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# The Use of Agent-Based Modeling and Data Farming for Planning Systems of Systems Tests in Joint Environments

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76th MORSS June 2008

<u>SEED Center Mission</u>: Advance the collaborative development and use of simulation experiments and efficient designs to provide decision makers with timely insights on complex systems and operations

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# Agenda

- SEED Center and Philosophy
- Data Farming
- Support to Joint Test and Evaluation Methodology (JTEM)
- Agent Based Modeling
- "TheTester" ABM

### SEED Center in a nutshell...

Enable rapid and efficient computational experimentation and analysis to be readily available to those informing decision makers

# Harnessing Enabling Technologies

- High-performance computation

New Design of Experiments (DOE)

(Emerging) models

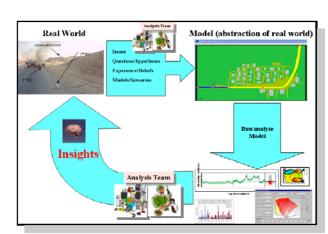
Data mining and visualization

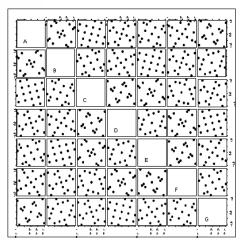




# Revolution in analysis capabilities

- Quick turnaround...
- Address uncertainties
- Robust solutions





# **Resources: SEED Center for Data Farming**

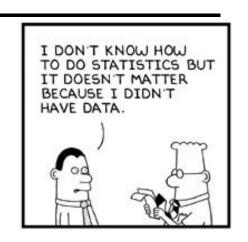
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- lists of student theses (available online)
- spreadsheets & software
- pdf files for several of our publications, publication info for the rest
- links to other resources
- updates

All models are wrong, but some are useful—George Box







# Data Farming: Iterative Loop of Loops

### Data Farming Loop

### Scenario/Model Building Loop

- Iterate model/simulation for experiment definition and analysis to support definition of hypothesis, and areas of interest

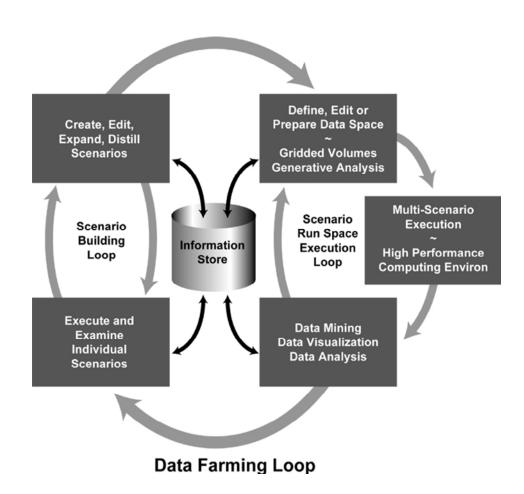
### Possibility Space **Development Loop**

- Iterate model/simulation using highperformance computing to refine analysis, study parameter sensitivity, drill-down into areas of interest, and confirmation or refutation of hypothesis
- Data exploration, mining

### and then

### Adjust-Synthesize (another loop)

 Adjust model/simulation with knowledge/ concepts/intuition from data farming... Repeat



# Support to Joint Test & Evaluation Methodology

- Overall Objective: Determine if analytical techniques employing agent-based models and data farming can be applied to the following areas
  - Helping to select a limited number of test vignettes for accomplishment in an actual L/V/C joint mission environment
  - Determining overall joint mission effectiveness
  - Establishing the relationship between system or system-ofsystem performance and joint mission effectiveness

### **Previous Effort:**

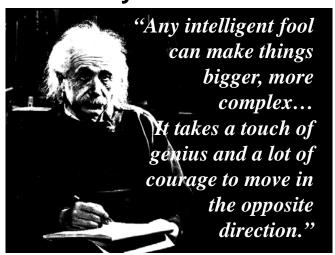
- Tested other agent-based models for applicability
- Ran computational experiments within the SEED Center's Data Farming environment
- Developed custom-made agent-based modeling environment ("TheTester")

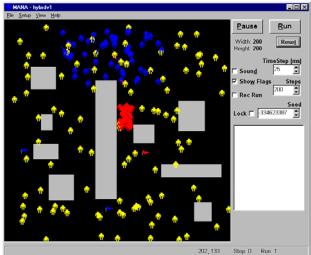
# Agent Based Modeling (ABM)

### What is an ABM?

- Composed of (usually) relatively simple discrete autonomous entities making decisions based on interactions with other agents and their local environment
- Are characteristically intuitive, transparent, transportable, repeatable, and farmable
- Have been useful in studying complex adaptive systems in a number of domains
- Several have been developed specifically for military domain (ISAAC, MANA, Pythagoras, SEAS)

 Scenarios (usually) can be produced in a matter of hours/days vs weeks/months





### "TheTester" ABM

- Motivation: To address some of the limitations encountered using more traditional agent-based models based on reactive agents, while retaining their strengths in farmability, ease of use, and fast run times
- Primary Design Goal: Focus on Systems of Systems testing, initially modeling one aspect (Joint Fires) of the C2 Joint Capability Area (JCA)

### "TheTester": Model structure

- Is written in JAVA, and uses the MASON multi-agent simulation toolkit for its underlying simulation infrastructure www.cs.gmu.edu/~eclab/projects/mason/
- Time-stepped
- Continuous 3D space, flat terrain
- Uses XML for input working on an Automated Scenario Generator
- Selectable MOEs (CSV output)
- 3D visualization with probes

# "TheTester": Other Design Goals

### Composable

allows users to build up or construct agents using software components specific to the domain

### Extensible

allows users to develop their own software components to extend functionality provided by the basic framework

### Farmable

☐ enhances computational experiments with the model by allowing users to easily vary input parameters associated with the agents

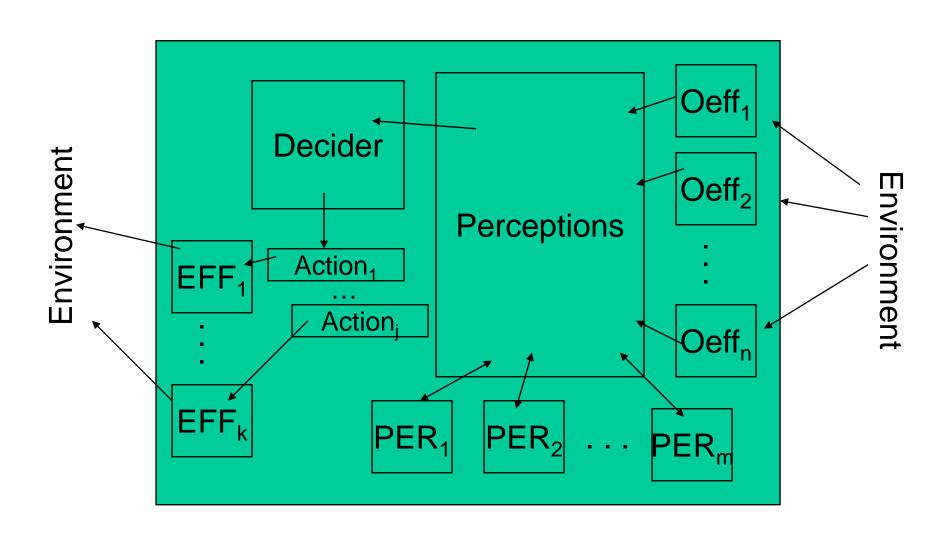
### Fast-running

analyses could be completed within a reasonably short period of time, commensurate with our experience with other agent-based models used for similar purposes

# **Agent Decision Making**

- Each Agent has OODA loop
- "Observe" depends on whether Agent has Effector for sensing
- Orient
  - Process Comm messages
  - Update Perceptions from other Perceivers
- Decide
  - Agent Decision Making is based on Deciders: these are composable object structures that base decisions on Perceptions - SimpleRuleBaseDecider currently implemented. Different agents can have different Deciders. SimpleRuleBaseDecider has a set of Rules that are a conjunction of Clauses (Perception Condition Value), with Actions as consequents
  - E.g., If NewEnemyDeteteced then SendMessageASR
- Act
- Each Agent has a set of Actions that it can accomplish (based) on what Effectors can do)

# "TheTester": Agent structure



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# **Examples (Implemented So Far)**

- Observe-type Effectors
  - CookieCutterSensor
- Perceivers
  - SimpleThreatPerceiver
  - BasicMessageProcessor
  - MessageSentTracker
  - MemoryContactFilter
- Other Effector types
  - MoveAlongWaypoints
  - AgentCarrier / AgentCarried
  - BasicMessageSender
  - SingleMissionEffector
  - MultipleMissionEffector
  - FiresMissionTasker
  - BasicIndirectWeapon

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# **Examples (cont.)**

- Perceptions (concepts an agent "knows about")
  - AgentPercept
  - LocationPercept
  - MessagePercept
  - Observation
  - RestrictedOperatingZone
  - SimplePercept
  - TargetPercept
- Deciders (used to choose an action, based on the current state of perceptions)
  - SimpleMoveDecider
  - RuleBaseDecider

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# Comm modeling

- CommLinks
  - Explicit communication links specified in input file
  - Reliability for the link
  - Range for the link
- MessageData for each message class
  - messageClass for each message
  - probUnderstood
  - inProcessTime, inProcessTimeOffset
  - outProcessTime, outProcessTimeOffset
  - probability distribution used for times
- MessageHandlers for inserting and extracting content
- Implemented Message Handlers
  - CallForFireMessageHandler
  - FiresMissionMessageHandler
  - GoToRequestMessageHandler
  - ThreatLocationMessageHandler

### **FY07 Scenario Comm Matrix**

_	RSTA	BNFSE	BDEFSE	CAOC/JA	<b>OKS</b> OC	AWACS	FIRE BN	FBEOS/FS	<b>DE</b> TTARS	JTAC	CAS_AIRCI	ROSALETVI/
RSTA		CFF										
BNFSE			RELAY-CFF									
BDEFSE					ACMREQ1-COP' ACMREQ2; RFZ		FIREMISS	SION				
222.02					ACMREQ1-APPR		I III III I					
CAOC/JAOC			RELAY-ACMF APPROVAL		COPY; ACMREC APPROVAL	COORD			ACMREQ2 APPROVA			
						ASR-						
ASOC			ACMREQ2- COORD			APPROVAL TASKING				ASR-APPRO TASKING		
				ACMREQ1-								
AWACS				APPROVAL							CASMISSIO	N
								RELAY-				
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# Short Term Future Work on "TheTester" Will Include ...

- Expert System / Fuzzy Logic Decider (JESS, Fuzzy JESS)
- Move to a Discrete Event Framework
- GUI / Automated Scenario Generator

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# **QUESTIONS?**

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