# A critical analysis of the functional parameters of the quiet eye using immersive virtual reality

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#### Abstract

2 Directing ocular fixations towards a target assists the planning and control of visually-guided 3 actions. In far aiming tasks, the quiet eye, an instance of pre-movement gaze anchoring, has 4 been extensively studied as a key performance variable. However, theories of quiet eye are 5 yet to establish the exact functional role of the location and duration of the fixation. The 6 present work used immersive virtual reality to manipulate key parameters of the quiet eye -7 location (experiment 1) and duration (experiment 2) – to test competing theoretical 8 predictions about their importance. Across two pre-registered experiments, novice 9 participants (n=127) completed a series of golf putts while their eye movements, putting 10 accuracy, and putting kinematics were recorded. In experiment 1, participants' pre-movement 11 fixation was cued to locations on the ball, near the ball, and far from the ball. In experiment 12 2, long and short quiet eye durations were induced using auditory tones as cues to movement 13 phases. Linear mixed effects models indicated that manipulations of location and duration 14 had little effect on performance or movement kinematics. The findings suggest that, for novices, the spatial and temporal parameters of the final fixation may not be critical for 15 movement pre-programming and may instead reflect attentional control or movement 16 17 inhibition functions.

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Keywords: QE; golf putting; gaze; attention; VR; aiming

# **19 Public Significance Statement**

20 Although directing eye gaze on a target before initiating an action toward it appears

21 fundamental to proper execution of the action, it is unclear exactly how eye movements guide

22 aiming actions. This study demonstrates that, for far aiming tasks, variations in the timing

and location of eye movements may be less important than previously thought.

# A critical analysis of the functional parameters of the quiet eye using 24 immersive virtual reality 25 26 **General Introduction** For visually-guided motor skills, the way in which visual attention is deployed, both 27 during and prior to skill execution, is a key determinant of successful execution (Goodale, 28 2011; Land & Hayhoe, 2001; Mann et al., 2007; Neggers & Bekkering, 2002). With 29 30 experience, and through training, experts in visually-guided skills learn to strategically direct their gaze control system to optimise efficient information acquisition and guide accurate 31 goal-directed movement (Land, 2009). One particular visual behaviour - known as the quiet 32 eye (QE; Vickers, 1996, 2007) – has been identified as an important determinant of 33 movement quality and performance outcomes in target and aiming tasks (Lebeau et al., 2016; 34 35 Rienhoff et al., 2016). The QE fixation is the final fixation made to the target location that is initiated prior to movement execution (Vickers, 1996a, 1996b). When throwing a ball, 36 37 shooting a weapon or controlling a surgical instrument a long, stable fixation has been 38 proposed as a critical period for planning and controlling the motor response (Gonzalez et al., 2017; Vickers, 1996a; Williams et al., 2002). Yet, despite numerous studies examining this 39 phenomenon, the exact manner in which the QE fixation provides performance benefits 40 41 remains unclear (Klostermann et al., 2016; Rienhoff et al., 2016; Wilson et al., 2016). The QE fixation is characterised by two key dimensions, the *location* and the *duration* 42

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of the fixation<sup>1</sup>. Definitions of the QE differ slightly across studies but have generally

44 specified that the critical fixation must be directed to the location of the target (within  $1-3^{\circ}$  of

<sup>&</sup>lt;sup>1</sup> The timing of the fixation in relation to movement phases is also relevant, but is less well understood and rather more task specific (Vickers, Causer, & Vanhooren, 2019).

visual angle) and last in excess of 100ms (long enough for visual information to be
consciously processed) (Vickers, 1996a, 2007). The functionality of a long, stable fixation
directed to the target is intuitively appealing, as co-alignment of visual and motor systems in
space simplifies the computational problem of visually-guided movement (Land, 2009;
Neggers & Bekkering, 2002).

50 There has, however, been limited experimental work that has addressed whether the exact location and duration of the fixation are determinants of performance outcome. Two of 51 52 the most prominent theoretical accounts of QE make divergent predictions regarding the importance of the exact location and duration of the final fixation. The *response* 53 54 programming explanation proposes that the QE fixation supports acquisition of visual information to process task parameters and prepare the upcoming movement (Gonzalez et al., 55 2017; Vickers, 1996a; Williams et al., 2002). Consequently, the exact location and duration 56 57 are important for acquiring sufficient visual information from the most informative areas of the visual scene, at the right time. 58

59 By contrast, the attentional control explanation emphasises that the importance of the OE does not primarily lie in its information acquisition role. Instead the OE is thought to be 60 reflective of a visuomotor system that is optimised toward current goals. Vine and Wilson 61 (2011) equate longer OE fixations with governance by a top-down, goal-directed attentional 62 63 system, and describe how longer fixations may help to suppress distractions from bottom-up, salience-driven interruptions (Corbetta & Shulman, 2002). However, under this account, it is 64 not the fixation itself that is driving performance, but attentional processes more generally. 65 66 Maintaining a still fixation on the ball during the putt may just help to avoid distraction while the motor response is being prepared and executed. While a longer QE might be an indicator 67 of better attentional control, it is not the fixation *per se*, but rather the underlying attentional 68



state, that is important for performance. Consequently, the exact location and duration areless important, provided the performer can maintain appropriate attentional control.

71 In a more general sense, the response programming explanation can be characterised as an 'outward-in' explanation, in that the duration and location of the fixation are vital for 72 ongoing visuomotor computations<sup>2</sup> and act as determinants of performance outcomes 73 74 (Gonzalez et al., 2017; Vickers, 1996a; Walters-Symons et al., 2018; Williams et al., 2002). Meanwhile, the attentional control explanation can be characterised as predicting an 'inward-75 out' role, where the QE is merely reflective of the cognitive processes (e.g. good attention 76 control) that are the more direct determinants of performance. If the QE does indeed play a 77 more inward out role, the focus on measuring the final fixation in QE research may actually 78 be missing what really drives the effect (e.g. attentional control/investment more generally). 79

80 While the existence of the QE has been identified in upwards of 30 motor tasks 81 (Vickers, 2016), it is important to consider how the nature of the task may moderate the importance of the timing and location parameters (Wilson et al., 2016). Those 30 tasks can be 82 subdivided along one important dimension; whether they are *self-paced* or *externally-paced*. 83 While, during self-paced tasks, a performer has time to pre-programme an action using a 84 85 series of fixations across a preparation window (Button et al., 2011; Dicks et al., 2017; Vickers & Rodrigues, 2000), spatial and timing parameters may become more critical when 86 actions are under temporal pressure (Miles et al., 2015; Wilson et al., 2016). In the current 87 work we adopt the skill of golf putting, a self-paced task, in order to examine the 88 89 functionality of the location and duration of the QE when there is ample pre-programming 90 time and the fixation is not required to locate the target.

<sup>&</sup>lt;sup>2</sup> Or to facilitate more direct performer-environment relationships in the case of ecological accounts (Oudejans et al., 2005).

#### 91 The present studies

92 Attempts at examining QE mechanisms have, to some extent, been hampered by the practicalities of manipulating the task environment. The use of immersive virtual reality may 93 94 provide a new route for more precise experimental manipulations and improved study of 95 visuomotor skills (Craig, 2013; Zaal & Bootsma, 2011). Previous QE studies have used semi-96 virtual tasks (e.g. targets on a screen; Klostermann et al., 2013; Klostermann & Hossner, 2018) and simulations (e.g. surgical and military simulators; Moore et al., 2014; Wilson et 97 al., 2011), and the current approach builds on this work by adopting a fully immersive, high-98 fidelity virtual reality golf putting simulation (Harris et al., 2019). As all aspects of the virtual 99 100 environment can be tracked, virtual reality also supports the automation of calculating QE 101 duration (e.g. see Kredel et al., 2015), answering calls from some researchers to replace 102 manual coding of gaze with algorithmic approaches (Klostermann et al., 2016). In two 103 studies we aimed to use the experimental control afforded by virtual reality to examine the 104 competing predictions of the response programming and attentional control explanations of QE (and, more broadly, the outward-in versus inward-out role for QE) by manipulating the 105 spatial and temporal parameters of the final fixation. 106

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#### **Experiment 1 - Location**

Models of visually-guided behaviour describe how the repositioning of visual attention precedes a motor action, with the eyes moving to fixate a target prior to acting upon it (Bekkering & Sailer, 2002; Land, 2009). It seems natural that in the golf putt, the ball (the initial target) and the hole (the final target) would then be targets for visual attention prior to the initiation of the swing (Vickers, 2007), with the final fixation on the ball to guide putterball contact. However, for self-paced tasks, like putting, the pre-shot fixation does not need to locate/monitor a moving target, and much of the necessary visual information can be

collected during previews of the ball location during shot preparation (or available via
proprioception in the case of body/putter location) (Button et al., 2011). Indeed, some studies
have shown visual occlusion during the putt to induce only small reductions in putting
accuracy (Aksamit & Husak, 1983; Vine et al., 2017; but see also Causer et al., 2017 who
found larger disruptions as a result of occlusion during the putting action). Therefore, it is
unclear how much additional information is acquired during an extended QE fixation, and
whether a similar level of performance could be achieved by fixations to other locations.

A compelling finding by Mackenzie, Foley and Adamczyk (2011) has suggested that 122 it may even be effective to attend to a location that is nowhere near the ball. Mackenzie and 123 124 colleagues trained participants to focus on either the ball (the initial target) or the hole (the final target) during the putt. Attending to the hole (at a distance of either 1.22 or 4 meters) 125 126 during the putting stroke had no detrimental effect on performance outcomes, no effect on 127 measures of putter-ball contact quality, and even improved putting kinematics by reducing 128 putter speed variability. Similarly, unpublished doctoral work by Lee (2015) details that training participants to attend to either the ball or hole during the putt resulted in no 129 differences in putting outcomes or putting kinematics. These findings suggest that even 130 without peripheral sight of the ball putting performance could be maintained. They are, 131 132 however, still compatible with the response programming explanation, as fixations to the far target could still serve to support movement planning. 133

The variation in the way in which researchers have defined the spatial bounds of the QE, ranging between one (Vine & Wilson, 2010) and three degrees (Behan & Wilson, 2008) of visual angle, also suggests that the exact location may be incidental. QE fixations within 3 degrees of visual angle of the ball equate to ~8cm either side of the ball for an average height adult; a sizeable variation in location. The precision of current mobile eye tracking



(the ball) appear to be effective. This is illustrated, in extremis, in a study by Aksamit and 145 Husak (1983), who found that fixating the ball, the hole or even putting *while blindfolded* had 146 no effect on radial errors. We aimed to not only further examine the role of fixating the hole, 147 148 but also to explore the effect of viewing the ball with the parafovea, by directing fixations close to, but not directly on the ball. While the response programming explanation would 149 suggest that fixation locations away from the target (near or far) would be detrimental, the 150 151 attentional control explanation can account for no performance decrement. Based on the findings of Mackenzie, Foley and Adamczyk (2011) and Lee (2015) it was predicted that QE 152 fixations to locations around the ball, or even to the hole, would have no detrimental effect on 153 putting performance or putting kinematics. 154

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#### Methods

#### 156 **Preregistration**

157 The research question, hypotheses, sampling plan, methods, materials, and statistical 158 analyses were all pre-registered on the Open Science Framework and can be accessed online 159 (<u>https://osf.io/35fgp/</u>). Any additional analyses not present in the preregistration are specified 160 as exploratory.

#### 161 Design

A repeated measures design was used, with participants completing four location conditions in counterbalanced order based on a Latin squares design. The location conditions were: 1) on the ball; 2) above the ball; 3) behind the ball; and 4) on the hole. The primary outcome measure was putting accuracy (radial error in cm), and secondary measures were QE durations (in milliseconds) and putting kinematics (movement of the putter head in x, y and z planes).

### 168 Participants

Eighty (40 female) non-golfers, i.e. novices, were recruited via convenience sampling 169 from the University undergraduate population. A novice population was chosen to enable 170 sufficient statistical power and to avoid the confounding effects of disrupting the well-171 172 established putting routines of expert golfers with the experimental manipulations. Establishing participants as novice golfers was based on having no prior formal golf training 173 or official handicap (as in Moore, Vine, Cooke, et al., 2012). Sample size estimation was 174 calculated using the "SIMR" package for R (Green & MacLeod, 2016). A very small 175 difference, a 10cm change in putting radial error, was selected as the smallest meaningful 176 177 effect of interest. Monte Carlo simulations (n = 1000) of a series of linear mixed effects models with participant as a random factor (and  $\beta = 10.0$ ) were run under scenarios of 178 increasing sample size using SIMR to generate a power curve. Given 20 trials per participant, 179 180 95% power was reached for a sample size of 60 (the R code and the power curve for the analysis is available in the supplementary materials: https://osf.io/35fgp/). Additional 181 participants were recruited to make the sample robust to any potential data loss. Participants 182 183 were provided with details of the study and gave written informed consent on the day of the

testing visit. Ethical approval was granted by the departmental Ethics Committee prior to datacollection.

#### **186** Task and Materials

# 187 VR golf putting

The VR golf putting simulation was developed using the gaming engine Unity 188 189 2019.2.12 (Unity technologies, CA) and C#. The simulation was displayed using the HTC-Vive (HTC, Taiwan), a 6-degrees of freedom, consumer-grade VR-system which allows a 190 360° environment and 110° field of view. The Vive headset includes a Tobii eve-tracker, 191 192 which uses binocular eye tracking at 120Hz over the whole field of view to an accuracy of 0.5-1.1°. Gaze was calibrated in VR over 5 points prior to each block of putts. The Tobii 193 system automatically detected when gaze was directed at the cued location. The accuracy was 194 195 then further checked by the experimenter by asking the participant to fixate on the ball. Data was recorded for offline analysis. Graphics were generated on an HP EliteDesk PC running 196 197 Windows 10, with an Intel i7 processor and Titan V graphics card (NVIDIA Corp., Santa 198 Clara, CA). The VR putter was created and tracked by attaching a Vive sensor to the head of a real golf club. Participants putted from 10ft (3.05m) to a target the same size and shape 199 200 (diameter 10.80cm) as a standard hole. Participants were instructed to land the ball as close as possible to the target, but the ball did not drop into the hole. Auditory feedback mimicking 201 the sound of a club striking a ball was provided concurrent to the visual contact of the club 202 203 head with the ball. The game also featured ambient environmental noise to simulate a realworld golf course and enhance immersion. We have previously demonstrated the construct 204 validity of an earlier version of this task for simulating putting (see Harris et al., 2019 for 205 206 more details of the simulation validation).



Figure 1. The golf putting task (left) and fixation locations on and around the ball (right)

#### 209 Measures

# 210 **Putting performance**

As is typical of most recent quiet eye and targeting tasks (Causer et al., 2017; Horn & Marchetto, 2020; Razeghi et al., 2020; Walters-Symons et al., 2018), performance was assessed using a radial error measure. The distance of the ball from the hole (i.e. the twodimensional Euclidean distance between the centre of the ball and the centre of the target; in cm) was automatically measured by the simulation. Performance was therefore assessed as a continuous measure of accuracy with putts landing on top of the hole assigned an error of zero.

# 218 Quiet eye period

The QE period was operationalised as the final fixation directed toward the ball, prior to the critical movement (Vickers, 2007). The critical movement in this case was defined as the initiation of the clubhead backswing, as in previous work in golf putting (Moore, Vine, Cooke, et al., 2012; Vine & Wilson, 2010). A fixation was defined as a gaze event

maintained on an object within 1° of visual angle for a minimum of 100ms. The QE onset
had to begin before movement initiation, but could continue right through the putting
movement (e.g. as in Causer et al., 2017). QE offset occurred when gaze deviated from the
target (ball or fixation marker) by more than 3° of visual angle, for longer than 100ms
(Moore, Vine, Cooke, et al., 2012; Vickers, 2007). The absence of a QE fixation was scored
as a zero.

An automated method of QE analysis (see Klostermann & Hossner, 2018 and Kredel 229 et al., 2015 for similar approaches) was developed in MATLAB R2018a (Mathsworks, MA), 230 231 which first identified fixations using a spatial dispersion algorithm using the EYEMMV 232 toolbox for MATLAB (Krassanakis et al., 2014). Fixations parameters were set to a minimum duration criterion of 100ms and spatial dispersion of 1° (as recommended in 233 Salvucci & Goldberg, 2000). Identification of the critical movement – the initiation of the 234 235 club swing - was based on x-plane velocity of the Vive tracker, identified using peak 236 detection in MATLAB. The final fixation initiated prior to this event, directed to the location of the target, was selected as the QE fixation (as in previous quiet eye work Causer et al., 237 2017; Vickers, 1996a). The location of gaze in the virtual environment could be determined 238 at all times based on calculating a gaze vector from the known spatial orientation of the head 239 240 and the gaze in head direction, which could be combined with the known position of all objects in the scene. The spatial locations of all objects were recorded on each frame of the 241 simulation, so were timestamped and synchronised. All analysis code is available from the 242 243 OSF: https://osf.io/35fgp/.

# 244 Putting kinematics

Two kinematic variables were calculated to index the quality of the putter
swing/impact (Mackenzie et al., 2011; Mackenzie & Evans, 2010; Moore, Vine, Wilson, et

247 al., 2012). Lower clubhead accelerations during the downswing have previously been linked to putting expertise and clubhead accelerations are frequently used as an indirect measure of 248 motor control in putting studies (Cooke et al., 2012; Moore, Vine, Wilson, et al., 2012). 249 250 Movement of the putter head in x, y, z planes (corresponding to the plane of the swing, the plane perpendicular to the swing, and up and down respectively) was recorded by the virtual 251 environment. Kinematic data was de-noised using a five-point moving-average lowpass filter. 252 253 Then, the velocity of the putter head at the moment of contact with the ball was calculated to 254 index quality of impact, and mean accelerations during the swing were calculated for the x-255 axis (the plane of the downswing).

#### 256 **Procedure**

257 Participants attended the lab for a single visit, which lasted approximately 30 minutes. First, participants had details of the experiment explained to them and they provided written 258 informed consent. Next the experimenter checked that the participant had not experienced 259 VR sickness before, and the participant was fitted with the VR headset. Participants 260 completed 3 familiarisation putts followed by 20 test putts in each condition, in a 261 counterbalanced order. In the 'ball' condition participants were instructed to look at the ball 262 while they executed the putt. In the 'above', 'behind', and 'hole' conditions a blue circle was 263 placed in the scene, which the participant was instructed to fix their gaze on whilst they 264 executed the putt (Figure 1). They were told that they could look wherever they wanted 265 266 whilst they were preparing, but that they must attend to the blue fixation point before and during the putt. To ensure the veracity of the manipulation, only pre-shot fixations directed to 267 268 the instructed location were included in the analysis<sup>3</sup>. In the hole condition the fixation point

<sup>&</sup>lt;sup>3</sup> Of the potential 1600 trials, 25% (SD=3.3, min=0, max=16 per participant) were excluded from the hole condition, 27% (SD=3.7, min=0, max=13) from the behind condition, 24% (SD=3.2, min=0, max=12) in the

was placed on top of the hole. In the above and behind conditions the fixation point was
located 2.5° of visual angle above and behind the ball respectively. This distance was chosen
to make sure that the ball was clearly outside the foveal region but within the parafovea
(Duchowski, 2017). The eye tracker was calibrated over 5 points in the visual scene prior to
each block of putts. Participants were instructed to putt to the best of their ability and land
the ball as close to the hole as possible. After completion of all conditions, participants were
thanked for their participation and debriefed.

# 276 Data Analysis

Data analysis was performed in RStudio v1.0.143 (R Core Team, 2017). Data was 277 first screened for outlying values more than 3 standard deviations from the mean (Tabachnick 278 279 & Fidell, 1996), which were replaced with a Winsorized score by changing the outlying value to a value 1% larger (or smaller) than the next most extreme score. Error and QE data 280 exhibited a positive skew and were transformed for analyses using a square root transform. A 281 linear mixed effects model (LMM) was used to examine the effect of condition (ball, above, 282 behind, hole) on the primary outcome variable, putting radial error, using the lme4 package 283 284 for R (Bates et al., 2014). LMMs were also used to compare QE durations and putting kinematics (putter head velocity at contact, and x-plane accelerations). Most QE research has 285 used averaged scores rather than examining individual trials, so the use of LMMs – which 286 287 use trial level data – enables a more sensitive approach that more accurately models withinparticipant variance (Speelman & McGann, 2013). In order to determine the best fitting 288 model, a maximal model was initially run, with random factors for participants and trial (Barr 289 290 et al., 2013).

ball condition and 28% (SD=3.9, min=0, max=15) in the above condition. In addition to trials where participants did not adhere to the instructions, these exclusions also reflect the removal of trials where there was eye tracking data loss or there was a difficulty with reliably identifying the initiation of the critical movement.

291 Principal Components Analysis was used to identify random factors that contributed to explaining additional variance to avoid overfitting, as described by Bates, Kliegl, Vasishth, 292 and Baayen (2018). The best fitting model in each instance was chosen by simplifying the 293 294 structure in line with the number of principal components. The Akaike information criterion was also used to compare subsequent models and check that the simplified model provided a 295 better fit. While the experiment was powered to find even very small effects, Bayes Factors 296 (using JZS priors) for LMMs were obtained using the BayesFactor package (Morey & 297 Rouder, 2015) in order to provide more informative conclusions about null effects. We report 298 299 BF, which represents the probability of the data under the alternative<sup>4</sup>. All analysis scripts and raw data are available from the Open Science Framework: https://osf.io/35fgp/. 300

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#### Results

#### 302 Performance

303 To examine the effect of location condition on putting performance a linear mixed effects model with a random factor for participant was run. The overall model had a total 304 explanatory power (conditional R<sup>2</sup>) of 13.67%, in which the fixed effects explain 0.18% of 305 306 the variance (marginal  $R^2$ ). The model's intercept is at 0.80 (SE = 0.018, 95% CI [0.76, 0.83]). Within this model the effect of condition was not significant, p=.08,  $n_p^2 = .002$ , BF = 307 0.005 (Figure 2). Even though the fixed effects explained little variance and the BF supported 308 the null, as the main effect did approach significance, we ran pairwise tests (with Bonferroni-309 Holm correction) to check for group differences, but none were significant (ps>.37). 310

<sup>&</sup>lt;sup>4</sup> I.e. values greater than one (>1) indicate the alternative to be the more likely model, while values less than one (<1) indicate the null to be more likely.



Figure 2. Box plot of putting accuracy across location conditions, displaying mean (labelled)
median (black line), standard deviation (σ) and 95% CIs.

# 314 Quiet eye

315 To examine the effect of location condition on QE durations a linear mixed effects model with a random factor for participant was run. The overall model had a total R<sup>2</sup> of 316 317 28.56%, in which the fixed effects explain 2.54% of the variance. The model's intercept is at 21.44 (SE = 0.58, 95% CI [20.29, 22.58]). Within this model the effect of condition is 318 significant, p < .001,  $n_p^2 = .034$ , BF= 5.9\*10<sup>20</sup>. Pairwise comparisons with a Bonferroni-Holm 319 correction indicated that QE durations in the ball and hole conditions were shorter than in the 320 above and behind conditions (all ps<.001). There was no difference between above and 321 behind (p=.07) and between ball and hole (p=.07), as is illustrated in Figure 3. 322



Figure 3. Box plot of QE durations across conditions, displaying mean (labelled) median
(black line), standard deviation (σ) and 95% CIs.

326 To examine the effect of location condition on putter control, linear mixed effects models were run on putting kinematic variables (with participant as a random factor). The 327 overall model predicting putter head velocity at contact had an R<sup>2</sup> of 37.16%, in which the 328 fixed effects explain 0.40% of the variance. The model's intercept is at 4.05 (SE = 0.065, 329 330 95% CI [3.92, 4.18]). Within this model the effect of condition was significant but very small, p < .001,  $n_p^2 = .006$ , BF = 7.04 (see Figure 4). Pairwise comparisons with a 331 332 Bonferroni-Holm correction indicated that putter head velocity for the hole condition was lower than for the above (p = .006) and ball (p = .002) conditions but was not significantly 333 334 different from the behind condition (p = .09). There were no other differences between conditions (ps > .26). 335



Figure 4. Box plot of putter velocity at contact across conditions, displaying mean (labelled),
median (black line), standard deviation (σ) and 95% CIs.

The model predicting x-plane accelerations had an R<sup>2</sup> of 34.74%, in which the fixed effects explain 0.35% of the variance. The model's intercept is at 13.15 (SE = 0.38, 95% CI [12.40, 13.89]). Within this model the effect of condition is significant but very small, p <.001, n<sub>p</sub><sup>2</sup> = .005, BF = 0.09. Even though the effect was very small, paired contrasts were run to examine the significant effect. The comparisons indicated greater accelerations in the above (p = .002) and hole conditions (p < .001) compared to the behind condition. No other comparisons were significantly different (ps > .21).

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#### Discussion

347 The aim of experiment 1 was to examine the importance of QE location in the348 performance of a simulated golf putting task, building on existing work using similar

simulated tasks (Causer et al., 2017; Vickers, 1996a). While the QE is always defined as a
fixation to the target, there has been little evidence to demonstrate that attending to the target
actually confers a functional benefit over other locations. In line with our pre-registered
hypothesis we found that the location of the pre-shot fixation had no effect on putting
performance (supported by a Bayes Factor strongly favouring the null; BF = 0.005),
suggesting that the exact location of the fixation was unimportant; a finding that poses a
challenge for a response programming explanation for this task.

356 Analysis of QE durations suggested that participants made longer fixations when 357 attending to the above and behind locations than on the ball or the hole (see Figure 3). The 358 location manipulation may have induced participants to dissociate their overt attention from the location of the visual fixation, and consequently employed a longer QE to compensate. 359 Similar effects have been observed previously when participants deliberately dissociated their 360 361 gaze from their aiming intention during soccer penalties (Wood et al., 2017). Wood et al. 362 suggest that when participants used a deceptive gaze strategy, longer QE durations were required to cope with the increased processing demands. 363

Analysis of putting kinematics indicated some differences in execution of the putting stroke (e.g. a reduction in putter head velocity at contact for the hole condition) but these changes were very small. Figure 4 also suggests slightly greater variability in contact velocity, possibly because participants had no visual feedback on putter head movement and had to rely on proprioception alone (Volcic & Domini, 2016).

Previous work (Mackenzie et al., 2011) has suggested that training participants to attend to the distant target, during aiming tasks that require contact between an instrument and an object (e.g. in golf putting), does not impair performance. Indeed, in the task of realworld golf putting, some professional golfers (e.g. Jordan Spieth) report using this strategy

for short putts. Here we extend these findings to other locations, not directly on either the near or far target, to demonstrate that a QE close to the ball was as effective as on the ball. However, changes in QE duration might have compensated for the additional difficulty when not fixating the ball directly. We were also able to demonstrate this effect in a much larger sample than most previous work, and with the ability to ensure the veracity of the manipulation using eye tracking. Next we aimed to explore the importance of the other defining feature of the QE, its duration.

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#### **Experiment 2 - Duration**

The rationale for the functional benefit of longer QE (up to a point; see Klostermann, 381 et al., 2018) is based on the discovery of longer durations in experts versus novices and on 382 383 successful versus unsuccessful trials (Vickers, 1996; 2007). A recent meta-analysis has supported the reliability of the expert/novice ( $\overline{d}=1.04, 95\%$  CI [0.04; 2.04]) and 384 successful/unsuccessful ( $\overline{d}$ =.58, 95% CI [-0.07; 1.23]) effects (Lebeau et al., 2016). While 385 386 the response programming explanation suggests that an elongated fixation enables extended task parameterisation (e.g. force and direction), there has been limited direct manipulation of 387 QE duration. Studies that have attempted to manipulate QE duration are somewhat limited by 388 an accompanying uncertainty about target location. Klostermann et al. (2013, 2018) and Sun 389 et al. (2016) have previously manipulated fixation duration by controlling target onset, 390 391 finding shorter QE durations to be detrimental to performance when throwing a ball to a 392 stationary or moving target. In these studies, QE onset was manipulated by delaying the appearance of the target relative to the instructed initiation of the throwing action. The studies 393 394 of Klostermann et al. presented the target at one of four possible locations and Sun et al. 395 occluded the early trajectory of a moving target. However, for these studies, participants in 396 the short QE condition had less time to locate or monitor the position of the target and were

uncertain about target location when planning the action. Klosterman et al. (2013) actually
report that during pilot work the effect of the shorter QE manipulation on performance was
absent when target location was predictable, and uncertainty about final location had to be
added to elicit the effect. In a task when the target location is already known, such as golf
putting, it is unclear whether shorter QE durations would still be detrimental.

402 Initial support for the idea that shorter QE durations may not be detrimental comes from doctoral dissertation data by Lee (2015), which revealed no effect of training long 403 versus short QE durations in a putting task. Participants were trained over 2 days (420 trials) 404 405 to adopt either a long (2500ms) or short (400ms) pre-shot fixation, yet there was no 406 performance difference between the two groups at a retention or a pressure test. Both groups significantly improved their putting performance as a result of training, supporting the idea 407 408 that the benefits of QE training may not be entirely due to longer pre-shot fixations. There are 409 issues with this finding (it was likely underpowered, and the short QE group still maintained 410 a QE of around 1000ms when unconstrained after training), but it provides an indication that when the location of the target is already known there may be little benefit to longer QE 411 durations. 412

To further explore the importance of the QE duration we experimentally manipulated 413 414 the duration of the early QE (before movement initiation) using auditory timing cues (as in 415 Klosterman et al. 2018). We compared putting performance between conditions which allowed for short (400ms) and long (2500ms) pre shot QEs, with a free putting condition, in 416 line with Lee (2015). If the QE plays an outward-in role in supporting motor programming 417 418 (Mann et al., 2011) then longer QE durations should relate to better performance and shortened ones should be detrimental. However, based on an attentional control interpretation 419 420 and Lee's (2015) findings relating to QE training, we suggest that the exact duration of the

421	fixation will not have a major effect on putting accuracy. Similarly, some researchers have
422	suggested that the importance of the QE may lie in its timing, such that only a portion of the
423	fixation is critical, but that longer fixations are maintained 'just in case' (Oudejans et al.,
424	2002). Therefore, our pre-registered hypothesis was that there would be no difference in
425	putting performance between long and short conditions, and that best performance would
426	occur in the free putting condition.
427	Methods
428	Preregistration
429	The research question, hypotheses, sampling plan, methods, materials, and statistical
430	analyses were again pre-registered on the Open Science Framework ( <u>https://osf.io/35fgp/</u> ).
431	Participants
432	Forty-seven novices (15 female) were again recruited from the University
433	undergraduate population, but were an entirely different sample from experiment 1.
434	Participants were provided with details of the study before attending testing and gave written
435	informed consent on the day of the testing visit. Ethical approval was obtained from the
436	departmental Ethics Committee prior to data collection. Sample size estimation was again
437	calculated using the "SIMR" package (Green & MacLeod, 2016) based on a smallest
438	meaningful effect of 10cm. Monte Carlo simulations ( $n = 1000$ ) indicated that, given 20 trials
439	per participant, power of >85% was reached for a sample size of 45 (the power curves are
440	available in the supplementary materials: <u>https://osf.io/35fgp/</u> ).

#### 441 Design

A repeated measures design was used, with participants completing three putting conditions – 1) short QE, 2) long QE, 3) free putting – in a counterbalanced order using a Latin squares design. The primary outcome measure was putting accuracy (radial error in cm), and the secondary measures were putting kinematics (accelerations in the x-plane and velocity at contact). QE durations (in milliseconds) were also calculated as a manipulation check.

448 Task, Materials and Measures

The VR golf putting task and outcome measures were calculated as in Experiment 1.

# 450 **Procedure**

Participants attended testing on one occasion for approximately 30 minutes. After 451 452 having the details of the study explained to them and providing informed consent, they 453 completed the three putting conditions which consisted of 25 putts in each condition. The 454 first five trials were for participants to learn the timing of the beeps and were discarded from the analysis. The participant heard beeps of three different sounds. The first sound indicated 455 456 to look to the hole, the second indicated to look to the ball, and a final (different tone) sound provided the cue to initiate the putt (see Figure 5). Participants were cued to look from the 457 ball to the hole twice over, before returning to the ball and initiating the putt. Adherence to 458 the instructions was constantly monitored by the experimenter. 459

Instruction	L. B	all 2.H	lole 3.B	all 4.H	lole 5. B	all 6.P	utt 7. Lo	ook
Short QE	:	2000	2000	2000	2000	400	500	
Long QE:		2000	2000	2000	2000	2500	500	
	,	Ļ,		, <u>,</u>		, ,	Ļ,	

460

461 Figure 5. Illustration of auditory cues given to participants.

#### 462 Data Analysis

Data analysis was conducted as in Experiment 1, using linear mixed effects models to 463 examine the effect of putting conditions (short, long, free) on performance, QE duration and 464 putting kinematics. Individuals trials were excluded from the baseline (151; 16%), long (87; 465 9%) and short (111; 11%) conditions when there was a loss of eye or head movement 466 467 tracking, or when the critical movement could not be reliably identified. Error and QE data 468 again showed positive skew and were square root transformed for analyses. All analysis scripts and raw data are available from https://osf.io/35fgp/. 469 **Results** 470

# 471 Quiet eye

To ensure the effectiveness of the QE manipulation an LMM was run on QE durations. The overall model predicting QE duration (with random slopes and intercept for participant) had a total explanatory power of 59.78%, in which the fixed effects explain 5.90% of the variance. The model's intercept is at 12.34 (SE = 1.32, 95% CI [9.70, 14.99]). Within this model the effect of condition is significant, p < .001,  $n_p^2 = .018$ , BF =  $1.69*10^{25}$ . As there was clear evidence for an effect of condition, for both frequentist and Bayesian

478 models, pairwise comparisons with Bonferroni-Holm adjustment were run. The comparisons 479 clearly indicated that the long condition produced longer QE fixations than the short (p <480 .001) or free (p < .001) conditions. There was no significant difference between the short and 481 free conditions (p = .69). Consequently, the manipulation was successful at creating a clear 482 difference between long (mean = 529.5ms, sd = 254.0) and short (mean = 261.6ms, sd = 483 245.2) conditions (see Figure 6).



Figure 6. Box plot of participants mean QE durations (in milliseconds), displaying mean
(labelled) median (black line), standard deviation (σ) and 95% CIs.

# 487 Performance

To examine the effect of duration condition on putting accuracy an LMM was run on radial error scores. The overall model predicting putting error (with random slopes and intercept for the factor participant) had a total explanatory power of 22.73%, in which the fixed effects explain just 0.68% of the variance. The model's intercept is at 0.85 (SE = 0.026,

- 492 95% CI [0.80, 0.90]). Within this model the effect of condition is marginally significant but
- 493 very weak, p = .04,  $n_p^2 = .004$ , BF = 0.60 (see Figure 7). As the effect was very weak and the
- 494 Bayes factor supported the null, no further tests were run.



496 Figure 7. Box plot of participants mean radial errors (in cm), displaying mean (labelled)
497 median (black line), standard deviation (σ) and 95% CIs.

#### 498 **Putting kinematics**

To examine the effect of duration condition on putter control an LMM was run on putting kinematics (with random slopes and intercept for the factor participant). The overall model predicting velocity at contact had a total R<sup>2</sup> of 60.56%, in which the fixed effects explain 0.63% of the variance. The model's intercept is at 4.17 (SE = 0.12, 95% CI [3.93, 4.42]). Within this model the effect of condition is not significant and very weak, p = .09,  $n_p^2$ = .003, BF = 0.03.

The overall model predicting x-plane accelerations had an R<sup>2</sup> of 49.35%, in which the fixed effects explain 2.35% of the variance. The model's intercept is at 13.18 (SE = 0.55, 95% CI [12.09, 14.31]). Within this model the effect of conditions was significant but weak, p =.009, n<sub>p</sub><sup>2</sup> = .006, BF = 1.64\*10<sup>6</sup>. Pairwise comparisons indicated that putter accelerations in the downswing were marginally greater in the short compared to the long fixation condition (p =.04), but there were no differences between long and baseline (p = .52) and short and baseline (p = .16).

512

#### Discussion

513 In the QE literature, longer fixations are consistently linked with improved performance outcomes (Klostermann et al., 2018; Lebeau et al., 2016), but it remains to be 514 515 established whether the duration is driving performance effects or is merely reflective of internal processes such as good attentional control. By manipulating the duration of the 516 fixation, we aimed to determine whether the fixation itself is the functional element of the 517 518 QE, or if attentional processes more generally (which can dissociate from gaze) may be more important. The findings here were in line with our pre-registered hypothesis, that there would 519 be no performance differences when participants were manipulated into either a long or short 520 QE. Despite the effect of condition on radial error being marginally significant, the effect was 521 very small (0.4% of the variance) and the Bayes Factor supported the null over the alternative 522 523 (BF = 0.60). Therefore, these results are at odds with the findings of Klostermann et al. 524 (2018) Sun et al. (2016) who both found that manipulations to shorten the quiet eye disrupted performance. As discussed previously, this discrepancy may well be a result of the 525 526 predictability of target location. In contrast to our prediction, participants did not perform any better in the free putting condition, but this may actually support the success of the 527

manipulation, in that the instructions for creating a long or short QE were not in any waydisruptive to normal performance.

530	Analysis of putting kinematics did suggest some small changes as a result of the
531	manipulation. There were no changes in putter head velocity at contact, but compared to the
532	long condition, the short condition induced larger accelerations in the plane of the
533	downswing. Previous work has generally identified lower accelerations during the
534	downswing as a feature of expertise (Cooke et al., 2012; Moore, Vine, Wilson, et al., 2012),
535	so there may have been some slight disruption to the swing in the short condition. However,
536	these were small effects so we should be wary of overinterpretation.
537	While the LMM indicated that the QE manipulation was successful in creating
538	significant differences between the long and short conditions it should be noted that the
539	durations in the long condition (mean = 529.5ms) might still not be considered 'optimal' in
540	the context of those typically taught during QE training (Moore, Vine, Cooke, et al., 2012;
541	Vine & Wilson, 2011). Hence it is possible that the QE was not sufficiently extended as to
542	observe an improvement in performance. However, the differences in analysis method should
543	also be borne in mind. The algorithmic approach used here may be responsible for the shorter
544	durations when compared to manual coding studies; an issue we return to in the general
545	discussion. Still, regardless of the analysis method we would have expected to see some
546	performance differences between long and short groups given an increase in QE duration of
547	more than 200%. The present finding that manipulation of the duration had no effect on
548	putting accuracy certainly raises questions about the functional mechanism of the QE, and the
549	response programming explanation.

550

#### **General Discussion**

551	In the present study we used innovative manipulations made possible by virtual
552	reality, to address a core theoretical assumption of QE theory. Specifically, we aimed to
553	establish whether the exact location and duration of the QE fixation are determinants of
554	performance outcomes, as suggested by outward-in accounts, such as response programming.
555	While much existing work has correlated QE with performance, we adopted experimental
556	manipulations of the spatial and temporal parameters of the fixation to shed light on the exact
557	functional mechanisms by which the QE informs goal-directed actions.
558	Experiment 1 illustrated that performance can be maintained even when the pre-shot
559	fixation is directed to a range of locations. Experiment 2 found that inducing long or short
560	QEs had no effect on performance and minimal effects on control of the putter. While

fixations on the ball (Experiment 1) and longer final fixations (Experiment 2) were 561 descriptively better, in line with the initial predictions of Vickers (1992, 1996a), the effects 562 563 were sufficiently small that they were not statistically meaningful. These results effectively suggest that controlling the two defining features of the QE actually had little impact on skill 564 execution. When considered together, the results do raise questions about the exact functional 565 role of the QE. The present findings suggest that, for a self-paced task at least, a long fixation 566 on the target is not necessary and any stable QE might provide the necessary quiet period of 567 568 motor preparation for fine tuning the timing and coordination of the shot. In the golf putting 569 task much of the visual information required to plan the movement can be processed during the entire 'visual routine' (Ballard & Hayhoe, 2009) of preparing for the putt, making the 570 571 final fixation less important.

572 Evidently the current results pose a challenge for a response programming573 explanation of the QE in self-paced tasks. If variations in location and duration have little

574 effect on performance, then it is unlikely that the primary function of the QE fixation is for gathering information to pre-programme the putt. Electroencephalogram (EEG) measurement 575 has previously linked the QE period with an event-related potential (ERP) over the motor 576 577 cortex believed to indicate movement preparation (i.e. the Bereitschaftspotential; Mann et al., 2011). However increased alpha power in visual cortex during the QE fixation has also been 578 observed in EEG recordings (Gallicchio & Ring, 2019), which suggests reduced or inhibited 579 visual processing. Taken together these findings suggest that while motor preparation may be 580 occurring during the QE, it is not the primary function of the QE to collect visual information 581 582 to enable that programming.

583 Two other explanations of QE are, however, consistent with the present findings. Firstly, an attentional control explanation would suggest that the primary importance of the 584 QE is not for gathering visual information, but that a longer fixation on the target is reflective 585 586 of the wider attentional state of the performer (and may help to maintain that state). From this 587 perspective, the manipulations used here would have little impact on performance, provided the performer maintained a goal-directed focus of attention. Indeed, this is what was 588 observed, manipulations of the parameters of the QE did not affect performance, indicating 589 that they were not a functional element of the QE in this task. The extent to which our 590 591 manipulations served to dissociate overt and covert attention (e.g. attending the ball as well as the cued location) is unknown, but explicit manipulations of covert attention while 592 performers maintain stable overt visual attention could serve to test the attentional control 593 594 explanation and determine whether allocation of (covert) attention is more important than 595 overt gaze.

596 Secondly, the inhibition hypothesis of Klosterman and colleagues proposes that the597 QE duration serves to inhibit the preparation of non-optimal task solutions in favour of the

598 optimal movement variant (Klostermann et al., 2014). The inhibition hypothesis is proposed 599 to explain the 'efficiency paradox' whereby experts display longer QEs, despite expertise being associated with economisation of behaviour and automatization of control. Klosterman 600 601 et al. suggest that experts have a much greater movement repertoire, and hence more suboptimal movement variants requiring inhibition. Consequently, the location of the fixation 602 would have little impact on performance and a short QE might fulfil the inhibition needs of 603 novices; particularly as 'short' QE durations were similar to unconstrained QE here (i.e., free 604 605 putting condition). A replication of the present work with expert performers could serve as a 606 test of the inhibition hypothesis, as experimental shortening of the QE should be much more detrimental in experts. 607

### 608 Limitations

609 In defence of the response programming explanation, it could be argued that the use of novices in the present study – in contrast to those of Sun et al. (2016) and Klosterman et al. 610  $(2013)^5$  – limits the conclusions that can be drawn about QE functionality, as manipulations 611 612 of QE parameters might have a reduced impact in a novice population. For instance, it is reasonable to assume that the motor programme (e.g. Schmidt, 1975), or ability to generate 613 accurate motor predictions from inverse models (e.g. Wolpert & Flanagan, 2001), is not well 614 615 developed in novices. Hence if the benefit of the QE fixation lies in supporting fine tuning of motor commands, variations in location and duration of the QE may have more limited 616 effects in novices who do not have a well-developed motor programme to adjust. Further, it 617 may be the case that a certain amount of experience is needed to extract and make use of the 618 619 relevant pre-shot visual information (as is the case in many areas of visual expertise; Brams

<sup>&</sup>lt;sup>5</sup> Both studies used throwing tasks which are less complex than a golf putt and participants (primarily sports science students) would likely be relatively proficient at this skill.

620 et al., 2019), such that, again, novices may be less affected by the exact location and duration of the QE. Early QE studies examined successful and unsuccessful execution in more skilled 621 populations with a focus on optimal performance, where the effects of the QE may be the 622 623 clearest (Vickers, 1992, 1996a). However, if QE is truly an important perception-action variable that supports information processing, movement preprograming, and coalignment of 624 625 attentional and motor systems (Vickers, 2007) – as opposed to just being an irregularity of high-level performers – then similar effects should also be observable across skill levels. The 626 possibility that the QE has slightly different functions, or just varying degrees of importance, 627 628 in experts and novices means that it is crucial to extend these findings to more experienced performers in future work. 629

As discussed at the outset, these findings may only be relevant for self-paced aiming 630 tasks, as externally-paced interceptive tasks do not permit a series of fixations during the pre-631 632 shot preparation time, and hence may place greater importance on the duration and location of the final fixation. The divergence from the findings of Klosterman et al. (2013; 2018) and 633 Sun et al. (2016) in experiment 2 highlights that specific aspects of the task, like 634 predictability of target location, might also modulate the duration effect. As Wilson et al. 635 (2016) point out, the functional role of the QE may vary considerably across tasks, 636 637 particularly as a function of the pre-programming time available (Horn & Marchetto, 2020). Therefore, it is necessary for future work to replicate the present findings but also to extend 638 639 them to more complex aiming tasks with temporal constraints and more varied task demands. 640 For similar reasons, it may be instructive to examine temporal and spatial manipulations of the portion of QE that occurs during the putt ('online QE'), which may have elevated 641 importance in self-paced tasks. 642

643 While we see this as a strength of the study, rather than a limitation, it is fair for us to highlight the manner in which QE was calculated in the present work, which differs from 644 much of the literature to date (but see Klosterman & Hossner, 2018 for a similar algorithmic 645 646 approach). Here we applied a stricter criterion for identifying the OE. The most common method of calculating the QE 'fixation' has been through manual coding, where the 647 experimenter decides if the gaze cursor in the eye tracking video remains on the target during 648 the critical period and then records the onset and offset. However, what is recorded is not 649 650 really a 'fixation' in the truest sense; it is gaze directed to a particular location. Here we used 651 an algorithmic approach that determined the occurrence of true fixations, based on spatial dispersion of consecutive points of gaze (Krassanakis et al., 2014). The durations of the QE 652 detailed in Experiment 2 would be considered relatively short in the context of previous 653 654 work, and short of the 'ideal' duration. However, this is likely to be a result of the stricter criteria that were used based on identifying a true fixation (e.g. as in Gallicchio et al., 2017; 655 656 Klosterman & Hossner, 2018).

# 657 Conclusions

The current experiments have sought to extend enquiry into the proposed causal role 658 of the QE in supporting performance in the far aiming task of golf putting. We conducted a 659 critical analysis of fundamental tenets of QE theory, finding that the spatial and temporal 660 661 parameters of the fixation may be less important than previously thought; results which favour attentional control and inhibition accounts over response programming in self-paced 662 tasks. A core finding of this work is that it is possible to manipulate gaze without affecting 663 664 performance, which suggests that the core functional benefit of the QE may be dissociable from overt gaze (i.e. an inward-out role). Perhaps close enough (experiment 1) and long 665 enough (experiment 2) is good enough. 666

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