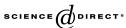


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Continuous time random walks and queues: Explicit forms and approximations of the conditional law with respect to local times[☆]

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Abstract

In the filtering problem considered here, the state process is a continuous time random walk and the observation process is an increasing process depending deterministically on the trajectory of the state process. An explicit construction of the filter is given. This construction is then applied to a suitable approximation of a Brownian motion and to a rescaled M/M/1 queueing model. In both these cases, the sequence of the observation processes converges to a local time, and a convergence result for the respective filters is given. The case of a queueing model when the observation is the idle time is also considered. © 2006 Elsevier B.V. All rights reserved.

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1. Introduction

The kind of problems we are interested in arises from the following situation. Suppose that in a queue we can observe, up to time t, whether the queue is busy or idle, but we cannot observe the size of the queue, so that the observation process is the total time the queue has spent in 0,

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i.e. the so called *idle time* (see [9]). Then the problem is to evaluate the size of the queue at time t, given this information, i.e. to compute the conditional law (or the filter) of the queue given the observation process up to time t. In the setup of a heavy traffic limit, the rescaled queue converges to a reflected Brownian motion and the observation process converges to its local time. The limit model can be constructed as $(W_t + \Lambda_t, \Lambda_t)$, where W_t is a Brownian motion and

$$\Lambda_t = \ell_t(W),\tag{1}$$

where

$$\ell: D_{\mathbb{R}}[0,\infty) \to D_{\mathbb{R}}[0,\infty), x \to \ell(x), \quad \text{such that } \ell_t(x) = -\inf_{s \le t} x(s) \land 0, \tag{2}$$

is the functional involved in the solution of the Skorohod problem for $x \in D_{\mathbb{R}}[0, \infty)$, with $x(0) \ge 0$, i.e. $(z, v) = (x + \ell(x), \ell(x))$ is the unique pair of functions (z, v) satisfying z(t) = x(t) + v(t), and such that $z(t) \ge 0$, for all $t \ge 0$, v(0) = 0, v is nondecreasing and increases only when z(t) = 0.

In the limit model, the corresponding filtering problem is the computation of the conditional law of a reflected Brownian motion $W_t + \Lambda_t$ when the observation process is its local time Λ_t , i.e. the computation of the filter $E[g(W_t + \Lambda_t)/\mathcal{F}_t^{\Lambda}]$ for g in a sufficiently large class of functions.

The first problem is to find the exact expression for the filters, both for the limit model and for the rescaled queue model. The second problem concerns the convergence of the latter to $E[g(W_t + \Lambda_t)/\mathcal{F}_t^{\Lambda}]$.

The filter of the limit Brownian motion model is derived in [8] (Sections 4 and 6), where it is obtained by means of a suitable sequence of processes Λ^n approximating the observation process Λ . Each process Λ^n is proportional to a counting process, and therefore the nonlinear filtering techniques for counting processes are used. The filter can also be derived by means of the Azéma martingale, and this derivation is shortly discussed in [8]. For sake of completeness, we recall its explicit expression.

Theorem 1.1. Let W_t be a Brownian motion with diffusion coefficient a^2 and drift $c \in \mathbb{R}$ and let Λ_t be the local time defined in (1). Let g be a bounded measurable function.

Denote

$$\Pi(s,l;g) = \int_0^\infty g\left(-l + y\sqrt{s}\right) y \exp\left(-\frac{1}{2}y^2\right) dy \quad s \ge 0,$$
(3)

$$\Pi_{a^2,c}(s,l;g) = \frac{\Pi\left(a^2s,l;g(\cdot)\exp\left(\frac{c}{a^2}\cdot\right)\right)}{\Pi\left(a^2s,l;\exp\left(\frac{c}{a^2}\cdot\right)\right)},\tag{4}$$

$$\hat{\Pi}_{a^2,c}(s;g) = \Pi_{a^2,c}(s,0;g).$$
(5)

Then

$$\pi_t(g) = E\left[g(W_t)/\mathcal{F}_t^{\Lambda}\right] = \Pi_{a^2,c}(\zeta_t, \Lambda_t; g),\tag{6}$$

and

$$\hat{\pi}_t(g) = E\left[g(W_t + \Lambda_t)/\mathcal{F}_t^\Lambda\right] = \hat{\Pi}_{a^2,c}(\zeta_t;g),\tag{7}$$

where \mathcal{F}_t^{Λ} is the history generated by Λ_u up to time t, ζ_t is the elapsed time from the last visit to 0 for the process $W_t + \Lambda_t$, i.e.

$$\zeta_t = \gamma_t^0 (W + \Lambda) = \gamma_t(\Lambda), \tag{8}$$

with

$$\gamma_t^0(x) = t - \sup\{s < t : x_s = 0\},\tag{9}$$

$$\gamma_t(x) = t - \sup\{s < t : x_s < x_t\}.$$
(10)

Note that $\Pi_{1,0}(s, l; g) = \Pi(s, l; g) = E[g(-l + W_s^*)/\Lambda_s^* = 0]$, where W^* is any standard Brownian motion and Λ^* is the local time of its Skorohod reflection.

In this paper we start with a somehow simplified version of the motivating problem: we consider a continuous time random walk Y_t and its conditional law w.r.t. $L_u = \ell_u(Y)$ up to time t and, in analogy with the Brownian motion case, though incorrectly, in the following we refer to L_t as the local time associated to Y_t . The above problem is connected with the original one, indeed in several cases a queueing model can be represented as the reflection $Y_t + L_t$ of a continuous time random walk Y_t , and the jump times of L_t belong to the set $\{s \ge 0 \text{ s.t. } Y_s + L_s = 0\}$. It is worth observing that it would be more natural to refer to C_t , the time the process $Y_t + L_t$ spends in 0, as the "local time" of $Y_t + L_t$: indeed, in contrast to L_t , the process C_t has continuous paths, and the measure dC_t is carried by the set $\{s \ge 0 \text{ s.t. } Y_s + L_s = 0\}$.

It turns out (see Proposition 2.1) that the filter of Y_t w.r.t. L_u up to time t can be expressed as a probability measure depending deterministically on L_t and $\gamma_t(L)$, where γ_t is defined in (10). We also derive a more explicit expression for the filter under the assumption that the process Y_t can be decomposed as $Y_t = V_{Z_t}$, where Z_t is a renewal process and V_k is a discrete time random walk, with Z_t and V_k mutually independent. Similar results also hold for rescaled random walks.

We are interested in the situation when a sequence X_t^n of rescaled random walks converges to a Brownian motion W_t in $D_{\mathbb{R}}[0, +\infty)$. Then a continuous map argument applies to show that $(X_t^n, L_t^n) = (X_t^n, \ell_t(X^n))$ converges to $(W_t, \Lambda_t) = (W_t, \ell_t(W))$, and analogously the systems with the reflected random walk $(X_t^n + L_t^n, L_t^n)$ converge to the system with the reflected Brownian motion $(W_t + \Lambda_t, \Lambda_t)$ (see Section 5 for the details). In analogy with the second equality of (8), we denote

$$\xi_t^n = \gamma_t(L^n) = t - \sup\{u \le t \text{ such that } L_u^n < L_t^n\}.$$
(11)

the elapsed time from last jump time of L^n . Then, for random walk systems, the corresponding filter is

$$\pi_t^n(g) = E[g(X_t^n) / \mathcal{F}_t^{L^n}] = \Sigma^n(\xi_t^n, L_t^n; g)$$
(12)

with $\Sigma^n(s, l)$ defined in (20), while for the reflected systems the filter is

$$\hat{\pi}_{t}^{n}(g) = E[g(X_{t}^{n} + L_{t}^{n})/\mathcal{F}_{t}^{L^{n}}] = \hat{\Sigma}^{n}(\xi_{t}^{n};g)$$
(13)

with $\hat{\Sigma}^n(s) = \Sigma^n(s, 0)$.

The problem whether $\pi_t^n = \Sigma^n(\xi_t^n, L_t^n)$ converge weakly to the filter $\pi_t = \prod_{a^2,c}(\zeta_t, \Lambda_t)$ of the limit is strictly related to the convergence of the filters $\hat{\pi}_t^n = \hat{\Sigma}^n(\xi_t^n)$ for the reflected random walks to $\hat{\pi}_t = \hat{\Pi}_{a^2,c}(\zeta_t)$. Depending on the model, we select one or the other problem.

On the other hand, from a computational point of view, it is quite difficult to use the exact expression of $\hat{\Sigma}^n(s)$ to compute the filter $\hat{\pi}_t^n$. Then it is also interesting to find a good

approximation of the filter of the discrete system, depending on the actually observed process L^n , so that it can be used in applications. For the reflected random walk system, a natural choice in order to give a manageable approximation of the filter is to use the limit functional $\hat{\Pi}_{a^2,c}(s)$, evaluated at $s = \xi_t^n$.

Approximation problems in filtering have been studied in more general situations by many authors, among which we recall in particular Bhatt et al. in [1] and Goggin ([6,5]). Most of these results concern diffusive models and do not apply to our case. Moreover, usually the applications concern the problem to approximate a given signal/observation process with a suitably chosen sequence of signal/observation processes so that the corresponding sequence of filters converges to the filter of the original process. We start from a different point of view: the sequence of processes is given and the problem is to show the convergence of the filters to the filter of the state/observation limit, in the sense specified above.

The problem of weak convergence of the sequence of filters is not a trivial problem, as even strong convergence of random variables does not imply convergence of the conditional laws. This is clearly explained by the following simple and illuminating example (see [6]). Let ξ be a real random variable, and $(\xi_n, \eta_n) = (\xi, \xi/n)$. Then (ξ_n, η_n) converges strongly to (ξ, η) , with $\eta = 0$. Nevertheless, for any measurable function g, $E(g(\xi_n)/\eta_n) = g(\xi)$, so that the conditional law of ξ_n given η_n is the measure concentrated in $\xi(\omega)$, while $E(g(\xi)/\eta) = E(g(\xi))$, so that the conditional law of ξ given η coincides with the (deterministic) law $P \circ \xi^{-1}$ of ξ .

In this example, although the sequence of the conditional laws of ξ_n given η_n does not converge to the conditional law of the limit, it is a constant sequence and therefore is a converging sequence. This is indeed not surprising in the light of the next general result, which is a slight generalization of a result of Goggin [6] (the proof of Theorem 2.1, Step 1): one has only to replace the sequence of σ -algebras used in [6] with a general sequence.

Lemma 1.2. Let R_n be a sequence of random variables with values in a Polish space, let \mathcal{H}^n be a sequence of σ -algebras, and let α^n be a regular version of the conditional distribution of R_n given \mathcal{H}^n . If $\{R_n, n \in \mathbb{N}\}$ is tight, then $\{\alpha^n, n \in \mathbb{N}\}$ is tight.

Then, as far as weak convergence is concerned, for the systems converging to a Brownian motion W, the main problem is to check whether the limit points of the sequence of filters are all equal to the filter of W w.r.t. the local time Λ .

The first model we consider is a non-Markovian queueing model arising when a Brownian motion W is approximated by a sequence of continuous time random walks W^n , obtained with a suitable interpolation procedure. The approximation scheme we propose for W follows some of the ideas used in [5] to study a filter approximation problem in diffusive models, and is related to the approximation scheme used in [8]. In this particular case, we get a strong convergence result for the approximating filter.

The second model we consider is the case when the renewal process of the random walk is a Poisson process, so that the reflected random walk is an M/M/1 queue. The main results are weak convergence of the corresponding filters (see Theorem 5.2) and approximation in $L^p(\Omega \times [0, T])$ -norm (see Theorem 5.3) and are based on the weak convergence of (ξ_t^n, L_t^n) to (ζ_t, Λ_t) (see Proposition 5.5) and on the convergence of $\hat{\Sigma}^n(\cdot)$ to $\hat{\Pi}_{2\lambda,c}(\cdot)$ (see Proposition 5.4), in the sense that

$$\lim_{n \to \infty} \hat{\Sigma}^n(s_n; g) = \hat{\Pi}_{2\lambda, c}(s; g), \tag{14}$$

for any g in a convergence determining class, whenever s_n converges to s, with s > 0. We prove the above key convergence result in Section 5.2, where we reformulate the problem in terms of the symmetric random walk by using a suitable change of measure and a reflection principle (see Lemma 5.7).

It is important to note that, when we deal with a queue $Q_t^n = X_t^n + L_t^n$, i.e. with a reflected random walk, the previous results concern the filter w.r.t. the filtration

$$\mathcal{G}_t^n = \mathcal{F}_t^{L'}$$

generated by the local time associated with the random walk, while the motivating problem concerns the filter of the queue w.r.t. the filtration

$$\mathcal{H}_t^n = \mathcal{F}_{t^+}^{C^n}$$

generated by the idle time C_t^n , i.e. the total time spent in 0 up to t. These two problems are strictly related: for instance (Q_t^n, C_t^n) , as well as (Q_t^n, L_t^n) , converges weakly to the reflected system $(W_t + \Lambda_t, \Lambda_t)$. This property, among others, allows us to extend the previous convergence and approximation results to this situation (see Theorems 6.4 and 6.6 in the last section).

2. The model

Fix a probability space (Ω, \mathcal{F}, P) and consider on it a sequence $\{(T_j, U_j), j \ge 1\}$ satisfying the assumption

H The $\mathbb{R}^+ \times \{+1, -1\}$ -valued random variables (T_j, U_j) , for $j \ge 1$, are identically distributed and mutually independent.

Put $\tau_0 = 0$, $\tau_k = \sum_{j=1}^k T_j$ for $k \ge 1$, and consider the renewal process $Z_t = \sum_{j=1}^\infty \mathbb{I}(\tau_j \le t)$ and the random walk $\{V_j, j \ge 0\}$ defined by $V_0 = 0$, $V_j = V_{j-1} + U_j$, $j \ge 1$.

Finally, consider the continuous time random walk

$$Y_t = V_{Z_t} = \sum_{j=1}^{\infty} U_j \mathbb{I}(\tau_j \le t) = \sum_{j \le Z_t} U_j.$$
 (15)

The solution of the Skorohod problem for the process Y_t is given by the pair $(Y_t + L_t, L_t)$, with

$$L_t = \ell_t(Y) = \sum_{j=1}^{\infty} \mathbb{I}(\sigma_j \le t), \tag{16}$$

where ℓ is defined in (2), and the sequence of its jump times $\{\sigma_j, j \ge 0\}$ is the subsequence of $\{\tau_j, j \ge 0\}$ defined by $\sigma_0 = 0$ and

$$\sigma_j = \inf\{\tau_k \text{ s.t. } Y_{\tau_k} \le -j\} = \inf\{t > 0 \text{ s.t. } Y_t \le -j\} \quad \text{for } j \ge 1.$$

Set

$$\mathcal{G}_t = \mathcal{F}_t^L = \sigma\{L_s, s \leq t\}.$$

Obviously, $\{\sigma_i, j \ge 0\}$ are stopping times w.r.t. both the histories \mathcal{G}_t and \mathcal{F}_t^Y .

Moreover, condition **H** implies that the process $Y_{s+\sigma_j} - Y_{\sigma_j}$ is independent of \mathcal{G}_{σ_j} and is equal in law to the process Y_s , and therefore the process L_t is a renewal process, with inter-arrival times $\{S_h = \sigma_h - \sigma_{h-1}, h \ge 1\}$. The following representations for the filter of Y_t given \mathcal{G}_t are then straightforward. **Proposition 2.1.** Assume **H**, then the conditional law of Y_t given \mathcal{G}_t admits the following *P*-a.s. representations

$$\begin{split} E[g(Y_t)/\mathcal{G}_t] &= \sum_{j=0}^{\infty} \frac{E\left[g(-j+Y_{s+\sigma_j}-Y_{\sigma_j})\mathbb{I}\left(S_{j+1}>s\right)\right]}{E\left[\mathbb{I}(S_{j+1}>s)\right]} \bigg|_{s=t-\sigma_j} \mathbb{I}\{\sigma_j \leq t < \sigma_{j+1}\},\\ &= \frac{E[g(-j+Y_s)\mathbb{I}(\sigma_1>s)]}{E[\mathbb{I}(\sigma_1>s)]} \bigg|_{j=L_t,s=\gamma_t(L)}, \end{split}$$

where $\gamma_t(\cdot)$ is defined in (10).

Proof. The first representation can be obtained using standard techniques. For the second one, it is enough to note that

$$E[g(-j + Y_{s+\sigma_j} - Y_{\sigma_j})\mathbb{I}(S_{j+1} > s)] = E[g(-j + Y_s)\mathbb{I}(\sigma_1 > s)],$$

and finally that, if $\sigma_j \leq t < \sigma_{j+1}$, then $\sigma_j = \sup\{u \leq t \text{ s.t. } L_u < L_t\}$. \Box

In order to get a more explicit representation of the filter, we observe that defining recursively the sequence $\{M_i, i \ge 0\}$ by $M_0 = 0$ and $M_i = \inf\{k \ge 0 : V_{M_0 + \dots + M_{i-1} + k} - V_{M_0 + \dots + M_{i-1}} = -1\}$, then

$$\sigma_0 = 0, \quad \sigma_h = \sum_{i=1}^{M_1 + \dots + M_h} T_i = \tau_{M_1 + \dots + M_h}, \quad h \ge 1.$$
(17)

Under Condition **H**, the sequence $\{M_i, i \ge 1\}$ is a sequence of i.i.d. random variables. Under the further assumption,

K the random variables T_1 and U_1 are mutually independent, with

$$P(T_1 \le t) = F(t), \quad P(U_j = 1) = p, \quad P(U_j = -1) = 1 - p = q, \quad p \in (0, 1),$$

the sequences $\{T_j, j \ge 1\}$ and $\{U_j, j \ge 1\}$ are mutually independent, and clearly also $\{\tau_i, i \ge 1\}$ and $\{M_i, i \ge 1\}$ are mutually independent. The next result provides a more explicit expression for the filter.

Proposition 2.2. Assume conditions H and K. Then

$$E[g(Y_t)/\mathcal{G}_t] = \frac{\sum_{k=1}^{\infty} E[\mathbb{I}(M_1 \ge k)g(-j + V_{k-1})](F_{k-1}(s) - F_k(s))}{\sum_{m=1}^{\infty} P(M_1 \ge m)(F_{m-1}(s) - F_m(s))} \bigg|_{j=L_t, s=\gamma_t(L)}$$
(18)

where F_k is the distribution function of τ_k , i.e. $F_k = F^{*k}$, the k-fold convolution of F.

Proof. Taking into account (15) and (17) and the independence of $\{\tau_i, i \ge 1\}$ and $\{M_i, i \ge 1\}$, it is sufficient to observe that

$$E\left[g(-j+Y_s)\mathbb{I}\left(\sigma_1 > s\right)\right] = E\left[\sum_{m=1}^{\infty} \mathbb{I}\left(M_1 = m\right)g\left(-j + V_{Z_s}\right)\mathbb{I}\left(\tau_m > s\right)\right]$$
$$= E\left[\sum_{m=1}^{\infty} \sum_{k=1}^{m} \mathbb{I}\left(M_1 = m\right)g\left(-j + V_{k-1}\right)\mathbb{I}\left(\tau_{k-1} \le s < \tau_k\right)\right].$$

The state space of the process Y_t being discrete, the filter $E[g(Y_t)/\mathcal{G}_t]$ is determined by its discrete density $v_t(x)$, $x \in \mathbb{Z}$, i.e. $v_t(x) = E[g(Y_t)/\mathcal{G}_t]$ with $g(z) = \mathbb{I}_{\{x\}}(z), z \in \mathbb{Z}$. Then

$$\nu_t(x) = \frac{\sum_{k=1}^{\infty} P(V_{k-1} = x + j, M_1 \ge k)(F_{k-1}(s) - F_k(s))}{\sum_{m=1}^{\infty} P(M_1 \ge m)(F_{m-1}(s) - F_m(s))} \bigg|_{j=L_t, s=\gamma_t(L)}$$

where

$$P(V_{k-1} = a, M_1 \ge k) = \frac{a+1}{k} {\binom{k}{\frac{k+a+1}{2}}} p^{\frac{k+a-1}{2}} q^{\frac{k-a-1}{2}}$$
(19)

when k + a - 1 is even and $|a| \le k - 1$, while it is 0 otherwise. Finally, we note that the normalization factor in (18) can also be written as $\sum_{m=1}^{\infty} P(M_1 = m)(1 - F_m(s))$.

3. Scaling and notations

Let $\{\tilde{X}^n, n \in \mathbb{N}\}$ be a sequence of continuous time random walks defined in $(\Omega^n, \mathcal{F}^n, P^n)$. We assume that $\tilde{X}^n_t = \tilde{V}^n_{\tilde{Z}^n_t}$, where \tilde{V}^n_k and \tilde{Z}^n_t are defined as in Section 2 starting from a sequence $\{(\tilde{T}^n_j, \tilde{U}^n_j); j \ge 1\}$. Consider the deterministic linear time-space scaling

$$X_t^n = b_n \tilde{X}_{a_n t}^n$$

where $\{a_n, n \in \mathbb{N}\}$ and $\{b_n, n \in \mathbb{N}\}$ are suitable sequences of real positive numbers. Then the process $L_t^n = \ell_t(X^n)$ can be obtained just applying the same scaling to the process $\tilde{L}_t^n = \ell_t(\tilde{X}^n)$, i.e. $L_t^n = \ell_t(X^n) = b_n \tilde{L}_{a_nt}^n$. We are interested in the conditional law of X_t^n w.r.t. $\mathcal{F}_t^{L^n} = \mathcal{F}_{a_nt}^{\tilde{L}^n}$, i.e. the filter

$$\pi_t^n(g) = E^{P^n}[g(X_t^n)/\mathcal{F}_t^{L^n}] = E^{P^n}[g(b_n \tilde{X}_{a_n t}^n)/\mathcal{F}_{a_n t}^{L^n}],$$

where $E_t^{P^n}$ denotes the expectation w.r.t. P^n . For the sake of notational convenience, we will denote $\mathcal{F}_t^{L^n}$ as \mathcal{G}_t^n and, when unnecessary, drop the symbol P^n in the expectation, so that the filter becomes

$$\pi_t^n(g) = E[g(X_t^n)/\mathcal{G}_t^n].$$

For each *n*, let σ_1^n be the first exit time of the process X_t^n from the set $(-b_n, \infty)$, denote by $\Sigma^n(s, l)$ the probability measure such that

$$\Sigma^{n}(s,l;g) = \frac{E[g(-l+X_{s}^{n})\mathbb{I}(\sigma_{1}^{n}>s)]}{E[\mathbb{I}(\sigma_{1}^{n}>s)]},$$
(20)

and assume that the sequences $\{(\tilde{T}_j^n, \tilde{U}_j^n); j \ge 1\}$ satisfy the assumption **H** stated in Section 2. Then the filter can be written in brief as

$$\pi_t^n(g) = E[g(X_t^n) / \mathcal{G}_t^n] = \Sigma^n(\xi_t^n, L_t^n; g),$$
(21)

where ξ_t^n is defined in (11).

By taking into account that $\hat{\pi}_t^n(g) = E[g(X_t^n + L_t^n)/\mathcal{G}_t^n] = E[g(X_t^n + m)/\mathcal{G}_t^n]|_{m=L_t^n}$, the filter can be written as

$$\hat{\pi}_t^n(g) = E[g(X_t^n + L_t^n)/\mathcal{G}_t^n] = \hat{\Sigma}^n(\xi_t^n; g),$$
(22)

where

$$\hat{\Sigma}^{n}(s;g) = \Sigma^{n}(s,0;g) = \frac{E[g(X_{s}^{n})\mathbb{I}(\sigma_{1}^{n} > s)]}{E[\mathbb{I}(\sigma_{1}^{n} > s)]}.$$
(23)

Remark 3.1. Note that $\hat{\Sigma}^n(s; g)$, as well as $\Sigma^n(s, l)$, also depends on the probability measure P^n , i.e. $\hat{\Sigma}^n(s, l) = \hat{\Sigma}^n_{pn}(s, l)$. This dependence will be emphasized when necessary.

When the process $\tilde{X}_{t}^{n} = \tilde{V}_{\tilde{Z}_{t}^{n}}^{n}$ also satisfies assumption **K** of Section 2, then Proposition 2.2 easily provides the explicit expressions of $\Sigma^{n}(s, l)$:

$$\Sigma^{n}(s,l;g) = \frac{\sum_{k=1}^{\infty} E[\mathbb{I}(\tilde{M}_{1}^{n} \ge k)g(b_{n}\tilde{V}_{k-1}^{n} - l)](\tilde{F}_{k-1}^{n}(a_{n}s) - \tilde{F}_{k}^{n}(a_{n}s))}{\sum_{m=1}^{\infty} P(\tilde{M}_{1}^{n} = m)(1 - \tilde{F}_{m}^{n}(a_{n}s))},$$
(24)

where \tilde{M}_1^n , \tilde{F}_k^n have a similar meaning to M_1 , F_k in (18). More precisely, \tilde{F}_1^n is the distribution function of $\tilde{T}_1^n = \inf\{t > 0 \text{ s.t. } |\tilde{X}_t^n| \ge 1\}$ and, if T_1^n denotes the first jump time of the process X_t^n , then $T_1^n = \tilde{T}_1^n/a_n$, and therefore $\tilde{F}_1^n(a_n s) = F_1^n(s)$ is the distribution function of T_1^n , and analogously $\tilde{F}_k^n(a_n s) = F_k^n(s)$, where F_k^n is the k-fold convolution of F_1^n .

We end this section by introducing the notation $\omega_g(\delta) = \sup_{|x-y| \le \delta} |g(x) - g(y)|$ for the modulus of continuity of a uniformly continuous function g.

4. The interpolating Brownian motion model

In this section we study the case of a continuous time random walk arising when a Brownian motion W is approximated with a sequence of processes W^n . The processes W^n are defined on the probability space of W, and are obtained pathwise by an interpolation procedure. For this model we are able to get a strong convergence result for the filter. We start by introducing the approximating models, then we show the convergence result. Successively, we discuss how the approximating models W^n fall into the frame of the previous sections. In particular, when the process W is a standard Brownian motion, the processes W^n correspond to the case examined at the end of the previous section, with scaling parameters $a_n = 2^{2n}$ and $b_n = 1/2^n$, $p_n = q_n = 1/2$, and $\tilde{F}_1^n = \tilde{F}_1$, where

$$\tilde{F}_{1}(t) = 4 \sum_{j=0}^{+\infty} (-1)^{j} \frac{1}{\sqrt{2\pi}} \int_{\frac{(2j+1)}{\sqrt{t}}}^{+\infty} \exp\left(-\frac{1}{2}x^{2}\right) \mathrm{d}x.$$
(25)

The basic idea is to approximate the state W by the stepwise interpolation of the random points where W hits a uniform grid and consider as an approximating observation the local time of the approximating state. This procedure is a deterministic one, therefore we describe it in the deterministic case.

Let $z \in D_{\mathbb{R}}[0, +\infty)$ and let $h \in \mathbb{R}^+$ be a fixed threshold. Consider the sequence $\{\widehat{\tau}_k^h(z), k \ge 0\}$:

$$\begin{cases} \widehat{\tau}_{0}^{h}(z) = 0\\ \widehat{\tau}_{k}^{h}(z) = \inf\{t > \widehat{\tau}_{k-1}^{h}(z) : |z(t) - z(\widehat{\tau}_{k-1}^{h}(z))| > h\}, \quad k \ge 1, \end{cases}$$
(26)

and the function $z^h \in D_{\mathbb{R}}[0, +\infty)$:

$$z^{h}(t) = \sum_{k=0}^{\infty} \mathbb{I}_{[\hat{\tau}^{h}_{k}(z), \hat{\tau}^{h}_{k+1}(z))}(t) z(\hat{\tau}^{h}_{k}(z)).$$
(27)

We need the following result whose proof is left to the reader.

Lemma 4.1. Let $z \in D_{\mathbb{R}}[0, +\infty)$. Then $\sup_{t \in \mathbb{R}^+} (|z^h(t) - z(t)|) \le h$, and $(z^h, \ell(z^h))$ converge uniformly to $(z, \ell(z))$, where the functional ℓ is defined by (2).

Remark 4.2. When z is a continuous function, the process $\ell(z^h)$ admits the representation

$$\ell_t(z^h) = 0 \lor (-z_0) - \sum_{j=0}^{\infty} z(\sigma_j^h(z)) \mathbb{I}_{[\sigma_j^h(z), \sigma_{j+1}^h(z))}(t),$$

where

$$\sigma_j^h(z) = \inf\{t \text{ s.t. } z(t) - z_0 \le -jh\} = \inf\{\widehat{\tau}_k^h(z) \text{ s.t. } z(\widehat{\tau}_k^h(z)) - z_0 \le -jh\}.$$
(28)

When furthermore $z_0 = 0$, then $z(\sigma_i^h(z)) = -jh$ and

$$\ell_t(z^h) = \sum_{j=0}^{\infty} jh \mathbb{I}(\sigma_j^h(z) \le t < \sigma_{j+1}^h(z)) = \sum_{j=0}^{\infty} h \mathbb{I}(\sigma_j^h(z) \le t).$$
(29)

We now apply this approximating procedure to the (not necessarily standard) Brownian motion W_t . Now fix the sequence of thresholds $h_n = \frac{1}{2^n}$, and consider the stopping times $\tau_k^n := \hat{\tau}_k^h(W)$, when using $h = h_n = \frac{1}{2^n}$ in (26). Then the approximating signal/observation process (W^n, Λ^n) is a $D_{\mathbb{R}^2}[0, +\infty)$ -valued process, where

$$W_t^n = \sum_{k=0}^{\infty} W(\tau_k^n) \mathbb{I}_{[\tau_k^n, \tau_{k+1}^n)}(t), \quad \text{and} \quad \Lambda_t^n = \ell_t(W^n).$$
(30)

Note that Lemma 4.1 provides the following convergence result.

Lemma 4.3. Let (W^n, Λ^n) be defined as in (30). Then, for each $t \in \mathbb{R}^+$,

$$|W_t^n - W_t| \le \frac{1}{2^n},$$
(31)

and $(W^n, \Lambda^n) = (W^n, \ell(W^n))$ converge to $(W, \Lambda) = (W, \ell(W))$ a.s., w.r.t. the topology of the uniform convergence.

By (29),

$$\Lambda_t^n = \sum_{j=0}^\infty \frac{1}{2^n} \mathbb{I}(\sigma_j^n \le t), \tag{32}$$

where

$$\sigma_j^n = \inf\left\{t \text{ s.t. } W_t \le -\frac{j}{2^n}\right\} = \inf\left\{t \text{ s.t. } \Lambda_t \ge \frac{j}{2^n}\right\}.$$
(33)

Moreover, with the above choice of the threshold, the *n*-th grid is generated by considering the dyadic intervals of rank *n*. Then, in the passage from the *n*-th grid to the (n + 1)-th grid, each threshold is split into two parts, and therefore $\sigma_{2j}^{n+1} = \sigma_j^n$. This property is decisive, since it guarantees that, for any t, $\{\mathcal{G}_t^n = \mathcal{F}_t^{\Lambda^n}, n \in \mathbb{N}\}$ is an increasing family of σ -algebras, with $\mathcal{G}_t^n \uparrow \mathcal{F}_t^{\Lambda}$ (see Lemma 2.3 of [8], where the process Λ_t^n is defined as in (32)). The last fact allows us to show the claimed strong convergence result, which is a slight generalization of Theorem 2.4 of [8].

Theorem 4.4. Let π_t and π_t^n be the filters defined in (6) and (21). Consider them as random variables with values in the space of probability measures on \mathbb{R} , endowed with the topology of weak convergence. Then the sequence π_t^n converges to π_t almost certainly. As a consequence, for all $g \in C_b(\mathbb{R})$,

$$\pi_t^n(g) = E[g(W_t^n)/\mathcal{G}_t^n] \to \pi_t(g) = E[g(W_t)/\mathcal{F}_t^\Lambda], \quad a.s. \text{ and in } L^1.$$
(34)

Proof. Observe that $|\pi_t(g) - \pi_t^n(g)|$ is bounded above by

$$|E[g(W_t)/\mathcal{F}_t^{\Lambda}] - E[g(W_t)/\mathcal{G}_t^n]| + |E[g(W_t)/\mathcal{G}_t^n] - E[g(W_t^n)/\mathcal{G}_t^n]|.$$

The first term converges to zero almost certainly and in L^1 -sense. Indeed, as in Theorem 2.4 of [8], we apply Doob's convergence theorem to the discrete time martingale $E[g(W_t)/\mathcal{G}_t^n]$. For all g uniformly continuous, with modulus of continuity ω_g , the second term is bounded above by

$$|E[|g(W_t) - g(W_t^n)|/\mathcal{G}_t^n]| \le \omega_g(1/2^n) \to 0,$$

and so we get (34) for all g in a convergence determining class. Without loss of generality, we can take this class to be denumerable, and therefore we obtain the convergence of π_t^n to π_t . The convergence result (34) for all bounded and continuous g is then straightforward.

One can get the analogous convergence results for the corresponding queueing model generated by reflecting W^n . In particular, the conditional laws defined by $E[g(W_t^n + \Lambda_t^n)/\mathcal{G}_t^n]$ converge a.s. to the conditional law $\hat{\pi}_t$ defined by (7).

In addition, the strong convergence of Theorem 4.4 implies the weak convergence for the filters of any rescaled model X^n sharing the same law as W^n . As an example, we can take $\tilde{X}^n = W^0$ for all n, and $X_t^n = \frac{1}{2^n} W_{2^{2n}t}^0$.

Now we show that the approximating model falls into the frame of the previous sections. The sequence $\{(\tilde{T}_k^n, \tilde{U}_k^n), k \ge 1\}$ is defined as

$$\tilde{T}_k^n = (\tau_k^n - \tau_{k-1}^n)/2^{2n}, \qquad \tilde{U}_k^n = 2^n \left(W_{\tau_k^n} - W_{\tau_{k-1}^n} \right),$$

which clearly satisfies condition H. Then

$$W_t^n = \frac{1}{2^n} \tilde{V}_{\tilde{Z}_{2^{2n_t}}^n}^n,$$

where \tilde{Z}_t^n is the renewal process defined by the sequence of i.i.d. inter-arrival times $\{\tilde{T}_k^n, k \in \mathbb{N}\}$, and $\tilde{V}_k^n = 2^n W_{\tau_k^n}$. Therefore, recalling (21), $E[g(W_t^n)/\mathcal{G}_t^n] = \Sigma^n(\gamma_t(W^n), \ell_t(W^n); g)$, with $\Sigma^n(s, l; g)$ as in (23), and γ_t as in (10). A similar result also holds for $E[g(W_t^n + \ell_t(W^n))/\mathcal{G}_t^n]$.

When the drift coefficient of W is zero, the random variables \tilde{T}_k^n have common law

$$\tilde{F}^{n}(t) = P(\tilde{T}_{k}^{n} \le t) = \tilde{F}_{1}(2^{2n}a^{2}t),$$
(35)

where a^2 is the diffusion coefficient and \tilde{F}_1 is defined in (25), and \tilde{U}_k^n is symmetric and independent of \tilde{T}_k^n , for each k (see e.g. [4] page 342). Therefore, $\tilde{V}_k^n = 2^n W_{\tau_k^n}$ is a symmetric random walk, independent of the renewal process \tilde{Z}_t^n . Then condition **K** holds, and one can use (24) to define $\Sigma^n(s, l)$.

When the drift coefficient is $c \neq 0$, the processes \tilde{Z}_t^n and \tilde{V}_k^n , defined as above, are not mutually independent, so one cannot use (24). Nevertheless, (24), with \tilde{F}^n as in (35) above, could be used to get the approximate expression

$$\tilde{\pi}_t^n(g) = \frac{E^{P_0}[g(W_t^n)\exp(\frac{c}{a^2}W_t^n)/\mathcal{G}_t^n]}{E^{P_0}[\exp(\frac{c}{a^2}W_t^n)/\mathcal{G}_t^n]} = \frac{\Sigma^n(s,l;g(\cdot)\exp(\frac{c}{a^2}\cdot))}{\Sigma^n(s,l;\exp(\frac{c}{a^2}\cdot))}\bigg|_{s=\gamma_t(W^n), l=\ell_t(W^n)}$$

Indeed, from the Kallianpur Striebel formula and Girsanov Theorem

$$E[g(W_t^n)/\mathcal{G}_t^n] = \frac{E^{P_0}[g(W_t^n)\exp(\frac{c}{a^2}W_t)/\mathcal{G}_t^n]}{E^{P_0}[\exp(\frac{c}{a^2}W_t)/\mathcal{G}_t^n]}$$

where P_0 is equivalent to P, and under P_0 the process W has drift coefficient zero. Then

$$E[g(W_t^n)/\mathcal{G}_t^n] = \frac{E^{P_0} \left[g(W_t^n) \exp(\frac{c}{a^2} W_t^n) \exp(\frac{c}{a^2} (W_t - W_t^n)) / \mathcal{G}_t^n \right]}{E^{P_0} \left[\exp(\frac{c}{a^2} W_t^n) \exp(\frac{c}{a^2} (W_t - W_t^n)) / \mathcal{G}_t^n \right]}$$

Moreover, taking into account that $|W_t - W_t^n| \le \frac{1}{2^n}$, one can get that

$$|E[g(W_t^n)/\mathcal{G}_t^n] - \tilde{\pi}_t^n(g)| \le 4 \exp\left(2\frac{|c|}{a^2}\frac{1}{2^n}\right) \frac{|c|}{a^2}\frac{1}{2^n} \|g\|_{\infty}.$$
(36)

5. The M/M/1 queueing model

In this section we consider a random walk with exponential inter-arrival times, and the M/M/1 queue, with arrival intensity λ_n and service potential μ_n , generated by reflecting the random walk. We use the techniques introduced in Section 2 to derive the filter of the M/M/1 queue (and therefore of the random walk) with respect to the local time associated with the random walk. Moreover, under a suitable set of conditions, which are related to the heavy traffic conditions, we also get the weak limit of the filter of the rescaled system (Theorem 5.2) and an approximation for the filter (Theorem 5.3).

5.1. Description of the model and main results

The sequence of random walks we consider is defined by means of the same rule as in (15), namely for each $n \in \mathbb{N}$

$$\tilde{X}_t^n = \tilde{V}_{\tilde{Z}_t^n}^n = \sum_{j=1}^{\tilde{Z}_t^n} \tilde{U}_j^n,$$

where

- A1 \tilde{Z}_{t}^{n} is a Poisson process with intensity $\lambda_{n} + \mu_{n}$; A2 \tilde{V}_{j}^{n} is defined by $\tilde{V}_{j}^{n} = \tilde{V}_{j-1}^{n} + \tilde{U}_{j}^{n}$, where $\{\tilde{U}_{j}^{n}, j \in \mathbb{N}\}$ is a sequence of i.i.d. random variables with $P^{n}(\tilde{U}_{k}^{n} = +1) = \frac{\lambda_{n}}{\lambda_{n} + \mu_{n}}$ and $P^{n}(\tilde{U}_{k}^{n} = -1) = \frac{\mu_{n}}{\lambda_{n} + \mu_{n}}$;
- A3 $\{\tilde{U}_k^n, k \in \mathbb{N}\}$ and \tilde{Z}_t^n are mutually independent.

In this case, the inter-arrival times \tilde{T}_k^n of the renewal process \tilde{Z}_t^n are exponential random variables with expectation $1/(\lambda_n + \mu_n)$. Therefore we are in the situation discussed at the end of Section 3, with $p_n = \lambda_n / (\lambda_n + \mu_n)$, \tilde{F}_1^n the distribution function of an exponential random variable of parameter $\lambda_n + \mu_n$, and moreover the scaling parameters are $a_n = n$ and $b_n = \sqrt{n}$, and then F_k^n is the gamma distribution function with parameter $(k, n(\lambda_n + \mu_n))$.

The conditions C1, C2, and C3 are defined as follows:

C1
$$\lambda_n, \mu_n > 0;$$

C2 $(\lambda_n, \mu_n) \xrightarrow[n \to +\infty]{} (\lambda, \lambda);$
C3 $\sqrt{n}(\lambda_n - \lambda) \xrightarrow[n \to +\infty]{} c(1) \qquad \sqrt{n}(\mu_n - \lambda) \xrightarrow[n \to +\infty]{} c(2)$

Condition C1 avoids considering pure birth or pure death processes, and C3 clearly implies condition C2 and condition

C3*
$$\sqrt{n}(\lambda_n - \mu_n) \xrightarrow[n \to +\infty]{} c = c(1) - c(2).$$

We recall that, when $\lambda_n < \mu_n$, the set of conditions C1, C2, C3* are known in the literature as the *heavy traffic conditions*, and in this case $c \leq 0$. These conditions guarantee the existence of the diffusive limit of the rescaled system, more precisely the sequence of processes $X_t^n = \tilde{X}_{nt}^n / \sqrt{n}$ converges weakly in $D_{\mathbb{R}}[0, +\infty)$ to a Brownian motion W_t , with diffusion coefficient 2λ and drift coefficient c.

Remark 5.1. It is interesting to note that conditions C1, C2, C3 are equivalent to the weak convergence in $D_{\mathbb{R}^2}[0, +\infty)$ of the processes (X_t^n, Z_t^n) , where $Z_t^n = (\tilde{Z}_{nt}^n - 2\lambda nt)/\sqrt{n}$, to a pair of independent Brownian motions (W_t, B_t) with drift c = c(1) - c(2) and d = c(1) + c(2)respectively, and both with variance 2λ . Indeed, the processes \hat{X}_t^n and \hat{Z}_t^n can be represented as

$$\tilde{X}_t^n = \tilde{A}_t^n - \tilde{N}_t^n, \quad \tilde{Z}_t^n = \tilde{A}_t^n + \tilde{N}_t^n$$
(37)

where, if $\tilde{\tau}_k^n$ are the jump times of \tilde{Z}^n ,

$$\tilde{A}_t^n = \sum_{k=0}^{\infty} \mathbb{I}(\tilde{U}_k^n = 1) \mathbb{I}(\tilde{\tau}_k^n \le t)$$
(38)

$$\tilde{N}_t^n = \sum_{k=0}^\infty \mathbb{I}(\tilde{U}_k^n = -1)\mathbb{I}(\tilde{\tau}_k^n \le t),$$
(39)

so that

$$X_t^n = \frac{\tilde{A}_{nt}^n - \tilde{N}_{nt}^n}{\sqrt{n}} = \frac{\tilde{A}_{nt}^n - n\lambda_n t}{\sqrt{n}} - \frac{\tilde{N}_{nt}^n - n\mu_n t}{\sqrt{n}} + \sqrt{n}(\lambda_n - \mu_n)t,$$

$$Z_t^n = \frac{\tilde{A}_{nt}^n - n\lambda_n t}{\sqrt{n}} + \frac{\tilde{N}_{nt}^n - n\mu_n t}{\sqrt{n}} + \sqrt{n}(\lambda_n + \mu_n - 2\lambda)t.$$

By Watanabe's Theorem (see, for instance, [2]) the processes \tilde{A}^n and \tilde{N}^n are mutually independent Poisson processes with intensities λ_n and μ_n , respectively. As a consequence the processes $(\frac{\tilde{A}_{nt}-n\lambda_n t}{\sqrt{n}}, \frac{\tilde{N}_{nt}-n\mu_n t}{\sqrt{n}})$ converge weakly to a pair of independent Brownian motions with zero drift and diffusion coefficient 2λ .

The solution of the Skorohod problem for the process \tilde{X}_t^n is the pair $(\tilde{Q}_t^n, \tilde{L}_t^n)$, where

$$\tilde{Q}_t^n = \tilde{X}_t^n + \tilde{L}_t^n$$

is a M/M/1 queue (see, for instance, [2]), and \tilde{L}_t^n is the local time associated with the process \tilde{X}_t^n . Then, thanks to the weak convergence of X^n , a continuous map argument applies, showing that

$$(X_t^n, Q_t^n, L_t^n) = \left(\frac{\tilde{X}_{nt}^n}{\sqrt{n}}, \frac{\tilde{Q}_{nt}^n}{\sqrt{n}}, \frac{\tilde{L}_{nt}^n}{\sqrt{n}}\right) \Rightarrow (W_t, W_t + \Lambda_t, \Lambda_t),$$
(40)

where $\Lambda_t = \ell_t(W)$ is the local time of the Skorohod reflection of W_t . Indeed, the functional ℓ_t is continuous with respect to the topology of uniform convergence on bounded intervals of time, and X_t^n converges to W_t with respect to this topology, since W_t has continuous trajectories.

The main results are stated in the following theorems, which are proven at the end of this subsection. We recall (see (12) and (13)) that π_t^n and $\hat{\pi}_t^n$ denote the filters of X_t^n and of Q_t^n given the filtration \mathcal{G}_t^n , respectively, where, as in Section 3, \mathcal{G}_t^n denotes the filtration generated by L_t^n .

Theorem 5.2. Assume A1, A2, A3 and C1, C2, C3. Then, for any $t \ge 0$, π_t^n converge weakly to π_t , and $\hat{\pi}_t^n$ converge weakly to $\hat{\pi}_t$, as random variables with values in the space of probability measures endowed with the topology of weak convergence.

In particular, for any $t \ge 0$, and for any bounded continuous function g

$$\pi_t^n(g) = E[g(X_t^n)/\mathcal{G}_t^n] \Rightarrow \pi_t(g) = E[g(W_t)/\mathcal{F}_t^\Lambda]$$
(41)

and

$$\hat{\pi}_t^n(g) = E[g(Q_t^n)/\mathcal{G}_t^n] \Rightarrow \hat{\pi}_t(g) = E[g(W_t + \Lambda_t)/\mathcal{F}_t^\Lambda].$$
(42)

As explained in the introduction, it is interesting to find a good approximation for the filter $\hat{\pi}_t^n = \hat{\Sigma}^n(\xi_t^n)$ which is, at the same time, simpler to handle and depends on the actually observed trajectory. A natural candidate is $\hat{\Pi}_{2\lambda,c}(\xi_t^n)$, where $\hat{\Pi}_{2\lambda,c}(s)$ is defined in (5). We prove that this natural candidate is an $L^p(\Omega \times [0, T])$ -norm approximation of the filter $\hat{\pi}_t^n$.

Theorem 5.3. Under the same assumptions of Theorem 5.2, for all g bounded and continuous, and for each T > 0, p > 0,

$$\int_0^T E|\hat{\Sigma}^n(\xi_t^n;g) - \hat{\Pi}_{2\lambda,c}(\xi_t^n;g)|^p dt \underset{n \to \infty}{\longrightarrow} 0.$$

The proofs of the previous theorems are based on the representations for $\pi_t^n = \Sigma^n(\xi_t^n, L_t^n)$ and $\hat{\pi}_t^n = \hat{\Sigma}^n(\xi_t^n)$, respectively, and the results of Propositions 5.4 and 5.5 below. The first result is the key convergence result (14) announced in the Introduction.

Proposition 5.4. Under the same assumptions of Theorem 5.2, $\hat{\Sigma}^n(s; g)$ converge pointwise to $\hat{\Pi}_{2\lambda,c}(s; g)$ for every bounded continuous function $g : \mathbb{R}^+ \to \mathbb{R}$ and $s \ge 0$. Moreover the

convergence is uniform on bounded intervals contained in $(0, \infty)$, i.e. whenever $s_n \rightarrow s$, with s > 0,

$$\hat{\Sigma}^n(s_n;g) \xrightarrow[n \to \infty]{} \hat{\varPi}_{2\lambda,c}(s;g).$$
(43)

Proof. The proof of this key result is postponed to the next subsection.

The second result concerns the weak convergence of $\xi_t^n = \gamma_t(L^n)$ to $\zeta_t = \gamma_t^0(W + \Lambda) = \gamma_t(\Lambda)$, with γ_t^0 and γ_t defined in (9) and (10), respectively. However, we show a slightly stronger result concerning the weak convergence of $\gamma_t^0(X^n + L^n) = \gamma_t^0(Q^n)$ to ζ_t . This stronger result is used later in Section 6.

Proposition 5.5. Assume A1, A2, A3 and C1, C2, C3*. Then, for each t > 0,

 $(\gamma_t^0(Q^n), \gamma_t(L^n), L_t^n) \Rightarrow (\zeta_t, \zeta_t, \Lambda_t).$

Proof. Define

$$\eta_t^n = \sup\{s < t : L_s^n < L_t^n\}, \quad \eta_t = \sup\{s < t : \Lambda_s < \Lambda_t\}, \\ \beta_t^n = \sup\{s < t : Q_s^n = 0\}, \quad \beta_t = \sup\{s < t : W_s + \Lambda_s = 0\},$$

with $\eta_t^n = t$, $\eta_t = t$, $\beta_t^n = t$ and $\beta_t = t$ when the corresponding sets are empty. Note that

$$\eta_t^n = \sup\{s < t : X_t^n - X_s^n < Q_t^n - Q_s^n\},\\ \eta_t = \sup\{s < t : W_t - W_s < W_t + \Lambda_t - W_s - \Lambda_s\}.$$

Applying the Skorohod representation theorem, we can assume that all the processes live on the same probability space $(\bar{\Omega}, \bar{\mathcal{F}}, \bar{P})$, and that

$$\sup_{s \le t} (|X_s^n - W_s| + |Q_s^n - W_s - \Lambda_s|) \to 0 \quad \vec{P}\text{-a.s.}$$

$$\tag{44}$$

This implies that $L^n \to \Lambda$ uniformly in [0, t], \overline{P} -a.s., and

$$\liminf_{n\to\infty} \quad \eta_t^n \ge \eta_t.$$

Then, since $\gamma_t^0(Q^n) = t - \beta_t^n$ and $\gamma_t(L^n) = t - \eta_t^n$, the result is achieved once we prove that the sequence (β_t^n, η_t^n) converges \bar{P} -a.s. to (η_t, η_t) and $\zeta_t = t - \eta_t$. Let $\beta_t^\infty = \limsup_{n \to \infty} \beta_t^n$ and note that $Q^n(\beta_t^n)$ assumes only the values 0 or $\frac{1}{\sqrt{n}}$. Then, by (44), $W_{\beta_t^\infty} + \Lambda_{\beta_t^\infty} = 0$. It follows that

 $\limsup_{n\to\infty}\beta_t^n\leq\beta_t.$

Moreover, (i) if $\eta_t^n < t$, then $Q^n(\eta_t^n) = 0$, and (ii) if $\eta_t^n = t$, then $\beta_t^n = t$. Therefore

$$\eta_t^n \leq \beta_t^n$$
 for all t, \bar{P} -a.s.,

and then

$$\eta_t \leq \liminf_{n \to \infty} \eta_t^n \leq \limsup_{n \to \infty} \beta_t^n \leq \beta_t, \quad \text{for all } t, \ \bar{P}\text{-a.s.}$$

The proof is achieved since $\bar{P}(\eta_t = \beta_t) = 1$, and then $\zeta_t = \gamma_t^0(W + \Lambda) = t - \beta_t = t - \eta_t = \gamma_t(\Lambda)$.

Remark 5.6. In the Skorohod space $(\bar{\Omega}, \bar{\mathcal{F}}, \bar{P})$ used in the proof of Proposition 5.5, choose a jointly measurable version of $\xi_t^n = \gamma_t(L^n) = t - \eta_t^n$. Then $M = \{(\omega, t) \in \Omega \times [0, T] \text{ s.t. } \xi_t^n(\omega) \not\to \zeta_t(\omega)\}$ is a zero $d\bar{P} \times dt$ -measure set. Moreover, a similar result holds for $\gamma_t^0(Q^n) = t - \beta_t^n$, namely $M_0 = \{(\omega, t) \in \Omega \times [0, T] \text{ s.t. } \gamma_t^0(Q^n)(\omega) \not\to \zeta_t(\omega)\}$ is a zero $d\bar{P} \times dt$ -measure set.

We are now ready to prove Theorems 5.2 and 5.3.

Proof of Theorem 5.2. The weak convergence for filters of the reflected random walk follows, since we can use the Skorohod representation probability space as in Proposition 5.5, and in this space, for each t > 0, $\bar{P}(\xi_t^n = \gamma_t(L^n) \rightarrow \zeta_t) = 1$ and, on the other hand, $\bar{P}\{\omega : \zeta_t(\omega) > 0\} = 1$, as observed in Remark 5.6. As a consequence, taking into account the key convergence result of Proposition 5.4,

$$\bar{P}(\hat{\Sigma}^n(\xi_t^n;g) \underset{n \to \infty}{\longrightarrow} \hat{\varPi}_{2\lambda,c}(\zeta_t;g), \text{ for every } g: \mathbb{R}^+ \to \mathbb{R} \text{ bounded and continuous}) = 1,$$

and the above property is equivalent to showing that $\hat{\pi}_t^n$ converges weakly to $\hat{\pi}_t$.

The proof of the weak convergence for the filter of the random walk is similar, since the convergence of $\Sigma^n(s_n, l_n; g)$ to $\Pi_{2\lambda,c}(s, l; g)$ whenever (s_n, l_n) converges to (s, l), with s > 0, is just a slight extension of Proposition 5.4, that is, for any $g : \mathbb{R}^+ \to \mathbb{R}$ bounded and uniformly continuous,

$$\Sigma^{n}(s_{n}, l_{n}; g) \underset{n \to \infty}{\longrightarrow} \Pi_{2\lambda, c}(s, l; g).$$

$$\tag{45}$$

Indeed, on the one hand $|\Sigma^n(s_n, l_n; g) - \Sigma^n(s_n, l; g)| \le \omega_g(|l_n - l|)$ and therefore converge to zero, and on the other hand, $\Sigma^n(s_n, l; g) = \hat{\Sigma}^n(s_n; g_l)$ converge to $\Pi(s, l; g) = \hat{\Pi}(s; g_l)$, where $g_l(x) = g(-l + x)$. The set of bounded and uniformly continuous functions is a convergence determining class, and then (45) follows for all bounded continuous functions g. Then, again using the Skorohod representation space, we get that $\bar{P}((\xi_l^n, L_l^n) \to (\zeta_l, \Lambda_l), \zeta_l > 0) = 1$, and

$$P(\Sigma^{n}(\xi_{t}^{n}, L_{t}^{n}; g) \xrightarrow[n \to \infty]{} \Pi_{2\lambda, c}(\zeta_{t}, \Lambda_{t}; g),$$

for every $g : \mathbb{R}^{+} \to \mathbb{R}$ bounded and continuous) = 1

Therefore, π_t^n converge weakly to π_t , and Theorem 5.2 is completely achieved.

Proof of Theorem 5.3. The limit we are looking for depends only on the distribution of ξ_t^n , therefore using the Skorohod representation space $(\bar{\Omega}, \bar{\mathcal{F}}, \bar{P})$, as in the proof of Proposition 5.5, the thesis is equivalent to

$$\int_0^T E^{\bar{P}} |\hat{\Sigma}^n(\xi_t^n;g) - \hat{\Pi}_{2\lambda,c}(\xi_t^n;g)|^p \mathrm{d}t \underset{n \to \infty}{\longrightarrow} 0.$$

As observed in Remark 5.6, we can assume that $\xi_t^n(\omega)$ converge to $\zeta_t(\omega) d\bar{P} \times dt$ -a.e., and then by Proposition 5.4 we get

$$\hat{\Sigma}^{n}(\xi_{t}^{n};g) \underset{n \to \infty}{\longrightarrow} \hat{\Pi}_{2\lambda,c}(\zeta_{t};g) \quad \text{and} \quad \hat{\Pi}_{2\lambda,c}(\xi_{t}^{n};g) \underset{n \to \infty}{\longrightarrow} \hat{\Pi}_{2\lambda,c}(\zeta_{t};g) \tag{46}$$

for each (ω, t) such that $\zeta_t(\omega) > 0$.

The observation that $\{(\omega, t) \in \Omega \times [0, T] \text{ such that } \zeta_t(\omega) = 0\}$ is a zero measure set with respect to $d\overline{P} \times dt$, and an easy application of the dominated convergence theorem, imply that

$$\int_0^T E^{\bar{P}}[|\hat{\Sigma}^n(\xi_t^n;g) - \hat{\Pi}_{2\lambda,c}(\zeta_t;g)|^p] \to 0, \quad \text{for any } p > 0$$

and

$$\int_{0}^{T} E^{\bar{P}}[|\hat{\Sigma}^{n}(\xi_{t}^{n};g) - \hat{H}_{2\lambda,c}(\xi_{t}^{n};g)|^{p}] \to 0, \quad \text{for any } p > 0. \quad \Box$$
(47)

5.2. The key result

In this subsection our aim is to prove Proposition 5.4, i.e. the key result (14) under conditions A1, A2, A3 and C1, C2, C3.

Without loss of generality, we can assume that all the processes involved are defined on the same measurable space (Ω, \mathcal{F}) , but with different probability measures P^n . Moreover, we can assume that: (i) the processes defined in (37) are the same for all *n*, namely we can take $\tilde{X}_t^n = \tilde{X}_t = \tilde{V}_{\tilde{Z}_t}$ and $\tilde{Z}_t^n = \tilde{Z}_t$, with $\tilde{V}_k = \sum_{j=1}^k \tilde{U}_j$; (ii) the measures P^n are all absolutely continuous with respect to a given measure P (see (48) below); and, finally, (iii) under the measure P, the process \tilde{Z}_t is a Poisson process \tilde{Z}_t of intensity 2λ and \tilde{V}_k is a symmetric random walk.

Starting from the processes \tilde{X}_t and \tilde{Z}_t , and in analogy with (38) and (39) of Remark 5.1, we can define the process \tilde{A}_t as the process counting the positive jumps of \tilde{X}_t , and the process \tilde{N}_t as the process counting the negative jumps of \tilde{X}_t .

On (Ω, \mathcal{F}) we consider the filtration $\{\mathcal{F}_t^n, t \in [0, T]\}$ generated by the time-rescaled processes $(\hat{A}_t^n, \hat{N}_t^n) = (\tilde{A}_{nt}, \tilde{N}_{nt})$, and the probability measure P^n , absolutely continuous with respect to P, such that

$$\frac{\mathrm{d}P^{n}}{\mathrm{d}P}\Big|_{\mathcal{F}_{t}^{n}} = \mathcal{L}_{t}^{n} = \left(\frac{\lambda_{n}}{\lambda}\right)^{\hat{A}_{t}^{n}} \exp\{-n(\lambda_{n}-\lambda)t\}\left(\frac{\lambda_{n}}{\lambda}\right)^{\hat{N}_{t}^{n}} \exp\{-n(\mu_{n}-\mu)t\}.$$
(48)

Under the measure P, the processes \hat{A}_t^n , \hat{N}_t^n are mutually independent Poisson processes with intensities $n\lambda$, $n\lambda$, while (see [2], Chapter VIII), under P^n the processes, \hat{A}_t^n , \hat{N}_t^n are mutually independent Poisson processes with intensities $n\lambda_n$, $n\mu_n$. Finally note that, in the probability space $(\Omega, \mathcal{F}, P^n)$, the conditions A1, A2, A3 are satisfied with $\tilde{Z}_t^n = \tilde{Z}_t = \tilde{A}_t + \tilde{N}_t$, $\tilde{U}_i^n = \tilde{U}_j$.

From now to the end of this section, we denote by E^P and E^{P^n} the expectations with respect to the probability measures P and P^n , respectively. Then, by the Kallianpur Striebel formula, we get

$$E^{P^n}[g(X_t^n)/\mathcal{G}_t^n] = \frac{E^P[g(X_t^n)\mathcal{L}_t^n/\mathcal{G}_t^n]}{E^P[\mathcal{L}_t^n/\mathcal{G}_t^n]}.$$
(49)

Moreover, setting $\hat{X}_t^n = \hat{A}_t^n - \hat{N}_t^n$, and $\hat{Z}_t^n = \hat{A}_t^n + \hat{N}_t^n$, the rescaled processes are $X_t^n = \frac{\hat{X}_t^n}{\sqrt{n}}$ and $Z_t^n = \frac{\hat{Z}_t^n - 2n\lambda t}{\sqrt{n}}$, and under the measure *P* the sequence of processes (X_t^n, Z_t^n) converges weakly in $D_{\mathbb{R}^2}([0, \infty))$ to two independent Brownian motions $(W_t, B_t) := (W_t^n - W_t^N, W_t^n + W_t^N)$.

Indeed,

$$X_t^n = \frac{\hat{X}_t^n}{\sqrt{n}} = \frac{\tilde{A}_{nt} - \tilde{N}_{nt}}{\sqrt{n}} = \frac{\tilde{A}_{nt} - n\lambda t}{\sqrt{n}} - \frac{\tilde{N}_{nt} - n\lambda t}{\sqrt{n}} \Rightarrow W_t^A - W_t^N$$
$$Z_t^n = \frac{\hat{Z}_t^n - 2n\lambda t}{\sqrt{n}} = \frac{\tilde{A}_{nt} - n\lambda t}{\sqrt{n}} + \frac{\tilde{N}_{nt} - n\lambda t}{\sqrt{n}} \Rightarrow W_t^A + W_t^N,$$

where W_t^A and W_t^N are clearly independent Brownian motions (the last property implies the independence of W and B). Therefore it is natural to get an alternative expression of \mathcal{L}_t^n in terms of the processes X_t^n and Z_t^n . Taking into account that $\hat{A}_t^n = (\hat{Z}_t^n + \hat{X}_t^n)/2$, $\hat{N}_t^n = (\hat{Z}_t^n - \hat{X}_t^n)/2$, and that

$$\log(\mathcal{L}_t^n) = \log\left(\frac{\lambda_n}{\lambda}\right) \hat{A}_t^n - n(\lambda_n - \lambda)t + \log\left(\frac{\mu_n}{\lambda}\right) \hat{N}_t^n - n(\mu_n - \lambda)t,$$

we get immediately that

$$\log(\mathcal{L}_t^n) = c_n X_t^n + d_n Z_t^n + e_n t,$$
(50)

where

$$c_n = \frac{1}{2}\sqrt{n} \left[\log\left(\frac{\lambda_n}{\lambda}\right) - \log\left(\frac{\mu_n}{\lambda}\right) \right]$$
(51)

$$d_n = \frac{1}{2}\sqrt{n} \left[\log\left(\frac{\lambda_n}{\lambda}\right) + \log\left(\frac{\mu_n}{\lambda}\right) \right]$$
(52)

$$e_n = n \left[\log \left(\frac{\lambda_n}{\lambda} \right) + \log \left(\frac{\mu_n}{\lambda} \right) \right] \lambda - n \left(\lambda_n + \mu_n - 2\lambda \right).$$
(53)

Therefore, (49) can be rewritten as

$$E^{P^n}\left[g(X_t^n)/\mathcal{G}_t^n\right] = \frac{E^P\left[g(X_t^n)\exp(c_nX_t^n)\exp(d_nZ_t^n)/\mathcal{G}_t^n\right]}{E^P\left[\exp(c_nX_t^n)\exp(d_nZ_t^n)/\mathcal{G}_t^n\right]}.$$
(54)

Under conditions C1, C2 and C3, the sequence (c_n, d_n) converges to (\bar{c}, \bar{d}) , where $\bar{c} = c/(2\lambda)$ (see Lemma 5.9 at the end of the section). If we substitute the formal limits in the right hand side of the above expression, we get

$$\frac{E\left[g(W_t)\exp(\bar{c}W_t)\exp(\bar{d}B_t)/\mathcal{F}_t^A\right]}{E\left[\exp(\bar{c}W_t)\exp(\bar{d}B_t)/\mathcal{F}_t^A\right]} = \frac{E\left[g(W_t)\exp(\bar{c}W_t)/\mathcal{F}_t^A\right]}{E\left[\exp(\bar{c}W_t)/\mathcal{F}_t^A\right]} = \hat{H}_{2\lambda,c}(\zeta_t;g), \quad (55)$$

where the first equality holds since $\mathcal{F}_t^A \subset \mathcal{F}_t^W$ and the processes W and B are independent, while the second equality follows by the fact that W_t has drift zero and diffusion coefficient 2λ , by the value of the limit \bar{c} and by again using the Kallianpur–Striebel formula.

The above considerations lead to a heuristic proof of our main result. However, we do not formalize the above heuristic reasoning to get the proof, but we use the following expression for the filter of the queue

$$E^{P^n}\left[g(Q_t^n)/\mathcal{G}_t^n\right] = \left.\frac{E^P\left[g(X_s^n)\exp(c_nX_s^n)\exp(d_nZ_s^n)\mathbb{I}(\sigma_1^n > s)\right]}{E^P\left[\exp(c_nX_s^n)\exp(d_nZ_s^n)\mathbb{I}(\sigma_1^n > s)\right]}\right|_{s=\xi_t^n}.$$
(56)

The above expression can be obtained easily by taking into account (22) and (23), the definition (48) of P^n by means of (50), namely using the notations of Remark 3.1, $E^{P^n}[g(Q_t^n)/\mathcal{G}_t^n] = \hat{\Sigma}_{P^n}^n(\xi_t^n; g)$, and

$$\hat{\Sigma}_{P^n}^n(s;g) = \frac{E^{P^n}\left[g(X_s^n)\mathbb{I}\left(\sigma_1^n > s\right)\right]}{E^{P^n}\left[\mathbb{I}(\sigma_1^n > s)\right]} = \frac{E^P\left[\mathcal{L}_s^n g(X_s^n)\mathbb{I}\left(\sigma_1^n > s\right)\right]}{E^P\left[\mathcal{L}_s^n\mathbb{I}(\sigma_1^n > s)\right]}$$
$$= \frac{E^P\left[g(X_s^n)\exp(c_nX_s^n)\exp(d_nZ_s^n)\mathbb{I}(\sigma_1^n > s)\right]}{E^P\left[\exp(c_nX_s^n)\exp(d_nZ_s^n)\mathbb{I}(\sigma_1^n > s)\right]}.$$
(57)

In order to get the limit of the previous filter, the idea is to show the convergence of the function $\hat{\Sigma}_{pn}^{n}(s; g)$, and then a first essential step consists of evaluating

$$E^{P}\left[f(X_{s}^{n})\exp(d_{n}Z_{s}^{n})\mathbb{I}(\sigma_{1}^{n}>s)\right],$$

either for $f(x) = g_n(x) = g(x) \exp(c_n x)$ or for $f(x) = \exp(c_n x)$, and this can be found in the following lemma, which is based on the reflection principle.

Lemma 5.7. Let f be a function with continuous derivative f'. Then

$$E^{P}\left[f(X_{s}^{n})\exp(d_{n}Z_{s}^{n})\mathbb{I}(\sigma_{1}^{n}>s)\right]$$

= $E^{P}\left[\frac{2}{\sqrt{n}}\mathbb{I}(X_{s}^{n}\geq 2/\sqrt{n})f'(X_{s}^{n}-2\theta_{f}^{n}/\sqrt{n})\exp(d_{n}Z_{s}^{n})\right]$
+ $E^{P}\left[\mathbb{I}(0\leq X_{s}^{n}<2/\sqrt{n})f(X_{s}^{n})\exp(d_{n}Z_{s}^{n})\right],$

where θ_f^n is a random variable with values in (0, 1).

Proof. It is sufficient to prove that

$$E^{P}[f(X_{s}^{n})\exp(d_{n}Z_{s}^{n})\mathbb{I}(\sigma_{1}^{n}>s)] = E^{P}[f(X_{s}^{n})\mathbb{I}(X_{s}^{n}\geq 0)\exp(d_{n}Z_{s}^{n})\mathbb{I}(\sigma_{1}^{n}>s)]$$

$$= E^{P}[\tilde{f}(X_{s}^{n})\exp(d_{n}Z_{s}^{n})] - E^{P}[\tilde{f}(X_{s}^{n})\exp(d_{n}Z_{s}^{n})\mathbb{I}(\sigma_{1}^{n}\leq s)]$$

$$= E^{P}\left[\left\{\tilde{f}(X_{s}^{n}) - \tilde{f}\left(X_{s}^{n} - \frac{2}{\sqrt{n}}\right)\right\}\exp(d_{n}Z_{s}^{n})\right],$$
(58)

where $\tilde{f}(x) = f(x)\mathbb{I}(x \ge 0)$, and where we apply the reflection principle in order to get the last equality. Indeed, if \bar{X}_s^n is the process obtained by reflecting X_s^n at time σ_1^n , i.e. if $\bar{X}_s^n = (\bar{A}_s^n - \bar{N}_s^n)/\sqrt{n}$ where $(\bar{A}_s^n, \bar{N}_s^n)$ is defined as $(\hat{A}_s^n, \hat{N}_s^n)$ for $s < \sigma_1^n$ and as $(\hat{A}_{\sigma_1^n}^n + (\hat{N}_s^n - \hat{N}_{\sigma_1^n}^n), \hat{N}_{\sigma_1^n}^n + (\hat{A}_s^n - \hat{A}_{\sigma_1^n}^n))$ for $s \ge \sigma_1^n$, then, on the one hand,

$$f(X_{s}^{n})\mathbb{I}(X_{s}^{n} \geq 0) \exp(d_{n}Z_{s}^{n})\mathbb{I}(\sigma_{1}^{n} \leq s)$$

= $f(-\bar{X}_{s}^{n} - 2/\sqrt{n})\mathbb{I}(\bar{X}_{s}^{n} \leq -2/\sqrt{n}) \exp(d_{n}Z_{s}^{n})\mathbb{I}(\bar{\sigma}_{1}^{n} \leq s)$
= $f(-\bar{X}_{s}^{n} - 2/\sqrt{n})\mathbb{I}(\bar{X}_{s}^{n} \leq -2/\sqrt{n}) \exp(d_{n}Z_{s}^{n}),$ (59)

since

(i) $\sigma_1^n \leq s$ if and only if $\bar{\sigma}_1^n \leq s$, where $\bar{\sigma}_1^n = \inf\{u \text{ such that } \bar{X}_u^n \leq -1/\sqrt{n}\}$, (ii) if $\bar{\sigma}_1^n \leq s$, then $X_s^n + 1/\sqrt{n} = -1/\sqrt{n} - \bar{X}_s^n$, and therefore, when $\bar{\sigma}_1^n \leq s$, (iii) $X_s^n \geq 0$ if and only if $-2/\sqrt{n} \geq \bar{X}_s^n$, which implies $\bar{\sigma}_1^n \leq s$. On the other hand, $(-\bar{X}_s^n, Z_s^n)$ has the same law as (X_s^n, Z_s^n) under *P*, so that (58) follows by (59). \Box

We are now ready to prove the main result of this subsection.

Proof of Proposition 5.4. We start with the case $s_n = s > 0$. The idea is to prove the following chain of equalities:

$$\lim_{n \to \infty} \Sigma_{P^n}^n(s;g) = \lim_{n \to \infty} \frac{\sqrt{n} E^P \left[g(X_s^n) \exp(c_n X_s^n) \exp(d_n Z_s^n) \mathbb{I}(\sigma_1^n > s) \right]}{\sqrt{n}, E^P \left[\exp(c_n X_s^n) \exp(d_n Z_s^n) \mathbb{I}(\sigma_1^n > s) \right]}$$
$$= \frac{\int_0^\infty g(x) \exp(\bar{c}x) \frac{x}{2\lambda s} \exp\left\{ -\frac{1}{2} \frac{x^2}{2\lambda s} \right\} dx}{\int_0^\infty \exp(\bar{c}x) \frac{x}{2\lambda s} \exp\left\{ -\frac{1}{2} \frac{x^2}{2\lambda s} \right\} dx}$$
$$= \frac{\Pi \left(2\lambda s, 0; g(\cdot) \exp(\frac{c}{2\lambda} \cdot) \right)}{\Pi \left(2\lambda s, 0; \exp(\frac{c}{2\lambda} \cdot) \right)} = \hat{\Pi}_{2\lambda,c}(s;g),$$

where $\bar{c} = \lim_{n} c_n = c/(2\lambda)$. The first equality is immediately obtained by multiplying the numerator and the denominator of (57) by \sqrt{n} . So we need only to prove the second equality, since the others are obvious.

Without loss of generality, we can assume that g has a continuous bounded derivative. Then, by Lemma 5.7, we need to evaluate the limit of

$$\sqrt{n}E^{P}\left[\frac{2}{\sqrt{n}}\mathbb{I}(X_{s}^{n}\geq 2/\sqrt{n})g_{n}'(X_{s}^{n}-2\theta_{g}/\sqrt{n})\exp(d_{n}Z_{s}^{n})\right]$$
(60)

$$+\sqrt{n}E^{P}\left[\mathbb{I}(0\leq X_{s}^{n}<2/\sqrt{n})g_{n}(X_{s}^{n})\exp(d_{n}Z_{s}^{n})\right],\tag{61}$$

when $g_n(x) = g(x) \exp(c_n x)$, for the numerator, and then the limit of the denominator follows taking g(x) = 1. Recalling that (under P) (X_t^n, Z_t^n) converge weakly in $D_{\mathbb{R}^2}([0, \infty))$ to two independent Brownian motions (W_t, B_t) , the limit of (60) is

$$2E\left[\mathbb{I}(0 < W_s < \infty)f'(W_s)\exp(\bar{d}B_s)\right] = 2E\left[\mathbb{I}(0 < W_s < \infty)f'(W_s)\right]E\left[\exp(\bar{d}B_s)\right],$$

with $f(x) = g(x) \exp(\bar{c}x)$. By standard computations, using the formula for integration by parts,

$$E[\mathbb{I}(0 < W_s < \infty) f'(W_s)] = \frac{1}{\sqrt{2\pi}\sqrt{2\lambda s}} \left(-g(0) + \int_0^\infty g(x) \exp\left(\frac{c}{2\lambda}x\right) \frac{x}{2\lambda s} \exp\left\{-\frac{1}{2}\frac{x^2}{2\lambda s}\right\} dx \right).$$

Furthermore, by Lemma 5.8 below, the addend (61) converge to

$$\frac{2}{\sqrt{2\pi}\sqrt{2\lambda s}}g(0)E[\exp(\bar{d}B_s)].$$

Then the result is achieved for any constant sequence $s_n = s$. The case of s_n converging to s > 0 is achieved in a similar way, using the weak convergence of (X_s^n, Z_s^n) to (W_s, B_s) in the uniform norm on bounded intervals, and again by Lemma 5.8. \Box

Lemma 5.8. Let $g : \mathbb{R}^+ \to \mathbb{R}$ be a bounded continuous function, and let

$$q_n(s) := E^P \left[\mathbb{I}(0 \le X_s^n < 2/\sqrt{n})g(X_s^n) \exp(c_n X_s^n) \exp(d_n Z_s^n) \right].$$

Then

$$\lim_{n \to \infty} \sqrt{n} q_n(s_n) = \frac{2}{\sqrt{2\pi}\sqrt{2\lambda s}} g(0) E^P[\exp(\bar{d}B_s)], \tag{62}$$

whenever $s_n \rightarrow s$, with s > 0.

Proof. We start with the symmetric case, i.e. when $\lambda_n = \mu_n = \lambda$, since the proof is technically simpler. Indeed, in this case, $c_n = d_n = 0$, and therefore (62) is achieved by proving that

$$\lim_{n \to \infty} \sqrt{n} P(X_{s_n}^n \in [0, 2/\sqrt{n})) = \frac{2}{\sqrt{2\pi}\sqrt{2\lambda s}}$$

Without loss of generality, we can assume $\lambda = \frac{1}{2}$. Otherwise, we can use the deterministic change of time $t/(2\lambda)$ instead of t and consider the sequence of processes $X_{t/(2\lambda)}^n$, which converges to a standard Brownian motion. Let F_s^n denote the distribution function of X_s^n . Then, as an easy consequence of the Berry–Esseen theorem, we get

$$\sup_{x \in \Gamma_n} \left| F_s^n(x) - \Phi\left(\frac{x}{\sqrt{s}}\right) \right| = o\left(\frac{1}{\sqrt{ns}}\right),\tag{63}$$

where $\Gamma_n = \{\frac{1}{\sqrt{n}} \left(z + \frac{1}{2}\right), z \in \mathbb{Z}\}$, and $\Phi(x)$ is the distribution function of a standard normal random variable. Clearly, $P(X_{s_n}^n \in [0, 2/\sqrt{n}))$ is equal to $P(X_{s_n}^n \in (-\frac{1}{\sqrt{n}}, \frac{3}{2}\frac{1}{\sqrt{n}}])$, and therefore to

$$\Phi\left(\frac{3}{2}\frac{1}{\sqrt{ns_n}}\right) - \Phi\left(-\frac{1}{2}\frac{1}{\sqrt{ns_n}}\right) + o\left(\frac{1}{\sqrt{ns_n}}\right) \simeq \frac{2}{\sqrt{ns_n}}\Phi'(\gamma_n) + o\left(\frac{1}{\sqrt{ns_n}}\right),$$

where $\gamma_n \in \left(-\frac{1}{2}\frac{1}{\sqrt{ns_n}}, \frac{3}{2}\frac{1}{\sqrt{ns_n}}\right)$. Moreover, as $s_n \to s$ and s > 0, there exists \bar{n} such that $s_n \ge \frac{1}{2}s$, for any $n > \bar{n}$, and then $o(\frac{1}{\sqrt{ns_n}}) = o(\frac{1}{\sqrt{n}})$, and we obtain the limit (62) in the symmetric case.

We now switch to the general case. First of all, we observe that

$$q_n(s) = \sum_{h=0}^{\infty} P(\tilde{A}_{ns} = h) P(\tilde{N}_{ns} = h) g(0) e^{c_n 0} e^{d_n \frac{2h - 2n\lambda s}{\sqrt{n}}} + \sum_{h=0}^{\infty} P(\tilde{A}_{ns} = h + 1) P(\tilde{N}_{ns} = h) g(1/\sqrt{n}) e^{c_n \frac{1}{\sqrt{n}}} e^{d_n \frac{2h + 1 - 2n\lambda s}{\sqrt{n}}},$$

and that $\sqrt{n} q_n(s_n)$ has the same behaviour as $g(0) \sqrt{n} \bar{q}_n(s_n)$, where

$$\bar{q}_n(s) \coloneqq \sum_{h=0}^{\infty} P(\tilde{A}_{ns} = h) P(\tilde{N}_{ns} = h) e^{d_n \frac{2h - 2n\lambda s}{\sqrt{n}}} + \sum_{h=0}^{\infty} P(\tilde{A}_{ns} = h + 1) P(\tilde{N}_{ns} = h) e^{d_n \frac{2h + 1 - 2n\lambda s}{\sqrt{n}}},$$

as can be immediately seen from

$$\min(g(0), g(1/\sqrt{n}))\sqrt{n}\bar{q}_n(s) \le \sqrt{n}q_n(s) \le e^{c_n \frac{1}{\sqrt{n}}} \max(g(0), g(1/\sqrt{n}))\sqrt{n}\bar{q}_n(s).$$

Taking into account that $\tilde{Z}_{ns} = \tilde{A}_{ns} + \tilde{N}_{ns}$ is a Poisson random variable of parameter $2\lambda ns$, one can see that

$$P(\tilde{A}_{ns} = h)P(\tilde{N}_{ns} = h) = P(\tilde{Z}_{ns} = 2h)\frac{(2h)!}{h! h!}\frac{1}{2^{2h}}$$

and that

$$P(\tilde{A}_{ns} = h+1)P(\tilde{N}_{ns} = h) = P(\tilde{Z}_{ns} = 2h+1)\frac{(2h+1)!}{(h+1)!\,h!}\frac{1}{2^{2h+1}}.$$

Then, setting

$$r(k) = \frac{k!}{(k - [k/2])! [k/2]!} \frac{1}{2^k},$$

we can rewrite

$$\bar{q}_n(s) = \sum_{k=0}^{\infty} P(\tilde{Z}_{ns} = k) e^{d_n \frac{k-2n\lambda s}{\sqrt{n}}} r(k)$$
$$= E^P \left[r(\tilde{Z}_{ns}) \exp\left(d_n \frac{\tilde{Z}_{ns} - 2n\lambda s}{\sqrt{n}}\right) \right] = E^P \left[r(\tilde{Z}_{ns}) \exp(d_n Z_s^n) \right].$$

Now, from the Stirling formula, $\hat{r}(m) = \sqrt{mr(m)}$ converge to $2/\sqrt{2\pi}$ as *m* increases to infinity, and therefore we rewrite

$$\sqrt{n}\bar{q}_n(s) = \sqrt{n}P(\tilde{Z}_{ns}=0) + E^P \left[\mathbb{I}(\tilde{Z}_{ns}>0)\hat{r}(\tilde{Z}_{ns})\frac{1}{\sqrt{\tilde{Z}_{ns_n}/n}}\exp(d_nZ_s^n) \right].$$

We are interested in the asymptotic behaviour of $\sqrt{n}\bar{q}_n(s_n)$, and first of all we note that the sequence $nP(Z_{s_n}^n = 0)$ converges to zero, as can be seen by direct calculations. Then we observe that, for each T > 0, from the Kolmogorov inequality:

$$P\left(\sup_{s\leq T}\left|\frac{1}{n}\tilde{Z}_{ns}-2\lambda s\right|\geq \varepsilon\right)\leq \frac{\operatorname{Var}(\tilde{Z}_{nT})}{n^{2}\varepsilon^{2}}=\frac{2n\lambda T}{n^{2}\varepsilon^{2}}$$

Furthermore, Z_s^n converge weakly to B_s in $D_{\mathbb{R}}([0,\infty))$ w.r.t. the topology of uniform convergence on bounded intervals, the limit process having continuous paths. Therefore the pair $(\tilde{Z}_{ns}/n, Z_s^n)$ converges in $D_{\mathbb{R}}([0,\infty)) \times D_{\mathbb{R}}([0,\infty))$, each component endowed with the topology of uniform convergence, and then $(\tilde{Z}_{ns}/n, Z_s^n)$ converges in distribution to $(2\lambda s, B_s)$ in the space $D_{\mathbb{R}^2}([0,\infty))$ endowed with the topology of uniform convergence on bounded intervals.

From the Skorohod theorem, we can assume w.l.o.g. that the above pair converges *P*-a.s., and uniformly on bounded intervals. Then,

$$\hat{r}(\tilde{Z}_{ns_n}) \mathbb{I}(\tilde{Z}_{ns_n} > 0) \frac{1}{\sqrt{\tilde{Z}_{ns_n}/n}} \exp(d_n Z_{s_n}^n) \to \frac{2}{\sqrt{2\pi}} \frac{1}{\sqrt{2\lambda s}} \exp(\bar{d}B_s) \qquad P\text{-a.s.}$$
(64)

whenever $s_n \to s$, with s > 0. The above convergence is equivalent to the uniform convergence on bounded and compact intervals of $(0, \infty)$, and its proof is straightforward. We only observe that, if we set $h_n(s) = \sqrt{\tilde{Z}_{ns}/n}$, then, for any T > 0, $h_n(s)$ converge to $h(s) = \sqrt{2\lambda s}$ uniformly in [0, T], and therefore, for any $\underline{h} > 0$, $1/h_n(s)$ converge to 1/h(s) uniformly in the set {*s*, such that $h(s) \ge \underline{h}$ }. The thesis follows, as the sequence on the left-hand side of (64) is uniformly integrable. Indeed

$$\sup_{n} E^{P}[(\sqrt{n} r(\tilde{Z}_{ns_{n}}) \exp(d_{n}Z_{s_{n}}^{n}))^{2}] \leq L < \infty,$$

since $\sup_m \hat{r}(m) = \sqrt{m} r(m) \le L' < \infty$, and

$$E^{P}\left[\mathbb{I}(\tilde{Z}_{ns_{n}} > 0)\frac{n}{\tilde{Z}_{ns_{n}}}\exp(2d_{n}Z_{s_{n}}^{n})\right]$$

= $\exp(-2d_{n}/\sqrt{n})\frac{1}{2\lambda s_{n}}\sum_{k=1}^{\infty}\frac{k+1}{k}\exp\left(2d_{n}\frac{k+1-2\lambda ns}{\sqrt{n}}\right)\frac{(2\lambda ns_{n})^{k+1}}{(k+1)!}e^{-2\lambda ns_{n}}$
 $\leq \exp(-2d_{n}/\sqrt{n})\frac{1}{\lambda s_{n}}E^{P}[\exp(2d_{n}Z_{s_{n}}^{n})].$

We end this section with the statement of the elementary technical lemma, which has been used in the proof of the previous results.

Lemma 5.9. If condition C3 holds, then

$$\lim_{n \to \infty} (c_n, d_n, e_n) = (\bar{c}, \bar{d}, \bar{e}), \tag{65}$$

where c_n , d_n and e_n are defined in (51)–(53), and where

$$\bar{c} = \frac{c}{2\lambda} = \frac{c(1) - c(2)}{2\lambda}, \quad \bar{d} = \frac{d}{2\lambda} = \frac{c(1) + c(2)}{2\lambda}, \quad \bar{e} = -(c^2(1) + c^2(2))/2\lambda.$$

6. The M/M/1 queueing model: Observing the idle time process

In this section we are interested in the conditional law of the M/M/1 queue $\tilde{Q}_t^n = \tilde{X}_t^n + \tilde{L}_t^n$, when the observation process is the *idle time* process, i.e.

$$\tilde{C}_t^n = \int_0^t \mathbb{I}(\tilde{Q}_s^n = 0) \, \mathrm{d}s,$$

the cumulative time the queue has spent in 0, up to t.

Equivalently, one can also consider, as an observation process, the bivariate point process $(\tilde{I}_t^n, \tilde{B}_t^n)$, where \tilde{I}_t^n is the process that counts the times when the system starts an idle period and \tilde{B}_t^n is the process that counts the times when the system starts a busy period, that is

$$\tilde{I}_{t}^{n} = \int_{0}^{t} \mathbb{I}(\tilde{Q}_{s-}^{n} = 1) \,\mathrm{d}\tilde{N}_{s}^{n},\tag{66}$$

$$\tilde{B}_{t}^{n} = \int_{0}^{t} \mathbb{I}(\tilde{Q}_{s-}^{n} = 0) \,\mathrm{d}\tilde{A}_{s}^{n}.$$
(67)

Indeed the filtration generated by the idle time process \tilde{C}_t^n and the filtration generated by the observation process $(\tilde{I}_t^n, \tilde{B}_t^n)$ coincide, or more precisely $\mathcal{F}_{t^+}^{\tilde{C}^n} = \mathcal{F}_t^{\tilde{I}^n, \tilde{B}^n}$.

Our first aim is to study the conditional law

$$E[g(\tilde{Q}_t^n)/\tilde{\mathcal{H}}_t^n],\tag{68}$$

where, for notational convenience, we denote

$$\tilde{\mathcal{H}}_t^n = \mathcal{F}_t^{I^n, B^n} = \mathcal{F}_{t^+}^{\tilde{C}^n},$$

and the explicit expression for the filter (68) in terms of $\gamma_t^0(\tilde{Q}^n)$ is given in (75).

Then we consider the rescaled processes

$$Q_t^n \coloneqq \frac{\tilde{Q}_{nt}^n}{\sqrt{n}}, \qquad I_t^n \coloneqq \frac{\tilde{I}_{nt}^n}{\sqrt{n}}, \qquad B_t^n \coloneqq \frac{\tilde{B}_{nt}^n}{\sqrt{n}}, \qquad C_t^n \coloneqq \sqrt{n}\mu_n \tilde{C}_{nt}^n, \tag{69}$$

and the conditional law of the rescaled queue

$$E[g(Q_t^n)/\mathcal{H}_t^n],\tag{70}$$

where \mathcal{H}_t^n is the filtration generated by the rescaled observation:

$$\mathcal{H}_t^n = \tilde{\mathcal{H}}_{nt}^n = \mathcal{F}_t^{I^n, B^n} = \mathcal{F}_{t^+}^{C^n}.$$
(71)

We are interested in the limit behaviour of the filter (70) under the same assumptions A1, A2, A3 and conditions C1, C2, C3 of Section 5. Under these assumptions, we already know that Q_t^n converge weakly to a Brownian motion W_t with diffusion coefficient 2λ and drift coefficient c. If one defines $\bar{X}_t^n := Q_t^n - C_t^n$, then clearly $Q_t^n = \bar{X}_t^n + C_t^n$, and therefore, since by definition C_t^n increases only when $Q_t^n = 0$, the pair (Q_t^n, C_t^n) is the solution of the Skorohod problem corresponding to \bar{X}_{t}^{n} . Moreover,

$$(\bar{X}_t^n, Q_t^n, C_t^n) \Rightarrow (W_t, W_t + \Lambda_t, \Lambda_t),$$

where, as usual, Λ_t is defined as in (1) (for a deeper investigation of these results, we refer to Kurtz [7]). It is therefore natural to expect that $E[g(Q_t^n)/\mathcal{H}_t^n]$ converges weakly to $E[g(W_t +$ $(\Lambda_t)/\mathcal{F}_t^{\Lambda}] = \hat{\Pi}_{2\lambda,c}(\zeta_t; g)$. This result is proven in Theorem 6.4. Moreover, $\hat{\Pi}_{2\lambda,c}(\gamma_t^0(Q^n); g)$ is a good approximation of the filter for the rescaled model (see Theorem 6.6).

Let $\{\sigma_k^{Bn}, k \in \mathbb{N}\}$ and $\{\sigma_k^{In}, k \in \mathbb{N}\}$ be the jump times of the process \tilde{I}_t^n and the process \tilde{B}_t^n , respectively. Under the assumption $\tilde{Q}_0^n = 0$, it easy to verify that

$$\sigma_k^{Bn} < \sigma_k^{In} < \sigma_{k+1}^{Bn} < \sigma_{k+1}^{In}$$
, for each $k \ge 1$,

and that $Q_t^n = 0$ when $\sigma_k^{In} \le t < \sigma_{k+1}^{Bn}$, for $k \ge 0$, while $Q_t^n > 0$ otherwise. We start by observing some regenerative properties of the above jump times, which are fundamental in the sequel. The first one is due to the strong Markov property for the process \tilde{Q}_t^n , and is given by the following lemma.

Lemma 6.1. For each $k \in \mathbb{N}$, the processes $\tilde{Q}_{k,t}^{In} = \tilde{Q}_{t+\sigma_k^{In}}^n - \tilde{Q}_{\sigma_k^{In}}^n$ and $\tilde{Q}_{k,t}^{Bn} = \tilde{Q}_{t+\sigma_k^{Bn}}^n - \tilde{Q}_{\sigma_k^{Bn}}^n$ are independent of $\mathcal{F}_{\sigma_k^{In}}^{\tilde{Q}^n}$ and $\mathcal{F}_{\sigma_k^{Bn}}^{\tilde{Q}^n}$, respectively. Moreover, the process $\tilde{Q}_{k,t}^{In}$ has the same law as the process \tilde{Q}_t^n .

The process \tilde{I}_t^n is a renewal process, and \tilde{B}_t^n is a delayed renewal process, i.e. the random variables $\sigma_{k+1}^{Bn} - \sigma_k^{Bn}$ are mutually independent for $k \ge 0$ and identically distributed for $k \ge 1$. Also, $\{\sigma_k^{In} - \sigma_k^{Bn}\}_{k \ge 1}$ is a sequence of mutually independent random variables.

In the setting of this section, the above considerations and Lemma 6.1 guarantee that the filter of \tilde{Q}_t^n given $\tilde{\mathcal{H}}_t^n$ admits a representation similar to that given in Proposition 2.1. The proof of the following proposition is left to the reader. However, we point out that, since the processes involved are all Markovian, the proof could be given by the techniques used in [3].

Proposition 6.2. The conditional law of \tilde{Q}_t^n given $\tilde{\mathcal{H}}_t^n$ admits the following representation:

$$E\left[g(\tilde{Q}_{t}^{n})/\tilde{\mathcal{H}}_{t}^{n}\right] = \mathbb{I}(\tilde{Q}_{t}^{n}=0)g(0) + \mathbb{I}(\tilde{Q}_{t}^{n}>0)$$

$$\times \sum_{j=1}^{\infty} \frac{E\left[g(\tilde{Q}_{s+\sigma_{j}^{Bn}}^{n}-\tilde{Q}_{\sigma_{j}^{Bn}}^{n}+1)\mathbb{I}(\sigma_{j}^{In}-\sigma_{j}^{Bn}>s)\right]_{s=t-\sigma_{j}^{Bn}}}{E\left[\mathbb{I}(\sigma_{j}^{In}-\sigma_{j}^{Bn}>s)\right]_{s=t-\sigma_{j}^{Bn}}}\mathbb{I}\{\sigma_{j}^{Bn}\leq t<\sigma_{j}^{In}\}.$$
(72)

It is important to note that

$$\sigma_j^{In} - \sigma_j^{Bn} = \inf\{u \ge 0 : \tilde{Q}_{j,u}^{Bn} + 1 = 0\},\tag{73}$$

and that the process $\tilde{Q}_{j,s}^{Bn} + 1$ for $s < \sigma_j^{In} - \sigma_j^{Bn}$ behaves like the continuous time random walk $\tilde{X}_s^n + 1$ for $s < \tilde{\sigma}_1^n = \inf\{u \ge 0 : \tilde{X}_u^n = -1\}$, and hence

$$\frac{E[g(\tilde{Q}_{j,s}^{Bn}+1)\mathbb{I}(\sigma_{j}^{In}-\sigma_{j}^{Bn}>s)]}{E[\mathbb{I}(\sigma_{j}^{In}-\sigma_{j}^{Bn}>s)]} = \frac{E[g(\tilde{X}_{s}^{n}+1)\mathbb{I}(\tilde{\sigma}_{1}^{n}>s)]}{E[\mathbb{I}(\tilde{\sigma}_{1}^{n}>s)]}.$$
(74)

As a consequence and observing that, by definition (9),

$$\gamma_t^0(\tilde{Q}^n) = t - \sup\{s < t \text{ such that } \tilde{Q}_s^n = 0\} = \sum_{j=1}^\infty (t - \sigma_j^{Bn}) \,\mathbb{I}\{\sigma_j^{Bn} \le t < \sigma_j^{In}\},$$

we can rewrite (72) as

$$E[g(\tilde{Q}_t^n)/\tilde{\mathcal{H}}_t^n] = \mathbb{I}(\tilde{Q}_t^n = 0)g(0) + \mathbb{I}(\tilde{Q}_t^n > 0) \left. \frac{E\left[g(\tilde{X}_s^n + 1)\mathbb{I}(\tilde{\sigma}_1^n > s)\right]}{E\left[\mathbb{I}(\tilde{\sigma}_1^n > s)\right]} \right|_{s = \gamma_t^0(\tilde{Q}^n)}.$$
 (75)

The above considerations leads us to state the following result.

Theorem 6.3. Consider the rescaled process Q_t^n , the rescaled observation processes I_t^n and B_t^n , defined in (69), and the history generated by (I_u^n, B_u^n) for $u \le t$, i.e. \mathcal{H}_t^n defined in (71). Then

$$E[g(\mathcal{Q}_t^n)/\mathcal{H}_t^n] = \mathbb{I}(\mathcal{Q}_t^n = 0)g(0) + \mathbb{I}(\mathcal{Q}_t^n > 0)\bar{\Sigma}^n(\gamma_t^0(\mathcal{Q}^n); g),$$
(76)

where $\bar{\Sigma}^n(s; g) = \hat{\Sigma}^n(s; \overline{g}_n)$, with $\hat{\Sigma}^n(s)$ the probability defined in (23), and $\overline{g}_n(x) = g(x + \frac{1}{\sqrt{n}})$. **Proof.** Equality (75) implies

$$E[g(Q_t^n)/\mathcal{H}_t^n] = \mathbb{I}(Q_t^n = 0)g(0) + \mathbb{I}(Q_t^n > 0) \left. \frac{E\left[g\left(X_s^n + \frac{1}{\sqrt{n}}\right)\mathbb{I}(\sigma_1^n > s)\right]}{E[\mathbb{I}(\sigma_1^n > s)]} \right|_{s = \gamma_t^0(Q^n)}$$

and clearly

$$\frac{E\left[g\left(X_{s}^{n}+\frac{1}{\sqrt{n}}\right)\mathbb{I}\left(\sigma_{1}^{n}>s\right)\right]}{E\left[\mathbb{I}\left(\sigma_{1}^{n}>s\right)\right]}=\hat{\Sigma}^{n}(s;\overline{g}_{n}).\quad \Box$$

As a consequence of the above theorem, the conditional law of Q_t^n given \mathcal{H}_t^n can be written as

$$\mathbb{I}\left(Q_t^n=0\right)\left[\delta_{\{0\}}-\bar{\Sigma}^n(\gamma_t^0(Q^n))\right]+\bar{\Sigma}^n(\gamma_t^0(Q^n)).$$

Moreover, for any g uniformly continuous,

$$\bar{\Sigma}^n(\gamma^0_t(Q^n);g) = \hat{\Sigma}^n(\gamma^0_t(Q^n);g) + \varepsilon(n,g),$$
(77)

with $|\varepsilon(n, g)| \le \omega_g(1/\sqrt{n})$. We are now ready to prove the main result of this section.

Theorem 6.4. Assume conditions C1, C2, C3 and A1, A2, A3. Then, for any $t \ge 0$, the sequence of measure-valued random variables defined by (70) converge weakly to $\hat{\pi}_t$, on the space of probability measures endowed with the topology of weak convergence. In particular, for any bounded and continuous function g,

$$E[g(Q_t^n)/\mathcal{H}_t^n] \Rightarrow E[g(W_t)/\mathcal{F}_t^\Lambda] = \hat{\Pi}_{2\lambda,c}(\zeta_t; g), \quad \text{for any } t \ge 0.$$

Proof. As in the proof of Theorem 5.2, using (77) it is possible to show that, in the Skorohod space of Proposition 5.5,

$$\bar{P}(\bar{\Sigma}^n(\gamma_t^0(Q^n);g) \xrightarrow[n \to \infty]{} \hat{H}_{2\lambda,c}(\zeta_t;g), \text{ for every } g: \mathbb{R}^+ \to \mathbb{R} \text{ bounded and continuous)}$$
$$= 1.$$

since, in that space $\gamma_t^0(Q^n)$, converges to ζ_t almost certainly. On the other hand, the total variation of the measure $\delta_{\{0\}} - \overline{\Sigma}^n(\gamma_t^0(Q^n))$ is at most 2, so the result is achieved once we prove that $\mathbb{I}(Q_t^n = 0)$ converges to zero in probability. Indeed, as recalled in (40), the sequence Q_t^n converges weakly to a reflected Brownian motion $W_t + \Lambda_t$. Then the above convergence can be obtained by noting that the function $\mathbb{I}(x = 0)$ has a discontinuity point at x = 0, $P(W_t + \Lambda_t = 0) = 0$, and that $\mathbb{I}(Q_s^n = 0)$ converges to zero by the continuous mapping theorem. \Box

Remark 6.5. As already observed at the beginning of this section,

$$(X_t^n, Q_t^n, C_t^n) \Rightarrow (W_t, W_t + \Lambda_t, \Lambda_t),$$

where $\bar{X}_t^n := Q_t^n - C_t^n$. Thanks to the continuity of the limit processes, the convergence can be considered in the space $D_{\mathbb{R}^3}[0,\infty)$ endowed with the topology of the uniform convergence on compact sets. Moreover, it is interesting to note that $\gamma_t^0(Q^n) = \gamma_t(C^n) \Rightarrow \gamma_t(\Lambda) = \zeta_t$,

Then, similarly to Proposition 5.5, it is possible to prove that

$$(\gamma_t^0(Q^n), \gamma_t(C^n), C_t^n) \Rightarrow (\gamma_t^0(W_t + \Lambda_t), \gamma_t^0(\Lambda_t), \Lambda_t) = (\zeta_t, \zeta_t, \Lambda_t),$$

and therefore an alternative proof of the previous theorem can be achieved by using these properties.

We end this section by noting that, even in this new situation, it is possible to give the same approximation for the filter as in Theorem 5.3, namely, for $E[g(Q_t^n)/\mathcal{H}_t^n]$, the following result holds.

Theorem 6.6. For all g bounded and continuous and for each T > 0, p > 0,

$$\int_0^T E|E[g(Q_t^n)/\mathcal{H}_t^n] - \hat{H}_{2\lambda,c}(\gamma_t^0(Q^n);g)|^p \mathrm{d}t \underset{n \to \infty}{\longrightarrow} 0.$$

Proof. Note that, by (77),

$$\begin{split} |E[g(Q_t^n)/\mathcal{H}_t^n] &- \hat{\Pi}_{2\lambda,c}(\gamma_t^0(Q^n);g)|^p \\ &= |\mathbb{I}(Q_t^n = 0)g(0) + \mathbb{I}(Q_t^n > 0)\hat{\Sigma}^n(\gamma_t^0(Q^n);g) + \varepsilon(n,g) - \hat{\Pi}_{2\lambda,c}(\gamma_t^0(Q^n);g)|^p \\ &\leq C(p)|\mathbb{I}(Q_t^n = 0)(g(0) + \hat{\Sigma}^n(\gamma_t^0(Q^n);g)) + \varepsilon(n,g)|^p \\ &+ C(p)|\hat{\Sigma}^n(\gamma_t^0(Q^n);g) - \hat{\Pi}_{2\lambda,c}(\gamma_t^0(Q^n);g)|^p, \end{split}$$

where C(p) is a suitable constant. Then

$$\begin{split} E[|E[g(Q_t^n)/\mathcal{H}_t^n] - \hat{H}_{2\lambda,c}(\gamma_t^0(Q^n);g)|^p] \\ &\leq C(p)E[|\mathbb{I}(Q_t^n = 0)2||g||_{\infty} + \varepsilon(n,g)|^p] \\ &+ C(p)E[|\hat{\Sigma}^n(\gamma_t^0(Q^n);g) - \hat{H}_{2\lambda,c}(\gamma_t^0(Q^n);g)|^p]. \end{split}$$

The thesis follows, since both the addends on the right hand side of the previous inequality converge to zero. The first addend converges to zero by the bounded convergence theorem. To prove that the second addend converges to zero, one just has to substitute ξ_t^n with $\gamma_t^0(Q^n)$ in the proof of Theorem 5.3. \Box

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