

Article

Stability Analysis and Dual Solutions of Micropolar Nanofluid over the Inclined Stretching/Shrinking Surface with Convective Boundary Condition

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Received: 30 November 2019; Accepted: 24 December 2019; Published: 2 January 2020



Abstract: The present study accentuates the heat transfer characteristics of a convective condition of micropolar nanofluid on a permeable shrinking/stretching inclined surface. Brownian and thermophoresis effects are also involved to incorporate energy and concentration equations. Moreover, linear similarity transformation has been used to transform the system of governing partial differential equations (PDEs) into a set of nonlinear ordinary differential equations (ODEs). The numerical comparison has been done with the previously published results and found in good agreement graphically and tabular form by using the shooting method in MAPLE software. Dual solutions have been found in the specific range of shrinking/stretching surface parameters and the mass suction parameter for the opposing flow case. Moreover, the skin friction coefficient, the heat transfer coefficient, the couple stress coefficient, and the concentration transfer rate decelerate in both solutions against the mass suction parameter for the augmentation of the micropolar parameter respectively. The first (second) solution is the stable (unstable) solution and can (not) be considered as a real solution as the values of the smallest eigenvalues are positive (negative).

Keywords: micropolar nanofluid; inclined plane; dual solutions; stability analysis

1. Introduction

During the past two decades researchers have constructed or modified the models of fluid where gyrating micro-components is the necessary factor. There exists such a model known as the micropolar fluid model. Initially, this model was introduced by Eringen [1] in which he added microscopic velocity field and atomic rotating motion in the fluid. These kinds of fluids contain rigid/spherical particles, nonsymmetric stress tensor, and micro rotational characteristics during the flow. Some common daily life examples of micropolar fluids are ferrofluids, bubbly fluids, animal blood, liquid crystals,

mixture of red and white cells, etc. [2,3]. Lukaszewicz [4] wrote a detailed book on micropolar fluid in which he explained that micropolar fluid contains five more viscosities of coefficients. It can be concluded from the survey of the past published literature that micropolar nanofluid has received much attention from many researchers. Micropolar nanofluid is the extension of Buongiorno's model [5] by considering the angular momentum effect on the fluid flow model. Hsiao et al. [6] examined micropolar nanofluid by using Buongiorno's model and found that the intensity of the thermophoresis enhanced the temperature of the fluid. Hayat et al. [7] considered the micropolar nanofluid over the stretching surface and found a single solution. Micropolar nanofluid over the vertical surface was investigated by Noor et al. [8]. They successfully obtained one solution. Haq et al. [9] studied the stagnation point flow of the micropolar nanofluid over the vertical sheet in which they considered the model of Buongiorno. Furthermore, only one solution was obtained successfully even in the opposing case. Recently, micropolar nanofluid in the presence of magnetic force was investigated by Patel et al. [10] in which they also noticed a single solution. Rafique et al. [11] considered micropolar nanofluid on the inclined stretching plane where they obtained a single local similarity solution. Moreover, they claimed that the effect of the Brownian motion is then inversely proportional to the rate of heat transfer. The same authors published an article of the local similarity solution (all parameters are not truly similar) in which they examined the stagnation point flow of micropolar nanofluid on the inclined plane with the effect of magnetohydrodynamic (MHD) and chemical reaction [12]. They successfully obtained only one solution. Some advances of the micropolar nanofluid can be seen in these articles in which researchers obtained a single solution [13–20]. Further, the dual solutions of micropolar nanofluid on the vertical surface were investigated by Lund et al. [21] in which they found that dual solutions are only possible in some ranges of the suction parameter. Dero et al. [22] found triple solutions during the examination of micropolar nanofluid over the stretching and shrinking surfaces. It was noticed that thermophoresis and Brownian motion are good agents to increase the thickness of thermal boundary layer and temperature of the fluid. However, they did not perform a stability analysis. Dual solutions, without performing the stability analysis, of micropolar nanofluid over the shrinking/stretching surface was found by Magodora et al. [23] in the presence of thermal effect. Triple solutions of micropolar nanofluid over the shrinking surface with the effect of the velocity slip was obtained by Ali et al. [24] in which they performed the analysis of stability in order to determine the stable solution. A few more related research articles of the micropolar fluid and nanofluid for the multiple solutions can be seen in References [25–30]. A vast analysis of the published works reveals that no one has considered micropolar nanofluid model over the inclined plane for multiple solutions. Further, stability analysis is performed which also can be considered as one of the prime objectives of the current study. Therefore, the effect of the inclined angle on the steady flow of the micropolar nanofluid over the linear plane is being examined. It is expected that this investigation would add an innovative approach for those researchers who are interested to find the characteristics of the multiple solutions of the micropolar nanofluid.

The boundary layer flow of fluids attracts numerous researchers due to its vast applications over stretching/shrinking surface on different fields of sciences such as mechanical, aeronautical, and civil engineering. Some applications of boundary layer flows are tinning and strengthening of copper wires, elastic sheets, non-stop cooling, fiber turning, wire drawing, expulsion of polymer, paper, and food processing, etc. It seems that Sakiadis [31] was the first who examined the boundary layer flow. Later on, many researchers considered boundary layer flow of Newtonian and non-Newtonian fluids. It should be noted that a lot of works have been done on boundary layer flow. However, we considered recently published works of boundary layer flow of nanofluids over stretching/shrinking surface for multiple solutions. Raju et al. [32] investigated nanofluid over non-linear stretching surface and found dual solutions. Oblique stagnation point flow of nanofluid on shrinking surface was examined by Li et al. [33] and successfully noticed dual solutions in the range of stretching/shrinking parameter. Nanofluid with the effect of Soret and Dufour was investigated and noticed a dual solution without performing the analysis of the stability of the solutions [34]. Dero et al. [35] studied the unsteady

flow of nanofluid on stretching/shrinking surface by considering various slip effects. Zaib et al. [36] used a single-phase nanofluids model for micropolar fluid and found dual solutions. The model of single-phase nanofluid in the presence of binary chemical reaction of the cross-flow of nanofluid over the stretching/shrinking surface was studied by Khan et al. [37]. They noticed dual solutions in various ranges of the physical parameters. Lund et al. [38] considered nanofluid over non-linear shrinking surface with the effect of viscous dissipation and found two solutions. They stated that the first solution can be realizable as compared to the second solution by performing the analysis of stability on the solutions. The advance works on boundary layer flow of various fluids can be seen in these articles [39–45]. In light of the above-mentioned references and literature survey, it is concluded that micropolar nanofluid over the inclined shrinking/stretching surface has not yet been studied for multiple solutions and these results are novel. Therefore, we attempt to examine micropolar nanofluid due to its rising desires in various areas of engineering and industries.

2. Problem Formulation

Two-dimensional steady flow of incompressible micropolar nanofluid on the linear inclined shrinking surface has been considered. Physical model and coordinate system of the problem is explained in Figure 1. Under the consideration of velocity and angular velocity field, temperature and nanoparticles volume fraction of the boundary layer equations for the flow of micropolar nanofluid can be written in the Buongiorno model [5] as below

$$\nabla \cdot \mathbf{V} = 0 \quad (1)$$

$$\rho_f \frac{d\mathbf{V}}{dt} = -\nabla P + (\mu_f + \kappa) \nabla^2 \mathbf{V} + \kappa (\nabla \times \mathbf{N}) + \rho_f [\beta_T (T - T_\infty) + \beta_C (C - C_\infty)] \mathbf{g} \cos \xi \quad (2)$$

$$\rho_f j \frac{d\mathbf{N}}{dt} = \gamma \nabla^2 \mathbf{N} - \kappa (2\mathbf{N} - \nabla \times \mathbf{V}) \quad (3)$$

$$(\rho c)_p \frac{dT}{dt} = k \nabla^2 T + (\rho c)_f \left[D_B \nabla C \cdot \nabla T + \frac{D_T}{T_\infty} (\nabla T)^2 \right] \quad (4)$$

$$\frac{dC}{dt} = D_B \nabla^2 C + \frac{D_T}{T_\infty} \nabla^2 T \quad (5)$$

in which $\mathbf{V} \equiv [u(x, y), v(x, y), 0]$ is the velocity vector, \mathbf{N} is the microrotation vector, the spin gradient viscosity is γ , micro-rotation viscosity coefficient is κ , the gravitational acceleration is \mathbf{g} , j is micro-inertia density, μ_f , ρ_f , p , D_B , k , D_T , $(\rho c)_f$, $(\rho c)_p$, and ξ stand for dynamic viscosity of base fluid, the densities of base fluid, pressure, the coefficient of Brownian motion, the thermal conductivity of base fluid, the thermophoretic diffusion coefficient, and the effective heat capacity of the base fluid, the effective heat capacity of the nanoparticle material, angle respectively. Further, T and C are the respective temperature and concentration, β_T and β_C are the respective coefficient of thermal and nanoparticle volumetric expansion.

According to scale analysis, we have the following boundary layer equations:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \quad (6)$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \left(\vartheta_f + \frac{\kappa}{\rho} \right) \frac{\partial^2 u}{\partial y^2} + \frac{\kappa}{\rho_f} \frac{\partial N}{\partial y} + [\beta_T (T - T_\infty) + \beta_C (C - C_\infty)] g \cos \xi \quad (7)$$

$$u \frac{\partial N}{\partial x} + v \frac{\partial N}{\partial y} = \frac{1}{\rho j} \left[\gamma \frac{\partial^2 N}{\partial y^2} - \kappa \left(2N + \frac{\partial u}{\partial y} \right) \right] \quad (8)$$

$$u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} = \alpha_f \frac{\partial^2 T}{\partial y^2} + \tau_w \left[D_B \frac{\partial C}{\partial y} \frac{\partial T}{\partial y} + \frac{D_T}{T_\infty} \left(\frac{\partial T}{\partial y} \right)^2 \right] \quad (9)$$

$$u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} = D_B \frac{\partial^2 C}{\partial y^2} + \frac{D_T}{T_\infty} \frac{\partial^2 T}{\partial y^2} \quad (10)$$

subject to boundary condition

$$\begin{aligned} v = v_0; u = u_w; N = -m \frac{\partial u}{\partial y}; -k_f \frac{\partial T}{\partial y} = h_f(T_f - T); C = C_w \text{ at } y = 0 \\ u \rightarrow 0; N \rightarrow 0; T \rightarrow T_\infty; C \rightarrow C_\infty \text{ as } y \rightarrow \infty \end{aligned} \quad (11)$$

where $u_w = cx$ is the velocity of sheet and c is the constant, α_f is the thermal diffusivity, τ_w is the ratio of effective heat capacity, v_0 is the suction/injection parameter, C_∞ and T_∞ are the ambient concentration and temperature respectively, such that $T_f > T_\infty$ and $C_w > C_\infty$. Following similarity will be used to get similarity solution of Equations (7)–(10) with subject to boundary conditions Equation (11). Moreover, m is the constant, where $m = 0$ which means that microelements are unable to rotate, when $m = 0.5$ which implies that antisymmetric part of the stress tensor is vanishing and where $m = 1$ which indicates the model of the turbulent flow.

$$\begin{aligned} \eta = y \sqrt{\frac{a}{\vartheta_f}}, u = axf'(\eta), v = -\sqrt{a\vartheta_f}f(\eta), N = \sqrt{\frac{a}{\vartheta_f}}axg(\eta), \theta(\eta) = \frac{(T-T_\infty)}{(T_f-T_\infty)}, \\ \varnothing(\eta) = \frac{(C-C_\infty)}{C_w-C_\infty}, \end{aligned} \quad (12)$$

By applying above relations and Equation (12) in Equations (7)–(10), we have

$$(1 + K)f'''' + f f'' - f'^2 + Kg' + (\lambda_T \theta + \lambda_C \varnothing) \cos \xi = 0 \quad (13)$$

$$\left(1 + \frac{K}{2}\right) g'' + f g' - g f' - 2Kg - Kf'' = 0 \quad (14)$$

$$\frac{1}{Pr} \theta'' + f \theta' + N_b \varnothing' \theta' + N_t (\theta')^2 = 0 \quad (15)$$

$$\frac{1}{Sc} \varnothing'' + f \varnothing' + \frac{1}{Sc} \frac{N_t}{N_b} \theta'' = 0 \quad (16)$$

along boundary conditions

$$\begin{aligned} f(0) = S, f'(0) = \lambda, g(0) = -mf''(0), \theta'(0) = -Bi[1 - \theta(0)], \varnothing(0) = 1 \\ f'(\eta) \rightarrow 0, g(\eta) \rightarrow 0, \theta(\eta) \rightarrow 0, \varnothing(\eta) \rightarrow 0 \text{ as } \eta \rightarrow \infty \end{aligned} \quad (17)$$

Here prime denotes the differentiation with respect to η , $K = \frac{\kappa}{\mu}$ is the micropolar parameter, $\lambda_T = \frac{Gr_{xT}}{(Re_x)^2}$ is the Buoyancy constraint where $Gr_{xT} = \frac{g\beta_T(T-T_\infty)x^3}{\vartheta_f\vartheta_f}$, $\lambda_C = \frac{Gr_{xC}}{(Re_x)^2}$ is the buoyancy force due to concentration difference where $Gr_{xC} = \frac{g\beta_C(T-T_\infty)x^3}{\vartheta_f\vartheta_f}$, $Pr = \frac{\vartheta_f}{\alpha_f}$ is the Prandtl number, $N_b = \frac{\tau_w D_B (C_w - C_\infty)}{\vartheta_f}$, $N_t = \frac{\tau_w D_T (T_f - T_\infty)}{\vartheta_f T_\infty}$ are the Brownian motion and thermophoresis parameters. Moreover, $Sc = \frac{\vartheta_f}{D_B}$ is the Schmidt number, $S = -\frac{v_0}{\sqrt{a\vartheta_f}}$ is the Suction/Blowing parameter, $\lambda = \frac{c}{a}$ is the stretching and shrinking parameter, and Biot number or convective parameter is $i = \frac{h_f}{k_f} \sqrt{\frac{\vartheta_f}{a}}$.

The physically quantity of interest are Skin friction coefficient, local Nusselt number and local Sherwood number, which can be expressed as

$$C_f = \frac{\left[(\mu + \kappa) \frac{\partial u}{\partial y} + \kappa N\right]_{y=0}}{\rho u_w^2}, N_u = \frac{-x \left[k \frac{\partial T}{\partial y}\right]_{y=0}}{(T_f - T_\infty)}, S_h = \frac{-x \left(\frac{\partial C}{\partial y}\right)_{y=0}}{C_w - C_\infty} \quad (18)$$

Using Equation (12) in Equation (18), we have

$$C_f(Re_x)^{\frac{1}{2}} = (1 + (1 - m)K)f''(0), N_u(Re_x)^{-\frac{1}{2}} = -\theta'(0), S_h(Re_x)^{-\frac{1}{2}} = -\phi'(0) \quad (19)$$

where $Re_x = ax^2/\nu_f$ is local Reynolds number.

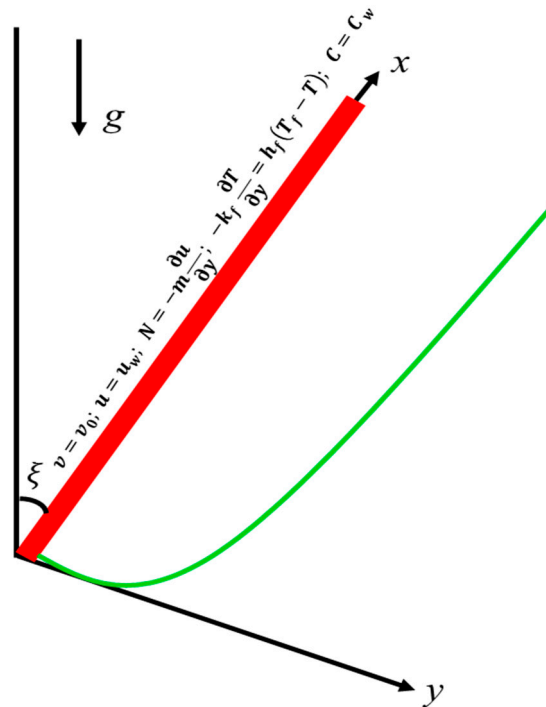


Figure 1. Physical model and coordinate system.

3. Stability Analysis

The analysis of the stability of the solutions is a significant analysis to check the consistency of the multiple similarities as well as local similarity solutions. It is worth mentioning that a boundary layer problem might have one, zero, or multiple solutions. For instance, if there exist non-unique solutions in any boundary layer problem but the investigators succeed in obtaining one solution only, that solution may be the second solution (not real/unstable). It may prompt the distortion of the heat transfer attributes and flow. For dual solutions, the double set of initial suppositions (one (second) set for first (second) solution) are required to get two disparate profiles (solutions) of the velocity, temperature and concentration in the numerical method subject to condition that both the first and second profiles must asymptotically fulfill the boundary conditions. The following researchers have considered this analysis in their studies [46–50].

According to Merkin [51] and Dero et al. [52], the first stage in the stability analysis is to change the system of governing equations into a system of an unsteady problem by introducing $\tau = at$ where t is the time since the disturbance may decay or grow with time. Thus, we have now following system of equations

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \left(\nu_f + \frac{\kappa}{\rho} \right) \frac{\partial^2 u}{\partial y^2} + \frac{\kappa}{\rho f} \frac{\partial N}{\partial y} + [\beta_T(T - T_\infty) + \beta_C(C - C_\infty)]g \cos \xi \quad (20)$$

$$\frac{\partial N}{\partial t} + u \frac{\partial N}{\partial x} + v \frac{\partial N}{\partial y} = \frac{1}{\rho j} \left[\gamma \frac{\partial^2 N}{\partial y^2} - \kappa \left(2N + \frac{\partial u}{\partial y} \right) \right] \quad (21)$$

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} = \alpha_f \frac{\partial^2 T}{\partial y^2} + \tau_w \left[D_B \frac{\partial C}{\partial y} \frac{\partial T}{\partial y} + \frac{D_T}{T_\infty} \left(\frac{\partial T}{\partial y} \right)^2 \right] \quad (22)$$

$$\frac{\partial C}{\partial t} + u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} = D_B \frac{\partial^2 C}{\partial y^2} + \frac{D_T}{T_\infty} \frac{\partial^2 T}{\partial y^2} \quad (23)$$

The new similarity transformation with $\tau = at$ can be expressed as

$$\eta = y \sqrt{\frac{a}{\mathfrak{S}_f}}, \tau = at, u = ax \frac{\partial f(\eta, \tau)}{\partial \eta}, v = -\sqrt{a \mathfrak{S}_f} f(\eta, \tau), N = \sqrt{\frac{a}{\mathfrak{S}_f}} ax g(\eta, \tau), \quad (24)$$

$$\theta(\eta, \tau) = \frac{(T - T_\infty)}{(T_w - T_\infty)}, \varnothing(\eta, \tau) = \frac{(C - C_\infty)}{C_w - C_\infty},$$

Using Equation (24) into Equations (20)–(23), we get

$$(1 + K) \frac{\partial^3 f}{\partial \eta^3} + f \frac{\partial^2 f}{\partial \eta^2} - \left(\frac{\partial f}{\partial \eta} \right)^2 + K \frac{\partial g}{\partial \eta} + (\lambda_T \theta + \lambda_C \varnothing) \cos \xi - \frac{\partial^2 f}{\partial \tau \partial \eta} = 0 \quad (25)$$

$$\left(1 + \frac{K}{2} \right) \frac{\partial^2 g}{\partial \eta^2} + f \frac{\partial g}{\partial \eta} - g \frac{\partial f}{\partial \eta} - Kg - K \frac{\partial^2 f}{\partial \eta^2} - \frac{\partial g}{\partial \tau} = 0 \quad (26)$$

$$\frac{1}{Pr} \frac{\partial^2 \theta}{\partial \eta^2} + f \frac{\partial \theta}{\partial \eta} + N_b \frac{\partial \varnothing}{\partial \eta} \frac{\partial \theta}{\partial \eta} + N_t \left(\frac{\partial \theta}{\partial \eta} \right)^2 - \frac{\partial \theta}{\partial \tau} = 0 \quad (27)$$

$$\frac{1}{Sc} \frac{\partial^2 \varnothing}{\partial \eta^2} + f \frac{\partial \varnothing}{\partial \eta} + \frac{1}{Sc} \frac{N_t}{N_b} \frac{\partial^2 \theta}{\partial \eta^2} - \frac{\partial \varnothing}{\partial \tau} = 0 \quad (28)$$

with the following boundary conditions

$$f(0, \tau) = S; \frac{\partial f(0, \tau)}{\partial \eta} = \lambda; g(0, \tau) = -m \frac{\partial^2 f(0, \tau)}{\partial \eta^2}; \frac{\partial \theta(0, \tau)}{\partial \eta} = -Bi[1 - \theta(0)]; \varnothing(0, \tau) = 1 \quad (29)$$

$$\frac{\partial f(\eta, \tau)}{\partial \eta} \rightarrow 0; g(\eta, \tau) \rightarrow 0; \theta(\eta, \tau) \rightarrow 0; \varnothing(\eta, \tau) \rightarrow 0 \text{ as } \eta \rightarrow \infty$$

The following functions are used to obtain the behavior of the solution's stability by perturbing with the disturbance [53].

$$\begin{cases} f(\eta, \tau) = f_0(\eta) + e^{-\varepsilon \tau} F(\eta) \\ g(\eta, \tau) = g_0(\eta) + e^{-\varepsilon \tau} G(\eta) \\ \theta(\eta, \tau) = \theta_0(\eta) + e^{-\varepsilon \tau} H(\eta) \\ \varnothing(\eta, \tau) = \varnothing_0(\eta) + e^{-\varepsilon \tau} S(\eta) \end{cases} \quad (30)$$

where $F(\eta)$, $G(\eta)$, $H(\eta)$, and $S(\eta)$ are small relative to $f_0(\eta)$, $g_0(\eta)$, $\theta_0(\eta)$ and $\varnothing_0(\eta)$, respectively. Further, $f_0(\eta)$, $g_0(\eta)$, $\theta_0(\eta)$ and $\varnothing_0(\eta)$ are the steady state solutions of the problem and ε is the unknown eigenvalue. Now, by substituting Equation (30) in Equations (25)–(28), we get following system of linearized eigenvalue problem

$$(1 + K)F_0''' + f_0 F_0'' + F_0 f_0'' - 2f_0' F_0' + KG_0' + (\lambda_T H_0 + \lambda_C S_0) \cos \xi + \varepsilon F_0' = 0 \quad (31)$$

$$\left(1 + \frac{K}{2} \right) G_0'' + f_0 G_0' + F_0 g_0' - g_0 F_0' - g_0 F_0' - 2KG_0 - KF_0'' + \varepsilon G_0 = 0 \quad (32)$$

$$\frac{1}{Pr} H_0'' + f_0 H_0' + F_0 \theta_0' + N_b \varnothing_0' H_0' + N_b S_0' \theta_0' + 2N_t \theta_0' H_0' + \varepsilon H_0 = 0 \quad (33)$$

$$S_0'' + Sc(f_0 \varnothing_0' + F_0 S_0') + \frac{N_t}{N_b} H_0'' + Sc \varepsilon S_0 = 0 \quad (34)$$

with the boundary conditions

$$\begin{aligned} F_0(0) = 0, F'_0(0) = 0, G_0(0) = -mF''_0(0), H'_0 = BiH_0(0), S_0(0) = 0 \\ F'_0(\eta) \rightarrow 0, G_0(\eta) \rightarrow 0, H_0(\eta) \rightarrow 0, S_0(\eta) \rightarrow 0 \text{ as } \eta \rightarrow \infty. \end{aligned} \quad (35)$$

According to Haris et al. [54], one boundary condition should be relaxed in the *BVP4C* solver to obtain the values of the smallest eigenvalue ε_1 . Here, $F'_0(\eta) \rightarrow 0$ as $\eta \rightarrow \infty$ is relaxed to $F''_0(0) = 1$.

4. Numerical Method

It is very difficult to find the exact solutions for ODEs system when it contains non-linearity. In this case, researchers opted for numerical approach. Since we are dealing with highly non-linear system of ODEs Equations (13)–(16) subject to boundary conditions Equation (17), shooting method is adopted to solve the system. However, this system needs to be reduced to the equivalent system of first order ODEs as follows

$$p = f'; q = p'; q' = \frac{1}{(1+K)} \{p^2 - fq - Ky_1 - (\lambda_T \theta + \lambda_C \phi) \cos \xi\} \quad (36)$$

$$y_1 = g'; y'_1 = \frac{2}{(2+K)} \{gp - fy_1 + 2Kg + Kq\} \quad (37)$$

$$r = \theta'; r' = Pr \{-fr - N_b s r - N_t r^2\} \quad (38)$$

$$s = \phi'; s' = -Scfs - \frac{N_t}{N_b} r' \quad (39)$$

subject to initial conditions

$$\begin{aligned} f(0) = S; p(0) = \lambda; q(0) = \alpha_1; g(0) = -m\alpha_1, y_1(0) = \alpha_2; \\ \theta(0) = 1 + \frac{\alpha_3}{Bi}; r(0) = \alpha_3; \phi(0) = 1; s(0) = \alpha_4 \end{aligned} \quad (40)$$

In order to solve Equations (36)–(39) subject to initial conditions Equation (40), the initial values $\alpha_1, \alpha_2, \alpha_3$ and α_4 are required. These values are approximated by using the shooting method. Then, the resultant system of first order ODEs is solved by employing Runge–Kutta of 4th order. By assuming $\eta_\infty = 10$, the calculated values of $f'(\eta) = 0; g(\eta) = 0; \theta(\eta) = 0;$ and $\phi(\eta) = 0$ are compared with given boundary condition $f'(10) = 0; g(10) = 0; \theta(10) = 0;$ and $\phi(10) = 0$ and the estimated values of $\alpha_1, \alpha_2, \alpha_3$ and α_4 , are adjusted to obtain a better approximate solution.

5. Results and Discussion

In this section, the results of the considered problems are discussed. In this analysis, we have taken the Prandtl number for the water is $Pr = 6.2$ in order to check the effect of micropolar parameters over the inclined plane. The comparison and the authenticity of our numerical solution for the skin friction $f''(0)$ with the results of Bhattacharyya et al. [55] is portrayed in Figure 2 in which the latter solution is highlighted with the solid lines while the new solution is shown with the dashed lines. Further, our results are compared numerically for some selected values of N_b and N_t and found in a good agreement with Khan and Pop [56] as highlighted in Table 1. Table 2 displays the values of the smallest eigenvalue with fixed parameters $\lambda_T = -0.2, \lambda_C = 0.2, \xi = 45^\circ, m = 0.5, Pr = 6.2, N_b = 0.3, N_t = 0.5, Sc = 1, \lambda = -1$ and $Bi = 5$. It is noticed that the positive (negative) values of smallest eigenvalues ε_1 indicates that the first (second) solution is stable (unstable). The solution in this paper is obtained for both branches which we refer as dual solutions. Throughout the paper, the first solution is represented by the solid blue lines, while the second solution is represented by the dashed red lines. The critical points in all the figures is marked

by the small green dot where both the solution behavior is changed at this position. These multiple solutions were found for different parameters and their results are plotted in distinct graphs.

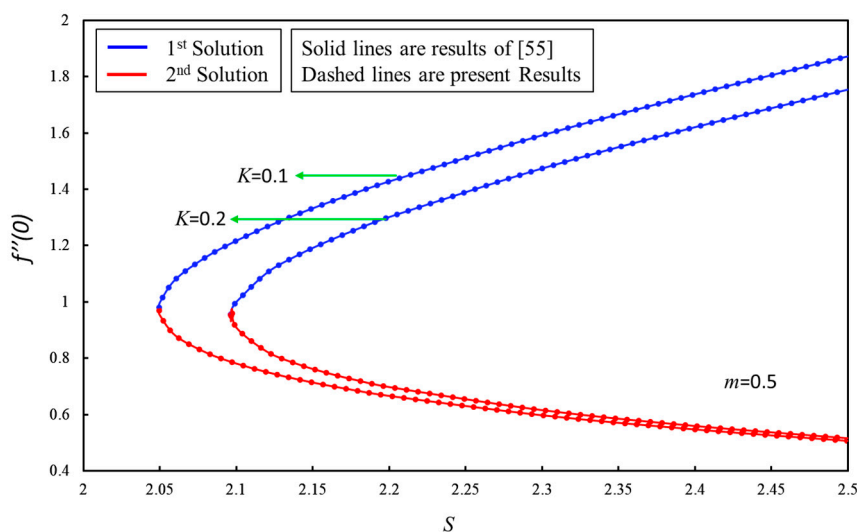


Figure 2. Comparison of $f''(0)$ with results of Bhattacharyya et al., when $m = 0.5$, $\lambda = -1$, $\xi = 90^\circ$.

Table 1. Comparison of results for the reduced Nusselt and Sherwood numbers when $S = 0$, $\lambda = 1$, $Bi = \infty$, $\xi = 90^\circ$, $K = 0$, $Sc = 10$, $Pr = 10$.

N_b	N_t	Khan and	Pop [56]	Present	Results
		$-\theta'(0)$	$-\phi'(0)$	$-\theta'(0)$	$-\phi'(0)$
0.1	0.1	0.9524	2.1294	0.9524	2.1294
	0.3	0.5201	2.5286	0.52005	2.5285
	0.5	0.3211	3.0351	0.3212	3.0351
0.2	0.2	0.3654	2.5152	0.3654	2.5152
	0.3	0.2731	2.6555	0.2731	2.6555
	0.5	0.1681	2.8883	0.1681	2.8883

Table 2. Smallest eigen values for different values of K and S .

K	S	ϵ_1	
		1st Solution	2nd Solution
0	3	1.53376	-1.51742
	2.5	1.08913	-1.20287
	2	0.97563	-0.8101
0.5	3	0.86261	-0.96571
	2.5	0.54185	-0.67231
	2	0.05935	-0.03765
1	3	0.45512	-0.52843

Figure 3 was drawn for the skin friction coefficient along x -axis $f''(0)$ against the parameter S or various values of non-Newtonian parameter K . The critical points of K are S_{c1} , S_{c2} , and S_{c3} where dual solutions exist. Moreover, after these points, there is no solution range. Absolute viscosity reduces for the higher values of the micropolar parameter due to this reduction, the first solution decreases. On the other hand, the dual trend is noticed in the second solution. Figure 4 shows the behavior of $f''(0)$ against λ for various values of angle ξ . The coefficient of skin friction is higher at the inclined plane in the first solution. Moreover, the dual solutions can be found in the shrinking case only. It is also noticed that λ has an inverse relation with the profile of $f''(0)$. The impacts of the material parameter K on the $g'(0)$ for S are demonstrated in Figure 5. It is noticed that the couple's stress coefficient is higher in the

first solution for the higher values of the suction as resistance is created in the fluid flow. On the other hand, dual behavior is noticed in the second solution. Figure 6 is plotted to show the effect of λ on the $g'(0)$ for the various values of ξ . The behavior is revealed in Figure 4. Figure 7 depicts a decreasing behavior in both branches of the solution as the non-Newtonian parameter K is increased. It can be explained as a material parameter enhances the heat transfer rate due to the reduction in the absolute viscosity. As a result, the thickness of the thermal boundary layer becomes thinner. The impact of angle ξ on the $-\theta'(0)$ against the parameter λ is highlighted in Figure 8. The heat transfer rate reduces in both solutions when λ increases.

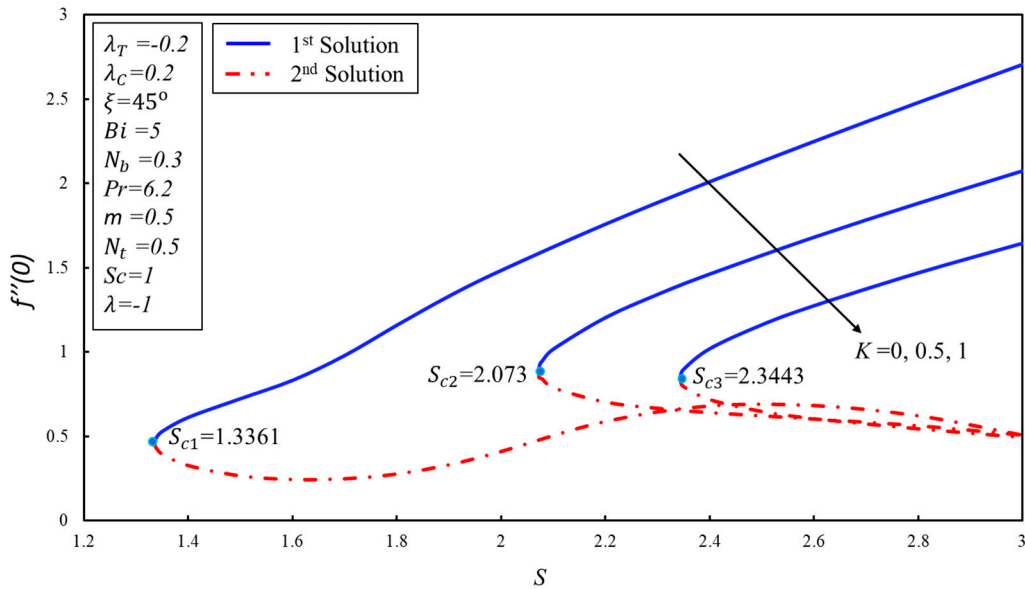


Figure 3. $f''(0)$ versus the suction S for varying material parameter K .

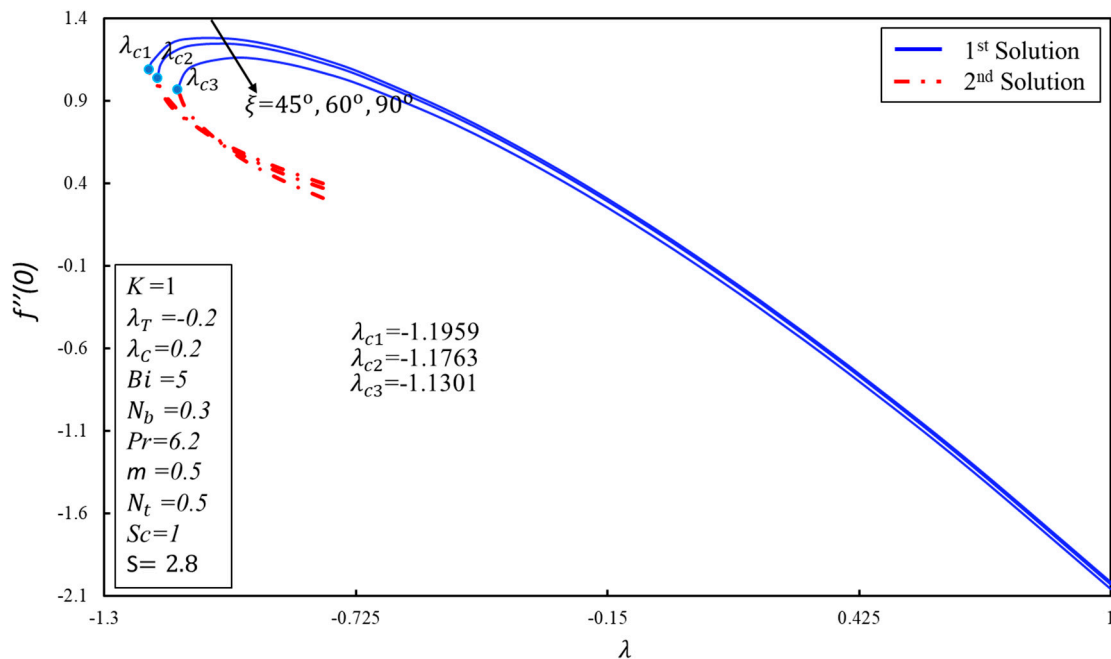


Figure 4. $f''(0)$ versus the stretching/shrinking parameter λ for varying angle ξ .

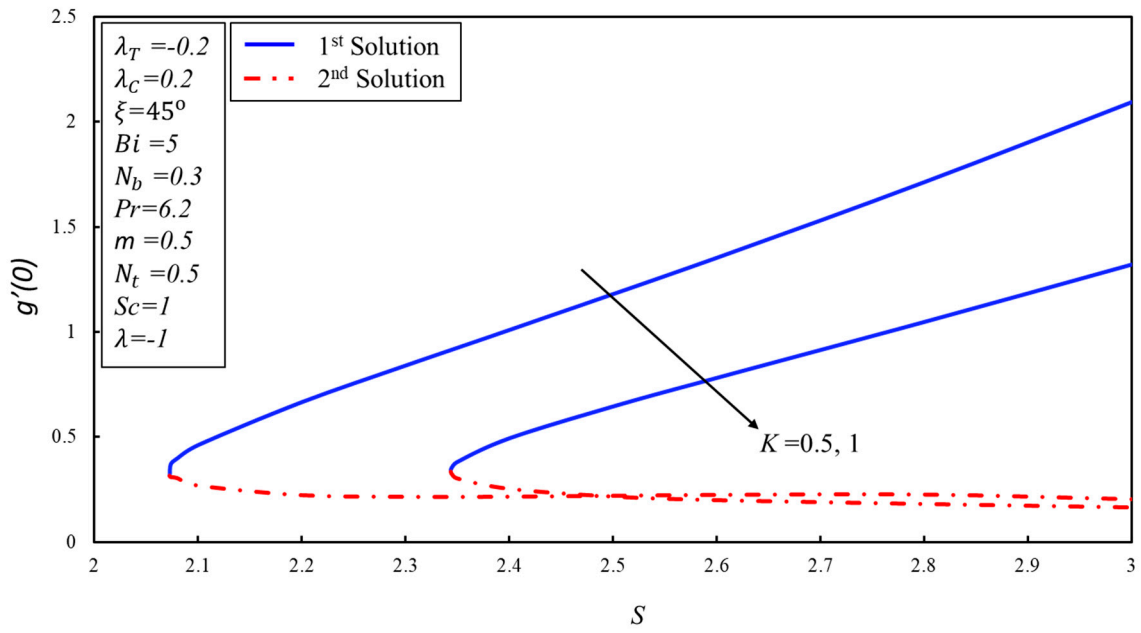


Figure 5. $g'(0)$ versus the suction S for varying material parameter K .

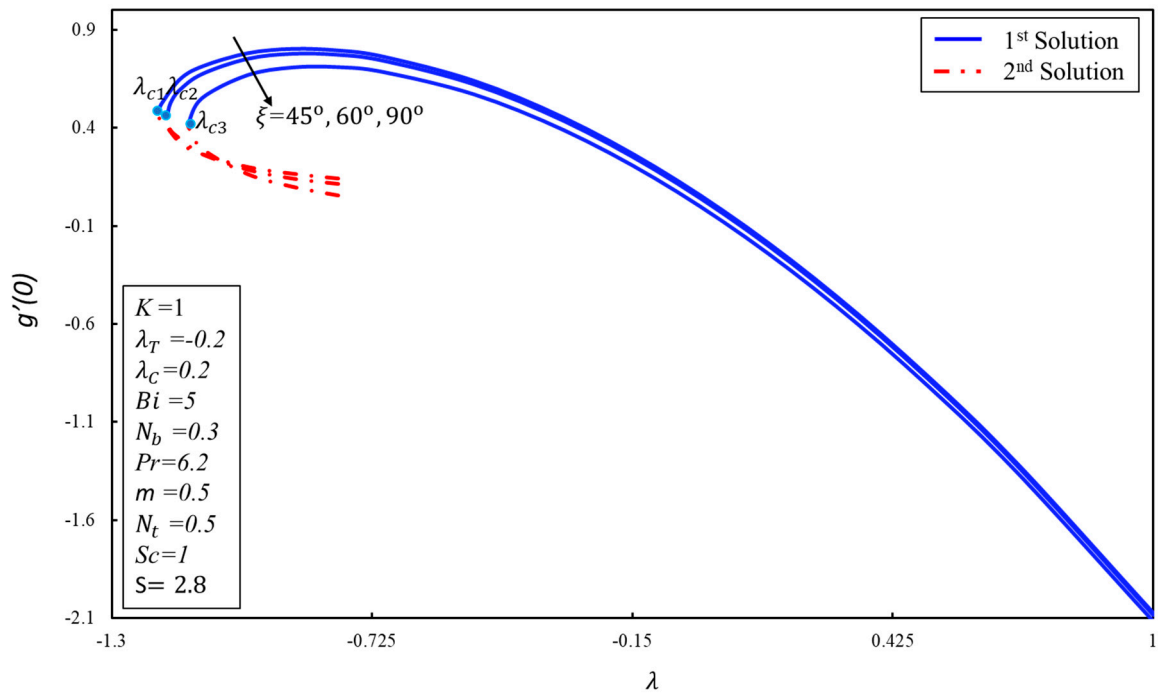


Figure 6. $g'(0)$ versus the stretching/shrinking parameter λ for varying angle ξ .

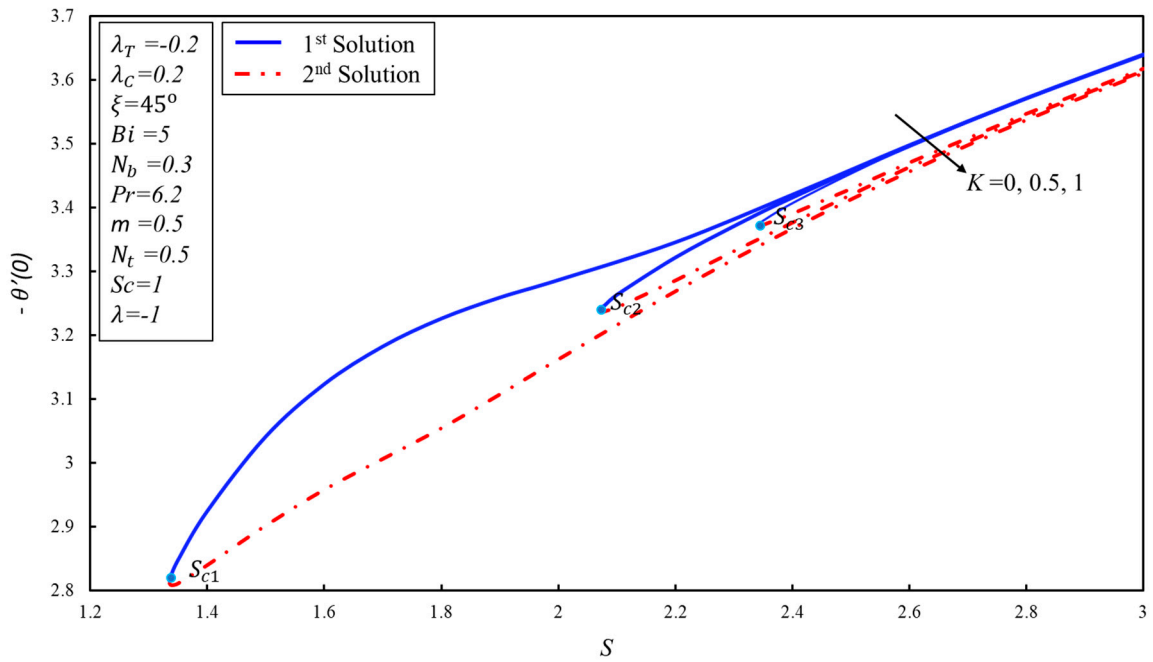


Figure 7. $-\theta'(0)$ versus the suction S for varying material parameter K .

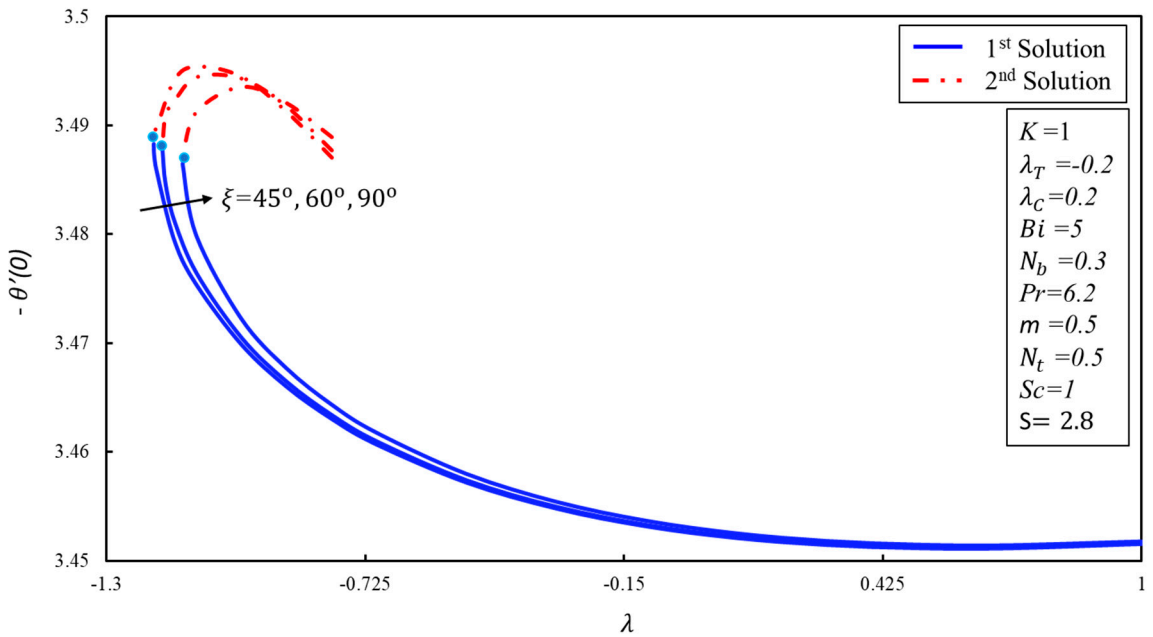


Figure 8. $-\theta'(0)$ versus the stretching/shrinking parameter λ for varying angle ξ .

Figure 9 displays the influences of K on the rate of mass transfer $-\phi'(0)$ against S . It elucidates that both solutions are decelerating for the larger values of K . In general, it can be noticed that the concentration boundary layer is moving down when K is increased. The effects of the angle parameter ξ on the rate of mass transfer against the parameter λ is captured in Figure 10. The similar behavior of solutions is observed in Figure 10 as is noticed in Figure 9.

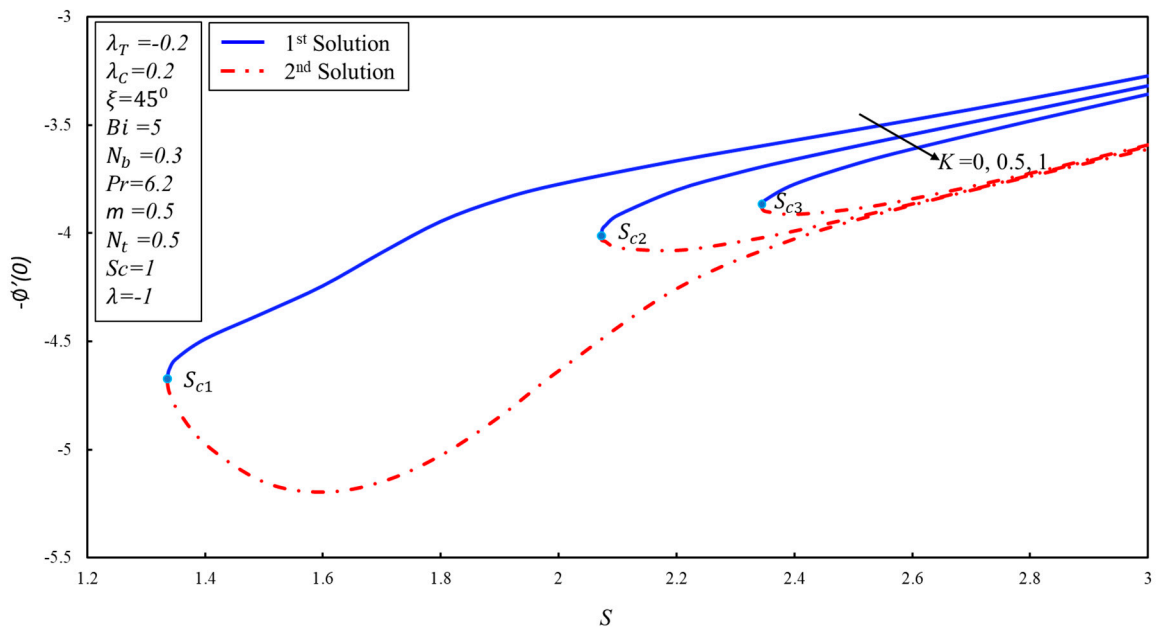


Figure 9. $-\phi'(0)$ versus the suction S for varying material parameter K .

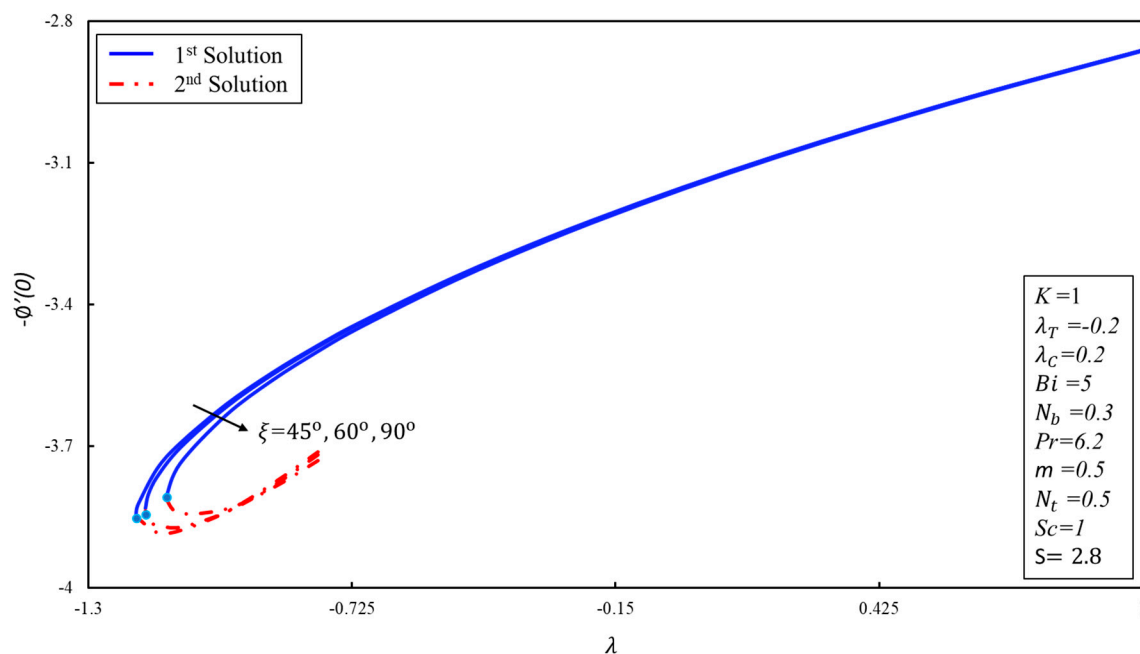


Figure 10. $-\phi'(0)$ versus the stretching/shrinking parameter λ for varying angle ξ .

Figures 11 and 12 show the behavior of the profiles for the $f'(\eta)$ and $g(\eta)$ for the various values of the material parameter K , respectively. Figure 11 demonstrated that the momentum boundary layer is declined in the first solution and inclined in the second solution as K is increased for some fixed angle value ξ as highlighted in the above figure, while the impact of the same corresponding parameter on the $g(\eta)$ is plotted in Figure 12 where the identical behavior is seen in the upper branch solution and the total reverse behavior is observed in the second branch solution. Figures 13–15 are plotted in order to expose the behavior of temperature profile $\theta(\eta)$ for various values of N_t thermophoresis parameter, Bi the Biot number and the Brownian motion parameter N_b , respectively. More exactly, it is scrutinized from Figures 13–15 that when we are augmenting the values of N_t , Bi and N_b , the temperature profile is boosted up in all the figures in both solutions, respectively.

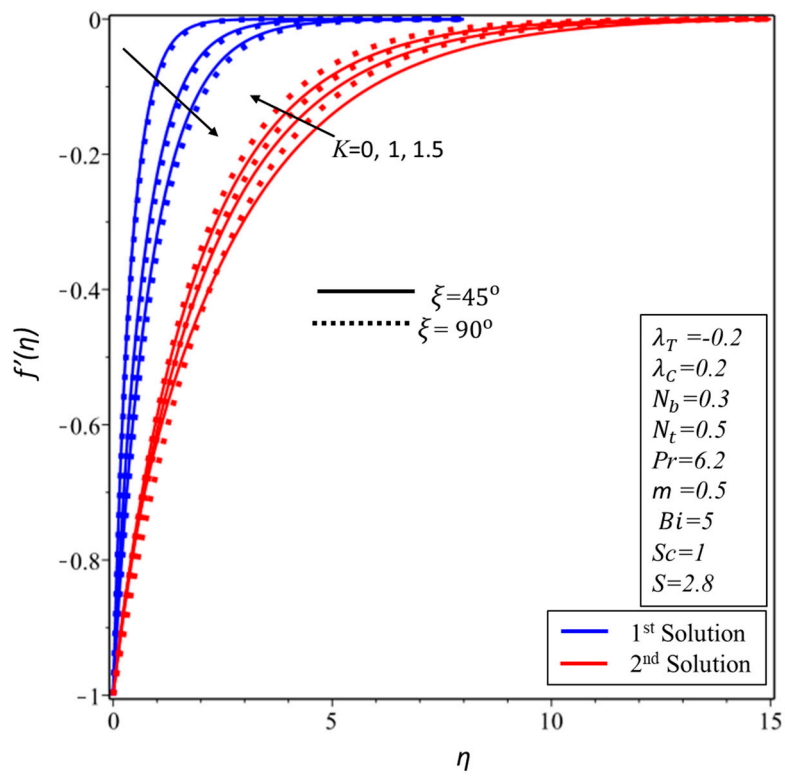


Figure 11. $f'(\eta)$ for various values of material parameter K .

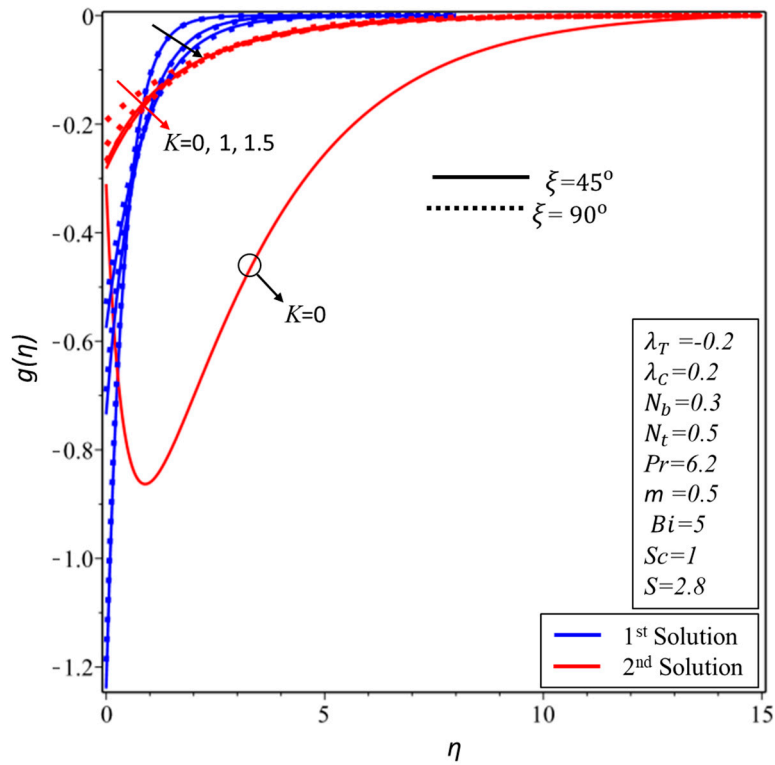


Figure 12. $g(\eta)$ for various values of material parameter K .

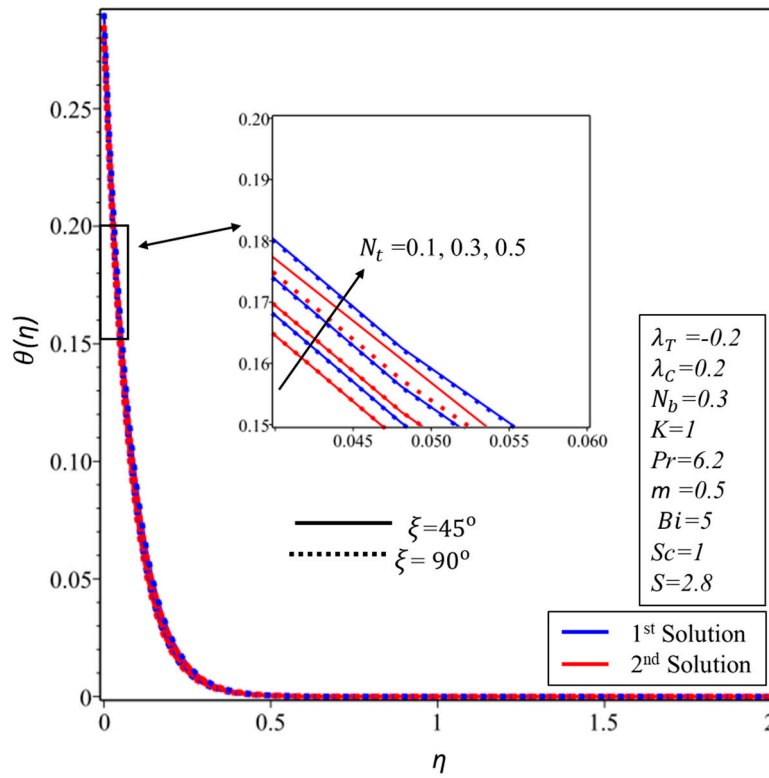


Figure 13. $\theta(\eta)$ for various values of thermophoresis parameter N_t .

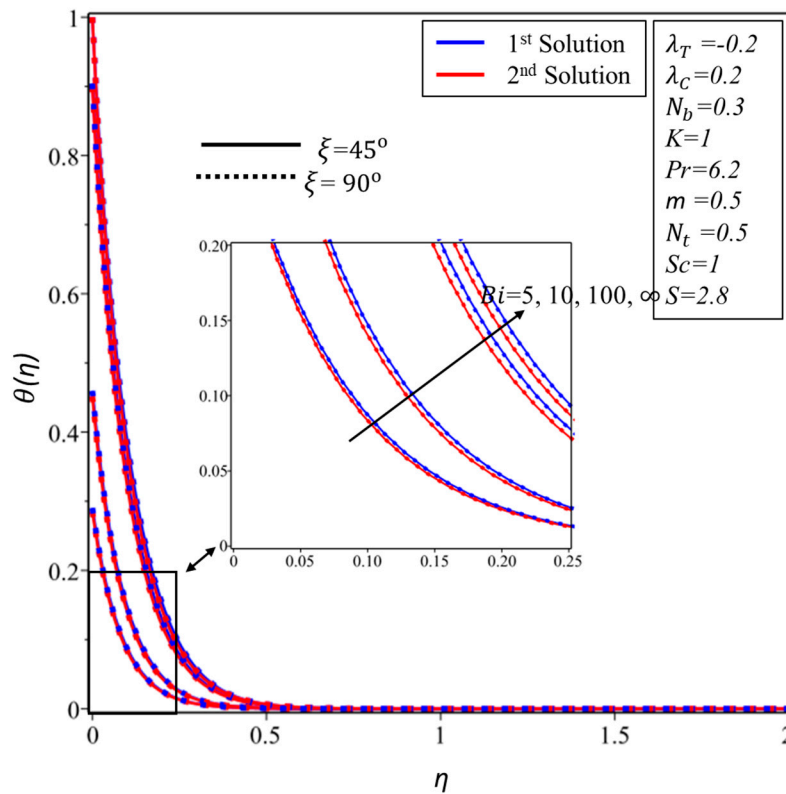


Figure 14. $\theta(\eta)$ for various values of Biot number Bi .

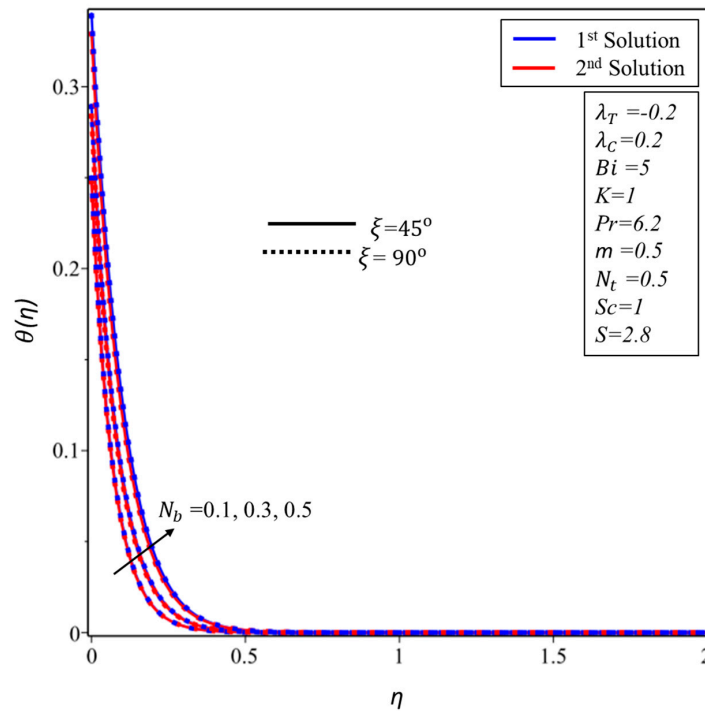


Figure 15. $\theta(\eta)$ for various values of Brownian motion parameter N_b .

Figures 16–18 are designed in order to interpret the behavior of concentration profile $\phi(\eta)$ for various values of N_t thermophoresis parameter, Bi the Biot number and the Brownian motion parameter N_b , respectively. Thus, it is investigated further, from Figures 16 and 17 that when we augment the values of N_t and Bi the concentration boundary layer is larger in both branches of solutions, respectively, whilst the total reverse behavior is observed in Figure 18 for the augmentation of the Brownian motion parameter N_b .

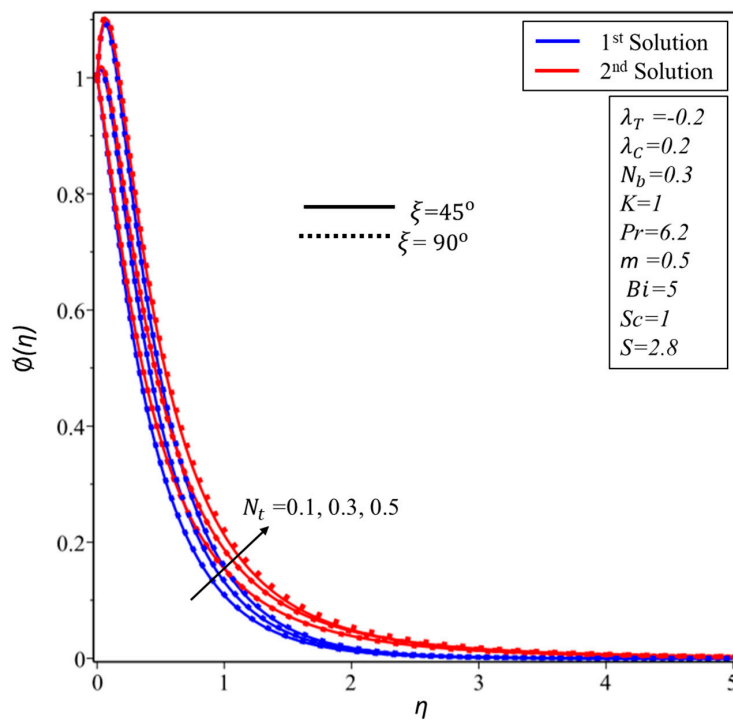


Figure 16. $\phi(\eta)$ for various values of thermophoresis parameter N_t .

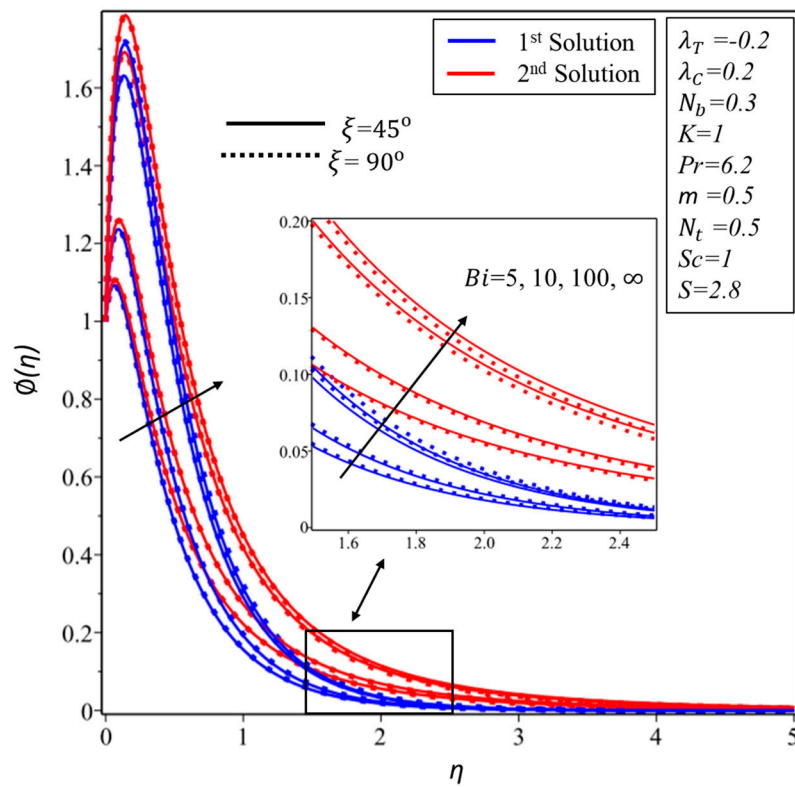


Figure 17. $\phi(\eta)$ for various values of Biot number Bi .

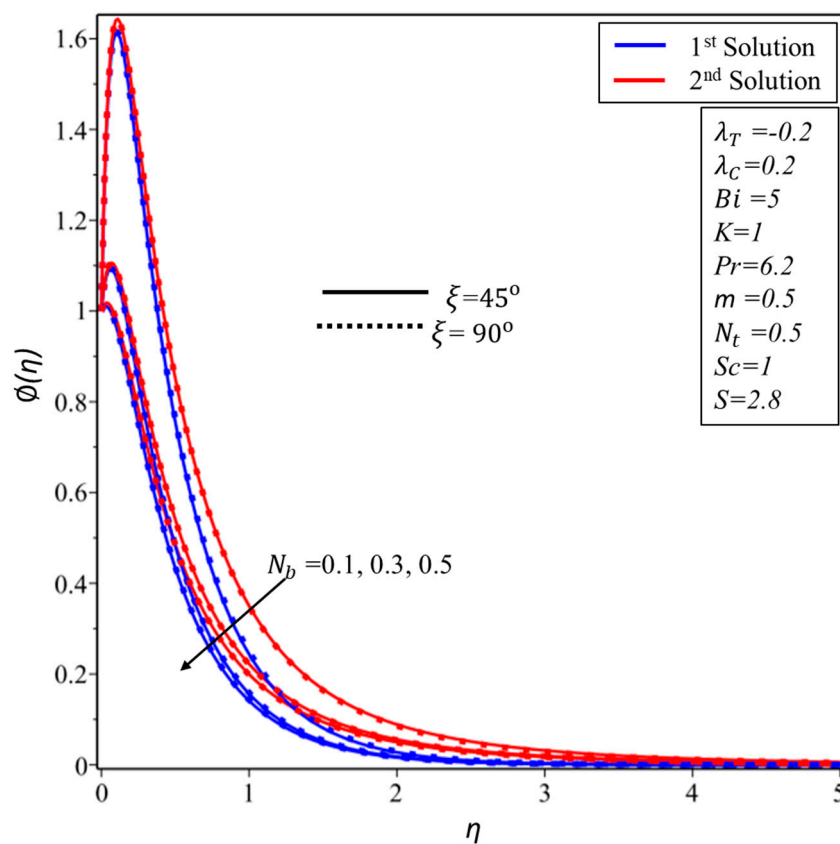


Figure 18. $\phi(\eta)$ for various values of Brownian motion parameter N_b .

6. Conclusions

The two-dimensional steady flow of incompressible micropolar nanofluid on the linear inclined shrinking/stretching surface has been considered in the presence of convective condition. The self-similar equations are solved numerically. The microrotation and the angle ξ effect on the flow implements when the material parameter varies. It is observed that due to the augmentation in the micropolar parameter the steady flow needs more amount of mass suction and the stretching and shrinking parameter. More exactly, in all the phenomenon the dual similarity solutions for velocity, temperature and concentration exist. The skin friction coefficient, the heat transfer coefficient, the $g'(0)$ and the mass transfer rate decelerate in both solutions (first and second solution) against the mass suction parameter for the augmentation of the material parameter K , respectively. On the other hand, the impact of the angle parameter ξ against the parameter λ on the skin friction, mass transfer rate and $g'(0)$ shows an increasing behavior in both solutions whilst the reverse flow is observed for the heat transfer rate.

Author Contributions: Conceptualization, L.A.L. and Z.O.; Funding acquisition, D.B.; Investigation, U.K. and I.K.; Methodology, L.A.L., U.K. and I.K.; Project administration, I.K.; Software, L.A.L., I.K., Z.O., U.K. and K.S.N.; Supervision, I.K.; Review and Revision: D.B. and K.S.N.; Formal Analysis: D.B. and K.S.N. All authors have read and agreed to the published version of the manuscript.

Funding: This research received no external funding.

Acknowledgments: The authors are thankful to the Universiti Utara Malaysia (UUM) for supporting this work.

Conflicts of Interest: The authors declare no conflict of interest.

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