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VARIATIONAL INEQUALITIES
AND APPROXIMATION

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A B S T R A C T

The existence and uniqueness of the solution of a variational inequality is considered, and methods of approximation of the solution are given.

Some elementary theorems concerning bilinear forms and antimonotone operators are given in the appendix.

Let H be a real Hilbert Space with its dual H' , whose inner product and norm are denoted by $((\cdot))$ and $\| \cdot \|$ respectively. The pairing between $f \in H'$ and $u \in H$ is denoted by (f, u) . Let F' be the Frechet differential of a nonlinear functional F on a closed convex set M in H .

Consider also a coercive continuous bilinear form $a(u, v)$ on H , i.e. there exists constants $\alpha > 0$, $\beta > 0$ such that

$$a(v, v) \geq \alpha \| v \|^2 \quad \text{for all } v \in H, \quad (1)$$

$$| a(u, v) | \leq \beta \| u \| \| v \| \quad \text{for all } u, v \in H. \quad (2)$$

Furthermore let F be a given element of H' . We now consider a functional $I[v]$ defined by

$$I[v] = a(v, v) - 2F(v) \quad \text{for all } v \in H.$$

Many mathematical problems either arise or can be formulated in this form. Here one seeks to minimize the functional $I[v]$ over a whole space H or on a convex set M in H . It is well—known [1] that if F is a linear functional, then the element u which minimizes $I[v]$ on M is given by

$$a(u, v-u) \geq (F, v-u) \quad \text{for all } v \in M. \quad (3)$$

For a nonlinear Frechet differentiable functional F , it was shown [3] that the minimum of the functional $I[v]$ on M is given by $u \in M$ such that

$$a(u, v-u) \geq (F'(u), v-u) \quad \text{for all } v \in M. \quad (4)$$

Such type of inequalities are known as variational inequalities [1]. Lions-Stampacchia. [1] have studied the existence of a unique solution of (3). The motivation for this report is to show that under certain conditions there does exist a unique solution of a more general variational inequality of which (4) is a special case.

Let us consider the following problem.

PROBLEM 1

Find $u \in M$ such that

$$a(u, v-u) \geq (Au, v-u) \quad \text{for all } v \in M, \tag{5}$$

where A is a nonlinear operator such that $Au \in H'$.

For $M = H$, the inequality (5) is equivalent to finding $u \in H$ such that

$$a(u, v) = (Au, v) \quad \text{for all } v \in H,$$

and thus our results include the Lax-Milgram lemma as a special case.

Definition

The operator $T : M \rightarrow H'$ is called antimonotone, if

$$(Tu - Tv, u - v) \leq 0 \quad \text{for all } u, v \in M,$$

and is said to be hemicontinuous [4], if for all $u, v \in M$, the mapping $t \in [0, 1]$ implies that $(T(u + t(v-u)), u - v)$ is continuous. Furthermore,

T is Lipschitz continuous, if there exists a constant $0 < \gamma \leq 1$ such that

$$\|Tu - Tv\| \leq \gamma \|u - v\| \quad \text{for all } u, v \in M.$$

Theorem 1.

Let $a(u, v)$ be a coercive continuous bilinear form and M

a closed convex subset in H . If A is a Lipschitz continuous antimonotone operator with $\gamma < \alpha$, then there exists a unique $u \in M$ such that (5) holds.

The following lemmas are needed for the proof.

Lemma 1 .

If A is an antimonotone hemicontinuous operator, then $u \in M$ is a solution of (5) if and only if u satisfies

$$a(u, v-u) \geq (Av, v-u) \quad \text{for all } v \in M \quad (6)$$

Proof

If for a given u in M , (5) holds, then (6) follows by the antimonotonicity of A .

Conversely, suppose (6) holds, then for all $t \in [0,1]$ and $w \in M$, $v_t \equiv u + t(w-u) \in M$, since M is a convex set. Setting $v = v_t$ in (6), we have

$$a(u, w-u) \geq (Av_t, w-u) \quad \text{for all } w \in M .$$

Now let $t \rightarrow 0$. Since A is hemicontinuous, $Av_t \rightarrow Au$. It follows that

$$a(u, w-u) \geq (Au, w-u) \quad \text{for all } w \in M.$$

The map $v \rightarrow a(u, v)$ is linear continuous on H , so by Reisz-Frechet theorem, there exists an element $\eta = Tu \in H'$ such that

$$a(u, v) = (Tu, v) \quad \text{for all } v \in H \quad (7)$$

Let Λ be a canonical isomorphism from H' onto H defined

by

$$(f, v) = ((\Lambda f, v)) \quad \text{for all } v \in H, f \in H' \quad (8)$$

Then $\|\Lambda\|_{H'} = \|\Lambda^{-1}\|_H = 1$. We note first that by (1),(2) and

(7), it follows that

$$(i) \quad \|T\| \leq \beta$$

$$(ii) \quad \alpha \leq \beta$$

The next lemma is a generalization of a lemma of Lions-Stampacchia [1].

Lemma 2

Let ζ be a number such that $0 < \zeta < \frac{2(\alpha - \gamma)}{\beta^2 - \gamma^2}$ and $\zeta < \frac{1}{\gamma}$

Then there exists a θ with $0 < \theta < 1$ such that

$$\|\phi(u_1) - \phi(u_2)\| \leq \theta \|u_1 - u_2\| \quad \text{for all } u_1, u_2 \in H,$$

where for $u \in H$, $\phi(u) \in H'$ is defined by

$$(\phi(u), v) = ((u, v)) - \zeta a(u, v) + \zeta (Au, v) \quad \text{for all } v \in H. \quad (9)$$

Proof:

For all $u_1, u_2 \in H$.

$$\begin{aligned} (\phi(u_1) - \phi(u_2), v) &= ((u_1 - u_2, v)) - \zeta a(u_1 - u_2, v) + \zeta (Au_1 - Au_2, v) \quad \text{for all } v \in H \\ &= ((u_1 - u_2, v)) - \zeta (T(u_1 - u_2), v) + \zeta (Au_1 - Au_2, v), \text{ by (7)} \\ &= ((u_1 - u_2, v)) - \zeta ((\Lambda T(u_1 - u_2), v)) + \zeta ((\Lambda Au_1 - \Lambda Au_2, v)), \text{ by (8)} \\ &= ((u_1 - u_2, v) - \zeta T(u_1 - u_2), v) + \zeta ((Au_1 - Au_2, v)) \end{aligned}$$

Thus

$$|(\phi(u_1) - \phi(u_2), v)| \leq \|u_1 - u_2 - \zeta AT(u_1 - u_2)\| \|v\| + \zeta \|Au_1 - Au_2\| \|v\|$$

for all $v \in H$.

Now using (7) and (8) we have

$$\begin{aligned} \|\mathbf{U}_1 - \mathbf{U}_2 - \zeta \mathbf{A} \mathbf{T}(\mathbf{u}_1 - \mathbf{u}_2)\|^2 &\leq \|\mathbf{u}_1 - \mathbf{u}_2\|^2 + \zeta^2 \|\mathbf{T}\|^2 \|\mathbf{u}_1 - \mathbf{u}_2\|^2 - 2\zeta \mathbf{a}(\mathbf{u}_1 - \mathbf{u}_2, \mathbf{u}_1 - \mathbf{u}_2) \\ &\leq (1 + \zeta^2 \beta^2 - 2\zeta \alpha) \|\mathbf{u}_1 - \mathbf{u}_2\|^2, \text{ by coercivity of } \mathbf{a}(\mathbf{u}, \mathbf{v}). \end{aligned}$$

Then

$$\begin{aligned} |(\phi(\mathbf{u}_1) - \phi(\mathbf{u}_2), \mathbf{v})| &\leq \sqrt{(1 + \zeta^2 \beta^2 - 2\zeta \alpha)} \|\mathbf{u}_1 - \mathbf{u}_2\| \|\mathbf{v}\| + \zeta \|\mathbf{A}\mathbf{u}_1 - \mathbf{A}\mathbf{u}_2\| \|\mathbf{v}\| \text{ for all } \mathbf{v} \in \mathbf{H}. \\ &\leq \theta \|\mathbf{u}_1 - \mathbf{u}_2\| \|\mathbf{v}\|, \text{ by the Lipschitz continuity of } \mathbf{A}, \end{aligned}$$

$$\text{and } \theta = \sqrt{1 + \zeta^2 \beta^2 - 2\zeta \alpha} + \gamma \zeta < 1 \text{ for } 0 < \zeta < 2 \frac{\alpha - \gamma}{\beta^2 - \gamma^2} \text{ and } \zeta < \frac{1}{\gamma}, \text{ because } \alpha > \gamma.$$

Hence for all $\mathbf{u}_1, \mathbf{u}_2 \in \mathbf{H}$

$$\|\phi(\mathbf{u}_1) - \phi(\mathbf{u}_2)\| = \sup_{\mathbf{v} \in \mathbf{H}} \frac{|(\phi(\mathbf{u}_1) - \phi(\mathbf{u}_2), \mathbf{v})|}{\|\mathbf{v}\|} \leq \theta \|\mathbf{u}_1 - \mathbf{u}_2\|.$$

The following results are proved by Mosco [2].

Lemma 3

Let M be a convex subset of \mathbf{H} . Then, given $z \in \mathbf{H}$ we have

$$\mathbf{x} = \mathbf{P}_M z,$$

if and only if

$$\mathbf{x} \in M; \quad ((\mathbf{x} - z, \mathbf{y} - \mathbf{x})) \geq 0 \quad \text{for all } \mathbf{y} \in M.$$

where \mathbf{P}_M is the projection of \mathbf{H} in M .

Lemma 4.

\mathbf{P}_M is non-expansive, i.e.,

$$\|\mathbf{P}_M z_1 - \mathbf{P}_M z_2\| \leq \|z_1 - z_2\| \quad \text{for all } z_1, z_2 \in \mathbf{H}.$$

Using the technique of Lions-Stampacchia [1] , we now prove theorem 1,

Proof of theorem 1,

(a) Uniqueness

Let $u_i, i=1,2$ be solutions in M of

$$a(u_i, v-u_i) \geq (Au_i-v, u_i) \quad \text{for all } v \in M.$$

Setting $v = u_{3-i}, i = 1, 2$ in the above inequality, by addition we have

$$a(u_1-u_2, u_1-u_2) \leq (Au_1-Au_2, u_1-u_2) .$$

Since $a(u,v)$ is a coercive bilinear form, there exists a constant $\alpha > 0$ such that

$$\alpha \| u_1-u_2 \|^2 \leq (Au_1-Au_2, u_1-u_2) \leq 0,$$

by the antimonotonicity of A . From which the uniqueness of the solution $u \in M$ follows.

(b) Existence

For a fixed ζ as in Lemma 2, and $u \in H$, define $\phi(u) \in H'$ by (9). By lemma 3, there exists a unique $w \in M$ such that

$$((w, v-w)) \geq (\phi(u), v-w) \quad \text{for all } v \in M,$$

and w is given by

$$w = P_M \wedge \phi(u) = Tu,$$

which defines a map from H into M .

Now for all $u_1, u_2 \in H$,

$$\begin{aligned} \|Tu_1 - Tu_2\| &= \|P_M \wedge \phi(u_1) - P_M \wedge \phi(u_2)\|, \\ &\leq \|\wedge \phi(u_1) - \wedge \phi(u_2)\|, \text{ by lemma 4,} \\ &\leq \|\phi(u_1) - \phi(u_2)\|, \\ &\leq \theta \|u_1 - u_2\|, \text{ by lemma 2.} \end{aligned}$$

Since $\theta < 1$, Tu is a contraction and has a fixed point $u = Tu$, which belongs to M , a closed convex set and satisfies

$$((u, v-u)) > (\phi(u), v-u) = ((u, v-u)) - \zeta [a(u, v-u) - (Au, v-u)]$$

Thus for $\zeta > 0$,

$$a(u, v-u) \geq (Au, v-u) \quad \text{for all } v \in M$$

showing that u is a unique solution of problem 1.

Remarks

1; It is obvious that for $Au = F'(u)$, the existence of a unique solution of a variational inequality (4) follows under the assumptions of theorem 1.

2: If A is independent of u , that is $Au = A'$ (say), then the Lipschitz constant γ is zero, and lemma 2 reduces to a lemma of

Lions-Stampacchia [1] and ζ is a number such that $0 < \zeta < \frac{2\alpha}{\beta^2}$.

Consequently theorem 1 is exactly the same as one proved by Lions-Stampacchia for the linear case. It is obvious that our result not only generalizes their result, but also includes it as a special case.

Method of Approximation

Suppose that the bilinear form is non-negative, i.e.

$$a(v,v) \geq 0 \quad \text{for all } v \in H. \quad (10)$$

Assume that there exists at least one solution $u \in M$ of

$$a(u,v-u) \geq (Au,v-u) \quad \text{for all } v \in M \quad (11)$$

and X is the set of all solutions of (11). Let, finally, $b(u,v)$ be a coercive bilinear form on H , that is there exists a constant $\alpha > 0$ such that

$$b(v,v) \geq \alpha \|v\|^2 \quad \text{for all } v \in H \quad (12)$$

First of all we prove some elementary but important lemmas.

Lemma 5

If $a(u,v)$ is a non-negative bilinear form and $u \in M$, then the inequality (5) is equivalent to the inequality

$$a(v,v-u) \geq (A(u),v-u) \quad \text{for all } v \in M. \quad (13)$$

Proof

Let (5) hold, then

$$a(v,v-u) \geq (A(u),v-u) + a(v-u,v-u) \geq (A(u),v-u), \text{ by (10).}$$

Thus (13) holds;

Conversely let (13) hold, then for all $t \in [0,1]$ and $w \in M$, $v_t = u + t(w-u) \in M$. Setting $v=v_t$ in (13) it follows that

$$a(u,w-u) + t a(w-u,w-u) \geq (A(u),w-u), \text{ for all } w \in M.$$

Letting $t \rightarrow 0$, (5) follows.

As a consequence of lemma 1 and lemma 5 we have the following result.

Lemma 6.

If $a(u,v)$ is non-negative bilinear form and A is hemicontinuous

antimonotone operator, then the inequality (5) is equivalent to
 $a(v, v-u) \geq (Av, v-u)$ for all $v \in M$.

Theorem 2

If $b(u, v)$ is a coercive continuous bilinear form and B is a Lipschitz continuous antimonotone operator with $\Upsilon < \alpha$ then there exists a unique solution $u_0 \in X$ such that

$$b(u_0, v-u_0) \geq (Bu_0, v-u_0) \text{ for all } v \in X. \tag{14}$$

Proof:

Obviously X is closed. In order to prove theorem (2), it is enough to show that X is convex. Since $a(u, v)$ is non-negative, so (11) is equivalent to

$$a(v, v-u) \geq (Av, v-u), \text{ by lemma 6 .}$$

Now for all $t \in [0, 1]$, $u_1, u_2 \in X$,

$$\begin{aligned} a(v, v-u_2-t(u_1-u_2)) &= a(v, v-u_2) - t a(v, u_1-u_2) \\ &= a(v, v-u_2) - t a(v, u_1 - v + v - u_2) \\ &= a(v, v-u_2) + t a(v, v-u_1) - t a(v, v-u_2) \\ &= (1-t) a(v, v-u_2) + t a(v, v-u_1) \\ &\geq (1-t) (Av, v-u_2) + t (Av, v-u_1), \end{aligned}$$

by lemma 6 .

Thus for all $t \in [0, 1]$, $u_1, u_2 \in X$, $tu_1 + (1-t)u_2 \in X$, which implies that X is a convex set. Hence by theorem (1), there does exist a unique solution $u_0 \in X$ satisfying (14).

Theorem 3

Assume that (10) and (12) hold. If $a(u, v) + \epsilon \in b(u, v)$ is a

continuous bilinear form and A, B are both antimonotone Lipschitz continuous with $Y < \alpha$, then there exists a unique solution $u_\varepsilon \in M$ such that

$$a(u_\varepsilon, v - u_\varepsilon) + \varepsilon b(u_\varepsilon, v - u_\varepsilon) \geq (Au_\varepsilon - \varepsilon Bu_\varepsilon, v - u_\varepsilon) \quad \text{for all } v \in M. \quad (15)$$

Proof:

Since for $\varepsilon > 0$ and by (10), (12), the continuous bilinear form $a(u, v) + \varepsilon b(u, v)$ is coercive on H , then by theorem 1, there exists a unique $u_\varepsilon \in M$ satisfying (15).

Using lemma 1 and the methods of Sibony [4] and Lions-Stampacchia [1], we prove that the elements of X can be approximated.

Theorem 4

Suppose $A, B: M \rightarrow H'$ are both hemicontinuous operators and the assumptions of theorems (2) and (3) hold. If u_0 is the element of X defined by (14) satisfying

$$a(u_0, v - u_0) \geq (Au_0, v - u_0) \quad \text{for all } v \in X. \quad (16)$$

and u_ε is the element of M defined by (15), then

$$u_\varepsilon \rightarrow u_0 \text{ strongly in } H \text{ as } \varepsilon \rightarrow 0.$$

Proof:

This is proved in three steps.

(i) u_ε is bounded in H .

Setting $v = u_0$ in (15) and $v = u_\varepsilon$ in (16), we get

$$a(u_\varepsilon, u_0 - u_\varepsilon) + \varepsilon b(u_\varepsilon, u_0 - u_\varepsilon) \geq (Au_\varepsilon + \varepsilon Bu_\varepsilon, u_0 - u_\varepsilon)$$

and

$$a(u_0, u_\varepsilon - u_0) \geq (Au_0, u_\varepsilon - u_0)$$

By addition of these inequalities, it follows from (10) and the antimonicity of A that

$$b(u_\varepsilon, u_0 - u_\varepsilon) \geq (Bu_\varepsilon, u_0 - u_\varepsilon) \quad (17)$$

Since $b(u_\varepsilon, u_\varepsilon)$ is a coercive bilinear form, there exists a constant $\alpha > 0$ such that

$$\alpha \|u_\varepsilon\|^2 \leq b(u_\varepsilon, u_0) + (Bu_\varepsilon, u_0 - u_\varepsilon).$$

It follows that $\|u_\varepsilon\| \leq \text{constant}$, independent of ε . Hence there exists a subsequence u_ε which converges to ξ , say.

(ii) ξ belongs to X.

Since A and B are antimonic operators, by (15) and the application of lemma 1, we get

$$a(u_\varepsilon, v - u_\varepsilon) + \varepsilon b(u_\varepsilon, v - u_\varepsilon) \geq (Av + \varepsilon Bv, v - u_\varepsilon) \quad \text{for all } v \in M.$$

Now let $\varepsilon \rightarrow 0$, then $u_\varepsilon \rightarrow \xi$ and $\liminf a(u_\varepsilon, u_\varepsilon) \geq a(\xi, \xi)$, [1] We have

$$a(\xi, v - \xi) \geq (Av, v - \xi) \quad \text{for all } v \in X,$$

which is by lemma 1 equivalent to

$$a(\xi, v - \xi) \geq (A\xi, v - \xi) \quad \text{for all } v \in X.$$

Thus $\xi \in X$.

(iii) Finally $\|u_\varepsilon\| \rightarrow \|c\|$ when $\varepsilon \rightarrow 0$,

Setting $v = u \in X$ in (15) and $v - u_\varepsilon \in X$ in (11)

We obtain

$$a(u_\varepsilon, u - u_\varepsilon) + \varepsilon b(u_\varepsilon, u - u_\varepsilon) \geq (Au_\varepsilon + \varepsilon Bu_\varepsilon, u - u_\varepsilon),$$

which is, by lemma 1, equivalent to

$$a(u_\varepsilon, u - u_\varepsilon) + \varepsilon b(u_\varepsilon, u - u_\varepsilon) \geq (Au + \varepsilon Bu, u - u_\varepsilon)$$

Also,

$$a(u, u_\varepsilon - u) \geq (Au, u_\varepsilon - u)$$

By addition one has

$$a(u_\varepsilon - u, u - u_\varepsilon) + \varepsilon b(u_\varepsilon, u - u_\varepsilon) \geq \varepsilon (Bu, u - u_\varepsilon)$$

Using (10), and for $\varepsilon > 0$, we get

$$b(u_\varepsilon, u - u_\varepsilon) \geq (Bu, u - u_\varepsilon) \quad \text{for all } u \in X.$$

Letting $\varepsilon \rightarrow 0$, $u_\varepsilon \rightarrow \xi$, we have

$$\begin{aligned} b(\xi, u - \xi) &\geq (Bu, u - \xi) \\ &\geq (B\xi, u - \xi), \quad \text{by lemma 1.} \end{aligned}$$

Thus $\xi \in X$ is a solution of (14) and since the solution is unique, it follows that $\xi = u_0$.

Also from (17), by the coercivity of $b(u_\varepsilon, u_\varepsilon)$, it follows that there exists a constant $\alpha > 0$ such that

$$\begin{aligned} \alpha \|u_\varepsilon - u_0\| &\leq b(u_\varepsilon - u_0, u_\varepsilon - u_0) \\ &\leq (Bu_\varepsilon, u_\varepsilon - u_0) - b(u_0, u_\varepsilon - u_0) \\ &\leq (Bu_0, u_\varepsilon - u_0) - b(u_0, u_\varepsilon - u_0), \text{ by lemma 1,} \end{aligned}$$

which $\rightarrow 0$, as, $\varepsilon \rightarrow 0$. Hence it follows that $u_\varepsilon \rightarrow u$ strongly in H .

Theorem 5

If $a(u, v)$, $b(u, v)$ are coercive continuous bilinear forms, M is a closed convex set in H , and A, B are hemicontinuous antimonotone Lipschitz continuous operators with $\alpha > \gamma$, then problem 1 has a

unique solution if and only if there exists a constant L , independent of ε , such that the solution of (15) satisfies

$$\| u_\varepsilon \| \leq L \tag{18}$$

Proof:

If there exists a solution, then from theorem 4, it follows that (18) holds. Conversely suppose that (18) holds, then there exists a subsequence u_{η} of u_ε which converges to

w weakly in H . Since M is a closed convex set, $w \in M$, Further writing (15) in the form

$$a(u, u - v) + \varepsilon b(u_\varepsilon, u_\varepsilon - v) \leq (Av + \varepsilon Bv, u_\varepsilon - v) \quad \text{for all } v \in M$$

and taking $\varepsilon \rightarrow \eta = 0$, we find that

$$a(w, w) \leq a(w, v) + (Av, w - v) \quad \text{for all } v \in M,$$

which is by lemma 1, equivalent to

$$a(w, w - v) \leq (Aw, w - v) \quad \text{for all } v \in M.$$

Thus w is the solution satisfying (11).

Existence of Solutions

In this section, the existence of the solution satisfying (10) for the cases, when M is bounded or an unbounded convex subset of H is considered.

Theorem 6

If M is a bounded closed convex subset, and A is a hemicontinuous Lipschitz antimonotone operation, then there exists a unique solution of problem (1).

Proof:

Let $u_\varepsilon \in M$ be the element defined by (15). Since M is bounded, then $\|u_\varepsilon\|$ is bounded, and theorem (6) follows from theorem (5).

Consider now the case when the set M is bounded. Let $M_R = \{k ; k \in M, \|k\| \leq R\}$ with R large enough so that $M_R \neq \emptyset$. Assume that A is hemicontinuous antimonotone operator, then by theorem (6), there exists a non-empty set,

$$X_R \equiv \text{set of all solution of } w \in M_R \text{ with} \tag{19}$$

$$a(w, v-w) \geq (Aw, v-w) \quad \text{for all } v \in M_R$$

Theorem 7

Suppose $a(u, v)$ is a continuous bilinear form and A is a hemicontinuous antimonotone operator. If $u \in X_R$ with $\|u\| < R$, then u satisfies (11).

Proof

In fact, let w be any solution in M . Then for $0 < \varepsilon < 1$, $u + \varepsilon(w-u) \in M$ and $\|u + \varepsilon(w-u)\| \leq \|u\| + \varepsilon \|w-u\| < R$ for sufficiently small ε . Thus for $0 < \varepsilon < \varepsilon_1$, $v = u + \varepsilon(w-u) \in M_R$.

Consequently such a v is allowed in (19) with $w = u$
and it follows that

$$a(u, w-u) \geq (Au, w-u) \quad \text{for all } w \in M.$$

This proves theorem 7.

APPENDIX

Let $a(u,v)$ be a coercive continuous bilinear form on H .
The Cauchy-Schwarz inequality holds for $a(u,v)$ and is given by

$$|a(u,v)|^2 \leq a(u,u)a(v,v) \quad \text{for all } u,v \in H.$$

Theorem 8

A bounded bilinear form is continuous with respect to the norm convergence.

Proof:

Let $u_n \rightarrow u$ and $v_n \rightarrow v$, these sequences are bounded. We let Y be their bound, and then $\|u_n\| \leq Y$.

Now

$$\begin{aligned} |a(u_n, v_n) - a(u, v)| &= |a(u_n, v_n) - a(u_n, v) + a(u_n, v) - a(u, v)| \\ &\leq |a(u_n, v_n - v)| + |a(u_n - u, v)| \\ &\leq C \gamma \|v_n - v\| + C_1 \|u_n - u\| \|v\|, \end{aligned}$$

by the Cauchy-Schwarz inequality. But $\|u_n - u\| \rightarrow 0$ and

$\|v_n - v\| \rightarrow 0$ as $n \rightarrow \infty$, and therefore

$$\begin{aligned} |a(u_n, v_n) - a(u, v)| &\rightarrow 0, \text{ i.e.,} \\ a(u_n, v_n) &\rightarrow a(u, v). \end{aligned}$$

Theorem 9

Let v be in H and M be a closed convex subset of H . If u is a minimizing vector and $a(x,v)$ is any continuous bilinear form such

that $a(x,y) = ((x,y))$, for all $x,y \in H$, then

$$a(u-v, w-u) \geq 0 \quad \text{for all } w \in M. \quad (20)$$

Conversely if (19) holds and $a(u,v)$ is also coercive, then

$$\|u-v\| \leq \alpha^{-1} c \|w-v\| \quad \text{for all } w \in M.$$

Proof:

If u is the unique minimizing vector, then we have to show that $a(u-v, w-u) \geq 0$ for all $w \in M$.

Suppose to the contrary that there is a vector $v_1 \in M$ such that $a(u-v, u-v_1) = \varepsilon > 0$. For all $t \in [0,1]$ and $v_1 \in M$, $v_t \equiv u + t(v_1-u) \in M$,

Now

$$\begin{aligned} \|v_t - v\|^2 &= \|u + t(v_1-u) - v\|^2 \\ &= \|u-v\|^2 + t^2 \|v_1-u\|^2 + 2t(u-v, v_1-u) \\ &< \|u-v\|^2, \end{aligned}$$

for, small positive t , which contradicts the minimizing property of u . Hence no such v_1 can exist.

Conversely let $u \in M$ such that (20) holds, then for any $w \neq u$, $w \in M$,

$$0 \leq a(u-v, w-u) = a(u-v, w-v + v-u)$$

implies that

$$a(u-v, u-v) \leq a(u-v, w-v).$$

Since $a(u, v)$ is a continuous coercive bilinear form, there exist constants $c > 0$, $\alpha > 0$ such that

$$\alpha \|u-v\|^2 \leq c \|u-v\| \|w-v\| \quad \text{for all } w \in M,$$

i.e.,

$$\|u-v\| \geq \alpha^{-1} c \|w-v\| \quad \text{for all } w \in M.$$

The following representation of the differentiable functions is needed

$$F(u) - F(v) = \int_0^1 (u - v, F'(v + s(u - v))) ds.$$

Theorem 10.

If F' is antimonotone, then the real-valued functional F is weakly upper semicontinuous and concave.

Proof:

Consider

$$\begin{aligned} F(u_n) - F(u) &= \int_0^1 (u_n - u, F'(u + s(u_n - u))) ds \\ &= \int_0^1 (u_n - u, F'(u)) ds + \int_0^1 (u_n - u, F'(u_n + s(u_n - u)) - F'(u)) ds \end{aligned}$$

If $u_n \rightarrow u$ weakly, as $n \rightarrow \infty$, then the first term on R.H.S. tends to zero. The second term is always non-positive. In fact, by antimonotonicity $(u_n - u, F'(u + s(u_n - u)) - F'(u)) \leq 0$ for all $0 \leq s \leq 1$, and therefore the integrand ≤ 0 for all $0 \leq s \leq 1$. Hence for a sufficiently large n , there exists $\varepsilon_n \rightarrow 0$ as $n \rightarrow \infty$ such that $F(u_n) - F(u) \leq \varepsilon_n$, i.e.,

$$\lim_{n \rightarrow \infty} \sup F(u_n) \leq F(u).$$

Thus F is a weakly upper semicontinuous functional. Using a similar argument, it can be seen that the antimonotonicity of F' guarantees concavity of F .

Theorem 11.

If a functional F is concave on a convex set M , then the

Frechet differential F' of F is antimonotone .

Proof:

For all $t \in [0,1]$ and $u,v \in M$, $tu+(1-t)v = v + t(u-v) \in M$.

By definition

$$F(v+t(u-v)) \geq t F(u) + (1-t)F(v)$$

Dividing both sides by t , and letting $t \rightarrow 0$, we get

$$F'(v),u-v \geq F(u) -F(v)$$

Similarly

$$(F'(u),v-u) \geq F(v) -F(u)$$

By addition, it follows that

$$(F'(v) - F'(u) ,u-v) \geq 0 \quad \text{for all } u,v \in M.$$

Thus from theorem 10 and theorem 11 one concludes that
"A real—valued functional on a convex set in a Hilbert space
is concave if and only if its Frechet differential is an
antimonotone operator".

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