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Thermodynamically Constrained Averaging Theory Approach for Modeling Flow and Transport Phenomena in Porous Medium Systems: 7. Single-Phase Megascale Flow Models

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Abstract

This work is the seventh in a series that introduces and employs the thermodynamically constrained averaging theory (TCAT) for modeling flow and transport in multiscale porous medium systems. This paper expands the previous analyses in the series by developing models at a scale where spatial variations within the system are not considered. Thus the time variation of variables averaged over the entire system is modeled in relation to fluxes at the boundary of the system. This implementation of TCAT makes use of conservation equations for mass, momentum, and energy as well as an entropy balance. Additionally, classical irreversible thermodynamics is assumed to hold at the microscale and is averaged to the megascale, or system scale. The fact that the local equilibrium assumption does not apply at the megascale points to the importance of obtaining closure relations that account for the large-scale manifestation of small-scale variations. Example applications built on this foundation are suggested to stimulate future work.

Keywords

Averaging theory; TCAT; System scale; Model formulation

1 Introduction

Previous manuscripts in this series have laid out, and given examples of, the thermodynamically constrained averaging theory (TCAT) for modeling flow and transport in porous media. The objective of the TCAT approach is to increase the length scale of a model from the pore scale in a rigorous fashion. The method integrates conservation equations and thermodynamic relations over a region of interest to obtain revised equations that are posed at the scale of interest. Thus far, we have provided an overview of the elements of the TCAT approach [13], presented some mathematical identities that are useful when implementing TCAT [23], applied the TCAT formalism to obtain the equations for single-fluid-phase flow in porous media at a length scale on the order of tens to hundreds of pore diameters [14], laid out the additional considerations of importance for multi-species systems in which dispersive processes are operative [24], derived equations for species transport from the perspective of

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momentum equations for each phase and interface as well as the perspective of each species in the phase and interface [16], and considered additional complexity that arises when modeling multiple-fluid-phase flow due to the interactions between the phases and the deformable interface between those phases [19]. In the applications to particular porous medium systems, one consistent objective has been to obtain macroscale equations for which spatial as well as temporal variation of the upscaled variables are considered. The equations developed were closed by constitutive relations derived at the scale of the model.

In many cases, it is useful to model systems at reduced dimensionality. For example, flow in groundwater aquifers may often be considered to be a two-dimensional problem modeled after integration through the thickness of the flow domain [3,26]. Many instances of flow and transport in a laboratory column are modeled as one-dimensional problems. Although one can integrate the full three-dimensional equations developed using TCAT through one, two, or all three spatial dimensions to reduce the dimensionality of the problem, this approach also involves integration of approximate closure relations to produce lower dimensional counterparts. An alternative is to formulate the lower-dimension equations directly at the larger scale and then develop closure forms directly at the scale of interest. Theorems exist that allow the formulation of a model at the microscale (i.e., the pore scale) or macroscale (i.e., a length scale of tens to hundreds of pore diameters) in some dimensions while being fully integrated over space in the remaining dimensions [18], i.e. formulated at the megascale in those dimensions. Such a mixed approach has been employed in one analysis of open channel flow which involved study of only a single phase [11]. Here we will examine full integration to the megascale over all dimensions of conservation and thermodynamic equations for the case of single-fluid-phase flow in porous media. This will be accomplished in the context of the formalism prescribed for the TCAT approach as discussed previously [13,23]. We will make use of averaging theorems that eliminate all spatial derivatives such that the models are posed in terms of average variables representative of the entire system and in terms of fluxes at the boundary of the region [18].

We note in passing that the region of integration may be some subsection of a full physical region of interest. Then application of the approach to a collection of subsections and matching the fluxes at the boundaries between subsections provides a model of the entire system. Thus a domain may be modeled as a collection of uniform regions that are linked together. Alternatively, a portion of a region modeled at the megascale can be linked to adjacent subregions that are modeled at the macroscale, or even the microscale, as desired. Thus the flexibility of being able to make use of different length scales in different subregions of space presents an opportunity to optimize the study of a region based on computer resources, data availability, and the features of the region to be modeled. Therefore, the approach of megascale modeling within the TCAT framework has applications to a range of porous medium problems as well as problems in which no solid phase is present.

In the present work, the elements of the TCAT approach will be reviewed insofar as they need to be revisited to formulate the megascale flow and mass transport equations. The result of the analysis will be closed equations that can be used to model single-fluid-phase flow in porous media at the megascale.

2 System Description

The system under consideration in this work is a single-phase flow of a fluid, designated as the *w* phase, in a deforming porous medium, where the solid is designated as the *s* phase, in which species transport will be considered unimportant. Thus the equations obtained will be used to model the dynamics of an entity, but we will not consider transport of species. Separating the two phases is an interface, denoted as the *ws* interface, for which conservation

and thermodynamic equations will also be developed. This system is the same as that considered in Gray and Miller [14]. However, rather than integrating microscale equations over an averaging volume with a length scale much larger than the pore scale but much smaller than the system scale, integration will be performed over the entire domain. Thus spatial variability is integrated out of the system, and the resulting conservation equations are ordinary differential equations in time. The spatial integration of point equations to obtain global equations is not particularly novel, but the use of a constrained entropy inequality to obtain constitutive forms at the system scale, or megascale, is novel. The TCAT approach has yielded macroscale equations that are rigorously defined and consistent with the microscale precursor conservation equations and thermodynamic principles. These same qualities are sought in the current work for the target models at the macroscale.

For the present study, the domain is denoted as Ω and its volume is \mathbb{V} . Within this domain is a region occupied by a solid phase, Ω_s with a volume of magnitude \mathbb{V}_s ; a region occupied by the fluid phase, Ω_w with a volume of magnitude \mathbb{V}_w ; and the interfacial region between the solid and fluid phases, Ω_{ws} with an area of magnitude A_{ws} . These regions are referred to generically as entities. Microscale conservation equations for mass, momentum, and energy will be written for each entity. The external boundary of domain Ω is denoted as Γ_{e} . The part of this boundary that intersects the w entity is Γ_{we} and the part that intersects the s entity is Γ_{se} . Furthermore, the interface between phases will intersect the boundary of Ω along a collection of common curves designated Γ_{wse} . Although it is possible to work with species based momentum and energy equations, this will not be considered in the present exposition. Furthermore, microscale entropy balance equations will be employed for each entity along with appropriate thermodynamic relations. All these equations will be integrated over the corresponding entities to obtain megascale equations describing the system of interest. At this larger scale, the entropy equations are combined to eliminate the terms describing exchanges of entropy across the ws interface and to obtain the entropy balance for the system. The closed models obtained will account for the dynamics of the two phases and the interface between the phases.

Some shorthand notation will be used that makes the expression of the lengthier equations that arise more compact. The set of entities is denoted as

$$\varepsilon = \{\Omega_t | t \in \mathscr{I}\} = \{\Omega_w, \Omega_s, \Omega_{ws}\},\tag{1}$$

where Ω_{l} represents the domain of the lentity within Ω , $\mathcal{Q} = \{w, s, ws\}$ is the index set of entity qualifiers or identifiers, and *w*, *s*, and *ws* are specific qualifiers that indicate the fluid, or wetting, phase, the solid phase, and the interfacial area between the fluid and solid phases. In instances when we wish to work only with phase entities, we will denote the index set for the phases as $\mathcal{Q}_{P} = \{w, s\}$. The index set of the interfaces for this system consists of a single entity and is denoted as $\mathcal{Q}_{I} = \{ws\}$. With this convention, $\mathcal{Q} = \mathcal{Q}_{P} \cup \mathcal{Q}_{I}$.

A compact notation is also used to identify the connected set for an entity, that is the entities that are in contact with a particular entity. The connected sets for the *w*, *s*, and *ws* entities are, respectively, $\varepsilon_{cw} = \{\Omega_{ws}\}, \varepsilon_{cs} = \{\Omega_{ws}\}, \text{ and } \varepsilon_{cws} = \{\Omega_w, \Omega_s\}$ with corresponding connected entity index sets $\mathscr{Q}_{cw} = \{ws\}, \mathscr{Q}_{cs} = \{ws\}, \text{ and } \mathscr{Q}_{cws} = \{w, s\}.$

In the approach employed here, the length scale of Ω is taken to be much larger than the pore scale. Thus, we will define average quantities for the system. Because these averages apply to the system as a whole, they will not have variability with respect to the length scale of the averages. This distinguishes the current analysis from that in previous TCAT studies. Nevertheless, the integrals of microscale properties that certainly may vary within the system

domain will appear in the megascale equations; and accounting for these variations presents a significant challenge in obtaining closed equations at the scale of interest. The final equations will not contain explicit information about how the microscale entities are distributed within Ω , but the constitutive results will necessarily rely on some degree of specification of the distribution.

Though mathematically distinct from the previous TCAT studies, the approach employed here follows the same route as used in earlier derivations [14,16,19,24]. The existence of these earlier works allows the present contribution to concentrate on the new features incorporated into TCAT analysis here. In general, the formalism requires mathematical theorems that facilitate the change in scale; conservation equations, an entropy balance, and thermodynamic relations at the larger scale; combination of these equations into an entropy inequality that is constrained by the conservation laws; and development of closure relations for the conservation equations from this inequality. These will be developed subsequently.

3 Averaging Operator and Integration Theorems

The theorems employed to integrate the conservation equations for the entities in this system are the standard divergence and transport theorems in three and two dimensions. The primary important feature is to designate the boundaries of each entity explicitly as divided between those that are within the system (i.e., the interphase boundaries at the *ws* interface) and those that occur at the exterior boundary of the system. In the following theorems, we will make use of the definitions of integral operators as introduced previously [23] whereby

$$\langle \mathscr{P}_i \rangle_{\Omega_j, \Omega_k, W} = \frac{\int \mathscr{P}_i W \mathrm{dr}}{\int \Omega_k}, \qquad (2)$$

where \mathscr{P}_i is a property to be averaged to the megascale, and the subscripts on the operator correspond, respectively, to the domain of integration of the numerator, the domain of integration of the denominator, and a weighting function applied to the integrands in the definition of the averaging process. Omission of the third subscript on the averaging operator implies a weighting of unity, W = 1.

Shorthand notation will be employed to indicate various special forms of the averages that arise. The first of these is the average of the property of an entity over that entity, denoted with a superscript such that

$$\mathscr{P}^{\iota} = \langle \mathscr{P}_{\iota} \rangle_{\Omega_{\iota},\Omega_{\iota}}.$$
(3)

For cases when the mass density of the entity is used as a weighting function for averaging, we denote the average with an overbar on the superscript such that

$$\mathcal{P}^{\iota} = \langle \mathcal{P}_{\iota} \rangle_{\Omega_{\iota},\Omega_{\iota},\rho_{\iota}}.$$

$$\tag{4}$$

In some instances, we will average the property of an entity over the domain of another entity. For example, the property of a phase entity can be averaged over the interface that bounds the entity. This is designated by using a subscript to identity the entity to which the property belongs and a superscript to identify the region of integration such as

$$\mathscr{P}_{\iota}^{\kappa} = \langle \mathscr{P}_{\iota} \rangle_{\Omega_{\kappa},\Omega_{\kappa}} \tag{5}$$

and

$$\mathcal{P}_{\iota}^{\overline{\kappa}} = \langle \mathcal{P}_{\iota} \rangle_{\Omega_{\kappa},\Omega_{\kappa},\rho_{\iota}}.$$
(6)

Because the objective of this work is to develop megascale models that are consistent with established microscale conservation and balance equations and thermodynamics, theorems are needed to support rigorously the change of scale that is needed. In previous TCAT papers where equations were developed at the macroscale, the averaging region was fixed. Here, we integrate over an entire region, which may change with time. Therefore, the theorems used to facilitate the change in scale are integration forms rather than averaging forms. Because the microscale entities of concern include phases, which are inherently three-dimensional objects, and an interface, which is a two-dimensional object, theorems are needed to convert both three- and two-dimensional operators to the megascale. Since the megascale models considered in this work are megascale in all spatial dimensions, the class of theorems needed have been derived previously and we follow the naming convention established by Gray et al. [18]. The theorems needed to convert three-dimensional differential operators to the three-dimensional differential operators to the three-dimensional differential operators to the three-dimensional megascale form include the divergence theorem for a microscale phase quantity of the form

Theorem 1 (D[3,(0,0),3])

$$\int_{\Omega_{\iota}} \nabla \cdot \mathbf{f}_{\iota} d\mathbf{r} = \int_{\Omega_{WS}} \mathbf{n}_{\iota} \cdot \mathbf{f}_{\iota} d\mathbf{r} + \int_{\Gamma_{\ell e}} \mathbf{n}_{\iota} \cdot \mathbf{f}_{\iota} d\mathbf{r} \quad \iota \in \mathscr{I}_{\mathbf{p}},$$
(7)

where the microscale spatial vector function \mathbf{f}_{ι} is defined, continuous and differentiable in Ω_{ι} and \mathbf{n}_{ι} is a unit outward normal vector from the boundary of Ω_{ι} .

The gradient theorem for a microscale phase quantity is

Theorem 2 (G[3,(0,0),3])

$$\int_{\Omega_{\iota}} \nabla f_{\iota} d\mathbf{r} = \int_{\Omega_{WS}} \mathbf{n}_{\iota} f_{\iota} d\mathbf{r} + \int_{\Gamma_{\ell e}} \mathbf{n}_{\iota} f_{\iota} d\mathbf{r} \quad \iota \in \mathscr{I}_{\mathbf{P}},$$
(8)

where the microscale spatial scalar function f_t is defined, continuous and differentiable in Ω_t , and \mathbf{n}_t is a unit outward normal vector from the boundary of Ω_t .

The transport theorem for a microscale phase quantity is

Theorem 3 (T[3,(0,0),3])

$$\int_{\Omega_{t}} \frac{\partial f_{\iota}}{\partial t} d\mathbf{r} = \frac{d}{dt} \int_{\Omega_{t}} f_{\iota} d\mathbf{r} - \int_{\Omega_{ws}} \mathbf{n}_{\iota} \cdot \mathbf{v}_{ws} f_{\iota} d\mathbf{r} - \int_{\Gamma_{te}} \mathbf{n}_{\iota} \cdot \mathbf{v}_{ext} f_{\iota} d\mathbf{r}, \quad \iota \in \mathscr{I}_{P}$$
⁽⁹⁾

where f_t is continuous in time, t, \mathbf{v}_{ws} is the velocity vector for the ws interface, and \mathbf{v}_{ext} is the velocity of the exterior portion of the boundary of ι , Γ_{ue} .

Eqn (7)–Eqn (9) are presented in the specific context of integration over a region in a multiphase porous medium, but they are the same as standard divergence and transport theorems found in standard texts [e.g., 8,28]. For the single fluid system being considered here, no common curve exists. Therefore, the divergence and transport theorems for the interface between the two phases have boundaries only at the exterior of the system. The divergence theorem for the surface is

Theorem 4 (D[2,(0,0),3])

$$\int_{\Omega_{ws}} \nabla' \cdot \mathbf{f}_{ws} d\mathbf{r} = \int_{\Omega_{ws}} (\nabla' \cdot \mathbf{n}_t) \ \mathbf{n}_t \cdot \mathbf{f}_{ws} d\mathbf{r} + \int_{\Gamma_{wse}} \mathbf{n}_{ws} \cdot \mathbf{f}_{ws} d\mathbf{r},$$
(10)

where $\iota \in \mathcal{Q}_{\mathbf{P}}, \mathbf{f}_{ws}$ is a continuous, differentiable spatial vector function defined in $\Omega_{ws}, \nabla' \cdot is$ the surface divergence operator, Γ_{wse} is the curve on the system boundary where the Ω_{ws} surface intersects the boundary, and \mathbf{n}_{ws} is a unit vector at the boundary of the domain of interest that is tangent to the ws surface and normal to the boundary curve. Note that \mathbf{n}_{ws} is not necessarily normal to Γ_{e} .

The gradient theorem for the surface is

Theorem 5 (G[2,(0,0),3])

$$\int_{\Omega_{WS}} \nabla' f_{WS} d\mathbf{r} = \int_{\Omega_{WS}} (\nabla' \cdot \mathbf{n}_t) \mathbf{n}_t f_{WS} d\mathbf{r} + \int_{\Gamma_{WSe}} \mathbf{n}_{WS} f_{WS} d\mathbf{r},$$
(11)

where $\iota \in \mathscr{Q}_{P}$, f_{ws} is a continuous, differentiable spatial scalar function defined in Ω_{ws} , ∇' is the surface gradient operator, Γ_{wse} is the curve on the system boundary where the Ω_{ws} surface intersects the boundary, and \mathbf{n}_{ws} is a unit vector at the boundary of the domain of interest that is tangent to the ws surface and normal to the boundary curve.

The transport theorem for a scalar microscale property of the interface, f_{ws} , is

Theorem 6 (T[2,(0,0),3])

$$\int_{\Omega_{WS}} \frac{\partial' f_{WS}}{\partial t} d\mathbf{r} = \frac{d}{dt} \int_{\Omega_{WS}} f_{WS} d\mathbf{r} - \int_{\Omega_{WS}} (\nabla' \cdot \mathbf{n}_t) \, \mathbf{n}_t \cdot \mathbf{v}_{WS} f_{WS} d\mathbf{r} - \int_{\Gamma_{WSE}} \mathbf{n}_{WS} \cdot \mathbf{v}_{ext} f_{WS} d\mathbf{r}$$
(12)

where $\iota \in Q_P$, f_{ws} is continuous in time and differentiable and $\partial'/\partial \iota$ is the partial time derivative with surficial coordinates held constant.

These last three theorems are useful in working with surface conservation equations. Although TCAT and earlier averaging methods for porous media have employed such conservations equations [14,16,19,21] and employed surface theorems [12,18], the derivation of the theorems remains an area of active interest [5,9]. These theorems will be applied to the microscale species mass, momentum, and energy conservation equations as well as the entropy balance equation and the thermodynamic expressions for the *w* and *s* phases and for the *ws* interface. The result

4 Conservation Equations

The TCAT formulation makes use of conservation equations at the scale of interest for the derivation of closure relations. For the system under consideration here, the equations to be used are conservation equations for mass, momentum, and energy for the fluid, solid, and fluid-solid interface. They are obtained from their standard corresponding microscale forms by integration making use of the theorems in §3. Although a more general system could be examined that includes species transport, we will not consider that case here because the primary objective is to demonstrate the TCAT approach at the megascale. In this section, we will also develop the entropy balance equation that is employed in determining the constitutive forms. The equations needed are derived in the following subsections.

4.1 Mass Conservation

For the fluid and solid phase entities, the microscale equation of mass conservation takes the form

$$\frac{\partial \rho_{\iota}}{\partial t} + \nabla \cdot (\rho_{\iota} \mathbf{v}_{\iota}) = 0 \quad \iota \in \mathscr{I}_{\mathbf{p}}.$$
⁽¹³⁾

where ρ_1 is the microscale mass density, and \mathbf{v}_1 is the microscale velocity of the t entity.

Integration of this equation over the domain of the entity and application of the divergence and transport theorems, Eqn (7) and Eqn (9), yields the megascale form

$$\mathscr{M}^{\iota} = \frac{\mathrm{d}\mathbb{M}}{\mathrm{d}t} - \mathbb{V} \overset{WS \to \iota}{M} + \int_{\Gamma_{\mathrm{te}}} \rho_{\iota} (\mathbf{v}_{\iota} - \mathbf{v}_{\mathrm{ext}}) \cdot \mathbf{n}_{\iota} \mathrm{d}\mathbf{r} = 0 \quad \iota \in \mathscr{I}_{\mathrm{P}},$$
(14)

where

$$\mathbb{M}^{\iota} = \int_{\Omega_{\iota}} \rho_{\iota} \mathrm{d}\mathbf{r} \quad \iota \in \mathscr{I}_{\mathbf{P}}, \tag{15}$$

$$\mathbb{V} \stackrel{w_{3} \to \iota}{M} = \int_{\Omega_{w_{3}}} \rho_{\iota} \left(\mathbf{v}_{w_{3}} - \mathbf{v}_{\iota} \right) \cdot \mathbf{n}_{\iota} \, \mathrm{dr} \quad \iota \in \mathscr{I}_{\mathrm{P}},$$
(16)

V is the volume of the domain, M is the mass of the t entity in the domain Ω , and $\frac{w_s \to t}{M}$ is the rate of mass exchange from the *ws* interface to the t phase per unit volume per unit time.

Note that Eqn (14) does not contain any spatial derivatives. The first term is the rate of change of total mass of entity ι in the domain Ω , the second term accounts for the flux of mass into the entity ι due to mass exchange at the interface interior to the system, and the third term accounts for the flux of mass out of the system at the exterior boundary.

The mass conservation for the *ws* interface is a generalization of the usual jump condition at a surface of discontinuity in that mass is also allowed to accumulate in the interface. The general microscale mass conservation equation is written as

$$\frac{\partial' \rho_{ws}}{\partial t} + \nabla' \cdot (\rho_{ws} \mathbf{v}_{ws}) + \sum_{\iota \in \mathscr{I}_{\mathbf{p}}} [\rho_{\iota} (\mathbf{v}_{ws} - \mathbf{v}_{\iota}) \cdot \mathbf{n}_{\iota}]|_{\Omega_{ws}} = 0.$$
(17)

The first two terms account for the rate of change of mass at a location in the interface surface and the net outward flux from that point in directions tangent to the surface, respectively. If the interface is massless such that $\rho_{ws} = 0$, each of these terms is zero. The third term is the net flux from the adjacent phases to the interface. Eqn (17) is integrated over the entire interface domain within the system, and Eqn (10) and Eqn (12) are applied to obtain

$$\mathcal{M}^{ws} = \frac{d\mathbb{M}^{ws}}{dt} + \mathbb{V} \stackrel{ws \to \omega}{M} + \mathbb{V} \stackrel{ws \to s}{M} + \int_{\Gamma_{wse}} \rho_{ws}(\mathbf{v}_{ws} - \mathbf{v}_{ext}) \cdot \mathbf{n}_{ws} \, d\mathbf{r} = 0.$$
(18)

The integral in this expression accounts for flow out of the system of surface mass at the system boundary.

4.2 Momentum Conservation

For a phase entity, the microscale momentum conservation equation is

$$\frac{\partial(\rho_{\iota}\mathbf{v}_{\iota})}{\partial t} + \nabla \cdot (\rho_{\iota}\mathbf{v}_{\iota}\mathbf{v}_{\iota}) - \nabla \cdot \mathbf{t}_{\iota} - \rho_{\iota}\mathbf{g}_{\iota} = 0 \quad \iota \in \mathscr{I}_{\mathrm{P}},$$
(19)

where \mathbf{t}_{t} is the stress tensor and \mathbf{g}_{t} is the acceleration due to a body force. Often this acceleration will be taken to be gravity, although the derivation of equations will allow for more general contributions, such as Coriolis forces and electrical effects. Integration of Eqn (19) over the phase entity and application of divergence theorem Eqn (7) and transport theorem Eqn (9) yields the megascale equation

$$\mathcal{P}^{\iota} = \frac{\frac{d(\mathbb{M}^{\iota} \mathbf{v}^{\overline{\iota}})}{d\iota} - \mathbb{V} \mathbf{T} - \mathbb{V} \mathbf{v}_{\iota}^{\overline{WS} \to \iota} - \mathbb{M}^{\iota} \mathbf{g}^{\overline{\iota}} + \int_{\Gamma_{\iota e}} [\rho_{\iota} \mathbf{v}_{\iota} (\mathbf{v}_{\iota} - \mathbf{v}_{ext}) - \mathbf{t}_{\iota}] \cdot \mathbf{n}_{\iota} \, \mathrm{dr} = 0 \quad \iota \in \mathscr{I}_{\mathrm{P}}$$
(20)

where

$$\mathbb{M}^{\iota} \mathbf{v}^{\bar{\iota}} = \int_{\Omega_{\iota}} \rho_{\iota} \mathbf{v}_{\iota} \mathrm{d}\mathbf{r} \quad \iota \in \mathscr{I}_{\mathrm{P}}$$
(21)

$$\mathbb{V} \stackrel{w_{S} \to \iota}{\mathbf{T}} = \int_{\Omega_{w_{S}}} \left[\rho_{\iota} \left(\mathbf{v}_{\iota} - \mathbf{v}_{\iota}^{\overline{w_{S}}} \right) \left(\mathbf{v}_{w_{S}} - \mathbf{v}_{\iota} \right) + \mathbf{t}_{\iota} \right] \cdot \mathbf{n}_{\iota} \, \mathrm{d}\mathbf{r} \quad \iota \in \mathscr{I}_{\mathrm{P}},$$
(22)

and ${}^{w_{3} \rightarrow \iota}_{T}$ accounts for the transfer of momentum from the *ws* interface to the *ι* phase due to stress and deviations from mean processes per unit volume per unit time.

For the ws interface, the microscale momentum conservation equation is

$$\frac{\partial^{\prime}(\rho_{ws}\mathbf{v}_{ws})}{\partial t} + \nabla^{\prime} \cdot (\rho_{ws}\mathbf{v}_{ws}) - \nabla^{\prime} \cdot \mathbf{t}_{ws} - \rho_{ws}\mathbf{g}_{ws} + [\mathbf{t}_{w} - \rho_{w}\mathbf{v}_{w}(\mathbf{v}_{w} - \mathbf{v}_{ws})] \cdot \mathbf{n}_{w}|_{\Omega_{ws}} + [\mathbf{t}_{s} - \rho_{s}\mathbf{v}_{s}(\mathbf{v}_{s} - \mathbf{v}_{ws})] \cdot \mathbf{n}_{s}|_{\Omega_{ws}} = 0.$$
(23)

When the interface is massless, the first two and the fourth terms in Eqn (23) will be zero. The third term accounts for stress in the interface due to its interfacial tension. The last two terms, involving properties of the adjacent phase entities evaluated at the interface, are the standard terms for the jump condition at the interface. Application of divergence theorem Eqn (10) and transport theorem Eqn (12) leads to the megascale momentum equation for the interface

$$\mathcal{P}^{w_{S}} = \frac{d(\mathbb{M}^{w_{S}}\mathbf{v}^{\overline{w_{S}}})}{dt} + \mathbb{V} \stackrel{w_{S} \to w}{\mathbf{T}} + \mathbb{V} \stackrel{w_{S} \to s}{\mathbf{T}} + \mathbb{V}\mathbf{v}_{w}^{\overline{w_{S}}} \stackrel{w_{S} \to s}{M} + \mathbb{V}\mathbf{v}_{s}^{\overline{w_{S}}} \stackrel{w_{S} \to s}{M} - \mathbb{M}^{w_{S}}\mathbf{g}^{\overline{w_{S}}} - \int_{\Omega_{w_{S}}} (\nabla' \cdot \mathbf{n}_{w}) \mathbf{n}_{w} \cdot \mathbf{t}_{w_{S}} d\mathbf{r} + \int_{\Gamma_{w_{S}}} [\rho_{w_{S}}\mathbf{v}_{w_{S}}(\mathbf{v}_{w_{S}} - \mathbf{v}_{ext}) - \mathbf{t}_{w_{S}}] \cdot \mathbf{n}_{w_{S}} d\mathbf{r} = 0.$$
(24)

4.3 Energy Conservation

For the phase entities, the microscale equation for conservation of total energy is

$$\frac{\partial}{\partial t} \left(E_{\iota} + \frac{1}{2} \rho_{\iota} \mathbf{v}_{\iota} \cdot \mathbf{v}_{\iota} + \rho_{\iota} \psi_{\iota} \right) + \nabla \cdot \left[\mathbf{v}_{\iota} \left(E_{\iota} + \frac{1}{2} \rho_{\iota} \mathbf{v}_{\iota} \cdot \mathbf{v}_{\iota} + \rho_{\iota} \psi_{\iota} \right) \right] - \nabla \cdot \mathbf{q}_{\iota} - \nabla \cdot \left(\mathbf{t}_{\iota} \cdot \mathbf{v}_{\iota} \right) - h_{\iota} - \rho_{\iota} \frac{\partial \psi_{\iota}}{\partial t} = 0 \quad \iota \in \mathscr{I}_{\mathrm{P}},$$
(25)

where E_t is the internal energy density, ψ_t is the acceleration potential, \mathbf{q}_t is the non-advective heat flux density vector, and h_t is the heat source density.

Eqn (25) may be integrated over the corresponding phase entity. After application of divergence theorem Eqn (7) and transport theorem Eqn (9) and some rearrangement of the resulting expression, we obtain the megascale total energy equation

$$\varepsilon^{\iota} = \frac{d}{dt} \left(\mathbb{V} E^{\overline{t}} + \frac{1}{2} \mathbb{M}^{t} \mathbf{v}^{\overline{\iota}} \cdot \mathbf{v}^{\overline{\iota}} + \mathbb{M}^{t} \psi^{\overline{t}} + \mathbb{M}^{t} K_{E}^{\overline{t}} \right)$$

$$- \mathbb{V} \begin{bmatrix} W^{N \to \iota} \\ Q \end{bmatrix} + \mathbf{v}_{\iota}^{WS} \cdot \mathbf{T} + \left(\frac{\mathbb{V} E_{V}^{WS}}{\mathbb{M}^{t}} + \frac{1}{2} \mathbf{v}_{\iota}^{WS} \cdot \mathbf{v}_{\iota}^{WS} + \psi_{\iota}^{WS} \right) \mathbf{M}^{WS \to \iota} \end{bmatrix}$$

$$+ \int_{\Gamma_{tc}} \mathbf{n}_{t} \cdot \left[\left(\mathbf{v}_{\iota} - \mathbf{v}_{ext} \right) \left(E_{\iota} + \frac{1}{2} \rho_{\iota} \mathbf{v}_{\iota} \cdot \mathbf{v}_{\iota} + \rho_{\iota} \psi_{\iota} \right) - \mathbf{q}_{\iota} - \mathbf{t}_{\iota} \cdot \mathbf{v}_{\iota} \right] d\mathbf{r}$$

$$- \mathbb{V}^{\iota} h^{\overline{t}} - \int_{\Omega_{\iota}} \frac{\partial \psi_{\iota}}{\partial t} d\mathbf{r} = 0 \quad \iota \in \mathscr{I}_{p},$$

$$(26)$$

where the averages with the double overbar are particular forms of quantities obtained using the averaging operator such that

$$E^{\bar{\iota}} = \langle E_{\iota} \rangle_{\Omega_{\iota},\Omega} = \epsilon^{\iota} \langle E_{\iota} \rangle_{\Omega_{\iota}\Omega_{\iota}}, \tag{27}$$

$$E_{\iota}^{\overline{WS}} = \epsilon^{\iota} \langle E_{\iota} \rangle_{\Omega_{WS},\Omega_{WS}}, \tag{28}$$

the megascale kinetic energy per unit mass due to microscale velocity fluctuations is

$$K_{E}^{\overline{i}} = \frac{1}{2} \left\langle \left(\mathbf{v}_{\iota} - \mathbf{v}^{\overline{i}} \right) \cdot \left(\mathbf{v}_{\iota} - \mathbf{v}^{\overline{i}} \right) \right\rangle_{\Omega_{\iota},\Omega_{\iota},\Omega_{\iota},\rho_{\iota}},\tag{29}$$

and the term accounting for energy exchange at the interface due to heat exchange and deviation terms is given by

$$\mathbb{V} \stackrel{WS \to t}{Q} = \int_{\Omega_{ws}} \left[\mathbf{q}_{t} + \mathbf{t}_{t} \cdot \left(\mathbf{v}_{t} - \mathbf{v}_{t}^{\overline{WS}} \right) \right] \cdot \mathbf{n}_{t} \, \mathrm{dr} \\
+ \int_{\Omega_{ws}} \left\{ \frac{E_{t}}{\rho_{t}} - \frac{\mathbb{V}E_{t}^{\overline{WS}}}{\mathbb{M}^{t}} \right) \rho_{t} \left(\mathbf{v}_{ws} - \mathbf{v}_{t} \right) \cdot \mathbf{n}_{t} \, \mathrm{dr} \\
+ \int_{\Omega_{ws}} \left[\frac{1}{2} \left(\mathbf{v}_{t} - \mathbf{v}_{t}^{\overline{WS}} \right) \cdot \left(\mathbf{v}_{t} - \mathbf{v}_{t}^{\overline{WS}} \right) + \psi_{t} - \psi_{t}^{\overline{WS}} \right) \rho_{t} \left(\mathbf{v}_{ws} - \mathbf{v}_{t} \right) \cdot \mathbf{n}_{t} \, \mathrm{dr}.$$
(30)

The microscale equation for energy transport at the interface between phases allows for the possibility of accumulation of energy at the interface. Thus, the equation that accounts for interface energy properties along with the usual interface energy jump condition is

$$\frac{\partial'}{\partial t} \left(E_{ws} + \frac{1}{2} \rho_{ws} \mathbf{v}_{ws} \cdot \mathbf{v}_{ws} + \rho_{ws} \psi_{ws} \right) + \nabla' \cdot \left[\mathbf{v}_{ws} \left(E_{ws} + \frac{1}{2} \rho_{ws} \mathbf{v}_{ws} \cdot \mathbf{v}_{ws} + \rho_{ws} \psi_{ws} \right) \right] - \nabla' \cdot \mathbf{q}_{ws} - \nabla' \cdot \left(\mathbf{t}_{ws} \cdot \mathbf{v}_{ws} \right) - h_{ws} - \rho_{ws} \frac{\partial' \psi_{ws}}{\partial t} + \left[\mathbf{q}_w + \mathbf{t}_w \cdot \mathbf{v}_w - \left(E_w + \frac{1}{2} \rho_w \mathbf{v}_w \cdot \mathbf{v}_w + \rho_w \psi_{ws} \right) (\mathbf{v}_w - \mathbf{v}_{ws}) \right] \cdot \mathbf{n}_w \right|_{\Omega_{ws}} + \left[\mathbf{q}_s + \mathbf{t}_s \cdot \mathbf{v}_s - \left(E_s + \frac{1}{2} \rho_s | \mathbf{v}_s \cdot \mathbf{v}_s + \rho_s \psi_{ws} \right) (\mathbf{v}_s - \mathbf{v}_{ws}) \right] \cdot \mathbf{n}_s \right|_{\Omega_{ws}} = 0.$$
(31)

Integration of Eqn (31) over Ω_{ws} and then making use of divergence theorem Eqn (10) and transport theorem Eqn (12) provides the megascale equation, which can be rearranged to the form

$$\boldsymbol{\varepsilon}^{WS} = \frac{\mathrm{d}}{\mathrm{d}t} \left(\nabla E^{\overline{WS}} + \frac{1}{2} \mathbb{M}^{WS} \mathbf{v}^{\overline{WS}} \cdot \mathbf{v}^{\overline{WS}} + \mathbb{M}^{WS} \psi^{\overline{WS}} + \mathbb{M}^{WS} K_{\varepsilon}^{\overline{WS}} \right) \\
+ \nabla \left[\mathcal{Q}^{WS \to W} \cdot \mathbf{v}_{W}^{\overline{WS}} \cdot \mathbf{T}^{\mathbf{T}} + \left(\frac{\nabla E_{v}^{\overline{WS}}}{\mathbb{M}^{w}} + \frac{1}{2} \mathbf{v}_{W}^{\overline{WS}} \cdot \mathbf{v}_{W}^{\overline{WS}} + \psi_{W}^{\overline{WS}} \right) \mathcal{M}^{W} \right] \\
+ \nabla \left[\mathcal{Q}^{WS \to S} \cdot \mathbf{T}^{WS \to W} + \left(\frac{\nabla E_{v}^{\overline{WS}}}{\mathbb{M}^{S}} + \frac{1}{2} \mathbf{v}_{s}^{\overline{WS}} \cdot \mathbf{v}_{w}^{\overline{WS}} + \psi_{w}^{\overline{WS}} \right) \mathcal{M}^{WS} \right] \\
+ \nabla \left[\mathcal{V}_{vsc} - \mathbf{v}_{ext} \right) \left(E_{ws} + \frac{1}{2} \rho_{ws} \mathbf{v}_{ws} \cdot \mathbf{v}_{ws} + \rho_{ws} \psi_{ws} \right) - \mathbf{q}_{ws} - \mathbf{t}_{ws} \cdot \mathbf{v}_{ws} \right] d\mathbf{r} \\
- \int_{\Omega_{ws}} (\nabla' \cdot \mathbf{n}_{w}) \mathbf{n}_{w} \cdot (\mathbf{t}_{ws} \cdot \mathbf{v}_{ws} + \mathbf{q}_{ws}) d\mathbf{r} - \mathbb{A}^{ws} h^{\overline{WS}} - \int_{\Omega_{ws}} \rho_{ws} \frac{\partial \psi_{ws}}{\partial t} d\mathbf{r} = 0,$$
(32)

where \mathbb{A}^{ws} is area of the *ws* interface in Ω .

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4.4 Entropy balance

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The entropy balance equation expresses the rate of change of entropy due to transport as well as generation due to dissipative processes. For a phase entity, the microscale entropy balance is

$$\frac{\partial \eta_{\iota}}{\partial t} + \nabla \cdot (\mathbf{v}_{\iota} \eta_{\iota}) - \nabla \cdot \varphi_{\iota} - b_{\iota} = \Lambda_{\iota} \ge 0\iota \in \mathscr{I}_{\mathrm{p}},$$
(33)

where η_t is the entropy density, φ_t is the entropy density flux vector, b_t is the entropy source density, and Λ_t is the entropy production rate density.

This equation can be integrated over its corresponding domain. Then, after using divergence theorem Eqn (7) and transport theorem Eqn (9) and rearranging, one obtains

$$\mathcal{S}^{\iota} = \frac{\mathrm{d}}{\mathrm{d}\iota} (\mathbb{V}\eta^{\overline{t}}) - \mathbb{V} \begin{bmatrix} W^{S \to \iota} \\ \Phi \end{bmatrix} + \frac{\mathbb{V}\eta^{\overline{W^{S}}}}{\mathbb{M}^{\iota}} M^{T} \end{bmatrix} + \int_{\Gamma_{tc}} [\eta_{\iota} (\mathbf{v}_{\iota} - \mathbf{v}_{\mathrm{ext}}) - \varphi_{\iota}] \cdot \mathbf{n}_{\iota} \, \mathrm{dr} - \mathbb{V}^{\iota} b^{\iota} = \mathbb{V}^{\iota} \Lambda^{\overline{t}} \ge 0 \iota \in \mathscr{I}_{\mathrm{p}},$$
(34)

where

$$\eta^{\bar{t}} = \langle \eta_i \rangle_{\Omega_i,\Omega}, \tag{35}$$

$$\eta_{\iota}^{\overline{WS}} = \epsilon^{\iota} \langle \eta_{\iota} \rangle_{\Omega_{WS},\Omega_{WS}}, \qquad (36)$$

and the term accounting for entropy transport at the interior boundary of entity ι is defined as

$$\mathbb{V} \Phi^{WS \to \iota} = \int_{\Omega_{WS}} \left[\varphi_{\iota} + \left(\frac{\eta_{\iota}}{\rho_{\iota}} - \frac{\mathbb{V} \eta_{\iota}^{\overline{WS}}}{\mathbb{M}^{\iota}} \right) \rho_{\iota} (\mathbf{v}_{WS} - \mathbf{v}_{\iota}) \right] \cdot \mathbf{n}_{\iota} \, \mathrm{d}\mathbf{r}.$$
(37)

The microscale entropy balance for the ws interface is

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$$\frac{\partial' \eta_{ws}}{\partial t} + \nabla' \cdot (\mathbf{v}_{ws} \eta_{ws}) - b_{ws} - \nabla' \cdot \varphi_{ws} + [\varphi_w - \eta_w (\mathbf{v}_w - \mathbf{v}_{ws})] \cdot \mathbf{n}_w |_{\Omega_{ws}} + [\varphi_s - \eta_s (\mathbf{v}_s - \mathbf{v}_{ws})] \cdot \mathbf{n}_s |_{\Omega_{ws}} = \Lambda_{ws} \ge 0.$$
(38)

Eqn (38) is integrated over Ω_{ws} , and divergence theorem Eqn (10) and transport theorem Eqn (12) are applied, yielding the megascale entropy balance for the interface

$$\mathscr{P}^{ws} = \frac{d}{dt} \left(\mathbb{V} \eta^{\overline{ws}} \right) + \mathbb{V} \left[\stackrel{ws \to w}{\Phi} + \left(\frac{\mathbb{V} \eta^{\overline{ws}}}{M^w} \right) \stackrel{ws \to w}{M} \right] \\ + \mathbb{V} \left[\stackrel{ws \to s}{\Phi} + \left(\frac{\mathbb{V} \eta^{\overline{ws}}}{M^s} \right) \stackrel{ws \to s}{M} \right] - \mathbb{A}^{ws} b^{ws} \\ + \int_{\Gamma_{wsc}} \mathbf{n}_{ws} \cdot \left[(\mathbf{v}_{ws} - \mathbf{v}_{ext}) \eta_{ws} - \varphi_{ws} \right] dr \\ - \int_{\Omega_{ws}} (\nabla' \cdot \mathbf{n}_w) \mathbf{n}_w \cdot \varphi_{ws} dr = \mathbb{A}^{ws} \Lambda^{\overline{ws}} \ge 0.$$
(39)

In the entity-based entropy equations, Eqn (34) and Eqn (39), the terms for non-advective entropy transfer at the interfaces appear. These terms make analysis of each entity separately infeasible. Also, the averaging process makes each of these entropy equations a relation for only a portion of the system associated with a particular location. Therefore, the entropy balance that is employed is the summation over all entities. This eliminates the non-advective fluxes at the *ws* interface and provides

$$\sum_{e,\mathscr{I}} \mathscr{S}^{\iota} = \sum_{\iota \in \mathscr{I}} \left[\frac{\mathrm{d}}{\mathrm{d}\iota} (\mathbb{V}\eta^{\overline{i}}) + \int_{\Gamma_{tc}} \mathbf{n}_{\iota} \cdot [(\mathbf{v}_{\iota} - \mathbf{v}_{ext})\eta_{\iota} - \varphi_{\iota}] \,\mathrm{d}\mathbf{r} \right] \\ - \int_{\Omega_{ws}} (\nabla' \cdot \mathbf{n}_{w}) \,\mathbf{n}_{w} \cdot \varphi_{ws} \,\mathrm{d}\mathbf{r} - \mathbb{V}^{w} b^{w} - \mathbb{V}^{s} b^{s} - \mathbb{A}^{ws} b^{ws} \\ = \mathbb{V}^{w} \Lambda^{\overline{w}} + \mathbb{V}^{s} \Lambda^{\overline{s}} + \mathbb{A}^{ws} \Lambda^{\overline{ws}} = \Lambda \ge 0.$$
(40)

This entropy inequality, constrained by the conservation equations and thermodynamic relations, will be employed directly at the megascale to obtain constitutive closure relations. However, before proceeding, it is necessary to obtain the megascale thermodynamic relations.

5 Thermodynamic Relations

The use of thermodynamic relations at the megascale is complicated by the fact that the local equilibrium approximation may not apply for all variables at this scale. Thus, the direct postulation of thermodynamic relations at the megascale runs the risk of being posed in terms of variables that have no relationship to their well-understood microscale counterparts and, perhaps, lack a clear physical meaning. This situation is not unlike what has been noted by Maugin [22] in his discussion of variables used in rational thermodynamics.

Therefore in the TCAT approach, we start with microscale thermodynamic relations and integrate them to the larger scale. This ensures that all large-scale variables are clearly and uniquely defined in terms of their microscale antecedents. The local equilibrium approximation need not be invoked at the megascale. Because the entities in this study are thermodynamically different, being a fluid, a solid, and an interface, their thermodynamic formulations will be presented separately. The derivation follows along the lines of Gray [10] and is based on classical irreversible thermodynamics (CIT) at the microscale [7], but the divergence and transport theorems provided above are employed instead of averaging theorems. Other microscale thermodynamic formulations may be used as a basis for deriving the megascale thermodynamic relations as well, which should be considered if the models produced based upon CIT fail to describe a physical system of interest.

5.1 Fluid-phase thermodynamics

The microscale CIT expression for the energy of the *w* phase per unit volume is [1,4]

$$E_w - \theta_w \eta_w - \mu_w \rho_w + p_w = 0. \tag{41}$$

where θ_w is the temperature, μ_w is the chemical potential, and p_w is the fluid pressure. Integration of this equation over the *w* entity to obtain the megascale expression yields

$$\mathbb{V}E^{\overline{\overline{w}}} - \mathbb{V}\theta^{\overline{\overline{w}}}\eta^{\overline{w}} - \mathbb{M}^{w}\mu^{\overline{w}} + \mathbb{V}^{w}p^{w} = 0, \tag{42}$$

where

$$\theta^{\overline{w}} = \langle \theta_w \rangle_{\Omega_w, \Omega_w, \eta_w}. \tag{43}$$

The partial derivative of Eqn (41) with respect to time is

$$\frac{\partial E_w}{\partial t} - \theta_w \frac{\partial \eta_w}{\partial t} - \mu_w \frac{\partial \rho_w}{\partial t} = 0, \tag{44}$$

which can be rearranged to

$$\frac{\partial E_{w}}{\partial t} - \theta^{\overline{w}} \frac{\partial \eta_{w}}{\partial t} - \mu^{\overline{w}} \frac{\partial \rho_{w}}{\partial t} - \left(\theta_{w} - \theta^{\overline{w}}\right) \frac{\partial \eta_{w}}{\partial t} - \left(\mu_{w} - \mu^{\overline{w}}\right) \frac{\partial \rho_{w}}{\partial t} = 0.$$
(45)

This equation may be integrated using the transport theorem Eqn (9). Subsequent substitution of Eqn (41) then provides

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\mathbb{V}E^{\overline{w}} \right) - \theta^{\overline{w}} \frac{\mathrm{d}}{\mathrm{d}t} \left(\mathbb{V}\eta^{\overline{w}} \right) - \mu^{\overline{w}} \frac{\mathrm{d}\mathbb{M}^{w}}{\mathrm{d}t} + \int_{\Omega_{ws}} p_{w} \mathbf{v}_{ws} \cdot \mathbf{n}_{w} \,\mathrm{d}\mathbf{r} \\ + \int_{\Gamma_{we}} p_{w} \mathbf{v}_{ext} \cdot \mathbf{n}_{w} \,\mathrm{d}\mathbf{r} + \int_{\Omega_{w}} \left[\eta_{w} \frac{\partial \left(\theta_{w} - \theta^{\overline{w}} \right)}{\partial t} + \rho_{w} \frac{\partial \left(\mu_{w} - \mu^{\overline{w}} \right)}{\partial t} \right] \,\mathrm{d}\mathbf{r} = 0.$$
(46)

The gradient of Eqn (41) can be evaluated to obtain a form similar to Eqn (45)

$$\nabla E_{w} - \theta^{\overline{w}} \nabla \eta_{w} - \mu^{\overline{w}} \nabla \rho_{w} - \left(\theta_{w} - \theta^{\overline{w}}\right) \nabla \eta_{w} - \left(\mu_{w} - \mu^{\overline{w}}\right) \nabla \rho_{w} = 0.$$
(47)

This equation may be integrated over Ω_w and simplified using gradient theorem Eqn (8) giving

$$-\int_{\Omega_{ws}} p_{w} \mathbf{n}_{w} \, \mathrm{d}\mathbf{r} - \int_{\Gamma_{w}} p_{w} \mathbf{n}_{w} \, \mathrm{d}\mathbf{r} \\ + \int_{\Omega_{w}} \left[\eta_{w} \nabla \left(\theta_{w} - \theta^{\overline{w}} \right) + \rho_{w} \nabla \left(\mu_{w} - \mu^{\overline{w}} \right) \right] \, \mathrm{d}\mathbf{r} = 0.$$
(48)

The dot product of this equation with $\mathbf{v}^{\overline{w}}$ and addition with Eqn (46) yields

$$\mathcal{T}^{w} = \frac{\mathrm{d}}{\mathrm{d}t} \left(\mathbb{V}E^{\overline{w}} \right) - \theta^{\overline{w}} \frac{\mathrm{d}}{\mathrm{d}t} \left(\mathbb{V}\eta^{\overline{w}} \right) - \mu^{\overline{w}} \frac{\mathrm{d}M^{w}}{\mathrm{d}t} + \int_{\Omega_{ws}} p_{w} \left(\mathbf{v}_{ws} - \mathbf{v}^{\overline{w}} \right) \cdot \mathbf{n}_{w} \, \mathrm{d}r + \int_{\Gamma_{we}} p_{w} \left(\mathbf{v}_{ext} - \mathbf{v}^{\overline{w}} \right) \cdot \mathbf{n}_{w} \, \mathrm{d}r + \int_{\Omega_{ws}} \left[\eta_{w} \frac{\mathbf{D}^{\overline{w}} \left(\theta_{w} - \theta^{\overline{w}} \right)}{\mathrm{D}t} + \rho_{w} \frac{\mathbf{D}^{\overline{w}} \left(\mu_{w} - \mu^{\overline{w}} \right)}{\mathrm{D}t} \right] \, \mathrm{d}r = 0,$$
(49)

where the material derivative is defined as

$$\frac{\mathbf{D}^{t}}{\mathbf{D}t} = \frac{\partial}{\partial t} + \mathbf{v}^{\overline{t}} \cdot \nabla.$$
(50)

By expressing \mathcal{T}^w in this form, we obtain the condition that the terms accounting for non-local equilibrium from a megascale perspective are the integral terms that go to zero when temperature, chemical potential and the velocity differences are zero. The material derivative

defined in Eqn (50) with respect to entity velocity $v\bar{v}$ may be transformed to a form relative to the *s* entity by using the identity

$$\frac{\mathbf{D}^{\bar{\imath}}}{\mathbf{D}t} = \frac{\mathbf{D}^{\bar{\imath}}}{\mathbf{D}t} + \mathbf{v}^{\bar{\imath},\bar{\imath}} \cdot \nabla, \tag{51}$$

where solid-phase referenced velocities are defined as

$$\mathbf{v}^{\overline{t},\overline{\overline{s}}} = \mathbf{v}^{\overline{t}} - \mathbf{v}^{\overline{s}}.$$
(52)

Application of Eqn (51) with t replaced by w to the two material derivatives in Eqn (49) yields

$$\begin{aligned} \mathscr{T}^{w} &= \frac{d}{dt} \left(\mathbb{V}E^{\overline{w}} \right) - \theta^{\overline{w}} \frac{d}{dt} \left(\mathbb{V}\eta^{\overline{w}} \right) - \mu^{\overline{w}} \frac{d\mathbb{M}^{w}}{dt} \\ &+ \int_{\Omega_{ws}} p_{w} \left(\mathbf{v}_{ws} - \mathbf{v}^{\overline{w}} \right) \cdot \mathbf{n}_{w} \, d\mathbf{r} + \int_{\Gamma_{we}} p_{w} \left(\mathbf{v}_{ext} - \mathbf{v}^{\overline{w}} \right) \cdot \mathbf{n}_{w} \, d\mathbf{r} \\ &+ \int_{\Omega_{w}} \left[\eta_{w} \frac{\mathbf{D}^{\overline{s}} \left(\theta_{w} - \theta^{\overline{w}} \right)}{\mathbf{D}t} + \rho_{w} \frac{\mathbf{D}^{\overline{s}} \left(\mu_{w} - \mu^{\overline{w}} \right)}{\mathbf{D}t} \right] \, d\mathbf{r} \\ &+ \int_{\Omega_{w}} \eta_{w} \mathbf{v}^{\overline{w},\overline{s}} \cdot \nabla \left(\theta_{w} - \theta^{\overline{w}} \right) \, d\mathbf{r} + \int_{\Omega_{w}} \rho_{w} \mathbf{v}^{\overline{w},\overline{s}} \cdot \nabla \left(\mu_{w} - \mu^{\overline{w}} \right) \, d\mathbf{r}, \end{aligned}$$
(53)

Because the system under consideration is formulated at the megascale, $\nabla \theta^{\overline{w}} = 0$ and $\nabla \mu^{\overline{w}} = 0$. The microscale Gibbs-Duhem equation for the *w* phase is

$$\eta_w \nabla \theta_w + \rho_w \nabla \mu_w = \nabla p_w. \tag{54}$$

From Eqn (8), it follows that

$$\mathbf{v}^{\overline{w},\overline{s}} \cdot \int_{\Omega_{w}} \nabla p_{w} \, \mathrm{d}\mathbf{r} = \mathbf{v}^{\overline{w},\overline{s}} \cdot \int_{\Omega_{ws}} \mathbf{n}_{w} p_{w} \, \mathrm{d}\mathbf{r} + \mathbf{v}^{\overline{w},\overline{s}} \cdot \int_{\Gamma_{we}} \mathbf{n}_{w} p_{w} \, \mathrm{d}\mathbf{r}.$$
(55)

Eqn (53)-Eqn (55) can be combined to write

$$\mathcal{T}^{w} = \frac{\mathrm{d}}{\mathrm{d}t} (\mathbb{V}E^{\overline{w}}) - \theta^{\overline{w}} \frac{\mathrm{d}}{\mathrm{d}t} (\mathbb{V}\eta^{\overline{w}}) - \mu^{\overline{w}} \frac{\mathrm{d}\mathbb{M}^{w}}{\mathrm{d}t} + \int_{\Omega_{ws}} p_{w}(\mathbf{v}_{ws} - \mathbf{v}^{\overline{s}}) \cdot \mathbf{n}_{w} \, \mathrm{d}\mathbf{r} + \int_{\Gamma_{we}} p_{w}(\mathbf{v}_{ext} - \mathbf{v}^{\overline{s}}) \cdot \mathbf{n}_{w} \, \mathrm{d}\mathbf{r} + \int_{\Omega_{w}} \left[\eta_{w} \frac{\mathbf{D}^{\overline{s}}(\theta_{w} - \theta^{\overline{w}})}{\mathrm{D}t} + \rho_{w} \frac{\mathbf{D}^{\overline{s}}(\mu_{w} - \mu^{\overline{w}})}{\mathrm{D}t} \right] \mathrm{d}\mathbf{r}.$$
(56)

5.2 Solid-phase thermodynamics

For a solid, the CIT expression for the internal energy makes use of the fact that the solid particle movement can be tracked such that the energy of the *s* phase per unit volume is

$$E_s - \theta_s \eta_s - \mu_s \rho_s - \sigma_s: \frac{\mathbf{C}_s}{j_s} = 0,$$
(57)

where σ_s is the Lagrangian stress tensor, s is the Green's deformation tensor, j_s is the solidphase Jacobian, and : indicates a double dot product between the tensors σ_s and s. Integration of Eqn (57) over Ω_s yields the megascale expression for the internal energy

$$\mathbb{V}E^{\overline{s}} - \mathbb{V}\theta^{\overline{s}}\eta^{\overline{s}} - \mathbb{M}^{s}\mu^{\overline{s}} - \mathbb{V}^{s}\sigma^{\overline{s}}: \frac{\mathbf{C}^{s}}{j^{s}} = 0,$$
(58)

where

$$\sigma^{\overline{s}}: \frac{\mathbf{C}^{s}}{j^{s}} = \left\langle \sigma_{s}: \frac{\mathbf{C}_{s}}{j_{s}} \right\rangle_{\Omega_{s},\Omega_{s}}.$$
(59)

The partial derivative of Eqn (57) with respect to time is

$$\frac{\partial E_s}{\partial t} - \theta_s \frac{\partial \eta_s}{\partial t} - \mu_s \frac{\partial \rho_s}{\partial t} - \sigma_s : \frac{\partial}{\partial t} \left(\frac{\mathbf{C}_s}{j_s} \right) = 0.$$
(60)

Introduction of some macroscale variables allows this equation be rearranged to

$$\frac{\partial E_s}{\partial t} - \theta^{\overline{s}} \frac{\partial \eta_s}{\partial t} - \mu^{\overline{s}} \frac{\partial \rho_s}{\partial t} - \sigma^{\overline{s}} : \left(\frac{\mathbf{C}_s}{j_s}\right) - \left(\theta_s - \theta^{\overline{s}}\right) \frac{\partial \eta_s}{\partial t} - \left(\mu_s - \mu^{\overline{s}}\right) \frac{\partial \rho_s}{\partial t} - \left(\sigma_s - \sigma^{\overline{s}}\right) : \frac{\partial}{\partial t} \left(\frac{\mathbf{C}_s}{j_s}\right) = 0.$$
(61)

Integration of Eqn (61) over Ω_s , application of transport theorem Eqn (9), and substitution of Eqn (57) then provides

$$\frac{\mathrm{d}}{\mathrm{d}t}(\mathbb{V}E^{\overline{s}}) - \theta^{\overline{s}}\frac{\mathrm{d}}{\mathrm{d}t}(\mathbb{V}\eta^{\overline{s}}) - \mu^{\overline{s}}\frac{\mathrm{d}\mathbb{M}^{s}}{\mathrm{d}t} - \sigma^{\overline{s}}:\frac{\mathrm{d}}{\mathrm{d}t}\left(\mathbb{V}^{s}\frac{\mathbf{C}^{s}}{j^{s}}\right) + \int_{\Omega_{s}} \left[\eta_{s}\frac{\partial(\theta_{s} - \theta^{\overline{s}})}{\partial t} + \rho_{s}\frac{\partial(\mu_{s} - \mu^{\overline{s}})}{\partial t} + \frac{\mathbf{C}_{s}}{j_{s}}:\frac{\partial(\sigma_{s} - \sigma^{\overline{s}})}{\partial t}\right] \mathrm{d}\mathbf{r} = 0.$$

$$(62)$$

The gradient of Eqn (57) can be evaluated to obtain a form similar to Eqn (61)

$$\nabla E_{s} - \theta^{\overline{s}} \nabla \eta_{s} - \mu^{\overline{s}} \nabla \rho_{s} - \sigma^{\overline{s}} : \nabla \left(\frac{\mathbf{c}_{s}}{j_{s}} \right) - (\theta_{s} - \theta^{\overline{s}}) \nabla \eta_{s} - (\mu_{s} - \mu^{\overline{s}}) \nabla \rho_{s} - (\sigma_{s} - \sigma^{\overline{s}}) : \nabla \left(\frac{\mathbf{c}_{s}}{j_{s}} \right) = 0.$$
(63)

Integration of Eqn (63) over Ω_s and use of gradient theorem Eqn (8) in light of Eqn (57) gives

$$\int_{\Omega s} \left[\eta_s \nabla(\theta_s - \theta^{\overline{s}}) + \rho_s \nabla(\mu_s - \mu^{\overline{s}}) + \frac{\mathbf{C}_s}{j_s} : \nabla(\sigma_s - \sigma^{\overline{s}}) \right] d\mathbf{r} = 0.$$
(64)

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Taking the dot product of Eqn (64) with $\mathbf{v}^{\overline{s}}$ and adding the result to Eqn (62) yields

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$$\mathcal{T}^{s} = \frac{\mathrm{d}}{\mathrm{d}t} (\mathbb{V}E^{\overline{s}}) - \theta^{\overline{s}} \frac{\mathrm{d}}{\mathrm{d}t} (\mathbb{V}\eta^{\overline{s}}) - \mu^{\overline{s}} \frac{\mathrm{d}\mathbb{M}^{s}}{\mathrm{d}t} - \sigma^{\overline{s}} : \frac{\mathrm{d}}{\mathrm{d}t} (\mathbb{V}^{s} \frac{\mathbf{C}^{s}}{j^{s}}) + \int_{\Omega_{w}} \left[\eta_{s} \frac{\mathrm{D}^{\overline{s}}(\theta_{s} - \theta^{\overline{s}})}{\mathrm{D}t} + \rho_{s} \frac{\mathrm{D}^{\overline{s}}(\mu_{s} - \mu^{\overline{s}})}{\mathrm{D}t} + \frac{\mathbf{C}_{s}}{j_{s}} : \frac{\mathrm{D}^{\overline{s}}(\sigma_{s} - \sigma^{\overline{s}})}{\mathrm{D}t} \right] \mathrm{d}\mathbf{r} = 0.$$

$$(65)$$

Following the approach in Gray and Schrefler [17], we can show that

$$-\sigma^{\overline{s}}: \frac{d}{dt} \left(\mathbb{V}^{s} \frac{\mathbf{C}^{s}}{j^{s}} \right) + \int_{\Omega_{w}} \left[\frac{\mathbf{C}_{s}}{j_{s}}: \frac{\mathbf{D}^{\overline{s}}(\sigma_{s} - \sigma^{\overline{s}})}{\mathbf{D}t} \right] d\mathbf{r} = - \int_{\Omega_{ws}} \mathbf{n}_{s} \cdot \left[\frac{2}{j_{s}} \sigma_{s}: (\nabla_{x} \mathbf{x} \nabla_{x} \mathbf{x}) \cdot (\mathbf{v}_{s} - \mathbf{v}^{\overline{s}}) \right] d\mathbf{r} - \int_{\Gamma_{se}} \mathbf{n}_{s} \cdot \left[\frac{2}{j_{s}} \sigma_{s}: (\nabla_{x} \mathbf{x} \nabla_{x} \mathbf{x}) \cdot (\mathbf{v}_{s} - \mathbf{v}^{\overline{s}}) \right] d\mathbf{r} - \int_{\Omega_{s}} \left\{ \nabla \cdot \left[\frac{2}{j_{s}} \sigma_{s}: (\nabla_{x} \mathbf{x} \nabla_{x} \mathbf{x}) \right] - \nabla \sigma_{s}: \frac{\mathbf{C}_{s}}{j_{s}} \right\} \cdot (\mathbf{v}_{s} - \mathbf{v}^{\overline{s}}) d\mathbf{r} - \int_{\Omega_{ws}} \mathbf{n}_{s} \cdot (\mathbf{v}_{ws} - \mathbf{v}_{s}) \sigma_{s}: \frac{\mathbf{C}_{s}}{j_{s}} d\mathbf{r} - \int_{\Gamma_{se}} \mathbf{n}_{s} \cdot (\mathbf{v}_{ext} - \mathbf{v}_{s}) \sigma_{s}: \frac{\mathbf{C}_{s}}{j_{s}} d\mathbf{r},$$
(66)

where $\nabla_X \mathbf{x}$ is the derivative of a microscale location on the solid phase with respect to its initial location [8].

Substitution of this identity into Eqn (65) and minor rearrangement provides the megascale thermodynamic expression for the solid phase

$$\mathcal{T}^{s} = \frac{d}{dt} (\mathbb{V}E^{\overline{s}}) - \theta^{\overline{s}} \frac{d}{dt} (\mathbb{V}\eta^{\overline{s}}) - \mu^{\overline{s}} \frac{d\mathbb{M}^{s}}{dt} + \int_{\Omega_{ws}} \left[\eta_{s} \frac{\mathbf{D}^{\overline{s}}(\theta_{s} - \theta^{\overline{s}})}{\mathbf{D}t} + \rho_{s} \frac{\mathbf{D}^{\overline{s}}(\mu_{s} - \mu^{\overline{s}})}{\mathbf{D}t} \right] d\mathbf{r} + \int_{\Omega_{ws}} \left[\frac{2}{j_{s}} \sigma_{s} : (\nabla_{x} \mathbf{x} \nabla_{x} \mathbf{x}) \cdot (\mathbf{v}_{s} - \mathbf{v}^{\overline{s}}) \right] d\mathbf{r} + \int_{\Gamma_{sc}} \mathbf{n}_{s} \cdot \left[\frac{2}{j_{s}} \sigma_{s} : (\nabla_{x} \mathbf{x} \nabla_{x} \mathbf{x}) \cdot (\mathbf{v}_{s} - \mathbf{v}^{\overline{s}}) \right] d\mathbf{r} + \int_{\Omega_{s}} \left\{ \nabla \cdot \left[\frac{2}{j_{s}} \sigma_{s} : (\nabla_{x} \mathbf{x} \nabla_{x} \mathbf{x}) \right] - \nabla \sigma_{s} : \frac{\mathbf{C}_{s}}{j_{s}} \right\} \cdot (\mathbf{v}_{s} - \mathbf{v}^{\overline{s}}) d\mathbf{r} + \int_{\Omega_{ws}} \left\{ \nabla \cdot \left[\frac{2}{j_{s}} \sigma_{s} : (\nabla_{x} \mathbf{x} \nabla_{x} \mathbf{x}) \right] - \nabla \sigma_{s} : \frac{\mathbf{C}_{s}}{j_{s}} \right\} \cdot (\mathbf{v}_{s} - \mathbf{v}^{\overline{s}}) d\mathbf{r} - \int_{\Omega_{ws}} \mathbf{n}_{s} \cdot (\mathbf{v}_{ws} - \mathbf{v}_{s}) \sigma_{s} : \frac{\mathbf{C}_{s}}{j_{s}} d\mathbf{r} - \int_{\Gamma_{sc}} \mathbf{n}_{s} \cdot (\mathbf{v}_{ext} - \mathbf{v}_{s}) \sigma_{s} : \frac{\mathbf{C}_{s}}{j_{s}} d\mathbf{r}.$$
(67)

5.3 Interface thermodynamics

A surface is a two-dimensional entity and the stress in a surface is due to interfacial tension effects. The microscale thermodynamic expression obtained from CIT for a surface is

$$E_{ws} - \theta_{ws}\eta_{ws} - \mu_{ws}\rho_{ws} - \gamma_{ws} = 0.$$
(68)

where γ_{ws} is the interfacial tension. Integration of this expression over Ω_{ws} within the megascale volume yields

$$\mathbb{V}E^{\overline{ws}} - \mathbb{V}\theta^{\overline{ws}}\eta^{\overline{ws}} - \mathbb{M}^{ws}\mu^{\overline{ws}} - \mathbb{A}^{ws}\gamma^{ws} = 0.$$
(69)

The partial time derivative of Eqn (68) is taken while holding the surface coordinates constant such that

$$\frac{\partial' E_{ws}}{\partial t} - \theta_{ws} \frac{\partial' \eta_{ws}}{\partial t} - \mu_{ws} \frac{\partial' \rho_{ws}}{\partial t} = 0,$$
(70)

or after introduction of macroscale variables

$$\frac{\partial' E_{ws}}{\partial t} - \theta^{\overline{ws}} \frac{\partial' \eta_{ws}}{\partial t} - \mu^{\overline{ws}} \frac{\partial' \rho_{ws}}{\partial t} - (\theta_{ws} - \theta^{\overline{ws}}) \frac{\partial' \eta_{ws}}{\partial t} - (\mu_{ws} - \mu^{\overline{ws}}) \frac{\partial' \rho_{ws}}{\partial t} = 0.$$
(71)

Integration of Eqn (71) over Ω_{ws} and use of transport theorem Eqn (12) and identity Eqn (68) yields

$$\frac{\mathrm{d}}{\mathrm{d}t}(\mathbb{V}E^{\overline{ws}}) - \theta^{\overline{ws}}\frac{\mathrm{d}}{\mathrm{d}t}(\mathbb{V}\eta^{\overline{ws}}) - \mu^{\overline{ws}}\frac{\mathrm{d}\mathbb{M}^{ws}}{\mathrm{d}t} - \int_{\Omega_{ws}} (\nabla \cdot \mathbf{n}_{w}) \gamma_{ws} \mathbf{v}_{ws} \cdot \mathbf{n}_{w} \,\mathrm{d}r \\ - \int_{\Gamma_{wse}} \gamma_{ws} \mathbf{v}_{ext} \cdot \mathbf{n}_{ws} \mathrm{d}r + \int_{\Omega_{ws}} \left[\eta_{ws} \frac{\partial'(\theta_{ws} - \theta^{\overline{ws}})}{\partial t} + \rho_{ws} \frac{\partial'(\mu_{ws} - \mu^{\overline{ws}})}{\partial t} \right] \mathrm{d}r = 0.$$
(72)

The surface gradient of Eqn (68) can be evaluated to obtain a form similar to Eqn (71)

$$\nabla' E_{ws} - \theta^{\overline{ws}} \nabla' \eta_{ws} - \mu^{\overline{ws}} \nabla' \rho_{ws} - (\theta_{ws} - \theta^{\overline{ws}}) \nabla' \eta_{ws} - (\mu_{ws} - \mu^{\overline{ws}}) \nabla' \rho_{ws} = 0.$$
(73)

Integration of Eqn (73) over Ω_{ws} accompanied by use of the gradient theorem Eqn (11) and substitution of Eqn (68) gives

$$\int_{\Omega_{ws}} (\nabla \cdot \mathbf{n}_{w}) \gamma_{ws} \mathbf{n}_{w} d\mathbf{r} + \int_{\Gamma_{wse}} \gamma_{ws} \mathbf{n}_{ws} d\mathbf{r} + \int_{\Omega_{ws}} \left[\eta_{ws} \nabla'(\theta_{ws} - \theta^{\overline{ws}}) + \rho_{ws} \nabla'(\mu_{ws} - \mu^{\overline{ws}}) \right] d\mathbf{r} = 0.$$
(74)

The dot product of Eqn (74) with $v^{\overline{ws}}$ and addition to Eqn (72) yields

$$\frac{d}{dt}(\mathbb{V}E^{\overline{Ws}}) - \theta^{\overline{Ws}} \frac{d}{dt}(\mathbb{V}\eta^{\overline{Ws}}) - \mu^{\overline{Ws}} \frac{d\mathbb{M}^{ws}}{dt} - \int_{\Omega_{ws}} (\nabla \cdot \mathbf{n}_{w}) \gamma_{ws}(\mathbf{v}_{ws} - \mathbf{v}^{\overline{Ws}}) \cdot \mathbf{n}_{w} d\mathbf{r}
- \int_{\Gamma_{wse}} \gamma_{ws}(\mathbf{v}_{ext} - \mathbf{v}^{\overline{Ws}}) \cdot \mathbf{n}_{ws} d\mathbf{r}
+ \int_{\Omega_{ws}} \eta_{ws} \left[\frac{\partial'(\theta_{ws} - \theta^{\overline{Ws}})}{\partial t} + \mathbf{v}^{\overline{Ws}} \cdot \nabla'(\theta_{ws} - \theta^{\overline{Ws}}) \right] d\mathbf{r}
+ \int_{\Omega_{ws}} \rho_{ws} \left[\frac{\partial'(\mu_{ws} - \mu^{\overline{Ws}})}{\partial t} + \mathbf{v}^{\overline{Ws}} \cdot \nabla'(\mu_{ws} - \mu^{\overline{Ws}}) \right] d\mathbf{r} = 0.$$
(75)

Using the definition

$$\frac{\mathbf{D}'^{\overline{s}}}{\mathbf{D}t} = \frac{\partial'}{\partial t} + \mathbf{v}^{\overline{s}} \cdot \nabla', \tag{76}$$

Eqn (75) may be restated as

$$\frac{d}{dt}(\mathbb{V}E^{\overline{ws}}) - \theta^{\overline{ws}} \frac{d}{dt}(\mathbb{V}\eta^{\overline{ws}}) - \mu^{\overline{ws}} \frac{dh^{ws}}{dt} - \int_{\Omega_{ws}} (\nabla \cdot \mathbf{n}_{w})\gamma_{ws}(\mathbf{v}_{ws} - \mathbf{v}^{\overline{ws}}) \cdot \mathbf{n}_{w} d\mathbf{r} - \int_{\Gamma_{wse}} \gamma_{ws}(\mathbf{v}_{ext} - \mathbf{v}^{\overline{ws}}) \cdot \mathbf{n}_{ws} d\mathbf{r} + \int_{\Omega_{ws}} \eta_{ws} \left[\frac{\mathbf{D}'^{\overline{s}}(\theta_{ws} - \theta^{\overline{ws}})}{\mathbf{D}t} + (\mathbf{v}^{\overline{ws}} - \mathbf{v}^{\overline{s}}) \cdot \nabla'(\theta_{ws} - \theta^{\overline{ws}}) \right] d\mathbf{r} + \int_{\Omega_{ws}} \rho_{ws} \left[\frac{\mathbf{D}'^{\overline{s}}(\mu_{ws} - \mu^{\overline{ws}})}{\mathbf{D}t} + (\mathbf{v}^{\overline{ws}} - \mathbf{v}^{\overline{s}}) \cdot \nabla'(\mu_{ws} - \mu^{\overline{ws}}) \right] d\mathbf{r} = 0.$$
(77)

However, spatial derivatives of megascale quantities are zero and the Gibbs-Duhem equation provides

$$\eta_{ws} \nabla' \theta_{ws} + \rho_{ws} \nabla' \mu_{ws} + \nabla' \gamma_{ws} = 0.$$
⁽⁷⁸⁾

Therefore, Eqn (77) may be simplified to

$$\mathcal{T}^{ws} = \frac{d}{dt} (\mathbb{V} E^{\overline{ws}}) - \overline{\theta^{\overline{ws}}} \frac{d}{dt} (\mathbb{V} \eta^{\overline{ws}}) - \mu^{\overline{ws}} \frac{d\mathbb{M}^{ws}}{dt} - \int_{\Omega_{ws}} (\nabla \cdot \mathbf{n}_w) \gamma_{ws} (\mathbf{v}_{ws} - \mathbf{v}^{\overline{s}}) \cdot \mathbf{n}_w \, d\mathbf{r} - \int_{\Gamma_{wse}} \gamma_{ws} (\mathbf{v}_{ext} - \mathbf{v}^{\overline{s}}) \cdot \mathbf{n}_{ws} \, d\mathbf{r} + \int_{\Omega_{ws}} \left[\eta_{ws} \frac{D'^{\overline{s}} (\theta_{ws} - \overline{\theta^{\overline{ws}}})}{Dt} + \rho_{ws} \frac{D'^{\overline{s}} (\mu_{ws} - \mu^{\overline{ws}})}{Dt} \right] d\mathbf{r} = 0.$$
(79)

6 Constrained Entropy Inequality

The next step in the development of the TCAT model is to employ the conservation equations and the thermodynamic relations as constraints on the entropy inequality Eqn (40). The constraint equations developed previously (i.e., Eqn (14), Eqn (18), Eqn (20), Eqn (24), Eqn (26), Eqn (32), Eqn (49), Eqn (65), and Eqn (79)) may be employed to write the entropy inequality as

$$\sum_{\iota \in \mathscr{I}} (\mathscr{S}^{\iota} + \lambda_{\varepsilon}^{\iota} \varepsilon^{\iota} + \lambda_{\mathscr{P}}^{\iota} \cdot \mathscr{P}^{\iota} + \lambda_{\mathscr{M}}^{\iota} \mathscr{M}^{\iota} + \lambda_{\mathscr{T}}^{\iota} \mathscr{T}^{\iota}) = \Lambda \ge 0,$$
(80)

where the coefficients $\lambda_{\varepsilon}^{\iota}$, $\lambda_{\mathscr{P}}^{\iota}$, $\lambda_{\mathscr{M}}^{\iota}$ and $\lambda_{\mathscr{T}}^{\iota}$ are Lagrange multipliers whose values will be selected. Note that the quantities being added to the entropy inequality are all zero and thus the expression for entropy generation provided by entropy inequality Eqn (40) is preserved. The Lagrange multipliers are thus free parameters such that the generation term Λ is unaltered. By selecting the multipliers judiciously, most of the time derivatives in the equation can be eliminated so that the generation term takes on a form that is a collection of force-flux products [7,20]. Because of the integration over the entire domain to the macroscale, the force-flux relations are those for the entire domain plus those at the boundaries of the region. Those at the boundaries must also be evaluated at the megascale. Thus the generation term is of the general form

$$\sum_{i} J_{i}F_{i} + \sum_{j} \mathbf{J}_{j} \cdot \mathbf{F}_{j} + \sum_{k} \mathbf{J}_{k}: \mathbf{F}_{k} = \Lambda,$$
(81)

where each of the independent driving forces, designated as a scalar F, vector \mathbf{F} , or tensor, along with a subscript, is zero at equilibrium. Additionally, all the conjugate fluxes, designated as a scalar by J, a vector by \mathbf{J} , or a tensor by will also be zero at equilibrium.

With this in mind, the multipliers that cancel the time derivatives arising in Eqn (80) are

$$\lambda_{\mathscr{T}}^{\iota} = -\lambda_{\varepsilon}^{\iota} = \frac{1}{\theta^{\overline{\iota}}},\tag{82}$$

$$\boldsymbol{\lambda}_{\mathscr{P}}^{t} = \frac{\mathbf{v}^{t}}{\bar{\theta}^{\bar{t}}},\tag{83}$$

and

$$\lambda_{\mathscr{M}}^{\iota} = \frac{1}{\theta^{\overline{\iota}}} \left(\mu^{\overline{\iota}} + K_{E}^{\overline{\iota}} + \psi^{\overline{\iota}} - \frac{1}{2} \mathbf{v}^{\overline{\iota}} \cdot \mathbf{v}^{\overline{\iota}} \right).$$
(84)

Substitution of these values into Eqn (80) followed by algebraic rearrangement of expressions and some cancellations of terms yields the constrained entropy inequality (CEI) in the form

$$\begin{split} & -\frac{1}{\sigma} \prod_{r,w}^{\infty} \| w \cdot (w - v_{ext}) \left[\frac{1}{2} \rho_{w} \left(v_{w} - v_{w}^{\overline{w}} \right) \cdot \left(v_{w} - v_{w}^{\overline{w}} \right) \\ & + \rho_{w} \left(\mu_{w} + \psi_{w} - \mu^{\overline{w}} - K_{\overline{v}}^{\overline{w}} - \psi^{\overline{w}} \right) \right] dt \\ & -\frac{1}{\sigma} \prod_{r,w}^{\infty} (v_{x} - v_{ext}) \left[\frac{1}{2} \rho_{w} \left(v_{x} - v_{\overline{v}}^{\overline{w}} \right) \cdot \left(v_{x} - v_{\overline{v}}^{\overline{w}} \right) \right] \\ & + \rho_{v} \left(\mu_{w} + \psi_{w} - \mu^{\overline{w}} - K_{\overline{v}}^{\overline{w}} - \psi^{\overline{w}} \right) \right] dt \\ & -\frac{1}{\sigma} \prod_{r,w}^{\overline{w}} (u_{wr} + \psi_{wr} - u_{wr}^{\overline{w}} - K_{\overline{v}}^{\overline{w}} - \psi^{\overline{w}}) \right] dt \\ & -\frac{1}{\sigma} \prod_{r,w}^{\overline{w}} (u_{wr} + \psi_{wr} - u_{wr}^{\overline{w}} - K_{\overline{w}}^{\overline{w}} - \psi^{\overline{w}}) \right] dt \\ & -\frac{1}{\sigma} \prod_{r,w}^{\overline{w}} \left[\psi_{wr} - \frac{4w}{\phi_{\overline{v}}} - (v_{w} - v_{ext}) \eta_{w} \theta_{w} \left(\frac{1}{\theta_{w}} - \frac{1}{\theta_{\overline{v}}} \right) \right] dt \\ & -\frac{1}{\Gamma_{w}} \prod_{r,w}^{\overline{w}} \left[\theta_{wr}^{\overline{w}} - \frac{4w}{\theta_{\overline{v}}^{\overline{w}}} - (v_{w} - v_{ext}) \eta_{w} \theta_{w} \left(\frac{1}{\theta_{w}} - \frac{1}{\theta_{\overline{v}}} \right) \right] dt \\ & -\frac{1}{\Gamma_{w}} \prod_{r,w}^{\overline{w}} \left[\theta_{wr}^{\overline{w}} - \frac{4w}{\theta_{\overline{v}}} - (v_{w} - v_{ext}) \eta_{w} \theta_{w} \left(\frac{1}{\theta_{w}} - \frac{1}{\theta_{\overline{v}}} \right) \right] dt \\ & + \frac{1}{\frac{1}{\theta_{\overline{v}}}} \prod_{r,w}^{\overline{w}} \left[\eta_{w}^{\overline{w}} - \frac{1}{\theta_{\overline{v}}} - \eta_{w}^{\overline{w}} \right] dt \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w}}} \prod_{r,w}^{\overline{w}} \left[\eta_{w}^{\overline{w}} - \eta_{w}^{\overline{w}} - \eta_{w}^{\overline{w}} \right] dt \\ & + \left(\frac{1}{\theta_{\overline{v}}^{\overline{w}}} - \theta^{\overline{v}} \right) \nabla^{\overline{v}} + \frac{1}{\theta_{\overline{v}}} \prod_{r,w}^{\overline{w}} \left[\eta_{\overline{v}} \frac{D^{7} \left(\mu_{w} + \theta_{w} - \mu^{\overline{w}} - K_{\overline{v}}^{\overline{w}} - \eta_{\overline{v}}^{\overline{w}} \right) \right] dt \\ & + \left(\frac{1}{\theta_{\overline{v}}^{\overline{w}}} - b^{w} \right) A^{wz} \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w}}} \prod_{r,w}^{\overline{w}} \left\{ \sqrt{w_{\overline{w}}^{\overline{w}} - v^{\overline{v}} \right\} \right] dv \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w}}} \prod_{r,w}^{\overline{w}} \left\{ \sqrt{w_{\overline{w}}^{\overline{w}} - v^{\overline{v}} \right\} \right] dv \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w}}} \prod_{r,w}^{\overline{w}} \left\{ \sqrt{w_{\overline{w}}^{\overline{w}} - v^{\overline{v}} \right\} \right] dv \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w}}} \prod_{r,w}^{\overline{w}} \left\{ \sqrt{w_{\overline{w}}^{\overline{w}} - v^{\overline{v}} \right\} \right] dv \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w}}} \prod_{r,w}^{\overline{w}} \left\{ \sqrt{w_{\overline{w}}^{\overline{w}} - v^{\overline{v}} \right\} \right] dv \\ \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w}}} \prod_{r,w}^{\overline{w}} \left\{ \sqrt{w_{\overline{w}}^{\overline{w}} - v^{\overline{v}} \right\} \right] dv \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w}}} \prod_{r,w}^{\overline{w}} \left\{ \sqrt{w_{\overline{w}}^{\overline{w}} - v^{\overline{v}} \right\} \right] dv \\ \\ & + \frac{1}{\theta_{\overline{w}}^{\overline{w$$

This general form does not rely on any approximations or restrictions, except the selection of the microscale form of the thermodynamic relation, CIT. This equation therefore can be used as a general starting point for the analysis of a range of problems. We will consider a restricted set here.

7 Simplified Equation

Eqn (85) can be simplified to obtain an expression useful for extracting closure relations for certain cases. Here, we will impose one set of conditions that are not strongly restrictive and thus does not eliminate a large number of important systems.

As the first condition, we will restrict interest to what is commonly called simple systems [8]. The non-advective heat flux appears as a microscale quantity integrated at the boundary. Thus, we will invoke the condition

$$\boldsymbol{\varphi}_{\iota} = \frac{\mathbf{q}_{\iota}}{\theta_{\iota}} \iota \in \mathscr{I}.$$
 (86)

This condition indicates that the heat flux divided by the temperature is equal to the entropy flux at the microscale, a condition that allows the entropy flux to be eliminated from the CEI. Because the interface between the phases is two-dimensional, the non-advective fluxes \mathbf{q}_{ws} (and therefore ϕ_{ws}) and \mathbf{t}_{ws} only have components that are tangent to the interface. The energy source term appears at the megascale and for a simple megascale system is related to the entropy source according to

$$\begin{pmatrix}
\frac{h^{\bar{i}}}{\theta^{\bar{i}}} - b^{\iota}
\end{pmatrix} \mathbb{V}^{\iota} + \frac{1}{\theta^{\bar{i}}} \int_{\Omega_{\iota}} \left[\eta_{\iota} \frac{\mathbf{D}^{\bar{s}} \left(\theta_{\iota} - \theta^{\bar{i}}\right)}{\mathbf{D}t} + \rho_{\iota} \frac{\mathbf{D}^{\bar{s}} \left(\mu_{\iota} + \psi_{\iota} - \mu^{\bar{\iota}} - K_{E}^{\bar{i}} - \psi^{\bar{\imath}}\right)}{\mathbf{D}t} \right] \mathrm{d}\mathbf{r} = 0\iota \in \mathscr{I}_{\mathrm{P}},$$
(87)

and

$$\begin{pmatrix} \underline{h}^{\overline{ws}} \\ \overline{\theta^{\overline{ws}}} \end{pmatrix} \mathbb{A}^{ws} + \frac{1}{\theta^{\overline{ws}}} \int_{\Omega_{ws}} \left[\eta_{ws} \frac{\mathbf{D}^{\overline{s}} \left(\theta_{ws} - \theta^{\overline{ws}} \right)}{\mathbf{D}t} + \rho_{ws} \frac{\mathbf{D}^{\overline{s}} \left(\mu_{ws} + \psi_{ws} - \mu^{\overline{ws}} - \overline{K_E^{\overline{ws}}} - \psi^{\overline{ws}} \right)}{\mathbf{D}t} \right] d\mathbf{r} = 0.$$

(88)

The portions of these terms involving material derivatives do not appear in the microscale definition of a simple system [8]. By definition, at the microscale, the "average" values would be the point value; and thus the differences between microscale and megascale values in the material derivatives would be zero by definition.

Let us also consider the case where there is no mass exchange between entities such that

$$\overset{_{VS}\to\iota}{M}=0\iota\in\mathscr{I}_{\mathbf{P}}.\tag{89}$$

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When there is no mass exchange at the *ws* interface, the microscale condition also applies such that

$$\mathbf{n}_{W} \cdot \mathbf{v}_{W} = \mathbf{n}_{W} \cdot \mathbf{v}_{S} = \mathbf{n}_{W} \cdot \mathbf{v}_{WS}. \tag{90}$$

Also, let the interface be massless such that

$$\rho_{ws} = 0 \tag{91}$$

and

$$\mathbb{M}^{WS} = 0. \tag{92}$$

Microscale non-advective fluxes in the interface normal to the interface are taken to be zero so that

$$\mathbf{n}_{w} \cdot \mathbf{q}_{ws} = 0 \tag{93}$$

and

$$\mathbf{n}_{w} \cdot \mathbf{t}_{ws} = 0. \tag{94}$$

Eqn (86)-Eqn (94) can be used to reduce Eqn (85) to

$$\begin{split} &-\frac{1}{\theta^{\overline{v}}}\int_{\tau_{exc}}^{\mathbf{n}} \mathbf{n}_{w} \cdot (\mathbf{v}_{w} - \mathbf{v}_{ext}) \left[\frac{1}{2}\rho_{w} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] d\mathbf{r} \\ &- \frac{1}{\theta^{\overline{v}}}\int_{\tau_{w}}^{\mathbf{n}_{w}} \left(\mathbf{v}_{x} - \mathbf{v}_{x} \right) \left[\frac{1}{2}\rho_{x} \left(\mathbf{v}_{x} - \mathbf{v}^{\overline{z}} \right) \cdot \left(\mathbf{v}_{x} - \mathbf{v}^{\overline{z}} \right) \right] + \rho_{x} \left(\mu_{x} + \psi_{x} - \mu^{\overline{x}} - K_{\overline{x}}^{\overline{z}} - \psi^{\overline{x}} \right) \right] d\mathbf{r} \\ &- \int_{\tau_{x}}^{\mathbf{n}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} - \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{w}} - \frac{1}{\theta^{\overline{y}}} \right) d\mathbf{r} \\ &- \int_{\tau_{xx}}^{\mathbf{n}} \mathbf{n}_{x} \cdot \left[\mathbf{q}_{x} - \left(\mathbf{v}_{x} - \mathbf{v}_{ext} \right) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{w}} - \frac{1}{\theta^{\overline{y}}} \right) d\mathbf{r} \\ &- \int_{\tau_{xx}}^{\mathbf{n}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} - \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{w}} - \frac{1}{\theta^{\overline{y}}} \right) d\mathbf{r} \\ &- \int_{\tau_{xx}}^{\mathbf{n}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} - \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{wx}} - \frac{1}{\theta^{\overline{y}}} \right) d\mathbf{r} \\ &- \frac{1}{\theta^{\overline{y}}} \int_{\mathbf{n}}^{\mathbf{n}_{w}} \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{wx}} - \frac{1}{\theta^{\overline{y}}} \right) d\mathbf{r} \\ &- \frac{1}{\theta^{\overline{y}}} \int_{\mathbf{n}}^{\mathbf{n}_{w}} \left(\mathbf{v}_{w} - \mathbf{v}_{wx} \right) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{wx}} - \frac{1}{\theta^{\overline{y}}} \right) d\mathbf{r} \\ &+ \frac{1}{\theta^{\overline{y}}} \int_{\mathbf{n}_{wx}} \left(\mathbf{t}_{w} + p_{w} \right) \left(\mathbf{v}_{w} + \mathbf{v}^{\overline{w}} \mathbf{T}^{w} + \int_{\mathbf{n}_{w}} \mathbf{v}_{w} \mathbf{t} \mathbf{w} \mathbf{d} \mathbf{w} \right) \\ &+ \frac{1}{\theta^{\overline{y}}} \int_{\mathbf{n}_{wx}} \left(\mathbf{t}_{wx} - \mathbf{v}_{wx} \right) \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{y}} \right) d\mathbf{r} \\ &+ \frac{1}{\theta^{\overline{y}}} \int_{\mathbf{n}_{wx}} \left(\mathbf{t}_{wx} - \mathbf{v}_{wx} \right) \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{y}} \right) d\mathbf{r} \\ &+ \frac{1}{\theta^{\overline{y}}} \int_{\mathbf{n}_{wx}} \left(\mathbf{t}_{wx} - \mathbf{v}_{wx} \right) \left\{ \left(\nabla_{\mathbf{v}} - \mathbf{v}_{w} \right) \right\} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{y}} \right) \mathbf{v}_{wx} - \mathbf{v}_{wx} - \mathbf{v}_{wx} \right) \right\} \\ &+ \left(\frac{1}{\theta^{\overline{y}}} \int_{\mathbf{n}_{wx}} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{y}} \right) \left\{ \nabla_{\mathbf{v}} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{y}} \right) \mathbf{v}_{wx} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{y}} \right) \mathbf{v}_{wx} \left(\mathbf{v}_{wx} - \mathbf{v}^{\overline{y}} \right) \right\} \\ &+ \left(\frac{1}{\theta^{\overline{y}}} \int_{\mathbf{n}_{wx}} \left(\mathbf{v}_{wx} - \mathbf{v}^{\overline{y}} \right) \left\{ \mathbf{v}_{wx} \left(\mathbf{v}_{wx} - \mathbf{v}^{\overline{y}} \right) \mathbf{v}_{wx} \left(\mathbf{v}_{wx} - \mathbf{v}^{\overline{y}} \right) \mathbf{v}_{wx} \left(\mathbf{v}_{wx} - \mathbf{v}^{\overline{y}} \right) \right\} \\ &+ \left(\frac{$$

where the surface identity tensor is defined as

$$\mathbf{I}' = \mathbf{I} - \mathbf{n}_{\iota} \mathbf{n}_{\iota} \iota \in \mathscr{I}_{\mathbf{P}}.$$
(96)

We will make use of microscale constitutive relations for the fluid and the interface stress tensor. For the fluid let

$$\mathbf{t}_{w} = -\mathcal{P}_{w} \mathbf{I} + \boldsymbol{\tau}_{w}. \tag{97}$$

For the interface, assume that the stress is fully accounted for by the interfacial tension such that

$$\mathbf{t}_{ws} = \gamma_{ws} \mathbf{I'}. \tag{98}$$

Since the system of interest is a porous medium, we will consider the case where the solid velocity is very small and the solid behaves as a quasi-equilibrium system. Thus we make use of the microscale constitutive relation for the solid phase

$$\mathbf{t}_{s} = \frac{2}{j_{s}} \boldsymbol{\sigma}_{s} : (\nabla_{\boldsymbol{X}} \mathbf{x} \nabla_{\boldsymbol{X}} \mathbf{x})$$
(99)

with the off-diagonal elements of this tensor being zero at the ws interface such that

$$\mathbf{n}_s \cdot \mathbf{t}_s \cdot \mathbf{l'} = 0 \quad \text{on } \Omega_{ws}. \tag{100}$$

Because the magnitude of the solid phase velocity is very small relative to other dynamic motions, we will eliminate all integrals over Ω_s containing $\mathbf{v}_s - \mathbf{v}^{\bar{s}}$ in Eqn (95). The velocities of all entities are small so that terms involving the velocity squared can be considered to make a negligible contribution to energy and to the entropy generation relative to other terms. Finally, we will assume that the dynamics of the movement of the Ω_{ws} interface are so slow that the equilibrium force balance identity can be applied at all times on the surface (i.e., a semi-equilibrium approximation) with

$$\int_{\Omega_{ws}} \mathbf{n}_{w} \cdot (\mathbf{v}_{w} - \mathbf{v}^{\overline{s}}) \left\{ (\nabla' \cdot \mathbf{n}_{w}) \gamma_{ws} - p_{w} - \mathbf{n}_{s} \cdot \left[\frac{2}{j_{s}} \sigma_{s} : (\nabla_{\chi} \mathbf{x} \nabla_{\chi} \mathbf{x}) \right] \cdot \mathbf{n}_{s} \right\} \mathrm{dr} \approx 0.$$
(101)

relative to the other terms in Eqn (95).

Thus, the entropy inequality becomes

$$\begin{aligned} &-\frac{1}{\theta^{\overline{w}}} \int_{\Gamma_{we}}^{\mathbf{n}} \mathbf{n}_{w} \cdot (\mathbf{v}_{w} - \mathbf{v}_{ext}) \left[\rho_{w} \left(\mu_{w} + \psi_{w} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) \right] dt \\ &- \frac{1}{\theta^{\overline{s}}} \int_{\Gamma_{se}}^{\mathbf{n}} \mathbf{n}_{s} \cdot (\mathbf{v}_{s} - \mathbf{v}_{ext}) \left[\rho_{s} \left(\mu_{s} + \psi_{s} - \mu^{\overline{s}} - \psi^{\overline{s}} \right) \right] dt \\ &- \int_{\Gamma_{we}}^{\mathbf{n}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} - (\mathbf{v}_{w} - \mathbf{v}_{ext}) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{w}} - \frac{1}{\theta^{\overline{w}}} \right) dt \\ &- \int_{\Gamma_{we}}^{\mathbf{n}} \mathbf{n}_{s} \cdot \left[\mathbf{q}_{s} - (\mathbf{v}_{s} - \mathbf{v}_{ext}) \eta_{s} \theta_{s} \right] \left(\frac{1}{\theta_{s}} - \frac{1}{\theta^{\overline{s}}} \right) dt \\ &- \int_{\Gamma_{wse}}^{\mathbf{n}} \mathbf{n}_{ws} \cdot \left[\mathbf{q}_{ws} - (\mathbf{v}_{ws} - \mathbf{v}_{ext}) \eta_{ws} \theta_{ws} \right] \left(\frac{1}{\theta_{ws}} - \frac{1}{\theta^{\overline{ws}}} \right) dt \\ &- \frac{1}{\theta^{\overline{ws}}} \cdot \left(\mathbf{w}_{s}^{WS \to W} + \int_{\Gamma_{we}}^{\mathbf{n}} \mathbf{n}_{w} \cdot \mathbf{t}_{w} dt + \mathbb{M}^{w} \mathbf{g}^{\overline{w}} \right) \\ &+ \frac{1}{\theta^{\overline{w}}} \int_{\overline{W^{ws}}}^{\mathbf{n}} \mathbf{n}_{w} \cdot \tau_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{s}} \right) dt \\ &+ \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{ms}}} \right) \left[\mathbf{w}_{s}^{WS \to W} + \int_{\Omega_{ws}}^{\mathbf{n}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{s}} \right) p_{w} dt + \mathbf{w}_{s}^{WS \to W} \cdot \left(\mathbf{v}_{w}^{\overline{WS} - \mathbf{v}^{\overline{s}} \right) \right] \\ &+ \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{ms}}} \right) \left[\mathbf{w}_{s}^{WS \to W} - \int_{\Omega_{ws}}^{\mathbf{n}} \mathbf{n}_{s} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{s}} \right) \mathbf{n}_{s} \cdot \mathbf{t}_{s} \cdot \mathbf{n}_{s} dt \\ &+ \mathbf{w}_{s}^{WS \to S} \cdot \left(\mathbf{w}_{s}^{WS \to V} - \mathbf{v}^{\overline{s}} \right) \right\} = \mathbf{A} \ge \mathbf{0}. \end{aligned}$$

(102)

The integrals over the various portions of the external boundaries of the system typically involve products of microscale quantities. In fact, these products involve microscale forces and fluxes. It is useful to rearrange these terms so that the integrals can be evaluated. This is accomplished by making two significant, though exact, alterations to the system.

First, although the integrals are over the entire external boundary of an entity, these integrals can conveniently be subdivided into portions of the area that can be more easily evaluated separately. Then, integration over the external boundary of an entity is expressed as the sum of the integrals over each section. With this employed as needed, Eqn (102) becomes

$$\begin{aligned} &-\frac{1}{\theta^{\overline{w}}} \sum_{i \in \mathscr{F}_{\Gamma_{w}}} \int_{\Gamma_{w_{i}}} \mathbf{n}_{w} \cdot (\mathbf{v}_{w} - \mathbf{v}_{ext}) \left[\rho_{w} \left(\mu_{w} + \psi_{w} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) \right] d\mathbf{r} \\ &-\frac{1}{\theta^{\overline{v}}} \sum_{i \in \mathscr{F}_{\Gamma_{w}}} \int_{\Gamma_{w_{i}}} \mathbf{n}_{s} \cdot (\mathbf{v}_{s} - \mathbf{v}_{ext}) \left[\rho_{s} \left(\mu_{s} + \psi_{s} - \mu^{\overline{s}} - \psi^{\overline{s}} \right) \right] d\mathbf{r} \\ &- \sum_{i \in \mathscr{F}_{\Gamma_{w}}} \int_{\Gamma_{w_{i}}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} - (\mathbf{v}_{w} - \mathbf{v}_{ext}) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{w}} - \frac{1}{\theta^{\overline{w}}} \right) d\mathbf{r} \\ &- \sum_{i \in \mathscr{F}_{\Gamma_{w}}} \int_{\Gamma_{w_{i}}} \mathbf{n}_{s} \cdot \left[\mathbf{q}_{s} - (\mathbf{v}_{s} - \mathbf{v}_{ext}) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{s}} - \frac{1}{\theta^{\overline{s}}} \right) d\mathbf{r} \\ &- \sum_{i \in \mathscr{F}_{\Gamma_{w}}} \int_{\Gamma_{w_{i}}} \mathbf{n}_{w_{i}} \cdot \left[\mathbf{q}_{ws} - (\mathbf{v}_{ws} - \mathbf{v}_{ext}) \eta_{w} \theta_{w} \right] \left(\frac{1}{\theta_{s}} - \frac{1}{\theta^{\overline{s}}} \right) d\mathbf{r} \\ &- \sum_{i \in \mathscr{F}_{\Gamma_{ww}}} \int_{\Gamma_{w_{i}}} \mathbf{n}_{w_{i}} \cdot \left[\mathbf{q}_{ws} - (\mathbf{v}_{ws} - \mathbf{v}_{ext}) \eta_{w} \theta_{ws} \right] \left(\frac{1}{\theta_{ws}} - \frac{1}{\theta^{\overline{w}}} \right) d\mathbf{r} \\ &- \frac{v^{\overline{w}\overline{s}}}{\theta^{\overline{w}}} \cdot \left[\mathbf{v}^{ws \rightarrow w} + \mathbf{f} \mathbf{n}_{w} \cdot \mathbf{u}_{w} d\mathbf{r} + \mathbb{M}^{w} \mathbf{g}^{\overline{w}} \right] \\ &+ \frac{v^{\overline{w}\overline{s}}}{\theta^{\overline{w}}} \cdot \left[\nabla^{w} \mathbf{T}^{w} + \mathbf{v}^{w} \mathbf{T}^{w} - \int_{\Gamma_{w}}} \mathbf{n}_{w} \cdot \mathbf{t}_{ws} d\mathbf{r} \right] \\ &+ \frac{1}{\theta^{\overline{w}}}} \sum_{i \in \mathscr{F}_{\Gamma_{w}}} \int_{\Gamma_{w_{i}}} \mathbf{n}_{w} \cdot \mathbf{v}_{w} (\mathbf{v}_{w} - \mathbf{v}^{\overline{s}}) d\mathbf{r} \\ &+ \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}}} \right) \left[\nabla^{ws \rightarrow w} + \int_{\Omega_{ws}} \mathbf{n}_{w} \cdot \mathbf{v}_{w} d\mathbf{r} + \mathbb{M}^{w} \mathbf{g}^{w} d\mathbf{r} \right] \\ &+ \frac{1}{\theta^{\overline{w}}}} \sum_{i \in \mathscr{F}_{\Gamma_{w}}} \int_{W_{w_{i}}} \mathbf{n}_{w} \cdot \mathbf{v}_{w} (\mathbf{v}_{w} - \mathbf{v}^{\overline{s}}) d\mathbf{r} \\ &+ \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}} \right) \left[\nabla^{ws \rightarrow w} + \int_{\Omega_{ws}} \mathbf{n}_{w} \cdot (\mathbf{v}_{w} - \mathbf{v}^{\overline{s}}) p_{w} d\mathbf{r} + \overline{\nabla} \cdot \left(\mathbf{v}_{w}^{\overline{w}} - \mathbf{v}^{\overline{s}} \right) \right] \\ &+ \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}} \right) \left[\nabla^{ws \rightarrow w} + \int_{\Omega_{ws}} \mathbf{n}_{w} \cdot (\mathbf{v}_{w} - \mathbf{v}^{\overline{s}}) p_{w} d\mathbf{r} + \overline{\nabla} \cdot \left(\mathbf{v}_{w}^{\overline{w}} - \mathbf{v}^{\overline{s}} \right) \right] \\ &+ \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}} \right) \left\{ \nabla^{ws \rightarrow w} - \int_{\Omega_{ws}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{s}} \right) \mathbf{n}_{s} \cdot \mathbf{t}_{s} \cdot \mathbf{n}_{s} d\mathbf{r} \\ &+ \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}} \right) \left\{ \nabla^{ws \rightarrow w} - \int_{\Omega_{ws}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{s}} \right)$$

where

$$\Gamma_{\iota e} = \{ \Gamma_{\iota e_i} | i \in \mathscr{I}_{\Gamma_{\iota e}} \}, \tag{104}$$

i is a general index, Γ_{ue_i} is a subset of the external boundary Γ_{ue} , and $\mathcal{Q}_{\Gamma_{ue}}$ is an index set that includes indexes of all external boundary subsets for the external boundary of entity u.

Second, we will add and subtract averages over the boundaries to these terms so that the product of forces and fluxes can be written as a macroscale pair plus a pair that is still within the integral

(105)

where

$$\boldsymbol{\upsilon}_{\text{out}}^{\iota c_i} = \langle (\mathbf{v}_\iota - \mathbf{v}_{\text{ext}}) \cdot \mathbf{n}_\iota \rangle_{\Gamma_{\iota c_i}, \Gamma_{\iota c_i}, \rho_\iota}, \tag{106}$$

$$q_{\text{out}}^{\iota e_i} = \langle \mathbf{q}_\iota \cdot \mathbf{n}_\iota \rangle_{\Gamma_{\iota e_i}, \Gamma_{\iota e_i}},\tag{107}$$

$$f^{te_i} = \langle f_t \rangle_{\Gamma_{te_i}, \Gamma_{te_i}},\tag{108}$$

$$f^{\iota e_i} = \langle f_\iota \rangle_{\Gamma_{\iota e_i}, \Gamma_{\iota e_i}, \rho_\iota}, \tag{109}$$

$$(\mathbf{n}_{w}\cdot\boldsymbol{\tau}_{w}\cdot\mathbf{n}_{w})^{we_{i}} = \langle \mathbf{n}_{w}\cdot\boldsymbol{\tau}_{w}\cdot\mathbf{n}_{w}\rangle_{\Gamma_{we_{i}},\Gamma_{we_{i}}},$$
(110)

and \mathbb{L}^{wse_i} is the length of the *i*th segment of the external boundary of the *ws* entity. These

quantities are all averages over a portion of the external system boundary. For example, $v_{out}^{i\overline{e_i}}$ is the net (i.e., relative to the system boundary velocity) density weighted average outward normal velocity of entity ι over segment *i* of the total external boundary that intersects entity ι .

Recall that the development of megascale equations is intended to be useful for systems where smaller scale variations in system properties can be neglected. Consistent with that objective, we can eliminate some of the terms in the preceding equation. We make the assumption that the velocity of the external boundary is determined by the movement of the solid phase. Thus, for purposes of evaluating the integrals, we will neglect the terms $[\mathbf{n}_t \cdot (\mathbf{v}_t - \mathbf{v}_{ext}) - v_{out}^{\overline{e_t}}]$ as well as terms involving $\mathbf{n}_t \cdot (\mathbf{v}_{ext} - \mathbf{v}^{\overline{s}})$. The outward flow of solid material at the boundary is also zero so that $v_{out}^{\overline{se}} \approx 0$. Also, we will neglect the deviation term involving non-advective heat transfer that appears within integrals, $\mathbf{n}_t \cdot \mathbf{q}_t - q_{out}^{ter}|_{wet}$. Finally, two of the terms involving τ_w are arguably small in comparison to other terms in Eqn (105). The first is the term be integrated

over the boundary that multiplies the small velocity difference $\mathbf{n}_{w} \cdot (\mathbf{v}_{ext} - \mathbf{v}^{\overline{s}})$. Second, the tangential component of the microscale fluid velocity is considered to be negligible on the boundary so that this term may also be dropped. With all these observations implemented in Eqn (105), the remaining entropy inequality is

$$\begin{aligned} &-\frac{1}{\theta^{\overline{w}}} \sum_{i \in \mathscr{I}_{\Gamma_{we}}} \mathcal{V}_{out}^{\overline{we_i}} \left[\rho^{we_i} \left(\mu^{\overline{we_i}} + \psi^{\overline{we_i}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) - (\mathbf{n}_w \cdot \boldsymbol{\tau}_w \cdot \mathbf{n}_w)^{we_i} \right] \mathbb{A}^{we_i} \\ &-\sum_{i \in \mathscr{I}_{\Gamma_{we}}} \left(q_{out}^{we_i} - u_{out}^{\overline{we_i}} \eta^{we_i} \theta^{\overline{we_i}} \right) \left(\frac{1}{\theta^{\overline{we_i}}} - \frac{1}{\theta^{\overline{w}}} \right) \mathbb{A}^{we_i} \\ &-\sum_{i \in \mathscr{I}_{\Gamma_{we}}} q_{out}^{se_i} \left(\frac{1}{\theta^{\overline{se_i}}} - \frac{1}{\theta^{\overline{s}}} \right) \mathbb{A}^{se_i} \\ &-\sum_{i \in \mathscr{I}_{\Gamma_{we}}} \left(q_{out}^{we_i} - u_{out}^{\overline{we_i}} \eta^{we_i} \theta^{\overline{we_i}} \right) \left(\frac{1}{\theta^{\overline{we_i}}} - \frac{1}{\theta^{\overline{w}}} \right) \mathbb{E}^{wse_i} \\ &- \frac{1}{\theta^{\overline{w}}} \left(\mathbb{V}^{ws \to w} + \int_{\mathbf{n}_w} \mathbf{n}_w \cdot \mathbf{t}_w \, d\mathbf{t} + \mathbb{M}^w \mathbf{g}^{\overline{w}} \right) \cdot \mathbf{v}^{\overline{w},\overline{s}} \\ &+ \frac{1}{\theta^{\overline{w}}} \left(\mathbb{V}^{ws \to w} + \int_{\Gamma_{we}} \mathbf{n}_w \cdot (\mathbf{v}_w - \mathbf{v}^{\overline{s}}) p_w \, d\mathbf{r} + \mathbb{V}^{ws \to w} \cdot (\mathbf{v}_w^{\overline{ws}} - \mathbf{v}^{\overline{s}}) \right] \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}} \right) \\ &+ \left[\mathbb{V}^{ws \to w} - \int_{\Omega_{ws}} \mathbf{n}_w \cdot (\mathbf{v}_w - \mathbf{v}^{\overline{s}}) p_w \, d\mathbf{r} + \mathbb{V}^{ws \to w} \cdot (\mathbf{v}_w^{\overline{ws}} - \mathbf{v}^{\overline{s}}) \right] \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}} \right) \\ &+ \left[\mathbb{V}^{ws \to w} - \int_{\Omega_{ws}} \mathbf{n}_w \cdot (\mathbf{v}_w - \mathbf{v}^{\overline{s}}) \mathbf{n}_s \cdot \mathbf{t}_s \cdot \mathbf{n}_s \, d\mathbf{r} \\ &+ \mathbb{V}^{ws \to w} - (\mathbf{v}_s^{\overline{ws}} - \mathbf{v}^{\overline{s}}) \right] \left(\frac{1}{\theta^{\overline{s}}} - \frac{1}{\theta^{\overline{w}}} \right) = A \ge 0. \end{aligned}$$

This equation is in the flux-force form suggested by Eqn (81) with eight types of conjugate pairs. The actual number of conjugate pairs depends on the number of sections of the surface of the system over which integrations have been performed. In this implementation of the

TCAT approach, there are conjugate scalar and vector pairs, but no tensor conjugate pairs. The set of forces in Eqn (111) that go to zero at equilibrium is

$$\mathscr{F} = \left\{ \rho^{we} \left(\mu^{\overline{we}} + \psi^{\overline{we}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) - \left(\mathbf{n}_{w} \cdot \boldsymbol{\tau}_{w} \cdot \mathbf{n}_{w} \right)^{we}, \frac{1}{\bar{\theta}^{\overline{wv}}} - \frac{1}{\bar{\theta}^{\overline{w}}}, \frac{1}{\bar{\theta}^{\overline{sv}}} - \frac{1}{\bar{\theta}^{\overline{s}}}, \frac{1}{\bar{\theta}^{\overline{sv}}} - \frac{1}{\bar{\theta}^{\overline{sv}}}, \mathbf{v}^{\overline{ws},\overline{s}}, \mathbf{v}^{\overline{ws},\overline{s}}, \frac{1}{\bar{\theta}^{\overline{w}}} - \frac{1}{\bar{\theta}^{\overline{ws}}}, \frac{1}{\bar{\theta}^{\overline{sv}}} - \frac{1}{\bar{\theta}^{\overline{ws}}} \right\}.$$

$$(112)$$

8 Linearized Closure Relations

The TCAT approach leads to the development of an SEI, which in turn constrains the allowable forms of closure relations needed to produce well-posed, solvable models. Such closure relations are not unique in form, or even the order of the approximation. As a result, an infinite number of closure relations exist for a given model. It is both reasonable and common practice to start with a relatively simple set of closure relations and to increase the complexity of these relations as needed to describe physical systems of concern. A natural place to start is with a linear form of the closure relations. The most general linearization of the flux-force pairs is to make each flux a linear function of the full set of forces. Here we will consider a somewhat reduced, but nevertheless rather general, linear coupling. We will consider that there is coupling involving the average velocity and the average frictional drag within the system. Other coupling is assumed to be unimportant, although these assumptions can be examined further in the context of a physical system. Thus the restrictions employed are:

- The average velocity of the solid phase is essentially equal to the average velocity of the interface between the fluid and solid such that the force $v^{\overline{ws},\overline{s}} \approx 0$ and the conjugate flux of this term is also approximately zero.
- The heat transferred into the system at the system boundary where the interface intersects the boundary is negligible so that the heat flux at any boundary curve

 Γ_{wse_i} is restricted by $\left(q_{out}^{wse_i} - v_{out}^{\overline{wse_i}} \eta^{wse_i} \theta^{\overline{wse_i}}\right) \approx 0$ and its conjugate force is also negligible.

Each member of the set of boundary flow fluxes, $v_{out}^{\overline{we_i}}$ will depend on the conjugate force at that location as well as the force $\mathbf{v}^{\overline{w}} - \mathbf{v}^{\overline{s}}$. This is expressed as

$$\boldsymbol{\upsilon}_{\text{out}}^{\overline{\text{we}}_{i}} = -\widehat{\boldsymbol{K}}_{\upsilon}^{\text{we}_{i}} \left[\boldsymbol{\rho}_{v}^{\overline{\text{we}}_{i}} + \boldsymbol{\psi}^{\overline{\text{we}}_{i}} - \boldsymbol{\mu}^{\overline{w}} - \boldsymbol{\psi}^{\overline{w}} \right) - (\mathbf{n}_{w} \cdot \boldsymbol{\tau}_{w} \cdot \mathbf{n}_{w})^{\text{we}_{i}} \right] - \widehat{\mathbf{r}}_{\upsilon}^{\text{we}_{i}} \cdot \mathbf{v}^{\overline{w},\overline{s}},$$
(113)

where $\hat{\mathbf{r}}_{ij}^{we_i}$ is a closure vector.

• The flux with conjugate force **v**^{*w*,*s*} also depends on the forces conjugate to the boundary flow fluxes, which is of the form

$$\mathbb{V} \stackrel{w_{S} \to w}{\mathbf{T}} + \int_{\Gamma_{W} e} \mathbf{n}_{w} \cdot \mathbf{t}_{w} d\mathbf{r} + \mathbb{M}^{w} \mathbf{g}^{\overline{w}} = - \widehat{\mathbf{R}}^{w} \cdot \mathbf{v}^{\overline{w},\overline{s}} - \sum_{i \in \mathscr{I}_{\Gamma_{W} e}} \widehat{\mathbf{r}}_{\mu}^{we_{i}} \Big[\rho^{we_{i}} (\mu^{\overline{we_{i}}} + \psi^{\overline{we_{i}}} - \mu^{\overline{w}} - \psi^{\overline{w}}) - (\mathbf{n}_{w} \cdot \boldsymbol{\tau}_{w} \cdot \mathbf{n}_{w})^{we_{i}} \Big],$$
(114)

where $\hat{\mathbf{r}}_{\mu}^{we_i}$ is a closure vector.

• Each of the non-advective heat flux terms for the phases at the boundary will depend only on the conjugate force at that boundary. Therefore

$$q_{\text{out}}^{\text{we}_i} - \upsilon_{\text{out}}^{\overline{\text{we}_i}} \eta^{\text{we}_i} \overline{\theta^{\overline{\text{we}_i}}} = -\widehat{k_{\theta}^{\text{we}_i}} \left(\frac{1}{\overline{\theta^{\overline{\text{we}_i}}}} - \frac{1}{\overline{\theta^{\overline{w}}}}\right)$$
(115)

and

$$q_{\text{out}}^{se_i} = -\widehat{k}_{\theta}^{se_i} \left(\frac{1}{\theta^{\overline{se_i}}} - \frac{1}{\theta^{\overline{s}}} \right),\tag{116}$$

where \hat{k}_{θ} is a heat flux closure parameter.

• The non-advective heat flux terms within the system will depend only on the conjugate force. This is stated as

$$\mathbb{V} \stackrel{w_{\overline{s}} \to w}{Q} + \int_{\Omega_{w_{\overline{s}}}} \mathbf{n}_{w} \cdot (\mathbf{v}_{w} - \mathbf{v}^{\overline{s}}) p_{w} d\mathbf{r} + \mathbb{V} \stackrel{w_{\overline{s}} \to w}{\mathbf{T}} \cdot (\mathbf{v}_{w}^{\overline{w_{\overline{s}}}} - \mathbf{v}^{\overline{s}}) = \widehat{k}_{Q}^{w} \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}} \right)$$
(117)

and

$$\mathbb{V} \stackrel{WS \to S}{Q} - \int_{\Omega_{WS}} \mathbf{n}_{s} \cdot (\mathbf{v}_{s} - \mathbf{v}^{\overline{s}}) \mathbf{n}_{s} \cdot \left[\frac{2}{j_{s}}\sigma_{s} : (\nabla_{\chi}\mathbf{x}\nabla_{\chi}\mathbf{x})\right] \cdot \mathbf{n}_{s} \mathrm{d}\mathbf{r} \\
+ \mathbb{V} \stackrel{WS \to S}{\mathbf{T}} \cdot \left(\mathbf{v}_{s}^{\overline{WS}} - \mathbf{v}^{\overline{s}}\right) = \widehat{k}_{Q}^{S} \left(\frac{1}{\theta^{\overline{s}}} - \frac{1}{\theta^{\overline{Ws}}}\right),$$
(118)

where \hat{k}_Q is an inter-entity heat transfer closure parameter.

Note that if the system is isotropic, a linear dependence of a vector flux on a scalar force or of a scalar flux on a vector force will not exist because the proportionality parameter is a vector. No isotropic coefficient vector exists. For the megascale case, "isotropy" includes interaction with boundary fluxes as well as the actual properties of the materials making up the porous medium system. For a more general form, it is a small matter to include additional coupling between flow induced by temperature differences or energy transport induced by high flow rates. Closed equations may be obtained under the conditions and restrictions identified above.

9 Closed Conservation Equations

Closure relations may be implemented in the megascale conservation equations to provide a set of equations that describes the system. It is important to realize that some approximations will be made in this analysis consistent with the fact that the conservation equations are integrated over the entire system such that variability of properties within the system are treated only through average quantities. Such a description can be useful in many applications or in some regions of interest where the variability of properties is not important to answering a question of interest concerning the system. Here we will provide closed forms of the mass, momentum, and energy conservation equations that can serve as a basis for megascale analysis.

9.1 Closed mass conservation equations

The mass conservation equation for the phases is given in Eqn (14). When there is no mass exchange between phases, this simplifies to

$$\frac{\mathrm{d}\mathbb{M}^{\iota}}{\mathrm{d}t} + \int_{\Gamma_{\iota c}} \rho_{\iota}(\mathbf{v}_{\iota} - \mathbf{v}_{\mathrm{ext}}) \cdot \mathbf{n}_{\iota} \, \mathrm{d}\mathbf{r} = 0\iota \in \mathscr{I}_{\mathrm{p}}.$$
(119)

Making use of the definition of the outward volumetric flow per unit area given by Eqn (106) and the stipulation of the constraint that the boundary of the system moves with the solid phase, one can express this equation for the w and s phase, respectively, as

$$\frac{\mathrm{d}\mathbb{M}^{w}}{\mathrm{d}t} + \sum_{i\in\mathscr{I}_{\Gamma_{we}}} (\rho^{we_{i}} v_{\mathrm{out}}^{\overline{we_{i}}} \mathbb{A}^{we_{i}}) = 0$$
(120)

and

$$\frac{\mathrm{d}\mathbb{M}^{s}}{\mathrm{d}t} = 0. \tag{121}$$

Eqn (121) indicates that the solid mass in the system does not change with time while Eqn (120) expresses the change in mass of phase w as a function of the fluxes at the various locations on the boundary where fluxes occur. There are two options for specifying these fluxes. In one case, the flux might be specified directly, for example at a location where fluid is being added or withdrawn at a specified rate. A second option would involve the imposition of the head at the boundary so that the flow out would be due to a head gradient generated by the dynamics of the system. For this type of boundary condition, we can make use of the linear closure relation

for $v_{out}^{\overline{we_i}}$ out defined in Eqn (113). With this expression implemented at some locations, a form of mass conservation Eqn (120) that could be employed is

$$\frac{d\mathbb{M}^{w}}{dt} + \sum_{i \in \mathscr{I}_{\Gamma_{we_{\nu}}}} \left(\rho^{we_{i}} v_{out}^{\overline{we_{i}}} \mathbb{A}^{we_{i}} \right)
- \sum_{i \in \mathscr{I}_{\Gamma_{we_{\mu}}}} \rho^{we_{i}} \widehat{K}^{we_{i}} \left[\rho^{we_{i}} \left(\mu^{\overline{we_{i}}} + \psi^{\overline{we_{i}}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) - (\mathbf{n}_{w} \cdot \boldsymbol{\tau}_{w} \cdot \mathbf{n}_{w})^{we_{i}} \right] \mathbb{A}^{we_{i}}
- \sum_{i \in I_{\Gamma_{we_{\mu}}}} \rho^{we_{i}} \widehat{\boldsymbol{\tau}}_{v}^{we_{i}} \cdot \mathbf{v}^{\overline{w}, \overline{s}} \mathbb{A}^{we_{i}} = 0,$$
(122)

where $\mathscr{Q}_{\Gamma_{we_{0}}}$ is the set of locations where the velocity is specified and $\mathscr{Q}_{\Gamma_{we_{1}}}$ is the set of locations where the potential is specified with $\mathscr{Q}_{\Gamma_{we}} = \mathscr{Q}_{\Gamma_{we_{0}}} \cup \mathscr{Q}_{\Gamma_{we_{1}}}$. This distinction accounts for the fact that with some systems, at some boundary locations fluxes will be employed while at other locations the flux potential is used. The formulation is capable of handling this mix of conditions. In this equation $\widehat{K}^{we_{i}}$ is a megascale parameter that may depend on position on the boundary of the system as well as time. This parameter may be interpreted as similar to a

hydraulic conductivity, $\hat{K}_{H}^{We_{i}}$ with

$$\widehat{K}_{H}^{we_{i}} = \rho^{we_{i}} g l \epsilon^{we_{i}} \widehat{K}^{we_{i}}, \tag{123}$$

where *l* is a characteristic length such that the difference in potentials divided by this length approximates the normal gradient in potential at the boundary and ϵ^{wei} is the porosity at the boundary. The parameter $\hat{\mathbf{r}}_{n}^{we}$ accounts for coupling at the boundary between an exit, or

entrance, velocity and the average velocity within the system. The frictional loss term within the fluid in Eqn (122) may be neglected since most of the losses are due to fluid-solid interactions that account for the difference between chemical plus gravitational potential at the boundary and the average of the potentials in the interior of the system. In that instance, the mass conservation equation for the fluid may be simplified to

$$\frac{\mathrm{d}\mathbb{M}^{w}}{\mathrm{d}t} + \sum_{i \in \mathscr{I}_{\Gamma_{we_{\nu}}}} \left(\rho^{we_{i}} v^{\overline{we_{i}}} \mathbb{A}^{we_{i}} \right) \\
- \sum_{i \in \mathscr{I}_{\Gamma_{we_{\mu}}}} \rho^{we_{i}} \widehat{K}^{we_{i}} \left[\rho^{we_{i}} \left(\mu^{\overline{we_{i}}} + \psi^{\overline{we_{i}}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) \right] \mathbb{A}^{we_{i}} \\
- \sum_{i \in \mathscr{I}_{\Gamma_{we_{\mu}}}} \rho^{we_{i}} \widehat{\mathbf{r}}_{v}^{we_{i}} \cdot \mathbf{v}^{\overline{w},\overline{s}} \mathbb{A}^{we_{i}} = 0.$$
(124)

Since the interface is considered to be massless and no phase change occurs, mass conservation Eqn (18) for the interface is trivial with all terms being zero.

9.2 Closed momentum conservation equations

The megascale momentum equation for the phases when no mass exchange is taking place reduces from Eqn (20) to

$$\frac{\mathrm{d}(\mathbb{M}^{t}\mathbf{v}^{\overline{t}})}{\mathrm{d}t} - \mathbb{V} \stackrel{\mathrm{W}s \to \iota}{\mathbf{T}} - \mathbb{M}^{t}\mathbf{g}^{\overline{t}} + \int_{\Gamma_{te}} [\rho_{\iota}\mathbf{v}_{\iota}(\mathbf{v}_{\iota} - \mathbf{v}_{ext}) - \mathbf{t}_{\iota}] \cdot \mathbf{n}_{\iota} \,\mathrm{d}\mathbf{r} = 0\iota \in \mathscr{I}_{\mathrm{P}}.$$
(125)

The closure relation for this equation for the *w* phase is given by Eqn (114). Substitution into Eqn (125) when $\iota = w$ then gives

$$\frac{d\left(\mathbb{M}^{w}\mathbf{v}^{\overline{w}}\right)}{dt} + \widehat{\mathbf{R}}^{w} \cdot \mathbf{v}^{\overline{w},\overline{s}} + \int \rho_{w}\mathbf{v}_{w}\left(\mathbf{v}_{w} - \mathbf{v}_{ext}\right) \cdot \mathbf{n}_{w} dr$$

$$+ \sum_{i \in \mathscr{I}_{\Gamma_{we}}} \widehat{\mathbf{r}}_{\mu}^{we_{i}} \left[\rho^{we_{i}}\left(\mu^{\overline{we_{i}}} + \psi^{\overline{we_{i}}} - \mu^{\overline{w}} - \psi^{\overline{w}}\right) - \left(\mathbf{n}_{w} \cdot \boldsymbol{\tau}_{w} \cdot \mathbf{n}_{w}\right)^{we_{i}}\right] = 0.$$
(126)

The first term in this equation is the rate of change of *w* momentum. The second accounts for resistance to fluid flow due to frictional interactions of the fluid with the solid. The integral term accounts for momentum added or subtracted by flow across the system boundary, and the summation term accounts for the addition of momentum due to work done at the boundary of the system. Note that the integral term, in effect, involves the velocity squared.

It can be approximated as

$$\int_{\Gamma_{we}} \rho_{w} \mathbf{v}_{w} (\mathbf{v}_{w} - \mathbf{v}_{ext}) \cdot \mathbf{n}_{w} d\mathbf{r} \approx \sum_{i \in \mathscr{I}_{\Gamma_{we}}} \rho^{we_{i}} \mathbf{v}_{w}^{\overline{we_{i}}} v_{out}^{\overline{we_{i}}} \mathbb{A}^{we_{i}},$$
(127)

where at each section of the boundary

$$\mathbf{v}_{w}^{\overline{w}\mathbf{e}_{i}} = \langle \mathbf{v}_{w} \rangle_{\Gamma_{we_{i}},\Gamma_{we_{i}},\Gamma_{we_{i}},[\rho_{w}\mathbf{v}_{w}(\mathbf{v}_{w}-\mathbf{v}_{ext})\cdot\mathbf{n}_{w}]}.$$
(128)

Substitution of Eqn (127) and Eqn (120) into Eqn (126) with the intrafluid frictional stress term neglected then gives

$$\mathbb{M}^{w} \frac{\mathrm{d}\mathbf{v}^{\overline{w}}}{\mathrm{d}t} + \widehat{\mathbf{R}}^{\overline{w}} \cdot \mathbf{v}^{\overline{w},\overline{s}} + \sum_{i \in \mathscr{I}_{\Gamma_{we}}} \rho^{we_i} \left(\mathbf{v}_{w}^{\overline{we_i}} - \mathbf{v}^{\overline{w}} \right) \upsilon_{\text{out}}^{\overline{we_i}} \mathbb{A}^{we_i} + \sum_{i \in \mathscr{I}_{\Gamma_{we}}} \widehat{\mathbf{r}}_{\mu}^{we_i} \rho^{we_i} \left(\mu^{\overline{we_i}} + \psi^{\overline{we_i}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) = 0.$$
(129)

When the rate of change of average velocity of the *w* phase and the advective momentum flux at the boundary are small, the simplest form of the momentum equation is obtained as

$$\widehat{\mathbf{R}}^{W} \cdot \mathbf{v}^{\overline{w},\overline{s}} + \sum_{i \in \mathscr{I}_{\Gamma_{we}}} \widehat{\mathbf{r}}_{\mu}^{we_i} \rho^{we_i} \left(\mu^{\overline{we_i}} + \psi^{\overline{we_i}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) = 0.$$
(130)

To obtain the closed form of the solid phase momentum equation, we start with momentum Eqn (24) for the interface which simplifies for the case of no mass exchange and a massless interface to

$$\mathbb{V} \stackrel{w_{S} \to w}{\mathbf{T}} + \mathbb{V} \stackrel{w_{S} \to s}{\mathbf{T}} - \int_{\Gamma_{wse}} \mathbf{t}_{w_{S}} \cdot \mathbf{n}_{w_{S}} d\mathbf{r} = 0.$$
(131)

Combination of this expression with Eqn (114) yields

$$\mathbb{V} \stackrel{w_{S} \to s}{\mathbf{T}} = \int_{\mathbb{T}_{w_{e}}} \mathbf{n}_{w} \cdot \mathbf{t}_{w} d\mathbf{r} + \int_{\mathbb{T}_{w_{s}}} \mathbf{t}_{w_{s}} \cdot \mathbf{n}_{w_{s}} d\mathbf{r} + \mathbb{M}^{w} \mathbf{g}^{\overline{w}} + \widehat{\mathbf{R}}^{w} \cdot \mathbf{v}^{\overline{w},\overline{s}} + \sum_{i \in \mathscr{I}_{\Gamma_{w_{e}}}} \widehat{\mathbf{r}}_{\mu}^{w_{e_{i}}} \left[\rho^{w_{e_{i}}} \left(\mu^{\overline{w_{e_{i}}}} + \psi^{\overline{w_{e_{i}}}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) - (\mathbf{n}_{w} \cdot \boldsymbol{\tau}_{w} \cdot \mathbf{n}_{w})^{w_{e_{i}}} \right].$$
(132)

Substitution into Eqn (125) for the solid phase, while making use of the fact that no solid phase enters or leaves the system, then provides the momentum equation

$$\frac{\mathbb{M}^{s} \frac{d\mathbf{v}^{\overline{s}}}{dt}}{\sum_{i \in \mathscr{I}_{\Gamma_{we}}} \mathbb{P}_{\mu}^{we_{i}} \left[\rho^{we_{i}} \left(\mu^{\overline{we_{i}}} + \psi^{\overline{we_{i}}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) - (\mathbf{n}_{w} \cdot \boldsymbol{\tau}_{w} \cdot \mathbf{n}_{w})^{we_{i}} \right] - \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \mathbf{t}_{w} \, d\mathbf{r} - \int_{\Gamma_{se}} \mathbf{n}_{ws} \cdot \mathbf{t}_{ws} \, d\mathbf{r} = 0.$$
(133)

This equation provides an expression for the response of the solid phase momentum to gravitational forces, interaction with the fluid in the system, and forces applied at the boundary of the system. For conditions under which the flow is described by Eqn (130) and the acceleration of the solid phase is negligible, this equation may be simplified to a simple balance of forces acting on the solid

$$-\mathbb{M}^{w}\mathbf{g}^{\overline{w}} - \mathbb{M}^{s}\mathbf{g}^{\overline{s}} - \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \mathbf{t}_{w} d\mathbf{r} - \int_{\Gamma_{se}} \mathbf{n}_{w} \cdot \mathbf{t}_{s} d\mathbf{r} - \int_{\Gamma_{wse}} \mathbf{n}_{ws} \cdot \mathbf{t}_{ws} d\mathbf{r} = 0.$$
(134)

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9.3 Closed energy conservation equations

The development of the closed energy equation for the w phase begins with energy conservation Eqn (26) simplified to account for the fact that no phase change is being modeled. Additionally,

we will neglect the subscale kinetic energy term, $K_{E}^{\overline{w}}$ and assume that the only body force is due to gravity so that the partial time derivative of the microscale gravitational potential is zero. With these terms deleted and the time derivative of the kinetic energy expanded out using the product rule, the energy equation for entity *w* is

$$\frac{d}{dt} \left(\mathbb{V}E^{\overline{w}} \right) + \mathbf{v}^{\overline{w}} \cdot \frac{d}{dt} \left(\mathbb{M}^{w} \mathbf{v}^{\overline{w}} \right) - \frac{1}{2} \mathbf{v}^{\overline{w}} \cdot \mathbf{v}^{\overline{w}} \frac{d}{dt} (\mathbb{M}^{w}) + \frac{d}{dt} \left(\mathbb{M}^{w} \psi^{\overline{w}} \right) \\ -\mathbb{V} \quad Q \quad -\mathbf{v}^{\overline{ws}}_{w} \cdot \mathbb{V} \quad \mathbf{T} \quad -\int_{\Gamma_{we}} \mathbf{n}_{w} \cdot (\mathbf{q}_{w} + \mathbf{t}_{w} \cdot \mathbf{v}_{w}) d\mathbf{r} \\ + \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot (\mathbf{v}_{w} - \mathbf{v}_{ext}) \left(E_{w} + \frac{1}{2} \rho_{w} \mathbf{v}_{w} \cdot \mathbf{v}_{w} + \rho_{w} \psi_{w} \right) d\mathbf{r} \\ -\mathbb{V}^{w} h^{\overline{w}} = 0.$$
(135)

Next substitute mass conservation Eqn (119) and momentum conservation Eqn (125) for the w entity into this equation to eliminate the time derivatives of mass and momentum. Then rearrange terms to obtain

$$\frac{d}{dt} \left(\mathbb{V} E^{\overline{w}} \right) + \left(\mathbf{v}^{\overline{w}} - \mathbf{v}^{\overline{ws}}_{w} \right) \cdot \mathbb{V} \mathbf{T}
- \mathbb{V} \mathbf{Q} - \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} + \mathbf{t}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] dr
+ \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) \left[E_{w} + \frac{1}{2} \rho_{w} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] dr
- \mathbb{V}^{w} h^{\overline{w}} = 0.$$
(136)

Make use of the linearized force-flux relation of Eqn (117) to restate this equation as

$$\frac{d}{dt} \left(\mathbb{V} E^{\overline{w}} \right) + \mathbf{v}^{\overline{w},\overline{s}} \cdot \mathbb{V}^{w_{\overline{s}} \to w} \mathbf{T}^{w} + \int_{\Omega_{w_{\overline{s}}}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{s}} \right) p_{w} \, \mathrm{dr} - \widehat{k}_{o}^{w} \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{ws}}} \right) \\ - \int_{\Gamma_{w_{e}}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} + \mathbf{t}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] \, \mathrm{dr} \\ + \int_{\Gamma_{w_{e}}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) \left[E_{w} + \frac{1}{2} \rho_{w} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] \, \mathrm{dr} \\ - \mathbb{V}^{w} h^{\overline{w}} = 0. \tag{137}$$

Constitutive Eqn (114) is used to eliminate $\mathbb{V} \xrightarrow{w_{3} \to w} T$ from Eqn (137) to obtain, under conditions where Eqn (130) holds

$$\frac{d}{dt} \left(\mathbb{V} E^{\overline{w}} \right) - \mathbf{v}^{\overline{w},\overline{s}} \cdot \left[\widehat{\mathbf{R}}^{W} \cdot \mathbf{v}^{\overline{w},\overline{s}} + \mathbb{M}^{W} \mathbf{g}^{\overline{w}} \right]
- \mathbf{v}^{\overline{w},\overline{s}} \cdot \sum_{i \in \mathscr{I}_{\Gamma_{we}}} \widehat{\mathbf{r}}_{\mu}^{we_i} \left[\rho^{we_i} \left(\mu^{\overline{we_i}} + \psi^{\overline{we_i}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) \right]
- \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} + \mathbf{t}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{s}} \right) \right] d\mathbf{r}
+ \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) \left[E_{w} + \frac{1}{2} \rho_{w} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] d\mathbf{r}
+ \int_{\Omega_{ws}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{s}} \right) p_{w} d\mathbf{r} - \widehat{k}_{Q}^{w} \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{ws}}} \right)
- \mathbb{V}^{w} h^{\overline{w}} = 0.$$
(138)

Some additional rearrangement may be made involving the integral terms and using Eqn (97) to obtain

$$\frac{d}{dt} \left(\mathbb{V} E^{\overline{w}} \right) - \mathbf{v}^{\overline{w},\overline{s}} \cdot \widehat{\mathbf{R}}^{w} \cdot \mathbf{v}^{\overline{w},\overline{s}} \\
- \mathbf{v}^{\overline{w},\overline{s}} \cdot \sum_{i \in \mathscr{I}_{\Gamma_{we}}} \widehat{\mathbf{r}}_{\mu}^{we_i} \left[\rho^{we_i} \left(\mu^{\overline{we_i}} + \psi^{\overline{we_i}} - \mu^{\overline{w}} - \psi^{\overline{w}} \right) \right] \\
+ \mathbf{v}^{\overline{w},\overline{s}} \cdot \left(\int_{\Gamma_{we}} \mathbf{n}_{w} p_{w} \, d\mathbf{r} + \int_{\Omega_{ws}} \mathbf{n}_{w} p_{w} \, d\mathbf{r} - \mathbb{M}^{w} \mathbf{g}^{\overline{w}} \right) \\
- \mathbf{v}^{\overline{w},\overline{s}} \cdot \int_{\Gamma} \mathbf{v}' \cdot \tau_{w} \cdot \mathbf{n}_{w} \, d\mathbf{r} \\
- \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} + \mathbf{t}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] \, d\mathbf{r} \\
+ \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) \left[E_{w} + \frac{1}{2} \rho_{w} \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] \, d\mathbf{r} \\
+ \int_{\Omega_{ws}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) p_{w} \, d\mathbf{r} - \widehat{h}_{Q}^{w} \left(\frac{1}{d^{\overline{w}}} - \frac{1}{d^{\overline{m}s}} \right) \\
- \mathbb{V}^{w} h^{\overline{w}} = 0.$$
(139)

Terms that are second order in velocity will now be eliminated in light of the porous medium system being studied to obtain

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\mathbb{V}E^{\overline{w}} \right) - \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \left[\mathbf{q}_{w} + \mathbf{t}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) \right] \mathrm{d}r \\
+ \int_{\Gamma_{we}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}_{ext} \right) E_{w} \mathrm{d}r + \int_{\Omega_{ws}} \mathbf{n}_{w} \cdot \left(\mathbf{v}_{w} - \mathbf{v}^{\overline{w}} \right) p_{w} \mathrm{d}r \\
\overline{k}_{Q}^{w} \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}s}} \right) - \mathbb{V}^{w} h^{\overline{w}} = 0.$$
(140)

The linearized closure relation based on Eqn (115) is then substituted into Eqn (140) at locations where the temperature, rather than the heat flux, is specified at the boundary. This provides

$$\frac{d}{dt} \left(\mathbb{V}E^{\overline{w}} \right) - \sum_{i \in \mathscr{I}_{\Gamma_{weg}}} q_{out}^{we_i} \mathbb{A}^{we_i} + \sum_{i \in \mathscr{I}_{\Gamma_{weg}}} \widehat{k}_{\theta}^{we_i} \left(\frac{1}{\theta^{\overline{we}_i}} - \frac{1}{\theta^{\overline{w}}} \right) \mathbb{A}^{we_i} \\
+ \int_{\Gamma_{we}} \mathbf{n}_w \cdot \left(\mathbf{v}_{ext} - \mathbf{v}^{\overline{w}} \right) p_w \, d\mathbf{r} + \int_{\Omega_{wx}} \mathbf{n}_w \cdot \left(\mathbf{v}_w - \mathbf{v}^{\overline{w}} \right) p_w \, d\mathbf{r} \\
- \int_{\Gamma_{we}} \mathbf{n}_w \cdot \boldsymbol{\tau}_w \cdot \left(\mathbf{v}_w - \mathbf{v}^{\overline{w}} \right) \, d\mathbf{r} + \int_{\Gamma_{we}} \mathbf{n}_w \cdot \left(\mathbf{v}_w - \mathbf{v}_{ext} \right) p_w \mu_w \, d\mathbf{r} \\
- \widehat{k}_{\varrho}^w \left(\frac{1}{\theta^{\overline{w}}} - \frac{1}{\theta^{\overline{w}}} \right) - \mathbb{V}^w h^{\overline{w}} = 0,$$
(141)

where $\mathscr{Q}_{\Gamma_{weq}}$ is the index set of locations on the *w* external boundary where the flux is specified, $\mathscr{Q}_{\Gamma_{weq}}$ is the index set of locations on the *w* external boundary where the temperature of the *w* phase is specified, and $\mathscr{Q}_{\Gamma_{weq}} = \mathscr{Q}_{\Gamma_{weq}} \cup \mathscr{Q}_{\Gamma_{weq}}$.

The integrals that remain in Eqn (141) contain some challenges. The first two are related to the change in volume of the system in response to the pressure. The third integral involves frictional effects at the boundary of the system and is typically small. The last term can be managed by breaking the boundary into segments where flow is occurring and then using a closure relation such as

$$\boldsymbol{\upsilon}_{\text{out}}^{\overline{\text{we}_i}} \boldsymbol{\rho}_w^{we_i} \boldsymbol{\mu}_w^{\overline{\text{we}_i}} \mathbb{A}^{we_i} = \int\limits_{\Gamma_{we_i}} \mathbf{n}_w \cdot (\mathbf{v}_w - \mathbf{v}_{\text{ext}}) \boldsymbol{\rho}_w \boldsymbol{\mu}_w \, \mathrm{dr},$$
(142)

where the macroscale quantities $\mu_{W^{-}}^{\overline{\overline{We_i}}}$ are specified with an equation of state.

For the solid phase, the energy equation analogous to Eqn (136) may be obtained as

$$\frac{d}{dt} \left(\mathbb{V}E^{\overline{s}} \right) + \left(\mathbf{v}^{\overline{s}} - \mathbf{v}_{s}^{\overline{ws}} \right) \cdot \mathbb{V} \stackrel{ws \to s}{\mathbf{T}} \\ -\mathbb{V} \stackrel{Q}{\mathcal{Q}} - \int_{\Gamma_{sc}} \mathbf{n}_{s} \cdot \left[\mathbf{q}_{s} + \mathbf{t}_{s} \cdot \left(\mathbf{v}_{s} - \mathbf{v}^{\overline{s}} \right) \right] d\mathbf{r} \\ + \int_{\Gamma_{sc}} \mathbf{n}_{s} \cdot \left(\mathbf{v}_{s} - \mathbf{v}_{ext} \right) \left[E_{s} + \frac{1}{2} \rho_{s} \left(\mathbf{v}_{s} - \mathbf{v}^{\overline{s}} \right) \cdot \left(\mathbf{v}_{s} - \mathbf{v}^{\overline{s}} \right) \right] d\mathbf{r} \\ -\mathbb{V}^{s} h^{\overline{s}} = 0.$$
(143)

Substitution of Eqn (118) into Eqn (143) yields

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\mathbb{V}E^{\overline{s}} \right) - \int_{\Omega_{ws}} \mathbf{n}_{s} \cdot \left(\mathbf{v}_{s} - \mathbf{v}^{\overline{s}} \right) \, \mathbf{n}_{s} \cdot \mathbf{t}_{s} \cdot \mathbf{n}_{s} \, \mathrm{d}\mathbf{r} - \widehat{k}_{\varrho}^{s} \left(\frac{1}{\theta^{\overline{s}}} - \frac{1}{\theta^{\overline{ws}}} \right) \\ - \int_{\Gamma_{se}} \mathbf{n}_{s} \cdot \left[\mathbf{q}_{s} + \mathbf{t}_{s} \cdot \left(\mathbf{v}_{s} - \mathbf{v}^{\overline{s}} \right) \right] \mathrm{d}\mathbf{r} - \mathbb{V}^{s} h^{\overline{s}} = 0,$$
(144)

where we have made use of the definition of the system such that the normal component of the solid phase velocity at the boundary defines the velocity of the boundary. Substitution of the closure expression for the non-advective heat flux at the system boundary at locations were the temperature is known and leaving the heat flux explicitly where it is specified gives

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\mathbb{V}E^{\overline{s}} \right) - \sum_{i \in \mathscr{I}_{\mathrm{Fse}_{q}}} q_{\mathrm{out}}^{\mathrm{se}_{i}} \mathbb{A}^{\mathrm{se}_{i}} + \sum_{i \in \mathscr{I}_{\mathrm{Fse}_{\theta}}} \widehat{k}_{\theta}^{\mathrm{se}_{i}} \left(\frac{1}{\theta^{\overline{se}_{i}}} - \frac{1}{\theta^{\overline{s}}} \right) \mathbb{A}^{\mathrm{se}_{i}} - \int_{\mathrm{Fse}} \mathbf{n}_{s} \cdot \left(\mathbf{v}_{\mathrm{ext}} - \mathbf{v}^{\overline{s}} \right) \mathbf{n}_{s} \cdot \mathbf{t}_{s} \cdot \mathbf{n}_{s} \mathrm{dr} - \int_{\Omega_{\mathrm{exs}}} \mathbf{n}_{s} \cdot \left(\mathbf{v}_{s} - \mathbf{v}^{\overline{s}} \right) \mathbf{n}_{s} \cdot \mathbf{t}_{s} \cdot \mathbf{n}_{s} \mathrm{dr} - \widehat{k}_{\varrho}^{\mathrm{s}} \left(\frac{1}{\theta^{\overline{s}}} - \frac{1}{\theta^{\overline{s}}} \right) - \mathbb{V}^{s} h^{\overline{s}} - \int_{\Gamma_{\mathrm{se}}} \mathbf{n}_{s} \cdot \mathbf{t}_{s} \cdot \mathbf{l}' \cdot \left(\mathbf{v}_{s} - \mathbf{v}^{\overline{s}} \right) \mathrm{dr} = 0,$$
(145)

where $\mathscr{Q}_{\Gamma_{se_q}}$ is the index set of locations on the *s* external boundary where the flux is specified, $\mathscr{Q}_{\Gamma_{se_{\theta}}}$ is the index set of locations on the *s* external boundary where the temperature of the *s* phase is specified, and $\mathscr{Q}_{\Gamma_{se_q}} = \mathscr{Q}_{\Gamma_{se_{\theta}}} \cup \mathscr{Q}_{\Gamma_{se_{\theta}}}$.

10 Discussion

The purpose of this series of manuscripts on the TCAT approach is to lay the foundation for rigorous model building for a variety of porous medium systems. The approach that has evolved in this series to accomplish this goal is to present the components of the machinery needed to formulate models and to use this machinery to create frameworks that support a hierarchy of models. Thus our intent with these works is not to present solutions for a single problem, but to establish a series of frameworks that can be applied to entire families of problems, albeit with some additional effort. An important feature of this work is that the model formulation process proceeds in a series of formal, well-defined intermediate steps that provide convenient starting points for additional individual efforts without requiring the substantial foundational efforts needed to derive starting points such as the CEI or the SEI.

Given the primary restrictions on the class of problem of concern in this work and the applicability of CIT as an appropriate thermodynamic theory, the CEI that is derived is an exact expression, which can be broadly applied to single-fluid-phase megascale problems in general. The CEI is not strictly in the desired form of a set of forces and fluxes, which is needed to guide model closure. Because of this, a series of approximations and restrictions are applied to reduce the CEI to the SEI, which is in strictly force-flux form. The simplifications applied are a reasonable starting point, but may not be the final word. Alternative sets of simplifications to achieve force-flux forms can be explored starting from the CEI to produce alternative forms of the SEI if such efforts are deemed necessary to describe a physical system of concern. It should be noted that reducing the CEI to the SEI is much less effort than deriving the CEI, which requires a substantial series of manipulations. The sort of manipulations required to derive the CEI have been detailed in previous papers in this series [15,16].

The models considered in this work are megascopic in nature, by which we mean that a solution is sought in terms of variables averaged over the entire spatial domain of the system. Because of this, spatial variability within the domain is not resolved at the scale of the solution. It follows then that the theorems applied to derive the conservation equations of concern transform the spatial derivatives to boundary terms, and representing the boundary terms appropriately becomes a central focus of the work.

As an example, and initial starting point for modeling megascale single-fluid-phase systems, a set of linear closure relations are derived from the SEI. These closure relations are in turn used to derive a set of closed conservation of mass, momentum, and energy equations for a megascale system. These closed equations include model parameters that must be determined for application to any specific physical problem, which is typical of any mechanistic model. Because all quantities appearing in the final models are rigorously defined averages of microscale precursors, the means exists to link models across scales and to investigate the dependence of the resultant model parameters on the details of a sub-scale system. Multiscale computation would be one way to approach this problem, while alternative analytical approaches of linking megascale model parameters to microscale system properties are possible under certain, more restrictive conditions. Future works building upon this foundational work along these lines seems potentially fruitful. For example the theoretical underpinnings of Darcy's [6] foundational experimental work and data correlation can be explored. This can be important in determining problem parameters and also extensions to multiphase systems.

Megascale models are of most applicability when the spatial variations within the system are sufficiently simple in form to result in meaningful megascopic model parameters of a correspondingly simple form. When this is no longer the case, megascale models lose their utility. One way in which megascale models may be used advantageously is to subdivide a

system into a set of domains that can each be approximated with a megascopic model and linked together at the boundaries. A second extended way to use megascopic models is to separately treat a simple portion of a larger system with a megascopic model that is coupled to a more highly resolved macroscale model for the more complex portions of the domain that does represent spatial variability. An example of such a system is a highly dynamic unsaturated porous medium zone, or a dynamic system such as a lake, coupled to a more slowly changing saturated porous medium zone. These sorts of extensions are also potentially fruitful ways to employ this foundational work in rigorous study of multiscale systems [e.g., those described in 2,25,27].

11 Conclusions

Reduced dimensionality models are important tools for both preliminary analysis and as component parts of larger, more complex models. Derivation of these megascale models poses challenges that are identical to those faced in deriving macroscale models. In both cases, a rigorous foundation requires an exact representation of the averaged variables of concern in terms of the microscale precursors, constraints to ensure that the second law of thermodynamics is enforced, and closure relations that represent sub-scale processes adequately at the larger scale of concern. Corresponding parallels exist between the derivation of TCAT models at the macroscale and at the megascale in concept, although the detailed components of the process must be extended; these extensions were detailed in this work.

Conservation of mass, momentum, and energy and balance of entropy equations were derived for a megascopic single-fluid-phase porous medium system starting from the microscale. These equations do not include spatial derivatives, but they do include a set of boundary integral terms that represent the net input of the conserved or balanced quantity of concern. These conservation and balance equations are defined as precise averages of microscale quantities, which allows for connection across scales.

Classical irreversible thermodynamics is used along with the megascale conservation and balance equations to produce an augmented entropy inequality. A series of manipulations are applied to produce a constrained entropy inequality (CEI) for the megascale single-fluid-phase system of concern, which is an exact expression for the system of concern and the thermodynamic theory chosen. The CEI is an important inequality that can serve as a starting point for a variety of megascale models for single-fluid-phase systems of varying complexity. Because the significant amount of effort required to derive this equation does not need to be repeated, varying applications of this inequality are considered relatively straightforward.

Because the CEI is not strictly in force-flux form, a series of approximations are applied to reduce this inequality to the simplified entropy inequality (SEI), which is necessarily approximate in nature unlike the CEI. The approximations used to derive the SEI are clearly summarized and the resultant SEI formulation is detailed. While perhaps not the final word, the megascale SEI derived is still a rather general expression that may apply to many different systems of varying complexity. A significant number of models can be derived based upon this SEI and only if these models prove inadequate to describe a physical system of concern would the SEI need to be revisited.

The SEI is used to guide the formulation of closure relations. A linear form of these closure relations is detailed, which are deemed a reasonable first approximation but certainly neither unique nor of high complexity. The closure relations are in turn used to produce a complete set of closed equations for conservation of mass, momentum, and energy. These closed equations can be applied to model a range of physical systems. Resolution of the relation between the precise functional dependence of the megascale model parameters appearing in

the closed models in relation to specific underlying microscale, or macroscale, systems is an area of additional research deserving of attention using either analytical or numerical means.

In addition to purely megascopic models, the foundational work presented herein can be used to produce megascale models that are coupled to other megascale models, or megascale models that are coupled to macroscale models. The foundation laid in this work should enable such applications in a relatively straightforward manner.

Notation

Roman letters

	area, l^2
b	entropy source density
	Green's deformation tensor, —
E	internal energy density
3	the set of entities
3	conservation of energy equation, ml^2/t^3
ε _c	connected set of entities
F	scalar force for entropy generation
F	vector force for entropy generation
	tensor force for entropy generation
7	set of forces for entropy generation
f	general scalar function
f	general vector function
g	acceleration vector due to an external force, such as gravity, l/t^2
g	scalar magnitude of gravitational acceleration, l/t^2
h	heat source density
	identity tensor, – –
'	surface identity tensor, —
R	index set of entities
\mathcal{A}_{c}	index set of connected entities
\mathcal{Q}_{I}	index set of interface entities
\mathscr{Q}_{P}	index set of phase entities
\mathcal{Q}_{Γ}	index set of boundary subsets
J	scalar flux for entropy generation
J	vector flux for entropy generation
	tensor flux for entropy generation
j_s	solid-phase Jacobian, —
Ŕ	megascale conductivity parameter
K_E	megascale kinetic energy per unit mass due to microscale velocity fluctuations, l^2/t^2

$\hat{K_H}$	megascale hydraulic conductivity parameter, l/t
\hat{k}_Q	inter-entity heat transfer closure parameter
$\hat{k}_{ heta}$	heat flux closure parameter
	length, l
l	characteristic length, l
	mass, m
M	conservation of mass equation, m/t
$\stackrel{\kappa ightarrow i}{M}$	transfer of mass from the κ entity to the ι entity per unit volume per unit time, $m/(tl^3)$
nı	outward unit normal vector from the surface of a phase when $\iota \in \mathscr{Q}_P$ and the unit normal tangent to the surface and outward normal from the bounding curve when $\iota \in \mathscr{Q}_I$
	general property
	conservation of momentum equation, ml/t^2
р	fluid pressure, $m/(lt^2)$
$\overset{\kappa ightarrow \iota}{Q}$	transfer of energy from the κ entity to the ι entity resulting from heat transfer and deviation from mean processes per unit volume per unit time, $m/(lt^3)$
q	non-advective heat flux density vector
$q_{\rm out}$	is the outward normal component of the heat flux vector for the ι entity evaluated on the boundary of the domain
^	resistance tensor
ົ î ບ	resistance tensor closure vector
$\hat{\mathbf{r}}_{\upsilon}$ $\hat{\mathbf{r}}_{\mu}$	resistance tensor closure vector closure vector
$\hat{\mathbf{r}}_{\mathrm{b}}$ $\hat{\mathbf{r}}_{\mathrm{\mu}}$	resistance tensor closure vector closure vector entropy balance equation, $ml^2/(t^3T)$
$\hat{\mathbf{r}}_{\mathrm{u}}$ $\hat{\mathbf{r}}_{\mathrm{\mu}}$	resistance tensor closure vector closure vector entropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energy
$\hat{\mathbf{r}}_{\upsilon}$ $\hat{\mathbf{r}}_{\mu}$ \boldsymbol{r}_{μ}	resistance tensor closure vector closure vector entropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energy transfer of momentum from κ entity to the ι entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$
$\hat{\mathbf{r}}_{\upsilon}$ $\hat{\mathbf{r}}_{\mu}$ $\hat{\mathbf{r}}_{\mu}$ t	resistance tensor closure vector closure vector entropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energy transfer of momentum from κ entity to the ι entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensor
$\hat{\mathbf{r}}_{\upsilon}$ $\hat{\mathbf{r}}_{\mu}$ $\hat{\mathbf{r}}_{\mu}$ \mathbf{t} \mathbf{t} t	resistance tensor closure vector closure vector entropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energy transfer of momentum from κ entity to the ι entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensor time, t
$\hat{\mathbf{r}}_{\upsilon}$ $\hat{\mathbf{r}}_{\mu}$ $\hat{\mathbf{r}}_{\mu}$ t t t	resistance tensorclosure vectorclosure vectorentropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energytransfer of momentum from κ entity to the ι entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensortime, t volume, l^3
	resistance tensorclosure vectorclosure vectorentropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energytransfer of momentum from κ entity to the ι entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensortime, tvolume, l^3 initial volume of the solid phase, l^3
$\hat{\mathbf{r}}_{\upsilon}$ $\hat{\mathbf{r}}_{\mu}$ $\kappa \rightarrow \iota$ \mathbf{T} t t t v	resistance tensorclosure vectorclosure vectorentropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energytransfer of momentum from κ entity to the ι entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensortime, t volume, l^3 initial volume of the solid phase, l^3 velocity, l/t
$\mathbf{\hat{r}}_{\upsilon}$ $\mathbf{\hat{r}}_{\mu}$ $\mathbf{\hat{r}}_{\mu}$ $\mathbf{\hat{r}}_{\mu}$ t t t t v \mathbf{v}_{ext}	resistance tensorclosure vectorclosure vectorentropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energytransfer of momentum from κ entity to the ι entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensortime, t volume, l^3 initial volume of the solid phase, l^3 velocity, l/t velocity of the exterior portion of the boundary of the ι entity, l/t
$ \mathbf{\hat{r}}_{\upsilon} \mathbf{\hat{r}}_{\mu} $	resistance tensorclosure vectorclosure vectorentropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energytransfer of momentum from κ entity to the ι entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensortime, t volume, l^3 initial volume of the solid phase, l^3 velocity, l/t velocity of the exterior portion of the boundary of the ι entity, l/t is the normal velocity of the ι entity relative to the normal velocity of the external boundary evaluated at the external boundary, l/t
$\mathbf{\hat{r}}_{\upsilon}$ $\mathbf{\hat{r}}_{\mu}$ $\mathbf{\hat{r}}_{\mu}$ $\mathbf{\hat{r}}_{\mu}$ t t t t v \mathbf{v}_{ext} υ_{out} $\mathbf{v}^{\overline{z},\overline{s}}$	resistance tensorclosure vectorclosure vectorentropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energytransfer of momentum from κ entity to the ι entity due to stress and deviation frommean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensortime, tvolume, l^3 initial volume of the solid phase, l^3 velocity, l/t velocity of the exterior portion of the boundary of the ι entity, l/t is the normal velocity of the ι entity relative to the mormal velocity of the external boundary, l/t mass averaged velocity of the ι entity relative to the mass averaged velocity of the solid phase, $v^{w} - v^{\sigma}$, l/t
$\hat{\mathbf{r}}_{\upsilon}$ $\hat{\mathbf{r}}_{\mu}$ \boldsymbol{r}_{μ} \boldsymbol{r}_{τ} \boldsymbol{r}_{τ} \boldsymbol{r}_{τ} \boldsymbol{r}_{τ} \boldsymbol{r}_{τ} \boldsymbol{r}_{τ} \boldsymbol{v}_{ext} \boldsymbol{v}_{out} $\boldsymbol{v}_{\varepsilon,\overline{s}}$ \boldsymbol{w}	resistance tensorclosure vectorentropy balance equation, $ml^2/(t^3T)$ CIT-based thermodynamic equation for material derivative of internal energytransfer of momentum from k entity to the t entity due to stress and deviation from mean processes per unit volume per unit time, $m/(l^2t^2)$ stress tensortime, t volume, l^3 initial volume of the solid phase, l^3 velocity, l/t velocity of the exterior portion of the boundary of the t entity, l/t is the normal velocity of the t entity relative to the mass averaged velocity of the solid phase, $\mathbf{v}^{v_i} - \mathbf{v}^{v_i}$, l/t weight function

time

Х	position vector in the solid phase, l
Gre	ek letters
Г	boundary of domain of interest
γ	interfacial tension
ε ^ι	measure of quantity of entity t per macroscale volume
η	entropy density
θ	temperature
ι	entity qualifier
Λ	entropy production rate density
λ	vector of Lagrange multipliers
λ	Lagrange multiplier
μ	chemical potential
ρ	mass density
σ	Lagrangian stress tensor for the solid phase
τ	stress tensor
$\Phi^{\kappa o \iota}$	transfer of entropy from the κ entity to the ι entity per unit volume per unit
φ	entropy density flux vector
ψ	acceleration potential (e.g., gravitational potential)
Ω	spatial domain
Sub	oscripts and superscripts
3	energy equation qualifier
e	exterior of domain qualifier
i	general index
j	general index
k	general index
M	mass equation qualifier
	momentum equation qualifier
r	residual portion of specified equation
S	index that indicates a solid phase
sei	<i>i</i> th location where the s phase intersects the system boundary
	thermodynamic equation qualifier
w	entity index corresponding to the wetting phase
we _i	<i>i</i> th location where the <i>w</i> phase intersects the system boundary
ws	entity index corresponding to the wetting-solid interface

wse _i	th common line where the ws interface intersects the system boundary
ι	entity qualifier
Other ma	thematical symbols
-	closure of set (overline)
< >	averaging operator
$D^{\bar{\iota}}/Dt$	material derivative
$\partial'/\partial t$	partial derivative of a point on a potentially moving interface
∇'	microscale surficial del operator on an interface
$\nabla(\cdot) _{-}$	spatial derivative of the thermodynamic function (\cdot) taken with the quantities listed following the vertical bar held constant
Abbrevia	tions
ACIT	averaged classical irreversible thermodynamics
AEI	augmented entropy inequality
CEI	constrained entropy inequality
CIT	classical irreversible thermodynamics
EI	entropy inequality

- REV representative elementary volume
- SEI simplified entropy inequality
- TCAT thermodynamically constrained averaging theory

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