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COUNTABLE FRAMES FOR BIMODAL LOGICS $S5 \otimes S5$ and $Grz.3 \otimes Grz.3$

Abstract

In this paper we consider bimodal logics $S5 \otimes S5$ and $Grz.3 \otimes Grz.3$. We construct and describe two single countable frames which characterize systems $S5 \otimes S5$ and $Grz.3 \otimes Grz.3$, respectively.

Introduction

Multimodal logics are widely studied. They find substantial applications in computer science, in particular, to the knowledge representation (see e.g. [6]). For a modal logic L , a frame \mathcal{F} is called an L -frame if all theorems of L are true in \mathcal{F} . Let S be a class of L -frames. A modal logic L is *characterized* (or *determined*) by S if S refutes all formulas which are not theorems of L . If $S = \{\mathcal{F}\}$ then we say that L is characterized by the frame \mathcal{F} . Or \mathcal{F} is adequate for L . It is well-known that monomodal system $S5$ is characterized by the class of all finite frames whose relation is an equivalence relation, and also by the infinite countable cluster (see e.g. [1]). The system $Grz.3$ (also known as $S4.3Grz$, $Grz.3$ is equivalent to $S4.3Grz$ see e.g. [3]) is the smallest monomodal logic containing axiom K , Dummett's axiom $\Box(\Box\varphi \rightarrow \psi) \vee \Box(\Box\psi \rightarrow \varphi)$ and Grzegorzczuk's schema $\Box(\Box(\varphi \rightarrow \Box\varphi) \rightarrow \varphi) \rightarrow \varphi$. This system is determined by the class of finite frames whose relation is a linear order, and also by one infinite frame $\langle \omega, \geq \rangle$ (see e.g. Goldblatt [7]). In monomodal logics, the completeness theorem is often formulated for a class of frames. For some modal logics, it is possible to replace the class with a single frame which can be countably

infinite, as in the case of $S5$ and $Grz.3$. For bimodal logics, the problem of existence of one appropriate frame is more complicated. We will consider logics $S5 \otimes S5$ and $Grz.3 \otimes Grz.3$ which are fusions of $S5$ and $S5$ and $Grz.3$ and $Grz.3$, respectively (see [6]). According to transfer theorems from [8], canonicity is preserved under the formation of fusion. The system $S5 \otimes S5$ is canonical, so one could consider canonical frame as a single frame for $S5 \otimes S5$. But canonical frames are not easy to be described and applied. Moreover, usually they are uncountable. The system $Grz.3 \otimes Grz.3$ is not even canonical (see [4]). We construct and describe two countable frames which characterize systems $S5 \otimes S5$ and $Grz.3 \otimes Grz.3$, respectively. These results have practical applications. Both defined frames will allow us to find some of their finite subframes to reject non-theorems of $S5 \otimes S5$ or $Grz.3 \otimes Grz.3$, respectively.

Preliminaries

Let \mathcal{L}_1 and \mathcal{L}_2 be propositional monomodal languages with modal operators \Box_1 and \Box_2 , respectively. Let $\mathcal{L}_{1,2}$ be propositional bimodal language with both operators \Box_1 and \Box_2 . Bimodal logic $L \subset \mathcal{L}_{1,2}$ is called a fusion of $L_1 \subset \mathcal{L}_1$ and $L_2 \subset \mathcal{L}_2$ if L is the smallest system containing $L_1 \cup L_2$. In this case, we write $L_1 \otimes L_2$ instead of L (see [6]). Let \mathbb{N} be the set of positive integers $\{1, 2, \dots\}$.

A Kripke frame for monomodal logic is a pair $\mathcal{F} = \langle W, R \rangle$ where W is a nonempty set and R is a binary relation on W (R is an accessibility relation).

A Kripke frame for a bimodal logic is a triple $\mathcal{F} = \langle W, R_1, R_2 \rangle$ where W is a nonempty set and R_1, R_2 are accessibility relations. $\mathcal{F} = \langle W, R_1, R_2 \rangle$ is *connected* if for every $x, y \in W$ and $x \neq y$ there exists a sequence (x_1, \dots, x_{k-1}) of elements from W such that $xS_1x_1, x_1S_2x_2, \dots, x_{k-2}S_{k-1}x_{k-1}, x_{k-1}S_ky$, where $S_j \in \{R_1, R_2, R_1^{-1}, R_2^{-1}\}$ for $j \in \{1, \dots, k\}$. Let \mathcal{F} be a frame and $\mathcal{F}_1, \dots, \mathcal{F}_n$ pairwise disjoint connected parts of \mathcal{F} . If a formula φ is refuted in \mathcal{F} , then φ is refuted in \mathcal{F}_i for some $i \in \{1, \dots, n\}$. The other parts $\mathcal{F}_1, \dots, \mathcal{F}_{i-1}, \mathcal{F}_{i+1}, \dots, \mathcal{F}_n$ do not interfere with refutation of φ in \mathcal{F}_i . Hence it is enough to consider connected frames only. The relation \models is defined in a standard way (see [6]).

Below we list some axioms and corresponding to them conditions on relations in frames (see for example [1] and [2]).

K_i	$\Box_i(\varphi \rightarrow \psi) \rightarrow (\Box_i\varphi \rightarrow \Box_i\psi)$	no condition
T_i	$\Box_i\varphi \rightarrow \varphi$	$\forall_x xR_ix$ (reflexivity)
4_i	$\Box_i\varphi \rightarrow \Box_i\Box_i\varphi$	$\forall_x \forall_y \forall_z ((xR_iy \wedge yR_iz) \Rightarrow xR_iz)$ (transitivity)
B_i	$\Diamond_i\Box_i\varphi \rightarrow \varphi$	$\forall_x \forall_y (xR_iy \Rightarrow yR_ix)$ (symmetry)
$D1_i$	$\Box_i(\Box_i\varphi \rightarrow \psi) \vee \Box_i(\Box_i\psi \rightarrow \varphi)$	$\forall_x \forall_y \forall_z ((xR_iy \wedge xR_iz) \Rightarrow (yR_iz \vee zR_iy))$
Grz_i	$\Box_i(\Box_i(\varphi \rightarrow \Box_i\varphi) \rightarrow \varphi) \rightarrow \varphi$	There is no infinite chain x_1, x_2, \dots with $x_j R_i x_{j+1}$ and $x_j \neq x_{j+1}$, for all j .

Given two frames $\mathfrak{F} = \langle W, R_1, R_2 \rangle$ and $\mathfrak{B} = \langle V, S_1, S_2 \rangle$, a map f from W onto V is called a p -morphism from \mathfrak{F} to \mathfrak{B} if, for all $x, y \in W$ and $z \in V$, it satisfies the following conditions:

- (i) if xR_iy , then $f(x)S_if(y)$
- (ii) if $f(x)S_iz$, then there is $y \in W$ such that xR_iy and $f(y) = z$

for $i = 1, 2$.

Let f be a p -morphism from \mathfrak{F} to \mathfrak{B} . Then f is called a p -morphism from a model $\mathfrak{M} = \langle \mathfrak{F}, \mathfrak{M} \rangle$ to a model $\mathfrak{N} = \langle \mathfrak{B}, \mathfrak{N} \rangle$ if $x \in \mathfrak{M}(p)$ iff $f(x) \in \mathfrak{N}(p)$ for every propositional variable p and $x \in W$.

It is well-known that for all $\mathcal{L}_{1,2}$ -formulas φ and all $x \in W$, $(\mathfrak{M}, x) \models \varphi$ iff $(\mathfrak{N}, f(x)) \models \varphi$ (see e.g. [6]). It follows that if \mathfrak{B} is a p -morphic image of \mathfrak{F} and $\mathfrak{F} \models \varphi$ then $\mathfrak{B} \models \varphi$ for every $\mathcal{L}_{1,2}$ -formula φ . These definitions and properties also have monomodal counterpart.

Consider two classes \mathcal{C}_1 and \mathcal{C}_2 of frames that are closed under disjoint unions and isomorphic copies. The set $\mathcal{C}_1 \otimes \mathcal{C}_2 = \{ \langle W, R, S \rangle; \langle W, R \rangle \in \mathcal{C}_1, \langle W, S \rangle \in \mathcal{C}_2 \}$ will be called a *fusion* of \mathcal{C}_1 and \mathcal{C}_2 .

It is possible to transfer some theorems from monomodal to bimodal case. The monomodal system $S5$ is characterized by the class of finite frames whose relation is an equivalence relation. We will need the following theorem (see Theorem 4.1 from [6]):

THEOREM 1. *If the modal logics L_1 and L_2 are characterized by classes of frames \mathcal{C}_1 and \mathcal{C}_2 , respectively, and both classes are closed under the formation of disjoint unions and isomorphic copies, then the fusion $L_1 \otimes L_2$ is characterized by $\mathcal{C}_1 \otimes \mathcal{C}_2$.*

Moreover, working with finite frames allows us to consider finite disjoint unions of frames only.

$S5 \otimes S5$ is the smallest bimodal system which contains the axioms $K_i, T_i, 4_i, B_i$ and is closed under the rule of Modus Ponens (MP) $\frac{\varphi \rightarrow \psi, \varphi}{\psi}$

and the rules of Necessitation $(RN_i) \frac{\varphi}{\Box_i \varphi}$, for $i = 1, 2$. $Grz.3 \otimes Grz.3$ is the smallest bimodal system which contains the axioms $K_i, Grz_i, D1_i$ and is closed under the rule of Modus Ponens and the rules of Necessitation, for $i = 1, 2$. Monomodal logic $Grz.3$ is characterized by the class of finite frames whose relation is a linear order. If we close this class under the formation of finite disjoint unions it will still characterize $Grz.3$. From the previous theorem, it immediately follows:

COROLLARY 2.

- (i) The system $S5 \otimes S5$ is characterized by the class of finite frames $\mathfrak{B} = \langle V, S_1, S_2 \rangle$ whose relations are equivalence relations.
(ii) The system $Grz.3 \otimes Grz.3$ is characterized by the class of finite frames $\mathfrak{B} = \langle V, S_1, S_2 \rangle$ whose relations are linear orders, on every S_1 (or S_2) – connected component, which is connected with respect to S_1 (or S_2).

As mentioned before, if a formula φ is refuted in some frame, then φ is refuted in some connected part of this frame. Both classes from the previous corollary are closed under getting connected subframes. Hence, if φ is refuted in some frame from our class, then φ is refuted in some connected frame from our class. Therefore, both classes in the corollary above can be replaced by their subclasses consisting only of connected frames.

Countable frame adequate for $S5 \otimes S5$

Now we will describe the countable frame $\mathfrak{F} = \langle U, R, B \rangle$ which characterizes the system $S5 \otimes S5$. Set $U = \{(a_1, \dots, a_n) \in \mathbb{N}^n; n \in \{2, 3, \dots\}\}$, R and B are binary relations on U defined as follow:

$(a_1, \dots, a_n)R(b_1, \dots, b_m)$ iff

- $n = m = 2$ or
- $2 < m = n$ is even and $a_1 = b_1, \dots, a_{n-2} = b_{n-2}$ or
- $m = n$ is odd and $a_1 = b_1, \dots, a_{n-1} = b_{n-1}$ or
- $k = \min\{n, m\}$ is odd, $|n - m| = 1$ and $a_1 = b_1, \dots, a_{k-1} = b_{k-1}$.

$(a_1, \dots, a_n)B(b_1, \dots, b_m)$ iff

- $m = n$ is even and $a_1 = b_1, \dots, a_{n-1} = b_{n-1}$ or
- $m = n$ is odd and $a_1 = b_1, \dots, a_{n-2} = b_{n-2}$ or
- $k = \min\{n, m\}$ is even, $|n - m| = 1$ and $a_1 = b_1, \dots, a_{k-1} = b_{k-1}$.

One can check that both R and B are equivalence relations and that \mathfrak{F} is connected. By R^0 we denote the R -cluster which consists of all sequences of length 2. By B^{n_1} we denote the B -cluster which consists of all sequences of length 2 and 3 beginning with n_1 . R^{n_1, n_2} denotes the R -cluster which consists of all sequences of length 3 and 4 beginning with n_1, n_2 . Generally, for all $l \in \{1, 3, 5, \dots\}$, B^{n_1, \dots, n_l} denotes the B -cluster containing all sequences of length $l+1$ and $l+2$ beginning with n_1, \dots, n_l . Analogously, for all $l \in \{2, 4, 6, \dots\}$, R^{n_1, \dots, n_l} denotes the R -cluster containing all sequences of length $l+1$ and $l+2$ beginning with n_1, \dots, n_l . Let us note that both sets $R^0 \cap B^{n_1}$ and $R^0 \setminus B^{n_1}$ have infinitely many elements for each $n_1 \in \mathbb{N}$. All sets $R^{n_1, \dots, n_k} \cap B^{n_1, \dots, n_{k-1}}$, $R^{n_1, \dots, n_k} \setminus B^{n_1, \dots, n_{k-1}}$, $B^{n_1, \dots, n_{k+1}} \cap R^{n_1, \dots, n_k}$ and $B^{n_1, \dots, n_{k+1}} \setminus R^{n_1, \dots, n_k}$ are infinite for each $k \in \{2, 4, 6, \dots\}$. In other cases, the defined sets have empty intersection.

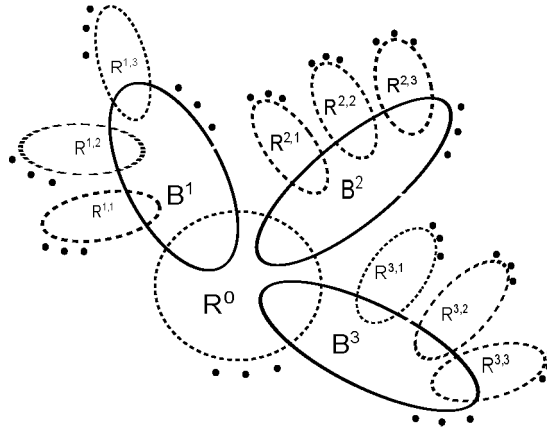
$$R^0 \cap B^{n_1} = \{(n_1, n_2); n_2 \in \mathbb{N}\} \text{ for } n_1 \in \mathbb{N}$$

if l is odd:

$$B^{n_1, \dots, n_l} \cap R^{n_1, \dots, n_l, n_{l+1}} = \{(n_1, \dots, n_{l+2}); n_{l+2} \in \mathbb{N}\} \text{ for } n_1, \dots, n_{l+1} \in \mathbb{N}$$

if l is even:

$$R^{n_1, \dots, n_l} \cap B^{n_1, \dots, n_l, n_{l+1}} = \{(n_1, \dots, n_{l+2}); n_{l+2} \in \mathbb{N}\} \text{ for } n_1, \dots, n_{l+1} \in \mathbb{N}$$



LEMMA 3. \mathfrak{F} is an $S5 \otimes S5$ -frame.

PROOF. Since R (correspond to \square_1) and B (correspond to \square_2) are equivalence relations we have $\mathfrak{F} \models T_i, 4_i, B_i$, for $i = 1, 2$. \square

LEMMA 4. *Every finite connected $S5 \otimes S5$ -frame is a p -morphic image of \mathfrak{F} .*

PROOF. (Sketch) Let $\mathfrak{B} = \langle V, S_1, S_2 \rangle$ be a finite connected $S5 \otimes S5$ -frame. We choose an S_1 -cluster and denote it by S_1^0 . Let $S_2^1, S_2^2, \dots, S_2^{m_0}$ denote all pairwise different S_2 -clusters having nonempty intersections with S_1^0 . m_0 is the number of all those clusters. Next, let $S_1^{k_1,1}, S_1^{k_1,2}, \dots, S_1^{k_1,m_{k_1}}$ denote all pairwise different S_1 -clusters having nonempty intersections with $S_2^{k_1}$ for $k_1 \in \{1, 2, \dots, m_0\}$ where m_{k_1} is the number of all those clusters. Suppose that $S_2^{k_1, \dots, k_l}$ is already defined for some $l \in \{1, 3, 5, \dots\}$ and m_{k_1, \dots, k_l} is the number of all pairwise different S_1 -clusters having nonempty intersections with $S_2^{k_1, \dots, k_l}$. We denote those clusters by $S_1^{k_1, \dots, k_l, 1}, S_1^{k_1, \dots, k_l, 2}, \dots, S_1^{k_1, \dots, k_l, m_{k_1, \dots, k_l}}$. Analogously, if we have $S_1^{k_1, \dots, k_l}$ for some $l \in \{2, 4, 6, \dots\}$, by $S_2^{k_1, \dots, k_l, 1}, S_2^{k_1, \dots, k_l, 2}, \dots, S_2^{k_1, \dots, k_l, m_{k_1, \dots, k_l}}$ we denote all pairwise different S_2 -clusters having nonempty intersections with $S_1^{k_1, \dots, k_l}$. This procedure will not stop in finitely many steps. Hence, every cluster will be named infinitely many times. Now let us denote all elements from V as follows:

$$S_1^0 \cap S_2^{k_1} = \{x_1^{k_1}, x_2^{k_1}, \dots, x_{t_{k_1}}^{k_1}\} \text{ for } k_1 \in \{1, \dots, m_0\}$$

Generally, if l is odd, for $k_1 \in \{1, \dots, m_0\}$ and $k_i \in \{1, \dots, m_{k_1, \dots, k_{i-1}}\}$ we put:

$$S_2^{k_1, \dots, k_l} \cap S_1^{k_1, \dots, k_l, k_{l+1}} = \{x_1^{k_1, \dots, k_{l+1}}, x_2^{k_1, \dots, k_{l+1}}, \dots, x_{t_{k_1, \dots, k_{l+1}}}^{k_1, \dots, k_{l+1}}\}$$

if l is even, for $k_1 \in \{1, \dots, m_0\}$ and $k_i \in \{1, \dots, m_{k_1, \dots, k_{i-1}}\}$ we put:

$$S_1^{k_1, \dots, k_l} \cap S_2^{k_1, \dots, k_l, k_{l+1}} = \{x_1^{k_1, \dots, k_{l+1}}, x_2^{k_1, \dots, k_{l+1}}, \dots, x_{t_{k_1, \dots, k_{l+1}}}^{k_1, \dots, k_{l+1}}\}$$

where $t_{k_1, \dots, k_{l+1}}$ is the number of elements in the intersections above. Every point will be named infinitely many times.

Now let us define a mapping $f : U \rightarrow V$:

$$f((n_1, \dots, n_l)) = x_z^{k_1, \dots, k_{l-1}} \text{ where } k_1 = \min\{n_1, m_0\} \text{ and } k_i = \min\{n_i, m_{k_1, \dots, k_{i-1}}\} \text{ for } i \in \{2, \dots, l-1\}, \text{ and } n_l = z \pmod{t_{k_1, \dots, k_{l-1}}}.$$

For our proof, it is enough to show that f is a p -morphism. Every point from \mathfrak{B} belongs to intersection of two clusters and is named as $x_z^{k_1, \dots, k_{l-1}}$.

It is easy to see that $x_z^{k_1, \dots, k_{l-1}} = f((k_1, \dots, k_{l-1}, z))$. The complete proof is in Appendix I. Let us consider the following three typical cases in the range of f (Pic.1-3):

- Case I (Pic.1) $S_1^{k_1, \dots, k_{l-1}} \cap S_2^{k_1, \dots, k_{l-1}, i} \neq \emptyset \neq S_2^{k_1, \dots, k_{l-1}, i} \setminus S_1^{k_1, \dots, k_{l-1}}$ for $i \in \{1, 2\}$ and there is no more S_2 -clusters which have nonempty intersection with $S_1^{k_1, \dots, k_{l-1}}$. Then:

$$f(R^{k_1, \dots, k_{l-1}} \cap B^{k_1, \dots, k_{l-1}, 1}) = S_1^{k_1, \dots, k_{l-1}} \cap S_2^{k_1, \dots, k_{l-1}, 1}, \text{ and}$$

$$f(R^{k_1, \dots, k_{l-1}} \cap B^{k_1, \dots, k_{l-1}, j}) = S_1^{k_1, \dots, k_{l-1}} \cap S_2^{k_1, \dots, k_{l-1}, 2} \text{ for } j \geq 2.$$

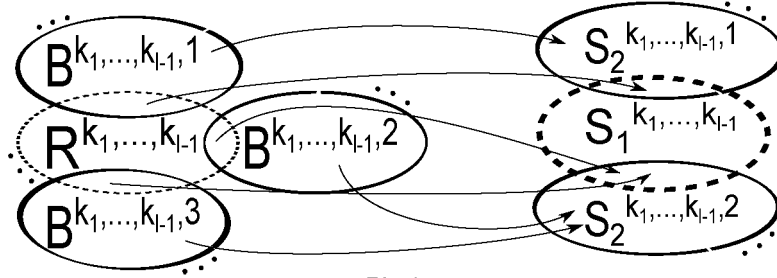
- Case II (Pic.2) $S_1^{k_1, \dots, k_{l-1}} \subsetneq S_2^{k_1, \dots, k_{l-1}, 1}$. Then:

$$f(R^{k_1, \dots, k_{l-1}} \cap B^{k_1, \dots, k_{l-1}, j}) = S_1^{k_1, \dots, k_{l-1}} \text{ for } j \in \mathbb{N}.$$

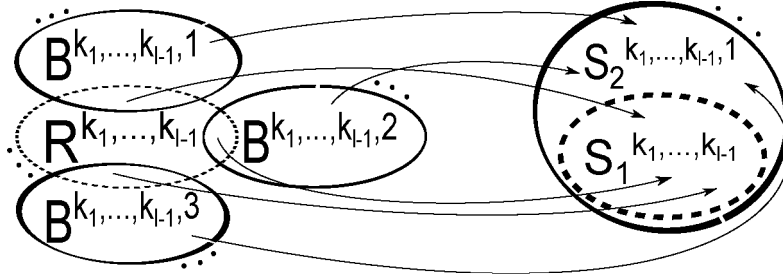
- Case III (Pic.3) $S_2^{k_1, \dots, k_{l-1}, 1} \subsetneq S_1^{k_1, \dots, k_{l-1}}$, $S_1^{k_1, \dots, k_{l-1}} \cap S_2^{k_1, \dots, k_{l-1}, 2} \neq \emptyset$ and there are no more S_2 -clusters which have nonempty intersection with $S_1^{k_1, \dots, k_{l-1}}$. Then:

$$f(R^{k_1, \dots, k_{l-1}} \cap B^{k_1, \dots, k_{l-1}, 1}) = S_2^{k_1, \dots, k_{l-1}, 1}, \text{ and}$$

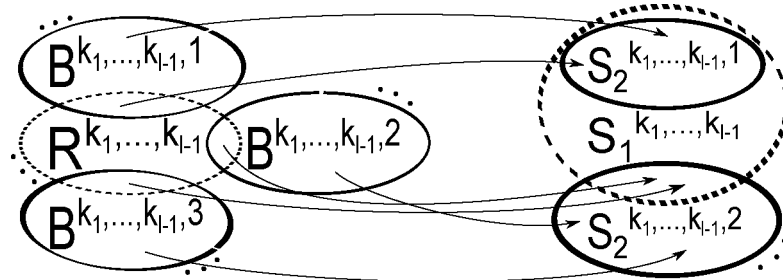
$$f(R^{k_1, \dots, k_{l-1}} \cap B^{k_1, \dots, k_{l-1}, j}) = S_1^{k_1, \dots, k_{l-1}} \cap S_2^{k_1, \dots, k_{l-1}, 2} \text{ for } j \geq 2.$$



Pic.1



Pic.2



Pic.3

□

From Corollary 2, Lemma 3 and Lemma 4 it follows that:

THEOREM 5. $S5 \otimes S5$ is characterized by the frame \mathfrak{F} .

REMARK. In order to refute a formula in \mathfrak{F} , it is enough to consider finite subframes of \mathfrak{F} . This is shown by the following example.

EXAMPLE. To show that $\Box_2(\Box_1(p \rightarrow \Box_2 p) \rightarrow p) \rightarrow (\Diamond_1 \Box_2 p \rightarrow p)$ is not theorem of $S5 \otimes S5$, it is sufficient to find a falsifying valuation v . This will be done at the point $(1, 1)$. To falsify $\Diamond_1 \Box_2 p \rightarrow p$, we need $\not\models_{\langle \mathfrak{F}, v, (1, 1) \rangle} p$ and $\forall x \in B^3 \models_{\langle \mathfrak{F}, v, x \rangle} p$. Putting $\forall x \in B^1 \setminus \{(1, 1)\} \models_{\langle \mathfrak{F}, v, x \rangle} p$ and $\exists x \in B^2 \not\models_{\langle \mathfrak{F}, v, x \rangle} p$, we validate $\Box_2(\Box_1(p \rightarrow \Box_2 p) \rightarrow p)$. Let $\mathfrak{F}' = \langle U', R', B' \rangle$ where $U' = \{(1, 1), (2, 1), (3, 1), (1, 1, 1), (2, 1, 1), (3, 1, 1)\}$, R' and B' are restriction of R and B , respectively. Then \mathfrak{F}' with valuation $v' = v|_{U'}$ is the desired model.

Countable frame adequate for $Grz.3 \otimes Grz.3$

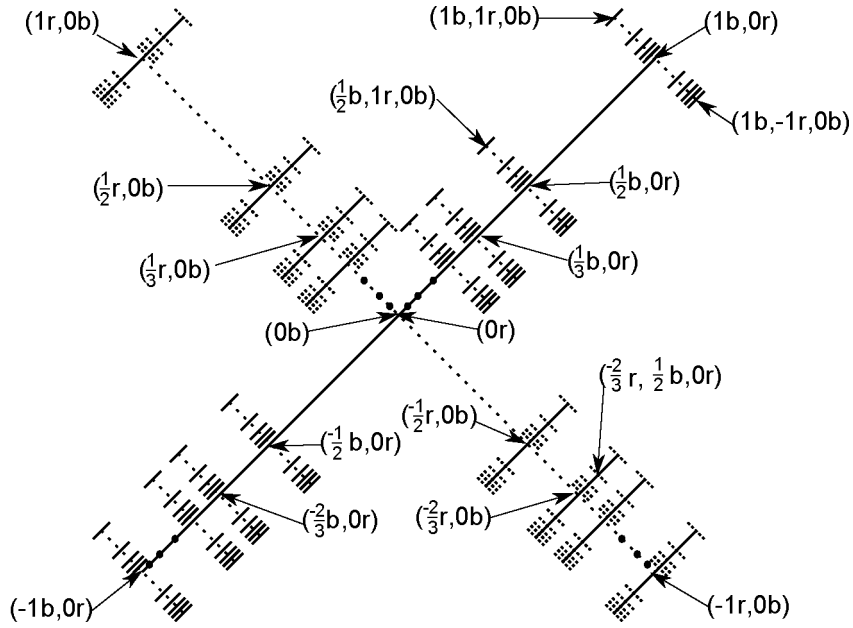
Let $\mathfrak{D} = \langle U, R, B \rangle$ be a frame built of r, b (two distinct constants) and some rational numbers, i.e. $U = \{(p_1 c_1, \dots, p_{n-1} c_{n-1}, 0 c_n); n \in \mathbb{N}, c_k \in \{r, b\}, c_k \neq c_{k+1}, p_k \in \{-\frac{n}{n+1}; n \in \mathbb{N}\} \cup \{\frac{1}{n}; n \in \mathbb{N}\} \cup \{-1\}\}$. $(0r)$ and $(0b)$ are the same element. Both R and B are binary relations on U (see the picture below):

$(p_1 c_1^1, \dots, p_{n-1} c_{n-1}^1, 0 c_n^1) R (q_1 c_1^2, \dots, q_{m-1} c_{m-1}^2, 0 c_m^2)$ iff

- $n = m, c_1^1 = c_1^2, p_s = q_s$ for $s \leq n - 2, c_{n-1}^1 = r, p_{n-1} \leq q_{m-1}$ or
- $n = m - 1, c_1^1 = c_1^2, p_s = q_s$ for $s \leq n - 1, c_n^1 = r, 0 < q_{m-1}$ or
- $n - 1 = m, c_1^1 = c_1^2, p_s = q_s$ for $s \leq n - 2, c_m^2 = r, p_{n-1} < 0$.

$(p_1 c_1^1, \dots, p_{n-1} c_{n-1}^1, 0 c_n^1) B (q_1 c_1^2, \dots, q_{m-1} c_{m-1}^2, 0 c_m^2)$ iff

- $n = m, c_1^1 = c_1^2, p_s = q_s$ for $s \leq n - 2, c_{n-1}^1 = b, p_{n-1} \leq q_{m-1}$ or
- $n = m - 1, c_1^1 = c_1^2, p_s = q_s$ for $s \leq n - 1, c_n^1 = b, 0 < q_{m-1}$ or
- $n - 1 = m, c_1^1 = c_1^2, p_s = q_s$ for $s \leq n - 2, c_m^2 = b, p_{n-1} < 0$.



It is easy to check that every R (or B) – *connected* part of the frame \mathfrak{D} is isomorphic to a frame $\mathfrak{K} = \langle U', \leq \rangle$ where $U' = \{-\frac{n}{n+1}; n \in \mathbb{N}\} \cup \{\frac{1}{n}; n \in \mathbb{N}\} \cup \{-1, 0\}$. The frame \mathfrak{K} is reflexive, transitive and converse weakly well-founded (for every nonempty set $X \subset U'$, there is an maximal element of X). According to [3], $\mathfrak{K} \models Grz$ and so $\mathfrak{D} \models Grz_i$ for $i = 1, 2$. U' is linearly ordered so $\mathfrak{K} \models D1$ and therefore $\mathfrak{D} \models D1_i$ for $i = 1, 2$. Hence:

LEMMA 6. \mathfrak{D} is an $Grz.3 \otimes Grz.3$ -frame.

LEMMA 7. Every finite connected $Grz.3 \otimes Grz.3$ -frame is a p -morphic image of \mathfrak{D} .

PROOF. Before giving a formal proof we present its main idea. Let $\mathfrak{B} = \langle V, R', B' \rangle$ be a finite connected $Grz.3 \otimes Grz.3$ -frame and x an element from V . We name it x_0 . Let z be an element in V such that $x_0 R' z$ and $z R' t$ for no $t \in V$ other than z . We name it $x_{0,1r'}$. Let $x_{0,nr'}$ be the name of an element from $V \setminus \{x_{0,n-1r'}\}$ which is directly before $x_{0,n-1r'}$ (with respect to R') and $x_0 R' x_{0,nr'}$ (it can be x_0). $x_{0,1b'}$ and $x_{0,nb'}$ are defined in the same way, with respect to B' . Let $x_{0,-1r'}$ be another name for element x_0 and $x_{0,-nr'}$ be the name for the element in $V \setminus \{x_{0,-(n-1)r'}\}$ which is the closest to $x_{0,-(n-1)r'}$ (with respect to R') and $x_{0,-nr'} R' x_{0,-(n-1)r'}$. Analogously for $x_{0,-1b'}$ and $x_{0,-nb'}$. Now suppose that we have already defined $x_{0,\pm n_1 c'_1, \dots, \pm n_k c'_k}$ ($c'_i \in \{r', b'\}$ and $c'_i \neq c'_{i+1}$). $x_{0,\pm n_1 c'_1, \dots, \pm (n_k+1) c'_k}$, $x_{0,\pm n_1 c'_1, \dots, \pm n_k c'_k, 1c'_{k+1}}$ and $x_{0,\pm n_1 c'_1, \dots, \pm n_k c'_k, -1c'_{k+1}}$ are defined analogously ($c'_{k+1} \neq c'_k$). For every element x_0 from V we define sets of successors and predecessors with respect to R' and B' :

$$R'_{x_0, \pm n_1 c'_1, \dots, \pm n_k b'}^+ = \{z \in V; x_{0, \pm n_1 c'_1, \dots, \pm n_k b'} R' z\},$$

$$R'_{x_0, \pm n_1 c'_1, \dots, \pm n_k b'}^- = \{z \in V; z R' x_{0, \pm n_1 c'_1, \dots, \pm n_k b'}\},$$

$$B'_{x_0, \pm n_1 c'_1, \dots, \pm n_k r'}^+ = \{z \in V; x_{0, \pm n_1 c'_1, \dots, \pm n_k r'} B' z\} \text{ and}$$

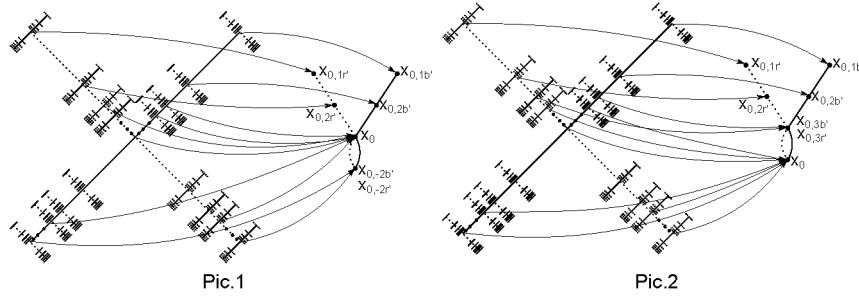
$$B'_{x_0, \pm n_1 c'_1, \dots, \pm n_k r'}^- = \{z \in V; z B' x_{0, \pm n_1 c'_1, \dots, \pm n_k r'}\}.$$

By $m_{x_0, \pm n_1 c'_1, \dots, \pm n_k b'}^{R'+}$, $m_{x_0, \pm n_1 c'_1, \dots, \pm n_k b'}^{R'-}$, $m_{x_0, \pm n_1 c'_1, \dots, \pm n_k r'}^{B'+}$ and $m_{x_0, \pm n_1 c'_1, \dots, \pm n_k r'}^{B'-}$ we denote the number of elements of the sets defined above, respectively.

Now let us define a mapping $f : U \rightarrow V$ such that $f((0c_1)) = x_0$ and $f((p_1c_1, \dots, p_{k+1}c_{k+1}, 0c_{k+2})) = x_{0,o_1c'_1, \dots, o_kc'_k, o_{k+1}c'_{k+1}}$ where $f((p_1c_1, \dots, p_kc_k, 0c_{k+1})) = x_{0,o_1c'_1, \dots, o_kc'_k}$ and:

- a) $o_{k+1} = n_{k+1}$ if $p_{k+1} = \frac{1}{n_{k+1}}$ and $n_{k+1} \leq m_{x_{0,o_1c'_1, \dots, o_kc'_k}}^{C'_{k-1}+}$
- b) $o_{k+1} = m_{x_{0,o_1c'_1, \dots, o_kc'_k}}^{C'_{k-1}+}$ if $p_{k+1} = \frac{1}{n_{k+1}}$ and $n_{k+1} > m_{x_{0,o_1c'_1, \dots, o_kc'_k}}^{C'_{k-1}+}$
- c) $o_{k+1} = -n_{k+1}$ if $p_{k+1} = \frac{-n_{k+1}}{n_{k+1}+1}$ and $n_{k+1} \leq m_{x_{0,o_1c'_1, \dots, o_kc'_k}}^{C'_{k-1}-}$
- d) $o_{k+1} = -m_{x_{0,o_1c'_1, \dots, o_kc'_k}}^{C'_{k-1}-}$ if $p_{k+1} = \frac{-n_{k+1}}{n_{k+1}+1}$ and $n_{k+1} > m_{x_{0,o_1c'_1, \dots, o_kc'_k}}^{C'_{k-1}-}$
- e) $o_{k+1} = -m_{x_{0,o_1c'_1, \dots, o_kc'_k}}^{C'_{k-1}-}$ if $p_{k+1} = -1$

We will show that f is a p-morphism. Let $x_{0,o_1c'_1, \dots, o_kc'_k}$ be an element from V . $x_{0,o_1c'_1, \dots, o_kc'_k} = f((p_1c_1, \dots, p_kc_k, 0c_{k+1}))$ where $p_i = \frac{1}{n_i}$ if $o_i = n_i$ or $p_i = \frac{-n_i}{n_i+1}$ if $o_i = -n_i$. Every R (or B) - connected part of the frame \mathfrak{D} is mapped onto some R' (or B') - connected part of the frame \mathfrak{B} with preserving order. Below we consider two examples that show how to map initial elements of \mathfrak{D} . In Pic.1, $f((0r))$ is not the first element of \mathfrak{B} . In Pic.2, $f((0r))$ is the first element of \mathfrak{B} .



Of course each element has infinitely many names. In the first example (Pic.1) x_0 is named $x_{0,-1b'}$, $x_{0,-1r'}$, $x_{0,3b'}$, $x_{0,3r'}$ among others. In the second example (Pic.2) x_0 is named $x_{0,-1b'}$, $x_{0,-1r'}$, $x_{0,4b'}$, $x_{0,4r'}$ among others. For details check Appendix II. \square

From Corollary 2, Lemma 6 and Lemma 7 it follows that:

THEOREM 8. $Grz.3 \otimes Grz.3$ is characterized by the frame \mathfrak{D} .

REMARK. Let us mention that in order to refute a formula in \mathfrak{D} it is enough to consider finite subframes of \mathfrak{D} .

EXAMPLE. To show that $\Box_1(\Box_2(p \rightarrow \Box_1 p) \rightarrow p) \rightarrow p$ is not a theorem of $Grz.3 \otimes Grz.3$ it is sufficient to find a falsifying valuation v . This will be done at the point $(0r)$. We need to falsify p in the point $(0r)$ ($\not\models_{\langle \mathfrak{D}, v, (0r) \rangle} p$). Putting $\forall n \in \mathbb{N} \Vdash_{\langle \mathfrak{D}, v, (\frac{1}{n}r, 0b) \rangle} p$, $\Vdash_{\langle \mathfrak{D}, v, (\frac{1}{n_0}b, 0r) \rangle} p$ and $\not\models_{\langle \mathfrak{D}, v, (\frac{1}{n_0}b, \frac{1}{m_0}r, 0b) \rangle} p$ for some $n_0, m_0 \in \mathbb{N}$ (let $n_0 = m_0 = 1$), we validate $\Box_1(\Box_2(p \rightarrow \Box_1 p) \rightarrow p)$. Let $\mathfrak{D}' = \langle U', R', B' \rangle$ where $U' = \{(0r), (1b, 0r), (1b, 1r, 0b), (1r, 0b)\}$, R' and B' are restriction of R and B , respectively. Then \mathfrak{D}' with valuation $v' = v|_{U'}$ is the desired model.

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Appendix I (Complete proof of Lemma 4)

Our aim is to prove that mapping:

$f((n_1, \dots, n_l)) = x_z^{k_1, \dots, k_{l-1}}$ where $k_1 = \min\{n_1, m_0\}$ and $k_i = \min\{n_i, m_{k_1, \dots, k_{i-1}}\}$ for $i \in \{2, \dots, l-1\}$, and $n_l = z \pmod{t_{k_1, \dots, k_{l-1}}}$. is a p-morphism.

Let $x_z^{k_1, \dots, k_{l-1}}$ be an element from V . Then $x_z^{k_1, \dots, k_{l-1}} = f((k_1, \dots, k_{l-1}, z))$. To show that the first condition is fulfilled, let $(n_1, \dots, n_p), (h_1, \dots, h_q) \in U$ such that $(n_1, \dots, n_p)R(h_1, \dots, h_q)$.

- Case I ($p = q = 2$)
 $f((n_1, n_2)) \in S_1^0$ and $f((h_1, h_2)) \in S_1^0$. Then $f((n_1, n_2))S_1f((h_1, h_2))$.
- Case II ($2 < p = q$ is even and $n_1 = h_1, \dots, n_{p-2} = h_{p-2}$)
 $f((n_1, \dots, n_{p-2}, n_{p-1}, n_p)) = x_z^{k_1, \dots, k_{p-2}, k_{p-1}}$ where $k_1 = \min\{n_1, m_0\}$ and $k_i = \min\{n_i, m_{k_1, \dots, k_{i-1}}\}$ for $i \in \{2, \dots, p-1\}$ and $n_p = z \pmod{t_{k_1, \dots, k_{p-2}, k_{p-1}}}$
 $f((n_1, \dots, n_{p-2}, h_{p-1}, h_p)) = x_{z'}^{k_1, \dots, k_{p-2}, k'_{p-1}}$ where $k'_{p-1} = \min\{h_{p-1}, m_{k_1, \dots, k_{p-2}}\}$ and $h_p = z' \pmod{t_{k_1, \dots, k_{p-2}, k'_{p-1}}}$.

Both are elements of $S_1^{k_1, \dots, k_{p-2}}$, so

$$f((n_1, \dots, n_{p-2}, n_{p-1}, n_p))S_1f((n_1, \dots, n_{p-2}, h_{p-1}, h_p)).$$

- Case III ($p = q$ is odd and $n_1 = h_1, \dots, n_{p-1} = h_{p-1}$)
 $f((n_1, \dots, n_{p-1}, n_p)) = x_z^{k_1, \dots, k_{p-1}}$ where $k_1 = \min\{n_1, m_0\}$ and $k_i = \min\{n_i, m_{k_1, \dots, k_{i-1}}\}$ for $i \in \{2, \dots, p-1\}$ and $n_p = z \pmod{t_{k_1, \dots, k_{p-1}}}$
 $f((n_1, \dots, n_{p-1}, h_p)) = x_{z'}^{k_1, \dots, k_{p-1}}$ where $h_p = z' \pmod{t_{k_1, \dots, k_{p-1}}}$.

Both are elements of $S_1^{k_1, \dots, k_{p-1}}$, so

$$f((n_1, \dots, n_{p-2}, n_{p-1}, n_p))S_1f((n_1, \dots, n_{p-2}, n_{p-1}, h_p)).$$

- Case IV ($k = \min\{p, q\}$ is odd, $|p - q| = 1$ and $n_1 = h_1, \dots, n_{k-1} = h_{k-1}$)
 Suppose that $k = q$.

$f((n_1, \dots, n_{p-1}, n_p)) = x_z^{k_1, \dots, k_{p-1}}$ where $k_1 = \min\{n_1, m_0\}$ and $k_i = \min\{n_i, m_{k_1, \dots, k_{i-1}}\}$ for $i \in \{2, \dots, p-1\}$ and $n_p = z \pmod{t_{k_1, \dots, k_{p-1}}}$

$f((n_1, \dots, n_{p-2}, h_{p-1})) = x_{z'}^{k_1, \dots, k_{p-2}}$ where $h_{p-1} = z' \pmod{t_{k_1, \dots, k_{p-2}}}$.

Both are elements of $S_1^{k_1, \dots, k_{p-2}}$, so

$f((n_1, \dots, n_{p-2}, n_{p-1}, n_p)) S_1 f((n_1, \dots, n_{p-2}, h_{p-1}))$.

Now suppose $f((n_1, \dots, n_p)) S_1 x_{z_1}^{h_1, \dots, h_l}$ and let $f((n_1, \dots, n_p)) = x_{z_2}^{k_1, \dots, k_{p-1}}$ ($k_1 = \min\{n_1, m_0\}$, $k_i = \min\{n_i, m_{k_1, \dots, k_{i-1}}\}$ and $n_p = z_2 \pmod{t_{k_1, \dots, k_{p-1}}}$).

- Case I (p is odd)

$x_{z_2}^{k_1, \dots, k_{p-1}} \in S_1^{k_1, \dots, k_{p-1}}$ and naturally $x_{z_1}^{h_1, \dots, h_l} \in S_1^{k_1, \dots, k_{p-1}}$. Therefore $x_{z_1}^{h_1, \dots, h_l}$ has another designation which defines its membership to $S_1^{k_1, \dots, k_{p-1}}$. It can be $x_{z_3}^{k_1, \dots, k_{p-1}}$ or $x_{z_4}^{k_1, \dots, k_{p-1}, k_p}$ for some z_3, z_4 and k_p . $x_{z_3}^{k_1, \dots, k_{p-1}} = f((n_1, \dots, n_{p-1}, z_3))$ and of course

$(n_1, \dots, n_p) R(n_1, \dots, n_{p-1}, z_3)$. $x_{z_4}^{k_1, \dots, k_{p-1}, k_p} = f((n_1, \dots, n_{p-1}, k_p, z_4))$ and of course $(n_1, \dots, n_p) R(n_1, \dots, n_{p-1}, k_p, z_4)$.

- Case II (p is even)

$x_{z_2}^{k_1, \dots, k_{p-1}} \in S_1^{k_1, \dots, k_{p-2}}$ and $x_{z_1}^{h_1, \dots, h_l} \in S_1^{k_1, \dots, k_{p-2}}$. Again we use another name for $x_{z_1}^{h_1, \dots, h_l}$ which defines its membership to $S_1^{k_1, \dots, k_{p-2}}$.

It can be $x_{z_3}^{k_1, \dots, k_{p-2}}$ or $x_{z_4}^{k_1, \dots, k_{p-1}}$ for some z_3, z_4 . $x_{z_3}^{k_1, \dots, k_{p-2}} = f((n_1, \dots, n_{p-2}, z_3))$ and $(n_1, \dots, n_p) R(n_1, \dots, n_{p-2}, z_3)$. $x_{z_4}^{k_1, \dots, k_{p-1}} = f((n_1, \dots, n_{p-1}, z_4))$ and $(n_1, \dots, n_p) R(n_1, \dots, n_{p-1}, z_4)$.

Appendix II (Complete proof of Lemma 6)

Let us define the mapping $f : U \rightarrow V$ such that $f((0c_1)) = x_0$ and $f((p_1c_1, \dots, p_{k+1}c_{k+1}, 0c_{k+2})) = x_{0, o_1c'_1, \dots, o_kc'_k, o_{k+1}c'_{k+1}}$ where $f((p_1c_1, \dots, p_kc_k, 0c_{k+1})) = x_{0, o_1c'_1, \dots, o_kc'_k}$ and:

- a) $o_{k+1} = n_{k+1}$ if $p_{k+1} = \frac{1}{n_{k+1}}$ and $n_{k+1} \leq m_{x_0, o_1 c'_1, \dots, o_k c'_k}^{C'_{k-1}+}$
b) $o_{k+1} = m_{x_0, o_1 c'_1, \dots, o_k c'_k}^{C'_{k-1}+}$ if $p_{k+1} = \frac{1}{n_{k+1}}$ and $n_{k+1} > m_{x_0, o_1 c'_1, \dots, o_k c'_k}^{C'_{k-1}+}$
c) $o_{k+1} = -n_{k+1}$ if $p_{k+1} = \frac{-n_{k+1}}{n_{k+1}+1}$ and $n_{k+1} \leq m_{x_0, o_1 c'_1, \dots, o_k c'_k}^{C'_{k-1}-}$
d) $o_{k+1} = -m_{x_0, o_1 c'_1, \dots, o_k c'_k}^{C'_{k-1}-}$ if $p_{k+1} = \frac{-n_{k+1}}{n_{k+1}+1}$ and $n_{k+1} > m_{x_0, o_1 c'_1, \dots, o_k c'_k}^{C'_{k-1}-}$
e) $o_{k+1} = -m_{x_0, o_1 c'_1, \dots, o_k c'_k}^{C'_{k-1}-}$ if $p_{k+1} = -1$

We will show that f is a p-morphism. Let $x_{0, o_1 c'_1, \dots, o_k c'_k}$ be an element from V . $x_{0, o_1 c'_1, \dots, o_k c'_k} = f((p_1 c_1, \dots, p_k c_k, 0c_{k+1}))$ where $p_i = \frac{1}{n_i}$ if $o_i = n_i$ or $p_i = \frac{-n_i}{n_i+1}$ if $o_i = -n_i$. Now let us take $(p_1 c_1^1, \dots, p_k c_k^1, 0c_{k+1}^1) \in U$ such that $(q_1 c_1^2, \dots, q_l c_l^2, 0c_{l+1}^2) \in U$ such that $(p_1 c_1^1, \dots, p_k c_k^1, 0c_{k+1}^1) R (q_1 c_1^2, \dots, q_l c_l^2, 0c_{l+1}^2)$.

- Case I ($k = l$, $c_1^1 = c_1^2$ ($c_k^1 = c_k^2$), $p_s = q_s$ for $s \in \{1, \dots, k-1\}$, $c_k^1 = r$, $p_k \leq q_k$)
 $f((p_1 c_1^1, \dots, p_k r, 0b)) = x_{0, o_1 c'_1, \dots, o_k r'}$
 $f((q_1 c_1^2, \dots, q_k r, 0b)) = f((p_1 c_1^1, \dots, p_{k-1} b, q_k r, 0b)) =$
 $x_{0, o_1 c'_1, \dots, o_{k-1} b', o'_k r'}$. It is easy to see that $o_k \leq o'_k$ (because $p_k \leq q_k$).
 $f((p_1 c_1^1, \dots, p_k c_k^1, 0c_{k+1}^1)) R' f((q_1 c_1^2, \dots, q_k c_k^2, 0c_{k+1}^2))$.
- Case II ($k = l - 1$, $c_1^1 = c_1^2$ ($c_k^1 = c_k^2$), $p_s = q_s$ for $s \in \{1, \dots, k\}$, $c_{k+1}^1 = r$, $0 < q_l$)
 $f((p_1 c_1^1, \dots, p_{l-1} b, 0r)) = x_{0, o_1 c'_1, \dots, o_{l-1} b'}$
 $f((q_1 c_1^2, \dots, q_{l-1} b, q_l r, 0b)) = f((p_1 c_1^1, \dots, p_{l-1} b, q_l r, 0b)) =$
 $x_{0, o_1 c'_1, \dots, o_{l-1} b', o'_l r'}$. It is easy to see that $0 < o'_l$ (because $0 < q_l$).
 $f((p_1 c_1^1, \dots, p_{l-1} b, 0r)) R' f((q_1 c_1^2, \dots, q_l r, 0b))$.
- Case III ($k-1 = l$, $c_1^1 = c_1^2$ ($c_k^1 = c_k^2$), $p_s = q_s$ for $s \in \{1, \dots, k-1\}$, $c_k^1 = r$, $p_k < 0$)
 $f((p_1 c_1^1, \dots, p_{k-1} b, p_k r, 0b)) = x_{0, o_1 c'_1, \dots, o_{k-1} b', o_k r'}$ and $o_k < 0$.
 $f((q_1 c_1^2, \dots, q_{k-1} b, 0r)) = f((p_1 c_1^1, \dots, p_{k-1} b, 0r)) = x_{0, o_1 c'_1, \dots, o_{k-1} b'}$
 $f((p_1 c_1^1, \dots, p_{k-1} c_{k-1}^1, p_k c_k^1, 0c_{k+1}^1)) R' f((q_1 c_1^2, \dots, q_{k-1} c_{k-1}^2, 0c_k^2))$.

Now suppose $f((p_1c_1, \dots, p_kc_k, 0c_{k+1}))R'z$ for some $z \in V$ and let $f((p_1c_1, \dots, p_kc_k, 0c_{k+1})) = x_{0,o_1c'_1, \dots, o_kc'_k}$.

- Case I ($c'_k = r'$)
 - a) $z = x_{0,o_1c'_1, \dots, o_{k-1}b', o'_k r'}$ for some $o_k \leq o'_k$.
 $z = f((p_1c_1, \dots, p_{k-1}b, p'_k r, 0b))$ for some $p_k \leq p'_k$.
 $(p_1c_1, \dots, p_kc_k, 0c_{k+1})R(p_1c_1, \dots, p_{k-1}b, p'_k r, 0b)$.
 - b) $o_k < 0$ ($p_k < 0$) and $z = x_{0,o_1c'_1, \dots, o_{k-2}r', o_{k-1}b'}$.
 $z = f((p_1c_1, \dots, p_{k-2}r, p_{k-1}b, 0r))$.
 $(p_1c_1, \dots, p_kc_k, 0c_{k+1})R(p_1c_1, \dots, p_{k-2}r, p_{k-1}b, 0r)$.
- Case II ($c'_k = b'$)
 - $z = x_{0,o_1c'_1, \dots, o_k b', o_{k+1}r'}$ for some $o_{k+1} > 0$.
 $z = f((p_1c_1, \dots, p_{k-1}r, p_k b, \frac{1}{o_{k+1}}r, 0b))$.
 $(p_1c_1, \dots, p_kc_k, 0c_{k+1})R(p_1c_1, \dots, p_{k-1}r, p_k b, \frac{1}{o_{k+1}}r, 0b)$.