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Fabio Vitor

Todd Easton

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# RESEARCH ARTICLE 

# Approximate and Exact Merging of Knapsack Constraints with Cover Inequalities 

Fabio Vitor* ${ }^{* a}$ and Todd Easton ${ }^{\text {b }}$<br>${ }^{a}$ Department of Mathematics, University of Nebraska at Omaha, Omaha, NE 68182, USA; ${ }^{b}$ Department of Industrial and Manufacturing Systems Engineering, Kansas State University, Manhattan, KS 66506, USA

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#### Abstract

This paper presents both approximate and exact merged knapsack cover inequalities, a class of cutting planes for knapsack and multiple knapsack integer programs. These inequalities combine the information from knapsack constraints and cover inequalities. Approximate merged knapsack cover inequalities can be generated through a $O(n \log n)$ algorithm, where $n$ is the number of variables. This class of inequalities can be strengthened to an exact version with a pseudo-polynomial time algorithm. Computational experiments demonstrate an average improvement of approximately $8 \%$ in solution time and $5 \%$ in the number of ticks from CPLEX when approximate merged knapsack cover inequalities are implemented as preprocessing cuts to solve some benchmark multiple knapsack problems. Furthermore, exact merged knapsack cover inequalities improve the solution time and number of ticks of some random multiple knapsack instances by $15 \%$ and $5 \%$, respectively.


Keywords: integer programming; cover inequalities; knapsack constraints; cutting planes; inequality merging; merged knapsack cover inequalities
AMS Subject Classification: MSC 90C10; MSC 90C27; MSC 90C39; MSC 90C57

## 1. Introduction

Integer program (IP) is a class of mathematical models used to formulate numerous optimization problems. Integer programs have been used by practitioners to solve several real world problems from areas such as portfolio management [1, 2], power generation [3, 4], capital budgeting [5, 6], supply chain and transportation of goods [7-12], scheduling [13, 14], and health care [15-18]. Unfortunately, IPs are $\mathcal{N} \mathcal{P}$-hard [19] and are typically solved by the branch and bound algorithm [20].
Formally, define an IP as maximize $z=c^{T} x$, subject to $A x \leq b$ and $x \in \mathbb{Z}_{+}^{n}$, where $n$ and $r$ are positive integers, $c \in \mathbb{R}^{n}, A \in \mathbb{R}^{r \times n}$, and $b \in \mathbb{R}^{r}$. Denote $N=\{1, \ldots, n\}$ to be the set of variable indices and $R=\{1, \ldots, r\}$ as the set of constraint indices. Let $P=\left\{x \in \mathbb{Z}_{+}^{n}: A x \leq b\right\}$ be the set of feasible integer solutions, $\left(z^{I P}, x^{I P}\right)$ be any feasible integer solution, and $\left(z^{I P^{*}}, x^{I P^{*}}\right)$ be an optimal solution to the IP. Furthermore, denote $P^{L R}=\left\{x \in \mathbb{R}_{+}^{n}: A x \leq b\right\}$ as the set of feasible linear relaxation solutions, ( $z^{L R}, x^{L R}$ ) to be any feasible linear relaxation solution, and $\left(z^{L R^{*}}, x^{L R^{*}}\right)$ to be an optimal linear relaxation solution to the IP.

The knapsack problem (KP) is a classical IP that models the idea of a hiker that has to decide which items to pack in a knapsack for a trip. Each item has

[^0]an associated benefit and weight. The problem seeks to maximize the amount of benefits constrained by a total weight limit. If the knapsack is limited to other such constraints (e.g. volume and price of items), then this problem is referred to as the multiple knapsack problem (MKP) or the multidimensional knapsack problem [21]. Observe that other formulations of MKPs also exist such as MKPs with multiple objectives [22-24]. Knapsack and multiple knapsack problems have been used in numerous different applications such as production planning and inventory control [25, 26], project and portfolio selection [27], resource allocation [28], machine scheduling [29, 30], and packing problems [31]. Observe that KPs and MKPs are also $\mathcal{N} \mathcal{P}$-hard and substantial research has been performed to more quickly solve these classes of IPs [32-36].
Formally, define a KP as maximize $z=c^{T} x$, subject to $a^{T} x \leq b$ and $x \in$ $\{0,1\}^{n}$, where $c \in \mathbb{R}_{+}^{n}, a \in \mathbb{R}_{+}^{n}$, and $b \in \mathbb{R}_{+}$. Denote $P_{K P}=\left\{x \in\{0,1\}^{n}:\right.$ $\left.a^{T} x \leq b\right\}$ as the set of feasible solutions of a KP. Additionally, define an MKP as maximize $z=c^{T} x$, subject to $A x \leq b$ and $x \in\{0,1\}^{n}$, where $c \in \mathbb{R}_{+}^{n}, A \in \mathbb{R}_{+}^{r \times n}$, and $b \in \mathbb{R}_{+}^{r}$. Let $P_{M K P}=\left\{x \in\{0,1\}^{n}: A x \leq b\right\}$. Without loss of generality, assume every KP has $a_{j} \leq b$ for all $j \in N$ and every MKP has $a_{i, j} \leq b_{i}$ for all $i \in R$ and $j \in N$. Otherwise, $x_{j}=0$ for all cases in which $a_{j}>b$ and $a_{i, j}>$ $b_{i}$, and these variables can be eliminated from the problem. Furthermore, denote $\left(z^{K P}, x^{K P}\right),\left(z^{K P^{*}}, x^{K P^{*}}\right),\left(z^{M K P}, x^{M K P}\right)$, and $\left(z^{M K P^{*}}, x^{M K P^{*}}\right)$ as any feasible integer solution and an optimal solution for KPs and MKPs, respectively.

The concept of convexity and polyhedral theory are vital to this paper. Let $S \subseteq \mathbb{R}^{n}$ be convex if, and only if, $\lambda x+(1-\lambda) x^{\prime} \in S$ for all $x$ and $x^{\prime} \in S$, and $\lambda \in[0,1]$. If $S \subseteq \mathbb{R}^{n}$, then its convex hull, $S^{c h}$, is the intersection of all convex sets that contain $S$. Furthermore, define a half space as $\left\{x \in \mathbb{R}^{n}: \sum_{j=1}^{n} \alpha_{j} x_{j} \leq \beta\right\}$, where $\alpha$ is a nonzero vector and $\beta$ is a scalar. Define a polyhedron as the intersection of a finite number of half-spaces and a polytope as a bounded polyhedron. Observe that $P^{c h}, P^{L R}, P_{K P}^{c h}$, and $P_{M K P}^{c h}$ are all polyhedra.

Frequently, cutting planes are used to improve the computational time to solve IPs. Cutting planes are valid inequalities that remove some space from $P^{L R}$ without eliminating any $x^{I P} \in P$. For instance, lifting [37], cover cuts [38, 39], disjunctive cuts [40], Chvátal Gomory cuts [41], mixed integer rounding cuts [42], superadditive cuts [43], and modular arithmetic cuts [44] are all examples of cutting planes for integer programming problems.

Formally, any inequality of the form $\sum_{j=1}^{n} \alpha_{j} x_{j} \leq \beta$ is valid for $P^{c h}$ if, and only if, $\sum_{j=1}^{n} \alpha_{j} x_{j}^{\prime} \leq \beta$ for every $x^{\prime} \in P$. If an inequality is valid and there exists an $x^{\prime \prime} \in P^{L R}$ such that $\sum_{j=1}^{n} \alpha_{j} x_{j}^{\prime \prime}>\beta$, then this inequality is a cutting plane. A valid inequality $\sum_{j=1}^{n} \alpha_{j} x_{j} \leq \beta$ weakly dominates another valid inequality $\sum_{j=1}^{n} \alpha_{j}^{\prime} x_{j} \leq$ $\beta^{\prime}$ if $\alpha_{j} \geq \alpha_{j}^{\prime}$ for all $j \in N$ and $\beta \leq \beta^{\prime}$.

The theoretical usefulness of cuttings planes is measured in terms of the dimension of the cutting plane's face $F=\left\{x \in P^{c h}: \sum_{j=1}^{n} \alpha_{j} x_{j}=\beta\right\}$. The dimension of a convex space, $P^{c h}$, is defined as the maximum number of affinely independent points minus one. Let $Q=\left\{x^{1}, x^{2}, \ldots, x^{q}\right\} \in \mathbb{R}^{n}$ be a set of affinely independent points if, and only if, the unique solution to $\sum_{k=1}^{q} \lambda_{k} x^{k}=0$ and $\sum_{k=1}^{q} \lambda_{k}=0$ is $\lambda_{k}=0$ for all $k \in\{1, \ldots, q\}$. If the dimension of $F$ equals the dimension of $P^{c h}$ minus one, then the inequality is said to be facet defining and is one of the theoretically strongest valid inequalities [45].

Since this paper presents merged knapsack cover inequalities, a new class of cutting planes for KPs and MKPs, some background information about covers, lifting, and inequality merging is useful to understand the paper. Covers represent an infeasible solution to a knapsack constraint and are used to create valid inequalities.

Formally, $C \subseteq N$ is a cover if, and only if, $\sum_{j \in C} a_{j}>b$. Every cover $C$ has a corresponding valid cover inequality $\sum_{j \in C} x_{j} \leq|C|-1$. If $\sum_{j \in C \backslash\{k\}} a_{j} \leq b$ for each $k \in C$, then the cover is minimal. For brevity, this paper assumes that all covers are minimal.
Lifting can be used to strengthen some valid inequalities [37]. Lifting begins with a valid inequality in the restricted space $P_{E, K}$ and creates a valid inequality over the entire dimensional space $P$. Let $E \subset N$ be an ordered set and $K=$ $\left(k_{1}, k_{2}, \ldots, k_{|E|}\right) \in \mathbb{Z}^{|E|}$. Define the restricted space $P_{E, K}=\left\{x \in P: x_{j}=k_{j} \forall j \in\right.$ $E\}$. Lifting begins with a valid inequality $\sum_{j \in E} \alpha_{j} x_{j}+\sum_{j \in N \backslash E} \alpha_{j} x_{j} \leq \beta$ of $P_{E, K}^{c h}$ and creates a valid inequality $\sum_{j \in E} \alpha_{j}^{\prime} x_{j}+\sum_{j \in N \backslash E} \alpha_{j} x_{j} \leq \beta^{\prime}$ of $P^{c h}$.

Valid inequalities can be: up, down, or middle lifted; exactly or approximately lifted; sequentially or simultaneously lifted. Inequalities are up, down, or middle lifted when for each $j \in E$, the values of $k_{j}$ are at the lower bound, upper bound, or in between the lower and upper bound, respectively [46]. Furthermore, lifting is considered exact if $\alpha^{\prime}$ cannot be increased and $\beta^{\prime}$ cannot be decreased [47-49]. On the other hand, if a lifted inequality has either an $\alpha^{\prime}$ that can be increased or a $\beta^{\prime}$ that can be decreased, then the corresponding inequality is approximately lifted. Finally, an inequality is sequentially lifted when $|E|=1$ and simultaneously lifted when $|E|>1$ [50-53].

One particular type of simultaneous lifting is referred to as inequality merging [54, 55]. Inequality merging occurs when two low dimensional valid inequalities are merged to create a new valid inequality of higher dimension. In such a case, one valid inequality is defined as the host inequality $\sum_{j \in C^{1}} \alpha_{j}^{1} x_{j} \leq \beta^{1}$, while the other valid inequality is defined as the donor inequality $\sum_{j \in C^{2}} \alpha_{j}^{2} x_{j} \leq \beta^{2}$, where $C^{1} \subseteq N$, $p \in C^{1}, C^{2} \subseteq\left(N \backslash C^{1}\right) \cup\{p\}$, and $\beta^{1}, \beta^{2}, \alpha_{j}^{1}, \alpha_{j}^{2} \in \mathbb{Z}_{+}$. Thus, the host inequality replaces at least one of its variables with a set of variables from the donor inequality and the resulting merged inequality is $\sum_{j \in C^{1} \backslash\{p\}} \alpha_{j}^{1} x_{j}+\sum_{j \in C^{2}} \frac{\alpha_{j}^{2}}{\beta^{2}} x_{j} \leq \beta^{1}$. Observe that merged inequalities may be valid and facet defining under certain conditions. Other techniques to merge inequalities not related to this paper also exist [56, 57].

This paper presents a $O(n \log n)$ algorithm to create valid approximate merged knapsack cover inequalities. The variables of a cover inequality are merged with a set of variables from a knapsack constraint. The merged knapsack coefficient must be greater than a certain predefined value, which allows a strengthening of the cover inequality. In addition, this paper describes a technique to strengthen these approximate inequalities into an exact version. Exact merged knapsack cover inequalities are generated in pseudo-polynomial time with a dynamic programming algorithm, and are the theoretically strongest such inequalities. Computational results demonstrate an average improvement of nearly $8 \%$ in solution time and $5 \%$ in the number of ticks from CPLEX when approximate merged knapsack cover inequalities are implemented as preprocessing cuts to solve some benchmark multiple knapsack instances. Moreover, exact merged knapsack cover inequalities improve the solution time of some random multiple knapsack problems by $15 \%$ and number of ticks by $5 \%$.

The remainder of the paper is organized as follows. Section 2 demonstrates the theory behind both approximate and exact merged knapsack cover inequalities. Section 3 provides the main computational results. Section 4 concludes the paper and presents potential topics for future work.

## 2. Merging Knapsack Constraints with Cover Inequalities

This section describes the theoretical and algorithmic results involving approximate and exact merged knapsack cover inequalities. Examples are provided to demonstrate this novel class of cutting planes. Preliminary results can also be found in a conference proceedings paper [58] and a thesis [59].

### 2.1. Approximate Merged Knapsack Cover Inequalities

Let $\sum_{j \in N} a_{j} x_{j} \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, $M \subseteq N$ be a set of merging indices, and $\alpha \in \mathbb{R}_{+}$be a merging coefficient. Define a merged knapsack cover inequality $M K C_{\alpha}$ as $\sum_{j \in C \backslash M} x_{j}+\alpha \sum_{j \in M} a_{j} x_{j} \leq|C|-1$. Observe that $\sum_{j \in C \backslash M} x_{j} \leq|C|-1$ is part of the cover inequality and $\sum_{j \in M} a_{j} x_{j}$ is a portion of the knapsack constraint. If there exists an $x^{K P} \in P_{K P}$ that meet $M K C_{\alpha}$ at equality, then $M K C_{\alpha}$ is an exact merged knapsack cover inequality. If not, then $M K C_{\alpha}$ is an approximate merged knapsack cover inequality. This definition follows identically to the terms used to define when an inequality is approximately or exactly lifted.

Observe that $\alpha=0$ results in $M K C_{\alpha}$ being weakly dominated by the cover inequality. If $\alpha>\frac{|C|-1}{\max \left\{a_{j}: j \in M\right\}}$, then there exists an $x^{K P} \in P_{K P}$ with $x_{j}=1$ for some $j \in M$ that violates the merged knapsack cover inequality, and $M K C_{\alpha}$ is not valid. Consequently, valid merged knapsack cover inequalities must have $0<\alpha \leq \frac{|C|-1}{\max \left\{a_{j}: j \in M\right\}}$ in order to be considered theoretically useful.

The approximate merging knapsack cover algorithm (AMKCA) determines valid merged knapsack cover inequalities that can be theoretically stronger than the corresponding cover inequality. This algorithm first determines a set of merging indices $M$ and calculates a value for $\alpha$ such that $M K C_{\alpha}$ is valid. Algorithm 1 presents AMKCA, which requires as input a knapsack constraint $\sum_{j \in N} a_{j} x_{j} \leq b$, a cover $C \subseteq N$ such that $C=\left\{f_{1}, f_{2}, \ldots, f_{|C|}\right\}$, and a set $M^{\prime} \subseteq C$, where $M^{\prime}=$ $\left\{g_{1}, g_{2}, \ldots, g_{\left|M^{\prime}\right|}\right\}$. One can view $M^{\prime}$ as a set of elements in $C$ that are merged jointly with the elements in $M$. That is, $M^{\prime}=M \cap C$. The output to AMKCA is an $\alpha \in \mathbb{R}_{+}$, a set of merging indices $M=\left\{h_{1}, h_{2}, \ldots, h_{|M|}\right\}$, and the approximate merged knapsack cover inequality $\sum_{j \in C \backslash M} x_{j}+\alpha \sum_{j \in M} a_{j} x_{j} \leq|C|-1$.

Algorithm 1 has four major steps. The first step (lines 2-12) initializes certain variables and sorts the knapsack constraint, the indices of $C$, and the indices of $M^{\prime}$ in descending order according to the values of $a$. The second step (lines 13-21) determines a set $M \subseteq N$ such that $\alpha>0$ (Theorem 2.1). The third step (lines 22-29), which is equivalent to calculating $\alpha=\min \left\{\frac{|C|-1-q}{b-\sum_{j=|C| M \mid-q+1}^{|C| a_{t_{j}}}}: 0 \leq q \leq p\right\}$ (see Theorem 2.2), defines a value for $\alpha$ by efficiently utilizing the sorted knapsack coefficients to determine feasible solutions for $P_{K P}$. Observe that any $x^{K P} \in P_{K P}$ may decrease the current estimate for $\alpha$ (Theorem 2.2). The last step (lines 30-32) reports the $\alpha$ value, $M$, and $M K C_{\alpha}$ determined by AMKCA.

The most expensive step in AMKCA is to sort the coefficients of the knapsack constraint. Therefore, approximate merged knapsack cover inequalities can be generated with $O(n \log n)$ effort. To prove that the inequalities reported by AMKCA are valid and not dominated by their corresponding cover inequality, one must evaluate both steps (B) and (C) of AMKCA. Theorem 2.1 proves that AMKCA determines a set of merging indices $M$ such that approximate merged knapsack cover inequalities are valid for some $\alpha>0$.

```
Algorithm 1: Approximate Merging Knapsack Cover Algorithm (AMKCA)
    begin
    (a) Initialization
        Sort \(a=\left(a_{1}, a_{2}, \ldots a_{n}\right)\) such that \(a_{j} \geq a_{j+1} \quad \forall j=\{1,2, \ldots,|N|-1\}\)
        Sort \(C=\left\{f_{1}, f_{2}, \ldots, f_{|C|}\right\}\) such that \(a_{f_{j}} \geq a_{f_{j+1}} \quad \forall j=\{1,2, \ldots,|C|-1\}\)
        Sort \(M^{\prime}=\left\{g_{1}, g_{2}, \ldots, g_{\left|M^{\prime}\right|}\right\}\) such that \(a_{g_{j}} \geq a_{g_{j+1}} \forall j=\left\{1,2, \ldots,\left|M^{\prime}\right|-1\right\}\)
        \(M \leftarrow \emptyset\)
        \(l \leftarrow\left|C \backslash M^{\prime}\right|\)
        \(\alpha \leftarrow \infty\)
        if \(\left|M^{\prime}\right| \leq 2\) then
            \(p \leftarrow|C|-2\)
        else
            \(p \leftarrow\left|C \backslash M^{\prime}\right|\)
    (B) Determine \(M\)
        if \(\left|M^{\prime}\right|=0\) then
            \(\theta \leftarrow b-\sum_{j=2}^{|C|} a_{f_{j}}\)
        else if \(\left|M^{\prime}\right|=1\) then
            \(\theta \leftarrow b-\sum_{j \in C \backslash M^{\prime}} a_{f_{j}}\)
        else
            \(\theta \leftarrow 0\)
        for each \(j \in N \backslash\left(C \backslash M^{\prime}\right)\) do
            if \(a_{j}>\theta\) then \(M \leftarrow M \cup\{j\}\)
    (c) Calculate \(\alpha\)
        \(\theta \leftarrow b\)
        for \(q=0\) to \(p\) do
            \(\alpha^{\prime} \leftarrow \frac{|C|-1-q}{\theta}\)
            if \(\alpha^{\prime}<\alpha\) then \(\alpha \leftarrow \alpha^{\prime}\)
            if \(q<p\) then
                \(\theta \leftarrow \theta-a_{f_{l}}\)
                \(l \leftarrow l-1\)
    (D) Output
        return \(\alpha \in \mathbb{R}^{+}\)and \(M=\left\{h_{1}, h_{2}, \ldots, h_{|M|}\right\}\)
        return \(M K C_{\alpha} \leftarrow \sum_{j \in C \backslash M} x_{j}+\alpha \sum_{j \in M} a_{j} x_{j} \leq|C|-1\)
    end
```

Theorem 2.1 Let $\sum_{j \in N} a_{j} x_{j} \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, and $M^{\prime} \subseteq C$ be a set of overlapping indices. AMKCA returns a set of merging indices $M$ such that $M K C_{\alpha}$ is valid for $P_{K P}^{c h}$ for some $\alpha>0$.

Proof. Let $\sum_{j \in N} a_{j} x_{j} \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, and $M^{\prime} \subseteq$ $C$ be a set of overlapping indices. Assume $M$ is the set of merging indices returned by AMKCA and $\alpha=\frac{1}{b}$. To show that $M K C_{\alpha}$ is valid for $P_{K P}^{c h}$, let $x^{\prime}$ be any solution in $P_{K P}$ and define $q=\sum_{j \in C \backslash M} x_{j}^{\prime}$. Since $C$ is a cover, then $\sum_{j \in C} x_{j} \leq|C|-1$ is a valid cover inequality and it holds that $q \leq \sum_{j \in C} x_{j}^{\prime} \leq|C|-1$.

Assume $q \leq|C|-2$. Applying $x^{\prime}$ to the left-hand side of $M K C_{\alpha}$ results in $q+\frac{1}{b}\left(\sum_{j \in M} a_{j} x_{j}^{\prime}\right) \leq|C|-2+\frac{1}{b}\left(\sum_{j \in M} a_{j} x_{j}^{\prime}\right)$. Since $x^{\prime}$ is feasible, $\sum_{j \in M} a_{j} x_{j}^{\prime} \leq b$. Hence, $|C|-2+\frac{1}{b}\left(\sum_{j \in M} a_{j} x_{j}^{\prime}\right) \leq|C|-1$ and $x^{\prime}$ satisfies $M K C_{\alpha}$.

Assume $q=|C|-1$ and $\left|M^{\prime}\right|=1$. Thus, $x_{j}^{\prime}=1$ for every $j \in C \backslash M$. Since $x^{\prime}$ is feasible, $\sum_{j \in C \backslash M} a_{j} x_{j}^{\prime}+\sum_{j \in M} a_{j} x_{j}^{\prime} \leq b$. Therefore, $\sum_{j \in M} a_{j} x_{j}^{\prime} \leq$
$b-\sum_{j \in C \backslash M} a_{j}$. Since $M$ is returned from AMKCA, $a_{j}>\theta$ for every $j \in M$, where $\theta=b-\sum_{j \in C \backslash M^{\prime}} a_{f_{j}}$ (lines 16-17). Thus, $x_{j}^{\prime}=0$ for every $j \in M$ and $\sum_{j \in C \backslash M} x_{j}^{\prime}+\frac{1}{b}\left(\sum_{j \in M} a_{j} x_{j}^{\prime}\right)=|C|-1$.

Assume $q=|C|-1$ and $\left|M^{\prime}\right|=0$. Since $x^{\prime}$ is feasible, $\sum_{j \in C} a_{j} x_{j}^{\prime}+\sum_{j \in M} a_{j} x_{j}^{\prime} \leq b$ implies that $\sum_{j \in M} a_{j} x_{j}^{\prime} \leq b-\sum_{j \in C} a_{j} x_{j}^{\prime}$. Because $C$ is sorted and $q=|C|-1$, then $\sum_{j \in C} a_{j} x_{j}^{\prime} \geq \sum_{j=2}^{|C|} a_{f_{j}}$. Since $M$ is returned from AMKCA, every $a_{j}>\theta$ where $\theta=b-\sum_{j=2}^{|C|} a_{f_{j}}$ (lines 14-15). Thus, $x_{j}^{\prime}=0$ for every $j \in M$ and $\sum_{j \in C \backslash M} x_{j}^{\prime}+$ $\frac{1}{b}\left(\sum_{j \in M} a_{j} x_{j}^{\prime}\right)=|C|-1$. Hence, $M K C_{\alpha}$ is valid for $P_{K P}^{c h}$. The cases are exhaustive and the result is shown.

From Theorem 2.1, AMKCA returns $M=\left\{h_{1}, h_{2}, \ldots, h_{|M|}\right\}$ such that $M K C_{\alpha}$ is valid for some $\alpha>0$. Theorem 2.2 proves that the $\alpha$ value returned by AMKCA implies that $\sum_{j \in C \backslash M} x_{j}+\alpha \sum_{j \in M} a_{j} x_{j} \leq|C|-1$ is a valid merged knapsack cover inequality for $P_{K P}^{c h}$.

Theorem 2.2 Let $\sum_{j \in N} a_{j} x_{j} \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, and $M \subseteq N$ be a set of merging indices. Then, $\sum_{j \in C \backslash M} x_{j}+\alpha^{\prime} \sum_{j \in M} a_{j} x_{j} \leq|C|-1$ is a valid inequality of $P_{K P}^{c h}$ for any $\alpha^{\prime} \leq \alpha$, where $\alpha$ is returned by AMKCA.

Proof. Let $\sum_{j \in N} a_{j} x_{j} \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, and $M \subseteq N$ be a set of merging indices. For contradiction, assume that there exists an $\alpha^{\prime} \leq \alpha$ such that $\sum_{j \in C \backslash M} x_{j}+\alpha^{\prime} \sum_{j \in M} a_{j} x_{j} \leq|C|-1$ is not a valid inequality of $P_{K P}^{c h}$, where $\alpha$ is returned by AMKCA. Thus, there exists an $x^{\prime} \in P_{K P}$ such that $\sum_{j \in C \backslash M} x_{j}^{\prime}+\alpha^{\prime} \sum_{j \in M} a_{j} x_{j}^{\prime}>|C|-1$. Define $q=\sum_{j \in C \backslash M} x_{j}^{\prime}$ and $C \backslash M=$ $\left\{t_{1}, t_{2}, \ldots, t_{|C \backslash M|}\right\}$. Since $x^{\prime}$ is feasible, $\sum_{j \in C \backslash M} a_{j} x_{j}^{\prime}+\sum_{j \in M} a_{j} x_{j}^{\prime} \leq b$ implies that $\sum_{j \in M} a_{j} x_{j}^{\prime} \leq b-\sum_{j \in C \backslash M} a_{j} x_{j}^{\prime}$. Therefore, $\sum_{j \in M} a_{j} x_{j}^{\prime} \leq b-\sum_{j=|C \backslash M|-q+1}^{|C \backslash M|} a_{t_{j}}$ due to the sets being sorted.
Assume $q \leq|C|-2$. Since $M K C_{\alpha^{\prime}}$ is not a valid inequality, $\alpha^{\prime} \sum_{j \in M} a_{j} x_{j}^{\prime}>|C|-$ $1-q$. Therefore, $\alpha^{\prime}>\frac{|C|-1-q}{\sum_{j \in M} a_{j} x_{j}^{\prime}}$ implies that $\alpha^{\prime}>\frac{|C|-1-q}{\left(b-\sum_{j=|C| C|M|-q+1}^{\mid C a_{t_{j}}}\right)}$. However, AMKCA requires $\left.\alpha \leq \frac{|C|-1-q}{\left(b-\sum_{j=|M|}^{|C| C|M|-q+1}\right.} a_{t_{j}}\right)$ (lines 22-29). Thus, $\alpha^{\prime}>\alpha$ contradicts $\alpha$ being returned by AMKCA.

Assume $q \geq|C|-1$. If $q \geq|C|, x^{\prime}$ violates the cover inequality and contradicts $C$ being a cover. If $q=|C|-1$, then $\alpha^{\prime} \sum_{j \in M} a_{j} x_{j}^{\prime}>(|C|-1)-(|C|-1)$ implies that $\alpha^{\prime}>0$ and $x_{j}^{\prime}=1$ for some $j \in M$. Since $\alpha^{\prime}>0$, AMKCA returns an $\alpha>0$. Thus, $\min \left\{a_{h_{j}}: j \in\{1,2, \ldots|M|\}\right\}>b-\sum_{j=2}^{|C|} a_{f_{j}}$ for $\left|M^{\prime}\right|=0$ or $\min \left\{a_{h_{j}}: j \in\right.$ $\{1,2, \ldots|M|\}\}>b-\sum_{j \in C \backslash M} a_{f_{j}}$ for $\left|M^{\prime}\right|=1$ (lines 14-17). Both cases contradict the feasibility of $x^{\prime}$ and the result follows.

The following example demonstrates the implementation of AMKCA to generate valid approximate merged knapsack cover inequalities.

Example 2.1 Consider the knapsack constraint described in (1), where $x_{j} \in\{0,1\}$ for every $j \in\{1,2, \ldots, 11\}$. Let $C=\{5,6,7,8,9\}$ be a cover and $M^{\prime}=\emptyset$ for this example.

$$
\begin{equation*}
30 x_{1}+25 x_{2}+20 x_{3}+15 x_{4}+12 x_{5}+11 x_{6}+11 x_{7}+10 x_{8}+10 x_{9}+5 x_{10}+x_{11} \leq 44 \tag{1}
\end{equation*}
$$

Since the knapsack constraint in (1) and the cover $C$ are given in a sorted order, and because $M^{\prime}=\emptyset$, the first steps in AMKCA initializes $M=\emptyset, l=5-0=5$, $\alpha=\infty$ and $p=5-2=3$ (lines 2-12). The subsequent step in AMKCA calculates $\theta=b-\sum_{j=2}^{|C|} a_{f_{j}}$, where $C=\left\{f_{1}, f_{2}, \ldots, f_{|C|}\right\}$ (lines 13-21). Consequently, $\theta=2$ and $M$ contains every $j \in N \backslash C$ such that $a_{j}>\theta=2$. Therefore, $M=\{1,2,3,4,10\}$. Observe that including the index corresponding to variable $x_{11}$ in $M$ violates the conditions described in Theorem 2.1. The following step in AMKCA calculates a value for $\alpha$ such that $\alpha=\min \left\{\frac{|C|-1-q}{\theta}\right\}$ for every $q=\{0, \ldots,|C|-2\}$ (lines 22-29). Thus, $\alpha=\min \left\{\frac{4}{44}, \frac{3}{34}, \frac{2}{24}, \frac{1}{13}\right\}=\frac{1}{13}$. The algorithm terminates (lines 30-32) and reports $\alpha=\frac{1}{13}, M=\{1,2,3,4,10\}$, and the valid approximate merged knapsack cover inequality $M K C_{\frac{1}{13}}$ presented in (2).

$$
\begin{equation*}
x_{5}+x_{6}+x_{7}+x_{8}+x_{9}+\frac{1}{13}\left(30 x_{1}+25 x_{2}+20 x_{3}+15 x_{4}+5 x_{10}\right) \leq 4 \tag{2}
\end{equation*}
$$

Observe that $M K C_{1}$ is also a cutting plane. To show that, consider the linear relaxation solution $x^{L^{13}}=\left(0,0,0, \frac{2}{15}, 0,1,1,1,1,0,0\right) \in P^{L R}$. Applying $x^{L R}$ to $M K C_{\frac{1}{13}}$ results in $\sum_{j \in C \backslash M} x_{j}^{L R}+\frac{1}{13} \sum_{j \in M} a_{j} x_{j}^{L R}=\frac{54}{13}$. Since $\frac{54}{13}>4, M K C_{\frac{1}{13}}$ cuts off the corresponding $x^{L R}$.

### 2.2. Exact Merged Knapsack Cover Inequalities

Since the $M K C_{\alpha}$ determined by AMKCA is approximate, an obvious question is whether these inequalities can be strengthened. This paper also presents a technique to determine an $\alpha^{*} \in \mathbb{R}_{+}$such that $\alpha^{*}$ cannot be increased and the inequality remains valid. These type of inequalities are referred to as exact merged knapsack cover inequalities.

Observe that AMKCA determines an $\alpha$ value such that $\alpha=\min \left\{\frac{|C|-1-q}{\theta_{q}}\right\}$ for every $q=\{0, \ldots,|C|-2\}$, where $\theta_{q}$ is dependent on the value of $q$. Exact merged knapsack cover inequalities have an $\alpha^{*}$ such that there exists an $x^{K P} \in P_{K P}$ that meets $M K C_{\alpha^{*}}$ at equality. Thus, one can determine the value of $\alpha^{*}$ by maximizing $z=\sum_{j \in M} a_{j} x_{j}$, subject to $\sum_{j \in M} a_{j} x_{j} \leq \theta_{q}$ and $x_{j} \in\{0,1\}$ for all $j \in M$. If $\alpha^{*}=\min \left\{\frac{|C|-1-q}{z_{q}}\right\}$ for every $q=\{0, \ldots,|C|-2\}$, where $z_{q}$ also depends on the value of $q$, then an optimal solution to the aforementioned maximization problem satisfies $M K C_{\alpha^{*}}$ at equality, and $M K C_{\alpha^{*}}$ is an exact merged knapsack cover inequality. Since $C$ is assumed to be minimal, and $q \leq|C|-2$, then $z_{q}>0$ for each of these subproblems.

The exact merging knapsack cover algorithm (EMKCA), described in Algorithm 2 , uses dynamic programming to determine the largest possible value of $\alpha^{*}$. This is achieved by tracking an array $d=\left(d_{0}, d_{1}, \ldots, d_{b}\right)$, where $d_{k} \in\{0,1\}$ for each $k \in\{0, \ldots, b\}$ (lines 12-15). If the sum of the coefficients of any combination of feasible solutions with indices in $M$ equals $k$, then $d_{k}=1$. If not, $d_{k}=0$ for all $k \in\{0, \ldots, b\}$. Once $d$ is computed, $\theta$ is updated by the same method as in AMKCA and $z$ is determined as the maximum index $k \leq \theta$ such that $d_{k}=1$ (lines 16-29).

The input to EMKCA is a knapsack constraint $\sum_{j \in N} a_{j} x_{j} \leq b$, a cover $C \subseteq N$, and a set of merging indices $M \subseteq N$. The set $M$ must satisfy the conditions of Theorem 2.1. Therefore, running steps (A) and (B) of AMKCA is sufficient to identify a suitable $M=\left\{h_{1}, h_{2}, \ldots, h_{|M|}\right\}$. The output to EMKCA is an $\alpha^{*} \in \mathbb{R}_{+}$
and the exact merged knapsack cover inequality $\sum_{j \in C \backslash M} x_{j}+\alpha^{*} \sum_{j \in M} a_{j} x_{j} \leq$ $|C|-1$ (lines 30-32).

```
Algorithm 2 : Exact Merging Knapsack Cover Algorithm (EMKCA)
    begin
    (a) Initialization
        \(d_{0} \leftarrow 1\)
        \(d_{k} \leftarrow 0\) for all \(k \in\{1, \ldots, b\}\)
        \(\theta \leftarrow b\)
        \(l \leftarrow|C \backslash M|\)
        \(\alpha^{*} \leftarrow \infty\)
        if \(|C \cap M| \leq 2\) then
            \(p \leftarrow|C|-2\)
        else
            \(p \leftarrow|C \backslash M|\)
    (B) Compute \(d\)
        for \(q=1\) to \(|M|\) do
            for \(r=b-a_{h_{q}}\) to 0 do
            if \(d_{r}=1\) then \(d_{r+a_{h_{q}}} \leftarrow 1\)
    (c) Calculate \(\alpha^{*}\)
        for \(q=0\) to \(p\) do
            \(t \leftarrow \theta\)
            flag \(\leftarrow 0\)
            while flag \(=0\) do
                if \(d_{t}=1\) then
                \(z \leftarrow t\)
                flag \(\leftarrow 1\)
            \(t \leftarrow t-1\)
            \(\alpha^{\prime} \leftarrow \underline{|C|-1-q}\)
            if \(\alpha^{\prime}<\alpha^{*}\) then \(\alpha^{*} \leftarrow \alpha^{\prime}\)
            if \(q<p\) then
                    \(\theta \leftarrow \theta-a_{f_{l}}\)
            \(l \leftarrow l-1\)
    (D) Output
        return \(\alpha^{*} \in \mathbb{R}^{+}\)
        return \(M K C_{\alpha^{*}} \leftarrow \sum_{j \in C \backslash M} x_{j}+\alpha^{*} \sum_{j \in M} a_{j} x_{j} \leq|C|-1\)
    end
```

Computational complexity of EMKCA is clearly $O(b n+n \log n)$. Since the running time is a function of input data, EMKCA is a pseudo-polynomial time algorithm that solves quickly if the right-hand side $b$ is bounded by a constant. The following theorem formally proves that EMKCA generates valid exact merged knapsack cover inequalities.

Theorem 2.3 Let $\sum_{j \in N} a_{j} x_{j} \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, $M \subseteq N$ be a set of merging indices, and $\alpha^{*}$ be returned by EMKCA. Thus, $\sum_{j \in C \backslash M} x_{j}+\alpha^{\prime} \sum_{j \in M} a_{j} x_{j} \leq|C|-1$ is a valid inequality of $P_{K P}^{c h}$ for any $\alpha^{\prime} \leq \alpha^{*}$ and is not a valid inequality of $P_{K P}^{c h}$ for any $\alpha^{\prime}>\alpha^{*}$.

Proof. Let $\sum_{j \in N} a_{j} x_{j} \leq b$ be a knapsack constraint, $C \subseteq N$ be a cover, $M \subseteq N$ be a set of merging indices, and $\alpha^{*}$ be returned by EMKCA. Assume $\alpha^{\prime} \leq \alpha^{*}$ and let $x^{\prime} \in P_{K P}$. Define $q^{\prime}=\sum_{j \in C \backslash M} x_{j}^{\prime}$ and $z^{\prime}=\sum_{j \in M} a_{j} x_{j}^{\prime}$. From Algorithm 2, $d_{z^{\prime}}=1$ (lines 12-15 and lines 21-22). Thus, $\alpha^{*} \leq \frac{|C|-1-q^{\prime}}{z^{\prime}}$ (line 25). Consequently, $\sum_{j \in C \backslash M} x_{j}^{\prime}+\alpha^{\prime} \sum_{j \in M} a_{j} x_{j}^{\prime} \leq q^{\prime}+\frac{|C|-1-q^{\prime}}{z^{\prime}} z^{\prime} \leq|C|-1$. Therefore, $\sum_{j \in C \backslash M} x_{j}^{\prime}+$ $\alpha^{\prime} \sum_{j \in M} a_{j} x_{j}^{\prime} \leq|C|-1$ is valid for $P_{K P}^{c h}$.

Assume $\alpha^{\prime}>\alpha^{*}$. Let $q^{\prime \prime}$ and $z^{\prime \prime}$ be the values of $q$ and $z$, respectively, that generated $\alpha^{*}$ in EMKCA. Clearly, $d_{z^{\prime \prime}}=1$ and there exists an $x^{\prime \prime} \in P_{K P}$ such that $\sum_{j \in C \backslash M} x_{j}^{\prime \prime}=q^{\prime \prime}$ and $\sum_{j \in M} a_{j} x_{j}^{\prime \prime}=z^{\prime \prime}$. Applying $x^{\prime \prime}$ to $M K C_{\alpha^{\prime}}$ results in $q^{\prime \prime}+\alpha^{\prime} z^{\prime \prime}>q^{\prime \prime}+\alpha^{*} z^{\prime \prime}=q^{\prime \prime}+\frac{|C|-1-q^{\prime \prime}}{z^{\prime \prime}} z^{\prime \prime}=|C|-1$. Thus, $x^{\prime \prime}$ violates $M K C_{\alpha^{\prime}}$ and $M K C_{\alpha^{\prime}}$ is not a valid inequality of $P_{K P}^{c h}$.

Theorem 2.3 proves that merged knapsack cover inequalities reported by EMKCA are exact because the $x^{\prime \prime}$ from the proof demonstrates that $M K C_{\alpha^{\prime}}$ supports $P_{K P}^{c h}$. Example 2.2 demonstrates the implementation of EMKCA.

Example 2.2 Consider the knapsack constraint presented in (1), the same cover $C=\{5,6,7,8,9\}$ from Example 2.1, and the set of merging indices $M=$ $\{1,2,3,4,10\}$ returned by AMKCA.

EMKCA initializes $d_{0}=1, \theta=44, l=5, \alpha^{*}=\infty$, and $p=5-2=3$ (lines 2-11). Step (B) of EMKCA runs $|M|$ times and defines the combination of all possible integers that can be achieved by points restricted to indices in $M$ (lines 12-15). Table 1 summarizes the final array $d$. Therefore, any combination of points from $\sum_{j \in C \backslash M} x_{j}$ results in $\sum_{j \in M} a_{j} x_{j}$ being equal to an integer represented by any index of $d$ where $d_{k}=1$ for all $k \in\{0,1, \ldots, b\}$.

Table 1. Final array $d$ of Example 2.2

| $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ | $\mathbf{7}$ | $\mathbf{8}$ | $\mathbf{9}$ | $\mathbf{1 0}$ | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{1}$ | 0 | 0 | 0 | 0 | $\mathbf{1}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ | $\mathbf{2 2}$ | $\mathbf{2 3}$ | $\mathbf{2 4}$ | $\mathbf{2 5}$ | $\mathbf{2 6}$ | $\mathbf{2 7}$ | $\mathbf{2 8}$ | $\mathbf{2 9}$ |
| $\mathbf{1}$ | 0 | 0 | 0 | 0 | $\mathbf{1}$ | 0 | 0 | 0 | 0 | $\mathbf{1}$ | 0 | 0 | 0 | 0 |
| $\mathbf{3 0}$ | $\mathbf{3 1}$ | $\mathbf{3 2}$ | $\mathbf{3 3}$ | $\mathbf{3 4}$ | $\mathbf{3 5}$ | $\mathbf{3 6}$ | $\mathbf{3 7}$ | $\mathbf{3 8}$ | $\mathbf{3 9}$ | $\mathbf{4 0}$ | $\mathbf{4 1}$ | $\mathbf{4 2}$ | $\mathbf{4 3}$ | $\mathbf{4 4}$ |
| $\mathbf{1}$ | 0 | 0 | 0 | 0 | $\mathbf{1}$ | 0 | 0 | 0 | 0 | $\mathbf{1}$ | 0 | 0 | 0 | 0 |

The algorithm continues and calculates a value for $\alpha^{*}$ such that $\alpha^{*}=$ $\min \left\{\frac{|C|-1-q}{z^{2}}\right\}$ for every $q=\{0, \ldots,|C|-2\}$ (lines 16-29). Therefore, $\alpha^{*}=$ $\min \left\{\frac{4}{40}, \frac{3}{30}, \frac{2}{20}, \frac{1}{5}\right\}=\frac{1}{10}$ and EMKCA reports $\alpha^{*}=\frac{1}{10}$ along with the valid exact merged knapsack cover inequality $M K C_{\frac{1}{10}}$ presented in (3) (lines 30-32).

$$
\begin{equation*}
x_{5}+x_{6}+x_{7}+x_{8}+x_{9}+\frac{1}{10}\left(30 x_{1}+25 x_{2}+20 x_{3}+15 x_{4}+5 x_{10}\right) \leq 4 \tag{3}
\end{equation*}
$$

Observe that $M K C_{\frac{1}{10}}$ is exact while $M K C_{\frac{1}{13}}$ is approximate. For instance, let $x^{K P}=(0,0,1,0,0,0,0,1,1,0,1) \in P_{K P}$. Applying $x^{K P}$ to $M K C_{\frac{1}{10}}$ and $M K C_{\frac{1}{13}}$ results in $M K C_{\frac{1}{10}}$ being equal to 4 while $M K C_{\frac{1}{13}}$ being equal to $\frac{46}{13}$. Thus, the corresponding solution $x^{K P}$ meets $M K C_{\frac{1}{10}}$ at equality, but not $M K C_{\frac{1}{13}}$. The reader can enumerate every $x^{K P} \in P_{K P}$ and see that the argument holds for all cases.

Clearly, $M K C_{\frac{1}{10}}$ dominates $M K C_{\frac{1}{13}}$. In addition, $M K C_{\frac{1}{10}}$ is facet defining while $M K C_{\frac{1}{13}}$ is not a facet defining inequality. Table 2 presents 11 affinely indepen-
dent points that meet $M K C_{\frac{1}{10}}$ at equality as part of the facet defining proof for $M K C_{\frac{1}{10}}$. Furthermore, $M K C_{\frac{1}{10}}$ is also a cutting plane because $\sum_{j \in C \backslash M} x_{j}^{L R}+$ $\frac{1}{10} \sum_{j \in M} a_{j} x_{j}^{L R}=\frac{21}{5}>4$, where $x^{L R}=\left(0,0,0, \frac{2}{15}, 0,1,1,1,1,0,0\right) \in P^{L R}$ from Example 2.1. Observe that $\frac{21}{5}>\frac{54}{13}$ and $M K C_{\frac{1}{10}}$ also cuts off $x^{L R}$ by more than $M K C_{\frac{1}{13}}$.

Table 2. Affinely independent points for $M K C_{\frac{1}{10}}$.

| $x_{1}$ | 0 | 0 | 0 | 0 | 0 | $\mathbf{1}$ | 0 | 0 | 0 | 0 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $x_{2}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $\mathbf{1}$ | $\mathbf{1}$ | 0 | 0 |
| $x_{3}$ | 0 | 0 | 0 | 0 | 0 | 0 | $\mathbf{1}$ | 0 | 0 | 0 | 0 |
| $x_{4}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $\mathbf{1}$ | 0 | $\mathbf{1}$ | 0 |
| $x_{5}$ | 0 | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1}$ | 0 | 0 | 0 | 0 | 0 | 0 |
| $x_{6}$ | $\mathbf{1}$ | 0 | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1}$ | 0 | 0 | 0 | 0 | 0 | $\mathbf{1}$ |
| $x_{7}$ | $\mathbf{1}$ | $\mathbf{1}$ | 0 | $\mathbf{1}$ | $\mathbf{1}$ | 0 | 0 | 0 | 0 | 0 | $\mathbf{1}$ |
| $x_{8}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1}$ | 0 | $\mathbf{1}$ | 0 | $\mathbf{1}$ | 0 | 0 | $\mathbf{1}$ | $\mathbf{1}$ |
| $x_{9}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1}$ | 0 | $\mathbf{1}$ | $\mathbf{1}$ | 0 | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1}$ |
| $x_{10}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $\mathbf{1}$ | $\mathbf{1}$ | 0 |
| $x_{11}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $\mathbf{1}$ |

Sequence independent lifting [49] is similar to both approximate and exact merged knapsack cover inequalities because the lifted coefficients are correlated to the size of the knapsack coefficients. For instance, consider the same knapsack constraint and cover from Examples 2.1 and 2.2. The resulting sequence independent lifted inequality is given in (4). Observe that $M K C_{\frac{1}{10}}$ weakly dominates the sequence independent lifted inequality in this case. Moreover, the sequence independent lifted inequality in (4) is not facet defining while $M K C_{\frac{1}{10}}$ is a facet defining inequality.

$$
\begin{equation*}
x_{5}+x_{6}+x_{7}+x_{8}+x_{9}+\frac{25}{9} x_{1}+\frac{20}{9} x_{2}+\frac{16}{9} x_{3}+\frac{11}{9} x_{4}+\frac{1}{3} x_{10} \leq 4 \tag{4}
\end{equation*}
$$

To demonstrate EMKCA when $M^{\prime} \neq \emptyset$, consider the same knapsack constraint described in (1) and cover $C=\{5,6,7,8,9\}$. Let $M^{\prime}=\{9\}$ and the inequality presented in (5) is returned by AMKCA while the inequality presented in (6) is returned by EMKCA. In this case, EMKCA's inequality weakly dominates AMKCA's inequality as well.

$$
\begin{align*}
& x_{5}+x_{6}+x_{7}+x_{8}+\frac{1}{12}\left(30 x_{1}+25 x_{2}+20 x_{3}+15 x_{4}+10 x_{9}+5 x_{10}+x_{11}\right) \leq 4  \tag{5}\\
& x_{5}+x_{6}+x_{7}+x_{8}+\frac{1}{11}\left(30 x_{1}+25 x_{2}+20 x_{3}+15 x_{4}+10 x_{9}+5 x_{10}+x_{11}\right) \leq 4 \tag{6}
\end{align*}
$$

## 3. Computational Study

This paper also presents a computational study that evaluates the real effectiveness of both AMKCA and EMKCA to solve MKPs. Multiple knapsack instances
were first solved in CPLEX [60], a high performance mathematical programming solver, at default settings. Thus, approximate and exact merged knapsack cover inequalities were added as preprocessing cuts, and the problems were solved again with these newly developed cutting planes.

The computational study was performed on an Intel ${ }^{\circledR}$ Core ${ }^{T M}$ i7-6700 3.4 GHz processor with 32 GB of RAM. Both AMKCA and EMKCA were implemented in C++ using Microsoft Visual Studio and CPLEX Version 12.7. Computational experiments also stored node files in the hard drive instead of RAM in order to avoid running out of memory.

Computational experiments evaluated approximate and exact merged knapsack cover inequalities with and without overlapping variables between $C$ and $M$. Therefore, computational experiments tested these inequalities with $\left|M^{\prime}\right|=0,\left|M^{\prime}\right|=1$, and $\left|M^{\prime}\right|=2$. Observe that only one inequality was implemented at a time for each multiple knapsack instance.

This study implemented these inequalities with minimal covers as discussed in Section 1. Furthermore, one cover inequality was generated for each constraint of the multiple knapsack instance. The cover inequality of each knapsack constraint $i \in R$ was generated by selecting variables $x_{j}^{L R^{*}}$ with the greatest ratios $r_{j}^{L R^{*}}=$ $\frac{d_{j}^{L R^{*}}}{a_{i, j}}+x_{j}^{L R^{*}}$ for all $j \in N$, where $d_{j}^{L R^{*}}$ is the reduced cost of variable $x_{j}^{L R^{*}}$.

Additionally, the knapsack constraint $i \in R$ selected to generate the newly created inequalities for each instance was determined as the $i^{\text {th }}$ constraint with the $\max \left\{\sum_{j \in C_{i}} x_{j}^{L R^{*}}\right\}$. Observe that the computational time to generate cover inequalities, approximate and exact merged knapsack cover inequalities, and perform other preprocessing operations were not included in the final results. However, these times were less than 0.01 seconds for every implementation and would not have impacted the final results.

Improvement in solution time for each instance is computed by $\Delta_{\text {time }}=$ $\left(\frac{s_{\text {CPLEX }}-s_{\text {MKCA }}}{s_{\text {CPLEX }}}\right) \times 100 \%$ and improvement in the number of ticks is calculated as $\Delta_{\text {ticks }}=\left(\frac{t_{\text {CPLEX }}-t_{\mathrm{MKCA}}}{t_{\text {CPIEX }}}\right) \times 100 \%$, where $s_{\mathrm{MKCA}}$ corresponds to the solution time and $t_{\text {MKCA }}$ is the number of ticks when solved with either approximate or exact merged knapsack cover inequalities, and $s_{\text {CPLEX }}$ is the solution time and $t_{\text {CPLEX }}$ represents the number of ticks when solved with CPLEX at default settings. When $\Delta_{\text {time }}$ and $\Delta_{\text {ticks }}$ of all instances from a corresponding problem set are averaged, it creates $\overline{\Delta_{\text {time }}}$ and $\overline{\Delta_{\text {ticks }}}$, respectively.

### 3.1. Computational Experiments for AMKCA

This paper first describes the results obtained with the implementation of AMKCA. Multiple knapsack instances solved in this study are benchmark problems from the OR-Library [61]. These problems set are named as mknapcb1, mknapcb2, ..., mknapcb9 and each problem set contains 30 instances with: 100, 250, and 500 variables; 5,10 , and 30 constraints. These MKPs are suggested by Chu and Beasley [32] and take the form of maximize $z=\sum_{j \in N} c_{j} x_{j}$, subject to $\sum_{j \in N} a_{i, j} x_{j} \leq b_{i}$ for all $i \in R$ and $x_{j} \in\{0,1\}$ for all $j \in N$.

Each $a_{i, j}$ is integer, randomly generated, and uniformly distributed between an $l b$ and $u b$, where $l b=0$ and $u b=1,000$. Right-hand side values were calculated as $b_{i}=\left\lfloor\delta \sum_{j \in N} a_{i, j}\right\rfloor$, where $\delta$ represents the tightness ratio. Cost coefficients were generated as $c_{j}=\sum_{i \in R} a_{i, j}+\left\lfloor 500 \gamma_{j}\right\rfloor$, where $\gamma_{j}$ is a uniform random number between 0 and 1 . Observe that each problem set from the OR-Library has 10 instances with $\delta=0.25,10$ instances with $\delta=0.50$, and 10 instances with $\delta=0.75$.

This paper solved the following problems set from the OR-Library: mknapcb1, mknapcb2, mknapcb3, mknapcb4, mknapcb5, and mknapcb7. Results for mknapcb6, mknapcb8, and mknapcb9 are not reported in this paper because numerous instances in each of these problems set could not be solved to optimality within a time limit of 24 hours. On average, instances in mknapcb1, mknapcb2, and $m k$ napcb4 4 were solved in less than one minute, instances in mknapcb7 were solved in less than 20 minutes, instances in mknapcb3 were solved in less than 1.5 hours, and instances in mknapcb5 were solved within 3.5 hours. Since problems set mknapcb3 and mknapcb5 appear to be more significant, the solution time and number of ticks for each instance of these sets are presented.

Table 3. Solution time in seconds ( $s_{\text {CPLEX }}$ and $\left.s_{\mathrm{MKCA}}\right)$ and number of ticks ( $t_{\text {CPLEX }}$ and $t_{\mathrm{MKCA}}$ ) obtained when AMKCA is tested with instances in problem set mknapcb3 from the OR-Library ( 500 variables and 5 constraints).

| $\delta$ | \# | $z^{M K P^{*}}$ | Time |  |  |  | Ticks |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | CPLEX | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ | CPLEX | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ |
| 0.25 | 1 | 120,148 | 36,934 | 28,368 | 34,018 | 25,977 | 963,584 | 651,123 | 605,318 | 551,337 |
|  | 2 | 117,879 | 533 | 493 | 272 | 380 | 43,538 | 41,037 | 30,669 | 33,835 |
|  | 3 | 121,131 | 3,795 | 3,823 | 3,887 | 4,711 | 193,531 | 224,182 | 224,300 | 239,284 |
|  | 4 | 120,804 | 2,822 | 2,701 | 1,746 | 3,007 | 195,990 | 192,826 | 176,250 | 189,761 |
|  | 5 | 122,319 | 651 | 622 | 639 | 586 | 67,145 | 65,835 | 68,847 | 65,573 |
|  | 6 | 122,024 | 983 | 963 | 868 | 905 | 150,098 | 117,044 | 110,274 | 111,720 |
|  | 7 | 119,127 | 57,114 | 55,726 | 55,172 | 52,208 | 607,606 | 669,035 | 782,955 | 596,255 |
|  | 8 | 120,568 | 366 | 418 | 404 | 373 | 80,258 | 79,576 | 77,837 | 75,227 |
|  | 9 | 121,586 | 8,394 | 8,653 | 8,333 | 7,796 | 602,556 | 670,157 | 632,483 | 481,723 |
|  | 10 | 120,717 | 6,954 | 7,291 | 4,949 | 7,251 | 319,905 | 346,621 | 240,408 | 356,204 |
| Average |  |  | 11,855 | 10,906 | 11,029 | 10,319 | 322,421 | 305,744 | 294,934 | 270,092 |
| 0.50 | 11 | 218,428 | 281 | 230 | 222 | 221 | 73,447 | 64,293 | 62,036 | 61,718 |
|  | 12 | 221,202 | 243 | 177 | 177 | 216 | 64,651 | 44,336 | 45,425 | 50,654 |
|  | 13 | 217,542 | 2,240 | 983 | 989 | 699 | 2,049,860 | 387,531 | 345,191 | 154,428 |
|  | 14 | 223,560 | 1,139 | 1,104 | 1,028 | 1,043 | 177,378 | 175,958 | 172,310 | 173,538 |
|  | 15 | 218,966 | 53 | 44 | 46 | 44 | 19,209 | 15,880 | 16,270 | 15,923 |
|  | 16 | 220,530 | 425 | 343 | 310 | 313 | 117,202 | 98,356 | 92,540 | 92,072 |
|  | 17 | 219,989 | 155 | 128 | 129 | 131 | 49,432 | 42,629 | 43,148 | 44,074 |
|  | 18 | 218,215 | 326 | 274 | 102 | 96 | 41,195 | 45,074 | 29,803 | 28,503 |
|  | 19 | 216,976 | 364 | 350 | 358 | 350 | 102,715 | 104,596 | 107,187 | 103,102 |
|  | 20 | 219,719 | 392 | 760 | 477 | 404 | 114,352 | 134,245 | 124,088 | 119,136 |
| Average |  |  | 562 | 439 | 384 | 352 | 280,944 | 111,290 | 103,800 | 84,315 |
| 0.75 | 21 | 295,828 | 8 | 8 | 8 | 8 | 2,284 | 2,529 | 2,595 | 2,476 |
|  | 22 | 308,086 | 91 | 75 | 73 | 92 | 28,000 | 23,586 | 23,327 | 27,662 |
|  | 23 | 299,796 | 38 | 32 | 34 | 33 | 11,555 | 9,991 | 10,659 | 10,247 |
|  | 24 | 306,480 | 214 | 167 | 163 | 163 | 60,935 | 50,357 | 48,948 | 49,501 |
|  | 25 | $300,342$ | 50 | 53 | 54 | 53 | 13,553 | 14,425 | 14,889 | 14,535 |
|  | 26 | 302,571 | 101 | 48 | 95 | 57 | 27,565 | 13,905 | 26,959 | 16,463 |
|  | 27 | 301,339 | 849 | 1,139 | 1,098 | 1,129 | 42,530 | 52,504 | 53,088 | 53,363 |
|  | 28 | 306,454 | 62 | 18 | 29 | 45 | 15,435 | 4,532 | 6,118 | 11,775 |
|  | 29 | 302,828 | 94 | 54 | 66 | 70 | 24,493 | 14,201 | 16,740 | 19,819 |
|  | 30 | 299,910 | 185 | 163 | 171 | 172 | 49,818 | 46,547 | 48,909 | 48,801 |
| Average |  |  | 169 | 176 | 179 | 182 | 27,617 | 23,258 | 25,223 | 25,464 |

Tables 3 and 4 provide the solution time and number of ticks for instances in problems set mknapcb3 and mknapcb5. Let \# denote which particular instance refers to the data set. Table 5 presents $\overline{\Delta_{\text {time }}}$ and $\overline{\Delta_{\text {ticks }}}$ for all 10 instances in each problem set tested in this study with $\delta=0.25, \delta=0.50$, and $\delta=0.75$. Recall that $|N|$ is the total number of variables and $|R|$ is the total number of constraints in each problem set. For mknapcb3, the average percentage improvement in solution time is $9.9 \%$ when $\left|M^{\prime}\right|=0,15.5 \%$ when $\left|M^{\prime}\right|=1$, and $13.3 \%$ when $\left|M^{\prime}\right|=2$. Number of ticks are improved on average by $11.3 \%$ when $\left|M^{\prime}\right|=0,12.2 \%$ when $\left|M^{\prime}\right|=1$, and $12.4 \%$ when $\left|M^{\prime}\right|=2$. For mknapcb5, solution time is improved on average by $1.9 \%, 3.6 \%$, and $2.5 \%$ when $\left|M^{\prime}\right|=0,\left|M^{\prime}\right|=1$, and $\left|M^{\prime}\right|=2$,
respectively. Furthermore, the average percentage improvement in the number of ticks is $1.1 \%$ for $\left|M^{\prime}\right|=0,1.9 \%$ for $\left|M^{\prime}\right|=1$, and $0.8 \%$ for $\left|M^{\prime}\right|=2$.

Table 4. Solution time in seconds ( $s_{\text {CPLEX }}$ and $s_{\mathrm{MKCA}}$ ) and number of ticks ( $t_{\text {CPLEX }}$ and $t_{\text {MKCA }}$ ) obtained when AMKCA is tested with instances in problem set mknapcb5 from the OR-Library ( 250 variables and 10 constraints).

| $\delta$ | \# | $z^{M K P^{*}}$ | Time |  |  |  | Ticks |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | CPLEX | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ | CPLEX | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ |
| 0.25 | 1 | 59,187 | 13,356 | 14,426 | 14,727 | 14,825 | 1,655,035 | 1,799,932 | 1,837,299 | 1,849,424 |
|  | 2 | 58,781 | 5,383 | 4,870 | 3,918 | 4,761 | 293,903 | 290,739 | 236,981 | 284,223 |
|  | 3 | 58,097 | 4,388 | 4,871 | 4,652 | 4,926 | 278,116 | 288,010 | 287,053 | 296,163 |
|  | 4 | 61,000 | 20,413 | 20,112 | 21,916 | 22,867 | 2,594,848 | 2,483,525 | 2,615,185 | 2,694,179 |
|  | 5 | 58,092 | 56,474 | 59,365 | 61,138 | 61,057 | 6,995,591 | 7,343,748 | 7,565,223 | 7,597,400 |
|  | 6 | 58,824 | 7,528 | 6,544 | 6,777 | 6,399 | 416,930 | 339,391 | 334,522 | 324,025 |
|  | 7 | 58,704 | 6,667 | 5,321 | 5,417 | 5,449 | 278,173 | 259,731 | 260,490 | 260,758 |
|  | 8 | 58,936 | 40,499 | 47,902 | 49,937 | 47,827 | 5,609,246 | 6,662,269 | 6,930,348 | 6,638,090 |
|  | 9 | 59,387 | 7,179 | 7,036 | 7,055 | 7,058 | 623,819 | 620,053 | 621,679 | 621,956 |
|  | 10 | 59,208 | 14,683 | 15,931 | 15,323 | 16,652 | 1,329,861 | 1,432,828 | 1,377,768 | 1,506,192 |
| Average |  |  | 17,657 | 18,638 | 19,086 | 19,182 | 2,007,552 | 2,152,023 | 2,206,655 | 2,207,241 |
| 0.50 | 11 | 110,913 | 10,336 | 13,086 | 11,860 | 12,515 | 840,879 | 1,054,597 | 954,854 | 1,008,154 |
|  | 12 | 108,717 | 13,784 | 11,822 | 11,787 | 11,196 | 1,212,435 | 1,099,852 | 1,155,044 | 1,077,073 |
|  | 13 | 108,932 | 8,859 | 7,670 | 7,669 | 7,579 | 1,014,826 | 890,074 | 889,910 | 879,614 |
|  | 14 | 110,086 | 33,651 | 33,616 | 33,292 | 33,597 | 4,115,762 | 4,094,506 | 4,030,001 | 4,076,060 |
|  | 15 | 108,485 | 5,942 | 5,124 | 5,246 | 5,175 | 457,495 | 402,188 | 411,568 | 406,124 |
|  | 16 | 110,845 | 14,029 | 13,703 | 13,510 | 13,302 | 1,375,114 | 1,326,986 | 1,318,684 | 1,333,611 |
|  | 17 | 106,077 | 16,051 | 13,796 | 14,370 | 14,166 | 1,639,047 | 1,440,350 | 1,446,479 | 1,446,363 |
|  | 18 | 106,686 | 9,434 | 10,270 | 10,225 | 10,239 | 1,077,533 | 1,162,989 | 1,179,287 | 1,180,920 |
|  | 19 | 109,829 | 9,530 | 9,282 | 9,268 | 9,326 | 1,021,183 | 1,005,362 | 1,003,806 | 1,010,045 |
|  | 20 | 106,723 | 7,214 | 6,343 | 6,340 | 6,432 | 377,800 | 312,434 | 329,835 | 330,633 |
| Average |  |  | 12,883 | 12,471 | 12,357 | 12,353 | 1,313,208 | 1,278,934 | 1,271,947 | 1,274,860 |
| 0.75 | 21 | 151,809 | 3,537 | 4,088 | 4,201 | 4,231 | 247,678 | 269,718 | 269,878 | 275,707 |
|  | 22 | 148,772 | 8,590 | 9,419 | 9,127 | 9,140 | 649,820 | 751,309 | 749,183 | 749,183 |
|  | 23 | 151,909 | 3,201 | 3,009 | 2,948 | 2,711 | 195,756 | 181,553 | 181,720 | 181,087 |
|  | 24 | 151,324 | 2,311 | 2,261 | 2,201 | 2,151 | 161,687 | 154,049 | 157,484 | 157,484 |
|  | 25 | 151,966 | 8,243 | 6,182 | 5,887 | 5,771 | 511,072 | 318,843 | 322,124 | 320,081 |
|  | 26 | 152,109 | 1,619 | 1,527 | 1,521 | 1,531 | 136,431 | 127,645 | 127,110 | 127,988 |
|  | 27 | 153,131 | 248 | 226 | 193 | 204 | 23,155 | 22,117 | 20,460 | 20,658 |
|  | 28 | 153,578 | 9,572 | 10,220 | 10,042 | 10,024 | 1,163,710 | 1,254,598 | 1,232,946 | 1,230,807 |
|  | 29 | 149,160 | 1,984 | 1,515 | 1,570 | 1,584 | 125,201 | 116,879 | 118,869 | 117,710 |
|  | 30 | 149,704 | 1,747 | 2,005 | 1,716 | 1,872 | 129,039 | 159,085 | 146,597 | 152,603 |
| Average |  |  | 4,105 | 4,045 | 3,941 | 3,922 | 334,355 | 335,580 | 332,637 | 333,331 |

When considering the overall average described in Table 5, solution time is improved on average by $8.0 \%$ when $\left|M^{\prime}\right|=0,8.3 \%$ when $\left|M^{\prime}\right|=1$, and $8.5 \%$ when $\left|M^{\prime}\right|=2$. Improvement in the number of ticks are $4.9 \%$ for $\left|M^{\prime}\right|=0,4.5 \%$ for $\left|M^{\prime}\right|=1$, and $5.1 \%$ for $\left|M^{\prime}\right|=2$. Observe that on average, computational results of approximate merged knapsack cover inequalities implemented with $\left|M^{\prime}\right|=0$, $\left|M^{\prime}\right|=1$, and $\left|M^{\prime}\right|=2$ are somewhat similar for the cases reported in this paper, and no conclusions can be made on which overlapping strategy is more efficient.

### 3.2. Computational Experiments for EMKCA

Exact merged knapsack cover inequalities were generated by EMKCA and also tested with benchmark instances from the OR-Library. In such a case, EMKCA's input was the same knapsack constraint and cover inequality used by AMKCA, and the set of merging indices $M$ returned by AMKCA. Surprisingly, each benchmark instance solved with EMKCA had $\alpha^{*}=\alpha$. Consequently, AMKCA generated exact merged knapsack cover inequalities for all the cases.

To investigate why EMKCA did not have any $\alpha^{*}>\alpha$, the authors tracked the array $d$ from EMKCA and noticed that $d$ had the majority, if not all, of its indices

Table 5. $\overline{\Delta_{\text {time }}}$ and $\overline{\Delta_{\text {ticks }}}$ of all 10 instances for each problem set tested from the OR-Library.

| Name | $\|N\|$ | \| $\boldsymbol{R} \mid$ | $\delta$ | Time |  |  | Ticks |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ |
| mknapcb1 | 100 | 5 | 0.25 | 4.7\% | -0.4\% | 3.4\% | -1.1\% | -3.9\% | -2.7\% |
|  |  |  | 0.50 | 4.6\% | -2.1\% | 6.2\% | -0.5\% | 2.3\% | 1.7\% |
|  |  |  | 0.75 | 10.7\% | 12.9\% | 12.7\% | -1.8\% | -2.3\% | 1.7\% |
|  |  |  | Average | 6.7\% | 3.5\% | 7.4\% | -1.1\% | -1.3\% | 1.2\% |
| mknapcb2 | 250 | 5 | 0.25 | 18.7\% | 12.9\% | 12.7\% | -1.8\% | -2.3\% | 4.5\% |
|  |  |  | 0.50 | 10.8\% | 13.7\% | 13.2\% | 11.0\% | 11.6\% | 11.1\% |
|  |  |  | 0.75 | -3.8\% | -6.5\% | -8.4\% | -7.5\% | -10.3\% | -11.4\% |
|  |  |  | Average | 8.6\% | 6.8\% | 7.7\% | 5.2\% | 2.4\% | 3.7\% |
| mknapcb3 | 500 | 5 | 0.25 | 2.1\% | 12.9\% | 5.5\% | 1.9\% | 7.9\% | 8.9\% |
|  |  |  | 0.50 | 8.6\% | 22.1\% | 24.1\% | 14.4\% | 19.5\% | 20.8\% |
|  |  |  | 0.75 | 19.1\% | 11.5\% | 10.2\% | 17.5\% | 9.2\% | 7.5\% |
|  |  |  | Average | 9.9\% | 15.5\% | 13.3\% | 11.3\% | 12.2\% | 12.4\% |
| mknapcb4 | 100 | 10 | 0.25 | 11.1\% | 10.3\% | 10.0\% | 4.9\% | 4.1\% | 3.9\% |
|  |  |  | 0.50 | 10.0\% | 9.6\% | 9.5\% | 9.3\% | 8.8\% | 9.5\% |
|  |  |  | 0.75 | 3.4\% | 4.1\% | 3.6\% | 3.5\% | 3.1\% | 3.9\% |
|  |  |  | Average | 8.1\% | 8.0\% | 7.7\% | 5.9\% | 5.3\% | 5.8\% |
| mknapcb5 | 250 | 10 | 0.25 | -0.5\% | -0.2\% | -2.8\% | -1.3\% | -0.4\% | -3.0\% |
|  |  |  | 0.50 | 3.7\% | 4.7\% | 4.7\% | 3.5\% | 3.6\% | 3.6\% |
|  |  |  | 0.75 | 2.4\% | 6.2\% | 5.8\% | 1.2\% | 2.6\% | 2.0\% |
|  |  |  | Average | 1.9\% | 3.6\% | 2.5\% | 1.1\% | 1.9\% | 0.8\% |
| mknapcb7 | 100 | 30 | 0.25 | 17.3\% | 15.9\% | 17.2\% | 8.1\% | 7.3\% | 9.1\% |
|  |  |  | 0.50 | 12.9\% | 13.1\% | 11.8\% | 6.1\% | 5.2\% | 4.8\% |
|  |  |  | 0.75 | 8.4\% | 7.7\% | 7.8\% | 7.5\% | 6.3\% | 6.2\% |
|  |  |  | Average | 12.9\% | 12.2\% | 12.3\% | 7.3\% | 6.3\% | 6.7\% |
| Overall Average |  |  |  | 8.0\% | 8.3\% | 8.5\% | 4.9\% | 4.5\% | 5.1\% |

marked with a 1. Hunsaker and Tovey [62] show that when knapsack instances are randomly generated, there exists a set $G \subseteq N$ with probability approaching 1 such that $\sum_{j \in G} a_{j} x_{j}=b$. Consequently, many random knapsack instances eliminate gaps in $d$ and so $\alpha^{*}=\alpha$.

To identify instances in which EMKCA produces inequalities that dominate the inequalities generated by AMKCA, observe that if all $a_{i, j}$ are random between 1 and some $a_{\text {max }}$, then several small and one large number can be combined to create numerous combinations between 1 and $2 \times a_{\max }$. Therefore, EMKCA may be useful if $a_{i, j}$ is between some $a_{\min }$ and $a_{\max }$, where $a_{\min }$ is at least $50 \%$ of $a_{\text {max }}$. Since there does not exist any publicly available benchmark instances that follow this criterion, new instances were randomly generated to test EMKCA. This paper attempted two sets of problems where $a_{\min }$ is $50 \%$ and $60 \%$ of $a_{\text {max }}$. These instances follow the same form proposed by Chu and Beasley [32] but instead, they have constraint coefficients from 2,500 to $5,000(l b=2,500$ and $u b=5,000)$ and from 3,000 to $5,000(l b=3,000$ and $u b=5,000)$. Additional experiments where $a_{\text {min }}$ is $90 \%$ of $a_{\text {max }}$ are also provided in Vitor [59].

Since the knapsack coefficients of the newly generated random instances are greater than the knapsack coefficients of the instances from the OR-Library, problems of the same size ( 100,250 , and 500 variables vs. 5,10 , and 30 constraints) are computationally challenging and could not be solved within 24 hours. Consequently, only the following variations of variables and constraints were tested: $40 \times 5,60 \times 5,80 \times 5$, and $100 \times 5$. Similar to the OR-Library, 30 instances were generated for each of these problems set where 10 instances have $\delta=0.25,10$ instances have $\delta=0.50$, and 10 instances have $\delta=0.75$.

On average, instances with 40 variables and 5 constraints were solved in less than 30 seconds, 60 variables and 5 constraints were solved within 15 minutes, 80 variables and 5 constraints were solved in less than 30 minutes, and instances with 100 variables and 5 constraints were solved within 2 hours. For simplicity, only instances that are more significant ( $80 \times 5$ and $100 \times 5$ ) have the solution time and number of ticks reported in this paper. In addition, only the solution time and number of ticks from MKPs where $l b=3,000$ and $u b=5,000$ are presented since the time and number of ticks required to solve instances where $l b=2,500$ and $u b=5,000$ are in the same order of magnitude.

Table 6 describes the results for instances with 80 variables and 5 constraints, and Table 7 presents the results for instances with 100 variables and 5 constraints when $l b=3,000$ and $u b=5,000$. Table 8 shows $\overline{\Delta_{\text {time }}}$ and $\overline{\Delta_{\text {ticks }}}$ for MKPs where $l b=2,500$ and $u b=5,000$, while Table 9 describes the results for MKPs with $l b=3,000$ and $u b=5,000$.

Table 6. Solution time in seconds ( $s_{\text {CPLEX }}$ and $\left.s_{\mathrm{MKCA}}\right)$ and number of ticks ( $t_{\text {CPLEX }}$ and $t_{\mathrm{MKCA}}$ ) obtained when EMKCA is tested with the newly generated random instances ( 80 variables and 5 constraints, $l b=3,000$ and $u b=5,000$ ).

| $\delta$ | \# | $z^{M K P^{*}}$ | Time |  |  |  | Ticks |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | CPLEX | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ | CPLEX | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ |
| 0.25 | 1 | 306,856 | 13 | 14 | 12 | 12 | 1,483 | 1,591 | 1,429 | 1,416 |
|  | 2 | 305,174 | 412 | 308 | 317 | 330 | 34,013 | 25,872 | 29,003 | 27,606 |
|  | 3 | 302,659 | 274 | 153 | 147 | 179 | 16,094 | 14,492 | 14,314 | 15,909 |
|  | 4 | 305,681 | 240 | 64 | 62 | 75 | 10,452 | 7,941 | 8,043 | 8,721 |
|  | 5 | 305,412 | 1,119 | 873 | 784 | 778 | 137,329 | 123,051 | 120,288 | 122,359 |
|  | 6 | 304,329 | 444 | 328 | 331 | 320 | 31,470 | 28,846 | 28,561 | 29,076 |
|  | 7 | 307,051 | 345 | 188 | 185 | 188 | 21,002 | 17,116 | 17,206 | 17,617 |
|  | 8 | 305,596 | 252 | 98 | 102 | 95 | 11,907 | 9,628 | 10,240 | 9,758 |
|  | 9 | 304,410 | 414 | 337 | 282 | 268 | 28,012 | 22,456 | 23,102 | 22,454 |
|  | 10 | 307,926 | 280 | 85 | 83 | 82 | 11,312 | 9,087 | 9,249 | 9,035 |
| Average |  |  | 379 | 245 | 230 | 233 | 30,307 | 26,008 | 26,144 | 26,395 |
| 0.50 | 11 | 612,457 | 11 | 8 | 7 | 11 | 1,151 | 1,037 | 1,062 | 1,269 |
|  | 12 | 609,312 | 804 | 635 | 526 | 522 | 79,464 | 90,415 | 75,540 | 76,624 |
|  | 13 | 604,381 | 869 | 555 | 521 | 528 | 86,548 | 73,147 | 74,140 | 73,818 |
|  | 14 | 610,098 | 4,782 | 3,039 | 3,165 | 3,326 | 849,785 | 654,599 | 662,967 | 708,887 |
|  | 15 | 610,287 | 828 | 495 | 647 | 655 | 83,604 | 63,987 | 72,838 | 70,892 |
|  | 16 | 607,745 | 1,367 | 959 | 901 | 866 | 176,228 | 141,850 | 145,215 | 142,257 |
|  | 17 | 610,020 | 1,538 | 1,035 | 1,081 | 1,028 | 233,426 | 190,440 | 202,157 | 180,326 |
|  | 18 | 608,220 | 73 | 49 | 47 | 48 | 3,933 | 4,392 | 4,362 | 4,443 |
|  | 19 | 614,610 | 381 | 243 | 244 | 223 | 28,805 | 22,464 | 21,971 | 20,657 |
|  | 20 | 615,434 | 2,980 | 1,083 | 1,081 | 1,090 | 521,019 | 187,990 | 192,793 | 190,608 |
| Average |  |  | 1,363 | 810 | 822 | 830 | 206,396 | 143,032 | 145,305 | 146,978 |
| 0.75 | 21 | 915,422 | 228 | 89 | 89 | 87 | 13,058 | 10,553 | 10,486 | 10,417 |
|  | 22 | 911,537 | 403 | 440 | 505 | 447 | 28,973 | 35,164 | 38,479 | 35,391 |
|  | 23 | 904,455 | 249 | 95 | 97 | 94 | 9,328 | 10,778 | 11,034 | 10,737 |
|  | 24 | 913,181 | 561 | 449 | 442 | 451 | 47,547 | 42,785 | 41,207 | 41,421 |
|  | 25 | 913115 | 1,957 | 1,146 | 1,142 | 1,166 | 332,707 | 227,867 | 230,703 | 234,761 |
|  | 26 | 909,672 | 169 | 63 | 61 | 61 | 6,777 | 7,291 | 7,451 | 7,506 |
|  | 27 | 917,076 | 1,575 | 1,164 | 1,371 | 1,419 | 236,014 | 187,904 | 201,840 | 200,749 |
|  | 28 | 912,923 | 423 | 290 | 418 | 252 | 31,820 | 23,991 | 28,066 | 20,614 |
|  | 29 | 909,901 | 437 | 342 | 326 | 341 | 33,535 | 32,020 | 31,301 | 32,783 |
|  | 30 | 919,204 | 596 | 360 | 364 | 384 | 44,869 | 37,674 | 35,485 | 40,203 |
| Average |  |  | 660 | 444 | 482 | 470 | 78,463 | 61,603 | 63,605 | 63,458 |

Overall, the average percentage improvement in solution time for MKPs where $l b=2,500$ and $u b=5,000$ (Table 8 ) is $12.8 \%$ when $\left|M^{\prime}\right|=0,13.2 \%$ when $\left|M^{\prime}\right|=1$, and $15.6 \%$ when $\left|M^{\prime}\right|=2$. Furthermore, the number of ticks are reduced on average by $5.1 \%$ when $\left|M^{\prime}\right|=0,5.3 \%$ when $\left|M^{\prime}\right|=1$, and $7.1 \%$ when $\left|M^{\prime}\right|=2$. For MKPs where $l b=3,000$ and $u b=5,000$ (Table 9), solution time is improved on average by $16.3 \%, 16.1 \%$, and $14.6 \%$ when $\left|M^{\prime}\right|=0,\left|M^{\prime}\right|=1$, and $\left|M^{\prime}\right|=2$, respectively.

Moreover, the average percentage improvement in the number of ticks is $5.1 \%$, $4.3 \%$, and $3.8 \%$ when $\left|M^{\prime}\right|=0,\left|M^{\prime}\right|=1$, and $\left|M^{\prime}\right|=2$, respectively.

Table 7. Solution time in seconds ( $s_{\text {CPLEX }}$ and $s_{\mathrm{MKCA}}$ ) and number of ticks ( $t_{\mathrm{CPLEX}}$ and $t_{\mathrm{MKCA}}$ ) obtained when EMKCA is tested with the newly generated random instances ( 100 variables and 5 constraints, $l b=3,000$ and $u b=5,000$ ).

| $\delta$ | \# | $z^{M K P^{*}}$ | Time |  |  |  | Ticks |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | CPLEX | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ | CPLEX | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ |
| 0.25 | 1 | 409,485 | 1,000 | 1,152 | 1,244 | 1,168 | 132,061 | 151,905 | 139,139 | 132,295 |
|  | 2 | 405,262 | 19,677 | 21,848 | 22,516 | 23,147 | 3,458,479 | 3,378,492 | 3,552,690 | 3,586,408 |
|  | 3 | 407,570 | 935 | 846 | 830 | 857 | 67,511 | 62,109 | 60,525 | 61,998 |
|  | 4 | 409,966 | 3,680 | 4,266 | 4,375 | 4,356 | 784,194 | 838,738 | 822,419 | 827,682 |
|  | 5 | 406,789 | 9,693 | 9,561 | 9,361 | 9,771 | 1,820,472 | 1,764,526 | 1,771,318 | 1,818,242 |
|  | 6 | 408,716 | 25,470 | 26,976 | 26,657 | 25,768 | 4,835,167 | 5,090,715 | 4,981,446 | 4,716,287 |
|  | 7 | 406,266 | 5,672 | 5,141 | 5,113 | 4,852 | 898,976 | 850,390 | 852,056 | 793,220 |
|  | 8 | 409,210 | 1,770 | 1,636 | 1,692 | 1,587 | 230,707 | 221,115 | 235,992 | 223,520 |
|  | 9 | 410,335 | 10,871 | 12,015 | 12,290 | 12,014 | 2,426,846 | 2,256,937 | 2,330,600 | 2,276,982 |
|  | 10 | 410,206 | 6,139 | 5,527 | 5,535 | 5,638 | 1,027,278 | 958,257 | 947,974 | 945,826 |
| Average |  |  | 8,491 | 8,897 | 8,961 | 8,916 | 1,568,169 | 1,557,318 | 1,569,416 | 1,538,246 |
| 0.50 | 11 | 810,884 | 1,264 | 1,078 | 1,117 | 1,095 | 178,991 | 158,193 | 171,134 | 163,621 |
|  | 12 | 812,400 | 7,355 | 6,518 | 6,645 | 6,528 | 1,644,317 | 1,479,536 | 1,494,633 | 1,481,837 |
|  | 13 | 814,371 | 279 | 300 | 274 | 274 | 20,521 | 23,309 | 20,489 | 20,295 |
|  | 14 | 817,131 | 3,633 | 3,923 | 4,418 | 4,446 | 785,714 | 760,945 | 836,401 | 826,337 |
|  | 15 | 814,120 | 5,402 | 6,087 | 7,089 | 7,106 | 1,179,329 | 1,202,764 | 1,498,645 | 1,469,905 |
|  | 16 | 805,030 | 869 | 863 | 853 | 849 | 94,711 | 91,784 | 91,954 | 91,581 |
|  | 17 | 814,805 | 5,494 | 3,719 | 3,914 | 3,968 | 1,012,339 | 653,912 | 687,046 | 699,573 |
|  | 18 | 817,795 | 2,680 | 2,511 | 2,503 | 2,544 | 429,913 | 409,150 | 412,954 | 413,551 |
|  | 19 | 820,410 | 2,896 | 3,503 | 3,602 | 3,693 | 611,374 | 711,224 | 728,024 | 730,709 |
|  | 20 | 809,899 | 2,433 | 2,458 | 2,473 | 2,517 | 407,233 | 439,357 | 446,258 | 430,681 |
| Average |  |  | 3,231 | 3,096 | 3,289 | 3,302 | 636,444 | 593,017 | 638,754 | 632,809 |
| 0.75 | 21 | 1,215,759 | 2,024 | 1,530 | 1,587 | 1,524 | 428,431 | 240,878 | 254,296 | 239,567 |
|  | 22 | 1,212,670 | 2,725 | 3,049 | 2,741 | 2,725 | 511,120 | 542,932 | 518,563 | 511,920 |
|  | 23 | 1,224,965 | 1,061 | 950 | 980 | 931 | 134,792 | 125,789 | 132,225 | 126,773 |
|  | 24 | 1,213,710 | 2,757 | 3,089 | 3,078 | 3,139 | 587,512 | 622,368 | 615,261 | 621,154 |
|  | 25 | 1,221,249 | 821 | 748 | 779 | 811 | 98,047 | 85,380 | 86,961 | 92,394 |
|  | 26 | 1,225,155 | 6,412 | 5,926 | 5,880 | 5,967 | 1,255,618 | 1,179,438 | 1,170,891 | 1,209,091 |
|  | 27 | 1,225,627 | 3,379 | 3,591 | 3,758 | 3,773 | 774,516 | 739,747 | 753,734 | 781,725 |
|  | 28 | 1,218,795 | 485 | 478 | 465 | 476 | 32,451 | 30,950 | 30,095 | 30,810 |
|  | 29 | 1,218,137 | 1,648 | 1,572 | 1,655 | 1,771 | 253,518 | 256,369 | 283,357 | 309,545 |
|  | 30 | 1,218,358 | 987 | 910 | 881 | 873 | 179,770 | 171,268 | 169,532 | 168,094 |
| Average |  |  | 2,230 | 2,184 | 2,180 | 2,199 | 425,578 | 399,512 | 401,492 | 409,107 |

Table 10 describes the percentage improvement in $\alpha^{*}$ for all newly generated random instances tested with EMKCA. Table 10 was obtained by implementing both EMKCA and AMKCA on each instance and comparing the returned merging coefficients, $\alpha^{*}$ and $\alpha$. Percentage improvement in $\alpha^{*}$ is defined for each instance as $\Delta_{\alpha^{*}}=\left(\frac{\alpha^{*}-\alpha}{\alpha}\right) \times 100 \%$, and $\overline{\Delta_{\alpha^{*}}}$ is defined similarly as $\overline{\Delta_{\text {time }}}$ and $\overline{\Delta_{\text {ticks }}}$. Overall, implementing EMKCA instead of AMKCA results in an $\alpha^{*}$ that is on average $8.5 \%, 3.3 \%$, and $1.8 \%$ greater than the $\alpha$ from AMKCA for $\left|M^{\prime}\right|=0,\left|M^{\prime}\right|=1$, and $\left|M^{\prime}\right|=2$, respectively.

When combining both sets of newly generated random multiple knapsack instances $(l b=2,500$ and $u b=5,000$ plus $l b=3,000$ and $u b=5,000)$, the average percentage improvement in solution time is $14.6 \%$ when $\left|M^{\prime}\right|=0,14.7 \%$ when $\left|M^{\prime}\right|=1$, and $15.1 \%$ when $\left|M^{\prime}\right|=2$. Furthermore, the average percentage improvement in the number of ticks is $5.1 \%, 4.8 \%$, and $5.5 \%$ when $\left|M^{\prime}\right|=0,\left|M^{\prime}\right|=1$, and $\left|M^{\prime}\right|=2$, respectively. Since improvement in solution time and number of ticks for each of the three overlapping strategies is somewhat similar, conclusions on which strategy is more efficient cannot be determined based only on the experiments performed for this paper. On the other hand, improvements in $\alpha^{*}$ appears to be more significant when $\left|M^{\prime}\right|=0$ than when $\left|M^{\prime}\right|=1$ and $\left|M^{\prime}\right|=2$. Consequently, one can
infer that even a small improvement in $\alpha^{*}$ can result in substantial improvements in solution time when implementing EMKCA against CPLEX at default settings.

Table 8. $\overline{\Delta_{\text {time }}}$ and $\overline{\Delta_{\text {ticks }}}$ of all 10 problems from the newly generated random instances with $l b=2,500$ and $u b=5,000$.

| $\|N\|$ | $\|\boldsymbol{R}\|$ | $\delta$ | Time |  |  | Ticks |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ | $\left\|M^{\prime}\right\|=\mathbf{0}$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ |
| 40 | 5 | 0.25 | 12.6\% | 4.8\% | 10.2\% | -0.6\% | -1.9\% | -1.6\% |
|  |  | 0.50 | 12.0\% | 11.9\% | 10.4\% | 5.8\% | 6.3\% | 5.8\% |
|  |  | 0.75 | 21.0\% | 23.8\% | 22.5\% | -5.4\% | -4.1\% | 2.1\% |
|  |  | Average | 15.2\% | 13.5\% | 14.4\% | -0.1\% | 0.1\% | 2.1\% |
| 60 | 5 | 0.25 | 1.3\% | 2.7\% | 9.2\% | -1.6\% | -1.8\% | 1.4\% |
|  |  | 0.50 | -7.6\% | -5.1\% | 16.7\% | -2.6\% | -4.3\% | 12.3\% |
|  |  | 0.75 | 10.5\% | 11.0\% | 12.2\% | 3.2\% | 3.2\% | 5.5\% |
|  |  | Average | 1.4\% | 2.9\% | 12.7\% | -0.3\% | -1.0\% | 6.4\% |
| 80 | 5 | 0.25 | 38.4\% | 38.4\% | 38.5\% | 18.8\% | 19.5\% | 17.5\% |
|  |  | 0.50 | 41.6\% | 42.6\% | 41.6\% | 17.9\% | 17.9\% | 16.5\% |
|  |  | 0.75 | 32.1\% | 33.6\% | 31.1\% | 13.2\% | 12.5\% | 11.2\% |
|  |  | Average | 37.3\% | 38.2\% | 37.1\% | 16.7\% | 16.6\% | 15.1\% |
| 100 | 5 | 0.25 | -4.7\% | -4.5\% | -5.3\% | 0.4\% | 1.3\% | -1.7\% |
|  |  | 0.50 | 5.5\% | 5.9\% | 7.5\% | 17.6\% | 19.0\% | 18.9\% |
|  |  | 0.75 | -9.0\% | -7.5\% | -7.2\% | -6.0\% | -3.9\% | -3.3\% |
|  |  | Average | -2.7\% | -2.0\% | -1.7\% | 4.0\% | 5.5\% | 4.6\% |
| Overall Average |  |  | 12.8\% | 13.2\% | 15.6\% | 5.1\% | 5.3\% | 7.1\% |

Table 9. $\overline{\Delta_{\text {time }}}$ and $\overline{\Delta_{\text {ticks }}}$ of all 10 problems from the newly generated random instances with $l b=3,000$ and $u b=5,000$.

| $\|\boldsymbol{N}\|$ | $\|\boldsymbol{R}\|$ | $\delta$ | Time |  |  | Ticks |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ |
| 40 | 5 | 0.25 | 14.1\% | 24.1\% | 23.2\% | -0.6\% | 1.9\% | 7.2\% |
|  |  | 0.50 | 0.9\% | 7.4\% | 5.9\% | -4.2\% | -0.7\% | -0.9\% |
|  |  | 0.75 | 27.6\% | 28.0\% | 24.4\% | 9.6\% | 9.9\% | 5.3\% |
|  |  | Average | 14.2\% | 19.8\% | 17.8\% | 1.6\% | 3.7\% | 3.9\% |
| 60 | 5 | 0.25 | 22.7\% | 15.6\% | 13.5\% | 7.8\% | 5.0\% | 2.1\% |
|  |  | 0.50 | 5.9\% | 7.1\% | 7.8\% | -2.9\% | -1.7\% | -2.3\% |
|  |  | 0.75 | 12.1\% | 5.3\% | -4.9\% | 0.4\% | -5.7\% | -10.9\% |
|  |  | Average | 13.6\% | 9.3\% | 5.5\% | 1.8\% | -0.8\% | -3.7\% |
| 80 | 5 | 0.25 | 38.0\% | 41.6\% | 39.8\% | 14.7\% | 14.2\% | 13.4\% |
|  |  | 0.50 | 35.5\% | 36.5\% | 33.2\% | 17.0\% | 16.9\% | 16.1\% |
|  |  | 0.75 | 35.6\% | 30.1\% | 34.5\% | 8.2\% | 5.6\% | 7.7\% |
|  |  | Average | 36.4\% | $\mathbf{3 6 . 1 \%}$ | 35.9\% | 13.3\% | 12.2\% | 12.4\% |
| 100 | 5 | 0.25 | -2.1\% | -3.7\% | -2.4\% | 0.9\% | 1.2\% | 3.0\% |
|  |  | 0.50 | 1.5\% | -1.8\% | -2.3\% | 2.8\% | -1.0\% | 0.2\% |
|  |  | 0.75 | 3.5\% | 3.4\% | 2.6\% | 7.0\% | 5.8\% | 4.2\% |
|  |  | Average | 1.0\% | -0.7\% | -0.7\% | 3.6\% | 2.0\% | 2.5\% |
| Overall Average |  |  | 16.3\% | 16.1\% | 14.6\% | 5.1\% | 4.3\% | 3.8\% |

In summary, approximate merged knapsack cover inequalities improved the solution time and number of ticks by nearly $8 \%$ and $5 \%$, respectively, while exact merged knapsack cover inequalities improved the solution time by $15 \%$ and the number of ticks by $5 \%$. Based on the computational results presented in this paper, both AMKCA and EMKCA help reduce the effort to solve multiple knapsack instances. The authors recommend implementing EMKCA to solve MKPs in which
the knapsack coefficients are restricted to the cases where the minimum knapsack coefficient is at least $50 \%$ of the maximum knapsack coefficient. Otherwise, AMKCA should be implemented.

| $\|N\|$ | $\|\boldsymbol{R}\|$ | $\delta$ | $l b=2,500$ and $u b=5,000$ |  |  | $l b=3,000$ and $u b=5,000$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ | $\left\|M^{\prime}\right\|=0$ | $\left\|M^{\prime}\right\|=1$ | $\left\|M^{\prime}\right\|=2$ |
| 40 | 5 | 0.25 | 9.4\% | $5.4 \%$ | 4.2\% | 15.8\% | 4.9\% | 1.3\% |
|  |  | 0.50 | 3.5\% | 6.7\% | 3.2\% | 11.4\% | 6.1\% | 3.4\% |
|  |  | 0.75 | 4.7\% | 9.6\% | 2.5\% | 14.8\% | 4.5\% | 0.9\% |
|  |  | Average | 5.9\% | 7.2\% | 3.3\% | 14.0\% | 5.1\% | 1.9\% |
| 60 | 5 | 0.25 | 5.8\% | 3.0\% | 2.5\% | 10.5\% | 4.1\% | 2.5\% |
|  |  | 0.50 | 8.3\% | 0.5\% | 3.9\% | 11.1\% | 2.6\% | 0.8\% |
|  |  | 0.75 | 4.9\% | 6.2\% | 1.0\% | 9.9\% | 3.5\% | 1.9\% |
|  |  | Average | 6.3\% | 3.2\% | 2.5\% | 10.5\% | 3.4\% | 1.7\% |
| 80 | 5 | 0.25 | 1.8\% | 0.5\% | 3.1\% | 10.2\% | 0.5\% | 0.2\% |
|  |  | 0.50 | 2.6\% | 1.2\% | 2.8\% | 11.2\% | 0.8\% | 0.8\% |
|  |  | 0.75 | 4.0\% | 2.0\% | 0.7\% | 10.2\% | 1.4\% | 0.3\% |
|  |  | Average | 2.8\% | 1.3\% | 2.2\% | 10.5\% | 0.9\% | 0.4\% |
| 100 | 5 | 0.25 | 4.3\% | 3.2\% | 1.9\% | 19.8\% | 5.5\% | 1.3\% |
|  |  | 0.50 | 7.2\% | 0.1\% | 0.1\% | 9.8\% | 2.3\% | 2.0\% |
|  |  | 0.75 | 3.5\% | 0.4\% | 0.5\% | 8.8\% | 4.3\% | 1.8\% |
|  |  | Average | 5.0\% | 1.2\% | 0.8\% | 12.8\% | 4.0\% | 1.7\% |
| Overall Average |  |  | 5.0\% | 3.2\% | 2.2\% | 12.0\% | 3.4\% | 1.4\% |

## 4. Conclusions and Future Research

Merged knapsack cover inequalities are a new class of cutting planes for multiple knapsack problems. These inequalities merge the variables of a knapsack constraint with the variables of a cover inequality. This paper presents an algorithm that requires $O(n \log n)$ effort, where $n$ is the number of variables, to generate valid approximate merged knapsack cover inequalities. Furthermore, a dynamic programming technique, which runs in pseudo-polynomial time, improves these approximate inequalities into an exact version.

Computational experiments tested the effectiveness of both approximate and exact merged knapsack cover inequalities versus CPLEX at default settings. In the studied benchmark multiple knapsack instances, approximate merged knapsack cover inequalities improved the solution time on average by nearly $8 \%$ and the number of ticks by $5 \%$. Moreover, exact merged knapsack cover inequalities improved the solution time and number of ticks of the newly generated random instances by $15 \%$ and $5 \%$, respectively.

Future research topics include identifying new classes of inequalities that can be merged to create strong cutting planes and perform computational experiments to show the effectiveness of these new inequalities. Examining new overlapping strategies other than the ones presented in this paper is also a potential future research topic. Computationally comparing the methods described in this paper to other algorithms to solve multiple knapsack problems [33, 35, 49] would also be beneficial to merged knapsack cover inequalities. Finally, one could view merging as a new type of lifting, called inequality lifting. Exploring methods to quickly perform inequality lifting could create new and useful classes of cutting planes.

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[^0]:    ${ }^{*}$ Corresponding author. Email: ftorresvitor@unomaha.edu

