Increasing Personal Safety in Road Transport Using the Emergency Call Service

Povećanje osobne sigurnosti u cestovnom prijevozu korištenjem usluge pozivanja hitne službe

Jakub Žabenský

VŠB – Technical University of Ostrava Faculty of Safety Engineering Department of Security services Czech Republic e-mail: jakub.zabensky.st@vsb.cz

Radomír Ščurek

VŠB – Technical University of Ostrava Faculty of Safety Engineering Department of Security services Czech Republic e-mail: radomir.scurek@vsb.cz

> DOI 10.17818/NM/2015/SI14 UDK 656.1:351.81 Original scientific paper / Izvorni znanstveni rad Paper accepted / Rukopis primljen: 27. 4. 2015.

Summary

Constantly increasing requirements on road safety lead to the development of new technologies and safety systems implemented in motor vehicles. Most of these systems help prevent accidents or reduce the severity of subsequent damage to persons and property occurred during an accident. However, these systems do not contribute to reduce the delay of the first aid ensured to injured persons. This function provides an emergency call system, which is capable of immediate detection of traffic accidents and ensures automatic transfer of information about the accident to the emergency call center. The information transfer is realized via GSM network, which may be disrupted by certain risk factors. The article presents the outcomes of the experiments in which these factors were evaluated.

KEY WORDS

emergency call car accident road safety accident detection Faraday cage

Sažetak

Stalno povećanje zahtjeva za sigurnošću na cesti dovelo je do razvoja novih tehnologija i sigurnosnih sustava koji se primjenjuju na motorna vozila. Većina ovih sustava pomaže spriječiti nesreće ili ublažiti njihove posljedice na ljude i imovinu. Međutim, ovi sustavi ne doprinose smanjenju vremenskog perioda koji je potreban da prva pomoć stigne do ozlijeđenih. Ova funkcija omogućuje sustav poziva hitne službe koji smjesta otkriva nesreće na cesti i automatski prenosi podatke o nesreći do pozivnog centra hitne službe. Prijenos podataka ostvaruje se pomoću GSM mreže, koju mogu ometati određeni faktori rizika. U ovom radu izloženi su rezultati eksperimenata u kojima su se ovi faktori procjenjivali.

KLJUČNE RIJEČI

poziv hitne službe prometna nesreća sigurnost na cesti otkrivanje nesreće Faradayev kavez

INTRODUCTION

Traffic accidents can be considered from the perspective of constantly developing road transportation networks as its unfavourable, but unfortunately also irrepresible part. In some traffic accidents its participants get into a situation, in which they are unable to use a mobile phone to call for emergency services, e.g. due to injuries, or they aren't able to give exact location of the accident. Both of these situations lead to a possible delay in providing first aid to the injured persons, which can cause fatal consequences. [1], [2]

In-vehicle system eCall is an emergency call system, which is designed for automatic transfer of information about a traffic accident via the GSM network to an emergency call center to ensure the first aid to injured persons as soon as possible. Activation of the eCall system could be realized in two different ways – automatically by signal comming from airbags unit, if a car crash occures with a deceleration exceeding predefined limit resulting in airbag activation (technical standard CSN EN 16072 allows alternative ways of automatic activation), or

manually by passengers, if they get stuck in an emergency situation. [3], [4], [5]

Under the head of the E-MERGE project has been performed a study based on evaluation of benefits that eCall system carries out, primarily focused on reduction of delays between a car accident occures and arrival of rescuers. Results are shown below:

- reduce the response time to the accident of about 50% in non-urban areas and 40% in urban areas;
- reduce injuries within EU25 of about 15% to save up to 2 500 lives per year. [6]

At the moment of the traffic accident, the eCall system is activated (manually or automatically) and immediately starts to dial up an emergency call, which is able to transmit besides the voice also other information about the accident to the nearest public-safety answering point (PSAP). The voice call enables passengers to communicate with the eCall operator and at the same time a minimum set of data (MSD) is sent to the

operator. MSD contains detailed information about the accident – its exact location, time, vehicle information, eCall status and information about service provider. [3], [7], [8]

To ensure reliable function of eCall system it is necessary to assess possible risk factors that may occure in real traffic and cause disruption of its function, which may mean potentional threat for seriously injured passengers.

RISK FACTORS ANALYSIS

As was stated in the previous chapter, function of the eCall system may be, under certain conditions, limited or completely interrupted. For the process of identifying risk factors, which may cause these disruptions, Ishikawa's cause-and-effect diagram was used. These risk factors were divided into two categories according to their characteristics – procedural and

structural. The first category contains factors, which are affected by human activities, the second one are mostly caused by objects or surrounding properties. [9]

After the step of identifying factors by Ishikawa diagram, Saaty Method of quantitative pair comparison was applied on its output to obtain quantitative information showing the severity of the negative effects of risk factors affecting disruptions of eCall system function. For the assessment of every single risk factor Saaty's scale with the scale of significance 1 - 9 was used.

The Table 1 below shows the output from Saaty matrix with preferential numbers R, and weight indexes v,.

Both categories of risks - procedural as well as structural assessed by Saaty Method - were sorted according to the values of preferential numbers Ri and placed into graph shown below, see Figure 1. The graph was then complemented with Lorentz curve and Pareto principle with the reliability ratio 60:40.

Table 1 Saaty matrix output

Order	Risk number	Risk type	Ri	vi	Risk	
1.	4	structural	5.63	0.208	Unavailable/Missing GSM signal	
2.	5	structural	4.20	0.155	GSM shielding by random structures	
3.	1	structural	3.78	0.140	Frequency disturbances	
4.	2	procedural	3.25	0.420	Intentional signal shielding	
5.	5	procedural	2.95	0.380	Intentional GSM jammer usage	
6.	2	structural	2.82	0.104	GSM shielding by car body	
7.	12	structural	1.47	0.054	Damaged antenna	
8.	8	structural	1.24	0.046	Damaged OBU in a crash	
9.	7	structural	1.17	0.043	Flooding of OBU	
10.	18	structural	1.00	0.037	Faulty installation of OBU	
11.	14	structural	0.91	0.034	OBU error	
12.	11	structural	0.87	0.032	Power supply interruption	
13.	3	procedural	0.81	0.100	Intentional antenne disconnection	
14.	16	structural	0.74	0.027	Temperature out of range	
15.	13	structural	0.69	0.025	Support systems failure	
16.	10	structural	0.63	0.023	Short circuit	
17.	1	procedural	0.50	0.060	Intentional OBU disconnection	
18.	15	structural	0.47	0.017	Software error	
19.	17	structural	0.43	0.016	Incorrect data input	
20.	9	structural	0.38	0.014	Car fire	
21.	6	structural	0.32	0.012	Influence of high-voltage lines	
22.	3	structural	0.30	0.011	External magnetic field	
23.	4	procedural	0.26	0.030	Changes in circuits by user	

Source: authors

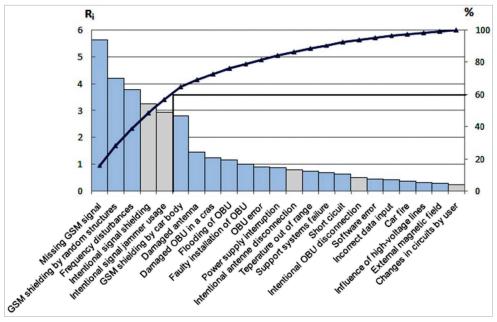


Figure 1 Risk factors ranked according to their severity.

Source: authors

Both of the previous steps enable to determine the treshold of the risk severity. According to this, risks lying above the treshold have been assessed as the most severe and were therefore subjected to further experimental investigation. Conversely, risks lying under the treshold were excluded from the investigation because of their low severity and also potentialy low influence on the eCall function.

The main objective of experiments, which have been performed, was to verify or refute theoretically obtained data by risk analysis. Because the threshold had been determined, only five out of twenty three highest severity risks were investigated:

- missing / unavailable GSM signal
- GSM shielding by random structures
- frequency disturbances
- intentional signal shielding
- intentional signal jammer usage

EXPERIMENTAL SECTION

This chapter describes process of every single experiment focused on investigation of the most severe risks, mentioned above. Outputs obtained from experiments should allow to verify data acquired from risk analysis and to suggest appropriate corrective measures if possible. Every experimental measurement was run under real conditions corresponding to the real environment, where eCall system is supposed to be used. [10, 11]

All the measurements were performed on ONI System monitoring on-board unit, see Figure 2:



Figure 2 ONI System on-board unit Source: authors

The first experiment was performed to determine the level of the negative impact on eCall system when the car equipped with OBU is passing through a route located in a geographical area without guaranteed GSM network coverage - the route has been selected according to the information about the availability of the signal obtained from mobile network operators and verified by an ordinary mobile phone. Total lenght of this route was about 6km and an average speed of measuring vehicle was set to 40km/h.

During this experiment on-board unit was used to measure values of current GSM signal intensity (units: dBm) in specified intervals set by GPS coordinates. That means every measured value of GSM intensity was assigned to the exact coordinates, which enables to track progression of the signal availability on the route and also enables to find exact location of signal loss, where some random shielding structures might be found.

Within the first experiment there were 6 measurements performed overall, collecting 390 values of GSM intensity which were statistically processed (see table 2) and placed into the graph 2 ilustrated by Figure 3. All units describing intensity of the GSM signal are in *dBm*. The lowest intensity takes the value -113dBm (= unavailability), the highest intensity takes up to -51dBm.

Avg. Min. Max. Me Measurement Dispersion Std. deviation [dBm] [dBm] [dBm] [dBm] 1. -97.04 -113 -85 -97 36.78 6.07 2. -96.68 -107 -85 -95 38.68 6.22 3. -95.89 -107 -83 -97 44.56 6.68 -97.39 -105 -83 -99 4. 44.49 6.67 5. -87 41.85 -96.39 -113 -97 6.47 6. -97.07 -113 -83 -97 79.71 8.93

Table 2 Statistically processed data from the first experimental measurements.

Source: authors

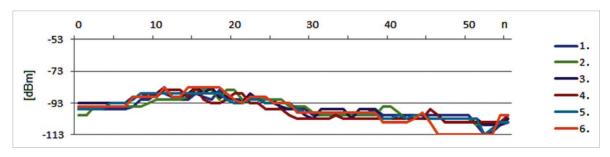


Figure 3 Progress of the GSM signal availability on the selected route.

Source: authors

Table 3 Dependence of the GSM signal availability on the shielding structure properties.

	Avg. [dBm]	Min. [dBm]	Max. [dBm]	Me [dBm]	Dispersion	Std. deviation	%
Referential	- 68.41	- 71	- 65	- 71	8.36	2.89	100
15 μm	- 83.71	- 91	- 79	- 85	8.44	2.90	81.7
30 μm	- 86.41	- 95	- 79	- 87	21.06	4.59	79.2
45 μm	- 92.53	- 95	- 91	- 91	3.07	1.75	73.9

Source: authors

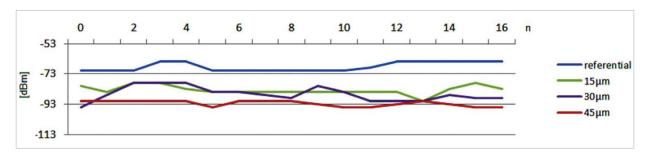


Figure 4 Dependence of the GSM signal availability on the shielding structure properties.

Source: authors

The second experiment was carried out to evaluate the possibility of disruption of eCall system function by intentional GSM signal shielding caused by a user (driver). One of the most probable ways to create a shielding barrier at home conditions is to use the principle of Faraday cage. For this reason common materials were chosen, as cardboard for creating a supporting structure and aluminum foil with thickness of 15 µm for ensuring its shielding effect. The whole body of the OBU has been closed into this cage and measuring of the GSM signal availability could start.

Within this experiment, four measurements were performed. The first one was used to collect referential values of the GSM signal intensity at selected area. During the second, the third and the fourth measurement values of the intensity while shielding OBU by the aluminum foil of thickness 15 μm , 30 μm and 45 μm were collected. Outcomes from these measurements are shown in the Table 3, respectively on the Figure 3. The blue line ilustrates referential values of the GSM signal intensity at selected area.

Note: To successful shielding of a mobile phone the thickness of 15 μm aluminum foil is sufficient.

The third experiment was performed to evaluate the possibility of intentional GSM signal jamming by a device

(see Figure 5) generating disturbing low-power signals in the spectrum of frequencies equal to mobile phone network. Such device prevents the communication between the onboard unit and an emergency call center, so at the moment of a traffic accident it is not possible to transfer any information about the situation, even though the capability of on-board unit to detect the accident stay retained. Moreover, usage of the jammer may also cause malfunction of mobile phones in the vicinity of an accident, which could make it impossible to call emergency services even by witnesses of the accident.

During this experiment there were only two measurements performed due to expected and clear results. Referential values of the signal intensity at selected area were taken over from the previous experiment because it ran under the same conditions. Other values were collected in two different arrangement of OBU and jammer. At first, both devices were placed next to each other, which may be taken as an example of a situation, when the driver knows, where the OBU is hidden in the car's interior. Subsequently, the OBU with its antenna was placed close to widescreen and the jammer was positioned between the front seats, which may illustrate a situation, when the exact possition of OBU is unknown. Measured data are shown in Table 4 and ilustrated by Figure 6.



Jammed spectrum: 850–894 MHz, 925–960 MHz,

1805-1880 MHz, 1900-1980 MHz,

2110-2170 MHz.

Output power: 0.5 W

Effective range: 2 - 8 m

Figure 5 The jammer

Source: authors

Table 4 Influence of jammer usage on GSM signal availability

Measurement	Avg. [dBm]	Min. [dBm]	Max. [dBm]	Me [dBm]	Dispersion	Std. deviation	%
Referential	- 68.41	- 71	- 65	- 71	8.36	2.89	100
1.	- 113	- 113	- 113	- 113	0	0	0
2.	- 113	- 113	- 113	- 113	0	0	0

Source: authors

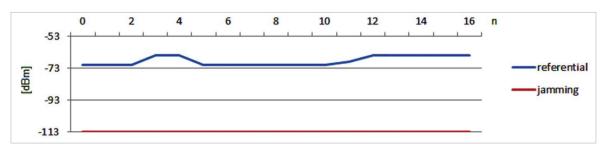


Figure 6 Influence of signal jamming on its availability

Source: authors

RESULTS, DISCUSSION AND CONCLUSION

The data recorded during all experimental measurements show that some of the investigated risk factors can have significant negative effect on eCall system, resulting in restriction or even complete disruption of its clutch function.

The most significant negative effect was noticed in the third experiment, representing an intentional usage of jamming device or unintentional frequency disturbances caused by random sources. In this case, the on-board unit was completely out of order all the time because its reciever was overwhelmed by disruptive signal, as illustrates Figure 6. It is also important to note the jammer, placed in a vehicle, may disrupt function of all passengers' mobile phones as well as it may cause unavailability of GSM signal of nearby the vehicles. This should be seen as a potential threat if an emergency situation occures.

As a possible way, how to reduce such negative influence of signal jamming on eCall function, may be application of high quality shielding of OBU's body and its antenna cable and also installation of an external antenna on the top of a car body. What should be also kept in mind is that using a GSM jammer is illegal in most of the european countries, but still there are many opportunities to purchase it on the market.

Slightly less severe results were obtained from the second experiment, where the possibility of an intentional signal shielding was investigated. A closer look on the Figure 4 suggests that shielding construction used in this experiment didn't cause any signal loss, but significantly lowered its intensity. The difference between a referential value and a value while shielding reaches up to 26% on average. That means if the referential signal intensity was lower, e.g. about -95 dBm, then the same shielding structure may cause some serious signal losses. Moreover, if any of more sophisticated shielding ways were used, like a packing made of lead sheets, then a signal loss may occure independently of the actual

signal intensity.

To prevent a possibility of OBU shielding or shielding its antenna, countermeasures should be done primarily based on OBU design – its shape and/or possitioning in the car's interior. It is possible to integrate OBU into other electronic car parts, e. g. airbag units, which is often hidden under the middle of the dashboard, or place the OBU separately into construction of the dashboard. Due to such placement of OBU or/and its antenna, it should be way more difficult to make an effective shielding.

As the least severe risk factors might be considered missing / unavailable GSM signal and GSM shielding by random structures due to the first experiment output, even though these risks were assessed as the most severe during the risk analysis. The reason of different results is most likely caused by conditions set for the first experiment – parameters of the selected route and the measurement method.

The Figure 3 shows progression of the signal intensity on the route, where six measurements were performed in total. Even though the signal coverage was not guaranteed and was proven by mobile phone measurements, OBU was able to keep relatively stable communication with the network. Only during 3 out of 6 measurements some signal losses were detected, where the longest one lasted for tens of seconds, other ones didn't exceed a few seconds. But it is important to keep in mind that these measurements were carried out at low speed around 40 km/h, which means these signal losses were in terms of distance at least around 15 meters long. Such a length is enough to be potentially dangerous if an accident occures in it, because its detection may not be successful.

At this point it would be difficult to suggest any countermeasures due to technological limitations. The onboard unit, used for all experiments mentioned in this article, has proved its ability to operate with very low intensity signal due to an external antenna and high sensitive GSM reciever.

However, there still cannot be given any guarantee of no signal losses, because of landscape character and partially inhomogeneous signal coverage (relates to the Czech Republic), which is fortunately still improving.

Contents of this article showed evaluation of some risk factors of eCall system based on an experimental basis, which may occure in real taffic and should be taken into account before eCall will be put into live operation, which is scheduled for the beginning of the year 2017.

REFERENCES

- Riley, P., Holubová, A. (2008). Ex-ante evaluation of the eCall system. [online].
 URL: http://iztern.plan.aau.dk/doks/pp/presentations/Session_1-3/Alexa ndraHolubova.pdf
- [2] Schmidler, K. (2011). Human Machine interface in car using ADAS and IVIS. Brno. p. 112. ISBN 978-80-86502-18-2.
- [3] ČSN EN 15722. (2012). Inteligentní dopravní systémy eSafety Minimální soubor dat pro eCall. Praha: ÚNMZ, pp. 8.
- [4] ČSN EN 16062. (2012). Inteligentní dopravní systémy Vysokoúrovňové aplikační požadavky na eCall. Praha: ÚNMZ, pp. 22-27.

- [5] ČSN EN 16072. (2012). Inteligentní dopravní systémy eSafety Provozní požadavky na Panevropský eCall. Praha: ÚNMZ, pp. 20.
- [6] Francsics, J., Anjum, O., Hopkin., J., Stevens, A. (2009). Impact assessment on the introduction of the eCall service in all new type-approved vehicles in Europe, insluding lability/legal issues. [online]. URL: http://pdf.911dispatch.com.s3.amazonaws.com/ecall_final_report.pdf>
- [7] Harmonised eCall European Pilot. (2010). About HeEro [online]. URL: http://www.heero-pilot.eu/view/en/heero.html
- [8] PŘIBYL, P. (2007). Inteligentní dopravní systémy a dopravní telematika 2, 1. vyd. Praha, Česká technika - nakladatelství ČVUT, ISBN 978-80-01-03648-8.
- [9] RBI support tool for industrial risk prevention / Hana Pacaiova, Milan Oravec, Jan Kolesar (2014). In: AHFE 2014: Advances in Human Factors and Ergonomics: proceedings of the 5th international conference: 19-23 July 2014, Kraków, Poland. - [Louisville]: AHFE Conference, 2014, pp. 2751-2758. - ISBN 978-1-4951-1572-1
- [10] Hovanec, M., Sinay, J., Pačaiová, H. (2014). Application of Proactive Ergonomics Utilizing Digital Plant Methods Based on Augmented Reality as a Tool Improving Prevention for Employees. In: International Symposium on Occupational Safety and Hygiene: 13. - 14.2.2014: Guimares, Portugalsko, pp. 182-185 Guimares: SPOSHO, 2014, ISBN: 978-989-98203-2-6
- [11] Pila, J. Adamčík, F. Korba, P. Antoško, M. (2014). Safety Hazard and Risk in Slovak Aviation Regulations - 2014. In: Our Sea, International Journal of Maritime Science and Technology. Vol. 61, no. 1-2 pp. 27-30. - ISSN 1848-6320