

Vocal characteristics of prairie dog alarm calls across an urban noise gradient

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Behavioral Ecology

DOI: 10.1093/beheco/arz200

Published: 01/03/2020

Peer reviewed version

Cyswllt i'r cyhoeddiad / Link to publication

Dyfyniad o'r fersiwn a gyhoeddwyd / Citation for published version (APA): Shannon, G., McKenna, M. F., Wilson-Henjum, G., Angeloni, L., Crooks, K., & Wittemyer, G. (2020). Vocal characteristics of prairie dog alarm calls across an urban noise gradient. Behavioral Ecology, 31(2), 393-400. https://doi.org/10.1093/beheco/arz200

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1	Vocal characteristics of prairie dog alarm calls across an urban noise gradient
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24 Abstract

25 Increasing anthropogenic noise is having a global impact on wildlife, particularly due to 26 the masking of crucial acoustical communication. However, there have been few studies 27 examining the impacts of noise exposure on communication in free-ranging terrestrial 28 mammals. We studied alarm calls of black-tailed prairie dogs (*Cynomys ludovicianus*) 29 across an urban gradient to explore vocal adjustment relative to different levels of noise 30 exposure. There was no change in the frequency 5%, peak frequency or duration of the 31 alarm calls across the noise gradient. However, the minimum frequency -a commonly 32 used, yet potentially compromised metric – did indeed show a positive relationship with 33 noise exposure. We suspect this is a result of masking of observable call properties by 34 noise, rather than behavioural adjustment. In addition, the proximity of conspecifics and 35 the distance to the perceived threat (observer) did affect the frequency 5% of alarm calls. 36 These results reveal that prairie dogs do not appear to be adjusting their alarm calls in 37 noisy environments but likely do in relation to their social context and the proximity of a 38 predatory threat. Anthropogenic noise can elicit a range of behavioural and physiological 39 responses across taxa, but elucidating the specific mechanisms driving these responses 40 can be challenging, particularly as these are not necessarily mutually exclusive. Our 41 research sheds light on how prairie dogs appear to respond to noise as a source of 42 increased risk, rather than as a distraction or through acoustical masking as shown in 43 other commonly studied species (e.g. fish, songbirds, marine mammals).

44

Key words: acoustics, mammal, anthropogenic disturbance, communication, masking,predation

47 Introduction

48 Human-induced rapid environmental change is having far-reaching impacts on natural 49 ecosystems across the globe, affecting animal behaviour, demographic processes and 50 community composition (Sih et al. 2011). The pervasive nature of rising anthropogenic 51 noise levels across terrestrial and aquatic habitats provides a prime example of how 52 human activities can dramatically alter the environment over a comparatively short time 53 frame (Barber et al. 2010). During the past two decades, increasing research effort has 54 explored the effects of noise on animal behaviour and demography, with particular focus 55 on how anthropogenic noise affects acoustic communication (Shannon, McKenna, et al. 56 2016).

57 Songbirds in particular have been the focus of numerous studies on the effects of 58 anthropogenic noise on behaviour and communication in urban environments, due to 59 their relative abundance, the important role of vocal communication in many aspects of 60 their behaviour (e.g., territoriality, mate attraction and agonistic social interactions) and 61 the established methodology for studying changes in song structure and singing 62 behaviour (Slabbekoorn 2013). The seminal paper by Slabbekoorn and Peet (2003), 63 which demonstrated that elevated noise levels in urban environments significantly altered 64 vocal communication in great tits (*Parus major*), was a key catalyst for research effort on 65 this topic. Scientists exploring avian acoustic communication have demonstrated a range 66 of responses to mitigate the effects of noise exposure, which include adjusting the time of 67 vocalising (Fuller et al. 2007), increasing the amplitude of the call (Lowry et al. 2012), 68 lengthening the duration of the call (Díaz et al. 2011), reducing syllable rate (Potvin et al. 69 2011) and shifting the minimum call frequency upwards (Slabbekoorn and Ripmeester

70 2008). These behavioural adjustments are believed to be adaptive responses that reduce 71 the masking of key signals by low frequency anthropogenic noise, which is 72 predominantly concentrated at <2KHz (Brumm et al. 2017). Furthermore, evidence 73 indicates that anthropogenic noise exposure may structure animal communities (Francis 74 et al. 2009; Proppe et al. 2013), as species that vocalise at lower frequencies with limited 75 behavioural flexibility are forced to adjust their distribution (Francis 2015). This suggests 76 responses to noise are likely conditioned on the degree of plasticity in communication 77 modalities.

78 Although the effects of anthropogenic noise on acoustic communication have 79 been studied extensively across a range of taxa, including birds, marine mammals, 80 amphibians and even invertebrates, there has been limited exploration of these effects in 81 terrestrial mammals (Shannon, McKenna, et al. 2016). Terrestrial mammals display 82 flexibility in call structures relative to social and geophysical conditions (Ey and Fischer 83 2009; Townsend and Manser 2013), and recent work has demonstrated that mongooses 84 exhibit reduced responsiveness to conspecific and heterospecific vocalisations in road 85 noise (Kern and Radford 2016; Morris-drake et al. 2017). However, studies explicitly 86 exploring the effects of noise on vocalisations have largely been limited to research on 87 bats. For example, Brazilian free-tailed bats (Tadarida brasiliensis) reduced the 88 bandwidth of their echolocation search calls when exposed to noise (Bunkley and Barber 89 2015), fringe-lipped bats (Trachops cirrhosus) shifted from targeting prey-generated 90 sources of sound to using echolocation when hunting in noise (Gomes et al. 2016), and 91 Asian particolored bats (Vespertilio sinensis) simplified the complexity and raised the 92 amplitude of their social calls when exposed to traffic noise (Jiang et al. 2019) but did not

adjust the vocal rate or duration of these vocalisations (Song et al. 2019). Other studies
have also explored shifts in frequency and amplitude of echolocating bats, but the
researchers exposed the animals to noise with a specific frequency (bandpass filtered),
compared with the broadband frequencies that are typical of anthropogenic noise (Hage
et al. 2013; Hage et al. 2014). The paucity of research on a wider range of mammal
species risks overlooking the impacts of a key anthropogenic stressor on terrestrial
systems.

100 In this paper, we explore whether a gradient of increasing urban traffic and 101 associated environmental noise affects the alarm call characteristics of black-tailed prairie 102 dogs (*Cynomys ludovicianus*) - hereafter referred to as prairie dogs. Prairie dogs are prey 103 species for a wide range of grassland predators including badgers (Taxidea taxus), 104 coyotes (*Canis latrans*), hawks and snakes (Hoogland 1995). Alarm calls – a series of 105 rapid high-pitched barks – provide one of the key anti-predator strategies employed by 106 this group-living species (Hoogland 1995), but the production of these calls appears to be 107 influenced by social context. For example, prairie dogs have been shown to give alarm 108 calls more readily when in the presence of kin compared to unrelated conspecifics 109 (Hoogland 1983; Hoogland 1995). This provides evidence that the seemingly costly 110 behaviour of an individual alerting a predator to their presence may have indirect fitness 111 benefits (Shelley and Blumstein 2005). Moreover, we recently demonstrated that the 112 presence of young influenced the alarm call characteristics of adult prairie dogs -113 whereby they lowered the central concentration of energy in their calls (Wilson-Henjum 114 et al. 2019). The social context and function of alarm call production provides an 115 interesting avenue for exploring the effects of exposure to anthropogenic noise on animal

vocalisation, particularly when contrasted with findings from the significant body of
work focussing on advertisement calls and songs (reviewed by Shannon, McKenna, et al.
2016).

119 Although prairie dog populations across the United States have been dramatically 120 reduced as a result of land-use changes and disease (Miller, Ceballos, & Reading, 1994; 121 Miller et al., 2007), they have shown the ability to inhabit urban environments (Magle et 122 al. 2010; Magle and Fidino 2018). In common with other wildlife species that can survive 123 in human-dominated landscapes, this persistence is likely to be a function of their 124 behavioural flexibility, which allows them to adjust to the environmental conditions of 125 their surroundings (Lowry et al. 2013). Prairie dogs therefore provide an interesting study 126 species for furthering our understanding of behavioural and demographic responses to 127 anthropogenic disturbance in a social mammal. In addition to exploring vocal plasticity 128 relative to noise exposure in a free-ranging terrestrial mammal, this study also focuses on 129 a form of vocal communication that has received less attention in this field of research – 130 alarm calling to signal the presence of a perceived threat (Potvin et al. 2014; Templeton 131 et al. 2016). While calls and songs aimed at attracting mates and defending territories 132 play a crucial role in the reproductive success of an animal, alarm calls arguably have an 133 even more immediate and profound effect on fitness through the mediation of survival. 134 Our previous research found that prairie dogs exposed to noise adjusted their 135 vigilance and foraging behaviour, consistent with the risk disturbance hypothesis, which 136 predicts anthropogenic disturbance will elicit increased antipredator behaviour (Shannon 137 et al. 2014). Because of their enhanced vigilance, prairie dogs detected and responded to 138 an approaching predator quicker in noise than during the ambient control - contrary to the

139	distracted prey hypothesis (Shannon, et al., 2016). Here, we explore whether prairie dogs			
140	exhibit vocal plasticity in noise – a potential mechanism to overcome acoustical masking			
141	- to further illustrate how prairie dogs perceive and respond to this novel pollutant. This			
142	will not only broaden the types of communication studied in the context of increasing			
143	anthropogenic noise, but has implications for conserving animals in evolutionarily novel			
144	environments, such as urban areas that are dramatically expanding with human			
145	population growth. We predicted that prairie dogs would elevate the lower frequency			
146	limit of their alarm calls when exposed to increasing road traffic noise – so as to			
147	minimize acoustical masking.			
148				
149	Methods			
150	Study sites			
151	The study was conducted across three prairie dog colonies in predominantly shortgrass			
152	prairie habitat located within or adjacent to the city of Fort Collins, Colorado, USA. The			
153	sites were selected to provide a gradient of exposure to urban traffic and associated noise.			
154	Pineridge Natural Area (250 ha), located on the western edge of the city with a small			
155	country road on the northwest boundary (~750m from the center of the colony),			
156	experiences the least anthropogenic noise of the three colonies and is a site that we have			
157	used for previous research on prairie dog responses to road traffic noise (Shannon et al.			
158	2016). Coyote Ridge Natural Area, situated close to the southwest boundary of the city, is			
159	840 ha in extent and adjacent to a larger open space to the south and west; the center of			
160	the prairie dog colony is located ~350m from the relatively busy County Road 19. The			
161	Coterie Natural Area is a small (1.6 ha) site located within the city at the intersection of			

two main roads (~50m to the center of the colony), resulting in considerable levels of
urban noise. All three of the sites can be accessed by trails that are used by walkers,
runners and cyclists. The prairie dogs are therefore regularly exposed to human activity.

100

166 Alarm call measurements

167 Prairie dog alarm calls were recorded from 28 August to 6 December 2014 using a Rode 168 NTG-2 shotgun microphone, which was connected to a Roland Moore R-05 digital 169 recorder. Data collection was carried out during daylight hours (0700 - 1900) by the 170 same single observer (GWH). Alarm calls were elicited by the observer approaching a 171 randomly selected prairie dog – with a systematic approach employed to ensure that 172 different areas of the colony (and animals) were sampled from one study site visit to the 173 next. Once the prairie dog began alarm calling the observer remained stationary and 174 recorded 30 seconds of vocalization while the animal was in situ. Distance to the target 175 animal and the distance from this individual to their nearest neighbor was measured using 176 a laser range finder. All calls were recorded within a distance of 18m from the animal (mean \pm SD = 9m \pm 3) with small differences between sites (Pineridge = 10m \pm 2, Coyote 177 178 Ridge = $11m \pm 3$, The Coterie = $8m \pm 2$). In order to reduce the possibility that the same 179 prairie dog was selected more than once during the same recording session, the observer 180 ensured that there was a minimum of 30m (the average size of a burrow system; Sheets et 181 al. 1971) between the individuals targeted for inclusion in the study. Wind speed and the 182 prevailing weather conditions were all documented at the time of recording. A total of 183 137 alarm call recording periods were collected across the three sites (Pineridge = 46, 184 Coyote Ridge = 44, The Coterie = 47).

185	A band-limited automated detector was used in Raven Pro v1.5 to select each of
186	the individual barks in the 30-second calling bouts and to optimize extraction of call
187	parameters. The following settings were used in the detector: minimum frequency of
188	2000 Hz, maximum frequency of 15000 Hz, minimum signal duration of 0.008 seconds,
189	maximum signal duration of 0.2 seconds, minimum separation of 0.2 seconds, minimum
190	occupancy of 30 percent, and a signal-to-noise threshold of 15 dB. Before measurements
191	were extracted on the individual barks, all detections were examined manually for
192	accuracy and adjusted to maximize the detection of all barks within a recording period
193	and to ensure the entire bandwidth and duration of calls were selected. Because prairie
194	dogs produce short duration, broadband barks, a standardized maximum frequency
195	(15000 Hz) was used for each detection box. Random selections of half of the barks in a
196	calling bout $(n = 4516)$ were then measured.
197	Four acoustic metrics were calculated for each bark: (1) minimum frequency (Hz)
198	- the lower frequency limit of the call, a commonly used metric in previous studies; (2)
199	frequency 5% (Hz) – the frequency where the summed energy equals 5% of the total, a

200 measure of lower frequency properties; (3) peak frequency (Hz) – the frequency with the

201 highest concentration of energy; and (4) bark duration (milliseconds) (Figure 1).

202

203 Ambient sound level measurements

Ambient sound levels were measured using a calibrated Larson-Davis 831 sound level meter (frequency weighting = A) over a 2-minute period as soon as the vocalization recording was completed. Sound pressure levels were measured as 1-second frequency weighted (12.5Hz - 20kHz) equivalent continuous levels (L_{Aeq, 1s}). Although ambient

208	sound levels may fluctuate slightly from the time that the alarm call was recorded to the
209	time that the sound pressure level was measured, we believe this variation was minimal
210	relative to overall variation in ambient sound levels across sampling events and sites.
211	Furthermore, it was not possible to conduct the measurements simultaneously, as the
212	ambient sound level recordings would have been biased from the alarm call of the prairie
213	dog. The sound pressure levels were downloaded with the SLM Utility-G3 and
214	customized scripts in R were used to calculate the L_{Aeq} over 120 seconds associated with
215	each recording period (see Electronic Supplementary Material for details).
216	
217	Statistical analysis
218	To explore differences in prairie dog vocalisations across the three colonies, alarm call
219	characteristics were initially analysed using a one-way ANOVA with Tukey's HSD.
220	Response variables included the four acoustic metrics described above, and the analysis
221	calculated the mean call characteristics for each target animal, averaged across multiple
222	barks within a bout of alarm calling. The distribution of the residuals was plotted to
223	check that the assumptions of the model were met (e.g., normality and homogeneity). To
224	reduce the likelihood of type 1 errors with multiple comparisons of call parameters across
225	sites, we used an alpha level of 0.01 to assess statistical significance.
226	Next, a generalized linear mixed model (GLMM) framework using the lme4
227	package in R (R Core Development Team 2019) was used to understand the conditions
228	that correlate with changes in alarm call characteristics. Response variables included the
229	four-acoustic metrics, and characteristics of each individual bark were entered into the
230	analyses with the individual observation number included as a random effect to account

231	for the repeated measures (multiple barks) within a given alarm call. Akaike's
232	Information Criterion adjusted for small sample size (AICc) was used for model selection
233	(Burnham and Anderson 2002). A total of 29 candidate models were generated for each
234	of the response variables using combinations of five predictor variables (Table 1).
235	Predictor variables included the <i>ambient sound level</i> ($L_{Aeq, 120s}$) when the calls bouts were
236	recorded, Julian day to establish if there was a change in response over the course of the
237	fieldwork, distance recorded to account for variation in the distance between the observer
238	and the target animal, wind speed to control for the influence of fluctuating acoustic
239	conditions, and distance to the nearest neighbor to determine if proximity to a
240	conspecific influences the observed alarm call response (Table 1). Two interactions were
241	also included to determine whether the effect of noise level exposure on acoustic
242	parameters was modulated by distance to the observer (ambient sound level * distance
243	recorded), and/or distance to the nearest prairie dog (ambient sound level * distance to
244	the nearest neighbor). These predictor variables were normalized so that the relative
245	contribution could be determined in the model averaged output (Table 2). The
246	AICcmodavg package was used to extract AICc scores and model weights for candidate
247	models of each response variable. Model averaging was conducted across models
248	accounting for ≥ 0.95 of the AICc weight to extract parameter β estimates and their 95%
249	confidence intervals (CI). The significance of the results was assessed by whether the
250	95% CI overlapped zero. This research was approved according to Colorado State
251	University Animal Care and Use Committee protocol 13-4112A.
252	

254 **Results**

255 Pineridge Natural Area was the quietest of the three colonies with ambient sound levels

256 of 26-50 dB $L_{Aeq,120s}$ (N = 46), mean = 36 dB ± 2 (95% CI), while Coyote Ridge

- experienced ambient sound levels of 34-54 dB $L_{Aeq,120s}$ (N = 45), mean = 42 dB ± 1 (95%)
- 258 CI) and The Coterie had the highest ambient sound levels 49-76 dB $L_{Aeq,120s}$ (N = 47),
- 259 mean = 58 dB \pm 2 (95% CI).
- 260 The minimum frequency of prairie dog alarm calls differed across the three
- 261 colonies (ANOVA: $F_{2,134} = 8.703$, P = 0.0003); Pineridge had the lowest minimum
- frequency (mean = 1151 Hz \pm 197 SD) followed by Coyote Ridge (1218 Hz \pm 149 SD)

and The Coterie (1297 Hz \pm 161 SD: Figure 2a). The Tukey HSD test revealed a

264 significant difference in minimum frequency between Pineridge and The Coterie (P =

265 0.0002), but not between Coyote Ridge and The Coterie (P = 0.04) and Pineridge and

- 266 Coyote Ridge (P = 0.22). We did not detect significant differences across colonies for
- 267 frequency 5% (ANOVA: $F_{2,134} = 1.694$, P = 0.188), peak frequency (ANOVA: $F_{2,134} =$

268 1.442, P = 0.24) or bark duration (ANOVA: $F_{2,134} = 1.648$, P = 0.196; Figure 2).

Minimum frequency of alarm calls was predicted by six top models, with three models contributing 63% of the AICc weight (Table 2). Ambient sound level ($L_{Aeq, 120s}$) was a key parameter across these models, with increasing noise predicting elevated minimum frequency of alarm calls (Table 3). None of the other explanatory variables demonstrated a significant relationship with the minimum frequency of alarm calls (Table 3).

The frequency 5% call property was predicted by 10 top models, with three accounting for 54% of the AICc weight (Table 2). Ambient sound level ($L_{Aeq,120s}$) was not 277 a significant predictor, with little evidence that higher noise led to a lower frequency 278 alarm call (measured as frequency 5%) (Table 3). Frequency 5% was greater for alarm 279 calls recorded at distances further from the observer (Dist recorded) and when calling 280 prairie dogs were closer to the nearest neighbour (Dist Neighbor) (Table 3). 281 Peak frequency was predicted by 11 top models, of which three accounted for 282 50% of the AICc weight (Table 2). As with the analysis of frequency 5%, there was no 283 evidence of a clear relationship between the ambient sound level and the peak frequency 284 of the call (Table 3). Furthermore, no other variables were significant predictors of peak 285 frequency.

Bark duration was predicted by 7 top models, with three contributing 61% of the AICc weight (Table 2). No explanatory variables had a significant relationship with bark duration (Table 3).

289

290 Discussion

291 Alarm calls provide crucial information on the presence and proximity of predatory 292 threats – essential for prairie dogs, which are social prey species that are targeted by a 293 number of terrestrial and aerial predators (Hoogland 1995). As such, and in line with 294 previous research on a range of bird and marine mammal species (Shannon, McKenna, et 295 al. 2016), we predicted that prairie dogs would reduce the masking effect of urban noise 296 by increasing the lower frequency limit of their alarm calls when exposed to elevated 297 anthropogenic noise. The evidence for this, however, was limited. We did detect an 298 increase in the minimum frequency of alarm calls with increasing urban noise, but there 299 was no effect of urban noise on the frequency 5% metric, which is a more robust measure

300 of the minimum frequency of animal vocalisations (Brumm et al. 2017). Likewise, peak 301 frequency and bark duration of alarm calls were not related to ambient sound levels. 302 Previous studies have also shown that the frequency of bird vocalisations are not 303 consistently adjusted in urban noise across species (Hu and Cardoso 2010), and even 304 when they are modified, they can shift in the opposite direction to that predicted, i.e. with 305 lower frequency calls in noisier conditions potentially to increase transmission distance 306 (Potvin et al. 2014). For taxa with particularly low frequency calls, it may prove too 307 energetically costly (or physiologically challenging) to actually shift the frequency of 308 vocalisation high enough to reduce the risk of masking, while those that use higher 309 frequency calls are less affected by noise and therefore might not need to adjust their calls 310 (Hu and Cardoso 2010). Prairie dogs have short duration alarm calls that extend across a 311 broad range of frequencies from 1 kHz to >8 kHz, with a peak frequency of 312 approximately 3.5 kHz, while the energy in urban noise is generally focussed below 2.5 313 kHz. It may well be the case that the relatively high frequency of their vocalisations 314 means that prairie dogs do not experience significant masking from exposure to urban 315 noise.

While our findings of an increase in minimum frequency with rising noise level concur with previous studies, scientists have recently questioned the methods used to measure minimum frequency because they may result in false positives (Ríos-Chelén et al. 2017; Brumm et al. 2017). Indeed, the majority of studies on this topic have relied on researchers visually inspecting the spectrogram to determine the minimum vocal frequency, a method that has been shown to potentially bias the results, particularly if the observer has *a priori* expectations (Ríos-Chelén et al. 2017; Brumm et al. 2017).

Furthermore, the signal to noise ratio in acoustic data can result in the minimum frequency being masked under elevated noise levels, resulting in artificial inflation of the observed minimum frequency (Brumm et al. 2017). It was interesting to note the marked difference in our model results for the minimum frequency and frequency 5% metrics, further highlighting the risk of using the absolute minimum frequency when exploring vocal adjustments by animals in anthropogenic noise.

329 We found evidence for changes in vocal behaviour related to the social context of the 330 alarm calls. Prairie dogs that were at a greater distance from conspecifics (i.e. more 331 isolated), and therefore may have been at a higher risk of predation, produced calls with 332 lower frequencies. We suggest that this could be a result of reduced call amplitude, which 333 is typically positively correlated with call frequency (Brumm and Naguib 2009; Zollinger 334 et al. 2012; Nemeth et al. 2013) – however it is important to note that we were unable to 335 measure alarm call amplitude in this study. Such a strategy of producing softer low-336 amplitude calls, documented across a range of species, can reduce eavesdropping and 337 detection by a third-party (Reichard and Anderson 2015), in this case an approaching 338 predator in the form of a human observer. Prairie dogs also produced alarm calls with 339 increased lower frequencies when the observer (i.e., predator threat) was further from the 340 calling animal. Prairie dogs may elevate call amplitude, and consequently generate higher 341 frequency calls, when predators are at a greater distance to increase the likelihood the 342 vocalisation is received across a greater area of the colony, without unduly increasing the 343 risk to the caller. This is especially pertinent given that the function of the alarm call is to 344 both warn conspecifics of approaching danger and to communicate to the predator that 345 they have been detected (Isbell and Bidner 2016). Additional experiments conducted by

our research group demonstrated that prairie dogs adjusted their alarm calls – reducing
the central concentration of energy – when calling in the presence of vulnerable pups
(Wilson-Henjum et al. 2019). Adjustment in prairie dog communication, therefore,
appears to be structured by social context mediated by spatial proximity to an
approaching threat. However, this is an area of research that warrants further detailed
investigation to reveal the specific drivers of vocal modulation.

352 Unlike many previous studies that have explored the effects of anthropogenic 353 noise on communication, our research focussed on alarm calls rather than songs or 354 vocalisations that animals use to advertise their quality or fitness to conspecifics 355 (reviewed in Shannon, McKenna, et al. 2016). The effective communication distance for 356 an alarm call in a colonial species may be significantly less than that of a call or song 357 aimed at attracting a mate or defending a territory. Therefore, even though the ambient 358 noise levels were considerable (mean of 58 dB at the Coterie, which is comparable to 359 normal conversation at 1m), they may not be loud enough to sufficiently mask the alarm 360 call from being perceived by nearby conspecifics. This raises a number of interesting 361 future research avenues regarding the function of a given vocalisation and its 362 susceptibility to masking from anthropogenic noise, as well as the plasticity in response 363 exhibited across taxa. It is also important to note that practical limitations meant that we 364 only had three sites in our study design, each with a different noise exposure resulting in 365 some level of pseudoreplication. Ideally, further research on this topic will identify 366 multiple sites at each broad level of noise exposure.

367 Elucidating the specific mechanisms (e.g., distraction, masking, predatory threat,
 368 social context) driving behavioural responses to anthropogenic noise can prove

369 challenging, particularly as they are not necessarily mutually exclusive. Nevertheless, a 370 combination of natural experiments and playback approaches can be used to identify the 371 key mechanisms for specific taxa, which can greatly inform our understanding of the 372 effects of noise, as well as assist in developing effective mitigation of these impacts 373 (Francis and Barber 2013). Our work on free-ranging prairie dogs has demonstrated that 374 they adjust critical behaviours when exposed to noise - including increased vigilance and 375 reduced foraging – which suggests that noise is responded to as an elevated level of 376 perceived risk (Shannon et al. 2014). Furthermore, in contrast to a number of aquatic 377 species (Chan et al. 2010; Wale et al. 2013; Simpson et al. 2015), prairie dogs did not 378 exhibit distraction from an approaching predator under noisy conditions – indeed, they 379 actually became alert and took flight sooner in traffic noise than under quieter control 380 conditions (Shannon et al. 2016). While the findings presented here suggest that the 381 acoustic characteristics of prairie dog alarm calls are consistent across a broad range of 382 ambient noise levels, indicating that masking may not be a key driver shaping their vocal 383 behaviour under these conditions.

384

385 Funding

The National Park Service Natural Sounds and Night Skies Division funded this research.

388 Acknowledgements

We would like to thank J. Shanahan and A. Meyer at Fort Collins Natural Areas for
logistical support and permission to conduct the study, and L. Cordes for statistical
advice.

392	Data accessibility: Analyses reported in this article can be reproduced using the data
393	provided by Shannon et al. (2019).
394	
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544	Figure legends				
545	Figure 1. Spectrogram of black-tailed prairie dog alarm calls collected from the colony at				
546	The Coterie Natural Area. The extracted call parameters are shown for a single call.				
547	Spectrogram parameters: 512 fast Fourier transformation, Hann window, 50% overlap,				
548	93-Hz frequency resolution, 3.25 ms temporal resolution. The dark band of energy below				
549	2.5 kHz is generated by urban noise at the study site.				
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551	Figure 2. Mean (\pm 95% CI) values for the four acoustic metrics extracted from prairie				
552	dog calls ($n = 137$) across the three study sites with increasing noise exposure from left to				
553	right.				
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Table 1. Structure of candidate models assessed for the four response variables

566 (minimum frequency, frequency 5%, peak frequency and bark duration). Individual

- 567 observation number was included as a random effect.

Null
Sound level
Wind speed
Julian day
Dist recorded
Dist neighbor
Sound level + Wind speed
Sound level + Julian day
Sound level + Dist recorded
Sound level + Dist neighbor
Julian day + Wind speed
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Julian day + Dist reighbor
Dist recorded + Dist neighbor
Dist neighbour + Wind speed
Sound level + Julian day + Wind speed
Sound level + Julian day + Dist recorded
Sound level + Julian day + Dist neighbour
Sound level + Dist recorded + Wind speed
Julian day + Dist recorded + Wind speed
Julian day + Dist recorded + Dist neighbor
Wind speed + Dist recorded + Dist neighbor
Sound level + Windspeed + Dist recorded + Dist neighbor
Sound level + Dist neighbour + Dist recorded + Julian Day
Sound level + Windspeed + Dist recorded + Julian Day
Wind speed + Dist neighbour + Dist recorded + Julian Day
Sound level + Julian day + Wind speed + Dist recorded + Dist neighbor
Sound level * Dist recorded
Sound level * Dist Neighbor

Table 2. Top models for the four-acoustic metrics of prairie dog alarm calls (≥ 0.95 of the

571 AICc weight). All models include the individual observation number as a random effect.

	K	ΔAICc	AICc weight	
a) Minimum frequency				
Sound level + Dist recorded + Julian Day + Dist neighbor	7	0.00	0.29	
Sound level * Dist neighbor	6	0.84	0.19	
Sound level + Dist neighbor	5	1.24	0.15	
Sound level + Dist recorded + Dist neighbour + Wind speed	7	1.54	0.13	
Sound level + Dist recorded + Julian Day + Dist neighbor + Wind speed	8	1.70	0.12	
Sound level + Julian Day + Dist neighbor	6	1.92	0.11	
a) Frequency 5%				
Dist recorded + Dist neighbor	5	0.00	0.25	
Julian Day + Dist recorded + Dist neighbor	6	1.12	0.15	
Wind speed + Dist recorded + Dist neighbor	6	1.12	0.14	
Dist recorded + Dist neighbor + Julian Day + Wind speed	7	2.11	0.09	
Dist neighbor	4	2.59	0.07	
Sound level + Dist recorded + Julian Day + Dist neighbor	7	2.78	0.06	
Sound level + Dist recorded + Dist neighbor + Wind speed	7	2.90	0.06	
Dist neighbor + Wind speed	5	3.48	0.05	
Sound level + Dist recorded + Julian Day + Dist neighbor + Wind speed	8	3.71	0.04	
Julian Day + Dist neighbor	5	3.81	0.04	
b) Peak frequency				
Dist neighbour	4	0.00	0.19	
Dist recorded * Dist neighbor	6	0.27	0.16	
Dist recorded + Dist neighbor	5	0.49	0.15	
Dist neighbor + Wind speed	5	1.12	0.11	
Sound level + Dist neighbor	5	1.71	0.08	
Wind speed + Dist recorded + Dist neighbor	6	1.75	0.08	
Julian day + Dist neighbor	5	2.00	0.07	
Julian day + Dist recorded + Dist neighbor	6	2.50	0.05	
Sound level + Julian day + Dist neighbor	6	3.70	0.03	
Wind speed + Dist neighbor + Dist recorded + Julian Day	7	3.76	0.03	
Sound level + Windspeed + Dist recorded + Dist neighbor	7	3.76	0.03	

4	0.00	0.28
5	1.03	0.17
5	1.04	0.16
5	1.75	0.12
6	2.27	0.09
6	2.32	0.09
6	2.76	0.07
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Table 3. The observed relationship between each response variable and the model-

590 averaged parameters from the top models (β -estimate $\pm 95\%$ CI). Bold text denotes β -

591 estimates with 95% CI that do not overlap zero.

	Parameter	β Estimate	(95% CI)
Minimum frequency	Sound level	67.63	(20.18 / 115.09)
	Dist recorded	44.16	(-0.27 / 88.58)
	Dist neighbor	8.10	(-33.65 / 49.85)
	Julian day	25.29	(-13.03 / 63.60)
	Wind speed	-1.27	(-6.26 / 3.72)
	Sound level * Dist neighbor	-40.89	(-92.22 / 10.44)
Frequency 5%	Sound level	17.02	(-100.00 / 134.04)
	Dist recorded	125.31	(11.3 / 239.31)
	Dist neighbor	-144.57	(-258.96 / -30.18)
	Julian day	52.54	(-52.68 / 157.76)
	Wind speed	-6.93	(-20.72 / 6.86)
Peak frequency	Sound level	-50.22	(-176.87 / 76.43)
	Dist recorded	69.38	(-44.69 / 183.46)
	Dist neighbor	-45.05	(-159.71 / 69.61)
	Julian day	-2.74	(-109.24 / 103.77)
	Wind speed	-6.38	(-20.29 / 7.53)
	Sound level * Dist neighbor	-134.37	(-274.70 / 5.96)
Bark duration	Sound level	0.91	(-1.39 / 3.22)
	Dist recorded	-0.55	(-3.08 / 1.98)
	Dist neighbor	0.12	(-2.37 / 2.61)
	Julian day	-1.13	(-3.44 / 1.18)
	Wind speed	-0.02	(-0.33 / 0.28)
	Sound level * Dis neighbor	-1.34	(-4.43 / 1.74)