## Technology or Incentives? Bycatch Avoidance in the BSAI Groundfish Fishery

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## Rights-based Management in Multi-species

 FisheriesAdditional complexity: catch-quota balancing
Ex ante examinations: weak targeting potential
$\Longrightarrow$ challenges for rights-based management Squires (1987), Pascoe (2007, 20I0)

Ex post examinations: stronger targeting potential than previously thought Sanchiricho (2006), Branch (2008)

## Rights-based Management in Multi-species

 FisheriesHypothesis:

Conventional models of fishery production reflect more about the incentives for substitutability than the technological possibilities of cross-species substitution.

Ability to target confounded with incentive to target.

## Conventional Production Function:

catch $=F($ labor, capital, duration $)$

## BSAI Non-Pollock Groundfish Fishery

## Did rights-based management induce bycatch avoidance?



# The Bering Sea Groundfish Fishery 

Pre-Amendment 80 (prior to 2008):

- Target species TACs allocated as common property over multiple "sub-seasons"
- TAC for PSC (e.g. halibut) allocated to target species fisheries
- Target fisheries typically closed due to binding PSC TAC


## The Bering Sea Groundfish Fishery

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- Target fisheries typically closed due to binding PSC TAC Post-Amendment 80 (2008 and after):
- Target species and PSC allocations vested directly into cooperatives or limited access fishery
- Initially one cooperative formed: 16 vessels, 7 companies


| Yellowfin Sole | Atka Mackerel | Cod | Rock Sole | Flathead Sole | llock | Other |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |



## Change in Fishing Practices



Abbott et al. (20I3) found:

- large scale movements out of halibut-rich areas
- finer scale movements after hauls with a large proportion of halibut
- less fishing at night when halibut bycatch is more prevalent


## Changes in Bycatch Intensity



## Changes in Bycatch Intensity




- Pre-A80 - Post-A80


## Reduced Form Fishery Production Function

A Hyperbolic Distance Function Approach

Transformation Function: $\quad T(x, y, b)=0$

$$
x=\text { inputs } \quad y=\text { good outputs } \quad b=\text { bad outputs }
$$

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Hyperbolic Output Distance Function:

$$
\begin{aligned}
& D^{H}(x, y, b)=\min _{\theta}\{\theta>0: T(x, y / \theta, b \theta) \leq 0\} \\
& 0<D^{H}(x, y, b) \leq 1
\end{aligned}
$$



Reduced Form Fishery Production Function
Hyperbolic Distance Function: Identification

$$
D^{H}(x, y, b)=\min _{\theta}\{\theta>0: T(x, y / \theta, b \theta) \leq 0\}
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## Reduced Form Fishery Production Function

Hyperbolic Distance Function: Identification

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D^{H}(x, y, b)=\min _{\theta}\{\theta>0: T(x, y / \theta, b \theta) \leq 0\}
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Distance is latent, so.....

$$
\begin{gathered}
y=y^{*} e^{v-u} \text { and } \quad b=b^{*} e^{u-v} \text { where } D^{H}\left(x, y^{*}, b^{*}\right)=1 \\
\Longrightarrow D^{H}\left(x, y e^{u-v}, b e^{v-u}\right)=1 \\
\Longrightarrow D^{H}(x, y, b)=e^{v-u}
\end{gathered}
$$

since $D^{H}(x, y, b)$ is almost homogeneous of degrees $1,1,-1,1$

## Reduced Form Fishery Production Function

Hyperbolic Distance Function: Identification

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\end{gathered}
$$

since $D^{H}(x, y, b)$ is almost homogeneous of degrees $1,1,-1,1$

$$
v \sim N\left(0, \sigma_{v}\right) \quad u \sim \Gamma\left(1, \sigma_{u}\right)
$$

## Reduced Form Fishery Production Function

A Hyperbolic Distance Function Approach

$$
\begin{aligned}
\ln D_{i t s}^{H}\left(\mathbf{x}_{i t s}, \mathbf{y}_{i t s}, \mathbf{b}_{i t s}\right) & =\alpha_{o}^{i s}+\alpha_{\mathbf{x}}^{s \prime} \ln \mathbf{x}_{i t s}+\alpha_{\mathbf{y}}^{s \prime} \ln \mathbf{y}_{i t s}+\alpha_{\mathbf{b}}^{s \prime} \ln \mathbf{b}_{i t s} \\
& +\frac{1}{2} \ln \mathbf{x}_{i t s}^{\prime} \mathbf{A}_{\mathbf{x x}}^{s} \ln \mathbf{x}_{i t s}+\frac{1}{2} \ln \mathbf{y}_{i t s}^{\prime} \mathbf{A}_{\mathbf{y} \mathbf{y}}^{s} \ln \mathbf{y}_{i t s}+\frac{1}{2} \ln \mathbf{b}_{i t s}^{\prime} \mathbf{A}_{\mathbf{b} \mathbf{b}}^{s} \ln \mathbf{b}_{i t s} \\
& +\ln \mathbf{y}_{i t s}^{\prime} \mathbf{A}_{\mathbf{y b}}^{s} \ln \mathbf{b}_{i t s}+\ln \mathbf{x}_{i t s}^{\prime} \mathbf{A}_{\mathbf{x} \mathbf{y}}^{s} \ln \mathbf{y}_{i t s}+\ln \mathbf{x}_{i t s}^{\prime} \mathbf{A}_{\mathbf{x b}}^{s} \ln \mathbf{b}_{i t s} \\
& =\varepsilon_{i t s}=v_{i t s}-u_{i t s}
\end{aligned}
$$

$x=$ Fishing Time, Vessel Length
$i=$ Individual
$y=$ Rock Sole, Yellowfin Sole, Cod, Other $\quad t=$ Day of season
$b=$ Halibut
Reform-induced "technological" change left latent

## Stochastic Production Function

 Measures of Substitution$$
y=\text { rock sole } \quad b=\text { halibut }
$$

Marginal Rate of Transformation: $\quad M R T_{b y}=\frac{\partial y}{\partial b}=-\frac{\partial D(\cdot) / \partial b}{\partial D(\cdot) / \partial y}$
Larger MRT implies a greater shadow value of halibut reduction.

Transformation Elasticity:

$$
s u b s_{b y}=\frac{\partial \ln y}{\partial \ln b}=-\frac{\partial \ln D(\cdot) / \partial \ln b}{\partial \ln D(\cdot) / \partial \ln y}
$$

Smaller elasticity implies greater potential to substitute rock sole for halibut reduction.

Marginal Rate of Transformation


Relative Substitutability


Frontiers: Rock sole-Halibut Space


Frontiers: Rock sole-Halibut Space


## Conclusion

Targeting "ability" in prior to A80 primarily determined by lack of incentives to avoid halibut bycatch

- Ex ante predictions likely reflect far more about incentives for substitutability than technological possibilities for substitutability
- Need to understand what the relevant margins of production are, which are fishery and context specific



## Acknowledgements



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