# ON THE FLOW PAST RECTANGULAR CYLINDERS: PHYSICAL ASPECTS AND NUMERICAL SIMULATION 

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## NOMENCLATURE

$A$ rectangular cylinder streamwise length, m
$B$ rectangular cylinder height, m
$C_{S} \quad$ Smagorinsky constant
$d$ normal distance to the closest wall, $m$
$D$ characteristic length, m
$f \quad$ vortex shedding frequency, $\mathrm{s}^{-1}$
$k$ von Kármán constant
$\ell \quad$ subgrid characteristic length, $m$
$L \quad$ rectangular cylinder spanwise length, m
$N$ number of grids over the cylinder side
$p \quad$ pressure, Pa
Re Reynolds number
$S_{i j} \quad$ rate-of-strain tensor, $\mathrm{s}^{-1}$
St Strouhal number
$t$ time, s
$u_{i} \quad x_{i}$-component velocity, m. $\mathrm{s}^{-1}$
$U_{\infty} \quad$ inlet velocity, m. $\mathrm{s}^{-1}$
$x_{i} \quad$ spatial coordinates, m
$v \quad$ kinematic viscosity, $\mathrm{m}^{2} . \mathrm{s}^{-1}$
$\mu \quad$ molecular viscosity, Pa.s
$\mu_{t} \quad$ eddy viscosity, Pa.s
$\rho \quad$ mass density, kg. $\mathrm{m}^{-3}$
$\tau_{i j} \quad$ subgrid-scale Reynolds stress, Pa
$\tau_{k k}$ normal stress, Pa
$\vartheta \quad$ computational cell volume, $\mathrm{m}^{3}$
$\delta_{i j}$ Kronecker delta
$\Delta t \quad$ time step, s
$\Delta t^{*} \quad$ dimensionless time step
$\phi \quad$ aspect ratio

## INTRODUCTION

Flow around square and rectangular cylinders is a frequent happening in engineering. Tall buildings, monuments, and towers are permanently exposed to wind. Similarly, piers, bridge pillars, and legs of offshore platforms are continuously submitted to the load produced by maritime or fluvial streams. This kind of flow is also found in many other technical applications, especially those concerning with thermal and hydraulic devices. For that reason, the literature about this subject is relatively well supplied, including both experimental and numerical investigations. In spite of that, several aspects of this topic remain misunderstood.

Since long ago, experimental works have been conducted in wind tunnels or water channels to determinate aerodynamics loads on cylinders of different cross sections and vortex shedding frequency in its wakes - Vickery (1966), Nakaguchi et al. (1968), Bearman and Trueman (1972), Durão et al. (1988), Hasan (1989), Nakamura et al. (1991), Norberg (1993), Lyn et al. (1995), Reisenberger et al. (2004), and Venugopal et al. (2006). In some cases, measurements are combined with flow visualizations in order to provide phenomenological insight on the fluid motion at the vicinity of the solid body - Okajima (1982), Davis et al. (1984), Nakamura et al. (1996), Lindquist (2000), Mills et al. (2003), Ozgoren (2006), Kuroda et al. (2007), Luo et al. (2007).

Numerical simulation of such a flow, in turn, never was considered a trivial task. Indeed,
notwithstanding the geometrical simplicity of the problem, flow surrounding a rectangular cylinder keeps a high level of complexity due to several factors: presence of adverse pressure gradients, separation and reattachment zones, recirculating regions, highly curved streamlines, and eddy interactions. Calculations performed before the nineties were basically 2 D and, usually, for flows at moderate Reynolds numbers, in which the turbulent effects could safely be neglected - Fromm and Harlow (1963), Davis and Moore (1982), Lee and Leal (1986). Later on, following computer evolution, a number of studies came up that, by means of mesh refining, achieved higher Reynolds numbers, still using 2D approach - Okajima (1990), Ohya et al. (1992), Kondo and Yamada (1995), Tamura et al. (1995), Nakamura et al. (1996), Yu and Kareem (1998), Bouris and Bergeles (1999), Shimada and Ishihara (2002). Nowadays, due to considerable advances in computer technology and numerical methods, 3D simulations of the flow around rectangular cylinders are yet feasible, as it have been performed by Breuer and Pourquié (1996), Kogaki et al. (1997), Noda and Nakayama (2003), Sohankar (2006), Koobus et al. (2007), Kuroda et al. (2007).

According to Monkewitz and Nguyen (1987), the approach 2D suitably represent the main fluid motion properties, since the primary instability mode in the wake of a 2D bluff body is essentially 2D. Nevertheless, experimental studies by Szepessy and Bearman (1992) have established that 2D simulations may substantially overestimate the fluctuating loads. Thus, as important computational resources are available, adequate 3D calculations can offer detailed information about the flow, disclosing physical mechanisms which couldn't be identified in 2D simulations. On the other hand, it is wellknown that 2D simulations using refined grids frequently yield better results than 3D ones performed with coarser meshes. Moreover, in the lack of computational support appropriate to solve 3D flows, the 2D approach remains a profitable tool for fluid flow analysis.

In the present paper, some typical features of the unconfined flow around rectangular cylinders are reviewed and discussed in light of previous works. Thereafter, 2D numerical simulations are accomplished in order to investigate the incompressible flow around rectangular cylinders with aspect ratios varying between 1 and 10 , and Reynolds number ranged from 300 to 22,000 . In some calculations, LES methodology has been employed, using the standard Smagorinsky sub-grid scale model. The results are discussed and confronted with numerical and experimental data from other authors.

## PHYSICAL CONSIDERATIONS AND GEOMETRICAL PARAMETERS

Flow pattern of rectangular cylinders is intrinsically associated to the Reynolds number ( $R e$ ) and aspect ratio $(\phi)$, defined respectively as:
$R e=\frac{U_{\infty} B}{v}$
$\phi=A / B$
where $A, B$ and $U_{\infty}$ are represented in Fig. 1.


Figure 1. Rectangular cylinder in cross-flow.
Based on experimental visualizations by Lindquist (2000), Fig. 2 sketches different flow configurations over a rectangular cylinder at moderate Reynolds numbers. In the Fig. 2(a), a steady flow with symmetric streamlines is established around the whole body. In such a regime, flow detachment cannot be clearly identified even over the leading and trailing edges. As the freestream velocity increases, two recirculating bubbles appear at the cylinder rear - Fig. 2(b) -, which will become asymmetric as the subsequent Reynolds number increasing - Fig. 2(c). In that case, the shear layers downstream the cylinder become unstable and an oscillatory motion can be noted in the wake. The amplitude of the oscillations increases as the Reynolds number grow up - Fig. 2(d). In the next stage, shown in Fig. 2(e), Kelvin-Helmholtz instabilities are generated and advected downstream the cylinder. An alternating vortex shedding regime is then established creating the well-known von Kármán street. In Fig. 2(f), two recirculating bubbles can be identified on the leading edge vicinities due to flow separation at the sharp corners. If the cylinder side length is long enough, a flow reattachment will most likely occur over the two sides of the cylinder. The length of the reattachment region tends to increase as a function of the Reynolds number. Somewhere over the cylinder the shear layer breaks up originating a small discrete vortex that will be shed and advected towards the trailing edges - Fig. 2(g). For Reynolds number beyond 350 - Fig. 2(h) - vortex interactions and mixing in the wake are improved, eddy structures begin to lose their identity, and flow details may became harder to visualize.

In the periodic flow regimes, vortex shedding frequency $(f)$ is related to the mean velocity of the flow $\left(U_{\infty}\right)$ and to the body characteristic length $(D)$ through the Strouhal number ( $S t$ ), defined as:
$S t=f D / U_{\infty}$
where $D$ can be represented by the cylinder transversal height $B$ or the streamwise width $A$.


Figure 2. Streaklines around a rectangular cylinder at moderate Reynolds numbers - based on experimental flow visualizations of Lindquist (2000).

As explained by Okajima et al. (1992), flow configurations over rectangular cylinders are also strongly dependent of the aspect ratio, as depicted in Fig. 3. For short cylinders the flow detaches completely when it passes on the leading edge so that a further reattachment over the cylinder sides is not observed - Fig. 3(a). Thus, two separated shear layers interact with each other behind the cylinder, and the wake structure is similar to that found at the back of a circular cylinder. Increasing the aspect ratio to values between 2 and 6, Fig. 3(b), it is possible to see the alternate reattachment of the boundary layer over the lateral sides of the cylinder. For elongate cylinders Fig. 3(c) - vortices in wake have two distinct geneses. The first one is due to eddies originated from the recirculation bubble splitting in the leading edges, which gallop downstream over the cylinder faces. According to the nomenclature proposed by Ozono et al. (1992), they are called L-vortices. The second origin is concerned with the vortices produced from the boundary layer detachment in the trailing edge, and are named T-vortices. Strong interactions between L-vortices and T-vortices occur at the rear of the cylinder modifying the wake structure, as discussed by Nakamura and Nakashima (1986). Besides, in such a situation vortex shedding is characterized by another type of flow instability not observed over short cylinders, which is called impinging shear-layer instability (ISLI), where a single separated shear layer can became unstable in the presence of a sharp downstream corner.


Figure 3. Influence of the aspect ratio on the flow configuration.

## MATHEMATICAL MODEL

The flow is assumed to be incompressible, unsteady, and 2D, with constant fluid properties. Calculations have been accomplished in two different ways: a) by solving continuity and time-dependent Navier-Stokes equations without turbulence modeling, for relatively low Reynolds numbers; b) employing LES methodology associated with the standard Smagorinsky sub-grid scale model (Smagorinsky, 1963), for Reynolds numbers beyond 1,000 . In this latter case, the governing equations are obtained by means of a filtering process, which leads to the following simultaneous equation system:
$\frac{\partial \bar{u}_{j}}{\partial x_{j}}=0$
$\rho\left[\frac{\partial \bar{u}_{i}}{\partial t}+\frac{\partial}{\partial x_{j}}\left(\bar{u}_{i} \bar{u}_{j}\right)\right]=\frac{\partial}{\partial x_{j}}\left[\mu\left(\frac{\partial \bar{u}_{j}}{\partial x_{j}}+\frac{\partial \bar{u}_{j}}{\partial x_{i}}\right)\right]-\frac{\partial \bar{p}}{\partial x_{i}}-\frac{\partial \tau_{i j}}{\partial x_{j}}$
where the overbar denotes a filtered quantity and $\tau_{i j}$ is the subgrid-scale Reynolds stress, written as:
$\tau_{i j} \equiv \rho\left(\overline{u_{i} u_{j}}-\bar{u}_{i} \bar{u}_{j}\right)$
which appears as additional unknown, and require some kind of modeling to represent it. Classically, the closure process is performed using the Boussinesq hypothesis:
$\tau_{i j}=-2 \mu_{t} \bar{S}_{i j}+\frac{1}{3} \tau_{k k} \delta_{i j}$
where $\mu_{t}$ is the turbulent viscosity, $\delta_{i j}$ is the Kronecker delta, and $\bar{S}_{i j}$ is the rate-of-strain tensor for the resolved scales, which is calculated using the filtered velocity field:
$\bar{S}_{i j}=\frac{1}{2}\left(\frac{\partial \bar{u}_{i}}{\partial x_{j}}+\frac{\partial \bar{u}_{j}}{\partial x_{i}}\right)$
The turbulent viscosity is given by:
$\mu_{t}=\rho\left(C_{s} \ell\right)^{2}\left(2 \bar{S}_{i j} \bar{S}_{i j}\right)^{1 / 2}$
where $\ell$ is the characteristic length for sub-grid turbulent structure, whose value is computed using:

$$
\begin{equation*}
\ell=\min \left(k d, \vartheta^{1 / 3}\right) \tag{10}
\end{equation*}
$$

where $k=0,41$ is the von Kárman constant, $d$ is the normal distance to the closest wall, and $\vartheta$ is the local volume of the computational cell, i.e. $\vartheta=\Delta x_{1} \Delta x_{2}$ in 2D calculations.

The Smagorinsky constant $\left(C_{S}\right)$, analytically estimated by Lilly (1966) as being 0.18 for homogeneous isotropic turbulence, depends in fact on the flow features and the intrinsic characteristics of the computational code, and should be adjusted for each case by means of a calibration process. For flow past bluff bodies simulations the most common values found in the literature are ranged from 0.1 up to 0.2 . In this work, Cs has been adjusted to 0.1 by means of several preliminary tests and this value has been used in turbulent or transitional simulations.

## NUMERICAL PROCEDURE

An incompressible SIMPLEC (Van Doormaal and Raithby, 1984) finite volume algorithm has been used, associated to QUICK scheme (Hayase et al. 1992) to treat the advective terms. A second-order central differences scheme has been employed for the diffusive terms. For time marching, a second-order fully implicit scheme has been adopted, with a dimensionless time step equal to:
$\Delta t^{*}=\Delta t U_{\infty} / B$
Figure 4 presents the computational domain, where a cylinder with aspect ratio equal to 7 , placed at a distance of $X_{l u}$ downstream the inlet boundary, bisects horizontally the domain in two symmetric parts. A Cartesian grid, more refined close to the cylinder surface and in its wake, was employed. Around the cylinder, this mesh is uniformly distributed in both $x_{1}$ and $x_{2}$ directions, being non-uniform out of that region. The number of intervals over the lateral faces of the cylinder $(N)$ has been varied according to the aspect ratio factor $(\phi)$. In order to avoid numerical drawbacks, inside non-uniform zones the grid expansion factor has been limited to $1.2 \%$. Tables 1 and 2 summarize the main data concerning with the different meshes used in all the present simulations.

The boundary conditions have been prescribed as follows: a) at the upstream boundary, the inlet flow has been assumed to be uniform $\left(U_{\infty}\right)$; b) at the outlet, a zero gradient boundary condition for both $u_{1}$ and $u_{2}$ has been used; c) at the upper and lower boundaries, free stream boundary conditions have been set to represent a frictionless wall $\left(u_{2}=\partial u_{1} / \partial x_{2}=0\right)$; d) inside the region occupied by the rectangular cylinder infinite viscosity has been adjusted, that is the same as imposing no-slip condition ( $u_{I}=u_{2}=0$ ) on its walls.

For the Strouhal number calculation, the temporal evolution of the $x_{2}$-component velocity has been captured with a numerical probe placed $1.5 B$ downstream the cylinder base and $2 B$ below the domain
centerline. Two different time steps, $\Delta t=10^{-4} s$ and $\Delta t=10^{-3} \mathrm{~s}$, have been used to advance the temporal solution. The smaller one was chosen to simulate the turbulent flow at $R e=22,000$, while the larger time step was suitable at low and moderate Reynolds numbers.


Figure 4. Computational domain and grid system for a cylinder with $\phi=7$.

Table 1. Computational domain configuration and grid size for $R e=300$.

| $\boldsymbol{M e s} \boldsymbol{h}$ |  |  |  |
| :---: | ---: | :---: | :--- |
| $\boldsymbol{\phi}$ | $\boldsymbol{N} / \boldsymbol{A}$ | $\boldsymbol{\varepsilon} / \boldsymbol{B}$ |  |
| 5 | $250 \times 90$ | 100 | 0.0003 |
| 7 | $270 \times 90$ | 120 | 0.00035 |
| 9 | $290 \times 90$ | 140 | 0.000385 |
| 10 | $300 \times 90$ | 150 | 0.0004 |
| 11 | $310 \times 90$ | 160 | 0.0004125 |
| $X_{2}=15 B$ | (90 horizontal grids) |  |  |
| $X_{I u}=10 B$ | (50 vertical grids) |  |  |
| $X_{l d}=20 B$ | (100 vertical grids) |  |  |

Table 2. Computational domain and grid size for

| $R e=1,000$ and $5,000$ |  |  |  |
| :---: | :---: | :---: | :---: |
| $\boldsymbol{\phi}$ | $\boldsymbol{M e s h}$ | $\boldsymbol{N} / \boldsymbol{A}$ | $\boldsymbol{\varepsilon} / \boldsymbol{B}$ |
| 1 | $240 \times 160$ | $20 *$ |  |
| 2 | $260 \times 160$ | 40 |  |
| 3 | $280 \times 160$ | 60 |  |
| 4 | $300 \times 160$ | 80 |  |
| 5 | $320 \times 160$ | 100 |  |
| 5.2 | $324 \times 160$ | 104 |  |
| 5.4 | $328 \times 160$ | 108 |  |
| 5.6 | $332 \times 160$ | 112 |  |
| 5.8 | $336 \times 160$ | 116 | 0.00075 |
| 6 | $340 \times 160$ | 120 |  |
| 7 | $360 \times 160$ | 140 |  |
| 8 | $380 \times 160$ | 160 |  |
| 8.2 | $384 \times 160$ | 164 |  |
| 8.4 | $388 \times 160$ | 168 |  |
| 8.6 | $392 \times 160$ | 172 |  |
| 8.8 | $396 \times 160$ | 176 |  |
| 9 | $400 \times 160$ | 190 |  |
| 10 | $420 \times 160$ | 200 |  |
| $X_{2}=13 B$ | $(160$ horizontal grids) |  |  |
| $X_{l u}=$ | $7 B$ | (70 vertical grids) |  |
| $X_{I d}=15 B$ | (150 vertical grids) |  |  |

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## RESULTS AND DISCUSSION

Preliminary simulations have been carried out in order to define adequate computational domains to assure grid independence. Both uniform and non-uniform meshes have been tested, with different refinements.

The first definitive simulations were performed without turbulence modeling, for rectangular cylinders with $5 \leq \phi \leq 11$ and $R e=300$. The principal physical goal here was to characterize the flow structure around the cylinder, as well as to determinate the vortex shedding frequencies for each case considered, comparing the present predictions with data of other authors.

The periodic behavior of the wake for $\phi$ up to 16 is characterized in the Fig. 5, in terms of the curve Strouhal versus aspect ratio. The good agreement among results indicates that the numerical schemes, the domain size, the mesh resolution, and the other parameters adjusted have been adequately chosen to capture the complex wake behavior, characterized by abrupt changes in the Strouhal number.


Figure 5. Strouhal number versus aspect ratio for cylinders with $1 \leq \phi \leq 16$, at $R e=300$.

The temporal evolution of streamlines over a cylinder with aspect ratio $\phi=7$ is depicted in Fig. 6, also for $R e=300$. It can be noted that the boundary layers on both cylinder sides detaches at the leading edges and reattaches after the middle of the body. Recirculating structures are identified close to the leading edges, over the cylinder sides, and at the rear of the body. The L-vortex and T-vortex discussed by Ozono et al. (1992) have been clearly captured in the present calculation.

In order to check the LES methodology implementation, a high Reynolds number calculation has been performed taking into account the flow around a square cylinder $(\phi=1)$. The mean longitudinal velocity and the total kinetic energy distribution at the centerline are presented in Fig. 7, for $R e=22,000$. In a general way, strong discrepancies among results of different authors are observed. Nevertheless, one can be verified that the present 2D calculation using LES is in a better agreement with the experimental data of Lyn et al. (1995) than several others, including the 3D LES
of Murakami et al. (1993). At first, this would not be expected, since at $R e=22,000$ the three dimensional effects in the wake are very important, and a 3D simulation should generate a better representation of the flow. That worsened performance may be attributed to either insufficient mesh resolution or the numerical methodology used by those authors. It is interesting also to observe that the $k-\varepsilon$ simulations were not able to predict neither the length of the recirculation zone in the rear of the cylinder nor the velocity recovery in the wake.


Figure 6. Temporal evolution of the streamlines contours for a cylinder with $\phi=7$, at $R e=300$.

The last part of this paper is devoted to the simulation of transitional flows around rectangular cylinders. As a first approach, calculations were performed without turbulence modeling for cylinders with $\phi=1,5$, and 10 , at $R e=1,000$. Figure 8 shows the typical $x_{2}$-velocity signals captured by numerical probes positioned behind the cylinders. The respective power spectral distributions, coming from a fast Fourier transform (FFT) of those fluctuating signals, are also presented, allowing to determine the dimensionless vortex shedding frequencies ( $S t$ ), which correspond to the picks of the larger amplitude founded in each graph.

It is important to mention that the broad range of frequencies that characterizes some of those spectra may not have physical meaning, since no turbulence model has been used and the molecular viscosity alone could be insufficient to dissipate adequately the kinetic energy of the flow.

Hence, similar calculations have been accomplished at the same precedent conditions using LES methodology with Smagorinsky sub-grid model. As expected, the results presented in Fig. 9 show that


Figure 7. Mean horizontal velocity and total kinetic energy distribution along the cylinder centerline, at

$$
R e=22,000 .
$$

the velocity signals are sharply more organized than those previously obtained. Consequently, their corresponding Fourier transforms present only some few discrete peaks, indicating that LES methodology introduced a damping effect on the flow, eliminating part of the spurious instabilities present in the prior signals.

Other simulations have been executed for cylinders with $1 \leq \phi \leq 16$. The results are summarized in Fig. 10 and 11 in terms of St versus $\phi$, for $R e=1,000$ and 5,000 , respectively. The present predictions are compared with results from Nakamura et al. (1996) and Lindquist (2000), for $R e=1,000$, and Okajima (1982) and Okajima (1991), for $R e=5,000$. For both flow conditions a good agreement has been found.

As already observed in the simulations for $R e=300$, presented in Fig. 5, the Strouhal number increases with the aspect ratio up to certain value and then shifts abruptly towards a higher value, presenting a very stiffen behavior in a specific value of $\phi$. Seemingly, this trend repeats itself in intervals that contain three integer aspect ratios. The dashed lines in Fig. 10 and 11 point out that trend in the Strouhal number curves. Although this singular behavior has been also captured in simulations without turbulence model, the LES results are in better agreement with experimental data.


Figure 8. Velocity signals and respective Fourier transforms for different cylinders, at $R e=1,000$.


Figure 9. Velocity signals and respective Fourier transforms for different cylinders, at $R e=1,000$, using LES.


Figure 10. Strouhal number versus aspect ratio for different cylinders, at $R e=1,000$.


Figure 11. Strouhal number versus aspect ratio for different cylinders, at $R e=5,000$.

Physically, those stepwise discontinuities, or plateaus, are related to a transition in the vortex shedding mode, as described in details by Nakamura et al. (1996) and Lindquist (2000). Briefly, for Reynolds numbers higher than 250 , the vortex shedding from rectangular cylinders is influenced by the so-called impinging-shear-layer instability, or simply ISLI. Differently from von Kármán instabilities, where two separated shear layers interact between themselves at the trailing edges, by means of ISLI mechanism a single separated shear layer can became unstable in the presence of a sharp trailing edge corner, as well explained by Ohya et al. (1992). As a consequence of that, the recirculation bubbles formed over the cylinder become unstable and begin to wobble and split in alternated discrete vortices, which are detached and advected downstream of the obstacle.

The numerical visualization of the vorticity field is very useful for the understanding of the Strouhal number behavior. Figures 12, 13, and 14 show the isovorticity contours related to the flow over the cylinders having $\phi=4,7$, and 10 , respectively, using LES. The time sequence shows the flow evolution, illustrating the dynamics of vortex formation and advection over and downstream the cylinder. It can be noted that the L-vortices formed on the faces of the cylinder are advected downstream and interact
with the T-vortices formed in the rear of the cylinder. This interaction seems to be stronger as the aspect ratio $(\phi)$ is increased.
(a) $t^{*}=166,6$


(b) $t^{*}=167,2$


Figure 12. Temporal evolution of the isovorticity contours for a cylinder with $\phi=4$, at $R e=1,000$, using LES.


Figure 13. Temporal evolution of the isovorticity contours for a cylinder with $\phi=7$, at $R e=1,000$, using LES.


Figure 14. Temporal evolution of the isovorticity contours for a cylinder with $\phi=10$, at $R e=1,000$, using LES.

The amount of vortices ( $n$ ) observed over the cylinder face and the Strouhal number $\left(S t_{A}\right)$, based on streamwise width $A$, can be correlated by the following empiric expression, due to Ohya et al. (1992) and Nakamura et al. (1996):
$S t_{A} \cong 0.6 n$
As indicated in the isovorticity maps of those figures, $n=1, n=2$, and $n=3$ for cylinders with $\phi=4, \phi=7$, and $\phi=10$, respectively. Using Eq.(11), the Strouhal number assumes values of $0.6,1.2$, and 1.8 , corresponding to the three first plateaus shown in Fig. 10.

In order to understand the physical behavior of the vortex shedding process related to the jump that appears in the Strouhal number, isovorticity contours of the vortex wake for cylinders with $5.2 \leq \phi \leq 5.8$ and $8.2 \leq \phi \leq 8.8$ are shown in Fig. 15 and 16 respectively. The number of vortices over the cylinders will determine the fundamental frequency of vortex shedding.

In the Fig. 15 there are only two vortices over the cylinders and the Strouhal numbers are nearly constant, keeping the Strouhal number at a same plateau, as seen in the Fig. 10. In Fig. 16 it can be identified two galloping vortices over the cylinders with $\phi=8.2$ and $\phi=8.4$. Therefore, the Strouhal number is placed now in the second plateau. The appearance of a third vortex over the cylinders for $\phi=8.6$ results in an increasing of the Strouhal number, bringing it to the third plateau. So, it seems that the stiffen variation of the Strouhal number is strongly related to the number of vortices resident


Figure 15. Isovorticity contours for cylinders with $5.2 \leq \phi \leq 5.8$, at $R e=1,000$, using LES results.


Figure 16. Isovorticity contours for cylinders with $8.2 \leq \phi \leq 8.6$, at $R e=1,000$, using LES.
over and under the cylinder. It should be remarked that this behavior is identified by two procedures: the FFT of the temporal velocity signature obtained by a numerical probe and by application of the Eq.(11) over the flow visualization given by vorticity fields.

## CONCLUDING REMARKS

A numerical investigation of the flow around rectangular cylinders with aspect ratios varying from 1 to 10 has been presented. Two-dimensional calculations have been accomplished employing large eddy simulation with the classical Smagorinsky turbulence model. Some simulations without turbulence modeling have been also performed. The simulations allowed observe the vortex generation process over the cylinder and its wake. The effects of the rectangular cylinder aspect ratio on the wake dynamics have been investigated with the help of isovorticity visualizations, spectral analysis, and physical parameters calculations as Strouhal number. The isovorticity flow visualizations have also provided support to explain some quantitative results, such as the ISLI (impinging-shear-layer instability). In spite of the 2D calculations, and the transitional nature of these flows, the numerical results with LES present a good agreement with the experimental data presented in previous works. Also, LES exhibits much better results as compared with the calculation without turbulence modeling.

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[^0]:    * $N / A$ increased to 40 for square cylinder simulated at $R e=22,000$.

