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## Two-Grid $hp$ -DGFEM for Second Order Quasilinear Elliptic PDEs Based on an Incomplete Newton Iteration

Scott Congreve and Paul Houston

ABSTRACT. In this paper we propose a class of so-called two-grid  $hp$ -version discontinuous Galerkin finite element methods for the numerical solution of a second-order quasilinear elliptic boundary value problem based on the application of a single step of a nonlinear Newton solver. We present both the *a priori* and *a posteriori* error analysis of this two-grid  $hp$ -version DGFEM as well as performing numerical experiments to validate the bounds.

### 1. Introduction

In our recent articles [4, 5] we have considered a class of two-grid finite element methods for strongly monotone partial differential equations. Here, the underlying problem is first approximated on a coarse finite element space; the resulting coarse solution is then used to linearise the underlying problem on a finer finite element space, so that only a linear system of equations is solved on this richer space. In this paper we consider an alternative two-grid interior penalty (IP) discontinuous Galerkin finite element method (DGFEM), based on employing a single step of a Newton solver on the finer space, cf. [1], [9, Section 5.2], for the numerical solution of the following quasilinear elliptic boundary value problem:

$$(1.1) \quad -\nabla \cdot (\mu(\mathbf{x}, |\nabla u|) \nabla u) = f \quad \text{in } \Omega, \quad u = 0 \quad \text{on } \Gamma,$$

where  $\Omega$  is a bounded polygonal domain in  $\mathbb{R}^2$ , with boundary  $\Gamma$  and  $f \in L^2(\Omega)$ .

We assume that  $\mu \in C^2(\bar{\Omega} \times [0, \infty))$  satisfies the condition: there exists positive constants  $m_\mu$  and  $M_\mu$  such that the following monotonicity property is satisfied:

$$(1.2) \quad m_\mu(t - s) \leq \mu(\mathbf{x}, t)t - \mu(\mathbf{x}, s)s \leq M_\mu(t - s), \quad t \geq s \geq 0, \quad \mathbf{x} \in \bar{\Omega}.$$

For ease of notation we write  $\mu(t)$  instead of  $\mu(\mathbf{x}, t)$ . The outline of this article is as follows. In Section 2 we state the proposed two-grid IP DGFEM. In Sections 3 and 4 we consider the *a priori* and *a posteriori* error analysis, respectively, of the two-grid IP DGFEM. Finally, in Section 5 we present some numerical results to validate the theoretical error bounds.

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## 2. Two-Grid $hp$ -Version IP DGFEM

We consider shape-regular meshes  $\mathcal{T}_h$  that partition  $\Omega \subset \mathbb{R}^2$  into open disjoint elements  $\kappa$  such that  $\bar{\Omega} = \bigcup_{\kappa \in \mathcal{T}_h} \bar{\kappa}$ . By  $h_\kappa$  we denote the element diameter of  $\kappa \in \mathcal{T}_h$ ,  $h = \max_{\kappa \in \mathcal{T}_h} h_\kappa$ , and  $\mathbf{n}_\kappa$  signifies the unit outward normal vector to  $\kappa$ . We allow the meshes  $\mathcal{T}_h$  to be *1-irregular*; further, we suppose that  $\mathcal{T}_h$  is of *bounded local variation*, i.e., there exists a constant  $\rho_1 \geq 1$ , independent of the element sizes, such that  $\rho_1^{-1} \leq h_\kappa/h_{\kappa'} \leq \rho_1$ , for any pair of elements  $\kappa, \kappa' \in \mathcal{T}_h$  which share a common edge  $e = \partial\kappa \cap \partial\kappa'$ . To each  $\kappa \in \mathcal{T}_h$  we assign a polynomial degree  $p_\kappa \geq 1$  and define the degree vector  $\mathbf{p} = \{p_\kappa : \kappa \in \mathcal{T}_h\}$ . We suppose that  $\mathbf{p}$  is also of bounded local variation, i.e., there exists a constant  $\rho_2 \geq 1$ , independent of the element sizes and  $\mathbf{p}$ , such that, for any pair of neighbouring elements  $\kappa, \kappa' \in \mathcal{T}_h$ ,  $\rho_2^{-1} \leq p_\kappa/p_{\kappa'} \leq \rho_2$ .

With this notation, we introduce the finite element space

$$V(\mathcal{T}_h, \mathbf{p}) = \{v \in L^2(\Omega) : v|_\kappa \in \mathcal{S}_{p_\kappa}(\kappa) \quad \forall \kappa \in \mathcal{T}_h\},$$

where  $\mathcal{S}_{p_\kappa}(\kappa) = \mathcal{P}_{p_\kappa}(\kappa)$  if  $\kappa$  is a triangle and  $\mathcal{S}_{p_\kappa}(\kappa) = \mathcal{Q}_{p_\kappa}(\kappa)$  if  $\kappa$  is a parallelogram. Here, for  $p \geq 0$ ,  $\mathcal{P}_p(\kappa)$  denotes the space of polynomials of degree at most  $p$  on  $\kappa$ , while  $\mathcal{Q}_p(\kappa)$  is the space of polynomials of degree at most  $p$  in each variable on  $\kappa$ .

For the mesh  $\mathcal{T}_h$ , we write  $\mathcal{E}_h^{\mathcal{I}}$  to denote the set of all interior edges of the partition  $\mathcal{T}_h$  of  $\Omega$ ,  $\mathcal{E}_h^{\mathcal{B}}$  the set of all boundary edges of  $\mathcal{T}_h$ , and set  $\mathcal{E}_h = \mathcal{E}_h^{\mathcal{B}} \cup \mathcal{E}_h^{\mathcal{I}}$ . Let  $v$  and  $\mathbf{q}$  be scalar- and vector-valued functions, respectively, which are sufficiently smooth inside each element  $\kappa \in \mathcal{T}_h$ . Given two adjacent elements,  $\kappa^+, \kappa^- \in \mathcal{T}_h$  which share a common edge  $e \in \mathcal{E}_h^{\mathcal{I}}$ , i.e.,  $e = \partial\kappa^+ \cap \partial\kappa^-$ , we write  $v^\pm$  and  $\mathbf{q}^\pm$  to denote the traces of the functions  $v$  and  $\mathbf{q}$ , respectively, on the edge  $e$ , taken from the interior of  $\kappa^\pm$ , respectively. With this notation, the averages of  $v$  and  $\mathbf{q}$  at  $\mathbf{x} \in e$  are given by  $\{v\} = 1/2(v^+ + v^-)$  and  $\{\mathbf{q}\} = 1/2(\mathbf{q}^+ + \mathbf{q}^-)$ , respectively. Similarly, the jumps of  $v$  and  $\mathbf{q}$  at  $\mathbf{x} \in e$  are given by  $[[v]] = v^+ \mathbf{n}_{\kappa^+} + v^- \mathbf{n}_{\kappa^-}$  and  $[[\mathbf{q}]] = \mathbf{q}^+ \cdot \mathbf{n}_{\kappa^+} + \mathbf{q}^- \cdot \mathbf{n}_{\kappa^-}$ , respectively, where  $\mathbf{n}_{\kappa^\pm}$  denotes the unit outward normal vector on  $\partial\kappa^\pm$ , respectively. On a boundary edge  $e \in \mathcal{E}_h^{\mathcal{B}}$ , we set  $\{v\} = v$ ,  $\{\mathbf{q}\} = \mathbf{q}$ ,  $[[v]] = v\mathbf{n}$  and  $[[\mathbf{q}]] = \mathbf{q} \cdot \mathbf{n}$ , with  $\mathbf{n}$  denoting the unit outward normal vector on the boundary  $\Gamma$ . For  $e \in \mathcal{E}_h$ , we define  $h_e$  to be the length of the edge; moreover, we set  $p_e = \max(p_\kappa, p_{\kappa'})$ , if  $e = \partial\kappa \cap \partial\kappa' \in \mathcal{E}_h^{\mathcal{I}}$ , and  $p_e = p_\kappa$ , if  $e = \partial\kappa \cap \Gamma \in \mathcal{E}_h^{\mathcal{B}}$ .

**2.1. Standard IP DGFEM discretisation.** Given a fine mesh partition  $\mathcal{T}_h$  of  $\Omega$ , with the corresponding polynomial degree vector  $\mathbf{p}$ , the standard IP DGFEM is defined as follows: find  $u_{h,p} \in V(\mathcal{T}_h, \mathbf{p})$  such that

$$(2.1) \quad A_{h,p}(u_{h,p}, v_{h,p}) = F_{h,p}(v_{h,p})$$

for all  $v_{h,p} \in V(\mathcal{T}_h, \mathbf{p})$ , where  $F_{h,p}(v) = \int_\Omega f v \, d\mathbf{x}$  and

$$\begin{aligned} A_{h,p}(u, v) &= \int_\Omega \mu(|\nabla_h u|) \nabla_h u \cdot \nabla_h v \, d\mathbf{x} - \sum_{e \in \mathcal{E}_h} \int_e \{ \mu(|\nabla_h u|) \nabla_h u \} \cdot [[v]] \, ds \\ &\quad + \theta \sum_{e \in \mathcal{E}_h} \int_e \{ \mu(h_e^{-1} ||[u]||) \nabla_h v \} \cdot [u] \, ds + \sum_{e \in \mathcal{E}_h} \int_e \sigma_{h,p} [u] \cdot [v] \, ds. \end{aligned}$$

Here,  $\theta \in [-1, 1]$ ,  $\nabla_h$  is the element-wise gradient operator and  $\sigma_{h,p} = \gamma p_e^2 / h_e$ , where  $\gamma > 0$  is a sufficiently large constant. We define the *energy norm* on  $V(\mathcal{T}_h, \mathbf{p})$ :

$$\|v\|_{\text{DG}}^2 = \|\nabla_h v\|_{L^2(\Omega)}^2 + \sum_{e \in \mathcal{E}_h} \int_e \sigma_{h,p} |[v]|^2 \, ds.$$

LEMMA 2.1 (See [6]). *The semilinear form  $A_{h,p}(\cdot, \cdot)$  is strongly monotone in the sense that, there exists  $\gamma_{\min} > 0$ , such that for any  $\gamma \geq \gamma_{\min}$*

(2.2)

$$A_{h,p}(w_1, w_1 - w_2) - A_{h,p}(w_2, w_1 - w_2) \geq C_m \|w_1 - w_2\|_{\text{DG}}^2 \quad \forall w_1, w_2 \in V(\mathcal{T}_h, \mathbf{p}),$$

where  $C_m$  is a positive constant, independent of the discretisation parameters.

**2.2. Two-grid IP DGFEM discretisation.** We now introduce a two-grid IP DGFEM based on employing a single step of the Newton iteration on the fine mesh. To this end, we consider two partitions  $\mathcal{T}_h$  and  $\mathcal{T}_H$  of  $\Omega$ , with granularity  $h$  and  $H$ , respectively. We assume that  $\mathcal{T}_h$  and  $\mathcal{T}_H$  are nested in that sense that for any element  $\kappa_h \in \mathcal{T}_h$  there exists an element  $\kappa_H \in \mathcal{T}_H$  such that  $\bar{\kappa}_h \subseteq \bar{\kappa}_H$ . Moreover for each mesh,  $\mathcal{T}_h$  and  $\mathcal{T}_H$ , we have a corresponding polynomial degree vector  $\mathbf{p} = \{p_\kappa : \kappa \in \mathcal{T}_h\}$  and  $\mathbf{P} = \{p_\kappa : \kappa \in \mathcal{T}_H\}$ , respectively, where given an element  $\kappa_h \in \mathcal{T}_h$  and an element  $\kappa_H \in \mathcal{T}_H$ , such that  $\bar{\kappa}_h \subseteq \bar{\kappa}_H$ , the polynomial degree vectors satisfy the condition that  $p_{\kappa_h} \geq p_{\kappa_H}$ . Thereby, the finite element spaces  $V(\mathcal{T}_h, \mathbf{p})$  and  $V(\mathcal{T}_H, \mathbf{P})$  satisfy the following the condition:  $V(\mathcal{T}_H, \mathbf{P}) \subseteq V(\mathcal{T}_h, \mathbf{p})$ .

Using this notation we introduce the  $hp$ -version two-grid IP DGFEM discretisation of (1.1) based on a single Newton iteration step, cf. [1], [9, Section 5.2]:

(1) Compute the coarse grid approximation  $u_{H,P} \in V(\mathcal{T}_H, \mathbf{P})$  such that

$$(2.3) \quad A_{H,P}(u_{H,P}, v_{H,P}) = F_{H,P}(v_{H,P}) \quad \text{for all } v_{H,P} \in V(\mathcal{T}_H, \mathbf{P}).$$

(2) Determine the fine grid solution  $u_{2G} \in V(\mathcal{T}_h, \mathbf{p})$  such that

$$(2.4) \quad A'_{h,p}[u_{H,P}](u_{2G}, v_{h,p}) = A'_{h,p}[u_{H,P}](u_{H,P}, v_{h,p}) - A_{h,p}(u_{H,P}, v_{h,p}) + F_{h,p}(v_{h,p})$$

for all  $v_{h,p} \in V(\mathcal{T}_h, \mathbf{p})$ .

Here,  $A'_{h,p}[u](\phi, v)$  denotes the Fréchet derivative of  $u \rightarrow A_{h,p}(u, v)$ , for fixed  $v$ , evaluated at  $u$ ; thereby, given  $\phi$  we have  $A'_{h,p}[u](\phi, v) = \lim_{t \rightarrow 0} \frac{A_{h,p}(u+t\phi, v) - A_{h,p}(u, v)}{t}$ .

REMARK 2.2. For simplicity of presentation, throughout the rest of this article we shall only consider the incomplete IP variation of the DGFEM, i.e., when  $\theta = 0$ .

LEMMA 2.3. *Under the assumptions on  $\mu$ , the following inequality holds:*

$$A'_{h,p}[u](v, v) \geq C_m \|v\|_{\text{DG}}^2 \quad \forall u, v \in V(\mathcal{T}_h, \mathbf{p}).$$

PROOF. Setting  $w_1 = u + tv$  and  $w_2 = u$  in Lemma 2.1,  $u, v \in V(\mathcal{T}_h, \mathbf{p})$ ,  $t > 0$ :

$$\frac{A_{h,p}(u + tv, v) - A_{h,p}(u, v)}{t} \geq C_m \|v\|_{\text{DG}}^2.$$

Taking the limit as  $t \rightarrow 0$ , we deduce the statement of the Lemma.  $\square$

### 3. A *Priori* Error Analysis

For simplicity of presentation, in this section we assume that the mesh is quasi-uniform with mesh size  $h$  and that  $\mathbf{p}$  is uniform over the mesh, i.e.,  $\mathbf{p} \equiv p$ .

THEOREM 3.1. *Assuming that  $u \in C^1(\Omega)$  and  $u \in H^k(\Omega)$ ,  $k \geq 2$ , the solution of  $u_{2G} \in V(\mathcal{T}_h, \mathbf{p})$  of the two-grid IP DGFEM satisfies*

$$(3.1) \quad \|u_{h,p} - u_{2G}\|_{\text{DG}} \leq C \frac{p^{7/2} H^{2S-2}}{h P^{2k-3}} \|u\|_{H^k(\Omega)},$$

$$(3.2) \quad \|u - u_{2G}\|_{\text{DG}} \leq C \frac{h^{s-1}}{p^{k-3/2}} \|u\|_{H^k(\Omega)} + C \frac{p^{7/2} H^{2S-2}}{h P^{2k-3}} \|u\|_{H^k(\Omega)},$$

with  $1 \leq s \leq \min\{p+1, k\}$ ,  $p \geq 1$  and  $1 \leq S \leq \min\{P+1, k\}$ ,  $P \geq 1$ , where  $C > 0$  is independent of the discretisation parameters.

**3.1. Auxiliary Results.** We first state the following auxiliary results.

LEMMA 3.2. For a function  $v \in V(\mathcal{T}_h, \mathbf{p})$  we have the inverse inequality

$$\|v\|_{L^4(\Omega)} \leq Cp h^{-1/2} \|v\|_{L^2(\Omega)},$$

where  $C$  is a positive constant, independent of the discretisation parameters.

PROOF. Given  $\kappa \in \mathcal{T}_h$ , employing standard inverse inequalities, see [8], gives

$$\int_{\kappa} |v|^4 \, d\mathbf{x} \leq \|v\|_{L^\infty(\kappa)}^2 \|v\|_{L^2(\kappa)}^2 \leq Cp^4 h^{-2} \|v\|_{L^2(\kappa)}^2 \|v\|_{L^2(\kappa)}^2 = Cp^4 h^{-2} \|v\|_{L^2(\kappa)}^4.$$

Summing over  $\kappa \in \mathcal{T}_h$ , employing the inequality  $\sum_{i=1}^n a_i \leq (\sum_{i=1}^n \sqrt{a_i})^2$ ,  $a_i \geq 0$ ,  $i = 1, \dots, n$ , and taking the fourth root of both sides, completes the proof.  $\square$

LEMMA 3.3. For any  $v, w, \phi \in V(\mathcal{T}_h, \mathbf{p})$ ,

$$(3.3) \quad A_{h,p}(w, \phi) = A_{h,p}(v, \phi) + A'_{h,p}[v](w - v, \phi) + \mathcal{Q}(v, w, \phi),$$

where the remainder  $\mathcal{Q}$  satisfies

$$|\mathcal{Q}(v, w, \phi)| \leq Cp^2 h^{-1} (1 + \|\nabla w\|_{L^\infty(\Omega)} + \|\nabla v\|_{L^\infty(\Omega)}) \|\nabla(w - v)\|_{\text{DG}}^2 \|\nabla \phi\|_{\text{DG}},$$

and  $C$  is a positive constant, independent of the discretisation parameters.

PROOF. We follow the proof outlined by [9, Lemma 3.1]; to this end, setting  $\xi(t) = v + t(w - v)$  and  $\eta(t) = A_{h,p}(\xi(t), \phi)$ , we note that the first equation follows from the identity

$$\eta(1) = \eta(0) + \eta'(0) + \int_0^1 \eta''(t)(1-t) \, dt,$$

where  $\mathcal{Q}(v, w, \phi) = \int_0^1 \eta''(t)(1-t) \, dt$  and  $\eta''(t) = A''_{h,p}[\xi(t)](w - v, w - v, \phi)$ . Thereby,

$$\begin{aligned} \mathcal{Q}(v, w, \phi) &= 2 \int_0^1 \int_{\Omega} \mu'_{\nabla u}(|\nabla \xi(t)|) \cdot \nabla(w - v) \nabla(w - v) \cdot \nabla \phi \, d\mathbf{x} (1-t) \, dt \\ &\quad + \int_0^1 \int_{\Omega} \mu''_{\nabla u}(|\nabla \xi(t)|) |\nabla(w - v)|^2 \nabla \xi(t) \cdot \nabla \phi \, d\mathbf{x} (1-t) \, dt \\ &\quad - 2 \int_0^1 \sum_{e \in \mathcal{E}_h} \int_e \{ \mu'_{\nabla u}(|\nabla \xi(t)|) \cdot \nabla(w - v) \nabla(w - v) \} \cdot \llbracket \phi \rrbracket \, ds (1-t) \, dt \\ &\quad - \int_0^1 \sum_{e \in \mathcal{E}_h} \int_e \{ \mu''_{\nabla u}(|\nabla \xi(t)|) |\nabla(w - v)|^2 \nabla \xi(t) \} \cdot \llbracket \phi \rrbracket \, ds (1-t) \, dt \\ &\equiv T_1 + T_2 + T_3 + T_4. \end{aligned}$$

Here,  $\mu'_{\nabla u}(|\cdot|)$  and  $\mu''_{\nabla u}(|\cdot|)$  denote the first and second derivatives of  $\mu(|\cdot|)$ , respectively. First consider  $T_1$ : given that  $\mu \in C^2(\bar{\Omega} \times [0, \infty))$ , Lemma 3.2 gives

$$T_1 \leq C \|\nabla(w - v)\|_{L^4(\Omega)}^2 \|\nabla \phi\|_{L^2(\Omega)} \leq Cp^2 h^{-1} \|\nabla(w - v)\|_{L^2(\Omega)}^2 \|\nabla \phi\|_{L^2(\Omega)}.$$

Secondly, term  $T_2$  is bounded in an analogous fashion as follows:

$$\begin{aligned} T_2 &\leq C (\|\nabla w\|_{L^\infty(\Omega)} + \|\nabla v\|_{L^\infty(\Omega)}) \|\nabla(w - v)\|_{L^4(\Omega)}^2 \|\nabla \phi\|_{L^2(\Omega)} \\ &\leq C (\|\nabla w\|_{L^\infty(\Omega)} + \|\nabla v\|_{L^\infty(\Omega)}) p^2 h^{-1} \|\nabla(w - v)\|_{L^2(\Omega)}^2 \|\nabla \phi\|_{L^2(\Omega)}. \end{aligned}$$

Term  $T_3$  is bounded via the inverse trace inequality, see [8], and Lemma 3.2:

$$\begin{aligned} T_3 &\leq C \left\{ \sum_{e \in \mathcal{E}_h} h_e p_e^{-2} \|\llbracket |\nabla(w-v)|^2 \rrbracket\|_{L^2(e)}^2 \right\}^{\frac{1}{2}} \left\{ \sum_{e \in \mathcal{E}_h} \int_F p_e^2 h_e^{-1} |\llbracket \phi \rrbracket|^2 ds \right\}^{\frac{1}{2}} \\ &\leq C \|\nabla(w-v)\|_{L^4(\Omega)} \|\phi\|_{\text{DG}} \leq Cp^2 h^{-1} \|\nabla(w-v)\|_{L^2(\Omega)} \|\phi\|_{\text{DG}}. \end{aligned}$$

We can bound  $T_4$  in an analogous manner as follows:

$$\begin{aligned} T_4 &\leq C \left\{ \sum_{e \in \mathcal{E}_h} h_e p_e^{-2} \|\llbracket |\nabla(w-v)|^2 |\nabla w| \rrbracket\|_{L^2(F)}^2 \right\}^{\frac{1}{2}} \left\{ \sum_{e \in \mathcal{E}_h} \int_F p^2 h^{-1} |\llbracket \phi \rrbracket|^2 ds \right\}^{\frac{1}{2}} \\ &\quad + C \left\{ \sum_{e \in \mathcal{E}_h} h_e p_e^{-2} \|\llbracket |\nabla(w-v)|^2 |\nabla v| \rrbracket\|_{L^2(F)}^2 \right\}^{\frac{1}{2}} \left\{ \sum_{e \in \mathcal{E}_h} \int_F p^2 h^{-1} |\llbracket \phi \rrbracket|^2 ds \right\}^{\frac{1}{2}} \\ &\leq C \{ \|\nabla(w-v)|^2 |\nabla w|\|_{L^2(\Omega)} + \|\nabla(w-v)|^2 |\nabla v|\|_{L^2(\Omega)} \} \|\phi\|_{\text{DG}} \\ &\leq Cp^2 h^{-1} \{ \|\nabla w\|_{L^\infty(\Omega)} + \|\nabla v\|_{L^\infty(\Omega)} \} \|\nabla(w-v)\|_{L^2(\Omega)} \|\phi\|_{\text{DG}}. \end{aligned}$$

Combining these bounds for terms  $T_1$ ,  $T_2$ ,  $T_3$  and  $T_4$  completes the proof.  $\square$

LEMMA 3.4. *Let  $u \in H^2(\Omega)$  be the analytical solution of (1.1), such that  $\nabla u \in [L^\infty(\Omega)]^2$ , and  $u_{h,p} \in V(\mathcal{T}_h, \mathbf{p})$  be the IP DGFEM defined by (2.1), we have that*

$$\|\nabla u_{h,p}\|_{L^\infty(\Omega)} \leq Cp^{3/2},$$

where  $C$  is a positive constant, independent of the discretisation parameters.

PROOF. Writing  $\mathcal{P}_u$  to denote the projection of  $u$  onto the finite element space  $V(\mathcal{T}_h, \mathbf{p})$  defined in [2], we have that  $\|u - \mathcal{P}_u\|_{H^q(\Omega)} \leq C \frac{h^{2-q}}{p^{2-q}} \|u\|_{H^2(\Omega)}$  and  $\|\nabla(u - \mathcal{P}_u)\|_{L^\infty(\Omega)} \leq C \|u\|_{H^2(\Omega)}$  for all  $q \leq 2$ . Exploiting these bounds, standard inverse inequalities, [8], and the *a priori* bound for the IP DGFEM, [6], gives

$$\begin{aligned} \|\nabla u_{h,p}\|_{L^\infty(\Omega)} &\leq \|\nabla(u_{h,p} - \mathcal{P}_u)\|_{L^\infty(\Omega)} + \|\nabla \mathcal{P}_u\|_{L^\infty(\Omega)} \\ &\leq Cp^2 h^{-1} \|\nabla(u_{h,p} - \mathcal{P}_u)\|_{L^2(\Omega)} + \|\nabla(u - \mathcal{P}_u)\|_{L^\infty(\Omega)} + \|\nabla u\|_{L^\infty(\Omega)} \\ &\leq Cp^{3/2} \{ \|u\|_{H^2(\Omega)} + \|\nabla u\|_{L^\infty(\Omega)} \}. \end{aligned}$$

Since  $u \in H^2(\Omega)$  and  $\nabla u \in [L^\infty(\Omega)]^2$ , the quantities  $\|u\|_{H^2(\Omega)}$  and  $\|\nabla u\|_{L^\infty(\Omega)}$  are both bounded uniformly by a constant; this then completes the proof.  $\square$

**3.2. Proof of Theorem 3.1.** We now exploit the above results to prove Theorem 3.1. For the first bound (3.1), we employ Lemma 2.3, (2.1), (2.4) and (3.3); thereby, with  $\phi = u_{h,p} - u_{2G}$ , we deduce that

$$\begin{aligned} C_m \|u_{h,p} - u_{2G}\|_{\text{DG}}^2 &\leq A'_{h,p}[u_{H,P}](u_{h,p} - u_{2G}, \phi) \\ &= A'_{h,p}[u_{H,P}](u_{h,p} - u_{H,P}, \phi) + A'_{h,p}[u_{H,P}](u_{H,P} - u_{2G}, \phi) \\ &= A'_{h,p}[u_{H,P}](u_{h,p} - u_{H,P}, \phi) + A_{h,p}(u_{H,P}, \phi) - F_{h,p}(\phi) \\ &= A'_{h,p}[u_{H,P}](u_{h,p} - u_{H,P}, \phi) + A_{h,p}(u_{H,P}, \phi) - A_{h,p}(u_{h,p}, \phi) \\ &= -\mathcal{Q}(u_{H,P}, u_{h,p}, \phi). \end{aligned}$$

Hence, from Lemma 3.3 we get that

$$\|u_{h,p} - u_{2G}\|_{\text{DG}} \leq Cp^2h^{-1} \left(1 + \|\nabla u_{h,p}\|_{L^\infty(\Omega)} + \|\nabla u_{H,P}\|_{L^\infty(\Omega)}\right) \|u_{h,p} - u_{H,P}\|_{\text{DG}}^2.$$

Applying Lemma 3.4, noting that  $p^{3/2} \geq P^{3/2} \geq 1$ , and the *a priori* bound for the standard IP DGFEM, cf. [6, Theorem 3.3], gives

$$\begin{aligned} \|u_{h,p} - u_{2G}\|_{\text{DG}} &\leq Cp^2h^{-1} \left(1 + p^{3/2} + P^{3/2}\right) \left\{ \|u - u_{h,p}\|_{\text{DG}}^2 + \|u - u_{H,P}\|_{\text{DG}}^2 \right\} \\ &\leq Cp^{7/2}h^{-1} \left\{ \frac{h^{2s-2}}{p^{2k-3}} \|u\|_{H^k(\Omega)}^2 + \frac{H^{2S-2}}{P^{2k-3}} \|u\|_{H^k(\Omega)}^2 \right\}. \end{aligned}$$

Noting that  $h \leq H$  and  $p \geq P$  completes the proof of the first bound (3.1). To prove the second inequality (3.2), we first employ the triangle inequality

$$\|u - u_{2G}\|_{\text{DG}} \leq \|u - u_{h,p}\|_{\text{DG}} + \|u_{h,p} - u_{2G}\|_{\text{DG}}.$$

Thereby, applying the *a priori* error bound for the standard IP DGFEM, together with the bound (3.1), completes the proof of Theorem 3.1.

#### 4. A *Posteriori* Error Analysis

Here, we state an *a posteriori* error bound for the two-grid IP DGFEM.

**THEOREM 4.1.** *Let  $u \in H_0^1(\Omega)$  be the analytical solution of (1.1),  $u_{H,P} \in V(\mathcal{T}_H, \mathbf{P})$  and  $u_{2G} \in V(\mathcal{T}_h, \mathbf{p})$  the numerical approximations obtained from (2.3) and (2.4), respectively; then the following *hp*-*a posteriori* error bound holds*

$$(4.1) \quad \|u - u_{2G}\|_{\text{DG}}^2 \leq C \sum_{\kappa \in \mathcal{T}_h} (\eta_\kappa^2 + \xi_\kappa^2),$$

with a constant  $C > 0$ , which is independent of  $h$ ,  $H$ ,  $\mathbf{p}$  and  $\mathbf{P}$ . Here, for  $\kappa \in \mathcal{T}_h$ ,

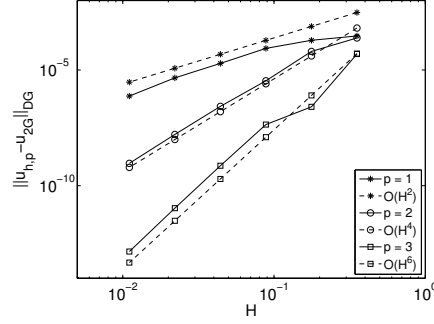
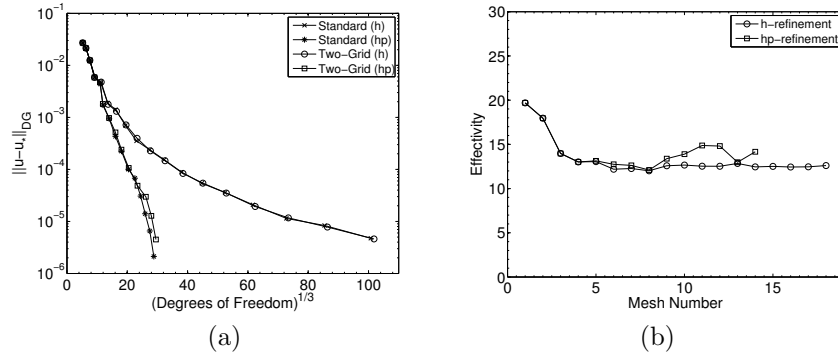
$$\begin{aligned} \eta_\kappa^2 &= h_\kappa^2 p_\kappa^{-2} \|\Pi_{\kappa, p_\kappa} f + \nabla \cdot \{\mu(|\nabla u_{H,P}|) \nabla u_{2G}\}\|_{L^2(\kappa)}^2 \\ &\quad + h_e p_e^{-1} \|\mu(|\nabla u_{H,P}|) \nabla u_{2G}\|_{L^2(\partial\kappa \setminus \Gamma)}^2 + \gamma^2 h_e^{-1} p_e^3 \|\llbracket u_{2G} \rrbracket\|_{L^2(\partial\kappa)}^2, \\ \xi_\kappa^2 &= \|(\mu(|\nabla u_{H,P}|) - \mu(|\nabla u_{2G}|)) \nabla u_{2G}\|_{L^2(\kappa)}^2 \\ &\quad + \|(\mu'_{\nabla u}(|\nabla u_{H,P}|) \cdot (\nabla u_{2G} - \nabla u_{H,P})) \nabla u_{H,P}\|_{L^2(\kappa)}^2 \\ &\quad + h_e p_e^{-1} \|(\mu'_{\nabla u}(|\nabla u_{H,P}|) \cdot (\nabla u_{2G} - \nabla u_{H,P})) \nabla u_{H,P}\|_{L^2(\partial\kappa)}^2, \end{aligned}$$

and  $\Pi_{\kappa, p_\kappa}$  denotes the (elementwise)  $L^2$ -projection onto  $V(\mathcal{T}_h, \mathbf{p})$ .

**PROOF.** The proof of this error bound follows in an analogous manner to the *a posteriori* proof presented in [5], cf. also [7]. For details, we refer to [3].  $\square$

#### 5. Numerical Experiments

In this section we perform numerical experiments to validate the *a priori* error bound, Theorem 3.1 and demonstrate the performance of the *a posteriori* error bound, Theorem 4.1; here, we set  $\gamma = 10$  and  $\theta = 0$ . Throughout this section, we let  $\Omega$  be the unit square  $(0, 1)^2 \subset \mathbb{R}^2$  and define the nonlinear coefficient as  $\mu(\mathbf{x}, |\nabla u|) = 2 + (1 + |\nabla u|)^{-1}$ . We select the right-hand forcing function  $f$  so that the analytical solution to (1.1) is given by  $u(x, y) = x(1-x)y(1-y)(1-2y)e^{-20(2x-1)^2}$ .

FIGURE 1. Convergence of error between  $u_{2G}$  and  $u_{h,p}$ .FIGURE 2. (a) Comparison of the error in the DGFEM norm, using both the IP DGFEM ( $u_* = u_{h,p}$ ) and the two-grid IP DGFEM ( $u_* = u_{2G}$ ); (b) Effectivity indices of the two-grid IP DGFEM.

**5.1. Validation of Theorem 3.1.** We first validate the bound given in Theorem 3.1; to this end we first solve the standard IP DGFEM on a  $256 \times 256$  uniform mesh of quadrilaterals to compute  $u_{h,p}$  for a fixed constant polynomial degree  $p = 1, 2, 3$ . We then compute the solution  $u_{2G}$  to (2.3)–(2.4), for  $p = 1, 2, 3$ , on a fixed fine  $256 \times 256$  mesh, while performing uniform  $h$ -refinement of the coarse mesh, starting from a  $4 \times 4$  mesh with polynomial degree  $P = p$ . Figure 1 shows the convergence rate of the error between  $u_{h,p}$  and  $u_{2G}$ , measured in the DG norm, compared to the size of the coarse mesh. Here, we observe that  $\|u_{h,p} - u_{2G}\|_{DG}$  tends to zero at the optimal rate  $\mathcal{O}(H^{2P})$ , for each fixed  $P$ , cf. Theorem 3.1.

**5.2. Adaptive Refinement using Theorem 4.1.** For this experiment we use the two-grid mesh adaptation algorithm from [5], with the *local error indicators*  $\eta_\kappa$  and *local two-grid error indicators*  $\xi_\kappa$  from Theorem 4.1, to automatically refine the coarse and fine meshes employing both  $h$ - and  $hp$ -adaptive mesh refinement. Figure 2 shows  $\|u - u_{2G}\|_{DG}$  compared to the third root of the degrees of freedom, as well as the effectivity indices of the error estimator. As can be seen for both  $h$ - and  $hp$ -adaptive refinement, the effectivity indices are roughly constant, indicating that the error bound overestimates the error by a roughly constant factor. For reference purposes, we also calculate the standard IP DGFEM solution  $u_{h,p}$ , using



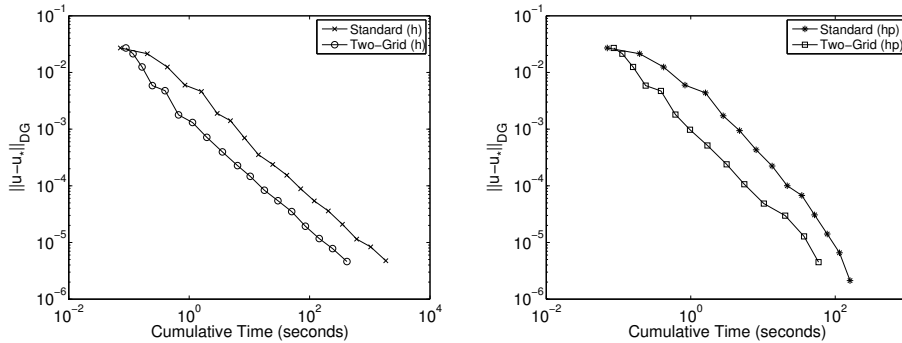


FIGURE 3. CPU timing of the IP DGFEM ( $u_* = u_{h,p}$ ) and the two-grid IP DGFEM ( $u_* = u_{2G}$ ) employing  $h$ - and  $hp$ -refinement.

both  $h$ - and  $hp$ -adaptive refinement; cf. Figure 2(a). Finally, in Figure 3 we compare the error in the standard and two-grid IP DGFEMs against the cumulative CPU time when both  $h$ - and  $hp$ -adaptive refinement are employed; here, we observe that the two-grid IP DGFEM is more efficient than the standard IP DGFEM.

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