

1 **Development of VR/AR applications for experimental tests of beams, columns and**  
2 **frames**

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24  
25 **Abstract**

26 This paper depicts a set of virtual reality (VR) and augmented reality (AR) applications  
27 conceived for the enrichment of laboratory experiences within the field of structural  
28 engineering. The experimental program correspond to the study of beams, columns and  
29 frames of austenitic stainless steel subjected to different types of static loading. The  
30 development of these applications encompasses the use of measured data from sensors,  
31 the use of 3D modelling tools, the use of game engines, and the corresponding  
32 mathematical treatment and post-process of the structural tests in a real-time fashion. The  
33 developed applications provided new possibilities for structural engineering laboratory  
34 experiences. In both cases (VR and AR), the developed applications were meant to  
35 enhance the experimental program experience to a variety of target users (researchers,  
36 technicians, students) by adding customized information related to the structural behavior  
37 of all elements during the tests as well as to basic concepts of health and safety in  
38 structural engineering laboratories.

39  
40 **Keywords:** Virtual Reality, Augmented Reality, Tests, Structural elements

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43 **Introduction**

44  
45 The role of structural engineering laboratories in the development of research, design and  
46 education within the Architecture, Engineering and Construction (AEC) fields is  
47 paramount. Research on new materials and/or structural configurations, the use of design  
48 assisted by testing or the relentless development of structural monitoring and control are  
49 only few of the needs that are routinely addressed and solved worldwide in those facilities.  
50 Historically, instrumentation and control in structural engineering laboratories has

51 included cutting-edge high-precision measurement techniques from which strains,  
52 displacements, forces, accelerations, pressures and several other physical magnitudes are  
53 gathered. Routinely performed tests on structural elements include sensors, data  
54 acquisition systems and classical visualization of measurements in the form of plots, bars  
55 or numbers. Usually, during the tests, the gathered data is recorded and the analysis of the  
56 results is only performed afterwards via post-processing.

57  
58 Measurement techniques and the degree of sophistication of the tests performed in  
59 structural engineering laboratories as well as in construction sites have evolved  
60 considerably. The data acquisition has experienced a surge both quantitatively and  
61 qualitatively. Classical tests on structural elements, are nowadays infused with data-  
62 intensive techniques such as digital image correlation (Lee et al. 2012), ubiquitous and  
63 innovative sensors (Sony et al. 2018), terrestrial laser scanning (Olsen et al. 2010), or  
64 tests based on hybrid simulations (Del Carpio Ramos et al. 2015). Therefore, a need of  
65 massive data-management tools as well as of massive data-visualization techniques  
66 emerges not only for laboratory facilities but also, for structural control at construction  
67 sites. Several technological players are providing potential frameworks for the creation  
68 of both standard data-management hubs as well as for the creation of data-visualization  
69 interfaces.

70  
71 For data-management, Building Information Modeling (BIM) tools are becoming main  
72 players when it comes to centralize information related to design (different information  
73 layers interact in the same model). Centralizing data at design stages for the  
74 corresponding interoperability in construction has been a great challenge in recent years  
75 (Hardin and McCool 2015, Cerovsek 2011). Integrated models encompassing all  
76 stakeholders present manifold aspects such as 3D modeling, constructability, structural  
77 analysis, material management and post occupancy evaluation. These fields are  
78 increasingly interacting throughout platform-neutral specifications such as Industry  
79 Foundation Classes (IFC), a data model intended to describe building and construction  
80 industry data or the Linked Building Data.

81  
82 For data-visualization, endless alternatives are available in many fields. The level of  
83 sophistication when it comes to data-visualization techniques increases relentlessly in  
84 other areas and thus, the AEC sector is continuously infused with such possibilities.  
85 Particularly in construction, Digital Twins (Kaewunruen and Lian 2019), Serious Games  
86 (Rüppel et al. 2011), Virtual Reality (VR) (Kim et al. 2013) and Augmented Reality (AR)  
87 (Behzadan and Kamat 2013) applications are data-visualization techniques that have been  
88 continuously explored.

89  
90 In this paper, a set of VR and AR applications aimed at enriching tests on structural  
91 elements are developed and assessed. These applications were conceived and assessed as  
92 potential experience- and cognitive-enhancers for different user groups. The experimental  
93 program on which the application were developed correspond to real tests on beams,  
94 columns and frames of austenitic stainless steel subjected to different types of static  
95 loading. The development of the applications encompassed the use i) game engines in the  
96 development of VR/AR applications ii) the use of measured data from sensors and the  
97 corresponding mathematical treatment and post-process of the structural tests in a real-  
98 time fashion and iii) 3D BIM tools able to centralize data in adequate standard form. The  
99 observations performed during the development and the corresponding appraisal allow

100 pinpointing advantageous and challenging remarks in the potential of VR/AR in structural  
101 engineering experimental environments.

## 104 **Literature review**

### 106 *VR/AR in research and education*

108 VR and AR technologies are relatively well-established tools with a diversity of  
109 applications spanning many fields. VR is an interactive simulated environment generated  
110 with computers (Sherman and Craig 2018) which replaces the user's physical world with  
111 a fully synthetic environment. The interaction between such environment and the user is  
112 typically generated with special screens, sound systems and joysticks embedded in  
113 customized helmets or glasses. AR is a real-world environment enriched with layers of  
114 information that are perceived by the user by means of multiple modalities. Screen-  
115 infused glasses with embedded hardware are one typical application of AR systems. In  
116 such scenario, the user's awareness of the real environment is preserved by compositing  
117 physical/virtual worlds in a blended space (Craig 2013). The user sees the real  
118 environment and layers of graphical information (or text) that is added and updated in  
119 real time. Although both VR/AR technologies are decades old in their simplest forms, the  
120 societal perception of these technologies is not as mature as the technologies themselves.  
121 The level of sophistication has increased with the relentless improvement in Hardware  
122 and Software and consequently, better CPUs, GPUs, data-storage facilities and cloud  
123 computing have enabled the use of more affordable gear to all kinds of developers. One  
124 of the uncontested contributions of VR/AR is their potential to enhance sensorial  
125 perception as well as to trigger advanced learning to users by means of immersive  
126 experience since realistic immersive creations represent tools for visual communication  
127 of massive data. In the particular case of VR/AR, benefits from 3D visualizations can be  
128 highlighted at educational (Chi et al. 2013), design (Dong et al., 2013) and construction  
129 stages (Behzadan et al. 2015).

131 From a pedagogical point of view, the cognitive-enhancement capabilities provided by  
132 VR/AR technologies have been studied in many fields such as economics (Innocenti  
133 2017) neurosurgery (Pelargos et al. 2017), cultural tourism education (Chiao et al. 2018)  
134 and pedagogy (Rau et al. 2018), to cite a few. In the AEC field, attention has also been  
135 paid to the pedagogical benefits that VR/AR technologies provide. Research aimed at  
136 assessing the cognitive effects of VR/AR techniques on the increase of spatial abilities in  
137 engineering graphics courses has been presented (Chen et al. 2011). Systematic reviews  
138 on this topic are also available (Keenaghan 2014). Attempts for infusing AR mobile-  
139 based tools as information delivery tool have successfully been implemented in  
140 classroom-scale experiments to enhance traditional lecture-based instruction and  
141 information delivery methods (Shirazu and Behzadan 2015, Behzadan & Kamat 2013).

143 At the analysis/design stage of AEC projects, VR/AR tools have been developed in  
144 several forms (Kim et al. 2013). From systems that integrate real-time simulations based  
145 upon Finite Element (FE) models and AR technologies (Huang et al., 2015) to systems  
146 that provide enriched information to designers in processes of piping assemblies (Hou et  
147 al. 2015), VR/AR technologies prove usefulness at decision-making levels of design. In  
148 (Turkan et al., 2017), advanced interactive 3D visualization techniques were piloted for  
149 enhancing students' perception and understanding of load effects, load paths and in

150 general, the ability to understand the deformed shape of simple structures. Moreover,, in  
151 (Ge and Kuester, 2015), an integrative data analysis environment for conceptual structural  
152 analysis is presented. Design, modeling and simulation are integrated together with  
153 sensors, devices and interfaces. The results presented in these papers suggest that standard  
154 framework are desired when integrating sensor measurement, Finite Element Analysis  
155 (FEA) simulation, design and scientific visualization into AR-based environment. This  
156 integration facilitate data post-processing and interpretation of results.

157  
158 At the construction site, as well as in all aspects related to construction (including safety  
159 management), a fairly varied ecosystem of VR/AR tools has been presented in academia.  
160 In particular, AR tools aimed at enriching the construction discussion have been presented  
161 in academic journals and conferences in the field (Fernandes et al. 2006, Lin et al. 2015,  
162 Kassem et al. 2017). One of the fields in which VR/AR have been explored considerably  
163 is the one related to safety management. VR/AR-based experience- and cognitive  
164 enhancers aimed at generating multi-modal levels of awareness for workers/researchers  
165 and students alike can be found in (Li et al. 2018, Park and Kim 2013, Ruppel and Schatz  
166 2011). VR serious games have been developed for hazard management and evacuations  
167 during disasters (Lovreglio et al., 2018).

168 In the particular topic of laboratories, experimental tests infused with augmented reality  
169 have been documented in academia in recent years. AR applications have been developed  
170 in science laboratories for the sake of enriching cognition (Andújar et al. 2010, Akçayir  
171 et al., 2016, Smith et al. 2016). These studies were fundamentally focused on studying  
172 the effect of AR on skills and attitudes towards experimental testing. Examples of use of  
173 AR in laboratories of chemistry (Yee et al., 2018), earth sciences (Vaughan et al, 2017)  
174 and medicine (Hanna et al., 2018) are documented. In the particular case of structural  
175 engineering, information is less abundant. (Basías et al., 2018) developed experiments in  
176 simply supported and cantilever beams provided with perspective projection video  
177 cameras and markers to track the beam motion during different types of loading. The goal  
178 of this study was to embed reduced order modeling in physical experiments for the sake  
179 of augmenting video streams through numerical simulations. These models proved  
180 interesting for such visualizations since they provide cost-effective numerical solutions  
181 of highly nonlinear problems with less computing capacity. In such research, neither  
182 sensors nor 3D rendering engines were used.

#### 183 184 185 *VR/AR in BIM environments*

186  
187 Moreover, the development of VR/AR applications that infuse real-time measurements  
188 generally implies intensive use of i) 3D modeling tools, ii) the use of multi-user platforms  
189 capable of rendering data-infused real-time applications and iii) the use of data in  
190 standardized form. BIM-based technologies allow centralizing all types of information in  
191 data-hubs. The parametric abilities, the multi-purpose nature of BIM-based platforms and  
192 their data-aggregation and analysis satisfy the needed requirements for their use of  
193 VR/AR in construction. Applications of VR/AR in the AEC field are not only meaningful  
194 due to their visualization capabilities but also, to their contribution to all workflows,  
195 processes, technologies and behaviors that BIM increasingly offer. Although the topic of  
196 data-driven analysis in BIM platforms is out of the scope of this case study, it is observed  
197 that the evolution of data-standardization in recent years is paramount for the  
198 development of integrated interoperable tools (Cerovsek 2011, Hardin and McCool 2015,  
199 Li et al. 2017). The navigation from BIM platforms to/from game engines implies

200 working on problems such as latency (Du et al. 2018), model updating, data-flow and  
201 real-time rendering (Yan et al. 2011) of the applications. Usually, tracking and sensing  
202 technologies such as radio frequency identification (RFID), laser pointing, sensors and  
203 motion tracking are needed for the sake of increasing the effectiveness of such  
204 applications (Wang et al. 2013).

205  
206 To tackle the interoperability issue, academic consensus suggest the adoption of Industry  
207 Foundation Classes (IFC) as the data exchange schema between BIM and other  
208 computerized maintenance management systems (Shalabi and Turkan 2017). Monitoring  
209 and control BIM tools, which heavily rely on proper data-acquisition from sensors, are  
210 increasingly based on standards defined by IFC (Theiler and Smarsly 2018, Ding et al.  
211 2017). Cloud services for ubiquitous sensing in AEC are generally based on JavaScript  
212 Notation Formats (JSON) which represent a popular lightweight data-interchange format  
213 for numerous AEC-related Software and web applications (Afsari et al. 2017).  
214 Notwithstanding, other initiatives based upon semantic web ontologies such as the Linked  
215 Building Data also provide conceptual frameworks for the development of BIM-based  
216 interoperable applications (Gómez-Romero et al. 2015, Radulovic et al. 2015).

### 217 *Summary*

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220 Summarizing, the literature review allows pinpointing some remarks:

- 221  
222 • VR/AR applications are found in the AEC in particular, at construction stages as  
223 cognitive enhancers for workers. Health and safety regulations infused with  
224 VR/AR is an active research topic. On the other hand, at design stages, academic  
225 papers are less abundant. Some authors suggest that standard framework are  
226 desired when integrating sensor measurement, Finite Element Analysis (FEA)  
227 simulation, design and scientific visualization. This integration facilitate data  
228 post-processing and interpretation of results. In addition, developing frameworks  
229 following BIM allow considering data flow in a standard fashion.
- 230  
231 • Education-wise, VR/AR applications have been developed and academically  
232 documented in numerous fields (Akçayir & Akçayir, 2017, Ibañez & Delgado-  
233 Kloos, 2018). Nevertheless, academic record related to the use as a cognitive  
234 enhancer is mainly focused on the use of VR/AR based on static information  
235 (layers with meaningful yet asynchronous information that is uploaded and stored  
236 prior to its usage).
- 237  
238 • Laboratory applications in which VR/AR tools are developed can be found in  
239 some fields. Sciences, medical and chemistry laboratories are among those in  
240 which academic papers can be found. VR/AR applications in civil engineering  
241 aimed at enriching laboratory experiences (both research- and education-wise)  
242 are, however less abundant.

243  
244 In this paper, an integrative set of VR/AR applications encompassing simulation and  
245 laboratory applications infused with sensors is developed. This approach includes  
246 systems and parts of systems that are found in the literature but in this case, the novelty  
247 stems in its integration within the field of experimental structural engineering. These  
248 applications are conceived for various target users (researchers, students and technical

249 staff) belonging to a vast experimental program on beams, columns and frames described  
250 in the following sections.

251

## 252 **Experimental program**

253

254 The experimental program on which the VR/AR applications have been developed  
255 corresponds to a series of tests on EN 1.4301 austenitic stainless steel beams, columns  
256 and frames. The tests were performed at the structural and materials technology laboratory  
257 LATEM at the Polytechnic University of Catalonia, Spain. The experimental program  
258 belongs to a research project aimed at studying the behavior of stainless steel frames  
259 under accidental actions both experimentally and numerically. The experimental program  
260 covers the study of stainless steel structures at material, member and structure levels  
261 including variations of cross-section (compact, semi-compact, slender) and global  
262 slenderness (sway, non-sway frames). The numerical program covers a broader range of  
263 studies including the behavior of frames subjected to static, seismic and fire loading. The  
264 experimental study includes both traditional high-precision measurement techniques for  
265 loads, displacements and strains as well as novel measurement and data-gathering  
266 techniques such as DIC, real-time visualization of the results in the form of digital twins,  
267 the use of cloud-based platforms for data storage and VR/AR immersive tools for the  
268 enhancement of the tests experiences. In this case study, only the general organization of  
269 the tests and results related to VR/AR applications are depicted. Figure 1 shows lateral  
270 views of the tests whereas Table 1 displays nominal geometries of all elements as well as  
271 some particular observations of each test. Further details about the experimental program  
272 on members and frames can be found in (Arrayago et al. 2019<sup>a</sup>, Arrayago et al. 2019<sup>b</sup>,  
273 Arrayago et al. 2019<sup>c</sup>).

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276 The tests on stainless steel beams consisted of 4 simply supported 1700 mm long  
277 specimens. Two concentrated loads were symmetrically applied as shown in Fig. 1 (a).  
278 The variation between elements was related to cross-sectional properties. The elements  
279 cross-sectional behavior ranged from compact to slender. The tests consisted on static  
280 incremental loading of the specimens. Sensor-infused VR applications were developed  
281 for visually enriching the experiments. For this purpose, the vertical deflection  $\delta_{\text{beam}}$  at  
282 mid-span was measured by using a distance sensor. Under the assumption of elastic beam  
283 theory and neglecting all geometrical and material nonlinearities, the behavior of the  
284 structure was characterized by this single magnitude at this stage.

285

286 The tests on stainless steel columns consisted of 8 pinned-pinned 1500 mm long  
287 specimens. The variations between elements were related to cross-sectional properties as  
288 well as to the position of the element during the test (since both major and minor axes  
289 were tested). The tests consisted on incremental axial loading of the specimens. VR  
290 applications were developed for these experiments. For this purpose, the horizontal  
291 deflection  $\delta_{\text{column}}$  at mid-span was measured by using a distance sensor. Under the  
292 assumption of elastic buckling theory in beams and neglecting all geometrical and  
293 material nonlinearities, the behavior of the structure was characterized by this single  
294 magnitude. Fig. 1(b) displays lateral view of the test deployment.

295

296 The tests on stainless steel frames consisted of 4 one-bay one-story specimens as indicated  
297 in Fig. 1(c). Two frames were designed as sway whereas the other two frames were  
298 designed as non-sway. All tests followed the same procedure. First, a vertical load  $P_v$  was

299 applied up to a pre-determined value (and held constant during subsequent steps). Second,  
300 a horizontal load was applied incrementally until failure. The application of this  
301 horizontal load was performed by means of a hydraulic jack that pushed a rigid beam  
302 laterally. The rigid beam was connected to both bottom ends of the frame whereas the  
303 upper beam-to-column joint was fixed. It is worth noticing that due to laboratory  
304 requirements, the imposed displacement  $\delta_{\text{frame}}$  was located at the bottom part. The main  
305 reason of this arrangement is the vertical load application, since hydraulic jacks were  
306 fixed in a vertical line. The horizontal displacement  $\delta_{\text{frame}}$  of the rigid beam was measured  
307 by using a distance sensor. Under the assumption of elastic buckling theory in frames,  
308 neglecting all geometrical and material nonlinearities and using the vertical load as a  
309 known of the problem, the behavior of the structure was characterized entirely by  $P_v$  and  
310  $\delta_{\text{frame}}$ . AR applications were developed for these experiments.

## 315 **Design of the system**

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317 All VR/AR systems were developed entirely from scratch. Three premises were set when  
318 developing these systems: i) the system ought to provide platform inter-operability, ii)  
319 the system addresses all parts of the information (from sensor to visual perception by end-  
320 users) and iii) the tools must be as versatile and replicable as possible. Figure 2 shows the  
321 basic parts of the system as well as the identified data-flow that was used for the  
322 conception of all parts. From left to right, one can observe how data is generated by  
323 sensors and transmitted to web servers. In this particular study, data was sent in JSON  
324 format to a game engine as well as to adequate mathematical post-processing (coding  
325 platforms). Post-processed data was also sent from mathematical post-processing in  
326 JSON formats to game engines. In addition, 3D models were rendered in platforms based  
327 on standard BIM capabilities and exported to game engines. Finally, at the game engine  
328 stage, all acquired data was used for the development of real-time visualizations of  
329 information in both VR and AR applications. Versatile data-formats are thus required in  
330 order to provide smooth data-exchange. Detailed description of all parts are separately  
331 presented.

### 333 *Data measurement and transmission*

334  
335 Sensors were installed in order to measure  $\delta_{\text{beam}}$  and  $\delta_{\text{column}}$  intended for the development  
336 of VR applications as well as  $\delta_{\text{frame}}$  for the development of AR applications. All  
337 measurements followed a similar principle. Data was gathered from sensors connected to  
338 electronic prototyping platforms and sent subsequently to other platforms and/or web  
339 servers. For all cases, distance was measured using a HC-SR04 ultrasonic sensor. The  
340 principle of this sensor is to generate high frequency sound and then calculate the time  
341 interval between the sending of signal and the receiving of echo. The measurement range  
342 of the sensor (5cm-100cm) was broad enough for the designed applications (in other  
343 applications, more precise laser sensors may be needed).

344  
345 In beams and columns, the sensor was connected to a Arduino Nano board (Arduino  
346 2018), which was connected to a laptop directly. Data was gathered and sent both locally  
347 to a game engine (Unity, 2018). Simultaneously, data was also sent to a platform

348 developed at the School of Civil Engineering as a Cloud Service for civil engineering  
 349 laboratories and academic use (Smartlab 2018).

350

351 In frames, the sensors were connected to a ESP32 prototyping board provided with  
 352 Bluetooth and Wi-Fi capabilities (Expressif Systems 2018). The vertical load  $P_v$  was  
 353 provided directly by the actuator (and held constant during the test).  $P_v$  was introduced  
 354 manually to the app interface at the beginning of each test. Data was sent from the board  
 355 to the server via Wi-Fi from which other applications retrieved the info under request.  
 356 Figure 3 shows basic connections, circuitry and implementation of the devices for beams,  
 357 columns and frame tests.

358

### 359 *Data processing*

360

361 In beams and columns, the mathematical treatment of data was straightforward. Both  $\delta_{beam}$   
 362 and  $\delta_{column}$  were used for inferring characteristics of the structural behavior of the  
 363 members (applied loads and deformed shape). On the one hand,  $\delta_{beam}$  allowed obtaining  
 364 information about the deformed shape of the beam as well as of the applied load. Under  
 365 the assumption of linear elastic bending according to a Bernoulli formulation, the set of  
 366 equations is presented in (1) to (6). Figure 4(a) shows the structural model of beams. From  
 367 this formulation, the deformed shape  $z(x)$  is expressed as a function of the characterizing  
 368 magnitude  $\delta_{beam}$  as well as of the geometric proportions  $a$  and  $L$ .

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$$z(x)_{a-c} = \frac{P \cdot x}{6EI} (3 \cdot a \cdot L - 3 \cdot a^2 - x^2) \quad (1)$$

$$z(x)_{c-d} = \frac{P \cdot a}{6EI} (3 \cdot L \cdot x - 3 \cdot x^2 - a^2) \quad (2)$$

$$z\left(\frac{L}{2}\right) = \delta_{beam} = \frac{P \cdot a}{24EI} (3 \cdot L^2 - 4 \cdot a^2) \quad (3)$$

$$P = \frac{24EI \delta_{beam}}{a(3 \cdot L^2 - 4 \cdot a^2)} \quad (4)$$

$$z(x)_{a-c} = 4 \delta_{beam} \cdot x \frac{(3 \cdot a \cdot L - 3 \cdot a^2 - x^2)}{(3 \cdot a \cdot L^2 - 4 \cdot a^2)} \quad (5)$$

$$z(x)_{c-d} = 4 \delta_{beam} \frac{(3 \cdot L \cdot x - 3 \cdot x^2 - a^2)}{(3 \cdot a \cdot L^2 - 4 \cdot a^2)} \quad (6)$$

371

372 On the other hand,  $\delta_{column}$  allowed obtaining information about the deformed shape of the  
 373 column. Under the assumption of linear elastic buckling according to the Euler  
 374 formulation for ideal members, the set of equations with which these magnitudes are  
 375 connected is presented in (7) to (12) and illustrated in Figure 4(b). The deformed shape  
 376  $z(x)$  is expressed as a function of the lateral deflection  $\delta_{column}$  and the total length  $L$ .

377

$$EI \cdot z''(x) + N \cdot z(x) = 0 \quad (7)$$

$$k^2 = \frac{N}{EI} \quad (8)$$

$$z(x) = A \cos(kx) + B \sin(kx) \quad (9)$$

$$BC \quad A = 0 \quad B \neq 0 \quad )$$

$$z(x) = B \sin\left(\frac{\pi}{L}x\right) \quad (10)$$

$$z\left(\frac{L}{2}\right) = B \sin\left(\frac{\pi}{L}\frac{L}{2}\right) = B = \delta_{column} \quad (11)$$

$$z(x) = \delta_{column} \sin\left(\frac{\pi}{L}x\right) \quad (12)$$

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In both cases, one single measurement provides enough information for characterizing the shape of the members. The data processing allowed generating animated objects based on shapes resulting from classical theories and enriched with real measurements.

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In frames, the mathematical treatment of data presented a slightly higher degree of sophistication. Both  $P_v$  and  $\delta_{frame}$  were introduced in a structural planar model of a frame implemented in Matlab (Matlab 2018) using a classical stiffness formulation solved by means of linear algebra. Under the assumption of linear elastic bending according to a Bernoulli, the pair of values [ $P_v$  ;  $\delta_{frame}$ ] generated results related to all reactions at fixed points [ $R_x$ ,  $R_y$ ,  $M_z$ ] as well as to the distribution of internal axial, shear forces and bending moments in all elements [ $N$ ,  $V$ ,  $M$ ]. Figure 4 (c) displays schematics of the frame to be solved according to the test setup. The set of variables are solved in matrix form and the displacement  $\delta_{frame}$  of both ends is introduced as a known boundary condition within the formulation.

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It is worth pointing out that for all cases, the constitutive equation of the material was considered to be linear. This assumption facilitated the mathematical processing of the results at this stage. Full generality may be achieved if the non-linear behavior of the material largely depicted by (Arrayago et al., 2017) is included in all formulations. Likewise, it is interesting to point out that more sophisticated tools such as FEM can be linked t

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#### *Data visualization*

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Finally, treated post-processed data was sent to a game engine in JSON format. The visualization of the data was different for VR and AR applications. Firstly, in beams and columns, an immersive 3D model intended to recreate the laboratory facilities was developed in Revit, a commercial fully functional BIM-infused platform (Revit 2018). This virtual synthetic facility was exported to Unity. At this stage, the render of the 3D lab was *static*. With the usage of a VR headset, users located anywhere are able to navigate throughout the whole facility by means of tele-transportation, a popular feature that is usually used in VR applications when appropriate remote controllers are connected to the VR headset. The user of the synthetic lab may or not be subjected to physical restrictions that are present in laboratory facilities such as safety ribbons, obstacles or similar features. Figure 5 displays general views of the reproduced synthetic environment and corresponding similar pictures of the same view. Furthermore, animated objects were also rendered.

417 At this stage, the animation transformed the render of the 3D lab was *dynamic*. The  
418 principal feature of these animations was related to the capabilities for acquiring data that  
419 shaped both beams and columns according to mathematical relationships. These objects  
420 were specifically designed in the form of rectangular hollow sections RHS. These Revit  
421 objects were thus generated and sent to Unity. Though imperceptible, a certain degree of  
422 latency was noticed when this procedure was used. When animated objects were directly  
423 created in Unity, no latency was observed. The animated beams and columns were thus  
424 scaled in shape according to the measurement performed throughout the incremental  
425 loading as seen in Figure 6. In this case, users need to connect the Unity environment to  
426 the web server from which real-time data is retrieved.

427  
428 In the case of frames, augmented reality glasses (Hololens) were used for visualization  
429 purposes. These glasses provide regular vision of the environment but on top of that,  
430 layers of information are added. In the particular case of frames, the user needed to be  
431 located near the test area during the experience as shown in Figure 7.

432  
433 Data obtained at the post-processing stage was stored in vector forms including all  
434 reactions and internal forces of the whole structure. This information was formatted in  
435 JSON format and used for the creation of customized layers of data in the form of  
436 diagrams, arrows, buttons, lines and floating text boxes. Thus, the AR application was  
437 conceived as a tool that allows the user to understand in real-time, the static behavior of  
438 a frame subjected to a particular set of loads and boundary conditions. The AR  
439 visualization was conceived for its implementation in the system embedded in Microsoft  
440 Hololens glasses using Vuforia (Vuforia 2018), a Software Development Kit (SDK) that  
441 allows operation between the Hololens OS and Unity. These glasses communicate via  
442 Wi-Fi and/or Bluetooth with the server. Figure 8 displays four elements that are included  
443 as information layers: i) buttons, ii) lines, iii) text and iv) arrows. Moreover, the tool was  
444 provided with other objects such as safety ribbons. These objects defined the boundaries  
445 of a limited area in which the user was not allowed to enter during the test (alarms and  
446 warnings were set to appear in such a case).

447  
448 Figure 9 shows a screen capture of the Unity work space in which the enclosed area of  
449 the test limited by the safety ribbon is shown. Other objects can also be seen in this figure  
450 (text boxes, lines, arrows).

### 451 452 453 **Implementation of the system during the tests**

454  
455 VR and AR applications were gradually implemented in all tests depicted in section 3.  
456 The number of tests (4 beams, 8 columns and 4 frames) allowed exploring different  
457 aspects of design in terms of functionality as well as in terms of usefulness of the  
458 applications. An iterative design was performed throughout the development of the  
459 experience. Details related to the whole system (from measurement to visual applications)  
460 were enhanced slightly from one experiment another. More realism, better  
461 synchronization and enhanced quality were added at each iteration. Beams, columns and  
462 frames were tested following this order resulting in first developing VR applications and  
463 subsequently, AR tools.

464  
465  
466 *VR applications in beams and columns*

467

468 Tests on beams and columns were provided with sensors and microcontrollers located at  
469 key points. Figure 10 displays the location of the ultrasonic sensor under the beam  
470 (measuring vertical deflection at mid-span) and next to the column (measuring horizontal  
471 deflection at mid-span). Following the information path depicted in section 4, measured  
472 data fed continuously the 3D model. The result was a real-time reproduction of the test  
473 within a synthetic environment. Non-present users provided with any VR headset  
474 connected appropriately to the web server may remotely though synchronously recreate  
475 the experimental test. Figure 11 displays graphical comparisons between the real test in  
476 beams and the corresponding 3D reproduction. Figure 12 shows a similar comparison but  
477 in this case, in columns.

478

479

#### 480 *AR applications in frames*

481

482 Tests on frames were also provided with sensors and microcontrollers located at key  
483 points. An ultrasonic distance sensor was located next to the sliding surface on which the  
484 supports were located as shown in Figure 13(a). In addition, recognition markers were  
485 needed to anchor the spatial location of the floating objects with respect to the actual  
486 location of the tests as displayed in Figure 13(b). These elements allow for the AR glasses  
487 to develop a spatial recognition of the working space. Markers are arbitrary images with  
488 clear patterns defined by the developer. The markers must be located within the testing  
489 premises (with the available equipment, these premises were limited to an imaginary  
490 square of 4 meters width). Once properly recognized, layers of information are placed  
491 correctly on top of the desired objects. As the user moves around the location of the  
492 frame, all layers adapt and float accordingly on the right spatial position.

493 Following the information path depicted in section 4, measured data fed continuously the  
494 animated objects. The result was a real-time augmentation of the test reality for both  
495 experience enhancement. Present users provided with HoloLens were able to recreate  
496 synchronously the experimental test with added layers of information such as axial, shear  
497 and bending moment diagrams or the resulting values of reactions at supports. Figures 14  
498 to 16 display several captures of the visual enhancement the user may get when  
499 experiencing the AR application. Diagrams, values and drawings are located spatially in  
500 such a way that moving users perceive these information layers as existing on top of the  
501 frame geometry (automatic adaptation of the spatial location).

502

503

#### 504 *Discussion*

505

506 The developed applications provided insightful information to users during the  
507 development of the tests. One aspect of the developments of such applications was to use  
508 a framework integrating sensor measurement, simulation, design based on BIM  
509 environments and scientific visualization of results. For this proof of concept, the  
510 mathematical problems that were solved were linear and based upon simple closed-form  
511 solutions. The system was conceived in way more sophisticated tools such as FEM can  
512 be also embedded as mathematical engines.

513

514 VR applications were meant for users that are not necessarily present within the  
515 laboratory facilities whereas AR applications were meant for users that are necessarily  
516 present within the laboratory premises. In VR, any user at any place with a synchronous

517 connection may experience the development of the test remotely. Immersive 3D  
518 reproductions of laboratories coupled with animated representations of the tested  
519 specimens can be blended in a virtual reality space. In AR, users can experience an  
520 enriched version of a structural test *in situ* without losing awareness of the real  
521 environment. Both applications are complementary and can be used simultaneously. A  
522 systematic appraisal of the deployed applications is presented in the following section.

## 527 **Appraisal of VR/AR applications in structural engineering laboratories**

528  
529 Both VR and AR applications were successfully implemented in the depicted tests. The  
530 focus of the development was concentrated in data acquisition, data processing and data  
531 visualization. From a mathematical perspective, in both cases, all formulations were  
532 linear and derived using closed-form analytical solutions. The visualization of these  
533 results was related to deformed shapes and response magnitudes in the form of diagrams  
534 and reactions. In the following, a comparison between systems as well as between users'  
535 perception is presented.

### 537 *Comparison between VR/AR systems*

538  
539 VR is an interactive fully synthetic environment generated with computers that replaces  
540 the user's physical world. AR is a real-world environment enriched with layers of  
541 information. In the latter, the user's awareness of the real environment is preserved by  
542 compositing physical/virtual worlds in a blended space.

543  
544 From the perspective of the laboratory experience, AR showed greater potential as  
545 experience- cognitive enhancer. It is pinpointed that the resources required to add layers  
546 of information are not excessive (Software and interoperable platforms) but the necessary  
547 equipment (Hardware) is presently rather expensive for the deployed modality. AR  
548 Hardware is still under development which is reflected in the market availability. Other  
549 AR modalities including other interfaces may be

550  
551 On the other hand, the resources required to recreate a realistic VR scene (Software) are  
552 larger than those required in AR applications but the necessary equipment (Hardware) is  
553 considerably more accessible. VR Hardware can be found in numerous forms and  
554 affordable prices nowadays. The amount of time needed to replicate a realistic VR  
555 environment is longer than the amount of time needed to recreate layers of information  
556 in AR. Notwithstanding, VR systems can be used as a way of recreating experimental  
557 experiences to remotely located users, which represents a major advantage. The amount  
558 of participants that may access to such events may be fairly larger considering that any  
559 user connected to a web server with an adequate VR gear can be immersed in such test.

### 561 *Appraisal of the applications provided by different user groups*

562  
563 Participants belonging to different user-groups were polled after testing the applications.  
564 3 full professors, 3 associate professors, 2 post-doctoral researchers, 6 students (graduate  
565 and undergraduate) and 4 laboratory technicians participated in the interviews during the  
566 tests. A reduced yet systematic scrutiny of the applications were performed by i) users

567 with high expertise in the subject (professors and post-doctoral researchers), ii) users with  
568 high expertise in structural engineering laboratories (technicians) and iii) civil  
569 engineering students. Conclusions related to the potential use of such tools in these  
570 facilities are thus separated for user groups:

- 571  
572 • Users with high expertise in the subject (the developers of the structural tests  
573 themselves), expect more sophisticated visualization of the results. Real-time  
574 data-processing with more advanced formulation is necessary when providing  
575 other layers of information. In the case of beams, columns and frames, several  
576 forms of plastic-hinges visualizations or visualization of the accumulated history  
577 of the tests were suggested by scrutinizers as potential enhancers for these  
578 particular applications.
- 579  
580 • Users with high expertise in structural engineering laboratories expect clear  
581 visualization of results associated with control of the test as well as with the  
582 overall safety of the experiment. These users are interested in monitoring the  
583 correct development of measurement as well as any potential malfunction of the  
584 set-up.
- 585  
586 • Users under training (civil engineering students) found that results were  
587 meaningful and useful for understanding purposes. Some of them were attracted  
588 by the use of technology as a cognitive-enhancer. In particular, students showed  
589 a quick understanding of the phenomenon visualized with AR applications.  
590 Notwithstanding, for these cases, the visualization was associated with internal  
591 force diagrams and reactions. It is required to scrutinize the cognitive  
592 enhancement these applications provide when more sophisticated visualizations  
593 are used in pedagogical terms.

594  
595  
596 *Identification of the potential and of technical issues in VR/AR tools for structural*  
597 *engineering laboratories.*

598  
599 From a general perspective, in structural engineering laboratories, experiments with other  
600 materials as well as with other types of structural tests can be infused with VR/AR  
601 immersive environments. Improvement in the formulations (e.g., accounting for the  
602 material non-linearity) and/or visualization of more sophisticated results are  
603 enhancements one may include in similar tests. Notwithstanding, the sophistication of the  
604 mathematical formulation involving highly nonlinear components adds latency to the  
605 system due to the required computational time with incremental/iterative procedures. In  
606 the deployed tools, a certain degree of latency was observed in VR applications (a  
607 temporal lag from the measurement to the moment the rendered imagery is presented to  
608 the user). The synthetic 3D environment, which needs to be refreshed in real time,  
609 consumes considerable CPU graphical resources. On the other hand, the AR applications  
610 were computationally treated in external CPUs. Subsequently, processed data was sent to  
611 the Hardware (HoloLens) in the form of layers of information that required limited amount  
612 of graphical resources. In such cases, latency was not an issue.

613  
614 Moreover, in AR applications, a recognition marker is required. When users enable the  
615 system, the AR glasses need to be placed close to the marker in order to locate spatially  
616 the layers of information (Figure 13 (b)). In static tests, in which the duration may exceed

617 a certain time (minutes to hours), the system is usually restarted during the test. It is  
618 recommended to place the marker in an accessible point within the premises of the test  
619 outside the safety ribbons.

620

### 621 *Future research*

622

623 The present case study has been developed as a proof of concept in real scale structural  
624 tests with a particular emphasis in including all the needed steps. An integrated  
625 framework including measurement, transmission, processing and visualization have been  
626 treated in all examples. In particular, several aspects related to structural engineering  
627 applications need further deepening (other technological aspects involving the equipment  
628 itself are also a matter of research but are not discussed herein). Throughout the  
629 development of the applications, some research trends have been identified:

630

631 • Development of VR/AR multivariable models in redundant structures. Redundant  
632 structures tested in laboratories are more complex to measure and analyze.  
633 Enriched visualizations of the results provide to test operators with more tools for  
634 decision-making and for safety control in such complex tests.

635

636 • Development of more sophisticated FEM models that predict the behavior of the  
637 tests up to failure. This development may provide enriched phenomenological  
638 insight to operators related to important events such as remaining life, failure,  
639 excessive deformation, etc during the tests.

640

641 • Development of AR application in which reduced order methods are used for  
642 calculations. This development may provide enriched phenomenological insight  
643 to operators with complex calculations that may be developed with less computing  
644 capacity. Latency may be reduced considerably using such models.

645

646 • Development analyses using cloud computing for the sake of optimizing  
647 calculations and avoid undesired latency.

648

649 • Development of VR/AR applications in real scale load tests. Routinely performed  
650 load tests in bridges are one example in which both remotely located users (VR)  
651 as well as users present in the field (AR) may need. The development of such  
652 applications including experimental (EMA) and operational modal analysis  
653 (OMA) is at development stages by the research group (Chacón et al. 2019).

654

655

656

### 657 **Conclusions**

658

659 In this paper, a set of VR and AR applications were successfully implemented in the form  
660 of experience-enhancers in structural engineering routine tests. Several experiments on  
661 beams, columns and frames in stainless steel were performed at the laboratory facilities.  
662 Immersive tools were successfully deployed in such tests, which cover several structural  
663 elements. These applications encompass the use of measured data from sensors, the  
664 deployment of synchronous data transmission and post-processing and finally, a real-time  
665 visualization of results. These visualizations were specifically conceived and developed

666 for these tests as potential experience- and cognitive enhancers. The developed  
667 applications have allowed enriching the perceptive experience for different users.

668

669 VR applications were meant for users that are not necessarily present within the  
670 laboratory facilities whereas AR applications were meant for users that are necessarily  
671 present within the laboratory premises. For the former case, any user at any place with a  
672 VR headset and a synchronous connection to servers may experience the development of  
673 the test remotely. Immersive 3D reproductions of laboratories coupled with animated  
674 representations of the tested specimens can be blended in a virtual reality space. From  
675 data, not only animations but also text, plots, numbers or any other interface can be added  
676 as experience enhancers. As a result, tests on structural elements, often limited and  
677 expensive, can be recreated by an unlimited amount of persons synchronously. For the  
678 latter case, users provided with AR headset can experience an enriched version of a  
679 structural test *in situ*. Without losing awareness of the real environment, users receive  
680 additional layers of information that enrich overall experimental experience. Although  
681 both applications are complementary and can be used simultaneously, considerable  
682 differences between both are pinpointed. VR applications require more computational  
683 resources than AR applications. Conversely, VR tools are more affordable and accessible  
684 nowadays than the AR counterparts.

685

686 Moreover, different user groups such as researchers, technical staff and civil engineering  
687 students were designated as scrutinizers of the applications. Qualitative suggestions were  
688 provided by different types of users. Researchers with high expertise suggested in adding  
689 complex post-processed information. Technical staff suggested that clear visualization of  
690 results at any time as clear warning about malfunctions or safety-related issues are of  
691 utmost importance. Students considered these applications as interesting technology-  
692 based cognitive enhancers even for simple cases such as beams and columns.

693

694 All applications were performed following some of the latest trends in AEC sector related  
695 to interoperability and data exchange. Since data-exchange was synchronously performed  
696 from sensors to real-time renders, standard protocols facilitated its implementation. Issues  
697 related to latency in VR and operability in AR were pinpointed. The development of  
698 environment-controlled laboratory experiences showed their conceptual applicability but  
699 interestingly, showed replicability in real structures infused with sensors that feed BIM  
700 models. Routinely performed load tests in real structures represent a starting point for the  
701 development of more ambitious applications for a broader range of users such as  
702 constructors, administrations and consultant engineers.

703

704

705

#### 706 **Data availability statement**

707

708 Some data, models, or code that support the findings of this study are available from the  
709 corresponding author upon reasonable request. (Measurement and structural analysis codes).

710

711

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713

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719

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Table 1. Geometrical and organizational characteristics of the tests.

Type	Number	RHS Cross-Section	Geometry	Observations
<b>Beams (VR)</b>	S1-B	120 x 80 x 6	Length = 1700 mm Span=1500mm	Compact
	S2-B	100 x 80 x 4		Compact
	S3-B	120 x 40 x 4		Semi-Compact
	S4-B	120 x 100 x 3		Slender
<b>Columns (VR)</b>	S1-C1	120 x 80 x 6	Height = 1500 mm	Major axis. FB
	S1-C2	120 x 80 x 6		Minor axis. FB
	S2-C1	100 x 80 x 4		Major axis. FB
	S2-C2	100 x 80 x 4		Minor axis. FB
	S3-C1	120 x 40 x 4		Major axis. FB
	S3-C2	120 x 40 x 4		Minor axis. FB
	S4-C1	120 x 100 x 3		Major axis. FB
	S4-C2	120 x 100 x 3		Minor axis. FB
<b>Frames (AR)</b>	S1-F	120 x 80 x 6	Height = 2000 mm Span = 4000 mm	Fixed supports
	S2-F	100 x 80 x 4		Fixed supports
	S3-F	120 x 40 x 4		Pinned supports
	S4-F	120 x 100 x 3		Pinned supports

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