

Consistency between Measurements

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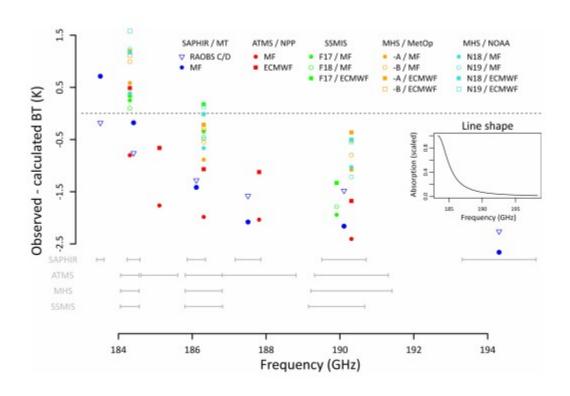
Consistency between Measurements

- Different Measurement Systems should give the "same" (consistent) values of the parameter being measured
- For Water Vapour, there are some examples where measurements are consistent and some in which they are not
- Ideally, before measurements from different systems are combined they should be proven to be consistent → Otherwise combination becomes difficult



Examples of NO Consistency

183 GHz Biases



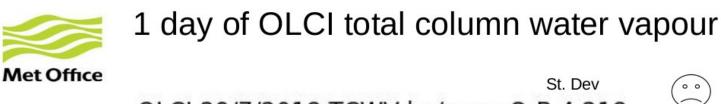
Brogniez et al., AMT, 2016

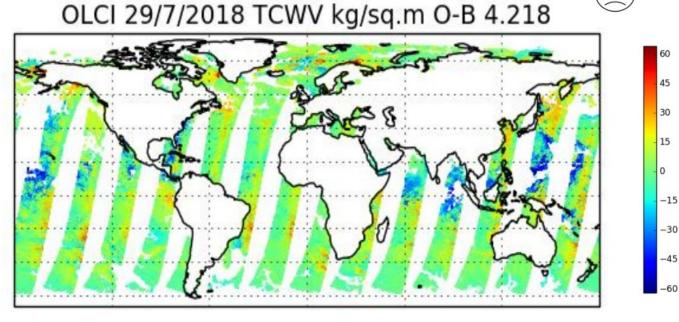




Examples of NO Consistency







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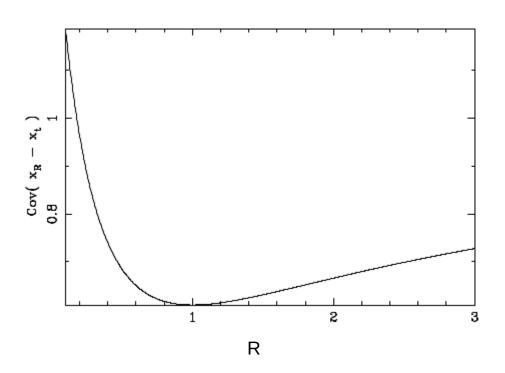


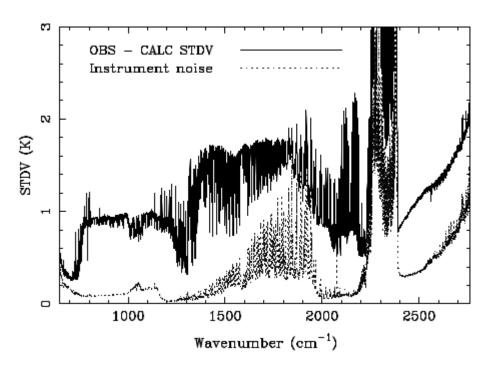


Examples of NO Consistency

OEM IASI WV Retrievals need R matrix values much bigger than instrument noise

$$J = (y - F(x))^{T} R^{-1} (y - F(x)) + (x - x_{a})^{T} B^{-1} (x - x_{a})$$



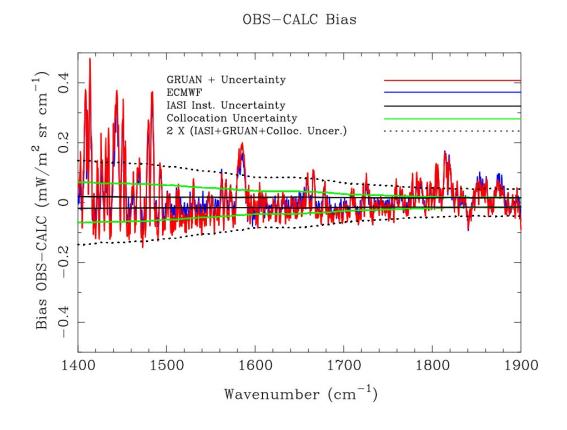


Calbet, arxiv, 2012



Examples of Consistency

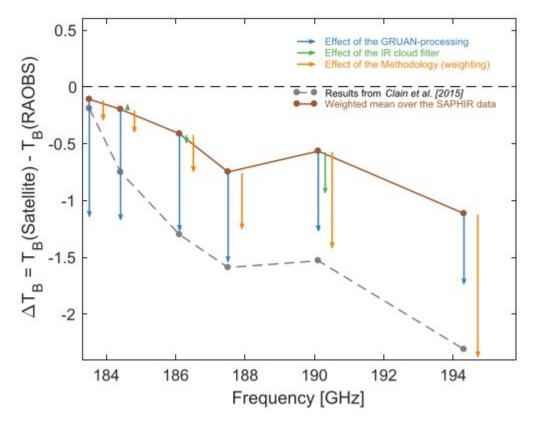
Consistency between GRUAN sondes, LBLRTM and IASI





Examples of Consistency

Consistency between GRUAN and MW over homogeneous scenes





What is going on?

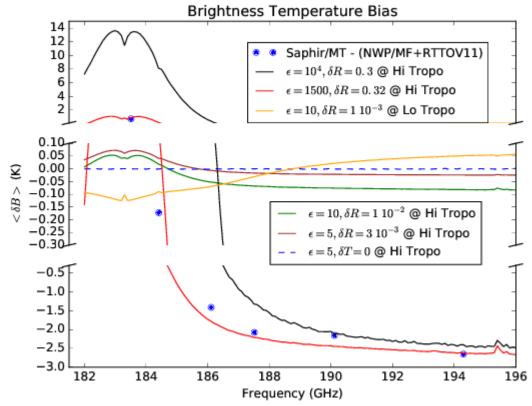
- Is there or is there NOT consistency?
- Are we missing anything?
- Perhaps the difference is in the homogeneity or inhomogeneity of the scenes → How much water vapour varies within the Field of View of the instrument





Effect of FOV inhomogeneity

Can turbulence (= inhomogeneity) within the field of view cause significant biases in radiative transfer modelling at the 183 GHz band?





Effect of FOV inhomogeneity

Can turbulence=inhomogeneity within the Field of View cause significant biases in radiative transfer modelling in MW or IR?

$$<\delta B> \approx \sum_{i=1}^{\text{All Levels}} \frac{dB}{dR_i} < \delta R_i > +\frac{1}{2} \frac{d^2B}{dR_i^2} < (\delta R_i)^2 >$$

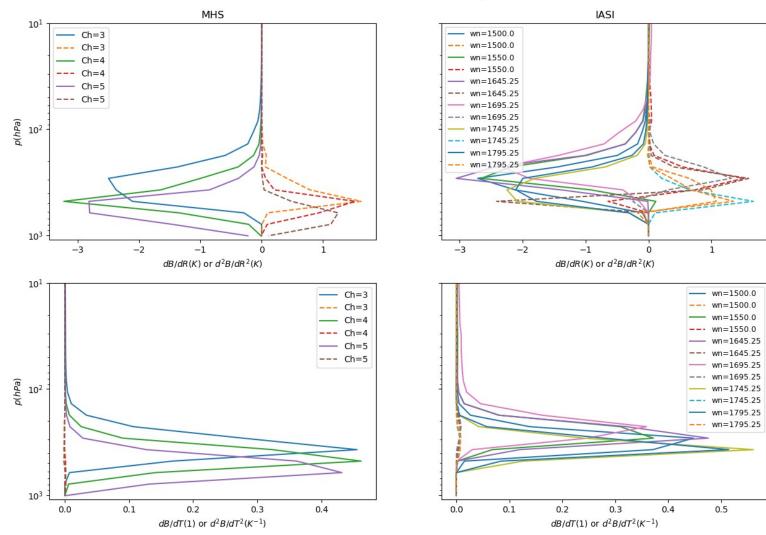




Effect of FOV inhomogeneity

Why can turbulence within the FOV cause big differences

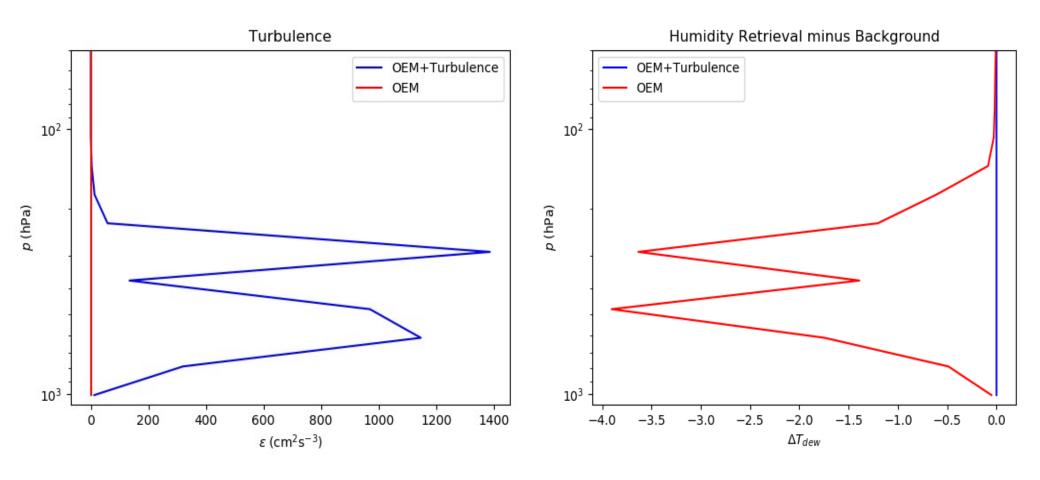
in BT?



- We can try Optimal Estimation Method (OEM) like techniques to retrieve the T and WV profiles and also WV Turbulence (= FOV inhomogeneity)
- Do we retrieve anything reasonable?



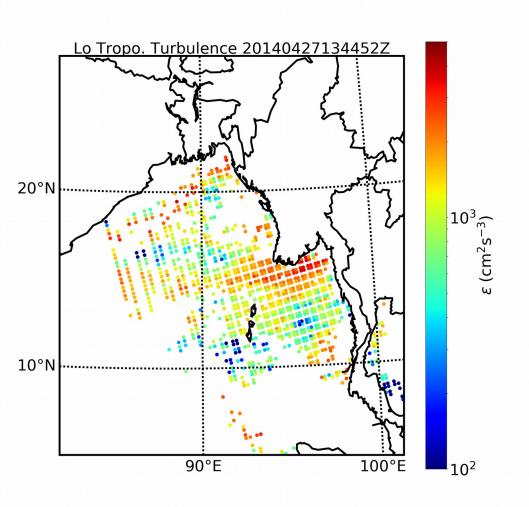
- We try OEM with an R exactly equal to instrument noise → We know this has failed before = too unconstrained system
- We use as background ECMWF analyses
- What happens when retrieving also turbulence?

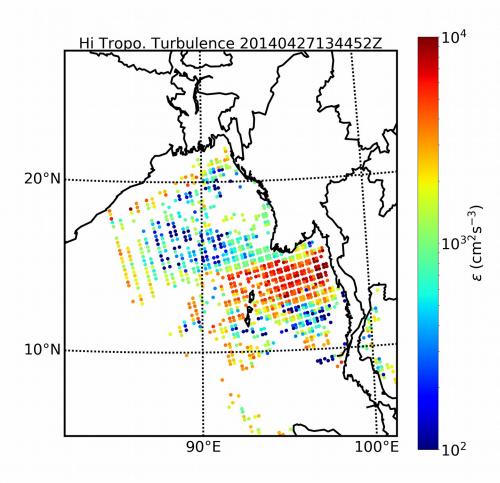




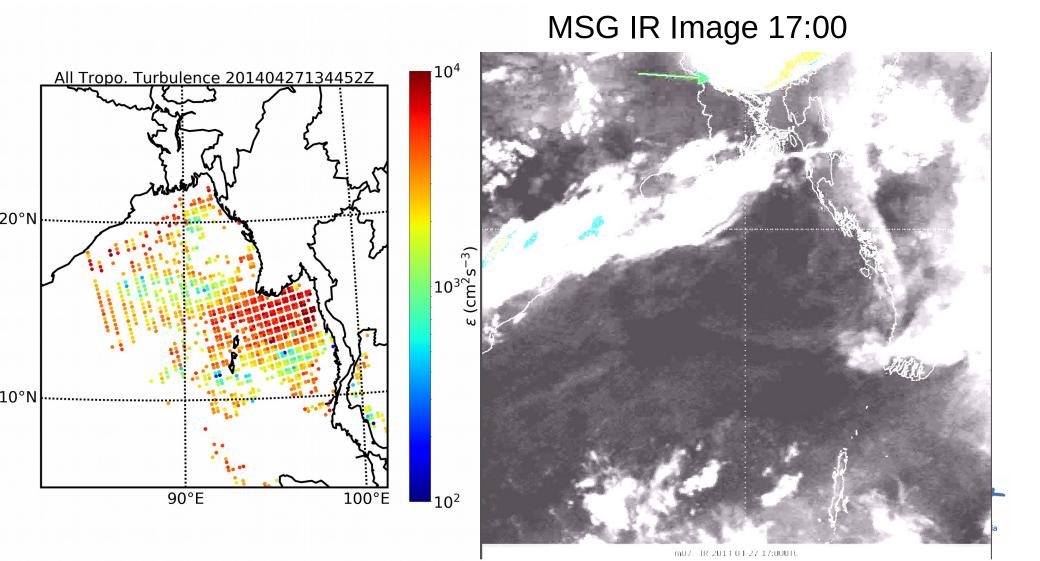


How does it look spatially?

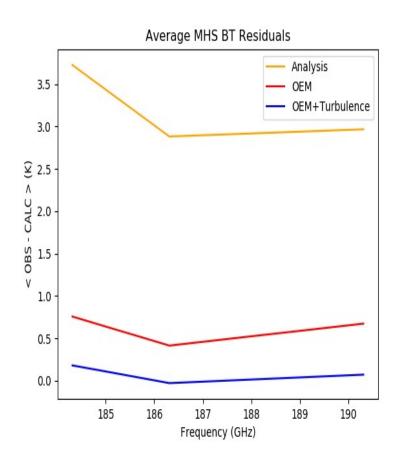


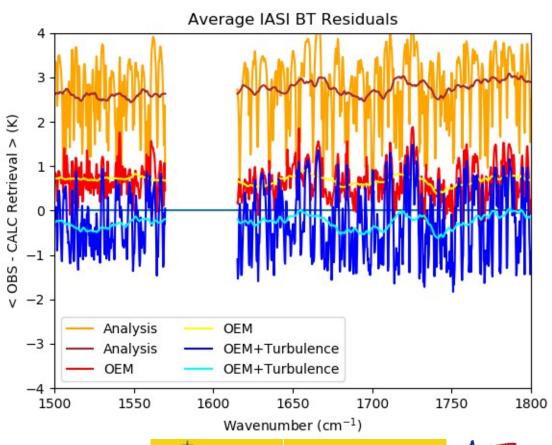


How does it look spatially? → Comparison with MSG seems consistent



Radiance residuals? Retrievals done for MHS \rightarrow MHS Residuals should be low \rightarrow How about residuals for IASI?







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Summary

- Ideally we should strive for consistency before combining different measurements
- There are still some remaining inconsistencies between different WV measurements
- Inhomogeneities within the FOV (turbulence) might explain the remaining inconsistencies
- Retrievals with turbulence (inhomogeneities) provide different humidity values with respect to OEM
- This would potentially allow the retrievals of turbulence, but would also complicate retrievals
- High spatial resolution humidity fields would help in this puzzle