

# 1 Review of current status, requirements and 2 opportunities for building performance simulation of 3 adaptive facades

4 Roel C.G.M. Loonen<sup>A#</sup>, Fabio Favoino<sup>B#</sup>, Jan L.M. Hensen<sup>A</sup>, Mauro  
5 Overend<sup>B</sup>.

6 <sup>A</sup> Building Physics and Services, Eindhoven University of Technology, Postbus 513  
7 5600 MB, Eindhoven, the Netherlands.

8 <sup>B</sup> Glass and Façade Technology research group, University of Cambridge, Trumpington Street,  
9 CB2 1PZ, Cambridge, UK.

10 <sup>#</sup> These authors contributed equally to this work

11

## 12 **Abstract**

13 Adaptive building envelope systems have the potential of reducing greenhouse gas emissions  
14 and improving the energy flexibility of buildings, while maintaining high levels of indoor  
15 environmental quality. The development of such innovative materials and technologies, as well  
16 as their real-world implementation, can be enhanced with the use of building performance  
17 simulation. Performance prediction of adaptive facades can, however, be a challenging task and  
18 the information on this topic is scarce and fragmented. The main contribution of this review  
19 article is to bring together and analyze the existing information in this field. In the first part, the  
20 unique requirements for successful modeling and simulation of adaptive facades are discussed.  
21 In the second part, the capabilities of five widely-used building performance simulation tools are  
22 reviewed, in terms of their ability to model energy and occupant comfort performance of  
23 adaptive facades. Finally, it discusses various ongoing trends and research needs in this field.

24 **Keywords:** building performance simulation, software review, adaptive building envelope,  
25 responsive building elements, control strategies.

## 26 **1 Introduction**

27 To meet the sustainability targets that are set for the building sector, there is a need for  
28 continuing development of new building concepts, technologies and materials that can further  
29 improve the energy efficiency of buildings, while simultaneously enhancing the indoor  
30 environmental comfort of building occupants. The building envelope, or building facade, plays a  
31 key role in this process. In particular, the technologies that are able to, actively and selectively,  
32 manage the energy and mass transfer between the building and its external environment are  
33 considered to be of crucial relevance (IEA 2013, Perino and Serra 2015). These so-called adaptive  
34 building envelopes have the ability to (i) significantly reduce the energy use of buildings (Perino  
35 2008), while (ii) improving the level of indoor environmental quality (Luble 2015), and (iii) having  
36 a positive impact on the match between on-site harvested renewable energy and building energy  
37 use (Reynders, Nuytten, and Saelens 2013).

38 The unique feature of adaptive building envelopes is the capability to adjust their thermo-optical  
39 properties in a reversible way to transient boundary conditions (either external, such as climate,  
40 or internal, such as occupants' requirements), in order to respond to changing priorities (i.e.  
41 minimizing the building energy use, maximizing the use of natural light, etc.). A state-of-the-art  
42 overview of various adaptive building envelope systems and components is presented in Loonen  
43 et al. (2013). Among the wide range of technology options, switchable glazing (Baetens, Jelle, and  
44 Gustavsen 2010), movable solar shading (Nielsen, Svendsen, and Jensen 2011), wall-integrated  
45 phase change materials (Kuznik et al. 2011), dynamic insulation (Kimber, Clark, and Schaefer  
46 2014), and multifunctional facades (Favoino et al. 2014) are identified as the most promising  
47 adaptive building envelope systems. However, studies show that there is ample scope for further  
48 improvements (Favoino, Overend, and Jin 2015; Loonen et al. 2013).

49 Successful design of adaptive facades is a challenging task. In fact, they present a large technical  
50 potential, as demonstrated in scientific publications and testing reports, but low real-world  
51 uptake. This is partly due to a lack of thorough understanding of the benefits and possible risks,  
52 and the inability to measure them in a reliable way.

53 Adaptive building envelopes are complex systems that typically influence multiple physical  
54 domains simultaneously (e.g. thermal, luminous, air quality, etc.). Unlike most HVAC-dominated  
55 buildings, the performance of buildings with adaptive facades is to a very large extent  
56 determined by local climatic conditions and interactions with occupants and the other building  
57 systems. Traditional characterisation methods for building envelopes, such as *U-value* and *g-*  
58 *value*, are based on static assumptions. Therefore, due to the intrinsic time-varying behavior of  
59 adaptive facades, these conventional metrics provide limited and potentially misleading  
60 information for these inherently dynamic systems. As will be discussed in the paragraphs that  
61 follow, a more accurate and credible evaluation would instead determine their performance in  
62 terms of more comprehensive, whole-building performance indicators, such as total primary  
63 energy use and/or indoor environmental quality metrics.

64 Building performance simulation (BPS) has the potential to provide this type of information to  
65 several stakeholders, including building designers, material scientists, sustainable building  
66 consultants, control engineers and building services professionals (Clarke and Hensen 2015). The  
67 potential of the integration of modeling and simulation activities for performance analysis of  
68 adaptive facades can be illustrated in a number of different possible uses in the design and  
69 operation of buildings:

- 70 • Informed decision-making to support the design process of buildings with specific  
71 adaptive building envelope components, in particular when an optimal performance is  
72 required across occupant comfort, economic and environmental aspects;
- 73 • Prediction of energy saving potential compared to a baseline design as part of green  
74 building certification schemes such as LEED and BREEAM;
- 75 • Virtual rapid prototyping to evaluate different future-oriented systems/materials and  
76 identifying promising alternatives for further refinement and product development;
- 77 • Exploration of high-potential control strategies that maximise the performance of  
78 adaptive building envelopes during operation;
- 79 • HVAC system sizing and fine-tuning of the interaction between adaptive building  
80 envelope and other building services;

- 81       • Virtual testing of the robustness of adaptive facade systems with respect to occupant  
82       behavior and variable weather influences.

83 For these reasons, modeling and simulation can bring insights into the mutual influence between  
84 design and performance aspects of adaptive building envelopes, and can therefore strongly  
85 contribute to their spread into the building construction market, as well as to the development  
86 of innovative technologies. However, as we will demonstrate in this article, simulation of  
87 adaptive facades can be significantly more complex than performance prediction of  
88 conventional, static facades, because existing simulation tools were not originally developed for  
89 this purpose. Designers, engineers and researchers who plan to use BPS for analyzing adaptive  
90 facades are faced with a number of challenges and should develop their simulation strategy  
91 accordingly. The currently available information about modeling approaches and issues  
92 regarding simulation of adaptive facades is fragmented. Simulation users therefore have limited  
93 guidance when it comes to factors such as software selection, availability of models for specific  
94 adaptive technologies, best-practice examples and important points of attention (such as  
95 modelling assumptions and strategies).

96 This paper intends to provide researchers and designers, who are approaching the simulation of  
97 adaptive building envelope systems, with a critical overview of existing information, in order to  
98 enable them to choose the most suitable tool/method according to their needs and resources.  
99 This work was partly conducted in the Framework of European COST Action TU1403 – Adaptive  
100 Facades Network, within the Task group on building performance simulation of adaptive facades  
101 ([www.adaptivefacade.eu](http://www.adaptivefacade.eu)). The main aim of this Task group and of the work reported in this  
102 article is threefold: (i) to describe the current capabilities of BPS tools, (ii) to describe their  
103 current limitations and (iii) to specify the requirements of novel simulation strategies suitable for  
104 adaptive building envelope systems. In section 2, the general requirements and main challenges  
105 related to whole building energy simulation of adaptive building envelope systems are described.  
106 Following, section 3 analyzes the opportunities and limitations of state-of-the-art simulation  
107 software at modelling adaptive building facades, based on their underlying assumptions and  
108 modeling methods. In section 4, we provide a detailed overview of the capabilities to model

109 adaptive facades in five of the most widely-used building performance simulation tools,  
110 including an overview of simplified simulation strategies and workarounds. Finally, section 5  
111 concludes the paper by presenting ongoing trends and research needs that are expected to  
112 move modeling and simulation of adaptive building envelopes forward in the coming years.

## 113 **2 Challenges for performance prediction of adaptive building envelopes**

114 Modeling and simulation of adaptive building envelopes has to accurately represent a sequence  
115 of time-varying building envelope system states (or properties), instead of a static  
116 representation of the building enclosure. Moreover, for effective performance prediction of  
117 adaptive building envelope systems, it is essential to simultaneously consider multiple levels, in  
118 terms of (i) spatial scales, (ii) time resolutions, and (iii) physical domains. Compared to  
119 simulation-based analysis of conventional, static facades, two major additional requirements for  
120 performance prediction of adaptive systems are identified:

121 **Modeling time-varying facade properties:** facade specifications (i.e. material properties or  
122 position of components) need to be changeable during simulation run-time to properly account  
123 for transient heat transfer and energy storage effects in building constructions (Loonen, Hoes,  
124 and Hensen 2014). Many state-of-the-art BPS tools have restricted functionalities for  
125 accomplishing this feature. These limitations, but also the various opportunities are further  
126 discussed in Section 4, together with some simplified simulation approaches used to overcome  
127 specific software constraints;

128 **Modeling the dynamic operation of facade adaptation:** the dynamic interactions in adaptive  
129 building envelope systems give rise to a strong mutual dependence between design and control  
130 aspects (Loonen et al. 2013). The performance of adaptive systems fully depends on the  
131 scheduling strategy (i.e. control logic) for facade adaptation during operation. Moloney (2011)  
132 describes it as: “The design outcome in a project with kinetic facades is a *process*, rather than a  
133 static object or artifact”. Thus, to identify the characteristics of high-performance adaptive  
134 building envelope systems, it requires not only design considerations (i.e. facade system design  
135 parameters), but also insights into adequate automated and occupant-driven operation

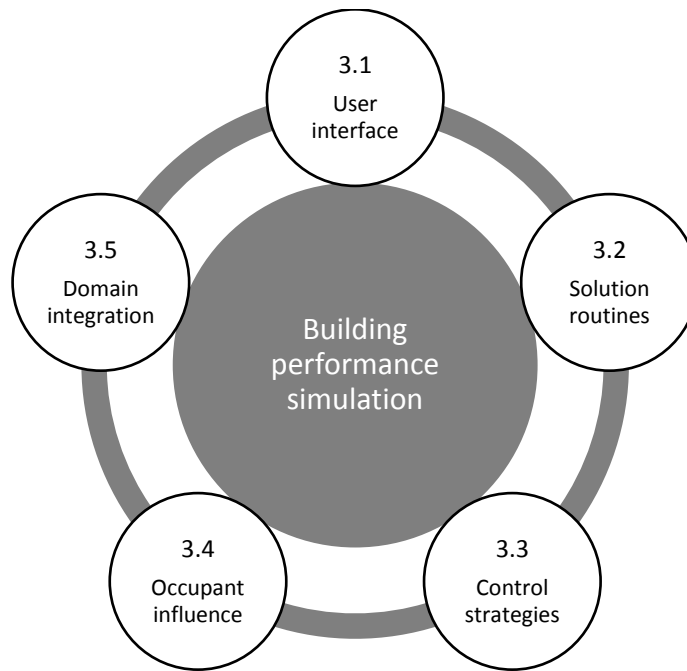
136 strategies of the dynamic facade. Moreover, effective design and operation of a dynamic facade  
137 system depends also on the integration with operations of the other building services. For  
138 example, limited lighting energy savings could be achieved if the operation of dynamic solar  
139 shading is not integrated with a lighting dimming system. Similarly, the integration with heating,  
140 ventilation and air-conditioning (HVAC), and renewable energy systems needs to be carefully  
141 considered. To explore such synergetic effects, it is important to take this integration into  
142 account in the simulation strategy.

### 143 **3 Requirements and limitations of current BPS software**

144 A large number of software tools are available for predicting the energy and comfort  
145 performance of buildings<sup>1</sup>. Each program has unique features in terms of modeling resolution,  
146 solution algorithms, intended target audience, modeling options, ease-of-use vs. flexibility, etc.  
147 The simulation tools with most powerful modeling capabilities, and which have undergone most  
148 rigorous validation studies (e.g. EnergyPlus, ESP-r, IDA ICE, IES VE, TRNSYS), are all legacy  
149 software programs (Crawley et al. 2008). Although these tools have active development  
150 communities, and receive regular updates and extension of modeling capabilities, their  
151 underlying concepts and basic software architecture do not change. Most tools stem from a time  
152 when adaptability of building components was not a primary consideration (Ayres and Stamper  
153 1995; Oh and Haberl 2015). Consequently, the building shape and material properties are usually  
154 not changeable during simulation run-time in these tools, which restricts the options for  
155 modelling adaptive building envelope systems. The requirements and limitations of existing BPS  
156 tools can be grouped into five aspects as shown in Figure 1, based on their characteristics and  
157 underlying assumptions.

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<sup>1</sup> The database of building energy analysis software maintained by the U.S. Department of Energy currently consists of 453 different tools (US DOE 2015b)



158

159 *Figure 1. Different modeling aspects playing a role in performance evaluation of adaptive building envelope systems.*

160 **3.1 User interface**

161 All modern BPS tools possess a graphical user interface (GUI) as a front-end for communication  
 162 with simulation users. In these programs, the input for constructions and material properties is  
 163 normally given in the form of scalar values. These parameters are either directly entered by the  
 164 user, or imported from pre-configured databases. The same static representation is  
 165 implemented for the size, geometry and orientation of the various surfaces that together form  
 166 the building envelope. In the most common approach, this information is then processed once,  
 167 prior to the actual simulation run, and is not updated further during the simulation. Users of the  
 168 simulation tools have limited flexibility to extend the functionality for modelling adaptive  
 169 building envelopes through the non-modifiable user interface and the restricted access to the  
 170 source code of (proprietary) simulation tools. This is especially the case in the simulation tools  
 171 that are geared towards the needs of architects (Attia et al. 2012) .

172 Some exceptions to this rule also exist, in which two types of modeling features can be  
 173 distinguished: (i) application-oriented and (ii) general-purpose features (Table 1). *Application-*  
 174 *oriented* indicates that the modeling capability was implemented in the software with a specific  
 175 adaptive building envelope technology in mind and is labeled in the software as such. The



176 adaptive mechanism and how it is triggered are therefore already embedded in the specific  
 177 model, and users can activate it easily by means of the GUI, but are limited to the presets  
 178 available. The *general-purpose* features, on the other hand, are not restricted to a specific  
 179 technology, but offer flexibility for user-defined combinations of adaptive thermo-physical  
 180 property variations and/or triggering mechanisms. This higher abstraction level affords more  
 181 freedom for exploring innovative adaptive building envelope systems, although it requires the  
 182 BPS user to define and code the control mechanism that triggers adaptation in the building  
 183 element.

184 *Table 1. GUI modelling capabilities for adaptive building envelope technologies, pros (+) and cons (-).*

<b>Modelling capability</b>	<b>Features</b>
Application-oriented	(+) Easy to use, robust (-) Restricted flexibility, limited number of options
General-purpose	(+) Offers more flexibility (-) Requires a high level of expertise and more input data from the BPS user

185

### 186 3.2 Solution routines for transient heat conduction through building elements

187 Many of the widely-used BPS tools adopt response factor techniques (e.g. Thermal Response  
 188 Factors [TRF] or Conduction Transfer Functions [CTF]) to solve the differential equations  
 189 governing the heat transfer phenomena through opaque building elements (Spitler 2011). These  
 190 methods are optimised for computational efficiency, but by virtue of their design, they can only  
 191 work with time-invariant thermo-physical properties (i.e. density, specific heat capacity, thermal  
 192 conductivity) (Clarke 2001). This is because the coefficients that are used in the equations are  
 193 constant and determined only once for each building envelope element at the beginning of the  
 194 simulation. As such, response factor methods do not permit variations in thermo-physical  
 195 material properties during simulation run-time (Delcroix et al. 2012; Pedersen 2007).

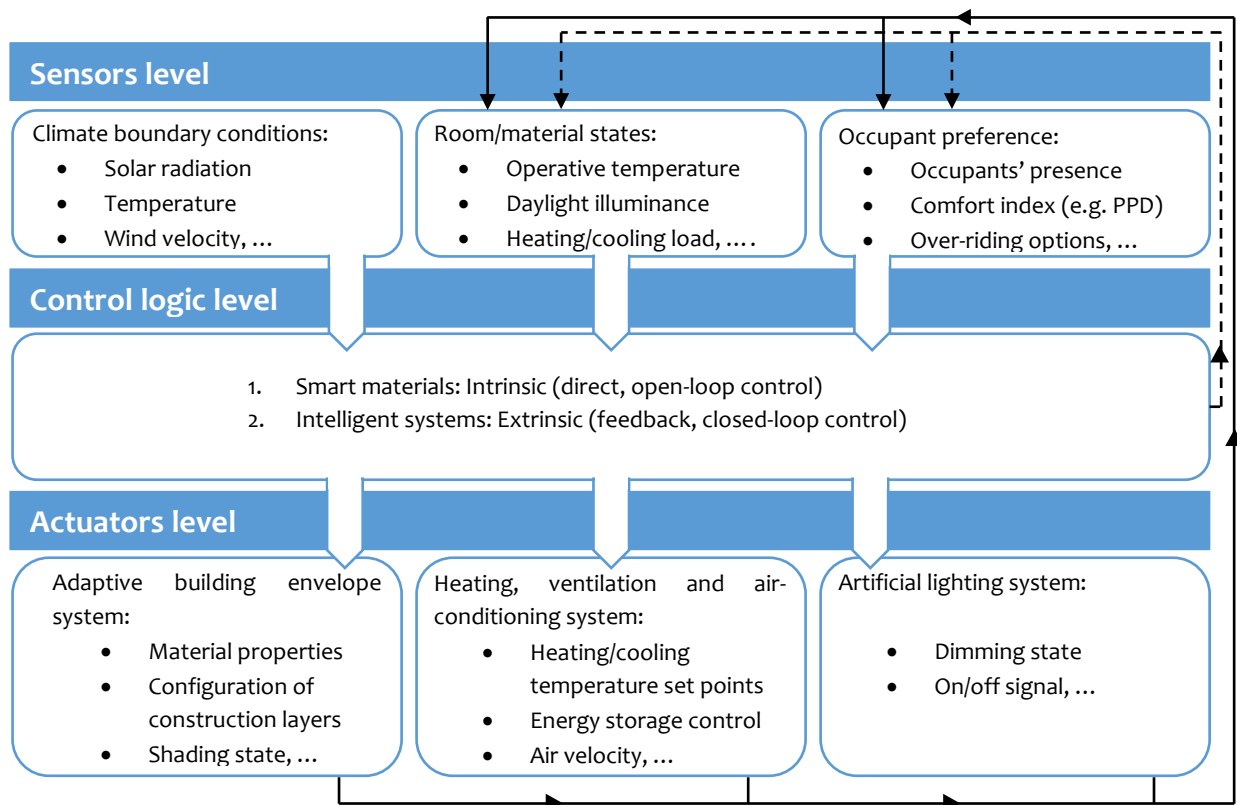
196 Other simulation tools use finite difference or finite volume methods for modeling transient  
 197 conduction. These numerical methods adopt an iterative procedure, thereby allowing for

198 updates of the matrix coefficients that describe heat transfer, as time steps of the simulation  
199 proceed. This makes the simulation of variable thermo-physical properties possible.

200 The models for calculating energy gains/losses through transparent portions of the building  
201 envelope, on the other hand, do not normally include thermal storage effects (Freire et al. 2011),  
202 so that it easier to take dynamically changing window properties into account in the simulation,  
203 also in BPS tools adopting response factors techniques. A similar approach can be chosen for so-  
204 called massless layers (i.e. constructions with no or very low thermal capacity), which only affect  
205 thermal resistance, but do not influence the storage term in the heat balance equations.

### 206 3.3 Control strategies

207 Control strategies in BPS models provide the link between sensed variables and actuator actions  
208 by means of a certain control logic. This feature is mostly used for control of HVAC systems but  
209 other opportunities also exist. The (non-)availability of actuator options is what in the end  
210 determines the types of adaptive facade technologies that can be modeled in a simulation tool.  
211 Figure 2 illustrates the general architecture for the control of building systems (including  
212 adaptive building envelope systems) in BPS tools, which can be divided into (i) sensors level  
213 (climatic boundary conditions, building internal boundary conditions, occupant preferences); (ii)  
214 control logic level; (iii) actuators level, i.e. any building component that can be controlled  
215 (including HVAC, artificial lighting and adaptive building envelope systems).



216

217 Figure 2. Control architecture for building systems, including building services and adaptive facades: the continuous line  
 218 represents active, closed-loop, control; the dashed line represents passive, open-loop, control.

219 The control of adaptive building envelopes can be subdivided into (i) *intrinsic* and (ii) *extrinsic*  
 220 concepts (Loonen et al. 2013). The term *intrinsic* indicates that the adaptive mechanism is  
 221 automatically triggered by a stimulus (e.g. surface temperature, solar radiation, etc.). This  
 222 intelligence is chemically embedded in the material and the switching mechanism is activated by  
 223 a variation in its internal energy. This kind of control (dashed arrows in Figure 2) is also referred  
 224 to as “direct” or “open-loop” control and the material is said to be “smart” (e.g. thermo-chromic,  
 225 photo-chromic, phase change materials), as no intervention from an external system/user is  
 226 required. In contrast, *extrinsic* refers to the presence of an external decision making component  
 227 that is able to trigger the adaptive mechanisms according to a feedback rule (continuous arrows  
 228 in Figure 2). This is the so-called “feedback” or “closed-loop” control type, and in this case, the  
 229 adaptive system, which includes the adaptive building envelope component and the controlling  
 230 system, is often referred to as “intelligent” (e.g. electro-chromic glazing, movable shading

231 devices, kinetic facades, etc.). Hence, intelligent systems require a control management system  
232 in order to respond in an adaptive manner, consisting of sensors, processors and actuators.

233 The control options for adaptive building envelope systems available in BPS tools can be  
234 classified into four groups: (i) hard-coded intrinsic, (ii) hard-coded extrinsic, (iii) time-scheduled,  
235 and (iv) script-based.

236 Hard-coded intrinsic control refers to control options for *application-oriented* modelling  
237 capabilities which are already implemented into the software and accessible through the GUI.  
238 This is the case, for example, for the actuation of thermo-optical properties of a fenestration  
239 system based on temperature (i.e. thermo-chromic windows), or for phase-changing materials,  
240 modeled via temperature-based changes in specific heat capacity.

241 Hard-coded extrinsic control, on the other hand, can usually be chosen from a limited number of  
242 fixed presets. These typically include if-then-else statements where the user can select (i) sensor  
243 types (e.g. incident solar radiation, room temperature, heating or cooling demand, etc., or  
244 combinations thereof) and (ii) control thresholds to actuate a specific adaptive technology.

245 Time-scheduled control shares many characteristics with hard-coded extrinsic control systems,  
246 but is different in the sense that control actions are pre-determined as a function of time,  
247 instead of being based on boundary conditions or simulation state variables.

248 Finally, more advanced intrinsic and extrinsic adaptive systems control options can be evaluated  
249 if a script-based control can directly be coded by the user in the simulation tool. Script-based  
250 control, referring to the ability to change the state of the building envelope during simulation  
251 run-time, gives the possibility to test a specific control approach, replicating and extending the  
252 hard-coded direct or feedback preset options. The fundamental steps of modelling a script-  
253 based control are: (i) selecting from a list of available sensors (i.e. simulation state variables or  
254 boundary conditions); (ii) selecting from a list of possible actuators (chosen according to the  
255 specific adaptive technology/concept that needs to be simulated); (iii) coding a control  
256 algorithm, which translates sensor signals into actions, by means of simple algebraic and Boolean  
257 operators.

258        *3.4 Occupant influence*

259        In contrast to conventional, static facades, adaptive building envelope systems can have an  
260        interdependent relationship with building occupants. For some applications, the simulation  
261        model needs to be able to evaluate not only how the adaptive building element affects occupant  
262        comfort conditions, but also how individual occupants may want to control a specific adaptive  
263        building envelope technology (Haldi and Robinson 2010) (Figure 2). This capability requires  
264        behavioral models that describe the interaction of building occupants with adaptive building  
265        envelope systems (Haldi and Robinson 2010; Hoes et al. 2009; Gunay et al. 2013). For example,  
266        different deterministic and probabilistic models are available for occupants' operation of blinds  
267        (Reinhart 2004) and window openings (Fabi et al. 2012). The development of occupant behavior  
268        models for integration in BPS tools is an active field of research, coordinated at an international  
269        level via IEA ECB Annex 66 (Yan et al. 2015). Until now, such occupant interactions can only be  
270        implemented via script-based control approaches (Section 3.3) but efforts to integrate them  
271        more seamlessly into BPS tools are ongoing (Hong et al. 2015). The available information on the  
272        interaction of people with more advanced adaptive facade technologies is, however, still scarce  
273        (Bakker et al. 2014).

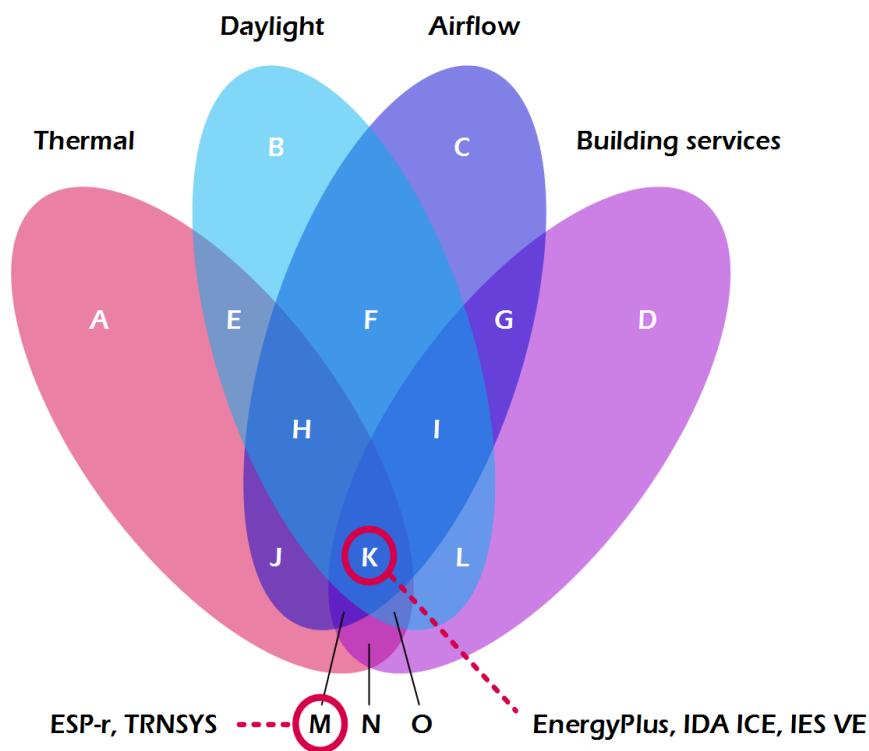
274        *3.5 Multi-domain integration and physical interactions*

275        The influence of the building envelope on the indoor environment can be evaluated in different  
276        physical domains: e.g. thermal, visual and mass-flow (air and/or moisture). Moreover, to ensure  
277        adequate levels of occupant comfort, there is a need to synchronise the actions of adaptive  
278        facades with the operation of building services. Because these multi-domain influences can be  
279        mutually interrelated, there may be a need to solve the differential equations that describe the  
280        relevant physical phenomena in a coupled way. Matching the required physical interactions of a  
281        specific adaptive facade technology with the capabilities of a BPS tool to assess the performance  
282        across these multiple domains is therefore an important requirement for selecting suitable  
283        simulation strategies.

284        The focus of this paper is on the use of BPS tools to evaluate comprehensive building energy use  
285        and occupant comfort indicators. Most of these BPS tools are able to integrate thermal, airflow

286 and building services (HVAC) domains, such as ESP-r, TRNSYS (Figure 3). A limited subset of  
 287 them also integrates daylight models<sup>2</sup> (and therefore artificial lighting models as well), such as  
 288 EnergyPlus, IDA ICE, IES VE (Figure 3).

289 Whenever a BPS tool presents restricted cross-domain modelling capabilities, the exchange of  
 290 information between different BPS tools across different domains, can be managed (i) before the  
 291 simulation (data and process model integration) or (ii) during simulation run-time (data and  
 292 process model co-operation) (Hensen et al., 2004), also called co-simulation (Trcka, Hensen and  
 293 Wetter 2009) (cf. Section 5.3).



294

295 Figure 3. Multi-domain integration required to model adaptive building facades in different BPS tools .

#### 296 4 Capabilities of various building energy simulation software tools

297 The previous section has introduced several challenges and limitations, but at the same time also  
 298 highlighted numerous opportunities for effective performance prediction of buildings with  
 299 adaptive facades, based on BPS tool characteristics and underlying modelling assumptions. The

<sup>2</sup> Although ESP-r does offer some rudimentary daylight prediction options, this functionality is not included in the present paper, because unlike for other tools, the advanced daylight models are not part of the ESP-r distribution, but should rather be classified under co-simulation.

300 main aim of this section is to develop these capabilities further by reviewing the specific  
301 adaptive envelope modeling capabilities of five widely-used BPS tools in more detail.

302 It should be noted, however, that simulation users have also developed various approaches to  
303 partially overcome or bypass the aforementioned limitations for modeling adaptive facade  
304 behavior in the simulation tool of their choice. The principles and possible pitfalls of such  
305 simplified approaches are described first (Section 4.1), before presenting the methodology  
306 (Section 4.2) and results of the review of application-oriented and general-purpose modeling  
307 features (Sections 4.3 and 4.4, respectively), and control options (Section 4.5).

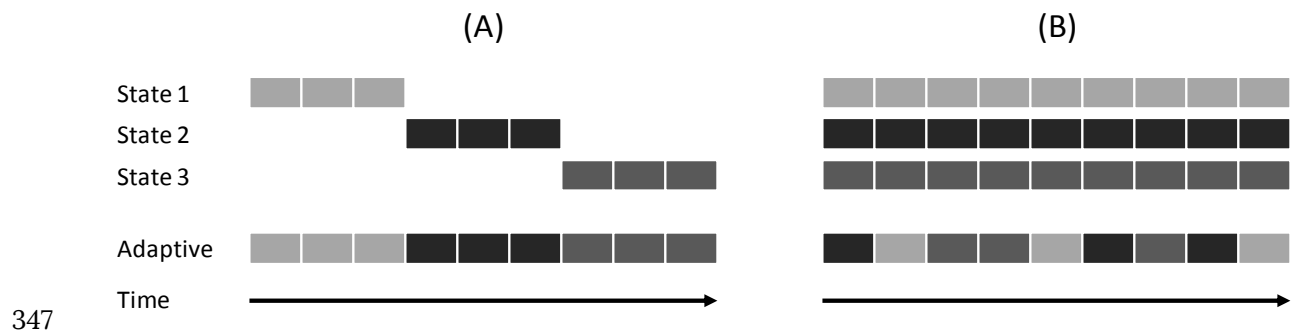
#### 308 4.1 Simplified simulation strategies and workarounds

309 Building performance simulation is a field where modeling features, almost by definition, lag  
310 behind the newest breakthrough technological developments and most creative design  
311 proposals. Workaround simulation strategies therefore have a long tradition in this field (Brahme  
312 et al. 2009), and can be used for various legitimate reasons such as: the complete absence of  
313 existing models for certain adaptive building envelope technologies; a lack of user  
314 expertise/experience; limited project resources (time, money) to move towards more complex  
315 models; the absence of advanced control options for determining the optimal dynamic building  
316 envelope properties. In many of these cases, the ability to reuse validated, high-resolution  
317 models is an important argument in favour of using existing software instead of the development  
318 of custom-made simulation code from scratch (Wetter 2011a), such as the approach taken by Liu  
319 et al. (2014). A main drawback of using workarounds is that they tend to rely on approximations  
320 or simplifications that might infringe the physics of model representations and, consequently,  
321 also put the credibility of simulation outcomes at risk.

322 Arguably, the simplest approach for representing an adaptive building envelope system is by  
323 subdividing the simulation period (e.g. one year) into several simulation runs with shorter  
324 periods (e.g. seasons, months, weeks, etc.), each with distinct building properties (Kasinalis et al.  
325 2014; Favoino, Jin, and Overend 2014; Joe et al. 2013; Hoes et al. 2011; Loonen, Trčka, and Hensen  
326 2011) (Figure 4a). This discrete approach works well for facade systems with long adaptation

327 cycles (e.g. seasonal), but it cannot accurately model short-term adaptive building envelope  
 328 dynamics. This is due to shortcomings in the initialization of equations at the start of each  
 329 simulation run, where the end states of one simulation (i.e. surfaces and construction nodes  
 330 temperatures) are different from the starting conditions of the subsequent simulation

331 An alternative approach uses separate models for the whole simulation period, each with static  
 332 properties that represent different states of the adaptive building envelope system. At a post-  
 333 processing stage, the results of these independent simulation models are combined in a single  
 334 representation of the performance of the building, according to a certain control strategy for the  
 335 adaptive facade (Figure 4b). This modelling approach can have the advantage of (i) mimicking  
 336 more advanced building operation controls and/or (ii) simulating adaptive building envelope  
 337 technologies and materials for which a model does not exist yet. Specifically, even though such a  
 338 modeling method is well able to capture switching of instantaneous solar gains, e.g. due to  
 339 changing window-to-wall ratio (Goia and Cascone 2014) or glazing properties (DeForest et al.  
 340 2013), it fails to account for the effect of delayed thermal response due to capacitance of building  
 341 components (i.e. slabs, walls and internal partitions). Therefore in cases where thermal mass is  
 342 involved in adaptive building envelope operations, the use of these approximate models would  
 343 probably lead to significant errors in the results, because they do not correctly handle transient  
 344 thermal energy storage effects (Erickson 2013). These inaccuracies may eventually compromise  
 345 decision-making based on simulation outcomes, but little information about this issue is  
 346 reported in literature.



348 Figure 4. Schematic representation of workaround strategies for modeling the performance of adaptive  
 349 facades. Case A represents the discrete approach that combines a number of short term simulations. Case B  
 350 represents the approach that assembles the results of simulations with static facades during post-processing.



## 4.2 Overview of capabilities – methodology

A review of the opportunities for modeling adaptive building envelope systems in state-of-the-art BPS tools was conducted to compile an overview of the current capabilities and existing development needs. Based on literature review (Crawley et al. 2008; Attia et al. 2012) and first-hand experience, five simulation tools (presented in Table 2) were selected on the basis of the following criteria:

- Extensive building envelope modeling capabilities, as identified by Crawley et al. (2008);
- Subject to active development by their development team or user community;
- Thorough validation through compliance with ANSI/ASHRAE Standard 140 (BESTEST) and other quality assurance procedures;
- Use in both research and consulting engineering practice;
- International user base.

Table 2. Characteristics of whole Building Energy Simulation tools with respect to performance prediction of adaptive building envelope systems.

	<b>Conduction solution method</b>	<b>User Interface<sup>3</sup></b>	<b>Source code access and modification</b>	<b>Control simulation capabilities</b>	<b>Physical domain integration</b>
<b>EnergyPlus v8.3</b>	CTF, Finite difference <sup>4</sup>	IDF editor, DesignBuilder, Comfen, OpenStudio, Simergy, Sefaira, DIVA, AECOSim	X	Presets, Time-scheduled, Energy Management System	Thermal, Visual, Airflow
<b>ESP-r</b>	Finite volume	Graphic and text mode	X	Presets, Time-scheduled	Thermal, Airflow <sup>5</sup>
<b>IDA ICE v4.7</b>	Finite difference	Standard and advanced level	X	Presets, Time-scheduled	Thermal, Visual, Airflow
<b>IES v2015</b>	Finite difference	IES VE, SketchUp and Revit plug-ins <sup>6</sup>		Presets, Time-scheduled, Formula profile (APpro)	Thermal, Visual,

<sup>3</sup> Options for modeling adaptive facades are significantly limited when the simulation engine is accessed through one of the third-party GUIs

<sup>4</sup> By default, EnergyPlus uses the CTF method, but it was recently extended with a new finite difference scheme for conduction, to allow for modelling temperature- or time-dependent material properties (Pedersen 2007; Tabares-Velasco and Griffith 2012). The usage of this new approach has been large unexplored in literature.

<sup>5</sup> Daylight performance predictions with ESP-r are possible but are either limited to the restricted functionality of the *obsolete* daylight factor metric, or require setting up a co-simulation with the Radiance daylight simulation engine. Unlike the other daylight models in this overview, Radiance is not part of the host software (ESP-r), it is not seamlessly integrated in the simulation workflow, and its use requires detailed operational knowledge of Radiance commands and algorithms. It is therefore not included in this overview.

<b>TRNSYS v17.1</b>	CTF <sup>7</sup>	TRNBuild, SketchUp plug-in	(X) <sup>8</sup>	Presets, Time-scheduled, user-defined <i>equations</i> in Simulation Studio, W- editor (Type 79)	Thermal, Airflow
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365 The analysis of capabilities is based on the information in user manuals, software tutorials,  
 366 release notes and contextual help facilities of the BPS tools, as well as communication with their  
 367 development teams. Furthermore, scientific articles, dissertations and the information exchange  
 368 in mailing lists were used to gather input. The review outcomes are divided into (i) application-  
 369 oriented, (ii) general-purpose, and (iii) control capabilities for each software, following the  
 370 descriptions in sections 3.1 and 3.3.

371 The review is also presented in a tabular fashion, the notation used is indicated in Table 3 and  
 372 includes: required and available relevant physical domains (T: thermal, V: visual, A: airflow), type  
 373 of control (represented by the cell color), control options related to a specific technology (only  
 374 for Table 6, indicating the modelling options for which this control is available), level of expertise  
 375 required (in the form of a superscript for knowledgeable users and expert users).  
 376 “Knowledgeable user” refers to the need to develop custom-made scripts within the software  
 377 interface. “Expert user” requires an even higher level of proficiency as it indicates that either  
 378 creative modeling approaches have to be used, that the features are not documented, or that  
 379 small source code modifications are necessary. The ability to include code modifications is only  
 380 possible in tools that allow access to its source code (Table 2). Such interventions can be  
 381 onerous, but are sometimes the only option to support modeling of innovative façade systems.  
 382 Open-source simulation tools also enable calls to external software programs in a co-simulation  
 383 framework, as is further discussed in Section 5.3.

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385

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<sup>6</sup> Additional modelling is needed in IES VE in order to perform a simulation, but some preliminary early-stage analysis could be performed via the plug-ins directly.

<sup>7</sup> Simulation users can also choose to bypass the CTF approach by coupling TRNSYS Type 56 with finite element or finite difference schemes such as Type 260 or Type 399 (Kosny, 2015)

<sup>8</sup> Excluding dynamic building model Type 56

386 Table 3. Legend for Tables 4 and 5.

Expertise required		Control	Physical Domain	
*	Knowledgeable user	Intrinsic	T	Thermal
**	Expert user	Extrinsic	V	Visual
			A	Airflow

387

388 **4.3 Application-oriented capabilities**

389 The software capabilities were assessed for 20 different adaptive facade technologies and  
 390 corresponding application-oriented modeling features (Table 4); the main findings are discussed  
 391 in this section.

392 Table 4. Overview of application-oriented features for modeling adaptive building envelope systems. See Table  
 393 3 for legend.

#	Adaptive facade technology	Required Domains	Energy Plus	ESP-r	IDA ICE	IES VE	TRNSYS	
Transparent	Switchable glazing	4.1 Electro-chromic (EC), Liquid crystal, SPD	T-V	T-V	T	T-V	T-V	T*
		4.2 Photo-volta-chromic	T-V	T-V *	T*	T-V**		T*
		4.3 Independently tunable NIR-VIS EC	T-V					T**
		4.4 Thermo- tropic / chromic	T-V	T-V	T	T-V**		T*
		4.5 Photo-chromic	T-V	T-V *	T	T-V**	T-V*	T*
		4.6 Fluidglass	T-V					
	Shadings	4.7 Screens / roller shades	T-V	T-V	T	T-V	T-V	T
		4.8 Blinds with slat angle control	T-V	T-V	T	T-V		
		4.9 Bi-directional transmission control	T-V	T-V	T	T-V		T**
		4.10 Insulating shutters	T-V	T-V		T-V	T-V	T
		4.11 Shading with dual-axis tracking	T-V					
		4.12 Phase change material	T-V			T-V		
Opaque	4.13 Double skin facade	T-V-A	T-V-A*	T-A*	T-V-A*	T-V-A*	T-A*	
	4.14 Double skin facade	T-A	T-A*	T-A*	T-A*	T-A*	T-A*	
	4.15 Trombe wall	T-A	T-A*	T-A*	T-A*	T-A*	T-A*	
	4.16 Green roof	T	T	T			T**	
	4.17 Green wall	T	T	T			T**	
	4.18 Movable/switchable insulation	T	T		T			
	4.19 Thermocollect	T						
	4.20 Phase change material	T	T	T	T		T**	

394 Different types of switchable windows, including electrochromic glazing, are commercially  
 395 available, and many research papers have been written about their application in buildings and  
 396 architecture (Baetens, Jelle, and Gustavsen 2010). As a result of their presence in the market,

397 options for modeling switchable glazing technologies are embedded in several simulation tools.  
398 All the software tools analyzed offer the possibility to control properties of the fenestration  
399 system during simulation run-time. The differences between the various implementations are  
400 the number of possible window states (e.g. on/off versus gradual transitions) and the simulation  
401 state variables that can be used for control of adaptation (e.g. room temperature, ambient  
402 temperature, incident radiation).

403 Thermo-tropic/chromic windows are slightly more complicated to simulate than other  
404 switchable window types because of their intrinsic control character; adaptation of the  
405 fenestration properties is directly triggered by window surface temperature instead of a control  
406 signal that is based on more general simulation variables. A provision for thermochromic window  
407 simulation was implemented in EnergyPlus (since v3.1, 2009) and ESP-r (Evans and Kelly 1996).  
408 The input of these models consists of sets of window properties at various temperatures. During  
409 the simulation, the thermochromic layer temperature of the previous time-step is automatically  
410 fed into a window control algorithm which then selects the window properties that best match  
411 with the given temperature. In IDA ICE and Trnsys, it is also possible to model thermo-  
412 tropic/chromic windows, but a significantly higher level of work and expertise is required from  
413 the user side (Section A.3 for IDA ICE and A.5 for TRNSYS).

414 Moveable internal and external solar shading is probably the most widely-used adaptive building  
415 envelope function. In all simulation tools that were included in this study, it is available in various  
416 forms. The GUIs of EnergyPlus, IDA ICE and IES VE offer the possibility to give dynamic shading  
417 devices additional thermal resistance properties. This makes it possible to simulate the  
418 performance of *insulating solar shading systems* (Hashemi and Gage 2012). In such an  
419 implementation, dynamic thermal insulation and solar shading are coupled, so that their  
420 separate effects cannot be analyzed. As the need for coupled analysis of thermal and daylight  
421 aspects gets increasingly recognised, the options for modeling more advanced optical facade  
422 systems in building energy simulation software are also expanding (Table 4). Recent additions in  
423 many tools include the possibility to control the slat angle of blind systems and the properties of  
424 light-redirecting complex fenestration systems.

425 Prediction models for wall-integrated *phase change materials* (PCM) are present in EnergyPlus  
426 (Tabares-Velasco, Christensen, and Bianchi 2012), ESP-r (Heim and Clarke 2004), IDA ICE (Plüss  
427 et al. 2014) and TRNSYS (Kuznik, Virgone, and Johannes 2010). These models influence heat  
428 transfer in constructions via either the 'effective heat capacity' or the 'additional heat  
429 source'/'enthalpy' method. The need to implement PCM features led the developers of  
430 EnergyPlus to abandon the CTF approach and introduce a numerical finite difference conduction  
431 algorithm (Pedersen 2007). This new algorithm includes a temperature coefficient that allows  
432 variable thermal conductivity during the simulation (Tabares-Velasco and Griffith 2012). Only a  
433 few applications of this latter model were found in literature. The performance of  
434 transparent/translucent PCM systems can only be modeled in IDA ICE (Plüss et al. 2014) or with  
435 the use of reduced-order building models (Goia, Perino, and Haase 2012).

436 The capability of simulating double skin facades (either transparent or opaque, including Trombe  
437 walls and ventilated facades) is generally available in several whole building simulation tools  
438 (EnergyPlus, ESP-r, TRNSYS, IDA ICE, IES VE) (Hensen, Bartak, and Drkal 2002; Kim and Park  
439 2011). Some BPS tools provide specific models for the simulation of double skin facades from the  
440 GUI (e.g. multi-skin in EnergyPlus), although their accuracy depends on the choice and  
441 availability of calculation methods for cavity heat transfer in terms of the mode of ventilation  
442 (buoyancy driven and/or mechanical), the ventilation air path (from outdoor to indoor, outdoor  
443 to outdoor, etc.), the type of solar shading in the ventilated cavity (Kim and Park 2011), and the  
444 spatial discretization of the air cavity (Mateus, Pinto, and Da Graça 2014). Additionally, it is  
445 generally possible to represent a multiple skin facade by coupling the thermal model with an  
446 airflow network, but additional modelling could be required in order to ensure reliability of the  
447 results (Favoino 2015).

448 EnergyPlus, ESP-r, and TRNSYS support the simulation of *green walls and roofs*. The models  
449 account for: (i) long-wave and short-wave radiative exchange within the plant canopy, (ii) plant  
450 canopy effects on convective heat transfer, (iii) evapotranspiration from the soil and plants, and  
451 (iv) heat conduction and storage in the soil layer (Sailor 2008; Djedjig, Bozonnet, and Belarbi

452 2015). In the EnergyPlus model, it is possible to include material properties that change over time  
453 with fluctuations in plant growth and moisture content (Sailor and Bass 2014).

454 Finally, EnergyPlus (Jin, Favoino, and Overend 2015) and IDA ICE (Bionda, Menti, and Manz 2014)  
455 can simulate the performance of building envelopes with *moveable insulation*. A controllable  
456 layer can be applied to the interior or exterior side of an opaque facade element to temporarily  
457 increase its thermal resistance. These materials are massless, which means that no thermal  
458 energy can be stored in a moveable insulation layer.

459 The suitability of a model for evaluating the performance of a particular adaptive building  
460 envelope system depends to a large extent on the flexibility that the BPS tool offers in terms of  
461 the control strategies that are available. This is especially the case for the application-oriented  
462 modelling features with extrinsic controls that are discussed in this Section. More attention to  
463 the implementation and availability of control options is given in a separate section (Section 4.5).

464 The review of application-oriented modelling options presented in this paper focuses on  
465 software capabilities. It is not intended to provide a comprehensive review of existing adaptive  
466 building envelope materials, technologies and systems. In fact, the tendency of BPS tools to lag  
467 behind the market availability of adaptive technologies limits the number of application-oriented  
468 modelling capabilities available in a specific BPS tool, compared to what is technologically  
469 available. As such, there are many adaptive building envelope systems (either at prototype or  
470 product stage), whose performance cannot be evaluated yet with the existing application-  
471 oriented simulation models. Some examples are included in Table 4 for illustration (i.e. 4.3  
472 (Llordés et al. 2013), 4.6 (Ritter 2014), 4.11 (Rossi, Nagy, and Schlueter 2012), 4.12 (Goia, Perino, and  
473 Haase 2012), 4.19 (Burdajewicz, Korjenic, and Bednar 2011)).

474 Therefore, from a product development point-of-view, it is more desirable to allow for bottom-  
475 up or general-purpose approaches to simulate emerging or not-yet-existing adaptive building  
476 envelope materials and technologies (Loonen et al. 2014).

477 **4.4 General-purpose modeling options**

478 General-purpose modeling options offer more flexibility than application-oriented features. A  
 479 review of available general-purpose adaptive features is presented in this section and the results  
 480 are summarised in Table 5. The discussion that follows provides the principal outcomes of this  
 481 review. A more extensive description of the capabilities of each simulation tool is provided in  
 482 Appendix A.

483 *Table 5. Overview of general-purpose modeling features for adaptive building envelope systems. See Table 3 for*  
 484 *legend.*

#	Controllable property	Required Domains	EnergyPlus	ESP-r	IDA ICE	IES VE	TRNSYS
5.1	Visible optical properties	T-V	T-V *	T	T-V*	T-V*	T*
5.2	Solar optical properties	T-V	T-V *	T	T-V*	T-V*	T*
5.3	Emissivity	T	T*				
5.4	Surface heat transfer coefficient	T	T*	T*	T*	T*	T*
5.5	Solar absorption	T	T*				
5.6	Conductivity	T	T*	T*	T**		T**
5.7	Density / specific heat capacity	T		T*	T**		
5.8	Facade geometry	T-V					
5.9	Site rotation	T-V	T-V**	T*			T*
5.10	Evaporation at surface	T		T*			

485

486 **EnergyPlus** Of all software tools analyzed, EnergyPlus has had the largest growth in adaptive  
 487 facade modeling capabilities since it was developed. Most notably, these developments have  
 488 been driven by the introduction of the EnergyPlus Runtime Language (ERL) (Ellis, Torcellini, and  
 489 Crawley 2007). With ERL, users can implement Energy Management Systems (EMS) of various  
 490 kinds by linking sensors, control logic and actuators. Among the possible EMS actuators are  
 491 various thermophysical building envelope material properties (Table 5). These actuators can be  
 492 controlled with user-defined IF-ELSE statements during simulation run-time.

493 **ESP-r** ESP-r is a simulation tool with an open-source environment aimed at the  
494 research community. Since its first version, various groups have contributed general-purpose  
495 functionalities for modeling adaptive facade technologies. The capabilities include: (i) *thermo-*  
496 *physical property substitution mode* (MacQueen 1997), (ii) transparent multi-layer construction  
497 control, (iii) *special materials* (Evans and Kelly 1996), (iv) variable thermo-physical properties  
498 (Nakhi 1995), and (v) the use of roaming files to model rotating buildings with changeable  
499 orientation. Each of these models has unique characteristics as well as control restrictions, as  
500 described in Appendix A and Section 4.5.

501 **IDA ICE** Unlike most other simulation tools, IDA ICE works with symbolic equations  
502 instead of variable assignments (Sahlin 2004). This feature makes it relatively easy to upgrade  
503 existing modeling functionality, as was recently done for the finite-difference multi-layer wall  
504 model (“fdwall”) that can now account for time-varying thermo-physical properties (“fdwalldyn”)  
505 (Bionda, Menti, and Manz 2014). Other adaptive features in IDA ICA can be activated by defining  
506 custom control macros, and selecting the advanced-level instead of standard user interface.

507 **IES VE** IES VE is a commercial simulation tool with a closed software environment. The  
508 program gives limited flexibility for modeling adaptive facades beyond the application-oriented  
509 features that were discussed in section 4.3. Nevertheless, using APro, the module for time-  
510 scheduling and profiles in IES VE, there are some opportunities to link user-selected sensor  
511 values with time-varying facade property actuators (Table 5).

512 **TRNSYS** In TRNSYS, the multi-zone building model (TYPE 56) is one out of a large number  
513 of possible system components. The *variable window id* option and a controllable bi-directional  
514 scattering distribution function (BSDF) (Hiller and Schöttl 2014) are directly implemented in  
515 TYPE 56. All other adaptive features in TRNSYS can be activated by manipulating (i.e. switching  
516 on/off or modulating) the connections to and from the TYPE 56 building model, via so-called  
517 equations using the either the graphical Simulation Studio or by editing text files. These  
518 functions include overhangs and wingwalls (TYPE 34), shading masks (TYPE 64), attached  
519 sunspaces (with or without movable thermal insulation) (TYPE 37), windows with variable



520 insulation properties (TYPE 35) and photovoltaic modules (TYPES 94, 180 and 194). In addition, it  
521 is also possible to adjust the way that weather files and radiation processors are connected to  
522 model the effect of time-varying facade orientations (e.g. rotating buildings).

#### 523 4.5 Control options

524 An overview of the control options, according to the definitions given in section 3.3 (hard-coded  
525 intrinsic, hard-coded extrinsic, time-scheduled and script-based), is provided in Table 6. The  
526 table provides different information for each of the four control options:

- 527 • hard-coded intrinsic: only available for application-oriented modelling capabilities, the  
528 reader is redirected to Table 4 for the specific passive technologies;
- 529 • hard-coded extrinsic: only available for application-oriented modelling capabilities. The  
530 rows indicate the different sensors options, and the number indicates the particular  
531 adaptive facade technology in Table 4 to which the specific control can be applied;
- 532 • time-scheduled: available for all hard-coded extrinsic application-oriented modelling  
533 capabilities;
- 534 • script-based: available for all application-oriented modelling capabilities (indicated as T4)  
535 and partially for general purpose modelling capabilities (indicated as a number in row  
536 6.19 referring to Table 5). Row 6.18 indicates the availability of sensor options.

537 The script-based control approaches include EMS (EnergyPlus), user-defined control macros  
538 (IDA ICE), APro (IES VE) and “equations” and W-editor (TRNSYS). This control approach can also  
539 be applied, differently for each BPS tool, to the other three control options (hard-coded intrinsic  
540 and extrinsic, as well as time scheduled). This is indicated with a shaded cell in the Table 6.

541 Table 6. Overview of control modeling features for adaptive building envelope systems, numbers in the table  
 542 entries indicate the applicability of the control to a specific model (cf. Table 4 and 5).

#	Control type	Boundary condition	Sensor	EnergyPlus	ESP-r	IDA ICE	IES VE	TRNSYS	
6.1	<b>Hard-coded Intrinsic</b>	Material state	NA	Cf. Table 4	Cf. Table 4	Cf. Table 4	Cf. Table 4	Cf. Table 4	
6.2	<b>Hard-coded Extrinsic</b>	Climate	Always on	All extrinsic	All extrinsic	All extrinsic			
6.3			Always off	All extrinsic	All extrinsic	All extrinsic			
6.4			Outdoor air temperature	4.1, 4.2, 4.7-10, 4.13-15, 4.18	4.1, 4.2, 4.7, 4.8, 4.9	4.13-4.15			
6.5			Horizontal solar radiation	4.1, 4.2, 4.7-10					
6.6			Perpendicular solar radiation	4.1, 4.2, 4.7-10	4.1, 4.2, 4.7, 4.8, 4.9	4.1, 4.2, 4.7-10	4.1, 4.2, 4.7, 4.10	4.7, 4.10	
6.7			Block beam solar radiation	4.1, 4.2, 4.7, 4.8					
6.8			Day/Night	4.18			4.10	4.10	
6.9			Wind speed	4.13-15			4.1, 4.2, 4.7-10		
6.10			Heating load	4.18					
6.11			Cooling load	4.1, 4.2, 4.7-10, 4.18					
6.12	Building states	Zone air temperature	4.1, 4.2, 4.7, 4.10, 4.13-15, 4.18	4.1, 4.2, 4.7, 4.8, 4.9, 5.6-7					
6.13		Daylight level	4.1, 4.2, 4.7-4.10						
6.14		CO <sub>2</sub> concentration	4.13, 4.14	4.13, 4.15					
6.15		Occupants' presence	4.1, 4.2, 4.7-10, 4.13-15, 4.18						
6.16	Occupant	Visual comfort (e.g. glare)	4.1, 4.2, 4.7-10						
		Thermal comfort (e.g. PMV, operative temperature)	4.13-15	4.1, 4.2, 4.7, 4.8, 4.9, 5.6-7					
6.17	<b>Time scheduled</b>	N/A	N/A	All extrinsic	All extrinsic	All extrinsic	All extrinsic	All extrinsic	
6.18	<b>Script-based</b>	N/A	Sensor	Any output		Any output	Limited	Any output	
6.19			Actuator	T4, 5.1-6, 5.9		T4, 5.1-2, 5.4, 5.6-7	T4, 5.1-2, 5.4	T4, 5.1, 5.2, 5.4, 5.6, 5.9	

543 Dynamic operation of building components is usually represented in BPS tools by means of  
 544 hard-coded preset rules (6.2 – 6.16) or time-scheduled operations (6.17). These control options  
 545 are related to application-oriented modelling capabilities, in which the control rule is often  
 546 closely related to operating modes of the technology itself. The hard-coded preset control rules

547 can be editable, if the specific technology allows for extrinsic control, by selecting from a limited  
548 number of sensor options in the GUI. Otherwise, if the specific technology modelled is a smart  
549 adaptive technology, that is, only intrinsic control is available, the preset control rule is fixed and  
550 cannot be edited (e.g. relationship between glazing thermo-optical properties and glass  
551 temperature for thermochromic glazing).

552 When adopting a general-purpose modelling approach, the user is required to explicitly model  
553 the way the adaptive mechanism is triggered by boundary conditions, by defining sensors,  
554 control algorithms (either intrinsic or extrinsic) and actuators, following the architecture  
555 represented in Figure 2. This can be done in the user interface of the specific BPS tool, by means  
556 of scripting and/or the use of graphical interfaces (Table 6, script-based control type). This  
557 approach, although requiring a higher level of user expertise, and more detailed information  
558 about how the adaptive building element/material is controlled, gives a higher level of flexibility  
559 for modelling innovative components with different and more advanced control  
560 strategies/algorithms.

561 Design performance evaluation of adaptive building envelope systems could require the need for  
562 calculating metrics that may not be directly available as outputs of the simulation tool. For  
563 example double skin facades can be evaluated and/or operated according to their dynamic  
564 insulation efficiency or pre-heating efficiency (Zanghirella, Perino, and Serra 2011). Allowing the  
565 user to make this intermediate step, by transforming simulation outputs into this type of custom  
566 performance metrics / control input could enable a more efficient design process, while  
567 simultaneously allowing the evaluation of more advanced control strategies. This can be done by  
568 means of script-based control strategies.

## 569 **5 Conclusions, trends and future perspectives**

570 This paper has highlighted the potential of simulation-based analysis in various stages of design  
571 and development of buildings with adaptive building envelopes. The main requirements and  
572 challenges compared to performance prediction of conventional, static building envelopes were  
573 identified. On these bases, we have presented a comprehensive comparative overview of

574 application-oriented, general-purpose and control capabilities for modeling and simulation of  
575 adaptive building envelopes in state-of-the-art whole building performance simulation software.  
576 It should be emphasised that simulation of adaptive facades tends to involve a high level of  
577 multi-domain interactions and corresponding reciprocal exchange with other energy systems in  
578 buildings. It is therefore important that users develop suitable simulation strategies, by carefully  
579 matching the performance evaluation objectives with the capabilities and limitations of the  
580 different models and simulation tools at hand.

581 Relative to the well-established position of BPS in performance-based building design, the  
582 application of modeling and simulation for adaptive building envelope assessment is still at an  
583 early stage of development, with many more aspects of this field that have yet to be explored.  
584 This review has focused on the more advanced and comprehensive subset of available simulation  
585 tools, which are not always considered to be user-friendly, or suitable for early-phase design  
586 explorations. Various different GUIs have recently been developed, aiming at an easier  
587 integration of the simulation engines behind these BPS tools with the building design process.  
588 Due to interface limitations arising from the trade-off between ease-of-use and modeling  
589 complexity, the number of options for modeling adaptive facades in these user-friendly GUIs  
590 ranges from very limited to none. Extending such options is a clear target for future work. This  
591 section concludes the article by discussing four parallel trends and future perspectives that have  
592 the potential to further improve the impact of simulation-based design, research and  
593 engineering of adaptive building envelopes.

#### 594 5.1 Advanced design support opportunities

595 In both research and engineering practice, it is increasingly common to extend BPS studies with  
596 more advanced analysis techniques such as uncertainty propagation and sensitivity analysis  
597 methods (Clarke and Hensen 2015). Although the number of reports on the application of this  
598 type of analysis in combination with adaptive facades is still limited, there is potential for  
599 considerable progress also in this domain. Sensitivity analysis methods can be useful to identify  
600 the envelope design variables that have the largest influence on relevant building performance  
601 indicators (Tian 2013). Uncertainty analysis methods can additionally be used to make better-

602 informed decisions by gaining in-depth understanding of the robustness of a particular adaptive  
603 facade design option with respect to possible scenarios regarding e.g. weather conditions and  
604 occupant behavior (Hopfe and Hensen 2011). Purposely-developed approaches such as dynamic  
605 sensitivity analysis can be helpful to deal with the time-varying features of adaptive facade  
606 problem configurations (Loonen and Hensen 2013).

607 Computational optimization is a second example of advanced design support that can assist in  
608 the performance assessment and design selection of adaptive building envelopes, as well as  
609 support the development and virtual prototyping of innovative adaptive facade technologies. The  
610 coupling of optimization algorithms with BPS tools allows for structured design space  
611 explorations that can help designers to find the most promising design solutions among the  
612 many possible alternatives (Evins 2013; Attia et al. 2013). Due to the close interaction between  
613 design and operational aspects of adaptive building envelopes, setting up the optimization  
614 formulation is a challenging task that requires novel approaches and further research (Favoino,  
615 Overend, and Jin 2015; Kasinalis et al. 2014).

### 616 5.2 Parametric and generative design tools

617 The work presented in this article has mostly focused on the use of BPS as a tool for  
618 performance analysis. Recently, however, there is a growing interest in the use of these tools for  
619 performance-based generative design and architectural form finding (Shi and Yang 2013). These  
620 applications, mostly driven by dedicated plug-ins that interface BPS programs with CAD tools  
621 such as Rhinoceros and Revit, can also have potential when applied to design of adaptive,  
622 especially kinetic facades. Existing work in this field has mostly addressed daylight aspects and  
623 innovative solar shading solutions (González and Fiorito 2015; Sharaidin, Burry, and Salim 2012).  
624 Future research could extend the scope to other performance aspects, and focus more on the  
625 design opportunities that the introduction of adaptive building envelopes brings along.

### 626 5.3 Co-simulation

627 Co-simulation is a simulation strategy in which two or more simulators solve systems of coupled  
628 equations, by exchanging data during simulation run-time (Trcka, Hensen, and Wetter 2009).

629 This strategy could become particularly important for performance prediction of adaptive  
630 building envelope systems, as it promotes opportunities for (i) integrating the simulations over  
631 different interrelated physical domains using different coupled tools, (ii) evaluating emerging  
632 technologies for which models may not be directly available in the specific BPS tool used, and (iii)  
633 assessing the potential of advanced control strategies of adaptive building envelope systems in  
634 specialised control-oriented software. The co-simulation functionality can be enabled by means  
635 of middleware software, such as BCVTB (Wetter 2011b). An alternative development relates to the  
636 functional mock-up interface (FMI), which promises to make the coupling between building  
637 simulation tools even more flexible and versatile. (Nouidui, Wetter, and Zuo 2013)

#### 638 5.4 Next-generation simulation tools

639 Whereas co-simulation tries to leverage and reuse the capabilities of existing simulation  
640 programs, there are also significant ongoing research efforts that aim at reconceiving BPS  
641 modeling approaches from the bottom up. At the center of these developments are the  
642 simulation libraries based on the Modelica modeling language (Wetter 2009). Within  
643 International Energy Agency (IEA) EBC Annex 60 *New generation computational tools for building  
644 and community energy systems based on the Modelica and Functional Mockup Interface standards*,  
645 these developments are coordinated at an international level. Modelica provides an equation-  
646 based, object-oriented approach that has potential to make modeling and simulation of complex  
647 building systems faster and more flexible. In the context of adaptive facades, it allows for high-  
648 resolution multi-domain analysis, rapid extension of modeling capabilities, as well as smooth  
649 interactions with other building-integrated energy systems. However, the development of  
650 Modelica for building performance simulation has not yet reached a mature phase. More  
651 research is needed to improve e.g. the robustness of component models, the interface with  
652 design tools, and simulation speed.

## 653 **6 Acknowledgments**

654 The authors would like to thank EU Cost Action TU1403 “Adaptive Facades Network” for  
655 providing excellent research networking. The Dutch authors acknowledge the support from RVO

656 EOSLT08016 project FACET. The British authors would like to acknowledge the support from  
657 EPSRC and project RG70518, funded by Wintech ltd.

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923

924 **Appendix A**

925 This appendix aims to provide a more comprehensive explanation of the general-purpose  
926 modelling capabilities and control options available in each of the BPS tools analyzed. By means  
927 of this appendix readers could investigate whether the specific BPS tool is suitable for their  
928 modelling purpose, if an application-oriented option is not available in the user interface already.

929 **A.1 EnergyPlus**

930 EnergyPlus is a modular whole building energy simulation program based on the best features  
931 and capabilities of BLAST and DOE-2.1, developed under auspices of the US Department of  
932 Energy. Its modular structure was designed in order to integrate different simulation engines  
933 (building loads and systems) and models (i.e. heat and mass balance, thermal comfort, daylight,  
934 advanced fenestration, etc.). One of the main goals for developing this tool was to enhance the  
935 possibility of adding and validating new models. Thanks to this feature, different modelling  
936 capabilities have been included into EnergyPlus so far, which is reflected by the high number of  
937 releases from the first one (currently at version 8.3). This has enabled the implementation of  
938 application-oriented modelling capabilities for different technologies, which was presented in  
939 the previous section. Recently, EnergyPlus Runtime Language (ERL) was added to EnergyPlus  
940 (Ellis, Torcellini, and Crawley 2007) in order to replicate a building Energy Management System  
941 (EMS) in the simulation tool. The system is based, as in the real world, on the same elements of an  
942 EMS (sensors, control logics/algorithms and actuators). Since the latest release of the EMS  
943 system (US DOE 2015a), new actuators were introduced that enable control of thermo-optical  
944 properties at the building envelope level. The available actuators are able to control different  
945 building envelope adaptive components and properties, such as window shading devices, slat  
946 angle of the shading device, surface heat transfer coefficients, material surface properties,  
947 surface construction state (material construction properties), and surface boundary conditions.  
948 Moreover, any schedulable action in EnergyPlus can be controlled by means of an actuator  
949 within the EMS. A control algorithm can be designed in the EMS by means of IF-ELSE statements  
950 and simple algebraic operations, adopting the ERL programming language. The control algorithm  
951 can be used to control any actuator, based on data from sensors (wherein any output of

952 EnergyPlus can potentially be treated as such). For example the surface construction state  
953 actuator can be used to simulate variable thermo-optical properties: different constructions can  
954 be created, characterised by different thermo-physical properties, to be used in sequence  
955 according to a user-defined control algorithm (Favoino, Overend, and Jin 2015). However the  
956 different constructions are required to have similar thermal capacity due to limitations of the  
957 solution routines for the transient conduction through the building envelope elements adopted  
958 in EnergyPlus (US DOE 2015a). The EMS can be used to simulate controllable building envelope  
959 properties, also of technologies for which a model is not available yet, or to implement more  
960 advanced control strategies which are not available in EnergyPlus as hard-coded presets.  
961 Moreover the EMS could be used to overcome some limitation at integrating smart glazing  
962 control with the simulation of artificial lighting systems control (Favoino and Overend 2015). In  
963 fact it is not possible to simulate the control of the lighting systems for intermediate states of  
964 the smart glazing, when using the application-oriented modelling approach.

965 Due to the relatively new development, few documented applications of the use of EMS to model  
966 adaptive building envelope systems are available in literature. Moreover little evidence was  
967 found in literature about the reliability of the EMS modelling approach when applied to dynamic  
968 building envelope components. Although for the specific case of modelling smart glazing,  
969 negligible differences exist between the application-oriented model and the general-purpose  
970 one by means of the EMS modelling approach (Favoino et al. 2015).

## 971 A.2 ESP-r

972 ESP-r is a multi-domain research-oriented BPS tool with an active development community and  
973 a source code that is accessible and modifiable. Over the course of the years, several  
974 functionalities that can be used to model adaptive behavior in the building shell have been  
975 implemented by various research groups. Nevertheless, the use of these capabilities has  
976 remained limited, possibly because the features are (i) not well-documented or (ii) concealed  
977 somewhere in the distributed menu-structure of ESP-r. This section summarises five of such  
978 features:

979 One of the control laws in ESP-r is called *thermo-physical property substitution mode*. It is the  
980 only strategy that is not used for controlling the operation of HVAC systems. Instead of this, this  
981 control strategy can replace the thermo-physical properties ( $\lambda$ ,  $c_p$ ,  $\rho$ ) of a construction during the  
982 course of the simulation. In essence, this control works like any other control algorithm in ESP-r,  
983 in the way that actions are triggered based on ‘tests’ applied to sensed variables during run-time  
984 (MacQueen 1997). Unfortunately, this feature does not allow for full flexibility since it only affects  
985 opaque wall elements and the only ‘sensor variable’ is indoor air temperature.

986 The previous feature dealt with opaque construction elements only, however, ESP-r also has a  
987 similar functionality available for modeling dynamic behavior of windows; transparent multi-  
988 layer construction control. This functionality can for example be used for performance  
989 prediction of switchable glazing technologies. Currently it is possible to replace window  
990 properties (.tmc-files) based on time, temperature, solar radiation level or illuminance level.  
991 Restrictions are that no more than two window states are supported without the possibility for  
992 gradual transitions. Recently, the capabilities of ESP-r have been further extended with the  
993 implementation of two new facilities for modeling transparent facade systems. Both the complex  
994 fenestration constructions (CFC) (Lomanowski and Wright 2012) and the advanced optics (Kuhn  
995 et al. 2011) module have powerful options for facade systems with dynamic fenestration  
996 properties.



997 In ESP-r, the *special materials* facility was introduced to model 'active building elements' (Evans  
998 and Kelly 1996). This universal functionality may be applied to any node within a multi-layer  
999 construction. The *special material* subroutines can actively modify the matrix coefficients of  
1000 these specific nodes at every time-step. By doing this, it directly changes basic thermo-physical  
1001 or optical properties and/or the associated energy flows at the equation-level, based on the  
1002 respective physical relationships. Currently, the following special materials are implemented:  
1003 building-integrated photovoltaics, ducted wind turbines, solar thermal collectors,  
1004 thermochromic glazing, evaporating surfaces and phase change materials. It is possible to add  
1005 new user-defined special materials; however this may require time-intensive programming  
1006 work.

1007 ESP-r offers the unique possibility to use *roaming files*. This facility is used to change the  
1008 location of a building as a function of time, and was originally intended to be used for cruise  
1009 ships. Because this roaming file not only includes coordinates but also orientation of the zone, it  
1010 is very well suited for simulation of rotating buildings.

1011 Nakhi (1995) introduced variable thermo-physical properties in ESP-r with the aim to model heat  
1012 transfer in building slabs in a more accurate way. The model takes into account that the  
1013 properties of most construction materials are not constant, but change as a function of  
1014 temperature and/or moisture content. This dependency is implemented via transient thermo-  
1015 physical material properties ( $\lambda$ ,  $c_p$ ,  $\rho$ ) that are linear or polynomial functions of layer temperature  
1016 or moisture content. The same functionality can be used to model certain types of adaptive  
1017 building envelopes.

### 1018 A.3 IDA ICE

1019 IDA Indoor Climate and Energy (IDA ICE) is a flexible, whole-building performance simulation  
1020 tool that is mostly used in Nordic and Central European countries. It covers multiple physical  
1021 domains, including models for building envelope heat transfer, flow networks, daylight  
1022 illuminance and energy systems analyses. IDA ICE works with symbolic equations instead of  
1023 variable assignments (as most other BPS tools do), and therefore it is relatively easy to extend

1024 the existing modeling functionality. For example, the finite-difference multi-layer wall model  
1025 “fdwall” was recently extended with a new model “fdwalldyn” that allows for time-varying  
1026 thermo-physical properties. The tool has both a standard and advanced level interface. This  
1027 enables a separation of concerns where expert users can implement adaptive features and  
1028 control strategies directly into the mathematical model using the latter approach. Especially the  
1029 possibility to define custom *control macros* is a useful feature in the context of adaptive facades,  
1030 as it enables simulation users to control the operation of various building systems, facade  
1031 actuators included.

#### 1032 A.4 IES VE

1033 Integrated Environment Solutions Virtual Environment is a consultancy oriented software,  
1034 integrating different calculation modules in a comprehensive user interface. It integrates tools  
1035 for thermal, airflow and daylight analysis, computational fluid dynamics (CFD), value engineering,  
1036 cost planning, life-cycle and occupant safety analysis. This modularity allows to integrate  
1037 building performance analysis in multiple domains (i.e. thermal, airflow and daylight). Although  
1038 the daylight analysis can only be used in the thermal module to evaluate the effect of dimmable  
1039 artificial lights, but not to control shading devices or smart glazing technologies. While the CFD  
1040 module can only use the results from the thermal analysis as boundary conditions and not vice-  
1041 versa.

1042 IES VE is a commercial program. Its code is not accessible and the user cannot add any  
1043 additional simulation modules to enhance either application-oriented or general-purpose  
1044 modelling capabilities. This limits the application of IES VE to application-oriented models  
1045 already included in the software and to some alternative approaches described in Section 4.3 or  
1046 approximate solutions such as for PCMs (Kendrick and Walliman 2007).

1047 Despite the limitations, a useful feature is found in the time-schedule module APpro. It enables  
1048 simulation of rule-based control of a building system and of the adaptive building envelopes  
1049 available (shading devices, cavity ventilation, electro-chromic glazing, etc.), even though it is  
1050 limited by the availability of sensors. In fact only some of the software inputs and outputs can be  
1051 used (cf. Table 6).

1052 A.5 TRNSYS

1053 The approach that TRNSYS takes towards managing complexity in the built environment is  
1054 characterised by breaking down the problems into a series of smaller components. One of these  
1055 components is a multi-zone building model – TYPE 56 – that can be connected to a large  
1056 number of other components, including: weather data, HVAC systems, occupancy schedules,  
1057 controllers, output functions, thermal energy storage, renewable (solar) energy systems, etc.  
1058 This particular configuration allows the user to set up and manipulate the connections between  
1059 the building and various other subsystems/components in the simulation environment.

1060 TRNSYS TYPE 56 offers the possibility to change the thermal and optical window properties  
1061 during run-time with a function called *variable window ID*. Additionally, it is also possible to  
1062 control the ratio of window/frame area which influences the degree of transparent facade  
1063 elements. In the near future, TRNSYS will be extended with a bi-directional scattering  
1064 distribution function (BSDF) that can be changed at every time step of the simulation (Hiller and  
1065 Schöttl 2014). All the other adaptive mechanisms in TRNSYS are not found in the (non-  
1066 modifiable) building model itself, but in the connections with other components. Using *equations*  
1067 in TRNSYS enables the application of Boolean logic and algebraic manipulations to almost all  
1068 state variables in the simulation. This flow of information can then be used to drive a control  
1069 algorithm that is able to dynamically ‘switch on’, ‘switch off’ or modulate e.g., overhangs and  
1070 wingwalls (TYPE 34), shading masks (TYPE 64), attached sunspaces (with or without movable  
1071 thermal insulation) (TYPE 37), windows with variable insulation properties (TYPE 35) and  
1072 photovoltaic modules (TYPES 94, 180 and 194). In addition, it is also possible to adjust the  
1073 connections with weather files and radiation processors. In this way, the effects of changing  
1074 orientations (e.g. rotating buildings) can be mimicked. Even more control flexibility can be  
1075 achieved by connecting TRNSYS models to the W-editor (Type 79) (Keilholz et al. 2009). Type 79  
1076 makes use of W, a simple programming language that can influence the connection between the  
1077 inputs and outputs of TRNSYS components at every iteration of the simulation.

1078 The standard TRNSYS distribution already comes with an extensive library of components. Yet,  
1079 one of the distinct benefits of TRNSYS’ modular structure is the fact that it allows users to add

1080 content by introducing new components (McDowell et al. 2004). With some coding efforts it is  
1081 possible to encapsulate the desired adaptive behavior in a new TRNSYS TYPE which can then be  
1082 linked to the building model. Due to constraints in TRNSYS' CTF method, coupling of these new  
1083 TYPES with the building envelope model works in a rather indirect way via the so-called 'slab-  
1084 on-grade approach'. In TRNSYS it is not possible to substitute building shell  
1085 constructions/properties during simulation run-time. Instead, developers can impose the  
1086 desired behavior by overwriting the inside surface layer temperatures of adjacent zones and the  
1087 respective heat transfer coefficients. With respect to adaptive facades, Kuznik et al. (2010) and  
1088 Claros-Marfil et al. (2014) recently demonstrated this approach for a new PCM wallboard TYPE,  
1089 and Djedjig et al. (2015) developed a model for green walls.

1090