Dömötör Pálvölgyi 💿

MTA-ELTE Lendület Combinatorial Geometry Research Group, Institute of Mathematics, Eötvös Loránd University (ELTE), Budapest, Hungary

http://domotorp.web.elte.hu

dom@cs.elte.hu

- Abstract

Define the k-th Radon number r_k of a convexity space as the smallest number (if it exists) for which any set of r_k points can be partitioned into k parts whose convex hulls intersect. Combining the recent abstract fractional Helly theorem of Holmsen and Lee with earlier methods of Bukh, we prove that r_k grows linearly, i.e., $r_k \leq c(r_2) \cdot k$.

2012 ACM Subject Classification Mathematics of computing \rightarrow Hypergraphs; Theory of computation \rightarrow Computational geometry

Keywords and phrases discrete geometry, convexity space, Radon number

Digital Object Identifier 10.4230/LIPIcs.SoCG.2020.60

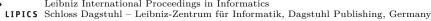
Funding Dömötör Pálvölgyi: Research supported by the Lendület program of the Hungarian Academy of Sciences (MTA), under grant number LP2017-19/2017.

Acknowledgements I would like to thank Boris Bukh and Narmada Varadarajan for discussions on [6], Andreas Holmsen for calling my attention to the difference between restricted and multiset Radon numbers, especially for confirming that Theorem 2 also holds for multisets, and Gábor Damásdi, Balázs Keszegh, Padmini Mukkamala and Géza Tóth for feedback on earlier versions of this manuscript, especially for fixing the computations in the proof of Lemma 3. I would also like to thank my anonymous referees for several valuable suggestions.

1 Introduction

Define a convexity space as a pair (X, \mathcal{C}) , where X is any set of points and \mathcal{C} , the collection of convex sets, is any family over X that contains \emptyset, X , and is closed under (arbitrary) intersection and under (arbitrary) union of nested sets. The convex hull, conv(S), of some point set $S \subset X$ is defined as the intersection of all convex sets containing S, i.e., $conv(S) = \bigcap \{C \in \mathcal{C} \mid S \subset C\}$; since \mathcal{C} is closed under intersection, conv(S) is the minimal convex set containing C. This generalization of convex sets includes several examples; for an overview, see the book by van de Vel [26] or for a more recent work, [20]. It is a natural question what properties of convex sets of \mathbb{R}^d are preserved, or what the relationships are among them for general convexity spaces. A much investigated parameter is the Radon number r_k (sometimes also called Partition number or Partition number), which is defined as the smallest number (if it exists) for which any set of r_k points can be partitioned into k parts whose convex hulls intersect. For k = 2, we simply write $r = r_2$.

In case of the convex sets of \mathbb{R}^d , it was shown by Radon [23] that r=d+2 and by Tverberg [25] that $r_k=(d+1)(k-1)+1$. Calder [7] and Eckhoff [11] raised the question whether $r_k \leq (r-1)(k-1)+1$ also holds for general convexity spaces (when r exists), and this became known as Eckhoff's conjecture. It was shown by Jamison [16] that the conjecture is true if r=3, and that the existence of r always implies that r_k exists and $r_k \leq r^{\lceil \log_2 k \rceil} \leq (2k)^{\log_2 r}$. His proof used the recursion $r_{k\ell} \leq r_k r_\ell$ which was later improved by Eckhoff [12] to $r_{2k+1} \leq (r-1)(r_{k+1}-1)+r_k+1$, but this did not significantly change the growth rate of the upper bound. Recently Bukh [6] disproved the conjectured bound





 $r_k \leq (r-1)(k-1)+1$ by showing an example where r=4, but $r_k \geq 3k-1$ (just one more than the conjectured value), and also improved the upper bound to $r_k = O(k^2 \log^2 k)$, where the hidden constant depends on r. We improve this to $r_k = O(k)$, which is optimal up to a constant factor and might lead to interesting applications.

▶ **Theorem 1.** If a convexity space (X, \mathcal{C}) has Radon number r, then $r_k \leq c(r) \cdot k$.

Our proof combines the methods of Bukh with recent results of Holmsen and Lee [15]. In particular, we will use the following version of the classical fractional Helly theorem [17].

▶ Theorem 2 (Holmsen-Lee [15]). For any $r \geq 3$ there is an f such that for any $\alpha > 0$ there is a $\beta > 0$ with the following property. If a convexity space (X, \mathcal{C}) has Radon number r, then for any finite family \mathcal{F} of convex sets if at least an α fraction of the f-tuples of \mathcal{F} are intersecting, then a β fraction of \mathcal{F} intersects.

There are several other connections between the parameters of a convexity space [26]; for example, earlier it was already shown [19] that in convexity spaces the Helly number is always strictly less than r (if r is finite), while in [15] it was also shown that the colorful Helly number [4] can be also bounded by some function of r (and this implied Theorem 2 combined with a combinatorial result from [14]). It was also shown in [15] that it follows from the work of Alon et al. [2] that weak ε -nets [1] of size $c(\varepsilon, r)$ also exist and a (p, q)-theorem [3] also holds, so understanding these parameters better might lead to improved ε -net bounds. It remains an interesting challenge and a popular topic to find new connections among such theorems; for some recent papers studying the Radon numbers or Tverberg theorems of various convexity spaces, see [8, 9, 10, 13, 18, 22, 21, 24], while for a comprehensive survey, see Bárány and Soberón [5].

Restricted vs. multiset

In case of general convexity spaces, there are two, slightly different definitions of Radon numbers ([26]: 5.19). When we do not allow repetitions in the point set P to be partitioned, i.e., P consist of different points, the parameter is called the restricted Radon number, which we will denote by $r_k^{(1)}$. If repetitions are also allowed, i.e., we want to partition a multiset, the parameter is called the unrestricted or multiset Radon number, which we will denote by $r_k^{(m)}$. The obvious connection between these parameters is $r_k^{(1)} \leq r_k^{(m)} \leq (k-1)(r_k^{(1)}-1)+1$. In the earlier papers multiset Radon numbers were preferred, while later papers usually focused on restricted Radon numbers; we followed the spirit of the age, so the results in the Introduction were written using the definition of $r_k^{(1)}$, although some of the bounds (like Jamison's or Eckhoff's) are valid for both definitions. The proof of Theorem 1, however, also works for multisets, so we will in fact prove the stronger $r_k^{(m)} = O(k)$, and in the following simply use r_k for the multiset Radon number $r_k^{(m)}$.

A similar issue arises in Theorem 2; is \mathcal{F} allowed to be a multifamily? Though not emphasized in [15], their proof also works in this case and we will use it for a multifamily. Note that this could be avoided with some cumbersome tricks, like adding more points to the convexity space without increasing the Radon number r to make all sets of a family different, but we do not go into details, as Theorem 2 anyhow holds for multifamilies.

We would like to point out that a difficulty in proving these results is that the existence of a Carathéodory-type theorem is not implied by the existence of r.

D. Pálvölgyi 60:3

2 Proof

Fix r, and a collection of points P with cardinality tk, where we allow repetitions and the cardinality is understood as the sum of the multiplicities. We will treat all points of P as if they were different even if they coincide in X, e.g., when taking subsets.

We need to show that if $t \geq c(r)$, then we can partition P into k sets whose convex hulls intersect. For a fixed constant s, define \mathcal{F} to be the family of convex sets that are the convex hull of some s-element subset of P, i.e., $\mathcal{F} = \{conv(S) \mid S \subset P, |S| = s\}$. Since we treat all points of P as different, \mathcal{F} will be a multifamily with $|\mathcal{F}| = {tk \choose s}$. We will refer to the point set S whose convex hull gave some $F = conv(S) \in \mathcal{F}$ as the vertices of F (despite that some of the points might be in the convex hull of the remaining ones). Note that for some $S \neq S'$, we might have conv(S) = conv(S'), but the vertices of conv(S) and conv(S') will still be S and S'; since P is a multiset, it is even possible that $S \cap S' = \emptyset$.

The constants t and s will be set to be large enough compared to some parameters that we get from Theorem 2 when we apply it to a fixed α . (Our arguments work for any $0<\alpha<1$.) First we set s to be large enough depending on α and r_f (where f is the fractional Helly number from Theorem 2; recall that $r_f \leq r^{\log f}$ is a constant [16]), then we set t to be large enough depending on s and β (which depends on our chosen α). In particular, we can set $s = \log(\frac{1}{1-\alpha_1})r_ff^{fr_f}$ and $t = \max(\frac{s^2}{\beta}; \frac{(fs)^2}{k(1-\alpha_2)})$, where $0 < \alpha_1, \alpha_2 < 1$ are any two numbers such that $\alpha_1 \cdot \alpha_2 = \alpha$. Also, we note that the proof from [14, 15] gives $f \leq r^{r^{\log r}}$ and $\beta = \Omega(\alpha^{r^f})$ for Theorem 2. Combining all these to get the best bound, note that $r^f, f^{r_f} \leq R \approx r^{r^{r^{\log r}}}$. Set $\alpha = 1 - \frac{1}{R}$ with, e.g., $\alpha_1 = \alpha_2 \approx 1 - \frac{1}{2R}$. This keeps β constant, and both s and t around t, so we get an upper bound of approximately $t^{r^{r^{\log r}}}$ for t. (The simpler t and t around t around give approximately t and t around t around t and t around t around t and t around t around t around t around t and t around t around t and t around t around t around t around t around t are t and t around t are t and t around t are t and t around t are t and t around t

▶ **Lemma 3.** An α fraction of the f-tuples of \mathcal{F} are intersecting.

Proof. Since t is large enough, almost all f-tuples will be vertex-disjoint, thus it will be enough to deal with such f-tuples. More precisely, the probability of an f-tuple being vertex-disjoint is at least $(1 - \frac{fs}{tk})^{fs} \ge 1 - \frac{(fs)^2}{tk} \ge \alpha_2$ by the choice of t. We need to prove that at least an α_1 fraction of these vertex-disjoint f-tuples will be intersecting.

Partition the vertex-disjoint f-tuples into groups depending on which (fs)-element subset of P is the union of their vertices. We will show that for each group an α_1 fraction of them are intersecting. We do this by generating the f-tuples of a group uniformly at random and show that such a random f-tuple will be intersecting with probability at least α_1 . For technical reasons, suppose that $m = \frac{s}{r_f}$ is an integer and partition the fs supporting points of the group randomly into m subsets of size fr_f , denoted by V_1, \ldots, V_m . Call an f-tuple $type(V_1, \ldots, V_m)$ if each set of the f-tuple intersects each V_i in r_f points. Since these V_i were picked randomly, it is enough to show that the probability that a (V_1, \ldots, V_m) -type f-tuple is intersecting is at least α_1 .

The (V_1,\ldots,V_m) -type f-tuples can be uniformly generated by partitioning each V_i into f equal parts of size r_f . Therefore, it is enough to show that such a random f-tuple will be intersecting with probability at least α_1 . Since $|V_i| \geq r_f$, there is at least one partition of the first r_f points of V_i to f parts whose convex hulls intersect. Since we can distribute the remaining $(f-1)r_f$ points of V_i to make all f parts equal, we get that when we partition V_i into f equal parts of size r_f , the convex hulls of these parts will intersect with probability at least $\binom{fr_f}{r_f,r_f,\ldots,r_f}^{-1} \geq f^{-fr_f}$. Since these events are independent for each i, we get that the final f-tuple will be intersecting with probability at least $1-(1-f^{-fr_f})^m \geq 1-e^{-mf^{-fr_f}} \geq \alpha_1$ by the choice of s.

Therefore, if s is large enough, the conditions of Theorem 2 are met, so at least $\beta\binom{tk}{s}$ members of $\mathcal F$ intersect. In other words, these intersecting sets form an s-uniform hypergraph $\mathcal H$ on tk vertices that is β -dense. We need to show that $\mathcal H$ has k disjoint edges to obtain the desired partition of P into k parts with intersecting convex hulls. For a contradiction, suppose that $\mathcal H$ has only k-1 disjoint edges. Then every other edge meets one of their (k-1)s vertices. There are at most $(k-1)s\binom{tk}{s-1}$ such edges, which is less than $\beta\binom{tk}{s}$ if $(k-1)s<\beta\frac{tk-s+1}{s}$, but this holds by the choice of t. This finishes the proof of Theorem 1.

Concluding remarks

It is an interesting question to study how big f can be compared to r and the Helly number h of (X,\mathcal{C}) . The current bound [15] gives $f \leq h^{r_h} \leq r^{r^{\log r}}$. We would like to point out that the first inequality, $f \leq h^{r_h}$, can be (almost) strict, as shown by the following example, similar to Example 3 (cylinders) of [20]. Let $X = \{1, \ldots, q\}^d$ be the points of a d-dimensional grid, and let \mathcal{C} consist of the intersections of the axis-parallel affine subspaces with X. (Note that for q = 2, X will be the vertices of a d-dimensional cube, and \mathcal{C} its faces.) It is easy to check that h = 2, $r = \lfloor \log(d+1) + 2 \rfloor$ and f = d+1; the last equality follows from that for $\alpha = \frac{d!}{d^d}$ we need $\beta = \frac{1}{q}$ when \mathcal{F} consists of all qd axis-parallel affine hyperplanes (if q is large enough).

It is tempting to assume that Theorem 1 would improve the second inequality, $h^{r_h} \leq r^{r^{\log r}}$, as instead of $r_h \leq r^{\log h}$ we can use $r_h = O(h)$. Unfortunately, recall that the hidden constant depended on r, in particular, it is around $r^{r^{\log r}}$. We have a suspicion that this might not be entirely sharp, so a natural question is whether this dependence could be removed to improve $r_k \leq r^{r^{\log r}} \cdot k$ to $r_k \leq c \cdot r \cdot k$. This would truly lead to an improvement of the upper bound on f in Theorem 2 and would lead to further applications [5].

- References -

- 1 N. Alon, I. Bárány, Z. Füredi, and D. J. Kleitman. Point selections and weak ε-nets for convex hulls. Comb. Prob. Comput., 1:189–200, 1992.
- 2 N. Alon, G. Kalai, J. Matoušek, and R. Meshulam. Transversal numbers for hypergraphs arising in geometry. *Adv. in Appl. Math.*, 29:79–101, 2002.
- 3 N. Alon and D. J. Kleitman. Piercing convex sets and the Hadwiger-Debrunner (p, q)-problem. Adv. Math., 96:103–112, 1992.
- 4 I. Bárány. A generalization of Carathéodory's theorem. Disc. Math., 40:141–152, 1982.
- 5 I. Bárány and P. Soberón. Tverberg's theorem is 50 years old: a survey. Bull. Amer. Math. Soc. (N.S.), 55(4):459–492, 2018.
- 6 B. Bukh. Radon partitions in convexity spaces. arXiv, 2010. arXiv:1009.2384.
- 7 J. R. Calder. Some elementary properties of interval convexities. J. London Math. Soc., 2(3):422-428, 1971.
- **8** J. A. de Loera, R. N. La Haye, D. Rolnick, and P. Soberón. Quantitative combinatorial geometry for continuous parameters. *Discrete Comput. Geom.*, 57(2):318–334, 2017.
- J. A. de Loera, R. N. La Haye, D. Rolnick, and P. Soberón. Quantitative Tverberg theorems over lattices and other discrete sets. *Discrete Comput. Geom.*, 58(2):435–448, 2017.
- J. A. de Loera, T. A. Hogan, F. Meunier, and N. H. Mustafa. Tverberg theorems over discrete sets of points. arXiv, 2018. arXiv:1803.01816.
- J. Eckhoff. Radon's theorem revisited. In Contributions to geometry (Proc. Geom. Sympos., Siegen, 1978), pages 164–185, Basel, 1979. Birkhäuser.
- J. Eckhoff. The partition conjecture. Disc. Math., 221 (Selected papers in honor of Ludwig Danzer):61–78, 2000.

D. Pálvölgyi 60:5

13 R. Fulek, B. Gärtner, A. Kupavskii, P. Valtr, and U. Wagner. The crossing Tverberg theorem. In Symposium on Computational Geometry (SoCG 2019), pages 38:1–38:13, 2019.

- 14 A. F. Holmsen. Large cliques in hypergraphs with forbidden substructures. *Combinatorica*, 2019. accepted. arXiv:1903.00245.
- A. F. Holmsen and D.-G. Lee. Radon numbers and the fractional Helly theorem. *Israel J. of Mathematics*, 2019. accepted. arXiv:1903.01068.
- 16 R. E. Jamison-Waldner. Partition numbers for trees and ordered sets. *Pacific J. Math.*, 96(1):115-140, 1981.
- M. Katchalski and A. Liu. A problem of geometry in Rⁿ. Proc. Amer. Math. Soc, 75:284–288, 1979.
- 18 S. Letzter. Radon numbers for trees. Disc. Math., 340:333–344, 2017.
- 19 F. W. Levi. On Helly's theorem and the axioms of convexity. *J. Indian Math. Soc.*, 15:65–76, 1951.
- 20 S. Moran and A. Yehudayoff. On weak ε-nets and the Radon number. In Symposium on Computational Geometry (SoCG 2019), pages 51:1–51:14, 2019.
- 21 Z. Paták. Properties of closure operators in the plane. arXiv, 2019. arXiv:1908.01677.
- 22 P. Patáková. Bounding Radon's number via Betti numbers. arXiv, 2019. arXiv:1909.08489.
- 23 J. Radon. Mengen konvexer Körper, die einen gemeinsamen Punkt enthalte. Math. Ann., 83:113–115, 1921.
- 24 P. Soberón. Tverberg partitions as weak ε -nets. Combinatorica, 39:447–458, 2019.
- 25 H. Tverberg. A generalization of Radon's theorem. J. London Math. Soc., 41:123–128, 1966.
- **26** M. L. J. van de Vel. *Theory of convex structures*, volume 50. North-Holland Mathematical Library, Amsterdam, 1993.