_{m,n}(a,\lambda)$ (such parameter Λ_1 can be found by using similar arguments to the ones of the proof of Theorem 4.3). It follows that

 $B_{a,\Lambda_1}^{m+2}(c_-(a,\Lambda_1)) \in A_n(a,\Lambda_1)$ for some n>0. We claim that the set of real numbers greater than $x_1(a,\Lambda_1)$ belongs to $A_{a,\Lambda_1}^*(\infty)$ and, therefore, $B_{a,\Lambda_1}^{m+2}(c_-(a,\Lambda_1)) < x_1(a,\Lambda_1)$.

We finish the proof demonstrating the claim. By Theorem 2.2, $\partial A_{a,\Lambda_1}^*(\infty)$ is a Jordan curve. Moreover, since the parameters a and Λ_1 are real, the dynamics of B_{a,Λ_1} are symmetric with respect to \mathbb{R} . It follows that $\partial A_{a,\Lambda_1}^*(\infty)$ is also symmetric with respect to \mathbb{R} and $\partial A_{a,\Lambda_1}^*(\infty) \cap \mathbb{R} = \{x_{-1}(a,\Lambda_1), x_1(a,\Lambda_1)\}$, where $x_{-1}(a,\Lambda_1) < x_1(a,\Lambda_1)$. Therefore, $(-\infty, x_{-1}(a,\Lambda_1)) \cup (x_1(a,\Lambda_1),\infty) \subset A_{a,\Lambda_1}^*(\infty)$.

We finish the proof of Theorem A proving the existence of parameters for which statement b) of Theorem 1.1 holds.

Theorem 4.5. Let $a \in \mathbb{D}^*$ fixed and $\lambda_0 \in \mathbb{D}^*_{\mathcal{C}(a)}$, such that $c_-(a, \lambda_0)$ belongs to an iterated preimage of $D_0(a, \lambda_0)$. Then the parameter λ_0 is surrounded, within $\mathbb{D}_{\mathcal{C}(a)}$, by hyperbolic components of parameters λ for which $c_-(a, \lambda)$ belongs to an iterated preimage of $A_0(a, \lambda)$ which does not surround z = 0. Moreover, if λ_0 is surrounded by a hyperbolic component $\Omega \subset \mathbb{D}_{\mathcal{C}(a)}$, then these hyperbolic components are multiply connected.

Remark 4.6. In Theorem 4.5 we say that λ_0 is surrounded within $\mathbb{D}_{\mathcal{C}(a)}$. By this we mean the following. Let Ω be the hyperbolic component which contains λ_0 and let $\lambda_1 \in \mathbb{D}^*_{\mathcal{C}(a)} \setminus \overline{\Omega}$. Then, there are hyperbolic components Ω' such that any path contained in $\mathbb{D}_{\mathcal{C}(a)}$ which joins λ_0 and λ_1 has non-empty intersection with Ω' .

Remark 4.7. We want to point out that the condition that λ_0 is surrounded by hyperbolic components $\Omega \subset \mathbb{D}_{\mathcal{C}(a)}$ is essentially technical. We conjecture that any such λ_0 is surrounded by a hyperbolic component Ω_{Δ} as in Theorem 4.3 (see Figure 2). This condition is somehow equivalent to the condition $s(a,\rho) \prec \Delta$ of Theorem 4.3. They guarantee that the hyperbolic components are contained in $\mathbb{D}^*_{\mathcal{C}(a)}$. This is important since all proven results depend on the validity of the conclusions of Theorem 2.2, which has as hypothesis $\lambda \in \mathbb{D}^*_{\mathcal{C}(a)}$. We conjecture that doubly connected hyperbolic components Ω_{Δ} accumulate on the boundary of the set of parameters where the conclusions of Theorem 2.2 hold.

Proof of Theorem 4.5. The proof is analogous to the one of Theorem 4.3. Let $a \in \mathbb{D}^*$ and $\lambda_0 \in \mathbb{D}^*_{\mathcal{C}(a)}$ such that $c_-(a,\lambda_0)$ belongs to an iterated preimage $D(a,\lambda_0)$ of $D_0(a,\lambda_0)$. Since it contains a critical point, $D(a,\lambda_0)$ is mapped 2-1 onto its image. In particular, it contains 2 preimages of the zero $z_0(a,\lambda)$, say $w^1(a,\lambda)$ and $w^2(a,\lambda)$. When we move the parameter λ so that $c_-(a,\lambda)$ exits the set $D(a,\lambda)$, this Fatou component continuously splits into the disjoint union of two preimages of $D_0(a,\lambda)$, say $D^1(a,\lambda)$ and $D^2(a,\lambda)$. The sets $D^1(a,\lambda)$ and $D^2(a,\lambda)$ contain $w^1(a,\lambda)$ and $w^2(a,\lambda)$, respectively.

We know from Corollary 3.4 that there are preimages $A_n(a,\lambda_0)$ of $A_0(a,\lambda_0)$ which accumulate on $\partial A_{a,\lambda_0}^*(\infty)$. As a consequence, there are preimages of $A_0(a,\lambda_0)$ which accumulate on any preimage of $\partial A_{a,\lambda_0}^*(\infty)$. In particular, we can take a multiply connected Fatou component $A(a,\lambda_0)$ which surrounds $D(a,\lambda_0)$ but does not surround z=0 (see Figure 7 (left)). Since the free critical point $c_-(a,\lambda_0)$ does not belong to any preimage of $A_0(a,\lambda_0)$, it follows from the Riemann-Hurwitz formula (see Theorem 2.3) that $A(a,\lambda_0)$ is indeed doubly connected (compare with the proof of Lemma 2.4). Let $Bdd(A(a,\lambda_0))$ denote the set of points

bounded by $A(a, \lambda_0)$. Since $\partial D(a, \lambda_0)$ is preperiodic, we may choose $A(a, \lambda_0)$ so that there is no annulus $A'(a, \lambda_0) \subset \operatorname{Bdd}(A(a, \lambda_0))$ such that $B^n_{a,\lambda_0}(A(a, \lambda_0)) = A'(a, \lambda_0)$ for some n > 0.

Let $\gamma_{\lambda} \subset A_0(a,\lambda)$ be any Jordan curve which surrounds z=0 and depends continuously on λ (we can take it since, by Corollary 3.10, $A_0(a,\lambda)$ depends continuously on λ). Then γ_{λ_0} has a unique preimage in $A(a,\lambda_0)$, say γ'_{λ_0} . Moreover γ'_{λ_0} is a Jordan curve. Assume that we can take a closed curve in the parameter plane $\eta:[0,1]\to \mathbb{D}_{\mathcal{C}(a)}$ such that $\eta(0)=\lambda_0$, that $c_-(a,\eta(y))\in \operatorname{Int}(\gamma'_{\eta(y)})$ for all $y\in(0,1)$, and that $c_-(a,\eta(1))\in\gamma'_{\eta(1)}$. It follows from the fact that there is no image of $A'(a,\lambda_0)$ in $\operatorname{Bdd}(A(a,\lambda_0))$ that $\gamma'_{\eta(y)}$ is a Jordan curve which moves continuously with respect to y for all $y\in[0,1)$. At the parameter $\eta(1)$, the curve $\gamma'_{\eta(1)}$ consists of the union of two Jordan curves, γ^1 and γ^2 , which have the common point $c_-(a,\eta(1))$. Each of the curves γ^1 and γ^2 surrounds one of the two Fatou components $D^1(a,\lambda)$ and $D^2(a,\lambda)$ in which the set $D(a,\lambda)$ splits after $c_-(a,\lambda)$ exits it since $B_{a,\lambda}(\operatorname{Int}(\gamma^1)) = B_{a,\lambda}(\operatorname{Int}(\gamma^2))$. Moreover, for all $y\in[0,1]$, the curve $\gamma'_{\eta(y)}$ does not surround z=0. By Lemma 2.4 we know that $A(a,\eta(1))$ is triply connected. The curves γ^1 and γ^2 bound two connected components of $\partial A(a,\eta(1))$. Since they do not surround z=0, the third connected component of $\partial A(a,\eta(1))$ is necessarily a Jordan curve which does not surround z=0. We conclude that $A(a,\eta(1))$ is a triply connected Fatou component which contains the point $c_-(a,\eta(1))$ and does not surround z=0 (see Figure 7 (right), c.f. Figure 1 (d)).

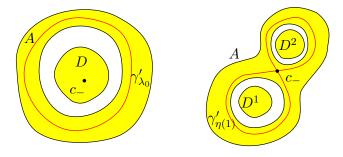


FIGURE 7. Scheme of the situation described in the proof of Theorem 4.5. We draw in red the curve $\gamma_{\eta(y)}^1$ for $\eta(0) = \lambda_0$ (left) and $\eta(1)$ (right).

To finish the proof we need to find the curve of parameters η . Take a parameter λ_{out} such that $c_- \notin \overline{D(a, \lambda_{out})}$ (for example, take λ_{out} in some hyperbolic component Ω_{Δ} as in Theorem 4.3). By redefining the set $A(a, \lambda)$, we may assume that $A(a, \lambda_{out})$ does not bound the critical point $c_-(a, \lambda_{out})$ (notice that, as we move λ continuously, $A(a, \lambda)$ may split into the disjoint union of several Fatou components (c.f. Proposition 3.11)). This may be done by taking $A(a, \lambda)$ so that $A(a, \lambda_{out})$ is sufficiently close to $D(a, \lambda_{out})$. Then, given any curve $\zeta: [0, 1] \to \mathbb{D}_{\mathcal{C}(a)}$ on the parameter plane such that $\zeta(0) = \lambda_0$ and $\zeta(1) = \lambda_{out}$, there is a curve $\eta \subset \zeta$ satisfying the previous conditions. Indeed, since by assumption $A(a, \lambda_0)$ is taken so that there is no annulus $A'(a, \lambda_0) \subset \operatorname{Bdd}(A(a, \lambda_0))$ such that $B_{a,\lambda_0}^n(A(a, \lambda_0)) = A'(a, \lambda_0)$ for some n > 0, the curve γ'_{λ} moves continuously with respect to λ for all λ within the open domain of parameters such that $c_-(a, \lambda) \in \operatorname{Int}(\gamma'_{\lambda})$. Since $\gamma'_{\lambda} \subset A(a, \lambda)$ and for $\lambda_{out} = \zeta(1)$ we have $c_-(a, \lambda_{out}) \notin \operatorname{Bdd}(A(a, \lambda_{out}))$, we can conclude that there is a minimal number $x \in (0, 1)$ such that $c_-(a, \zeta(x)) \in \gamma'_{\zeta(x)}$. It suffices to take $\eta := \zeta([0, x])$.

Finally, following the same reasoning used in the proof of Theorem 4.3, we can conclude that there is a hyperbolic component Ω which surrounds λ_0 in $\mathbb{D}_{\mathcal{C}(a)}$ such that if $\lambda \in \Omega$ then

 $c_{-}(a,\lambda) \in A(a,\lambda)$ and the multiply connected Fatou component $A(a,\lambda)$ does not surround z=0. Moreover, if λ_{out} belongs to a multiply connected hyperbolic component $\Omega_{out} \subset \mathbb{D}_{\mathcal{C}(a)}$ which surrounds λ_0 , then Ω is a multiply connected hyperbolic component which separates Ω_{out} and λ_0 .

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