

Local NLLS Estimation of Semiparametric Binary Choice Models

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May 2012

Abstract

In this paper, nonlinear least squares (NLLS) estimators are proposed for semiparametric binary response models under conditional median restrictions. The estimators can be identical to NLLS procedures for parametric binary response models (e.g. Probit), and consequently have the advantage of being easily implementable using standard software packages such as Stata. This is in contrast to existing estimators for the model, such as the maximum score estimator (Manski, 1975, 1985) and the smoothed maximum score (SMS) estimator (Horowitz, 1992). Two simple bias correction methods—a proposed jackknife method and an alternative nonlinear regression function—result in the same rate of convergence as SMS. The results from a Monte Carlo study show that the new estimators perform well in finite samples.

JEL Classification: C13, C14, C25.

Keywords: binary response, median restriction, NLLS, bias reduction, jackknife.

1 Introduction

The binary response model studied in this paper is of the form

$$y_i = I[x_i'\beta_0 - \epsilon_i \geq 0]$$

where $I[\cdot]$ is the indicator function, y_i is the observed response variable, taking the values 0 or 1, and x_i is an observed vector of covariates which affect the behavior of y_i . Both the disturbance term ϵ_i , and the vector β_0 are unobserved, the latter often being the parameter estimated from a random sample $\{y_i, x_i'\}_{i=1}^n$.

The disturbance term ϵ_i is restricted in ways that ensure identification of β_0 . Parametric restrictions specify the distribution of ϵ_i up to a finite number of parameters and assume it is distributed independently of the covariates x_i . The resulting models are often considered too restrictive, as standard estimators are usually inconsistent if the distribution of ϵ_i is misspecified or conditionally heteroskedastic.

Semiparametric, or “distribution-free,” restrictions have also been imposed in the literature, resulting in a variety of estimation procedures for β_0 . For a thorough survey on the various restrictions and proposed estimators, see Powell (1994). In this paper we focus exclusively on the conditional median restriction,

$$\text{med}(\epsilon_i | x_i) = 0,$$

which is widely regarded as the weakest restriction imposed in the literature (cf. Powell, 1994).

Several estimators of β_0 have been proposed under this restriction. The first was the maximum score estimator proposed by Manski (1975), which maximized the objective function

$$M_n(\beta) = \frac{1}{n} \sum_{i=1}^n \{I[y_i = 1]I[x_i'\beta \geq 0] + I[y_i = 0]I[x_i'\beta < 0]\}. \quad (1.1)$$

Since y_i is a binary variable, this is numerically equivalent to minimizing the least absolute deviations (LAD) objective function:

$$M'_n(\beta) = \frac{1}{n} \sum_{i=1}^n |y_i - I[x_i'\beta \geq 0]|. \quad (1.2)$$

Manski (1975, 1985) established the estimator’s consistency and Kim and Pollard (1990) showed that its rate of convergence is $n^{-1/3}$ and established its limiting distribution, which is non-standard and non-Gaussian, making inference based on this distribution infeasible. As an alternative, Delgado, Rodríguez-Poo, and Wolf (2001) established that inference based on subsampling is possible in such models, but Abrevaya and Huang (2005) showed that the bootstrap does not consistently estimate the asymptotic distribution.

In an effort to improve the situation, Horowitz (1992) modified the maximum score procedure

by “smoothing” the objective function in (1.1). Specifically, his approach was to maximize

$$S_n(\beta) = \frac{1}{n} \sum_{i=1}^n \{I[y_i = 1]K_h(x'_i\beta) + I[y_i = 0](1 - K_h(x'_i\beta))\}, \quad (1.3)$$

where $K_h(\cdot) \equiv K(\cdot/h)$ for some smooth kernel function $K(\cdot)$ and h denotes a smoothing parameter which converges to 0 with the sample size. Under stronger smoothness conditions on the distributions of ϵ_i and x_i , Horowitz showed that the estimator converges at the rate¹ of $n^{-2/5}$ with an asymptotically normal distribution. Although this makes it possible to carry out standard asymptotic inference with the smoothed maximum score (SMS) estimator, Horowitz (2002) showed that the bootstrap provides asymptotic refinements and provides Monte Carlo evidence of improved finite sample performance relative to first-order asymptotic approximations.

Both Manski and Horowitz assume that at least one component of x_i has full support on the real line to ensure that β is point identified. More recently, Komarova (2008) has developed set estimators based on the maximum score objective function for the case when x_i is discrete, and thus β may only be partially identified. Blevins (2010) extends this idea to the case of fixed effects panel data models where x_i may be either discrete or continuous but bounded.

Although both the maximum score and smoothed maximum score estimators have desirable asymptotic properties, they are difficult to implement in practice. The maximum score estimator has a discontinuous objective function, ruling out gradient-based optimization methods. The smoothed maximum score estimator is also difficult to implement, as the objective function can have several local maxima. Horowitz (1992) suggested using the simulated annealing algorithm (Corana, Marchesi, Martini, and Ridella, 1987; Goffe, Ferrier, and Rogers, 1994) to search for a global maximum. Unfortunately, such an algorithm, which requires the selection of several “tuning” parameters by the researcher, is not available in standard econometric software packages.²

The difficulty in implementing the maximum score and smoothed maximum score estimators in practice is precisely what motivates the estimators introduced in this paper. Specifically, we propose procedures that are analogous to NLLS estimators of parametric models such as Probit, and can thus be easily implemented using standard software packages such as Stata.

The rest of the paper is organized as follows. The following section describes the new procedures in detail and explores their asymptotic properties. Section 3 discusses bias correction procedures for improving the asymptotic properties of the estimators. Section 4 explores the finite sample properties of the estimator by way of a small scale simulation study, and Section 5 concludes by summarizing and discussing areas for future research. The proofs of the asymptotic properties of the estimators are left to the appendix.

¹Horowitz (1993a) showed that this is the fastest possible rate of convergence under these conditions.

²Furthermore, even in cases where such algorithms are readily available, the local NLLS estimator developed in this paper still has the advantage that standard gradient-based optimization methods can be used, which generally converge much faster than stochastic search algorithms.

2 Local NLLS Estimators

The estimators proposed herein combine ideas from the maximum score and smoothed maximum score objective functions in (1.2) and (1.3). First, note that the maximum score objective function in (1.2) is equivalent to the quadratic loss objective function

$$\frac{1}{n} \sum_{i=1}^n (y_i - I[x_i' \beta \geq 0])^2,$$

since both y_i and the indicator function are binary. Next, we replace the indicator function above with a smooth kernel function. Just as the smoothed maximum score estimator employs a kernel function to smooth the indicator in (1.2), we replace the indicator function above with a kernel function. In the case of SMS, the kernel function serves to approximate a cumulative distribution function (cdf). We take the same approach here and use the standard normal distribution³ with cdf $\Phi(\cdot)$ and probability density function (pdf) $\phi(\cdot)$.

Formally, let h_n be a positive sequence of real numbers which decreases to zero with the sample size. The sequence h_n can be viewed as a bandwidth sequence used in nonparametric kernel estimation. Because β is only identified up to scale, we use the customary scale normalization used in semiparametric models (e.g. Horowitz, 1992), where we fix β_k , the coefficient on the last regressor, equal to one, and consider estimation of θ_0 only, where $\beta_0 = (\theta_0', 1)'$. Our NLLS estimator is defined as

$$\hat{\beta} = \arg \min_{\beta \in \Theta \times 1} \frac{1}{n} \sum_{i=1}^n \left(y_i - \Phi \left(\frac{x_i' \beta}{h_n} \right) \right)^2 \quad (2.1)$$

where $\hat{\beta} = (\hat{\theta}', 1)'$. The primary advantage of this estimator is that it is a simple modification of the standard NLLS objective function. Aside from imposing the scale normalization on β and rescaling the index $x_i' \beta$, the objective function is identical to that of the NLLS probit estimator which is widely used to estimate parametric binary choice models. As such, the estimator can be readily computed using standard software packages such as Stata.⁴

As with other semiparametric estimators for the binary choice model, and even the parametric Probit and Logit models, the estimated coefficients must be interpreted in light of the required scale normalization. That is, only relative magnitudes of the coefficients are identified and the sign of the coefficient β_k is the same as the sign of the partial effect of x_k on the response probability. Thus, all coefficients should be interpreted relative to the coefficient on a particular chosen component of x . Note that for the NLLS estimator above, these relative magnitudes are unchanged when scaling by the inverse of the bandwidth h_n .

³Actually, the cdfs of other random variables can be used as well, so for example NLLS Logit can also be used as an estimator. We only use the normal cdf since its values can be easily computed using standard software packages.

⁴For example, in Stata, the `nl` command fits an arbitrary nonlinear function by least squares. The Probit regression function can be constructed using Stata's `norm` command, which returns cumulative probabilities from the standard normal distribution.

Our first result regarding the asymptotic properties of the estimator is based on the following assumptions:

A1 The vectors $(x'_i, \epsilon_i)'$ are i.i.d.

A2 $\theta_0 \in \Theta$, a compact subset of \mathbb{R}^{k-1} .

A3 The support of x_i , denoted \mathcal{X} , is not contained in any proper linear subspace of \mathbb{R}^k .

A4 The density function of $x'_i\beta_0$ conditional on \tilde{x}_i (the first $k - 1$ components of x_i), denoted $f_{Z|\tilde{X}}(\cdot)$, is positive in a neighborhood of 0.

A5 $\text{med}(\epsilon_i | x_i) = 0$.

First, the following theorem, whose proof appears in the appendix, establishes the consistency of the estimator.

Theorem 2.1. *Under Assumptions A1–A5, if $h_n \rightarrow 0$, then $\hat{\theta} - \theta_0 \xrightarrow{P} 0$.*

Next, we consider the rate of convergence and limiting distribution. We strengthen our assumptions to be able to draw comparisons to the smoothed maximum score estimator and impose conditions that are identical to those in Horowitz (1992).

A1' The vectors $(y_i, x'_i)'$ are i.i.d.

A2' The support of x_i , denoted \mathcal{X} , is not contained in any proper linear subspace of \mathbb{R}^k , and $0 < P(y_i = 1 | x_i) < 1$ almost surely. The density of the last component of x_i conditional on \tilde{x}_i is positive on the real line.

A3' $\text{med}(\epsilon_i | x_i) = 0$ almost surely.

A4' θ_0 is in the interior of a compact set $\Theta \subset \mathbb{R}^{k-1}$.

A5' Letting $\|\cdot\|$ denote the Euclidean norm, we have $E[\|\tilde{x}_i\|^4] < \infty$.

A6' The density function of $x'_i\beta_0$ conditional on \tilde{x}_i , denoted $f_{Z|\tilde{X}}(\cdot)$, is positive and continuously differentiable with bounded derivative.

A7' The conditional probability function of y_i , expressed as a function of \tilde{x}_i and $x'_i\beta_0$, is twice continuously differentiable with respect to $x'_i\beta_0$ with bounded derivatives for $x'_i\beta_0$ in a neighborhood of 0, for all \tilde{x}_i .

A8' The matrix

$$Q = E[\tilde{P}_2(\tilde{x}_i, 0)\tilde{x}_i\tilde{x}'_i f_{Z|\tilde{X}}(0|\tilde{x}_i)]$$

is nonsingular, where $\tilde{P}(\tilde{x}_i, x'_i\beta_0)$ denotes the conditional probability of $y_i = 1$ given x_i , which has been reparametrized as a function of $\tilde{x}_i, x'_i\beta_0$, and $\tilde{P}_2(\cdot, \cdot)$ denotes the partial derivative of $\tilde{P}(\cdot, \cdot)$ with respect to its second argument.

The following theorem characterizes the rate of convergence and limiting distribution of the estimator as a function of h_n . The proof of the theorem is left to the appendix.

Theorem 2.2. *Suppose that A1'–A8' hold and $h_n \rightarrow 0$.*

1. *If $nh_n^3 \rightarrow \infty$, then $h_n^{-1}(\hat{\theta} - \theta_0) \xrightarrow{P} \kappa$ where κ is a k -dimensional vector of constants.*
2. *If $h_n = O(n^{-1/3})$, then $n^{1/3}(\hat{\theta} - \theta_0) \xrightarrow{d} B$ where the random vector B has non-standard (i.e. non-Gaussian) distribution.*

Thus, the asymptotic properties of the NLLS estimator are similar to that of the maximum score estimator Manski (1975, 1985). In particular, the rate of convergence can be as fast as the $n^{-1/3}$ and the limiting distribution is non-Gaussian, as is the case with the maximum score estimator.⁵

Note that although the point estimates will be correct, the standard errors reported by a local nonlinear least squares routine are not correct. Furthermore, because of the complicated nature of the limiting distribution, inference based directly on Theorem 2.2 appears to be infeasible. Alternative methods are necessary, such as the bootstrap, which performs well for the closely-related smoothed maximum score estimator. See, for example, Section 4.3.3 of Horowitz (2009) on the use of the bootstrap for SMS.

The rate of convergence is slow, relative to the smoothed maximum score estimator of Horowitz (1992), due to the fact that the bias of the estimator converges at the rate h_n , in contrast to the rate h_n^2 for the smoothed maximum score estimator. Thus, given the different rates of convergence, the situation is similar to the differing rates for one- and two-sided kernel estimators in nonparametric density and regression estimation.

Fortunately, the rate of convergence of the local NLLS estimator can be improved by correcting the bias. The following section considers two procedures that result in the same rate of convergence as SMS while remaining easily implementable in standard statistical software packages.

3 Bias Correction Procedures

To motivate the bias correction procedures we propose, the following theorem, whose proof is left to the appendix, establishes a linear representation for the local NLLS estimator.

Theorem 3.1. *Assume Assumptions A1'–A8' hold, $h_n \rightarrow 0$, and $nh_n^3 \rightarrow \infty$. Then*

$$\hat{\theta} - \theta_0 = Q^{-1} \frac{1}{nh_n} \sum_{i=1}^n (\psi_{ni} - \mathbb{E}[\psi_{ni}]) + Q^{-1} \frac{\mathbb{E}[\psi_{ni}]}{h_n} + o_p\left(1/\sqrt{nh_n}\right)$$

where

$$\psi_{ni} = \left(y_i - \Phi\left(\frac{x_i' \beta_0}{h_n}\right) \right) \phi\left(\frac{x_i' \beta_0}{h_n}\right) \tilde{x}_i$$

⁵For the NLLS estimator, the non-Gaussianity stems from the result that the Hessian term in its linear representation converges to a random matrix, implying the estimator has an asymptotically mixed normal distribution (cf. van der Vaart and Wellner, 1996, Section 9.6).

It can be shown by a standard change of variables argument that the “bias term” in the linear representation, $Q^{-1} \frac{E[\psi_{ni}]}{h_n}$, is only of order h_n . As alluded to in the previous section, this is why the local NLLS probit estimator can only achieve a maximum rate of convergence of cube-root consistency. We propose simple methods for ensuring that the bias of the estimator is $O(h_n^2)$, which will enable a rate of convergence of $\hat{\theta}$ of $O(n^{-2/5})$, as with the SMS estimator, if $h_n = O(n^{-1/5})$.

3.1 Jackknifed Local NLLS

The first method we propose for reducing the order of bias for the local NLLS estimator is analogous to the “jackknife” method used in nonparametric estimation (Schucany and Sommers, 1977; Bierens, 1987). Our method involves constructing an estimator for θ_0 by simply taking a weighted average of two local NLLS estimators that involve two distinct constants in the smoothing parameter. We note that this procedure can still be performed using standard software packages such as Stata—it just involves computing the local NLLS estimator twice.

To construct our proposed jackknife estimator, let $h_{1n} = \kappa_1 n^{-1/5}$ and $h_{2n} = \kappa_2 n^{-1/5}$ denote two smoothing parameters, where κ_1 and κ_2 are positive constants. Let w_1 and w_2 denote the weights that will be assigned to the two estimators obtained by using smoothing parameters h_{1n} and h_{2n} . We impose the following conditions⁶ on w_1, w_2, κ_1 , and κ_2 :

$$\begin{aligned} w_1 + w_2 &= 1, \\ w_1 \kappa_1 + w_2 \kappa_2 &= 0. \end{aligned}$$

Let $\hat{\theta}_1$ and $\hat{\theta}_2$ denote the local NLLS estimators obtained using h_{1n} and h_{2n} as smoothing parameters, respectively. We define the jackknife NLLS estimator as

$$\hat{\theta}_{jk} = w_1 \hat{\theta}_1 + w_2 \hat{\theta}_2.$$

The following theorem, whose proof can be found in the appendix, characterizes the asymptotic properties of the jackknife NLLS estimator.

Theorem 3.2. *Under Assumptions A1’–A8’, if $h_n = O(n^{-1/5})$, then*

$$n^{2/5}(\hat{\theta}_{jk} - \theta_0) \xrightarrow{d} N(\mathcal{B}_{jk}, Q^{-1} V_{jk} Q^{-1})$$

where

$$Q = E[\tilde{P}_2(\tilde{x}_i, 0) \tilde{x}_i \tilde{x}_i' f_{Z|\tilde{X}}(0|\tilde{x}_i)],$$

$$V_{jk} = V_1(c_1 w_1^2 \kappa_1^{-1} + c_1 w_2^2 \kappa_2^{-1} + 2w_1 w_2 c_2 \kappa_1^{-1}),$$

⁶We note that $w_1, w_2, \kappa_1, \kappa_2$ need not be constants—they can all be functions of x_i and the arguments used in this section still carry through. We only assume they are constants for ease of exposition.

and

$$V_1 = \mathbb{E}[\tilde{x}_i \tilde{x}_i' f_{Z|\tilde{X}}(0|\tilde{x}_i)],$$

with

$$c_1 = \int \Phi^2(u) \phi^2(u) du,$$

$$r_\kappa = \kappa_1 / \kappa_2,$$

$$c_2 = \int \phi(u) \phi(u/r_\kappa) (0.5(1 - \Phi(u) - \Phi(u/r_\kappa)) + \Phi(u)\Phi(u/r_\kappa)) du,$$

and

$$\mathcal{B}_{jk} = (w_1 \kappa_1^2 + w_2 \kappa_2^2) \frac{1}{2} \mathbb{E} \left[\int \left\{ \left(\frac{1}{2} - \Phi(u) \right) f_{Z|\tilde{X}}(0|\tilde{x}_i) + 2\tilde{P}_2(\tilde{x}_i, 0) f'_{Z|\tilde{X}}(0|\tilde{x}_i) \right. \right. \\ \left. \left. + \tilde{P}_{22}(\tilde{x}_i, 0) f_{Z|\tilde{X}}(0|\tilde{x}_i) \right\} u^2 \phi(u) du \tilde{x}_i \right]$$

where $\tilde{P}_{22}(\cdot, \cdot)$ denotes the second derivative of $\tilde{P}(\cdot, \cdot)$ with respect to its second argument.

Thus the jackknifed local NLLS estimator can achieve the same rate of convergence as the smoothed maximum score estimator and has an asymptotic normal distribution. In standard non-parametric estimation, the jackknife is used to achieve bias reduction and attain the optimal rate of convergence for estimating a density or regression function. Here the motivation of combining NLLS estimators is to achieve bias reduction and attain the same rate of convergence as the smoothed maximum score estimator, which is the optimal rate under assumptions A1'–A8' (Horowitz, 1993a).

Furthermore, the form of the limiting distribution, which depends on the weights and constants, suggests choice of those parameters to minimize the asymptotic mean squared error. The optimal choices are discussed in Section A.5 of the appendix, as is a procedure to construct a feasible optimal jackknife estimator.

3.2 A Different Nonlinear Regression Function

As discussed in the proofs of Theorems 2.2 and 3.1, the bias problem of the local NLLS is associated with the fact that the normal cdf is used. An alternative bias correction procedure would be to use a function $F(\cdot)$ in the NLLS objective function as opposed to using the normal cdf $\Phi(\cdot)$. The bias term of the NLLS probit was of order h_n because $\int \Phi(u) \phi(u) u du \neq 0$ and the function $F(\cdot)$ will have to be chosen so the analogous integral $\int F(u) f(u) u du$, with $f(\cdot) = F'(\cdot)$, is 0.

Importantly, it is no more difficult to implement the estimator using a general function F than with the normal cdf because NLLS procedures in common statistical packages such as Stata allow the user to provide a generic regression function.

The restrictions preclude $F(\cdot)$ from being a cumulative distribution function, making this approach analogous to the use of higher order kernel functions⁷ which are not density functions in nonparametric density/regression estimation. Let $\hat{\theta}_F$ denote the NLLS estimator with $F(\cdot)$ replacing $\Phi(\cdot)$ in (2.1). The theorem below, whose proof can be found in the appendix, establishes that the following conditions on $F(\cdot)$ are sufficient for $\hat{\theta}_F$ to converge at the rate of $n^{-2/5}$ with an asymptotic Gaussian distribution.

$$\mathbf{F1} \quad \int (\frac{1}{2} - F(u))f(u) du = 0$$

$$\mathbf{F2} \quad \int f(u)u du = 0$$

$$\mathbf{F3} \quad \int F(u)f(u)u du = 0$$

$$\mathbf{F4} \quad \int ([\frac{1}{2} - F(u)]f'(u) - f^2(u)) du = 0$$

$$\mathbf{F5} \quad 0 < |\int f'(u)u du| < \infty$$

$$\mathbf{F6} \quad |\int ([\frac{1}{2} - F(u)]f'(u) - f^2(u)) u du| < \infty$$

Theorem 3.3. *Suppose that A1'–A8' hold, that $F(\cdot)$ satisfies F1–F6, and that $h_n = O(n^{-1/5})$. Then*

$$n^{2/5}(\hat{\theta}_F - \theta_0) \xrightarrow{d} N(\mathcal{B}_F, Q_F^{-1}V_FQ_F^{-1})$$

where

$$\begin{aligned} \mathcal{B}_F = \frac{1}{2} \int_{\tilde{X}} \int \left\{ \left(\frac{1}{2} - F(u) \right) f_{Z|\tilde{X}}(0|\tilde{x}_i) + 2\tilde{P}_2(\tilde{x}_i, 0)f'_{Z|\tilde{X}}(0|\tilde{x}_i) \right. \\ \left. + \tilde{P}_{22}(\tilde{x}_i, 0)f_{Z|\tilde{X}}(0|\tilde{x}_i) \right\} u^2 f(u) du \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i), \end{aligned}$$

$$Q_F = E \left[\left(c_{F_2}\tilde{P}_2(\tilde{x}_i, 0)f_{Z|\tilde{X}}(0|\tilde{x}_i) + c_{F_3}f'_{Z|\tilde{X}}(0|\tilde{x}_i) \right) \tilde{x}_i \tilde{x}_i' \right],$$

and $V_F = c_{F_1} \cdot E[\tilde{x}_i \tilde{x}_i' f_{Z|\tilde{X}}(0|\tilde{x}_i)]$, with $c_{F_1} = \int F^2(u)f^2(u) du$, $c_{F_2} = \int f'(u)u du$, and $c_{F_3} = \int ([\frac{1}{2} - F(u)]f'(u) - f^2(u)) u du$.

Remark 3.1. *When the function $F(\cdot)$ satisfies the following two symmetry properties, then the integral in condition F6 and c_{F_3} is zero:*

$$\mathbf{F7} \quad F(-u) = 1 - F(u),$$

$$\mathbf{F8} \quad f(u) = f(-u).$$

In this case, Q_F simplifies to $Q_F = E \left[c_{F_2}\tilde{P}_2(\tilde{x}_i, 0)f_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i \tilde{x}_i' \right]$. The particular family of regression functions we propose below satisfies these properties.

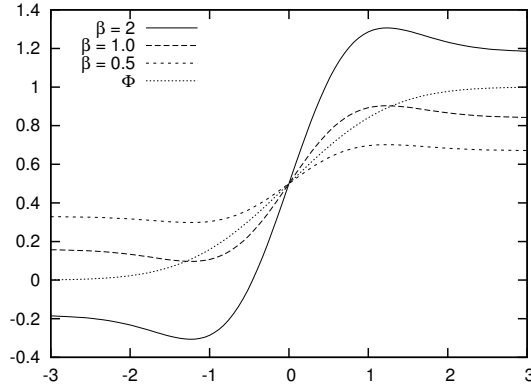


Figure 1: Nonlinear regression functions F compared to the normal cdf Φ

Functions satisfying the required conditions can be constructed using the error function, defined as $\text{erf}(u) = \frac{2}{\sqrt{\pi}} \int_0^u e^{-t^2} dt$. For example, functions of the form

$$F(u) = \frac{1}{2} + \alpha \cdot \text{erf}\left(\frac{u}{\sqrt{2}}\right) + \beta \cdot \text{erf}(u) \quad (3.1)$$

with $\alpha = -\frac{1}{2}(1 - \sqrt{2} + \sqrt{3})\beta$ and $\beta \neq 0$ satisfy the main conditions F1–F6 as well as the symmetry properties F7–F8.

This family of functions is plotted in Figure 1 for several values of β alongside the standard normal cdf $\Phi(u)$. Note that $\Phi(u)$ has the form above, but with $\alpha = 1/2$ and $\beta = 0$, so it is not a member of the same family of functions because the coefficient β is zero, violating the conditions required for unbiasedness, which cdfs do not satisfy. This family of alternative regression functions is examined in the following section, which discusses a series of Monte Carlo experiments designed to shed light on the small-sample properties of the estimator.

With the more standard rate and limiting distribution of the NLLS estimator, a natural extension to consider is then a weighted NLLS procedure. It is well known that in parametric settings, the efficiency of the NLLS Probit estimator can be improved by weighting the observations, and one can make the NLLS estimator as efficient as the MLE using optimal weights. For the problem at hand, the weight function can be chosen to minimize the asymptotic mean squared error of the estimator. The appendix provides the form of this optimal weighting matrix and further discusses implementation of a feasible weighted NLLS approach.

⁷See, for example, Newey, Hsieh, and Robins (2004) on “twicing kernels”, which are higher order.

4 Monte Carlo Results

In this section, we investigate the small-sample performance of the estimators introduced in this paper by ways of a small-scale Monte Carlo study. The model used in this simulation study is

$$y_i = I[\alpha_0 + x_{1i}\beta_0 + x_{2i} + \epsilon_i > 0]$$

where x_{1i} has a chi-square distribution with 1 degree of freedom (minus its mean of 1), x_{2i} has a standard normal distribution, α_0 was set at -0.5 and β_0 at -1. Three different distributions for ϵ_i were simulated: standard normal, chi-square with 1 degree of freedom minus its median, and Cauchy. Both homoskedastic and heteroskedastic designs were simulated, the heteroskedastic designs involved a multiplicative scale factor of the form $\exp(x_{1i} \cdot |x_{2i}|)$.

Tables I–VI report results for comparing the performance of the estimators discussed in this paper: the local NLLS (NLLS), jackknifed local NLLS (JKNLLS), local NLLS with an alternative regression function (NLLSF), and smoothed maximum score (SMS) estimators. For NLLSF, we use the regression function in (3.1) with $\beta = 1$. Reported are the mean bias, median bias, root mean square error (RMSE), and median absolute deviation (MAD) for sample sizes $n = 100, 200$, and 400, with 4001 replications each.

For each estimator, we select the bandwidth for each sample as follows. For NLLS, we choose h_n using cross-validation to minimize the leave-one-out sum of squared residuals. For JKNLLS, the weights and bandwidth constants are chosen for each sample according to the procedures outlined in the appendix. JKNLLS-1 indicates the first method, which chooses w_1 , w_2 , κ_1 , and κ_2 to minimize the constant portion of the asymptotic mean square error. For JKNLLS-2, we choose these constants to minimize an estimate of the asymptotic mean square error using a finite sample estimate of the asymptotic variance matrix. For NLLSF, we use the optimal bandwidth selection procedure suggested by Horowitz (1992) for SMS since both estimators have a similar asymptotically linear structure, which yields asymptotic normality with bias on the order of h_n^2 in both cases. For SMS, a normal kernel function was used and we compared three bandwidth selection procedures. For SMS-1, we use the same optimal SMS bandwidth selection procedure described above.⁸ For SMS-2, we select the bandwidth using Silverman’s rule of thumb, $h_n = 1.06 \cdot \hat{\sigma} \cdot n^{-1/5}$ where $\hat{\sigma}$ is the sample standard deviation of y_i . Finally, for SMS-3 we choose the bandwidth using leave-one-out least absolute deviations cross-validation.

All the estimators were computed⁹ using the Nelder-Mead simplex algorithm with multiple starting values, including the OLS and LAD estimates and zero.

As the results indicate, the finite sample performance is mostly, but not entirely in accordance

⁸For both NLLSF and SMS-1 we iterate this procedure, as suggested by Horowitz (1992). For each sample, we first obtain an estimate of $\hat{\theta}^{(0)}$ using the bandwidth $h_n^{(0)} = n^{-1/5}$. We then estimate the optimal bandwidth $h_n^{(1)}$, which we use obtain a second estimate $\hat{\theta}^{(1)}$. Then, using the second estimate, we obtain a second estimate of the optimal bandwidth, $h_n^{(2)}$. Finally, we report the estimate $\hat{\theta}^{(2)}$ obtained using the bandwidth $h_n^{(2)}$.

⁹The simulation study was performed in Fortran, despite the fact that the new estimators were motivated by the fact that they could be computed with Stata. Fortran was used so all estimators could be computed using a common random number generator, as SMS cannot be computed with Stata.

with the asymptotic theory. The biggest surprise is that in terms of RMSE, for some designs, the standard NLLS performs as well as, if not better than the other estimators despite its slower rate of convergence. The jackknife bias correction procedure (JKNLLS) generally results in a lower bias than the NLLS, but it appears this sometimes comes at the expense of a larger variance, leading to a higher finite-sample RMSE in some designs. Furthermore, the alternative regression function (NLLSF) achieves a relatively low RMSE uniformly across the experiments, having the lowest or second-lowest RMSE in all but two experiments. In all of the normal and Cauchy designs, and in all but the largest sample size chi-square specifications, it is second only to the baseline NLLS estimator. For the chi-square design with our largest sample size, the SMS-1 and SMS-2 estimators have the lowest RMSE, followed by NLLSF.

The NLLS estimators appear to perform better in the homoskedastic designs. The situation here is similar to that of parametric NLLS estimators, for which weighting can improve efficiency under heteroskedasticity. For example, in the probit model, an optimally weighted NLLS estimator is asymptotically equivalent to MLE. We discuss a weighted NLLS extension in the appendix.

Interestingly, both estimators proposed outperform the SMS in many designs, especially for the smaller sample sizes, though it may well be the case that relative performance depends on the bandwidth choice. Again, it is quite surprising that the standard NLLS sometimes outperforms SMS, as the latter converges at a faster rate.

Overall, these results indicate that the NLLS estimators introduced in this paper are a viable alternative to the smoothed maximum score estimator in empirical applications, since it appears that their ease in implementation does not come at the expense of finite sample performance.

5 Conclusions

In this paper, new estimation procedures for the binary response model under conditional median restrictions were proposed. The estimators were based on applying NLLS procedures for parametric models to this semiparametric model. Their primary advantage is their relative computational simplicity, as they can be applied using standard software packages such as Stata. A simulation study indicates these estimators perform adequately well in finite samples.

The work here suggests areas for future research. First we note that variations of the (smoothed) maximum score estimator have been developed for the analysis of binary choice in panel data (Manski, 1987; Charlier, Melenberg, and van Soest, 1995) and choice-based sampling model (Manski, 1986; Horowitz, 1993b, 2009), so the NLLS approach proposed in this paper can be extended to those settings as well. Thus, future work can derive the asymptotic properties of these estimators.

Second, the relative efficiency of the procedures introduced here needs to be explored, specifically in comparison to the SMS and its more efficient variant in Kotlyarova and Zinde-Walsh (2002). Related to this, efficiency gains of the NLLS estimator, either by optimally selecting the weights in the proposed jackknife or by a weighted nonlinear least squares (WNLLS) estimator, needs to be studied.

Furthermore, it would be useful to explore whether rates of convergence arbitrarily close to root- n can be attained by the proposed estimators under stronger smoothness conditions,¹⁰ as is the case with the smoothed maximum score estimator.

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¹⁰Specifically, the rate of convergence of the smoothed maximum score estimator is $n^{-h/(2h+1)}$ if a smoothing “kernel” function of order h is used, if $f_{Z|\tilde{X}}^{(i)}(\cdot)$ is continuous and bounded for $i = 1, \dots, h - 1$, and $\tilde{P}_2^{(i)}(\tilde{x}_i, x'_i\beta_0)$ is continuous and bounded in a neighborhood of 0 for almost every \tilde{x}_i for $i = 1, \dots, h$. As $h \rightarrow \infty$, the rate of convergence can be made to approach $n^{-1/2}$.

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A Appendix

A.1 Proof of Theorem 2.1

We first establish consistency using the standard consistency theorem of Newey and McFadden (1994, Theorem 2.1). The proof is similar to those found in Manski (1985) and Horowitz (1992).

Compactness follows from Assumption A2. Uniform convergence follows by the boundedness of the objective function and the law of large numbers, which follows from Assumption A1. Continuity of the limiting objective function follows from Assumption A4. We note by the assumption that $h_n \rightarrow 0$, that the component of the limiting objective function that depends on β is:

$$E[(1 - 2\tilde{P}_i)(I[x'_i\beta > 0] - I[x'_i\beta_0 > 0])]$$

where \tilde{P}_i denotes $\tilde{P}(\tilde{x}_i, x'_i\beta_0) \equiv P(y_i = 1|x_i)$. The above expectation is clearly 0 for $\beta = \beta_0$. By the strict monotonicity of $\Phi(\cdot)$, which is $> (<)1/2$ if its argument is $> (<)0$, and Assumptions A3, A4, A5, it follows that this component of the objective function is strictly positive if $\beta \neq \beta_0$, implying it is uniquely minimized at β_0 . This establishes consistency. \blacksquare

A.2 Proof of Theorems 2.2 and 3.1

This section derives the asymptotic theory for the NLLS estimator. The strategy adopted is to expand the first order condition as is typically done in standard parametric distributional theory, and separately derive the asymptotic properties of the ‘‘Hessian’’ and ‘‘score’’ terms. This approach permits the proof of both theorems in a common setting.

Before proving asymptotic theory, we briefly discuss some additional conditions imposed as well as notation used throughout. Throughout this section $\|\cdot\|$ will denote the Euclidean norm. Ranges of integration are denoted by subscripts, or otherwise meant to be the real line. Also, here we assume \tilde{x}_i , whose distribution function will be denoted by $P_{\tilde{X}}(\cdot)$, has bounded support, denoted by $\tilde{\mathcal{X}}$. This can be relaxed at the expense of longer proofs, either by decomposing the support of \tilde{x}_i and using Assumption A5', or along the lines of the proofs in de Jong and Woutersen (2011).

Furthermore, the following notation will also be adopted: let

$$\begin{aligned} &\Phi_{ni}, \phi_{ni}, \phi'_{ni}, \hat{\Phi}_{ni}, \hat{\phi}_{ni}, \hat{\phi}'_{ni}, \Phi^*_{ni}, \phi^*_{ni}, \phi'^*_{ni} \text{ denote} \\ &\Phi(x'_i\beta_0/h_n), \phi(x'_i\beta_0/h_n), \phi'(x'_i\beta_0/h_n), \Phi(x'_i\hat{\beta}/h_n), \phi(x'_i\hat{\beta}/h_n), \phi'(x'_i\hat{\beta}/h_n), \\ &\Phi(x'_i\beta^*/h_n), \phi(x'_i\beta^*/h_n), \phi'(x'_i\beta^*/h_n), \end{aligned}$$

respectively, where β^* denotes an intermediate value.

Throughout the proofs, we will use the following properties of the standard normal distribution¹¹ (all integrals below are from $-\infty$ to $+\infty$ and $\phi'(\cdot)$ denotes the derivative of the standard normal density function):

- $\int \phi'(u) du = 0$

¹¹Note the list of properties is not minimal in the sense that some on the list follow from others. They are listed in this fashion with the hope of making arguments in the proofs easier to follow.

- $\int u\phi'(u) du = -1$
- $\int(\Phi(u)\phi'(u) + \phi^2(u)) du = 0$
- $\int \Phi(u)\phi(u) du = \frac{1}{2}$
- $\int [(\frac{1}{2} - \Phi(u))\phi'(u) - \phi^2(u)] du = 0$
- $\int [(\frac{1}{2} - \Phi(u))\phi'(u) - \phi^2(u)] u du = 0$
- $\int \phi(u)^2 [\frac{1}{2} - \Phi(u)] du = 0$

Proceeding with the proof, we will let $\varepsilon > 0$ denote an arbitrarily small constant such for $|x'_i\beta_0| < \varepsilon$, the smoothness conditions in Assumptions A6' and A7' hold.

The first order condition can now be expressed as

$$\frac{1}{n} \sum_{i=1}^n (y_i - \hat{\Phi}_{ni}) \hat{\phi}_{ni} \tilde{x}_i = 0.$$

The usual mean value expansion yields

$$\hat{\theta} - \theta_0 = \left(\frac{1}{nh_n^2} \sum_{i=1}^n \left((y_i - \Phi_{ni}^*) \phi_{ni}^* - \phi_{ni}^{2*} \right) \tilde{x}_i \tilde{x}_i' \right)^{-1} \frac{1}{nh_n} \sum_{i=1}^n (y_i - \Phi_{ni}) \phi_{ni} \tilde{x}_i. \quad (\text{A.1})$$

Before proceeding with the remainder of the proofs, we first establish the following preliminary results which will be used in the remainder. The first two results will be used to establish limits of several integrals we encounter in the main proof. The third result is similar to (A16) in Horowitz (1992).

Lemma A.1. *Let ϕ denote the standard normal pdf and let the functions $g_{zx} : \mathbb{R} \times \mathcal{X} \rightarrow \mathbb{R}$ and $g_x : \tilde{\mathcal{X}} \rightarrow \mathbb{R}$ and the vector $\delta \in \mathbb{R}^{k-1}$ be given. Suppose that A6' holds, that \tilde{x}_i has bounded support, and that there is a constant $M < \infty$ such that $\sup |g_{zx}| < M$ and $\sup |g_x| \leq M$. Let $\phi_{ni\delta}$ denote $\phi(\frac{z_i}{h_n} + \tilde{x}_i'\delta)$. Then,*

$$h_n^{-1} \int_{\tilde{\mathcal{X}}} \int_{|z_i| \geq \varepsilon} g_{zx}(z_i, \tilde{x}_i) \phi_{ni\delta} f_{Z|\tilde{X}}(z_i | \tilde{x}_i) dz_i g_x(\tilde{x}_i) dP_{\tilde{X}}(\tilde{x}_i) = o(h_n). \quad (\text{A.2})$$

Proof. Because $f_{Z|\tilde{X}}(\cdot|\cdot)$ is bounded for $|z_i| > \varepsilon$ by A6', the Euclidean norm of (A.2) is bounded above by a constant times $h_n^{-1} \int_{\tilde{\mathcal{X}}} \int_{|z_i| > \varepsilon} \phi_{ni\delta} dz_i g_x(\tilde{x}_i) dP_{\tilde{X}}(\tilde{x}_i)$. With the change of variables $u = \frac{z_i}{h_n} + \tilde{x}_i'\delta$, noting that \tilde{x}_i is bounded, this term is bounded by a constant times $\int_{|u| > \varepsilon/h_n} \phi(u) du$, which is $o(h_n)$ by the tail behavior properties of the normal pdf. ■

Lemma A.2. *Let ϕ denote the standard normal pdf and let the functions $g_u : \mathbb{R} \rightarrow \mathbb{R}$ and $g_x : \tilde{\mathcal{X}} \rightarrow \mathbb{R}$ and the vector $\delta \in \mathbb{R}^{k-1}$ be given. Suppose that \tilde{x}_i has bounded support and that there is a*

constant $M < \infty$ such that $\sup |g_u| < M$ and $\sup |g_x| \leq M$. Then,

$$\int_{\tilde{X}} \int_{|u - \tilde{x}'_i \delta| \leq \varepsilon/h_n} g_u(u) \phi(u) du g_x(\tilde{x}_i) dP_{\tilde{X}}(\tilde{x}_i) = \mathbb{E}[C g_x(\tilde{x}_i)] + o(h_n) \quad (\text{A.3})$$

where $C = \int_{-\infty}^{\infty} g_u(u) \phi(u) du$.

Proof. Let I_n denote the left hand side of (A.3). We note that if the range of the above integral were $u \in (-\infty, +\infty)$, then the integral would evaluate to $\mathbb{E}[C g_x(\tilde{x}_i)]$. Intuitively, the range of integration approaches the real line as $n \rightarrow \infty$, however, we need to formally establish that the difference is $o(h_n)$.

Note that we can write $I_n = I_1 + I_{2n}$ where

$$I_1 = \int_{\tilde{X}} \int_{-\infty}^{\infty} g_u(u) \phi(u) du g_x(\tilde{x}_i) dP_{\tilde{X}}(\tilde{x}_i) = \mathbb{E}[C g_x(\tilde{x}_i)].$$

and

$$I_{2n} = \int_{\tilde{X}} \int_{|u - \tilde{x}'_i \delta| > \varepsilon/h_n} g_u(u) \phi(u) du g_x(\tilde{x}_i) dP_{\tilde{X}}(\tilde{x}_i).$$

Note that by the fact that $\|\tilde{x}_i\|$ is bounded and consequently $|h_n \tilde{x}'_i \delta|$ can be made arbitrarily small, we have that

$$h_n^{-1} \int_{|u - \tilde{x}'_i \delta| > \varepsilon/h_n} g_u(u) \phi(u) du \leq h_n^{-1} M \int_{|u| > \varepsilon/h_n} \phi(u) du.$$

The right hand side term converges to 0 as $n \rightarrow \infty$ by the tail behavior properties of the normal pdf. Thus $h_n^{-1} I_{2n} = o(1)$ by the dominated convergence theorem, which permits us to exchange limits and integrals, as g_x is bounded over the support of \tilde{x}_i . \blacksquare

Lemma A.3. *Under Assumptions A1'–A8', if $h_n \rightarrow 0$ and $nh_n \rightarrow \infty$, then $\hat{\theta} - \theta_0 = O_p(h_n)$.*

Proof. Let $z_i = x'_i \beta_0$, let δ be any $(k-1) \times 1$ vector, let $\Phi_{ni\delta}$ and $\phi_{ni\delta}$ denote $\Phi(\frac{z_i}{h_n} + \tilde{x}'_i \delta)$ and $\phi(\frac{z_i}{h_n} + \tilde{x}'_i \delta)$, respectively, and define the random process

$$T_n(\delta) = \frac{1}{nh_n^2} \sum_{i=1}^n (y_i - \Phi_{ni\delta}) \phi_{ni\delta} \tilde{x}_i.$$

We will first show that

$$\|\mathbb{E}[T_n(\delta)] - Q\delta\| = O(1) + O(h_n \|\delta\|) + O(h_n \|\delta\|^2). \quad (\text{A.4})$$

Before proving (A.4), we explain why it is being shown. If we let $\delta = h_n^{-1}(\hat{\theta} - \theta_0)$, then by the first order condition, $T_n(\delta) = o_p(1)$ and so the conclusion of Lemma A.3 will follow from the assumption that Q is full rank (A8').

To show (A.4), we first note that:

$$\mathbb{E}[T_n(\delta)] = h_n^{-2} \int_{\tilde{\mathcal{X}}} \int_{|z_i| \leq \varepsilon} \left(\tilde{P}(\tilde{x}_i, z_i) - \Phi_{ni\delta} \right) \phi_{ni\delta} f_{Z|\tilde{X}}(z_i|\tilde{x}_i) dz_i \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i) \quad (\text{A.5})$$

$$+ h_n^{-2} \int_{\tilde{\mathcal{X}}} \int_{|z_i| > \varepsilon} \left(\tilde{P}(\tilde{x}_i, z_i) - \Phi_{ni\delta} \right) \phi_{ni\delta} f_{Z|\tilde{X}}(z_i|\tilde{x}_i) dz_i \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i) \quad (\text{A.6})$$

The integral in (A.6) converges to zero by Lemma A.1.

Turing attention to (A.5), since the integral is over z_i in a neighborhood of 0, we take a second order expansion of $\tilde{P}(\tilde{x}_i, z_i)$ and $f_{Z|\tilde{X}}(z_i|\tilde{x}_i)$ around $z_i = 0$. Note this is permitted by Assumptions A6' and A7'. This gives us the sum of three terms and a remainder term.

$$h_n^{-2} \int_{\tilde{\mathcal{X}}} \int_{|z_i| \leq \varepsilon} \left(\frac{1}{2} - \Phi_{ni\delta} \right) \phi_{ni\delta} f_{Z|\tilde{X}}(0|\tilde{x}_i) dz_i \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i) \quad (\text{A.7})$$

$$h_n^{-2} \int_{\tilde{\mathcal{X}}} \int_{|z_i| \leq \varepsilon} \tilde{P}_2(\tilde{x}_i, 0) \phi_{ni\delta} f_{Z|\tilde{X}}(0|\tilde{x}_i) z_i dz_i \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i) \quad (\text{A.8})$$

$$h_n^{-2} \int_{\tilde{\mathcal{X}}} \int_{|z_i| \leq \varepsilon} \left(\frac{1}{2} - \Phi_{ni\delta} \right) \phi_{ni\delta} f'_{Z|\tilde{X}}(0|\tilde{x}_i) z_i dz_i \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i) \quad (\text{A.9})$$

In A.8, \tilde{P}_2 denotes the partial derivative of \tilde{P} with respect to the second argument, z_i . The remainder term involves all second order derivatives and will be dealt with after deriving the properties of each of the above three terms.

We first show (A.7) is $o(1)$. We do the change of variables $u = \frac{z_i}{h_n} + \tilde{x}'_i \delta$, and get

$$h_n^{-1} \int_{\tilde{\mathcal{X}}} \int_{|u - \tilde{x}'_i \delta| \leq \varepsilon/h_n} \left(\frac{1}{2} - \Phi(u) \right) \phi(u) f_{Z|\tilde{X}}(0|\tilde{x}_i) du \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i).$$

Then, we obtain the result by applying Lemma A.2 with $g_u(u) = \frac{1}{2} - \Phi(u)$, $g_x(\tilde{x}_i) = f_{Z|\tilde{X}}(0|\tilde{x}_i) \tilde{x}_i$, and $\int g_u(u) \phi(u) du = 0$, noting that the conditional density of z_i is bounded near 0 by A6', as is \tilde{x}_i over its support.

Turning attention to (A.8) the same change of variables as before yields:

$$\int_{\tilde{\mathcal{X}}} \int_{|u - \tilde{x}'_i \delta| \leq \varepsilon/h_n} \tilde{P}_2(\tilde{x}_i, 0) \phi(u) f_{Z|\tilde{X}}(0|\tilde{x}_i) (u - \tilde{x}'_i \delta) du \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i)$$

We apply Lemma A.2 separately to the integrals involving u and $\tilde{x}'_i \delta$ respectively, with $g_u(u) = u$, $\int g_u(u) \phi(u) du = 0$, $g_x(\tilde{x}_i) = \tilde{P}_2(\tilde{x}_i, 0) f_{Z|\tilde{X}}(0|\tilde{x}_i) \tilde{x}_i$ for the first integral and $g_u(u) = 1$, $\int g_u(u) \phi(u) du = 1$, $g_x(\tilde{x}_i) = \tilde{P}_2(\tilde{x}_i, 0) f_{Z|\tilde{X}}(0|\tilde{x}_i) \tilde{x}_i \tilde{x}'_i \delta$ for the second. Combining our results we may conclude that (A.8) is $Q\delta + o(1)$.

We now derive the limit of (A.9). With the same change of variables we get

$$\int_{\tilde{\mathcal{X}}} \int_{|u - \tilde{x}'_i \delta| \leq \varepsilon/h_n} \left(\frac{1}{2} - \Phi(u) \right) \phi(u) f'_{Z|\tilde{X}}(0|\tilde{x}_i)(u - \tilde{x}'_i \delta) du \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i)$$

As before we deal with the integral involving u and $\tilde{x}'_i \delta$ separately. We apply Lemma A.2 twice, with $g_u(u) = (1/2 - \Phi(u))u$, $g_x(\tilde{x}_i) = f_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i$, and $\int g_u(u)\phi(u) du = c_\phi \approx 0.28$ for the first integral and $g_u(u) = (1/2 - \Phi(u))$, $g_x(\tilde{x}_i) = f_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i\tilde{x}'_i\delta$, and $\int g_u(u)\phi(u) du = 0$ for the second. Combining our results we get that (A.9) is $E[c_\phi f'_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i] + o(1)$. This establishes the asymptotic properties of the three terms (A.7), (A.8), (A.9). Combined, their sum converges to $Q\delta + E[c_\phi f'_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i] + o(1)$.

Finally, we deal with the remainder term, which involves the integral evaluated at second order derivatives times z_i^2 . Using the same change of variable and limit arguments as in establishing the limits of (A.7), (A.8), (A.9), it follows that the Euclidean norm of the remainder term is $o(1) + O(h_n \|\delta\|) + O(h_n \|\delta\|^2)$. Collecting all results establishes (A.4).

Therefore the conclusion of the lemma follows since by setting $\delta = h_n^{-1}(\hat{\theta} - \theta_0)$ as in this case $T_n(\delta) = o_p(1)$ by the first order condition and the established consistency of the estimator. ■

Hessian Term As mentioned at the beginning of this section, both Theorems 2.2 and 3.1 will be proven by expanding the first order condition of the NLLS estimator. We first derive the probability limit of the ‘‘Hessian’’ term in (A.1), which we denote by \hat{H} :

$$\hat{H} = \frac{1}{nh_n^2} \sum_{i=1}^n \left((y_i - \Phi_{ni}^*) \phi'_{ni}{}^* - \phi_{ni}^{2*} \right) \tilde{x}_i \tilde{x}'_i \quad (\text{A.10})$$

To do so, we first evaluate

$$E \left[((y_i - \Phi_{ni}) \phi'_{ni} - \phi_{ni}^2) \tilde{x}_i \tilde{x}'_i \right] / h_n^2. \quad (\text{A.11})$$

As before, decompose the support of z_i into $|z_i| \leq \varepsilon$, $|z_i| > \varepsilon$, where $\varepsilon > 0$ is small enough so the smoothness assumptions in A6', A7' can be applied for $|z_i| \leq \varepsilon$. When $|z_i| > \varepsilon$, the integral is negligible (i.e., $o(1)$) as before by Lemma A.1. When $|z_i| \leq \varepsilon$, by the change of variables $u = z_i/h_n$, and a first order expansion around $h_n = 0$ (permitted by Assumptions A6' and A7'), it follows that (using Assumption A3', A5', and the properties of the normal integrals stated previously) this term can be expressed as

$$E \left[\tilde{P}_2(\tilde{x}_i, 0) f_{Z|\tilde{X}}(0|\tilde{x}_i) \tilde{x}_i \tilde{x}'_i \right] + O(h_n)$$

Note derivation of the above the above expectation is also using the property that $\int u^2 \phi(u) du = 1$, and the term in the expansion involving $f'_{Z|\tilde{X}}(0|\tilde{x}_i)$ vanished because of the last property of the normal distribution listed on the previous page. Now consider the expectation in (A.11) evaluated at $\beta = \beta_n$ where $\beta_n - \beta_0 = O(h_n)$. We do this because the Hessian term is evaluated not at β_0 but

at the intermediate value β^* , and we have established that $\hat{\beta} - \beta_0 = O(h_n)$.

Let z_{ni} denote $x'_i\beta_n$, let $\Phi_{\beta_{ni}}$ denote $\Phi(z_{ni}/h_n)$, and define $\phi_{\beta_{ni}}$ and $\phi'_{\beta_{ni}}$ analogously. We will evaluate

$$E \left[\left((y_i - \Phi_{\beta_{ni}})\phi'_{\beta_{ni}} - \phi_{\beta_{ni}}^2 \right) \tilde{x}_i \tilde{x}'_i \right] / h_n^2.$$

To do so we add and subtract $\tilde{P}(\tilde{x}_i, z_{ni}) \equiv P(\epsilon_i \leq z_{ni} | x_i)$ which here we will denote by \tilde{P}_{β_i} . So we will evaluate

$$E \left[\left((y_i - \tilde{P}_{\beta_i})\phi'_{\beta_{ni}} \right) \tilde{x}_i \tilde{x}'_i \right] / h_n^2 \quad (\text{A.12})$$

and

$$E \left[\left((\tilde{P}_{\beta_i} - \Phi_{\beta_{ni}})\phi'_{\beta_{ni}} - \phi_{\beta_{ni}}^2 \right) \tilde{x}_i \tilde{x}'_i \right] / h_n^2 \quad (\text{A.13})$$

Turning attention to (A.12), we express it as the integral:

$$h_n^{-2} \int_{\tilde{\mathcal{X}}} \int (\tilde{P}_i - \tilde{P}_{\beta_{ni}})\phi'_{\beta_{ni}} f_{Z|\tilde{X}}(z_{ni}|\tilde{x}_i) \tilde{x}_i \tilde{x}'_i dz_{ni} dP_{\tilde{X}}(\tilde{x}_i)$$

where recall \tilde{P}_i denotes $\tilde{P}(\tilde{x}_i, z_i)$. Now decompose the integral into the regions $|z_{ni}| \leq \varepsilon$, $|z_{ni}| > \varepsilon$. The integral in the latter region is negligible by Lemma A.1. In the former region, take a first order expansion of \tilde{P}_i around \tilde{P}_{β_i} , which yields:

$$h_n^{-2} \int_{\tilde{\mathcal{X}}} \int_{|z_{ni}| \leq \varepsilon} f_{\epsilon|X}(x'_i \tilde{\beta}_n) \phi'_{\beta_{ni}} f_{Z_n|\tilde{X}}(z_{ni}|\tilde{x}_i) \tilde{x}_i \tilde{x}'_i dz_{ni} dP_{\tilde{X}}(\tilde{x}_i) (\beta - \beta_0) \quad (\text{A.14})$$

where $f_{\epsilon|X}$ denotes the density of ϵ_i conditional on x_i evaluated at $x'_i \tilde{\beta}_n$ with $\tilde{\beta}_n$ denoting a value in between β_n and β_0 , and $f_{Z_n|\tilde{X}}(\cdot)$ denotes the conditional density function of z_{ni} . We note that since z_{ni} is in a neighborhood of 0, and $\tilde{\beta}_n$ is in a neighborhood of β_0 , with \tilde{x}_i bounded and the compactness of Θ it follows that $x'_i \tilde{\beta}_n$ is in a neighborhood of 0 as well, where the density of ϵ_i is bounded by Assumption A7'. Therefore, since $(\beta_n - \beta_0)/h_n = O(1)$ from Lemma A.3, the above integral in (A.14) will converge to 0 if we can show the integral

$$h_n^{-1} \int_{\tilde{\mathcal{X}}} \int_{|z_{ni}| \leq \varepsilon} \phi'_{\beta_{ni}} f_{Z_n|\tilde{X}}(z_{ni}|\tilde{x}_i) (\tilde{x}_i \tilde{x}'_i) \tilde{x}'_i dP_{\tilde{X}}(\tilde{x}_i)$$

converges to 0.

Next, doing the change of variables $u_i = x'_i \beta_n / h_n$, we express this integral as:

$$\int_{\tilde{\mathcal{X}}} \int_{|u| \leq \varepsilon/h_n} \phi'(u) du f_{Z_n|\tilde{X}}(uh_n|\tilde{x}_i) (\tilde{x}_i \tilde{x}'_i) \tilde{x}'_i dP_{\tilde{X}}(\tilde{x}_i)$$

take a first order expansion around $h_n = 0$, and noting that $\int \phi'(u) du = 0$, we get the above

integral converges to 0, again using the dominated convergence theorem.

Next, we deal with the term (A.13), which again we write as an integral decomposed into the regions $|z_n| \leq \varepsilon$ and $|z_n| > \varepsilon$. We can show the integral over the latter region is asymptotically negligible using Lemma A.1. In the former region, we make the same change of variables, yielding the integral:

$$h_n^{-1} \int_{\tilde{\mathcal{X}}} \int_{|u| \leq \varepsilon/h_n} \left[(\tilde{P}(\tilde{x}_i, uh_n) - \Phi(u))\phi'(u) - \phi^2(u) \right] f_{Z_n|\tilde{\mathcal{X}}}(uh_n|\tilde{x}_i)\tilde{x}_i\tilde{x}_i' dP_{\tilde{\mathcal{X}}}(\tilde{x}_i)$$

Take an expansion around $h_n = 0$. The lead term is of the form

$$h_n^{-1} \int_{\tilde{\mathcal{X}}} \int_{|u| \leq \varepsilon/h_n} [(1/2 - \Phi(u))\phi'(u) - \phi^2(u)] f_{Z_n|\tilde{\mathcal{X}}}(0|\tilde{x}_i) du\tilde{x}_i\tilde{x}_i' dP_{\tilde{\mathcal{X}}}(\tilde{x}_i)$$

which converges to 0 as $n \rightarrow \infty$, since the integral over $|u| \leq \varepsilon/h_n$ converges to 0 faster than h_n . The first derivative term in the expansion, which involves the term uh_n , is

$$\int_{\tilde{\mathcal{X}}} \int_{|u| \leq \varepsilon/h_n} \left\{ [(1/2 - \Phi(u))\phi'(u) - \phi^2(u)] u f'_{Z_n|\tilde{\mathcal{X}}}(0|\tilde{x}_i) - \tilde{P}_2(\tilde{x}_i, 0) f_{Z_n|\tilde{\mathcal{X}}}(0|\tilde{x}_i)\phi'(u)u \right\} du\tilde{x}_i\tilde{x}_i' dP_{\tilde{\mathcal{X}}}(\tilde{x}_i)$$

and converges to (by the stated normal integral properties and the tail behavior of the normal distribution) to $E \left[\tilde{P}_2(\tilde{x}_i, 0) f_{Z|\tilde{\mathcal{X}}}(0|\tilde{x}_i)\tilde{x}_i\tilde{x}_i' \right] + o(1)$. The second derivative term in the expansion is $O(h_n)$ by similar arguments.

Therefore, collecting all our results we have the expectation in (A.11) evaluated at $\beta = \beta^*$ instead of $\beta = \beta_0$ is $E \left[\tilde{P}_2(\tilde{x}_i, 0) f_{Z|\tilde{\mathcal{X}}}(0|\tilde{x}_i)\tilde{x}_i\tilde{x}_i' \right] + o(1)$.

As a last step we deal with the average in (A.10) minus its expectation. Here we adopt the notation that $\tilde{\psi}_{ni}(\theta)$ denotes the term in the summation in (A.10) when the parameter is θ . We will derive the asymptotic properties of

$$\frac{1}{nh_n^2} \sum_{i=1}^n \tilde{\psi}_{ni}(\theta) - E[\tilde{\psi}_{ni}(\theta)] \tag{A.15}$$

at $\theta = \theta_0$. Since the above term is mean 0, we evaluate the variance, which is of the form:

$$\frac{1}{nh_n^4} E \left[(\tilde{\psi}_{ni}(\theta) - E[\tilde{\psi}_{ni}(\theta)])^2 \right].$$

The lead term involves $E[\tilde{\psi}_{ni}(\theta)^2]/nh_n^4$, which after a change of variables (after decomposing the support of z_i into $|z_i| \leq \varepsilon$, $|z_i| > \varepsilon$ and proceeding as before) has first term with the constant $\frac{1}{nh_n^3}$

times the integral:

$$\int \{ [1/2 + \Phi(u)^2 - \Phi(u)] \phi'(u)^2 + \phi^4(u) - 2(1/2 - \Phi(u))\phi'(u)\phi^2(u) \} du$$

and the above integral is not 0. So the variance of the demeaned sum is $O(1/nh_n^3)$. Therefore, for (A.15) to converge in probability to 0, we need $nh_n^3 \rightarrow \infty$. If $nh_n^3 \rightarrow c \neq 0$, the demeaned sum converges to a non-degenerate random variable.

Therefore, we will proceed as if $nh_n^3 \rightarrow \infty$. The last step is to account for the fact that the demeaned sum is evaluated not at θ_0 but at θ^* , an intermediate value, so we want to evaluate

$$\frac{1}{nh_n^2} \sum_{i=1}^n \tilde{\psi}_{ni}(\theta^*) - \mathbb{E}[\tilde{\psi}_{ni}(\theta^*)]$$

Here we will again use the established result that $\hat{\theta} - \theta_0 = O_p(h_n)$. Subtract from the above term $\tilde{\psi}_{ni}(\theta_0) - \mathbb{E}[\tilde{\psi}_{ni}(\theta_0)]$. The resulting term is still mean 0, so as before we only need evaluate the variance. But by a mean value expansion of $\tilde{\psi}_{ni}(\theta_n)$ around $\tilde{\psi}_{ni}(\theta_0)$ for any θ_n such that $\theta_n - \theta_0 = O(h_n)$, we get terms involving $(\theta_n - \theta_0)/h_n$ which are $O(1)$, implying that as before, the variance is $O(1/nh_n^3)$ which is $o(1)$ under the assumption that $nh_n^3 \rightarrow \infty$. Therefore, it sufficed to work with the asymptotic properties of

$$\frac{1}{nh_n^2} \sum_{i=1}^n \tilde{\psi}_{ni}(\theta_0) - \mathbb{E}[\tilde{\psi}_{ni}(\theta_0)].$$

This concludes the asymptotic theory for the Hessian term. To summarize what we have shown, if $nh_n^3 \rightarrow \infty$, then $\hat{H} = Q + o_p(1)$, so by the invertibility of Q and Slutsky's theorem, we have $\hat{H}^{-1} = Q^{-1} + o_p(1)$. Also, if $nh_n^3 \rightarrow c < \infty$, \hat{H} converges to a nondegenerate random variable.

Score Term We next turn attention to the ‘‘score’’ term

$$\frac{1}{nh_n} \sum_{i=1}^n (y_i - \Phi_{ni})\phi_{ni}\tilde{x}_i.$$

We add and subtract the term $\mathbb{E}[(y_i - \Phi_{ni})\phi_{ni}\tilde{x}_i]/h_n$. We note that this expected value is $O(h_n)$ by the same change of variables argument (after decomposing the support of z_i as before). Specifically, by a second order expansion of $\tilde{P}(\tilde{x}_i, z_i)$ around $z_i = 0$, permitted by Assumption A7', it is of the form:

$$- \left\{ \mathbb{E}[f'_{z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i] \int \Phi(u)\phi(u)u du \right\} h_n + O(h_n^2)$$

Finally, we note that by the Lindeberg Theorem, when $nh_n \rightarrow \infty$,

$$\frac{1}{\sqrt{nh_n}} \sum_{i=1}^n \{(y_i - \Phi_{ni})\phi_{ni}\tilde{x}_i - \mathbb{E}[(y_i - \Phi_{ni})\phi_{ni}\tilde{x}_i]\}$$

converges in distribution to $N\left(0, c_1 \cdot \mathbb{E}\left[f_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i\tilde{x}_i'\right]\right)$, where recall $c_1 = \int \Phi^2(u)\phi^2(u) du$.

However, since the bias is $O(h_n)$ and the variance of the score term is $O(\frac{1}{nh_n})$ (using arguments identical to evaluating the order of the variance in nonparametric density estimation) the optimal rate of convergence (of the score term) in a mean squared error sense is $h_n = O(n^{-1/3})$. However, under this rate $nh_n^3 \rightarrow c < \infty$. Thus the Hessian term does not converge to a degenerate distribution, and the NLLS estimator is not asymptotically Gaussian.

So by combining our results with the Hessian term \hat{H} , we have the following representation (if $nh_n^3 \rightarrow \infty$) in the conclusion in Theorem 3.1:

$$\begin{aligned} \hat{\theta} - \theta_0 = (Q + o_p(1))^{-1} & \left[\left(\frac{1}{nh_n} \sum_{i=1}^n (y_i - \Phi_{ni})\phi_{ni}\tilde{x}_i - \mathbb{E}[(y_i - \Phi_{ni})\phi_{ni}\tilde{x}_i] \right) \right. \\ & \left. - \left\{ Q^{-1} \mathbb{E}[f'_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i] \int \Phi(u)\phi(u)u du \right\} h_n + O(h_n^2) \right] \quad (\text{A.16}) \end{aligned}$$

Furthermore, collecting all derived results regarding rates of convergence for the Hessian and score terms as a function of h_n , the conclusions of Theorem 2.2 follow. Specifically, if in the score term, we equate the standard deviation which is $O(1/\sqrt{nh_n})$ with the bias which is $O(h_n)$, we get $h_n = O(n^{-1/3})$, but this violates our assumption that $nh_n^3 \rightarrow \infty$ that was needed in the Hessian term. The Hessian condition is also violated if $h_n = o(n^{-1/3})$ which would also result in a slower rate of convergence. If $nh_n^3 \rightarrow \infty$, then the Hessian term converges in probability to Q , but the bias in the score term dominates the variance, and we get

$$h_n^{-1}(\hat{\theta} - \theta_0) \xrightarrow{p} -Q^{-1} \left\{ \int_{\tilde{X}} f_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i) \int \Phi(u)\phi(u)u du \right\}$$

■

Finally, as will be formally discussed in the next section, if the bias term in the linear component of the representation is $O(h_n^2)$ by some modified procedure, the optimal sequence is $h_n = O(n^{-1/5})$ in which case the Hessian term converges to a constant matrix. In this case we may apply Slutsky's theorem to conclude that the bias-corrected estimators are asymptotically normal and converge at the rate of $O_p(n^{-2/5})$.

A.3 Proof of Theorem 3.2

The theorem follows almost directly from the results in Theorem 3.1, and follows from establishing that the bias of the jackknifed estimator is $O(h_n^2)$.

For the jackknifed estimator the bias term is of the form:

$$- \left\{ Q^{-1} \mathbb{E}[f_{Z|\tilde{X}}(0|\tilde{x}_i)\tilde{x}_i] \int \Phi(u)\phi(u)u \, du \right\} (w_1\kappa_1 + w_2\kappa_2)h_n + \mathcal{B}_{jk}h_n^2 = O(h_n^2)$$

where here the second equality follows from the second condition imposed on w_1 , w_2 , κ_1 , and κ_2 , and

$$\begin{aligned} \mathcal{B}_{jk} = (w_1\kappa_1^2 + w_2\kappa_2^2) \frac{1}{2} \int_{\tilde{X}} \int \left\{ \left(\frac{1}{2} - \Phi(u) \right) f_{Z|\tilde{X}}(0|\tilde{x}_i) + 2\tilde{P}_2(\tilde{x}_i, 0)f'_{Z|\tilde{X}}(0|\tilde{x}_i) \right. \\ \left. + \tilde{P}_{22}(\tilde{x}_i, 0)f_{Z|\tilde{X}}(0|\tilde{x}_i) \right\} u^2 \phi(u) \, du \tilde{x}_i \, dP_{\tilde{X}}(\tilde{x}_i) \end{aligned}$$

Therefore, we have $n^{2/5}(\hat{\theta}_{jk} - \theta_0) \Rightarrow N(\mathcal{B}_{jk}, Q^{-1}V_{jk}Q^{-1})$ ■

A.4 Proof of Theorem 3.3

As alluded to in Section 3.2, the function $F(\cdot)$ in the objective function:

$$\frac{1}{n} \sum_{i=1}^n \left(y_i - F \left(\frac{x'_i \beta}{h_n} \right) \right)^2$$

cannot be a cumulative distribution function if bias reduction is to be achieved. Using the same arguments as in deriving the linear representation, we impose conditions F1–F6 on $F(\cdot)$ and its first and second derivatives, denote by $f(\cdot)$ and $f'(\cdot)$ respectively. Under these conditions, following the arguments used in the linear representation derivation, the NLLS estimator using function $F(\cdot)$ will converge at the rate of $O_p(n^{-2/5})$ which is the optimal rate as established in Horowitz (1993a). It will have an asymptotic Gaussian distribution with asymptotic bias \mathcal{B}_F and an asymptotic variance of the form $Q_F^{-1}V_FQ_F^{-1}$. ■

A.5 Jackknife Weights

The form of the limiting distribution of the jackknifed estimator is useful for providing guidance for the form of the weights w_1, w_2 . For example, with the analytic form of the asymptotic bias and asymptotic variance, one could attempt to select the two weights that minimize the asymptotic mean squared error subject to the constraints that $w_1 + w_2 = 1$, and $w_1\kappa_1 + w_2\kappa_2 = 0$, where, recall, κ_1 and κ_2 denote the two constants for the two bandwidth sequences. Even treating these two constants as given, the optimal values of w_1 and w_2 would depend on the unknown density and distribution function (as well as their derivatives) appearing in the asymptotic bias and variance. These would have to be estimated first, making implementation difficult and requiring the selection of additional bandwidths.

An easier to implement approach would be to only minimize with respect to the constant terms

in the asymptotic mean squared error. That is, to minimize the function

$$\frac{1}{4}(w_1\kappa_1^2 + w_2\kappa_2^2)^2 + c_1w_1^2\kappa_1^{-1} + c_1w_2^2\kappa_2^{-1} + 2w_1w_2c_2\kappa_1^{-1}$$

with respect to κ_1 and κ_2 subject to the constraints, which can be solved for κ_1 and κ_2 and substituted in as $w_1 = \kappa_2/(\kappa_2 - \kappa_1)$ and $w_2 = 1 - w_1 = -\kappa_1/(\kappa_2 - \kappa_1)$. The values which minimize this function are $\kappa_1 = 0.56334$, $\kappa_2 = 1.0180$, $w_1 = 2.2389$, and $w_2 = -1.2389$.

A second approach uses a simple “rule of thumb” estimate for the matrix $Q^{-1}V_1Q^{-1}$ appearing in the asymptotic variance given in Theorem 3.2. Let $\hat{E}[\tilde{x}_i\tilde{x}_i']$ denote the sample analog estimator of the expectation and let $\hat{E}[\tilde{x}_i\tilde{x}_i']^{-1}$ denotes its inverse. Then we could alter the above objective function to

$$\frac{1}{4}(w_1\kappa_1^2 + w_2\kappa_2^2)^2 + \hat{v}_{\text{ROT}} (c_1w_1^2\kappa_1^{-1} + c_1w_2^2\kappa_2^{-1} + 2w_1w_2c_2\kappa_1^{-1})$$

where $\hat{v}_{\text{ROT}} = 0.4^{-3} \cdot \left\| \hat{E}[\tilde{x}_i\tilde{x}_i']^{-1} \right\|_2$ is a rule of thumb approximation of the norm of $Q^{-1}V_1Q^{-1}$, under simplifying normality and independence assumptions. Here 0.4 is the value of the standard normal pdf evaluated at 0, $\phi(0)$, and $\|\cdot\|_2$ denotes the Frobenius norm, the square root of the sum of the squared elements of the matrix.

Both of these approaches are evaluated in the simulation studies, labeled JKNLLS-1 and JKNLLS-2 respectively.

A.6 Weighted NLLS

With the limiting Gaussian distribution in hand, a natural extension of the local NLLS would be consider a weighting observations to improve efficiency, analogous to generalized least squares. In the parametric Probit model, it is well known that NLLS is not as efficient as MLE, but an optimally weighted NLLS is asymptotically equivalent to MLE. For the local NLLS, a weighted version would aim to minimize the asymptotic mean squared error (AMSE).

The weighted estimator, referred to here as WNLLS, would minimize the objective function:

$$\frac{1}{n} \sum_{i=1}^n w(x_i) \left(y_i - F \left(\frac{x_i'\beta}{h_n} \right) \right)^2$$

where $w(\cdot)$ denotes the weight function. The limiting distribution follows immediately from our linear representation. Let $\tilde{w}(\tilde{x}_i, x_i'\beta_0)$ denote the reparametrized weight function, expressed as a function of the subset of regressors \tilde{x}_i and the index $x_i'\beta_0$. Now the asymptotic bias is of the form:

$$\begin{aligned} \mathcal{B}_F^w = \frac{1}{2} \int_{\tilde{X}} \int \left\{ \left(\frac{1}{2} - F(u) \right) f_{Z|\tilde{X}}(0|\tilde{x}) + 2\tilde{P}_2(\tilde{x}_i, 0) f'_{Z|\tilde{X}}(0|\tilde{x}) \right. \\ \left. + \tilde{P}_{22}(\tilde{x}_i, 0) f_{Z|\tilde{X}}(0|\tilde{x}) \right\} u^2 f(u) du \tilde{w}(\tilde{x}_i, 0) \tilde{x}_i dP_{\tilde{X}}(\tilde{x}_i) \end{aligned}$$

and the components of the asymptotic variance matrix are of the form:

$$V_F^w = c_{F_1} \cdot E[\tilde{w}^2(\tilde{x}_i, 0)\tilde{x}_i\tilde{x}_i'f_{Z|\tilde{X}}(0|\tilde{x}_i)]$$

and

$$Q_F^w = E \left[\left(c_{F_2}\tilde{P}_2(\tilde{x}_i, 0)f_{Z|\tilde{X}}(0|\tilde{x}_i) + c_{F_3}f'_{Z|\tilde{X}}(0|\tilde{x}_i) \right) \tilde{w}(\tilde{x}_i, 0)\tilde{x}_i\tilde{x}_i' \right]$$

This immediately suggests an infeasible weighting function. If we condition on a particular value of \tilde{x}_i , \tilde{x} , we can treat all the functions inside the expectations $\mathcal{B}_F^w, V_F^w, Q_F^w$ as given, and minimize the conditional mean squared error with respect to $w(\tilde{x}, 0)$, which we refer to here as $w^*(\tilde{x}, 0)$. This minimized value will obviously depend on the values of the other functions evaluated at \tilde{x} . Then our infeasible estimator minimizes the objective function

$$\frac{1}{n} \sum_{i=1}^n \tilde{w}^*(\tilde{x}_i, 0) \left(y_i - F \left(\frac{x_i'\beta}{h_n} \right) \right)^2.$$

Of course what makes this approach infeasible is that the optimal function $w^*(\tilde{x}, 0)$ depends on the other functions, such as $f_{Z|\tilde{X}}(0|\tilde{x})$ and $\tilde{P}_2(\tilde{x}_i, 0)$ which are unknown. But analogous to feasible GLS for the linear model, one can first estimate β_0 using a suboptimal weighting function (say, $w(x_i) = 1$) and use that to nonparametrically estimate the unknown nuisance functions $f_{Z|\tilde{X}}(0|\tilde{x}), \tilde{P}_2(\tilde{x}_i, 0)$, that can then be plugged into a feasible estimator of $\tilde{w}^*(\tilde{x}_i, 0)$.

Table I: Homoskedastic Normal

Estimator	α				β			
	Mean Bias	Med. Bias	RMSE	MAD	Mean Bias	Med. Bias	RMSE	MAD
<i>100 obs.</i>								
NLLS	-0.0648	-0.0238	0.2928	0.1564	-0.1015	-0.0402	0.4016	0.2160
JKNLLS-1	-0.0388	0.0161	0.5197	0.2491	-0.0558	0.0703	0.6806	0.3257
JKNLLS-2	-0.0069	0.0635	0.4503	0.2011	0.0274	0.1496	0.6062	0.2690
NLLSF	-0.0393	0.0164	0.3503	0.1704	-0.0445	0.0540	0.4710	0.2350
SMS-1	-0.4078	-0.2073	1.0589	0.2760	-0.7302	-0.4125	1.7279	0.3908
SMS-2	-0.1229	-0.0476	0.5059	0.2320	-0.2111	-0.0747	0.6788	0.3104
SMS-3	-0.1220	-0.0367	0.7432	0.2340	-0.2336	-0.0565	1.5163	0.3134
<i>200 obs.</i>								
NLLS	-0.0292	-0.0094	0.1763	0.1072	-0.0483	-0.0222	0.2426	0.1425
JKNLLS-1	-0.0243	0.0175	0.3723	0.1975	-0.0327	0.0569	0.5076	0.2547
JKNLLS-2	0.0148	0.0562	0.3148	0.1599	0.0557	0.1347	0.4279	0.2138
NLLSF	0.0047	0.0356	0.2228	0.1234	0.0216	0.0732	0.3016	0.1679
SMS-1	-0.2260	-0.1495	0.5029	0.1834	-0.4370	-0.2995	1.8058	0.2625
SMS-2	-0.0748	-0.0302	0.3268	0.1801	-0.1292	-0.0432	0.4508	0.2373
SMS-3	-0.0656	-0.0240	0.3309	0.1798	-0.1205	-0.0437	0.4552	0.2430
<i>400 obs.</i>								
NLLS	-0.0136	-0.0088	0.1150	0.0750	-0.0242	-0.0142	0.1607	0.1017
JKNLLS-1	-0.0191	0.0181	0.2903	0.1582	-0.0141	0.0532	0.3877	0.2087
JKNLLS-2	0.0256	0.0501	0.2258	0.1289	0.0680	0.1180	0.3136	0.1710
NLLSF	0.0241	0.0366	0.1533	0.0911	0.0517	0.0746	0.2139	0.1276
SMS-1	-0.1387	-0.1108	0.2583	0.1272	-0.2665	-0.2239	0.4072	0.1835
SMS-2	-0.0514	-0.0253	0.2326	0.1373	-0.0860	-0.0375	0.3233	0.1935
SMS-3	-0.0423	-0.0223	0.2344	0.1439	-0.0758	-0.0283	0.3224	0.1904

Table II: Heteroskedastic Normal

Estimator	α				β			
	Mean Bias	Med. Bias	RMSE	MAD	Mean Bias	Med. Bias	RMSE	MAD
<i>100 obs.</i>								
NLLS	0.0882	0.1370	0.3248	0.1812	0.1997	0.2563	0.4740	0.2726
JKNLLS-1	0.0243	0.1030	0.5040	0.2695	0.0980	0.2060	0.6729	0.3880
JKNLLS-2	0.0654	0.1508	0.4626	0.2284	0.1812	0.3019	0.6436	0.3296
NLLSF	0.0158	0.0800	0.3694	0.2122	0.0960	0.1712	0.5031	0.3038
SMS-1	-0.3029	-0.2115	0.6328	0.3084	-0.4358	-0.3245	0.8329	0.4101
SMS-2	-0.0573	0.0105	0.4478	0.2683	-0.0362	0.0389	0.5763	0.3669
SMS-3	-0.0334	0.0258	0.4575	0.2736	-0.0022	0.0824	0.5922	0.3692
<i>200 obs.</i>								
NLLS	0.1106	0.1395	0.2419	0.1356	0.2285	0.2596	0.3783	0.2038
JKNLLS-1	0.0383	0.0959	0.4140	0.2331	0.0945	0.1751	0.5578	0.3297
JKNLLS-2	0.0747	0.1347	0.3621	0.2045	0.1755	0.2538	0.5142	0.2880
NLLSF	0.0463	0.0833	0.2669	0.1654	0.1326	0.1765	0.3782	0.2284
SMS-1	-0.2143	-0.1735	0.4171	0.2247	-0.2979	-0.2450	0.5514	0.2927
SMS-2	-0.0321	0.0129	0.3401	0.2197	-0.0092	0.0341	0.4418	0.2883
SMS-3	-0.0136	0.0265	0.3449	0.2219	0.0148	0.0571	0.4499	0.2958
<i>400 obs.</i>								
NLLS	0.1247	0.1401	0.1967	0.0992	0.2477	0.2623	0.3285	0.1442
JKNLLS-1	0.0323	0.0806	0.3376	0.1956	0.0716	0.1270	0.4575	0.2736
JKNLLS-2	0.0676	0.1211	0.3027	0.1744	0.1511	0.2048	0.4310	0.2492
NLLSF	0.0612	0.0830	0.2025	0.1267	0.1507	0.1705	0.3042	0.1774
SMS-1	-0.1537	-0.1354	0.2891	0.1596	-0.2007	-0.1798	0.3788	0.2131
SMS-2	-0.0230	0.0004	0.2661	0.1769	-0.0029	0.0183	0.3473	0.2320
SMS-3	-0.0043	0.0174	0.2714	0.1824	0.0191	0.0304	0.3540	0.2384

Table III: Homoskedastic Chi-Square

Estimator	α				β			
	Mean Bias	Med. Bias	RMSE	MAD	Mean Bias	Med. Bias	RMSE	MAD
<i>100 obs.</i>								
NLLS	0.1881	0.1974	0.3039	0.1537	-0.0186	0.0152	0.3266	0.1977
JKNLLS-1	0.0221	0.0371	0.3878	0.2287	0.0086	0.0875	0.5355	0.2872
JKNLLS-2	0.0662	0.0823	0.3262	0.1831	0.0903	0.1508	0.4591	0.2467
NLLSF	0.1078	0.1166	0.2848	0.1667	-0.0168	0.0270	0.5107	0.2174
SMS-1	-0.0314	0.0130	0.5779	0.2180	-0.5941	-0.3738	2.1150	0.2933
SMS-2	0.0222	0.0222	0.3350	0.1985	-0.1408	-0.0563	0.6420	0.2664
SMS-3	0.0331	0.0354	0.5306	0.2041	-0.1392	-0.0438	1.7658	0.2793
<i>200 obs.</i>								
NLLS	0.1978	0.2019	0.2554	0.1062	0.0085	0.0204	0.2120	0.1385
JKNLLS-1	0.0115	0.0172	0.2996	0.1753	0.0258	0.0838	0.4064	0.2353
JKNLLS-2	0.0399	0.0490	0.2399	0.1479	0.0893	0.1231	0.3345	0.1968
NLLSF	0.1145	0.1238	0.2146	0.1174	0.0129	0.0244	0.2440	0.1543
SMS-1	0.0126	0.0260	0.2354	0.1402	-0.3234	-0.2841	0.4721	0.1942
SMS-2	0.0199	0.0119	0.2261	0.1464	-0.0661	-0.0385	0.3236	0.1904
SMS-3	0.0281	0.0194	0.2350	0.1492	-0.0584	-0.0352	0.3333	0.2033
<i>400 obs.</i>								
NLLS	0.2070	0.2089	0.2344	0.0743	0.0239	0.0298	0.1461	0.0969
JKNLLS-1	0.0033	0.0028	0.2294	0.1409	0.0352	0.0686	0.3145	0.1947
JKNLLS-2	0.0215	0.0226	0.1813	0.1149	0.0846	0.0989	0.2583	0.1509
NLLSF	0.1181	0.1224	0.1752	0.0869	0.0239	0.0300	0.1761	0.1107
SMS-1	0.0275	0.0312	0.1474	0.0918	-0.2232	-0.2090	0.3022	0.1279
SMS-2	0.0094	0.0006	0.1684	0.1084	-0.0429	-0.0317	0.2390	0.1478
SMS-3	0.0134	0.0046	0.1790	0.1152	-0.0331	-0.0227	0.2462	0.1571

Table IV: Heteroskedastic Chi-Square

Estimator	α				β			
	Mean Bias	Med. Bias	RMSE	MAD	Mean Bias	Med. Bias	RMSE	MAD
<i>100 obs.</i>								
NLLS	0.2472	0.2751	0.3811	0.1965	0.2052	0.2381	0.4428	0.2742
JKNLLS-1	0.0858	0.1146	0.4365	0.2674	0.1200	0.1958	0.5842	0.3553
JKNLLS-2	0.1118	0.1626	0.4107	0.2393	0.1567	0.2427	0.5592	0.3334
NLLSF	0.1366	0.1535	0.3465	0.2248	0.0906	0.1159	0.4320	0.2993
SMS-1	-0.0368	-0.0291	0.4965	0.2643	-0.4085	-0.3427	1.6540	0.3364
SMS-2	0.0536	0.0551	0.3662	0.2518	-0.0023	0.0242	0.5008	0.3326
SMS-3	0.0841	0.0769	0.4965	0.2573	0.0217	0.0545	1.0057	0.3378
<i>200 obs.</i>								
NLLS	0.2420	0.2613	0.3290	0.1550	0.2072	0.2166	0.3610	0.2077
JKNLLS-1	0.0515	0.0781	0.3713	0.2335	0.0896	0.1540	0.4975	0.3029
JKNLLS-2	0.0848	0.1220	0.3396	0.2076	0.1358	0.1953	0.4656	0.2836
NLLSF	0.1327	0.1416	0.2762	0.1731	0.0941	0.0974	0.3300	0.2265
SMS-1	-0.0203	-0.0186	0.2769	0.1849	-0.2876	-0.2816	0.4561	0.2316
SMS-2	0.0396	0.0312	0.2775	0.1954	0.0071	0.0092	0.3635	0.2501
SMS-3	0.0596	0.0481	0.2905	0.2001	0.0353	0.0350	0.3825	0.2647
<i>400 obs.</i>								
NLLS	0.2443	0.2526	0.2957	0.1159	0.2109	0.2147	0.3016	0.1496
JKNLLS-1	0.0324	0.0512	0.3095	0.1972	0.0759	0.1199	0.4146	0.2484
JKNLLS-2	0.0626	0.0875	0.2787	0.1771	0.1171	0.1559	0.3843	0.2289
NLLSF	0.1324	0.1388	0.2303	0.1334	0.0962	0.0951	0.2650	0.1712
SMS-1	-0.0071	-0.0075	0.1907	0.1283	-0.2212	-0.2198	0.3337	0.1665
SMS-2	0.0182	0.0074	0.2177	0.1530	-0.0021	-0.0097	0.2894	0.1936
SMS-3	0.0347	0.0224	0.2304	0.1564	0.0216	0.0119	0.3026	0.2085

Table V: Homoskedastic Cauchy

Estimator	α				β			
	Mean Bias	Med. Bias	RMSE	MAD	Mean Bias	Med. Bias	RMSE	MAD
<i>100 obs.</i>								
NLLS	-0.0719	-0.0079	0.4556	0.2147	-0.1249	0.0008	0.6835	0.2849
JKNLLS-1	-0.0253	0.0483	0.6761	0.2989	-0.0417	0.1237	0.9099	0.3763
JKNLLS-2	-0.0109	0.0856	0.6307	0.2548	0.0165	0.1866	0.8446	0.3329
NLLSF	-0.0556	0.0425	0.5304	0.2163	-0.0703	0.0959	0.7139	0.2951
SMS-1	-0.6901	-0.2570	2.1614	0.3991	-1.4549	-0.5148	4.5397	0.5661
SMS-2	-0.1307	-0.0234	0.6687	0.2779	-0.2455	-0.0349	1.0376	0.3767
SMS-3	-0.1929	-0.0089	2.6848	0.2862	-0.4327	-0.0071	5.0340	0.3756
<i>200 obs.</i>								
NLLS	-0.0151	0.0117	0.2427	0.1480	-0.0375	0.0137	0.3354	0.2016
JKNLLS-1	-0.0120	0.0344	0.4442	0.2355	-0.0306	0.0764	0.5953	0.3102
JKNLLS-2	0.0183	0.0663	0.3901	0.2036	0.0425	0.1449	0.5255	0.2672
NLLSF	0.0021	0.0443	0.3066	0.1603	0.0160	0.0888	0.4080	0.2184
SMS-1	-0.3793	-0.1850	1.1447	0.2567	-0.6799	-0.3929	1.6257	0.3669
SMS-2	-0.0864	-0.0218	0.4387	0.2180	-0.1668	-0.0496	0.6013	0.3017
SMS-3	-0.0755	-0.0116	0.5213	0.2211	-0.1501	-0.0401	0.9456	0.3036
<i>400 obs.</i>								
NLLS	0.0058	0.0171	0.1590	0.1011	0.0002	0.0224	0.2169	0.1370
JKNLLS-1	-0.0114	0.0255	0.3508	0.1922	-0.0206	0.0688	0.4690	0.2453
JKNLLS-2	0.0234	0.0598	0.2855	0.1591	0.0545	0.1236	0.3876	0.2097
NLLSF	0.0235	0.0487	0.2047	0.1119	0.0550	0.1012	0.2870	0.1507
SMS-1	-0.2003	-0.1320	0.4277	0.1736	-0.3762	-0.2718	0.6361	0.2424
SMS-2	-0.0513	-0.0186	0.2939	0.1630	-0.0990	-0.0355	0.4011	0.2184
SMS-3	-0.0440	-0.0127	0.3004	0.1673	-0.0926	-0.0313	0.4082	0.2294

Table VI: Heteroskedastic Cauchy

Estimator	α				β			
	Mean Bias	Med. Bias	RMSE	MAD	Mean Bias	Med. Bias	RMSE	MAD
<i>100 obs.</i>								
NLLS	0.1730	0.2252	0.3974	0.1974	0.3280	0.4110	0.5856	0.2892
JKNLLS-1	0.0611	0.1479	0.6019	0.3023	0.1537	0.3011	0.7898	0.4231
JKNLLS-2	0.0580	0.1718	0.5885	0.2593	0.1678	0.3656	0.8043	0.3774
NLLSF	0.0408	0.1347	0.4715	0.2339	0.1422	0.2555	0.6387	0.3573
SMS-1	-0.4206	-0.2151	1.1512	0.3985	-0.6373	-0.3712	1.6244	0.5341
SMS-2	-0.0351	0.0557	0.5401	0.2914	-0.0085	0.1052	0.7004	0.4157
SMS-3	-0.0101	0.0830	0.6236	0.3046	0.0259	0.1662	0.8556	0.4275
<i>200 obs.</i>								
NLLS	0.1921	0.2274	0.3162	0.1453	0.3547	0.4031	0.4989	0.2205
JKNLLS-1	0.0546	0.1309	0.4836	0.2545	0.1075	0.2154	0.6426	0.3613
JKNLLS-2	0.0782	0.1668	0.4451	0.2275	0.1748	0.3069	0.6235	0.3308
NLLSF	0.0736	0.1289	0.3386	0.1871	0.1807	0.2497	0.4772	0.2681
SMS-1	-0.2785	-0.1958	0.5972	0.2910	-0.4047	-0.3063	0.7841	0.3886
SMS-2	-0.0232	0.0340	0.4089	0.2423	0.0002	0.0695	0.5304	0.3357
SMS-3	-0.0053	0.0457	0.4331	0.2547	0.0234	0.0887	0.5594	0.3514
<i>400 obs.</i>								
NLLS	0.2185	0.2401	0.2810	0.1083	0.3941	0.4231	0.4672	0.1603
JKNLLS-1	0.0303	0.0967	0.4142	0.2313	0.0717	0.1622	0.5570	0.3222
JKNLLS-2	0.0775	0.1490	0.3637	0.1960	0.1624	0.2545	0.5226	0.2924
NLLSF	0.0824	0.1241	0.2603	0.1529	0.1916	0.2358	0.3893	0.2202
SMS-1	-0.1964	-0.1583	0.3889	0.2137	-0.2735	-0.2162	0.5150	0.2732
SMS-2	-0.0131	0.0215	0.3156	0.1986	0.0107	0.0499	0.4150	0.2682
SMS-3	-0.0019	0.0295	0.3191	0.2036	0.0289	0.0662	0.4217	0.2722