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# A numerical solution for heat transfer past a stretching sheet with ohmic dissipation and suction or injection problem using Haar wavelet quasilinearization method 

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#### Abstract

This paper represents a numerical analysis for heat transfer of a Jeffrey fluid flow past a stretching sheet with ohmic dissipation and suction/injection. The partial differential equations are reduced into a set of convenient nonlinear ordinary differential equations with the boundary conditions. Haar wavelet quasilinearization method (HWQM) is used to solve ordinary differential equations. The effect of various related parameters on velocity and temperature profiles are computed and analyzed. Then, comparison is made between the numerical results of proposed method with existing numerical solutions found in the literature, and reasonable agreement is noted.


## 1. Introduction

The boundary layer flows induced by a stretching sheet has great importance in the aerodynamic extrusion of plastic sheets, crystal growing, continuous casting, cooling of metallic plate in a bath, glass fiber and paper production, the boundary layer along a liquid film in the condensation process and many others [1]. Such consideration in the presence of heat transfer has central role in the polymer industry. An exact analytic solution for the two dimensional boundary layer flow of viscous fluid over a linearly stretching surface was firstly presented by Crane [2]. Later, this problem has been extensively examined through various aspects such as suction/blowing, stretching velocities, magnetohydrodynamics, heat/ mass transfer and so on. Further, the addition of heat generation/absorption term in energy expression is very important in the cases involving underground disposal of radioactive waste material, storage of food stuffs, heat removal from nuclear fuel fragments and packed bed reactors. Some of the studies on such effects can be seen in Ref. [1, 3-7].

Related to the presence of suction/injection, Vajravelu [8] has applied variable size of finite difference method for solving the convection flow and heat transfer of a viscous fluid near an infinite, porous and vertical stretching surface. Muthucumaraswamy [9] studied the effects of suction on heat and mass transfer along a moving vertical surface in the presence of chemical reaction. El-Arabawy [10] investigated the effects of suction/injection and chemical reaction on mass transfer over a stretching surface. Elbashbeshy and Bazid [11] have analyzed the effect of internal heat generation and suction or injection on the heat transfer in a porous medium over a stretching surface. Sultana et al. [12] discussed the effects of internal heat generation, radiation and suction or injection on the heat transfer in a porous
medium over a stretching surface. Rajeswari et al. [13] studied the effect of chemical reaction, heat and mass transfer on nonlinear MHD boundary layer flow through vertical porous surface with heat source in the presence of suction. Elbashbeshy et al. [14] used Runge-Kutta technique to study the effects of suction/injection and variable chemical reaction on mass transfer characteristics over unsteady stretching surface embedded in porous medium. Kumari and Nath [15] analyzed the significant results for heat transfer on a thin vertical cylinder in the presence of suction/injection. Siri et al. [16] studied the boundary layer flow of Maxwell fluid past a stretching surface in the presence of suction/injection using two different approaches, HWQM and RK Gill method. Some research were purposed, in Ref. [17-21] to examine the impact of suction/injection during the flow of a fluid in the case of different geometries. Later, many researchers [22-27] investigated the influences of ohmic and viscous dissipation on nanofluid flow under diverse conditions.

Based on our literature study, no research has been made so far to study suction/injection on a Jeffrey fluid flow past a steady stretching sheet by using our proposed method. The non-dimensionalized partial differential equations (PDEs) [28] were transformed into the ordinary differential equations (ODEs) and solved numerically by employing the HWQM. Chen and Hsiao [29] led the work using Haar wavelet to solve system analysis. They solved the lumped and the distributed-parameters systems using Haar operational matrix derived from an integration of Haar function. Later, numerous numerical method studies based on the Haar wavelet was conducted when solving differential and integral equations, partial differential equation, fractional calculus, hyperbolic heat conduction problem and finding numerical inversion of Laplace transform [30]. Recently, HWQM has been adopted to solve fractional non-linear equation, Burgers equation, and Cattaneo Christov heat flux problem [30]. For solving the nonlinear and PDEs, Bellman and Kalaba [31] proposed the quasilinearization method which is based on the Newton Raphson method.

## 2. Mathematical formulation

A steady two-dimensional boundary layer flow of an incompressible Jeffrey fluid flow over an impermeable stretched sheet with the presence of suction/injection is considered. Noted that the flow is generated by stretching the boundary sheet from a slit by commanding two equal and opposite forces. The flow region is exposed under uniform transverse magnetic fields $\vec{B}=\left(0, B_{0}, 0\right)$ and uniform electric field $\vec{E}=\left(0,0,-E_{0}\right)$, for which satisfies the Maxwell's equation, such that $\nabla \cdot \vec{B}=0$ and $\nabla \cdot \vec{E}=0$. If the magnetic field is not strong enough, the electric and magnetic field follow the Ohm's law, $\vec{J}=$ $\sigma(\vec{E}+\vec{q} \times \vec{B})$, where $\vec{J}$ is the Joule current, $\sigma$ is the magnetic permeability and $\vec{q}$ is the fluid velocity. Under the above stated assumptions, the governing boundary layer equations for momentum and energy are [28]

$$
\begin{align*}
& \frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}=0,
\end{align*} \begin{array}{r}
\begin{array}{r}
\text { Error! } \\
\text { Bookmark } \\
\text { not }
\end{array} \\
u \frac{\partial u}{\partial x}+v \frac{\partial u}{\partial y}= \\
\frac{V}{1+\lambda_{1}}\left[\frac{\partial^{2} u}{\partial y^{2}}+\lambda_{2}\left(u \frac{\partial^{3} u}{\partial x \partial y}-\frac{\partial u}{\partial x} \frac{\partial^{2} u}{\partial y^{2}}+\frac{\partial u}{\partial y} \frac{\partial^{2} u}{\partial x \partial y}+v \frac{\partial^{3} u}{\partial y^{3}}\right)\right]+\frac{\sigma E_{0} B_{0}}{\rho}- \\
\frac{\sigma B_{0}^{2}}{\rho} u,
\end{array} \begin{array}{r}
\text { Error! } \\
u \frac{\partial T}{\partial x}+v \frac{\partial T}{\partial y}=\frac{k}{\rho c_{p}} \frac{\partial^{2} T}{\partial y^{2}}+\frac{\mu}{\rho c_{p}}\left(\frac{\partial u}{\partial y}\right)^{2}+\frac{\sigma}{\rho c_{p}}\left(u B_{0}-E_{0}\right)^{2} \tag{3}
\end{array}
$$

The velocity components along the $x$ and $y$ directions are denoted as $u$ and $v$, respectively. $V$ is the kinematic viscosity, $\lambda_{1}$ is the fluid relaxation time, $\lambda_{2}$ is the thermal relaxation time, $T$ is the fluid
temperature, $k$ is the thermal conductivity, $\rho$ is fluid density, $\mu$ is the dynamic viscosity and $c_{p}$ is the specific heat at constant pressure.

The boundary conditions in the present problem are

$$
\begin{array}{lr}
u=a x, \quad v=v_{0}, \quad T=T_{w} \text { at } y=0, & \begin{array}{r}
\text { Error! } \\
\text { Bookmark } \\
\text { not }
\end{array} \\
u \rightarrow 0, \frac{\partial u}{\partial y} \rightarrow 0, T \rightarrow T_{\infty} \text { as } y \rightarrow \infty & \text { defined.(4) }
\end{array}
$$

In the Eqn. (4), $v_{0}$ represents the velocity of suction/injection at the wall, $T_{w}$ is the temperature at the wall, and $T_{\infty}$ is the ambient fluid temperature.

By using these similarity transformation,

$$
\eta=\sqrt{\frac{a}{V}} y, \quad \psi=\sqrt{a V} x f(\eta), \quad \theta=\left(\frac{T-T_{\infty}}{T_{w}-T_{\infty}}\right) \quad \begin{array}{r}
\text { Error! } \\
\text { Bookmark } \\
\text { not } \\
\text { defined.(1) }
\end{array}
$$

in which $\psi$ is the stream function defined in the $u=\frac{\partial \psi}{\partial y}$ and $v=-\frac{\partial \psi}{\partial x} \cdot \eta$ is the similarity variable, $f$ and $\theta$ are the dimensionless stream function and dimensionless temperature, respectively, Eqns. (2) and (3) can be reduced to a system ODEs as follows:

$$
\begin{aligned}
& f^{\prime \prime \prime}(\eta)-(1+\lambda)\left(f^{\prime 2}(\eta)-f(\eta) f^{\prime \prime}(\eta)-H a^{2}\left(E_{1}-f^{\prime}(\eta)\right)\right)+ \\
& \quad \beta\left(f^{\prime \prime 2}(\eta)-f(\eta) f^{i v}(\eta)\right)=0, \\
& \theta^{\prime \prime}(\eta)+\operatorname{Pr}\left(f(\eta) \theta^{\prime}(\eta)-2 f^{\prime}(\eta) \theta(\eta)\right)+ \\
& \quad \operatorname{Pr} E_{c} f^{\prime \prime 2}(\eta) \operatorname{Pr} E_{c} H a^{2}\left(f^{\prime 2}(\eta)-2 E_{1} f^{\prime}(\eta)+E_{1}^{2}\right)=0,
\end{aligned}
$$

$$
\begin{array}{r}
\text { Error! } \\
\text { Bookmark } \\
\text { not } \\
\text { defined.(2) } \\
\text { Error! } \\
\text { Bookmark } \\
\text { not } \\
\text { defined.(3) }
\end{array}
$$

and the transformed boundary conditions (4) are

$$
\begin{array}{lr}
\eta=0: f=s, f^{\prime}=1, \quad \theta=1 \\
\eta \rightarrow \infty: f^{\prime} \rightarrow 0, f^{\prime \prime} \rightarrow 0, \quad \theta \rightarrow 0 . & \begin{array}{r}
\text { Error! } \\
\text { Bookmark } \\
\text { not }
\end{array} \\
\text { defined.(4) }
\end{array}
$$

The Prandtl number is given as $\operatorname{Pr}=\frac{\mu c_{p}}{k}$, Eskert number, $E c=\frac{a^{2} l^{2}}{A c_{p}}$, Hartmann number, $H a=\sqrt{\frac{\sigma}{\rho a}} B_{0}$ and the local electrical parameter is given as $E_{1}=\frac{E_{0}}{B_{0} a x}$. The suction parameter is $s=-\frac{v_{0}}{\sqrt{c v}}$, where $c$ is a positive constant, $s>0$ (suction), $s<0$ (injection) and $s=0$ (impermeable surface).

## 3. Numerical solutions

This section presents the Haar wavelet quasilinearization method (HWQM) for solving nonlinear ODEs (6) - (8). Wavelet methods became a requisite mathematical tool in many investigations and have numerous applications including finding an approximate solution of differential equations. Among prominent wavelet basis used in numerical methods are Chebyshev-, Legendre-, Haar-, and Meyerwavelets. However, the Haar wavelet has caught special attention for the reason that it is the simplest orthogonal wavelet. Other beneficial features using Haar wavelet basis are discussed in Refs. [32-34].

### 3.1 Haar wavelets

The Haar scaling function for $\eta \in[0, X]$ is defined as

$$
h_{0}(\eta)=\left\{\begin{array}{lrr}
1, & 0 \leq \eta<X, & \text { Error! } \\
0, & \text { elsewhere in }[0, X), & \text { Bookmark } \\
\text { not } \\
\text { defined.(9) }
\end{array}\right.
$$

and corresponding Haar wavelet function

$$
h_{i}(\eta)=\left\{\begin{array}{llr}
1 & \frac{k X}{2^{\alpha}} \leq \eta<X & \text { Error! } \\
-1 & \frac{(k+1 / 2) X}{2^{\alpha}} \leq \eta<\frac{(k+1) X}{2^{\alpha}} & \begin{array}{r}
\text { Eorkar } \\
\text { not }
\end{array} \\
0 & \text { elsewhere in }[0, X), & \text { defined. }(10)
\end{array}\right.
$$

where $i=1,2, \ldots, m-1$ is the series index number and the resolution $m=2^{J}$ is a positive integer and $J$ is the maximum level of resolution. In Eqn. (10), $\alpha$ and $k$ represent the integer decomposition of the index $i$, i.e. $i=2^{\alpha}+k$ in which $\alpha=0,1, \ldots, J-1$ and $k=0,1, \ldots, 2^{\alpha}-1$.

In the Haar wavelet method, the following integrals are used

$$
\begin{array}{lr}
p_{i, j}(\eta)=\int_{0}^{\eta} h_{i}\left(\eta^{\prime}\right) d \eta^{\prime}, & \begin{array}{r}
\text { Error! } \\
\text { Bookmark } \\
\text { not }
\end{array} \\
& \begin{aligned}
\text { defined. }(11) \\
\text { Error! }
\end{aligned} \\
p_{i, j+1}(\eta)=\int_{0}^{\eta} h_{i, j}\left(\eta^{\prime}\right) d \eta^{\prime} \text { where } j=1,2,3 \ldots . & \text { Bookmark } \\
& \text { defined. }(12)
\end{array}
$$

The generalized Haar wavelet and its integration are derived and modified, hence the expansion of Haar series could be between zero to a number greater than one. It is a great help due to the boundary value problem always dealing with sufficiently a large interval $[0, X)$. Any square integrable function $f \in L^{2}[0, X]$ can be decomposed into a linear combination of Haar basis and can be written as

$$
f(\eta)=\sum_{i=0}^{\infty} c_{i} h_{i}(\eta)
$$

## Error! <br> Bookmark not <br> defined.(13)

where the Haar coefficients, $c_{i}$ can be obtained from

$$
c_{i}=\frac{2^{\alpha}}{X} \int_{0}^{X} f(\eta) h_{i}(\eta) d \eta . \quad \begin{array}{r}
\text { Error! } \\
\text { Bookmark } \\
\text { not } \\
\text { defined.(14) }
\end{array}
$$

The above series terminates at finite terms if $f(\eta)$ may be approximated as piecewise constant during each subinterval.

### 3.2 Quasilinearization method

The nonlinear boundary value problems ( BVPs ) is linearized in the quasilinearization method. Hence, it forms a series of equations, which is typically convergence in nature [ $31,35,36$ ].

We consider a nonlinear boundary value problems of second order differential equation,

$$
\theta^{\prime \prime}(\eta)=f\left(\theta^{\prime}(\eta), \theta(\eta), \eta\right)
$$

Error!<br>Bookmark not<br>defined.(15)

subject to boundary conditions,

|  |  |
| :--- | :--- |
| $\theta^{\prime}(a)=\kappa, \quad$ and | Error! <br> Bookmark <br> not |
|  |  |
| $\theta(b)=\tau, \quad a \leq \eta \leq b$, | defined.(16) |
| Error! |  |
|  | Bookmark |
| not |  |

where $f$ is a nonlinear differentiable function. Let $\theta_{0}(\eta)$ be an initial approximation of the function $\theta(\eta)$. The Taylor series expansion of f around $\theta_{0}(\eta)$ is

$$
\begin{array}{lr}
f\left(\theta^{\prime}(\eta), \theta(\eta), \eta\right)= & \text { Error! } \\
f\left(\theta_{0}^{\prime}(\eta), \theta_{0}(\eta), \eta\right)+\left(\theta_{(\eta)}-\theta_{0}(\eta)\right) f_{\theta_{0}}\left(\theta_{0}^{\prime}(\eta), \theta_{0}(\eta), \eta\right)+ & \text { Bookmark } \\
\quad\left(\theta^{\prime}(\eta)-\theta_{0}^{\prime}(\eta)\right) f_{\theta_{0}^{\prime}}\left(\theta_{0}^{\prime}(\eta), \theta_{0}(\eta), \eta\right) & \text { not } \\
\text { defined.(18) }
\end{array}
$$

where the function $f_{\theta}\left(\theta^{\prime}(\eta), \theta(\eta), \eta\right)=\partial f / \partial \theta$ and $f_{\theta^{\prime}}\left(\theta^{\prime}(\eta), \theta(\eta), \eta\right)=\partial f / \partial \theta^{\prime}$. Ignoring the second order and higher order terms in Equation (18). Then Eqn. (18) in Eqn. (15) yields

$$
\begin{array}{lr}
\theta^{\prime \prime}(\eta)= & \text { Error! } \\
f\left(\theta_{0}^{\prime}(\eta), \theta_{0}(\eta), \eta\right)+\left(\theta_{(\eta)}-\theta_{0}(\eta)\right) f_{\theta_{0}}\left(\theta_{0}^{\prime}(\eta), \theta_{0}(\eta), \eta\right)+ & \text { Bookmark } \\
\left(\theta^{\prime}(\eta)-\theta_{0}^{\prime}(\eta)\right) f_{\theta_{0}^{\prime}}\left(\theta_{0}^{\prime}(\eta), \theta_{0}(\eta), \eta\right) . & \text { not } \\
\text { defined. }(19)
\end{array}
$$

By solving Eqn. (19) for $\theta(\eta)$ and call it $\theta_{1}(\eta)$. Using $\theta_{1}(\eta)$ and again expanding Eqn. (15) about $\theta_{1}(\eta)$ yields

$$
\begin{aligned}
& \theta^{\prime \prime}(\eta)= \\
& \quad f\left(\theta_{1}^{\prime}(\eta), \theta_{1}(\eta), \eta\right)+\left(\theta_{(\eta)}-\theta_{1}(\eta)\right) f_{\theta_{1}}\left(\theta_{1}^{\prime}(\eta), \theta_{1}(\eta), \eta\right)+ \\
& \quad\left(\theta_{\eta}^{\prime}(\eta)-\theta_{1}^{\prime}(\eta)\right) f_{\theta_{1}^{\prime}}\left(\theta_{1}^{\prime}(\eta), \theta_{1}(\eta), \eta\right) .
\end{aligned}
$$

## Error!

Bookmark not
defined.(50)
And the third approximation for $\theta(\eta)$, and call it $\theta_{2}(\eta)$. Assuming that the problem converges and in general, the recurrence relation can be written as

$$
\begin{aligned}
& \theta_{r+1}^{\prime \prime}(\eta)= \\
& \quad f\left(\theta_{r}^{\prime}(\eta), \theta_{r}(\eta), \eta\right)+\left(\theta_{r+1}(\eta)-\theta_{r}(\eta)\right) f_{\theta_{r}}\left(\theta_{r}^{\prime}(\eta), \theta_{r}(\eta), \eta\right)+ \\
& \quad\left(\theta_{r+1}^{\prime}(\eta)-\theta_{r}^{\prime}(\eta)\right) f_{\theta_{r}^{\prime}}^{\prime}\left(\theta_{r}^{\prime}(\eta), \theta_{r}(\eta), \eta\right),
\end{aligned}
$$

$$
\begin{array}{r}
\text { Error! } \\
\text { Bookmark } \\
\text { not } \\
\text { defined.(21) }
\end{array}
$$

with $r=0,1,2, \ldots$ is number of iteration with

$$
\begin{array}{lrr} 
& \text { Error! } \\
\theta_{r+1}^{\prime}(a)=\kappa, \quad \text { and } & \text { Bookmark } \\
& \text { not } \\
& \text { defined. } 22 \text { ) } \\
& \text { Error! } \\
\theta_{r+1}(b)=\tau . & \text { Bookmark } \\
& \text { not } \\
& \text { defined. } 23)
\end{array}
$$

Eqn. (21) is all the time a linear and can be computed recursively using the Haar series [37]. The details of convergence for this method can be referred to in literature [35, 36].

Post quasilinearization of the Eqns. (6) and (7), yields

## Error!

$$
\alpha_{1, r} f_{r+1}^{(i v)}+\alpha_{2, r} f_{r+1}^{\prime \prime \prime}+\alpha_{3, r} f_{r+1}^{\prime \prime}+\alpha_{4, r} f_{r+1}^{\prime}+\alpha_{5, r} f_{r+1}=R_{1}
$$

## Bookmark

 notdefined.(24)
Error!

$$
\beta_{1, r} f_{r+1}^{\prime \prime}+\beta_{2, r} f_{r+1}^{\prime}+\beta_{3, r} f_{r+1}+\beta_{4, r} \theta_{r+1}^{\prime \prime}+\beta_{5, r} \theta_{r+1}^{\prime}+\beta_{6, r} \theta_{r+1}=R_{2}
$$

## Bookmark

 notdefined.(25)
where

$$
\begin{aligned}
& \alpha_{1, r}=\beta f_{r}^{2} \\
& \alpha_{2, r}=-f_{r}, \\
& \alpha_{3, r}=-f_{r}\left(f_{r}+\lambda f_{r}+2 \beta f_{r}^{\prime \prime}\right), \\
& \alpha_{4, r}=f_{r}\left(2 f_{r}^{\prime}+H a^{2}+2 \lambda f^{\prime}+\lambda H a^{2}\right), \\
& \alpha_{5, r}=f_{r}^{\prime \prime \prime}-(1+\lambda) f_{r}^{\prime 2}+(1+\lambda) H a^{2} E_{1}-H a^{2} f_{r}^{\prime}, \\
& \beta_{1, r}=2 \operatorname{Pr} E c f_{r}^{\prime \prime}, \\
& \beta_{2, r}=2 \operatorname{Pr}\left(-\theta_{r}+E c H a^{2}\left(f_{r}^{\prime}-E_{1}\right)\right), \\
& \beta_{3, r}=\operatorname{Pr} \theta_{r}^{\prime} \\
& \beta_{4, r}=1 \\
& \beta_{5, r}=\operatorname{Pr} f_{r}, \\
& \beta_{6, r}=-2 \operatorname{Pr} f_{r}^{\prime}, \\
& R_{1}=2 H a^{2} E_{1} f_{r}(1+\lambda)+f_{r}\left(f_{r}^{\prime \prime \prime}-(1+\lambda) H a^{2} f_{r}^{\prime}\right), \\
& R_{2}=\operatorname{Pr} E c\left(f_{r}^{\prime \prime 2}+H a^{2}\left(f_{r}^{\prime 2}-E_{1}^{2}\right)\right)+\operatorname{Pr}\left(\theta_{r}^{\prime} f_{r}-2 \theta_{r} f_{r}^{\prime}\right)
\end{aligned}
$$

The boundary conditions are at

$$
\begin{aligned}
& \eta=0: \quad f_{r+1}=s, \quad f_{r+1}^{\prime}=1, \quad \theta_{r+1}=1 \\
& \eta \rightarrow \infty: \quad f_{r+1}^{\prime} \rightarrow 0, \quad f_{r+1}^{\prime \prime} \rightarrow 0, \quad \theta_{r+1} \rightarrow 0
\end{aligned}
$$

Error! Bookmark not defined.

Error!
Bookmark
defined.
Haar wavelet method is applied to Eqns. (24) and (25), we get

$$
\begin{aligned}
& f_{r+1}^{(i v)}(\eta)=\sum_{i=0}^{m-1} a_{i} h_{i}(\eta), \text { and } \\
& \theta_{r+1}^{\prime \prime}(\eta)=\sum_{i=0}^{m-1} b_{i} h_{i}(\eta)
\end{aligned}
$$

Error!
Bookmark not
defined.(27)
Error!
Bookmark not
defined.(28)
The lower order derivatives are obtained as follows by integrating Eqns. (27) and (28).

$$
\begin{align*}
& f_{r+1}^{\prime \prime \prime}(\eta)=\sum_{i=0}^{m-1} a_{i}\left(\frac{2}{N^{2}} p_{i .3}(N)-\frac{2}{N} p_{i, 2}(N)+p_{i, 1}(\eta)\right)+\frac{2}{N^{2}} \\
& f_{r+1}^{\prime \prime}(\eta)= \\
& \sum_{i=0}^{m-1} a_{i}\left(p_{i .2}(N)-\left(\frac{2 \eta}{N}-1\right) p_{i, 2}(N)+\frac{2}{N}\left(\frac{\eta}{N}-1\right) p_{i, 3}(N)\right)+\frac{2 \eta}{N^{2}}+\frac{2}{N}  \tag{30}\\
& f_{r+1}^{\prime}(\eta)=\sum_{i=0}^{m-1} a_{i}\binom{p_{i .3}(\eta)+\frac{\eta^{2}}{N^{2}}\left(p_{i, 3}(N)-N p_{i, 2}(N)\right)}{+\eta\left(-p_{i, 2}(N)-\frac{2}{N} p_{i, 3}(N)+2 p_{i, 2}(N)\right)}+\frac{\eta^{2}}{N^{2}}-\frac{2 \eta}{N}+1 \tag{31}
\end{align*}
$$

Error! Bookmark not
defined.(29)

$$
\begin{align*}
& f_{r+1}(\eta)= \\
& \sum_{i=0}^{m-1} a_{i}\binom{p_{i .4}(\eta)-\frac{\eta^{3}}{3 N^{2}}\left(-p_{i, 3}(N)+N p_{i, 2}(N)\right)}{+\frac{\eta^{2}}{2}\left(-p_{i, 2}(N)-\frac{2}{N} p_{i, 3}(N)+2 p_{i, 2}(N)\right)}+\frac{\eta^{3}}{3 N^{2}}-\frac{\eta^{2}}{N}+\eta+s  \tag{32}\\
& \theta_{r+1}^{\prime}(\eta)=\sum_{i=0}^{m-1} b_{i}\left(p_{i, 1}(\eta)-\frac{1}{N} p_{i, 2}(N)\right)-\frac{1}{N}  \tag{33}\\
& \theta_{r+1}(\eta)=\sum_{i=0}^{m-1} b_{i}\left(p_{i, 2}(\eta)-\frac{\eta}{N} p_{i, 2}(N)\right)-\frac{\eta}{N}+1 \tag{34}
\end{align*}
$$

where $N$ is sufficiently large number. Substitute Eqns. (27) - (34) into Eqns. (24) and (25). By applying discretization on the Eqns. (24) and (25) and use the collocations points, $\eta_{c}=\frac{(c+0.5) N}{m}, c=0,1, \cdots, m-$ 1 , we obtain the following systems,

## Error!

$$
\sum_{i=0}^{m-1} a_{i} K_{1}=L_{1}
$$

## Bookmark

not
defined.(35)

$$
\sum_{i=0}^{m-1} a_{i} K_{2}+\sum_{i=0}^{m-1} b_{i} K_{3}=L_{2}
$$

Error!

## Bookmark

 notdefined.(36)
where

$$
\begin{aligned}
& K_{1}= \\
& \beta f_{r}^{2} h_{i}(\eta)-f_{r}\left(p_{i, 1}(\eta)+\frac{2}{N^{2}} p_{i, 3}(N)-\frac{2}{N} p_{i, 2}(N)\right)-f_{r}\left(f_{r}+\lambda f_{r}+2 \beta f_{r}^{\prime \prime}\right) \times \\
& \left(p_{i, 2}(\eta)+\frac{2 \eta}{N^{2}} p_{i, 3}(N)-\frac{2 \eta}{N} p_{i, 2}(N)-p_{i, 2}(N)-\frac{2}{N} p_{i, 3}(N)+2 p_{i, 2}(N)\right)+ \\
& f_{r}\left(2 f^{\prime}{ }_{r}+H a^{2}+2 \lambda f^{\prime}{ }_{r}+\lambda H a^{2}\right)\left(p_{i, 3}(\eta)+\left(\frac{\eta}{N}\right)^{2} p_{i, 3}(N)-\right. \\
& \left.\frac{\eta^{2}}{N} p_{i, 2}(N)-\eta p_{i, 2}(N)-\frac{2 \eta}{N} p_{i, 3}(N)+2 \eta p_{i, 2}(\eta)\right)\left(f_{r}^{\prime \prime \prime}-f_{r}^{\prime 2}+\right. \\
& \left.H a^{2} E_{1}-H a^{2} f_{r}^{\prime}-\lambda f_{r}^{\prime 2}+\lambda H a^{2} E_{1}-\lambda H a^{2} f_{r}^{\prime}+\beta f_{r}^{\prime \prime \prime}{ }^{2}\right)\left(p_{i, 4}(\eta)+\right. \\
& \left.\frac{\eta^{3}}{3 N^{2}} p_{i, 3}(N)-\frac{\eta^{3}}{3 N} p_{i, 2}(N)-\frac{\eta^{2}}{2} p_{i, 2}(N)-\frac{\eta^{2}}{N} p_{i, 3}(N)+\eta^{2} p_{i, 2}(N)\right), \\
& K_{2}= \\
& 2 \operatorname{PrEc} f_{r} "\left(p_{i, 2}(\eta)+\frac{2 \eta}{N^{2}} p_{i, 3}(N)-\frac{2 \eta}{N} p_{i, 2}(N)-p_{i, 2}(N)-\frac{2}{N} p_{i, 3}(N)+\right. \\
& \left.2 p_{i, 2}(N)\right)- \\
& 2 \operatorname{Pr}\left(\theta_{r}-E c H a^{2} f_{r}^{\prime}+E c E_{1} H a^{2}\right)\left(p_{i, 3}(\eta)+\left(\frac{\eta}{N}\right)^{2} p_{i, 3}(N)-\frac{\eta^{2}}{N} p_{i, 2}(N)-\right. \\
& \left.\eta p_{i, 2}(N)-\frac{2 \eta}{N} p_{i, 3}(N)+2 \eta p_{i, 2}(N)\right)+ \\
& \operatorname{Pr} \theta^{\prime}{ }_{r}\left(p_{i, 4}(N)+\frac{\eta^{3}}{3 N^{2}} p_{i, 3}(N)-\frac{\eta^{3}}{3 N} p_{i, 2}(N)-\frac{\eta^{2}}{2} p_{i, 2}(N)-\frac{\eta^{2}}{N} p_{i, 3}(N)+\right. \\
& \left.\eta^{2} p_{i, 2}(N)\right), \\
& K_{3}=h_{i}(\eta)-2 \operatorname{Pr} f_{r}^{\prime}\left(p_{i, 2}(\eta)-\frac{\eta}{N} p_{i, 2}(N)\right)+\operatorname{Pr} f_{r}\left(p_{i, 1}(\eta)-\frac{1}{N} p_{i, 2}(N)\right),
\end{aligned}
$$

$$
\begin{aligned}
& L_{1}= \\
& 2 H a^{2} E_{1} f_{r}(1+\lambda)+f_{r}\left(f_{r}^{\prime \prime \prime}+\frac{2}{N^{2}}\right)-H a^{2} f_{r} f_{r}^{\prime}(1+\lambda)- \\
& f_{r}\left(2 f_{r}^{\prime}+H a^{2}+2 \lambda f_{r}^{\prime}+\lambda H a^{2}\right)\left(\frac{\eta^{2}}{N^{2}}-\frac{2 \eta}{N}+1\right)- \\
& \left(f_{r}^{\prime \prime \prime}-f_{r}^{\prime 2}+H a^{2} E_{1}-H a^{2} f_{r}^{\prime}-\lambda f_{r}^{\prime 2}+\lambda H a^{2} E_{1}-\lambda H a^{2} f_{r}^{\prime}+\right. \\
& \left.\beta \boldsymbol{f}_{r}^{\prime \prime}\right)\left(\frac{\eta^{3}}{3 N^{2}}-\frac{\eta^{2}}{N}+\eta+s\right)+f_{r}^{2}\left(1+\lambda+\frac{2 \beta}{f_{r}} \boldsymbol{f}_{r}^{\prime \prime}\right)\left(\frac{2 \eta}{N^{2}}-\frac{2}{N}\right), \\
& L_{2}= \\
& \operatorname{Pr} E c\left(\boldsymbol{f}_{r}^{\prime \prime 2}+H a^{2} f_{r}^{\prime 2}-E_{1}^{2} H a^{2}\right)+\operatorname{Pr}\left(\theta_{r}^{\prime} f_{r}-2 \theta_{r} f_{r}^{\prime}\right)- \\
& \operatorname{Pr} \theta_{r}^{\prime}\left(\frac{\eta^{3}}{3 N^{2}}-\frac{\eta^{2}}{N}+\eta+s\right)- \\
& 2 \operatorname{Pr}\left(\frac{1}{2} \theta^{\prime}-\theta_{r}+E c H a^{2} f_{r}^{\prime}-E c E_{1} H a^{2}\right)\left(\frac{\eta^{2}}{N^{2}}-\frac{2 \eta}{N}+1\right)- \\
& \frac{4}{N} \operatorname{Pr} E c \boldsymbol{f}_{r}^{\prime \prime}\left(\frac{\eta}{N}-1\right)+2 \operatorname{Pr} f_{r}^{\prime}\left(-\frac{\eta}{N}+1\right)+\frac{\operatorname{Pr}}{L} f_{r} .
\end{aligned}
$$

To obtain Haar coefficients, $a_{i}$ and $b_{i}$, Eqns. (35) and (36) can be solved simultaneously.

## 4. Results and Discussions

The nonlinear ODEs (6) and (7) subjected to the boundary conditions (8) were numerically solved by means HWQM. All the computations are carried out by using MATLAB.

The numerical results for examining the surface friction coefficient and surface temperature gradient for different values of suction/injection parameter, $s$ and elasticity number, $\beta$ is shown as in Table 1. Referring to this table, the values of $f^{\prime \prime}(0)$ and $\theta^{\prime}(0)$ are reduced as $s$ increases. Table 2 shows the comparison of the present results by comparing with the published results for various values of parameter with the Newtonian fluid, $\beta$ is equal to zero. A good agreement is obtained between previous results and present results for different values of $\mathrm{Ha}, E c, E_{1}$ and Pr .

Table 1 A table with variations of $-f^{\prime \prime}(0)$ and $-\theta^{\prime}(0)$ when $H a=\lambda=0, E c=E_{1}=1$ and $\operatorname{Pr}=3$.

|  | $-f^{\prime \prime}(0)$ |  |  |  |  | $-\theta^{\prime}(0)$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\beta=1$ | $\beta=2$ | $\beta=3$ | $\beta=1$ | $\beta=2$ | $\beta=3$ |  |  |  |
| -0.5 | 0.06232022 | 0.18374761 | 0.10506315 | 1.78345485 | 1.82252559 | 1.87981412 |  |  |  |
| -0.3 | 0.02630196 | 0.36782901 | 0.11560706 | 1.94181132 | 2.08351599 | 2.07537062 |  |  |  |
| 0.0 | 0.70909591 | 0.58066866 | 0.50469544 | 2.13955960 | 2.29268996 | 2.37501346 |  |  |  |
| 0.3 | 0.74462245 | 0.59878632 | 0.51844900 | 2.58130462 | 2.76592253 | 2.85853625 |  |  |  |
| 0.6 | 0.77445969 | 0.61380622 | 0.52987424 | 3.09771174 | 3.30931226 | 3.41034400 |  |  |  |
| 1.0 | 0.80652589 | 0.62966799 | 0.54178347 | 3.88532509 | 4.12576487 | 4.23544956 |  |  |  |

Table 2 Local Nusselt number $-\theta^{\prime}(0)$ for various values of $H a, E c, E_{1}$ and $\operatorname{Pr}$ when $\beta=0$.

| Ha | Ec | $E_{1}$ | Pr | Pal \& Mondal [22] | Ahmad \& Wahid [28] | HWQM (Present Method) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 3 | 2.509715 | 2.5097 | 2.50972924 |
|  |  |  | 5 | 3.316479 | 3.3164 | 3.31644910 |
|  | 1 | 1 | 3 | 1.745111 | 1.7451 | 1.74508913 |
|  |  |  | 5 | 2.219381 | 2.2193 | 2.21933272 |
| 1 | 1 | 1 | 3 | 2.227830 | 2.2277 | 2.22964763 |
|  |  |  | 5 | 2.916217 | 2.9160 | 2.91291680 |
|  |  | 0 | 3 | 0.459953 | 0.4600 | 0.46004010 |
|  |  |  | 5 | 0.366367 | 0.3666 | 0.36651854 |

Figures 1 and 2 depict the velocity and temperature profiles for various values of $\beta$ and $H a$. When $\beta=0$, the fluid becomes the Newtonian fluid because the elastic force disappears. It is clear that with the increase of $\beta$ for a few values of $H a$, the velocity distribution shows increasing behaviour. Additionally, the thickness of the momentum boundary layer decreases with an increase in Ha . Physically, due to the presence of electromagnetic force given by $H a$, the flow velocity has been retarded at any point of boundary layer. Characteristics of $\beta$ on the temperature distribution is displayed in Fig. 2. For $H a=1$ and 2, the temperature distribution increases for large values of $\beta$, as shown in Fig. 2(b) and Fig. 2(c). The increase parameter of $\beta$ corresponds to larger relaxation time which provides resistance to the fluid motion, hence as a result more heat is produced. Therefore, temperature distribution increases. In contrary, Fig. 2(a) reveals that when $H a=0$, the temperature distribution decreases as $\beta$ increases.

Figures 3(a) and 3(b) show the velocity and the temperature profiles with respect to the suction/injection parameter, $s$. The fluid velocity and temperature field are found to decrease with increasing value of $s$. Suction $(s>0)$ causes to decrease the velocity of the fluid in the boundary layer region. This effect acts to decrease the wall shear stress. On the other hand, increase in suction causes progressive thinning of the boundary layer.

The influence of Pr on temperature profile is shown in Fig.4. It is observed that an increase in Pr leads to reduction in temperature and thermal boundary layer thickness. It should be noted that the thermal diffusivity is weaker for larger Pr due to the fact that the rate of diffusion decreases.


Fig. 1. The velocity profile for different values of $\beta$ when $m=128, N=10, E c=\operatorname{Pr}=\lambda=s=1$, $E_{1}=0$ and $H a=0,2$.


Fig. 2. The temperature profiles for (a) $H a=0$ (b) $H a=1$ (c) $H a=2$ when $m=256, N=$ $10, E c=\lambda=s=1 \beta=1,2,3,4, \operatorname{Pr}=3$ and $E_{1}=0$.


Fig. 3. The velocity and temperature profiles for (a) impermeable surface and suction (b) injection when $m=256, N=10, H a=E_{1}=0, E c=\beta=\lambda=\operatorname{Pr}=1$.


Fig. 4. The temperature profile for different values of $\operatorname{Pr}$ when $m=256, N=10, E_{1}=H a=$ $0, E_{1}=\lambda=s=1$.

## 5. Conclusions

The numerical analysis for heat transfer of a Jeffrey fluid flow past a stretching sheet with ohmic dissipation effect and suction/injection parameter is numerically studied by using HWQM. The results can be summarized as follows:
a) the velocity increases as $\beta$ increases but it has opposite effects on temperature field, for $\mathrm{Ha}=0$,
b) temperature profile decreases as Pr increases and the temperature boundary layer becomes thinner,
c) the velocity and temperature distributions decrease on increasing the value of $s$,
d) $f^{\prime \prime}(0)$ decreases when suction/injection parameter increases.

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