1	Numerical ordinality in a wild nectarivore
2	
3	Tas I. F. Vámos ¹ , Maria C Tello-Ramos ¹ , T. Andrew Hurly ² & Susan D. Healy ¹
4	
5	¹ School of Biology, University of St Andrews, St Andrews KY16 9TH, UK
6	² Department of Biological Sciences, University of Lethbridge, Alberta, Canada
7	
8	Abstract
9	Ordinality is a numerical property that nectarivores may use to remember the specific order in
10	which to visit a sequence of flowers, a foraging strategy also known as traplining. In this
11	experiment, we tested whether wild, free-living rufous hummingbirds (Selasphorus rufus) could
12	use ordinality to visit a rewarded flower. Birds were presented with a series of linear arrays of 10
13	artificial flowers; only one flower in each array was rewarded with sucrose solution. During
14	training, birds learned to locate the correct flower independent of absolute spatial location. The
15	birds' accuracy was independent of the rewarded ordinal position (1st, 2nd, 3rd or 4th), which
16	suggests that they used an object-indexing mechanism of numerical processing, rather than a
17	magnitude-based system. When distance cues between flowers were made irrelevant during test
18	trials, birds could still locate the correct flower. The distribution of errors during both training
19	and testing indicates that the birds may have used a so-called 'working up' strategy to locate the
20	correct ordinal position. These results provide the first demonstration of numerical ordinal
21	abilities in a wild vertebrate and suggest that such abilities could be used during foraging in the

- 22 wild.

24 Introduction

25 Number is an emergent property of the world that defines quantities of individually discriminable sets of objects [1]. Number exists independent of sensory modality, and is 26 27 considered more reliable than sensory-dependent stimuli [2]. The ability to comprehend number 28 has the potential to profoundly influence an animal's fitness by affecting aspects of its life such 29 as foraging, breeding, and conflict [3, 4]. However, the investigation of numerical cognition 30 research has often been rather anthropocentric, with attempts to discover whether or not animals 31 have human-like mathematical abilities, such as the ability to count [5]. This approach can then 32 become entangled in definitional issues as to what constitutes 'counting', which distract from study of the ecological and evolutionary significance of numerical abilities. A different approach 33 34 is to examine the numerical abilities of animals in relation to ecological 'problems' that animals 35 solve on a daily basis [6]. Such an approach acknowledges that animals' numerical abilities may have been shaped by the ecological and evolutionary pressures of their natural environments. 36 37 Many human numerical abilities, such as advanced mathematics, are possible only as a result of our species' linguistic abilities, especially the ability to verbally label numbers [2]. 38 However, research on languages without number words demonstrates that language is not a 39 40 prerequisite to having a number sense, which suggests the existence of pre-verbal numerical cognitive mechanisms [7]. There appear to be two pre-verbal systems [8, 9]. One is an object-41 42 indexing system used to process small numerosities (numerical values): each item in a set is 43 processed as a discrete unit, allowing an exact representation of numerosity. The upper limit of the object-indexing system is around four items in humans, but may be higher in some animals 44 45 [10]. Larger numerosities are processed by an analogue magnitude system in which numerosities 46 are represented as imprecise magnitudes. This second system abides by Weber's Law:

discrimination between numerosities is dependent on their relative magnitudes. The point at
which animals switch between mechanisms appears to depend not only on absolute amount, but
also on variables such as experience, attentional load, and the spatial characteristics of items in a
set [8].

51 Cardinality is the property of number that describes the final value of a set. For instance, 52 a set of three objects has a cardinality of three. Experimentally, cardinality is investigated primarily using numerosity discrimination tasks, which test whether animals can differentiate 53 between cardinalities independent of the physical characteristics of the sets being compared. 54 55 Numerosity discrimination is taxonomically widespread [e.g. 11, 12, 13, 14]. Numerosity 56 discrimination tasks do not, however, explicitly test for an understanding of the relationships 57 between numbers. This requires an understanding of ordinality, a numerical property describing 58 the sequential relationships between items in a set [15]. While an understanding of cardinality allows discrimination between the quantities '1', '2', and '3', ordinality allows one to understand 59 that the 3^{rd} item in a set comes after the 2^{nd} , and that both come after the 1^{st} . 60

An understanding of numerical ordinality would allow animals to exploit the inherent 61 reliability of numerical aspects of their environment to their benefit. Studies on Alex, an African 62 63 grey parrot (*Psittacus erithacus*), were among the first to show that animals possess ordinal mechanisms: Alex could spontaneously infer the cardinal value of a numerosity based on its 64 65 ordinal position [16] while rats [17], guppies [18], monkeys [19], and bees [20] can all learn to 66 re-locate spatially presented ordinalities with only minimal training. However, untrained success in laboratory paradigms does not indicate the contexts (if any) in which numerical ordinality is 67 68 used by wild animals: animals in the lab may not necessarily use the same cognitive mechanisms as those in the wild, even on similar tasks [21] and ordinality demonstrated in the laboratory can
sometimes be achieved by subjects associating non-numerical cues with the order of items [22].

Hypothesising about ecological contexts in which animals may use numerical ordinality 71 72 allows for the construction of testing paradigms that better reflect the pressures that wild animals 73 are likely to face. One such context is during navigation between food patches whereby an 74 animal may be able to return to a food patch based on the ordinal positions of landmarks. For 75 example, Petrazzini et al., [18] suggested that guppies may use the ordinal position of landmarks as a guide to navigate within the rivers in which they live, where other cues are often unreliable. 76 77 Furthermore, wild bees can use ordinality when visiting multiple nectaries on a single flower during foraging [4]. With the exception of this latter study, however, there has been little, if any, 78 79 research into the ordinal abilities of wild, free-living animals in their natural habitats. Studying 80 animals in the wild is advantageous, as it allows animals to solve problems without the stressors present in the lab. 81

82 Rufous hummingbirds (Selasphorus rufus) are a species that has been used as a model to investigate a variety of cognitive phenomena in the wild [23, 24]. Several aspects of their life 83 history make them ideal wild subjects for cognitive experiments. Males of the species form 84 85 individual territories in which they are easily observable, they can be marked for individual identification and trained to feed from artificial flowers, which they will re-visit every 10-15 86 87 minutes. Past research has shown that rufous hummingbirds forage primarily using spatial 88 information [25] and can learn the re-fill rates of artificial flowers [26]. The knowledge of the spatial positions and re-fill rates of flowers within their territories could allow territorial males to 89 90 form traplines between flowers in their territories. Traplining is a foraging strategy in which 91 animals use only a fraction of the many possible routes that they could travel between a series of

92	food patches [27]. And, indeed, rufous hummingbirds will engage in traplining behaviour while
93	visiting a sequence of rewarded locations [28, 29]. These birds might develop a trapline by using
94	a memorised sequence of movements (i.e. associative chaining). But it is also possible that they
95	use ordinal information to form traplines by assigning each artificial flower a numerical value
96	and visiting them in order.
97	In order to test whether rufous hummingbirds could use ordinal information while
98	foraging, we designed an experiment to test the birds' ability to re-locate a flower based only on
99	its ordinal position in an array. Success by the birds would provide the first concrete evidence of
100	ordinal numerical abilities in a wild vertebrate, assist with dispelling criticism about the
101	ecological irrelevance of number, and provide a possible mechanism by which rufous
102	hummingbirds can form traplines.
103	
103 104	Methods
103 104 105	Methods Subjects and Study Site
103 104 105 106	Methods Subjects and Study Site The subjects were nine wild male rufous hummingbirds observed in the Westcastle Valley,
103 104 105 106 107	Methods Subjects and Study Site The subjects were nine wild male rufous hummingbirds observed in the Westcastle Valley, eastern Rocky Mountains, Alberta, Canada (N49.349153, W114.410864) between May and July
103 104 105 106 107 108	Methods Subjects and Study Site The subjects were nine wild male rufous hummingbirds observed in the Westcastle Valley, eastern Rocky Mountains, Alberta, Canada (N49.349153, W114.410864) between May and July 2017. Rufous hummingbirds winter in Mexico and begin to arrive in the valley in May. Prior to
103 104 105 106 107 108 109	MethodsSubjects and Study SiteThe subjects were nine wild male rufous hummingbirds observed in the Westcastle Valley,eastern Rocky Mountains, Alberta, Canada (N49.349153, W114.410864) between May and July2017. Rufous hummingbirds winter in Mexico and begin to arrive in the valley in May. Prior tothe birds' arrival, artificial feeders containing 20% sucrose solution were placed at sites
103 104 105 106 107 108 109 110	MethodsSubjects and Study SiteThe subjects were nine wild male rufous hummingbirds observed in the Westcastle Valley,eastern Rocky Mountains, Alberta, Canada (N49.349153, W114.410864) between May and July2017. Rufous hummingbirds winter in Mexico and begin to arrive in the valley in May. Prior tothe birds' arrival, artificial feeders containing 20% sucrose solution were placed at sitesthroughout the valley, to encourage males to establish territories around them. After an initial
103 104 105 106 107 108 109 110 111	MethodsSubjects and Study SiteThe subjects were nine wild male rufous hummingbirds observed in the Westcastle Valley,eastern Rocky Mountains, Alberta, Canada (N49.349153, W114.410864) between May and July2017. Rufous hummingbirds winter in Mexico and begin to arrive in the valley in May. Prior tothe birds' arrival, artificial feeders containing 20% sucrose solution were placed at sitesthroughout the valley, to encourage males to establish territories around them. After an initialperiod of observation to determine that a male had consolidated its territory around an artificial
103 104 105 106 107 108 109 110 111 112	MethodsSubjects and Study SiteThe subjects were nine wild male rufous hummingbirds observed in the Westcastle Valley,eastern Rocky Mountains, Alberta, Canada (N49.349153, W114.410864) between May and July2017. Rufous hummingbirds winter in Mexico and begin to arrive in the valley in May. Prior tothe birds' arrival, artificial feeders containing 20% sucrose solution were placed at sitesthroughout the valley, to encourage males to establish territories around them. After an initialperiod of observation to determine that a male had consolidated its territory around an artificialfeeder, the territorial bird was trapped, marked with non-toxic ink for identification during
103 104 105 106 107 108 109 110 111 112 113	Methods Subjects and Study Site The subjects were nine wild male rufous hummingbirds observed in the Westcastle Valley, eastern Rocky Mountains, Alberta, Canada (N49.349153, W114.410864) between May and July 2017. Rufous hummingbirds winter in Mexico and begin to arrive in the valley in May. Prior to the birds' arrival, artificial feeders containing 20% sucrose solution were placed at sites throughout the valley, to encourage males to establish territories around them. After an initial period of observation to determine that a male had consolidated its territory around an artificial feeder, the territorial bird was trapped, marked with non-toxic ink for identification during experimentation, and released.

115 Initial Training

Each hummingbird was trained to feed from artificial flowers containing 25% sucrose solution.
Artificial flowers consisted of a coloured foam disk, 6 cm in diameter, with a central 1.5 ml
centrifuge tube. Each flower was affixed to a wooden stake, 60 cm long, which could be inserted
vertically into the ground as in Figure 1 a/b. Once a bird had been trained to feed from the
artificial flower in the experimental arena, the experimental training phase began.

121

122 Experimental Training

123 A male's feeder was removed during the hours of the experiment (returned at night and during 124 intervals of precipitation). Birds were presented with a linear array of ten identical artificial 125 flowers (F1-10), spaced at intervals of 20 cm from each other. One end of the array was closer to 126 the location that the feeder normally occupied than was the other end. This orientation potentially provided a stable reference point for the birds as to the ordinal positions of the 127 flowers: the flower closest to the feeder location was always F1, the next was F2, and so on 128 129 (Figure 1c). We had an array of 10 flowers, even though only four were ever rewarded, to control for the direction from which the birds approached the array. 130

Only one flower in the array was filled with 25% sucrose solution and the other nine flowers were empty. On each visit to the array, the hummingbird probed the artificial flowers until he discovered the rewarded position, fed, and flew away. A probe was defined as the bird lowering its bill into a flower's centrifuge tube (Figure 1b). The ordinal position of each probed flower was recorded. Following each visit, the positions of the individual flowers in the array were scrambled so that the bird could not learn to associate reward with small visual cues on the individual flowers, rather than their ordinal positions [30]. Training began with F1 rewarded. Once the bird had probed F1 first on four consecutive visits, the array was moved at least 60 cm from the location of the previous array so that the bird could not depend upon the absolute spatial location of the rewarded flower. The angle of the new array with respect to the feeder location was varied within the predetermined experimental arena, but one end of the array was always closer to the feeder location, to retain the reference point for the bird (Figure 1 c).

To move to the next phase of training (Training to flower F2), the bird needed to meet 144 one of two criteria. If the bird visited F1 on his first visit to the moved array we considered that 145 146 he had learned the ordinal position of the rewarded flower independent of its absolute spatial 147 location, and the next phase of training could begin. Otherwise, the bird was required to search 148 until he found the correct flower, and he had to visit F1 first on four consecutive visits. Then the 149 whole array was moved again, to a new location, to test whether the bird had learned that F1 was 150 rewarded independent of the spatial location. The training array was moved to a maximum of 151 four different locations for each training flower before the training for the next ordinal location 152 began. On reaching either criterion the bird was considered to have learned the ordinal position 153 of the rewarded flower (Supplementary material F1).

This process was repeated for rewarded positions F2 and F3. When F4 was rewarded, training occurred as above, but with the addition of probe test trials, which were conducted on the completion of each training array. Once a bird had visited F4 first four consecutive times, the array was moved to a new location and the distance between the flowers within the array was varied as described below.

159

160 Test Protocol

Because during training flowers were always 20 cm apart in the array, the birds could have used distance from the edge of the array, rather than ordinal position, to locate the rewarded flower. To remove this possible confound, test trials were conducted in which the distances between the artificial flowers were varied.

165 A bird was presented with a test trial once he had reached one of the test criteria (four 166 consecutive visits in which the first flower he probed was F4, or he probed F4 first on the first 167 visit to a new array location after a previous test). Leaving the array in the same location as 168 during training, the distances between the artificial flowers were varied: rather than 20 cm 169 between each flower, the distance was either 10, 30, or 40 cm, with each distance appearing three 170 times randomly throughout the array (Figure 1d). This resulted in the reinforced F4 occurring 171 either nearer to F1 or farther away than it had in training. None of the flowers in the array were 172 rewarded during test trials. The bird's first probe to the test array was recorded. Following this single visit, the array was moved as per the training protocol, and the next training trial presented 173 (i.e. 10 flowers spaced at 20 cm intervals with F4 containing reward). Four test trials were 174 175 conducted per bird, one after each of the F4-rewarded training arrays.

176

177 Analyses

Both training and test data from the combined visits of all birds to a particular location were analysed using one-sample and paired t-tests to determine the significance of percentage probes to each flower in all arrays for a given position. The effect that position of the flower had on the number of mistakes was analysed with a factorial repeated measures ANOVA. A Repeatability test was used to assess if the number of visits during each training phase was repeatable within a bird. A Friedman's ANOVA was used to compare the number of trials the birds took to learn the four different ordinal positions. A chi-square test was used to determine whether during the four training trials birds were equally likely to visit the correct flower as to visit the adjacent flowers. We used Spearman's correlations to test whether the total number of trials or the number of trials when F4 was rewarded were correlated with the test performance of the hummingbirds. We used a binomial test to determine if the birds visited F4 more often than expected by chance at 0.10.

189 All analyses were conducted using R version 3.3.2 [31].

190

191 Results

192 Training Trials

193 A total of 2094 probes made by nine males were recorded during the training phase of the experiment (F1 rewarded: 156 probes, F2: 482 probes, F3: 489 probes, F4: 967 probes). There 194 195 was no consistency in the number of trials individual birds took to reach each flower's training 196 criterion (Repeatability test with a Gaussian distribution, r = 0.06, 95% CI =0-0.38, p = 0.40). 197 Data were analysed at the group level: for each rewarded position, the raw frequencies of probes 198 to reach criterion for each flower by all birds were summed and transformed into percentages. 199 While the percentage of correct choices when the rewarded position was F1 was no 200 different to that when the birds learnt that F4 was the rewarded position (Paired-samples t-test: t₈ = 1.811, p = 0.108), the birds took significantly fewer trials to learn the rewarded position F1 201 than they took to learn rewarded position F4 (Mean number of trials to reach criterion \pm SE, F1: 202 203 17.33 ± 4.1 ; F2: 53.56 ± 11.43 ; F3: 54.33 ± 15.59 ; F4: 107.4 ± 16.59). The birds took 204 significantly more trials to learn the different ordinal positions of the reward (Friedman's ANOVA, $X_3^2 = 19.81$, p < 0.001). Pairwise *Post hoc* tests with Bonferroni correction showed 205 206 that the birds took significantly more trials to learn that F4 was rewarded than when F1 was

rewarded (difference = 24 where the critical difference was 14.45 with α = .05). There was no difference in the number of trials taken to reach criterion between the other pairwise comparisons (e.g. F1 vs F2, F2 vs F3 and so on were all < 14.45).

210 For all rewarded positions, only the rewarded flower was probed significantly above the chance level of 10% (One-sample t-tests: F1 rewarded: $t_8 = 6.838$, p < 0.001; F2: $t_8 = 10.095$, p < 211 0.001; F3: $t_8 = 9.875$, p < 0.001; F4: $t_8 = 19.169$, p < 0.001; Figure 2A). When the rewarded 212 position was F1, the birds probed all other non-rewarded flowers significantly below chance (all 213 t-values \leq -6, all p < 0.05). When the rewarded position was F2, the adjacent F1 and F3 were 214 probed at chance (one-sample t-tests: F1: $t_8 = -0.986$, p = 0.353; F3: $t_8 = -0.016$, p = 0.988); all 215 216 others were probed significantly below chance (all t-values \leq -18, all p < 0.05). When the 217 rewarded position was F3, the adjacent F2 and F4 were probed at chance (one-sample t-tests: F2: 218 $t_8 = -0.988$, p = 0.352; F4: $t_8 = -1.534$, p = 0.164). All other flowers were probed significantly 219 below chance (all t-values \leq - 4.4, all p \leq 0.05). Finally, when the rewarded position was F4, adjacent F3 was probed at chance (one-sample t-test: $t_8 = -0.378$, p = 0.715). All other flowers 220 221 were probed significantly below chance (all t-values \leq - 20, all p \leq 0.05).

In all cases, the birds chose the correct flower significantly more often than they chose the adjacent flowers ($X^{2}_{3} = 8.52$, p = 0.03). When either F2, F3, or F4 were rewarded, which of these flowers was rewarded had no significant effect on the percentage of errors to either side of the correct flower (Factorial repeated measures ANOVA: F_{2, 16} = 0.49, p = 0.61). Specifically, birds were not more likely to make an error to the flower closest to the start of the array (near flower) or to the other side of the rewarded flower (far flower; F_{1, 8} = 0.001, p = 0.97) when either F2, F3 or F4 were rewarded (Figure 2B).

230 Test Trials

Each of the 9 birds completed 4 tests. They chose F4 a mean of 1.78 (±0.36) times. There was variation in individual performance, ranging from 0 to 4 choices. The performance during the test was not correlated with either the total number of trials the birds completed during the training ($r_s = 0.10$, p = 0.79) or with the number of trials birds took to reach the F4 criterion ($r_s =$ 0.05, p = 0.88). Overall, F4 was chosen 16 times whereas chance performance would predict 3.6 times.

The birds probed F4 significantly more often than the chance level of 10% (one-sample ttests: $t_8 = 3.782$, p = 0.005). They visited F1-3 and F5 at chance (one-sample t-tests: all t-values ≤ 1.131 , all p-values ≥ 0.291), while all other flowers were visited significantly below chance (One-sample t-tests: all t-values ≤ -2.6 , all $p \leq 0.032$; Figure 3A).

241 For arrays for which distance data were available (Supplementary material F2), F4 was 242 located between 50 cm and 110 cm into the array, compared to the training distance for F4, 243 which was always 60 cm. Therefore, the relative location of F4 in the test array compared to its 244 location in the training array may have played a role in each bird's decision as to which flower to probe. Unfortunately, due to human error during data collection, the actual distances between 245 246 flowers were recorded for only 22 of the 36 test arrays. Thus, we further analysed only the 247 choices made by the hummingbirds during the tests for which we have distance data. 248 Additionally, there was a 1/11 chance that the distance to F4 in training would be identical to the 249 training distance of 60 cm. This redundancy of distances occurred in two of the test arrays for 250 which distance was recorded, but may also have occurred during one or more of the test arrays 251 for which distance data are missing.

During the tests for which we know the distance between flowers, ordinality (the 4th flower) strongly influenced the choice made by those 6 birds (binomial test with an expected proportion of 0.10 for F4: 9/22, Z = 4.83 p < 0.001). Exclusion of the two tests for which distances were redundant (60 cm) made little difference to the significance of the results (binomial test with an expected proportion of 0.10 for F4: 8/20, Z = 4.47 p < 0.001). Therefore, they have been included in all later analyses.

258 Distance from the edge of the array did not strongly influence flower choice as neither 259 correct (F4) nor incorrect (other choices) were concentrated at or near the F4 training distance of 260 60 cm (Figure 3B). When a flower actually occurred at the 60 cm distance (6 times during the 261 tests) however, it was selected more frequently than chance (binomial test with an expected proportion of 0.10 for the flower at 60 cm: 3/6, Z = 3.26, p = 0.01). Flowers occurring near or at 262 263 this distance (50, 60 or 70 cm) were probed more frequently than chance (binomial test with an expected proportion of 0.10 for the flowers at 50, 60 and 70 cm: 6/22, Z =2.7, p = 0.01). Birds 264 265 visited the 4th flower in the array in 41% of the tests, while the flower position at or closest to 60 266 cm was visited 27% of the tests. Errors were concentrated at the near end of the array with birds 267 visiting F1, F2 and F3 more often than expected by chance (binomial test with an expected 268 proportion of 0.10 for either F1, F2, F3: 10/13, Z = 8.04, p < 0.01).

269

270 Discussion

Rufous hummingbirds were tested for their ability to re-locate a rewarded artificial flower based
on its ordinal position in a linear array. During training, the birds probed only the rewarded
flower significantly above chance and did so consistently across four sequentially rewarded
positions: the birds were no more accurate at re-locating rewarded F1 than they were at re-

275 locating rewarded F4. Errors during training were concentrated around the flowers adjacent to 276 the rewarded flower, although at rewarded F4 the birds showed a bias toward erring on the 277 adjacent flower on the near side of the rewarded flower (i.e. F3). During testing, the distances 278 between the individual flowers in the array were altered so that distance information within the 279 training array was rendered ineffective. Above chance performance on the test arrays indicates 280 that the birds had encoded ordinal information during training and could apply it in the tests. 281 Additionally, during tests there was a clear directional bias to the birds' errors: most occurred on the near side of the array, i.e. choices to flowers the birds had previously experienced as 282 283 rewarded. However, test choices were better explained by ordinal position than by distance from 284 the beginning of the array.

These data support the proposition that the birds used an object-indexing system rather than a magnitude-based mechanism to determine the ordinal position of the rewarded flower. This result is perhaps not surprising, as the analogue magnitude preverbal number system appears to become salient only when animals process numerosities greater than four (e.g. [32] but see [10]).

290 The distributions of errors that the birds made during training were not constant across 291 rewarded positions. When F1 was rewarded, the birds visited all non-rewarded flowers 292 significantly below chance. This could be because the birds learned to forage at the edge of the 293 array, rather than from the first ordinal position. When F2 and F3 were rewarded, in both cases 294 the two flowers adjacent to the rewarded flower were visited at chance (Figure 2A), indicating 295 that errors were mostly concentrated around the rewarded flower. This distribution of errors 296 could be the result of mistakes due to generalisation of the spatial location of the rewarded 297 flower: the bird learned that the reward was near the closest edge of the array. The distribution of

298 errors when F4 was rewarded however, was notable in that only F3, the adjacent flower on the 299 near side of the array, was visited at chance: all other flowers, including adjacent F5, were 300 probed significantly below chance. The tendency for the birds to make more errors towards the 301 near edge of the array could be the result of a recency effect (i.e. a bias towards visiting a 302 recently rewarded position). Rugani et al., [33], using a similar paradigm to investigate ordinality 303 in chicks, controlled for past experience and observed a similar effect, attributing it to the birds 304 using a 'working up' strategy to locate the correct ordinal position, similar to that observed in rats [17]. If the birds used one edge of the array as a reference point and mentally 'worked up' to 305 306 find the correct ordinal position, they should have made more errors on the near side of array 307 closest to the reference edge, in this case F1. This is exactly where the hummingbirds made their 308 mistakes during the tests, closest to the F1 edge of the array. It is also how we trained the birds. 309 A working up strategy could relate to the way the hummingbirds perceived the array. Previous studies that used a similar paradigm to the present study were all conducted in the lab, 310 311 allowing for a greater amount of control over the way in which the animals initially perceived the 312 array, as the subjects' point of view could be controlled by designating a starting location for 313 them. Subjects are more accurate when they can see the entire array at once, rather than 314 encountering items in the array sequentially [e.g., 18]. Since the hummingbirds in this study were 315 wild and took part in the experiment by choice, the way in which the birds visually perceived the 316 array could not be controlled. Nonetheless, because the flowers were reasonably large, the 317 training array was less than 2m in length, and birds could view the array from several metres above the ground, it can be assumed with relative certainty that the birds encountered the array 318 319 visually as a whole and were thus operating similarly to laboratory subjects given a complete 320 view of an array.

321 Overall, the distribution of errors during testing exhibited a directional bias that was a 322 more extreme version of the effect demonstrated during training to F4. While during training the 323 birds erred mostly on the near adjacent position, F3, during tests the birds additionally erred at 324 F1 and F2, on a sizable proportion of visits. Unlike training at F4, the birds also visited F5, the 325 other adjacent flower, at chance rather than below chance. Despite these differences, the birds' 326 performance suggests that the birds were using the same ordinal strategy during testing as they 327 were during training. If so, it follows that some aspect of the birds' ordinal strategy was 328 confounded by the change in the test array. In other words, the 'working up' strategy posited to 329 be the reason behind the directionally biased error effect in training was somehow exacerbated 330 by the manipulation of inter-flower distances. It is possible however, that the birds were using 331 both ordinal as well as distance information. When the distance information was made unreliable 332 during the tests and even though birds did visit the fourth flower more often than expected by 333 chance, when they made an error they made it to the flowers that were near the training distance. 334 A male rufous hummingbird may spend weeks or months in a territory, but the flowers 335 from which he feeds will be far more ephemeral. Thus, a traplining hummingbird should be able 336 to constantly adjust its trapline as some flowers bloom and others die. Using ordinality would 337 allow this kind of flexibility. If each position in a hummingbird's trapline is assigned an ordinal 338 value, the bird could follow this order and make adjustments as needed. If one location is no 339 longer viable (e.g. the flower has senesced), then the bird could skip to the next ordinal position 340 and strike the defunct flower from its trapline. Likewise, if a bird encountered a newly bloomed flower, it could adjust its trapline by inserting the flower in between adjacent ordinal positions. 341 342 As research into the numerical abilities of non-human animals has gained momentum 343 over the past two decades, there is now broad consensus that animals perceive number and that

344	the ability for elementary numerical computation such as ordering units, is taxonomically
345	widespread, from arthropods to humans [34]. To our knowledge, our data represent the first
346	demonstration of numerical ordinality in a free-living wild vertebrate. It remains to be seen
347	whether numerical ordinality is governed by an object-indexing or an analogue magnitude
348	system of number, and to what extent the system used is a reflection of the birds' ecological role
349	as pollinators.
350	
351	References
352	[1] Brannon EM. 2006. The representation of numerical magnitude. Curr. Opin. Neurobiol. 16,
353	222–229.
354	[2] Gallistel CR, Gelman R. 1992. Preverbal and verbal counting and computation. Cognition 44,
355	43–74.
356	[3] White DI Ho I. Freed-Brown G 2009 Counting chicks before they hatch: female cowbirds
357	can time readiness of a host nest for parasitism. <i>Psychol. Sci.</i> 20 , 1140–1145.
358	[4] Bar-Shai N, Keasar T, Shmida A. 2011. The use of numerical information by bees in foraging
359	tasks. <i>Behav. Ecol.</i> 22 , 317–325.
360	[5] Davis H, Pérusse R. 1988. Numerical competence in animals: Definitional issues, current
361	evidence, and a new research agenda. Behav. Brain Sci. 11, 561-615.
362	[6] Hutchins E. 2010. Cognitive Ecology. Top. Cogn. Sci. 2, 705–715.
363	[7] Pica P, Lemer C, Izard V, Dehaene S. 2004. Exact and approximate arithmetic in an
364	Amazonian indigene group. Science 306, 499–503.

- [8] Hyde DC. 2011. Two systems of non-symbolic numerical cognition. *Front. Hum. Neurosci.*5, 1–8.
- 367 [9] Haun DBM, Jordan FM, Vallortigara G, Clayton NS. 2010. Origins of spatial, temporal, and
 368 numerical cognition: Insights from comparative psychology. *Trend. Cogn.* 14, 552-560.
- 369 [10] Garland A, Low J, Burns KC. 2012. Large quantity discrimination by North Island robins
 370 (*Petroica longipes*). *Anim. Cogn.* 15, 1129–1140.
- [11] Rugani R, Vallortigara G, Regolin L. 2014. From small to large: Numerical discrimination
 by young domestic chicks (*Gallus gallus*). J. Comp. Psychol. 128, 163–171.
- 373 [12] Stancher G, Rugani R, Regolin L, Vallortigara G. 2015. Numerical discrimination by frogs
 374 (*Bombina orientalis*). *Anim. Cogn.* 18, 219–229.
- 375 [13] Gazzola A, Vallortigara G, Pellitteri-Rosa D. 2018. Continuous and discrete quantity
 376 discrimination in tortoises. *Biol. Lett.* 14, 1–4.
- 377 [14] Bortot M, Stancher G, Vallortigara G. 2020. Transfer from Number to Size Reveals
- 378 Abstract Coding of Magnitude in Honeybees. *iScience* 23, 101122 (2020).
- [15] Lyons IM. Vogel SE, Ansari D. 2016. On the ordinality of numbers: A review of neural and
 behavioral studies. *Prog. Brain. Res.* 227, 187-221.
- [16] Pepperberg IM, Carey S. 2012. Grey parrot number acquisition: The inference of cardinal
 value from ordinal position on the numeral list. *Cognition* 125, 219–232.
- [17] Davis H, Bradford SA. 1986. Counting behavior by rats in a simulated natural environment. *Ethology* 73, 265–280.

- [18] Petrazzini MEM, Lucon-Xiccato T, Agrillo C, Bisazza A. 2015. Use of ordinal information
 by fish. *Sci. Rep.* 5, 1–11.
- [19] Drucker CB, Brannon EM. 2014. Rhesus monkeys (*Macaca mulatta*) map number onto
 space. *Cognition* 132, 57–67.
- 389 [20] Dacke M, Srinivasan MV. 2008. Evidence for counting in insects. *Anim. Cogn.* 11, 683–
 390 689.
- [21] Pritchard DJ, Hurly TA, Tello-Ramos MC, Healy SD. 2016. Why study cognition in the
 wild (and how to test it)? *J. Exp. Anal. Behav.* 105, 41–55.
- 393 [22] Brannon EM. 2002. The development of ordinal numerical knowledge in infancy.
 394 *Cognition*, 83, 223–240.
- 395 [23] Healy SD, Hurly TA. 2003. Cognitive Ecology: Foraging in hummingbirds as a model
 396 system. *Adv. Stud. Behav.* 32, 325–359.
- 397 [24] Healy SD, Hurly TA. 2013. What hummingbirds can tell us about cognition in the wild.
 398 *Comp. Cogn. Behav Rev.* 8, 13–28.
- 399 [25] Hurly TA, Healy SD. 1996. Memory for flowers in rufous hummingbirds: Location or local
 400 visual cues? *Anim. Behav.* 51, 1149–1157.
- 401 [26] Tello-Ramos MC, Hurly TA, Higgott C, Healy SD. 2015. Time-place learning in wild, free402 living hummingbirds. *Anim. Behav.* 104, 123–129.
- 403 [27] Ackerman JD, Mesler MR, Lu KL, Montalvo AM. 1982. Food-foraging behavior of male
 404 euglossini (*Hymenoptera: Apidae*): Vagabonds or trapliners? *Biotropica* 14, 241–248.

405	[28] Tello-Ramos MC, Hurly TA, Healy SD. 2015. Traplining in hummingbirds: Flying short						
406	distance sequences among several locations. Behav. Ecol. 26, 812-819.						
407	[29] Tello-Ramos MC, Hurly TA, Healy SD. 2019. From a sequential pattern temporal						
408	adjustments emerge in hummingbird traplining. Integr. Zool. 14, 182-192.						
409	[30] Hornsby MAW, Hurly TA, Hamilton CE, Pritchard DJ, Healy SD. 2014. Wild, free-living						
410	rufous hummingbirds do not use geometric cues in a spatial task. Behav. Proc. 108, 138-						
411	141.						
412	[31] R Core Team. 2016. R: A language and environment for statistical computing. R						
413	Foundation for Statistical Computing, Vienna, Austria. URL https://www.R-project.org/.						
414	[32] Hauser MD, Carey S, Hauser LB. 2000. Spontaneous number representation in semi-free-						
415	ranging rhesus monkeys. P Roy Soc B-Biol Sci. 267, 829-833.						
416	[33] Rugani R, Regolin L, Vallortigara G. 2007. Rudimental numerical competence in 5-day-old						
417	domestic chicks (Gallus gallus): Identification of ordinal position. J Exp Psychol. 33, 21-						
418	31.						
419	[34] Butterworth B, Gallistel CR, Vallortigara G. 2018. Introduction: The origins of numerical						
420	abilities," Philos. Trans. R. Soc. B Biol. Sci., 373, 20160507.						
421							
422 423							
424							
425							
420 427							
428							
429							
430 421							
431 432							

433 Figure Legends

434 Figure 1. (a) Photograph of an array. (b) A rufous hummingbird probing an artificial flower. 435 Photographs: Tom Oldridge. (c) Schematic of four possible training array positions. Flower 436 positions F1-10 were determined based on the array's orientation towards the feeder. Distance 437 between flowers is 20 cm. Note: during the experiment, the feeder was removed. One end of 438 each array is always closer to the feeder location than the other, allowing the birds a reference 439 point for determining which position was rewarded. F1 in each array is always at least 60 cm away from F1 of the previous array. (d) A training array (top) and an example test array 440 441 (bottom). Circled flowers are the reinforced positions (no reward provided during test trials). Note: the distance from the first flower to the rewarded flower in the training array is 60 442 443 (20+20+20) while in the test array it is 110 (40+30+40). Figures not to scale. 444 445 Figure 2. A) The percentage of probes made by birds to each position, for each rewarded 446 position during training trials (Mean +/- SEM). The dashed line represents chance at 10%. B) The percentage of errors made to flowers near (white bars) and far (grey bars) from the edge of 447 448 the array when F2, F3, and F4 was rewarded (Mean +/- SEM). For example, when F2 was 449 rewarded the "near" flower was F1 and the "far" flower was F3.

450

Figure 3. A) The percentage of probes by birds to each position of test arrays (Mean +/- SEM).
The dashed line represents chance at 10%. B) Number of visits to flowers at different distances
from the edge of the array. White bars represent visits to flowers that were not F4. Grey bars
represent visits to F4 at different distances during the test. The red box represents the distance of
F4 during training (at 60 cm).

457 Acknowledgements

- 459 This work was supported by the Association for the Study of Animal Behaviour (S. D. H.), the
- 460 University of Lethbridge, and the Natural Sciences and Engineering Research Council of Canada
- 461 (RGPIN 121496-2003; T. A. H.). We also thank Georgina Glasser and Tom Oldridge for their
- 462 help with field work and two anonymous reviewers for their helpful suggestions.
- 464 Figure1







Supplementary material F1. Diagram of the training criteria. In order to move to the next phase of training, the bird needed to meet one of two criteria. Once a bird had visited four consecutive times the rewarded flower in first place the array was moved. If the bird visited the rewarded flower first at the new location we considered that bird had learned the ordinal position of the rewarded flower and the criterion was met. The bird was then trained to visit the next rewarded location. Alternatively, the bird was required to search until he found the correct flower and to visit the rewarded flower first for four consecutive visits. The training array was moved to a maximum of four different locations for each training flower before the training for the next ordinal location began. On reaching either criterion the bird was considered to have learned the ordinal position of the rewarded flower.



Bird 1, Test 1	0	30 40	80	120	150 16	0 170	200	240
Bird 1, Test 2	0 10	40	80	110	150 16	190	0	230 240
Bird 1, Test 3	0	40 50	80 90	(130 (16	.0 (190	0 200	240
Bird 1, Test 4	0 10	50 64	90	100 (130	170	200	240
Bird 3, Test 1	0 10	50 60	90	(130 (16	0	200 210	240
Bird 3, Test 2	0	30	70	100	130 140 150 16	0	200	240
Bird 3, Test 3	0	30 40	70	110	150 16	0	200 210	240
Bird 3, Test 4	0	40	70 80	110	140	180 190	•	230 240
Bird 6, Test 1	0 10	50	90	100	130 140	170	210	240
Bird 6, Test 2	0	40	70 (100 (130	170 180 190	0 200	240
Bird 6, Test 3	0	30 60		100 110	150 16	0 170	210	240
Bird 6, Test 4	0 10	40 50 60		100	140	180	210	240
Bird 7, Test 1	0	40	80	110	140	180 19	0 200 210	240
Bird 7, Test 2	0 10	40 50	90	100	130 16	0	200	240
Bird 7, Test 3	0	30	70 80 90	(130 140	170	210	240
Bird 8, Test 1	0	30 64	70	110	140 150 16	0	200	240
Bird 8, Test 2	0 10	50	90	100 (130 140	170	210	240
Bird 8, Test 3	0	30	70 80	110	150 16	0	200	230 240
Bird 8, Test 4	0	30 64	0 70	110 120	(16	i0 170	200	240
Bird 9, Test 1	0 10	20 50	90	120	130 (16	0	200	240
Bird 9, Test 2	0	40	70	100 110	140 150	(19	0	230 240
Bird 9, Test 3	0	40 50	80 90	120	(16	0 170	210	240

Supplementary material F2. Test arrays for which the distance between flowers are known (22 test for 6 birds). Circles represent flowers. The numbers inside each flowers are the distances from the edge of the array to that flower. The coloured flowers represent the bird's visit to that flower and were the green ones were probed 'correctly' (F4).