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A quantum algorithm to estimate the Gowers U_2 norm and linearity testing of Boolean functions

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Abstract. We propose a quantum algorithm to estimate the Gowers U_2 norm of a Boolean function, and extend it into a second algorithm to distinguish between linear Boolean functions and Boolean functions that are ϵ -far from the set of linear Boolean functions, which seems to perform better than the classical BLR algorithm. Finally, we outline an algorithm to estimate Gowers U_3 norms of Boolean functions.

Keywords: Boolean functions, Fourier spectrum, Gowers uniformity norms, quantum algorithms

1 Introduction

Gowers uniformity norms were introduced by Gowers [6] to prove Szemerédi's theorem. In their full generality, Gowers uniformity norms operate over functions from finite sets to the field of complex numbers. The Gowers uniformity norm of dimension d of a function f tells us the extent of correlation of f to the polynomial phase functions of degree up to $d - 1$. In this paper, we consider the Gowers uniformity norm U_2 of dimension 2 for Boolean functions, and find a quantum estimate of its upper bound. We also propose a linearity test of Boolean functions based on the same quantum algorithm, which seems to perform better than the classical BLR algorithm.

1.1 Boolean functions

We denote the ring of integers, the set of positive integers, and the fields of real numbers and complex numbers by \mathbb{Z} , \mathbb{Z}^+ , \mathbb{R} , and \mathbb{C} , respectively. For any $n \in \mathbb{Z}^+$, the set $[n] = \{i \in \mathbb{Z}^+ : 1 \leq i \leq n\}$, and $\mathbb{F}_2^n = \{x = (x_1, \dots, x_n) : x_i \in \mathbb{F}_2, \text{ for all } i \in [n]\}$ where \mathbb{F}_2 is the prime field of characteristic 2. Addition in each of the above algebraic systems is denoted by '+'. An n -variable Boolean function F is a function from \mathbb{F}_2^n to \mathbb{F}_2 . The set of all such functions is denoted by \mathfrak{B}_n . Each function $F \in \mathfrak{B}_n$ has its character form $f : \mathbb{F}_2^n \rightarrow \mathbb{R}$ defined by $f(x) = (-1)^{F(x)}$, for all $x \in \mathbb{F}_2^n$. In this article, abusing notation, we refer to the character form f as Boolean functions and go to the extent of writing $f \in \mathfrak{B}_n$, whenever $F \in \mathfrak{B}_n$, if there is no danger of confusion. For any $x, y \in \mathbb{F}_2^n$, the inner product $x \cdot y = \sum_{i \in [n]} x_i y_i$ where the sum is over \mathbb{F}_2 . The (Hamming) weight of a vector $u = (u_1, \dots, u_n) \in \mathbb{F}_2^n$ is $\text{wt}(u) = \sum_{i \in [n]} u_i$, where the sum is over \mathbb{Z} . The weight of a Boolean function $F \in \mathfrak{B}_n$, or equivalently $f \in \mathfrak{B}_n$ is the cardinality $\text{wt}(F) = |\{x \in \mathbb{F}_2^n : F(x) \neq 0\}|$, or equivalently $\text{wt}(f) = |\{x \in \mathbb{F}_2^n : f(x) \neq 1\}|$. The Hamming distance between $F, G \in \mathfrak{B}_n$, or equivalently, between $f, g \in \mathfrak{B}_n$ is $d_H(F, G) =$

$|\{x \in \mathbb{F}_2^n : F(x) \neq G(x)\}|$, or, $d_H(f, g) = |\{x \in \mathbb{F}_2^n : f(x) \neq g(x)\}|$. Any Boolean function $F \in \mathfrak{B}_n$ can be expressed as a polynomial, called the algebraic normal form (ANF),

$$F(x_1, \dots, x_n) = \sum_{u \in \mathbb{F}_2^n} \lambda_u x^u \text{ where } \lambda_u \in \mathbb{F}_2, \text{ and } x^u = \prod_{i \in [n]} x_i^{u_i}. \quad (1)$$

The algebraic degree of a Boolean function $\deg(F) = \max\{\text{wt}(u) : \lambda_u \neq 0\}$. A Boolean function with algebraic degree at most 1 is said to be an affine function. An affine function in \mathfrak{B}_n is of the form $\varphi(x) = u \cdot x + \varepsilon$ for some $u \in \mathbb{F}_2^n$ and $\varepsilon \in \mathbb{F}_2$. An affine function with $\varepsilon = 0$ is said to be a linear function. We denote the set of all n -variable affine functions by \mathfrak{A}_n , and the set of all n -variable linear functions by \mathfrak{L}_n .

The Fourier series expansion of $f \in \mathfrak{B}_n$ is

$$f(x) = \sum_{u \in \mathbb{F}_2^n} \widehat{f}(u) (-1)^{u \cdot x}. \quad (2)$$

The coefficients $\widehat{f}(u)$ are said to be the Fourier coefficients of f . The transformation $f \mapsto \widehat{f}$ is the Fourier transformation of f . It is known that

$$\sum_{x \in \mathbb{F}_2^n} (-1)^{v \cdot x} = \begin{cases} 0 & \text{if } v \neq 0 \\ 2^n & \text{if } v = 0. \end{cases} \quad (3)$$

Equations (2) and (3) yield

$$\begin{aligned} \sum_{x \in \mathbb{F}_2^n} f(x) (-1)^{u \cdot x} &= \sum_{x \in \mathbb{F}_2^n} \sum_{v \in \mathbb{F}_2^n} \widehat{f}(v) (-1)^{(u+v) \cdot x} \\ &= \sum_{v \in \mathbb{F}_2^n} \widehat{f}(v) \sum_{x \in \mathbb{F}_2^n} (-1)^{(u+v) \cdot x} = 2^n \widehat{f}(u), \end{aligned} \quad (4)$$

that is, $\widehat{f}(u) = 2^{-n} \sum_{x \in \mathbb{F}_2^n} f(x) (-1)^{u \cdot x}$. The sum

$$\begin{aligned} \sum_{x \in \mathbb{F}_2^n} f(x)^2 &= \sum_{x \in \mathbb{F}_2^n} \sum_{u \in \mathbb{F}_2^n} \widehat{f}(u) (-1)^{u \cdot x} \sum_{v \in \mathbb{F}_2^n} \widehat{f}(v) (-1)^{v \cdot x} \\ &= \sum_{u \in \mathbb{F}_2^n} \sum_{v \in \mathbb{F}_2^n} \widehat{f}(u) \widehat{f}(v) \sum_{x \in \mathbb{F}_2^n} (-1)^{(u+v) \cdot x} = 2^n \sum_{u \in \mathbb{F}_2^n} \widehat{f}(u)^2. \end{aligned}$$

The identity $\sum_{x \in \mathbb{F}_2^n} \widehat{f}(x)^2 = 2^{-n} \sum_{x \in \mathbb{F}_2^n} f(x)^2$, is known as the *Plancherel's identity*. This is true for $f : \mathbb{F}_2^n \rightarrow \mathbb{R}$. If $f \in \mathfrak{B}_n$, we have the *Parseval's identity* $\sum_{u \in \mathbb{F}_2^n} \widehat{f}(u)^2 = 1$. For $f, g \in \mathfrak{B}_n$ the convolution product, $f * g$ is defined as

$$(f * g)(x) = 2^{-n} \sum_{y \in \mathbb{F}_2^n} f(y) g(x + y) = 2^{-n} \sum_{y \in \mathbb{F}_2^n} f(x + y) g(y). \quad (5)$$

Using (4) on (5)

$$\begin{aligned} \widehat{f * g}(u) &= 2^{-n} \sum_{x \in \mathbb{F}_2^n} (f * g)(x) (-1)^{u \cdot x} = 2^{-2n} \sum_{x \in \mathbb{F}_2^n} \sum_{y \in \mathbb{F}_2^n} f(y) g(x + y) (-1)^{u \cdot x} \\ &= 2^{-2n} \sum_{x \in \mathbb{F}_2^n} \sum_{y \in \mathbb{F}_2^n} f(y) (-1)^{u \cdot y} g(x + y) (-1)^{u \cdot (x+y)} \\ &= \left(2^{-n} \sum_{y \in \mathbb{F}_2^n} f(y) (-1)^{u \cdot y} \right) \left(2^{-n} \sum_{x \in \mathbb{F}_2^n} g(x) (-1)^{u \cdot x} \right) = \widehat{f}(u) \widehat{g}(u). \end{aligned} \quad (6)$$

For each $x \in \mathbb{F}_2^n$, $(f * f)(x) = 2^{-n} \sum_{y \in \mathbb{F}_2^n} f(y) f(x + y)$ is said to be the *autocorrelation* of f at x , and $\widehat{f * f}(x) = \widehat{f}(x)^2$.

The derivative of $f \in \mathfrak{B}_n$ at $c \in \mathbb{F}_2^n$ is the function

$$\Delta_c f(x) = f(x)f(x+c), \text{ for all } x \in \mathbb{F}_2^n. \quad (7)$$

We write

$$\Delta_{x^{(1)}, \dots, x^{(k)}} f(x) = \prod_{S \subseteq [k]} f\left(x + \sum_{i \in S} x^{(i)}\right), \quad (8)$$

where $x^{(i)} \in \mathbb{F}_2^n$, for all $i \in [k]$, and some $k \in \mathbb{Z}^+$. In Equation (7) we have defined derivatives of a Boolean function when the codomain of the function is $\{1, -1\}$. In that case, the resulting derivative turns out to be function from \mathbb{F}_2^n to $\{1, -1\}$. The derivative of a Boolean function $F : \mathbb{F}_2^n \rightarrow \mathbb{F}_2$, at a point $a \in \mathbb{F}_2^n$ is

$$\Delta_a F(x) = F(x) + F(x+a), \text{ for all } x \in \mathbb{F}_2^n. \quad (9)$$

For any $a, b \in \mathbb{F}_2^n$

$$\Delta_{a,b} F(x) = F(x) + F(x+b) + F(x+a) + F(x+a+b). \quad (10)$$

For $a, b, c \in \mathbb{F}_2^n$,

$$\begin{aligned} \Delta_{a,b,c} F(x) = & F(x) + F(x+c) + F(x+b) + F(x+b+c) + F(x+a) \\ & + F(x+a+c) + F(x+a+b) + F(x+a+b+c). \end{aligned} \quad (11)$$

In general for $x^{(1)}, \dots, x^{(k)} \in \mathbb{F}_2^n$,

$$\Delta_{x^{(1)}, \dots, x^{(k)}} F(x) = \sum_{S \subseteq [k]} F\left(x + \sum_{i \in S} x^{(i)}\right). \quad (12)$$

1.2 Gowers uniformity norms

Gowers [6] introduced (now, called Gowers) uniformity norms in his work on Szmerédi's theorem. For an introductory reading on the topic, we refer to the Ph.D. thesis of Chen [4]. The Gowers U_k norm of $f \in \mathfrak{B}_n$, denoted by $\|f\|_{U_k}$, is defined as

$$\|f\|_{U_k} = \left(2^{-(k+1)n} \sum_{x, x^{(1)}, \dots, x^{(k)} \in \mathbb{F}_2^n} \prod_{S \subseteq [k]} f\left(x + \sum_{i \in S} x^{(i)}\right) \right)^{2^{-k}}. \quad (13)$$

The Gowers U_2 norm is

$$\begin{aligned} \|f\|_{U_2} &= \left(2^{-3n} \sum_{x \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{b \in \mathbb{F}_2^n} f(x)f(x+a)f(x+b)f(x+a+b) \right)^{2^{-2}} \\ &= \left(2^{-3n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} f(x)f(x+a) \sum_{b \in \mathbb{F}_2^n} f(x+b)f(x+a+b) \right)^{2^{-2}} \\ &= \left(2^{-3n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} f(x)f(x+a) \sum_{y \in \mathbb{F}_2^n} f(y)f(y+a) \right)^{2^{-2}} \\ &= \left(2^{-n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} \widehat{f}(x)^2 (-1)^{x \cdot a} \sum_{y \in \mathbb{F}_2^n} \widehat{f}(y)^2 (-1)^{y \cdot a} \right)^{2^{-2}} \end{aligned}$$

$$= \left(2^{-n} \sum_{x \in \mathbb{F}_2^n} \sum_{y \in \mathbb{F}_2^n} \widehat{f}(x)^2 \widehat{f}(y)^2 \sum_{a \in \mathbb{F}_2^n} (-1)^{(x+y) \cdot a} \right)^{2^{-2}} = \left(\sum_{x \in \mathbb{F}_2^n} \widehat{f}(x)^4 \right)^{2^{-2}}.$$

The Gowers U_3 norm is

$$\|f\|_{U_3} = \left(2^{-4n} \sum_{x \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{b \in \mathbb{F}_2^n} \sum_{c \in \mathbb{F}_2^n} f(x)f(x+a)f(x+b)f(x+a+b) \right. \\ \left. f(x+c)f(x+a+c)f(x+b+c)f(x+a+b+c) \right)^{2^{-3}}. \quad (14)$$

Substituting the derivative in (14)

$$\|f\|_{U_3} = \left(2^{-4n} \sum_{c \in \mathbb{F}_2^n} \sum_{x, a, b \in \mathbb{F}_2^n} \Delta_c f(x) \Delta_c f(x+a) \Delta_c f(x+b) \Delta_c f(x+a+b) \right)^{2^{-3}} \\ = \left(2^{-n} \sum_{c \in \mathbb{F}_2^n} \|\Delta_c f(x)\|_{U_2}^2 \right)^{2^{-3}}. \quad (15)$$

In general, the Gowers U_k norm of $f \in \mathfrak{B}_n$ is

$$\|f\|_{U_k} = \left(2^{-(k+1)n} \sum_{x, x^{(1)}, \dots, x^{(k)} \in \mathbb{F}_2^n} \prod_{S \subseteq [k] \setminus [2]} \prod_{T \subseteq [2]} f \left(x + \sum_{i \in S} x^{(i)} + \sum_{j \in T} x^{(j)} \right) \right)^{2^{-k}} \\ = \left(2^{-(k+1)n} \sum_{x, x^{(1)}, \dots, x^{(k)} \in \mathbb{F}_2^n} \prod_{T \subseteq [2]} \prod_{S \subseteq [k] \setminus [2]} f \left(x + \sum_{i \in S} x^{(i)} + \sum_{j \in T} x^{(j)} \right) \right)^{2^{-k}} \\ = \left(2^{-(k+1)n} \sum_{x^{(3)}, \dots, x^{(k)} \in \mathbb{F}_2^n} \sum_{x^{(1)}, x^{(2)} \in \mathbb{F}_2^n} \prod_{T \subseteq [2]} \Delta_{x^{(3)}, \dots, x^{(k)}} f \left(x + \sum_{j \in T} x^{(j)} \right) \right)^{2^{-k}} \\ = \left(2^{-(k-2)n} \sum_{x^{(3)}, \dots, x^{(k)} \in \mathbb{F}_2^n} \left\| \Delta_{x^{(3)}, \dots, x^{(k)}} f(x) \right\|_{U_2}^2 \right)^{2^{-k}}. \quad (16)$$

Equation (16) shows the relation between the Gowers U_k norm and the U_2 norms of the $(k-2)$ th derivatives of f . The time complexity of computing the Gowers U_2 norm of a Boolean function $f \in \mathfrak{B}_n$ is $O(n2^{2n})$. Arguing in the same way, the time complexity of computing Gowers U_k norm is $O(n2^{kn})$.

In this paper, we propose a quantum algorithm to estimate an upper bound of Gowers U_2 norm and based upon that, we find a quantum counterpart of the BLR linearity testing [2] that tends to perform better than the classical version, assuming the availability of a quantum computer with sufficient number of qubits. The complexities of the quantum algorithms are independent of the number of variables n , of course, again with the strong assumption of the availability of a fairly large quantum computer.

1.3 Gowers uniformity norms and approximation of Boolean functions by low degree Boolean functions

In this section, we discuss the connection between the Gowers uniformity norms and the approximation of Boolean functions by low degree Boolean functions. The nonlinearity,

denoted by $nl(f)$, of a Boolean function $f \in \mathfrak{B}_n$ is the minimum Hamming distance from f to all affine functions in \mathfrak{A}_n . That is

$$nl(f) = \min\{d_H(f, \varphi) : \varphi \in \mathfrak{A}_n\}. \quad (17)$$

The r th-order nonlinearity of a Boolean function f , denoted by $nl_r(f)$, is the minimum Hamming distance from f to the functions having algebraic degree less than or equal to r . The first-order nonlinearity $nl_1(f) = nl(f)$. It is well known that (cf. [5])

$$nl(f) = 2^{n-1} \left(1 - \max_{x \in \mathbb{F}_2^n} |\widehat{f}(x)|\right). \quad (18)$$

Carlet [3] obtained lower bounds of r th-order nonlinearity of Boolean functions by using nonlinearities of their higher-order derivatives. This establishes a relationship between the r th-order nonlinearities of Boolean functions and Fourier coefficients of their derivatives. Gowers uniformity norms involve Fourier coefficients of higher-order derivatives (16), and serve the same purpose as evident from the following theorem.

Theorem 1 ([4], Fact 2.2.1). *Let $k \in \mathbb{Z}^+$, $\epsilon > 0$. Let $P : \mathbb{F}_2^n \rightarrow \mathbb{F}_2$ be a polynomial of degree at most k , and $f : \mathbb{F}_2^n \rightarrow \mathbb{R}$. Suppose $\left|2^{-n} \sum_{x \in \mathbb{F}_2^n} f(x)(-1)^{P(x)}\right| \geq \epsilon$. Then $\|f\|_{U_{k+1}} \geq \epsilon$.*

For $k = 1$, informally, this means that if, for some f , the norm $\|f\|_{U_2}$ is small then its Fourier coefficients are small, and therefore f has high nonlinearity. On the other hand,

$$\begin{aligned} \|f\|_{U_2}^4 &= \sum_{x \in \mathbb{F}_2^n} \widehat{f}(x)^4 \\ &\leq \max_{x \in \mathbb{F}_2^n} |\widehat{f}(x)|^2 \sum_{x \in \mathbb{F}_2^n} \widehat{f}(x)^2 \\ &= \max_{x \in \mathbb{F}_2^n} |\widehat{f}(x)|^2 \quad (\text{applying Parseval identity}) \\ &= (1 - 2^{1-n} nl(f))^2 \quad (\text{using (18)}). \end{aligned} \quad (19)$$

Equation (19) tells us that if a Boolean function has high nonlinearity then its U_2 norm is small, and if U_2 norm is large, then the nonlinearity is small.

The second-order nonlinearity of a Boolean function is the minimum of the distances of that function from the quadratic Boolean function (i.e., the Boolean functions with algebraic degree at most 2). By Theorem 1, for all polynomials $P : \mathbb{F}_2^n \rightarrow \mathbb{F}_2$ of degree at most 2, if $\|f\|_{U_3} < \epsilon$, then $\left|2^{-n} \sum_{x \in \mathbb{F}_2^n} f(x)(-1)^{P(x)}\right| < \epsilon$. Therefore, the second-order nonlinearity of such functions ought to be high. Green and Tao [7] proved that just as for U_2 , if a Boolean function has high second-order nonlinearity, then its U_3 norm is low. They also proved that such an implication is not valid for U_k norms for $k \geq 4$.

The discussion in this section points to the fact that Gowers U_2 and U_3 norms have the promise of being good indicators for the first and second-order nonlinearities of a Boolean function. Determination of these nonlinearities have complexities that scale exponentially with the number of input variables of Boolean functions. In the following section, we propose a quantum algorithm to estimate an upper bound of the Gowers U_2 norm that is probabilistic in nature, the probability converges as $e^{-2m^2 t^2}$ where m is the number of trials and t is a positive error margin.

1.4 Quantum information: definitions and notation

In this section, we will introduce some notation that we use throughout the paper. For an introduction to quantum computing, we refer to Rieffel and Polak [12], or Nielsen and Chuang [11].

A *qubit* or *qu-bit* can be described by a vector $|\psi\rangle = (a, b)^T \in \mathbb{C}^2$, where ‘ T ’ indicates the transpose, $|a|^2$ is the probability of observing the value 0 when we measure the qubit, and $|b|^2$ is the probability of observing 1. If both a and b are nonzero, the qubit has both the value 0 and 1 at the same time, and we call this a *superposition*. Once we have measured the qubit, however, the superposition collapses, and we are left with a classical state that is either 0 or 1 with certainty. A state of n qubits is represented by a normalized complex vector with 2^n elements. We define $\langle\psi|$ as the conjugate transpose of $|\psi\rangle$. This notation is known as the bra-ket notation. We denote the standard basis (column) vectors as $|0\rangle$ and $|1\rangle$, and then $|\psi\rangle = (a, b)^T = a|0\rangle + b|1\rangle$.

In the following, we will use the conventional notation $|a\rangle|b\rangle := |a\rangle \otimes |b\rangle$, or $|ab\rangle := |a\rangle \otimes |b\rangle$. A state on n qubits can be represented as a \mathbb{C} -linear combination of the vectors of the standard basis $|\psi\rangle = \sum_{x \in \mathbb{F}_2^n} a_x |x\rangle$, where $a_x \in \mathbb{C}$, $\forall x \in \mathbb{F}_2^n$, and $\sum_{x \in \mathbb{F}_2^n} |a_x|^2 = 1$. Let $|0_n\rangle$ be the quantum state associated with the zero vector in \mathbb{F}_2^n . Let $|+\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}$ and $|-\rangle = \frac{|0\rangle - |1\rangle}{\sqrt{2}}$. For any $x \in \mathbb{F}_2^n$ and $\epsilon \in \mathbb{F}_2$, the *bit oracle implementation* U_F of F is

$$|\epsilon\rangle |x\rangle \xrightarrow{U_F} |\epsilon + F(x)\rangle |x\rangle. \quad (20)$$

Here, n -qubits in $|x\rangle$ specify the input state that changes the target qubit $|\epsilon\rangle$ according to the value of the Boolean function $F(x)$.

If the first qubit is $|-\rangle$, then $|-\rangle |x\rangle \xrightarrow{U_F} (-1)^{F(x)} |-\rangle |x\rangle$. We write $|x\rangle \xrightarrow{U_F} (-1)^{F(x)} |x\rangle$ with the understanding that there is an additional target qubit in the $|-\rangle$ state that remains unchanged and refer to this as the *phase oracle implementation* of the function F . Suppose that a computational basis state is of the form $|x^{(1)}\|x^{(2)}\|\dots\|x^{(m)}\rangle$ where for any two vectors $x \in \mathbb{F}_2^r$ and $y \in \mathbb{F}_2^s$, the concatenation $x\|y = (x_1, \dots, x_r, y_1, \dots, y_s)$ is a vector in \mathbb{F}_2^{r+s} . It is reasonable to write $|x^{(1)}\|x^{(2)}\|\dots\|x^{(m)}\rangle = |x^{(1)}\rangle |x^{(2)}\rangle \dots |x^{(m)}\rangle$. The vector $x^{(i)} \in \mathbb{F}_2^{r_i}$, for some $r_i \in \mathbb{Z}^+$ is said to be the content of the i th register. If $x^{(i)}, x^{(j)} \in \mathbb{F}_2^{r_i}$, for some $r \in \mathbb{Z}^+$, we define $MCNOT_i^j$ as

$$|x^{(1)}\rangle \dots |x^{(i)}\rangle \dots |x^{(j)}\rangle \dots |x^{(m)}\rangle \xrightarrow{MCNOT_i^j} |x^{(1)}\rangle \dots |x^{(i)} + x^{(j)}\rangle \dots |x^{(j)}\rangle \dots |x^{(m)}\rangle.$$

We can realize the transformation induced by $MCNOT_i^j$ by using an appropriate number of conventional *CNOT* gates.

Let $I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ be the 2×2 identity matrix, and $H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$ be the 2×2 Hadamard matrix. The tensor product of matrices is denoted by \otimes . The matrix H_n is recursively defined as:

$$\begin{aligned} H_2 &= H \otimes H, \\ H_n &= H_{n-1} \otimes H_{n-1}, \text{ for all } n \geq 3. \end{aligned} \quad (21)$$

Note that, for $x \in \mathbb{F}_2^n$, $H_n |x\rangle = 2^{-\frac{n}{2}} \sum_{x' \in \mathbb{F}_2^n} (-1)^{x \cdot x'} |x'\rangle$.

In the next section we propose an algorithm to compute Gowers U_2 norm of Boolean functions. Our approach resembles that employed by Bera, Maitra, and Tharmrashantha [1] to estimate the autocorrelation spectra of Boolean functions.

2 A quantum algorithm to estimate Gowers uniformity norms

We prepare the quantum state $2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} |x\rangle |a\rangle |b\rangle$, and apply the following transformations:

$$2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} |x\rangle |a\rangle |b\rangle$$

$$\begin{aligned}
& \xrightarrow{U_F \otimes I \otimes I} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{F(x)} |x\rangle |a\rangle |b\rangle \\
& \xrightarrow{MCNOT_1^2} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{F(x)} |x+a\rangle |a\rangle |b\rangle \\
& \xrightarrow{U_F \otimes I \otimes I} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{F(x)+F(x+a)} |x+a\rangle |a\rangle |b\rangle \\
& \xrightarrow{MCNOT_1^2} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{F(x)+F(x+a)} |x\rangle |a\rangle |b\rangle \\
& \xrightarrow{MCNOT_1^3} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{F(x)+F(x+a)} |x+b\rangle |a\rangle |b\rangle \\
& \xrightarrow{U_F \otimes I \otimes I} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{F(x)+F(x+a)+F(x+b)} |x+b\rangle |a\rangle |b\rangle \\
& \xrightarrow{MCNOT_1^2} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{F(x)+F(x+a)+F(x+b)} |x+a+b\rangle |a\rangle |b\rangle \\
& \xrightarrow{U_F \otimes I \otimes I} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{\Delta_{a,b} F(x)} |x+a+b\rangle |a\rangle |b\rangle \\
& \xrightarrow{MCNOT_1^2} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{\Delta_{a,b} F(x)} |x+b\rangle |a\rangle |b\rangle \\
& \xrightarrow{MCNOT_1^3} 2^{-\frac{3n}{2}} \sum_{b \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{x \in \mathbb{F}_2^n} (-1)^{\Delta_{a,b} F(x)} |x\rangle |a\rangle |b\rangle \\
& \xrightarrow{H_n^{\otimes 3}} \sum_{a', b', x' \in \mathbb{F}_2^n} (2^{-3n} \sum_{x, a, b \in \mathbb{F}_2^n} (-1)^{\Delta_{a,b} F(x) + a \cdot a' + b \cdot b' + x \cdot x'}) |x'\rangle |a'\rangle |b'\rangle.
\end{aligned} \tag{22}$$

It should be remembered that in addition to the three n -qubit registers used, there is an additional target qubit that is in the $|-\rangle$ state and remains unchanged throughout, owing to this fact the qubit has been dropped from the sequence of operations, for brevity. The above sequence of operations excluding the last $H_n^{\otimes 3}$ is summarized as

$$2^{-\frac{3n}{2}} \sum_{a, b, x \in \mathbb{F}_2^n} |x, a, b\rangle \xrightarrow{\mathfrak{D}_F} 2^{-\frac{3n}{2}} \sum_{a, b, x \in \mathbb{F}_2^n} (-1)^{\Delta_{a,b} F(x)} |x, a, b\rangle. \tag{23}$$

The probability that a measurement of the resultant state yields the result $|0_n\rangle |0_n\rangle |0_n\rangle$ is given by

$$\Pr[x' = a' = b' = 0_n] = \left(2^{-3n} \sum_{x, a, b \in \mathbb{F}_2^n} (-1)^{\Delta_{a,b} F(x)} \right)^2$$

and since $f(x) = (-1)^{F(x)}$, using (10)

$$\Pr[x' = a' = b' = 0_n] = (\|f\|_{U_2}^4)^2 = \|f\|_{U_2}^8. \tag{24}$$

2.1 Estimation of the upper bound of Gowers U_2 norm

Let the final output state at the end of the transformation described in (22) be

$$|\Psi\rangle = \sum_{a', b', x' \in \mathbb{F}_2^n} C(x', a', b') |x' a' b'\rangle. \tag{25}$$

The probability amplitude of the state $|x' a' b'\rangle$ is

$$C(x', a', b') = 2^{-3n} \sum_{x, a, b \in \mathbb{F}_2^n} (-1)^{\Delta_{a,b} F(x) + a \cdot a' + b \cdot b' + x \cdot x'}. \tag{26}$$

The outcome of a measurement, with respect to the computational basis, performed on the output state is a $3n$ bit string $(x' \| a' \| b')$, where $x', a', b' \in \mathbb{F}_2^n$, and the probability of measuring said string is $|C(x', a', b')|^2$. Therefore, the eighth power of the Gowers U_2 norm is given by $|C(0_n, 0_n, 0_n)|^2$. The next theorem outlines a strategy to determine a probabilistic upper bound of the Gowers U_2 norm.

Theorem 2. *We assume that the measurements are done with respect to the computational basis. Suppose that Y is a random variable defined on the set of all possible measurement outcomes on the quantum state $H_n^{\otimes 3} \circ \mathcal{D}_F \left(2^{-\frac{3n}{2}} \sum_{a,b,x \in \mathbb{F}_2^n} |x\rangle |a\rangle |b\rangle \right)$ as*

$$Y(x', a', b') = 2^{-3n} (x' \| a' \| b')_{10},$$

where $(x' \| a' \| b')_{10}$ is the decimal value of the concatenated $3n$ bit string. Following the usual convention, we write Y instead of $Y(x', a', b')$. Suppose that (Y_1, \dots, Y_m) be a random sample such that each Y_i is independent and identically distributed as Y . Let $\bar{Y} = \frac{1}{m} \sum_{i \in [m]} Y_i$. Then

$$\Pr \left[\|f\|_{U_2} \leq (1+t-\bar{Y})^{1/2^3} \right] \geq 1 - \exp(-2m^2 t^2),$$

for any positive real number t .

Proof. Let the expectation of Y , $E[Y] = \mu$. Let $\Pr[Y = 0] = \|f\|_{U_2}^8 = p$, so $\Pr[Y \neq 0] = 1 - p$. The range of the random variable Y has 2^{3n} distinct values in the interval $[0, 1]$ including 0. Let us denote them by $y_0, y_1, \dots, y_{2^{3n}-1}$, where $y_j = 2^{-3n} j$. The expectation of Y is

$$\begin{aligned} \mu = E[Y] &= y_0 \Pr[Y = 0] + y_1 \Pr[Y = y_1] + \dots + y_{2^{3n}-1} \Pr[Y = y_{2^{3n}-1}] \\ &= y_1 \Pr[Y = y_1] + y_2 \Pr[Y = y_2] + \dots + y_{2^{3n}-1} \Pr[Y = y_{2^{3n}-1}] \\ &< \Pr[Y = y_1] + \Pr[Y = y_2] + \dots + \Pr[Y = y_{2^{3n}-1}] \\ &= \Pr[Y \neq 0] = 1 - p. \end{aligned} \tag{27}$$

Suppose that (Y_1, \dots, Y_m) be a random sample of size m . The sample mean is $\bar{Y} = \frac{1}{m} \sum_{i \in [m]} Y_i$. By the Hoeffding's inequality [9]

$$\Pr \left[\bar{Y} \geq \mu + t \right] \leq \exp(-2m^2 t^2). \tag{28}$$

where t is any positive real number. Using equations (27) and (28),

$$\begin{aligned} \Pr \left[1 - p > \mu \geq \bar{Y} - t \right] &\geq 1 - \exp(-2m^2 t^2), \\ \text{which implies } \Pr \left[p < 1 + t - \bar{Y} \right] &\geq 1 - \exp(-2m^2 t^2), \\ \text{that is, } \Pr \left[\|f\|_{U_2} < (1+t-\bar{Y})^{1/2^3} \right] &\geq 1 - \exp(-2m^2 t^2). \end{aligned} \tag{29}$$

The theorem is shown. \square

The last line of (29) tells us that if we measure m times and compute \bar{Y} , then the probability that $\|f\|_{U_2}$ is bounded above by $(1+t-\bar{Y})^{1/2^3}$ is $1 - \exp(-2m^2 t^2)$. Therefore with an appropriate choice of m and t we can estimate an upper bound of the Gowers U_2 norm of f with a very high probability.

2.2 Linear approximation employing the Gowers U_2 norm

We start by defining distance between Boolean functions in terms of probabilities.

Definition 3. For any two functions $f, g \in \mathfrak{B}_n$,

$$\text{dist}(f, g) = \Pr_{\mathbf{x} \sim \mathbb{F}_2^n} [f(\mathbf{x}) \neq g(\mathbf{x})] = \frac{d_H(f, g)}{2^n}$$

where \mathbf{x} is a random variable uniformly distributed over \mathbb{F}_2^n .

The function f is said to be ϵ -close to g if $\text{dist}(f, g) \leq \epsilon$, and ϵ -far from g if $\text{dist}(f, g) > \epsilon$. We will now design an algorithm to determine whether a function is linear or ϵ -far from linear; we refer to Hillery and Anderson [8, Section III] for a discussion on such tests.

Algorithm 1 Linearity checking with the Gowers U_2 norm.

Input: Quantum implementation of $f \in \mathfrak{B}_n$.

- 1: Initial state: $2^{-\frac{3n}{2}} \sum_{a, b, x \in \mathbb{F}_2^n} |x, a, b\rangle$.
- 2: Perform the following sequence of transformations:

$$\begin{aligned} & 2^{-\frac{3n}{2}} \sum_{a, b, x \in \mathbb{F}_2^n} |x, a, b\rangle \\ & \xrightarrow{\mathcal{D}_F} 2^{-\frac{3n}{2}} \sum_{a, b, x \in \mathbb{F}_2^n} (-1)^{\Delta_{a, b} F(x)} |x, a, b\rangle \\ & \xrightarrow{H_n^{\otimes 3}} \sum_{a', b', x' \in \mathbb{F}_2^n} (2^{-3n} \sum_{x, a, b \in \mathbb{F}_2^n} (-1)^{\Delta_{a, b} F(x) + a \cdot a' + b \cdot b' + x \cdot x'}) |x', a', b'\rangle. \end{aligned}$$

- 3: Measure the output state with respect to the computational basis.
 - 4: If the measurement result is $|0_n, 0_n, 0_n\rangle$ then “ACCEPT” (the function is linear).
 - 5: Else “REJECT”.
-

Theorem 4. If f is a linear function then the output is “ACCEPT” with probability 1. If f is ϵ -far from linear functions, then probability of “REJECT” is greater than $1 - \exp(-8\epsilon)$.

Proof. If f is a linear function, then the output is “ACCEPT” with certainty. This directly follows from the definition of Gowers U_2 norm. If f is ϵ -far from linear functions, then

$$\|f\|_{U_2}^2 \leq \left(1 - 2\frac{nl(f)}{2^n}\right)^4 \leq (1 - 2\epsilon)^4.$$

This means that the probability that the output is “ACCEPT” is less than or equal to $(1 - 2\epsilon)^4$; therefore the probability of “REJECT” is greater than $1 - (1 - 2\epsilon)^4 \approx 1 - \exp(-8\epsilon)$. \square

The result concerning the BLR test is:

Theorem 5. [10, Theorem 1.30] Suppose the BLR Test accepts $F : \mathbb{F}_2^n \rightarrow \mathbb{F}_2$ with probability $1 - \epsilon$. Then f is ϵ -close to being linear.

By the BLR test, if a function is ϵ -far from the linear functions, and it is promised that we have such functions and linear functions only, then given a function from the latter class, the probability that the algorithm will REJECT is greater than ϵ .

Remark 6. The algorithm presented here has been implemented in the IBM quantum machine (<https://www.ibm.com/quantum-computing/>) for some small examples and has given the expected output of probabilities.

3 Appendix: generalization to higher Gowers norms

The same technique can be used for other Gower's norms. For instance, we can apply the unitary transformation $H_n^{\otimes 4} \circ \mathfrak{D}_F^3$ to the state $2^{-2n} \sum_{x \in \mathbb{F}_2^n} \sum_{a \in \mathbb{F}_2^n} \sum_{b \in \mathbb{F}_2^n} \sum_{c \in \mathbb{F}_2^n} |x\rangle |a\rangle |b\rangle |c\rangle$, where, with notation $M_i^j = MCNOT_i^j$ and $U_F^3 = U_F \otimes I \otimes I \otimes I$,

$$\mathfrak{D}_F^3 = M_1^3 \circ U_F^3 \circ M_1^3 \circ M_1^4 \circ U_F^3 \circ M_1^3 \circ U_F^3 \circ M_1^2 \circ U_F^3 \circ M_1^4 \circ U_F^3 \circ M_1^3 \circ U_F^3 \circ M_1^2 \circ U_F^3.$$

We obtain thus the state $\sum_{a', b', b', x' \in \mathbb{F}_2^n} 2^{-4n} \sum_{a, b, c, x \in \mathbb{F}_2^n} (-1)^{\Delta_{a, b, c} F(x)} |x, a, b, c\rangle$. Then, $Pr[x' = a' = b' = c' = 0_n] = \left(2^{-4n} \sum_{a, b, c, x \in \mathbb{F}_2^n} (-1)^{\Delta_{a, b, c} F(x)}\right)^2$, and, using (11), $Pr[x' = a' = b' = c' = 0_n] = \left(\|f\|_{U_3}^8\right)^2 = \|f\|_{U_3}^{16}$.

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