

Resonant phenomena in extended chaotic systems subject to external noise: the Lorenz'96 model case

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Abstract

We investigate the effects of a time-correlated noise on an extended chaotic system. The chosen model is the Lorenz'96, a kind of “toy” model used for climate studies. Through the analysis of the system's time evolution and its time and space correlations, we have obtained numerical evidence for two stochastic resonance-like behavior. Such behavior is seen when both, the usual and a generalized signal-to-noise ratio function are depicted as a function of the external noise intensity or the system size. The underlying mechanism seems to be associated to a *noise-induced chaos reduction*. The possible relevance of these and other findings for an *optimal* climate prediction are discussed.

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I. INTRODUCTION

The last decades have witnessed a growing interest in the study of the effect of noise on dynamical systems. It was proved that, under some conditions, when a nonlinear dynamical system is subject to noise, new phenomena can arise, phenomena that only occur under the effect of such noise. All these phenomena are lump together under the name *noise-induced phenomena*. A few examples are: *stochastic resonance* in zero-dimensional and extended systems [1, 2, 3], noise-induced transitions [4], noise-induced phase transitions [5, 6], noise-induced transport [7, 8], noise-sustained patterns [9, 10], noise-induced limit cycle [11].

Clearly, some of the above indicated noise-induced phenomena occur in spatially extended systems, where another phenomena of great relevance exists: *spatio-temporal chaos* [12]. However, studies on the effect of noise on spatially extended chaotic systems are scarce [13]. There are studies on chaotic systems where the *pseudo-random* behavior of the system is the trigger of phenomena usually associated with the effect of a *real* stochastic process (see for instance [14, 15]). Hence, we can refer to the presence of a *deterministic* noise, that is a pseudo-noisy behavior associated to the chaotic character of the system.

Among others, one of the most relevant and largely analyzed application of studies of chaos in extended systems corresponds to climate prediction. These kind of problems have been described by Lorenz [17] as falling into two categories. On one hand those which depend on the initial conditions, while on the other are those depending on the boundaries. However, both kind of prediction problems are affected by errors in the model equations used to approximately described the behavior of real systems.

In a recent work [16], and with the aim to improve the limited weather predictability that results from a combination of initial conditions uncertainty and model error, it was presented a study of the effect of a stochastic parametrization in the Lorenz'96 model [18, 19]. It is well known that much of the current error in weather predictability derives from the practice of representing the effects of process occurring at unresolved scales by using simple forms of deterministic *parametrization*, attempting to summarize the effects of small-scale processes in terms of larger-scale, resolved, prognostic variables.

In this work, and with a similar objective as in a previously indicated paper [16], we investigate the effect of a time-correlated noise on an extended chaotic system, analyzing the competence between the above indicated *deterministic* noise and a *real* stochastic process.

In order to perform such a study we have chosen the Lorenz'96 model [17]. In spite of the fact that it is a kind of *toy-model*, at variance with the cases studied in [13], it has a clear contact with real systems as it is of interest for the analysis of climate behavior and weather prediction [16, 18, 19]. In fact, this model has been heuristically formulated as the simplest way to take into account certain properties of global atmospheric models. To reach our objective, we have assumed that the only model parameter is time dependent and composed of two parts, a constant deterministic contribution plus a stochastic one.

Through the analysis of the system's temporal evolution and its time and space correlations, we have obtained numerical evidence for two *stochastic resonance*-like (SR) [1] behaviors. Such behaviors are seen when both, the usual *signal-to-noise ratio* (SNR) and a *generalized* function SNR_{glob} (that we call *global* SNR), are depicted as function of the external noise intensity or the system size. In accord with what was shown in previous works [1], a SR phenomenon can occur in systems without external periodic forcing, but having an internal typical frequency. Hence, it seems reasonable to assume that the present resonances typically occur at frequencies corresponding to a system's internal quasi-periodic behavior, as well as at an *optimal* system's size. Finally, we discuss the possible relevance of these findings for climate prediction.

II. THE MODEL AND RESPONSE MEASURES

A. The Model Lorenz'96

The equations corresponding to the Lorenz'96 model [17, 18] are

$$\begin{aligned}\dot{x}_j(t) &= -x_{j-1}(x_{j-2} - x_{j+1}) - x_j + F, \\ j &= 1, 2, 3, \dots, N,\end{aligned}\tag{1}$$

where $\dot{x}_j(t)$ indicates the time derivative of $x_j(t)$. In order to simulate a scalar meteorological quantity extended around a latitude circle, we consider periodic boundary conditions: $x_0 = x_N$, $x_{-1} = x_{N-1}$.

As indicated before, the Lorenz'96 model [17] has been heuristically formulated as the simplest way to take into account certain properties of global atmospheric models. The terms included in the equation intend to simulate advection, dissipation and forcing respectively.

In contrast with other toy models used in the analysis of extended chaotic systems and based on coupled map lattices, the Lorenz'96 system exhibits extended chaos ($F > 9/8$), with a spatial structure in the form of moving waves [17]. The length of these waves is close to 5 spatial units. It is worth noting that the system has scaled variables with unit coefficients, hence the time unit is the dissipative decay time. In these units the group velocity of the waves is close to $v_{gr} = 1.20$ implying an eastward propagation. If, as done by Lorenz, we associate the time unit to 5 days and the system size of 40 to the length of a latitude circle, we have a highly illustrative representation of a global model. If in addition we adjust the value of the parameter F to give a reasonable signal to noise ratio (Lorenz considered $F = 8$) the model could be most adequate to perform basic studies of predictability. Hence, within this framework, the signal analyzed in this paper would correspond to the passing of waves in a generic observational site, in what is a simple mimic of forecasting at an intermediate time range.

B. Stochastic contribution

As indicated before, here we assume that the model parameter F becomes time dependent, and has two contributions, a constant and a random one

$$F_j(t) = F_{med} + \Psi_j(t), \quad (2)$$

with $\Psi_j(t)$ a dichotomic process. That is, $\Psi_j(t)$ adopts the values $\pm\Delta$, with a transition rate γ : each state ($\pm\Delta$) changes according to the waiting time distribution $\psi_i(t) \sim e^{-\gamma t}$. The noise intensity for this process is defined through [20, 21] $\xi = \frac{\Delta^2}{2\gamma}$.

C. System Response

As a measure of the SR system's response we have used the *signal-to-noise ratio* (SNR) [1]. To obtain the SNR we need to previously evaluate $S(\omega)$, the power spectral density (psd), defined as the Fourier transform of the correlation function [20, 21]

$$S(\omega) = \int_{-\infty}^{\infty} e^{i\omega\tau} \langle x_j(0)x_j(\tau) \rangle d\tau, \quad (3)$$

where $\langle \rangle$ indicates the average over realizations. As we have periodic boundary conditions simulating a closed system, $\langle x_j(0)x_j(\tau) \rangle$ has a homogeneous spatial behavior. Hence, it is

enough to analyze the response in a single site.

We consider two forms of SNR. In one hand the usual SNR measure at the resonant frequency ω_o (that is, in fact, at the frequency associated to the highest peak in $S(\omega)$) is

$$SNR = \frac{\int_{\omega_o-\sigma}^{\omega_o+\sigma} d\varpi S(\varpi)}{\int_{\omega_o-\sigma}^{\omega_o+\sigma} d\varpi S_{back}(\varpi)}, \quad (4)$$

where 2σ is a very small range around the resonant frequency ω_o , and $S_{back}(\omega)$ corresponds to the background psd. On the other hand we consider a global form of the SNR (SNR_{glob}) defined through

$$SNR_{glob} = \frac{\int_{\omega_{min}}^{\omega_{max}} d\omega S(\omega)}{\int_{\omega_{min}}^{\omega_{max}} d\omega S_{back}(\omega)}, \quad (5)$$

where ω_{min} and ω_{max} define the frequency range where $S(\omega)$ has a reach peak structure (with several *resonant* frequencies).

III. RESULTS

We have analyzed the typical behavior of trajectories as $x_1(t) - x_{med-T}$, where x_{med-T} is the time average. It is worth commenting that when the Lorenz96 system evolves without external noise (that is $F_j(t)$ is constant), the time evolution shows a random-like behavior, with the main feature that the amplitude of the oscillator is constant over all the time. However, when the system is subject to a random force as described in Eq. (2), the temporal response decays, due to the fact that the interaction between the intrinsic evolution and the external noise produces a dissipative contribution on the system. Hence the system's time evolution consists of a transitory regime and a stationary one. This was analyzed through the behavior of the ‘‘decay’’ of $\langle x_1(t) - x_{med-T} \rangle$. We assumed that this decay can be adjusted by an exponential law. The decay parameter (λ) only depends on F_{med} and it does not depend neither on the system size nor on the noise intensity. This analysis is relevant when studying the effects of noise on the stationary regime. From those results it was possible to anticipate, and approximately identify, the existence of two regimes: a weak or undeveloped chaos for $F_{med} < 6.0$, and strong or completely developed chaos for $F_{med} > 6.0$.

The typical numbers we have used in our simulations are: averages over 10^3 histories, and $\sim 10^4$ simulation time steps (within the stationary regime, see later).

We have evaluated the psd $S(\omega)$ in a standard way. Figure 1-a shows the typical form of the psd $S(\omega)$ for a couple of values of F_{med} ($F_{med} = 4.5, 7.8$) and for a noise intensity $\Delta = 0.1$

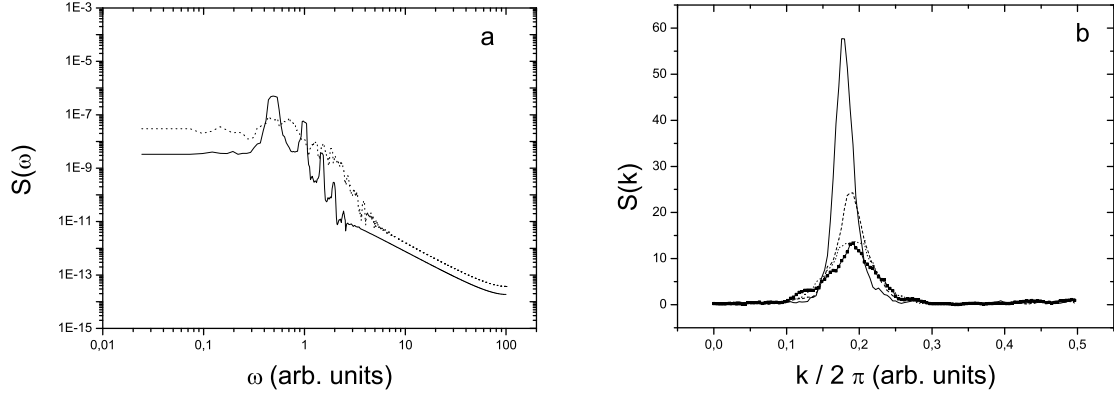


FIG. 1: (a) $S(\omega)$ for a couple of values of F_{med} ($F_{med} = 4.5, 7.8$) and for a small noise intensity ($\xi = 5 \times 10^{-4}$, $\Delta = 0.1$ and $N = 128$). (b) Spatial spectrum for $N = 256$, $\Delta = 0.001$ and $\gamma = 10$, for several values of F_{med} : continuous line $F_{med} = 5$, dashed $F_{med} = 6$, dotted $F_{med} = 7$ and dash-dotted $F_{med} = 8$.

($\xi = 5 \times 10^{-4}$). The figure shows a rich peak structure within the interval $0.22 < \omega < 1.3$. It is worth to comment that the frequencies associated to the different peaks seems to correspond to the harmonics of the main (or first) peak frequency. In Fig. 1-b, we show the form of $S(k)$, the associated spatial spectrum. Here we depict the spectrum for fixed values of the system's size ($N = 256$), and noise intensity ($\Delta = 0.001$ and $\gamma = 10$), and different values of F_{med} . The independence of the position of the peak (indicating a single spatial structure of wavelength $k/2\pi = 0.2$) is apparent. However there is a strong dependence on the peak intensity when varying F_{med} , from a net peak for underdeveloped chaos ($F_{med} = 5$) to a reduced peak for well developed chaos ($F_{med} = 8$). It is worth here remarking that there is no dependence (or eventually a very weak one) of this behavior on the noise intensity.

Figure 2 shows the dependence of SNR_{glob} –for a space-temporal noise– on Δ for fixed values of N and a couple of values of F_{med} . It shows a peak for $\Delta \sim 6 - 7 \times 10^{-3}$, that corresponds to the *fingerprint* of the more usual form of SR. The insert shows the same case but for SNR .

The analysis of the dependence of SNR_{glob} on F_{med} have also shown the existence of the previously indicated two regimes: a weak or undeveloped chaos for $F_{med} < 6.0$, and a strong or completely developed chaos for $F_{med} > 6.0$. Those regimes are characterized by

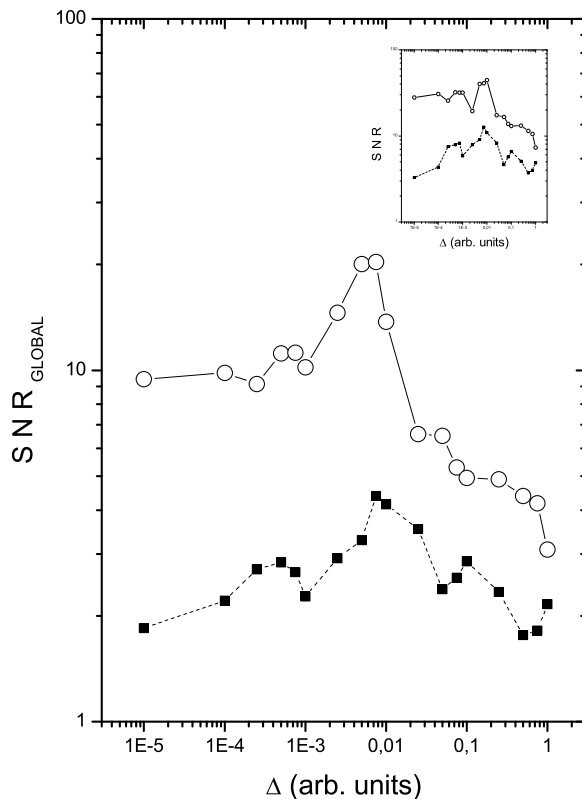


FIG. 2: SNR_{glob} vs Δ , for fixed values of $N = 64$ and $\gamma = 10$; and a couple of values of F_{med} : white circles $F_{med} = 5$, black squares $F_{med} = 6$. The insert shows the behavior of the usual SNR for the same cases.

the existence of well defined peaks in the psd, in the former case, and a less defined peak structure in the latter case, as seen in Fig. 1a .

It is worth to detach the strong similarities in the behavior of SNR and SNR_{glob} –which becomes apparent when comparing the main Fig. 2 with its insert– indicating that the second one is an adequate and more versatile measure to characterize the system’s response. Hence, due to the clearness in the determination of SNR_{glob} (compared with the difficulties for a correct determination of SNR for large values of F_{med}) in what follows we adopt it for the system’s analysis.

In Fig. 3 we depict the dependence of SNR_{glob} on N , for the case of space-temporal noise, for fixed values of $\Delta = 0.1$ and $\gamma = 5$ ($\xi = 0.001$) and a couple of values of F_{med} .

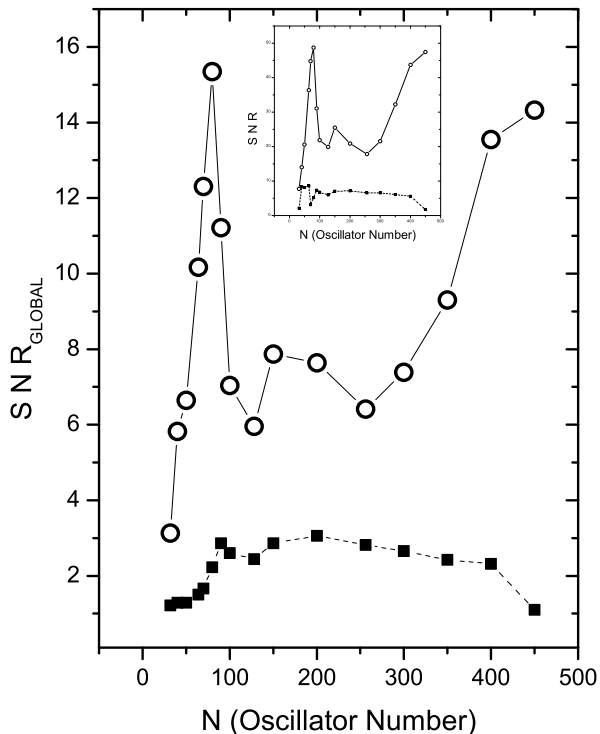


FIG. 3: SNR_{glob} vs N , for fixed values of $\Delta = 0.1$ and $\gamma = 5$ ($\xi = 0.001$), and a couple of values of F_{med} : white circles $F_{med} = 5$, black squares $F_{med} = 6$. The insert shows the behavior of the usual SNR for the same cases.

The existence of the peak at $N \sim 60$ for $F_{med} = 5.0$ is apparent. In addition, we observe an increase of SNR_{glob} for large values of N . However, for $F_{med} = 6.0$, the peak has disappeared, as well as the increase with larger values of N . The presence of the peak at $N \sim 60$ indicates a kind of *system-size stochastic-resonance* (SSSR) [23]. The insert shows the same case but for SNR . Again, as indicated above, the nice agreement between the behavior of SNR_{glob} and that of SNR .

The figures clearly show that the system's response (SNR) is stronger when the system is in the underdeveloped chaos range than when it is in the highly-developed chaos one. Our results also show that the main resonant frequency does not depend on the noise intensity, system size, or correlation rate.

We want to close this section commenting that the SR phenomena found here looks

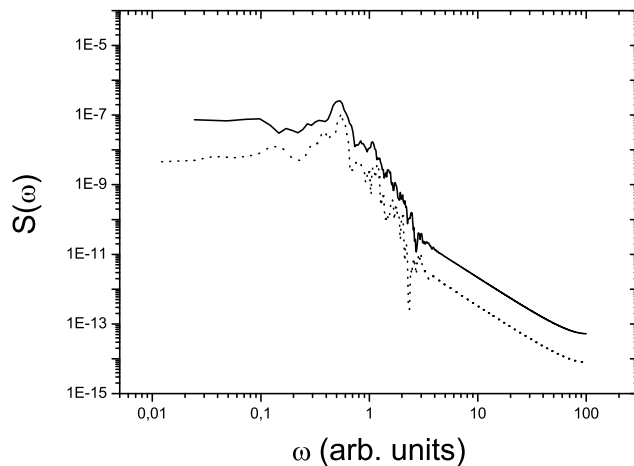


FIG. 4: $S(\omega)$ with and without external noise, for $F = 5$ and $\gamma = 10$. Continuous line $\Delta = 0$, dot-line $\Delta = 0.1$.

similar to the so called *internal signal* SR [22]. In previous studies it was shown that in some systems having an internal typical frequency, SR can occur not only at the frequency of an external driving signal, but at the frequency corresponding to the internal periodic behavior [22]. Regarding the present mechanism of SR, what we can indeed comment is that the increase in the SNR is related not to a *reinforcement* of the peak high respect to the noisy background at a given frequency, but with a *reduction* of the *pseudo* (or deterministic) noisy background when turning on the *real* noise. That is, the interplay between “real” noise and “deterministic” noise conforms a kind of *noise-induced chaos reduction*. Figure 4 shows, for fixed values of F and γ , the behavior of $S(\omega)$ in both cases: with ($\Delta \neq 0$) and without noise ($\Delta = 0$). The above indicated reduction trend, as the *real* noise is turned on, is apparent. However, the present mechanism is not completely clear so far, and requires further studies.

IV. CONCLUSIONS

We have investigated the effect of a time-correlated noise on an extended chaotic system, analyzing the competence between the indicated *deterministic* or *pseudo-noise* and the real random process. For our study we have chosen the Lorenz’96 model [17] that, in spite of

the fact that it is a kind of *toy* model, is of interest for the analysis of climate behavior [16, 19]. It is worth remarking that it accounts in a simple way of the spatial structure of geostrophic waves and the dynamics of tropical winds. The time series obtained at a generic site $x_i(t)$ mimics the passing of such waves, which is in fact a typical forecast event. We have assumed that the unique model parameter F , is time dependent and composed of two parts, a constant deterministic, and a stochastic contribution in a spatial-temporal form.

We have done a thorough analysis of the system's temporal evolution and its time and space correlations. From our results it is clear that, using two complementary SNR measures, a usual and a global one, we have obtained numerical evidence for two SR-like behaviors. In one hand a "normal" SR phenomenon occurs at frequencies that seem to correspond to a system's quasi-periodic behavior. On the other hand, we have found a SSSR-like behavior, indicating that there is an optimal system size for the analysis of the spatial system's response. As indicated before, the effect of noise is stronger when the chaos is underdeveloped.

We argue that these findings are of interest for an *optimal* climate prediction. It is clear that the inclusion of the effect of an external noise, that is a stochastic parametrization of unknown external influences, could strongly affect the deterministic system response, particularly through the possibility of an enhanced system's response in the form of resonant-like behavior. It is worth here remarking the excellent agreement between the resonant frequencies and wave length found here, and the estimates of Lorenz [18].

The effect of noise is weak respect to changes in the spatial structure, with the main frequencies remaining unaltered, but it is strong concerning the strength of the "self-generated" deterministic noise. In fact, in such a system and at the resonant frequencies, forecasting could be improved by the external noise due to the effect of suppression of the self-generated chaotic noise. The detailed analysis of such an aspect will be the subject of a forthcoming study [24].

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