# HIGHER-ORDER ENERGY EXPANSIONS AND SPIKE LOCATIONS 

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Abstract. We consider the following singularly perturbed semilinear elliptic problem:

$$
\left\{\begin{array}{l}
\epsilon^{2} \Delta u-u+f(u)=0 \text { in } \Omega  \tag{I}\\
u>0 \text { in } \Omega \text { and } \frac{\partial u}{\partial \nu}=0 \text { on } \partial \Omega
\end{array}\right.
$$

where $\Omega$ is a bounded domain in $R^{N}$ with smooth boundary $\partial \Omega, \epsilon>0$ is a small constant and $f$ is some superlinear but subcritical nonlinearity. Associated with (I) is the energy functional $J_{\epsilon}$ defined by

$$
J_{\epsilon}[u]:=\int_{\Omega}\left(\frac{\epsilon^{2}}{2}|\nabla u|^{2}+\frac{1}{2} u^{2}-F(u)\right) d x \quad \text { for } u \in H^{1}(\Omega)
$$

where $F(u)=\int_{0}^{u} f(s) d s$. Ni and Takagi ([24], [25]) proved that for a single boundary spike solution $u_{\epsilon}$, the following asymptotic expansion holds:

$$
J_{\epsilon}\left[u_{\epsilon}\right]=\epsilon^{N}\left[\frac{1}{2} I[w]-c_{1} \epsilon H\left(P_{\epsilon}\right)+o(\epsilon)\right],
$$

where $c_{1}>0$ is a generic constant, $P_{\epsilon}$ is the unique local maximum point of $u_{\epsilon}$ and $H\left(P_{\epsilon}\right)$ is the boundary mean curvature function at $P_{\epsilon} \in \partial \Omega$. In this paper, we obtain a higher-order expansion of $J_{\epsilon}\left[u_{\epsilon}\right]$ :

$$
J_{\epsilon}\left[u_{\epsilon}\right]=\epsilon^{N}\left[\frac{1}{2} I[w]-c_{1} \epsilon H\left(P_{\epsilon}\right)+\epsilon^{2}\left[c_{2}\left(H\left(P_{\epsilon}\right)\right)^{2}+c_{3} R\left(P_{\epsilon}\right)\right]+o\left(\epsilon^{2}\right)\right]
$$

where $c_{2}, c_{3}$ are generic constants and $R\left(P_{\epsilon}\right)$ is the Ricci scalar curvature at $P_{\epsilon}$. In particular $c_{3}>0$. Some applications of this expansion are given.

## 1. Introduction

We consider the following singularly perturbed semilinear elliptic problem:

$$
\left\{\begin{array}{l}
\epsilon^{2} \Delta u-b u+f(u)=0 \text { in } \Omega  \tag{1.1}\\
u>0 \text { in } \Omega \text { and } \frac{\partial u}{\partial \nu}=0 \text { on } \partial \Omega
\end{array}\right.
$$

[^0]where $\Omega$ is a bounded domain in $R^{N}$ with smooth boundary $\partial \Omega, \epsilon>0$ is a small constant, $\Delta:=\sum_{j=1}^{N} \frac{\partial^{2}}{\partial x_{j} \partial x_{j}}$ denotes the Laplace operator in $R^{N}, \nu$ stands for the unit outer normal to $\partial \Omega$ and $\partial / \partial \nu$ for the normal derivative, $b>0$ is a positive constant and $f(t)$ is a function in $C^{1+\sigma}(R) \cap C_{\mathrm{loc}}^{2}(0,+\infty)$ such that $f(0)=f^{\prime}(0)=0$. Typical examples of the function $-b u+f(u)$ are
\[

$$
\begin{align*}
& -b u+f(u)=-u+u_{+}^{p} \text { with } u_{+}=\max (0, u), \quad b=1  \tag{1.2}\\
& -b u+f(u)=u(u-a)(1-u) \text { with } 0<a<\frac{1}{2}, \quad b=a \tag{1.3}
\end{align*}
$$
\]

where

$$
\begin{equation*}
1<p<\left(\frac{N+2}{N-2}\right)_{+}\left(=\frac{N+2}{N-2} \text { when } N \geq 3 ;=+\infty \text { when } N=1,2\right)_{(1} . \tag{1.4}
\end{equation*}
$$

Equation (1.1) with (1.2) or (1.3) arises in many branches of the applied sciences. For example, it can be viewed as a steady-state equation for the shadow system of the Gierer-Meinhardt system in biological pattern formation ([13], [29], [35]) or of parabolic equations in chemotaxis, population dynamics and phase transitions ([2], [3], [23], [27]).

Without loss of generality, we may assume that $b=1$.
Associated with (1.1) is the energy functional $J_{\epsilon}$ defined by

$$
\begin{equation*}
J_{\epsilon}[u]:=\int_{\Omega}\left(\frac{\epsilon^{2}}{2}|\nabla u|^{2}+\frac{1}{2} u^{2}-F(u)\right) d x \quad \text { for } u \in H^{1}(\Omega), \tag{1.5}
\end{equation*}
$$

where $F(u)=\int_{0}^{u} f(s) d s$.
It is known that any solution $u$ of (1.1) is a critical point of $J_{\epsilon}$ and vice versa. In this paper, we restrict ourselves to families of solutions $\left\{u_{\epsilon}\right\}_{0<\epsilon<\epsilon_{0}}$ of (1.1) with finite energy, i.e.

$$
\begin{equation*}
\epsilon^{-N} J_{\epsilon}\left[u_{\epsilon}\right]<+\infty \quad \text { for } 0<\epsilon<\epsilon_{0} . \tag{1.6}
\end{equation*}
$$

It can be proved that for $\epsilon$ sufficiently small, any family of solutions of (1.1) satisfying (1.6) can have at most a finite number of local maximum points (see [24]). Let the local maximum points be $\left\{P_{1}^{\epsilon}, \ldots, P_{K}^{\epsilon}\right\} \subset \bar{\Omega}$. If $P_{j}^{\epsilon} \in \partial \Omega, j=1, \ldots, K$, we call $u_{\epsilon}$ a $K$-boundary spike solution. If $K=1$, we call $u_{\epsilon}$ a single boundary spike solution.

In the pioneering papers [23], [24] and [25], Lin, Ni and Takagi established the existence of least-energy solutions and showed that for $\epsilon$ sufficiently small the least-energy solution is a single boundary spike solution and has only one local maximum point $P_{\epsilon}$ with $P_{\epsilon} \in \partial \Omega$. Moreover, $H\left(P_{\epsilon}\right) \rightarrow \max _{P \in \partial \Omega} H(P)$ as $\epsilon \rightarrow 0$, where $H(P)$ is the mean curvature of $\partial \Omega$ at $P$.

Since then many works have been devoted to finding solutions with multiple spikes for the Neumann problem as well as the Dirichlet problem. See [1], [2], [3], [4], [6], [7], [8], [9], [10], [11], [12], [15], [16], [17], [18], [19], [21], [22], [24], [25], [26], [27], [28], [31], [32], [36], [37], and the references therein. Recent surveys can be found in [29], [35].

A common tool for proving the existence of spike solutions is the energy expansion: In [24] and [25], Ni and Takagi proved, among others, that for a single boundary spike solution $u_{\epsilon}$, the following asymptotic expansion for $J_{\epsilon}\left[u_{\epsilon}\right]$ holds:

$$
\begin{equation*}
J_{\epsilon}\left[u_{\epsilon}\right]=\epsilon^{N}\left[\frac{1}{2} I[w]-c_{1} \epsilon H\left(P_{\epsilon}\right)+o(\epsilon)\right], \tag{1.7}
\end{equation*}
$$

where $c_{1}>0$ is a generic constant, $P_{\epsilon}$ is the unique local maximum point of $u_{\epsilon}, H\left(P_{\epsilon}\right)$ is the mean curvature function at $P_{\epsilon} \in \partial \Omega, w$ is the unique solution of the following ground-state problem:

$$
\left\{\begin{array}{l}
\Delta w-w+f(w)=0, \quad w>0 \quad \text { in } R^{N}  \tag{1.8}\\
w(0)=\max _{y \in R^{N}} w(y), \quad \lim _{|y| \rightarrow+\infty} w(y)=0
\end{array}\right.
$$

and $I[w]$ is the ground-state energy

$$
\begin{equation*}
I[w]=\frac{1}{2} \int_{R^{N}}|\nabla w|^{2} d y+\frac{1}{2} \int_{R^{N}} w^{2} d y-\int_{R^{N}} F(w) d y \tag{1.9}
\end{equation*}
$$

(Note that Ni and Takagi ([24], [25]) proved (1.7) for least-energy solutions. But it is easy to see that it also holds for any single boundary spike solution.)

Based on (1.7), Ni and Takagi [25] showed that the least energy solution must concentrate at a maximum point of the mean curvature function.

If $H(P)$ has more than one maximum points on $\partial \Omega$, the asymptotic expansion (1.7) is no longer sufficient to derive the spike location and the next order term in (1.7) becomes important. This is exactly the purpose of this paper.

Before stating our main result, we introduce some notation.
First we give some conditions on the function $f(t)$ :
(f1) $f \in C^{1+\sigma}(R) \cap C_{\mathrm{loc}}^{2}(0,+\infty)$ with $0<\sigma \leq 1, f(0)=0, f^{\prime}(0)=0$ and $f(t) \equiv 0$ for $t \leq 0$.
(f2) The problem (1.8) in the whole space has a unique solution $w$, which is nondegenerate, i.e.

$$
\begin{equation*}
\text { Kernel }\left(\Delta-1+f^{\prime}(w)\right)=\operatorname{span}\left\{\frac{\partial w}{\partial y_{1}}, \ldots, \frac{\partial w}{\partial y_{N}}\right\} . \tag{1.10}
\end{equation*}
$$

By the well-known result of Gidas, Ni, and Nirenberg [14], $w$ is radially symmetric: $w(y)=w(|y|)$ and strictly decreasing: $w^{\prime}(r)<0$ for $r>0, r=$ $|y|$. Moreover, we have the following asymptotic behavior of $w$ :

$$
\begin{gather*}
w(r)=A_{N} r^{-\frac{N-1}{2}} e^{-r}\left(1+O\left(\frac{1}{r}\right)\right) \\
w^{\prime}(r)=-A_{N} r^{-\frac{N-1}{2}} e^{-r}\left(1+O\left(\frac{1}{r}\right)\right) \tag{1.11}
\end{gather*}
$$

as $r \rightarrow \infty$, where $A_{N}>0$ is a generic constant.
The uniqueness of $w$ is proved in [20] for the case $f(u)=u^{p}$. For a general nonlinearity, see [5]. For $f(u)$ defined by (1.3), the uniqueness of the entire solution was proved by Peletier and Serrin [30].

In what follows we always assume that $f(t)$ satisfies (f1) and (f2).
Next, we introduce boundary deformations.
Let $P \in \partial \Omega$. We can define a diffeomorphism straightening the boundary in a neighborhood of $P$. After rotation and translation of the coordinate system we may assume that the inward normal to $\partial \Omega$ at $P$ points in the direction of the positive $x_{N^{-}}$-axis and that $P=0$. Denote $x^{\prime}=$ $\left(x_{1}, \ldots, x_{N-1}\right), B^{\prime}(\delta)=\left\{x^{\prime} \in R^{N-1}:\left|x^{\prime}\right|<\delta\right\}$, and $\Omega_{1}=\Omega \cap B(P, \delta)$, where $B(P, \delta)=\left\{x \in R^{N}:|x-P|<\delta\right\}$.

Then, since $\partial \Omega$ is smooth, we can find a constant $\delta>0$ such that $\partial \Omega \cap$ $B(P, \delta)$ can be represented by the graph of a smooth function

$$
\begin{gathered}
\rho_{P}: B^{\prime}(\delta) \rightarrow R, \text { where } \rho_{P}(0)=0, \nabla \rho_{P}(0)=0, \text { and } \\
\Omega \cap B(P, \delta)=\left\{\left(x^{\prime}, x_{N}\right) \in B(P, \delta): x_{N}-P_{N}>\rho\left(x^{\prime}-P^{\prime}\right)\right\} .
\end{gathered}
$$

Moreover, we may assume that

$$
\begin{gathered}
\rho_{P}\left(x^{\prime}-P^{\prime}\right)=\frac{1}{2} \sum_{i=1}^{N-1} k_{i}\left(x_{i}-P_{i}\right)^{2} \\
+\frac{1}{6} \sum_{i, j, k=1}^{N-1} \rho_{i j k}(0)\left(x_{i}-P_{i}\right)\left(x_{j}-P_{j}\right)\left(x_{k}-P_{k}\right)+O\left(\left|x^{\prime}-P^{\prime}\right|^{4}\right)
\end{gathered}
$$

where

$$
\rho_{i j k}(0)=\frac{\partial^{3} \rho_{P}(0)}{\partial x_{i} \partial x_{j} \partial x_{k}}, \quad i, j, k=1, \ldots, N-1 .
$$

From now on we omit the $P$ of $\rho_{P}$ and write $\rho$ instead if this can be done without causing confusion.

Here $k_{i}, i=1, \ldots, N-1$, are the principal curvatures at $P$. Furthermore, the average of the principal curvatures of $\partial \Omega$ at $P$ is the mean curvature $H(P)=\frac{1}{N-1} \sum_{i=1}^{N-1} k_{i}$.

For $N \geq 3$, we also need to define

$$
\begin{equation*}
R(P)=\sum_{i \neq j} k_{i} k_{j}, \tag{1.12}
\end{equation*}
$$

which is called Ricci scalar curvature at $P$ (up to a constant). When $N=2$, we let $R(P)=0$.

Throughout the paper, we use the following notation:

$$
\begin{equation*}
y=\left(y^{\prime}, y_{N}\right), \quad y^{\prime}=\left(y_{1}, \ldots, y_{N-1}\right), \quad R_{+}^{N}=\left\{y \in R^{N}: y_{N}>0\right\} . \tag{1.13}
\end{equation*}
$$

Now we can state the main result of this paper.
Theorem 1.1. Let $u_{\epsilon}$ be a single boundary spike solution of (1.1) with local maximum point $P_{\epsilon} \in \partial \Omega$. Then, for $\epsilon$ sufficiently small, we have

$$
\begin{equation*}
J_{\epsilon}\left[u_{\epsilon}\right]=\epsilon^{N}\left[\frac{1}{2} I[w]-c_{1} \epsilon H\left(P_{\epsilon}\right)+\epsilon^{2}\left[c_{2}\left(H\left(P_{\epsilon}\right)\right)^{2}+c_{3} R\left(P_{\epsilon}\right)\right]+o\left(\epsilon^{2}\right)\right], \tag{1.14}
\end{equation*}
$$

where

$$
\begin{equation*}
c_{1}=\frac{N-1}{N+1} \int_{R_{+}^{N}}\left(w^{\prime}(|y|)\right)^{2} y_{N} d y>0 \tag{1.15}
\end{equation*}
$$

and $c_{2}, c_{3}$ are generic constants to be defined later (see (3.26) of Section 3). Moreover, we have $c_{3}>0$.

For multiple boundary spike solutions, we have a similar asymptotic expansion:

Theorem 1.2. Let $u_{\epsilon}$ be a $K$-boundary spike solution of (1.1) with local maximum point $P_{1}^{\epsilon}, \ldots, P_{K}^{\epsilon} \in \partial \Omega$. Let $P_{j}^{\epsilon} \rightarrow P_{j}^{0} \in \partial \Omega$. Suppose that $P_{i}^{0} \neq P_{j}^{0}$ for $i \neq j$. Then, for $\epsilon$ sufficiently small, we have
$J_{\epsilon}\left[u_{\epsilon}\right]=\epsilon^{N}\left[\frac{K}{2} I[w]-c_{1} \epsilon \sum_{j=1}^{K} H\left(P_{j}^{\epsilon}\right)+\epsilon^{2} \sum_{j=1}^{K}\left[c_{2}\left(H\left(P_{j}^{\epsilon}\right)\right)^{2}+c_{3} R\left(P_{j}^{\epsilon}\right)\right]+o\left(\epsilon^{2}\right)\right]$,
From Theorem 1.1, we can give a refinement of the results of [24] and [25]. To this end, we assume that $f$ satisfies (f1) and
(f3) For $t \geq 0, f$ admits the following decomposition in $C^{1+\sigma}(R)$ :

$$
f(t)=f_{1}(t)-f_{2}(t)
$$

where $(i) f_{1}(t) \geq 0$ and $f_{2}(t) \geq 0$ with $f_{1}(0)=f_{1}^{\prime}(0)=0$, whence it follows that $f_{2}(0)=f_{2}^{\prime}(0)=0$ by (f1); and (ii) there is a $q \geq 1$ such that $f_{1}(t) / t^{q}$ is nondecreasing in $t>0$, whereas $f_{2}(t) / t^{q}$ is nonincreasing in $t>0$, and in case $q=1$ we require further that the above monotonicity condition for $f_{1}(t) / t$ is strict,
(f4) $f(t)=O\left(t^{p}\right)$ as $t \rightarrow+\infty$ where $p$ satisfies (1.4),
(f5) There exists a constant $\theta \in\left(0, \frac{1}{2}\right)$ such that $F(t) \leq \theta t f(t)$ for $t \geq 0$.
By taking a function $e(x) \equiv k$ for some constant $k$ in $\Omega$, and choosing $k$ large enough, we have $J_{\epsilon}[e]<0$, for all $\epsilon \in(0,1)$. Then for each $\epsilon \in(0,1)$, we can define the so-called mountain-pass value

$$
\begin{equation*}
c_{\epsilon}=\inf _{h \in \Gamma} \max _{0 \leq t \leq 1} J_{\epsilon}[h(t)] \tag{1.17}
\end{equation*}
$$

where $\Gamma=\left\{h:[0,1] \rightarrow H^{1}(\Omega) \mid h(t)\right.$ is continuous, $\left.h(0)=0, h(1)=e\right\}$.
In [24] and [25], it is proved that there exists a mountain-pass solution $u_{\epsilon}$ which is also a least-energy solution. Moreover, as $\epsilon \rightarrow 0, u_{\epsilon}$ develops a spike layer behavior near a maximum point of the mean curvature function. Now we have

Corollary 1.3. Suppose that $f(u)$ satisfies (f1), (f3), (f4) and (f5). Let $u_{\epsilon}$ be a least energy solution of (1.1) (constructed in [24]) and let $P_{\epsilon}$ be the
unique local maximum point of $u_{\epsilon}$. Then, for $\epsilon$ sufficiently small, we have

$$
\begin{equation*}
H\left(P_{\epsilon}\right) \rightarrow \max _{P \in \partial \Omega} H(P), \quad R\left(P_{\epsilon}\right) \rightarrow \min _{Q \in \partial \Omega, H(Q)=\max _{P \in \partial \Omega} H(P)} R(Q) . \tag{1.18}
\end{equation*}
$$

Remark: 1. If $N=2$, (1.18) yields no new result. In that case, we have to expand $J_{\epsilon}\left[u_{\epsilon}\right]$ up to the order $O\left(\epsilon^{3}\right)$ to obtain more information on the spike locations.
2. The asymptotic expansion (1.14) shows that the Ricci scalar curvature can play an important role in the case of constant mean curvature boundary.

The proof of Theorem 1.1 is divided into three steps:

Step 1: We choose a good approximate function, concentrating at a boundary point $P$ and called $\tilde{w}_{\epsilon, P}$, such that

$$
\begin{equation*}
\epsilon^{2} \Delta \tilde{w}_{\epsilon, P}-\tilde{w}_{\epsilon, P}+f\left(\tilde{w}_{\epsilon, P}\right)=O\left(\epsilon^{1+\sigma}\right), \tag{1.19}
\end{equation*}
$$

where $\sigma$ is the Holder exponent of $f^{\prime}$ (see assumption (f1)).
This is done in Section 2.

Step 2: Our key observation is that in order to obtain the term of order $\epsilon^{2}$ in the asymptotic expansion of $J_{\epsilon}\left[u_{\epsilon}\right]$, we do not need to expand $u_{\epsilon}$ up to the order $O\left(\epsilon^{2}\right)$. In fact, it is enough to have

$$
\begin{equation*}
u_{\epsilon}=\tilde{w}_{\epsilon, P_{\epsilon}}+O\left(\epsilon^{\tau}\right) \tag{1.20}
\end{equation*}
$$

for some $\tau>1$. We choose $\tau=1+\frac{\sigma}{2}$. We do not even need to know the term of order $\epsilon^{\tau}$ in the asymptotic expansion of $u_{\epsilon}$. From (1.20) we derive that

$$
\begin{equation*}
J_{\epsilon}\left[u_{\epsilon}\right]=J_{\epsilon}\left[\tilde{w}_{\epsilon, P_{\epsilon} \epsilon}\right]+o\left(\epsilon^{N+2}\right) . \tag{1.21}
\end{equation*}
$$

This is proved in Section 5.

Step 3: It then remains to compute the energy of $\tilde{w}_{\epsilon, P}$. A higher-order energy expansion is derived Section 3 and in Section 4 it is shown that $c_{1}>0$ and $c_{3}>0$.

Finally, the proofs of Theorem 1.1, Theorem 1.2, and Corollary 1.3 are contained in Section 6.

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## 2. A suitable approximate function $\tilde{w}_{\epsilon, P}$

In this section, we introduce a suitable approximate function $\tilde{w}_{\epsilon, P}$.
Let $\Omega$ be a smooth domain in $R^{N}$ and $w$ be the unique solution of (1.8). For $P \in \partial \Omega$, we define $w_{\epsilon, P}(x)$ to be the unique solution of the following problem:

$$
\left\{\begin{array}{l}
\epsilon^{2} \Delta w_{\epsilon, P}-w_{\epsilon, P}+f\left(w\left(\frac{x-P}{\epsilon}\right)\right)=0 \text { in } \Omega,  \tag{2.1}\\
\frac{\partial w_{\epsilon, P}}{\partial \nu}=0 \text { on } \partial \Omega .
\end{array}\right.
$$

The function $w_{\epsilon, P}$ was first introduced and studied in [36]. It can be considered as a projection of $w\left(\frac{x-P}{\epsilon}\right) \in H^{1}(\Omega)$ into

$$
H_{\nu}^{1}(\Omega)=\left\{u \in H^{1}(\Omega): \frac{\partial u}{\partial \nu}=0 \text { at } \partial \Omega\right\} .
$$

Set

$$
w_{\epsilon, P}=w\left(\frac{x-P}{\epsilon}\right)-h_{\epsilon, P}(x) .
$$

Then $h_{\epsilon, P}$ satisfies

$$
\left\{\begin{array}{l}
\epsilon^{2} \Delta h_{\epsilon, P}-h_{\epsilon, P}=0 \text { in } \Omega  \tag{2.2}\\
\frac{\partial h_{\epsilon, P}}{\partial \nu}=\frac{\partial w\left(\frac{x-P}{\epsilon}\right)}{\partial \nu} \text { on } \partial \Omega
\end{array}\right.
$$

We deform the boundary near $P$ as in Section 1. For $x \in \Omega_{1}=\Omega \cap B(P, \delta)$, set now

$$
\begin{equation*}
\epsilon y^{\prime}=x^{\prime}-P^{\prime}, \quad \epsilon y_{N}=x_{N}-P_{N}-\rho\left(x^{\prime}-P^{\prime}\right) \tag{2.3}
\end{equation*}
$$

This transformation is denoted as $y=T_{\epsilon}(x)$. Note that the Jacobian of $T_{\epsilon}$ equals $\epsilon^{-N}$. Its inverse is called $x=T_{\epsilon}^{-1}(y)$. One computes that

$$
\begin{equation*}
x^{\prime}=P^{\prime}+\epsilon y^{\prime}, \quad x_{N}=P_{N}+\epsilon y_{N}+\rho\left(\epsilon y^{\prime}\right) \tag{2.4}
\end{equation*}
$$

In our coordinate system, for $x \in \omega_{1}:=\partial \Omega \cap B(P, \delta)$, we have

$$
\begin{gathered}
\nu(x)=\frac{1}{\sqrt{1+\left|\nabla_{x^{\prime}} \rho\right|^{2}}}\left(\nabla_{x^{\prime}} \rho,-1\right), \\
\frac{\partial}{\partial \nu}=\left.\frac{1}{\sqrt{1+\left|\nabla_{x^{\prime}} \rho\right|^{2}}}\left\{\sum_{j=1}^{N-1} \rho_{j} \frac{\partial}{\partial x_{j}}-\frac{\partial}{\partial x_{N}}\right\}\right|_{x_{N}-P_{N}=\rho\left(x^{\prime}-P^{\prime}\right)}
\end{gathered}
$$

and the Laplace operator becomes

$$
\begin{equation*}
\epsilon^{2} \Delta_{x}=\Delta_{y}+\left|\nabla_{x^{\prime}} \rho\right|^{2} \frac{\partial^{2}}{\partial y_{N}^{2}}-2 \sum_{i=1}^{N-1} \rho_{i} \frac{\partial^{2}}{\partial y_{i} \partial y_{N}}-\epsilon \Delta_{x^{\prime}} \rho \frac{\partial}{\partial y_{N}} \tag{2.5}
\end{equation*}
$$

We need to analyze the behavior of $h_{\epsilon, P}$ up to the order $O\left(\epsilon^{3}\right)$. To this end, we recall the following three functions introduced in [36].

Let $v_{1}$ be the unique solution of

$$
\left\{\begin{array}{l}
\Delta v_{1}-v_{1}=0 \quad \text { in } R_{+}^{N},  \tag{2.6}\\
\frac{\partial v_{1}}{\partial y_{N}}=-\frac{w^{\prime}(|y|)}{2|y|} \sum_{i=1}^{N-1} k_{i} y_{i}^{2} \quad \text { on } \partial R_{+}^{N}, ~
\end{array}\right.
$$

$v_{2}$ be the unique solution of

$$
\left\{\begin{array}{ll}
\Delta v_{2}-v_{2}-2 \sum_{i=1}^{N-1} k_{i} y_{i} \frac{\partial^{2} v_{1}}{\partial y_{i} \partial y_{N}}-\left(\sum_{i=1}^{N-1} k_{i}\right) \frac{\partial v_{1}}{\partial y_{N}}=0  \tag{2.7}\\
\frac{\partial v_{2}}{\partial y_{N}}=\sum_{i=1}^{N-1} k_{i} y_{i} \frac{\partial v_{1}}{\partial y_{i}} & \text { on } \partial R_{+}^{N},
\end{array} \quad \text { in } R_{+}^{N},\right.
$$

and $v_{3}$ be the unique solution of

$$
\left\{\begin{array}{l}
\Delta v_{3}-v_{3}=0 \quad \text { in } R_{+}^{N}  \tag{2.8}\\
\frac{\partial v_{3}}{\partial y_{N}}=-\frac{w^{\prime}}{3|y|} \sum_{i, j, k=1}^{N-1} \rho_{i j k} y_{i} y_{j} y_{k} \quad \text { on } \partial R_{+}^{N} .
\end{array}\right.
$$

Note that $v_{1}, v_{2}$ are even functions in $y^{\prime}=\left(y_{1}, \ldots, y_{N-1}\right)$ and $v_{3}$ is an odd function in $y^{\prime}=\left(y_{1}, \ldots, y_{N-1}\right)$ (i.e. $v_{1}\left(y^{\prime}, y_{N}\right)=v_{1}\left(-y^{\prime}, y_{N}\right), v_{3}\left(y^{\prime}, y_{N}\right)=$ $\left.-v_{3}\left(-y^{\prime}, y_{N}\right)\right)$. Moreover, it is easy to see that $\left|v_{1}\right|,\left|v_{2}\right|,\left|v_{3}\right| \leq C e^{-a|y|}$ for some $a>0$.

Let $\chi(x)$ be a smooth cut-off function such that $\chi(x)=1$ for $x \in B\left(0, \frac{\delta}{2}\right)$ and $\chi(x)=0$ for $x \notin B(0, \delta)$.

Set

$$
h_{\epsilon, P}(x)=\epsilon v_{1}\left(T_{\epsilon}(x)\right) \chi(x-P)+\epsilon^{2}\left[v_{2}\left(T_{\epsilon}(x)\right) \chi(x-P)\right.
$$

$$
\begin{equation*}
\left.+v_{3}\left(T_{\epsilon}(x)\right) \chi(x-P)\right]+\epsilon^{3} \Psi_{\epsilon, P}(x), \tag{2.9}
\end{equation*}
$$

where $y=T_{\epsilon}(x)$ is given in (2.3).
Then we have the following asymptotic expansion, whose proof can be found in Proposition 2.1 of [36].

Proposition 2.1. For $\epsilon$ sufficiently small,

$$
\begin{gather*}
w_{\epsilon, P}(x)=w\left(\frac{x-P}{\epsilon}\right)-\epsilon v_{1}\left(T_{\epsilon}(x)\right) \chi(x-P) \\
-\epsilon^{2}\left(v_{2}\left(T_{\epsilon}(x)\right)+v_{3}\left(T_{\epsilon}(x)\right)\right) \chi(x-P)+\epsilon^{3} \Psi_{\epsilon, P}(x), \tag{2.10}
\end{gather*}
$$

where $\Psi_{\epsilon, P}$ satisfies

$$
\begin{gather*}
\epsilon^{-N} \int_{\Omega}\left(\epsilon^{2}\left|\nabla \Psi_{\epsilon, P}\right|^{2}+\left|\Psi_{\epsilon, P}\right|^{2}\right) d x \leq C  \tag{2.11}\\
\left|\Psi_{\epsilon, P}\left(T_{\epsilon}^{-1}(y)\right)\right| \leq C e^{-a|y|} \tag{2.12}
\end{gather*}
$$

for some constant $a>0$.
Next we study the properties of the following linear operator:

$$
\begin{equation*}
L_{0}:=\Delta-1+f^{\prime}(w): \quad H^{2}\left(R^{N}\right) \rightarrow L^{2}\left(R^{N}\right) \tag{2.13}
\end{equation*}
$$

By assumption (f2),

$$
\text { Kernel }\left(L_{0}\right)=\operatorname{span}\left\{\frac{\partial w}{\partial y_{j}}: j=1, \ldots, N\right\} .
$$

If we restrict $L_{0}$ to

$$
H_{\nu}^{2}\left(R_{+}^{N}\right)=H^{2}\left(R_{+}^{N}\right) \cap\left\{\frac{\partial u}{\partial y_{N}}=0 \text { on } \partial R_{+}^{N}\right\}
$$

then we have

$$
\begin{equation*}
\text { Kernel }\left(L_{0}\right) \cap H_{\nu}^{2}\left(R_{+}^{N}\right)=\operatorname{span}\left\{\frac{\partial w}{\partial y_{j}}: j=1, \ldots, N-1\right\} . \tag{2.14}
\end{equation*}
$$

By (2.14), there is a unique solution to

$$
\left\{\begin{array}{l}
\Delta \Phi_{0}-\Phi_{0}+f^{\prime}(w) \Phi_{0}-f^{\prime}(w) v_{1}=0 \quad \text { in } R_{+}^{N}  \tag{2.15}\\
\frac{\partial \Phi_{0}}{\partial y_{N}}=0 \quad \text { on } \partial R_{+}^{N} \\
\Phi_{0} \text { is even in } y^{\prime}
\end{array}\right.
$$

We call this solution $\Phi_{0}$. We modify $\Phi_{0}$ to a new function $\Phi_{\epsilon, P}$ which satisfies the Neumann boundary condition. To this end, let $\phi_{\epsilon, P}$ be the solution of

$$
\left\{\begin{array}{l}
\epsilon^{2} \Delta \phi_{\epsilon, P}-\phi_{\epsilon, P}=0 \text { in } \Omega,  \tag{2.16}\\
\frac{\partial \phi_{\epsilon, P}}{\partial \nu}=\frac{\partial\left(\Phi_{0}\left(T_{\epsilon}(x)\right) \chi(x-P)\right)}{\partial \nu} \text { on } \partial \Omega .
\end{array}\right.
$$

Put

$$
\begin{equation*}
\Phi_{\epsilon, P}(x)=\Phi_{0}\left(T_{\epsilon}(x)\right) \chi(x-P)-\phi_{\epsilon, P}(x) . \tag{2.17}
\end{equation*}
$$

It is easy to see that $\Phi_{\epsilon, P}$ satisfies the Neumann boundary condition and $\Phi_{\epsilon, P}\left(T_{\epsilon}^{-1}(y)\right)=\Phi_{0}(y)+O\left(\epsilon e^{-a|y|}\right)$. Furthermore, $\left|\Phi_{\epsilon, P}\left(T_{\epsilon}^{-1}(y)\right)\right| \leq C e^{-a|y|}$ for some $a>0$.

Finally, we introduce the following approximate function:

$$
\begin{equation*}
\tilde{w}_{\epsilon, P}(x)=w_{\epsilon, P}(x)+\epsilon \Phi_{\epsilon, P}(x), \quad x \in \Omega . \tag{2.18}
\end{equation*}
$$

Note that $\tilde{w}_{\epsilon, P}(x)$ satisfies the Neumann boundary condition.
Our next lemma says that $\tilde{w}_{\epsilon, P}$ satisfies the equation (1.1) up to the order $O\left(\epsilon^{1+\sigma}\right)$.

Lemma 2.2. Let

$$
\begin{equation*}
S_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]:=\epsilon^{2} \Delta \tilde{w}_{\epsilon, P}-\tilde{w}_{\epsilon, P}+f\left(\tilde{w}_{\epsilon, P}\right) \tag{2.19}
\end{equation*}
$$

Then, for $\epsilon$ sufficiently small, we have

$$
\begin{equation*}
\left|S_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]\right| \leq C \epsilon^{1+\sigma} e^{-a|y|} \tag{2.20}
\end{equation*}
$$

Proof: We expand $S_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]$ :

$$
\begin{gather*}
S_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]=S_{\epsilon}\left[w_{\epsilon, P}\right]+\epsilon\left[\epsilon^{2} \Delta \Phi_{\epsilon, P}-\Phi_{\epsilon, P}+f^{\prime}\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}\right]  \tag{2.21}\\
+\left[f\left(w_{\epsilon, P}+\epsilon \Phi_{\epsilon, P}\right)-f\left(w_{\epsilon, P}\right)-\epsilon f^{\prime}\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}\right]=S_{1}+S_{2}+S_{3},
\end{gather*}
$$

where $S_{1}, S_{2}$ and $S_{3}$ are defined by the last equality.
By (2.1), Proposition 2.1 and (2.15),

$$
\begin{aligned}
S_{1}+S_{2} & =f\left(w_{\epsilon, P}\right)-f\left(w\left(\frac{x-P}{\epsilon}\right)\right)+\epsilon\left[\epsilon^{2} \Delta \Phi_{\epsilon, P}-\Phi_{\epsilon, P}+f^{\prime}\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}\right] \\
& =\left[f\left(w_{\epsilon, P}\right)-f\left(w\left(\frac{x-P}{\epsilon}\right)\right)+\epsilon v_{1} \chi f^{\prime}\left(w\left(\frac{x-P}{\epsilon}\right)\right)\right] \\
+ & \epsilon\left[\epsilon^{2} \Delta \Phi_{\epsilon, P}-\Phi_{\epsilon, P}+f^{\prime}\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}-f^{\prime}\left(w\left(\frac{x-P}{\epsilon}\right)\right) v_{1} \chi\right]
\end{aligned}
$$

$$
=O\left(\epsilon^{2} e^{-a|y|}\right)
$$

On the other hand, it follows by the mean-value theorem that

$$
\begin{equation*}
\left|f(a+b)-f(a)-f^{\prime}(a) b\right| \leq C|a|^{\sigma}|b|^{1+\sigma} \tag{2.22}
\end{equation*}
$$

for any $a, b$ such that $|b| \leq 2|a| \leq C$. Thus

$$
\begin{equation*}
S_{3}=O\left(\epsilon^{1+\sigma}\left|w_{\epsilon, P}\right|^{\sigma}\left|\Phi_{\epsilon, P}\right|^{1+\sigma}\right)=O\left(\epsilon^{1+\sigma} e^{-a|y|}\right) \tag{2.23}
\end{equation*}
$$

This proves the lemma.

## 3. The computation of $J_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]$

In this section, we compute the energy of the approximate function $\tilde{w}_{\epsilon, P}$. In the next section, we will show that $\tilde{w}_{\epsilon, P}$ contributes the energy expansion up to the order $o\left(\epsilon^{2}\right)$.

We begin with

$$
\begin{gather*}
J_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]=J_{\epsilon}\left[w_{\epsilon, P}+\epsilon \Phi_{\epsilon, P}\right] \\
=J_{\epsilon}\left[w_{\epsilon, P}\right]+\epsilon \int_{\Omega}\left(\epsilon^{2} \nabla w_{\epsilon, P} \nabla \Phi_{\epsilon, P}+w_{\epsilon, P} \Phi_{\epsilon, P}-f\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}\right) d x \\
+\epsilon^{2}\left(\frac{\epsilon^{2}}{2} \int_{\Omega}\left|\nabla \Phi_{\epsilon, P}\right|^{2} d x+\frac{1}{2} \int_{\Omega}\left|\Phi_{\epsilon, P}\right|^{2} d x-\frac{1}{2} \int_{\Omega} f^{\prime}\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}^{2} d x\right) \\
-\int_{\Omega}\left[F\left(w_{\epsilon, P}+\epsilon \Phi_{\epsilon, P}\right)-F\left(w_{\epsilon, P}\right)-\epsilon f\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}-\frac{\epsilon^{2}}{2} f^{\prime}\left(w_{\epsilon, P}\right)\left|\Phi_{\epsilon, P}\right|^{2}\right] d x . \tag{3.1}
\end{gather*}
$$

The last term in (3.1) can be estimated using (2.22):

$$
\begin{gather*}
\left.\left.\int_{\Omega}\left|F\left(w_{\epsilon, P}+\epsilon \Phi_{\epsilon, P}\right)-F\left(w_{\epsilon, P}\right)-\epsilon f\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}-\frac{\epsilon^{2}}{2} f^{\prime}\left(w_{\epsilon, P}\right)\right| \Phi_{\epsilon, P}\right|^{2} \right\rvert\, d x \\
\leq C \epsilon^{2+\sigma} \int_{\Omega} w_{\epsilon, P}^{\sigma}\left|\Phi_{\epsilon, P}\right|^{2+\sigma} d x \leq C \epsilon^{N+2+\sigma} \tag{3.2}
\end{gather*}
$$

Using (2.1) and (3.2), we see that

$$
\begin{align*}
J_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]=J_{\epsilon}\left[w_{\epsilon, P}\right] & +\epsilon \int_{\Omega}\left(f\left(w\left(\frac{x-P}{\epsilon}\right)\right)-f\left(w_{\epsilon, P}\right)\right) \Phi_{\epsilon, P} d x \\
+\frac{\epsilon^{2}}{2}\left[\epsilon^{2} \int_{\Omega}\left|\nabla \Phi_{\epsilon, P}\right|^{2} d x\right. & \left.+\int_{\Omega}\left|\Phi_{\epsilon, P}\right|^{2} d x-\int_{\Omega} f^{\prime}\left(w_{\epsilon, P}\right) \Phi_{\epsilon, P}^{2} d x\right]+o\left(\epsilon^{N+2}\right) \\
& =I_{1}+I_{2}+I_{3}+o\left(\epsilon^{N+2}\right) \tag{3.3}
\end{align*}
$$

where $I_{1}, I_{2}$ and $I_{3}$ are defined by the last equality.
We compute $I_{3}$ first. In fact, it is easy to see that

$$
\begin{gather*}
\epsilon^{-N-2} I_{3} \rightarrow \frac{1}{2} \int_{R_{+}^{N}}\left(\left|\nabla \Phi_{0}\right|^{2}+\left|\Phi_{0}\right|^{2}-f^{\prime}(w) \Phi_{0}^{2}\right) d y  \tag{3.4}\\
=-\frac{1}{2} \int_{R_{+}^{N}} f^{\prime}(w) v_{1} \Phi_{0} d y
\end{gather*}
$$

The last equality follows from equation (2.15).
Next, for $I_{2}$ we get:

$$
\begin{equation*}
\epsilon^{-N-2} I_{2} \rightarrow \int_{R_{+}^{N}} f^{\prime}(w) v_{1} \Phi_{0} d y \tag{3.5}
\end{equation*}
$$

Combining (3.4) and (3.5), we deduce that

$$
\begin{equation*}
I_{2}+I_{3}=\frac{\epsilon^{N+2}}{2} \int_{R_{+}^{N}} f^{\prime}(w) v_{1} \Phi_{0} d y+o\left(\epsilon^{N+2}\right) \tag{3.6}
\end{equation*}
$$

Now it remains to compute $I_{1}$. Using equation (2.1) and Proposition 2.1, we deduce that

$$
\begin{align*}
& I_{1}= \frac{\epsilon^{2}}{2} \int_{\Omega}\left|\nabla w_{\epsilon, P}\right|^{2} d x+\frac{1}{2} \int_{\Omega} w_{\epsilon, P}^{2} d x-\int_{\Omega} F\left(w_{\epsilon, P}\right) d x \\
&=\frac{1}{2} \int_{\Omega} f(w) w_{\epsilon, P} d x-\int_{\Omega} F\left(w_{\epsilon, P}\right) d x \\
&=\frac{1}{2} \int_{\Omega} f(w)\left(w-\epsilon v_{1} \chi-\epsilon^{2}\left(v_{2}+v_{3}\right) \chi\right) d x \\
&-\int_{\Omega} F\left(w-\epsilon v_{1} \chi-\epsilon^{2}\left(v_{2}+v_{3}\right) \chi\right) d x+o\left(\epsilon^{N+2}\right) \\
&= \int_{\Omega}\left[\frac{1}{2} w f(w)-F(w)\right] d x+\frac{\epsilon}{2} \int_{\Omega} f(w) v_{1} d x \\
&+\frac{\epsilon^{2}}{2} \int_{\Omega}\left(f(w) v_{2}-f^{\prime}(w) v_{1}^{2}\right) d x+o\left(\epsilon^{N+2}\right) . \tag{3.7}
\end{align*}
$$

Here we have used the fact that $v_{3}$ is odd in $y^{\prime}$ and hence $\int_{R_{+}^{N}} f(w) v_{3} d y=0$.
Let

$$
I_{1,1}=\int_{\Omega}\left[\frac{1}{2} w f(w)-F(w)\right] d x, \quad I_{1,2}=\int_{\Omega} f(w) v_{1} d x
$$

Now we compute these two terms up to $o\left(\epsilon^{2}\right)$. To this end, let us calculate $\frac{|x-P|}{\epsilon}$ under the transformation (2.3):

$$
\frac{|x-P|}{\epsilon}=\frac{1}{\epsilon} \sqrt{\epsilon^{2}\left|y^{\prime}\right|^{2}+\left(\epsilon y_{N}+\rho\left(\epsilon y^{\prime}\right)\right)^{2}}
$$

$$
=\sqrt{|y|^{2}+\epsilon \sum_{i=1}^{N-1} k_{i} y_{i}^{2} y_{N}+\frac{\epsilon^{2}}{3} \sum_{i, j, k=1}^{N-1} \rho_{i j k} y_{i} y_{j} y_{k} y_{N}+\frac{\epsilon^{2}}{4}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2}\right)^{2}+O\left(\epsilon^{3}|y|^{5}\right)} .
$$

We state the following useful lemma.
Lemma 3.1. Suppose that $A(|y|)$ is a radially symmetric function such that

$$
\left|A^{\prime}(|y|)\right|+\left|A^{\prime \prime}(|y|)\right|+\left|A^{\prime \prime \prime}(|y|)\right| \leq C e^{-a|y|}
$$

for some $a>0$. Then, for $\epsilon$ sufficiently small, we have

$$
\begin{gather*}
A\left(\frac{|x-P|}{\epsilon}\right)=A(|y|)+\epsilon \frac{A^{\prime}(|y|)}{2|y|} \sum_{i=1}^{N-1} k_{i} y_{i}^{2} y_{N} \\
+\epsilon^{2}\left[\frac{A^{\prime}(|y|)}{2|y|}\left(\frac{1}{3} \sum_{i, j, k=1}^{N-1} \rho_{i j k} y_{i} y_{j} y_{k} y_{N}+\frac{1}{4}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2}\right)^{2}\right)\right] \\
+\epsilon^{2}\left[\frac{A^{\prime \prime}(|y|)}{8|y|^{2}}-\frac{A^{\prime}(|y|)}{8|y|^{3}}\right]\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2}\right)^{2} y_{N}^{2}+O\left(\epsilon^{3} e^{-a|y| / 2}\right) \tag{3.9}
\end{gather*}
$$

and

$$
\begin{equation*}
\int_{\Omega} A\left(\frac{|x-P|}{\epsilon}\right) d x=\epsilon^{N} \int_{R_{+}^{N}} A(|y|) d y-\frac{1}{2} \epsilon^{N+1} H(P) \int_{\partial R_{+}^{N}} A(|y|)|y| d y^{\prime}+o\left(\epsilon^{N+2}\right) . \tag{3.10}
\end{equation*}
$$

Proof: Equation (3.9) follows by using Taylor expansion.
By (3.9), we have

$$
\begin{align*}
& \int_{\Omega} A\left(\frac{|x-P|}{\epsilon}\right) d x=\epsilon^{N} \int_{R_{+}^{N}} A(|y|) d y+\epsilon^{N+1} \int_{R_{+}^{N}} \frac{A^{\prime}(|y|)}{2|y|}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2} y_{N}\right) d y \\
& +\epsilon^{N+2} \int_{R_{+}^{N}}\left[\frac{A^{\prime}(|y|)}{8|y|}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2}\right)^{2}+\frac{\left(A^{\prime}(|y|) /|y|\right)^{\prime}}{8|y|}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2} y_{N}\right)^{2}\right] d y+o\left(\epsilon^{N+2}\right) . \tag{3.11}
\end{align*}
$$

The last term can be estimated as follows:

$$
\begin{gather*}
\int_{R_{+}^{N}}\left[\frac{A^{\prime}(|y|)}{8|y|}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2}\right)^{2}+\frac{\left(A^{\prime}(|y|) /|y|\right)^{\prime}}{8|y|}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2} y_{N}\right)^{2}\right] d y \\
\left.=\frac{1}{8} \int_{R_{+}^{N}} \frac{A^{\prime}(|y|)}{|y|}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2}\right)^{2} d y+\frac{1}{8} \int_{R_{+}^{N}} y_{N} \frac{\partial\left(A^{\prime}(|y|) /|y|\right)}{\partial y_{N}}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2}\right)^{2} d y\right] \\
=\frac{1}{8} \int_{R_{+}^{N}} \frac{\partial}{\partial y_{N}}\left(\frac{A^{\prime}(|y|)}{|y|} y_{N}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2}\right)^{2}\right) d y=0 . \tag{3.12}
\end{gather*}
$$

Substituting (3.12) into (3.11), we obtain the lemma.
From Lemma 3.1, it follows that

$$
\begin{gather*}
I_{1,1}=\epsilon^{N} \int_{R_{+}^{N}}\left[\frac{1}{2} w f(w)-F(w)\right] d y \\
+\epsilon^{N+1} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}}\left[\frac{1}{4} w f^{\prime}(w)-\frac{1}{4} f(w)\right] \frac{w^{\prime}}{|y|} y_{N} y_{i}^{2} d y+o\left(\epsilon^{N+2}\right) \\
=\epsilon^{N} \frac{1}{2} I[w]-\epsilon^{N+1} \frac{H(P)}{4} \int_{\partial R_{+}^{N}}[w f(w)-2 F(w)]|y|^{2} d y^{\prime}+o\left(\epsilon^{N+2}\right) . \tag{3.13}
\end{gather*}
$$

Using Lemma 3.1 and (2.6), we see that

$$
\begin{aligned}
& I_{1,2}=\epsilon^{N} \int_{R_{+}^{N}} f(w) v_{1} d y+\epsilon^{N+1} \int_{R_{+}^{N}} \frac{f^{\prime}(w) w^{\prime}}{2|y|}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2} y_{N}\right) v_{1}(y) d y+O\left(\epsilon^{N+2}\right) \\
& =\epsilon^{N} \frac{H(P)}{2} \int_{\partial R_{+}^{N}} w w^{\prime}|y| d y^{\prime}+\epsilon^{N+1} \int_{R_{+}^{N}} \frac{f^{\prime}(w) w^{\prime}}{2|y|}\left(\sum_{i=1}^{N-1} k_{i} y_{i}^{2} y_{N}\right) v_{1}(y) d y+O\left(\epsilon^{N+2}\right) .
\end{aligned}
$$

Combining the estimates for $I_{1,1}, I_{1,2}, I_{2}, I_{3}$, we arrive at

$$
\begin{equation*}
J_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]=\frac{\epsilon^{N}}{2} I(w)-c_{1} \epsilon^{N+1} H(P)+\epsilon^{N+2} A_{0}+o\left(\epsilon^{N+2}\right), \tag{3.15}
\end{equation*}
$$

where

$$
\begin{equation*}
c_{1}=\frac{1}{4} \int_{\partial R_{+}^{N}}\left[w f(w)-2 F(w)-2 \frac{w w^{\prime}}{|y|}\right]|y|^{2} d y^{\prime} \tag{3.16}
\end{equation*}
$$

and

$$
\begin{align*}
A_{0}= & \frac{1}{2} \int_{R_{+}^{N}} f^{\prime}(w) v_{1}\left(\Phi_{0}-v_{1}\right) d y+\frac{1}{2} \int_{R_{+}^{N}} f(w) v_{2} d y \\
& +\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} \frac{f^{\prime}(w) w^{\prime}}{|y|} y_{i}^{2} y_{N} v_{1}(y) d y \tag{3.17}
\end{align*}
$$

Now we are going to simplify $A_{0}$. Let $\Phi_{i}, i=1, \ldots, N-1$, be the unique solution of the following problem:

$$
\left\{\begin{array}{l}
\Delta \Phi_{i}-\Phi_{i}+f^{\prime}(w) \Phi_{i}=0 \quad \text { in } R_{+}^{N},  \tag{3.18}\\
\frac{\partial \Phi_{i}}{\partial y_{N}}=\frac{w^{\prime}(|y|)}{|y|} y_{i}^{2} \quad \text { on } \partial R_{+}^{N}, \\
\Phi_{i} \text { is even in } y^{\prime} .
\end{array}\right.
$$

Note that $\Phi_{i}, i=2, \ldots, N-1$, can be obtained from $\Phi_{1}$ by rotation. This fact will be used frequently.

We claim that

## Lemma 3.2.

$$
\begin{equation*}
A_{0}=\frac{1}{8}\left(\sum_{i=1}^{N-1} k_{i}\right)^{2} \int_{\partial R_{+}^{N}} \Phi_{1} \frac{\partial \Phi_{1}}{\partial y_{N}} d y^{\prime}+\frac{1}{8} \sum_{i \neq j} k_{i} k_{j} \int_{\partial R_{+}^{N}} \Phi_{1} \frac{\partial\left(\Phi_{2}-\Phi_{1}\right)}{\partial y_{N}} d y^{\prime} \tag{3.19}
\end{equation*}
$$

Proof: First, using the equations (2.6) and (2.15), we obtain

$$
\begin{gathered}
\frac{1}{2} \int_{R_{+}^{N}} f^{\prime}(w) v_{1}\left(\Phi_{0}-v_{1}\right) d y=-\frac{1}{2} \int_{R_{+}^{N}} v_{1}\left(\Delta \Phi_{0}-\Phi_{0}\right) d y \\
=-\frac{1}{2} \int_{R_{+}^{N}}\left(\Delta v_{1}-v_{1}\right) \Phi_{0} d y-\frac{1}{2} \int_{\partial R_{+}^{N}} \Phi_{0} \frac{\partial v_{1}}{\partial y_{N}} d y^{\prime}=\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{\partial R_{+}^{N}} \frac{w^{\prime}}{|y|} \Phi_{0} y_{i}^{2} d y^{\prime} . \\
(3.20)
\end{gathered}
$$

Next, using (2.7),

$$
\begin{gathered}
\frac{1}{2} \int_{R_{+}^{N}} f(w) v_{2} d y=-\frac{1}{2} \int_{R_{+}^{N}}(\Delta w-w) v_{2} d y \\
=-\frac{1}{2} \int_{R_{+}^{N}}\left(\Delta v_{2}-v_{2}\right) w d y+\frac{1}{2} \int_{\partial R_{+}^{N}}\left(v_{2} \frac{\partial w}{\partial y_{N}}-w \frac{\partial v_{2}}{\partial y_{N}}\right) d y^{\prime} \\
=-\frac{1}{2} \int_{R_{+}^{N}}\left(2 \sum_{i=1}^{N-1} k_{i} y_{i} \frac{\partial^{2} v_{1}}{\partial y_{i} y_{N}}+\sum_{i=1}^{N-1} k_{i} \frac{\partial v_{1}}{\partial y_{N}}\right) w d y-\frac{1}{2} \int_{\partial R_{+}^{N}} w \sum_{i=1}^{N-1} k_{i} y_{i} \frac{\partial v_{1}}{\partial y_{i}} d y^{\prime} \\
=\sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} \frac{\partial\left(y_{i} w\right)}{\partial y_{i}} \frac{\partial v_{1}}{\partial y_{N}} d y-\frac{1}{2} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} w \frac{\partial v_{1}}{\partial y_{N}} d y+\frac{1}{2} \sum_{i=1}^{N-1} k_{i} \int_{\partial R_{+}^{N}} v_{1} \frac{\partial\left(w y_{i}\right)}{\partial y_{i}} d y^{\prime} \\
=\sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} y_{i} \frac{\partial w}{\partial y_{i}} \frac{\partial v_{1}}{\partial y_{N}} d y+\frac{1}{2} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} w \frac{\partial v_{1}}{\partial y_{N}} d y+\frac{1}{2} \sum_{i=1}^{N-1} k_{i} \int_{\partial R_{+}^{N}} v_{1} \frac{\partial\left(w y_{i}\right)}{\partial y_{i}} d y^{\prime} \\
=\sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} y_{i} \frac{\partial w}{\partial y_{i}} \frac{\partial v_{1}}{\partial y_{N}} d y-\frac{1}{2} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} v_{1} \frac{\partial w}{\partial y_{N}} d y+\frac{1}{2} \sum_{i=1}^{N-1} k_{i} \int_{\partial R_{+}^{N}} v_{1} y_{i} \frac{\partial w}{\partial y_{i}} d y^{\prime} \\
=-\sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} y_{i} \frac{\partial^{2} w}{\partial y_{i} \partial y_{N}} v_{1} d y-\frac{1}{2} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} v_{1} \frac{\partial w}{\partial y_{N}} d y-\frac{1}{2} \sum_{i=1}^{N-1} k_{i} \int_{\partial R_{+}^{N}} v_{1} \frac{w^{\prime}}{|y|} y_{i}^{2} d y^{\prime} . \\
(3.21)
\end{gathered}
$$

Finally,

$$
\begin{gathered}
\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} f^{\prime}(w) \frac{w^{\prime}}{|y|} y_{i}^{2} y_{N} v_{1} d y=\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} y_{i}^{2} \frac{\partial f(w)}{\partial y_{N}} v_{1} d y \\
=-\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} y_{i}^{2}\left(\Delta \frac{\partial w}{\partial y_{N}}-\frac{\partial w}{\partial y_{N}}\right) v_{1} d y
\end{gathered}
$$

$$
\begin{gather*}
=\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{\partial R_{+}^{N}} v_{1} y_{i}^{2} \frac{w^{\prime}}{|y|} d y^{\prime}-\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}}\left[4 y_{i} \frac{\partial v_{1}}{\partial y_{i}}+2 v_{1}\right] \frac{\partial w}{\partial y_{N}} d y \\
=\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{\partial R_{+}^{N}} v_{1} \frac{w^{\prime}}{|y|} y_{i}^{2} d y^{\prime}+\sum_{i=1}^{N-1} k_{i} \int_{R_{+}^{N}} y_{i} \frac{\partial^{2} w}{\partial y_{i} \partial y_{N}} v_{1} d y \\
+\frac{\sum_{i=1}^{N-1} k_{i}}{2} \int_{R_{+}^{N}} v_{1} \frac{\partial w}{\partial y_{N}} d y \tag{3.22}
\end{gather*}
$$

Combining (3.20), (3.21) and (3.22), we have

$$
\begin{align*}
A_{0} & =\frac{1}{4} \sum_{i=1}^{N-1} k_{i} \int_{\partial R_{+}^{N}}\left(\Phi_{0}-v_{1}\right) \frac{w^{\prime}}{|y|} y_{i}^{2} d y^{\prime} \\
& =\frac{1}{8} \sum_{i, j=1}^{N-1} k_{i} k_{j} \int_{\partial R_{+}^{N}} \Phi_{j} \frac{\partial \Phi_{i}}{\partial y_{N}} d y^{\prime} . \tag{3.23}
\end{align*}
$$

By symmetry, we have

$$
\begin{gather*}
\int_{\partial R_{+}^{N}} \Phi_{i} \frac{\partial \Phi_{i}}{\partial y_{N}} d y^{\prime}=\int_{\partial R_{+}^{N}} \Phi_{1} \frac{\partial \Phi_{1}}{\partial y_{N}} d y^{\prime}, \quad i=1, \ldots, N-1, \\
\int_{\partial R_{+}^{N}} \Phi_{k} \frac{\partial \Phi_{l}}{\partial y_{N}} d y^{\prime}=\int_{\partial R_{+}^{N}} \Phi_{1} \frac{\partial \Phi_{2}}{\partial y_{N}} d y^{\prime}, \quad k, l=1, \ldots, N-1, k \neq l . \tag{3.24}
\end{gather*}
$$

Hence

$$
\begin{gather*}
A_{0}=\frac{1}{8}\left(\sum_{i=1}^{N-1} k_{i}\right)^{2} \int_{\partial R_{+}^{N}} \Phi_{1} \frac{\partial \Phi_{1}}{\partial y_{N}} d y^{\prime}+\frac{1}{8} \sum_{i \neq j} k_{i} k_{j} \int_{\partial R_{+}^{N}} \Phi_{1} \frac{\partial\left(\Phi_{2}-\Phi_{1}\right)}{\partial y_{N}} d y^{\prime} \\
=c_{2}(H(P))^{2}+c_{3} R(P) \tag{3.25}
\end{gather*}
$$

where

$$
\begin{equation*}
c_{2}=\frac{(N-1)^{2}}{8} \int_{\partial R_{+}^{N}} \Phi_{1} \frac{\partial \Phi_{1}}{\partial y_{N}} d y^{\prime}, \quad c_{3}=\frac{1}{8} \int_{\partial R_{+}^{N}} \Phi_{1} \frac{\partial\left(\Phi_{2}-\Phi_{1}\right)}{\partial y_{N}} d y^{\prime} \tag{3.26}
\end{equation*}
$$

In summary, we have derived the following proposition.

Proposition 3.3. Let $P \in \partial \Omega$ and $\tilde{w}_{\epsilon, P}$ be defined at (2.18). Then, for $\epsilon$ sufficiently small, we have

$$
\begin{equation*}
J_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]=\epsilon^{N}\left[\frac{1}{2} I[w]-c_{1} \epsilon H(P)+\epsilon^{2}\left[c_{2}(H(P))^{2}+c_{3} R(P)\right]+o\left(\epsilon^{2}\right)\right], \tag{3.27}
\end{equation*}
$$

where $c_{1}, c_{2}, c_{3}$ are the generic constants defined by (3.16) and (3.26), respectively.

## 4. The signs of $c_{1}$ And $c_{3}$

In this section, we study the constants $c_{1}$ and $c_{3}$. Even though we can not compute them explicitly, we can determine their signs.

We begin with $c_{1}$. Since $w$ is radially symmetric, integration by parts gives

$$
c_{1}=\frac{1}{4} \int_{\partial R_{+}^{N}}\left[\left(w^{\prime}\right)^{2}+w^{2}-2 F(w)\right]|y|^{2} d y^{\prime}
$$

By Lemma 3.3 of [24],

$$
\begin{gather*}
c_{1}=\frac{N-1}{4} \int_{R_{+}^{N}}\left[\left(w^{\prime}\right)^{2}+w^{2}-2 F(w)\right] y_{N} d y^{\prime} \\
\quad=\frac{N-1}{N+1} \int_{R_{+}^{N}}\left(w^{\prime}(|y|)\right)^{2} y_{N} d y>0 . \tag{4.1}
\end{gather*}
$$

The sign of $c_{3}$ is more difficult to determine. To this end, we begin with the following lemma.

Lemma 4.1. Consider the following eigenvalue problem:

$$
\left\{\begin{array}{l}
\Delta \phi-\phi+f^{\prime}(w) \phi=\lambda \phi, \quad \phi \in H^{2}\left(R_{+}^{N}\right)  \tag{4.2}\\
\frac{\partial \phi}{\partial y_{N}}=0 \text { on } \partial R_{+}^{N}
\end{array}\right.
$$

Then we can arrange the eigenvalues in such a way that

$$
\lambda_{1}>0=\lambda_{2}>\lambda_{3}>\ldots
$$

where the eigenspace to $\lambda_{1}$ is spanned by a radially symmetric eigenfunction $\Psi_{1}$ which can be made positive. The eigenspace to $\lambda_{2}=0$ is $(N-1)$ dimensional and is spanned by $\frac{\partial w}{\partial y_{j}}, j=1, \ldots, N-1$.

Proof: The fact that the eigenspace to $\lambda_{2}=0$ is spanned by $\frac{\partial w}{\partial y_{j}}, j=$ $1, \ldots, N-1$ follows from assumption (f2). The first eigenvalue $\lambda_{1}$ is called principal eigenvalue and it is a standard result that the corresponding eigenspace is spanned by a radially symmetric eigenfunction which can be made positive.

The fact that $\lambda_{1}>\lambda_{2}=0$ follows from Proposition 1.3 of [2].
We define the following quadratic form:

$$
\begin{equation*}
Q[\phi]:=\frac{\int_{R_{+}^{N}}\left(|\nabla \phi|^{2}+\phi^{2}-f^{\prime}(w) \phi^{2}\right) d y}{\int_{R_{+}^{N}} \phi^{2} d y} \text { for } \phi \in H^{1}\left(R_{+}^{N}\right), \phi \not \equiv 0 . \tag{4.3}
\end{equation*}
$$

Lemma 4.1 implies the following inequality.
Lemma 4.2. We have

$$
\begin{equation*}
-\lambda_{3}=\int_{\int_{R_{+}^{N}} \phi \Psi_{1} d y=\int_{R_{+}^{N}} \inf _{\phi \frac{\partial w}{\partial y_{j}}} d y=0, j=1, \ldots, N-1} Q[\phi]>0 . \tag{4.4}
\end{equation*}
$$

Now we claim
Lemma 4.3. We have $c_{3}>0$.
Proof: Since $\Phi_{i}$ is even in $y^{\prime}$, we see that

$$
\begin{equation*}
\int_{R_{+}^{N}}\left(\Phi_{1}-\Phi_{2}\right) \frac{\partial w}{\partial y_{j}} d y=0, \quad j=1, \ldots, N-1 \tag{4.5}
\end{equation*}
$$

Since $\Psi_{1}$ is radially symmetric, we also get

$$
\begin{equation*}
\int_{R_{+}^{N}}\left(\Phi_{1}-\Phi_{2}\right) \Psi_{1} d y=0 \tag{4.6}
\end{equation*}
$$

Now we compute

$$
\begin{gathered}
\int_{R_{+}^{N}}\left[\left|\nabla\left(\Phi_{1}-\Phi_{2}\right)\right|^{2}+\left|\Phi_{1}-\Phi_{2}\right|^{2}-f^{\prime}(w)\left(\Phi_{1}-\Phi_{2}\right)^{2}\right] d y \\
=-\int_{R_{+}^{N}}\left(\Phi_{1}-\Phi_{2}\right) \frac{\partial\left(\Phi_{1}-\Phi_{2}\right)}{\partial y_{N}} d y \\
=\int_{R_{+}^{N}} \Phi_{1} \frac{\partial\left(\Phi_{2}-\Phi_{1}\right)}{\partial y_{N}} d y+\int_{R_{+}^{N}} \Phi_{2} \frac{\partial\left(\Phi_{1}-\Phi_{2}\right)}{\partial y_{N}} d y
\end{gathered}
$$

By symmetry of $\Phi_{1}$ and $\Phi_{2}$, we see that

$$
\int_{R_{+}^{N}} \Phi_{1} \frac{\partial\left(\Phi_{2}-\Phi_{1}\right)}{\partial y_{N}} d y+\int_{R_{+}^{N}} \Phi_{2} \frac{\partial\left(\Phi_{1}-\Phi_{2}\right)}{\partial y_{N}} d y
$$

$$
\begin{equation*}
=2 \int_{R_{+}^{N}} \Phi_{1} \frac{\partial\left(\Phi_{2}-\Phi_{1}\right)}{\partial y_{N}} d y=16 c_{3} . \tag{4.7}
\end{equation*}
$$

By (4.5), (4.6) and Lemma 4.2, we have

$$
\begin{equation*}
16 c_{3}=\left(\int_{R_{+}^{N}}\left|\Phi_{1}-\Phi_{2}\right|^{2} d y\right) Q\left[\Phi_{1}-\Phi_{2}\right]>0 . \tag{4.8}
\end{equation*}
$$

## 5. The asymptotic Behavior of $u_{\epsilon}$ and $J_{\epsilon}\left[u_{\epsilon}\right]$

Let $u_{\epsilon}$ be a single boundary spike solution of (1.1) and $P_{\epsilon}$ be its local maximum point. In this section, we compute the energy of $u_{\epsilon}$. The key observation is that by using $\tilde{w}_{\epsilon, P_{\epsilon}}$ as our approximating function, we just need to expand $u_{\epsilon}$ up to $O\left(\epsilon^{\tau}\right)$ for some $\tau>1$. Now we choose $\tau=1+\frac{\sigma}{2}$.

We first prove the following theorem.
Theorem 5.1. For $\epsilon$ sufficiently small, we have

$$
\begin{equation*}
u_{\epsilon}=\tilde{w}_{\epsilon, P_{\epsilon}}+\epsilon^{\tau} \phi_{\epsilon}, \tag{5.1}
\end{equation*}
$$

where $\phi_{\epsilon}$ satisfies

$$
\begin{equation*}
\left\|\phi_{\epsilon}\right\|_{L^{\infty}(\bar{\Omega})}+\epsilon^{-N} \int_{\Omega}\left(\epsilon^{2}\left|\nabla \phi_{\epsilon}\right|^{2}+\left|\phi_{\epsilon}\right|^{2}\right) \leq C . \tag{5.2}
\end{equation*}
$$

Let us first assume that Theorem 5.1 holds. We then have
Lemma 5.2. For $\epsilon$ sufficiently small, we have

$$
\begin{equation*}
J_{\epsilon}\left[u_{\epsilon}\right]=J_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]+o\left(\epsilon^{N+2}\right) . \tag{5.3}
\end{equation*}
$$

Proof of Lemma 5.2: Note that both $\tilde{w}_{\epsilon, P_{\epsilon}}$ and $\phi_{\epsilon}$ satisfy the Neumann boundary condition. So we have

$$
\begin{gathered}
J_{\epsilon}\left[u_{\epsilon}\right]=J_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right] \\
+\epsilon^{\tau} \int_{\Omega}\left(\epsilon^{2} \nabla \tilde{w}_{\epsilon, P} \nabla \phi_{\epsilon}+\tilde{w}_{\epsilon, P} \phi_{\epsilon}-f\left(\tilde{w}_{\epsilon, P}\right) \phi_{\epsilon}\right) d x \\
+\frac{\epsilon^{2 \tau}}{2}\left(\int_{\Omega}\left(\epsilon^{2}\left|\nabla \phi_{\epsilon}\right|^{2}+\left|\phi_{\epsilon}\right|^{2}\right) d x-\int_{\Omega} f^{\prime}\left(\tilde{w}_{\epsilon, P_{\epsilon}}\right) \phi_{\epsilon}^{2} d x\right) \\
-\int_{\Omega}\left[F\left(\tilde{w}_{\epsilon, P_{\epsilon}}+\epsilon^{\tau} \phi_{\epsilon}\right)-F\left(\tilde{w}_{\epsilon, P_{\epsilon}}\right)-\epsilon^{\tau} f\left(\tilde{w}_{\epsilon, P_{\epsilon}}\right) \phi_{\epsilon}-\frac{\epsilon^{2 \tau}}{2} f^{\prime}\left(\tilde{w}_{\left.\epsilon, P_{\epsilon}\right)}\right) \phi_{\epsilon}^{2}\right] d x .
\end{gathered}
$$

By Theorem 5.1, the last two terms are $O\left(\epsilon^{N+2 \tau}\right)$. Now, integrating by parts, we obtain that

$$
\begin{aligned}
& \epsilon^{\tau} \int_{\Omega}\left(\epsilon^{2} \nabla \tilde{w}_{\epsilon, P} \nabla \phi_{\epsilon}+\tilde{w}_{\epsilon, P} \phi_{\epsilon}-f\left(\tilde{w}_{\epsilon, P}\right) \phi_{\epsilon}\right) d x \\
& \quad=\epsilon^{\tau} \int_{\Omega} S_{\epsilon}\left[\tilde{w}_{\left.\epsilon, P_{\epsilon}\right]}\right] \phi_{\epsilon} d x=O\left(\epsilon^{N+\tau+1+\sigma}\right) .
\end{aligned}
$$

This finishes the proof of Lemma 5.2.
We are now ready to prove Theorem 5.1. The key step is the following lemma.

Lemma 5.3. For $\epsilon$ sufficiently small, we have

$$
\begin{equation*}
\left\|\phi_{\epsilon}\right\|_{L^{\infty}(\bar{\Omega})} \leq C \tag{5.4}
\end{equation*}
$$

Proof: Recall

$$
S_{\epsilon}[u]=\epsilon^{2} \Delta u-u+f(u), \quad S_{\epsilon}^{\prime}[u](\phi)=\epsilon^{2} \Delta \phi-\phi+f^{\prime}(u) \phi .
$$

Then, substituting $u_{\epsilon}=\tilde{w}_{\epsilon, P_{\epsilon}}+\epsilon^{\tau} \phi_{\epsilon}$ into equation (1.1), we see that $\phi_{\epsilon}$ satisfies

$$
\left\{\begin{array}{l}
\epsilon^{2} \Delta \phi_{\epsilon}-\phi_{\epsilon}+f^{\prime}\left(\tilde{w}_{\epsilon, P_{\epsilon}}\right) \phi_{\epsilon}=-\epsilon^{-\tau} S_{\epsilon}\left[\tilde{w}_{\epsilon, P_{\epsilon}}\right]+N_{\epsilon}\left[\phi_{\epsilon}\right] \text { in } \Omega  \tag{5.5}\\
\frac{\partial \phi_{\epsilon}}{\partial \nu}=0 \text { on } \partial \Omega
\end{array}\right.
$$

where

$$
\begin{equation*}
N_{\epsilon}\left[\phi_{\epsilon}\right]=-\epsilon^{-\tau}\left[f\left(\tilde{w}_{\epsilon, P_{\epsilon}}+\epsilon^{\tau} \phi_{\epsilon}\right)-f\left(\tilde{w}_{\epsilon, P_{\epsilon}}\right)-\epsilon^{\tau} f^{\prime}\left(\tilde{w}_{\epsilon, P_{\epsilon}}\right) \phi_{\epsilon}\right] . \tag{5.6}
\end{equation*}
$$

From Lemma 2.2, we have

$$
\begin{equation*}
\epsilon^{-\tau} S_{\epsilon}\left[\tilde{w}_{\epsilon, P_{\epsilon}}\right]=O\left(\epsilon^{\sigma / 2}\right) \tag{5.7}
\end{equation*}
$$

By the mean value theorem, we get

$$
\begin{equation*}
\left|N_{\epsilon}\left[\phi_{\epsilon}\right]\right|=o(1)\left|\phi_{\epsilon}\right| . \tag{5.8}
\end{equation*}
$$

Now we can prove Lemma 5.2. Suppose not, that is there exists a sequence $\epsilon_{k} \rightarrow 0$ such that $\left\|\phi_{\epsilon_{k}}\right\|_{L^{\infty}(\bar{\Omega})} \rightarrow+\infty$. For simplicity of notation, we still denote $\epsilon_{k}$ as $\epsilon$. Set

$$
M_{\epsilon}=\left\|\phi_{\epsilon}\right\|_{L^{\infty}(\bar{\Omega})} \rightarrow+\infty .
$$

Let $M_{\epsilon}=\left|\phi_{\epsilon}\left(x_{\epsilon}\right)\right|$, where $x_{\epsilon} \in \bar{\Omega}$. Without loss of generality, we may assume that $x_{\epsilon}$ is a maximum point of $\phi_{\epsilon}$.

We proceed in two claims.

Claim 1: $\frac{\left|x_{\epsilon}-P_{\epsilon}\right|}{\epsilon} \leq C$.
In fact, suppose not. That is $\frac{\left|x_{\epsilon}-P_{\epsilon}\right|}{\epsilon} \rightarrow+\infty$. Then $-1+f^{\prime}\left(\tilde{w}_{\epsilon, P_{\epsilon}}\left(x_{\epsilon}\right)\right) \leq-\frac{1}{4}$ for $\epsilon$ small. Since $\frac{\partial \phi_{\epsilon}}{\partial \nu}=0$, by the Hopf boundary Lemma, $x_{\epsilon} \notin \partial \Omega$. So $x_{\epsilon} \in \Omega$, which implies that

$$
\Delta \phi_{\epsilon}\left(x_{\epsilon}\right) \leq 0 .
$$

From (5.5) we deduce that

$$
\left(1-f^{\prime}\left(\tilde{w}_{\epsilon, P_{\epsilon}}\left(x_{\epsilon}\right)\right)\right) M_{\epsilon}+o(1) M_{\epsilon}+O\left(\epsilon^{\tau-1}\right) \leq 0
$$

and hence $M_{\epsilon}$ is bounded. A contradiction.
This proves Claim 1.
Let

$$
\begin{equation*}
\hat{\phi}_{\epsilon}(y)=\frac{\phi_{\epsilon}(x)}{M_{\epsilon}} \chi\left(x-P_{\epsilon}\right), \quad y=T_{\epsilon}(x), \tag{5.9}
\end{equation*}
$$

where $y=T_{\epsilon}(x)$ is given in (2.3) (replacing $P$ by $P_{\epsilon}$ ).
Claim 2: $\hat{\phi}_{\epsilon}(y) \rightarrow 0$ in $C_{\text {loc }}^{1}\left(R_{+}^{N}\right)$ as $\epsilon \rightarrow 0$.
In fact, from the equation for $\hat{\phi}_{\epsilon}$, we see that as $\epsilon \rightarrow 0, \hat{\phi}_{\epsilon} \rightarrow \hat{\phi}_{0}$ which satisfies

$$
\begin{gathered}
\Delta \hat{\phi}_{0}-\hat{\phi}_{0}+f^{\prime}(w) \hat{\phi}_{0}=0,\left|\hat{\phi}_{0}\right| \leq 1 \text { in } R_{+}^{N}, \\
\frac{\partial \hat{\phi}_{0}}{\partial y_{N}}=0 \text { on } \partial R_{+}^{N}
\end{gathered}
$$

By the nondegeneracy of $w$ (see (2.14)), there exist $N-1$ constants $a_{1}, \ldots, a_{N-1}$ such that

$$
\begin{equation*}
\hat{\phi}_{0}=\sum_{j=1}^{N-1} a_{j} \frac{\partial w}{\partial y_{j}} . \tag{5.10}
\end{equation*}
$$

On the other hand, we know that $\nabla_{x_{k}} u_{\epsilon}\left(P_{\epsilon}\right)=0, k=1, \ldots, N-1$ and hence

$$
\begin{gathered}
0=\nabla_{x_{k}}\left(\tilde{w}_{\epsilon, P_{\epsilon}}\left(P_{\epsilon}\right)+\epsilon^{\tau} \phi_{\epsilon}\left(P_{\epsilon}\right)\right) \\
=O\left(\epsilon^{2}\right)+\nabla_{x_{k}}\left(w\left(\frac{x-P_{\epsilon}}{\epsilon}\right)-\epsilon v_{1} \chi-\epsilon^{2}\left(v_{2}+v_{3}\right) \chi\right)+\epsilon^{\tau-1} M_{\epsilon} \nabla_{y_{k}} \hat{\phi}_{\epsilon}(0) \\
=O(\epsilon)+\epsilon^{\tau-1} M_{\epsilon} \nabla_{y_{k}} \hat{\phi}_{\epsilon}(0) .
\end{gathered}
$$

(Note that $\nabla_{y_{k}} v_{1}(0)=\nabla_{y_{k}} v_{2}(0)=0$.) Thus we have $\nabla_{y_{k}} \hat{\phi}_{\epsilon}(0) \rightarrow 0$ which shows that $\nabla_{y_{k}} \hat{\phi}_{0}(0)=0, k=1, \ldots, N-1$. This implies that

$$
\left.\nabla_{y_{k}}\left(\sum_{j=1}^{N-1} a_{j} \frac{\partial w}{\partial y_{j}}\right)\right|_{y=0}=0, \quad k=1, \ldots, N-1
$$

Thus $a_{1}=\ldots=a_{N-1}=0$.
This proves Claim 2.
Lemma 5.3 now follows from Claim 1 and Claim 2: Let $y_{\epsilon}=\frac{x_{\epsilon}-P_{\epsilon}}{\epsilon}$, then by Claim $1,\left|y_{\epsilon}\right| \leq C$. So we may assume that $y_{\epsilon} \rightarrow y_{0}$ as $\epsilon \rightarrow 0$. Since $\hat{\phi}_{\epsilon}\left(y_{\epsilon}\right)=1$, we have $\hat{\phi}_{0}\left(y_{0}\right)=1$ which contradicts Claim 2.

Theorem 5.1 now follows from Lemma 5.3: In fact, multiplying (5.5) by $\phi_{\epsilon}$ and integrating over $\Omega$, we obtain

$$
\begin{gathered}
\epsilon^{2} \int_{\Omega}\left|\nabla \phi_{\epsilon}\right|^{2} d x+\int_{\Omega}\left|\phi_{\epsilon}\right|^{2} d x \\
=\int_{\Omega} f^{\prime}\left(\tilde{w}_{\epsilon, P_{\epsilon}}\right) \phi_{\epsilon} d x-\int_{\Omega} N_{\epsilon}\left[\phi_{\epsilon}\right] \phi_{\epsilon} d x+\epsilon^{-\tau} \int_{\Omega} S_{\epsilon}\left[\tilde{w}_{\left.\epsilon, P_{\epsilon}\right]} \phi_{\epsilon} d x\right. \\
\leq C \epsilon^{N}+o(1) \int_{\Omega}\left|\phi_{\epsilon}\right|^{2} d x
\end{gathered}
$$

This finishes the proof of Theorem 5.1.
6. The proofs of Theorem 1.1, Theorem 1.2, and Corollary 1.3

Theorem 1.1 follows from Lemma 5.2 and Proposition 3.2.
To prove Theorem 1.2, we follow the proof of Theorem 1.1: first we note that

$$
\begin{equation*}
S_{\epsilon}\left[\sum_{j=1}^{K} \tilde{w}_{\epsilon, P_{j}^{\epsilon}}\right]=\sum_{j=1}^{K} S_{\epsilon}\left[\tilde{w}_{\epsilon, P_{j}^{\epsilon}}\right]+O\left(e^{-\delta / \epsilon}\right) \tag{6.1}
\end{equation*}
$$

for some $\delta>0$, since $\min _{i \neq j}\left|P_{i}^{\epsilon}-P_{j}^{\epsilon}\right| \geq \delta$. Then we decompose

$$
u_{\epsilon}=\sum_{j=1}^{K} \tilde{w}_{\epsilon, P_{j}^{\epsilon}}+\epsilon^{\tau} \phi_{\epsilon}
$$

and show that $\left\|\phi_{\epsilon}\right\|_{L^{\infty}(\bar{\Omega})} \leq C$. The rest of the proof is exactly the same.
Finally, we prove Corollary 1.3.

Proof of Corollary 1.3: Let $u_{\epsilon}$ be a least energy solution of (1.1). By Theorem 1.1, we have

$$
\begin{gather*}
c_{\epsilon}:=J_{\epsilon}\left[u_{\epsilon}\right] \\
=\epsilon^{N}\left[\frac{1}{2} I[w]-c_{1} \epsilon H\left(P_{\epsilon}\right)+\epsilon^{2}\left(c_{2}\left(H\left(P_{\epsilon}\right)\right)^{2}+c_{3} R\left(P_{\epsilon}\right)\right)+o\left(\epsilon^{2}\right)\right] . \tag{6.2}
\end{gather*}
$$

On the other hand, let

$$
\begin{equation*}
\beta(t)=J_{\epsilon}\left[t \tilde{w}_{\epsilon, P}\right], \quad t>0 \tag{6.3}
\end{equation*}
$$

where $\tilde{w}_{\epsilon, P}$ is given by (2.18).
By Lemma 3.1 of [24],

$$
\begin{equation*}
c_{\epsilon} \leq \max _{t>0} \beta(t) . \tag{6.4}
\end{equation*}
$$

By assumption (f3) (see (3.16) of [24]), there exists a unique $t=t_{\epsilon, P}$ such that

$$
\beta^{\prime}\left(t_{\epsilon, P}\right)=0, \quad \beta\left(t_{\epsilon, P}\right)=\max _{t>0} \beta(t) .
$$

Note that

$$
\begin{aligned}
\beta^{\prime}(1)= & \int_{\Omega}\left[\epsilon^{2} \nabla \tilde{w}_{\epsilon, P} \nabla \tilde{w}_{\epsilon, P}+\tilde{w}_{\epsilon, P}^{2}-f\left(\tilde{w}_{\epsilon, P}\right) \tilde{w}_{\epsilon, P}\right] d x \\
& =\int_{\Omega} S_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right] \tilde{w}_{\epsilon, P} d x=O\left(\epsilon^{N+1+\sigma}\right)
\end{aligned}
$$

Similar to (3.16) of [24], one can show that

$$
\begin{equation*}
t_{\epsilon, P}=1+O\left(\epsilon^{1+\sigma}\right) \tag{6.5}
\end{equation*}
$$

Then

$$
\begin{gathered}
\beta\left(t_{\epsilon, P}\right)=\beta(1)+\beta^{\prime}(1)\left(t_{\epsilon, P}-1\right)+O\left(\epsilon^{N}\left|t_{\epsilon, P}-1\right|^{2}\right) \\
=\beta(1)+o\left(\epsilon^{N+2}\right)
\end{gathered}
$$

which implies that

$$
\begin{gather*}
c_{\epsilon} \leq \max _{t>0} \beta(t)=J_{\epsilon}\left[t_{\epsilon, P} \tilde{w}_{\epsilon, P}\right]=J_{\epsilon}\left[\tilde{w}_{\epsilon, P}\right]+o\left(\epsilon^{N+2}\right) \\
\leq \epsilon^{N}\left[\frac{1}{2} I[w]-c_{1} \epsilon H(P)+\epsilon^{2}\left(c_{2}(H(P))^{2}+c_{3} R(P)\right)+o\left(\epsilon^{2}\right)\right] \tag{6.6}
\end{gather*}
$$

for any $P \in \partial \Omega$.

Now we take $P=Q_{0}$ such that

$$
H\left(Q_{0}\right)=\max _{P \in \partial \Omega} H(P), R\left(Q_{0}\right)=\min _{Q \in \partial \Omega, H(Q)=\max _{P \in \partial \Omega} H(P)} R(Q) .
$$

Comparing (6.6) with (6.2), we arrive at

$$
\begin{aligned}
& c_{1} H\left(Q_{0}\right)-\epsilon\left[c_{2}\left(H\left(Q_{0}\right)\right)^{2}+c_{3} R\left(Q_{0}\right)\right]+o(\epsilon) \\
& \leq c_{1} H\left(P_{\epsilon}\right)-\epsilon\left[c_{2}\left(H\left(P_{\epsilon}\right)\right)^{2}+c_{3} R\left(P_{\epsilon}\right)\right]+o(\epsilon)
\end{aligned}
$$

Since $c_{1}>0, c_{3}>0$, (the sign of $c_{2}$ is not important), we conclude that

$$
H\left(P_{\epsilon}\right) \rightarrow \max _{P \in \partial \Omega} H(P), \quad R\left(P_{\epsilon}\right) \rightarrow_{Q \in \partial \Omega, H(Q)=\max _{P \in \partial \Omega} H(P)} R(Q)
$$

as $\epsilon \rightarrow 0$.

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