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RESEARCH ARTICLE

Approximate and Exact Merging of Knapsack Constraints with Cover Inequalities

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This paper presents both approximate and exact merged knapsack cover inequalities, a class of cutting planes for knapsack and multiple knapsack integer programs. These inequalities combine the information from knapsack constraints and cover inequalities. Approximate merged knapsack cover inequalities can be generated through a $O(n\log n)$ algorithm, where n is the number of variables. This class of inequalities can be strengthened to an exact version with a pseudo-polynomial time algorithm. Computational experiments demonstrate an average improvement of approximately 8% in solution time and 5% in the number of ticks from CPLEX when approximate merged knapsack cover inequalities are implemented as preprocessing cuts to solve some benchmark multiple knapsack problems. Furthermore, exact merged knapsack cover inequalities improve the solution time and number of ticks of some random multiple knapsack instances by 15% and 5%, respectively.

Keywords: integer programming; cover inequalities; knapsack constraints; cutting planes; inequality merging; merged knapsack cover inequalities

AMS Subject Classification: MSC 90C10; MSC 90C27; MSC 90C39; MSC 90C57

1. Introduction

Integer program (IP) is a class of mathematical models used to formulate numerous optimization problems. Integer programs have been used by practitioners to solve several real world problems from areas such as portfolio management [1, 2], power generation [3, 4], capital budgeting [5, 6], supply chain and transportation of goods [7–12], scheduling [13, 14], and health care [15–18]. Unfortunately, IPs are \mathcal{NP} -hard [19] and are typically solved by the branch and bound algorithm [20].

Formally, define an IP as maximize $z=c^Tx$, subject to $Ax \leq b$ and $x \in \mathbb{Z}_+^n$, where n and r are positive integers, $c \in \mathbb{R}^n$, $A \in \mathbb{R}^{r \times n}$, and $b \in \mathbb{R}^r$. Denote $N = \{1, ..., n\}$ to be the set of variable indices and $R = \{1, ..., r\}$ as the set of constraint indices. Let $P = \{x \in \mathbb{Z}_+^n : Ax \leq b\}$ be the set of feasible integer solutions, (z^{IP}, x^{IP}) be any feasible integer solution, and (z^{IP^*}, x^{IP^*}) be an optimal solution to the IP. Furthermore, denote $P^{LR} = \{x \in \mathbb{R}_+^n : Ax \leq b\}$ as the set of feasible linear relaxation solutions, (z^{LR}, x^{LR}) to be any feasible linear relaxation solution, and (z^{LR^*}, x^{LR^*}) to be an optimal linear relaxation solution to the IP.

The knapsack problem (KP) is a classical IP that models the idea of a hiker that has to decide which items to pack in a knapsack for a trip. Each item has

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an associated benefit and weight. The problem seeks to maximize the amount of benefits constrained by a total weight limit. If the knapsack is limited to other such constraints (e.g. volume and price of items), then this problem is referred to as the multiple knapsack problem (MKP) or the multidimensional knapsack problem [21]. Observe that other formulations of MKPs also exist such as MKPs with multiple objectives [22–24]. Knapsack and multiple knapsack problems have been used in numerous different applications such as production planning and inventory control [25, 26], project and portfolio selection [27], resource allocation [28], machine scheduling [29, 30], and packing problems [31]. Observe that KPs and MKPs are also \mathcal{NP} -hard and substantial research has been performed to more quickly solve these classes of IPs [32–36].

Formally, define a KP as maximize $z = c^T x$, subject to $a^T x \leq b$ and $x \in \{0,1\}^n$, where $c \in \mathbb{R}^n_+$, $a \in \mathbb{R}^n_+$, and $b \in \mathbb{R}_+$. Denote $P_{KP} = \{x \in \{0,1\}^n : a^T x \leq b\}$ as the set of feasible solutions of a KP. Additionally, define an MKP as maximize $z = c^T x$, subject to $Ax \leq b$ and $x \in \{0,1\}^n$, where $c \in \mathbb{R}^n_+$, $A \in \mathbb{R}^{r \times n}_+$, and $b \in \mathbb{R}^r_+$. Let $P_{MKP} = \{x \in \{0,1\}^n : Ax \leq b\}$. Without loss of generality, assume every KP has $a_j \leq b$ for all $j \in N$ and every MKP has $a_{i,j} \leq b_i$ for all $i \in R$ and $j \in N$. Otherwise, $x_j = 0$ for all cases in which $a_j > b$ and $a_{i,j} > b_i$, and these variables can be eliminated from the problem. Furthermore, denote $(z^{KP}, x^{KP}), (z^{KP^*}, x^{KP^*}), (z^{MKP}, x^{MKP})$, and (z^{MKP^*}, x^{MKP^*}) as any feasible integer solution and an optimal solution for KPs and MKPs, respectively.

The concept of convexity and polyhedral theory are vital to this paper. Let $S \subseteq \mathbb{R}^n$ be convex if, and only if, $\lambda x + (1 - \lambda)x' \in S$ for all x and $x' \in S$, and $\lambda \in [0,1]$. If $S \subseteq \mathbb{R}^n$, then its convex hull, S^{ch} , is the intersection of all convex sets that contain S. Furthermore, define a half space as $\{x \in \mathbb{R}^n : \sum_{j=1}^n \alpha_j x_j \leq \beta\}$, where α is a nonzero vector and β is a scalar. Define a polyhedron as the intersection of a finite number of half-spaces and a polytope as a bounded polyhedron. Observe that P^{ch} , P^{LR} , P^{ch}_{KP} , and P^{ch}_{MKP} are all polyhedra. Frequently, cutting planes are used to improve the computational time to solve

Frequently, cutting planes are used to improve the computational time to solve IPs. Cutting planes are valid inequalities that remove some space from P^{LR} without eliminating any $x^{IP} \in P$. For instance, lifting [37], cover cuts [38, 39], disjunctive cuts [40], Chvátal Gomory cuts [41], mixed integer rounding cuts [42], superadditive cuts [43], and modular arithmetic cuts [44] are all examples of cutting planes for integer programming problems.

Formally, any inequality of the form $\sum_{j=1}^{n} \alpha_j x_j \leq \beta$ is valid for P^{ch} if, and only if, $\sum_{j=1}^{n} \alpha_j x_j' \leq \beta$ for every $x' \in P$. If an inequality is valid and there exists an $x'' \in P^{LR}$ such that $\sum_{j=1}^{n} \alpha_j x_j'' > \beta$, then this inequality is a cutting plane. A valid inequality $\sum_{j=1}^{n} \alpha_j x_j \leq \beta$ weakly dominates another valid inequality $\sum_{j=1}^{n} \alpha_j' x_j \leq \beta'$ if $\alpha_j \geq \alpha_j'$ for all $j \in N$ and $\beta \leq \beta'$.

The theoretical usefulness of cuttings planes is measured in terms of the dimension of the cutting plane's face $F = \{x \in P^{ch} : \sum_{j=1}^{n} \alpha_j x_j = \beta\}$. The dimension of a convex space, P^{ch} , is defined as the maximum number of affinely independent points minus one. Let $Q = \{x^1, x^2, ..., x^q\} \in \mathbb{R}^n$ be a set of affinely independent points if, and only if, the unique solution to $\sum_{k=1}^{q} \lambda_k x^k = 0$ and $\sum_{k=1}^{q} \lambda_k = 0$ is $\lambda_k = 0$ for all $k \in \{1, ..., q\}$. If the dimension of F equals the dimension of F minus one, then the inequality is said to be facet defining and is one of the theoretically strongest valid inequalities [45].

Since this paper presents merged knapsack cover inequalities, a new class of cutting planes for KPs and MKPs, some background information about covers, lifting, and inequality merging is useful to understand the paper. Covers represent an infeasible solution to a knapsack constraint and are used to create valid inequalities.

Formally, $C \subseteq N$ is a cover if, and only if, $\sum_{j \in C} a_j > b$. Every cover C has a corresponding valid cover inequality $\sum_{j \in C} x_j \leq |C| - 1$. If $\sum_{j \in C \setminus \{k\}} a_j \leq b$ for each $k \in C$, then the cover is minimal. For brevity, this paper assumes that all covers are minimal.

Lifting can be used to strengthen some valid inequalities [37]. Lifting begins with a valid inequality in the restricted space $P_{E,K}$ and creates a valid inequality over the entire dimensional space P. Let $E \subset N$ be an ordered set and $K = (k_1, k_2, ..., k_{|E|}) \in \mathbb{Z}^{|E|}$. Define the restricted space $P_{E,K} = \{x \in P : x_j = k_j \ \forall j \in E\}$. Lifting begins with a valid inequality $\sum_{j \in E} \alpha_j x_j + \sum_{j \in N \setminus E} \alpha_j x_j \leq \beta$ of $P_{E,K}^{ch}$ and creates a valid inequality $\sum_{j \in E} \alpha'_j x_j + \sum_{j \in N \setminus E} \alpha_j x_j \leq \beta'$ of $P_{E,K}^{ch}$. Valid inequalities can be: up, down, or middle lifted; exactly or approximately

Valid inequalities can be: up, down, or middle lifted; exactly or approximately lifted; sequentially or simultaneously lifted. Inequalities are up, down, or middle lifted when for each $j \in E$, the values of k_j are at the lower bound, upper bound, or in between the lower and upper bound, respectively [46]. Furthermore, lifting is considered exact if α' cannot be increased and β' cannot be decreased [47–49]. On the other hand, if a lifted inequality has either an α' that can be increased or a β' that can be decreased, then the corresponding inequality is approximately lifted. Finally, an inequality is sequentially lifted when |E| = 1 and simultaneously lifted when |E| > 1 [50–53].

One particular type of simultaneous lifting is referred to as inequality merging [54, 55]. Inequality merging occurs when two low dimensional valid inequalities are merged to create a new valid inequality of higher dimension. In such a case, one valid inequality is defined as the host inequality $\sum_{j \in C^1} \alpha_j^1 x_j \leq \beta^1$, while the other valid inequality is defined as the donor inequality $\sum_{j \in C^2} \alpha_j^2 x_j \leq \beta^2$, where $C^1 \subseteq N$, $p \in C^1$, $C^2 \subseteq (N \setminus C^1) \cup \{p\}$, and β^1 , β^2 , α_j^1 , $\alpha_j^2 \in \mathbb{Z}_+$. Thus, the host inequality replaces at least one of its variables with a set of variables from the donor inequality and the resulting merged inequality is $\sum_{j \in C^1 \setminus \{p\}} \alpha_j^1 x_j + \sum_{j \in C^2} \frac{\alpha_j^2}{\beta^2} x_j \leq \beta^1$. Observe that merged inequalities may be valid and facet defining under certain conditions. Other techniques to merge inequalities not related to this paper also exist [56, 57].

This paper presents a $O(n \log n)$ algorithm to create valid approximate merged knapsack cover inequalities. The variables of a cover inequality are merged with a set of variables from a knapsack constraint. The merged knapsack coefficient must be greater than a certain predefined value, which allows a strengthening of the cover inequality. In addition, this paper describes a technique to strengthen these approximate inequalities into an exact version. Exact merged knapsack cover inequalities are generated in pseudo-polynomial time with a dynamic programming algorithm, and are the theoretically strongest such inequalities. Computational results demonstrate an average improvement of nearly 8% in solution time and 5% in the number of ticks from CPLEX when approximate merged knapsack cover inequalities are implemented as preprocessing cuts to solve some benchmark multiple knapsack instances. Moreover, exact merged knapsack cover inequalities improve the solution time of some random multiple knapsack problems by 15% and number of ticks by 5%.

The remainder of the paper is organized as follows. Section 2 demonstrates the theory behind both approximate and exact merged knapsack cover inequalities. Section 3 provides the main computational results. Section 4 concludes the paper and presents potential topics for future work.

2. Merging Knapsack Constraints with Cover Inequalities

This section describes the theoretical and algorithmic results involving approximate and exact merged knapsack cover inequalities. Examples are provided to demonstrate this novel class of cutting planes. Preliminary results can also be found in a conference proceedings paper [58] and a thesis [59].

2.1. Approximate Merged Knapsack Cover Inequalities

Let $\sum_{j\in N} a_j x_j \leq b$ be a knapsack constraint, $C\subseteq N$ be a cover, $M\subseteq N$ be a set of merging indices, and $\alpha\in\mathbb{R}_+$ be a merging coefficient. Define a merged knapsack cover inequality MKC_α as $\sum_{j\in C\setminus M} x_j + \alpha \sum_{j\in M} a_j x_j \leq |C|-1$. Observe that $\sum_{j\in C\setminus M} x_j \leq |C|-1$ is part of the cover inequality and $\sum_{j\in M} a_j x_j$ is a portion of the knapsack constraint. If there exists an $x^{KP}\in P_{KP}$ that meet MKC_α at equality, then MKC_α is an exact merged knapsack cover inequality. If not, then MKC_α is an approximate merged knapsack cover inequality. This definition follows identically to the terms used to define when an inequality is approximately or exactly lifted.

Observe that $\alpha=0$ results in MKC_{α} being weakly dominated by the cover inequality. If $\alpha>\frac{|C|-1}{\max\{a_j:j\in M\}}$, then there exists an $x^{KP}\in P_{KP}$ with $x_j=1$ for some $j\in M$ that violates the merged knapsack cover inequality, and MKC_{α} is not valid. Consequently, valid merged knapsack cover inequalities must have $0<\alpha\leq\frac{|C|-1}{\max\{a_j:j\in M\}}$ in order to be considered theoretically useful.

The approximate merging knapsack cover algorithm (AMKCA) determines valid merged knapsack cover inequalities that can be theoretically stronger than the corresponding cover inequality. This algorithm first determines a set of merging indices M and calculates a value for α such that MKC_{α} is valid. Algorithm 1 presents AMKCA, which requires as input a knapsack constraint $\sum_{j\in N}a_jx_j\leq b$, a cover $C\subseteq N$ such that $C=\{f_1,f_2,...,f_{|C|}\}$, and a set $M'\subseteq C$, where $M'=\{g_1,g_2,...,g_{|M'|}\}$. One can view M' as a set of elements in C that are merged jointly with the elements in M. That is, $M'=M\cap C$. The output to AMKCA is an $\alpha\in\mathbb{R}_+$, a set of merging indices $M=\{h_1,h_2,...,h_{|M|}\}$, and the approximate merged knapsack cover inequality $\sum_{j\in C\setminus M}x_j+\alpha\sum_{j\in M}a_jx_j\leq |C|-1$.

Algorithm 1 has four major steps. The first step (lines 2-12) initializes certain variables and sorts the knapsack constraint, the indices of C, and the indices of M' in descending order according to the values of a. The second step (lines 13-21) determines a set $M \subseteq N$ such that $\alpha > 0$ (Theorem 2.1). The third step (lines 22-29), which is equivalent to calculating $\alpha = \min\left\{\frac{|C|-1-q}{b-\sum_{j=|C\backslash M|-q+1}^{|C|}a_{t_j}}: 0 \le q \le p\right\}$ (see Theorem 2.2), defines a value for α by efficiently utilizing the sorted knapsack coefficients to determine feasible solutions for P_{KP} . Observe that any $x^{KP} \in P_{KP}$ may decrease the current estimate for α (Theorem 2.2). The last step (lines 30-32) reports the α value, M, and MKC_{α} determined by AMKCA.

The most expensive step in AMKCA is to sort the coefficients of the knapsack constraint. Therefore, approximate merged knapsack cover inequalities can be generated with $O(n\log n)$ effort. To prove that the inequalities reported by AMKCA are valid and not dominated by their corresponding cover inequality, one must evaluate both steps (B) and (C) of AMKCA. Theorem 2.1 proves that AMKCA determines a set of merging indices M such that approximate merged knapsack cover inequalities are valid for some $\alpha > 0$.

Algorithm 1 : Approximate Merging Knapsack Cover Algorithm (AMKCA)

```
1: begin
 2: (A) Initialization
           Sort a = (a_1, a_2, ...a_n) such that a_j \ge a_{j+1} \ \forall j = \{1, 2, ..., |N| - 1\}
           Sort C = \{f_1, f_2, ..., f_{|C|}\} such that a_{f_i} \ge a_{f_{i+1}} \ \forall j = \{1, 2, ..., |C| - 1\}
 4:
           Sort M' = \{g_1, g_2, ..., g_{|M'|}\} such that a_{g_i} \ge a_{g_{i+1}} \ \forall j = \{1, 2, ..., |M'| - 1\}
 5:
           M \leftarrow \emptyset
 6:
           l \leftarrow |C \setminus M'|
 7:
           \alpha \leftarrow \infty
 8:
           if |M'| \leq 2 then
 9:
                p \leftarrow |C| - 2
10:
11:
                p \leftarrow |C \setminus M'|
12:
     (B) Determine M
13:
           if |M'| = 0 then
           \theta \leftarrow b - \sum_{j=2}^{|C|} a_{f_j} else if |M'| = 1 then
15:
16:
                \theta \leftarrow b - \sum_{i \in C \setminus M'} a_{f_i}
17:
           else
18:
19:
           for each j \in N \setminus (C \setminus M') do
20:
                if a_i > \theta then M \leftarrow M \cup \{j\}
21:
     (c) Calculate \alpha
22:
           \theta \leftarrow b
23:
           for q = 0 to p do
24:
                \alpha' \leftarrow \frac{|C|-1-q}{\theta}
25:
                if \alpha' < \alpha then \alpha \leftarrow \alpha'
26:
                if q < p then
27:
                      \theta \leftarrow \theta - a_{f_l}
28:
29:
     (D) OUTPUT
30:
           return \alpha \in \mathbb{R}^+ and M = \{h_1, h_2, ..., h_{|M|}\}
31:
           return MKC_{\alpha} \leftarrow \sum_{j \in C \setminus M} x_j + \alpha \sum_{j \in M} a_j x_j \leq |C| - 1
32:
33: end
```

THEOREM 2.1 Let $\sum_{j \in N} a_j x_j \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, and $M' \subseteq C$ be a set of overlapping indices. AMKCA returns a set of merging indices M such that MKC_{α} is valid for P_{KP}^{ch} for some $\alpha > 0$.

Proof. Let $\sum_{j\in N} a_j x_j \leq b$ be a knapsack constraint, $C\subseteq N$ be a cover, and $M'\subseteq C$ be a set of overlapping indices. Assume M is the set of merging indices returned by AMKCA and $\alpha=\frac{1}{b}$. To show that MKC_{α} is valid for P_{KP}^{ch} , let x' be any solution in P_{KP} and define $q=\sum_{j\in C\setminus M} x'_j$. Since C is a cover, then $\sum_{j\in C} x_j \leq |C|-1$ is a valid cover inequality and it holds that $q\leq \sum_{j\in C} x'_j \leq |C|-1$.

Assume $q \leq |C| - 2$. Applying x' to the left-hand side of MKC_{α} results in $q + \frac{1}{b} \left(\sum_{j \in M} a_j x_j' \right) \leq |C| - 2 + \frac{1}{b} \left(\sum_{j \in M} a_j x_j' \right)$. Since x' is feasible, $\sum_{j \in M} a_j x_j' \leq b$. Hence, $|C| - 2 + \frac{1}{b} \left(\sum_{j \in M} a_j x_j' \right) \leq |C| - 1$ and x' satisfies MKC_{α} .

Assume q = |C| - 1 and |M'| = 1. Thus, $x'_j = 1$ for every $j \in C \setminus M$. Since x' is feasible, $\sum_{j \in C \setminus M} a_j x'_j + \sum_{j \in M} a_j x'_j \leq b$. Therefore, $\sum_{j \in M} a_j x'_j \leq b$.

 $b - \sum_{j \in C \setminus M} a_j$. Since M is returned from AMKCA, $a_j > \theta$ for every $j \in M$, where $\theta = b - \sum_{j \in C \setminus M'} a_{f_j}$ (lines 16-17). Thus, $x'_j = 0$ for every $j \in M$ and $\sum_{j \in C \setminus M} x'_j + \frac{1}{b} \left(\sum_{j \in M} a_j x'_j \right) = |C| - 1$.

Assume q = |C| - 1 and |M'| = 0. Since x' is feasible, $\sum_{j \in C} a_j x'_j + \sum_{j \in M} a_j x'_j \leq b$ implies that $\sum_{j \in M} a_j x'_j \leq b - \sum_{j \in C} a_j x'_j$. Because C is sorted and q = |C| - 1, then $\sum_{j \in C} a_j x'_j \geq \sum_{j=2}^{|C|} a_{f_j}$. Since M is returned from AMKCA, every $a_j > \theta$ where $\theta = b - \sum_{j=2}^{|C|} a_{f_j}$ (lines 14-15). Thus, $x'_j = 0$ for every $j \in M$ and $\sum_{j \in C \setminus M} x'_j + \frac{1}{b} \left(\sum_{j \in M} a_j x'_j \right) = |C| - 1$. Hence, MKC_α is valid for P_{KP}^{ch} . The cases are exhaustive and the result is shown.

From Theorem 2.1, AMKCA returns $M = \{h_1, h_2, ..., h_{|M|}\}$ such that MKC_{α} is valid for some $\alpha > 0$. Theorem 2.2 proves that the α value returned by AMKCA implies that $\sum_{j \in C \setminus M} x_j + \alpha \sum_{j \in M} a_j x_j \leq |C| - 1$ is a valid merged knapsack cover inequality for P_{KP}^{ch} .

THEOREM 2.2 Let $\sum_{j\in N} a_j x_j \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, and $M \subseteq N$ be a set of merging indices. Then, $\sum_{j\in C\setminus M} x_j + \alpha' \sum_{j\in M} a_j x_j \leq |C|-1$ is a valid inequality of P_{KP}^{ch} for any $\alpha' \leq \alpha$, where α is returned by AMKCA.

Proof. Let $\sum_{j\in N} a_j x_j \leq b$ be a knapsack constraint, $C\subseteq N$ be a cover, and $M\subseteq N$ be a set of merging indices. For contradiction, assume that there exists an $\alpha'\leq\alpha$ such that $\sum_{j\in C\setminus M} x_j + \alpha'\sum_{j\in M} a_j x_j \leq |C|-1$ is not a valid inequality of P^{ch}_{KP} , where α is returned by AMKCA. Thus, there exists an $x'\in P_{KP}$ such that $\sum_{j\in C\setminus M} x'_j + \alpha'\sum_{j\in M} a_j x'_j > |C|-1$. Define $q=\sum_{j\in C\setminus M} x'_j$ and $C\setminus M=\{t_1,t_2,...,t_{|C\setminus M|}\}$. Since x' is feasible, $\sum_{j\in C\setminus M} a_j x'_j + \sum_{j\in M} a_j x'_j \leq b$ implies that $\sum_{j\in M} a_j x'_j \leq b - \sum_{j\in C\setminus M} a_j x'_j$. Therefore, $\sum_{j\in M} a_j x'_j \leq b - \sum_{j=|C\setminus M|-q+1} a_{t_j}$ due to the sets being sorted.

Assume $q \leq |C|-2$. Since $MKC_{\alpha'}$ is not a valid inequality, $\alpha' \sum_{j \in M} a_j x_j' > |C|-1-q$. Therefore, $\alpha' > \frac{|C|-1-q}{\sum_{j \in M} a_j x_j'}$ implies that $\alpha' > \frac{|C|-1-q}{\left(b-\sum_{j=|C\setminus M|-q+1}^{|C\setminus M|} a_{i_j}\right)}$. However, AMKCA requires $\alpha \leq \frac{|C|-1-q}{\left(b-\sum_{j=|C\setminus M|-q+1}^{|C\setminus M|} a_{i_j}\right)}$ (lines 22-29). Thus, $\alpha' > \alpha$ contradicts α being returned by AMKCA.

Assume $q \geq |C| - 1$. If $q \geq |C|$, x' violates the cover inequality and contradicts C being a cover. If q = |C| - 1, then $\alpha' \sum_{j \in M} a_j x_j' > (|C| - 1) - (|C| - 1)$ implies that $\alpha' > 0$ and $x_j' = 1$ for some $j \in M$. Since $\alpha' > 0$, AMKCA returns an $\alpha > 0$. Thus, $\min\{a_{h_j}: j \in \{1, 2, ...|M|\}\} > b - \sum_{j=2}^{|C|} a_{f_j}$ for |M'| = 0 or $\min\{a_{h_j}: j \in \{1, 2, ...|M|\}\} > b - \sum_{j \in C \setminus M} a_{f_j}$ for |M'| = 1 (lines 14-17). Both cases contradict the feasibility of x' and the result follows.

The following example demonstrates the implementation of AMKCA to generate valid approximate merged knapsack cover inequalities.

Example 2.1 Consider the knapsack constraint described in (1), where $x_j \in \{0, 1\}$ for every $j \in \{1, 2, ..., 11\}$. Let $C = \{5, 6, 7, 8, 9\}$ be a cover and $M' = \emptyset$ for this example.

$$30x_1 + 25x_2 + 20x_3 + 15x_4 + 12x_5 + 11x_6 + 11x_7 + 10x_8 + 10x_9 + 5x_{10} + x_{11} \le 44$$
 (1)

Since the knapsack constraint in (1) and the cover C are given in a sorted order, and because $M'=\emptyset$, the first steps in AMKCA initializes $M=\emptyset$, l=5-0=5, $\alpha=\infty$ and p=5-2=3 (lines 2-12). The subsequent step in AMKCA calculates $\theta=b-\sum_{j=2}^{|C|}a_{f_j}$, where $C=\{f_1,f_2,...,f_{|C|}\}$ (lines 13-21). Consequently, $\theta=2$ and M contains every $j\in N\setminus C$ such that $a_j>\theta=2$. Therefore, $M=\{1,2,3,4,10\}$. Observe that including the index corresponding to variable x_{11} in M violates the conditions described in Theorem 2.1. The following step in AMKCA calculates a value for α such that $\alpha=\min\{\frac{|C|-1-q}{\theta}\}$ for every $q=\{0,...,|C|-2\}$ (lines 22-29). Thus, $\alpha=\min\{\frac{4}{44},\frac{3}{34},\frac{2}{24},\frac{1}{13}\}=\frac{1}{13}$. The algorithm terminates (lines 30-32) and reports $\alpha=\frac{1}{13},\ M=\{1,2,3,4,10\}$, and the valid approximate merged knapsack cover inequality $MKC_{\frac{1}{13}}$ presented in (2).

$$x_5 + x_6 + x_7 + x_8 + x_9 + \frac{1}{13}(30x_1 + 25x_2 + 20x_3 + 15x_4 + 5x_{10}) \le 4$$
 (2)

Observe that $MKC_{\frac{1}{13}}$ is also a cutting plane. To show that, consider the linear relaxation solution $x^{LR}=(0,0,0,\frac{2}{15},0,1,1,1,1,0,0)\in P^{LR}$. Applying x^{LR} to $MKC_{\frac{1}{13}}$ results in $\sum_{j\in C\backslash M}x_j^{LR}+\frac{1}{13}\sum_{j\in M}a_jx_j^{LR}=\frac{54}{13}$. Since $\frac{54}{13}>4$, $MKC_{\frac{1}{13}}$ cuts off the corresponding x^{LR} .

2.2. Exact Merged Knapsack Cover Inequalities

Since the MKC_{α} determined by AMKCA is approximate, an obvious question is whether these inequalities can be strengthened. This paper also presents a technique to determine an $\alpha^* \in \mathbb{R}_+$ such that α^* cannot be increased and the inequality remains valid. These type of inequalities are referred to as exact merged knapsack cover inequalities.

Observe that AMKCA determines an α value such that $\alpha = \min\left\{\frac{|C|-1-q}{\theta_q}\right\}$ for every $q = \{0, ..., |C|-2\}$, where θ_q is dependent on the value of q. Exact merged knapsack cover inequalities have an α^* such that there exists an $x^{KP} \in P_{KP}$ that meets MKC_{α^*} at equality. Thus, one can determine the value of α^* by maximizing $z = \sum_{j \in M} a_j x_j$, subject to $\sum_{j \in M} a_j x_j \leq \theta_q$ and $x_j \in \{0,1\}$ for all $j \in M$. If $\alpha^* = \min\left\{\frac{|C|-1-q}{z_q}\right\}$ for every $q = \{0, ..., |C|-2\}$, where z_q also depends on the value of q, then an optimal solution to the aforementioned maximization problem satisfies MKC_{α^*} at equality, and MKC_{α^*} is an exact merged knapsack cover inequality. Since C is assumed to be minimal, and $q \leq |C| - 2$, then $z_q > 0$ for each of these subproblems.

The exact merging knapsack cover algorithm (EMKCA), described in Algorithm 2, uses dynamic programming to determine the largest possible value of α^* . This is achieved by tracking an array $d=(d_0,d_1,...,d_b)$, where $d_k\in\{0,1\}$ for each $k\in\{0,...,b\}$ (lines 12-15). If the sum of the coefficients of any combination of feasible solutions with indices in M equals k, then $d_k=1$. If not, $d_k=0$ for all $k\in\{0,...,b\}$. Once d is computed, θ is updated by the same method as in AMKCA and z is determined as the maximum index $k\leq\theta$ such that $d_k=1$ (lines 16-29).

The input to EMKCA is a knapsack constraint $\sum_{j\in N} a_j x_j \leq b$, a cover $C\subseteq N$, and a set of merging indices $M\subseteq N$. The set M must satisfy the conditions of Theorem 2.1. Therefore, running steps (A) and (B) of AMKCA is sufficient to identify a suitable $M=\{h_1,h_2,...,h_{|M|}\}$. The output to EMKCA is an $\alpha^*\in\mathbb{R}_+$

and the exact merged knapsack cover inequality $\sum_{j \in C \setminus M} x_j + \alpha^* \sum_{j \in M} a_j x_j \le |C| - 1$ (lines 30-32).

Algorithm 2: Exact Merging Knapsack Cover Algorithm (EMKCA)

```
1: begin
 2: (A) INITIALIZATION
          d_0 \leftarrow 1
 3:
           d_k \leftarrow 0 \text{ for all } k \in \{1, ..., b\}
 4:
           \theta \leftarrow b
 5:
          l \leftarrow |C \setminus M|
 6:
           \alpha^* \leftarrow \infty
 7:
           if |C \cap M| \leq 2 then
                p \leftarrow |C| - 2
 9:
          else
10:
                p \leftarrow |C \setminus M|
11:
12: (B) Compute d
           for q = 1 to |M| do
13:
14:
                for r = b - a_{h_q} to 0 do
                     if d_r = 1 then d_{r+a_{h_q}} \leftarrow 1
15:
     (c) Calculate \alpha^*
16:
           for q = 0 to p do
17:
                t \leftarrow \theta
18:
                flag \leftarrow 0
19:
                while flag = 0 do
20:
                      if d_t = 1 then
21:
22:
                           z \leftarrow t
                           flag \leftarrow 1
23:
                \alpha' \leftarrow \frac{t-1}{|C|-1-q}
24:
25:
                if \alpha' < \alpha^* then \alpha^* \leftarrow \alpha'
26:
                if q < p then
27:
                      \theta \leftarrow \theta - a_f
28:
                     l \leftarrow l - 1
29:
     (D) OUTPUT
30:
           return \alpha^* \in \mathbb{R}^+
31:
          return MKC_{\alpha^*} \leftarrow \sum_{j \in C \setminus M} x_j + \alpha^* \sum_{j \in M} a_j x_j \leq |C| - 1
32:
33: end
```

Computational complexity of EMKCA is clearly $O(bn + n \log n)$. Since the running time is a function of input data, EMKCA is a pseudo-polynomial time algorithm that solves quickly if the right-hand side b is bounded by a constant. The following theorem formally proves that EMKCA generates valid exact merged knapsack cover inequalities.

THEOREM 2.3 Let $\sum_{j\in N} a_j x_j \leq b$ be a knapsack constraint, $C\subseteq N$ be a cover, $M\subseteq N$ be a set of merging indices, and α^* be returned by EMKCA. Thus, $\sum_{j\in C\setminus M} x_j + \alpha' \sum_{j\in M} a_j x_j \leq |C| - 1$ is a valid inequality of P_{KP}^{ch} for any $\alpha' \leq \alpha^*$ and is not a valid inequality of P_{KP}^{ch} for any $\alpha' > \alpha^*$.

Proof. Let $\sum_{j\in N} a_j x_j \leq b$ be a knapsack constraint, $C\subseteq N$ be a cover, $M\subseteq N$ be a set of merging indices, and α^* be returned by EMKCA. Assume $\alpha'\leq\alpha^*$ and let $x'\in P_{KP}$. Define $q'=\sum_{j\in C\setminus M} x_j'$ and $z'=\sum_{j\in M} a_j x_j'$. From Algorithm 2, $d_{z'}=1$ (lines 12-15 and lines 21-22). Thus, $\alpha^*\leq\frac{|C|-1-q'}{z'}$ (line 25). Consequently, $\sum_{j\in C\setminus M} x_j'+\alpha'\sum_{j\in M} a_j x_j'\leq q'+\frac{|C|-1-q'}{z'}z'\leq |C|-1$. Therefore, $\sum_{j\in C\setminus M} x_j'+\alpha'\sum_{j\in M} a_j x_j'\leq |C|-1$ is valid for P_{KP}^{ch} .

Assume $\alpha' > \alpha^*$. Let q'' and z'' be the values of q and z, respectively, that generated α^* in EMKCA. Clearly, $d_{z''} = 1$ and there exists an $x'' \in P_{KP}$ such that $\sum_{j \in C \setminus M} x_j'' = q''$ and $\sum_{j \in M} a_j x_j'' = z''$. Applying x'' to $MKC_{\alpha'}$ results in $q'' + \alpha' z'' > q'' + \alpha^* z'' = q'' + \frac{|C|-1-q''}{z''} z'' = |C|-1$. Thus, x'' violates $MKC_{\alpha'}$ and $MKC_{\alpha'}$ is not a valid inequality of P_{KP}^{ch} .

Theorem 2.3 proves that merged knapsack cover inequalities reported by EMKCA are exact because the x'' from the proof demonstrates that $MKC_{\alpha'}$ supports P_{KP}^{ch} . Example 2.2 demonstrates the implementation of EMKCA.

Example 2.2 Consider the knapsack constraint presented in (1), the same cover $C = \{5, 6, 7, 8, 9\}$ from Example 2.1, and the set of merging indices $M = \{1, 2, 3, 4, 10\}$ returned by AMKCA.

EMKCA initializes $d_0 = 1$, $\theta = 44$, l = 5, $\alpha^* = \infty$, and p = 5 - 2 = 3 (lines 2-11). Step (B) of EMKCA runs |M| times and defines the combination of all possible integers that can be achieved by points restricted to indices in M (lines 12-15). Table 1 summarizes the final array d. Therefore, any combination of points from $\sum_{j \in C \setminus M} x_j$ results in $\sum_{j \in M} a_j x_j$ being equal to an integer represented by any index of d where $d_k = 1$ for all $k \in \{0, 1, ..., b\}$.

Table 1. Final array d of Example 2.2.

0 1		2 0	-	5 1			11 0		
_				20 1				27 0	29 0
30 1	31 0	32 0		35 1			41 0		

The algorithm continues and calculates a value for α^* such that $\alpha^* = \min\left\{\frac{|C|-1-q}{2}\right\}$ for every $q=\{0,...,|C|-2\}$ (lines 16-29). Therefore, $\alpha^* = \min\left\{\frac{4}{40},\frac{3}{30},\frac{2}{20},\frac{1}{5}\right\} = \frac{1}{10}$ and EMKCA reports $\alpha^* = \frac{1}{10}$ along with the valid exact merged knapsack cover inequality $MKC_{\frac{1}{10}}$ presented in (3) (lines 30-32).

$$x_5 + x_6 + x_7 + x_8 + x_9 + \frac{1}{10}(30x_1 + 25x_2 + 20x_3 + 15x_4 + 5x_{10}) \le 4$$
 (3)

Observe that $MKC_{\frac{1}{10}}$ is exact while $MKC_{\frac{1}{13}}$ is approximate. For instance, let $x^{KP}=(0,0,1,0,0,0,0,1,1,0,1)\in P_{KP}$. Applying x^{KP} to $MKC_{\frac{1}{10}}$ and $MKC_{\frac{1}{13}}$ results in $MKC_{\frac{1}{10}}$ being equal to 4 while $MKC_{\frac{1}{13}}$ being equal to $\frac{46}{13}$. Thus, the corresponding solution x^{KP} meets $MKC_{\frac{1}{10}}$ at equality, but not $MKC_{\frac{1}{13}}$. The reader can enumerate every $x^{KP}\in P_{KP}$ and see that the argument holds for all cases.

Clearly, $MKC_{\frac{1}{10}}$ dominates $MKC_{\frac{1}{13}}$. In addition, $MKC_{\frac{1}{10}}$ is facet defining while $MKC_{\frac{1}{13}}$ is not a facet defining inequality. Table 2 presents 11 affinely independent

dent points that meet $MKC_{\frac{1}{10}}$ at equality as part of the facet defining proof for $MKC_{\frac{1}{10}}$. Furthermore, $MKC_{\frac{1}{10}}$ is also a cutting plane because $\sum_{j\in C\backslash M} x_j^{LR} + \frac{1}{10}\sum_{j\in M}a_jx_j^{LR} = \frac{21}{5} > 4$, where $x^{LR} = (0,0,0,\frac{2}{15},0,1,1,1,1,0,0) \in P^{LR}$ from Example 2.1. Observe that $\frac{21}{5} > \frac{54}{13}$ and $MKC_{\frac{1}{10}}$ also cuts off x^{LR} by more than $MKC_{\frac{1}{12}}$.

Sequence independent lifting [49] is similar to both approximate and exact merged knapsack cover inequalities because the lifted coefficients are correlated to the size of the knapsack coefficients. For instance, consider the same knapsack constraint and cover from Examples 2.1 and 2.2. The resulting sequence independent lifted inequality is given in (4). Observe that $MKC_{\frac{1}{10}}$ weakly dominates the sequence independent lifted inequality in this case. Moreover, the sequence independent lifted inequality in (4) is not facet defining while $MKC_{\frac{1}{10}}$ is a facet defining inequality.

$$x_5 + x_6 + x_7 + x_8 + x_9 + \frac{25}{9}x_1 + \frac{20}{9}x_2 + \frac{16}{9}x_3 + \frac{11}{9}x_4 + \frac{1}{3}x_{10} \le 4$$
 (4)

To demonstrate EMKCA when $M' \neq \emptyset$, consider the same knapsack constraint described in (1) and cover $C = \{5, 6, 7, 8, 9\}$. Let $M' = \{9\}$ and the inequality presented in (5) is returned by AMKCA while the inequality presented in (6) is returned by EMKCA. In this case, EMKCA's inequality weakly dominates AMKCA's inequality as well.

$$x_5 + x_6 + x_7 + x_8 + \frac{1}{12}(30x_1 + 25x_2 + 20x_3 + 15x_4 + 10x_9 + 5x_{10} + x_{11}) \le 4$$
 (5)

$$x_5 + x_6 + x_7 + x_8 + \frac{1}{11}(30x_1 + 25x_2 + 20x_3 + 15x_4 + 10x_9 + 5x_{10} + x_{11}) \le 4$$
 (6)

3. Computational Study

This paper also presents a computational study that evaluates the real effectiveness of both AMKCA and EMKCA to solve MKPs. Multiple knapsack instances

were first solved in CPLEX [60], a high performance mathematical programming solver, at default settings. Thus, approximate and exact merged knapsack cover inequalities were added as preprocessing cuts, and the problems were solved again

with these newly developed cutting planes. The computational study was performed on an $Intel^{\circledR}$ $Core^{TM}$ i7-6700 3.4GHz processor with 32 GB of RAM. Both AMKCA and EMKCA were implemented in C++ using Microsoft Visual Studio and CPLEX Version 12.7. Computational experiments also stored node files in the hard drive instead of RAM in order to avoid running out of memory.

Computational experiments evaluated approximate and exact merged knapsack cover inequalities with and without overlapping variables between C and M. Therefore, computational experiments tested these inequalities with |M'|=0, |M'|=1, and |M'|=2. Observe that only one inequality was implemented at a time for each multiple knapsack instance.

This study implemented these inequalities with minimal covers as discussed in Section 1. Furthermore, one cover inequality was generated for each constraint of the multiple knapsack instance. The cover inequality of each knapsack constraint $i \in R$ was generated by selecting variables $x_j^{LR^*}$ with the greatest ratios $r_j^{LR^*} = \frac{d_j^{LR^*}}{a_{i,j}} + x_j^{LR^*}$ for all $j \in N$, where $d_j^{LR^*}$ is the reduced cost of variable $x_j^{LR^*}$. Additionally, the knapsack constraint $i \in R$ selected to generate the newly cre-

Additionally, the knapsack constraint $i \in R$ selected to generate the newly created inequalities for each instance was determined as the i^{th} constraint with the max $\left\{\sum_{j \in C_i} x_j^{LR^*}\right\}$. Observe that the computational time to generate cover inequalities, approximate and exact merged knapsack cover inequalities, and perform other preprocessing operations were not included in the final results. However, these times were less than 0.01 seconds for every implementation and would not have impacted the final results.

Improvement in solution time for each instance is computed by $\Delta_{time} = \left(\frac{s_{\text{CPLEX}} - s_{\text{MKCA}}}{s_{\text{CPLEX}}}\right) \times 100\%$ and improvement in the number of ticks is calculated as $\Delta_{ticks} = \left(\frac{t_{\text{CPLEX}} - t_{\text{MKCA}}}{t_{\text{CPLEX}}}\right) \times 100\%$, where s_{MKCA} corresponds to the solution time and t_{MKCA} is the number of ticks when solved with either approximate or exact merged knapsack cover inequalities, and s_{CPLEX} is the solution time and t_{CPLEX} represents the number of ticks when solved with CPLEX at default settings. When Δ_{time} and Δ_{ticks} of all instances from a corresponding problem set are averaged, it creates $\overline{\Delta_{time}}$ and $\overline{\Delta_{ticks}}$, respectively.

3.1. Computational Experiments for AMKCA

This paper first describes the results obtained with the implementation of AMKCA. Multiple knapsack instances solved in this study are benchmark problems from the OR-Library [61]. These problems set are named as mknapcb1, mknapcb2, ..., mknapcb9 and each problem set contains 30 instances with: 100, 250, and 500 variables; 5, 10, and 30 constraints. These MKPs are suggested by Chu and Beasley [32] and take the form of maximize $z = \sum_{j \in N} c_j x_j$, subject to $\sum_{j \in N} a_{i,j} x_j \leq b_i$ for all $i \in R$ and $x_j \in \{0,1\}$ for all $j \in N$.

Each $a_{i,j}$ is integer, randomly generated, and uniformly distributed between an lb and ub, where lb = 0 and ub = 1,000. Right-hand side values were calculated as $b_i = \lfloor \delta \sum_{j \in N} a_{i,j} \rfloor$, where δ represents the tightness ratio. Cost coefficients were generated as $c_j = \sum_{i \in R} a_{i,j} + \lfloor 500\gamma_j \rfloor$, where γ_j is a uniform random number between 0 and 1. Observe that each problem set from the OR-Library has 10 instances with $\delta = 0.25$, 10 instances with $\delta = 0.50$, and 10 instances with $\delta = 0.75$.

This paper solved the following problems set from the OR-Library: mknapcb1, mknapcb2, mknapcb3, mknapcb4, mknapcb5, and mknapcb7. Results for mknapcb6, mknapcb8, and mknapcb9 are not reported in this paper because numerous instances in each of these problems set could not be solved to optimality within a time limit of 24 hours. On average, instances in mknapcb1, mknapcb2, and mknapcb4 were solved in less than one minute, instances in mknapcb7 were solved in less than 20 minutes, instances in mknapcb3 were solved in less than 1.5 hours, and instances in mknapcb5 were solved within 3.5 hours. Since problems set mknapcb3 and mknapcb5 appear to be more significant, the solution time and number of ticks for each instance of these sets are presented.

Table 3. Solution time in seconds (s_{CPLEX} and s_{MKCA}) and number of ticks (t_{CPLEX} and t_{MKCA}) obtained when AMKCA is tested with instances in problem set mknapcb3 from the OR-Library (500 variables and 5 constraints).

δ	#	z^{MKP*}		Ti	me			Tio	ks	
	"	~	CPLEX	M' = 0	M' = 1	M' =2	CPLEX	M' = 0	M' = 1	M' =2
	1	120,148	36,934	28,368	34,018	25,977	963,584	651,123	605,318	551,337
	2	117,879	533	493	272	380	43,538	41,037	30,669	33,835
	3	121,131	3,795	3,823	3,887	4,711	193,531	224,182	224,300	239,284
	4	120,804	2,822	2,701	1,746	3,007	195,990	192,826	176,250	189,761
0.25	5	122,319	651	622	639	586	67,145	65,835	68,847	$65,\!573$
0.25	6	122,024	983	963	868	905	150,098	117,044	$110,\!274$	111,720
	7	119,127	57,114	55,726	$55,\!172$	52,208	607,606	669,035	782,955	596,255
	8	$120,\!568$	366	418	404	373	80,258	79,576	77,837	75,227
	9	$121,\!586$	8,394	8,653	8,333	7,796	$602,\!556$	670,157	632,483	481,723
	10	120,717	6,954	7,291	4,949	$7,\!251$	319,905	346,621	$240,\!408$	356,204
	Average		11,855	10,906	11,029	10,319	$322,\!421$	305,744	294,934	270,092
	11	218,428	281	230	222	221	73,447	64,293	62,036	61,718
	12	221,202	243	177	177	216	$64,\!651$	44,336	45,425	$50,\!654$
	13	$217,\!542$	2,240	983	989	699	2,049,860	387,531	345,191	154,428
	14	223,560	1,139	1,104	1,028	1,043	177,378	175,958	172,310	173,538
0.50	15	218,966	53	44	46	44	19,209	15,880	16,270	15,923
0.50	16	$220,\!530$	425	343	310	313	117,202	$98,\!356$	$92,\!540$	92,072
	17	219,989	155	128	129	131	49,432	42,629	43,148	44,074
	18	218,215	326	274	102	96	41,195	45,074	29,803	$28,\!503$
	19	216,976	364	350	358	350	102,715	$104,\!596$	107,187	103,102
	20	219,719	392	760	477	404	$114,\!352$	134,245	124,088	119,136
	Aver	age	562	439	384	352	280,944	111,290	103,800	84,315
	21	295,828	8	8	8	8	2,284	2,529	2,595	2,476
	22	308,086	91	75	73	92	28,000	$23,\!586$	23,327	27,662
	23	299,796	38	32	34	33	11,555	9,991	10,659	10,247
	24	306,480	214	167	163	163	60,935	50,357	48,948	49,501
0.75	25	300,342	50	53	54	53	$13,\!553$	$14,\!425$	14,889	$14,\!535$
0.75	26	$302,\!571$	101	48	95	57	27,565	13,905	26,959	$16,\!463$
	27	301,339	849	1,139	1,098	1,129	42,530	$52,\!504$	53,088	53,363
	28	$306,\!454$	62	18	29	45	$15,\!435$	$4,\!532$	6,118	11,775
	29	$302,\!828$	94	54	66	70	24,493	14,201	16,740	19,819
	30	299,910	185	163	171	172	49,818	46,547	48,909	48,801
	Aver	age	169	176	179	182	27,617	23,258	25,223	25,464

Tables 3 and 4 provide the solution time and number of ticks for instances in problems set mknapcb3 and mknapcb5. Let # denote which particular instance refers to the data set. Table 5 presents $\overline{\Delta_{time}}$ and $\overline{\Delta_{ticks}}$ for all 10 instances in each problem set tested in this study with $\delta=0.25$, $\delta=0.50$, and $\delta=0.75$. Recall that |N| is the total number of variables and |R| is the total number of constraints in each problem set. For mknapcb3, the average percentage improvement in solution time is 9.9% when |M'|=0, 15.5% when |M'|=1, and 13.3% when |M'|=2. Number of ticks are improved on average by 11.3% when |M'|=0, 12.2% when |M'|=1, and 12.4% when |M'|=2. For mknapcb5, solution time is improved on average by 1.9%, 3.6%, and 2.5% when |M'|=0, |M'|=1, and |M'|=2,

respectively. Furthermore, the average percentage improvement in the number of ticks is 1.1% for |M'| = 0, 1.9% for |M'| = 1, and 0.8% for |M'| = 2.

Table 4. Solution time in seconds (s_{CPLEX} and s_{MKCA}) and number of ticks (t_{CPLEX} and t_{MKCA}) obtained when AMKCA is tested with instances in problem set mknapcb5 from the OR-Library (250 variables and 10 constraints).

δ	#	z^{MKP*}		Tiı	me			Ti	cks	
	"	~	CPLEX	M' = 0	M' = 1	M' =2	CPLEX	M' = 0	M' =1	M' =2
	1	59,187	13,356	14,426	14,727	14,825	1,655,035	1,799,932	1,837,299	1,849,424
	2	58,781	5,383	4,870	3,918	4,761	293,903	290,739	236,981	284,223
	3	58,097	4,388	4,871	4,652	4,926	278,116	288,010	287,053	296,163
	4	61,000	20,413	20,112	21,916	$22,\!867$	2,594,848	2,483,525	2,615,185	2,694,179
0.25	5	58,092	56,474	59,365	61,138	61,057	6,995,591	7,343,748	7,565,223	7,597,400
0.25	6	58,824	7,528	6,544	6,777	6,399	416,930	339,391	334,522	324,025
	7	58,704	6,667	5,321	5,417	5,449	278,173	259,731	260,490	260,758
	8	58,936	40,499	47,902	49,937	47,827	5,609,246	6,662,269	6,930,348	6,638,090
	9	59,387	7,179	7,036	7,055	7,058	623,819	620,053	621,679	621,956
	10	$59,\!208$	14,683	15,931	15,323	16,652	1,329,861	$1,\!432,\!828$	1,377,768	$1,\!506,\!192$
	Averag		17,657	18,638	19,086	19,182	2,007,552	2,152,023	2,206,655	2,207,241
	11	110,913	10,336	13,086	11,860	12,515	840,879	1,054,597	954,854	1,008,154
	12	108,717	13,784	11,822	11,787	11,196	1,212,435	1,099,852	1,155,044	1,077,073
	13	108,932	8,859	7,670	7,669	7,579	1,014,826	890,074	889,910	879,614
	14	110,086	33,651	33,616	33,292	33,597	4,115,762	4,094,506	4,030,001	4,076,060
0.50	15	108,485	5,942	5,124	5,246	5,175	457,495	402,188	411,568	406,124
0.50	16	110,845	14,029	13,703	13,510	13,302	1,375,114	1,326,986	1,318,684	1,333,611
	17	106,077	16,051	13,796	14,370	14,166	1,639,047	1,440,350	1,446,479	1,446,363
	18	106,686	9,434	10,270	10,225	10,239	1,077,533	1,162,989	1,179,287	1,180,920
	19	109,829	9,530	9,282	9,268	9,326	1,021,183	1,005,362	1,003,806	1,010,045
	20	106,723	7,214	6,343	6,340	6,432	377,800	312,434	$329,\!835$	330,633
	Aver	age	12,883	$12,\!471$	$12,\!357$	12,353	1,313,208	1,278,934	$1,\!271,\!947$	1,274,860
	21	151,809	3,537	4,088	4,201	4,231	247,678	269,718	269,878	275,707
	22	148,772	8,590	9,419	9,127	9,140	649,820	751,309	749,183	749,183
	23	151,909	3,201	3,009	2,948	2,711	195,756	$181,\!553$	181,720	181,087
	24	$151,\!324$	2,311	2,261	2,201	2,151	$161,\!687$	154,049	157,484	$157,\!484$
0.75	25	151,966	8,243	6,182	5,887	5,771	511,072	318,843	322,124	320,081
0.75	26	152,109	1,619	1,527	1,521	1,531	136,431	127,645	127,110	127,988
	27	153,131	248	226	193	204	23,155	22,117	20,460	20,658
	28	$153,\!578$	9,572	10,220	10,042	10,024	$1,\!163,\!710$	$1,\!254,\!598$	1,232,946	1,230,807
	29	149,160	1,984	1,515	1,570	1,584	$125,\!201$	116,879	118,869	117,710
	30	149,704	1,747	2,005	1,716	1,872	129,039	159,085	$146,\!597$	152,603
	Aver	age	4,105	4,045	3,941	3,922	334,355	335,580	332,637	333,331

When considering the overall average described in Table 5, solution time is improved on average by 8.0% when |M'| = 0, 8.3% when |M'| = 1, and 8.5% when |M'| = 2. Improvement in the number of ticks are 4.9% for |M'| = 0, 4.5% for |M'| = 1, and 5.1% for |M'| = 2. Observe that on average, computational results of approximate merged knapsack cover inequalities implemented with |M'| = 0, |M'| = 1, and |M'| = 2 are somewhat similar for the cases reported in this paper, and no conclusions can be made on which overlapping strategy is more efficient.

3.2. Computational Experiments for EMKCA

Exact merged knapsack cover inequalities were generated by EMKCA and also tested with benchmark instances from the OR-Library. In such a case, EMKCA's input was the same knapsack constraint and cover inequality used by AMKCA, and the set of merging indices M returned by AMKCA. Surprisingly, each benchmark instance solved with EMKCA had $\alpha^* = \alpha$. Consequently, AMKCA generated exact merged knapsack cover inequalities for all the cases.

To investigate why EMKCA did not have any $\alpha^* > \alpha$, the authors tracked the array d from EMKCA and noticed that d had the majority, if not all, of its indices

Table 5. $\overline{\Delta_{time}}$ and $\overline{\Delta_{ticks}}$ of all 10 instances for each problem set tested from the OR-Library.

Name	N	R	δ		Time			Ticks	
	• •	10		M' = 0	M' = 1	M' = 2	M' = 0	M' = 1	M' = 2
			0.25	4.7%	-0.4%	3.4%	-1.1%	-3.9%	-2.7%
mknapcb1	100	5	0.50	4.6%	-2.1%	6.2%	-0.5%	2.3%	1.7%
			0.75	10.7%	12.9%	12.7%	-1.8%	-2.3%	1.7%
			Average	6.7%	3.5%	7.4%	-1.1%	-1.3%	1.2%
			0.25	18.7%	12.9%	12.7%	-1.8%	-2.3%	4.5%
mknapcb2	250	5	0.50	10.8%	13.7%	13.2%	11.0%	11.6%	11.1%
			0.75	-3.8%	-6.5%	-8.4%	-7.5%	-10.3%	-11.4%
			Average	8.6%	6.8%	7.7%	5.2%	2.4%	3.7%
			0.25	2.1%	12.9%	5.5%	1.9%	7.9%	8.9%
mknapcb3	500	5	0.50	8.6%	22.1%	24.1%	14.4%	19.5%	20.8%
-			0.75	19.1%	11.5%	10.2%	17.5%	9.2%	7.5%
			Average	9.9%	15.5%	13.3%	11.3%	$\boldsymbol{12.2\%}$	12.4%
			0.25	11.1%	10.3%	10.0%	4.9%	4.1%	3.9%
mknapcb4	100	10	0.50	10.0%	9.6%	9.5%	9.3%	8.8%	9.5%
			0.75	3.4%	4.1%	3.6%	3.5%	3.1%	3.9%
			Average	8.1%	8.0%	7.7%	5.9%	5.3%	5.8%
			0.25	-0.5%	-0.2%	-2.8%	-1.3%	-0.4%	-3.0%
mknapcb5	250	10	0.50	3.7%	4.7%	4.7%	3.5%	3.6%	3.6%
			0.75	2.4%	6.2%	5.8%	1.2%	2.6%	2.0%
			Average	1.9%	3.6%	2.5%	1.1%	1.9%	0.8%
			0.25	17.3%	15.9%	17.2%	8.1%	7.3%	9.1%
mknapcb?	100	30	0.50	12.9%	13.1%	11.8%	6.1%	5.2%	4.8%
			0.75	8.4%	7.7%	7.8%	7.5%	6.3%	6.2%
			Average	12.9%	12.2%	12.3%	7.3%	6.3%	6.7%
Ov	Overall Average				8.3%	8.5%	4.9%	4.5%	5.1%

marked with a 1. Hunsaker and Tovey [62] show that when knapsack instances are randomly generated, there exists a set $G \subseteq N$ with probability approaching 1 such that $\sum_{j \in G} a_j x_j = b$. Consequently, many random knapsack instances eliminate gaps in d and so $\alpha^* = \alpha$.

To identify instances in which EMKCA produces inequalities that dominate the inequalities generated by AMKCA, observe that if all $a_{i,j}$ are random between 1 and some a_{\max} , then several small and one large number can be combined to create numerous combinations between 1 and $2 \times a_{\max}$. Therefore, EMKCA may be useful if $a_{i,j}$ is between some a_{\min} and a_{\max} , where a_{\min} is at least 50% of a_{\max} . Since there does not exist any publicly available benchmark instances that follow this criterion, new instances were randomly generated to test EMKCA. This paper attempted two sets of problems where a_{\min} is 50% and 60% of a_{\max} . These instances follow the same form proposed by Chu and Beasley [32] but instead, they have constraint coefficients from 2,500 to 5,000 (lb=2,500 and ub=5,000) and from 3,000 to 5,000 (lb=3,000 and ub=5,000). Additional experiments where a_{\min} is 90% of a_{\max} are also provided in Vitor [59].

Since the knapsack coefficients of the newly generated random instances are greater than the knapsack coefficients of the instances from the OR-Library, problems of the same size (100, 250, and 500 variables vs. 5, 10, and 30 constraints) are computationally challenging and could not be solved within 24 hours. Consequently, only the following variations of variables and constraints were tested: 40×5 , 60×5 , 80×5 , and 100×5 . Similar to the OR-Library, 30 instances were generated for each of these problems set where 10 instances have $\delta = 0.25$, 10 instances have $\delta = 0.50$, and 10 instances have $\delta = 0.75$.

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> On average, instances with 40 variables and 5 constraints were solved in less than 30 seconds, 60 variables and 5 constraints were solved within 15 minutes, 80 variables and 5 constraints were solved in less than 30 minutes, and instances with 100 variables and 5 constraints were solved within 2 hours. For simplicity, only instances that are more significant $(80 \times 5 \text{ and } 100 \times 5)$ have the solution time and number of ticks reported in this paper. In addition, only the solution time and number of ticks from MKPs where lb = 3,000 and ub = 5,000 are presented since the time and number of ticks required to solve instances where lb = 2,500 and ub = 5,000 are in the same order of magnitude.

> Table 6 describes the results for instances with 80 variables and 5 constraints, and Table 7 presents the results for instances with 100 variables and 5 constraints when lb = 3,000 and ub = 5,000. Table 8 shows $\overline{\Delta_{time}}$ and $\overline{\Delta_{ticks}}$ for MKPs where lb = 2,500 and ub = 5,000, while Table 9 describes the results for MKPs with lb = 3,000 and ub = 5,000.

Table 6. Solution time in seconds (s_{CPLEX} and s_{MKCA}) and number of ticks (t_{CPLEX} and t_{MKCA}) obtained when EMKCA is tested with the newly generated random instances (80 variables and 5 constraints, lb = 3,000 and ub = 5,000).

δ	#	z^{MKP*}		$\mathbf{Ti}_{\mathbf{i}}$	me			Tic	cks	
	"	~	CPLEX	M' = 0	M' = 1	M' = 2	CPLEX	M' = 0	M' =1	M' =2
	1	306,856	13	14	12	12	1,483	1,591	1,429	1,416
	2	305,174	412	308	317	330	34,013	25,872	29,003	27,606
	3	302,659	274	153	147	179	16,094	14,492	14,314	15,909
	4	305,681	240	64	62	75	10,452	7,941	8,043	8,721
0.25	5	305,412	1,119	873	784	778	137,329	123,051	120,288	122,359
0.25	6	304,329	444	328	331	320	31,470	28,846	28,561	29,076
	7	307,051	345	188	185	188	21,002	17,116	17,206	17,617
	8	305,596	252	98	102	95	11,907	9,628	10,240	9,758
	9	304,410	414	337	282	268	28,012	22,456	23,102	22,454
	10	307,926	280	85	83	82	11,312	9,087	9,249	9,035
	Average		379	245	230	233	30,307	26,008	26,144	26,395
	11	612,457	11	8	7	11	1,151	1,037	1,062	1,269
	12	609,312	804	635	526	522	79,464	90,415	75,540	76,624
	13	604,381	869	555	521	528	86,548	73,147	74,140	73,818
	14	610,098	4,782	3,039	3,165	3,326	849,785	654,599	662,967	708,887
0.50	15	610,287	828	495	647	655	83,604	63,987	72,838	70,892
0.50	16	607,745	1,367	959	901	866	176,228	141,850	145,215	142,257
	17	610,020	1,538	1,035	1,081	1,028	233,426	190,440	202,157	180,326
	18	608,220	73	49	47	48	3,933	4,392	4,362	4,443
	19	614,610	381	243	244	223	28,805	22,464	21,971	20,657
	20	$615,\!434$	2,980	1,083	1,081	1,090	521,019	187,990	192,793	190,608
	Avei	age	1,363	810	822	830	206,396	143,032	$145,\!305$	146,978
	21	$915,\!422$	228	89	89	87	13,058	10,553	10,486	10,417
	22	911,537	403	440	505	447	28,973	35,164	38,479	35,391
	23	904,455	249	95	97	94	9,328	10,778	11,034	10,737
	24	913,181	561	449	442	451	47,547	42,785	41,207	41,421
0.75	25	913115	1,957	1,146	1,142	1,166	332,707	227,867	230,703	234,761
0.75	26	$909,\!672$	169	63	61	61	6,777	7,291	7,451	7,506
	27	917,076	1,575	1,164	1,371	1,419	236,014	187,904	201,840	200,749
	28	912,923	423	290	418	252	31,820	23,991	28,066	20,614
	29	909,901	437	342	326	341	33,535	32,020	31,301	32,783
	30	919,204	596	360	364	384	44,869	37,674	$35,\!485$	40,203
	Avei	age	660	444	482	470	78,463	61,603	63,605	63,458

Overall, the average percentage improvement in solution time for MKPs where lb = 2,500 and ub = 5,000 (Table 8) is 12.8% when |M'| = 0,13.2% when |M'| = 1,and 15.6% when |M'|=2. Furthermore, the number of ticks are reduced on average by 5.1% when |M'| = 0, 5.3% when |M'| = 1, and 7.1% when |M'| = 2. For MKPs where lb = 3,000 and ub = 5,000 (Table 9), solution time is improved on average by 16.3\%, 16.1\%, and 14.6\% when |M'| = 0, |M'| = 1, and |M'| = 2, respectively.

Moreover, the average percentage improvement in the number of ticks is 5.1%, 4.3%, and 3.8% when |M'| = 0, |M'| = 1, and |M'| = 2, respectively.

Table 7. Solution time in seconds (s_{CPLEX} and s_{MKCA}) and number of ticks (t_{CPLEX} and t_{MKCA}) obtained when EMKCA is tested with the newly generated random instances (100 variables and 5 constraints, lb = 3,000 and ub = 5,000).

δ	#	z^{MKP*}		Ti	me			Ti	cks	
	"	~	CPLEX	M' = 0	M' = 1	M' =2	CPLEX	M' = 0	M' = 1	M' =2
	1	409,485	1,000	1,152	1,244	1,168	132,061	151,905	139,139	132,295
	2	405,262	19,677	21,848	$22,\!516$	23,147	3,458,479	3,378,492	3,552,690	3,586,408
	3	407,570	935	846	830	857	67,511	62,109	60,525	61,998
	4	409,966	3,680	4,266	4,375	4,356	784,194	838,738	822,419	827,682
0.25	5	406,789	9,693	9,561	9,361	9,771	1,820,472	1,764,526	1,771,318	1,818,242
0.25	6	408,716	25,470	26,976	26,657	25,768	4,835,167	5,090,715	4,981,446	4,716,287
	7	406,266	5,672	5,141	5,113	4,852	898,976	850,390	852,056	793,220
	8	409,210	1,770	1,636	1,692	1,587	230,707	221,115	235,992	$223,\!520$
	9	410,335	10,871	12,015	12,290	12,014	2,426,846	2,256,937	2,330,600	2,276,982
	10	$410,\!206$	6,139	$5,\!527$	$5,\!535$	5,638	1,027,278	$958,\!257$	$947,\!974$	$945,\!826$
	Ave	rage	8,491	8,897	8,961	8,916	1,568,169	1,557,318	1,569,416	1,538,246
	11	810,884	1,264	1,078	1,117	1,095	178,991	158,193	171,134	163,621
	12	812,400	7,355	6,518	6,645	6,528	1,644,317	1,479,536	1,494,633	1,481,837
	13	814,371	279	300	274	274	20,521	23,309	20,489	20,295
	14	817,131	3,633	3,923	4,418	4,446	785,714	760,945	836,401	826,337
0.50	15	814,120	5,402	6,087	7,089	7,106	$1,\!179,\!329$	1,202,764	1,498,645	1,469,905
0.50	16	805,030	869	863	853	849	94,711	91,784	91,954	91,581
	17	814,805	5,494	3,719	3,914	3,968	1,012,339	653,912	687,046	699,573
	18	817,795	2,680	2,511	2,503	2,544	429,913	409,150	412,954	$413,\!551$
	19	820,410	2,896	3,503	3,602	3,693	$611,\!374$	711,224	728,024	730,709
	20	809,899	2,433	2,458	2,473	2,517	407,233	$439,\!357$	$446,\!258$	430,681
	Ave	rage	3,231	3,096	3,289	3,302	$636,\!444$	593,017	638,754	632,809
	21	1,215,759	2,024	1,530	1,587	1,524	428,431	240,878	254,296	239,567
	22	1,212,670	2,725	3,049	2,741	2,725	511,120	542,932	518,563	511,920
	23	1,224,965	1,061	950	980	931	134,792	125,789	132,225	126,773
	24	1,213,710	2,757	3,089	3,078	3,139	587,512	622,368	615,261	621,154
0.75	25	1,221,249	821	748	779	811	98,047	85,380	86,961	92,394
0.75	26	$1,\!225,\!155$	6,412	5,926	5,880	5,967	$1,\!255,\!618$	1,179,438	$1,\!170,\!891$	1,209,091
	27	$1,\!225,\!627$	3,379	3,591	3,758	3,773	774,516	739,747	753,734	781,725
	28	$1,\!218,\!795$	485	478	465	476	$32,\!451$	30,950	30,095	30,810
	29	$1,\!218,\!137$	1,648	$1,\!572$	1,655	1,771	$253,\!518$	256,369	$283,\!357$	309,545
	30	1,218,358	987	910	881	873	179,770	$171,\!268$	$169,\!532$	168,094
<u> </u>	Ave	rage	2,230	2,184	2,180	2,199	425,578	399,512	401,492	409,107

Table 10 describes the percentage improvement in α^* for all newly generated random instances tested with EMKCA. Table 10 was obtained by implementing both EMKCA and AMKCA on each instance and comparing the returned merging coefficients, α^* and α . Percentage improvement in α^* is defined for each instance as $\Delta_{\alpha^*} = \left(\frac{\alpha^* - \alpha}{\alpha}\right) \times 100\%$, and $\overline{\Delta_{\alpha^*}}$ is defined similarly as $\overline{\Delta_{time}}$ and $\overline{\Delta_{ticks}}$. Overall, implementing EMKCA instead of AMKCA results in an α^* that is on average 8.5%, 3.3%, and 1.8% greater than the α from AMKCA for |M'| = 0, |M'| = 1, and |M'| = 2, respectively.

When combining both sets of newly generated random multiple knapsack instances (lb = 2,500 and ub = 5,000 plus lb = 3,000 and ub = 5,000), the average percentage improvement in solution time is 14.6% when |M'| = 0, 14.7% when |M'| = 1, and 15.1% when |M'| = 2. Furthermore, the average percentage improvement in the number of ticks is 5.1%, 4.8%, and 5.5% when |M'| = 0, |M'| = 1, and |M'| = 2, respectively. Since improvement in solution time and number of ticks for each of the three overlapping strategies is somewhat similar, conclusions on which strategy is more efficient cannot be determined based only on the experiments performed for this paper. On the other hand, improvements in α^* appears to be more significant when |M'| = 0 than when |M'| = 1 and |M'| = 2. Consequently, one can

infer that even a small improvement in α^* can result in substantial improvements in solution time when implementing EMKCA against CPLEX at default settings.

Table 8. $\overline{\Delta_{time}}$ and $\overline{\Delta_{ticks}}$ of all 10 problems from the newly generated random instances with lb = 2,500 and ub = 5,000.

N	R	δ		\mathbf{Time}			Ticks	
1-1	1201	Ů	M' = 0	M' = 1	M' = 2	M' = 0	M' = 1	M' = 2
		0.25	12.6%	4.8%	10.2%	-0.6%	-1.9%	-1.6%
40	5	0.50	12.0%	11.9%	10.4%	5.8%	6.3%	5.8%
		0.75	21.0%	23.8%	22.5%	-5.4%	-4.1%	2.1%
		Average	15.2%	13.5%	14.4%	-0.1%	0.1%	2.1%
		0.25	1.3%	2.7%	9.2%	-1.6%	-1.8%	1.4%
60	5	0.50	-7.6%	-5.1%	16.7%	-2.6%	-4.3%	12.3%
		0.75	10.5%	11.0%	12.2%	3.2%	3.2%	5.5%
		Average	1.4%	2.9%	12.7%	-0.3%	-1.0%	6.4%
		0.25	38.4%	38.4%	38.5%	18.8%	19.5%	17.5%
80	5	0.50	41.6%	42.6%	41.6%	17.9%	17.9%	16.5%
		0.75	32.1%	33.6%	31.1%	13.2%	12.5%	11.2%
		Average	37.3%	38.2%	37.1%	16.7%	16.6%	15.1%
		0.25	-4.7%	-4.5%	-5.3%	0.4%	1.3%	-1.7%
100	5	0.50	5.5%	5.9%	7.5%	17.6%	19.0%	18.9%
		0.75	-9.0%	-7.5%	-7.2%	-6.0%	-3.9%	-3.3%
		Average	-2.7%	-2.0%	-1.7%	4.0%	5.5%	4.6%
Ov	Overall Average		12.8%	$\boldsymbol{13.2\%}$	15.6%	5.1%	5.3%	7.1%

Table 9. $\overline{\Delta_{time}}$ and $\overline{\Delta_{ticks}}$ of all 10 problems from the newly generated random instances with lb=3,000 and ub=5,000.

N	R	δ		Time			Ticks	
	1201		M' = 0	M' = 1	M' = 2	M' = 0	M' = 1	M' = 2
		0.25	14.1%	24.1%	23.2%	-0.6%	1.9%	7.2%
40	5	0.50	0.9%	7.4%	5.9%	-4.2%	-0.7%	-0.9%
		0.75	27.6%	28.0%	24.4%	9.6%	9.9%	5.3%
		Average	14.2%	19.8%	17.8%	1.6%	3.7%	3.9%
		0.25	22.7%	15.6%	13.5%	7.8%	5.0%	2.1%
60	5	0.50	5.9%	7.1%	7.8%	-2.9%	-1.7%	-2.3%
		0.75	12.1%	5.3%	-4.9%	0.4%	-5.7%	-10.9%
		Average	13.6%	9.3%	5.5%	1.8%	-0.8%	-3.7%
		0.25	38.0%	41.6%	39.8%	14.7%	14.2%	13.4%
80	5	0.50	35.5%	36.5%	33.2%	17.0%	16.9%	16.1%
		0.75	35.6%	30.1%	34.5%	8.2%	5.6%	7.7%
		Average	36.4%	36.1%	35.9%	13.3%	$\boldsymbol{12.2\%}$	12.4%
		0.25	-2.1%	-3.7%	-2.4%	0.9%	1.2%	3.0%
100	5	0.50	1.5%	-1.8%	-2.3%	2.8%	-1.0%	0.2%
		0.75	3.5%	3.4%	2.6%	7.0%	5.8%	4.2%
		Average	1.0%	-0.7%	-0.7%	3.6%	2.0%	2.5%
Ov	Overall Average		16.3%	16.1%	14.6%	5.1%	4.3%	3.8%

In summary, approximate merged knapsack cover inequalities improved the solution time and number of ticks by nearly 8% and 5%, respectively, while exact merged knapsack cover inequalities improved the solution time by 15% and the number of ticks by 5%. Based on the computational results presented in this paper, both AMKCA and EMKCA help reduce the effort to solve multiple knapsack instances. The authors recommend implementing EMKCA to solve MKPs in which

the knapsack coefficients are restricted to the cases where the minimum knapsack coefficient is at least 50% of the maximum knapsack coefficient. Otherwise, AMKCA should be implemented.

Table 10.	Δ_{α^*} of all 10 pr	roblems from the new	ly generated	random	instances	with $lb =$	= 2,500
and $ub = 5$	5,000, and lb = 3.	000 and ub = 5,000.					

N	R	δ	lb=2,	500 and ub	= 5,000	lb = 3,0	000 and ub = 0	= 5,000
	1-01	<u> </u>	M' = 0	M' =1	M' =2	M' = 0	M' = 1	M' =2
		0.25	9.4%	5.4%	4.2%	15.8%	4.9%	1.3%
40	5	0.50	3.5%	6.7%	3.2%	11.4%	6.1%	3.4%
		0.75	4.7%	9.6%	2.5%	14.8%	4.5%	0.9%
		Average	5.9%	7.2%	3.3%	14.0%	5.1%	1.9%
		0.25	5.8%	3.0%	2.5%	10.5%	4.1%	2.5%
60	5	0.50	8.3%	0.5%	3.9%	11.1%	2.6%	0.8%
		0.75	4.9%	6.2%	1.0%	9.9%	3.5%	1.9%
		Average	6.3%	3.2%	2.5%	10.5%	3.4%	1.7%
		0.25	1.8%	0.5%	3.1%	10.2%	0.5%	0.2%
80	5	0.50	2.6%	1.2%	2.8%	11.2%	0.8%	0.8%
		0.75	4.0%	2.0%	0.7%	10.2%	1.4%	0.3%
		Average	2.8%	1.3%	2.2%	10.5%	0.9%	0.4%
		0.25	4.3%	3.2%	1.9%	19.8%	5.5%	1.3%
100	5	0.50	7.2%	0.1%	0.1%	9.8%	2.3%	2.0%
		0.75	3.5%	0.4%	0.5%	8.8%	4.3%	1.8%
		Average	5.0%	1.2%	0.8%	12.8%	4.0%	1.7%
Ov	Overall Average		5.0%	3.2%	2.2%	12.0%	3.4%	1.4%

Conclusions and Future Research

Merged knapsack cover inequalities are a new class of cutting planes for multiple knapsack problems. These inequalities merge the variables of a knapsack constraint with the variables of a cover inequality. This paper presents an algorithm that requires $O(n \log n)$ effort, where n is the number of variables, to generate valid approximate merged knapsack cover inequalities. Furthermore, a dynamic programming technique, which runs in pseudo-polynomial time, improves these approximate inequalities into an exact version.

Computational experiments tested the effectiveness of both approximate and exact merged knapsack cover inequalities versus CPLEX at default settings. In the studied benchmark multiple knapsack instances, approximate merged knapsack cover inequalities improved the solution time on average by nearly 8% and the number of ticks by 5%. Moreover, exact merged knapsack cover inequalities improved the solution time and number of ticks of the newly generated random instances by 15% and 5%, respectively.

Future research topics include identifying new classes of inequalities that can be merged to create strong cutting planes and perform computational experiments to show the effectiveness of these new inequalities. Examining new overlapping strategies other than the ones presented in this paper is also a potential future research topic. Computationally comparing the methods described in this paper to other algorithms to solve multiple knapsack problems [33, 35, 49] would also be beneficial to merged knapsack cover inequalities. Finally, one could view merging as a new type of lifting, called inequality lifting. Exploring methods to quickly perform inequality lifting could create new and useful classes of cutting planes.

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