

1
2
3
4
5
6
7

Beyond the Virtual Intracranial Stenting Challenge 2007: non-Newtonian and flow pulsatility effects

4 Marco Cavazzuti^a, Mark Atherton^{*,b}, Michael Collins^b, Giovanni Barozzi^a

5 ^a*Dipartimento di Ingegneria Meccanica e Civile, Università degli Studi*
6 *di Modena e Reggio Emilia, via Vignolese 905, 41125 Modena, Italy*

7 ^b*School of Engineering and Design, Brunel University, West London, UB8 3PH, UK*

8 **Abstract**

9 The Virtual Intracranial Stenting Challenge 2007 (visc'07) is becoming a
10 standard test case in computational minimally-invasive cerebrovascular in-
11 tervention. Following views expressed in the literature and consistent with
12 the recommendations of a report, the effects of non-Newtonian viscosity and
13 pulsatile flow are reported. Three models of stented cerebral aneurysms,
14 originating from visc'07 are meshed and the flow characteristics simulated
15 using commercial Computational Fluid Dynamics (CFD) software. We con-
16 clude that non-Newtonian and pulsatile effects are important to include in
17 order to discriminate more effectively between stent designs.

18 *Key words:* cerebral aneurysm, visc'07, stent

19 **1. Introduction**

20 The work presented here uses benchmark models from the Virtual In-
21 tracranial Stenting Challenge (VISC 2007), an international initiative to as-
22 sess the effectiveness of state-of-the-art numerical modelling of blood flow in
23 stented cerebral aneurysms. The results submitted to visc'07 by six simu-
24 lation teams (Radaelli *et al.* 2008) highlight the desirability of considering
25 the effects of *non-Newtonian viscosity* and *flow pulsatility* in future work for
26 purposes of clinical relevance, both of which were included in our studies
27 briefly reported here.

*corresponding author

Email addresses: mark.atherton@brunel.ac.uk (Mark Atherton), +44(0)1895
274000 (Mark Atherton)

Preprint submitted to Elsevier

May 4, 2010

28 **2. Methods**

29 The Fluent code was used for the simulations. The following boundary
30 conditions were set: uniform velocity with $2.36 \frac{\text{g}}{\text{s}}$ mass flow rate at the inlet,
31 zero gauge pressure on the outlet and no slip walls, as set by VISC'07.

32 A steady-state laminar solver was used with second order upwind momen-
33 tum discretization and SIMPLE pressure-velocity coupling. The fluid flowing
34 in the artery was initially defined as water (as requested by VISC'07), and
35 later it was changed to blood with density (ρ) $1060 \frac{\text{kg}}{\text{m}^3}$ and viscosity (μ) 4 cP.

36 Since a Newtonian model is prone to underestimate the WSS in a CFD
37 analysis at lower velocity gradients (Chen *et al.* 2006, Lee and Steinman
38 2006, Gijzen *et al.* 1999a,b), it was decided to investigate a non-Newtonian
39 formulation as well. The Fluent power-law option for dynamic viscosity (Flu-
40 ent 2006) was used, as no one model is universally accepted and this is a valid
41 option at lower shear rates (Johnson *et al.* 2004, Shibeshi and Collins 2005):

$$\mu_{min} < \mu = k \cdot \dot{\gamma}^{n-1} < \mu_{max} \quad (1)$$

42 where μ is the dynamic viscosity in $\frac{\text{kg}}{\text{m s}}$, k is the consistency index whose
43 value is $0.0161 \frac{\text{kg s}^{n-2}}{\text{m}}$, n the power-law index is 0.63, and $\dot{\gamma}$ is the shear rate
44 in s^{-1} (Owen *et al.* 2005). μ_{min} and μ_{max} are lower and upper limits of the
45 power-law function and were set to $10^{-5} \frac{\text{kg}}{\text{m s}}$ and $1 \frac{\text{kg}}{\text{m s}}$ respectively.

46 In order to address the inclusion of pulsatility (c.f. Radaelli *et al.* 2008
47 and others), unsteady simulations were configured for the unstented and the
48 three stented cases. The inlet waveform for a basilar artery (Ford *et al.* 2008)
49 was slightly modified as follows: the mean flow rate was set to the steady-
50 state value of $2.36 \frac{\text{g}}{\text{s}}$ as specified by VISC'07 and implemented in Fluent as
51 a uniform velocity profile of $0.179 \frac{\text{m}}{\text{s}}$; the pulse rate was set to 70 beats
52 per minute; and the waveform was slightly smoothed in order to reduce the
53 number of time steps needed to represent the whole cycle.

54 A standard grid independency procedure on the stented aneurysm models
55 was carried out, and a suitable meshing of 2.30 million elements meshes was
56 selected.

57 **3. Results**

58 For brevity, we focus the results on two regions of interest. (i) The
59 aneurysm Neck Section, which corresponds to the minimum section area
60 of the aneurysm and is comparable with that of cut-plane P2 in Radaelli

61 *et al.* 2008. (ii) Segment x, the first $\frac{1}{3}$ aneurysm volume immediately after
62 the Neck Section. Results are given in terms of mass flow rate and average
63 Wall Shear Stress (wss).

64 *3.1. Newtonian vs. non-Newtonian*

65 Referring to the table of results for steady-state (Table 1), the non-
66 Newtonian case significantly increases dynamic viscosity and slightly modifies
67 mass flow rate in the lower aneurysm area resulting in a much higher average
68 WSS. The Newtonian models overestimate mass flow rate by about 3% for
69 Stent 1 and Stent 2 and underestimate by just under 2% for Stent 3, whereas
70 the average WSS in the Newtonian models is consistently underestimated by
71 15-20%.

Table 1: *Comparison between unstented and stented cases for steady-state flow. Percentages refer to difference between stented case and unstented artery.*

Case	Mass Flow (g/s) through Neck Section	Average Dynamic Viscosity (cP = mPa s) in Segment x	Average WSS (Pa) in Segment x
Unstented artery non-Newtonian	0.3809	7.142	2.057
Stent 1 Newtonian	0.3391 -11.0 %	4.000 -44.0 %	1.091 -46.9 %
Stent 2 Newtonian	0.3427 -10.0 %	4.000 -44.0 %	1.054 -48.8 %
Stent 3 Newtonian	0.2738 -28.1 %	4.000 -44.0 %	0.960 -53.3%
Stent 1 non-Newtonian	0.3268 -14.2 %	8.003 +12.1 %	1.296 -37.0 %
Stent 2 non-Newtonian	0.3320 -12.8 %	7.938 +11.1 %	1.282 -37.6 %
Stent 3 non-Newtonian	0.2785 -26.9 %	8.555 +19.8 %	1.195 -41.9 %

72 The results do not contradict Gijzen *et al.* (1999a,b), who, using both ex-
73 periments and simulations, essentially state the importance of non-Newtonian
74 (shear-thinning) blood modelling since it alters significantly the velocity pro-
75 files. As a non-Newtonian model produces higher fluid viscosities in the
76 aneurysm region (where the shear rate is low) compared to the Newtonian

77 model, this implies that the fluid tends to reduce its speed much more quickly
 78 inside the aneurysm, and hence the non-Newtonian model produces a smaller
 79 mass flow rate. Also, the lower velocity gradient promotes a lower WSS while
 80 a higher viscosity promotes a higher WSS.

81 In the lower aneurysm, the effect of the increased viscosity is domi-
 82 nant and the Newtonian model significantly underestimates the average WSS.
 83 Overall, it seems that the non-Newtonian hypothesis redistributes the veloc-
 84 ity profiles and the WSS in a more uniform and smooth way and thus peaks
 85 are smoothed out (Figure 1).

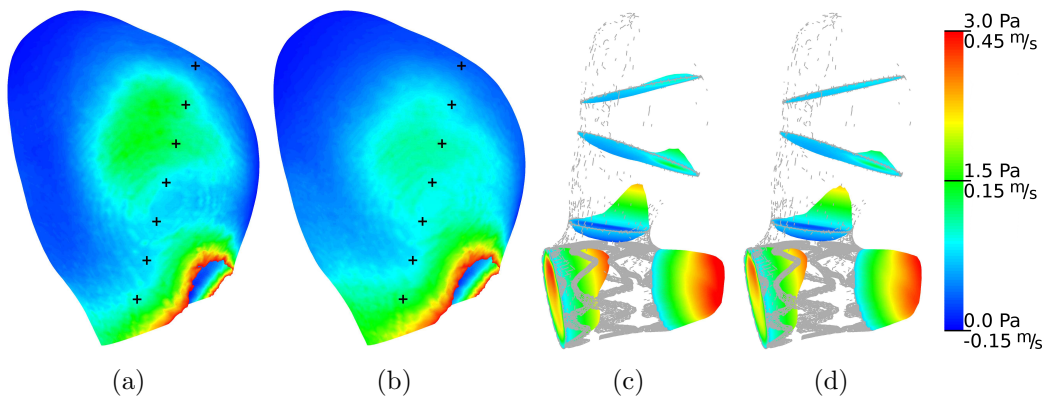


Figure 1: WSS and velocity profiles in aneurysm region for stent 3 steady simulation: Newtonian versus non-Newtonian: (a) WSS, Newtonian case; (b) WSS, non-Newtonian case; (c) velocity profiles, Newtonian case; (d) velocity profiles, non-Newtonian case

86 3.2. Pulsatile flow

87 In Figure 2 the mass flow rate entering the aneurysm (i.e. crossing the
 88 Neck Section) is shown. The pulse cycle in the main artery is also shown
 89 scaled to $\frac{1}{5}$ -th of its amplitude.

90 The mass flow rate entering the aneurysm in the unstented case at time
 91 0 s is equal to $0.3488 \frac{\text{g}}{\text{s}}$ (15 % of the mass flow rate in the main artery). This
 92 ratio remains in the range from 10 % to 20 % for all the cases investigated
 93 and for most of the pulse cycle, except when the mass flow rate in the artery
 94 drops to its minimum.

95 The presence of the stent reduces the mass flow rate in the aneurysm
 96 region and also promotes small changes in the phase between the mass flow
 97 rate in the main artery and in the aneurysm. In fact, the main pulse cycle is

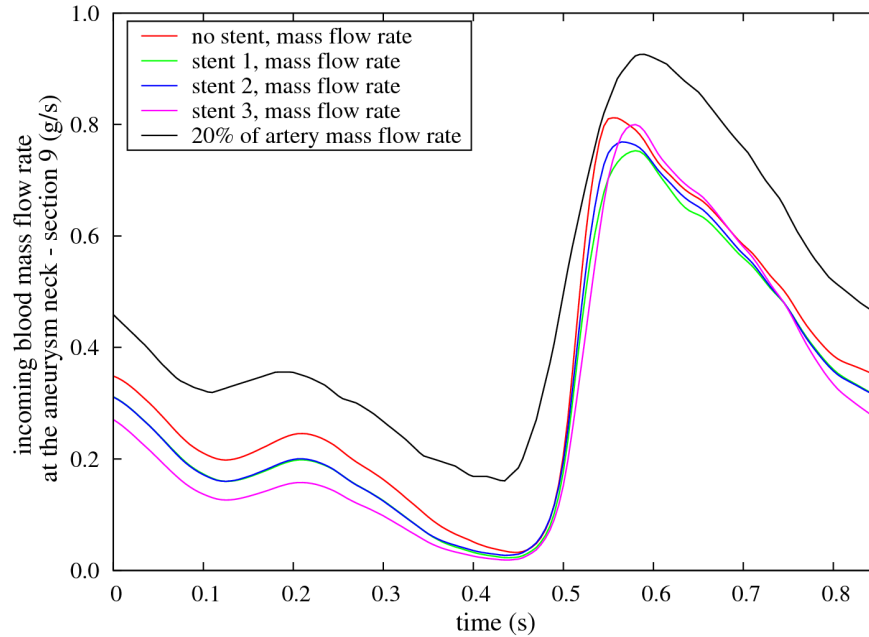


Figure 2: *Mass flow through Section 9*

98 reflected in the aneurysm mass flow rate with a minimum phase delay from
 99 0 to 0.5s. However, the maximum peak in the aneurysm mass flow rate,
 100 which is found at ≈ 0.57 s for each of the four simulations, anticipates the
 101 corresponding peak in the main artery, which is found at 0.59s. The change
 102 in the phase shift, even if small, together with the change in mass flow ratio
 103 along the cycle suggest the relevance of adopting unsteady simulations for
 104 better accuracy.

105 The third stent is particularly efficient in reducing the mass flow rate
 106 entering the aneurysm, in particular in the first half of the pulse cycle with
 107 reductions ranging from 20% to 50% when compared to the unstented artery.
 108 The third stent also shows better performance, when compared with the other
 109 two stents, for more than 75% of the pulse cycle.

110 3.3. *Evaluating three stents from VISC'07*

111 Considering the non-Newtonian blood model (see Table 1), the mass flow
 112 rates of stent 1 and stent 2 are not so different from each other. Stent 2 has
 113 a higher mass flow rate through the Neck Section ($0.3320 \frac{g}{s}$ equal to a 12.8%
 114 reduction in the mass flow rate compared to the unstented case). Stent 3

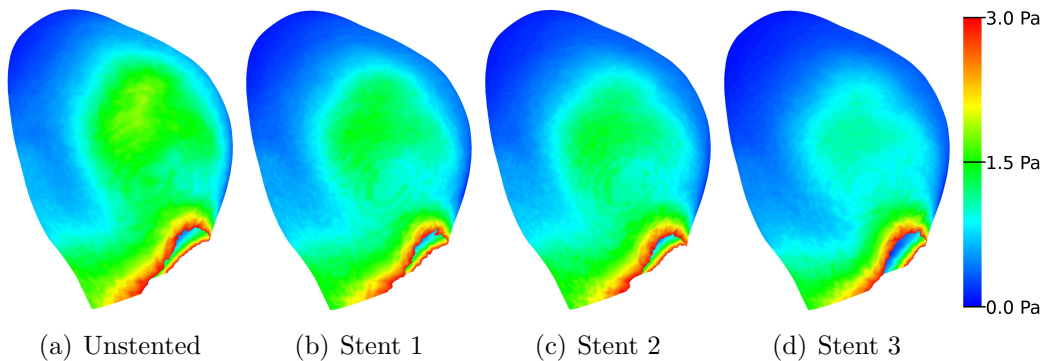


Figure 3: wss on surface of aneurysm for steady non-Newtonian simulations

115 appears to be much more effective in reducing the mass flow rate in the
 116 aneurysm since the blood crossing the Neck Section in this case amounts to
 117 $0.2785 \frac{g}{s}$ (a 26.9 % reduction).

118 From these initial considerations stent 3 is expected to be a better clinical
 119 performer than the other two.

120 Comparing the wss in the unstented case with the three stented models
 121 (Figure 3 and Table 1), the use of a stent appears to be very effective in
 122 reducing the wss.

123 4. Conclusions

124 The inclusion of non-Newtonian and pulsatile effects in the visc'07 mod-
 125 els are shown to be important. Stent 3 emerges as the best design, which is
 126 consistent with the results published in the literature.

127 Conflict of interest statement

128 The authors have no financial or personal relationships with other people
 129 or organisations that could inappropriately influence (bias) their work.

130 Acknowledgements

131 We thank Dr Matthieu De Beule from the Institute Biomedical Technol-
 132 ogy, Ghent University, Belgium for his generous advice on how to implement
 133 the Magics software. Also, our thanks to Dr Peter Flynn, Consultant Radi-
 134 ologist, Victoria Hospital, Belfast Trust, for his helpful comments on clinical
 135 aspects of the paper.

136 **References**

- 137 Chen, J., Lu, X-Y., Wang, W., 2006, Non-Newtonian effects of blood flow
138 on hemodynamics in distal vascular graft anastomoses. *J. Biomech.* 39
139 (11), 1983–1995.
- 140 Fluent 6.3 User Guide, 2006, section 8.4.5.
- 141 Ford, M.D., Niklov, H.N., Milner, J.S., Lownie, S.P., DeMont, E.M., Kalata,
142 W., Loth, F., Holdsworth, D.W., Steinman, D.A., 2008. PIV-measured
143 versus CFD-predicted flow dynamics in anatomically realistic cerebral
144 aneurysm models. *J. Biomech. Eng.* 130 (2), 021015 (9 pages).
- 145 Gijsen, F.J.H., van de Vosse, F.N., Janssen, J.D., 1999a. The influence of the
146 non-Newtonian properties of blood on the flow in larger arteries: steady
147 flow in a carotid bifurcation model. *J. Biomech.* 32 (6), 601–608.
- 148 Gijsen, F.J.H., Allanic, E., van de Vosse, F.N., Janssen, J.D., 1999b. The
149 influence of the non-Newtonian properties of blood on the flow in larger
150 arteries: unsteady flow in a 90° curved tube. *J. Biomech.* 32 (6), 705–
151 713.
- 152 Johnson, B.M., Johnson, P.R., Corney, S., Kilpatrick, D., 2004. Non-
153 Newtonian blood flow in human right coronary arteries: steady state
154 simulations. *J. Biomech.* 37 (5), 709–713.
- 155 Lee, S.-W., Steinman, D.A., 2006. On the relative importance of rheology
156 for image-based CFD models of the carotid bifurcation. *J. Biomech.* 39
157 (1), S283.
- 158 Owen, I., Gray, J., Escudier, M., Poole, R., 2005. The importance of the non-
159 Newtonian characteristics of blood in flow modelling studies. Abstracts
160 of Second Physiological Flow Network meeting, University of Edinburgh,
161 26-27 September 2005.
- 162 Radaelli, A.G., Augsburger, L., Cebal, J.R., Ohta, M., Rufenacht, D.A.,
163 Balossino, R., Benndorf, G., Hose, D.R., Marzo, A., Metcalfe, R.,
164 Mortier, P., Mut, F., Raymond, P., Soggi, L., Verheghe, B., Frangi,
165 A.F., 2008. Reproducibility of haemodynamical simulations in a subject-
166 specific stented aneurysm model – A report on the Virtual Intracranial
167 Stenting Challenge 2007. *J. Biomech.* 41 (10), 2069–2081.

- 168 Shibeshi, S.S., Collins, W.E., 2005. The Rheology of Blood Flow in a
169 Branched Arterial System. *Applied Rheology* 15 (6), 398–405.
- 170 VISC 2007 The 1st Virtual Intracranial Stenting Challenge
171 <http://www.cilab.upf.edu/visc06> (accessed 29 January 2009)