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4	The relationship between lateralisation patterns from sequence based motor tasks and
5	hemispheric speech dominance
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29 Abstract

Objective: Skilled motor praxis and speech production display marked asymmetries at the 30 individual and the population level, favouring the right hand and the left hemisphere 31 respectively. Theories suggesting a common processing mechanism between praxis and 32 speech are supported by evidence that shared neural architecture underlies both functions. 33 Despite advances in understanding the neurobiology of this left-hemisphere specialisation the 34 cortical networks linking these two functions are rarely investigated on a behavioural level. 35 *Method*: This study deploys functional Transcranial Doppler (fTCD) ultrasound to directly 36 measure hemispheric activation during skilled manual praxis tasks shown to be correlated to 37 hemispheric speech lateralisation indices. In a new paradigm we test the hypothesis that 38 praxis tasks are highly dependent on the left hemisphere's capacity for processing sequential 39 40 information will be better correlated with direction and strength of hemispheric speech lateralisation 41

42 *Results*: Across two experiments we firstly show that only certain praxis tasks (pegboard and 43 coin-rotation) correlated with direct measurements of speech lateralisation despite shared 44 properties across all tasks tested. Secondly, through novel imaging of hemispheric activation 45 during praxis, results showed that the pegboard differed in the lateralisation pattern created 46 and furthermore that it was significantly related to speech laterality indices, which was not 47 the case for either of the other two tasks.

Conclusion: These results are discussed in terms of a lateralised speech-praxis control
mechanism and demonstrates that measurements of motor paradigms through the use of
fTCD are reliable enough to provide a new insight to the behavioural relationship been
speech and handedness.

52	Key Words:
53	Motor Praxis
54	Speech Production
55	Cerebral Lateralisation
56	Functional Transcranial Doppler (fTCD)
57	Sequencing
58	
59	Public Significance Statement:
60	It is well known that the left side of the brain plays an important role in the function of both
61	speech and fine motor movement. This study shows that the brain activity produced by motor
62	tasks that require sequential processing occurs predominantly in the left-hemisphere of the
63	brain, irrespective of which hand is used. The study also showed that this is a similar pattern
64	of brain activity seen in speech production tasks. This suggests that the two functions may
65	rely on similar neural networks, which increases our understanding of how the two functions
66	interact in the brain, and how they may sub serve each other in recovery from injury to this
67	brain region.
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73 **1. Introduction**

74 Skilled motor praxis and the capacity for language production have been described as the two defining characteristics of the human species (Corballis, 2010). Both functions 75 76 display marked asymmetries at the individual and the population level, favouring the righthand and the left-hemisphere respectively (McManus, 2002; Knecht et al., 2000a, b). Strong 77 left-hemisphere asymmetry for language processing is a robust finding across methodologies 78 (e.g. Costafreda et al., 2006; Dehaene-Lambertz et al., 2006; Knecht et al., 2000a, b) and 79 similarly, the cortical activation patterns of manual praxis, that is, the ability to generate, 80 coordinate and perform complex gestures and intentional actions, also reveal a left-81 hemisphere bias (Buxbaum et al., 2005; Haaland et al., 2004; Goldenberg, 2013). Despite 82 advances in understanding the neurobiology of this left-hemisphere specialisation for fine 83 motor action (Verstynen et al., 2005; Serrien et al., 2006) and speech production (Sahin et al., 84 85 2009; Flinker et al 2015) the cortical networks linking these two functions are rarely investigated on a complex behavioural level, for example by using praxis tasks commonly 86 87 used in neuropsychology to determine motor-skill and handedness. This is predominantly due to constraints from these complex motor tasks inducing unacceptable movement artefacts in 88 commonly used neuroimaging techniques, like fMRI, rendering exact simulations of 89 neuropsychological assessments of motor-skill tasks unfeasible. 90

The association between praxis and language is longstanding in neuropsychology, with evidence revealing that left-hemisphere lesions often lead to combined impairments in motor control and speech processing (Rasmussen and Milner, 1975; Goldenberg, 2013) and that children with developmental language learning impairments often also present with impaired praxis skills (Redle et al., 2014; Hill, 2001). Evidence suggests that both speech and action involving fine motor control of the hands rely on common neural architecture (Vingerhoets et al., 2013); classic frontal-temporal speech production areas, namely the pars

opercularis (PO) and pars triangularis (PT), are activated during motor tasks (Binkofski and
Buccino, 2004) and motor cortex and pre-motor areas are active during language tasks (de
Lafuente and Romo, 2004). These findings underlie the hypothesis that both functions share a
common evolutionary origin specifically that spoken language may have evolved from
gestural communication (Corballis, 2003; Arbib, 2000, 2005).

Such neurological overlap between praxis and speech is hypothesised to result from 103 the two functions relying on similar processing mechanisms as well as shared architecture. 104 One suggestion is that tasks which rely on sequential processing to execute complex actions 105 will make use of similar cortical networks, independent of modality, and will predominantly 106 lateralise to the left-hemisphere (e.g. Flowers and Hudson, 2013; Grimme et al., 2011). The 107 left-hemisphere is recruited for complex sequential processing in a range of cognitive 108 domains, and has been shown to be specifically involved in visuomotor control of action 109 110 (Verstynen, et al., 2005) as well as being crucial sequential properties of language (Sahin, et al., 2009). Furthermore, left-hemisphere pathways activate more strongly than right-111 hemisphere homologues during complex fine motor tasks, regardless of the hand that is 112 moving or the participant's handedness (Haaland, et al., 2004; Serrien et al., 2006). It has also 113 been demonstrated that handedness tasks involving fine motor sequencing are related to the 114 direction of hemispheric lateralisation of speech activation (Gonzalez and Goodale, 2009; 115 Hodgson and Hudson, 2016) and even that performance differences between the hands on 116 skilled motor tasks can predict direction of language lateralisation, as measured by the Wada 117 procedure (Flowers and Hudson, 2013). 118

119 What has not yet been measured, however, is the extent to which left-hemisphere 120 speech regions are active during complex motor-skill tasks more commonly associated with 121 measurements of praxis or handedness. Behavioural imaging paradigms that have attempted 122 to address this have been limited to discreet button presses or finger tapping tasks (e.g

Haarland, et al., 2004; Verstynen et al., 2005) due to the confounds created by deploying 123 more complex motor tasks in neuroimaging techniques (like fMRI) through unacceptable 124 signal-to noise artefacts created from the excess movement, or incompatibility of praxis task 125 equipment with the scanner. Paradigms using button presses or finger movements are 126 arguably oversimplifications of the complexities of manual praxis underlying theories of 127 motor and speech development (Corballis, 2010). Furthermore, despite agreement that 128 sequential processing may be key to revealing the links between hemispheric specialisation 129 for speech production and skilled motor praxis (Hodgson, Tremlin and Hudson, 2019; Hsu 130 131 and Bishop, 2014; Grimme et al., 2011), previous studies examining this relationship use tasks which fail to effectively tap into this mechanism (e.g. Groen, et al., 2013). 132

The first experiment in this study was designed to probe this hypothesised left-133 lateralised preference for sequential processing, by correlating performance across a range of 134 135 skilled praxis tasks with direct measurements of hemispheric speech lateralisation. A range of tasks was necessary to assess whether additional component processes may contribute to the 136 successful execution of complex motor tasks, in addition to sequencing. Task selection was 137 based upon identifying other candidate cognitive/behavioural elements that may relate 138 strongly to speech lateralisation. These additional processes can be categorised as follows: 1) 139 Precision grip and release and grip strength; this skill is crucial in determining an individual's 140 ability to pick up the pegs smoothly and accurately and release them as fast as possible. 141 Evidence suggests that precision grip is one of the later aspects of hand manipulation skills to 142 develop in young children (Scharoun and Bryden, 2014) and it has also been demonstrated 143 that tasks which require use of the pincer grip motion are performed more accurately with the 144 dominant hand (Gonzalez, Ganel and Goodale, 2006). A study by Annett, Annett, Hudson 145 and Turner (1979) using stop-motion video analysis demonstrated that participants who had 146 slower movement times on a pegboard task actually deployed a less effective release motion 147

of the peg, but were comparable on other aspects of the grasp action. 2) Finger dexterity; this 148 skill involves the ability to quickly and accurately manipulate the fingers into different 149 positions and move individual digits at varying speeds and angles, as required by the task. 150 151 Models of corticomotoneuronal pathways indicate that crucial rostrocaudal connections which project bilaterally from the brain stem are heavily involved in finger dexterity, and 152 severing these connections at various points limits digit mobility to varying degrees of 153 severity (Isa, Kinoshita and Nishimura, 2013). 3) Arm movement; skilled manual tasks often 154 require an element of upper arm motion especially if the task involves crossing the midline of 155 156 the body. This additional element of gross motor function involves separate muscle and nerve groups which may vary the pattern of hemispheric activity. 4) Psychomotor speed; this 157 function is defined as the ability to maintain focus on a task requiring manual/motor response 158 by accurately integrating relevant cognitive processes. It relies heavily on aspects such as 159 working memory, attention and other 'top-down' processes to maintain motor speed and 160 concentration on a specific task. Patients with deficits in regulation of psychomotor speed 161 have been shown to have lesions extending bilaterally through parietal and temporal regions 162 (Goldenberg, 2013). Experiment 1 deconstructed these factors into separate tasks and then 163 correlated left- and right-hand performance across these tasks with separately derived speech 164 lateralisation indices. 165

The second experiment then deployed a novel imaging paradigm using functional
Transcranial Doppler ultrasound (fTCD) to derive lateralisation indices of *motor action*during three selected tasks. The use of fTCD in lateralisation research is well established (e.g.
Aaslid et al., 1982; Deppe et al., 2004; and for a visual demonstration of the technique see
Bishop et al., 2010) and has important methodological benefits over other imaging
modalities. For example, it can be easily applied to clinical groups unable to undergo more
invasive scanning procedures and is also appealing to developmental populations due to its

unintimidating protocol. Previous work on imaging the motor cortex via fTCD has deployed 173 simple finger tapping tasks to activate contralateral motor pathways as an indicator of 174 functional relocalisation in stroke patients with aphasia and/or apraxia diagnoses (Silvestrini 175 et al., 1993). Uomini and Meyer (2013) used fTCD to explore hemispheric activation of 176 motor action and word generation during an archaeological study of stone tool use, and found 177 correlations between the profile of motor activation and speech lateralisation. However the 178 measurement of motor lateralisation using fTCD has not yet been applied to motor praxis 179 tasks as used in neuropsychological assessments, or those known to correlate with speech 180 181 laterality profiles (Hodgson et al., 2016). It was hypothesised that the tasks which correlate more strongly with speech lateralisation scores in experiment 1 will also display an increased 182 left-hemisphere activation bias for both hands (contralateral activation for right-hand motion 183 and ipsilateral activation for left-hand motion), in comparison to a baseline task in experiment 184 2. In addition it was hypothesised that derived motor lateralisation indices with a strong left-185 hemisphere bias would be more accurate predictors of degree of speech lateralisation indices. 186 This would indicate that task-specific motor activation links to speech activation, which 187 would provide insight to the component processes underlying both functions. 188

189

190 **2. Experiment 1**

191 2.1 Methods

1922.1.1. Participants

Forty adults aged between 18 and 40 years (17 males; mean age: 20.07yrs; SD age: 3.7) were recruited from the University. Participants gave informed consent prior to taking part in the study. All participants had normal, or corrected to normal, vision

196	and none had history of neurological disorders or trauma, or any condition known to
197	affect the circulatory or central nervous systems. All participants were Caucasian and
198	had English as their first language. They received research credits in return for their
199	participation. The study received ethical approval by the School of Psychology
200	Research Ethics Committee, University of Lincoln. Participants completed a
201	shortened version of the Edinburgh Handedness Inventory to determine their self-
202	reported hand preference (see Flowers and Hudson, 2013), which revealed that 6 of
203	the 40 participants were left handed, denoted by a handedness quotient at or below
204	zero.
205	
206	2.1.2 Motor Skill Tasks
207	All participants performed 6 separate manual praxis tasks. The ordering of
208	task presentation was counterbalanced between participants. Each task was performed
209	with both hands, alternating between right and left on each trial, with the self-reported
210	preferred hand going first on each task. Table 1 shows how each task corresponds
211	theoretically to the component processes involved in skilled praxis tasks.
212	Task 1. Electronic Pegboard – This procedure has been described in detail in
213	Hodgson and Hudson (2016). In brief, 20 pegs (6mm diameter \times 24mm long) were
214	moved one at a time from a row of holes on one side of a rectangular board to a row
215	of holes at the opposite side of the board. The pegboard consisted of a 280 \times 100 \times
216	20mm board with two rows of 20 holes (7mm diameter) drilled 13mm apart along the
217	length. The distance between the two lines of holes was 70mm. The Fitts' (1954)
218	Index of Difficulty (Id) measurement for this board was $Id = 7.6$, making it unlikely
219	that the task can be performed by pre-programmed aimed movements, and must

involve some "online" movement control where handedness differences are most
consistently found (Annett, Annett, Hudson, & Turner, 1979; Flowers and Hudson,
2013). This task was performed 3 times with each hand, as fast as possible, and exact
timings (in milliseconds) were measured by the electrical circuitry hidden in the
board.

225

Task 2. Coin-Rotation – Participants were asked to rotate a British two pence coin 226 (diameter = 25.9 mm, thickness = 1.85 mm, weight = 7.12 g) as quickly as possible 227 with their thumb, index, and middle fingers. The action required participants to turn 228 the coin over 180° repeatedly, just using the fingers mentioned above. The time to 229 perform 20 half turns was measured. The experimenter counted and timed the turns. 230 This was performed 3 times with each hand. Performance was measured in seconds. 231 This task has previously been shown to accurately measure manual dexterity in 232 233 healthy adults (Mendoza et al., 2009) and patient groups (Heldner et al., 2014).

234

Task 3. Finger Tapping – Participants placed both hands flat on the table in front of
them and were required to tap their index finger 10 times as fast as possible, whilst
keeping their other fingers in contact with the table surface. This was performed 5
times with each hand. Taps were recorded by the experimenter and performance was
measured in seconds.

240

Task 4. Pen and Paper Dotting – This task was designed as a pen and paper version
of the pegboard. Participants were asked to hold a short felt tip pen in a pincer grip

and place a single dot inside circles laid out in two rows on a piece of paper. They
were instructed to do this as fast as possible and be as accurate as possible. The
dimensions of the two rows of dots matched exactly the dimensions of the pegboard
(see above) and the ordering of trial completion was also the same. Occasions where
the dot was not inside the circle were classed as errors. Three trials were performed
with each hand and the mean time and accuracy scores were calculated.

249

Task 5. Peg Placing – Participants were required to place 20 identical pegs from a 250 pot positioned at the side of a board into 5 cups arranged on the board. The cups were 251 placed in a circle in grooved slots to ensure the exact dimensions were consistent 252 across participants. Participants were instructed to ensure all 20 pegs were sorted as 253 fast as possible and they were explicitly told not to place into the same pot on two 254 consecutive pegs, or to use an adjacent pot to the one just selected on consecutive 255 pegs. These rules were to avoid participants placing into each pot in a circular manner 256 257 or just making use of one pot.

258

Task 6. Grip strength – This static measurement was included as an alternative
measure for hand preference, having previously been shown to effectively
discriminate between preferred and non-preferred hand performance (Petersen et al.,
1989). This was included as the hand preference questionnaire administered was
based on self-report. Grip was assessed using a handheld dynamometer. Participants
were required to sit with their feet flat on the floor and their arm at a comfortable right
angled position by the side of their body. They were instructed to squeeze the device

as hard as they could for 2 seconds and then release their grip. This was performed 3
times with each hand. Performance was measured in Kilograms.

- 268
- 269

[INSERT TABLE 1 HERE]

270 2.1.3 Speech Laterality

Cerebral blood flow velocity (CBFV) was measured via functional transcranial 271 Doppler (fTCD) ultrasound whilst participants completed a word generation task. This task 272 involved the silent production of words corresponding to a stimulus letter displayed on a 273 computer screen. The paradigm has been described in detail elsewhere (Knecht et al., 2000a; 274 Hodgson and Hudson, 2016) but briefly, participants receive a 5 s 'clear mind' message 275 before a stimulus letter is displayed on the screen. At this point participants are asked to 276 begin word generation silently until they see the next instruction to repeat the words they 277 were just thinking of out loud. This is followed by a 35 s rest phase. The task has been well 278 used in language lateralisation studies (Deppe et al., 2000; Knecht et al., 1998; Knecht et al., 279 2000a) and is known to reliably elicit hemispheric activation. Measurements of middle 280 cerebral artery blood flow velocity during the periods of silent word generation are compared 281 with the rest phase of the trial. Participants performed 23 trials with a different letter 282 presented each time. Speech laterality indices were derived for each participant by taking the 283 mean difference between left- and right-sided activity within a 10 sec window (see Woodhead 284 et al., 2018 for explanation), from the period of interest which occurred 5-15secs after the 285 286 start of each trial. The period of interest mean was then compared to the baseline rest phase extracted from the period -10 - 0 s during each epoch. Epochs last for 1 minute, from -10 s to 287 50 s. Speech laterality was assumed to be clear in all cases in which the LI deviated by > 2288 SE from 0 (Knecht et al., 2001). Left-hemisphere or right-hemisphere speech dominance was 289

indicated by positive or negative indices respectively. Cases with an LI < 2 SE from 0 were
categorised as having bilateral speech representation.

292

293 2.2 Procedure

294 2.2.1 Motor Skill Tasks

Performance on 5 of the 6 motor tasks (Pegboard; Coin-rotation; Dotting; Finger 295 Tapping; Peg Placing) was measured by the speed with which the tasks were completed. 296 Mean movement times were calculated for preferred and non-preferred hand performance. 297 For the sixth motor task, Grip Strength, performance was measured by the mean force 298 squeezed in kilograms, for the preferred and non-preferred hands. Correlation coefficients 299 were generated for the mean scores for each hand, across each task, and the data were then 300 entered into a principal components analysis to identify common factors underpinning the 301 performance differences. 302

303

304

2.2.2 Functional Transcranial Doppler

Speech lateralisation indices were derived from measurements of cerebral blood flow 305 velocity (CBFV) taken from bilateral insonation of the middle cerebral arteries whilst 306 participants performed the word generation task. Recordings were made with a commercially 307 available system (DWL Doppler-BoxTMX: manufacturer, DWL Compumedics Germany 308 GmbH) via a 2-MHz transducer probe attached to an adjustable headset, positioned over each 309 temporal acoustic window. PsychoPy Software (Pierce, 2007) controlled the word generation 310 experiment and sent marker pulses to the Doppler system to denote the onset of a trial. Data 311 were analysed off-line with a MATLAB (Mathworks Inc., Sherborn, MA, USA) based 312

313	software package called dopOSCCI version 2 (see Badcock, Holt, Holden and Bishop, 2012
314	for a detailed description).

315

316 **2.3 Results**

317 2.3.1 Motor Skill Tasks

318 To assess the relative hand performance across each task non-parametric tests were deployed due to non-normally distributed data. Wilcoxon signed rank tests were performed to 319 examine differences between the preferred and non-preferred hand performance across each 320 of the 6 tasks. Four of the tasks revealed significant differences between preferred and non-321 preferred hand skill. The preferred hand (PH) demonstrated greater proficiency than the non-322 preferred hand (NPH) on the Pegboard, (PH median = 23.1 s vs. NPH median = 23.9 s; Z = -323 2.55, p < .02, r = -.29); coin-rotation (PH median = 15.2 s vs NPH median = 17.9 s; Z = -324 5.12, p < .001, r = -.57); dotting task (PH median = 22.26 s vs. NPH median = 26.02; Z = -325 326 5.44, p < .001, r = -.61) and grip strength measurements (PH Median = 26 kg vs. NPH 327 median = 24.8 kg; z = -2.64, p < .01, r = -.29). There were no significant differences between the hands on the placing task (PH Median = 35.3 s; NPH Median = 35.8 s; Z = -.66, p = .51) 328 329 or the finger tapping task (PH Median = 1.78 s; NPH Median = 1.77 s; Z = -.96, p = .34). See table 2 for mean performance scores. 330

331

[INSERT TABLE 2 HERE]

332

2.3.2 Speech Laterality

334	Speech Lateralisation indices were obtained for 34 of the 40 participants. Six cases
335	were unusable due to excess variability in the individual epoch recordings such that they had
336	less than 50% acceptable trials recorded. LI values ranged from 3.79 to -2.36 (mean = 2.31 ,
337	SD = 1.8) with 4 cases classed as atypically lateralised (i.e. had right-hemisphere or bilateral
338	language distribution). Mean number of words generated per trial at the group level was 4.6
339	(SD=.066). In order to assess the relationship between speech laterality and the performance
340	on the motor-skill tasks correlation coefficients were generated for each task and each hand
341	against the speech LI scores (see Table 3). These indicate that only the Pegboard and Coin-
342	rotation tasks correlated significantly with Speech LI scores.

343

[INSERT TABLE 3 HERE]

344 2.3.3 Factor Analysis

Initially, the data from the performance of the right- and left-hands across the 6 skill 345 tasks was examined for its suitability to be included in the factor analysis. Several well 346 347 recognised criteria for the factorability of a correlation were used. Firstly, it was observed that all 12 items correlated at least .3 with at least one other item, suggesting reasonable 348 factorability. Secondly, the Kaiser-Meyer-Olkin measure of sampling adequacy was .61, 349 350 above the commonly recommended value of .6, and Bartlett's test of sphericity was significant (χ^2 (66) = 464.16, p < .001). The diagonals of the anti-image correlation matrix 351 were also all over .5. Finally, the communalities were all above .3, further confirming that 352 each item shared some common variance with other items. Given these overall indicators, 353 factor analysis was deemed to be suitable with all items. 354

355 Principal components analysis was used because the primary purpose was to identify356 the factors underlying the relationship between the motor-skill tasks used. Initial eigen values

indicated that the first four factors explained 40.4%, 18.8%, 13.2% and 10.8% of the variance 357 respectively. Factors 5 to 12 had eigen values under one, and cumulatively explained 17% of 358 the variance. Solutions for three and four factor models were each examined using varimax 359 rotations of the factor loading matrix. The three factor solution, which explained 73.2% of the 360 variance, was preferred because of: (a) the tasks included in this solution were similar to one 361 another in terms of properties; (b) the 'levelling off' of eigen values on the scree plot after 362 three factors; and (c) the two tasks included in the final component of the 4 factor solution 363 were grip strength for right and left hands respectively, meaning that grip must represent 364 365 distinct component of handedness, not directly relevant to the function of praxis ability/motor skill. See table 4 for results. 366

367

[INSERT TABLE 4 HERE]

368 2.4 Summary

Experiment 1 correlated behavioural performance on 6 different praxis tasks, selected due to shared component processing, with speech lateralisation indices derived using fTCD. Factor analysis revealed that the best fitting model included three separate component processes to describe the relationship between handedness performance measures. Scrutiny of the handedness tasks contributing to each factor (see table 4), and cross refencing with the processing requirements of each task (see table 1), indicates that the three components could be labelled as follows:

Component 1: Psychomotor speed. The majority of the tasks contributed to this factor,
suggesting it most closely relates to the elements of visual and cognitive attention, required to
carry out these motor actions efficiently, which we term psychomotor speed.

Component 2: Finger dexterity/ Arm movement. The two tasks which contribute to this factor
(finger tapping and peg-placing) are those which require some degree of arm or hand
movement as their main mode to completion. The movements of these two tasks are fairly
rhythmic, and they are less complex to perform under time constraints.

Component 3: Sequencing. Only two tasks contributed to this factor, but they both involve a high level of visual and motor coordination, including cognitive control and precision placing and timing to follow the correct task pattern and most efficient route to completion of the movement. This concurs with evidence that sequential movements are more complex, and thus may be distinct from other types of motor action.

Following on from this it could be suggested that Component 3, sequencing, was most 388 389 indicative of the type of action underlying speech and motor interactions seen in the literature. This was supported by the correlational analysis, which indicated that the two 390 motor-skill tasks which contributed to Component 3 were also the tasks which correlated well 391 392 with speech scores; pegboard task and coin-rotation, for both left- and right-hand movement. 393 To explore the activation patterns created by these tasks this in greater depth, and to assess whether the sequencing component of these tasks is driving the connection between speech 394 395 and motor action we conducted a second experiment. Experiment 2 was designed to assess the relationship between the hemispheric lateralisation indices created by different praxis 396 tasks; whether these indices would be hand dependant, and finally, whether these indices 397 could be significantly related to lateralisation patterns created by speech. The study was 398 designed to obtain direct physiological measurements of hemispheric laterality during motor 399 400 tasks, as well as during speech production, to compare hemispheric dominance between the hands and across functions. 401

402

403	3. Experiment 2
404	3.1 Methods
405	3.1.1 Participants
406	These were 23 adults aged 18-27 (5 males; mean age = 19.2 ; SD age = 1.92).
407	19 were right-handed, 3 left-handed and one individual was mixed handed, as
408	measured by a handedness inventory (Flowers & Hudson, 2013). Participants satisfied
409	the same criteria for inclusion as Experiment 1 and were recruited similarly.
410	
411	3.1.2 Motor Skill Laterality Measurements
412	Two of the motor tasks from Experiment 1 were selected to form the
413	experimental conditions in Experiment 2; the Pegboard and Coin-rotation. These tasks
414	were chosen as they were the only ones to significantly correlate with speech
415	lateralisation indices for both the right- and left-hand in the previous study, indicating
416	that they may best tap into the common processing mechanisms underlying speech
417	and praxis. A third task from Experiment 1, Finger tapping, was selected to serve as a
418	control condition. A new paradigm was developed in order to measure the relative
419	hemispheric activation during performance of these three motor tasks. Participants
420	were seated at a computer screen with their hands placed on marked areas on the table
421	in front of them. They were then instructed to keep absolutely still and not move their
422	hands from the designated area until instructed to by the computer. A Psychopy
423	software (Pierce, 2007) controlled computer program then ran the paradigm. Epochs
424	lasted for 30 seconds each. This consisted of a pre-action 'get ready' phase (0 -3 s),
425	followed by a 12 s 'move' phase $(3 - 15s)$, where the instruction of either 'Left' or

426 'Right' was given indicating the participants should start performing the task with the 427 corresponding hand. These direction prompts were displayed in a randomly generated 428 order, but always consisted of 15 'right' trials and 15 'left' trials, totalling 30 trials per 429 task. This was followed by a final rest phase (15 - 30 s) to allow the CBFV to return 430 to baseline. The tasks were presented in a block design, the order of which was 431 counterbalanced between participants.

432 The task formats were controlled to correspond with the fTCD paradigm, which meant that participants performed the action for 12 seconds and then stopped. 433 The Finger Tapping control condition was performed exactly as described in 434 Experiment 1 (see 2.1.2) using the second digit (index finger) only. The Coin-rotation 435 was set up so that the 2 pence coin was placed in between the marked areas where the 436 hands were resting. At the instruction of either 'Left' or 'Right' the participant was 437 required to pick up the coin with the corresponding hand, and rotate it as many times 438 as possible within the 12 s window. The Pegboard task was the most adapted from the 439 original version described in Experiment 1. In this paradigm only half the pegs on the 440 board were used (10 in total) and the board was positioned ipsilateral to the moving 441 hand on each trial. This was done to ensure that the board did not cross the 442 443 participants' midline, to minimise movement of the upper arm as this could confuse the laterality measurement (the board was repositioned on each trial by the 444 experimenter via sliding it between the pre-designated placement areas). 445

446

447 3.2. Data Analysis - Motor fTCD

448 Motor lateralisation indices were derived from measurements of cerebral blood flow
449 velocity (CBFV) taken from bilateral insonation of the middle cerebral arteries whilst

participants performed the three motor tasks described in 3.1.2. A set of 6 laterality indices 450 (LI) was derived for each participant corresponding to left and right hand movement across 451 each of the three tasks. These indices were calculated by extracting information from the 452 Psychopy (Pierce, 2007) program to denote which of the 30 epochs were the 'left' and which 453 were the 'right' trials, which were subsequently matched up to the LI values produced from 454 the analysis. Following the method set out in Woodhead et al. (2018), as with the speech 455 paradigms, the LI values were calculated from the mean difference between left and right 456 hemisphere activity within the 10sec period of interest (POI) in each trial. In the present 457 458 paradigm the POI was taken from the 'move' phase of the paradigm which was 5 - 15 s following onset of the trial. The baseline period was taken from the 'rest' phase. 459 Motor laterality was assumed to be clear in all cases in which the LI deviated by > 2460 SE from 0 (Knecht et al., 2001). Left-hemisphere or right-hemisphere motor dominance was 461 indicated by positive or negative indices respectively. Cases with an LI < 2 SE from 0 were 462 categorised as having bilateral motor representation. Participants required a minimum of 15 463 acceptable trials (i.e. 50%) to be included in the analysis. Criteria for acceptable trials were 464 those which maintained a consistent insonation signal throughout the whole epoch capture, 465 (i.e. didn't contain any drop in signal), or those which did not include any behavioural 466 variation from the task (i.e. where the participants stopped, or dropped equipment). Although 467 this 50% threshold was chosen arbitrarily, all participants well exceeded this threshold, and 468 only 1 was excluded for behavioural reasons (dropped peg). Evoked flow plots showing the 469 mean signal pattern from the left and right hemisphere channels during an epoch, are firstly 470 displayed across tasks (see Figure 1) and then separated by task and hand (see Figure 2). 471 472 [INSERT FIGURE 1 HERE] 473 474

475

[INSERT FIGURE 2 HERE]

476	
477	
478	3.3 Speech Laterality
479	Speech lateralisation indices were obtained for each participant following completion
480	of the motor paradigm. Participants performed the word generation paradigm, the overview
481	of and outline of the fTCD analysis procedure for this task was identical to that described in
482	Experiment 1 – see section 2.1.3
483	
484	3.3 Statistical analysis
485	Initially LI scores were derived from each motor task, for each hand. This data was
486	then analysed using paired sample t-tests for each task to measure differences between the
487	hemispheric lateralisation indices produced between the left- and right-hands, at the group
488	level. Variables were then entered into a repeated measures ANOVA, with a 2-way within
489	subjects variable of 'hand' (left and right) and a 3-way within subjects variable of task (coin,
490	tapping and pegboard), and between subjects variables of hand preference and speech
491	laterality group (right and left).
492	
493	3.3 Results
494	3.3.1 Lateralisation of Motor Skill Tasks
495	One participant was excluded from the analysis as their LI scores did not meet the
496	quality thresholds required during pre-processing analysis and too many trials were unusable
497	(for further detail on the processing steps involved see Badcock et al, 2012). Split half
498	reliabilities of the odd and even epoch LI values were calculated for the left- and right-hand

499	trials, across each of the three tasks. Pearson correlations indicated medium internal
500	reliability in each of these calculations (see Table 5). To assess whether LI scores were
501	significantly different to zero, thus indicating lateralised hemispheric activation, one-sample
502	T tests were conducted (see table 6). This showed that at the group level all tasks exhibited
503	lateralised activation patterns (either to left or right hemisphere), except the left-hand
504	Pegboard task and the right-hand coin rotation task, which both displayed bilateral activation
505	patterns.
506	[INSERT TABLE 5 HERE]
507	
508	[INSERT TABLE 6 HERE]
509	To assess the interaction between 'task' and 'hand used' a two-way repeated measures
510	ANOVA was conducted using the variables 'Hand' (2 levels; left and right) and 'Task' (3
511	levels; coin-rotation, Finger tapping and Pegboard). Results showed that there was a
512	
	significant interaction between hand used and task performed ($F(2,40) = 4.01 \ p < .05, \eta_p^2 =$
513	significant interaction between hand used and task performed ($F(2,40) = 4.01 \ p < .05, \eta_p^2 =$.17). This interaction effect shows that the laterality indices produced by the left- and right-
513 514	

516 Bonferroni correction applied. Results show that there was a statistically significant simple

517 main effect of hand used ($F(1,20) = 161.4 \ p < .0001, \ \eta_p^2 = .89$) across each of the motor tasks

518 (Pegboard: mean difference of -2.13 between left and right hand LI scores (95% CI, -2.59 to -

519 1.67); Coin Rotation: mean difference of -2.39 between left and right hand LI scores (95%

520 CI, -3.06 to -1.72); Finger Tapping: mean difference of -3.2 between left and right hand LI

scores (95% CI, -3.97 to -2.46), which indicates that the lateralisation indices derived from

522 the left and right hands significantly differ in direction regardless of task.

523	There was also a significant simple main effect of task ($F(2,40) = 9.41 \ p < .0001, \eta_p^2$
524	= .32) demonstrating a difference between the hemispheric lateralisation indices depending
525	on the task that was being performed. Scrutiny of the pairwise comparisons for each task
526	show that there were significant differences in the LIs between the pegboard and coin rotation
527	tasks for the left-hand (a mean difference in LI score of 1.31 (95% CI, .32 to 2.29) and the
528	right-hand (a mean difference in LI score of 1.05 (95% CI,03 to 2.12). There were also
529	significant differences in the LIs between the pegboard and finger tapping tasks for the left
530	hand (a mean difference in LI score of 1.63 (95% CI, .56 to 2.68), but these were not
531	significant for the right hand (a mean difference in LI score of .54 (95% CI,37 to 1.45).
532	Comparisons between the coin rotation and finger tapping task LIs were not statistically
533	significant for either the left (a mean difference in LI score of .32 (95% CI,46 to 1.11) or
534	right (a mean difference in LI score of50 (95% CI, -1.34 to .33) hands.
535	
536	[INSERT FIGURE 3 HERE]
537	
538	3.3.2 Speech Lateralisation
539	The word generation task produced the expected left-hemisphere dominant LI value
540	across the sample as a whole; LI mean = 2.03 , SD = 1.76 . The range of mean LI scores was -
541	2.65 to 4.67, and there were 2 individuals who were right-hemisphere lateralised (mean LI
542	scores of -2.65 and -1.98 respectively) and 2 classed as bilateral (mean LI scores of .61 and
543	.95). Split half reliabilities of the odd and even epoch LI values are shown in Table 5, and
544	one-sample T tests showing lateralised hemispheric activation are shown in Table 6.

546

3.3.3 Predictive Relationship Between Speech Lateralisation and Motor Lateralisation

547 To assess the predictive relationship between the speech indices and the indices from the motor tasks, multiple regression was conducted using the stepwise entry method with 548 mean speech lateralisation indices as the dependent variable. The mean lateralisation indices 549 derived from the three praxis tasks by each hand were all entered as predictor variables. From 550 this analysis a significant regression model was produced (see Table 7 for regression 551 statistics), which explains 22% of the variance in speech lateralisation indices. Both of the 552 models included only lateralisation indices from the right hand of the pegboard task and 553 excluded each of the other task/hand combinations, indicating that the specific processing 554 555 requirements in the pegboard task are most similar to those underlying speech production. Correlations of the LI values from each motor task, for each hand, and the Speech LI scores 556 also reveal that only the right-hand of the pegboard task significantly correlated to the Speech 557 score (see Table 8). Figure 4 plots the relationship between the mean speech indices derived 558 from the word generation task and the mean motor indices derived from the pegboard task for 559 560 the right hand.

- 561
- 562 563

564

565

[INSERT FIGURE 4 HERE]

[INSERT TABLE 7 HERE]

[INSERT TABLE 8 HERE]

- 566 567
- 568 **4. Discussion**

569 Theories suggesting a common processing mechanism between praxis and speech are 570 supported by evidence that shared neural architecture underlies both functions (e.g. Binkofski

and Buccino, 2004). This relationship is rarely investigated on a complex behavioural level 571 using neuroimaging, due to the movement artefacts necessarily created by standard 572 neuropsychological praxis tasks. This study makes use of an emerging technique in cognitive 573 neuroscience, fTCD, to investigate the hemispheric specialisation underlying lateralised 574 behaviour. Across a set of two experiments the hypothesis that motor praxis and speech share 575 cortical networks as both are reliant on complex sequential processing controlled by the left-576 hemisphere was investigated in an overt paradigm (e.g. Grimme et al, 2011; Flowers and 577 Hudson, 2013). In Experiment 1 performance on the pegboard task and five additional 578 579 motor-skill tasks sharing common processing requirements were compared to speech lateralisation indices derived from a word generation task during fTCD ultrasound. Results 580 indicated that only two of the six motor tasks correlated significantly with speech LI scores; 581 the pegboard and the coin-rotation task. A factor analysis model confirmed that only these 582 two tasks contributed to the best fitting model to explain the shared components across all of 583 the handedness tasks. 584

These tasks were then used in Experiment 2 with an fTCD motor paradigm to derive 585 lateralisation indices during movement of the left- and right-hands. This second experiment 586 demonstrated that the right-hand activated the contralateral (left) hemisphere for the pegboard 587 task, but not the coin rotation task (which displayed bilateral activation), whereas the left-588 hand activated the right hemisphere during the coin rotation task, but not the pegboard task, 589 590 which produced bilateral activation. This was compared to a control condition task of finger tapping, with a single digit (index finger), during which both hands activated the contralateral 591 hemisphere. In addition, a good proportion of the variance in speech lateralisation indices 592 could be predicted by the motor indices produced from the right hand of the pegboard task. 593 Together these data provide good evidence that the inherent properties within sequencing-594

based praxis tasks are more linked to speech processing than a non-complex motor task suchas tapping, and that they are represented more strongly in the left hemisphere.

The validity of the tasks chosen as effective skill-based motor activities for measuring 597 hand performance was demonstrated as each were accurate in distinguishing the dominant 598 hand, although in two of the tasks this difference was not significant (Placing Task and 599 Finger Tapping). If hand performance had differed in direction, rather than just degree, across 600 601 each of these tasks then it would be concerning for the subsequent comparisons with speech indices in terms of making assumptions about the hemispheric control of each task. There 602 603 were however some unexpected findings from the results between speech and motor performance across the 6 tasks. The first observation of interest was that the pen and paper 604 version of the pegboard; the Dotting task, did not significantly correlate with speech 605 606 laterality, despite it appearing as primary factors in the first component of the factor analysis. This lack of relationship with speech indices is surprising because the only component it did 607 not share with the pegboard was the grip and release mechanism of picking up the pegs 608 (participants kept a constant hold of the pen during this task). Therefore this is an indicator 609 that the sequential movement and manipulation of the fingers in the pegboard task may be a 610 key factor regarding its common processing with speech. Support for this is provided by data 611 from fMRI of finger movement tasks which show increased left-hemisphere activation during 612 sequential and non-sequential finger movements (Hayashi, et al., 2008). 613

The second observation from comparisons of each of these tasks is that the placing task did not correlate well with speech indices, or indeed with many of the other motor tasks. This is likely due to the parameters of the task, as observations of participant behaviour during task execution suggested that it was more cognitively demanding than the other, more purely motor, comparators. For example, often participants hovered over a pot whilst deciding whether it would constitute an illegal move on that trial, before then making the peg

placement. Thus it is clear that the task involved a greater working memory component than 620 the other tasks, as well as a greater requirement for effective response inhibition. Such 621 mechanisms are known to be controlled predominantly by the right-hemisphere (Aron, 622 Robbins and Poldrack, 2014), and so it is likely that a reduced left-hemisphere network 623 would be involved, even in right-hand movement, thus reducing its relationship with speech 624 indices. This however means it was a successful choice as a task in terms of one which 625 626 eliminated motor sequencing, however it was perhaps not as comparable with the other handedness tasks in terms of measuring a component of motor skill (as it seemed to rely on 627 628 more cognitive motor planning mechanisms).

629 Experiment 2 demonstrated that the patterns of hemispheric activity resulting from motor skill tasks varied depending on how speech-related the tasks were. Two tasks were 630 tested based on factor analysis from Experiment 1 indicating that they share common 631 632 components, the pegboard and the coin-rotation task, along with a third task, finger tapping, which showed to load on a distinct component in the factor analysis, and so was used as a 633 control condition. Results confirmed the hypothesis that greater left-hemisphere activation 634 would be seen in the experimental tasks regardless of the hand that is moving, although this 635 was more pronounced for the Pegboard task than the coin-rotation task. This is a novel 636 finding as it demonstrates the left-hemisphere bias for motor sequencing tasks in real time, 637 and is an indicator as to why links between speech laterality and pegboard performance have 638 been found previously (Flowers and Hudson, 2013; Hodgson and Hudson, 2016). 639 Furthermore the fTCD data has been shown to be reliable in this new paradigm, which 640 suggests that the activation patterns seen are representative of motor networks. It should be 641 noted however, that reliability measures in fTCD studies are frequently high, and so this 642 paradigm may benefit from inclusion of additional trials per participant in future studies, to 643 see if reliability can be increased even further. It may be that in motor paradigms participant 644

fatigue becomes an issue with maintaining performance consistency, which could also impact
on results if too many trials were included. These issues could be explored in future studies of
motor action measured by fTCD.

Figure 5 is a schematic representation of the results presented in Experiment 2. It 648 indicates that in the control condition, finger tapping, predominantly contralateral activation 649 was displayed, evidenced by the strong connections between each opposing hemisphere and 650 651 hand. Weak ipsilateral networks are represented in order to account for the fact that some epochs present this type of activation (i.e. the LI is a mean score), which suggests that both 652 hemispheres are working to greater or lesser degrees in support of task execution. This is the 653 case across each task shown in Figure 5. The Coin-rotation task is represented by less strong 654 contralateral activation and an increased role for the left hemisphere ipsilateral network, to 655 reflect the mean LI scores being close to zero. Finally the pegboard task is represented by 656 increased contralateral activation compared to the coin-rotation task, but is also supported by 657 much more activation in the left hemisphere ipsilateral network. This representation is 658 supported by evidence indicating ipsilateral control exhibits a functional asymmetry between 659 hemispheres whereby activation in left motor cortex during left-handed movements is 660 stronger than activation in right motor cortex during right-handed movements (Van den Berg, 661 Swinnen and Wenderoth, 2011; Hayashi et al., 2008; Kobayashi, Hutchinson, Schlaug and 662 Pascual-Leone, 2003). 663

664

[INSERT FIGURE 5 HERE]

Differences in the characteristics of the three motor tasks imaged require
consideration. One of the factors inherent in the pegboard task is the reliance on visual
processing in order to successfully complete the task. This differs from the requirements of
the coin-rotation and the finger tapping, where visual feedback does not inform the

continuation of the motor action in the same way. For example, participants often reported it 669 was easier to complete the finger tapping and the coin-rotation by fixating the gaze at a point 670 away from their hands. Due to the size of the pegs and holes of the pegboard task, it would 671 not be possible to complete it accurately without the integration of visual information. Visual 672 feedback has been shown to be integral to successful execution of handedness tasks (Smith, 673 McCrary and Smith, 1960; Miall, Weir and Stein, 1985), and the disruption of accurate visual 674 feedback during the grooved pegboard task has been show to neural processing speed and 675 considerably impair performance (Fujisaki, 2012). Lateralisation of visuospatial control has 676 677 reliably been shown to produce a right hemisphere bias (e.g. Whitehouse and Bishop, 2009; Flöel et al., 2001), which would not account for the predominant left hemisphere activation 678 pattern seen in the pegboard task, which is more visually dependent than others in this study. 679 However evidence from grasping studies altering the visual properties of the target reveal that 680 visuomotor mechanisms encapsulated in the left hemisphere play a crucial role in the visual 681 control of action (Gonzalez, Ganel and Goodale, 2006), thus supporting the notion that the 682 pegboard is more heavily dependent on sensory processing streams which also make use of 683 specialised left hemispheric networks. In addition the lateral arm movement required in the 684 pegboard task is greater relative to the two other conditions. Although this was minimised in 685 Experiment 2 by reducing the length of the board from 20 down to 10 pegs, and by 686 positioning the board on the ipsilateral side of space, some increased arm and shoulder 687 688 movement remained. Evidence from studies of cerebral lateralisation of arm movement control suggest that each hemisphere activates a specialised system of control, resulting 689 bilateral activation is at different stages of the movements (Mutha, Haaland and Sainburg, 690 691 2013). If this is the case, then it seems unlikely that excess arm movement will have impacted significantly on the laterality pattern, as predominant left hemisphere activation, rather than 692 bilateral, was found in the pegboard task. 693

An interesting finding from the regressions analysis of speech LI scores and motor LI 694 scores from experiment 2, was that only right-hand pegboard lateralisation indices were 695 significant predictors of speech lateralisation scores, with left-hand indices from the Pegboard 696 approaching significance. None of the other motor-skill task indices were significant 697 predictors of speech indices. This could be explained by the presence of a theoretical 698 lateralised praxis centre model, which makes use of strong contra-lateral connections between 699 the left-hemisphere and right-hand, and makes additional use of ipsilateral connections 700 between left-hemisphere and hand when performing complex tasks. Such a model has been 701 702 proposed by Hodgson and Hudson (2018; see also McManus et al., 2016) based upon the differential performance of the hands across skilled motor tasks. Such models suggest that 703 704 although the contralateral pathways for control of the hands are still activated during 705 handedness tasks, it could be that a specialised region in the left hemisphere, a so called 'praxis centre', mediates the control of this system in complex tasks. Hodgson and Hudson 706 (2018) argue that extent of left hemispheric control of motor output is potentially determined 707 708 by the complexity of the motor task. For complex movements requiring sequential timing. visuomotor control and accurate integration of visual feedback the use of a lateralised praxis 709 centre may be required, which is typically in the left-hemisphere. They suggest the praxis 710 centre model can explain why non-preferred hand performance is usually worse, as it is said 711 to rely on an 'inherently nosier' motor centre in the right-hemisphere, which is dependent on 712 713 transfer of information via the corpus callosum for control of the left hand. The data in the current study could extend that theory by integrating speech processing into such a model. A 714 left lateralised speech-praxis centre model proposes that the left-hemisphere 'centre' 715 716 activated by speech and praxis functions on a computational basis of integration between 'areas' or 'sets' of neural connections involved in the processing of key functions including; 717 motor action, visuo-motor control, motor planning, phonological and auditory processing and 718

sequential control of complex 'higher order' operations. Evidence from TMS studies lends 719 support to this notion, for example it has been shown that the optimal site to elicit motor 720 evoked potentials (MEPs) for the ipsilateral hand are in areas slightly lateral and ventral to 721 the site of maximal contralateral MEP (Ziemann, et al., 1999). This shift in location within 722 the left-hemisphere for control of ipsilateral relative to contralateral hand movements has also 723 been shown using neuroimaging (e.g. Cramer, et al, 1999). Furthermore recent evidence 724 demonstrates that even within Broca's area, the region classically thought of as the heart of 725 speech production and, crucially, an area which is confined to a specific part of the left 726 727 hemisphere, there are spatially and temporally separate processes which occur to support speech (Flinker et al., 2015; Sahin et al., 2009). Therefore a revised model of speech and 728 praxis argues that the interconnectedness of these functions will determine the efficiency with 729 730 which the left-hemisphere is able to support motor control of both hands as well as speech production processes. The data presented here is currently not sufficient to address this 731 theory, but future work developing the paradigm used here to measure speech related motor 732 praxis activation using fTCD could extend this theory further, especially in terms of the 733 characteristics expected during typical and atypical development. 734

735

736 **5.** Limitations

Although the data presented here demonstrate that variations in hemispheric activation across
motor praxis tasks exist, it is important to note the limitations of the current study. Firstly, the
initial analysis linking motor-tasks with speech LI scores is correlational, therefore it could be
argued that the selection of the pegboard and coin-rotation tasks was relatively arbitrary.
Secondly, whilst experiment 2 did show the predictive nature of the motor task lateralisation

r42 indices on speech indices, it is not possible to draw conclusions about underlying neural

architecture based on these data alone. Instead the data can only be used to make assumptions

that may prove useful in shaping future research paradigms investigating the relationshipbetween speech and motor-skill.

746

747 6. Conclusions

These studies demonstrate that the relationship between speech and motor networks can be 748 investigated with a behavioural imaging paradigm, hereby bridging the practice-imaging gap, 749 by integrating praxis tasks typical to neuropsychological assessments of motor function, with 750 tasks optimised for imaging paradigms. The data suggest that the relationship between left-751 hemisphere involvement in motor-skill tasks is mediated by the components of the task, and 752 that where these components are complex and sequential in nature, and thus resemble speech 753 754 production, there will be overlap in the activation patterns observed. This has implications for the design of future studies which should aim to explore the component processing of motor-755 skill activation further, and should explore whether lateralisation patterns are consistent 756 within individuals, across tasks and across modalities from an imaging perspective. 757

758

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924 Table 1. Theoretical overview of the how each task relates to component processes of the925 Pegboard.

	Sequencing	Finger Dexterity	Psychomotor speed	Grip and Release	Arm Movement
Electronic Pegboard	Х	Х	Х	Х	Х
Coin Rotation	Х	Х	Х	Х	
Peg Placing			X	Х	Х
Pen and Paper Dotting	Х		Х		Х
Finger Tapping		Х	Х		
Grip Strength				Х	

Table 2. Performance data for the 6 hand-skill tasks, means and standard deviations. PH =

Preferred Hand; NPH = Non-Preferred Hand

	Mean	Standard deviation
Peg Placing PH (secs)	35.11	4.59
Peg Placing NPH (secs)	35.43	4.35
Peg Board PH (secs)	22.96	1.91
Peg Board NPH (secs)	23.76	2.73
Finger Tapping PH (secs)	1.89	.3
Finger Tapping NPH (secs)	1.88	.3
Pen & Paper Dotting PH (secs)	22.79	3.59
Pen & Paper Dotting NPH (secs)	26.9	5.33
Coin Rotation NPH (secs)	15.57	2.84
Coin Rotation PH (secs)	17.92	4.10
Grip Strength PH (kg)	27.64	8.81
Grip Strength NPH (kg)	26.4	9.51

Table 3. Spearman's Rho values for the LI scores from the 6 hand skill tasks and the speechLI scores from Experiment 1. * indicates p < 0.05; ** indicates p < 0.01

	Motor Task	Speech LI score
	Pegboard	35*
LIs)	Dotting	13
Preferred Hand (Mean LIs)	Peg Sorting	23
red Han	Coin Rotation	49**
Prefer	Grip	01
	Finger Tapping	13
	Pegboard	43*
n LIs)	Dotting	05
ınd (Mea	Peg Sorting	32
Non-Preferred Hand (Mean LIs)	Coin Rotation	42*
Jon-Pref	Grip	.04
4	Finger Tapping	18

Table 4. Factor loadings and communalities based on a principal components analysis withvarimax rotation for 10 items (mean task performance scores used). PH = Preferred Hand;NPH = Non-Preferred Hand

	Component	Component	Component	Communalities
	1	2	3	Communancies
Peg Placing PH	.906			.84
Peg Placing NPH	.875			.84
Peg Board PH	.644		.483	.76
Finger Tapping NPH		.931		.91
Finger Tapping PH		.883		.84
Pen & Paper Dotting PH	.614	.662		.86
Pen & Paper Dotting NPH	.422	.643		.68
Coin Rotation NPH			.903	.88
Coin Rotation PH			.831	.78
Peg Board NPH	.410		.743	.74

Table 5. Pearson correlations calculating split half reliabilities of odd and even epochs, firstly

 across each motor-task and for both hands (for experiment 2), and secondly for the word

 generation speech task for experiment 1 and experiment 2. The mean number of trials

 accepted for each task is also included. * *denotes significant correlation*

	Left Han	ıd		Right Ha	nd	
	Mean accepted trials (total = 15)	r	р	Mean accepted trials (total = 15)	r	р
Pegboard	13	.54	.02*	12	.55	.019*
Coin Rotation	14	.77	.001*	14	.55	.021*
Finger Tapping	11	.47	.05*	13	.51	.03*
	Experime	nt 1		Experime	ent 2	
	Mean accepted	r	р	Mean accepted	r	р
	trials (total $= 23$)		P	trials (total $= 23$)		P
Word Generation	21	.62	.001*	21	.68	.001*

Table 6. One sample T-tests to assess whether LI scores for the motor and speech tasks are significantly different to zero, for experiment 2. Significant results indicate that LI scores show lateralised hemispheric activation (either to the left- or right- hemisphere), and non-significant scores indicate a bilateral hemispheric activation pattern. **denotes significance*

		Left Hand				Right H	Iand	
	Mean	SD	t	р	Mean	SD	t	р
Pegboard	44	1.29	-1.55	.14	1.69	1.3	5.96	.001*
Coin Rotation	-1.69	1.1	-7.29	.001*	.57	1.4	1.88	.07
Finger Tapping	-2.1	1.14	-8.41	.001*	1.19	1.3	4.41	.001*
Word Generation	2.03	1.87	5.09	.001*	2.03	1.87	5.09	.001*

Table 7. Summary of multiple regression analysis for the motor-skill variables

predicting speech lateralisation indices.

		В	SE B	β	р
Model 1	Constant	3.16	0.64		.001
	Pegboard – Right Hand	0.66	0.3	45	.042

Note: Model 1; $R^2 = .22$ (*ps* < 0.05); excluded variables = Pegboard (Left-hand); Coin

(Left-hand); Coin (Right-hand); Finger Tapping (Lefthhand); Finger Tapping (Right-hand).

Table 8. Pearson R values for the LI scores from the three motor tasks, for right and lefthands, and for the speech LI scores from Experiment 2. * indicates p < 0.05;

	Motor Task	Speech LI score
Aean	Pegboard	45*
Right Hand (Mean LIs)	Coin Rotation	.05
Right	Finger Tapping	17
ean	Pegboard	29
Left Hand (Mean LIs)	Coin Rotation	05
Left F	Finger Tapping	.41

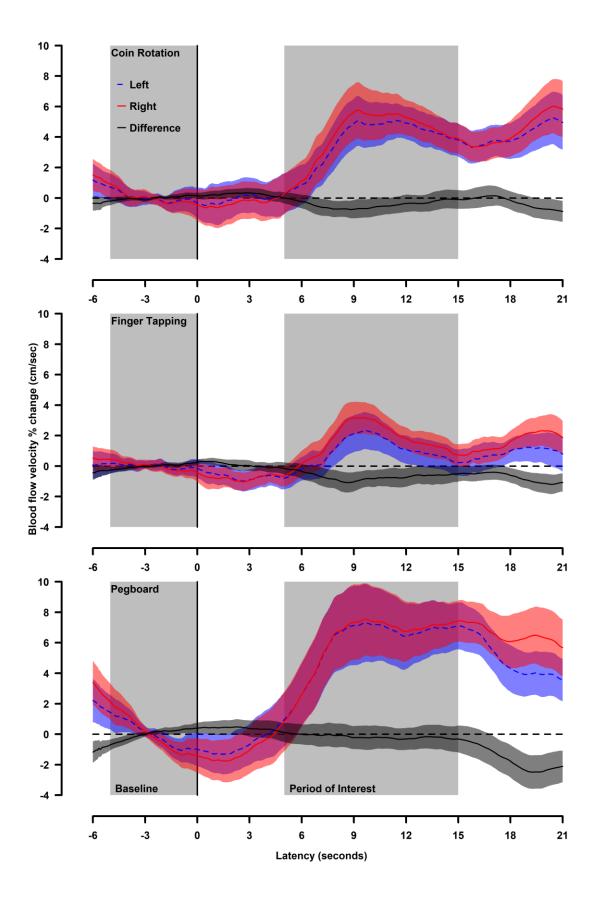


Figure 1. fTCD evoked flow plots for each task showing the left- and right-hemisphere signals, and the difference between the left and right, over the time course of an epoch. Error bars represent 95% confidence intervals.

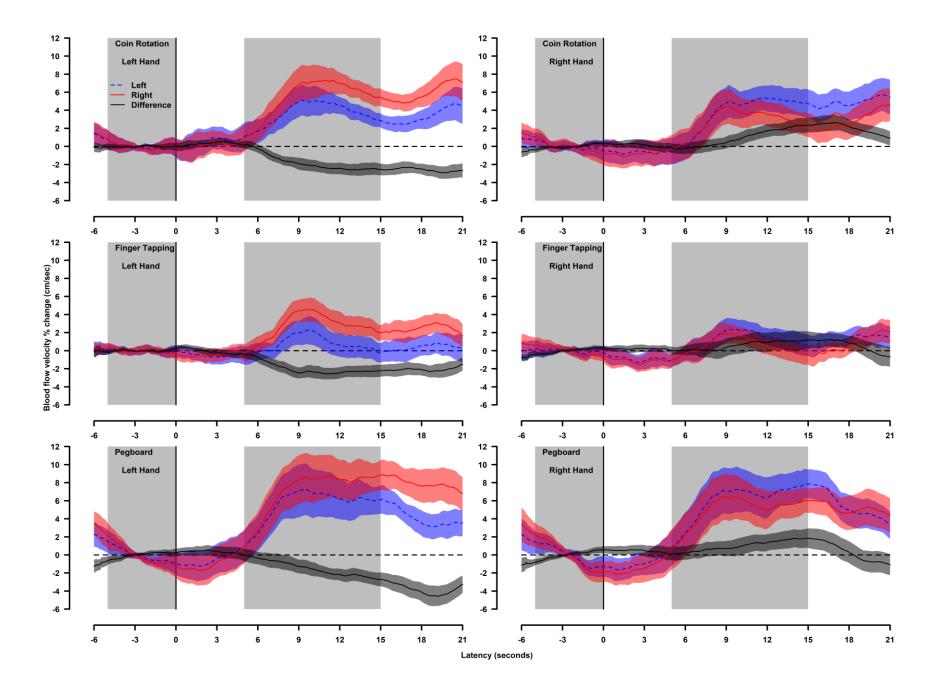


Figure 2. fTCD evoked flow plots for each task and each hand. Each plot shows the left (blue) and right (red) hemispheric activation patterns across time, with the difference between the left and right denoted in black. Error bars represent 95% confidence intervals.

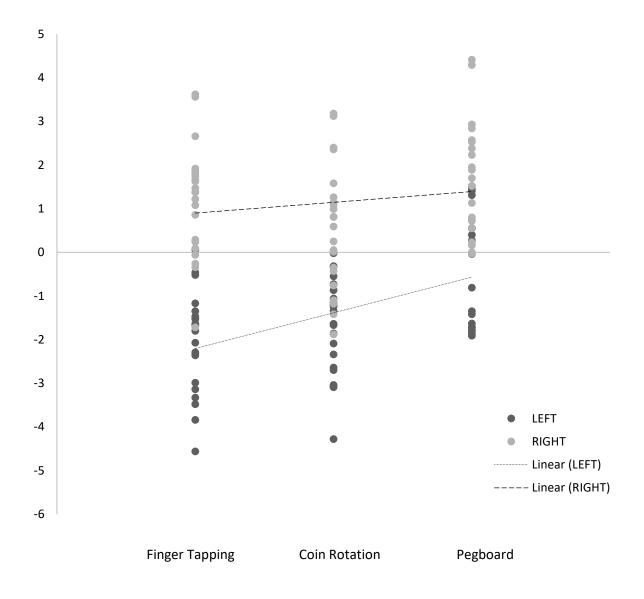


Figure 3. Plot showing mean hemispheric lateralisation index values produced by the movement of each hand, across each task. Negative values indicate right-hemisphere activation and positive values are left-hemisphere activation. Linear regression lines are fitted for the left- and right-hands.

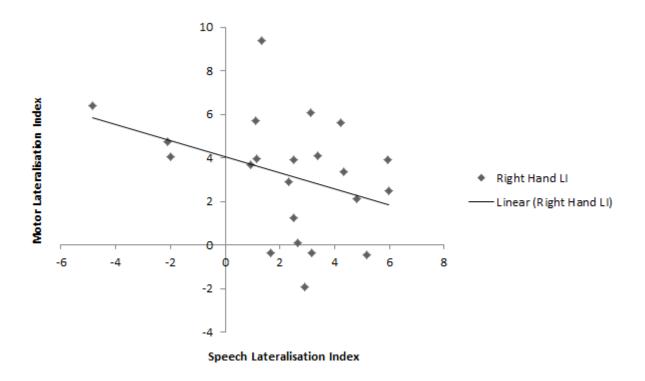


Figure 4. (Right-hand movement vs speech) Plot showing the mean lateralisation index scores for the word generation task compared to the motor lateralisation indices derived from the pegboard task, for the **right-hand**. Positive values indicate left-hemisphere activation; negative values indicate right-hemisphere activation.

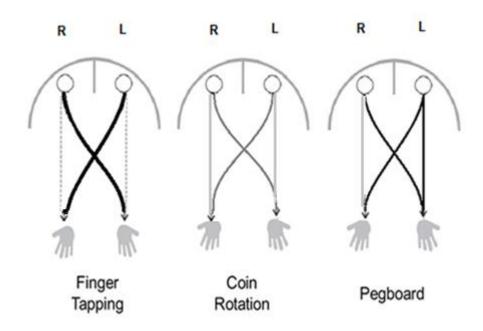


Figure 5. Schematic representing the activation patterns derived from the fTCD motor paradigm. Shading of the line relates to strength of activation. Dotted line indicates weak, but discernible activation.