A COMPUTER SIMULATION OF THE PALLETIZING SYSTEM AT FRITO-LAY, INC. IN TOPEKA, KANSAS

Бу

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I. INTRODUCTION

There are five major steps involved in producing a product in a Frito-Lay, Inc. manufacturing plant. The first step involves receiving raw materials into a plant and feeding them into the production process. The next step is to transform these raw materials into an edible product. The third step is to package the edible product in the appropriate packages. The fourth step is to store the packaged product in a storage facility, such as a warehouse, and the fifth step is to ship the finished product to the various customers. This report researches the interface between two of these steps, the transfer of the finished packaged product to the warehouse facility for storage until shipping to the customer.

Originally, the Frito-Lay plant in Topeka, Kansas had transferred the finished packaged product from the packaging floor into the warehouse by employees pulling full skids of finished product from the packaging floor into the warehouse with hand jacks. In October of 1983, a conveyor system was installed to transfer the finished cases of product from the packaging floor into the warehouse, thus eliminating the manual transportation of product. With the new system, the packers, whose prior responsibilities included packing the bags of product into cardboard cases, stacking the cases onto pallet board, and accounting for the cases that were packed, are now only responsible for packing the bags of product into cases and placing the cases of finished product onto a conveyor. Their other responsibilities were transferred to

employees called palletizers. The palletizers are located at the end of the conveyor system at a continuous loop called a palletizing loop. Their responsibilities included stacking the cases of finished product onto pallet boards and accounting for the cases produced, for up to four different items. It is the activity of the palletizer that is the topic of this thesis.

This conveyor system was developed specifically for Frito-Lay, Inc. and has not been previously modeled using a computer simulation. Pertinent conveyor research reveals a moderate amount of consideration of conveyor theory and modeling. Kwo, 1958, was the first to quantify basic conveyor principles. His research, however, presented only a minimum amount of operating characteristics. literature, it appears that "there has been a fair amount of prior research concerned with non-recirculating conveyor supplied systems, [and that] there appears to be only a meager amount of work concerned with the recirculation system in which the conveyor is a continuous loop moving at a constant speed," Bussey, 1972. Bussey presents a model for analyzing closed loop conveyor systems with multiple workstations. His research, however, investigates a closed loop conveyor with discretely spaced loads. Another simulation model developed in this area is that of Buxev and Owen, 1981, dealing with the final assembly of a telephone. Bobillier, Kahan and Probst, 1976, also modeled a continuous loop conveyor with discretely spaced loads in their

simulation of an automatic warehouse.

The above models, although similiar to the model needed for this conveyor system, do not include the decision process for the palletizer at the palletizing loop. These considerations also do not deal with the continuous loop with randomly spaced loads. This loop has been referred to in past research but very few papers have dealt directly with this system. These aspects of the simulation model of this system make it a unique model applying specifically to the Frito-Lay conveyor system in Topeka, Kansas.

The purpose of this study was to develop a model to explore possible productivity improvements to the current palletizing system. The areas researched in this study were the current conditions of the system which provided the highest productivity levels. A simulation model written in GPSSH was the tool used to model the system and determine the productivity improvements.

II. DESCRIPTION OF THE SYSTEM OPERATION

There are four major aspects of the system operation: the infeed of the cases into the conveyor system; the programmable controller which controls the conveyor system; the conveyor and case accumulation capabilities of the conveyor; and the palletizing loop and palletizer. To model this system it was necessary to understand each of these components. A discussion of these aspects of the system will be given below.

Case Infeed

The cases of product are fed into the conveyor system and placed onto the infeed conveyor on the packaging floor by employees called packers. Bags of product are produced at the packaging machines and travel up a short conveyor to the packer. The packer then takes the bags of finished product and places them into a cardboard case with a pre-set bag configuration and case count. After the packer places the correct number of bags into the case, he or she closes the cardboard case and places a case label on it to identify the contents of the case. The packer then places the finished case onto a conveyor located directly in front of the packing station. This conveyor is the infeed of cases into the palletizing loop.

There are 8 to 10 packaging machines which supply one infeed conveyor and one palletizing loop. There are 39 packaging machines on the packaging floor. The 39 packaging machines are specifically used in one of the five major

departments of products produced in this manufacturing facility: potato chips; Doritos(R); extruded products; Tostitos(R); and universal corn products/Variety Pack(R). These departments supply one of the four existing palletizing loops.

The size and type of product run on the packaging machines shift is determined from the production schedule. The production schedule for each department is determined the prior day by a real time demand from the route salesmen. A salesman can submit an order for his route up to 78 hours before delivery and can change his submitted order by phone up to 24 hours beforehand. Because of the salesmen's ordering procedures, the production schedule is determined one day in advance.

The production schedules are a very important aspect of this computer simulation model. The items on the production schedule are not produced at the same case per hour rate and because of this, the different combinations of products being run in one department can greatly affect the amount of cases to be palletized in a given shift.

The Programmable Controller.

The entire conveyor, from case infeed to the palletizing loop is controlled through a programmable controller. Photo cells are placed on the conveyor in strategic places to monitor the flow attributes of the cases on the conveyor. When buildup conditions on the conveyor

exist, certain segments of the conveyor will shut off and accumulate cases as a temporary storage area. When these accumulation areas collect a pre-set number of cases, the photo cell will trigger the programmable controller to react to the condition in some other manner, i.e. turn on a segment of conveyor or shut off another segment of the conveyor.

The programmable controller with the aid of the photo cell also provides case spacing before the case enters the palletizing loop. An accumulation area prior to the decline conveyor entering the palletizing loop will store cases to allow adequate spacing. When a case passes by the photo cell at position A (see Figure 1), it stops the case at B for a pre-set time period. After that period elapses, the case in area B begins to move again, and the process continues. This spaces the cases before entering the loop to avoid any jams at the entrance to the palletizing loop.

The controller is programmed with ladder logic to perform certain actions under certain conditions. The broken or unbroken beams of the photo cell are the source that relays these conditions to the the programmable controller. The programmable controller, therefore, acts as the "traffic cop" to the conveyor system by controlling the case flow. The application of the programmable controller and the ladder logic to the simulation model is discussed later in this study.

Conveyor and Case Accumulation

The conveyor rollers throughout the length of the

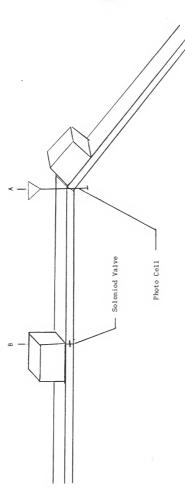


Figure 1; Case Spacing Before a Case Enters the Palletizing Loop

conveyor are chain driven live rollers with intersperced dead rollers. The live rollers are the mechaninsm that makes the cases move along the conveyor. In certain areas of the conveyor there exists the capability of zero pressure accumulation. Zero pressure accumulation is the process of stopping and storing cases on the conveyor without having the cases exert any pressure on each other. Zero pressure accumulation provides temporary storage for the cases on the conveyor. This zero pressure accumulation is controlled by pressure sensor rollers located at 30 inch intervals down the length of the conveyor. When a case rolls over a pressure roller, the clutch disengages the rollers in the near vicinity. When a case can continue to roll over the pressure roller, the clutch re-engages the rollers to continue the case movement process. When there is an accumulation situation and the case can not move off the pressure roller. the case sitting on the pressure roller temporarily disengages the clutch for the rollers in the vicinity and stops the case movement process. This is the process used to accumulate cases on the conveyor.

The entire accumulation and release process is started by the activiation and deactivation of certain solenoid valves as determined by the programmable controller. The broken or unbroken beams of the photo cells are the signal to the programmable controller to begin the accumulation process. When cases are released from accumulation, they are released by reversing the accumulation condition of the

solinoid valve to allow the first case in the accumulation area to move. The remainder of the cases are released by the process of singulation. Releasing the cases by singulation allows spacing between the cases because they are realeased one by one.

There are certain areas of the conveyor where accumulation can occur. These areas are the long straight segments of the conveyor. The conveyor segments with bends do not have the capability of accumulating cases. This is to aviod unecessary jams in the curved part of the conveyor.

The Palletizing Loop and the Palletizer

The palletizing loop contains three major functions: case infeed, case pickup and case recirculation (see Figure 2). Cases are fed into the loop by a belt driven conveyor which is controlled by the programmable controller. Cases are allowed to feed into the loop unless there is a backup in the recirculating-accumulation area. If there is a backup with the recirculating cases, control will be given to this conveyor section until those cases have been cleared. Photo cells are located at three points on the loop, the case infeed, the beginning of the recirculating-accumulation section and the end of the recirculating-accumulation segment on the loop to control the infeed and recirculation processes.

As the cases are being fed onto the conveyor, they follow a guide that turns the case sideways so the case label can be easily read by the palletizer. The case then

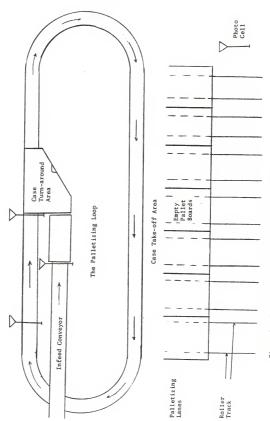


Figure 2: The Palletizing Loop and Palletizing Area

continues in this position the entire time it is on the loop. The cases follow the the conveyor until they reach the front side of the loop where the palletizer is standing (see Figure 2). If the palletizer misses a case, the case recirculates around the loop. The case follows around to the back side of the conveyor where it either accumulates or recirculates, according to the present conditions on the loop as determined by the photo cells.

The palletizer's workstation consists of the conveyor with cases circulating on it, the pallet stacking area, and a small desk used to facilitate counting the cases that have been produced (see Figure 2). The palletizer takes a case off of the conveyor and stacks it on a pallet board located behind him. There are seven to eleven lanes for empty and full pallet boards at each palletizing loop. Each of these lanes consists of roller track for easy movement of the pallet board, and a stacking guide for straight stacking of product. One of the lanes is used to store empty pallet boards.

Cases are stacked on the pallets according to product line and item. As the palletizer stacks the appropriate number of cases on the pallet as determined by product and line item, he or she must place an inventory ticket on the pallet and record the ticket on a line sheet. This is the accounting system for production and shipping to determine of the number of cases produced on a shift. The palletizer then pushes the pallet along the roller track into a position

where the shipping personel can pick up the pallet with a fork lift and put it into inventory. The palletizer then puts down an empty pallet board on the roller track and begins stacking cases on the empty pallet board. Each palletizer is responsible for palletizing between one to five different items at a time, depending on the hourly production rate of these items.

III. DEVELOPMENT OF SYSTEM PARAMETERS

Before determining the criterion to be used in the final model of this system, there were several areas studied to determine the appropriate approach to the model. A brief discussion will be given below on the different aspects of the system that were evaluated for the simulation model.

A Study of the System's Ladder Logic as it Relates to Product Flow

Initially, the simulation model was to be based on the ladder logic of the programmable controller. Ladder logic is the computer language that tells a programmable controller how to react to certain conditions in the operating system. An example of the format is shown in Figure 3. Ladder logic functions much like boolean variables. If certain conditions are true a reaction will occur in the system. If the conditions are not true a different reaction will occur in the system. A study was performed to decode the ladder logic into actual bollean variables. After converting the ladder logic into boolean variables, the plan for the model was to utilize the various conditions set forth in the logic of the programmable controller to become the basis for action in the After modeling only a short segment of the conveyor model. with a large amount of code it was determined that this approach was much too complicated for the purpose of study and that simplification of the model was necessary.

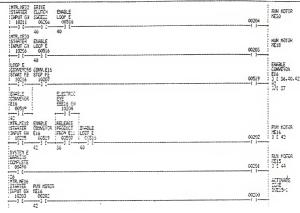


Figure 3: Ladder Logic of the Programmable Controller

After abandoning the ladder logic approach, it was decided to gain more information about the activities of the palletizers on a daily basis. This led to an occurrance sample of the activities of the palletizers. The activities of the palletizers were divided into sixteen categories as

shown in Table 1.

initial assumption of the management at Frito-Lay, Inc. was that the palletizers spend a large quantity of their time in idle activities, i.e. walking and standing. The occurrance sample was based on the idle time of the palletizers as shown by the calculations in Table Αn initial sample of 78 observations was taken to determine the activities and the initial percentage breakdown for the sample. An idle time percentage of 25% and a relative accuracy of 12% was used to determine the number of observations needed to provide a statistical confidence interval about 25% idle time between 22% and 28%. idle time activity percentage was 28% using 563 observations.

The occurance sample provided a breakdown of the activities of the palletizer. It also confirmed the assumption that the palletizer did spend a fair amount of his time walking for the most part to pick up a case and standing idley or waiting for a case to come to him. Due to the complexity of incorporating each of the activities into the simulation model, the occurance sample was used to gain a knowledge of the hourly functions of the palletizer.

Table 1. Occurance Sample Description

1.	Filling out line sheets	8	1.3%
2.	Throw case on skid	70	11.7%
3.	Place case on skid	42	7.0%
4.	Place ticket on skid	12	2.0%
5.	Walking	97	16.1%
6.	Standing	71	11.9%
	Putting down pallet board	19	3.2%
	Walking with case	41	6.8%
	Placing two cases on skid	8	1.3%
	Re-arranging skid	17	2.8%
	Writing on line sheet	61	10.2%
	Re-arranging case on loop	6	1.0%
	Pushing back skid	13	2.2%
	Picking up case	97	16.2%
	Pushing back case	12	2.0%
	No one on loop	25	4.2%
10.	No one on roop	25	4.2%
	Total Observations	599	
Actu	ual case pickup and placement	on skid = 34.9%	
Time	spent walking or standing =	28.0%	
Time	spent doing other palletizi	ng activities = 37.1%	

Observations Percent

Calculations:

Activity

1/2				
A=sp=z(p(1-p)/n)	where	п	=	no. of observations
		Р	=	mean percent occurrance
s=.12		z	=	no. of std deviations
				for confidence interval
p=.25		Α	=	desired absolute accuracy
		s	=	relative accuracy
z=1.645 @ 90% C.I.				·
n=563 observations accor	rding to	> F	er	cent idle time

The dimensions of the palletizing loop were determined from a blue print of the palletizing area. The conveyor speed is rated at 90 feet per minute. Although there may be some case slippage from the rollers due to friction, the simulation model uses this conveyor running rate. Both the length of the conveyor and the the conveyor running rate are used in the model to simulate the amount of time it takes for a case to travel around the length of the conveyor.

Determining the Operating Speed and Length of the Conveyor

A Study of Production Schedules

Approximately six weeks of production schedules at three shifts per day were reviewed to determine some typical production schedules. As was previously discussed, the production schedule is determined by a real time demand by the route salesmen and is variable on a day-to-day basis. The production schedules were studied by department, being categorized by the item and bag size being run i.e. \$1.49 Lays(R) Potato Chips. From the breakdown of line items, the schedules were further refined by determining the actual cases produced with a schedule by applying the standard machine speeds to the schedule. This was done in attempt to find some typical production schedules for each department. The study showed that there was a wide variety in the number of cases per hour run in a given production schedule. It was determined at this point to utilize the high and low points in the range of cases generated per hour to determine how the palletizer would react in productivity to the various conditions. The range of case per man hour inputs were 260 cases per hour to 521 cases per hour. The study of production schedules was performed for each of the five departments. However, the actual simulation model only represents potato chip production so the study of production schedules proved to be more detailed than necessary. The exact rates used in the model will be discussed in Section IV.

IV. MODELING THE SYSTEM

After attempting to model the system through the ladder logic of the programmable controller, it was evident that a simpler modeling approach was necessary. One assumption that was made in the model was that the cases arrive at the palletizing loop in a random pattern. It was also determined from the production schedules that the quantity of the different items to be generated could be assigned a probability distribution. The probability was based on the individual case per hour output of the item on a given production schedule. These assumptions gave the model a basis for the case infeed into the system. The flow of the cases around the palletizing loop was also known, as well as the basic pattern used by a palletizer to pick up a case of product. The final model was determined from the knowledge of these characteristics of the system.

Case Infeed and Product Flow

Figure 4 shows an example of a production schedule. The schedule lists the items to be produced on the shift as well as the quantity of each item. Each item is scheduled at 90% of the standard machine speed for that package size. In the area of potato chip palletizing, there are limitations on the pounds of potato chips that can be produced in an hour. Because of this, a package may not be able to be run at the 90% of standard machine speed. The input probability distribution for the case type generation in the model was

DAILY PRODUCTION SCH	HEOULE
- 7/10/84 Tue - 15	± PC
1 2 ACH 1 2	3 a 5 c ;
CPSCOWPC	650 min 800 max
1.39.5C. OWPC.	950 min 1050 max
- VendScow PC	200 min 300 mgs
CPSC ON PC	
SPK PC	900 min 1000 Max
BPK PC	(so mid lobs may
8-PKPC	
1.39 PC	1600 min 1500 max
1.99 PC	1100 min 1500 may
2.44 PC	1000 min 1300 Mal
	LP PC 400 min No max
	CP PC.
Vend BBQPC	240 max 40 BBQ PC
CP BBQ PC	650min 500 may
139 BBQ PC	600 min 750 max

Figure 4: Daily Production Schedule

developed with this in mind. Table 2 shows the number of items run in each of the simulation runs of the model. The first column lists how many palletizers were used in the model which, is either one or two palletizers. The second column lists the total number of cases per hour that were run into the system. The third column lists the probability distribution of the different case types run into the system, and the fourth column shows the total number of different items run into the system. The different case types are identified by a number of one through six instead of by the name used on the production floor, such as \$1.49 Lays(R) Potato Chips, etc. Again, case type probability distributions are taken from actual production schedules. and the number of palletizers assigned to the palletizing loop is that number which would have been assigned for crewing on the production floor.

When Frito-Lay, Inc. installed the palletizing loops into their Topeka, Kansas facility, a standard was established for the cases per man-hour output, which was four hundred cases per man-hour. The eight simulation runs made of the model vary around that standard cases per man-hour output. This procedure was used to establish the characteristics of the overload and underload points of the palletizer. A Generate statement was used to input cases into the palletizing loop at the various inter-arrival times, which would provide the system with the given cases per hour input. After a case had been generated into the system, it would be assigned a case-type, according to the various probability distributions.

Table 2. Probability distributions for Simulation Runs

No. of Falletizers	Total Cases per Hour	Item Distribution	Total Items
1	280	.5,1/1,2	2
1	394	.678,1/1,2	2
1	460	.580,1/.710,2/1,3	3
1	521	.457,1/,578,2/1,3	3
2	673	.218,1/.500,2/.698,4/	/1,5 4
2	812	.180,1/.500,2/.836,4/	/1,5 4
2	882	.461,1/.530,2/.708,4/	/ 5
2	969	.874,5/1,6 .289,1/.441,2/.510,3/ .675,4/.716,5/1,6	/ 6

This provided the model a case type assignment and a case rate input into the system.

To simplify the model of the palletizing system, only the palletizing loop and its characteristics were used. Therefore, when the cases were generated into the system, they were generated directly onto the palletizing loop. As was previously mentioned, the palletizing loop is a recirculating continuous loop conveyor.

The palletizing loop can be divided into three sections. The first section is the case entry section where the cases are fed onto the loop; the next section is case take-off, where the palletizers remove the cases from the loop and place them on pallet boards for storage in the warehouse; and the last section is recirculation, where there is no normal case removal or case infeed. This model was developed such that the cases were fed onto the conveyor after the case take-off section. Therefore, the cases enter onto the conveyor, travel into the recirculation section, and then travel through the case take-off section. Actually. the come onto the conveyor in the middle the recirculating area, then through the case take-off section to a portion of the recirculating conveyor back to the case infeed section. For simplicity, the cases in the model are fed into beginning of the recirculating conveyor.

The product flow around the palletizing loop is developed through the a series of Advance statements to model the case travel at 90 feet per minute. The recirculating section of the conveyor is a Storage facility which can

contain a maximum of 35 cases. The cases reside in the Storage for the duration of the recirculating period and leave the Storage on a first-in first-out basis. The case take-off segment is sub-divided into two Storage facilities, one for each palletizer, and it contains a total of 15 cases. Each of the two palletizer's take-off sections are subdivided into five Storage areas, which can contain a total of three cases. The reason for this, is to control the logic used for the case pickup, which will be explained under the next sub heading and to maintain a truer product flow in the area where the palletization occurs.

Palletization of Cases

The palletization logic is based on two GPSSH programming concepts. The first of those is the use of a Group in conjunction with the Scan and Alter blocks. In this simulation model, a group is used to mark a case in each of the two palletizing areas when it has been identified as a case to be picked up. The Scan and the Alter blocks are the mechanisms which enable the logic to mark the next case on the palletizing loop to be palletized. The second basic GPSSH concept used in the simulation model is a series of Test blocks which determine the status of the case as it travels on the loop in respect to the current location of the palletizer, the case type, and the current location of the case on the loop. These basic concepts are the crux of the simulation model and will be explained in detail in this

section.

When a case enters one of the two palletizing take off areas it joins a Group. As previously stated, the maximum content of one of these palletizing areas is 15 cases. Therefore, the maximum content of each of the two Groups is also 15 cases. Therefore, when a case enters or leaves a palletizing take off area it also enters or leaves the same As the case enters the case take off area and the group. group, it is given a number from 1 to 15 to represent its postion in that group. These case number assignments are important in the simulation model because they are used the process of determining the next case to be picked up off the loop. This enables the model to look at case take off candidates in a first-in first-out basis so to avoid favoring case number one in the case takeoff procedure. case number is basically a position marker of the case based on the length of time the case has spent in the group.

Each of the two palletizer take off areas are divided into 5 storage areas of three case widths (see Figure 5). Each of these storage areas represents the location of a particular case on the loop, i.e. if the case is in the first storage area it is at location 1 on the loop; or, if the case is in the second storage area it is at location 2 on the loop, etc. These storage area give the model a marker of case location. These markers provide one of the three testing criteria to determine if the case can potentially be taken off of the loop.

There are two other criteria used to determine if a case

Three	Three Case Widths	tion Locati
Group 1 - Five Storage Blocks of Three Case Widths		Location S
Five Storage Case Widths		ocation Loc 4 on Area for
Group 1 - F		Location L 5 Palletizati
		n Location
Group 2 - Five Storage Blocks of Three Case Widths		Location Location Location Location S 2 2 4 5 5 Palletization Area for Palletizer 2
Five Storage Bl Case Widths		ion Locati 3 rea for Pa
2 - Five		ion Locat 4 ization A
Group		Locat

Figure 5: Components of the Palletizing Areas in the Simulation Model

can be potentially taken off of the loop. Those criterion are the case type, that is, type of product and the location of the palletizer at that time. The case type of the product is determined when the case is generated into the system by the different probability distributions. The current location of the palletizer is represented by the last case to be palletized. The last case to be palletized represents the current location of the palletizer because the palletizer takes the case off of the loop and places the case onto a pallet board and waits at that location until he or she decides on the next case to be picked up.

After the case travels one case width in the case takeoff area it is tested according to current case location on the loop, case type and current location of the palletizer. If the case meets all of the above criteria, a one is placed into a matrix to denote that that specific case in the group can be a candidate for case takeoff. The matrix is a 2 column by 15 row matrix. The two columns represent the two independent case take-off areas. The 15 rows represent the 15 potential cases in the case take-off areas. It is this matrix which stores the status of the 15 cases in the case take-off group. The one is placed into the matrix according to the given case number of the case in that group. This is a status record of a particular case in one of the two groups and is the basis from which the scan is made determine which case is the next case to be taken off of the loop. If a case travels through one location marker (one of

the five locations in a case take off area) to the next location marker and has met the criterion in the previous location marker, the matrix value is reset to zero to allow testing without retaining the status of the case at the previous location marker. It is this testing and recording procedure occurring throughout the length of the case take-off section that provides the model with the knowledge of which cases are in the proper postition for case take-off.

The above procedure explains how a potential candidate for case pick up is determined. It does not, however, explain how the case actually leaves the loop and consequencially leaves the system. There are four points in the simulation model that determine next case to he oalletized. These points are before a case enters each the two case take-off areas and immediately after a case palletized by one of the two palletizers. The cases flowing through the system at these points trigger the procedure used to determine the next case to be taken off of the loop. The first two testing areas are immediately after a case is palletized at the palletizers. The testing is done at this point to model the real-world situation. It is not until after a palletizer palletzed a case, that he then looks for the next case to be palletized. The second two testing areas just prior to each of the case take-off areas are triggered by any case traveling through that area. This is done to insure that there is an ongoing test being made to determine the next case to be palletized. If the test procedure were made at this point, an intital case would never be designated to be palletized. The second two testing areas provide a backup to the testing done after the case is palletized.

The basic procedure used to determine the next case to be palletized is by scanning the matrix to determine if any of the cases meet criteria to be palletized. The scan is performed on the case that had been in the group the longest. second longest, etc. which is determined from the last case number assigned in one of the two groups. If, for example, the last case number assigned in the group for palletizer 1 was number 10, the model will scan column 1 row 11 in the matrix to determine if the case has met the necessary criteria to be palletized. If, the case has met the criteria (it has a 1 in that postion in the matrix). the case will be marked in one of its parameters with a 1. The 1 marked in the parameter shows the system that this is the next case to be taken off of the palletizing loop to be palletized. Ιf column 1 row 11 has not met the criteria to be palletized, the model will check column 1 row 12 through column 1 row 10 it finds a case that meets the criteria palletization or until it ends the scan because no case the group meets the necessary criteria.

The actual marking of the cases is done through the use of the Alter block in conjunction with use of the Group. Using the Alter block and the Group enables the system to place a 1 in the designated parameter without necessitating the case to travel through an assign block to mark the

parameter.

Before a the testing procedure begins to determine the next case to be palletized, it must first be determined whether or not a case in the group is currently marked for pickup. This is done to insure that two cases are not marked at the same time for pick up. This again is where the Group is useful because it can enable the system to scan all the cases in the group to test for pick-up marking without needing the cases to travel through a block for the testing.

The cases are tested at every case width to determine whether the case has been marked for pickup. If the case has been marked and the palletizer is not busy, the case is transfered off of the loop to the palletizer. At the palletizer, the case is palletized for eight seconds which is based on the pre-set standard of 400 cases per manhour. After being palletized, the case is used to determine the next case to be palletized and tabulates some statistics about its travel on the palletizing loop.

A complete documentation of the computer program used to \mbox{model} the system is shown in Appendix A.

V. RESULTS

This section shows the results tabulated from the statistics generated from the different simulation runs made of the model. The overall plan of the simulation was to run the model at the various case per hour generation rates eight hour shift to deterime the effects on the palletizers when operating under the current system. The most important statisics gathered were the utilization of the first and second palletizers. Other statistics gathered were the interarrival times of the the cases as they go through the system and the mean number of times a case traveled around the palletizing loop before it was picked up to be palletized. The following tables show the information derived from the simulation runs and uses a reference point of the number of cases generated per hour into the system. Also shown are the number of cases palletized according to the number of cases generated into the systems.

Figures 6a, 6b and 6c, along with Table 3, show the results of the simulation runs with respect to the palletizer utilization or busy time, and the number of cases generated to each of the palletizers. The graph illustrates the break point, the point at which generating more cases into the palletizing loop does not increase the number of cases palletized by the palletizer. This point is at a case generation rate of approximately 435 cases per hour. Any case generation rate higher than 435 cases per hour will decrease the utilization of the the palletizer.

The overall utilization of the palletizers in the different scenarios, i.e. palletizer 1 utilization when run with palletizer 2, palletizer 2 utilization when run with palletizer 1 and palletizer 1 run alone show that running the palletizing loop with only palletizer 1 being fed is the most efficient use of a palletizer. The efficiency of palletizer 1 being run alone is 1.4% higher than that of the other two palletizer scenarios, the highest utilization factor being 95.8%. This seems to be intuitively correct that running with one palletizer is more efficient because the case flow to the palletizer is more consistent since all of the cases passing by the palletizer are palletizer specific. overall efficiency of palletizer 2 being run with palletizer 1 is lower than that of palletizer 1 being run with palletizer 2 and that of palletizer 1 being run alone. could be due to a higher wait time for palletizer 2 because the cases have to travel farther to reach the palletizer, and because of the gaps created by palletizer 1. The conclusion at this point is that palletizer 1 running alone has the greatest efficiency.

TABLE 3. UTILIZATION OF PALLETIZERS

CASES/HOUR	PALLETIZER 1	PALLETIZER 2
========	=========	=========
800	90.2%	86.4%
812	92.0%	88.6%
882	94.4%	85.0%
969	93.6%	90.0%
673	76.8%	73.2%
394	87.5%	
280	61.7%	
460	95.8%	
521	95.7%	

PALLETIZER UTILIZATION

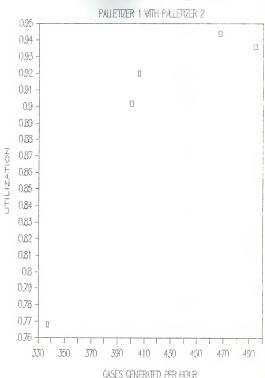


Figure 6a: Palletizer Utilization - Palletizer 1 with Palletizer 2

PALLETIZER UTILIZATION

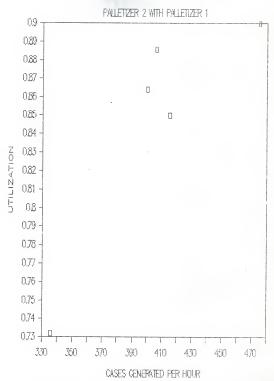


Figure 6b: Palletizer Utilization - Palletizer 2 with Palletizer 1

PALLETIZER UTILIZATION

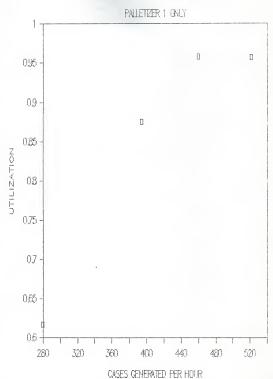


Figure 6c: Palletizer Utilization - Palletizer 1 Only

Figures 7a, 7b and 7c and Table 4 show the effects of the number of cases generated on the interarrival times of the cases as they go through the palletizing loop. The interarrival time is the time between two cases being palletized. The Figures show that the break point for the shortest interarrival times through is at approximately 435 cases per hour. At 435 cases per hour, the cases have the shortest interarrival times. At any higher case generation rates, the interarrival times increases. Again the graph shows that palletizer 1 has the shortest interarrival times and palletizer 2 with palletizer 1 has the overall longest interarrival times. The shortest average interarrival time for any of the simulation runs was palletizer 1 alone at 83.4 time units or 8.36 seconds. The results of interarrival times of the different simulation runs are consistent with that of the results of the efficiencies of the palletizers. The palletizer with the highest utilization is going to process more cases through the system per time interval.

TABLE 4. INTERARRIVAL TIMES OF CASES GOING THROUGH SYSTEM

	PALLETIZER 1		PALLETIZER 2	
CASES/HR	MEAN	STD. DEV.	MEAN	STD. DEV.
=======	====	========	====	
800	88.6	19.2	92.3	29.8
812	87.0	17.0	90.1	28.2
882	84.4	11.4	93.8	34.2
969	85.2	12.6	88.6	22.2
673	103.7	50.9	108.7	62.7
394	91.1	24.6		
280	129.1	92.5		
460	83.4	8.1		
521	83.6	8.5		

DALLETTIES 4

CASE INTERARRIVAL TIMES

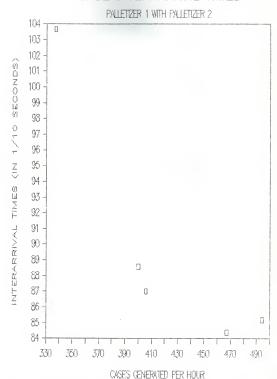


Figure 7a: Case Interarrival Times - Palletizer 1 with Palletizer 2

CASE INTERARRIVAL TIMES

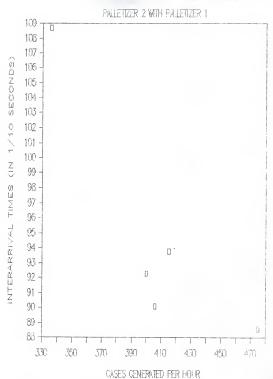


Figure 7b: Case Interarrival Times - Palletizer 2 with Palletizer 1

CASE INTERARRIVAL TIMES

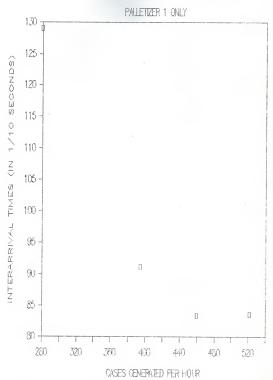


Figure 7c: Case Interarrival Times - Palletizer 1 Only

Figures 8a,8b and 8c and Table 5 show the results of the number of times a case travels around the palletizing loop versus the number of cases generated per hour. For the three model scenarios, the graph does not show a definite trend. What the graph does show is an upward trend in the number of times a case travels around the loop versus a greater number of cases generated into the loop. This is an intuitive conclusion; the more cases on the loop, the less chance of a case being picked up the first time around the loop. The Figures show that palletizer 2 run with palletizer 1 has the curve with the fewest average number of trips around the loop. Palletizer 1 alone has the greatest number of trips around the loop. This is consistent with the utilization factors of the palletizers in the different cases.

Because palletizer 2 run with palletizer 1 has the lowest utilization factor, it is capable of picking up more of the cases when they go by the first time. This graph also shows that with palletizer 1 alone, there is a faster increase in the number of times a case travels around the loop, as the number of cases per hour generated increases. shows a trade-off between the palletizer utilization and the number of times a case travels around the palletizing loop. The most important of these characteristics is palletizer utilization: the conveyor carrying the cases is already running for the system so there is no loss for having a case travel around the loop a few extra times. This is a concern, however, when the excess number of cases causes a backup in the palletizing system.

TIMES TRAVELED AROUND LOOP

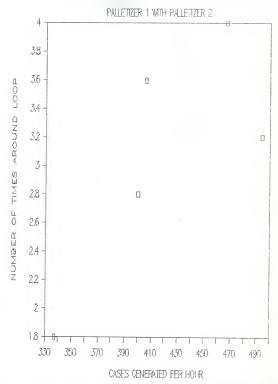


Figure 8a: Times Traveled Around Loop - Palletizer 1 with Palletizer 2

TIMES TRAVELED AROUND LOOP

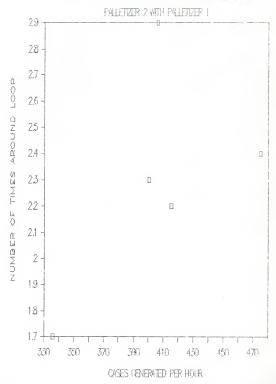


Figure 8b: Times Traveled Around Loop - Palletizer 2 with Palletizer 1

TIMES TRAVELED AROUND LOOP

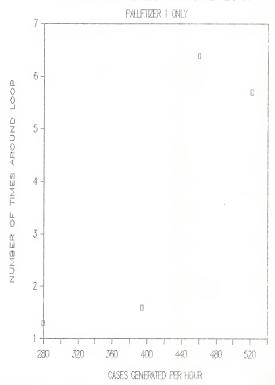


Figure 8c: Times Traveled Aruond Loop - Palletizer 1 Only

TABLE 5. NUMBER OF TIMES A CASE TRAVELED AROUND LOOP

	PALLETIZER 1		PALLE	PALLETIZER 2	
CASES/HR	MEAN	STD. DEV.	MEAN	STD. DEV.	
======	====		====	=======	
800	2.8	4.1	2.3	3.7	
812	3.6	5.5	2.9	4.1	
882	4.0	4.8	2.2	3.5	
969	3.2	4.3	2.4	3.5	
673	1.8	2.8	1.7	2.6	
394	1.6	2.6			
280	1.3	2.0			
460	6.4	8.8			
521	5.7	8.3			

Table 6 shows the relationship between the number of cases generated per hour versus the number of cases palletized per hour. The impact on the system shown by this table is two-fold. It shows that nearly all of the cases generated below an approximate 450 cases per palletizer per hour rate are palletized. Above that rate, there are excess cases in the system which are not being palletized. It should be mentioned that the palletizing time was a constant in this model which would not account for any speed up or slow down by a palletizer.

This table also shows a relative number of overflow cases in the system. The implication of this figure is that if too many cases are generated into the system, the system may back up because it is unable to handle all of the cases. The worst case of an overflow onto the loop is running the system with two palletizers where 973 cases are being generated per hour, and only 85% or 827 cases per hour are being palletized. This means that an average of 146 extra

cases are on the loop per hour.

The computer model was not developed with a shut off mechanism for an overflow of cases on a palletizing loop, but was developed with a maximum capacity of 95 cases on the loop at any one time. Although this simulation with 973 cases per hour being generated may appear to show a backup condition on the palletizing loop, in actuality the loop is controlled by photocells. These photo cells control the number of cases allowed on the palletizing loop thus for the most part control any backup on the palletizing loop.

Table 6. Number of Cases Palletized

Cases/Hour Generated	Cases/Hour Palletized	Percent Cases Palletized of Generated Cases
========	========	=======================================
800	794.8	99.3%
812	811.9	99.9%
882	808.5	92.1%
969	827.3	85.0%
673	669.1	99.5%
394	393.4	99.5%
280	277.5	99.5%
460	430.5	93.2%
521	429.9	83.1%

The above results are based on the input production schedules generated into the model. The schedule itself, or the number of cases generated by the production schedule, are the basis of the results tabulated. Therefore, it is the production schedule which determines the overall productivity of the palletizer. If the palletizers are scheduled a suboptimal number of cases per hour, their overall utilization will also be sub-optimal.

VI. CONCLUSIONS

Overall, the results of the simulation runs have proven to be a realistic model of the actual palletizing system in the Frito-Lay plant. The model has shown a maximum number of cases per hour to be approximately 435 cases per man hour, which is very close to the predetermined standard of 400 cases per manhour. This fact, as well as the other results described in the previous section, support the model as being a realistic representation of the palletizing system.

There are five main conclusions that can be made from this simulation model of the palletizing system. First, there is a break point in generating cases onto the palletizing loop where there is a diminishing return in generating additional cases onto the loop. This break point is approximately 435 cases per hour per palletizer. Any case generation rate above this, according to a constant palletizing rate, will not increase the number of cases palletized per hour. And, in fact, may decrease the number of cases that can be palletized per hour by a palletizer.

Second, using two palletizers on a palletizing loop is not as efficient as one palletizer working alone. This was shown in the results of the palletizer utilization (See Table 3 and Figures 6a through 6c) for different model scenarios. If each of two palletizers is assigned specific cases to palletize, the setup of the loop determines that there will be cases passing each palletizer that are not their responsibility to palletize. This mixing of cases that are

assigned for palletizing to specific palletizers makes it such that there are inherent delays in a two palletizer per loop setup.

Third, that palletizer 2 is not as efficient as palletizer one in any scenarios. Palletizer 2 has an overall longer waiting time for cases to come to him or her in relation to the position of palletizer 1. Also, palletizer 2 is farther away from the case infeed area onto the loop, thus supplementing the cases recirculating with newly produced or generated cases takes longer than it does for palletizer 1.

Fourth, that there are inherent delays in product flow built into the current palletizing system. Even running the model with only one palletier, the maximum utilization of palletizer 1 was 95.8%. This maximum utilization can be attributed to start up time or the time to bring the system into a state of equilibrium. This maximum utilization limit can also be attributed to the manner in which the product is fed to the palletizer. Even with a maximum number of cases on a palletizing loop, there is some waiting involved in picking a case off of the palletizing loop. There are also gaps or delays in the product flow on the palletizing loop.

The final conclusion that can be made from the model is that the production schedule is the most important input into the productivity of an individual palletizer. If the production schedule starves the palletizer, he or she will have a low utilization for the shift. Conversely, if the production schedule floods the palletizer, the he or she will

not be capable of palletizing the cases on the loop, and the loop may experience a backup condition.

VII. RECOMMENDATIONS

The results from the study show two recommendations to current palletizing system. The first of recommendations is running a single palletizer on a palletizing loop whenever possibly for a higher palletizer productivity. The second recommendation is to schedule the palletizer workload at at least 435 cases per hour to fully utilize the palletizer. This optimally scheduled workload is achieved by combining the scheduled package case per hour output for the different products flowing onto palletizing loop to achieve the 435 cases per hour output and assigning these packages to an individual palletizer. The ability to optimally schedule the workload of the palletizer is dependent on the production schedule assigned to be run for the day. Therefore, the productivity of the palletizers basically lies in the control of the production schedule and should be an accountability of the production scheduler.

With the recommendation of utilizing one palletizer per loop, one would expect that the current palletizing loop sizes would be too large. Further study could determine what an optimal loop size for a single palletizer would be.

Also, in trying to optimally schedule the workload of a palletizer, if more flexibility existed in what packages could be fed onto what loop, there may be an opportunity for increased overall palletizer utilization. Further study would need to be conducted to determine the opportunity in this recommendation.

The final question to be answered in reference to this palletizing system is whether or not this system is the most optimal system for a case flow process. It would be possible to have a laser scanner sort the cases as they come onto the palletizing loop into case storage lanes, and the palletizer could walk from lane to lane emptying the cases onto the pallet boards. Taking this idea one step further, instead of having the palletizer empty the cases in the lanes onto the pallet boards, have automatic palletizers performing this function. Finally, in a product flow situation such as that at Frito-Lay, Inc., would it be necessary to have the cases, which are coming from different packaging machines running different products, be mixed together onto one conveyor and then sorted at the end of the same conveyor? This study does not have the scope to answer questions such as these, but future study of these concepts may provide some interesting results to these questions.

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APPENDIX A

:ELEASE 1.0 (E8233A) 1 MAP 85 14:38:21 FILE: PALT

DU BLUCK# *LOC OPERATION A.B.C.D.E.F.G CLIMENTS

4

LEAVE

CUNVL

```
SIMULATE
        PEALLOCATE COM. 20000
        STORAGE
                 $$CONVL.35/$$DECAL,15/$$DECA2.15
        STUPAGE
                  $$DEC1.3/$$DEC2.3/$$DEC3.3/$$DEC4.3/$$DEC5.3
        STORAGE
                  $$DEC12,3/$$DEC22,3/$$DEC32,3/$$DEC42,3
                 S$DEC 52 .3
        STORAGE
                                      FOR PALT 162 DLCIS. AREAS
                   S$TRT1.15/S$TPT2.15
        STUPAGE
 * DECISION AREAS 1 - 5 HAVE CAPACITY OF THREE
 1
       MATRIX MX.15.2
   INITIALIZING MATRIX FOR DECISION PURPOSES
        INITIAL
                  XH1.1
        INITIAL
                  XH2 . 8
                  XH3 .4
        INITIAL
 CASTP FUNCTION
                  RN2 , D6
                                            ASSIGNS CASE TYPE
0.167,1/0.334,2/0.501,3/0.668,4/0.875,5/1.00.6
       FUNCTION XH1-4L3
                                            *LUWER PANGE VALUES FOR
 .1/.1/.2
                                             DECISION RULES. INPUT
 3
       FUNC TI UN
                 XH1,L3
                                            =LAST PALT LOC. AND FN
 .2/.2/.2
                                            NO = CASE TYPE + 1. DUT-
       FUNCTION
                  XH1,L3
                                            PUT = LEWER BOUND FUR
, 2/, 3/, 3
                                            PICKUP.
 5
       FUNCTION
                  XH1.13
                                            UPPER RANGES VALUES FOR
,3/,3/,4
                                            DECISION RULES. INPUT
       FUNCTION
                  XH1,L3
                                            =LAST PALT LCC. AND FN
.41.41.4
                                            NO = CASE TYPE + 1. OUT-
 7
      FUNCTION
                  XH1.L3
                                            PUT = LCKER SCUND FOR
.4/.5/.5
                                            PICKUP.
 8
       FUNCTION
                P82.L5
.DFC1/.DEC2/.DEC3/.DEC4/.DEC5
                                           PEMOVES TRANS FROM PICAC
 Q
       FUNCTION
                  PB2 + L5
. DEC 12/. DEC 22/. DEC 32/. DEC 42/. DEC 52
                                           PEMOVES TRANS FROM PRICAC
1.0
      FUNCTION
                 XH3,D3
                                            LOWER PANGE PALT PU 2
4,1/5,1/6,2
11
      FUNCTION
                  XH3, D3
4,2/5,2/6,2
12
      FUNCTION
                 XH3.D3
4,2/5,3/6,3
13
      FUNCTION
                XH3.D3
                                           UPPEP RANGE PALT PU 2
4,3/5,3/6,4
14
      FUNCTION
                XH3 • D3
4,4/5,4/6,4
15
      FUNCTION.
                X113, D3
4,4/5,5/6.5
     BVARIABLE PB1"E"1 *FNUSPALT
                                           CASE MAPKED & PALT NOT USE
      BVARIABLE PB1 *E* 1 *FNU $PALT?
 2
 1
      VARIABLE
                 PH1+1
                                           LOWER BOUND EN PEFERENCE
 2
      VARIABLE
                 PH1 +4
                                           UPPER BLUTC EN PEFERENCE
 3
      VARIABLE PH1+6
                                           LOWER BD FN REFERENCE P2
      VARIABLE PHI+9
                                           UPPER NO EN REFERENCE P2
      GENERATE
                 45.5...3PB.2PF.1PH
                                          GENERATES TRANS. INTO LOJP
      ASSIGN
                 1.FNSCASTP.PII
AGAIN ENTER
                 CONVL
                                           ADVANCE TIME FOR THE REMAIN-
      ADVANCE
                 339
```

DER OF LUCP OUT OF PALT.S

REACH . 40FT AND 25 CASES

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TEST L
                      PH1 . 4 . TRV1
                                                 TESTS FUR CASE TYPE
  7
            ENTER
                      DECAR
                                                LITERS PALT. DECISION AREA
  я
            TEST L
                      XB1 .15 . ZZ Z
                                                LAST PKG NC < 15
  9
            SAVEVALUE 1+.1.XB
                                                LAST PKG + 1 ASSIGNED
 10
                      .YYY
            TRANSFER
                                                GCES TO STOPE PKG NO
 11
      ZZZ
          SAVEVALUE 1.1.XB
                                                ASSIGNS PKG NC TO 1
 12
      YYY
            ASSIGN
                       2.XB1.PF
                                                ASSIGNS PKG NC TO TRANS
 13
            MIDL
                                                JOINS DECISION GROUP 1
 14
            SCAN E
                      I.IPB.I...DETEM
                                                SCANS THE DEC SPOUP TO
 15
16 DETRM ASSIGN 1-15-PF
TEST L XB1-15-9K1
                                                GC TO DECISION AREA ONE
                                                LOUPING PAPAMETER
                                                IF POINTER= 15. BACK TO I
            TEANSEER
                      *ASXB3
                                                TRANS TO XE3 ASSIGNMENT
 19
           SAVEVALUE 3.1.XB
    BK 1
                                                GIVES XB3 VAL OF 1 FRCM 13
 20
                      • G O G
           TRANSFER
                                                TRANSFERS TO LOOP TEST
 21
     ASXB3 SAVEVALUE 3.XB1.XB
                                                ASSIGNS XB1 = XB3
 22
           SAVEVALUE 3+.1.XB
                                                INCPEMENTS X83 BY 1
 23
    GOG
           TEST G
                      PF1.0.NXT
                                               HAS TRANS LCCPED 15 TIMES
                    MX1 (XB3.1), 0. [C]
 24
           TEST E
                                               TESTS FOR VAL OF 1 IN MX1
 25
           TEST L
                     XB3 •15 • HCH
                                               TESTS FUL XE3=15
 26
           SAVEVALUE 3+.1.XB
                                                INCREMENTS XB3 FOR TEST
 27
           ASSIGN
                     1-.1.PF
                                                DEC. LOOPING PARAMETER
 28
           TRANSFER
                      • 606
                                                TRANSFERS BK TO TEST
29
    HOH SAVEVALUE 3.1.XB
                                                ASSIGNS XB3=1 IF PREV=15
30
                      1- .1 .PF
           ASSIGN
                                                DEC. LOOPING PARAMETER
31
           TRANSF EP.
                      • GOG
                                                TRANSFERS BK TO TEST
          ALTER E
3.2
    101
                     1.1.128.1.22F.X83.NXT
                                                *ARKS IF PKG NO=XB2
33
     NXT
          BUFFER
                                                RELEASE PAITR
    * AS THE CASE ENTERS A DECISION APEA IT TRAVELS A TOTAL OF 3.5 FEET.
      THE AREA IS DIVIDED INTO THICE AREAS IN ALLOW FOR THE TESTING
    * PROCEDURE. THE TOTAL TRAVEL TIME IS 5.3 SECONDS.
34
     ADV1 ENTER
                   DEC1
35
           ASSIGN:
                     2++1.PB
36
           ADVANCE
                     XH2
37
           TEST GI
                   PB2.FN*V1.XXX
PB2.FN*V2.XXX
3 B
           TEST LE
39
           MSAVEVALUE 1.PF2.1.1.MX
40
          TEST E BVI.O.PALTP
ADVANCE XH2
41 XXX ADVANCE
                   PB2 . FN * V1 . WWW
PB2 . FN * V2 . WWW
42
          TEST GE
43
           TEST LE
          MSAVEVALUE 1.PF2.1.1.MX
44
45
          TEST E BV1.0. PALTP
46
   WWW
          ADVANCE
                    XH2
47
          TEST GE PB2.FN*V1.VVV
48
          TEST LE
                    PB2 • FN * V2 • VVV
49
          MSAVEVALUE 1.PF2.1.1.MX
   VVV
50
          ENTEP DEC2
51
          ASSIGN
                    2++1+PB
                                              ENTERS DECISION AREA TWO
52
                    DEC 1
          LEAVE
53
          TEST E
                     BV1 . O . PALTE
54
          MSAVEVALUE 1.PF2.1.0.4X
55
          ADVANCE XH2
56
          TEST GE
                    PB2.FN*V1.UUU
57
          TEST LE PB2,FN*V2,UUU
58
          "SAVEVALUE 1.PE2.1.1.MX
```

ILFASE 1.0 (EB233A) 1 MAR 85 14:38:21 FILE: PALT

TO BLOCK# *LOC OPERATION A.B.C.D.E.F.G (CMMEMTS

```
59
              TEST E
                           PVI.O.PALTE
  60
       UUU
              ADVANCE
                          XH2
              TEST GE
                          PB2.FN # VL. ITT
  61
  62
              TEST LE
                           PB2.FN*V2.TTT
  63
              MSAVEVALUE 1.PF2.1.1.MX
  64
              TEST E
                          BV1.0.PALTP
  65
       TTT
              ADVANCE
                          XH2
  66
              TEST GE
                          PB2.FN*V1.SSS
  67
              TEST LE
                          P82, FN*V2, SSS
  68
              MSAVEVALUE 1.PF2.1.1.MX
  69
       SSS
              ENTER
                          CEC3
  70
              ASSIGN
                           2+ + 1 + PB
                                                        ENTERS DECISION AREA THRES
  71
              LEAVE
                          DEC2
  72
              TEST F
                          BV1 . O . PALTR
 73
              MSAVEVALUE 1.PF2.1.0.MX
 74
              ADVANCE
                          XH2
 75
              TEST GE
                          PB2+FN*V1+P.RR
 76
              TEST LE
                          P82 . FN * V2 . PPP
 77
              MSAVEVALUE 1.PF2.1.1.MX
 7.8
              TEST E
                          BV1.0.PALTR
 79
       RPP
              ADVANCE
                          XH2
 a٥
              TEST GE
                          P82,FN*V1,000
                          PB2 . FN * V2 . COO
 81
              TEST LE
 82
              MSAVEVALUE 1.PF2.1.1.MX
 83
              TEST E
                          BV1.0.PALTR
 84
       000
              ADVANCE
                          XH2
 85
              TEST GE
                          PB2,FN*V1,PPP
 86
              TEST LE
                          PB2 . FN * V2 . PPP
 87
              MSAVEVALUE 1.PF2.1.1.MX
 88
       DDD
              ENTER
                          CEC4
 89
              ASSIGN
                          2+,1,PB
                                                      ENTERS DUCISION AREA 4
 90
              LEAVE
                          DEC 3
 91
              TEST E
                          BVI.O. PALTR
 92
              MSAVEVALUE 1.PF2.1.0.MX
 93
              ADV ANC E
                          XH2
 94
              TEST GE
                          PB2 ,FN* V1 ,UOO
 95
             TEST LE
                          PB2.FN*V2.000
 96
              MSAVEVALUE 1.PF2.1.1.MX
 97
             TEST E
                          PV1 . O. PAL TR
 98
       CUC
              ADVANCE
                          XH2
 22
             TEST GE
                          PB2 . FN * VI . NNN
100
             TEST LE
                          P82 + FN * V2 + NNN
101
             MSAVEVALUE 1. PF2.1.1. MX
102
             TEST E
                          BV1.0. PALTR
      MM
             ADVANCE
                          XH2
104
             TEST GE
                          PB2 . FN* V1 . MMM
105
             TEST LE
                          PB2.FN*V2.MMM
106
             MSAVEVALUE 1, PF2, 1,1, MX
107
      ммм
             ENTER
                          DEC 5
                                                       ENTERS DECISION APEA FIVE
108
             ASS1GM
                          2+,1,PB
109
             LEAVE
                          DEC 4
                          BV1.0.PALTE
110
             TEST F
111
             MSAVEVALUE 1.PF2.1.0.MX
112
             ADVANCE
                          XH2
113
             TEST GE
                          PB2.FN+V1.LLL
114
             TEST LE
                         PB2.FN*V2.LLL
```

LEASE 1.0 (EB233A) 1 MAR 85 14:38:21 FILE: PALT OF BLOCK# *LOC OPERATION A.B.C.D.E.F.G COMMENTS 115 MSAVEVALUE 1.PF2.I.1.MX 116 TEST E BV1.0.PALTP TEST GE PB2.FN*VI.KKK TEST LE PR2.FN*VI.KKK 117 LLL 118 119 120 MSAVEVALUE 1.PF2.1.1.MX 121 TEST E BV1.0.PALTP KKK ADVANCE 122 XH2 123 TEST GE PB2.FN*V1.JJJ TEST LE PB2.FN*V2.JJJ 124 125 MSAVEVALUE 1.PF2.1.1.MX 126 JJJ TEST E BV1.0.PALTE 127 MSAVEVALUE 1, PF2, 1,0, MX 128 LEAVE DEC 5 129 REMOVE REMOVES ALL TRANS FROM GROUP 130 LEAVE DECAR LEAVES THE DECISION AREA 131 ASS I GN 2.0.PB ASSIGNS DECISION AREA TO 0 132 3+,1.PB ASSIGN COUNTS THE NO OF TIMES LOOPE 133 .CONT TRANSFEE. TRANSFERS TO BEG OF LOGP 134 TRV1 SAVEVALUE 1+,1,XB 135 ENTER TRT1 136 ADVANCE 120 137 LEAVE TRTI 138 TRANSFER , CONT * THIS SECTION IS REPRESENTS THE PALLETIZER. THERE ARE THE ASSUMPTIONS MADE FOR THE OPERATION OF THE PALLETIZER. THE ASSUMPTIONS ARE THAT * THE PALLETIZER WILL ALWAYS PE ABLE TO PICK UP A CASE IF HE DECIDES TO TO DO SC AND THAT THERE WILL BE AN AVERAGE PALLETIZING TIME ASSUME) * WITH A DISTPIBUTION. THIS WILL BE MADE BECAUSE THE DECISION AREAS OF THE SAME LENGTH. ACCURDING TO CASE TYPE 139 PALTR SEIZE PALT CASE SEIZES PALTE 140 SAVEVALUE 1, PH1, XH ASSIGNS PALLETIZER LOC 141 LEAVE DECAR LEAVES DECAR 142 LEAVE FN8 LEAVES CURRENT DECI-5 143 ADVANCE 80.10 ADVANCES FOR PALLETIZING 144 MSAVEVALUE 1, PF2, 1,0, MX SETS MATRIX TO 0 145 REMOVE 1 TAKES CASE FROM GROUP 146 SCAN E 1.1PB.0... ## XT SCANS TO SEE IF TPANS MKD ASSIGN 147 1.15.PF LOOPING PAPAMETER 148 TEST I X81,15,8KTU1 IF POINTER=15. BACK TC 1 149 TRANSFER ASXB2 150 BKTU1 SAVEVALUE 2,1,XB TRANS TO XB2 ASSIGNMENT GIVES XB2 VAL OF 1 FRCM 15 151 TRANSFER .GGG ASXB2 SAVEVALUE 2,XB1,XB TRANSFERS TO LOCP TEST 152 ASSIGNS XAI=XA2 153 SAVEVALUE 2+, 1, XP INCREMENTS XB2 BY 1 GCC TEST G 154 PF1.0.NEXT HAS TRANS LOUPLD IS TIMES 155 TEST E MX1(XB2.1).0.111 TESTS FOR VAL OF 1 IN MXI 156 TEST L TESTS FCR Y82=15 X82,15, HHH 157 SAVEVALUE 2+.1.XB INCREMENTS X82 FOR TEST 158

DEC. LUCPING PAPAMETER

DEC. LOGPING PARAMETER

ASSIGNS XB2=1 IF PREV=15

TRANSFERS BK TO TEST

TRANSFERS BK TO TEST

MAPKS IF PKG NO=XE2

ASSIGN

TRANSFER

ASSIGN

159

160

161

162

163

14441

1-,1.PF

1-,1,PF

TRANSFER .GGG
III ALTER E 1.1.1PB.1.2PF.KB2.MEXT

• GGG

SAVEVALUE 2.1.XB

```
DO BLOCK# *LOC OPERATION A.B.C.D.E.F.; CUMMENTS
      164
                TRANSFER
                          , NEXT
      165 NEXT RELEASE
                          PALT
                                                  RELEASE PALTE
      166
                TABULATE
                          1
      167
```

CASE TYPE TABULATE INTERAPRIVAL TIME 168 TABULATE SAVEVALUE XHI 169 TABULATE RECIRCULATING TIMES 170 TABULATE CASE MAFKED WHEN P-U 171 TERM INATE

* ENTERING THE SECOND DECISION AREA. THIS DECISION AREA OPERATES THE SAME AS DECISION AREA I

PH1.3.TRV2 173 ENTER CECA2 174 TEST L X84,15,ZZZZ 175 SAVEVALUE 4+,1,XB YYY2 176 TRANSFER 177 ZZZZ SAVEVALUE 4.1.XB 178 YYY2 ASSIGN 2.X84.PF 179 NIOL 2. 1PB.1...DETR2 180 SCAN F TRANSFER ,ADV12 181 182 DETR 2 ASSIGN 1,15,PF 183 TEST L X84,15,8K12 184 .ASXB6 TRANSFER 185 BK12 SAVEVALUE 6.1.XH TRANSFER .GOG2 SAVEVALUE 6+,1,XB TEST E MX1(X86,2),0,1012

172

199

200

201

202

203

204 205

208

209 210

211

CDET TEST G

186 186 ASXB6 SAVEVALUE 6.X84.X8 189 GUG2 TEST G PF1.0.NXT2 190 191 X86,15,HOH2 TEST 1 SAVEVALUE 6+,1,XB 192 TRANSFER 1-,1,PF 193 194 195 HUHZ SAVEVALUE 6,1,XB 196 ASSIGN 1-,1,PF 197 TRANSFER • GD G 2 198

1012 ALTER E 2,1,1P8,1,2PF, YEC, NXT2 NXT2 BUFFER * AS THE CASE ENTERS A DECISION AREA IT TRAVELS A TOTAL OF 3.5 FEET. THE AREA IS DIVIDED INTO THREE AFEAS TO ALLOW FOR THE TESTING PROCEDURE. THE TOTAL TRAVEL TIME IS 5.3 SECONDS.

ADV12 ENTER DEC12 ASSIGN 2+,1,PB ADVANCE XH2 TEST GE PB2+FN*V3+XXX2 P32+FN*V4+XXX2 TEST LE MSAVEVALUE 1.PF2.2.1.MX 206 TEST E EV2.0.PLTP2 207 XXX2 ADVANCE XH2 TEST GE PB2,FN*V3,WWW2
TEST LE PB2,FN*V4,WWW2

MSAVEVALUE I.PF2, 2,1.MX TEST E 8V2.0.PLTR2 212 WHIZ ADVANCE XH2

ENTERS PALT. DECISION AREA LAST PKG NO < 15 LAST PYC + 1 ASSIGNED GOES TO STORE PKG NO ASSIGNS PKG NC TC I ASSIGNS PKG NO TO TRANS JOINS DECISION GROUP 1 SCANS THE DEC GROUP TO GO TO DECISION AREA ONE LCOPING PARAMETER IF POINTER=15, BACK TO 1 TRANS TO XB3 ASSIGNMENT GIVES XB3 VAL CF I FROM 15

TRANSFERS TO LUCP TEST ASSIGNS XB1=X83 INCREMENTS X83 BY 1 HAS TRANS LCOPED 15 TIMES TESTS FOR VAL OF 1 IN MX1 TESTS FOR X83=15 INCREMENTS XB3 FOR TEST DEC. LOOPING PARAMETER

TRANSFERS BK TC TEST ASSIGNS X83=1 IF PREV=15 DEC. LOOPING PARAMETER TPANSFERS BK TO TEST MARKS IF PKG NO=XH2 RELEASE PALTR

57

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DO BLUCK# *LOC OPERATION A.B.C.D.E.F.G COMMENTS

266

267

268

TEST LE

TEST E

```
TEST SE
 213
                          PB2.FN*V3.VVV2
 214
              TEST LE
                          PB2.FN* V4. V VV?
 215
              MSAVEVALUE 1.PF2.2.1.MX
 216
       VV V 2
              ENTER
                          DEC22
 217
              ASSIGN
                           2+.1.PB
                                                       ENTERS DECISION AREA THO
 218
              LEAVE
                           DEC12
 219
              TEST E
                          BV2.0.PLTR2
220
              MS AV EVALUE 1.PF2.2.0.MX
 221
              ADVANCE
                          XH2
222
              TEST GE
                          PB2,FN*V3,UUU2
              TEST LE
223
                          PB2 . FN * V4 . UUU 2
224
              MSAVEVALUE 1.PF2,2,1,MX
225
              TEST E
                          EV2.0.PLTR2
226
       UUU2 ADVANCE
                          XH2
              TEST GE
                          P82.FN*V3.TTT2
228
              TEST LE
                          PB2 . FN * V4 . TTT?
229
              MSAVEVALUE 1, PF2, 2, 1, MX
230
              TEST E
                          BV2.0.PLTR2
231
       TTT2 ADVANCE
                          XH2
232
              TEST GE
                          PB2 • FN * V3 • SSS2
233
              TEST LE
                          PB2 .FN* V4 . SSS2
234
              MSAVEVALUE 1.PF2.2.1.MX
235
       SSS2
             ENTER
                          DEC32
             ASSIGN
236
                          2+ . 1 . P B
                                                        ENTERS DECISION AREA THREE
237
              LEAVE
                          DEC22
238
              TEST E
                          BV2.0.PLTR2
239
             MSAVEVALUE 1.PF2,2,0,MX
240
             ADVANCE
                          XH2
241
                          PB2, FN*V3, RPP2
             TEST GE
242
             TEST LE
                          P82 . FN * V4 . RRP 2
243
             MSAVEVALUE 1.PF2.2.1.4X
244
                          BV2.0.PLTR2
             TEST E
245
       RPP2
             ADVANCE
                          XH2
246
              TEST GE
                          PB2,FN*V3,C002
247
             TEST LE
                          PB2 . FN * V4 . CCC?
248
             MSAVEVALUE 1.PF2.2.1.MX
249
             TEST E
                          BV2.0.PLTRZ
250
      0002
             ADVANCE
                          XH2
251
             TEST GE
                          PB2.FN*V3.PPP2
252
             TEST LE
                          PB2.FN*V4.PPP2
253
             MSAVEVALUE 1.PF2.2.1.MX
       PPP2
254
             ENTER
                          DEC42
255
                                                       ENTERS DECISION AREA 4
             ASSIGN
                          2+ + 1 + PB
256
             LEAVE
                          DEC 32
257
             TEST E
                          BV2.0.PLTR2
258
             MSAVEVALUE 1.PF2.2.0.MX
259
             ADVANCE
                          XH2
260
             TEST GE
                          PB2 - FN * V3 - GCG2
261
             TEST LE
                          PB2, FN*V4, UCC2
262
             MSAVEVALUE 1.PF2.2.1.MX
             TEST E
263
                          BV2.0.PLTP2
      COC2
264
             ADVANCE
                         YH2
265
             TEST GE
                          PB2 , FN * V3 , NAN2
```

PB2.FN*V4.NNN2

PV2. O. PLTP 2

MSAVEVALUE 1, PF2, 2,1, MX

JO BLOCK# *LOC OPERATION A.B.C.D.L.F.G COMMENTS

```
NNN2 ADVANCE
269
                           XH2
                           PB2, FN * V3, MMM 2
270
              TEST GE
271
              TEST LE
                            PB2 . FN*V4 . MMM2
272
              MSAVEVALUE 1.PF2.2.1.MX
273
              ENTER
                           05052
                                                         ENTERS DECISION AREA FIVE
274
              ASSIGN
                            2+,1,PB
275
              LEAVE
                           DEC 42
276
              TEST E
                           BV2 . O . PLTR2
277
              MSAVEVALUE 1.PF2,2.0, MX
278
              ADVANCE
                           XH2
279
              TEST GE
                           PR2. FN + V3.1112
280
              TEST LE
                           PB2.FN*V4.LLL2
281
              MSAVEVALUE 1.PF2.2.1.MX
282
              TEST F
                           BV2.0.PLTR2
283
       LLL2 ADVANCE
                           YH2
284
              TEST GE
                           PR2.FN*V3.KKK2
285
              TEST LE
                           PB2 . FN: * V4 . KKK2
286
              MSAVEVALUE 1. PF2.2.1. MX
287
              TEST F
                           EV2.0.PLTR2
288
       KKK2
              ADVANCE
                           YH2
289
              TEST GE
                           PB2.FN*V3.JJJ2
290
              TEST LE
                           PB2 • FN * V4 • JJJ ?
291
              MSAVEVALUE 1.PF2.2.1.MX
       JJ J2
              TEST E
                           BV 2 . 0 . P1 TR 2
293
              MSAVEVALUE 1.PF2.2.0.MX
294
              LEAVE
                           DEC52
205
              REMOVE
                                                          REMOVES ALL TRANS FROM GROUP
296
              LEAVE
                           DECA2
                                                          LEAVES THE DECISION APEN
297
              ASSIGN
                           2.0.PB
                                                          ASSIGNS DECISION AREA TO )
298
                                                          COUNTS THE NO OF TIMES LODPE
              ASSIGN
                           3+.1.PB
299
              TRANSFER
                           . AGAIN
                                                         TRANSFERS TO BEG OF LCCP
300
       TR V2 SAVE VALUE
                           4+ . 1 . XB
301
              ENTER
                           TRT2
302
              ADVANCE
                           120
303
              LEAVE
                           TRT2
304
              TRANSFER
                          . AGAIN
        THIS SECTION IS REPRESENTS THE PALLETIZER. THERE ARE TWO ASSUMPTIONS MADE FOR THE OPERATION OF THE PALLETIZER. THE ASSUMPTIONS ARE THAT THE PALLETIZER WILL ALMAYS BE ANLE TO PICK UP A CASE IF HE DECIDES TO
        TO DO SO AND THAT THEPE WILL BE AN AVERAGE PALLETIZING TIME ASSUME)
        WITH A DISTRIBUTION. THIS WILL BE MADE BECAUSE THE DECISION AREAS
        OF THE SAME LENGTH.
                                                          ACCORDING TO CASE TYPE
```

305 PLTR2 SEIZE PALT2 CASE SEIZES PALTR 306 SAVEVALUE 3.PHI.XH ASSIGNS PALLETIZER LOC 307 LEAVE DEC A2 LEAVES DECAR 308 LEAVE ENIG LEAVES CUPPENT DEC1-5 309 ADVANCE 80.10 ADVANCES FOR PALLETIZING 310 MSAVEVALUE 1.PF2.2.0.MX SETS MATRIX TO D 311 REMOVE TAKES CASE FROM GROUP 312 SCAN E 2.1P8.0...*IEXT2 SCANS TO SEE IF THANS MKJ 313 ASSIGN 1.15.PF LOUPING PAPAMETER 314 TEST L X84.15.8KTC2 IF POINTER= 15. BACK TO 1 315 TRANSFER , ASXB5 TRANS TO XB2 ASSIGNMENT 316 BKTO2 SAVEVALUE 5.1.XR GIVES XB2 VAL OF I FREM 15 317 TRANSFER •GGG2 TRANSFERS TO LOCP TEST

DO BLOCK# *LOC OPERATION A.B.C.D.E.F.G COMMENTS

```
ASX85 SAVEVALUE 5.X84.X8
                                                    ASSIGNS X81=X92
318
            SAVEVALUE
                        5+ , 1 , XB
                                                    INCREMENTS XB2 BY 1
319
                                                    HAS TRANS LCCPED 15 TIMES
320
      GGG2
            TEST G
                        PF1.0. NEX T2
                        MX1(XB5,2),0,1112
                                                    TESTS FOR VAL OF 1 IN MKI
321
            TEST E
                                                    TESTS FOR X82=15
            TEST L
                        XB5.15.HHH2
322
                                                    INCREMENTS XU2 FOR TEST
323
            SAVEVALUE
                        5+.1.XB
                                                    DEC. LOCPING PARAMETER
            ASSIGN
                         1-.1.PF
324
                                                    TRANSFERS BK TO TEST
325
            TRANSFER
                         •GGG2
                                                    ASSIGNS X82=1 IF PPEV=15
326
      HHH2
            SAVEVALUE
                        5 . 1 . X8
                                                    DEC. LUCPING PARAMETER
                        1-.1.PF
327
            ASSIGN
                                                    TRANSFERS BK TO TEST
                         ,GGG2
32B
            TRANSFER.
329
      III2 ALTER E
                         2,1,1P8,1,2PF,XB5,NEXT2
                                                    MAPKS IF PKG NC=XB2
                        NEXT2
330
            TRANSFER
                        PAL T2
                                                    RELEASE PALTR
331
      NEXT 2 RELEASE
                                                    CASE TYPE
332
            TABULATE
                        6
                                                    INTERARRIVAL TIME
333
            TABULATE
                        7
                                                    SAVEVALUE XHI
334
            TABULATE
                        8
                        q
                                                    RECIRCULATING TIMES
335
            TABULATE
                                                    CASE MARKED WHEN P-U
336
            TABULATE
                        10
337
            TERMINATE
                        288000
                                                    ONE HOURS TIME
338
            GENERATE
                                                    TEPMINATE SIMULATION
339
            TERMINATE
            TABLE
                        PH1 -1 -1 -4
                        IA, 10, 10, 15
      2
            TABLE
      3
                        XH1.1.1.4
            TABLE
      4
            TABLE
                        PB3.0.1.8
      5
            TABLE
                        PB1.0.1.3
      6
            TABLE
                        PH1 +4+1+4
      7
                        IA. 10. 1C. 15
            TABLE
      8
            TABLE
                        XH3.4.1.4
      9
            TABLE
                        P83.0.1.8
      10
            TABLE
                        PB1.0.1.3
            START
                        1
            END
```

A COMPUTER SIMULATION OF THE PALLETIZING SYSTEM AT FRITO-LAY, INC. IN TOPENA, EDGERGE

by

DEANDRA TILLMAN CASSONE

B.S., Kansas State University, 1982

AN ABSTRACT OF A MASTER'S THESIS

submitted in partial fulfillment of the

requirements for the degree

MASTERS OF SCIENCE

Department of Industrial Engineering

KANSAS STATE UNIVERSITY.

1985

ABSTRACT

At Frito-Lay, Inc. in Topeka, Kansas a conveyorized palletizing system was installed to transfer product from the packaging floor to the shipping warehouse. The purpose of this study was to optimize the current operation of this system. Data was gathered on the operating characteristics of this system and a simulation model was developed using the programming language GPSSH. The results of the simulation model showed the following conclusions. The model was a realistic representation of the current system. Based on a 8 second per case palletizing time, the maximum number of cases per hour to be generated to one palletizer was approximately 435 cases per manhour and that there is a diminishing return beyond this point. One palletizer working alone is more efficient than two palletizers working together. Palletizer 2 is not as efficient as palletizer 1 in any case. There are inherent delays in product flow built into the system. And. that the production schedule is the most important input into the system. The recommendations to the current system were to run only one palletizer per loop whenever possible, to schedule at least 435 cases per manhour to each of the palletizers through optimally scheduling product on the production schedules and to look at capital improvements to increase the efficiency of the system.

