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Poor encoding of position by contrast-defined motion

Harriet A. Allen^{a,*}, Tim Ledgeway^b, Robert F. Hess^a

^a McGill Vision Research Unit, 687 Pine Avenue West, Rm. H4-14, Montreal, Que., Canada H3A 1A1

^b School of Psychology, University of Nottingham, University Park, Nottingham NG7 2RD, UK

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Abstract

Second-order (contrast-defined) motion stimuli lead to poor performance on a number of tasks, including discriminating form from motion and visual search. To investigate this deficiency, we tested the ability of human observers to monitor multiple regions for motion, to code the relative positions of shapes defined by motion, and to simultaneously encode motion direction and location. Performance with shapes from contrast-defined motion was compared with that obtained from luminance-defined (first-order) stimuli. When the position of coherent motion was uncertain, direction-discrimination thresholds were elevated similarly for both luminance-defined and contrast-defined motion, compared to when the stimulus location was known. The motion of both luminance- and contrast-defined structure can be monitored in multiple visual field locations. Only under conditions that greatly advantaged contrast-defined motion, were observers able to discriminate the positional offset of shapes defined by either type of motion. When shapes from contrast-defined and luminance-defined motion were presented under comparable conditions, the positional accuracy of contrast-defined motion was found to be poorer than its luminance-defined counterpart. These results may explain some, but possibly not all, of the deficits found previously with second-order motion.

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Keywords: Second-order motion; First-order motion; Position; Direction

1. Introduction

Most objects in the visual world are defined by changes in luminance (brightness) over space. The motion of these objects is correlated with a change in luminance over time and space and is often termed ‘first-order’ motion (Cavanagh & Mather, 1989). Objects and motion can also be defined by changes in other visual characteristics, such as changes in texture type, element size or element contrast. These patterns are often termed ‘second-order’ (Cavanagh & Mather, 1989). This paper is concerned with one type of ‘second-order’ moving pattern—moving contrast-defined patterns.

1.1. Failures with second-order motion

There are several tasks that have been found to be difficult, or impossible, with moving contrast-defined patterns. Observers are unable to find a patch of con-

trast-defined structure moving in one direction when it is surrounded by patches of contrast-defined structure moving in another direction. This is the case when the motion areas are abutting, creating a surface (Doshier, Landy, & Sperling, 1989), when they are arranged in a visual search display (Ashida, Seiffert, & Osaka, 2001), when they define three-dimensional shape (Ziegler & Hess, 1999) or form a global optic flow pattern (Allen & Derrington, 2000). These failures might indicate that judging the direction of contrast-defined motion may only be possible at one location in the visual field at a time, for example, because second-order motion perception is mediated primarily by an attention-driven process. Another possibility is that even though multiple estimates of second-order motion can be made across the visual field, individual detectors are poorly labeled for location.

Consistent with the idea that attention is required to discriminate the direction of contrast-defined motion Lu, Liu, and Doshier (2000) found that attention enhances observers’ performance when they discriminate the direction of contrast-defined motion. In their study, observers made successive judgments of the directions of

* Corresponding author. Present address: School of Psychology, University of Birmingham, Edgbaston, Birmingham B15 2TT, UK.
E-mail address: h.a.allen@bham.ac.uk (H.A. Allen).

60 motion in two, spatially distinct, patches. They found
61 that observers were better able to discriminate the
62 direction of contrast-defined motion in the attended
63 patch, compared to the unattended patch. When the
64 patches contained first-order, luminance-defined, mo-
65 tion, there was no difference between observers' per-
66 formance with the two patches. Lu et al. (2000)
67 proposed that attention enhances the processing of
68 contrast-defined motion, however this does not neces-
69 sarily mean that attention is always required for pro-
70 cessing of contrast-defined motion.

71 When attention is distracted, by a distracter task,
72 from contrast-defined motion, performance does not
73 decrease compared to when the same task is performed
74 without a distracter task (Allen & Derrington, 2001; Ho,
75 1998). Furthermore, Allen and Ledgeway (2003) found
76 that although they could replicate the different perfor-
77 mance with attended and unattended contrast-defined
78 motion reported by Lu et al. (2000), the magnitude of
79 the attentional enhancement found depended critically
80 on the speed and duration of the stimuli used. These
81 results taken together suggest that, as with many tasks,
82 attending to the stimulus may help observers when
83 sensitivity to the stimulus is low, but attention is not
84 always a necessary requirement for processing second-
85 order motion.

86 An alternative explanation for observers' poor per-
87 formance on certain tasks with second-order motion is
88 that the position of contrast-defined motion is not en-
89 coded with great precision. If the encoded position of
90 motion is poorly specified, it could compromise the
91 fidelity with which this motion could be used to deter-
92 mine three-dimensional shape based on motion cues
93 alone. In a search display, if the ability to accurately
94 locate the positions of the motion elements is relatively
95 impoverished, it might also be difficult to discriminate
96 an odd motion, since motion direction is typically
97 dependant on position in experiments of this kind (Allen
98 & Derrington, 2000). This study was designed to directly
99 investigate how well the human visual system is able to
100 discriminate the position or location of contrast-defined
101 motion.

102 *1.2. Locating second-order structure*

103 Although no studies have directly investigated the
104 ability of observers to identify the location of second-
105 order motion, there have been some studies addressing
106 the ability of observers to identify the location of both
107 static contrast-defined form and another second-order
108 stimulus: motion-defined form.

109 The mechanism that processes static contrast-defined
110 form seems similar in its ability to localize an object (or
111 border) to the mechanism that processes luminance-de-
112 fined form. Although localization of contrast-modula-
113 tions is worse than for luminance-modulated patterns, it

can be explicable in terms of gross differences in stimulus
complexity or spectral content and is nonetheless in the
hyperacuity range (Voltz & Zanker, 1996). As with first-
order patterns, the perceived location of contrast-mod-
ulations can be predicted by the position of their cent-
roids (Whitaker, McGraw, Pacey, & Barrett, 1996).
Adapting to a static stimulus can influence the perceived
position of a subsequently viewed pattern (McGraw,
Levi, & Whitaker, 1999; Whitaker, McGraw, & Levi,
1997) and this is the case for both luminance-defined
and contrast-defined patterns, suggesting that similar
mechanisms process the two types of pattern. Results
from contrast-defined static form have not always,
however, generalized to moving contrast-defined pat-
terns. Long presentation durations are required to dis-
criminate the direction of some moving contrast-defined
patterns (Derrington, Badcock, & Henning, 1993)
whereas static contrast-modulations are visible at short
durations (Cropper, 1998; Schofield & Georgeson,
2000).

The ability of observers to discriminate the position
of one sort of form from a second-order cue, namely
motion-defined form, has also been studied. Observers
are able to discriminate a Vernier offset between two
motion-defined rectangles with fairly high precision
(Regan, 1986). Vernier acuity for motion-defined form
can match that found with luminance-defined form if
the perceptual quality (e.g. perceived contrast) is mat-
ched between the two types of stimulus (Banton & Levi,
1993). Furthermore, motion-defined forms can be
compared over space with similar accuracy as that for
luminance-defined forms (Kohly & Regan, 2002). Thus
it is clear that there is some mechanism able to identify
the location of motion-defined form.

It is often assumed that all forms of second-order
stimuli are processed equivalently. Form-cue invariant
neurons have been found in the medial-temporal area of
the rhesus monkey (Albright, 1992). These respond to
flicker-defined forms as well as luminance-defined pat-
terns. This cue-invariance does not seem to generalize to
motion-defined forms (Churan & Ilg, 2001). In
behavioural and psychophysical studies performance
with different forms of second-order motion is often
similar, but not identical. Both contrast-defined motion
and flicker-defined motion lead to slow, inefficient
search performance, but response times to flicker-de-
fined motion are much faster than those to contrast-
defined motion (Ashida et al., 2001). Whilst the direc-
tion of moving contrast-modulations can be discrimi-
nated in the periphery (Smith & Ledgeway, 1998) the
direction of moving flicker-defined bars cannot be re-
solved in the periphery (McCarthy, Pantle, & Pinkus,
1994) even though the bars can be detected. At the very
least, different forms of second-order moving patterns
must be processed by different processes at the earliest
stages of processing. This may lead to different proper-

170 ties at later stages of processing. Furthermore, moving
171 contrast-defined patterns combine both motion-defined
172 form and contrast-defined cues, if all second-order mo-
173 tion is processed (eventually) by a common mechanism,
174 one might expect that combining these cues might
175 advantage performance. On the other hand, if contrast-
176 defined form and motion-defined form are resolved at
177 different places in the visual stream performance might
178 be disadvantaged, for example, contrast-defined form
179 might be resolved late in the visual stream, and not be
180 available to the processes that resolve relative motion.

181 It seems that the relative location of an item can be
182 accurately determined when it is defined by luminance,
183 contrast or relative motion. The aim of this study was to
184 investigate if the location of form defined by moving
185 contrast-defined structure can also be discriminated with
186 a similar degree of efficacy.

187 1.3. Spatial uncertainty

188 Since we wanted to investigate location discrimina-
189 tion in relation to direction discrimination, it was nec-
190 essary to also simultaneously measure direction-
191 discrimination performance. This task is essentially a
192 motion-discrimination task under cued and uncued
193 spatial location conditions, similar to those that have
194 been used to investigate mechanisms of attention. This
195 allowed us to also investigate whether the deficits asso-
196 ciated with second-order motion stimuli are due to an
197 inability to simultaneously monitor multiple locations
198 across the visual field.

199 When observers have to find a patch containing
200 contrast-defined motion moving in an inconsistent
201 direction to the global pattern, their performance is
202 consistent with a slow, patch by patch search of the
203 display (Allen & Derrington, 2000). The duration re-
204 quired to find the inconsistent motion depends on the
205 number of possible positions of the motion patch. The
206 same task is quick, easy and not dependent on the
207 number of possible positions with moving luminance-
208 defined patterns. This could indicate that positional
209 uncertainty selectively disadvantages the mechanisms
210 that process contrast-defined motion.

211 When spatial uncertainty is reduced, for example by
212 cueing the location of the stimulus, sensitivity typically
213 improves. This can be attributed to a change in the way
214 a mechanism responds to the stimulus (e.g. Carrasco,
215 Penpeci-Talgar, & Eckstein, 2000), often termed stimu-
216 lus enhancement. The improvement in performance can
217 also be attributed to a change in the number of locations
218 or channels that a hypothesized decision process moni-
219 tors (e.g. Foley & Schwarz, 1998, see this reference for a
220 review).

221 In a different task, where observers had to report the
222 direction of motion in two locations, but without spe-
223 cifically manipulating spatial uncertainty, Lu et al.

(2000) found results consistent with signal enhancement 224
for contrast-defined motion in the attended location, but 225
no such signal enhancement for first-order motion. If 226
manipulating (e.g. reducing) spatial uncertainty also 227
leads to signal enhancement, we would expect a greater 228
effect for second-order motion. Similarly, if manipulat- 229
ing spatial uncertainty changes the number of locations 230
that need to be monitored, and observers are worse at 231
monitoring multiple locations for second-order motion, 232
we would also expect a greater effect of spatial cueing for 233
second-order motion. 234

235 1.4. Three location/position tasks

236 We carried out three experiments. First we measured 236
direction-discrimination performance both with and 237
without spatial uncertainty regarding the position of the 238
motion. Second, we measured observers' ability to dis- 239
criminate whether a motion-defined form was to the left 240
or right of two reference cues. Results from pilot 241
experiments suggested that observers were unable to do 242
this task with many examples of contrast-defined mo- 243
tion. We ran extensive pilot investigations to find a set of 244
parameters for which we were able to estimate relative 245
position thresholds. We collected data for contrast-de- 246
fined stimuli at different modulation depths, with cue 247
squares defined by moving and static dots, with and 248
without a carrier in the background of the stimulus, with 249
different densities of dots, different speeds and different 250
viewing distances. In all cases, position discrimination 251
was poor and in most cases performance was at chance. 252
Finally we measured the ability of observers to dis- 253
criminate the absolute location of form conveyed by 254
luminance-defined and contrast-defined motion stimuli 255
supporting comparable (i.e. relative to threshold) levels 256
of performance. 257

258 2. Methods

259 2.1. Observers

260 There were four observers, all had normal or cor- 260
rected-to-normal vision and were experienced partici- 261
pants in psychophysical tasks. Observer HA was one of 262
the authors, observers JD, NK and PH were naïve to the 263
purposes of the experiment. 264

265 2.2. Apparatus

266 The stimuli were presented on a Sony Trinitron 266
Multiscan 520GS monitor with a mean luminance of 41 267
cd/m² and a frame refresh rate of 100 Hz. One screen 268
pixel extended 0.3 mm horizontally and vertically. Prior 269
to the experiment the relationship between the voltage 270
input to the monitor and the screen luminance was lin- 271

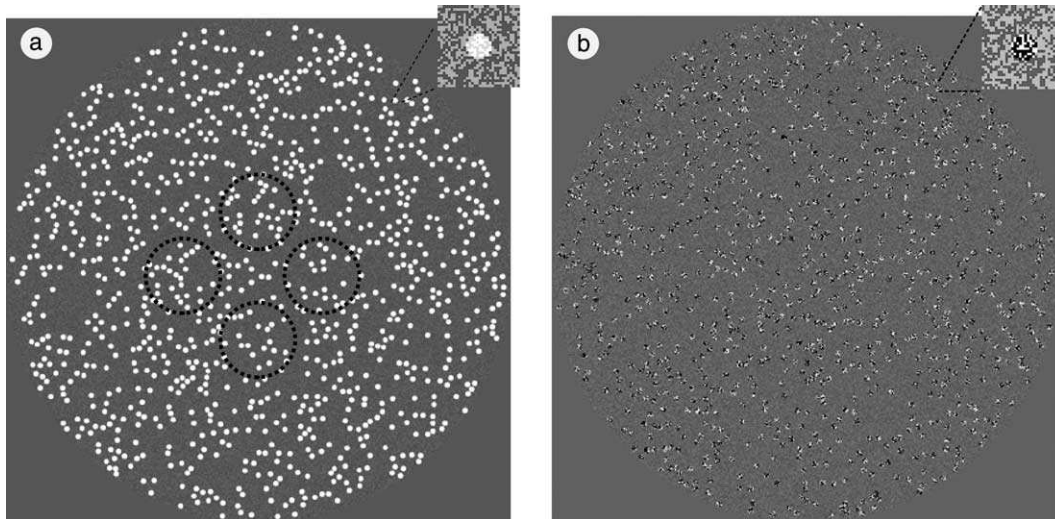


Fig. 1. (a) First-order (luminance-defined) dots as used in Experiment 1 (and also Experiment 3). The dotted circles illustrate the positions of the possible target areas defined by coherent motion (the dotted outlines of the circles were not presented in the actual experiments). (b) Second-order (contrast-defined) dots at maximum modulation depth as used in Experiment 1 (and Experiment 3). Insets to (a) and (b) show a magnified view illustrating the detailed structure of a single dot.

272 earised (gamma corrected) using a *UDT S370* photometer and look-up-tables. The adequacy of the applied
273 gamma correction was also confirmed using a sensitive
274 psychophysical nulling task (Ledgeway & Smith, 1994;
275 Nishida, Ledgeway, & Edwards, 1997).
276

277 3. Experiment 1

278 In experiment 1 the observers judged the direction of
279 motion in a patch containing coherently moving dots
280 that was positioned in one of four locations. Performance
281 was compared when the observers had prior
282 knowledge of the position of the coherent motion and
283 when they did not have this knowledge. This experiment
284 was designed to measure the effect of positional uncertainty
285 on the ability of observers to discriminate the
286 direction of motion and whether observers can monitor
287 multiple locations over the visual field for motion
288 direction.

289 3.1. Stimuli

290 Stimuli were presented within a circular display
291 window (aperture) that subtended 14.8° (diameter) of
292 visual angle at a viewing distance of 97.8 cm. The
293 remainder of the screen was at mean luminance. A
294 central fixation point that appeared immediately before
295 and after each stimulus was presented in order to minimize
296 ocular tracking and maintain stable fixation.

297 The stimuli were moving circular dots presented on a
298 low contrast, two-dimensional (2-d), binary, static noise
299 background (carrier). The background noise had a
300 Michelson contrast of 0.1. Luminance-modulated dots

or contrast-modulated dots (794) were presented on this
noise background. Dots were 10 pixels in diameter. To
generate luminance-modulated dots the mean luminance
of the noise (both 'dark' and 'light' elements) was increased
within the circular region bounding each dot. To generate the
contrast-modulated dots the contrast of the noise elements
was increased within the circular region bounding each dot. Fig. 1
shows example frames of first-order dots at high contrast (1a)
and second-order dots at maximum modulation depth (1b).

The duration of the motion sequence was either 250 or 100 ms. Motion sequences were constructed by displacing the dots by 7 pixels every 50 ms for the long duration stimulus and by 3 pixels every 20 ms for the short duration stimulus, giving the dots in each case a speed of $3^\circ/s$. The direction of motion of each dot was independently determined on each displacement depending on whether that dot belonged to the population of dots that were required to move coherently ('signal' dots moving either upwards or downwards on each trial) or randomly ('noise' dots) and whether or not the dot was inside the area of the display containing the patch of coherent motion to be judged by the observer.

Dots in the background area always moved in a random direction on each jump (i.e. were 'noise dots'). On each trial an area was defined as the area of coherent motion, termed for convenience, the target area. The dots within this area moved either up or down with various levels of coherence (i.e. contained a proportion of 'signal' to 'noise' dots so that the signal:noise ratio could be varied). The target area was circular, its radius was 0.9° and its center was 1.7° from the center of the display area. It could be in one of four positions, either

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335 directly above, below, left or right of the center of the
336 display area (as illustrated in Fig. 1). When the observer
337 had prior knowledge of the position of the target area
338 containing coherent motion, this position remained the
339 same throughout all the trials of a run. When the ob-
340 server did not have prior knowledge of the location of
341 motion the position of the target area was randomly
342 selected, on each trial, from the four possible positions.
343 Throughout the experiment the observers fixated the
344 center of the stimulus area.

345 It is important to note that there were no spatial
346 density differences between the target area and remainder
347 of the display which observers could use to identify the
348 location of the target area (the target area differed only
349 from the background in that it contained a proportion of
350 dots that underwent some degree of coherent, unidirec-
351 tional motion). Whenever a dot was displaced such that
352 it would fall outside the target area it was immediately re-
353 plotted within the area at the diagrammatically opposite
354 location. Thus even when there was a high level of mo-
355 tion coherence there were no spatial dot density cues
356 available that could be used to locate the target patch.

357 3.2. Procedure

358 A single interval, 2-Alternative-Forced-Choice
359 (2AFC) procedure was employed. On each trial
360 observers were presented with a central fixation point
361 followed by a motion stimulus. After the presentation of
362 the stimulus, observers indicated with a key press whe-
363 ther they saw upwards or downwards motion. Motion
364 coherence within the target area (or dot visibility, see
365 below) was controlled by a 1-up 3-down staircase that
366 converged on a threshold corresponding to a perfor-
367 mance level of 79% correct. The staircase terminated
368 after eight reversals and the threshold was taken as the
369 mean of the last six reversals. For each condition tested,
370 10 staircases were completed and the data point for that
371 condition was taken as the mean of the 10 staircase
372 threshold estimates.

373 3.3. Modulation-depth thresholds

374 In this and the following experiments, first-order dots
375 were (unless otherwise specified) luminance-modulations
376 (LM) of a spatially 2-d, binary, noise field, such that the
377 luminance of the noise within each dot was higher than
378 that of the background. The dot luminance-modulation
379 depth (dot contrast) was defined as:

$$\text{Luminance-modulation depth} = (D_L - B_L)/(D_L + B_L) \quad (1)$$

381 where D_L and B_L are the mean luminances of the 2-d
382 noise (carrier) comprising the dots and the background,
383 respectively. Second-order dots were contrast-modula-

384 tions (CM) of 2-d noise, with higher contrast than the
385 background. The dot contrast-modulation depth was
386 defined as:

$$\text{Contrast-modulation depth} = (D_c - B_c)/(D_c + B_c) \quad (2)$$

387 where D_c and B_c are the mean contrasts of the 2-d noise
388 within the dots and the background, respectively. 389

390 Modulation-depth thresholds were measured sepa-
391 rately for each observer. On each trial, all of the dots
392 within the target area moved either up or down with
393 100% coherence. The staircase controlled the luminance-
394 modulation depth (for first-order) or the contrast-
395 modulation depth (for second-order) of all the dots,
396 both inside and outside the target area.

397 3.4. Coherence thresholds

398 The staircase controlled the number of dots within
399 the target area that moved coherently either up or down
400 (i.e. 'signal' dots). The second-order dots were presented
401 at their maximum possible modulation depth (0.8). The
402 contrast of the first-order dots was set at an equal
403 multiple of their modulation-depth threshold (approx-
404 imately twice) for each observer.

405 3.5. Results

406 In order to aid comparison of the magnitude of effects
407 found between the conditions when the target area
408 location was known (fixed throughout each run of trials)
409 to the observer and those when it was unknown (ran-
410 domized on each trial), the raw data were normalized.
411 To normalize the data, the average threshold for dis-
412 criminating the direction of motion in a random, un-
413 known position was divided by the average threshold for
414 discriminating direction of motion in the four known
415 positions. Fig. 2a and c show these ratios for modula-
416 tion-depth thresholds and Fig. 2b and d show the
417 computed ratios for the coherence thresholds.

418 When the motion was presented for 250 ms (a, b) the
419 ratios (of thresholds obtained in the unknown to known
420 location) are similar, for each observer, for the lumi-
421 nance-modulated dots (solid bars) and the contrast-
422 modulated dots (striped bars). This is true for both the
423 modulation-depth thresholds (a) and the coherence
424 thresholds (b). This is not to say that absolute perfor-
425 mance itself was necessarily the same for the two vari-
426 eties of motion stimulus, it was not and performance for
427 contrast-defined motion was always worse, however it is
428 the effect of knowing location that is the crucial factor of
429 interest in this study. Once the different absolute per-
430 formance levels for the two stimulus types are factored
431 out by our normalizing procedure, the effect of not
432 knowing the location of the coherent motion was the
433 same for luminance-defined and contrast-modulated
434 dots.

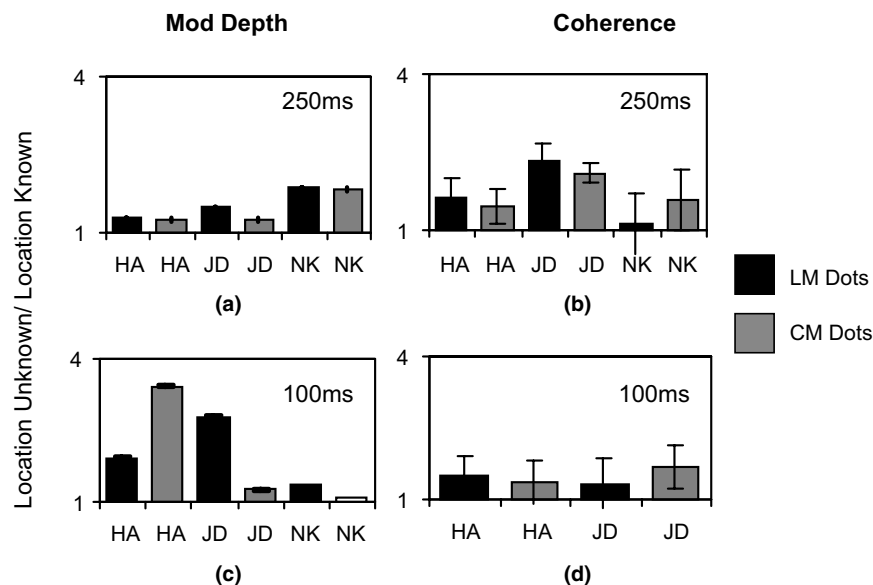


Fig. 2. Results of Experiment 1: observers discriminated the direction of motion in a target area, the prior location of which was either known or unknown. The average direction-discrimination threshold when the location was unknown was divided by the average threshold for direction discrimination in the known location to compute a threshold ratio. Performance was compared in terms of modulation-depth thresholds (a, c) and coherence thresholds (b, d) for both the luminance-modulated (LM) and contrast-modulated (CM) dots. Two stimulus durations were tested: (a, b) 250 ms and (c, d) 100 ms.

435 When the stimulus duration was 100 ms, the effect of
 436 not knowing the location of the motion on coherence
 437 thresholds was the same overall for luminance-modu-
 438 lated dots and contrast-modulated dots (d). For modu-
 439 lation-depth thresholds (c), one observer showed a
 440 greater effect for contrast-modulated dots (HA) but
 441 another observer showed the opposite pattern (JD).
 442 Since fixation was not monitored, it is possible that these
 443 results are due to both positional uncertainty and
 444 changes in eccentricity, despite our well trained observers
 445 and clearly visible fixation marker. Sensitivity to
 446 contrast-defined motion is lower at eccentric locations
 447 compared to sensitivity to luminance-defined stimuli.
 448 Any changes in fixation may have selectively advantaged
 449 performance with the contrast-defined stimulus, which
 450 clearly did not happen. Although the magnitude of the
 451 effect of positional uncertainty is unclear from this
 452 experiment, at present it is sufficient to conclude here
 453 that prior knowledge of stimulus location can have a
 454 marked and measurable differential effect on perfor-
 455 mance on this task. This is equally true, however, for
 456 both luminance-defined and contrast-defined motion
 457 patterns. Thus the motion of contrast-defined structure,
 458 like its luminance-defined counterpart, can be moni-
 459 tored simultaneously at multiple visual field positions.

460 **4. Experiment 2**

461 Experiment 1 investigated the effect of positional
 462 uncertainty solely on the ability to discriminate motion

direction for both luminance-defined and contrast-de- 463
 464 fined stimuli. Although both types of motion were af- 465
 466 fected to a similar degree, we did not address the issue of 467
 468 observers' ability to discriminate position. In Experiment 2 469
 470 observers judged the location of a motion-defined square, 471
 472 relative to the position of two, flanking, cue squares. This experiment was designed to measure the ability of observers to discriminate the relative location of moving contrast-modulated dots.

472 **4.1. Stimulus**

473 The stimuli were moving dots presented on a back- 474
 475 ground of mean luminance. Dots were squares, sub- 476
 477 tending 0.04° horizontally and vertically. First-order 478
 479 stimuli were typically presented with a low LM dot 480
 481 contrast of 0.05 (see Eq. 2) and a 2-d noise carrier added 482
 483 throughout the display. Second-order dots were typi- 484
 485 cally presented at maximum modulation depth. 2025 486
 487 dots were presented within a square stimulus display 488
 489 area (window) subtending 9.8° . The dots moved to- 490
 491 gether, coherently either left or right and with a drift 492
 493 speed of either 0.9 (duration 810 ms) or $1.5^\circ/s$ (duration 494
 495 540 ms). Within the stimulus area two smaller squares 496
 497 were defined as the cue (reference) squares (each sub- 498
 499 tending 2°). These contained static dots (see the 'Intro- 500
 501 duction' and 'Results' for a further list of stimulus 502
 503 parameters tested in pilot studies). A central, target, 504
 505 square (2°) contained motion in the opposite direction 506
 507 to the remainder of the stimulus. The target and cue 508
 509 squares were defined solely by their relative motion with 510

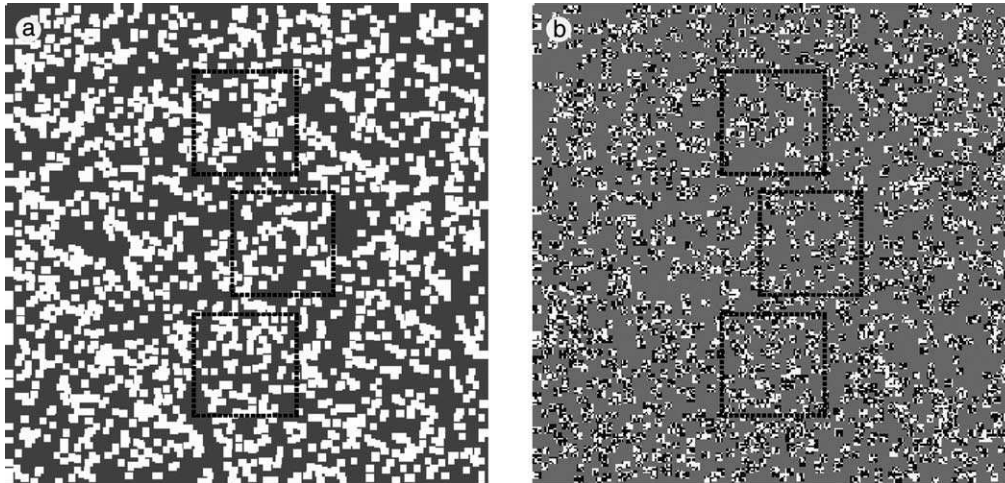


Fig. 3. (a) First-order, luminance-modulated (LM) dots used in Experiment 2. The square regions shown by the dashed outline (shown for illustrative purposes only and not visible in the actual experiments) contained motion in the opposite direction (or static dots) to the remainder of the display and were defined solely by this cue. (b) Second-order, contrast-modulated (CM) dots at maximum modulation depth as used in Experiment 2, with square positions illustrated as in (a).

492 respect to the background dots. The target square was
493 positioned in the center of the stimulus area and the cue
494 squares were presented above and below the target
495 square, with an edge to edge separation of 0.2° (unless
496 otherwise stated). The central, target, square was offset
497 horizontally either to the left or right of the cue squares
498 by a variable amount. Fig. 3 a and b show illustrations
499 of the stimuli.

500 4.2. Procedure

501 Observers judged, in a one interval, 2AFC procedure
502 whether the central target square was to the left or right
503 of the cue squares. On each trial the central square was
504 offset to the left or right (with equal probability) by a
505 variable amount under control of the experimenter
506 (method of constant stimuli). Each run tested a range of
507 offsets, spanning the entire available range. Observers
508 indicated their response with a key press. A second key
509 press indicated when they were ready to proceed to the
510 next trial. A central fixation marker was presented be-
511 tween the trials and no feedback was given.

512 4.3. Results

513 Fig. 4 shows data for three observers each performing
514 the task with 2 dot speeds (for the central, target square
515 and background), cue squares were defined by static
516 dots and the separation between the squares was 0.2° .
517 The proportion of correct responses is plotted on the
518 ordinate against the offset between the center and cue
519 squares on the abscissa.

520 It is clear that observers rarely reached good levels of
521 performance with either type of dot. This was the case
522 for contrast-modulated dots (solid symbols), even

though these dots were at maximum modulation depth,
clearly visible and well above their motion discrimina-
tion thresholds. Performance appears to initially im-
prove and then decrease as the offset increases. The data
we show here reflect the best performance produced with
contrast-modulated dot stimuli. In pilot studies we
measured performance with a range of dot densities,
speeds and viewing distances. In all these cases, perfor-
mance was not different from chance. Observers also
performed the task at lower modulation depths (0.35)
but performance never reached 75% correct and was
close to chance. Similarly when the cue squares con-
tained opposed motion (rather than static dots) perfor-
mance was not different from chance, perhaps reflecting
that it was necessary to locate both the cue and test
regions. Other manipulations that might affect perfor-
mance are reported below.

For low contrast luminance-modulated dots in the
presence of a noise carrier (open diamonds) perfor-
mance was comparable to that obtained with the con-
trast-modulated dots. The same 'n' shaped pattern of
performance is shown. It should be noted that this
pattern of performance is not an idiosyncratic feature of
our particular stimulus configuration or observers. As a
control, the experiment was repeated with luminance-
modulated dots, but without the 2-d noise carrier. All
observers reported that this task was comparatively
easy. For all observers, at both speeds, offset discrimi-
nation reached 75% correct at offsets of about 0.1° (see
Fig. 4). Thus, the presence of an additional spatial
component degraded performance for the patch of
luminance-modulated dots (perhaps because it reduced
its visibility).

For both the contrast-modulated patterns and the
luminance-modulated patterns presented with a noise

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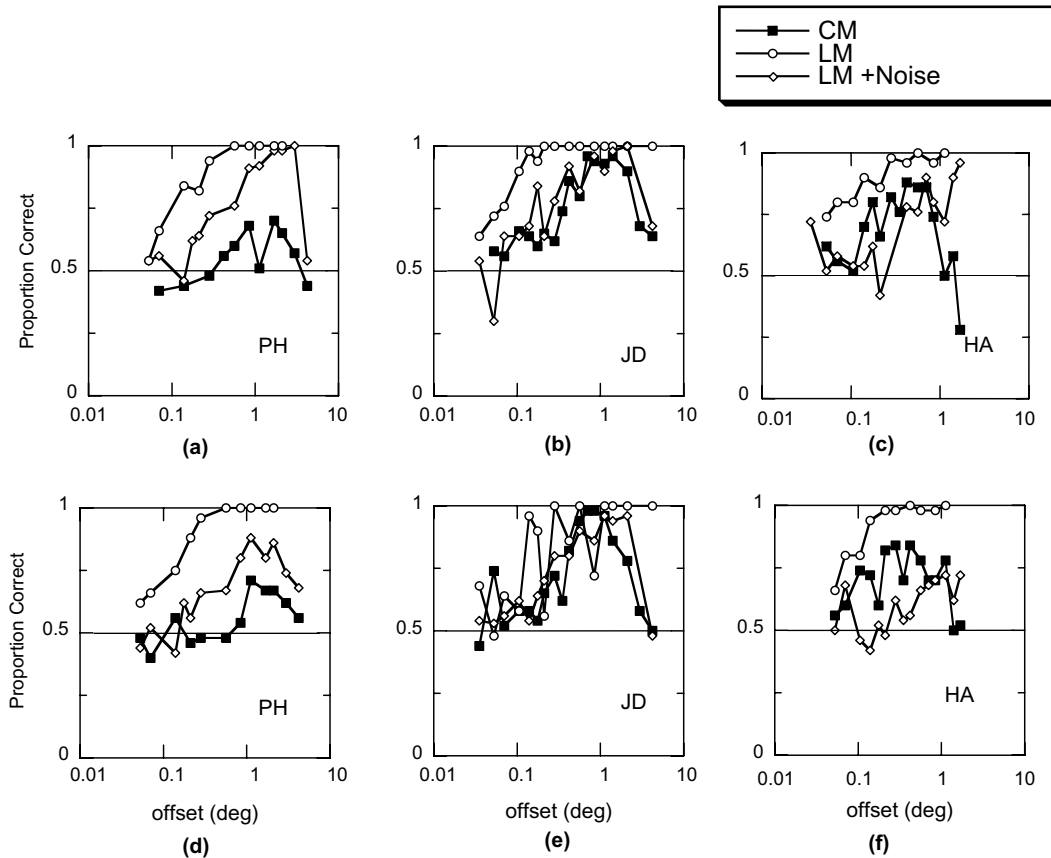


Fig. 4. Results of Experiment 2: discriminating the location (left or right of cue squares) of a motion-defined target square. The stimulus area was filled by dots moving in one direction, cue squares were defined by static dots, target squares were defined by motion in the opposite direction to the background. Dots were either contrast-modulations (CM) or luminance-modulations (LM) or luminance modulations with added visual noise. The results of three observers are shown, performing the task at two speeds: (a-c) 1.5°/s motion; (d-f) 0.9°/s motion.

558 mask, there is a decrease in position discrimination
 559 performance at larger offsets. Although this pattern of
 560 results has not been seen in position discrimination
 561 experiments previously, it is likely that it is a simple
 562 result of the presence of the noise pattern. At larger
 563 eccentricities the visibility of high spatial frequencies is
 564 reduced, reducing the visibility of the luminance-defined
 565 dots or reducing the visibility of the carrier of the contrast-modulations.
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567 Since different results have, in the past been found
 568 with different separations of cue and target item (Whitaker, Bradley, Barrett, & McGraw, 2002) we tested
 569 whether our results were specific to the configuration
 570 that we used. We increased the vertical distance between
 571 the cue squares and the target square (Fig. 5). The
 572 spatial separation between the edges of the squares was
 573 0.2°, 1° or 2°. The data show that changing the separation
 574 between the squares did not change performance
 575 appreciably with the contrast-defined stimulus (shown in
 576 a-c). Similarly when luminance-defined dots were presented
 577 (shown in d-f), increasing the separation also had
 578 little or no effect on performance.
 579

580 In the previous conditions, the cue squares were always
 581 presented in the same, central position. This was
 582 done to facilitate performance with contrast-modulated
 583 dots since pilot studies had suggested that the task was
 584 difficult. Without jittering the position of the cue squares
 585 it is not possible, however, to determine whether performance
 586 is based on the position of the target square relative to the
 587 cue squares or other cues such as the edges of the monitor.
 588 We tested the effect of randomly jittering the positions of
 589 the cue squares. The amount of jitter was randomly selected
 590 on each trial and could be between 0 and the maximum
 591 offset used in the run. Fig. 6 compares performance with
 592 and without this jitter. Jittering the position of the cue
 593 squares has little influence on performance with luminance-
 594 defined dots (d-f). For contrast-defined dots (a-c), however,
 595 adding jitter to the cue squares (solid circles) may actually
 596 marginally improve performance in some cases, though overall
 597 performance levels are again little affected by positional
 598 jittering. Thus we find no difference between contrast-
 599 defined and luminance-defined motion when it comes to
 600 indicating the position over two regions (i.e. in principle
 601 at least the task could be performed by a gross com-
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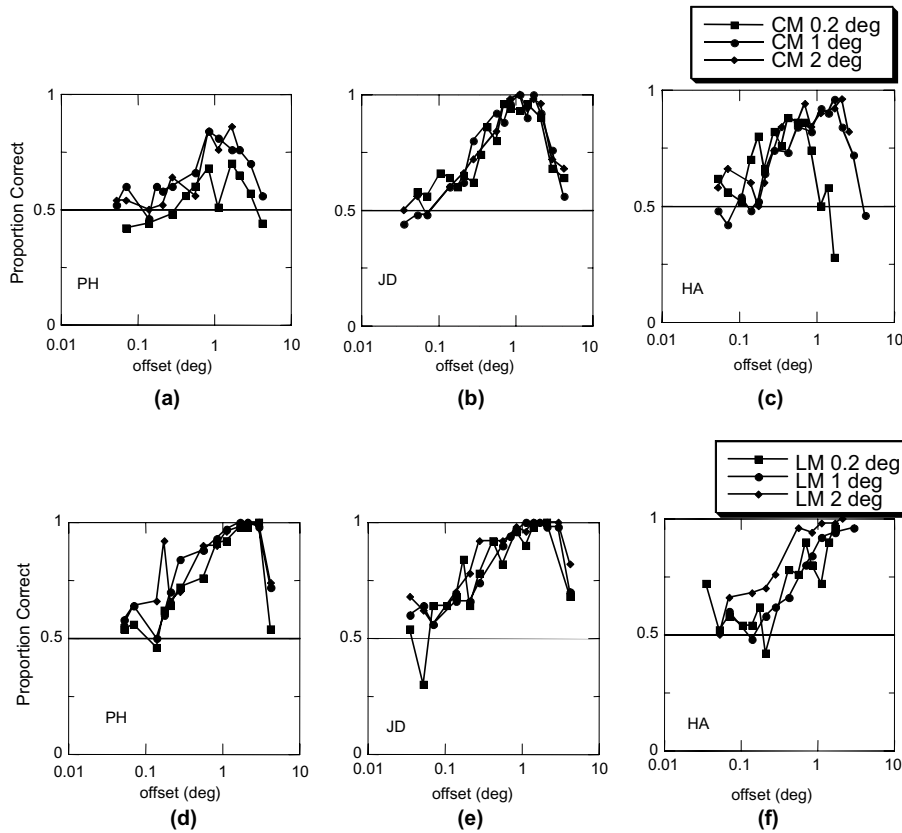


Fig. 5. Results of Experiment 2: discriminating the location (left or right of cue squares) of motion-defined target squares. Cue squares were positioned vertically at three different edge-to-edge separations from the target square (shown by the different symbols). Results from three observers are shown for (a-c) CM dots and (d-f) LM dots.

603 parison of the positions of the target and a single cue
604 square) of local motion.

605 **5. Experiment 3**

606 In Experiment 1 we found that observers were able to
607 monitor a number of the visual field locations for the
608 presence of coherent contrast-defined motion. In
609 Experiment 2, observers could perform a crude left-right
610 judgment on the position of contrast-defined moving
611 dots. Although observers performed at a comparable
612 level with luminance-defined and contrast-defined mov-
613 ing dots, the stimulus conditions advantaged contrast-
614 defined motion relative to luminance-defined motion. In
615 the third experiment we compared the positional accu-
616 racy of luminance- and contrast-defined motion when
617 they were equated for motion performance. To do this
618 we compared performance at the direction-discrimina-
619 tion threshold for motion. Observers simultaneously
620 judged the location and direction of motion in one of
621 four randomly selected possible target patches contain-
622 ing coherent motion. We used the same stimulus con-
623 figuration as previously described in Experiment 1 since
624 our results showed that observers are able to monitor this

display for both moving luminance-modulations and
contrast-modulations to an equivalent degree.

627 **5.1. Stimuli**

628 Stimuli were the same as those used for the mea-
629 surement of coherence thresholds in Experiment 1 with
630 unknown location (shown schematically in Fig. 1). The
631 presentation duration was 250 ms and the experiment
632 was performed at three viewing distances of 48.5, 97.8
633 (as in Experiment 1) and 197 cm. At 48.5 cm the display
634 area subtended 29° and the center of the target area
635 (radius 1.7°) was at a distance of 3.5° from the center of
636 the display. At 197 cm, the display area was 7.4° in
637 diameter and the center of the target area (radius 0.4°)
638 was situated 0.9° from the center of the display. The
639 position of the target area was randomly chosen to be
640 either above, below, left or right of the display center on
641 each trial.

642 **5.2. Procedure**

643 On each trial, observers first indicated with a key
644 press whether they perceived upwards or downwards
645 coherent motion in a one interval, 2AFC task. Observ-

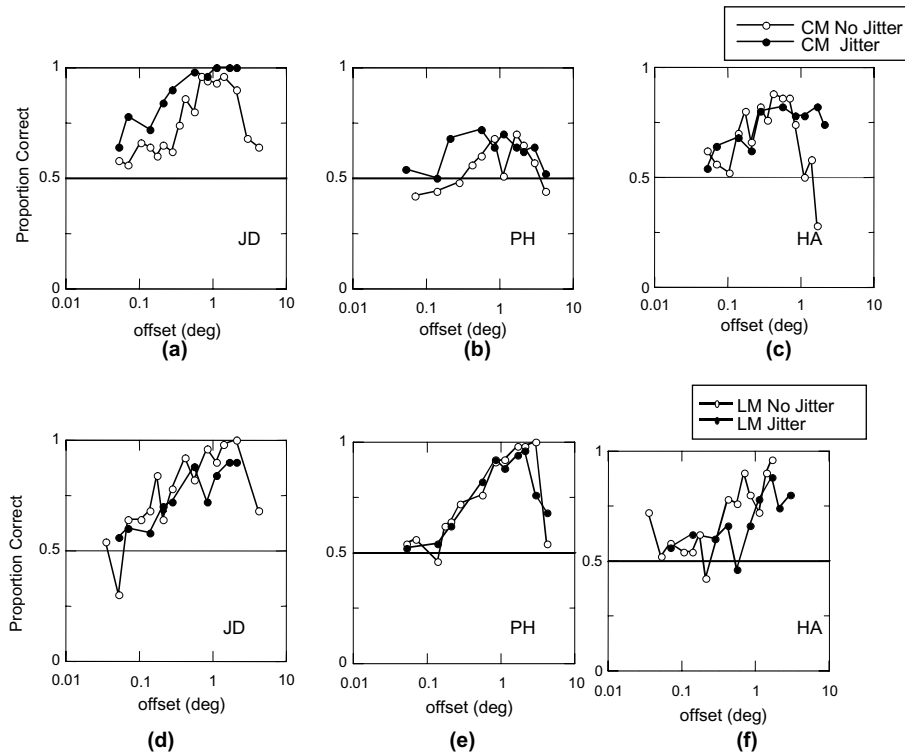


Fig. 6. Results of Experiment 2: discriminating the location (left or right of cue squares) of motion-defined target squares. Performance is shown for conditions when the cue squares remained in the same position on all trials (open symbols) and when their horizontal positions were randomly jittered on each trial (solid symbols). Results from three observers are shown with (a-c) LM dots and (d-f) CM dots.

646 ers then indicated, using a 4AFC procedure, whether the
647 target area, containing coherent motion, was in the top,
648 bottom, left or right position relative to the center of the
649 screen. The responses from this location-discrimination
650 task were used to control a 1-up 2-down adaptive
651 staircase. Motion coherence within the target area was
652 controlled by this staircase, which converged on a
653 threshold performance level of 70%. The staircase ter-
654 minated after eight reversals. For each condition tested,
655 10 staircases were completed.

656 5.3. Results

657 When analyzing our results, we found that, in many
658 conditions performance in the location-discrimination
659 task had not reached the threshold criterion perfor-
660 mance level. In these cases, therefore, the output of the
661 staircase would be an unreliable and meaningless esti-
662 mate of the location-identification performance of the
663 observer. Furthermore, direction discrimination was
664 measured in a 2AFC task and location-discrimination
665 was measured using a 4AFC task. These two tasks have
666 different chance levels (i.e. guessing rates of 50% and
667 25% correct, respectively) and thus percent correct per-
668 formance and thresholds cannot be directly compared.
669 To resolve these two issues we first took the raw percent
670 correct at each stimulus level as recorded by our stair-

case procedure. We averaged performance over 10 runs,
but discarded any data from stimulus levels that had
been tested less than 5 times (an unbiased, conservative
criterion that served to minimize the impact of less
reliable data points). We then normalized these data for
the different guess rates of the two tasks using the fol-
lowing simple formula:

$$P_{C(NORM)} = (P_C - G)/(1 - G) \quad (3)$$

where $P_{C(NORM)}$ is the normalized proportion of correct
responses at each stimulus level, P_C is the raw (unnor-
malized) proportion of correct responses at each stimu-
lus level and G is the task guess rate (either 0.5 or 0.25).

Data are shown in Figs. 7-9. In each plot the nor-
malized proportion of correct responses is shown for the
two tasks in each stimulus condition. Chance perfor-
mance on both tasks is indicated as 0, perfect perfor-
mance as 1 and threshold performance (i.e. midway
between perfect performance and guessing) is shown as
0.5. Each of the Figs. 7-9 shows data obtained at a
different viewing distance.

At a viewing distance of 48 cm, for luminance-mod-
ulated dots (Fig. 7a-c) the difference in performance
between the two tasks is small and the functions for the
two tasks overlap. For contrast-modulated dots (Fig.
7d-f) observers can judge the direction of motion (solid

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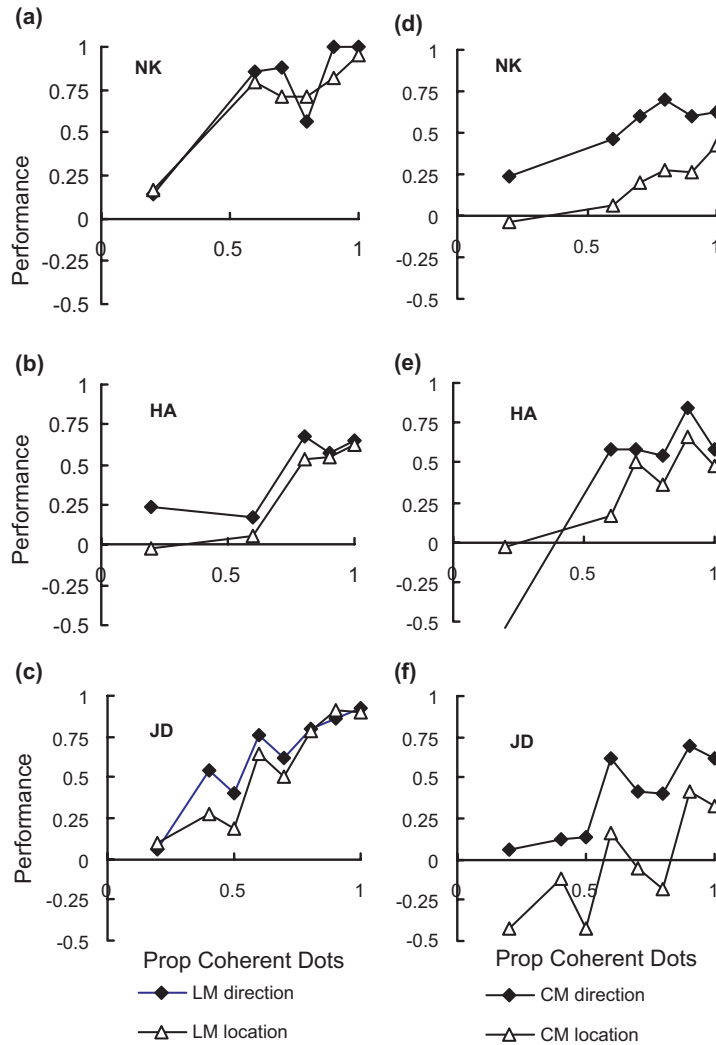


Fig. 7. Results of Experiment 3: observers judged the both the location (4AFC) and the direction (2AFC) of motion in a target area at a viewing distance of 48 cm. Performance was normalized for the different chance levels (guessing rates) in the two tasks, such that 0 in these plots represents chance performance on both tasks and 1 represents perfect performance. Three observers performed the task with moving LM dots (a-c) and CM dots (d-f). In all cases, performance is shown for both the location discrimination (open symbols) and direction discrimination (solid symbols) tasks.

696 symbols) with much greater accuracy than they can
697 judge its location (open symbols).

698 We tested if the difference between location-discrim-
699 ination performance and direction-discrimination per-
700 formance for contrast-modulated stimuli was specific to
701 the short viewing distance. In Experiment 2, perfor-
702 mance with contrast-defined dots decreased at the
703 greatest eccentricities tested. In the present experiment
704 increasing the viewing distance will decrease the eccen-
705 tricity of the patches and the total stimulus area, pos-
706 sibly leading to an improvement in performance. At
707 viewing distances of 97 cm (Fig. 8) and 194 cm (Fig. 9)
708 the difference between location-discrimination perfor-
709 mance and direction-discrimination performance is still
710 much larger for contrast-defined motion than for lumi-
711 nance-defined motion. It seems that, in general, judging
712 the location of second-order motion in one of four

713 unpredictable locations is much more difficult than
714 judging either the direction of that second-order motion
715 or the location of comparable first-order motion.

716 To ensure that the direction-discrimination tasks
717 were equivalent in Experiments 1 and 3, we examined
718 the data of two observers (JD and HA) who took part in
719 both experiments. Their psychometric functions for
720 discriminating the direction of motion in an unknown
721 location in Experiment 1 overlapped the psychometric
722 functions for discriminating motion in Experiment 3.
723 This provides good evidence that the requirement of
724 performing two consecutive judgments in Experiment 3
725 (location- and direction-discrimination) rather than one
726 (direction-discrimination) in Experiment 1, had little
727 effect on performance and the effects found do not
728 simply reflect a change in overall task difficulty.

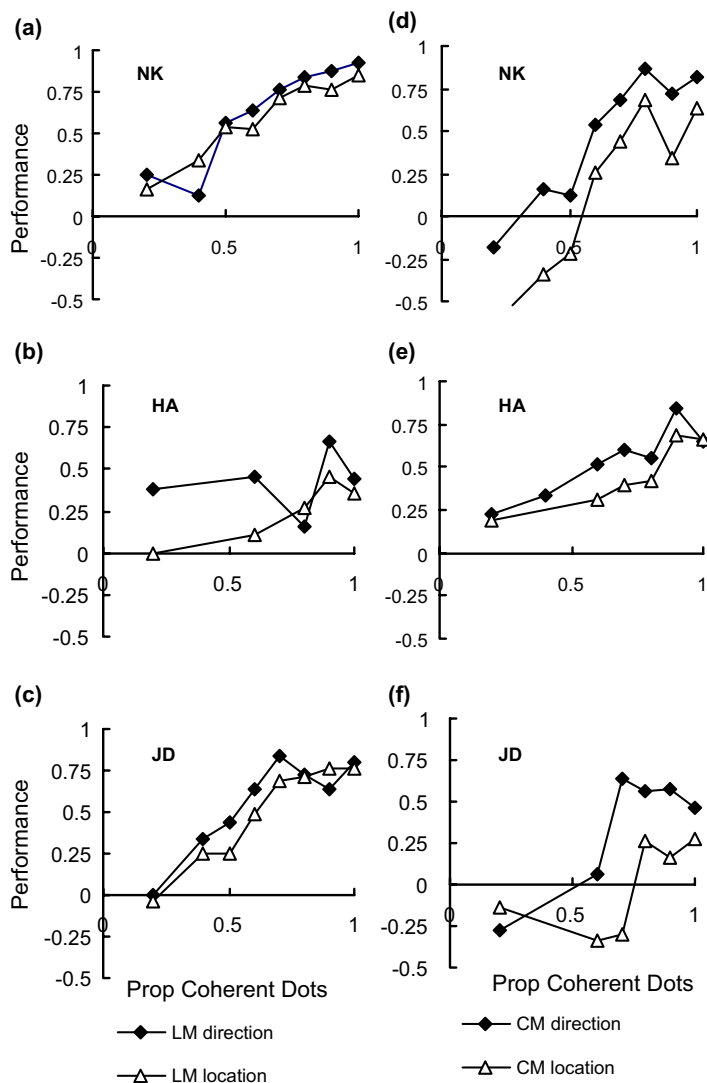


Fig. 8. Results of Experiment 3: as Fig. 7, except the viewing distance was 97 cm.

729 **6. Discussion**

730 We investigated the limitations of the mechanism that
 731 processes contrast-defined motion, specifically with re-
 732 spect to encoding its position (location) in the visual
 733 field. Our motivation for this study was the previously
 734 reported failure of second-order motion to support some
 735 tasks, such as visual search and form from motion.
 736 Using contrast-defined motion as an exemplar of sec-
 737 ond-order motion we addressed two possible reasons for
 738 these failures. First, second-order motion may not be
 739 processed in an efficient, and perhaps automatic, fash-
 740 ion across the visual field. Second, given that the me-
 741 chanisms that process second-order motion can monitor
 742 different field locations in parallel; are they also able
 743 to adequately encode the position (location) of that mo-
 744 tion. Our results suggest that observers can monitor
 745 mechanisms for second-order motion across the visual
 746 field. The ability to locate (i.e. label position) patches of

second-order motion, however, appears to be limited
 compared with first-order motion. It is important to
 emphasize that prior to formal data collection consid-
 erable effort was taken to establish the optimal condi-
 tions for measuring location-discrimination perfor-
 mance for the contrast-defined motion stimuli used in
 the current study. To achieve this we optimized a
 number of key stimulus parameters to obtain best per-
 formance with contrast-defined motion, including dot
 density, modulation depth, speed and carrier contrast.
 Thus we are confident that the effects found are robust
 and do not simply reflect a particular choice of condi-
 tions that disadvantaged contrast-defined motion.

6.1. Monitoring second-order motion in multiple locations

The suggestion that second-order motion is not pro-
 cessed efficiently over the visual field is based on the
 results of visual search tasks (Ashida et al., 2001) and

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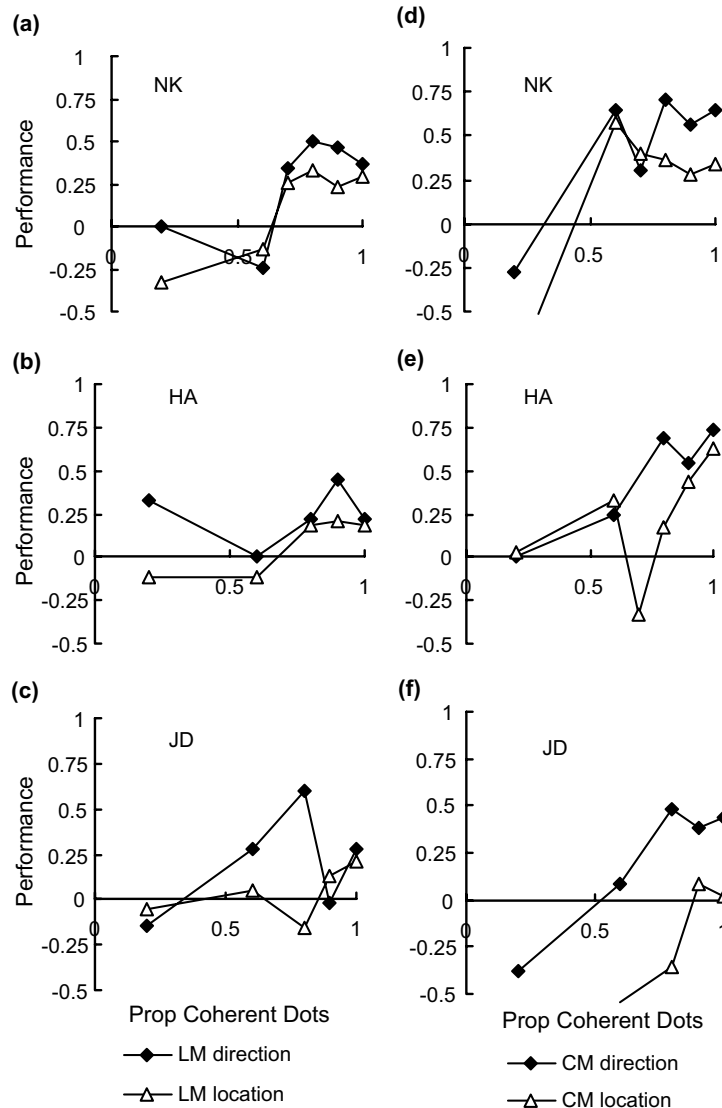


Fig. 9. Results of Experiment 3: as Fig. 7, except the viewing distance was 194 cm.

764 the pattern of results found in a task where observers
 765 had to find an inconsistent direction of motion (Allen &
 766 Derrington, 2000). In these studies the greatest effects of
 767 number of distracters were found at speeds lower than
 768 those used in Experiment 1, although similar to those
 769 used in Experiment 2. At these lower speeds, it is possible
 770 that second-order motion perception is better
 771 served by an indirect (e.g. cognitive based) higher-level
 772 mechanism (Seiffert & Cavanagh, 1999). In Experiment
 773 1, the higher drift speed used would potentially favor the
 774 operation of low-level motion mechanisms that can
 775 mediate the processing of second-order motion. It appears
 776 that these mechanisms have the capacity to monitor
 777 multiple locations in the visual field.

6.2. Position encoding for second-order motion

778

779 We tested the fidelity with which position is encoded
 780 by the mechanisms that process contrast-defined motion
 781 in two different experiments. In Experiment 2 we tested
 782 whether these mechanisms can signal relative position
 783 over at least two regions of local motion. We found that
 784 the mechanisms that encode contrast-defined motion do
 785 not completely discard position, although good performance
 786 was highly dependant on the exact stimulus
 787 parameters used. Observers were never able to accurately
 788 discriminate position offsets as small as those
 789 typically found for luminance-defined motion stimuli. In
 790 Experiment 3 we investigated whether the mechanisms
 791 underlying luminance- and contrast-defined motion
 792 have the same positional accuracy when compared un-

793 der similar levels of motion-discrimination performance.
794 The motion coherence required for reliable position
795 judgments was clearly higher for contrast-defined motion
796 in Experiment 3. Thus even though we were able to
797 show that the visual system can monitor for the presence
798 of motion over the visual field (Experiment 1) it does not
799 appear to encode the position of that motion with a high
800 degree of accuracy over the same stimulus area
801 (Experiment 3).

802 The underlying reason for the relatively poor position
803 coding for contrast-defined motion is unclear. Previous
804 studies indicate that the poor performance is not due to
805 limitations in extracting contrast-defined spatial struc-
806 ture and thus it is specific to a moving contrast-defined
807 form (Voltz & Zanker, 1996). One possible reason is that
808 the mechanisms that process first-order motion and
809 those that encode second-order motion have different
810 spatial summation areas (i.e., areas over which local
811 motion signals are pooled or combined in order to ex-
812 tract the overall, net direction of movement). If a mo-
813 tion signal of sufficient strength falls within a direction-
814 selective detector's summation area, then that mecha-
815 nism is likely to be able to signal the motion direction.
816 Although a larger summation area would enable a mo-
817 tion mechanism to pool motion information over more
818 extended regions of visual space (advantageous for
819 encoding the net motion of large objects), it would limit
820 the ability of that mechanism to signal the precise
821 location of that motion. There is an inevitable trade-off
822 between summation area extent and positional accuracy
823 for any motion-detecting mechanism. It is thus possible,
824 that the mechanisms that process contrast-defined mo-
825 tion may have larger summation areas than those that
826 process first-order motion. Intuitively this is unsurpris-
827 ing since it has been found that the summation area for
828 contrast-defined static form is larger than the summa-
829 tion area for similar luminance-defined form (Schofield
830 & Georgeson, 1999), and it is possible that this may also
831 be true for contrast-defined motion. Similarly, the
832 summation area for luminance-defined motion has been
833 investigated (e.g. Anderson & Burr, 1991; Fredericksen,
834 Verstraten, & vandeGrind, 1994; Watamaniuk, 1993),
835 but it is not clear that there is yet a reliable estimate
836 (Fredericksen, Verstraten, & vandeGrind, 1997). There
837 have been no studies of the summation area for second-
838 order, contrast-defined motion, an issue that we are
839 currently investigating.

840 Contrast-defined motion might be processed by a
841 direct, motion energy type mechanism (e.g. Lu & Sper-
842 ling, 1995) or by an indirect mechanism that relies on the
843 change in position of image features over time (Der-
844 rington & Ukkonen, 1999; Seiffert & Cavanagh, 1998).
845 Poor position acuity and larger receptive fields could be
846 compatible with either processing mechanism. A mecha-
847 nism that determines motion direction from a change
848 in position is likely to have a receptive field that

encompasses position coders at two locations. The size 849
of the receptive field will, therefore depend on the size of 850
the local position detectors, but will always be larger 851
than these detectors. In the case of a direct mechanism 852
for contrast-defined motion, it has recently been sug- 853
gested that the mechanism that processes second-order 854
motion is only weakly direction selective (Ledgeway & 855
Hess, 2002). This weak direction selectivity could, per- 856
haps, arise from larger receptive fields. It is possible that 857
both types of mechanism act on second-order motion 858
but that in both cases position is poorly coded. 859

6.3. Deficits with second-order motion 860

861 Although we find that observers can monitor multiple 862
locations in the visual field for the presence of a region 863
containing coherent second-order motion, they appear 864
to have only limited access to spatial position informa- 865
tion. These results may explain why many previous 866
studies have found that second-order motion is an 867
impoverished stimulus for driving some visual phe- 868
nomena. For example, the reduced performance found 869
when judging three-dimensional shape from second-or- 870
der motion might be partially attributable to poor po- 871
sition coding in multiple locations. Shape would be 872
ambiguous if the exact positions of the edges that de- 873
fined the shapes were poorly encoded. It is also possible 874
that discriminating distortions in flow fields could be 875
affected by poor position coding since these also involve 876
accurate representation of the locations of particular 877
velocity distributions.

878 Poor position coding by itself, however, may not be 879
sufficient to explain all previously found failures with 880
second-order motion. Slow visual search might be 881
attributed to this deficit when the task is to locate an 882
inconsistent motion, but performance is also poor when 883
observers have to simply indicate the presence or ab- 884
sence of second-order motion in a pre-specified direction 885
(Ashida et al., 2001). However recent evidence also 886
suggests that the accuracy with which the direction of 887
motion can be extracted from second-order displays is 888
relatively poor, and these two deficits together could 889
compromise the ability to perform visual search tasks 890
rapidly and efficiently (Ledgeway & Hess, 2002).

7. Conclusion 891

892 The mechanisms that detect contrast-defined, second- 893
order motion can simultaneously monitor multiple 894
locations in the visual field for the presence of move- 895
ment. It appears that the mechanism that processes 896
second-order motion can code rudimentary spatial po- 897
sition to some extent, but it requires a stronger motion 898
signal to do so and is incapable of achieving as high 899
precision as the mechanism that processes first-order

900 motion. The results of the present study therefore have
901 important implications for our understanding of motion
902 processing in human vision and offer some new insights
903 into why second-order motion stimuli may be relatively
904 impoverished at eliciting some visual phenomenon.

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