Advanced modelling of runoff and soil redistribution for agricultural systems: the SERT model

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19 Abstract

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Hydrological and soil erosion models allow mapping and quantifying rates of runoff depths 20 21 and soil redistribution for different land uses and climatic scenarios. Mediterranean soils are 22 threatened by marked seasonal changes in the climatic, thus soil and vegetation parameters 23 and modelling predictions at monthly scale are required. The semi-physically-based Soil 24 Erosion and Redistribution Tool (SERT) model is presented together with the results of its 25 application in a Mediterranean agro-ecosystem (NE Spain) with a detailed database. The 26 hydrological module is based on the recently published DR2 (Distributed Rainfall-Runoff) 27 water balance model and the effects of man-made infrastructures on the natural dynamics of runoff connectivity are added. The erosion module is built using, as the basis, the Revised 28 29 Morgan, Morgan and Finney model, and the new Remaining runoff Transport Capacity (TC_r) 30 factor used to estimate the rates of soil loss and deposition. Predicted runoff depth varied in 31 time and space, presenting areas without runoff production mainly in Rendzic Leptosols and Haplic Calcisols between November and April. Average soil erosion was high in cultivated 32 and bare soils, ca. 20 and 10 Mg ha^{-1} yr⁻¹, whereas rangeland soils were affected by moderate 33 and, in some areas, by limited erosion processes. Soil erosion was minimal in February (0.08 34 Mg ha⁻¹ month⁻¹ on average) and 23 times higher in October. The SERT model allowed 35 36 mapping the significant changes in the monthly values of soil redistribution quantifying the 37 variability in the magnitude of the processes involved. Predicted values of average soil loss and deposition were validated against quantified values with ¹³⁷Cs obtaining an average 38

- Nash–Sutcliffe efficiency of 0.48 (Pearson's r = 0.709) and a sediment balance of -1.15 Mg yr⁻¹ for the whole catchment that is consistent with the karst processes of the study area. The new model is an easy-to-run, reliable, low-input-demanding management tool with valuable outputs for hydrological and soil erosion studies in small agricultural catchments.
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Keywords: DR2 model; Cumulative runoff; SERT model; Soil redistribution; Agricultural
 system; ¹³⁷Cs

46

47 **1. Introduction**

48 Soil erosion by water is a widespread problem throughout the world that causes the loss of 49 fertile soil and crop yield in agricultural areas and a reduction in the overall quality and 50 functions of the soils (Pimentel, 2000; Stavi and Lal, 2011). The current average erosion rates 51 are a factor of 12 higher than soil sustainability, on the basis of the average rate of soil 52 formation (Pimentel et al., 1999), and also the social and economic costs of erosion remain 53 high due to the on-site and off-site consequences (e.g. Diao and Sarpong, 2011; Rivera et al., 54 2011). Accurate studies and measurements and sustainable land management are the keys to 55 reduce agricultural soil loss. However, surface runoff, soil detachment and sediment delivery 56 are non-linear processes that depend on many soil, climatic, topographic, vegetation and land 57 use parameters and, furthermore, their effects change when considering different temporal and 58 spatial scales (Cerdà et al., 2013). Hydrologic and soil erosion processes also vary as a 59 function of the conditions prior to a rainfall event (De Baets et al., 2011) and of the magnitude of the erosion process itself (Gonzalez-Hidalgo et al., 2010). Moreover, human activities have 60 61 been transforming the landscape since the first settlements, the creation of agricultural lands 62 and the overexploitation of forests (García-Ruiz, 2010) accelerating and triggering in some places the processes of soil loss and degradation. As a consequence of these activities, 63 64 numerous linear landscape elements (unpaved and paved trails, roads, land levelling, irrigation ditches, stone walls, dams, etc.) appear in landscapes, modifying the patterns of the 65 66 overland flow and sediment connectivity.

Modelling hydrology and soil erosion is a difficult task to perform accurately in terms of time, space and rates due to its great complexity and the many factors involved. Initial attempts were carried out as empirical equations for small or limited areas (e.g. plots, fields and hillslopes). The studies of Mockus (1949) and Andrews (1954) constituted the building blocks of the Soil Conservation Service – runoff Curve Number (*SCS-CN*) (SCS-USDA, 1985) that has been successfully used in many environments and even incorporated in one of

the most ambitious and currently used models, the Soil and Water Assessment Tool (SWAT; 73 74 Arnold et al., 1998). The studies on plots undertaken by Wischmeier and Smith (1958 and 75 **1978**) regarding the relationship between rainfall energy, soil erodibility and soil loss as well 76 as the development of the Universal Soil Loss Equation (USLE), yield the basis for the well-77 known *RUSLE* model (Renard et al., 1991), that has been one of the most studied and most 78 used predictive models for rill and interrill soil erosion by water. An adapted version of the 79 *RUSLE* equation is the *WATEM/SEDEM* (Van Rompaey et al., 2001) model that predicts 80 spatially distributed rates of annual soil loss and deposition at catchment scale and also 81 estimates tillage erosion. Other models have been developed to simulate not only surface runoff and soil erosion processes but also nutrient, pollutant and sediment delivery and 82 deposition processes, such as the *CREAMS* (Kinsel, 1980) and *AGNPS* (Young et al., 1987) 83 84 models.

85 Other available models are the expert-based STREAM (Cerdan et al., 2002) and the distributed split-parameter TETIS (Francés et al., 2007) hydrological models, and the dynamic 86 87 LISEM (De Roo et al., 1995) model of soil erosion. All these models are integrated and run 88 with GIS techniques and in some cases offer the possibility of being downloaded as 89 executable files, as is the case of the empirical RUSLE2 (Foster et al., 2000), the processbased WEPP (Adams et al., 2012), the complex river basin SWAT (Arnold et al., 1998) and 90 91 the reduced-complexity SedNet (Prosser et al., 2001) models at continuous temporal scale, 92 and also the event-based TOPMODEL (Beven et al., 1995) and EUROSEM (Morgan et al., 93 **1998**) models.

94 Previous studies demonstrate that large parts of the world are affected by intense processes 95 of soil degradation and about 10 million ha of cropland are lost each year due to soil erosion, 96 thus reducing the soil available for food production (Pimentel, 2006). In Mediterranean 97 cultivated and set-aside soils the magnitude of erosion rates significantly varies throughout 98 the year and seasons due to changes in the soil, climate and plant phenology (e.g. De Santisteban et al., 2006; López-Vicente et al., 2008 and Fiener et al., 2011). Thus, there is a 99 100 necessity to develop an accurate, adaptable and easy-to-run model to predict spatially 101 distributed values of runoff, soil erosion and redistribution at a monthly scale instead of the 102 commonly used empirical annual-based models or the complex event scale models. In this 103 study we present the Soil Erosion and Redistribution Tool (SERT) model and the results of its 104 application in a small Mediterranean agricultural catchment with a detailed database. Run in a 105 GIS environment, the SERT model predicts average monthly values of runoff production, soil 106 erosion and sediment redistribution. This model has been developed with the aim of coupling

107 the physically-based equations of the DR2 (López-Vicente and Navas, 2012) water balance 108 model, with the structure of the RMMF (Morgan, 2001) and Modified MMF (Morgan and 109 Duzant, 2008) models of soil erosion and sediment delivery, and the conceptual basis of the 110 Index of Connectivity (IC) of Borselli et al. (2008) that includes the role of the man-made 111 infrastructures. The SERT model has been designed to account for the temporal variations in 112 climatic and vegetation parameters and tillage practices that occur throughout the year. Validation procedure is carried out with rates that are quantified with the radionuclide ¹³⁷Cs in 113 114 133 control points. The topography of the study area is controlled by the presence of a 115 sinkhole and thus is a closed-hydrological system where the balance between the amount of 116 soil loss and deposition can be calculated accurately. The SERT model aims to be an accurate, 117 easy-to-run, low-input-demanding management tool of spatially distributed runoff and soil 118 erosion and redistribution for small and medium size agricultural catchments.

119

120 **2. Material and methods**

121 2.1. The SERT model

122 The Soil Erosion and Redistribution Tool (SERT) model is a semi-physically-based approach 123 to predict monthly rates of runoff depth, soil erosion in rill and interrill areas and sediment 124 redistribution in small and medium size catchments. Processes that take place in permanent 125 water courses (e.g., creeks, rivers, ponds, dams) are not considered and thus the SERT model is not suitable for large catchments or river basins. The SERT model divides the simulation 126 127 procedure into four modules: i) hydrology (SERT-Hy), ii) soil erosion (SERT-Er), iii) soil 128 redistribution (SERT-Rd) and iv) modelling validation (SERT-V) (Fig. 1). As the SERT model 129 is run at monthly scale most of its inputs are measured and calculated at monthly scale (Table 1). The SERT model has the conceptual basis and part of the equations of the DR2, RMMF 130 131 and IC models, to which are added water and sediment balance factors to achieve an accurate 132 prediction ability. The other novel aspect of this model, in comparison with other similar 133 models, is the high number of processes that can be simulated with a moderate number of 134 inputs.

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136 2.1.1. The hydrologic module (SERT-Hy)

137 The GIS-based water balance <u>D</u>istributed <u>R</u>ainfall-<u>R</u>unoff (DR2) model (<u>López-Vicente and</u>

Navas, 2012) yields the basis of the hydrological module. The *DR2* model computes the depth
of water stored and infiltrated in the soil profile and the runoff depth considering spatial and

temporal variations in rainfall intensity, soil saturation and upslope contribution factors. This

141 model was run in the medium size Estaña Lakes catchment, where the small study area of this 142 research is located, and it allowed humidity variations and trends in time and space to be monitored. The DR2 model calculates the monthly effective cumulative runoff (CQ_{eff-m} , mm) 143 144 following a three-step procedure. In the first step, the unsaturated cells and cells saturated by 145 direct rainfall (no runoff contribution) are differentiated. Time to ponding, Tp (s), is the time 146 it takes for the soil surface to become saturated in conditions of rainfall intensity greater than the saturated hydraulic conductivity of the topsoil (K_{fs} , cm s⁻¹) and is calculated as the mean 147 value between the minimum and maximum time to ponding, following the approach of 148 149 Hogarth et al. (1991):

150
$$\frac{1}{2} \frac{Sp_{im}^2}{K_{fs}} \ln \left(\frac{I_m}{I_m - K_{fs}} \right) \le Tp_{im} \le \frac{1}{2} \frac{Sp_{im}^2}{I_m - K_{fs}}$$
(1)

151
$$Sp_{im} = \sqrt{2 \cdot \mathbf{A} \theta_{im} \, \mathbf{A}_i} \tag{2}$$

152
$$\Delta \theta_{im} = \theta_{Seff-i} - \theta_{0-im} \tag{3}$$

where Sp is the soil sorptivity (cm s^{-0.5}), I (cm s⁻¹) is the average rainfall intensity, ϕ is the 153 matrix flux potential (cm² s⁻¹) of each soil type, and θ_{Seff} (% vol.) and θ_0 (% vol.) are the 154 155 effective saturated and initial volumetric water content of the soil, respectively. The subscripts 156 *i* and *m* correspond to each cell of the digitalized study area, and each month of the year, 157 respectively. The initial water content is the volume directly measured in the field (antecedent 158 topsoil moisture), the θ_{Seff} parameter accounts for the maximum amount of water that can be stored within the soil taking into account the volume of rocks and $\Delta \theta$ is the difference 159 160 between both values. Coarse fragments play a critical role in the processes of topsoil 161 saturation and initiation of runoff (Smets et al., 2011) and are very frequent in the 162 Mediterranean soils and thus have to be considered in studies of soil redistribution (Soto and 163 Navas, 2008). Once topsoil is saturated overland flow appears and the initial runoff per raster 164 cell, Q_0 (mm), is estimated as a function of the depths of effective rainfall, ER (mm), rainfall to ponding, Rp (mm), and the average number of rainfall events, e (n): 165

$$Q_{0im} = ER_{im} - \langle R p_{im} e_m \rangle = ER_{im} - \langle P_{im} I_m e_m \rangle]0$$
(4)

$$ER_{im} = R_m \left(-A_{im} \right) \cos S_i \tag{5}$$

Values of *ER* are estimated after considering the depth of precipitation intercepted by the canopy of the crops and natural vegetation, A (0–1), from the total rainfall depth, R (mm), and using the improvement presented by Morgan and Duzant (2008) to consider the effect of slope angle, S (radians), on the quantity of rain received per unit area. Once time to ponding

172 and initial runoff are calculated at each sampling point, the corresponding maps for the whole 173 catchment are created with the Kriging interpolation method (ordinary type with constant 174 trend removal) that gets the minimum standard error. In the second step of the DR2 model, 175 initial runoff is routed into the digital elevation model (DEM) of the catchment using the 176 multiple flow accumulation algorithm (Acc. Algorithm_{MD}), with a coefficient of concentration 177 of 0.9 and the potential cumulative runoff, CQ_0 (mm), is obtained. The subscript resol 178 corresponds to the spatial resolution of the DEM because the depth of calculated cumulative 179 runoff also depends on this parameter. In the SERT-Hy module the effect of the man-made 180 linear landscape elements (LLEs) is added as effective players modifying the natural runoff 181 connectivity along the hillslopes and fields. This concept is based on the index of connectivity (*IC*) presented by Borselli et al. (2008) and successfully used by these authors and by others 182 183 (e.g. Cavalli et al., 2012; López-Vicente et al., 2013) in medium-size agricultural and 184 mountainous catchments in Italy and Spain to identify areas with net soil loss and deposition.

185

$$CQ_{0m} = f \left(\mathbf{Q}_{0m}, \text{Acc. Algori thm}_{\text{MD}}^{c=0.9}, LLEs, \text{DEM}_{\text{resol}} \right)$$
 (6)

186 As there are many types of cumulative algorithms, and each type generates a different map 187 with different values, a water balance correction factor (α) is added to achieve that the volume 188 of balanced potential cumulative runoff (CQ_{0B}) equals the initial volume of available water to be accumulated along the catchment. The " α " factor allows other users of the SERT model to 189 190 choose whatever type of cumulative algorithm they wish to use. A map including all LLEs 191 was created and a mask with two values, 0 for the LLEs and 1 for the remaining area, was 192 created to modify the map of flow direction used in the flow accumulation algorithm. The effective cumulative runoff, CQ_{eff} (mm), is calculated after considering the saturated hydraulic 193 conductivity, K_{fs} (mm s⁻¹), and the average duration of a storm after the soil becomes 194 195 saturated until the end of the rainfall event for each month m, Tq_m (s):

196
$$CQ_{0Bm} = \alpha \cdot CQ_{0m} = \frac{\sum_{i=1}^{i=k} ER_{im} - \sum_{i=1}^{i=k} Rp_{im} e_m}{\sum_{i=1}^{i=k} CQ_{0m}} \cdot CQ_{0m}$$
(7)

197
$$CQ_{eff-m} = \langle Q_{0Bm} - K_{fs} Tq_m ee_m - SS_{max-m} ee_m \rangle \sin S$$
(8)

198
$$Tq_m = (TER_m - Tp_m) + Tq_{AftER} = (TER_m - Tp_m) + \langle FlL/FlV \rangle$$
(9)

and the maximum amount of water retained on the soil surface, SS_{max} (mm), according to 200 Driessen (1986):

201
$$SS_{\max-m} = 0.5 RG_m \frac{\sin^2 (IG - S) \cot (IG + S) + \cot (IG - S)}{\sin (IG) 2 \cos (IG) \cos (S)}$$
(10)

202 where ee_m (n) is the average number of monthly rainfall erosive events, TER_m (s) is the total 203 duration of an average monthly storm event, FlL (m) is the flow length, FlV (m/s) is the flow 204 velocity, RG (mm) is the surface roughness, i.e. the maximum depth of the soil microrelief, 205 SIG (radians) is the surface soil and surface furrow angle, and S (radians) is the slope angle of 206 the land. An erosive event has a rainfall amount >12.7 mm or a peak rainfall intensity >6.35 mm in 15 min (Renard et al., 1991). A SIG value of 30° is used in the study area according to 207 208 the value used in the previous application of the DR2 model. Surface roughness is the 209 configuration of the soil caused by the randomly orientated arrangement of soil clods. In this 210 work the roughness value for forest areas (random roughness, RG = 20.3 mm) was taken from 211 **Renard et al.** (1991). Tillage tools produce random and orientated roughness. For the tillage 212 direction perpendicular to the contours, RG is the roughness immediately after tillage and 213 before rainfall, and it is 32 mm for the plough, 23 mm for the heavy cultivator and 18 mm for 214 the disk-harrow (Gilley and Finkner, 1991). For the tillage direction parallel to the contours, 215 RG is the orientated surface roughness, which can be considered to be equal to the initial 216 tillage depth immediately after tillage and before rainfall (250 mm for the plough, 150 mm for 217 the heavy cultivator and 80 mm for the disk-harrow).

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219 2.1.2. The soil erosion module (SERT-Er)

The *SERT-Er* module calculates the monthly splash (F_m , Mg ha⁻¹ month⁻¹) and runoff (H_m , Mg ha⁻¹ month⁻¹) detachment rates according to the revised Morgan, Morgan and Finney (*RMMF*) model (Morgan, 2001) and it compares the sum of these rates with the runoff transport capacity (TC_m , Mg ha⁻¹ month⁻¹) to predict the monthly rates of soil erosion (E_m , Mg ha⁻¹ month⁻¹):

225 $E_m = \min \left\{ F_m + H_m \right\} T C_m$

$$F_m = K \cdot EE_m \cdot 10^{-2} \tag{12}$$

$$H_{m} = Z_{i} \cdot CQ_{eff-m}^{1.5} \cdot (-GC_{m}) 10^{-2}$$
(13)

$$Z_i = \frac{1}{0.5 \cdot COH_i} \tag{14}$$

229
$$TC_m = C_m \cdot P \cdot CQ_{eff-m}^{\ \beta} \cdot 10^{-2}$$
(15)

where K (g J⁻¹) is the soil erodibility, EE (J m⁻²) is the total rainfall energy, Z (kPa⁻¹) is the resistance of the soil to being detached and delivered, GC (%) is the ground cover (e.g. rocks,

(11)

232 litter and stubble), COH (kPa) is the cohesion of the soil estimated from the soil texture, and 233 C and P are the factor of cover management and support practices of the RUSLE model (Renard et al., 1991). The β factor range [1.3–2.9] in order to model the loss of transport 234 235 capacity due to runoff from the divides to the bottom of the hillslope as runoff increase the 236 load of sediment delivered. The map of the β factor was obtained from the map of effective 237 cumulative runoff. In the original *RMMF* model, the runoff depth is not accumulated along 238 the hillslope and it is calculated according to the critical value of soil moisture storage and the 239 mean rain per rainday and total rainfall volume. In the SERT model, runoff depth is spatially 240 distributed and computed using the approach described in the hydrological module. Rainfall energy is estimated as the sum of the kinetic energy of the leaf drainage raindrops E(LD) (J 241 m^{-2}) and the energy of the direct throughfall rainfall E(DT) (J m^{-2}): 242

243 $EE_m = E \mathbf{O}T_{\mathbf{M}} + E \mathbf{O}L_{\mathbf{M}}$ (16)

244

$$E \Phi T_{\mathcal{M}} = DT_m \cdot KE_m \tag{17}$$

245
$$E \not (D)_{m} = \not (5.8 PH_{m}^{0.5}) - 5.87$$
 (18)

where DT_m (mm) is the direct throughfall volume of monthly rainfall estimated from the total depth of effective rainfall (ER_m , mm) and the depth of leaf drainage (LD_m , mm), and KE_m (J m^{-2} mm⁻¹) is the kinetic energy of the rain at each month:

 $DT_m = ER_{im} - LD_m \tag{19}$

250

$$LD_m = ER_m \cdot CC_m \tag{20}$$

where CC_m (0–1) is the percentage of the soil surface protected by the canopy. Monthly variations in the values of the A_m , see Eq. (5), and CC_m factors are associated with the phenology of the crops and the presence of deciduous trees. The kinetic energy of the rain is a function of the rainfall intensity, I (mm h⁻¹), and is estimated in this study using the equation developed by Coutinho and Tomás (1995) and considered suitable for the western Mediterranean areas:

257
$$KE_m = 35.9 - 0.559 \exp(-0.034 I_m^{3})$$
 (21)

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259 2.1.3 The soil redistribution module (SERT-Rd)

As described in the *Modified MMF* (Morgan and Duzant, 2008) model, soil redistribution is the result of a balance between the amounts of soil detached by raindrop impact (F_m , Mg ha⁻¹ month⁻¹) and by runoff (H_m , Mg ha⁻¹ month⁻¹) and the amount of delivered soil which is deposited downslope. Using this conceptual basis, the *SERT-Rd* module estimates the

Remaining runoff Transport Capacity (TC_{r-m} , Mg ha⁻¹ month⁻¹) factor that allows a different 264 265 relocation of the sediments from one month to another month as a consequence of the significant temporal changes that happen in the number, duration and intensity of the rainfall 266 events, runoff depth, and tillage practices. Thus, the potential $(DEP_{pot-m}, Mg ha^{-1} month^{-1})$ 267 and net $(DEP'_m, Mg ha^{-1} month^{-1})$ rates of monthly soil deposition in each cell of the modeled 268 study area are calculated. When the runoff transport capacity $(TC_m, Mg ha^{-1} month^{-1})$ is the 269 limiting factor of soil erosion in a cell, there is not enough energy for the downwards delivery 270 of the sediment coming from the upslope cells (E_{up-m} , Mg ha⁻¹ month⁻¹). Conversely, when 271 the total rate of detached particles is lower than the rate of TC_m , there is a remaining runoff 272 Transport Capacity per cell, TC_{r-m} , and accumulated one along the hillslope (TC_{r-up} , Mg ha⁻¹ 273 month⁻¹) that can deliver part or the whole amount of sediment coming from the upslope 274 275 cells:

$$TC_{r-m} = \langle C_m - E_m \rangle 0$$
(22)

277
$$E_{up-m} = f \, (\mathbf{E}_m, \text{Acc.Algorithm}_{\text{MD}}^{c=1.1}) \forall \, \text{surface} TC_{r-m} > 0$$
(23)

278
$$TC_{r-up-m} = f \left(C_{r-m}, \text{Acc.Algorithm}_{\text{MD}}^{c=1.1} \right) \text{ surface } TC_{r-m} > 0$$
(24)

279
$$DEP'_{m} = DEP_{pot-m} - E_{m} = \langle E_{up-m} - TC_{r-up-m} \rangle - E_{m} \forall \text{ surface } DEP'_{m} > 0$$
(25)

We use a multiple flow accumulation algorithm (Acc. Algorithm_{MD}) with a concentration 280 281 coefficient equal to 1.1 to redistribute the detached particles. Although overland flow 282 accumulation, Eq. (6), and sediment redistribution, Eq. (23), happen simultaneously in nature, 283 we divide these processes into two different equations to facilitate the computational process, 284 and also assign two different values for the c coefficient of concentration in order to 285 distinguish the spatial redistribution of runoff and detached particles. Finally, the balance 286 between the total rates of soil loss, sediment deposited and sediment yield at the outlet of the 287 catchment should be zero. The presence of karstic processes and the development of a 288 sinkhole at the bottom of the study area prevent the occurrence of the typical outlets associated with rivers and gullies, and thus the balance is performed between rates of soil loss 289 290 and deposition:

$$291 DEP_m = DEP'_m \cdot x (26)$$

292
$$x = \frac{LOSS_{T-m}}{DEP_{T-m}}$$
(27)

where DEP_m (Mg ha⁻¹ month⁻¹) is the weighted rate of soil deposition, and x is the weighting factor between the values of total soil loss ($LOSS_{T-m}$, Mg month⁻¹) and total deposited sediment before weighting $(DEP'_{T-m}, Mg \text{ month}^{-1})$. On a yearly basis, values of soil redistribution are computed as the sum of the processes of soil redistribution that happen in each month of the year:

298
$$RED_{yr} = \sum_{m=1}^{m=12} DEP_m - \sum_{m=1}^{m=12} LOSS_m$$
(28)

299

306

300 2.1.4 Model analysis and validation with ¹³⁷Cs derived rates

A sensitivity analysis was carried out to test that the model behaved rationally and to determine which input parameters had most effect on the predictions of runoff and soil erosion. Sensitivity was analysed using the average linear sensitivity (*ALS*) approach (McCuen and Snyder, 1986), which expresses a relative normalized change in output to a normalized change in input:

$$ALS = \frac{\left[O_{2} - O_{1} / O_{1,2}\right]}{\left[I_{2} - I_{1} / I_{1,2}\right]}$$

where O_1 and O_2 are the values of the model output obtained with the values of I_1 and I_2 for 307 input parameter I, and $I_{1,2}$ and $O_{1,2}$ are the means of the two input and two output values 308 309 respectively. This approach is appropriate for comparing the sensitivities of input parameters 310 with values of different orders of magnitude and has been used to perform sensitivity analysis 311 in other erosion predicting models such as WEPP (Nearing et al., 1990) and Modified MMF (Morgan and Duzant, 2008). Although it does not deal well with sensitivity when the output 312 313 of the model is related non-linearly to an input, this issue can be addressed by examining how 314 the value of ALS changes as the input is varied over small ranges.

315 The validation process of the predicted soil redistribution rates constitutes the SERT-V 316 module and is adaptable to any method that can provide accurate values of net soil loss and deposition along the catchment or sediment yield at the outlet. In this study we use spatially 317 distributed rates of soil loss and deposition quantified with ¹³⁷Cs. Caesium-137 derived from 318 319 nuclear testing in the past century has been widely used as a sediment tracer of soil 320 redistribution, providing information on medium term (40-50 years) erosion rates. As the 321 SERT model has been run with average weather data for a period of fifteen years, not at event 322 or specific year scale, output maps and rates were also average predictions and thus the choice 323 of the aforementioned radionuclide technique seems to be very adequate for our study. 324 Additionally, the study area did not have a river or a creek where a gauging station could be

(29)

325 installed to measure sediment delivery. In this study we use the models of Soto and Navas 326 (2004, 2008) to quantify the net rates of soil redistribution. In order to ensure the reliability of the Cs-137 technique to provide accurate values of soil redistribution any soil sample with a 327 high content of organic matter and/or coarse fragments was removed. The ¹³⁷Cs activities 328 were measured using a high resolution, low background, coaxial gamma-ray detector of 329 330 hyperpure germanium coupled to an amplifier and multichannel analyser. The efficiency of 331 the detector is 30%, with 1.92 keV resolution (shielded to reduce background) and was 332 calibrated using certified standard samples of the same geometry as the measured samples. Gamma emissions of 137 Cs (662 keV line in mBq g⁻¹ air-dry soil) were measured for the soil 333 samples with a counting time of 30,000 s (more details about the method in Navas et al., 334 335 2012).

336

337 2.2. Study area and field survey

338 The study area is a small sub-catchment, the so-called Pilot catchment, of the Estaña Lakes 339 catchment which is located in the Spanish Pyrenean Marginal Ranges and within the Ebro 340 River Basin (Fig. 2a). The land uses and the physiographic characteristics of this agro-341 ecosystem are those typically found in the Mediterranean rain-fed agricultural systems. The 342 study area has a reduced area of 0.73 ha, elevation ranges between 686 and 698 m a.s.l. and 343 the mean slope steepness is 17%. Steep slopes (S higher than 22.5%) occupy 28% of the study 344 area and are associated with the walls of the sinkhole that appears in the *Pilot catchment* whereas gentle slopes are cultivated with winter cereals (wheat and barley) (S lower than 8%) 345 and cover 18%. This area has a relatively long history (dating back to the 10th century) of 346 347 human occupation, agricultural practices and water management (Morellón et al., 2011). 348 Natural and anthropogenic areas are heterogeneously distributed in small patches and 349 numerous stone-walls appear in the study area modifying the natural dynamics of runoff and 350 sediment connectivity (López-Vicente et al., 2013). The *Pilot catchment* has two fields of 351 winter cereal that cover 30% of the study area, and a dense Mediterranean forest of dry-352 resistant deciduous oaks (Q. faginea) and holm oaks (Quercus rotundifolia and Q. coccifera) 353 that occupy another 53%. Patches of Mediterranean shrubs (mainly Buxus sempervirens, 354 Juniperus oxycedrus and Rosmarinus officinalis) and meadows cover 13% of the study area 355 (Fig. 2b, c). The other 4% is associated with a small settlement, a man-made accumulation of 356 rocks and the unpaved trail that connect the cultivated areas with the rest of the Estaña Lakes 357 catchment.

358 Climate is continental Mediterranean with two humid periods, one in spring (April and 359 May) and a second in autumn (September and October). Low summer precipitation causes 360 summer droughts and long periods of low rainfall depth trigger severe damage in natural 361 vegetation and crops. At Canelles weather station, located 8 km to the southeast of the study 362 area, the mean annual precipitation for the reference period 1961-1990 considered by the 363 World Meteorological Organization, was 520 mm whilst over the last fifteen years (1997-364 2011) it was 13% lower (454 mm) (data source: Ebro Basin Water Authorities). Annual 365 precipitation has a strong inter-annual oscillation that for the period 1941–2011 was 378%. 366 From an average number of 83 annual rainfall events only 11 had a precipitation above 12.7 367 mm and could be considered as erosive events following the definition proposed by Renard et al. (1991). The average maximum rainfall intensity in 30 min, I_{30} , is higher than 16 mm h⁻¹ 368 between May and October with highest values in August and September (ca. 25 mm h⁻¹) and 369 below 7 mm h^{-1} in winter months (Fig. 2d, e). All weather inputs were obtained from the 370 371 values recorded every 15 minutes at Canelles weather station over a period of fifteen years 372 (1997-2011).

373 The Estaña Lakes catchment has a complex geological and geomorphological history (see 374 López-Vicente et al., 2009 and Pérez-Bielsa et al., 2012) that explains the variety of the parent 375 material of the soils: Mesozoic gypsiferous marls, dolomites, limestones and Holocene doline 376 deposits. Six types of soils are distinguished using the FAO classification (Machín et al., 377 **2008**) that can be grouped into three main types: Calcisols (covering 60% of the total surface 378 area, which is mainly cultivated), Leptosols (39% and covered with forest) and Regosols (1%) 379 (Fig. 2f). Texture is mainly silty loam and in some parts sandy loam, loam and silty clay. A 380 total number of 266 soil samples were collected using a regular 5x5 metre grid (Fig. 2g) in 381 spring 2007. Samples were air-dried, ground, homogenized and quartered to pass through a 2 382 mm sieve. The different inputs related to the soil properties were measured and calculated 383 using the soil samples and direct measurements in the field (more details in López-Vicente, 384 2008).

Large areas of this study site are affected by active soil erosion by water, as described in the literature (e.g. Soto and Navas, 2008; López-Vicente and Navas, 2009; Gaspar et al., 2013) with high rates of soil loss mainly having an impact on crops (ranging from almost zero to 108 Mg / ha yr) and areas with low vegetation cover (unpaved trails, disperse scrublands) and those located on steep slopes. However, the magnitude of the erosion process varies significantly throughout the year and thus monthly values of soil erodibility and net soil loss also vary (López-Vicente et al., 2008). Active processes of sediment delivery and soil 392 redistribution along the hillslopes and the influence of man-made linear landscape elements 393 (LLEs) on the processes of runoff accumulation and sediment trapping effectiveness have 394 been also described in detail in this study area (López-Vicente et al., 2013; Navas et al., 395 2012). To assess the accuracy of the soil loss and deposition predictions with SERT and to 396 perform the validation procedure, 133 control points (CPs) were established along the whole 397 *Pilot catchment.* The *CPs* were located every two soil sampling sites using a regular 10x10 398 metre grid to obtain 45 CPs for the cultivated area, 60 for the oak forest, 10 for the holm oak 399 forest, 5 for the scrublands, 9 for the pastures and 4 for the unpaved trails and areas of bare 400 soil. The extensive database available and the background of prior studies performed in the 401 *Pilot catchment* provide an excellent frame to run and test the new SERT model in this 402 location.

403

404 **3. Results and discussion**

405 3.1. Runoff and Soil erosion

406 The initial runoff depth generated per raster cell, Q_0 , reveals significant variations in time and 407 space. As can be seen in Figure 3a, mirroring the spatial distribution of the different soil 408 types, those areas with higher values of saturated hydraulic conductivity present the lowest 409 values of annual runoff depth. This spatial trend remains constant throughout the twelve 410 months of the year although the differences in the monthly values become more significant in 411 the six month period from November to April, when the intensity of rainfall events decreases 412 significantly. Runoff coefficients related to the values of Q_0 are plotted in Figure 3b and show 413 that no runoff is expected in Haplic Calcisols (CLha) for six months and in Rendzic Leptosols 414 (LPrz) for five months. The average annual runoff coefficient decreases from 99.6% in Leptic 415 Calcisols (CLle) to 97.8% in Haplic Calcisol with Haplic Leptosol (CLha + LPha) 57.8% in 416 LPrz and 44.1% in CLha. These results highlight the key role played by the factors associated 417 with the different soil types, especially the saturated hydraulic conductivity of the topsoil, K_{fs} , see Eq. (1), to explain the temporal and spatial variability of time to ponding, initiation of 418 419 runoff and total runoff depth. As for the average volume of water stored on the soil surface, 420 SS_{max-m} in Eq.(8), this varies between 4 and 7 mm due to the different tillage practices 421 throughout the year. The ALS of the SERT-Hy module, see Eq. (29), was performed on the 422 values of effective cumulative runoff (CQ_{eff}) in October when the maximum values of 423 overland flow occur, showing that sensitivity is greatest for the factors of upslope 424 contributing area (ALS = 1.38), slope steepness (ALS = 0.86), soil roughness (ALS = 0.42) and 425 saturated hydraulic conductivity (ALS = 0.37), and to a lesser extent, for the matrix flux

426 potential (ALS = 0.11). The ALS of CQ_{eff} for the other inputs is low (ALS < 0). In addition, in 427 relation to the two most important factors, values of CQ_{eff} present high sensitivity in the 428 ranges of low upslope contributing areas and high slope steepness.

The SERT-Er module predicted an average annual erosion rate of 11.04 Mg ha^{-1} vr⁻¹ for 429 the whole *Pilot catchment* (Fig. 4a). This value clearly exceeds the maximum tolerable rate of 430 1.4 Mg ha^{-1} yr⁻¹ proposed by Verheijen et al. (2009) for the prevalent conditions in European 431 cultivated lands and hence poses a threat to the sustainability of this agro-ecosystem. The 432 433 above-described spatial pattern of soil erosion remains almost constant throughout the year 434 although average values vary significantly between low average erosion rates in January, February and July (below 0.15 Mg ha⁻¹ month⁻¹) and the higher values in April, May, 435 September, October and November (between 0.8 and 1.9 Mg ha^{-1} month⁻¹) (Fig. 4b). Monthly 436 437 rainfall depths correlate well with monthly average and standard deviation (sd) values of soil 438 erosion in the whole catchment (Pearson's r = 0.96 and 0.85, respectively), whereas rainfall intensity correlates poorly with the average (r = 0.25) and the sd values (r = 0.27) of soil 439 440 erosion. The same temporal pattern is observed in the percentages of eroded and non-eroded 441 areas (Table 2). Soil erosion is mainly triggered in five months (April, May, September, 442 October and November) totalling 86, 86, 84 and 80% of the total annual erosion in CLha, 443 CLha + LPha, CLle and LPrz, respectively. The highest rates always occur in October but the 444 temporal pattern of the values of soil erosion change in the case of different soil types (see bold numbers in Table 2). Additionally, no linear relationship has been found between the 445 446 percentage of eroded area and the mean values of soil erosion, indicating the complexity of 447 the processes of soil detachment and delivery. The percentage of soil surface affected by 448 water erosion is very high and almost constant between April and October in the four soil 449 types, whereas the largest areas without soil erosion are predicted in winter, with the largest 450 surface without soil erosion occurring in March. The temporal patterns of runoff depth and 451 soil erosion described with *SERT* mainly agree with those highlighted by López-Vicente et al. 452 (2008) in cultivated lands of the Estaña Lakes catchment and by other authors in similar 453 landscapes and climatic conditions (e.g. Renschler et al., 1999) although the SERT model 454 emphasizes the monthly differences in the magnitude and extension of the soil affected by 455 water erosion. This characteristic of the SERT model makes it more valuable to obtain a 456 detailed assessment of the risk of soil erosion in each month and erosion period of the year.

457 Cultivated (*CLha* and *CLha* + *LPha*) and bare (*CLha* + *LPha*) soils are affected by intense 458 processes of soil erosion and present average rates of 20 and 10 Mg ha⁻¹ yr⁻¹, respectively. 459 High values of soil erosion also affect the soils of the Mediterranean forest and oak forest (9.1

and 8.2 Mg ha⁻¹ yr⁻¹ on average, respectively) due to their location on steep slopes while 460 461 pastures and scrublands display the lowest soil erosion values, with average rates of 1.7 and 2.3 Mg ha⁻¹ yr⁻¹, respectively. Predicted rates of soil erosion in the cropland of the *Pilot* 462 *catchment* are in the same range of magnitude as those estimated with ¹³⁷Cs by Gaspar et al. 463 (2013) and Navas et al. (2012) and with the RMMF model by López-Vicente and Navas 464 465 (2010) in other cultivated soils in the Estaña Lakes catchment. The highest values appear in 466 those areas where cumulative runoff and slope steepness reach high values and soil surface is 467 bare during some months or throughout the whole year. We consider that further research 468 should be done to improve the runoff connectivity estimation along the walls of the sinkhole 469 where many blocks of limestone appear as well as cloggy soils (López-Vicente et al., 2009). 470 In addition, it seems necessary to account for the processes of percolation as the study area 471 presents karst processes that have not been considered in the estimation of the cumulative 472 runoff depth. On a monthly basis and selecting the month of October which is when the 473 highest values of soil erosion occur, the average linear sensitivity (ALS) of the predicted rates 474 of soil erosion is greatest for the inputs of slope steepness (ALS = 4.62), effective cumulative 475 runoff (ALS = 3.23) and the C-RUSLE factor (ALS = 1.19) and, in a minor way, for the soil 476 cohesion (ALS = 0.56) and soil detachability (ALS = 0.25) factors. On the other hand, the ALS477 of the rates of soil erosion is below zero for plant height, canopy cover, rainfall interception 478 and surface cover factors.

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480 3.2. Soil Redistribution and modelling validation

481 Soil redistribution was estimated for each month of the year, revealing significant variations 482 in the values and areas affected by soil loss and deposition (Fig. 5). The temporal variations in the magnitude of the values mirror the variability described in the monthly rates of soil 483 484 erosion, although the spatial changes reflect the temporal and spatial variability in the rates of 485 splash (F_m) and runoff (H_m) detachment, transport capacity (TC_m) , and remaining transport capacity (TC_{r-m}) . Stable areas, without processes of soil loss or deposition, are relatively 486 487 frequent in January (2.6% of the total surface), February (1.3%), March (2.6%), July (1.3%), 488 November (2.1%) and December (2.2%), whereas for the other six months the percentage 489 remains ca. or below 1%. Predominantly, soil loss processes take place in February, June, 490 July and August when the percentage of the soil surface affected by net soil loss is above 491 85%, whereas soil deposition affects larger areas in March, April, May, September, October 492 and December (between 28 and 51% of the soil surface). There is a positive correlation 493 between the intensity of soil erosion processes and the surface of the bottom of the catchment 494 affected by sediment deposition (Pearson's r = 0.825). These results show the complexity of 495 the processes of soil loss and sediment delivery and deposition and contribute valuable 496 information to previous studies relating to seasonal dynamics of runoff-contributing areas 497 (Latron and Gallart, 2007) and sediment delivery (Navas et al., 2009) in the Spanish Pyrenees 498 and other agricultural landscapes (e.g. Francia Martínez et al., 2006 in olive orchards).

499 On an average annual scale, the total surface of the *Pilot catchment* affected by soil loss is 62% and has an average value of soil loss of 10 Mg ha^{-1} yr⁻¹, whereas the remaining surface 500 presents a mean value of soil deposition of 9 Mg ha^{-1} yr⁻¹ (Figure 6a). The abrupt changes 501 502 between values of soil loss and deposition that occur in some parts of the study area can be 503 explained by the effect of the landscape linear elements that interrupt sediment connectivity and by the changes in land uses. The performance of the model is satisfactory and provides 504 505 statistically significant correlations for total soil redistribution (Pearson's r = 0.709) and soil 506 loss (Pearson's r = 0.652). Predicted values of soil deposition have a lower however satisfactory correlation with quantified values with ¹³⁷Cs (Pearson's r = 0.564) (see Figure 507 508 6b). Considering each sampling point as a test point, the Nash-Sutcliffe coefficient was 0.48, showing the good prediction ability of the SERT model and also highlighting the high quality 509 510 of the modelling parameterization carried out in this study. The performance values have to be evaluated taking into account that the analytical precision of the measurements done with 511 137 Cs is approximately $\pm 5\%$ and the processes of soil loss and deposition are modelled 512 separately with the ¹³⁷Cs measurements. 513

The analysis of soil redistribution for the different land uses was performed with both 514 observed (137 Cs) and predicted (*SERT-Rd*) values (see Table 3). Cultivated areas present high 515 rates of both soil loss and deposition which, on average, range between -11 and 13 Mg ha^{-1} 516 yr⁻¹. The standard deviation values are also high. Conversely, mean rates of soil loss and 517 518 deposition in rangeland are much lower and high rates only appear on small patches. These 519 values reveal the heterogeneity of the processes of soil redistribution in the *Pilot catchment*. Finally, the sediment balance predicted with the SERT-Rd model was -1.15 Mg yr⁻¹ and the 520 observed balance of soil redistribution with ¹³⁷Cs was -0.59 Mg yr⁻¹. Both values are similar, 521 522 negative and close to zero and can be considered to be a good estimation since the Pilot 523 *catchment* is an endorheic area affected by moderate karst processes. As the topographic 524 characteristics of the study area enable the accurate estimation of the sediment balance, the 525 predictions of the SERT model should be improved in further research, considering the 526 processes of percolation of fine particles on the lowlands where the sinkhole is slightly active, 527 the deposition of soil particles in the cloggy soils, and the occurrence of tillage erosion. In 528 order to broaden the use of the *SERT* model in other study areas, further research will also 529 focus on developing a calibration module using the β factor, Eq. (15), for monitored 530 catchments where data of sediment delivered in gullies and river systems are available.

531

532 **4. Conclusions**

533 The SERT model has proved to be an accurate model for small and medium-size catchments to estimate monthly and annual rates of runoff depth, soil erosion and sediment redistribution, 534 taking advantage of current GIS-based techniques. The ability of the new model to 535 536 discriminate stable areas and the high sensitivity of the model to predict different spatial and temporal patterns of initial runoff, total runoff depth, and soil loss and deposition makes the 537 538 SERT model a useful tool for soil and hydrologic simulations. With a total number of 24 input 539 parameters, the SERT model requires a significantly lower number of inputs than other 540 spatially distributed and temporal continuous models, and thus the new approach can be easily 541 run for studies of soil erosion risk, especially in areas with limited information. In addition, 542 the four-module structure of the SERT model makes it adaptable to any method that can provide accurate rates of cumulative runoff and net soil loss and deposition throughout the 543 catchment or at the outlet. After validation with ¹³⁷Cs derived rates the performance and good 544 parameterization of the SERT model has been successfully proved. Finally, the application of 545 546 the new model in the *Pilot catchment* has provided valuable information on the processes of 547 soil saturation, runoff and soil redistribution that can be used in other agro-ecosystems. In 548 order to extend the use of the SERT model we are currently developing a module for open-549 source and free SAGA GIS software that will be called SERT-2013 SAGA v1.0. This module is 550 built using C++ code and contains all scientific methods and equations, and is presented in a 551 user-friendly interface that will be of interest to the scientific and academic community. The 552 module will be available at our research centre website in autumn 2013.

553

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Figure 1 Flowchart of the SERT model. White shapes are based on the RMMF model (Morgan, 2001) and grey shapes are specific of the SERT model. SERT-Hy: Hydrologic
 module; SERT-Er: Soil erosion module; SERT-Rd: Soil redistribution module. V: Vegetation; W: Weather; T: Topography; S: Soil; LU: Land use.



Type of data	Input	Description	Monthly variation
Climatic	R _m	Rainfall depth (mm)	Yes
	I_m	Maximum rainfall intensity (cm s ⁻¹)	Yes
	TR _m	Average duration of a storm event (s)	Yes
	e _m	Number of erosive rainfall events (n)	Yes
Soil	θ_{Seff}	Effective volumetric water content at saturation (% vol.)	No
	θ_{0m}	Volumetric water content at field conditions (% vol.)	Yes
	Vol _{eff}	Effective volume of the soil (%)	No
	K _{fs}	Saturated hydraulic conductivity (cm s ⁻¹)	No
	Φ	Matrix flux potential (cm ² s ⁻¹)	No
	SIG	Surface soil and surface furrow angle (radian)	No
	RG _m	Soil surface roughness (mm)	Yes
	Κ	Soil detachability index $(g J^{-1})$	No
	GC_m	Ground cover, e.g. rocks, litter, stubble (%)	Yes
	COH	Soil cohesion (kPa)	No
	BD_{f}	Bulk density of fine fraction ($<2 \text{ mm}$) (Mg m ⁻³) – only used in the ¹³⁷ Cs model	No
Topography	S	Slope steepness (radian)	No
	MD	Multiple flow accumulation algorithm	No
Land use	LLE	Landscape linear elements (mask)	No
	Tll-Prc	Tillage practices (mask)	Yes
	С	Crop management factor of the RUSLE model $(0-1)$	Yes
	Р	Support practices factor of the RUSLE model $(0-1)$	No
Vegetation	A _m	Rainfall interception by canopy (%)	Yes
-	CC_m	Canopy cover (%)	Yes
	PH_m	Plant height (m)	Yes

Table 1 Input parameters of the *SERT* model and their temporal variability.

- 698 Figure 2 Location of the study area in NE Spain within the Ebro River Basin (a), map of land uses (b), photo of
- 699 the cereal crop and oak forest (e) monthly values of rainfall and evapotranspiration depth and temperature (d),
- 700 monthly values of rainfall intensity and number of erosive events (e), map of the different soil types with the
- 701 location of the soil sampling points (f) and photo of the soil sampling survey (g). *CLha*: Haplic Calcisol; *CLha* +
- 702 *LPha*: Haplic Calcisol + Haplic Leptosol; *CLle*: Leptic Calcisol; *LPli* + *RGli*: Lithic Leptosol + Lithic Regosol;
- 703 *LPrz*: Rendzic Leptosol; *RGli*: Lithic Regosol.





- 706 Figure 3 Map of the total annual runoff generated per raster cell (a) and monthly average runoff coefficients for
- 707 the different soil types (b): CLha: Haplic Calcisol; CLha+LPha: Haplic Calcisol + Haplic Leptosol; CLle: Leptic
- 708 Calcisol; LPrz: Rendzic Leptosol.





- **Figure 4** Map of average annual soil erosion (*SERT-Er*) at the *Pilot catchment* (a) and boxplots of the monthly
- 712 rates of soil erosion at the soil sampling points (b). The Y axis of the boxplots are in logarithmic scale and
- horizontal lines represent the 10%, 25%, 50%, 75%, 90% and average values. All outliers are included.



717 **Table 2** Percentage of eroded area within each type of soil for each month of the year and mean and standard

deviation values of predicted soil erosion with the *SERT* model. *CLha*: Haplic Calcisol; *CLha+LPha*: Haplic
Calcisol + Haplic Leptosol; *CLle*: Leptic Calcisol; *LPrz*: Rendzic Leptosol.

	Soil type and number of soil samples												
	<i>CL ha</i> (<i>n</i> =58)			CL	CL ha + LP ha			<i>CL le</i> (<i>n</i> =26)			<i>LP rz</i> (<i>n</i> =102)		
Month				(<i>n</i> =80)									
	%Ea*	<i>m</i> **	sd***	%Ea	т	sd	%Ea	т	sd	%Ea	т	sd	
Jan	97.4	0.28	0.45	97.4	0.13	0.40	99.3	0.16	0.25	94.5	0.18	0.29	
Feb	100.0	0.13	0.20	98.1	0.06	0.20	100.0	0.08	0.11	99.8	0.09	0.15	
Mar	96.8	0.45	0.68	97.1	0.22	0.66	99.3	0.40	0.57	92.8	0.39	0.54	
Apr	98.8	2.25	2.47	98.1	0.89	1.75	100.0	2.04	2.51	100.0	1.62	1.20	
May	100.0	0.58	0.37	98.1	0.42	0.91	100.0	1.36	1.67	100.0	1.25	0.96	
Jun	100.0	0.55	0.73	98.1	0.20	0.47	100.0	0.33	0.41	100.0	0.39	0.42	
Jul	100.0	0.21	0.28	98.1	0.06	0.16	100.0	0.06	0.07	100.0	0.08	0.11	
Aug	100.0	0.52	0.68	98.1	0.15	0.39	100.0	0.15	0.19	100.0	0.21	0.26	
Sep	100.0	3.02	3.93	98.1	0.88	2.19	100.0	1.31	1.60	100.0	1.31	1.07	
Oct	100.0	11.15	4.94	98.1	4.22	5.59	100.0	2.78	3.07	100.0	2.20	1.73	
Nov	97.0	1.91	2.28	97.2	0.70	1.48	99.3	0.86	1.13	93.4	0.75	0.89	
Dec	97.7	0.87	1.14	97.4	0.34	0.82	99.3	0.43	0.60	93.4	0.43	0.57	
Year	100.0	21.92	16.01	98.1	8.27	12.88	100.0	9.96	11.60	100.0	8.88	7.12	

720 %Ea*: Percentage of eroded area; m**: mean value of soil erosion; and sd***: standard deviation value of soil

721 erosion



Figure 5 Maps of soil redistribution at the Pilot catchment for each month of the year estimated with the *SERT* model.

- Figure 6 Map of average annual soil redistribution estimated with the SERT model (a) and correlation between
- 725 predicted (SERT-Rd) and measured (¹³⁷Cs) values of soil loss and deposition (b). LLE: Landscape Linear
- Element.



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728

729 Table 3 Soil redistribution rates (in Mg ha⁻¹ yr⁻¹) quantified with ¹³⁷Cs and predicted with the SERT model

730	(SERT-Rd module) for the different land uses and in the control points.
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Land use			¹³⁷ Cs					SERT-Rd				
		n*	min	mean	max		n [*]	min	mean	max		
Cultivated	Loss	19	1.9	29.4	63.9	· <u> </u>	48	0.1	10.9	36.3		
Cultivated	Dep.	26	0.4	24.8	136.5		43	0.2	13.4	48.3		
	Loss	41	0.1	9.4	107.4		111	0.1	4.7	55.3		
Rangeland	Dep.	46	0.2	7.8	178.9		57	0.1	3.3	13.5		
	Stable	1	0.0	0.0	0.0		7	0.0	0.0	0.0		
Total in	Loss	60	0.1	15.8	107.4		159	0.1	6.6	55.3		
Pilot	Dep.	72	0.2	14.1	178.9	-	100	0.1	7.7	48.3		
sub-catchment	Stable	1	0.0	0.0	0.0		7	0.0	0.0	0.0		

731 n^* : Number of control points in each land use

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