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Two-dimensional conceptual design of a superconducting iron-free opposite field septum magnet

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ABSTRACT

A novel concept of a superconducting iron-free opposite field septum magnet is presented, which could provide a magnetic field jump of 1.4 T between its two domains, with a septum blade thickness of about 4 mm.

1. Introduction

One of the key elements of the extraction systems of particle accelerator rings is the septum magnet, which creates two regions with very different values of the magnetic field, in close proximity. For a sharp transition of the field, a physical, current-carrying wall, called the septum blade, separates the two regions. The circulating beam passes through one of these two regions. In the case of fast extraction within a single turn, the beam is kicked into the other region ("extraction region") by a fast upstream kicker magnet. When slow extraction over several turns is required, the beam size is gradually increased using a 3rd order resonance excited by sextupole magnets, and particles at large amplitudes are "sliced off" using an electrostatic septum consisting of a very thin blade (a stretched foil, or a series of stretched wires) with a high electric field at its external side, which gives the beam a small outward kick, directing it into the extraction region of the magnetic septum. In both schemes, the trajectory of the extracted beam then diverges from the circulating beam downstream of the septum magnet.

Designers must find the best trade-off between the following two requirements. The magnet needs to have a large jump of the magnetic field across the blade, i.e. a large separating power, in order to make the extraction region compact (total length of the septum magnet(s), and distance of the first ring magnet placed downstream of the septum). On the other hand, the septum blade must be as thin as possible, in order to reduce the requirements on the upstream kicker magnet's strength, and/or decrease the distance between the kicker magnet and the septum. For a given operating engineering current density J_e in the blade, the blade thickness d limits the achievable field jump:

$\Delta B = \mu_0 d J_e$. Also, a thin blade may cause mechanical problems if high magnetic forces are present.

In the most common arrangement (ZH — zero/high-field) the septum magnet creates zero (or negligible) magnetic field in the region of the circulating beam, and high field at the extracted beam. The advantage of this configuration is the looser requirement on field quality compared to the ring magnets, since the beam passes through the high-field region only once. A typical value is $\pm 1\%$ field homogeneity, in contrast to the standard 1 unit tolerance of higher multipoles (10^{-4} of the main multipole component's magnitude, evaluated typically at 2/3 of the aperture) in ring magnets. For the circulating beam this septum magnet represents a drift space.

Another configuration is the opposite-field (OF) arrangement, where the magnetic field has opposite directions, $\pm B_0$ at the two sides of the septum blade. The advantage of this configuration is that there are no net forces on the blade, and therefore it can be made thinner. Superconducting solutions also benefit from the peak field reduction of about a factor 2 in the coils compared to the ZH configuration for the same separation power $\Delta B = 2B_0$. This enables higher operating currents, and thereby a higher separation power for the same blade thickness. On the other hand, the circulating beam is running in a high magnetic field, which has to fulfill the strict quality requirements of the ring magnets, also during ramping. This might be an issue (in fact for any magnet around the circulating beam), if significant eddy currents are induced in the support structure of the magnet's winding. This is the case for example if fast ramping is planned to be combined with magnets based on the canted cosine theta configuration, which is the subject of some recent R&D activities [1–4]. In these magnets the superconducting wires are wound into grooves machined

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into bulk aluminium or aluminium-bronze “formers”. A similar concept – although with different geometry – is also a possible realization scheme for the magnet proposed in this article. For the OF configuration the septum must necessarily be ramped following the beam momentum, and the kick given to the circulating beam by the septum must either be integrated into the optics of the ring, or be compensated by other magnets as in [5,6]. In the latter case these extra magnets increase the total effective length of the device, and this solution is therefore disadvantageous when compactness is a primary goal.

Future accelerators may require new solutions for the extraction septa. In order to deal with the unprecedented beam rigidity of the Future Circular Collider (FCC), two new septum concepts were proposed. One of them is based on the truncated cosine theta principle [7,8]. The other concept uses the combination of a superconducting magnet and a passive superconducting shield (“SuShi septum”) [9,10], having the advantage of a relatively thin septum blade despite the large mechanical forces. Future superconducting medical hadron accelerators will require very compact solutions in general, and consequently as thin as possible blades for the extraction septum magnet, for moderate beam rigidities around 6.6 Tm. While the SuShi concept could be scaled down to a few-mm blade thickness with about 1 T magnetic field for the extracted beam, if slow extraction is required, the beam losses necessarily associated with this scheme may (partially) quench the superconducting shield, interfere with the history of the passive, induced persistent currents, and lead to the uncontrolled magnetic state of the shield. The robustness of this configuration in the environment of a medical accelerator or with slow extraction needs to be confirmed by dedicated experiments. This paper presents the 2D concept of an opposite-field iron-free septum magnet with no passive elements and a thin blade.

2. 2D concept

The 2D magnetic field of a $J_z(\theta) = J_0 \cos(\theta)$ sheet current on a circle of radius R is

$$|B| = \begin{cases} \mu_0 J_0/2 = B_0 & \text{if } r < R \\ \mu_0 J_0/2 \cdot (R/r)^2 & \text{if } r > R \end{cases} \quad (1)$$

The induction lines (contour lines of the vector potential’s third component, A_z) are straight vertical lines within the current sheet, and circles passing through the origin, with a center on the horizontal axis, outside of the current sheet, as illustrated in Fig. 1.

Following the recipe of “truncating” a known magnetic field configuration, described in [11], one has to select first a closed induction line which splits the 2D plane into two domains. The magnetic field can be set to zero in one of the domains, if a sheet current density $|J_{\text{trunc}}| = |B|/\mu_0$ is prescribed along this line, and the part of the original current distribution is eliminated within the domain. The direction of the truncating current distribution depends on which domain was chosen to be made field-free. The resulting magnetic field and current distribution satisfy everywhere Maxwell’s equations. A truncated cosine theta septum magnet configuration is usually created by keeping the magnetic field within the truncation line, and setting it to zero outside of it.

A different field configuration can be created by reversing the direction of the truncating currents. Choose the induction line A–B–C–D–A in Fig. 1 for truncation, set the magnetic field to zero within the shaded domain encircled by this line, and eliminate the part A–E–C of the original $\cos(\theta)$ current distribution. The magnetic field in the domain encircled by the line A–B–C–F–A will remain a pure dipole field $B_y = -\mu_0 J_0/2$. The resulting geometry of the sheet currents will be symmetric to the line A–C. The superposition of the current distribution with its horizontal mirror image will result in a field configuration with opposite fields $B_y = \pm \mu_0 J_0/2$ in the two domains A–B–C–D–A and A–B–C–F–A, respectively. Using the path length parameter s along the

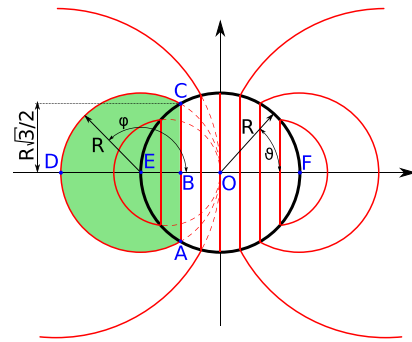


Fig. 1. Illustration of the induction lines (red) of a $\cos(\theta)$ sheet current distribution (thick black circle). The dashed lines show the extensions of the induction lines of the external domain to the interior of the current distribution. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

line B–C–D, a building unit of the combined current distribution can be described as

$$J_z(s) = \begin{cases} -B_0/\mu_0 & \text{if } 0 < s < R\sqrt{3}/2, \text{ (B–C line)} \\ -\frac{B_0}{\mu_0} \left(2 \cos(\varphi) + \frac{1}{2-2\cos(\varphi)} \right) & \text{if } R\frac{\sqrt{3}}{2} < s < s_{\text{max}} = R \cdot 120^\circ + R\frac{\sqrt{3}}{2}, \text{ (C–D line)} \end{cases} \quad (2)$$

$$\varphi = \frac{s - R\sqrt{3}/2}{R} + 60^\circ \quad \text{if } s > R\sqrt{3}/2 \quad (3)$$

where the first term of the expression for the C–D line is the mirrored original $\cos(\theta)$ current, and the second term is the truncating current density equal in magnitude to $|B|/\mu_0$ of the original $\cos(\theta)$ current distribution. Note that the current density along the vertical symmetry line given above is only half of that required to have a magnetic field jump of $\Delta B = 2B_0$ across the blade, since the final current distribution is the superposition of this current distribution with its own mirror images around both axes. Fig. 2 shows the surface current density of this building unit for $R = 47$ mm and $B_0 = 0.7$ T, with a separating power of $\Delta B = 1.4$ T. The radius has been chosen such that a beam-pipe with 60 mm inner diameter, 1.5 mm wall thickness can be inserted with a radial gap of 1.5 mm inside the winding, leaving about 1 mm material to support the wires at points D, B and F. The wires experience an outward magnetic force at points D and F, and no net force at point O. The resulting blade thickness is about 4 mm. The concept is easily scaleable to larger apertures with the same blade thickness. As a comparison, the normal-conducting Lambertson septum magnets of the Large Hadron Collider have blade thicknesses between 6 and 18 mm for magnetic field differences of $\Delta B = 0.76$ and 1.17 T, respectively [12]. The SuShi septum concept promises a blade thickness of 15 mm for a magnetic field difference of $\Delta B = 3$ T [10]. The proposed truncated cosine theta septum magnet for the FCC would have a blade thickness of 30 mm for a magnetic field difference of 4 T. The “thin” and “thick” normal-conducting extraction septum magnets of the MedAustron medical accelerator have blade thicknesses of 10.5 and 21 mm for nominal maximum fields of 0.49 and 0.98 T, respectively [13].

3. Field calculations, field quality

In practice the sheet currents are realized by appropriately placing discrete wires along the lines A–D–C, A–F–C and A–B–C, the latter being referred to as the blade in the following. The positions of these wires is determined as follows. The integral functions of the current density Eq. (2) are numerically calculated for the positive and negative parts:

$$J_1(s) = \int_0^s |J(s')| ds' \quad 0 < s < s_0 \quad (4)$$

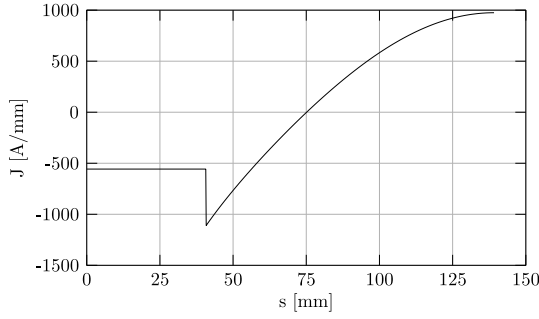


Fig. 2. Surface current density of the building unit of the current configuration, along the line B-C-D, for a ± 0.7 T opposite-field septum.

$$\mathcal{J}_2(s) = \int_{s_0}^s J(s') ds' \quad s_0 < s < s_{\max} \quad (5)$$

where s_0 is the zero-crossing point of the current density: $J(s_0) = 0$. For N positive and N negative wires within 1/4 of the full configuration, the range of \mathcal{J}_1 and \mathcal{J}_2 is divided into N equal intervals, which are then projected back to s -space via the inverse of these functions. The wires with a current of $\pm I_0 = \pm I_{\text{tot}}/N = \pm \mathcal{J}_1(s_0)/N$ are placed at the center of gravity of the intervals, using $|J(s)|$ as the weight function.

Note that the complete wire configuration has overlapping wires in the vertical midplane A-B-C, due to the superposition of the 1/4 wire distribution with its own horizontally mirrored image. In order to avoid collision, and be able to wind the left and right halves of the magnet on separate formers, the wires at the blade have to be displaced by $\pm D_{\text{wire}}/2$ horizontally.

In order to avoid the too high density, and therefore the collision of the wires, the target magnetic field B_0 and the number of the wires N should be limited such that the maximum surface current density Eq. (2) does not exceed $I_{\text{max}}/(D_{\text{wire}} + G)$, where I_{max} is the maximum safe operating current at the given magnetic field, and G is the minimum necessary gap to place the wires with sufficient accuracy (i.e. into individual grooves machined into aluminium formers, for example). If a higher magnetic field is required, the wires need realignment, for example using the following simple algorithm. Whenever two subsequent wires are closer than the minimum allowed distance, they are both snapped to their average position along the arc $(s_1 + s_2)/2$, displaced by $\pm D_{\text{wire}}/2$ in the normal direction. Fig. 3 shows the resulting wire configuration and the magnetic field map for $B_0 = 0.7$ T and $N = 54$. The required wire current is $I_0 = 753$ A, which is 64% of the short-sample critical current of two high-performance industrial superconducting wires, the Bruker F54-1.35-0.85 [14] and Supercon 54S43-54-1.3-0.85 [15], extrapolated to this low field value, as shown in Fig. 4, at the same field and a temperature of 4.2 K. The peak field in a realistic 3D coil is not yet studied in this work. Using a pessimistic estimate of $B_{\text{peak}}/B_0 = 2$, the magnet current would still be only at 70% of the critical current of the wires (see Fig. 4, dotted lines). Both wires have an insulated diameter of 0.9 mm and are therefore compatible with the wire layout presented above. The distance of the wires or pairs of wire is everywhere greater than about 1.4 mm.

The relative weight of the higher multipoles, sampled at 2/3 of the aperture, is shown in Fig. 5, demonstrating the excellent field quality with all multipoles having a magnitude below 1 unit.

4. Summary and outlook

The presented realistic 2D wire arrangement creates an opposite-field septum field configuration with an accelerator-grade dipole field of ± 0.7 T in two adjacent domains separated by about 4 mm. The wire configuration can be separated into two halves, which could be individually wound into aluminium formers with machined grooves for the wires, similarly to the canted cosine theta magnets, but with axial

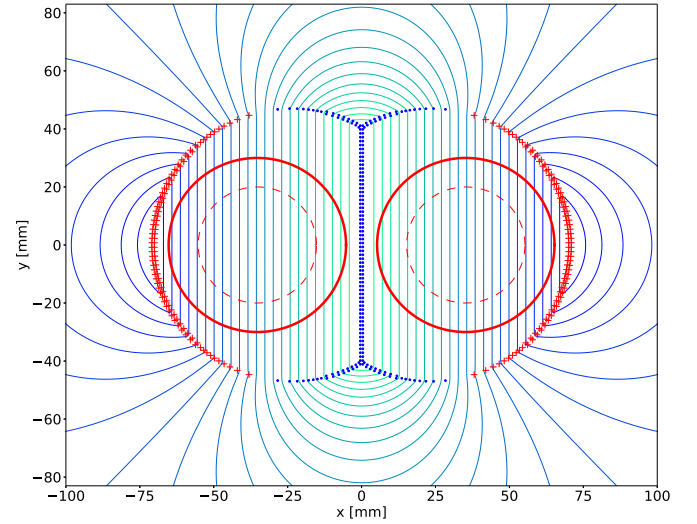


Fig. 3. Field configuration of the opposite-field truncated cosine theta septum magnet with discrete wires (+ for positive, • for negative currents). The thick solid red circles show 60 mm diameter apertures, the dashed circles show the sampling line for multipole analysis at 2/3 of the aperture. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

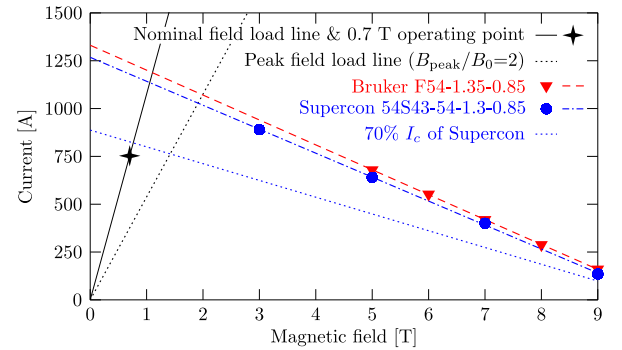


Fig. 4. Load lines of the magnet, and the critical current values of two industrial superconducting wires. Symbols show the values specified in the data sheets, the dashed and dash-dotted lines show a linear fit.

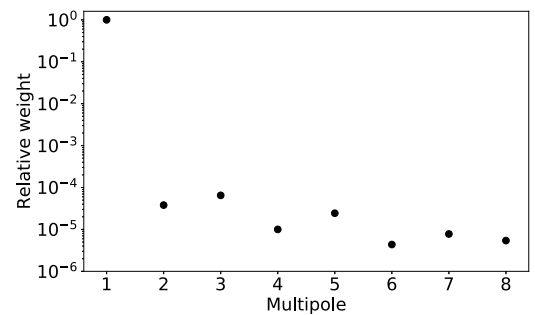


Fig. 5. Relative weights of the multipoles.

grooves. The coil ends need a 3D design, and their effect on the quality of the integrated field must still be studied. The two coils can then be embedded in a larger support block, and epoxy-impregnated. The concept is easily scaleable to larger apertures without any complications. In case the large bulk supporting formers are made from conductive materials, the effect of eddy currents in fast-ramping rings must be studied.

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

CRediT authorship contribution statement

Dániel Barna: Conceptualization, Methodology, Writing - original draft, Writing - review & editing, Visualization. **Martin Novák:** Software, Visualization.

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