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THE DISTRIBUTION, WHEN THE RESIDUALS ARE SMALL,
OF STATISTICS TESTING OVERIDENTIFYING RESTRICTIONS

Joseph B. Kadane

June 19, 1968

THE DISTRIBUTION, WHEN THE RESIDUALS ARE SMALL,

OF STATISTICS TESTING OVERIDENTIFYING RESTRICTIONS*

by

Joseph B. Kadane

Abstract

In the estimation of simultaneous equation econometric models, overidentifying restrictions improve estimates of the remaining parameters. Natural test statistics for the hypothesis that an equation is overidentified have been developed by Anderson and Rubin and by Basmann. If the residuals are jointly normal, serially uncorrelated, and small, both the above overidentification test statistic have the Snedecor F distribution asymptotically as the variance of the residuals gets small. This gives analytic confirmation of Monte Carlo results of Basmann. The results given apply to linear models in which predetermined variables can be exogenous or lagged endogenous.

1. Introduction

Anderson and Rubin [1] found that the likelihood ratio statistic for testing the overidentifying restrictions on a single equation in a system of simultaneous equations is equivalent to the smallest root, λ ,

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of the determinental equation appearing in the theory of the limited information (single equation) maximum likelihood estimator. They also proposed a conservative test of significance for λ , comparing $\frac{T-K}{K_2}$ (λ -1) with an F distribution with K_2 and T-K degrees of freedom and rejecting for large values. (Here T is the sample size, K the number of predetermined variables in the system and K_2 the number of predetermined variables excluded from the equation in question.)

In a later paper, Anderson and Rubin [2] found that $T(\lambda-1)$ has a large-sample asymptotic X^2 distribution with L degrees of freedom where L is the degree of overidentification.

Basmann [4] pointed out the difficulty that the proposed conservative test for λ does not coincide with the large-sample test as the sample size increases and proposed that $\frac{T-K}{L}(\lambda-1)$ be compared to an F distribution with L and T-K degrees of freedom. He justified this proposal on heuristic grounds, and referred to an unpublished Monte-Carlo study [3] which supports his proposal at one set of parameter and exogenous variable values. His criticism does not imply that Anderson and Rubin erred, but rather that their proposed test of significance is very conservative.

Additionally he proposed a slightly different test statistic $\hat{\lambda}$ (\hat{p} + 1 in the notation of [4]) based on two-stage least squares (GCL) estimates of structural parameters, and proposed the same test

of significance for $\hat{\lambda}$: compare $\frac{T-K}{L}(\hat{\lambda}-1)$ to an F distribution with L and T-K degrees of freedom. The Monte Carlo study reported in [4] strongly supported this approximation to the distribution of $\hat{\lambda}$.

In a later article Basmann [5] derived the exact distribution of $\hat{\lambda}$ for a special case. Finally Richardson [7] derived the excat distribution of $\hat{\lambda}$ in two special cases (of which one was the same as that of Basmann above) and showed that $\hat{\lambda}$ has the asymptotic distribution conjectured by Basmann in [3] as "the concentration parameter" $\hat{\mu}^2$ approaches infinity.

The purpose of this paper is to demonstrate that the distribution (for both statistics) originally conjectured by Basmann is the first order term of a (random) Taylor series expansion as the variance of the residuals in the model approaches zero (which implies that Richardson's $\mu^2 + \infty$.) Basmann's conjecture is established, in this sense, for any linear simultaneous equation model of any size. The results here apply to models with or without lagged endogenous variables appearing as predetermined variables.

Taylor series of this type (called small- σ asymptotics) are a useful general method for studying small-sample properties of econometric statistics. Intuitively the idea of small- σ asymptotics is that the model is getting increasingly good as $\sigma \to 0$. This is a more natural ideal case for many regression problems than the usual

large sample case. Other work [6] applies small-o asymptotics to the comparison of alternative econometric estimators.

2. Statement of Theorem

Let the complete system

$$YB + Z\Gamma + \sigma U = 0$$

have a possibly overidentified (but certainly identified) first equation

$$y = Y_1 \beta + Z_1 \gamma + \sigma u$$

where Y is a T x G matrix of endogenous variables, partitioned Y = (y, Y_1, Y_2) where y is T x l , Y_1 is T x G_1 and Y_2 is T x G_2 (G = G_1 + G_2 + l); Z is a T x K matrix of predetermined variables, partitioned Z = (Z_1, Z_2) where Z_1 is T x K_1 and Z_2 is T x K_2 (K = K_1 + K_2); B is a non-singular G x G matrix of parameters with first column (-l, β^* , 0^*) where -l is a number, β is l x G_1 and 0 is a l x G_2 vector of zeros; Γ is a K x G matrix of parameters with first column (γ^* , 0^*), where γ is l x K_1 and 0 is a l x K_2 vector of zeros; U is a T x G matrix of jointly normal residuals with zero means and covariances $Eu_{ti}u_{t^*,j} = \sigma_{ij}\delta_{tt^*u}$; and σ is a (small) positive number. The

general k-class estimate of $\binom{\beta}{\gamma}$ is

$$\begin{pmatrix} \beta \\ \gamma \end{pmatrix}_{k} = \begin{bmatrix} Y_{1}^{i} & Y_{1} - kV^{i}V & Y_{1}^{i} & Z_{1} \\ Z_{1}^{i} & Y_{1} & & Z_{1}^{i} & Z_{1} \end{bmatrix}^{-1} \begin{bmatrix} (Y_{1} - kV)^{i} \\ Z_{1}^{i} \end{bmatrix} y$$

where $V = P_Z Y_1$ and $P_X = I - X(X'X)^{-1} X'$ is the projection onto the space orthogenal to the columns of X, for any matrix X. As is well-known, the two-stage least squares (GCL) estimate, corresponds to k = 1, and limited information (single equation) maximum likelihood corresponds to $k = \lambda$, where

$$\lambda = \min_{\beta_{*}} \frac{\beta_{*}^{'} Y_{*}^{'} P_{Z_{1}} Y_{*} \beta_{*}}{\beta_{*}^{'} Y_{*}^{*} P_{Z_{1}} Y_{*} \beta_{*}} = \frac{\hat{\beta}_{*}^{'} Y_{*}^{'} P_{Z_{1}} Y_{*} \hat{\beta}_{*}}{\hat{\beta}_{*}^{'} Y_{*}^{*} P_{Z_{1}} Y_{*} \hat{\beta}_{*}}$$

and $Y_* = (y, Y_1)$.

 $\hat{\beta}_{\star}$ in (4), when normalized, can be written as $(-1, \hat{\beta}_{\lambda}')$ where $\hat{\beta}_{\lambda}$ is limited information maximum likelihood estimator of β . The identifiability test statistic associated with limited information maximum likelihood is λ . The identifiability test statistic associated with two-stage least squares, λ_{1} , is λ above with $(-1, \hat{\beta}_{1}')$, the two stage least squares estimate for $(-1, \beta)$, substituted for $\hat{\beta}$. Now we can state

Theorem: Asymptotically as $\sigma \to 0$, λ and λ_1 each have the same distribution as $1 + X_1/X_2$ where X_1 has a χ^2 distri-

bution with L degrees of freedom, independent of x_2 which has a χ^2 distribution with T-K degrees of freedom.

Actually the proof applies to any k-class estimator where k=0 p(1) as $\sigma \neq 0$. In particular, the analogous statistics with ordinary least squares or Nagar's unbiased k-class estimators have the above distribution.

3. Proof of Theorem

Lemma 1:
$$\lambda = O_p(1)$$
 as $\sigma \to 0$

Proof

$$1 \leq \lambda = \min_{\widehat{\boldsymbol{\beta}}} \frac{\widehat{\boldsymbol{\beta}}^{\dagger} Y_{*}^{\dagger} P_{Z_{1}} Y_{*} \widehat{\boldsymbol{\beta}}}{\widehat{\boldsymbol{\beta}}^{\dagger} Y_{*}^{\dagger} P_{Z} Y_{*} \widehat{\boldsymbol{\beta}}}$$

$$= \frac{(-y^{\dagger} + \beta^{\dagger} Y_{1}^{\dagger}) P_{Z_{1}} (-y + Y_{1} \beta)}{(-y^{\dagger} + \beta^{\dagger} Y_{1}^{\dagger}) P_{Z_{1}} (-y + Y_{1} \beta)}$$

From (2),
$$(-y + Y_1\beta) = -Z_1\gamma - \sigma u$$
. Also
$$P_{Z_1}^{\ \ Z_1} = P_Z^{Z_1} = 0$$
.

Hence

(5)
$$1 \leq \lambda \leq \frac{\sigma^2 u^* P_Z u}{\sigma^2 u^* P_Z u} = \frac{u^* P_Z u}{u^* P_Z u}.$$

In the case when the predetermined variables Z are in fact exogenous (and hence considered constant), the proof of lemma 1 is complete, as the expression on the right hand side of (5) is a random variable not involving σ . In the case in which lagged endogenous variables are permitted as predetermined variables, however, more explanation is required.

Write $Z=R+\sigma S$, in general, where R is constant and S is a random variable, depending on the lag structure, not involving σ . Then since Z is partitioned $Z=(Z_1,Z_2)$, R and S can be partitioned conformably as $R=(R_1,R_2)$ and $S=(S_1,S_2)$. Now

$$P_{Z_1} = P_{R_1} + O_p(\sigma)$$
 and

$$P_Z = P_R + O_p(\sigma)$$
.

Hence (5) can be written

$$1 \le \lambda \le \frac{u^{\epsilon} P_{R_{\underline{1}}} u + O_{\underline{p}}(\sigma)}{u^{\epsilon} P_{R_{\underline{1}}} u + O_{\underline{p}}(\sigma)} = O_{\underline{p}}(1) .$$
 QED.

Similarly, the reduced form for a lag structure can be written

$$[Y_1, Z_1] = X + \sigma V^*$$

where X is constant and is the space spanned by R , and V^{\star} is a random variable not involving σ .

Lemma 2

$$\begin{pmatrix} \beta \\ \gamma \end{pmatrix}_{k} = \begin{pmatrix} \beta \\ \gamma \end{pmatrix} + \sigma(X^{\dagger}X)^{-1}X^{\dagger}u + O_{p}(\sigma^{2}) \quad \text{if } k = O_{p}(1)$$

[In particular, Lemma 2 applies if k=1 and if $k=\lambda$ (using Lemma 1).]

Proof

$$(V, O) = P_Z[Y_1, Z_1] = P_Z[X + \sigma V^*] = \sigma P_Z V^*$$
.

Hence using (3),

$$\begin{pmatrix} \beta \\ \gamma \end{pmatrix}_{k} = \begin{pmatrix} \beta \\ \gamma \end{pmatrix} + \sigma\{(X + \sigma V^{*})^{\dagger}(X + \sigma V^{*}) - k\sigma^{2}V^{*\dagger}P_{Z}V^{*}\}^{-1}\{X^{\dagger} - \sigma(I - kP_{Z})V^{*\dagger}\}u$$

$$= \begin{pmatrix} \beta \\ \gamma \end{pmatrix} + \sigma(X^{\dagger}X)^{-1}X^{\dagger}u + O_{p}(\sigma^{2}) \quad \text{if } k = O_{p}(1)$$
QED.

Using Lemma 2,

$$P_{Z_{1}}Y_{*}\hat{\beta}_{k} = P_{Z_{1}}(y, Y_{1})\left\{\begin{pmatrix} -1 \\ \beta \end{pmatrix} + \sigma \begin{bmatrix} 0 \\ 0 \\ X^{*} \end{bmatrix} X^{*}u + O_{p}(\sigma^{2})\right\}$$
where $(X^{*}X)^{-1} = \begin{bmatrix} X^{*} \\ X^{**} \end{bmatrix}$

$$\begin{split} P_{Z_{1}}Y_{*}\hat{\beta}_{k} &= P_{Z_{1}}\{-y + Y_{1}\beta + \sigma Y_{1}X^{*}X^{*}u + O_{p}(\sigma^{2})\} \\ &= P_{Z_{1}}\{-Z_{1}\gamma - \sigma u + \sigma Y_{1}X^{*}X^{*}u + O_{p}(\sigma^{2})\} \quad (\text{from } (2)) \\ &= P_{Z_{1}}\{-\sigma u + \sigma Y_{1}X^{*}X^{*}u + \sigma Z_{1}X^{**}X^{*}u + O_{p}(\sigma^{2})\} \\ &= -\sigma P_{Z_{1}}P_{X}u + O_{p}(\sigma^{2}) . \end{split}$$

So

$$\lambda = \frac{\sigma^{2} u^{*} P_{X} P_{Z_{1}} P_{X} u + O_{p}(\sigma^{3})}{\sigma^{2} u^{*} P_{X} P_{Z} P_{X} u + O_{p}(\sigma^{3})}$$

$$= \frac{u^{*} P_{X} u}{u^{*} P_{Z} u} + O_{p}(\sigma) = 1 + \frac{u^{*} [P_{X} - P_{R}] u}{u^{*} P_{R} u} + O_{p}(\sigma)$$

 P_R and $(P_X - P_R)$ are projections and $P_R(P_X - P_R) = 0$ since X is in the space spanned by R. $u^*[P_X - P_R]u$ and u^*P_Ru are therefore independent X^2 distributions with degrees of freedom $tr(P_X - P_R) = L$ and $trP_R = T-K$ respectively. This completes the proof of the theorem.

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