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Fluctuating hydrodynamics for dilute granular gases

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Starting from the kinetic equations for the fluctuations and correlations of a dilute gas of inelastic hard spheres or disks, a Boltzmann-Langevin equation for the one-particle distribution function of the homogeneous cooling state is constructed. This equation is the linear Boltzmann equation with a fluctuating white-noise term. Balance equations for the fluctuating hydrodynamic fields are derived. New fluctuating forces appear as compared with the elastic limit. The particular case of the transverse velocity field is investigated in detail. Its fluctuations can be described by means of a Langevin equation, but exhibiting two main differences with the Landau-Lifshitz theory: the noise is not white, and its second moment is not determined by the shear viscosity. This shows that the fluctuation-dissipation relations for molecular fluids do not straightforwardly carry over to inelastic gases. The theoretical predictions are shown to be in good agreement with molecular-dynamics simulation results.

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I. INTRODUCTION

The (modified) nonlinear Boltzmann equation for the oneparticle distribution function provides an accurate description of transport phenomena in a low-density gas of inelastic hard spheres or disks [1–5]. These particles are often used to model granular fluids [6], especially in the rapid-flow regime [7]. The Boltzmann equation does not provide any direct information about correlations and fluctuations in the gas other than the particle velocity moments. Nevertheless, methods used in the derivation of the Boltzmann equation have been extended to obtain kinetic equations for the equaland different-time correlations, in the same low-density approximation. The general idea is that in order to obtain these equations, the needed approximations are the same as those used to derive the Boltzmann equation itself.

One of the earliest and physically more transparent methods used to study fluctuations is that of Langevin equations. Almost 40 years ago, in a seminal paper Bixon and Zwanzig [8] showed how a Boltzmann-Langevin equation could be constructed by generalizing the reasonings leading to the Boltzmann equation for molecular gases. The latter describes the behavior of the average value of the one-particle distribution function, while the former incorporates the effects of the fluctuations. As the authors indicated themselves in the paper, the derivation was based on physical intuition and analogy. A more systematic derivation of the same result, starting from first principles, was given in Ref. [9].

A second approach to the study of correlations in dilute gases makes use of functional analysis. Its more general result is a kinetic equation for a generating functional at low density, from which all multipoint correlations can be obtained by functional differentiation [10]. A closely related general scheme for the study of correlations is the hierarchical method [11,12]. The starting points are hierarchies of coupled equations for the time distribution functions describing the fluctuations and correlations. Then, the hierarchies are closed by using the same kind of approximations as needed to derive the kinetic equation, i.e., the Boltzmann equation in the case of dilute gases. This method has been recently extended to describe fluctuations and correlations of dilute inelastic gases in their simplest state, the homogeneous cooling state (HCS) [13]. As an application, the fluctuations of the total energy were studied and good agreement between theory and simulation results was found [13,14]. Previously, there had been some studies based on a model kinetic equation for dilute granular gases [15].

One of the aims of this paper is to translate the above formalism in terms of kinetic equations for the correlation functions into a Langevin equation formulation, i.e., to extend the fluctuating Boltzmann equation to the case of inelastic hard spheres or disks. The relationship between kinetic equations and the fluctuating Boltzmann equation has been analyzed in detail in molecular gases [12,16]. One advantage of the Langevin formulation is that it is closer to the fluctuating hydrodynamic equations. Actually, the fluctuating Boltzmann equation for molecular systems has been shown [8,17,18] to lead to the same Langevin equations for the hydrodynamic fields as obtained by Landau and Lifshitz [19] using thermodynamic fluctuation theory. The noise terms in these equations are assumed to be white with second moments determined by the Navier-Stokes transport coefficients of the fluid. Their expressions are known as fluctuationdissipation relations of the second kind [20].

The derivation of fluctuating hydrodynamic equations from the fluctuating Boltzmann equation for inelastic hard particles will be also addressed here. Attention will be focused on a particular state, the HCS, and on a specific hydrodynamic field, the transverse component of the velocity. The main conclusion will be that the fluctuation-dissipation relation for elastic gases cannot be directly extrapolated to inelastic ones, but it needs to be significantly modified. The second moment of the noise is not determined by the Navier-Stokes shear viscosity. Moreover, the noise cannot be assumed to be white. These theoretical predictions are in qualitative and quantitative agreement with molecular-dynamics simulation results.

The consideration of the HCS does not imply by itself that the results obtained here are not relevant for other states more accessible experimentally. The HCS plays for inelastic gases a role similar to the equilibrium state for molecular gases. In the case of molecular systems, the expressions of the transport coefficients obtained by linearizing around equilibrium are the same as those appearing in the nonlinear Navier-Stokes equations as predicted by the Chapman-Enskog method and successfully used in many far-fromequilibrium problems [21]. Also, the fluctuation-dissipation relations derived for near-local-equilibrium states in the original Landau-Lifshitz theory have proven to be accurate for many other hydrodynamic states [22]. For dilute gases composed of inelastic hard particles, the equivalence between the transport coefficients obtained by linear perturbations of the HCS and by applying the Chapman-Enskog procedure has also been established [23]. Something similar might be expected for the fluctuations and correlations.

In the system being considered here, the particles move freely and independently between consecutive collisions. More specifically, they are not coupled to any external energy source or thermal bath, contrary to the driven granular gas models. For these models, the linear response to an external perturbation [24] as well as the validity of the Einstein relation [25] has been investigated by numerical simulations, and some empirical models have been proposed. It is not evident that there is a direct relation between the free model considered here and the above driven models.

The plan of the paper is as follows. In Sec. II, the kinetic equations for the one-time and two-time correlation functions of a dilute gas in the HCS derived in Ref [13] are shortly reviewed. These equations are translated into an equivalent Boltzmann-Langevin equation for the one-particle distribution function in Sec. III. When written in the appropriate variables, this equation is the linear Boltzmann equation to which a fluctuating force term is added, similarly to what happens in molecular elastic gases. An expression for the second moment of the fluctuating force in terms of the collisional Boltzmann kernel is derived. In Sec. IV, the fluctuating hydrodynamic fields are defined, and balance equations for them are obtained from the Boltzmann-Langevin equation. They involve formal expressions for the fluctuating pressure tensor, the fluctuating heat flux, and the fluctuating cooling rate. In addition, an intrinsically inelastic fluctuating force shows up in the equation for the energy.

To get a closed description for the hydrodynamic fluctuations, expressions for the heat flux, the pressure tensor, and the cooling rate in terms of the fluctuating hydrodynamic fields are needed. This can be accomplished by means of the Chapman-Enskog procedure. Here only the case of the transverse component of the velocity field will be considered. As a consequence, only the expression for the nondiagonal elements of the pressure tensor is required. This is computed in Sec. V. The final result is a Langevin equation that is the linear macroscopic equation for the transverse velocity field plus a fluctuating force term. Therefore, the structure is similar to what one could expect by extrapolating from the corresponding equation for molecular systems [26]. Nevertheless, in Sec. VI it is shown that the noise term is not white and its second moment is not given by the usual fluctuationdissipation relation. It is verified that the obtained theoretical predictions are in good agreement with molecular-dynamics simulation results. Section VII contains some general comments and conclusions. Finally, Appendixes A–C provide some details of the calculations needed to derive the results presented in the bulk of the paper.

II. KINETIC EQUATIONS FOR THE HOMOGENEOUS COOLING STATE

The system considered is a dilute gas of *N* smooth inelastic hard spheres (d=3) or disks (d=2) of mass *m* and diameter σ . The position and velocity of the *i*th particle at time *t* will be denoted by $\mathbf{R}_i(t)$ and $V_i(t)$, respectively. The effect of a collision between particles *i* and *j* is to instantaneously modify their velocities according to the rule

$$V_{i} \rightarrow V_{i}' = V_{i} - \frac{1+\alpha}{2} (\hat{\boldsymbol{\sigma}} \cdot V_{ij}) \hat{\boldsymbol{\sigma}},$$
$$V_{j} \rightarrow V_{j}' = V_{j} + \frac{1+\alpha}{2} (\hat{\boldsymbol{\sigma}} \cdot V_{ij}) \hat{\boldsymbol{\sigma}},$$
(1)

where $V_{ij} = V_i - V_j$ is the relative velocity, $\hat{\sigma}$ is the unit vector pointing from the center of particle *j* to the center of particle *i* at contact, and α is the coefficient of normal restitution. It is defined in the interval $0 < \alpha \le 1$ and it will be considered here as constant, independent of the velocities of the particles involved in the collision. A more realistic modeling of granular gases would require consideration of a velocitydependent restitution coefficient [5].

Given a trajectory of the system, one-point and two-point microscopic densities in phase space at time t are defined by

$$F_1(x_1,t) = \sum_{j=1}^{N} \delta(x_1 - X_j(t))$$
(2)

and

$$F_2(x_1, x_2, t) = \sum_{i}^{N} \sum_{j \neq i}^{N} \delta(x_1 - X_i(t)) \delta(x_2 - X_j(t)), \qquad (3)$$

respectively. Here $X_i(t) = \{\mathbf{R}_i(t), \mathbf{V}_i(t)\}$, while the $x_i = \{\mathbf{r}_i, \mathbf{v}_i\}$ are field variables referring to the one-particle phase space (μ space). The density $F_1(x_1, t)$ obeys the equation [11,13]

$$\left[\frac{\partial}{\partial t} + \boldsymbol{v}_1 \cdot \frac{\partial}{\partial \boldsymbol{r}_1}\right] F_1(x_1, t) = \int dx_2 \overline{T}(x_1, x_2) F_2(x_1, x_2, t), \quad (4)$$

with

$$\overline{I}(x_i, x_j) = \sigma^{d-1} \int d\hat{\boldsymbol{\sigma}} \; \Theta(\boldsymbol{v}_{ij} \cdot \hat{\boldsymbol{\sigma}}) |\boldsymbol{v}_{ij} \cdot \hat{\boldsymbol{\sigma}}| \\ \times [\alpha^{-2} \delta(\boldsymbol{r}_{ij} - \boldsymbol{\sigma}) b_{\boldsymbol{\sigma}}^{-1}(\boldsymbol{v}_i, \boldsymbol{v}_j) - \delta(\boldsymbol{r}_{ij} + \boldsymbol{\sigma})], \quad (5)$$

where $d\hat{\sigma}$ is the solid angle element for $\hat{\sigma} \equiv \sigma/\sigma$, $r_{12} \equiv r_1 - r_2$, Θ is the Heaviside step function, and $b_{\sigma}^{-1}(v_1, v_2)$ is an operator replacing all the functions of v_1 and v_2 to its right by the same functions of the precollisional values v_1^* and v_2^* given by

$$\boldsymbol{v}_1^* \equiv \boldsymbol{b}_{\boldsymbol{\sigma}}^{-1} \boldsymbol{v}_1 = \boldsymbol{v}_1 - \frac{1+\alpha}{2\alpha} (\hat{\boldsymbol{\sigma}} \cdot \boldsymbol{v}_{12}) \hat{\boldsymbol{\sigma}},$$

$$\boldsymbol{v}_2^* \equiv \boldsymbol{b}_{\boldsymbol{\sigma}}^{-1} \boldsymbol{v}_2 = \boldsymbol{v}_2 + \frac{1+\alpha}{2\alpha} (\hat{\boldsymbol{\sigma}} \cdot \boldsymbol{v}_{12}) \hat{\boldsymbol{\sigma}}.$$
 (6)

It is seen that Eq. (4) for F_1 involves the two-particle density F_2 . Actually, it is the first equation of an infinity hierarchy [13].

The averages of $F_1(x_1,t)$ and $F_2(x_1,x_2,t)$ over the initial probability distribution of the system $\rho(\Gamma,0)$, $\Gamma \equiv \{X_1,\ldots,X_N\}$, are the usual one-particle and two-particle distribution functions,

$$f_1(x_1,t) = \langle F_1(x_1,t) \rangle, \quad f_2(x_1,x_2,t) = \langle F_2(x_1,x_2,t) \rangle,$$
(7)

where the notation

$$\langle G \rangle \equiv \int d\Gamma G(\Gamma) \rho(\Gamma, 0)$$
 (8)

has been employed. Two-time reduced distribution functions can also defined from the microscopic densities and the initial probability distribution. The simplest one is the twoparticle two-time distribution function

$$f_{1,1}(x_1,t;x_1',t') = \langle F_1(x_1,t)F_1(x_1',t') \rangle.$$
(9)

From the definitions in Eqs. (7) and (9) it follows that

$$f_{1,1}(x_1,t;x_1',t) = \delta(x_1 - x_1')f_1(x_1,t) + f_2(x_1,x_1',t).$$
(10)

It is convenient to introduce one-time and two-time correlation functions as

$$g_2(x_1, x_2, t) \equiv f_2(x_1, x_2, t) - f_1(x_1, t) f_1(x_2, t), \qquad (11)$$

and

$$h_{1,1}(x_1,t;x_1',t') \equiv f_{1,1}(x_1,t;x_1',t') - f_1(x_1,t)f_1(x_1',t'),$$
(12)

respectively. Equation (10) translates into

$$h_{1,1}(x_1,t;x_1',t) = \delta(x_1 - x_1')f_1(x_1,t) + g_2(x_1,x_1',t).$$
(13)

In the low-density limit, a closed set of kinetic equations for f_1 , g_2 , and $h_{1,1}$ can be derived [13] by extending the methods developed for molecular gases [12]. They can be used to analyze the average properties as well as correlations and fluctuations in arbitrary states of a dilute granular gas. Here attention will be restricted to a particular state of a freely evolving granular gas, the so-called HCS [27]. Macroscopically, it is characterized by a uniform number of particles density n, a vanishing velocity field, and a uniform time-dependent temperature T(t). It is further defined by the one-particle distribution function having the scaled form [1]

$$f(\boldsymbol{v},t) = n \boldsymbol{v}_0^{-d}(t) \boldsymbol{\chi}(c), \qquad (14)$$

$$v_0(t) \equiv \left[\frac{2T(t)}{m}\right]^{1/2} \tag{15}$$

is a thermal velocity and $\chi(c)$ is an isotropic function of the scaled velocity $c \equiv v/v_0(t)$. The distribution $\chi(c)$ and the granular temperature T(t) are specified by the pair of coupled equations

$$\frac{\partial T}{\partial s} = -\zeta_0 T(s), \tag{16}$$

$$\sum_{c=0}^{k_0} \frac{\partial}{\partial c} \cdot (c\chi) = J_c[c|\chi].$$
(17)

In the above expressions,

$$\zeta_0 = \frac{(1 - \alpha^2)\pi^{(d-1)/2}}{2\Gamma\left(\frac{d+3}{2}\right)d} \int d\mathbf{c}_1 \int d\mathbf{c}_2 c_{12}^3 \chi(c_1)\chi(c_2) \quad (18)$$

is the dimensionless cooling rate in the time scale s defined by

$$s \equiv \int_0^t dt_1 \frac{v_0(t_1)}{\lambda},\tag{19}$$

with $\lambda \equiv (n\sigma^{d-1})^{-1}$, and $J_c[c|\chi]$ is the inelastic Boltzmann collision term. Its explicit form is

$$J_{c}[\boldsymbol{c}|\boldsymbol{\chi}] = \int d\boldsymbol{c}_{1} \overline{T}_{0}(\boldsymbol{c},\boldsymbol{c}_{1})\boldsymbol{\chi}(c)\boldsymbol{\chi}(c_{1}), \qquad (20)$$

$$\bar{T}_{0}(\boldsymbol{c},\boldsymbol{c}_{1}) = \int d\hat{\boldsymbol{\sigma}} \Theta[(\boldsymbol{c}-\boldsymbol{c}_{1})\cdot\hat{\boldsymbol{\sigma}}](\boldsymbol{c}-\boldsymbol{c}_{1})\cdot\hat{\boldsymbol{\sigma}}[\alpha^{-2}b_{\boldsymbol{\sigma}}^{-1}(\boldsymbol{c},\boldsymbol{c}_{1})-1].$$
(21)

The variable *s* defined in Eq. (19) is proportional to the accumulated number of collisions per particle. For thermal velocities, i.e., values of *c* on the order of unity, a good approximation to the solution of Eqs. (16) and (17) is provided by the first Sonine approximation, in which [1,28]

$$\chi(c) = \frac{e^{-c^2}}{\pi^{d/2}} [1 + a_2(\alpha) S^{(2)}(c^2)], \qquad (22)$$

with

$$S^{(2)}(c^2) = \frac{c^4}{4} - \frac{d+2}{2}c^2 + \frac{d(d+2)}{8}$$
(23)

and

$$a_2(\alpha) = \frac{16(1-\alpha)(1-2\alpha^2)}{9+24d+(8d-41)\alpha+30\alpha^2-30\alpha^3}.$$
 (24)

In the same approximation

$$\zeta_0 = \frac{\sqrt{2} \, \pi^{(d-1)/2} (1-\alpha^2)}{\Gamma(d/2) d} \left[1 + \frac{3a_2(\alpha)}{16} \right]. \tag{25}$$

A numerically exact solution of Eqs. (16) and (17) was recently reported in [29]. The two-particle one-time correlation

where

function of the HCS is assumed to have also a scaled form [13],

$$g_2(\boldsymbol{r}_{12}, \boldsymbol{v}_1, \boldsymbol{v}_2, t) = n\lambda^{-d} v_0^{-2d}(t) \tilde{g}(\boldsymbol{l}_{12}, \boldsymbol{c}_1, \boldsymbol{c}_2), \qquad (26)$$

where the scaled length scale $l \equiv r/\lambda$ has been introduced. The dimensionless correlation \tilde{g} does not depend on *s* and obeys the equation

$$\begin{bmatrix} \boldsymbol{c}_{12} \cdot \frac{\partial}{\partial \boldsymbol{l}_{12}} - \Lambda(\boldsymbol{c}_1) - \Lambda(\boldsymbol{c}_2) \end{bmatrix} \tilde{g}(\boldsymbol{l}_{12}, \boldsymbol{c}_1, \boldsymbol{c}_2)$$
$$= \delta(\boldsymbol{l}_{12}) \overline{T}_0(\boldsymbol{c}_1, \boldsymbol{c}_2) \chi(\boldsymbol{c}_1) \chi(\boldsymbol{c}_2), \qquad (27)$$

where $\Lambda(c_i)$ is the linearized Boltzmann collision operator [30],

$$\Lambda(\boldsymbol{c}_i) \equiv \int d\boldsymbol{c}_3 \overline{T}_0(\boldsymbol{c}_i, \boldsymbol{c}_3) (1 + P_{i3}) \chi(\boldsymbol{c}_3) - \frac{\zeta_0}{2} \frac{\partial}{\partial \boldsymbol{c}_i} \cdot \boldsymbol{c}_i. \quad (28)$$

The operator P_{ij} interchanges the labels of particles *i* and *j* of the quantities to its right. For the two-particle two-time correlation function the scaling reads [13]

$$h_{1,1}(x_1,t;x_1',t') = n\lambda^{-d}v_0^{-d}(t)v_0^{-d}(t')\tilde{h}(l_1 - l_1',c_1,s - s';c_1')$$
(29)

and the kinetic equation is

$$\left[\frac{\partial}{\partial s} + \boldsymbol{c}_1 \cdot \frac{\partial}{\partial l_1} - \Lambda(\boldsymbol{c}_1)\right] \tilde{h}(l_1 - l_1', \boldsymbol{c}_1, s - s'; \boldsymbol{c}_1') = 0, \quad (30)$$

valid for s > s' > 0. The initial condition for this equation is

$$\widetilde{h}(\boldsymbol{l}_{1} - \boldsymbol{l}_{1}', \boldsymbol{c}_{1}, 0; \boldsymbol{c}_{1}') \equiv \widetilde{h}_{1,1}(\boldsymbol{l}_{1} - \boldsymbol{l}_{1}', \boldsymbol{c}_{1}; \boldsymbol{c}_{1}')
= \widetilde{g}(\boldsymbol{l}_{1} - \boldsymbol{l}_{1}', \boldsymbol{c}_{1}, \boldsymbol{c}_{1}') + \delta(\boldsymbol{c}_{1} - \boldsymbol{c}_{1}')\delta(\boldsymbol{l}_{1} - \boldsymbol{l}_{1}')\chi(\boldsymbol{c}_{1}).$$
(31)

An equation for this distribution follows from Eqs. (17) and (27),

$$\begin{bmatrix} \boldsymbol{c}_1 \cdot \frac{\partial}{\partial \boldsymbol{l}_1} + \boldsymbol{c}_1' \cdot \frac{\partial}{\partial \boldsymbol{l}_1'} - \Lambda(\boldsymbol{c}_1) - \Lambda(\boldsymbol{c}_1') \end{bmatrix} \tilde{h}(\boldsymbol{l}_1 - \boldsymbol{l}_1', \boldsymbol{c}_1; \boldsymbol{c}_1')$$
$$= \delta(\boldsymbol{l}_1 - \boldsymbol{l}_1') \tilde{\Gamma}(\boldsymbol{c}_1, \boldsymbol{c}_1'), \qquad (32)$$

with

$$\bar{\Gamma}(\boldsymbol{c}_{1},\boldsymbol{c}_{1}') = -\left[\Lambda(\boldsymbol{c}_{1}) + \Lambda(\boldsymbol{c}_{1}')\right]\delta(\boldsymbol{c}_{1} - \boldsymbol{c}_{1}')\chi(\boldsymbol{c}_{1}) + \bar{T}_{0}(\boldsymbol{c}_{1},\boldsymbol{c}_{1}')\chi(\boldsymbol{c}_{1})\chi(\boldsymbol{c}_{1}').$$
(33)

Equations (27) and (30) describe the correlations between fluctuations in the HCS. They become closed once the solution to Eqs. (16) and (17) is known. In Sec. III, an alternative and consistent description to that provided by these kinetic equations will be developed.

III. FLUCTUATING BOLTZMANN EQUATION AROUND THE HCS

Equation (4) is an exact consequence of the dynamical equations governing the motion of the particles. The aim of

this section is to approximate it in such a way that it gives a closed description of the effective dynamics of a dilute granular gas in the HCS. To do so, the spatial separation between the centers of colliding particles will be neglected in the operator $\overline{T}(x_1, x_2)$, and $F_2(x_1, x_2, t)$ will be approximated by an effective (Boltzmann) two-particle phase-space density at the mesoscopic level $F_2^{\mathcal{B}}(x_1, x_2, t)$. Moreover, the dimensionless time scale *s* and length scale *l* introduced in Sec. II will be used. Then, Eq. (4) becomes

$$\left(\frac{\partial}{\partial s} + \frac{\zeta_0}{2}\frac{\partial}{\partial c_1} \cdot c_1 + c_1 \cdot \frac{\partial}{\partial l_1}\right) \widetilde{F}_1(l_1, c_1, s)$$
$$= \int dc_2 \overline{T}_0(c_1, c_2) \widetilde{F}_2^B(l_1, c_1, l_1, c_2, s), \qquad (34)$$

where dimensionless phase-space densities have been defined by

$$\widetilde{F}_{1}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},s) = n^{-1} v_{0}^{d}(t) F_{1}(x_{1},t), \qquad (35)$$

$$\widetilde{F}_{2}^{B}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},\boldsymbol{l}_{2},\boldsymbol{c}_{2},s) = n^{-2} v_{0}^{2d}(t) F_{2}^{B}(x_{1},x_{2},t).$$
(36)

Comparison of the ensemble average of Eq. (34) with Eq. (17) gives the conditions

$$\langle \tilde{F}_1(\boldsymbol{l}_1, \boldsymbol{c}_1, \boldsymbol{s}) \rangle_{\mathrm{H}} = \chi(\boldsymbol{c}_1), \qquad (37)$$

$$\int d\boldsymbol{c}_{2} \overline{T}_{0}(\boldsymbol{c}_{1},\boldsymbol{c}_{2}) \langle \widetilde{F}_{2}^{B}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},\boldsymbol{l}_{1},\boldsymbol{c}_{2},\boldsymbol{s}) \rangle_{\mathrm{H}} = J_{c}[\boldsymbol{c}|\boldsymbol{\chi}]. \quad (38)$$

The subindex H in the angular brackets indicates that the ensemble average is taken over the probability distribution for the HCS.

The deviation of the microscopic density from its average value is defined by

$$\delta \widetilde{F}_1(\boldsymbol{l}_1, \boldsymbol{c}_1, \boldsymbol{s}) \equiv \widetilde{F}_1(\boldsymbol{l}_1, \boldsymbol{c}_1, \boldsymbol{s}) - \chi(\boldsymbol{c}_1).$$
(39)

An evolution equation for this quantity follows by subtracting Eqs. (34) and (17),

$$\left(\frac{\partial}{\partial s} + \frac{\zeta_0}{2} \frac{\partial}{\partial c_1} \cdot c_1 + c_1 \cdot \frac{\partial}{\partial l_1}\right) \delta \widetilde{F}_1(l_1, c_1, s)$$
$$= \int dc_2 \overline{T}_0(c_1, c_2) [\widetilde{F}_2^B(l_1, c_1, l_1, c_2, s) - \chi(c_1)\chi(c_2)].$$
(40)

The structure of this equation suggests the introduction of a cluster decomposition for \tilde{F}_2^B of the form

$$\widetilde{F}_{2}^{B}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},\boldsymbol{l}_{1},\boldsymbol{c}_{2},s) = \chi(c_{1})\chi(c_{2}) + \chi(c_{1})\delta\widetilde{F}_{1}(\boldsymbol{l}_{1},\boldsymbol{c}_{2},s) + \chi(c_{2})\delta\widetilde{F}_{1}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},s) + \widetilde{\Phi}_{2}^{B}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},\boldsymbol{c}_{2},s).$$
(41)

This equation defines the microscopic correlation density $\tilde{\Phi}_2^B(l_1, c_1, c_2, s)$. Substitution of its ensemble average in Eq. (38) yields

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$$\int d\boldsymbol{c}_2 \bar{T}_0(\boldsymbol{c}_1, \boldsymbol{c}_2) \langle \tilde{\Phi}_2^B(\boldsymbol{l}_1, \boldsymbol{c}_1, \boldsymbol{c}_2, \boldsymbol{s}) \rangle_{\rm H} = 0.$$
(42)

Moreover, use of Eq. (41) into Eq. (40) allows rewriting of the equation in the equivalent form

$$\left[\frac{\partial}{\partial s} + \boldsymbol{c}_1 \cdot \frac{\partial}{\partial \boldsymbol{l}_1} - \Lambda(\boldsymbol{c}_1)\right] \delta \widetilde{F}_1(\boldsymbol{l}_1, \boldsymbol{c}_1, s) = \widetilde{S}(\boldsymbol{l}_1, \boldsymbol{c}_1, s), \quad (43)$$

where

$$\widetilde{S}(\boldsymbol{l}_1,\boldsymbol{c}_1,\boldsymbol{s}) \equiv \int d\boldsymbol{c}_2 \overline{T}_0(\boldsymbol{c}_1,\boldsymbol{c}_2) \widetilde{\Phi}_2^B(\boldsymbol{l}_1,\boldsymbol{c}_1,\boldsymbol{c}_2,\boldsymbol{s})$$
(44)

and the operator $\Lambda(c_1)$ was defined in Eq. (28). Equation (43) can be interpreted as a fluctuating Boltzmann-Langevin equation for the one-particle distribution function [8,17,18], with the "noise term" being $\tilde{S}(l_1, c_1, s)$. Of course, this does add any new physical insight by itself in the understanding of starting equation (34). The relevance and usefulness of this representation will depend on the properties of the noise term. The first one follows directly from Eq. (42), which is equivalent to

$$\langle \widetilde{S}(\boldsymbol{l}_1, \boldsymbol{c}_1, \boldsymbol{s}) \rangle_{\mathrm{H}} = 0, \qquad (45)$$

i.e., the noise has zero average. In the following, other properties of \tilde{S} will be derived by requiring consistency with the results derived in Sec. II. Multiplication of Eq. (43) by $\delta \tilde{F}_1(l'_1, c'_1, s')$, with s' < s, followed by averaging gives

$$\left[\frac{\partial}{\partial s} + \boldsymbol{c}_{1} \cdot \frac{\partial}{\partial l} - \Lambda(\boldsymbol{c}_{1})\right] \langle \delta \widetilde{F}_{1}(\boldsymbol{l}_{1}, \boldsymbol{c}_{1}, s) \delta \widetilde{F}_{1}(\boldsymbol{l}_{1}', \boldsymbol{c}_{1}', s') \rangle_{\mathrm{H}}$$
$$= \langle \widetilde{S}(\boldsymbol{l}_{1}, \boldsymbol{c}_{1}, s) \delta \widetilde{F}_{1}(\boldsymbol{l}_{1}', \boldsymbol{c}_{1}', s') \rangle_{\mathrm{H}}.$$
(46)

From the definition of $\delta \tilde{F}_1(l_1, c_1, s)$ it is easily verified that

$$\langle \delta \widetilde{F}_1(\boldsymbol{l}_1, \boldsymbol{c}_1, \boldsymbol{s}) \, \delta \widetilde{F}_1(\boldsymbol{l}_1', \boldsymbol{c}_1', \boldsymbol{s}') \rangle_{\mathrm{H}} = n^{-1} \lambda^{-d} \widetilde{h}(\boldsymbol{l}_1 - \boldsymbol{l}_1', \boldsymbol{c}_1, \boldsymbol{s} - \boldsymbol{s}'; \boldsymbol{c}_1'),$$
(47)

where \tilde{h} is defined in Eq. (29). Therefore, consistency of Eqs. (46) and (30) implies that

$$\langle \widetilde{S}(\boldsymbol{l}_1, \boldsymbol{c}_1, \boldsymbol{s}) \, \delta \widetilde{F}_1(\boldsymbol{l}_1', \boldsymbol{c}_1', \boldsymbol{s}') \rangle_{\mathrm{H}} = 0, \qquad (48)$$

for s > s'. Since, by hypothesis, the parameters of the system are such that the HCS is stable, the long-time solution of Eq. (43) is

$$\delta \widetilde{F}_1(\boldsymbol{l}_1, \boldsymbol{c}_1, \boldsymbol{s}) = \int_{-\infty}^{s} d\tau \ e^{(s-\tau)L(\boldsymbol{l}_1, \boldsymbol{c}_1)} \widetilde{S}(\boldsymbol{l}_1, \boldsymbol{c}_1, \tau), \qquad (49)$$

where the linear operator

$$L(\boldsymbol{l}_1, \boldsymbol{c}_1) \equiv \Lambda(\boldsymbol{c}_1) - \boldsymbol{c}_1 \cdot \frac{\partial}{\partial \boldsymbol{l}_1}$$
(50)

has been introduced. Using Eq. (49), it is obtained that

$$[L(\boldsymbol{l}_{1},\boldsymbol{c}_{1}) + L(\boldsymbol{l}_{1}',\boldsymbol{c}_{1}')]\langle \delta \widetilde{F}_{1}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},s) \delta \widetilde{F}_{1}(\boldsymbol{l}_{1}',\boldsymbol{c}_{1}',s')\rangle_{\mathrm{H}}$$

$$= -\int_{-\infty}^{s} d\tau \ e^{(s-\tau)L(\boldsymbol{l}_{1},\boldsymbol{c}_{1})}\langle \widetilde{S}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},\tau)\widetilde{S}(\boldsymbol{l}_{1}',\boldsymbol{c}_{1}',s)\rangle_{\mathrm{H}}$$

$$-\int_{-\infty}^{s} d\tau \ e^{(s-\tau)L(\boldsymbol{l}_{1}',\boldsymbol{c}_{1}')}\langle \widetilde{S}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},s)\widetilde{S}(\boldsymbol{l}_{1}',\boldsymbol{c}_{1}',\tau)\rangle_{\mathrm{H}}.$$
 (51)

This equation must be compared with Eq. (32), having in mind Eq. (47). The time independence of the right-hand side of Eq. (32) prompts one to introduce the hypothesis that the noise term \tilde{S} is Markovian, and write

$$\langle \tilde{S}(l_1, c_1, s) \tilde{S}(l_1', c_1', s') \rangle_{\rm H} = H(c_1, c_1') \,\delta(l_1 - l_1') \,\delta(s - s') \,.$$
(52)

On introduction of this into Eq. (51) and comparison with Eq. (32), it follows that

$$H(\boldsymbol{c}_1, \boldsymbol{c}_1') = n^{-1} \lambda^{-d} \widetilde{\Gamma}(\boldsymbol{c}_1, \boldsymbol{c}_1'), \qquad (53)$$

with $\tilde{\Gamma}$ defined in Eq. (33).

The properties given by Eqs. (45), (48), and (52) guarantee that the description provided by Langevin equation (43) leads to the same expressions for the two-particle one-time and two-time correlation functions as the formulation in terms of reduced distributions functions reviewed in Sec. II.

IV. FLUCTUATING HYDRODYNAMIC FIELDS AND BALANCE EQUATIONS

The fluctuating number of particles' density $N(\mathbf{r},t)$, momentum density $G(\mathbf{r},t)$, and energy density $E(\mathbf{r},t)$ are defined in terms of the microscopic phase-space density as

$$N(\mathbf{r},t) = \int d\mathbf{v} F_1(x,t), \qquad (54)$$

$$\boldsymbol{G}(\boldsymbol{r},t) = \int d\boldsymbol{v}m\boldsymbol{v}F_1(\boldsymbol{x},t), \qquad (55)$$

$$E(\boldsymbol{r},t) = \int d\boldsymbol{v} \frac{mv^2}{2} F_1(x,t).$$
 (56)

Dimensionless deviations from their averages values in the HCS are given by

$$\delta\rho(\boldsymbol{l},s) \equiv \frac{\delta N(\boldsymbol{r},t)}{n} = \int d\boldsymbol{c} \,\delta \widetilde{F}_1(\boldsymbol{l},\boldsymbol{c},s),\tag{57}$$

$$\delta \boldsymbol{\omega}(\boldsymbol{l},s) \equiv \frac{\delta \boldsymbol{G}(\boldsymbol{r},t)}{mnv_0(t)} = \int d\boldsymbol{c}\boldsymbol{c}\,\delta \widetilde{F}_1(\boldsymbol{l},\boldsymbol{c},s), \qquad (58)$$

$$\delta \boldsymbol{\epsilon}(\boldsymbol{l},s) \equiv \frac{2\,\delta \boldsymbol{E}(\boldsymbol{r},t)}{dnT(t)} = \frac{2}{d} \int d\boldsymbol{c} c^2 \delta \tilde{F}_1(\boldsymbol{l},\boldsymbol{c},s). \tag{59}$$

The quantity $\delta \omega(l,s)$ is the dimensionless velocity field. Balance equations for these fluctuating fields follow by taking

velocity moments in Langevin-Boltzmann equation (43) and using the properties of the noise \tilde{S} . Some details of the calculations are given in Appendix A. The resulting equations read

$$\frac{\partial}{\partial s}\delta\rho(l,s) + \frac{\partial}{\partial l}\cdot\delta\omega(l,s) = 0, \qquad (60)$$

$$\left(\frac{\partial}{\partial s} - \frac{\zeta_0}{2}\right) \delta \boldsymbol{\omega}(\boldsymbol{l}, \boldsymbol{s}) + \frac{\partial}{\partial \boldsymbol{l}} \cdot \delta \boldsymbol{\Pi}(\boldsymbol{l}, \boldsymbol{s}) = 0, \quad (61)$$

$$\left(\frac{\partial}{\partial s} - \zeta_0\right) \delta \epsilon(\boldsymbol{l}, \boldsymbol{s}) + \frac{d+2}{d} \frac{\partial}{\partial \boldsymbol{l}} \cdot \delta \boldsymbol{\omega}(\boldsymbol{l}, \boldsymbol{s}) + \delta \zeta_0(\boldsymbol{l}, \boldsymbol{s}) + \frac{2}{d} \frac{\partial}{\partial \boldsymbol{l}} \cdot \delta \boldsymbol{\phi}(\boldsymbol{l}, \boldsymbol{s}) = \widetilde{S}_{\epsilon}(\boldsymbol{l}, \boldsymbol{s}).$$
(62)

In the above equations, $\delta \Pi(l,s)$ and $\delta \phi(l,s)$ are the fluctuating pressure tensor and heat flux, respectively. Their definitions in terms of the fluctuating one-particle distribution function are

$$\delta \mathbf{\Pi}(\boldsymbol{l},\boldsymbol{s}) = \frac{\delta \boldsymbol{\epsilon}(\boldsymbol{l},\boldsymbol{s})}{2} \mathbf{l} + \int d\boldsymbol{c} \boldsymbol{\Delta}(\boldsymbol{c}) \,\delta \widetilde{F}_1(\boldsymbol{l},\boldsymbol{c},\boldsymbol{s}), \tag{63}$$

$$\delta \boldsymbol{\phi}(\boldsymbol{l},s) = \int d\boldsymbol{c} \boldsymbol{\Sigma}(\boldsymbol{c}) \,\delta \widetilde{F}_1(\boldsymbol{l},\boldsymbol{c},s), \qquad (64)$$

where \mathbf{I} is the unit tensor of dimension d, and

$$\Delta(c) \equiv cc - \frac{c^2}{d}\mathbf{I},\tag{65}$$

$$\Sigma(\mathbf{c}) \equiv \left(c^2 - \frac{d+2}{2}\right)\mathbf{c}.$$
 (66)

The term $\delta \zeta_0(l,s)$ represents the fluctuations of the cooling rate about its average value in the HCS. Its formal expression is

$$\delta\zeta_{0}(\boldsymbol{l},s) = \frac{(1-\alpha^{2})\pi^{(d-1)/2}}{\Gamma\left(\frac{d+3}{2}\right)d} \int d\boldsymbol{c}_{1} \int d\boldsymbol{c}_{2}c_{12}^{3}\chi(c_{1})\,\delta\widetilde{F}_{1}(\boldsymbol{l},\boldsymbol{c}_{2},s).$$
(67)

Finally, $\tilde{S}_{\epsilon}(l,s)$ is a fluctuating force term with the properties

$$\langle \widetilde{S}_{\epsilon}(\boldsymbol{l},s) \rangle_{\mathrm{H}} = 0$$
 (68)

and

$$\langle \tilde{S}_{\epsilon}(\boldsymbol{l},s)\tilde{S}_{\epsilon}(\boldsymbol{l}',s')\rangle_{\mathrm{H}} = n^{-1}\lambda^{-d}\delta(s-s')\delta(\boldsymbol{l}-\boldsymbol{l}')$$

$$\times \left[\int d\boldsymbol{c}_{1}\int d\boldsymbol{c}_{2}\chi(c_{1})\chi(c_{2})\Phi(\boldsymbol{c}_{1},\boldsymbol{c}_{2})\right]$$

$$-\frac{8}{d^{2}}\zeta_{0}\int d\boldsymbol{c}c^{4}\chi(c), \qquad (69)$$

with $\Phi(c_1, c_2)$ given by Eq. (A16). This noise term is intrin-

sic to the inelasticity of collisions and has no analog in normal fluids. Of course, in the elastic limit $\alpha \rightarrow 1$, $\chi(c)$ becomes a Gaussian and the fluctuating force \tilde{S}_{ϵ} is seen to vanish in agreement with the well-known results for hydrodynamic fluctuations in molecular fluids [19]. The other main difference between Eq. (62) and the one for molecular gases is the presence of the two terms involving the cooling rate ζ_0 and its fluctuations $\delta\zeta_0$. The presence of these terms is directly associated with existence of the cooling term in the macroscopic equation for the average energy [3,31,32].

V. LANGEVIN EQUATION FOR THE VELOCITY FIELD

Equations (60)–(62) do not provide a closed description of the hydrodynamic fluctuations of a granular gas in the HCS until $\delta \Pi$, $\delta \phi$, and $\delta \zeta_0$ are expressed in terms of the fluctuating hydrodynamic fields. This turns out to be not a simple task, and attention will be restricted in the following to the equation of the velocity field $\delta \omega(l, s)$ [Eq. (61)].

Given two functions f(c) and g(c), their scalar product is defined as

$$\langle f|g\rangle \equiv \int d\boldsymbol{c} \chi^{-1}(c) f^{+}(\boldsymbol{c}) g(\boldsymbol{c}), \qquad (70)$$

where $f^+(c)$ is the complex conjugate of f(c). Next, a projection operator \mathcal{P} is introduced by

$$\mathcal{P}f(\boldsymbol{c}) \equiv \sum_{\beta=1}^{d+2} \xi_{\beta}(\boldsymbol{c}) \langle \bar{\xi}_{\beta} | f \rangle.$$
(71)

Here, the functions $\xi_{\beta}(c)$, with $\beta=1, \ldots, d+2$, are the eigenfunctions of the linear Boltzmann operator $\Lambda(c)$ defined in Eq. (28), corresponding to the hydrodynamic part of its spectrum. Therefore, they are solutions of the equation

$$\Lambda(\boldsymbol{c})\xi_{\beta}(\boldsymbol{c}) = \lambda_{\beta}\xi_{\beta}(\boldsymbol{c}). \tag{72}$$

Their expressions are [30,23]

$$\xi_1(\mathbf{c}) = \chi(\mathbf{c}) + \frac{\partial}{\partial \mathbf{c}} \cdot [\mathbf{c}\chi(\mathbf{c})], \quad \xi_2(\mathbf{c}) = -\frac{\partial\chi(\mathbf{c})}{\partial \mathbf{c}},$$

$$\xi_3(\boldsymbol{c}) = -\frac{\partial}{\partial \boldsymbol{c}} \cdot [\boldsymbol{c}\chi(\boldsymbol{c})].$$
(73)

The associated eigenvalues are found to be

$$\lambda_1 = 0, \quad \lambda_2 = \frac{\zeta_0}{2}, \quad \lambda_3 = -\frac{\zeta_0}{2},$$
 (74)

the eigenvalue λ_2 being *d*-fold degenerate. Finally the functions $\overline{\xi}_{\beta}(c)$ are

$$\overline{\xi}_1(\boldsymbol{c}) = \chi(c), \quad \overline{\xi}_2(\boldsymbol{c}) = \boldsymbol{c}\chi(c), \quad \overline{\xi}_3(\boldsymbol{c}) = \left(\frac{c^2}{d} + \frac{1}{2}\right)\chi(c).$$
(75)

The sets of functions $\{\xi_{\beta}(c)\}\$ and $\{\overline{\xi}_{\beta}(c)\}\$ are seen to have the biorthogonality property

$$\langle \overline{\xi}_{\beta} | \xi_{\beta'} \rangle = \delta_{\beta,\beta'}, \tag{76}$$

with β , $\beta' = 1, 2, ..., d+2$. This guarantees that \mathcal{P} as defined by Eq. (71) is really a projector operator; i.e., it verifies $\mathcal{P}^2 = \mathcal{P}$. It projects any function of *c* onto the subspace spanned by the hydrodynamic eigenfunctions of Λ .

In the following, it will be more convenient to work in the Fourier representation. The Fourier transform of $\delta \tilde{F}_1(l,c,s)$ is

$$\delta \widetilde{F}_1(\boldsymbol{k},\boldsymbol{c},s) = \int d\boldsymbol{l} e^{-i\boldsymbol{k}\cdot\boldsymbol{l}} \delta \widetilde{F}_1(\boldsymbol{l},\boldsymbol{c},s).$$
(77)

By means of \mathcal{P} , $\delta \tilde{F}_1(\mathbf{k}, \mathbf{c}, s)$ can be decomposed into its hydrodynamic and nonhydrodynamic parts,

$$\delta \widetilde{F}_1(\boldsymbol{k},\boldsymbol{c},s) = \mathcal{P} \delta \widetilde{F}_1(\boldsymbol{k},\boldsymbol{c},s) + \mathcal{P}_{\perp} \delta \widetilde{F}_1(\boldsymbol{k},\boldsymbol{c},s), \qquad (78)$$

where $\mathcal{P}_{\perp} \equiv 1 - \mathcal{P}$. The Fourier representation of the balance equation for the velocity fluctuations [Eq. (61)] is

$$\left(\frac{\partial}{\partial s} - \frac{\zeta_0}{2}\right) \delta \boldsymbol{\omega}(\boldsymbol{k}, s) + i\boldsymbol{k} \cdot \delta \boldsymbol{\Pi}(\boldsymbol{k}, s) = 0, \qquad (79)$$

$$\delta \Pi(\boldsymbol{k},s) = \frac{\delta \boldsymbol{\epsilon}(\boldsymbol{k},s)}{2} \mathbf{I} + \int d\boldsymbol{c} \boldsymbol{\Delta}(\boldsymbol{c}) \, \delta \widetilde{F}_1(\boldsymbol{k},\boldsymbol{c},s), \qquad (80)$$

where $\Delta(c)$ is defined in Eq. (65). Getting an explicit expression for $\delta \Pi(k,s)$ in terms of the fluctuating hydrodynamic fields is the next issue to be addressed. By direct evaluation, it is easily verified that

$$\int d\boldsymbol{c} \boldsymbol{\Delta}(\boldsymbol{c}) \boldsymbol{\xi}_{\boldsymbol{\beta}}(\boldsymbol{c}) = 0, \qquad (81)$$

with $\beta = 1, \dots, d+2$. Hence Eq. (80) is equivalent to

$$\delta \mathbf{\Pi}(\boldsymbol{k},s) = \frac{\delta \boldsymbol{\epsilon}(\boldsymbol{k},s)}{2} \mathbf{I} + \int d\boldsymbol{c} \boldsymbol{\Delta}(\boldsymbol{c}) \mathcal{P}_{\perp} \delta \widetilde{F}_{1}(\boldsymbol{k},\boldsymbol{c},s). \quad (82)$$

To compute $\mathcal{P}_{\perp}\tilde{F}_1(\boldsymbol{k},\boldsymbol{c},s)$, the operator \mathcal{P}_{\perp} is applied to both sides of the Fourier transform of Boltzmann-Langevin equation (43),

$$\begin{cases} \frac{\partial}{\partial s} - \mathcal{P}_{\perp}[\Lambda(\boldsymbol{c}) - i\boldsymbol{k} \cdot \boldsymbol{c}] \end{cases} \mathcal{P}_{\perp} \delta \widetilde{F}_{1}(\boldsymbol{k}, \boldsymbol{c}, s) \\ = - \mathcal{P}_{\perp} i\boldsymbol{k} \cdot \boldsymbol{c} \mathcal{P} \delta \widetilde{F}_{1}(\boldsymbol{k}, \boldsymbol{c}, s) + \mathcal{P}_{\perp} \widetilde{S}(\boldsymbol{k}, \boldsymbol{c}, s), \qquad (83) \end{cases}$$

where use has been made of the property $\mathcal{P}_{\perp}\Lambda\mathcal{P}=0$, which is a consequence of the fact that \mathcal{P} projects over a subspace generated by eigenfunctions of Λ . The solution of the above equation can be formally written as

$$\mathcal{P}_{\perp} \delta \overline{F}_{1}(\boldsymbol{k}, \boldsymbol{c}, \boldsymbol{s}) = \mathcal{U}(\boldsymbol{k}, \boldsymbol{c}, \boldsymbol{s}) \mathcal{P}_{\perp} \delta \overline{F}_{1}(\boldsymbol{k}, \boldsymbol{c}, \boldsymbol{0}) + \int_{0}^{s} ds' \mathcal{U}(\boldsymbol{k}, \boldsymbol{c}, \boldsymbol{s}') \mathcal{P}_{\perp}[-i\boldsymbol{k} \cdot \boldsymbol{c} \times \mathcal{P} \delta \widetilde{F}_{1}(\boldsymbol{k}, \boldsymbol{c}, \boldsymbol{s} - \boldsymbol{s}') + \widetilde{S}(\boldsymbol{k}, \boldsymbol{c}, \boldsymbol{s} - \boldsymbol{s}')],$$
(84)

with

$$\mathcal{U}(\boldsymbol{k},\boldsymbol{c},s) \equiv \exp[s\mathcal{P}_{\perp}L(\boldsymbol{k},c)\mathcal{P}_{\perp}], \qquad (85)$$

$$L(\mathbf{k},\mathbf{c}) \equiv \Lambda(\mathbf{c}) - i\mathbf{k} \cdot \mathbf{c}.$$
(86)

Taking again into account that the HCS is assumed to be stable for the system considered, the first term on the right-hand side of Eq. (84) can be neglected for large enough times s. Moreover, to derive hydrodynamic equations valid to Navier-Stokes order, only the first order in k of the pressure tensor is needed. To this order,

$$\int_{0}^{s} ds' \mathcal{U}(\boldsymbol{k},\boldsymbol{c},s') \mathcal{P}_{\perp}(-i\boldsymbol{k}\cdot\boldsymbol{c}) \mathcal{P}\delta \widetilde{F}_{1}(\boldsymbol{k},\boldsymbol{c},s-s')$$

$$\rightarrow \int_{0}^{s} ds' e^{s' \mathcal{P}_{\perp}\Lambda(\boldsymbol{c})\mathcal{P}_{\perp}} \mathcal{P}_{\perp}(-i\boldsymbol{k}\cdot\boldsymbol{c}) \mathcal{P}\delta \widetilde{F}_{1}(\boldsymbol{k},\boldsymbol{c},s-s')$$

$$= \int_{0}^{s} ds' \mathcal{P}_{\perp} e^{s'\Lambda(\boldsymbol{c})}(-i\boldsymbol{k}\cdot\boldsymbol{c}) \mathcal{P}\delta \widetilde{F}_{1}(\boldsymbol{k},\boldsymbol{c},s-s'). \quad (87)$$

Then, for large s Eq. (84) reduces to

$$\mathcal{P}_{\perp}\delta\widetilde{F}_{1}(\boldsymbol{k},\boldsymbol{c},s) = \int_{0}^{s} ds' \mathcal{P}_{\perp}e^{s'\Lambda(\boldsymbol{c})}(-i\boldsymbol{k}\cdot\boldsymbol{c})\mathcal{P}\delta\widetilde{F}_{1}(\boldsymbol{k},\boldsymbol{c},s-s') + \int_{0}^{s} ds'\mathcal{U}(\boldsymbol{k},\boldsymbol{c},s')\mathcal{P}_{\perp}\widetilde{S}(\boldsymbol{k},\boldsymbol{c},s-s'), \quad (88)$$

and substitution of this into Eq. (82) yields

$$\delta \mathbf{\Pi}(\boldsymbol{k}, s) = \frac{\delta \boldsymbol{\epsilon}(\boldsymbol{k}, s)}{2} \mathbf{I} + \delta_1 \mathbf{\Pi}(\boldsymbol{k}, s) + \mathbf{R}(\boldsymbol{k}, s), \qquad (89)$$

where

$$\delta_{1} \mathbf{\Pi}(\boldsymbol{k}, \boldsymbol{s}) = \int_{0}^{s} d\boldsymbol{s}' \int d\boldsymbol{c} \boldsymbol{\Delta}(\boldsymbol{c}) e^{\boldsymbol{s}' \boldsymbol{\Lambda}(\boldsymbol{c})} (-i\boldsymbol{k} \cdot \boldsymbol{c}) \mathcal{P} \delta \widetilde{F}_{1}(\boldsymbol{k}, \boldsymbol{c}, \boldsymbol{s} - \boldsymbol{s}'),$$
(90)

and

$$\mathbf{R}(\boldsymbol{k},s) = \int_{0}^{s} ds' \int d\boldsymbol{c} \boldsymbol{\Delta}(\boldsymbol{c}) \mathcal{U}(\boldsymbol{k},\boldsymbol{c},s') \mathcal{P}_{\perp} \widetilde{S}(\boldsymbol{k},\boldsymbol{c},s-s').$$
(91)

Upon writing Eq. (90), Eq. (81) has been employed to remove the operator \mathcal{P}_{\perp} appearing in the first term on the right-hand side of Eq. (88). Because of the isotropy of the operator $\Lambda(c)$, only the projection onto $\xi_2(c)$ gives a nonvanishing contribution to the above expression for $\delta_1 \Pi(k,s)$, which can be simplified to

$$\delta_{1} \mathbf{\Pi}(\mathbf{k}, s) = \int_{0}^{s} ds' \int d\mathbf{c} \Delta(\mathbf{c}) e^{s' \Lambda(\mathbf{c})} (-i\mathbf{k} \cdot \mathbf{c})$$

$$\times \boldsymbol{\xi}_{2}(\mathbf{c}) \cdot \langle \boldsymbol{\xi}_{2}(\mathbf{c}) | \delta \widetilde{F}_{1}(\mathbf{k}, \mathbf{c}, s - s') \rangle$$

$$= \int_{0}^{s} ds' \int d\mathbf{c} \Delta(\mathbf{c}) e^{s' \Lambda(\mathbf{c})} (-i\mathbf{k} \cdot \mathbf{c})$$

$$\times \boldsymbol{\xi}_{2}(\mathbf{c}) \cdot \delta \boldsymbol{\omega}(\mathbf{k}, s - s')$$

$$\approx \int_{0}^{s} ds' \int d\mathbf{c} \Delta(\mathbf{c}) e^{s' \Lambda(\mathbf{c})} (-i\mathbf{k} \cdot \mathbf{c})$$

$$\times e^{-s' \boldsymbol{\xi}_{0}/2} \boldsymbol{\xi}_{2}(\mathbf{c}) \cdot \delta \boldsymbol{\omega}(\mathbf{k}, s). \qquad (92)$$

In the previous transformations, the definition in Eq. (58) has been used, and it has been taken into account that to lowest order in k,

$$\delta\omega(\boldsymbol{k}, \boldsymbol{s} - \boldsymbol{s}') = e^{-\boldsymbol{s}'\zeta_0/2}\delta\omega(\boldsymbol{k}, \boldsymbol{s}), \qquad (93)$$

according to the balance equation for the fluctuating velocity field [Eq. (61)]. Using again the symmetry of $\Lambda(c)$, it is obtained that

$$\delta_{1}\Pi_{ij}(\boldsymbol{k},s) = -i\,\widetilde{\eta}(s) \left[k_{i}\delta\omega_{j}(\boldsymbol{k},s) + k_{j}\delta\omega_{i}(\boldsymbol{k},s) - \frac{2}{d}\delta_{ij}\boldsymbol{k}\cdot\delta\widetilde{\boldsymbol{\omega}}(\boldsymbol{k},s) \right].$$
(94)

This is the same as the Navier-Stokes expression for the pressure tensor with the only difference that the average macroscopic velocity field is substituted by the fluctuating one. It involves the (time-dependent) dimensionless shear viscosity $\tilde{\eta}(s)$ defined by

$$\tilde{\eta}(s) = \frac{1}{d^2 + d - 2} \sum_{i} \sum_{j} \int_{0}^{s} ds' \int d\mathbf{c} \Delta_{ij}(\mathbf{c}) e^{s'(\Lambda - \zeta_{0}/2)} \xi_{2,i}(\mathbf{c}) c_{j}.$$
(95)

This expression is equivalent to the one obtained from the nonlinear Boltzmann equation for inelastic hard spheres or disks by the Chapman-Enskog method [31,32] and also to the Green-Kubo formulas derived in Ref. [33]. Let us remark that the results obtained here apply in the limit of large s. It is in this limit when hydrodynamics in the usual sense is expected to apply. If this is true, the shear viscosity in Eq. (95) will become independent of s. Although there is no a mathematical proof of this "aging to hydrodynamics" for granular gases up to now, numerical evaluation of the righthand side of Eq. (95) by using the direct Monte Carlo simulation method has shown the existence of such a limit value [34]. Moreover, the simulation results for the shear viscosity $\tilde{\eta}$ are in good agreement with the expression obtained by evaluating the Chapman-Enskog result in the first Sonine approximation [31,32],

$$\widetilde{\nu}(\alpha) = \frac{\pi^{(d-1)/2}}{2\sqrt{2}d(d+2)\Gamma(d/2)} (3 - 3\alpha + 2d)(1+\alpha) \left[1 - \frac{a_2(\alpha)}{32}\right].$$
(97)

When Eq. (94) is substituted into Eq. (89) and the resulting expression is used into Eq. (79), a Langevin-type equation is obtained for the velocity field,

$$\left(\frac{\partial}{\partial s} - \frac{\zeta_0}{2}\right) \delta \boldsymbol{\omega}(\boldsymbol{k}, s) + \frac{i}{2} \delta \boldsymbol{\epsilon}(\boldsymbol{k}, s) \boldsymbol{k} + \tilde{\boldsymbol{\eta}} \left[k^2 \delta \boldsymbol{\omega}(\boldsymbol{k}, s) + \frac{d-2}{d} \boldsymbol{k} \cdot \delta \boldsymbol{\omega}(\boldsymbol{k}, s) \boldsymbol{k} \right] = \boldsymbol{W}(\boldsymbol{k}, s),$$
(98)

with the noise term given by

$$W(k,s) \equiv -ik \cdot \mathbf{R}(k,s), \qquad (99)$$

where the term $\mathbf{R}(\mathbf{k}, s)$ is defined in Eq. (91). It follows from Eq. (45) that

$$\left\langle \boldsymbol{W}(\boldsymbol{k},s)\right\rangle_{\rm H} = 0. \tag{100}$$

A formal expression for the correlation function of W is obtained directly by using Eq. (52). Its conversion into an explicit one, valid to Navier-Stokes order and, therefore, consistent with the left-hand side of Eq. (98), will be carried out in Sec. VI for the particular case of the transverse component of the velocity field.

VI. NOISE TERM IN THE EQUATION FOR THE TRANSVERSE VELOCITY FIELD

The transverse part of the fluctuating velocity field, $\delta \omega_{\perp}(k,s)$, is defined by

$$\delta \boldsymbol{\omega}_{\perp}(\boldsymbol{k},s) \equiv \delta \boldsymbol{\omega}(\boldsymbol{k},s) - \delta \boldsymbol{\omega}(\boldsymbol{k},s) \cdot \frac{\boldsymbol{k}}{k^2} \boldsymbol{k}.$$
 (101)

Its evolution equation can be written down directly from Eq. (98),

$$\left(\frac{\partial}{\partial s} - \frac{\zeta_0}{2} + \tilde{\eta}k^2\right) \delta \boldsymbol{\omega}_{\perp}(\boldsymbol{k}, s) = \boldsymbol{W}_{\perp}(\boldsymbol{k}, s), \qquad (102)$$

where

$$\boldsymbol{W}_{\perp}(\boldsymbol{k},s) = -i\boldsymbol{k}\left(\boldsymbol{\mathsf{I}} - \frac{\boldsymbol{k}\boldsymbol{k}}{\boldsymbol{k}^2}\right): \boldsymbol{\mathsf{R}}(\boldsymbol{k},s). \tag{103}$$

Substitution of the expression of **R** given in Eq. (91) yields

$$\boldsymbol{W}_{\perp}(\boldsymbol{k},s) = -i \int_{0}^{s} ds' \int d\boldsymbol{c} \, \boldsymbol{k} \cdot \boldsymbol{c} \left(\boldsymbol{c} - \frac{\boldsymbol{c} \cdot \boldsymbol{k}}{k^{2}} \boldsymbol{k} \right)$$
$$\times \mathcal{U}(\boldsymbol{k},\boldsymbol{c},s') \mathcal{P}_{\perp} \widetilde{S}(\boldsymbol{k},\boldsymbol{c},s-s'). \tag{104}$$

By using this expression, it is shown in Appendix B that for two components, $W_{\perp,i}(\mathbf{k},s)$ and $W_{\perp,j}(\mathbf{k},s)$, of the noise of the transverse velocity field to lowest order in k

$$\langle W_{\perp,i}(\boldsymbol{k},s)W_{\perp,j}(\boldsymbol{k}',s')\rangle_{\mathrm{H}} = \delta_{i,j}\delta_{\boldsymbol{k},-\boldsymbol{k}'}\frac{\widetilde{V}^2}{N}k^2G(|s-s'|),$$
(105)

for $s > s' \ge 1$. Here \tilde{V} is the volume of the system in the length scale *l*, i.e., $\tilde{V} \equiv N/n\lambda^d$, and

$$G(|s|) = \int d\boldsymbol{c} \int d\boldsymbol{c}' \Delta_{xy}(\boldsymbol{c}) \Delta_{xy}(\boldsymbol{c}') \widetilde{\psi}_{\text{HCS}}(\boldsymbol{c}, s; \boldsymbol{c}'), \quad (106)$$

with

$$\widetilde{\psi}_{\text{HCS}}(\boldsymbol{c},s;\boldsymbol{c}') = \int dl \widetilde{h}(\boldsymbol{l},\boldsymbol{c},s;\boldsymbol{c}').$$
(107)

The distribution $\tilde{h}(l, c, s; c')$ is defined in Eq. (29). Then, by integration of Eq. (30) it follows that $\tilde{\psi}_{\text{HCS}}(c, s; c')$ obeys the equation

$$\left[\frac{\partial}{\partial s} - \Lambda(\boldsymbol{c})\right] \widetilde{\psi}_{\text{HCS}}(\boldsymbol{c}, s; \boldsymbol{c}') = 0, \qquad (108)$$

valid for s > 0. In principle, this equation must be solved with the initial condition $\tilde{\psi}_{HCS}(c;c')$, given by

$$\widetilde{\psi}_{\text{HCS}}(\boldsymbol{c};\boldsymbol{c}') = \int d\boldsymbol{l} \ \widetilde{g}(\boldsymbol{l},\boldsymbol{c},\boldsymbol{c}') + \delta(\boldsymbol{c}-\boldsymbol{c}')\chi(\boldsymbol{c}), \quad (109)$$

obtained by integration of Eq. (31). Nevertheless, it was shown in Ref. [34] by particle simulation that contributions from the correlations in the HCS of dilute granular gases are negligible, at least for not too strong inelasticity, $\alpha \ge 0.5$. Therefore, the term involving \tilde{g} in Eq. (109) has been neglected in the results reported below.

The solution of Eq. (102) in the limit of large s can be written as

$$\delta\omega_{\perp,i}(\boldsymbol{k},s) = \int_{-\infty}^{s} ds_1 e^{\lambda_{\perp}(k)(s-s_1)} W_{\perp,i}(\boldsymbol{k},s_1), \qquad (110)$$

where

$$\lambda_{\perp}(k) \equiv \frac{\zeta_0}{2} - \tilde{\eta}k^2. \tag{111}$$

Next, using Eq. (105) it is obtained that

$$\langle \delta \omega_{\perp,i}(\boldsymbol{k},s) \, \delta \omega_{\perp,i}(\boldsymbol{k}',s) \rangle_{\mathrm{H}} = -\frac{\tilde{V}^2}{2N} k^2 \delta_{\boldsymbol{k},-\boldsymbol{k}'} \frac{\tilde{\eta}'}{\lambda_{\perp}(k)}, \quad (112)$$

with the coefficient $\tilde{\eta}'$ defined as

$$\widetilde{\eta}' = 2 \int_0^\infty ds G(|s|) e^{\zeta_0/2}.$$
(113)

This coefficient can be computed in the first Sonine approximation. Some details of the calculations are given in Appendix C. The result reads



FIG. 1. (Color online) The shear viscosity $\tilde{\eta}$ and the new coefficient $\tilde{\eta}'$ determining the transverse velocity fluctuations in granular gases in the HCS. The solid and dashed lines are the theoretical predictions for $\tilde{\eta}$ and $\tilde{\eta}'$ given by Eqs. (96) and (114), respectively, normalized by the elastic value of the shear viscosity, $\tilde{\eta}_e$. The circles $(\tilde{\eta}/\tilde{\eta}_e)$ and squares $(\tilde{\eta}'/\tilde{\eta}_e)$ are molecular-dynamics simulation results. The dotted line is the result obtained in the white-noise approximation [Eq. (119)].

$$\widetilde{\eta}' = \frac{1 + a_2(\alpha)}{8\widetilde{\nu}(\alpha) - 3\zeta_0(\alpha)},\tag{114}$$

where $\tilde{\nu}(\alpha)$ was defined in Eq. (97).

The two-time self-correlation function of the transverse velocity field can also be computed from Eqs. (105) and (110). Again, details of the calculations are given in Appendix C. For s-s'>0, it is obtained that

$$\langle \delta \omega_{\perp,i}(\boldsymbol{k},s) \, \delta \omega_{\perp,j}(\boldsymbol{k}',s') \rangle_{\mathrm{H}} \\ \simeq -\frac{\tilde{V}^2}{2N} \delta_{i,j} \delta_{\boldsymbol{k},-\boldsymbol{k}'} \frac{(\tilde{\eta}'+\tilde{\eta}_{\mathrm{l}})k^2}{\lambda_{\perp}(k)} e^{\lambda_{\perp}(k)(s-s')}, \quad (115)$$

where

$$\widetilde{\eta}_1 = \int_0^\infty ds G(|s|) [e^{-\lambda_\perp(k)s} - e^{\lambda_\perp(k)s}].$$
(116)

It is worth to stress that this result only holds after a transient interval s-s', and for this reason it does not reduce to Eq. (112) for s=s'. On the other hand, the coefficient $\tilde{\eta}_1$ can be expected to be small, since the second factor in the integrand remains small for the decay of the first one.

To check the theory developed along the paper, Eqs. (115) and (112) have been used to measure the shear viscosity $\tilde{\eta}$ and $\tilde{\eta}'$ by means of molecular-dynamics simulation of dilute granular gases. The results turn out to be in qualitative agreement with the theory, in the sense that the scaled one-time correlation function is independent of the variable *s*, and the two-time correlation function only depends on the difference s-s' and decays exponentially after a short transient period. More details of the simulation method employed and the analysis of the data are given in [35]. The comparison between the values of $\tilde{\eta}$ and $\tilde{\eta}'$, obtained from the simulation results and the theoretical predictions given by Eqs. (96) and (114), respectively, is shown in Fig. 1. Of course, all the simulation data have been obtained with low-density systems in the HCS. It can be observed that the agreement is very good over a quite wide range of values of the restitution coefficient α , then providing a very strong support for both the theory developed here and the specific algorithm used to compute the coefficients.

VII. SUMMARY AND DISCUSSION

The primary objective here has been to investigate hydrodynamic fluctuations in the homogeneous cooling state of dilute granular gases, modeled as an ensemble of inelastic hard particles. From this point of view, fluctuating balance equations (60)-(62), together with fluctuating Boltzmann equation (43), provide a solid starting point. The remaining task is to construct explicit expressions for the fluctuating flux and the cooling rate in terms of the (fluctuating) hydrodynamic fields by using, for instance, the Chapman-Enskog procedure. This part of the analysis turns out to be technically rather complex, and has been limited here to the particular case of the transverse flow field.

The structure of the fluctuating balance equations is similar to those for elastic molecular systems with two main differences, both in the equation for the energy [Eq. (62)]. The equation contains a term, $\delta \zeta_0$, associated to the fluctuations of the cooling rate and also an intrinsic noise term \tilde{S}_{ϵ} . Both give contributions even to zeroth order in the gradients and therefore play a relevant role in describing the fluctuations of global properties of the system [13].

With regards to the fluctuating transverse velocity field, it has been found that it can be described by a Langevin equation, but it exhibits two crucial differences as compared with the elastic case. The form of the fluctuation-dissipation relation changes both qualitatively and quantitatively. The second moment of the noise term is not determined by the shear viscosity. In addition, the noise is not white; i.e., it presents memory effects. Both aspects have been confirmed by the results obtained by molecular-dynamics simulations.

It could be wondered at what extension the memory effects mentioned above are relevant. Suppose the hypothesis of a white noise would have made and Eq. (105) were substituted by

$$\langle W_{\perp,i}(\boldsymbol{k},s)W_{\perp,j}(\boldsymbol{k}',s')\rangle_{\mathrm{H}} = \delta_{i,j}\delta_{\boldsymbol{k},-\boldsymbol{k}'}\frac{\widetilde{V}^2}{N}k^2\widetilde{\eta}''\delta(s-s'),$$
(117)

with

$$\widetilde{\eta}'' = 2 \int_0^\infty ds G(|s|). \tag{118}$$

By using the same method as outlined in Appendix C it is found that

$$\tilde{\eta}'' = \frac{1 + a_2(\alpha)}{8\,\tilde{\nu}(\alpha) - 2\,\zeta_0(\alpha)}.\tag{119}$$

This coefficient is also plotted in Fig. 1, and it is seen to clearly underestimate the amplitude of the second moment of

the noise measured in the simulation. It is worth to stress that the violation of the elastic fluctuation-dissipation relations is already significant for values of the restitution coefficient α on the order of 0.95.

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APPENDIX A: DERIVATION OF THE FLUCTUATING HYDRODYNAMIC EQUATIONS

In this appendix the derivation of Eqs. (60)–(62) will be outlined. The calculations are facilitated by using that for arbitrary functions $f(c_1, c_2)$ and $g(c_1, c_2)$,

$$\int d\mathbf{c}_{1} \int d\mathbf{c}_{2} f(\mathbf{c}_{1}, \mathbf{c}_{2}) \overline{T}_{0}(\mathbf{c}_{1}, \mathbf{c}_{2}) g(\mathbf{c}_{1}, \mathbf{c}_{2})$$
$$= \int d\mathbf{c}_{1} \int d\mathbf{c}_{2} g(\mathbf{c}_{1}, \mathbf{c}_{2}) T_{0}(\mathbf{c}_{1}, \mathbf{c}_{2}) f(\mathbf{c}_{1}, \mathbf{c}_{2}), \quad (A1)$$

where

$$T_0(\boldsymbol{c}_1, \boldsymbol{c}_2) = \int d\hat{\boldsymbol{\sigma}} \Theta(\boldsymbol{c}_{12} \cdot \hat{\boldsymbol{\sigma}}) \boldsymbol{c}_{12} \cdot \hat{\boldsymbol{\sigma}} [b_{\boldsymbol{\sigma}}(\boldsymbol{c}_1, \boldsymbol{c}_2) - 1].$$
(A2)

The operator b_{σ} is the inverse of b_{σ}^{-1} defined in Eq. (6). From Eqs. (57) and (43),

$$\frac{\partial}{\partial s} \delta \rho(\boldsymbol{l}, s) = \int d\boldsymbol{c} \frac{\partial}{\partial s} \delta \widetilde{F}_{1}(\boldsymbol{l}, \boldsymbol{c}, s)$$
$$= -\int d\boldsymbol{c} \boldsymbol{c} \cdot \frac{\partial}{\partial l} \delta \widetilde{F}_{1}(\boldsymbol{l}, \boldsymbol{c}, s)$$
$$+ \int d\boldsymbol{c} \Lambda(\boldsymbol{c}) \delta \widetilde{F}_{1}(\boldsymbol{l}, \boldsymbol{c}, s) + \widetilde{S}_{\rho}(\boldsymbol{l}, s), \quad (A3)$$

with

$$\widetilde{S}_{\rho}(\boldsymbol{l},s) \equiv \int d\boldsymbol{c} \widetilde{S}(\boldsymbol{l},\boldsymbol{c},s).$$
(A4)

By using the definition given in Eq. (28) and property (A1) it is easy to see that

$$\int d\boldsymbol{c} \Lambda(\boldsymbol{c}) \,\delta \widetilde{F}_1(\boldsymbol{l}, \boldsymbol{c}, \boldsymbol{s}) = 0. \tag{A5}$$

Moreover,

$$\begin{split} \langle \widetilde{S}_{\rho}(\boldsymbol{l},s)\widetilde{S}_{\rho}(\boldsymbol{l}',s')\rangle_{\mathrm{H}} &= \int d\boldsymbol{c}_{1} \int d\boldsymbol{c}_{2} \langle \widetilde{S}(\boldsymbol{l},\boldsymbol{c}_{1},s)\widetilde{S}(\boldsymbol{l}',\boldsymbol{c}_{2},s')\rangle_{\mathrm{H}} \\ &= \delta(s-s')\,\delta(\boldsymbol{l}-\boldsymbol{l}')n^{-1}\lambda^{-d} \\ &\times \int d\boldsymbol{c}_{1} \int d\boldsymbol{c}_{2}\widetilde{\Gamma}(\boldsymbol{c}_{1},\boldsymbol{c}_{2}), \end{split}$$
(A6)

where Eqs. (52) and (53) have been employed. But, use again of Eq. (A1) yields

$$\int d\boldsymbol{c}_1 \int d\boldsymbol{c}_2 \widetilde{\Gamma}(\boldsymbol{c}_1, \boldsymbol{c}_2) = 0, \qquad (A7)$$

and consequently the second moment of \tilde{S}_{ρ} vanishes, implying that the noise itself also identically vanishes. When all the above results are substituted into Eq. (A3) and the definition in Eq. (58) is taken into account, Eq. (60) follows directly.

The balance equation for the fluctuating velocity field is obtained in a similar way. Multiplication of Eq. (43) by c_1 and integration over it gives

$$\frac{\partial}{\partial s}\delta\boldsymbol{\omega}(\boldsymbol{l}_{1},s) = -\frac{\partial}{\partial \boldsymbol{l}_{1}} \cdot \delta\boldsymbol{\Pi}(\boldsymbol{l}_{1},s) + \int d\boldsymbol{c}_{1}\boldsymbol{c}_{1}\Lambda(\boldsymbol{c}_{1})\delta\widetilde{F}_{1}(\boldsymbol{l}_{1},\boldsymbol{c}_{1},s) + \widetilde{\boldsymbol{S}}_{\boldsymbol{\omega}}(\boldsymbol{l}_{1},s), \tag{A8}$$

where $\delta \Pi$ is defined in Eq. (63) and

$$\widetilde{S}_{\omega}(l_1,s) \equiv \int d\boldsymbol{c}_1 \boldsymbol{c}_1 \widetilde{S}(l_1,\boldsymbol{c}_1,s). \tag{A9}$$

A simple calculation, using Eq. (A1), and taking into account the momentum conservation in collisions leads to

$$\int d\boldsymbol{c}_1 \boldsymbol{c}_1 \Lambda(\boldsymbol{c}_1) \,\delta \widetilde{F}_1(\boldsymbol{l}_1, \boldsymbol{c}_1, s) = \frac{\zeta_0}{2} \,\delta \boldsymbol{\omega}(\boldsymbol{l}_1, s). \quad (A10)$$

For the correlation of the noise \tilde{S}_{ω} by means of Eq. (52) it is found that

$$\langle \tilde{S}_{\omega}(\boldsymbol{l}_{1},s)\tilde{S}_{\omega}(\boldsymbol{l}_{1}',s')\rangle_{\mathrm{H}} = -\delta(s-s')\delta(\boldsymbol{l}_{1}-\boldsymbol{l}_{1}')n^{-1}\lambda^{-d}$$

$$\times \int d\boldsymbol{c}_{1}\int d\boldsymbol{c}_{1}'\boldsymbol{c}_{1}\boldsymbol{c}_{1}'[\Lambda(\boldsymbol{c}_{1})+\Lambda(\boldsymbol{c}_{1}')]$$

$$\times\delta(\boldsymbol{c}_{1}-\boldsymbol{c}_{1}')\chi(\boldsymbol{c}_{1})$$

$$+\bar{T}_{0}(\boldsymbol{c}_{1},\boldsymbol{c}_{1}')\chi(\boldsymbol{c}_{1})\chi(\boldsymbol{c}_{1}')\}. \quad (A11)$$

The calculation of the first term on the right-hand side of the above equation is straightforward, giving

$$\int d\boldsymbol{c}_{1} \int d\boldsymbol{c}_{1}' \boldsymbol{c}_{1} \boldsymbol{c}_{1}' [\Lambda(\boldsymbol{c}_{1}) + \Lambda(\boldsymbol{c}_{1}')] \delta(\boldsymbol{c}_{1} - \boldsymbol{c}_{1}') \chi(\boldsymbol{c}_{1})$$
$$= \zeta_{0} \int d\boldsymbol{c}_{1} \boldsymbol{c}_{1} \boldsymbol{c}_{1} \chi(\boldsymbol{c}_{1}) = \frac{\zeta_{0}}{2} \mathbf{I}, \qquad (A12)$$

where I is the unit tensor of dimension *d*. The evaluation of the last term on the right-hand side of Eq. (A11) involves calculating several standard angular integrals. The result is

$$\int d\mathbf{c}_{1} \int d\mathbf{c}_{1}' \mathbf{c}_{1} \mathbf{c}_{1}' \overline{T}_{0}(\mathbf{c}_{1}, \mathbf{c}_{1}') \chi(c_{1}) \chi(c_{1}')$$

$$= \frac{(1 - \alpha^{2}) \pi^{(d-1)/2}}{4\Gamma\left(\frac{d+3}{2}\right) d} \mathbf{I} \int d\mathbf{c}_{1} \int d\mathbf{c}_{1}' c_{11'}^{3} \chi(c_{1}) \chi(c_{1}') = \frac{\zeta_{0}}{2} \mathbf{I}.$$
(A13)

Substitution of Eqs. (A12) and (A13) into Eq. (A11) shows that the second moment of the noise S_{ω} vanishes, implying that the noise itself also vanishes identically. Then Eqs. (A8) and (A10) lead to Eq. (61).

Finally, multiplication of Eq. (43) by $2c_1^2/d$ and integration over c_1 yields

$$\frac{\partial}{\partial s} \delta \epsilon(\boldsymbol{l}_{1}, s) = -\frac{2}{d} \frac{\partial}{\partial \boldsymbol{l}_{1}} \cdot \delta \boldsymbol{\phi}(\boldsymbol{l}_{1}, s) + \frac{d+2}{d} \frac{\partial}{\partial \boldsymbol{l}_{1}} \cdot \delta \omega(\boldsymbol{l}_{1}, s) + \frac{2}{d} \int d\boldsymbol{c}_{1} c_{1}^{2} \Lambda(\boldsymbol{c}_{1}) \delta \widetilde{F}_{1}(\boldsymbol{l}_{1}, \boldsymbol{c}_{1}, s) + \widetilde{S}_{\epsilon}(\boldsymbol{l}_{1}, s),$$
(A14)

with the heat flux $\delta \phi$ defined by Eq. (64). Given that the kinetic energy is not conserved in collisions, the calculation of the second term on the right-hand side of the above equation is more involved than in previous cases, although it is still quite easy to get

$$\frac{2}{d} \int d\boldsymbol{c}_1 c_1^2 \Lambda(\boldsymbol{c}_1) \,\delta \widetilde{F}_1(\boldsymbol{l}_1, \boldsymbol{c}_1, s) = - \,\delta \zeta_0(\boldsymbol{l}, s) + \zeta_0 \,\delta \boldsymbol{\epsilon}(\boldsymbol{l}, s) \,. \tag{A15}$$

The expression of the fluctuating cooling rate $\delta \zeta_0$ is given in Eq. (67).

Also the calculation of the second moment of the noise term \tilde{S}_{ϵ} is more cumbersome than for the other ones. Actually, it is the only one that does not vanish. The result is provided by Eq. (69) with

$$\Phi(\boldsymbol{c}_{1},\boldsymbol{c}_{2}) = \frac{\pi^{(d-1)/2}}{\Gamma\left(\frac{d+5}{2}\right)d^{2}} \left\{ \left[d+1-4\alpha-(d+5)\alpha^{2}\right]C^{2}c_{12}^{3} + \frac{(1-\alpha^{2})(d+5-2\alpha^{2})}{4}c_{12}^{5} + 2(1+\alpha)(2d+3-3\alpha)c_{12}(\boldsymbol{C}\cdot\boldsymbol{c}_{12})^{2} \right\}, \quad (A16)$$

where $c_{12} \equiv c_1 - c_2$ and $C \equiv (c_1 + c_2)/2$.

APPENDIX B: DERIVATION OF EQ. (105)

The Fourier transform of Eq. (52) is

$$\langle \tilde{S}(\boldsymbol{k},\boldsymbol{c},s)\tilde{S}(\boldsymbol{k}',\boldsymbol{c}',s')\rangle_{\mathrm{H}} = \delta_{\boldsymbol{k},-\boldsymbol{k}'}\delta(s-s')\frac{\tilde{V}^2}{N}\tilde{\Gamma}(\boldsymbol{c},\boldsymbol{c}'),$$
(B1)

where $\tilde{V} \equiv V\lambda^{-d}$, V being the volume of the system. Then, for any two components of W_{\perp} , from Eq. (104) it is obtained that

$$\langle W_{\perp,i}(\boldsymbol{k},s)W_{\perp,j}(\boldsymbol{k}',s')\rangle_{\mathrm{H}} = \frac{\widetilde{V}^2}{N}\delta_{ij}\delta_{\boldsymbol{k}-,\ \boldsymbol{k}'}k^2\int_0^s ds_1\int_0^{s'}ds_1'\int d\boldsymbol{c}'$$
$$\times \int d\boldsymbol{c}'c_{\parallel}c_{\perp,i}c_{\parallel}'c_{\perp,j}'\mathcal{U}(\boldsymbol{k},\boldsymbol{c},s_1)$$
$$\times \mathcal{U}(-\boldsymbol{k},\boldsymbol{c}',s_1')\delta(s-s_1-s'+s_1')$$

$$\times \mathcal{P}_{\perp} \mathcal{P}'_{\perp} \widetilde{\Gamma}(\boldsymbol{c}, \boldsymbol{c}'). \tag{B2}$$

Here \mathcal{P}' is defined like \mathcal{P} , but acting on functions of the velocity \mathbf{c}' , and c_{\parallel} denotes the component of \mathbf{c} along \mathbf{k} . Now, it is taken into account that: (i) because calculations are restricted to the lowest order in k, which is k^2 , the k factors in the \mathcal{U} operators can be neglected, i.e., the operator $L(\mathbf{k}, \mathbf{c})$ in Eq. (85) can be replaced by $\Lambda(\mathbf{c})$; and (ii) Eq. (81) implies that, in particular, $\langle \chi c_i c_j | \xi_\beta \rangle = 0$, where $\beta = 1, \ldots, d+2$ for $i \neq j$. Then, the projection operator \mathcal{P}_{\perp} can be eliminated everywhere in Eq. (B2). Note that this can be only done after the operator $L(\mathbf{k}, \mathbf{c})$ has been replaced by $\Lambda(\mathbf{c})$. Then by carrying out the integral over s_1 , it is obtained that

$$\langle W_{\perp,i}(\boldsymbol{k},s)W_{\perp,j}(\boldsymbol{k}',s')\rangle_{\mathrm{H}} = \frac{\widetilde{V}^{2}}{N}\delta_{\boldsymbol{k},-\boldsymbol{k}'}k^{2}\int d\boldsymbol{c}$$
$$\times \int d\boldsymbol{c}' c_{\parallel}c_{\perp,i}c_{\parallel}'c_{\perp,j}'e^{(s-s')\Lambda(\boldsymbol{c})}$$
$$\times \int_{0}^{s'} ds_{1}'e^{s_{1}'[\Lambda(\boldsymbol{c})+\Lambda(\boldsymbol{c}')]}\widetilde{\Gamma}(\boldsymbol{c},\boldsymbol{c}'),$$
(B3)

for s > s'. Again, it is assumed that the HCS is linearly stable with respect to homogeneous perturbations for the system under consideration. Then, taking the limit $s' \ge 1$, the above equation can be rewritten as

$$\langle W_{\perp,i}(\boldsymbol{k},s)W_{\perp,j}(\boldsymbol{k}',s')\rangle_{\mathrm{H}}$$

$$= \frac{\widetilde{V}^{2}}{N} \delta_{\boldsymbol{k},-\boldsymbol{k}'} k^{2} \int d\boldsymbol{c} \int d\boldsymbol{c}' c_{\parallel} c_{\perp,i} c_{\parallel}' c_{\perp,j}' e^{(s-s')\Lambda(\boldsymbol{c})} \widetilde{\vartheta}_{\mathrm{HCS}}(\boldsymbol{c},\boldsymbol{c}').$$
(B4)

The function $\tilde{\vartheta}_{\text{HCS}}(\boldsymbol{c},\boldsymbol{c}')$ is the solution of the equation

$$[\Lambda(\boldsymbol{c}) + \Lambda(\boldsymbol{c}')]\tilde{\vartheta}_{\mathrm{HCS}}(\boldsymbol{c},\boldsymbol{c}') = -\tilde{\Gamma}(\boldsymbol{c},\boldsymbol{c}'), \qquad (B5)$$

i.e. [see Eq. (32)],

$$\widetilde{\vartheta}_{\text{HCS}}(\boldsymbol{c},\boldsymbol{c}') = \int d\boldsymbol{l} \widetilde{h}(\boldsymbol{l},\boldsymbol{c}\,;\boldsymbol{c}')\,. \tag{B6}$$

To give account of the time dependence in Eq. (B4) we introduce

$$\widetilde{\psi}_{\text{HCS}}(\boldsymbol{c},s;\boldsymbol{c}') = \int dl \widetilde{h}(\boldsymbol{l},\boldsymbol{c},s;\boldsymbol{c}'). \tag{B7}$$

It obeys the equation [see Eq. (30)]

$$\left[\frac{\partial}{\partial s} - \Lambda(\boldsymbol{c})\right] \widetilde{\psi}_{\text{HCS}}(\boldsymbol{c}, s; \boldsymbol{c}') = 0.$$
(B8)

By writing Eq. (B4) in terms of $\overline{\psi}_{\text{HCS}}(\boldsymbol{c}, \boldsymbol{s}; \boldsymbol{c}')$, Eq. (105) follows after a trivial change in the notation, taking into account the isotropy of $\Lambda(\boldsymbol{c})$.

APPENDIX C: SOME DETAILS OF THE CALCULATIONS DESCRIBED IN SEC. VI

The explicit expression of the function G(|s|) defined in Eq. (106) is

$$G(|s|) = \int d\mathbf{c} \int d\mathbf{c}' c_x c_y c'_x c'_y e^{s\Lambda(c)} \chi(c) \,\delta(\mathbf{c} - \mathbf{c}')$$
$$= \int d\mathbf{c} c_x c_y e^{s\Lambda(c)} \chi(c) c_x c_y. \tag{C1}$$

The term involving the two-particle correlation function g_{HCS} in Eq. (109) has been neglected. The reason for this is that numerical simulations of dilute granular gases [34] have shown that it gives much smaller contributions than the term kept. Substitution of the above expression in Eq. (113) and integration over time *s* leads to

$$\tilde{\eta}' = 2 \int d\boldsymbol{c} c_x c_y C_{xy}(\boldsymbol{c}), \qquad (C2)$$

where $C_{xy}(c)$ obeys the equation

$$\left[\Lambda(\boldsymbol{c}) + \frac{\zeta_0}{2}\right] C_{xy}(\boldsymbol{c}) = -\chi(c)c_x c_y.$$
(C3)

This equation will be now solved in the first Sonine approximation, i.e., by keeping only the first term of the expansion of the solution in Sonine polynomials [21], which due the isotropy of the operator $\Lambda(\mathbf{c})$ has the form

$$C_{xv}(\boldsymbol{c}) = Ac_x c_v \varphi_0(c), \qquad (C4)$$

where φ_0 is the Gaussian

$$\varphi_0 = \pi^{-d/2} e^{-c^2}.$$
 (C5)

To determine the constant A, Eq. (C3) is multiplied by $c_x c_y$ and integrated over c, after replacing $C_{xy}(c)$ by its expression in Eq. (C4). Moreover, the velocity distribution of the HCS is also approximated by its expression in the first Sonine approximation [Eq. (22)]. From this point, the only remaining task is to evaluate several integrals. Although lengthy, the calculation is straightforward and similar to the one needed to compute the Navier-Stokes transport coefficients [31]. The result found for the constant A reads

$$A = \frac{1 + a_2(\alpha)}{4\tilde{\nu}(\alpha) - \frac{3\zeta_0}{2}},$$
 (C6)

with $\tilde{\nu}(\alpha)$ given by Eq. (97). Finally, Eq. (C4) is substituted in Eq. (C2) and result (114) follows quite easily.

In order to derive an expression for the two-time correlation function of the transverse velocity, Eqs. (105) and (110) are employed. Taking $s > s' \ge 1$,

$$\begin{split} \langle \delta \omega_{\perp,i}(\boldsymbol{k},s) \, \delta \omega_{\perp,j}(\boldsymbol{k}',s') \rangle_{\mathrm{H}} \\ &= \frac{\widetilde{V}^2}{N} k^2 \delta_{i,j} \delta_{\boldsymbol{k},-\boldsymbol{k}'} \\ &\times \Bigg[\int_{-\infty}^{s'} ds_1 \int_{-\infty}^{s'} ds_1' e^{\lambda_{\perp}(\boldsymbol{k})(2s'-s_1-s_1')} G(|s_1-s_1'|) \\ &+ \int_{s'}^{s} ds_1 \int_{-\infty}^{s'} ds_1' e^{\lambda_{\perp}(\boldsymbol{k})(s+s'-s_1-s_1')} G(|s_1-s_1'|) \Bigg]. \end{split}$$
(C7)

The first integral on the right-hand side is related with the coefficient $\tilde{\eta}'$ computed before,

$$\int_{-\infty}^{s'} ds_1 \int_{-\infty}^{s'} ds_1' e^{\lambda_{\perp}(k)(2s'-s_1-s_1')} G(|s_1-s_1'|) = -\frac{\tilde{\eta}'}{2\lambda_{\perp}(k)}.$$
(C8)

The other integral in Eq. (C7) can be evaluated, for instance, by introducing the variables $g \equiv s_1 - s'_1$ and $S \equiv (s_1 + s'_1)/2$. Then, the integral is decomposed into three. For large enough s-s', the only remaining one is

$$\int_{0}^{\infty} dg G(|g|) \int_{s'-g/2}^{s'+g/2} dS e^{\lambda_{\perp}(k)(s+s'-2S)} = -\frac{\tilde{\eta}_{1}}{2\lambda_{\perp}(k)} e^{\lambda_{\perp}(k)(s-s')},$$
(C9)

with $\tilde{\eta}_1$ given by Eq. (116). Use of Eqs. (C8) and (C9) into Eq. (C7) gives Eq. (115).

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