

Day and night time sprinkler irrigated tomato:

Irrigation performance and crop yield

by

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Abstract

The effect of day time vs. night time sprinkler irrigation on irrigation performance and tomato crop yield is assessed in this paper for the conditions of Tunisia. Field experiments were performed at the experimental station of Cherfech under two rectangular sprinkler spacings: 24 x 18 m and 18 x 18 m, denoted as plots M₁ and M₂, respectively. Results of performance evaluations indicate a relevant effect of climatic and operation conditions on

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15 irrigation uniformity and wind drift and evaporation losses (WDEL). Experimental data
16 were used to calibrate and validate a ballistic solid-set sprinkler irrigation simulation model
17 and a soil-water-yield crop model. Based on the analysis of the main meteorological
18 parameters during the irrigation season, the validated models were used to simulate night
19 time irrigation (characterized by moderate wind speed and evaporative demand).
20 Simulation results indicate that night time irrigation greatly improved performance respect
21 to day time operation: WDEL decreased from 24 to 7 %, while CU increased from 50 to
22 64 % in M_1 and from 71 to 80 % in M_2 . Simulated results showed that night time irrigation
23 decreased relative yield losses (from 26 to 16 % in M_1 and from 11 to 3 % in M_2), as well
24 as the spatial variability of crop yield (simulated yield CV in M_2 decreased from 17 to
25 6 %). Adoption of night irrigation in the study area will finally depend on local
26 socioeconomic and water management constraints.

27

28 **Keywords:** Sprinkler; irrigation; wind; daytime; nighttime; tomato; yield

29 **Nomenclature**

30	α	Angle formed between the drop velocity in the air and the wind speed;
31	β	Angle formed between the drop velocity in the air and the drop velocity
32		respect to the ground;
33	C	Drag coefficient;
34	C'	Modified drag coefficient;
35	CU	Christiansen uniformity coefficient, %;
36	CV	Coefficient of variation, %;
37	D	Drop diameter, mm;
38	D ₅₀	Mean drop diameter, mm;
39	ET ₀	Reference evapotranspiration, mm;
40	ET _a	Seasonal actual crop evapotranspiration, mm;
41	ET _c	Crop evapotranspiration, mm;
42	ET _{max}	Maximum seasonal crop evapotranspiration, mm;
43	h _d	Water depth discharged by the sprinkler, mm;
44	h _i	Individual water depth collected at the i th collector, mm;
45	\bar{h}	Average water depth collected at all collectors, mm;
46	ID	Irrigation duration, h;
47	k	Number of water depth observations;
48	K1	Empirical coefficient for the modified drag coefficient;
49	K2	Empirical coefficient for the modified drag coefficient;
50	K _c	Crop coefficient;

51	K_y	Coefficient for water stress effect on crop yield;
52	L_s	Spacing between laterals, m;
53	MAD	Management allowable deficit, %;
54	n	Empirical coefficient for drop diameter distribution;
55	P_e	Effective precipitation, mm;
56	P_v	Emitted volume in drops smaller than diameter D , %;
57	q	Sprinkler discharge, $m^3 h^{-1}$;
58	R^2	Determination coefficient;
59	RH	Relative humidity, %;
60	RMSE	Root mean square error;
61	S_s	Spacing between sprinklers, m;
62	T	Air temperature, °C;
63	WD	Azimuth wind direction, °;
64	WDEL	Wind drift and evaporation losses, %;
65	WS	Wind speed, $m s^{-1}$;
66	Y_a	Actual yield, $t ha^{-1}$; and
67	Y_{max}	Maximum crop yield, $t ha^{-1}$.

68 **Introduction**

69 Irrigation uniformity and wind drift and evaporation losses (WDEL) are related to crop
70 yield and to the efficient use of agricultural resources. Consequently, engineers and
71 agronomists regard these as important factors to be considered in the selection, design and
72 management of sprinkler irrigation systems (Solomon, 1990). In arid and semi arid
73 regions, water is scarce. Furthermore, competition for water between users, environmental
74 issues and increasing energy costs are the major reasons for improving sprinkler irrigation
75 performance.

76 Both uniformity and WDEL are affected by meteorological and technical factors such as
77 wind speed, operating pressure, sprinkler characteristics and sprinkler spacing (Keller and
78 Bliesner, 1990). Analyzing the effect of these factors on irrigation uniformity, a set of
79 performance guidelines and recommendations was presented by Tarjuelo et al. (1999) in
80 order to improve design and management of sprinkler irrigation in semi arid areas. Recent
81 progress in ballistic models for sprinkler irrigation (Carrión et al., 2001; Dechmi et al.,
82 2004a) allows simulating irrigation performance under various operation and
83 environmental conditions. Despite the fact that ballistic simulation models require an
84 important effort for calibration and validation, practical applications to sprinkler irrigation
85 management and design have been reported by Playán et al., (2006) and Zapata et al.,
86 (2007).

87 Field experiments and theoretical studies dealing with sprinkler irrigation uniformity and
88 crop yield have been performed by several authors (Stern and Bresler, 1983; Warrick and
89 Gardner, 1983; Lety et al., 1984; Or and Hanks, 1992 and Mateos et al., 1997), indicating a
90 relevant effect of non-uniformity on available soil water and on crop yield. Moreover,
91 using crop production functions, Mantovani et al., (1995) and Li (1998) developed
92 approaches to simulate the effect of sprinkler irrigation uniformity on crop yield.

93 Simulation results quantified the increase in crop yield with increasing uniformity in
94 different agroecosystems. These results also showed that the optimum irrigation amount
95 depended on agronomic and economic factors.

96 In this study, sprinkler irrigation experiments were carried out at the Cherferch perimeter,
97 located at the northeast of Tunisia. In Tunisia, sprinkler irrigation systems cover
98 110,000 ha, representing about 32 % of the total irrigated area. The objectives of this work
99 were: 1) to characterize irrigation uniformity and WDEL under the local, day time,
100 climatic and operation conditions; 2) to calibrate and validate a ballistic sprinkler irrigation
101 simulation model and a soil-water-yield simulation model; and 3) to combine both models
102 in order to explore the impact of night time irrigation on irrigation performance and crop
103 yield. Beyond the regional implications of this work, the presented methodology represents
104 a contribution to the use of irrigation and crop simulation models as tools leading to
105 adequate sprinkler irrigation management.

106 **Materials and Methods**

107 **Experimental site**

108 Field experiments were carried out at the Cherfech Experimental Station of the National
109 Research Institute for Rural Engineering, Water and Forests near Ariana, Tunisia (Lat. 37 °
110 N, Long. 10° E, Alt. 10 m). The climate is Mediterranean semiarid, with yearly average
111 precipitation of 450 mm. According to the USDA classification, soil texture is silty clay
112 loam (34.8 % clay, 57.6 % loam, 7.6 % sand). Bulk density is 1.53 Mg m⁻³, and the readily
113 available water is 163 mm m⁻¹ (water content at field capacity, $\theta_{fc} = 0.42$, water content at
114 wilting point, $\theta_{wp} = 0.26$). Irrigation water is pumped from a reservoir supplied from the
115 Medjerda canal. The average electrical conductivity of the irrigation water is 2.5 dS m⁻¹.

116 **Experimental design**

117 Sprinkler irrigation experiments were performed on a 0.5 ha solid-set field equipped with
118 two sprinkler spacings: square 18 x 18 m and rectangular 24 x 18 m (Fig. 1a). The
119 sprinkler model was RC 11C, manufactured by Rolland Arroseurs (Mognard, France). The
120 sprinkler nozzle (4.5 mm in diameter) was located at an elevation of 1 m over the soil
121 surface. The nozzle operating pressure was kept constant throughout the irrigation season
122 at 300 kPa. Two adjacent experimental plots were defined. The plots were named M₁ and
123 M₂, and were equipped with the abovementioned sprinkler spacings: 24 x 18 m for M₁ and
124 and 18 x 18 m for M₂ (Fig. 1a).

125 A tomato crop (cv. Rio Grande) was planted in April 26, 2006, at a density of 3 plants m⁻²
126 (in a square spacing of 0.33 x 1 m). Appropriate fertilizer, herbicide and pesticide
127 applications were performed during the growing season. Crop yield was determined at the
128 end of the season, dividing both plots in arrays of 3 x 3 m parcels (48 in M₁ and 36 in M₂).

129 **Irrigation system evaluation**

130 Sprinkler irrigation evaluations were conducted in plots M_1 and M_2 following the
 131 methodology described by Merriam and Keller (1978) and Merriam et al. (1980). A
 132 3 x 3 m square collector network was set up within plots M_1 and M_2 , as presented in Figs.
 133 1b and 1c. Collectors were 0.079 m in diameter and 0.24 m high, and were mounted on
 134 plastic support tubes so that the top of the collector was located at an elevation of 0.50 m
 135 over the soil surface. This collector model resulted very adapted to the experimental
 136 requirements, although its diameter was smaller than recommended in international
 137 standards (Anonymous 1987, 1990, 1995). Playán et al. (2005) reported the results of an
 138 experiment in which similar collectors were compared with collectors as large as 210 mm
 139 in diameter. Collector diameter only played a relevant role (errors exceeding 2 %) for wind
 140 speeds beyond 4.0 – 4.5 m s⁻¹.

141 During each evaluation, the wind speed (WS, m s⁻¹), azimuth wind direction (WD, °), air
 142 temperature (T, °C) and relative humidity (RH, %) were recorded with a frequency of 5
 143 min using an automatic meteorological station. The wind measurement instruments
 144 (manufactured by Weather Wizard III, Hayward, California, USA) were installed at an
 145 elevation of 2 m above the soil surface, and located at a distance of about 100 m from the
 146 experimental field.

147 Following each irrigation, the water collected in both collector sets was recorded and used
 148 to determine the Christiansen Uniformity Coefficient (CU) (Christiansen, 1942) using eq.
 149 [1]:

$$150 \quad CU = 100 \left(1 - \frac{\sum_{i=1}^k |h_i - \bar{h}|}{k \bar{h}} \right) \quad [1]$$

151 where h_i is the individual water depth collected at the i^{th} collector (mm), \bar{h} is the average
 152 water depth collected at all collectors (mm), and k is the number of observations. Likewise,
 153 the Wind Drift and Evaporation Losses (WDEL) were evaluated as:

$$154 \quad WDEL = 100 \frac{\left(h_d - \frac{1}{k} \sum_{i=1}^k h_i \right)}{h_d} \quad [2]$$

155 where h_d is the water depth (mm) discharged by the sprinkler in an irrigation event,
 156 determined as:

$$157 \quad h_d = \frac{1000 q}{L_s S_s} ID \quad [3]$$

158 where L_s is the spacing between laterals (18 m), S_s is the spacing between sprinklers (18 or
 159 24 m), q is the sprinkler discharge ($\text{m}^3 \text{h}^{-1}$) and ID is the irrigation duration (h).

160 **Irrigation scheduling**

161 The irrigation events applied between tomato planting (April 26) and May 24 were
 162 performed using a temporary sprinkler system (with a 12 x 12 m spacing) covering the
 163 whole experimental field. This narrow sprinkler spacing was used to ensure high
 164 uniformity during the initial crop development phase. The water depths resulting from
 165 these irrigation events were only used for irrigation scheduling purposes. During the rest of
 166 the season the experimental field was setup as described in Figure 1. All irrigation events
 167 performed after May 24 were evaluated following the procedures described in the previous
 168 section. All experimental irrigation events were performed during the day time.

169 Locations P_1M_1 (in plot M_1) and P_1M_2 (in plot M_2) (Figs. 1b and 1c) were selected as
 170 control points. Irrigation was applied to both plots when the control points reached a
 171 management allowable deficit (MAD) of 50 %. Soil water was gravimetrically measured
 172 during the season at twelve sites for M_1 and nine sites for M_2 (Figs. 1b and 1c). As

173 selected, these sites represent different situations of water distribution (a quarter of the
174 sprinkler spacing), and were supposed representative of each plot (M_1 and M_2) for
175 irrigation simulation purposes.

176 **Sprinkler irrigation model (Ador Sprinkler)**

177 A ballistic simulation model (Dechmi et al., 2004a) was used to simulate solid-set sprinkler
 178 irrigation in the experimental plots. The first step was to model WDEL in the experimental
 179 conditions. An empirical approach is commonly used for this purpose, relating observed
 180 WDEL to meteorological variables (Playán et al., 2005). For day time irrigation operation,
 181 the experimental data set was used to derive empirical WEDL predictive equations based
 182 on a multiple linear regression approach using WS and RH as independent variables
 183 (Playán et al., 2005). For night time irrigation operation, the following WDEL predictive
 184 equation, developed by Playán et al. (2005), was implemented in the model:

$$185 \quad WDEL = 3.7 + 1.31 WS^2 \quad [4]$$

186 The ballistic model is based on the hypothesis that a sprinkler produces drops of different
 187 diameters (Fukui et al., 1980; Carrión et al., 2001; and Montero et al. 2001). For a given
 188 pressure, a sprinkler produces a statistical distribution of drop diameters, which can be
 189 modelled using the following expression (Li et al., 1994):

$$190 \quad P_v(D) = 100 \left(1 - e^{-0.693 \left(\frac{D}{D_{50}} \right)^n} \right) \quad [5]$$

191 where P_v is the percentage of emitted volume in drops smaller than diameter D , D_{50} is the
 192 mean drop diameter, and n is an empirical coefficient.

193 The flight of a drop from the sprinkler nozzle to the soil surface is governed by the ballistic
 194 equations (Fukui et al., 1980). These equations can be solved numerically to determine the
 195 drop velocity vector from the initial condition (at the nozzle) to the landing point (drop
 196 elevation is equal to the elevation of the soil, the crop canopy or the collector). During the
 197 flight, the drop is subjected to the action of gravity (vertical), to a drag force (same

198 direction as its velocity, opposing to it), and to the wind vector (assumed horizontal). The
199 drag coefficient C was determined in the model as a function of the drop Reynolds number,
200 following Seginer et al. (1991).

201 Seginer et al. (1991) and Tarjuelo et al. (1994) reported that a model developed following
202 the steps above would not adequately predict the deformation of the circular water
203 application area in the presence of wind. Consequently, they proposed a refined version of
204 the drag coefficient (C'), including empirical parameters $K1$ and $K2$:

$$205 \quad C' = C(1 + K1 \sin \beta - K2 \cos \alpha) \quad [6]$$

206 where α and β are angles related to the drop velocity vector and the wind speed vector
207 (Tarjuelo et al., 1994).

208 This model formulation requires input data on system geometry, wind speed, nozzle
209 diameter and pressure to simulate the flight of a single drop. In order to simulate a solid-set
210 system, drops of all possible diameters must be simulated at all possible horizontal angles
211 (reproducing sprinkler revolution). Weights need to be assigned to each drop diameter,
212 according to empirical Eq. [5]. Finally, a number of sprinklers in the solid set are to be
213 simulated (typically 16), and the drops landing in different areas of the central sprinkler
214 spacing need to be accounted for in order to estimate irrigation depth and irrigation
215 uniformity.

216 Model calibration is based on the determination of the four empirical parameters presented
217 in Eqs. [5] and [6]: D_{50} , n , $K1$ and $K2$. Calibration proceeds in two steps:

- 218 1. A no-wind experiment is used to calibrate D_{50} and n , since $K1$ and $K2$ have no effect
219 under these conditions (the water application area is circular). In this experiment the
220 radial water application pattern is determined, and simulations are performed with
221 different values of the empirical parameters to identify the values resulting in: a)

222 maximum correlation between observed and simulated radial water application; and b)
223 minimum RMSE (Root Mean Square Error) between both variables.

224 2. A number of experiments under variable wind speed are required to calibrate K1 and
225 K2. For each wind speed, simulations are performed with the calibrated values of D_{50}
226 and n and different values of K1 and K2. The optimum value of these last two
227 parameters results in: a) minimum difference between observed and simulated CU; b)
228 minimum RMSE between observed and simulated irrigation depths; and c) maximum
229 correlation between observed and simulated irrigation depths. This step results in two
230 empirical functions: $K1(WS)$ and $K2(WS)$.

231 A validation phase completes the process. In this phase, additional experiments are used to
232 establish the predictive capacity of the model.

233 In previous studies, the Ador Sprinkler model has proven to have a relevant predictive
234 capacity. Dechmi et al. (2004a) reported that following calibration to a particular sprinkler
235 model and operating pressure, the model could explain 87% of the observed variability in
236 CU. When validation focused on the spatial distribution of irrigation water, the calibrated
237 model attained a RMSE of 0.95 mm h^{-1} , which was comparable to the error between two
238 adjacent experimental plots with the same characteristics. In a successive development,
239 Playán et al. (2006) calibrated and validated the model for different sprinkler models and
240 operating pressures, and produced management tables for a variety of sprinkler
241 arrangements and spacings. The model has been recently applied to the environment-
242 sensitive simulation of collective irrigation scheduling in irrigated areas (Zapata et al.,
243 2009).

244 **Soil – water – yield model (ISAREG model)**

245 Assessment of irrigation scheduling was performed using the irrigation scheduling
 246 simulation model ISAREG (Teixeira and Pereira, 1992). ISAREG is based on the soil
 247 water balance method proposed by Doorenbos and Kassam (1979). The model can be used
 248 to determine the adequate dates and volumes of irrigation for a given crop or to evaluate
 249 the effect of a selected scheduling on crop yield. As described in Teixeira and Pereira
 250 (1992), the ISAREG model requires the following input data:

251 – Meteorological data: Effective precipitation, P_e (mm) and reference evapotranspiration,
 252 ET_0 (mm) were determined according to the FAO-Penman-Monteith method (Allen et
 253 al., 1998).

254 – Crop data, including the duration of the different crop stages, crop coefficients K_c , root
 255 depth z (m), soil water depletion fractions for no stress and the seasonal response factor
 256 K_y predicting yield losses caused by soil water shortages. The yield – water stress
 257 function was proposed by Doorenbos and Kassam (1979) :

$$258 \left(1 - \frac{Y_a}{Y_{\max}}\right) = K_y \left(1 - \frac{ET_a}{ET_{\max}}\right) \quad [7]$$

259 where Y_a is the actual yield, Y_{\max} is the maximum yield, ET_a is the seasonal crop
 260 evapotranspiration, and ET_{\max} is the maximum seasonal crop evapotranspiration. Crop
 261 data were calculated from field observations using the KCISA program (Rodrigues et
 262 al., 2000), following the methodology proposed by FAO (Allen et al., 1998).

263 Under Tunisian experimental circumstances, ISAREG was validated for yield loss
 264 predictions by Teixeira et al. (1995). Zairi et al. (1998) validated the model for sprinkler
 265 irrigated winter wheat at the Hendi Zitoun experimental station (Centre of Tunisia). The
 266 validation exercise proved that the model had a satisfactory predictive capacity of soil

267 water along the crop season. Rodrigues et al. (2001) used ISAREG to develop strategies
268 for living with drought and water scarcity in semi-arid regions (Siliana, Centre of Tunisia)
269 and sub-humid regions (Vigia, South East of Portugal). These authors proposed irrigation
270 scheduling strategies minimising water demand and producing acceptable impacts on
271 cereals and horticultural crops. Zairi et al. (2003) combined ISAREG with linear
272 programming to identify and evaluate strategies for supplemental irrigation of cereals and
273 deficit irrigation of horticultural field crops in central Tunisia.

274 In this work, ISAREG was validated using experimental data, and then applied to the
275 simulation of actual ET and crop yield. Measured and simulated irrigation data were used
276 as input to the model.

277 **Results and Discussion**

278 **Analysis of the irrigation evaluations: CU and WDEL**

279 Table 1 presents the main characteristics of the irrigation system evaluations performed in
280 the experimental solid set system during the irrigation season. All irrigation events were
281 performed under day time conditions. Except for two irrigation events, the wind speed was
282 higher than 2 m s^{-1} . In 79 % of the irrigation events, the wind speed was in the range of 2 -
283 4 m s^{-1} . Temperature ranged from 24.2°C to 44.3°C , while relative humidity ranged from
284 15.0 % to 59.8 %. Table 1 also presents the average meteorological conditions for the night
285 period of the days when daytime irrigations were performed (from 19:00 till 7:00 next
286 day). The Table shows a strong decrease in WS (from 3.0 m s^{-1} to 1.4 m s^{-1} on the average)
287 and a relevant increase in RH (from 41 % to 66 % on the average). Night time conditions
288 are much more suited to sprinkler irrigation than day time conditions.

289 Using the same experimental working pressure (300 kPa) and wind conditions
290 (simultaneous daytime irrigation), the average CU values were 49 % for M_1 and 71 % for
291 M_2 , following the expected trend. According to the classification proposed by Keller and
292 Bliesner (1990) for solid set systems, irrigation uniformity was very low in M_1 and
293 relatively low in M_2 . The seasonal CU was determined adding all the seasonally applied
294 water at each collector location. The resulting values were 56 % for M_1 and 80 for M_2 .
295 Seasonal uniformity was higher than average uniformity of individual irrigation events
296 (with an increase of 6.9 % for M_1 plot and 9.4 % for M_2 plot). Keller and Bliesner (1990)
297 reported that since the wind speed and direction differ from an irrigation event to another,
298 there is a trend for seasonal uniformity to be higher than average uniformity. Sanden et al
299 (2000) found a general increase of 4 to 8 % in seasonal distribution uniformity over
300 average DUs resulting from multiple evaluations performed in a solid set system.

301 CU time variability in plot M₁ was large, ranging from 20.9 % to 66.7 %. Very low CU
 302 values can be explained by poor sprinkler overlapping caused by inadequate working
 303 pressure and/or sprinkler spacing. Montero et al. (2000) reported that the maximum
 304 spacing recommended for extensive herbaceous crops is 18 x 18 m. These authors also
 305 recommended operating pressures in the range of 250 to 350 kPa. While the experimental
 306 pressure was in the adequate range, the sprinkler spacing was too large.

307 The lowest values of CU in plot M₂ were usually recorded for wind speeds higher than
 308 4 m s⁻¹. The highest CU value (81 %) was recorded under a wind speed of 1.8 m s⁻¹. For
 309 the lowest wind speed (1.7 m s⁻¹), the resulting CU was 78 %. The duration of the
 310 irrigation events, and the random component of wind speed and direction may explain
 311 these differences. For wind speeds ranging between 2 and 3 m s⁻¹ (50 % of the irrigation
 312 evaluations), the average CU value was 74 %. In the wind speed range of 3 to 4 m s⁻¹
 313 (18 % of the irrigation evaluations), the average CU value decreased to 65 %. Under low
 314 wind speeds (less than 3 m s⁻¹), uniformity seems to be highly limited by the use of single
 315 nozzle. Analysing uniformity in the Loma de Quinto Irrigation District (LQD), Dechmi et
 316 al. (2003) found that with relatively low pressure (210 kPa) and double nozzle sprinklers,
 317 the 18 m x 18 m spacing resulted in high CU (an average of 87 %) under wind speeds
 318 below 3 m s⁻¹.

319 In both plots, the analysis of wind speed and CU data revealed that uniformity was clearly
 320 affected by wind speed. The best regressions between CU and wind speed were obtained
 321 by third degree polynomials:

$$322 \text{ Plot M}_1 : CU = 0.242WS^3 - 2.47WS^2 - 2.08WS + 72.1 ; \quad R^2 = 0.88 \quad [8]$$

$$323 \text{ Plot M}_2 : CU = 0.069WS^3 - 0.026WS^2 - 8.97WS + 95.2 ; \quad R^2 = 0.85 \quad [9]$$

324 The determination coefficients were significant at the 95 % level. Similar results were
 325 reported by Montero et al (2000).

326 Playán et al. (2006) reported simulation results for two types of two-nozzle sprinklers
 327 operating in similar conditions as in plot M₂. The reported values of simulated CU were
 328 92 % for WS = 2 m s⁻¹ and 80 % for WS = 4 m s⁻¹. These results are 14 % and 13 % higher
 329 than the results obtained in this experiment for the same wind speeds (Eq. [9]),
 330 respectively.

331 **WDEL analysis**

332 The average values of WDEL were quite similar in both plots, about 24 % (Table 1). These
 333 losses are similar to those reported by Playán et al. (2005). Martinez-Cob et al., (2008)
 334 preformed a study based on lysimetric and sap flow measurements, and concluded that in
 335 their experimental conditions, 85 % of WDEL are consumptive, i.e., do not contribute to
 336 decrease crop water requirements. In the context of water scarcity characterizing Tunisia, it
 337 is difficult to accept such consumptive losses.

338 WDEL variability was higher in M₁ (CV of 31 %) than in M₂ (CV of 25 %). Statistical
 339 regressions were performed to model experimental WDEL as a function of environmental
 340 variables. The results of fitting a multiple linear regression model on WDEL at M₁ using
 341 WS, T and RH as independent variables indicate that WS and T were not statistically
 342 significant at the 90% confidence level. RH was the only environmental variable
 343 explaining WDEL at M₁ (Eq. [10]). The multiple linear regression model applied to
 344 WDEL at M₂, indicated that T was not statistically significant at the 90% confidence level.
 345 The model for WDEL at M₂ included WS and RH (Eq. [11]):

$$346 \text{ Plot } M_1 : WDEL = 43.82 - 0.46 RH \quad ; \quad R^2 = 0.32 \quad [10]$$

$$347 \text{ Plot } M_2 : WDEL = 24.91 + 3.70WS - 0.28RH \quad ; \quad R^2 = 0.53 \quad [11]$$

348 **Calibration and validation of the Ador-Sprinkler model**

349 The results of the first step of the calibration process are presented in Fig. 2. In this figure,
350 the observed radial application pattern in no-wind conditions is presented, along with the
351 simulation results for the optimum combination of the drop diameter parameters:
352 $D_{50} = 1.9$ mm and $n = 2.2$. The correlation coefficient between observed and simulated
353 water application was 0.83, while the RMSE between observations and simulations was
354 0.79 mm h⁻¹.

355 The second step of the calibration process (determination of K1 and K2) was performed on
356 irrigations 2 and 18 for M₁ and 2, 11, 14 and 18 for M₂. These six irrigation events covered
357 the range in wind speeds and included data from both sprinkler spacings. Fig. 3 presents
358 the resulting values of K1 and K2, which shows a clear dependence on WS. This
359 dependence was previously reported by Dechmi et al. (2004a) and Playán et al. (2006). On
360 the average of the six calibration cases, simulated CU was 0.86 % higher than measured
361 CU, the correlation coefficient between observed and measured irrigation depths was 0.55,
362 and the RMSE between observed and simulated irrigation depths amounted to 2.08 mm h⁻¹.

363 The Ador-sprinkler model was validated using the rest of the irrigation evaluations in
364 which all required data was available (Table 1). The comparison between measured and
365 simulated CU is presented in Fig. 4. Different symbols are used in the scatter plot for both
366 sprinkler spacings (M₁ and M₂). The results of the regression analysis confirm that
367 uniformity was adequately predicted by the model ($R^2 = 0.81$), significant at 95 %
368 probability level. The resulting standard error was 4.5 %.

369 **ISAREG model validation**

370 In a first step, ISAREG model validation was performed by comparing the soil water
371 contents observed in the field experimental plots with those simulated by the model

372 (Fig. 5). For both plots, each observed value of soil water represents the average of
373 measurements performed at the sub-plots. The model appropriately described soil water
374 content ($R^2 = 0.67$, significant at 95 % level) with a standard error of the linear regression
375 model of 0.83 %.

376 Concerning tomato crop response to applied water, simulations focused on the M_1 plot
377 since it provided larger variability of applied irrigation depths than the M_2 plot. Seasonal
378 crop evapotranspiration for tomato was calculated by performing a water balance at the
379 twelve sub-plots identified in M_1 . The crop coefficients (K_c) and the soil water depletion
380 fractions for no stress (p) determined with KCISA are presented in Table 2, as well as the
381 root depth during the crop season. For each sub-plot, ISAREG was run using the
382 corresponding soil characteristics and the measured irrigation depths. The comparison
383 between measured and simulated values of tomato yield is presented in Fig. 6. Results
384 confirm the predictive capability of the model in the local conditions. The resulting value
385 of R^2 (0.81, significant at the 99% level) was higher and more significant than for soil
386 water content.

387 **Meteorological data analysis (day and night conditions)**

388 The irrigation evaluations showed a relevant effect of climatic conditions on uniformity
389 and WDEL. In order to analyse viable management options, the daily climatic data of the
390 experimental season (2006) were analysed, concentrating on day and night values of the
391 main meteorological variables. As in Table 1, the period from 7:00 to 19:00 h was
392 considered as day irrigation timing, and the remaining was considered as night irrigation
393 timing.

394 Table 3 presents the results of this study. Wind speed and air temperature were reduced by
395 52 % and 72 % during the night time, respectively. Relative humidity increased by 59 %
396 during the night time period. The moderate values of the meteorological variables during

397 the night time (in Tables 1 and 3) suggest that night time sprinkler irrigation can result in
398 reduced WDEL and increased CU. This justifies the interest of analyzing the opportunity
399 of adopting night sprinkler irrigation to improve irrigation performance and crop yield.

400 **Ador-Sprinkler application to night conditions**

401 The validated Ador-sprinkler model was used to simulate irrigation uniformity under night
402 operation conditions. The data presented in Table 1 for night time meteorology were used
403 as model input, along with the WDEL predictive Equation [3]. During the simulated
404 irrigation season, WDEL fluctuated between 4 % and 20 % in the different irrigation
405 events, with an average of 7 %, much lower than the seasonal average 24 % determined for
406 day time irrigation conditions.

407 The experimental (day time) and simulated (night time) CU values were plotted against
408 wind speed (Fig. 7). Results illustrate how night time conditions resulted in increased
409 irrigation uniformity in both experimental plots. For the same experimental working
410 pressure (300 kPa) and night wind conditions, the average simulated CU values were
411 64.4 % for M₁ and 80.2 % for M₂. These results are 14.9 and 9.4 % higher than the
412 respective values for day time operation. For the M₁ plot, irrigation uniformity remains
413 very low because of the inadequate sprinkler spacing. Similar increases in CU owing to
414 night time irrigation operation were reported by Dechmi et al., (2004b) for the conditions
415 of the central Ebro river basin in Spain.

416 **ISAREG model application to day and night conditions**

417 The average irrigation depths computed with the ballistic model for day time and night
418 time irrigation operation were used in the ISAREG model to evaluate the water-yield
419 relationship in plots M₁ and M₂. Table 4 presents the crop response to irrigation water
420 application. For both plots, net seasonal irrigation depth for night time irrigations was

421 larger than this for day time irrigation, due to the decrease in WDEL (74 mm in M_1 and
422 93 mm in M_2). This additional water contributed to reduce irrigation deficit and thus to
423 satisfy crop irrigation requirements. Results show that night time irrigation induced a
424 noteworthy increase in actual ET (59 mm in M_1 and 50 mm in M_2) and a decrease in
425 relative yield loss (9.7 % in M_1 and 8.2 % in M_2). A similar response of tomato to net
426 sprinkler irrigation was reported by Zairi et al., (2003) in similar agrometeorological
427 conditions for Siliana (central Tunisia). These authors indicated that since most tomato ET
428 needs to be supplied by irrigation, any reduction in the applied water will lead to ET and
429 yield decrease. For the M_1 plot, night time irrigation still maintained yield loss at an
430 important value of 16 %. For the M_2 plot, night time sprinkler irrigation resulted in
431 irrelevant simulated yield losses (3 %).

432 In order to estimate tomato yield variability under night irrigation, the simulated irrigation
433 depths for the M_2 plot (36 parcels of 3 x 3 m) were used in combination with the ISAREG
434 model to estimate the spatial variability in crop yield. Table 5 presents basic statistics for
435 seasonal applied water and simulated yield under day and night time irrigation in M_2 .
436 Regardless of day or night irrigation timing, irrigation variability was higher than yield
437 variability. Confirming the results presented in Table 4, the adoption of night irrigation
438 increased net seasonal irrigation depth and crop yield. At the same time, the spatial CVs in
439 irrigation depth and crop yield were severely reduced. Night time irrigation reduced water
440 stress in sub-irrigated areas, thus contributing to high and uniform yield. These results
441 confirm the findings of Dechmi et al. (2004b) for corn in the conditions of Zaragoza
442 (Spain), quantifying the effect in a different agro-ecosystem.

443 **Conclusions**

444 In this paper, field experiments were conducted to analyse the impact of design and
445 operational factors on irrigation uniformity and tomato crop yield. The following
446 conclusions can be drawn from this study:

447 – For the experimental conditions, irrigation performance and crop yield seem to be
448 limited by inadequate sprinkler spacing in plot M₁ (24 x 18 m). Using a sprinkler
449 equipped with two nozzles could have resulted in better uniformity.

450 – The high values of WDEL (24 %) highlight a relevant effect of climatic parameters
451 (temperature, relative humidity and wind speed) on the applied water depths during the
452 irrigation season. The hydrological implications of these losses in the dry conditions of
453 Tunisia are very relevant.

454 – The Ador-sprinkler and ISAREG models were successfully calibrated and validated to
455 the experimental conditions. Their predictive capacity was established through
456 comparisons with experimental results.

457 – The night irrigation scenario resulted in a relevant decrease in WDEL (down to less
458 than 7 %) and in an increase in CU (64 and 80 % against average observed CU values
459 of 50 and 71 % for plots M₁ and M₂, respectively).

460 – For both plots, tomato crop yield simulations indicated that night irrigation reduced
461 water deficit and relative yield losses. The analysis of tomato crop yield response to
462 applied water denoted that plot M₂ (18 x 18 m spacing) reached almost maximum yield
463 night when the irrigation scenario was simulated. A substantial decrease was observed
464 in spatial yield variability in this scenario.

465 Night sprinkler irrigation stands as an adequate technical choice and a hydrological need in
466 the dry conditions of Tunisia. Although the environmental sustainability of this measure
467 has been demonstrated in this paper through its effect on water conservation, the
468 socioeconomic implications need to be assessed. Increased crop yield needs to overcome
469 the labour or automation costs related to night irrigation operation. The intensification of
470 night water uses will also need to fit in the water management practices of the Medjerda
471 canal.

472

473 **Acknowledgements**

474 This research was partially funded by INRGREF (Tunisia), and by the Agencia Española
475 de Cooperación y Desarrollo (AECID) of the Government of Spain, through grant
476 A/7661/07. Thanks are also due to Prof. L. S. Pereira and his staff for kindly offering the
477 ISAREG and KCISA software applications.

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583 Solid-Set Sprinkler Irrigation Controller for Optimum Water Productivity. *J. Irrig.*
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585 **List of tables**

586 Table 1. Main characteristics of the day time irrigation system evaluations. Meteorological
587 data include measured day time values during the irrigation event and measured night
588 time values during the following night.

589 Table 2. Tomato crop parameters for the experimental conditions, as computed with the
590 KCISA program.

591 Table 3: Day and night time values of wind speed, air temperature and relative humidity
592 for the irrigation period (May – August 2006) in Cherfech (Tunisia).

593 Table 4. Crop response to day time (experimental) and night time (simulated) irrigation.
594 Average data are used for each plot.

595 Table 5. Simulated results for day and night time irrigation and crop yield in the 36 parcels
596 (3 x 3 m) defined inside plot M₂.

597 **List of Figures**

598 Figure 1. Experimental set-up. (a) Solid set system. Solid lines represent sprinkler
599 pipelines, dots represent sprinklers and the dashed lines represent plots M1 and M2. (b)
600 and (c) layout of catch cans in plots M₁ and M₂, respectively. Trapezoids represent
601 collectors, and the dashed lines represent the area where gravimetric soil water
602 measurements were performed.

603 Figure 2. Observed (dots) and simulated (line) radial application pattern of an isolated
604 sprinkler.

605 Figure 3. Calibrated values of K1 (solid dots and line) and K2 (white dots and dashed line)
606 as a function of wind speed.

607 Figure 4. Observed vs. simulated CU for the calibration (white dots) and validation
608 conditions (both sprinkler spacings: solid dots for R18x18 and solid triangles for
609 R24x18).

610 .Figure 5. Observed vs. simulated soil water content (% in volume) along the tomato crop
611 season for plots M₁ and M₂. A regression analysis resulted in $y = 0.598 x + 13.9$
612 ($R^2 = 0.671^{**}$).

613 Figure 6. Observed vs. simulated tomato crop yield ($t\ ha^{-1}$) along the tomato crop season
614 for plots M₁ and M₂. A regression analysis resulted in $y = 0.972 x + 1.64$
615 ($R^2 = 0.808^{**}$).

616 Figure 7. Christiansen coefficient of uniformity (CU) vs. wind speed (WS) for the
617 observed day time conditions (solid dots) and for the corresponding simulated night time
618 conditions (white dots). Results are presented for plots M₁ (a) and M₂ (b).

Table 1

Irrig. #	Date (dd/mm)	ID (h)	WS (m s ⁻¹)		WD (°)	T (°c)		RH (%)		CU (%)		WDEL (%)	
			Day	Night		Day	Night	Day	Night	M ₁	M ₂	M ₁	M ₂
1	29/05	5.8	2.3	1.5	155	36	27	29	50	53	72	32	32
2	02/06	2	6.1	3.5	262	24	19	43	48	21	54	23	29
3	10/06	7	3.6	1.2	109	24	16	47	83	43	59	24	23
4	16/06	7	-	-	-	36	24	40	67	42	67	21	21
5	22/06	7	3.0	1.4	210	44	27	15	44	47	71	46	34
6	26/06	7	2.5	1.7	71	39	29	39	59	59	77	22	19
7	29/06	6	2.3	2.0	243	34	23	-	-	56	77	20	20
8	03/07	7	2.5	1.8	111	39	29	-	-	63	75	26	24
9	06/07	4	-	-	-	39	28	31	57	50	79	19	18
10	10/07	6	-	-	-	31	25	42	63	34	61	31	27
11	13/07	7	2.6	1.0	135	32	23	45	77	60	75	25	21
12	18/07	7	2.8	1.2	45	31	23	41	69	49	70	30	27
13	21/07	7	2.2	0.7	57	36	24	31	65	57	76	25	22
14	24/07	7	1.7	0.6	129	36	25	37	72	56	78	18	18
15	27/07	7	2.8	0.5	81	33	24	49	76	50	74	23	19
16	31/07	7	3.3	1.5	300	36	28	44	67	43	67	23	27
17	03/08	7	2.1	1.1	105	30	24	53	77	60	77	27	24
18	08/08	5	3.9	2.1	293	33	26	41	60	37	64	23	26
19	12/08	5	1.8	1.2	134	34	25	43	61	67	81	6	13
20	14/08	6	3.1	1.5	39	32	24	41	64	47	69	28	26
21	17/08	6	2.7	1.2	71	35	28	60	79	59	73	15	17
22	21/08	6	4.9	1.7	278	34	26	52	80	38	63	30	37
Average		6.2	3.0	1.4	-	34	25	41	66	49	71	24	24
Maximum		7.0	6.1	3.5	-	44	29	60	83	67	81	46	37
Minimum		2.0	1.7	0.5	-	24	16	15	44	21	54	6	13

Table 2

	Crop development stages			
	Initial	Development	Mid season	Final season
Period (dd/mm)	28/04 – 30/05	30/05 – 04/07	04/07 – 05/08	05/08 – 25/08
Period length (d)	32	35	32	20
K_c	0.83	0.83 – 1.15	1.15	1.15 – 0.68
p	0.45	0.45 – 0.31	0.31	0.45
Rooting depth (m)	0.1 – 0.53	0.53 – 1	1	1

Table 3

Month	Wind speed (m s^{-1})			Air temperature ($^{\circ}\text{C}$)			Relative humidity (%)		
	Day (m s^{-1})	Night (m s^{-1})	Night/Day (%)	Day ($^{\circ}\text{C}$)	Night ($^{\circ}\text{C}$)	Night/Day (%)	Day (%)	Night (%)	Night/Day (%)
May	4.53	2.49	55	25.6	16.9	66	52.4	85.2	163
June	5.22	2.87	55	28.5	19.4	68	43.7	72.3	165
July	4.62	2.02	44	31.1	23.0	74	51.3	82.7	161
August	5.72	3.06	54	29.6	23.0	78	52.8	77.0	146
Average			52			72			159

Table 4

	Net Seasonal Irrigation (mm)	Actual Crop ET (mm)	Relative ET (%)	Relative Yield Loss (%)
Plot M ₁				
Day	433	482	75.4	26
Night	507	541	84.7	16
Plot M ₂				
Day	549	571	89.4	11
Night	642	621	97.2	3

Table 5

	Net seasonal irrigation (mm)		Yield (t ha ⁻¹)	
	Day	Night	Day	Night
Average	549	642	49.0	58.6
Maximum	768	762	62.0	61.6
minimum	386	500	35.7	51.3
SD	110	79	8.2	3.2
CV (%)	20	12	17	6

Figure 1

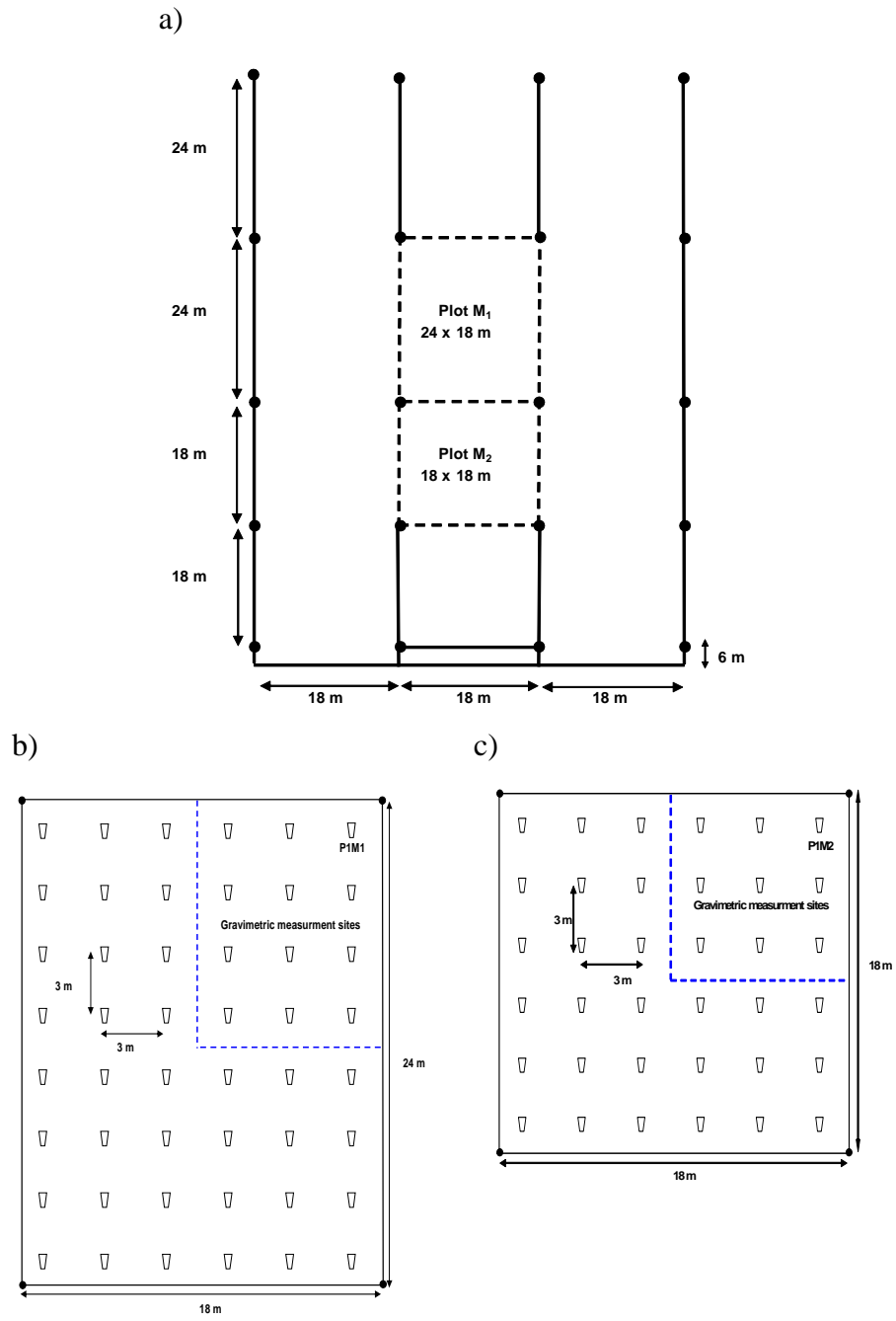


Figure 2

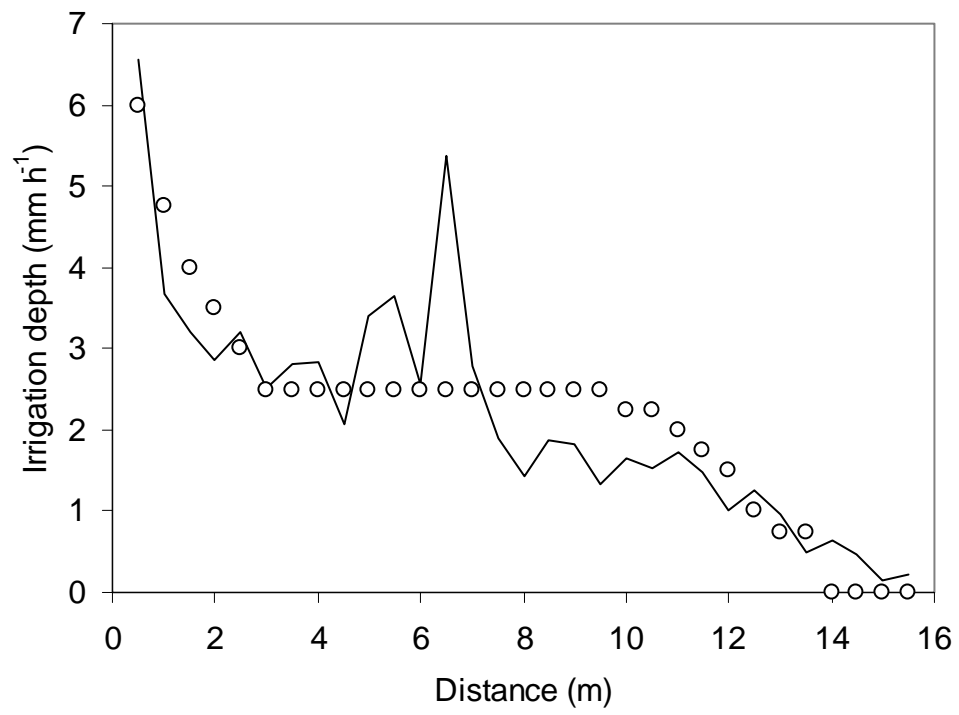


Figure 3

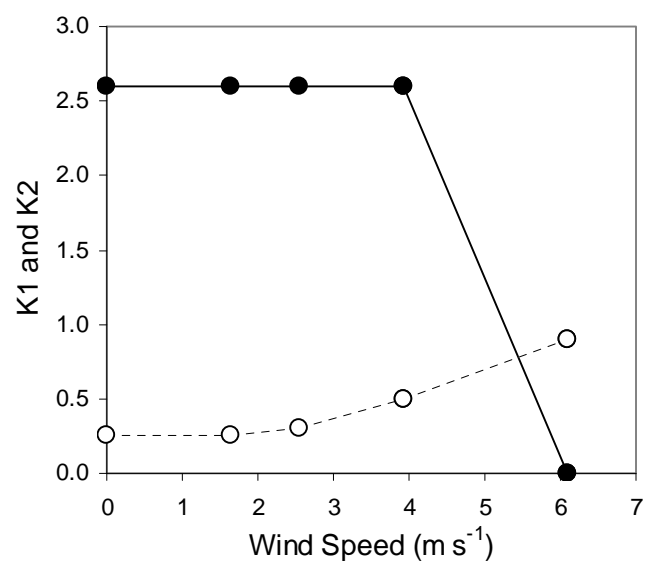


Figure 4

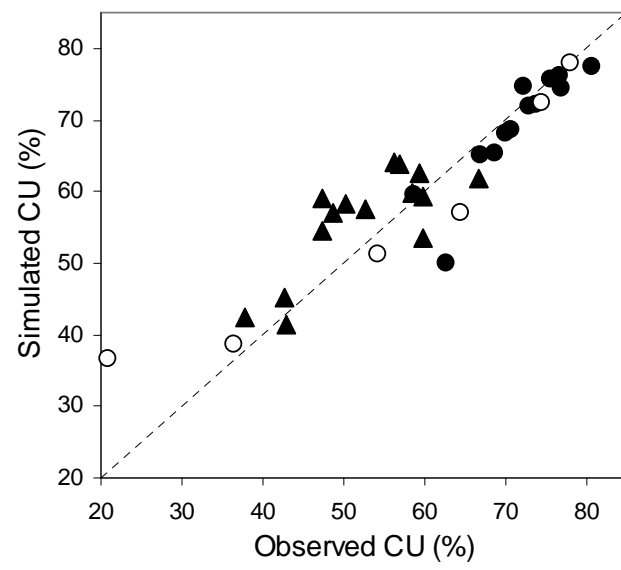


Figure 5

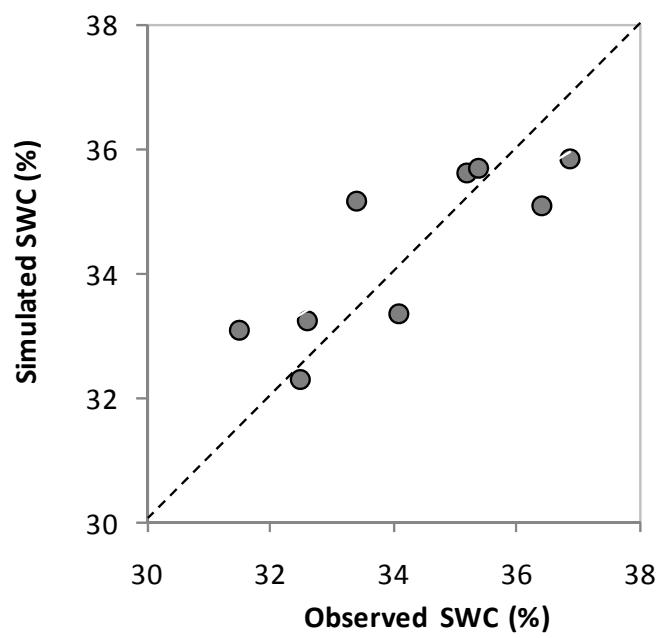


Figure 6

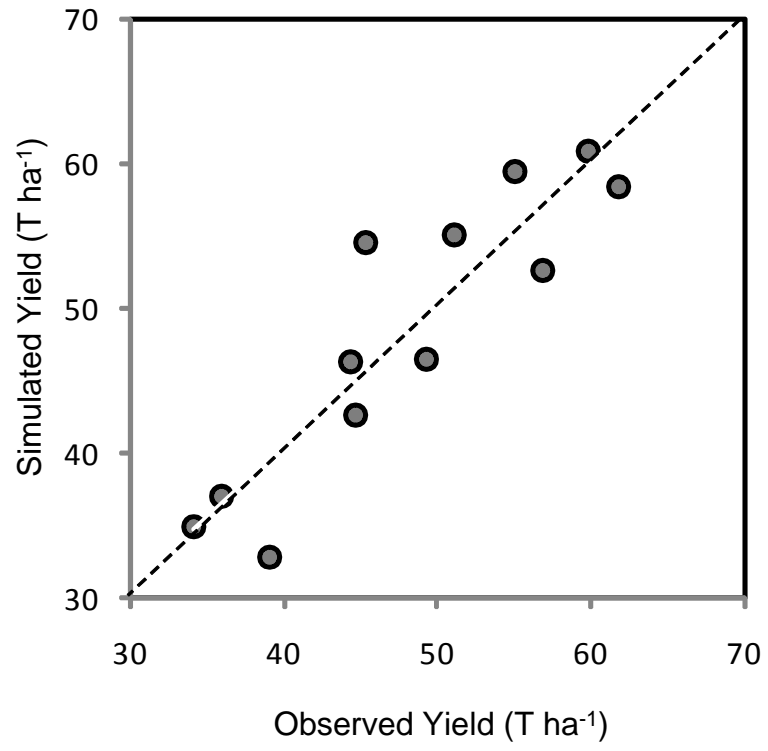


Figure 7

