



Space Dynamics

LABORATORY

Utah State University Research Foundation

Absolute Radiance Recalibration of FIRST using a Cold Blackbody

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Outline

- ▶ FIRST
- ▶ FIRST calibration
- ▶ Previous calibration results
- ▶ New absolute radiance response calibration

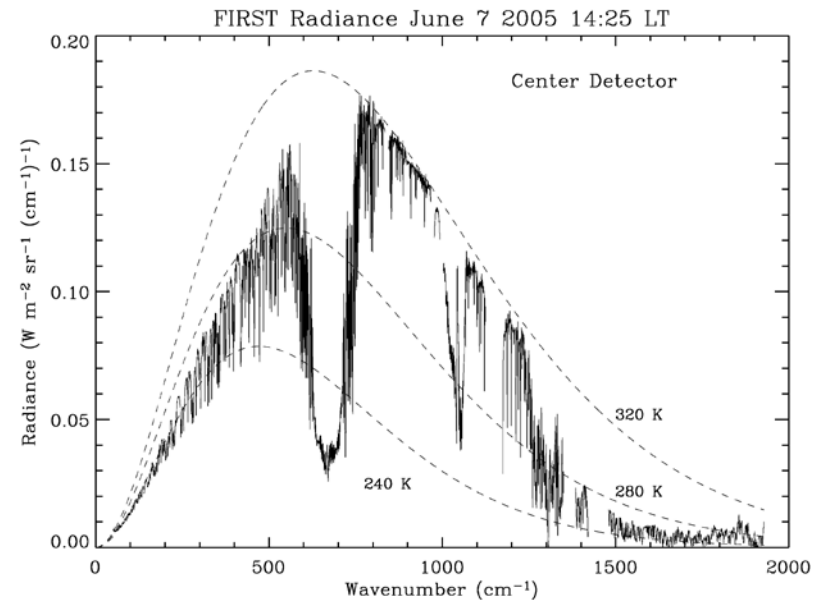


FIRST (Far-IR Spectroscopy of the Troposphere)

- ▶ FIRST is an instrument that measures the Earth's atmospheric radiance in the FAR-IR
- ▶ Has been successfully used since 2005 from high altitude balloons and from the ground
- ▶ FIRST developed under an Instrument Incubator Program
 - Goal of developing technology needed to attain daily global coverage, from low-earth orbit, of the Earth's far-infrared spectrum
 - Technology to be demonstrated with a prototype instrument in a space like environment

Far-IR ($>15 \mu\text{m}$, $<667 \text{ cm}^{-1}$)

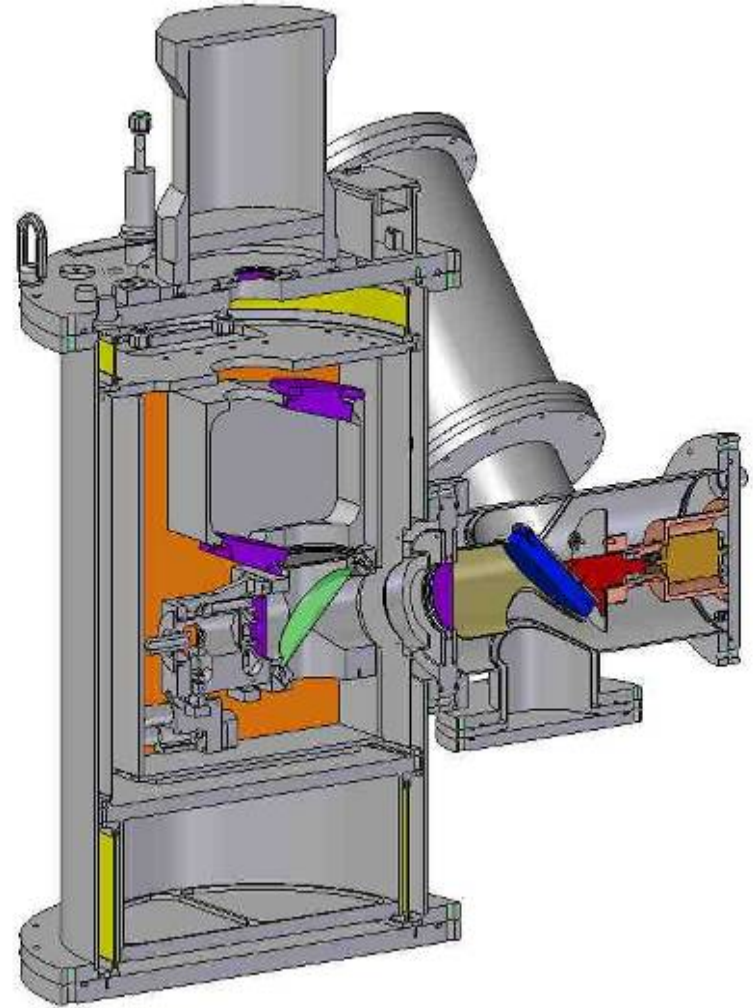
- ▶ Contains half of Earth's outgoing long-wave radiation
- ▶ Is not well observed spectrally



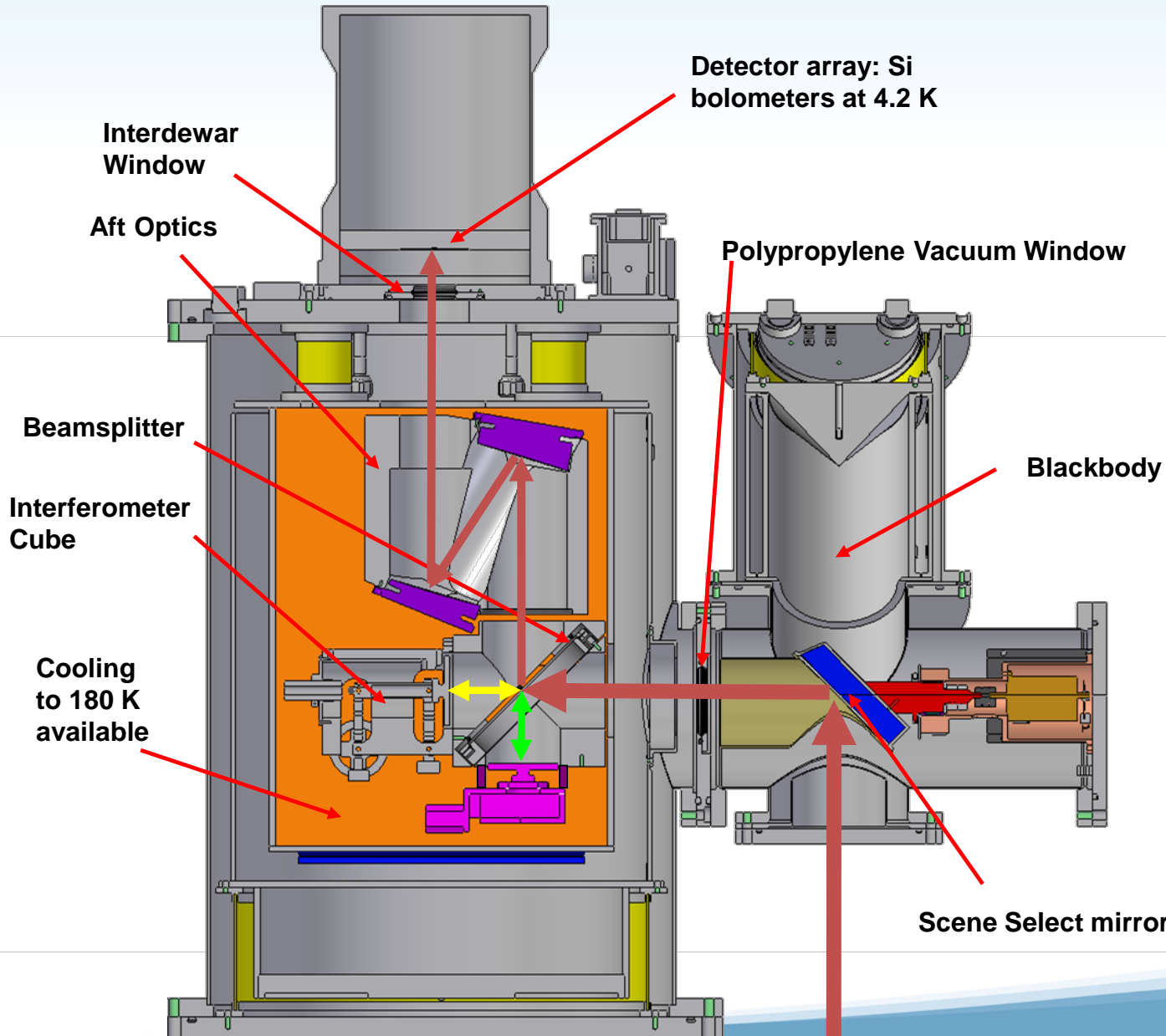
FIRST spectrum from high altitude balloon

FIRST specs

- ▶ Fourier Transform spectrometer
 - Michelson interferometer
 - Coverage
 - Goal: 100 to 1000 cm^{-1} (100 to 10 μm)
 - Actual: 50 to 2200 cm^{-1} (200 to 4.5 μm) with breaks
- ▶ Spectral Resolution: 0.643 cm^{-1} (unapodized)
- ▶ NE Δ T goals
 - 0.2 K (k=1) 170 to 1000 cm^{-1} @ 230 K
 - 0.5 K (k=1) 100 to 170 cm^{-1} @ 230 K
- ▶ Accuracy goal: equal to NE Δ T
- ▶ Two on-board blackbodies or blackbody and space view for calibration
- ▶ 7 cm aperture
- ▶ Ability to have 4.4° FOV (~100 km from orbit)
 - 10 detectors in sparsely populated array
- ▶ Liquid He cooled Si bolometers
- ▶ 0.41° IFOV (~10 km from orbit)
- ▶ 24576 points per interferogram
- ▶ 11.5 sec collection time



FIRST



- Simple optics
- 3 sections
- 3 port SSA scene select assembly (SSA)
- SSA can be rotated
- COTS electronics

FIRST on-board calibration

- ▶ FIRST views both on-board calibration sources during data collection
- ▶ Calibration equation

$$R_{Target} = \frac{S_{Target} - S_{ABB}}{\mathfrak{R}} + P(T_{ABB}) \quad \mathfrak{R} = \frac{S_{WBB} - S_{ABB}}{P(T_{WBB}) - P(T_{ABB})}$$

S_{Target} , S_{WBB} , S_{ABB} : Observed signal from target, warm and ambient blackbodies

T_{WBB} , T_{ABB} : Temperature of warm and ambient blackbodies

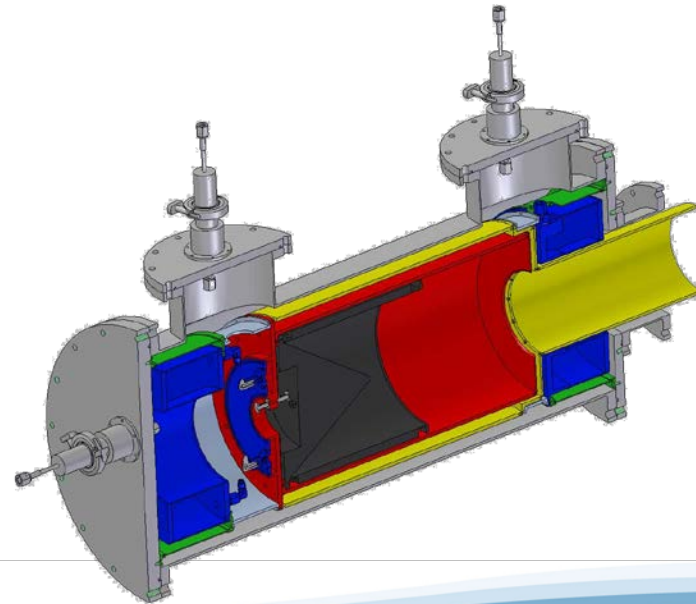
- ▶ Used to calculate target radiance
- ▶ Warm, Ambient blackbodies used for ground data
- ▶ Warm blackbody, space view used for balloon data
- ▶ Forward and backward scans are calibrated independently

FIRST ground calibration

- ▶ FIRST calibrated for absolute response on ground by observing on-board blackbodies and LWIRCS (calibrator blackbody) on the open port.
- ▶ Observe LWIRCS at a set of temperatures, compare observed brightness temperature to LWIRCS temperature

LWIRCS

- ▶ Wavelength range 1 to 100 μm
- ▶ Temperature range: 80 to 350 K
- ▶ Aperture: 6.1 inches
- ▶ Beam divergence: 6° full angle
- ▶ Temperature unc 130 mK 180 K
60 mK 290 K
- ▶ Emissivity ≥ 0.9998 ($< 35 \mu\text{m}$)
 ≥ 0.9980 ($> 35 \mu\text{m}$)

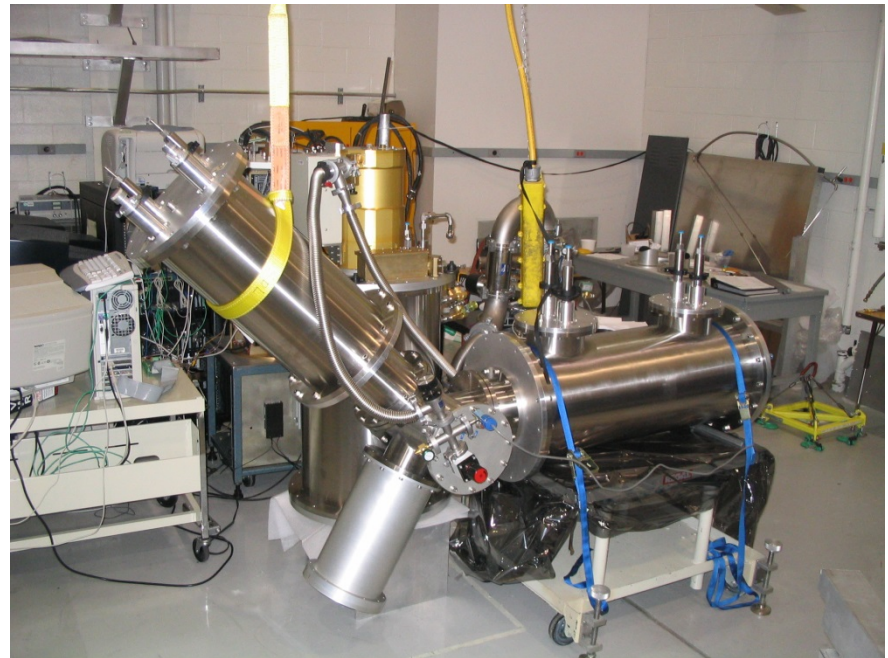


Previous results

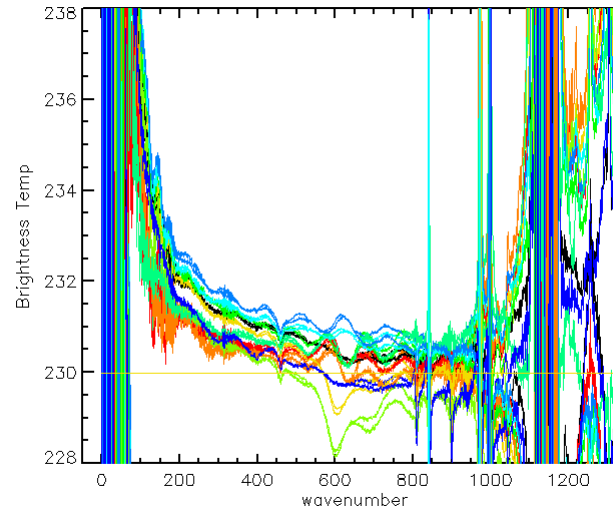
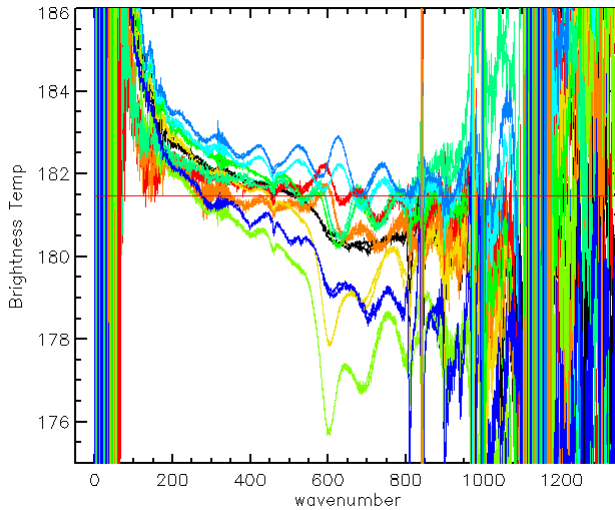
- ▶ Calibrated in 2012 using warm and ambient blackbodies over 170 to 320 K range
- ▶ Results (presented at last CALCON)
 - Accuracy 1.5 K or better (peak deviation) for $T > 200$ K
 - From 270 to 330 K, accuracy meets design goals of 0.2 K ($k=1$) 170 to 1000 cm^{-1}
- ▶ Conclusions
 - Deviations are due to small systematic effects combined with large increase in error from extrapolating from blackbodies
 - Stray light confirmed as an error source
 - Window variation with vacuum cycle suspected as error source

2013 Calibration

- ▶ Repeated calibration using warm blackbody (324.5 K) and space view simulator (77 K)

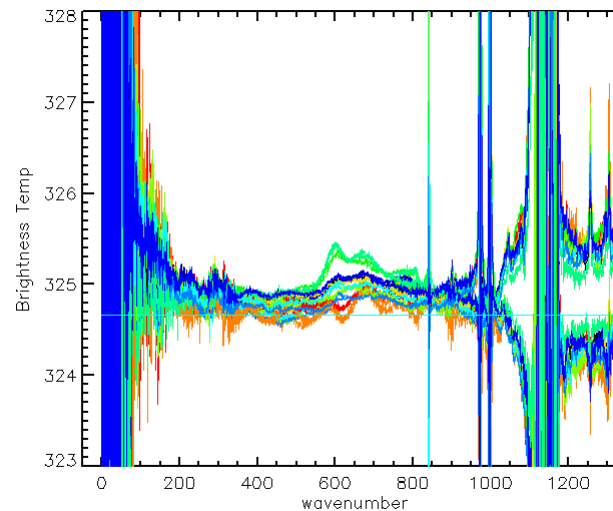
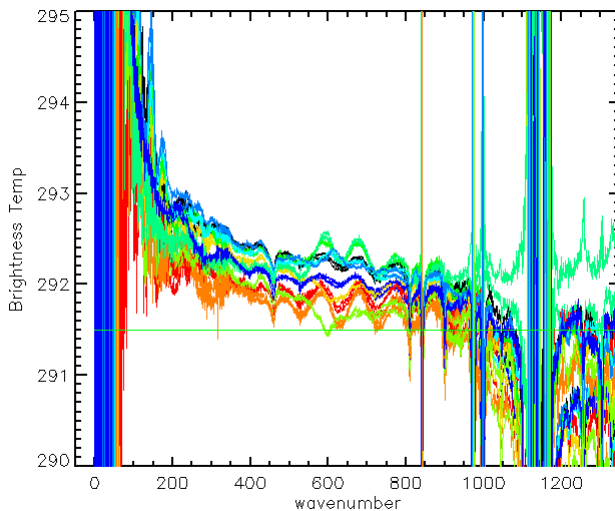


Some temperature deviations



Key: detectors 1-10 are in black, red, orange, yellow, yellow-green, green, blue-green, cyan, light blue, blue.

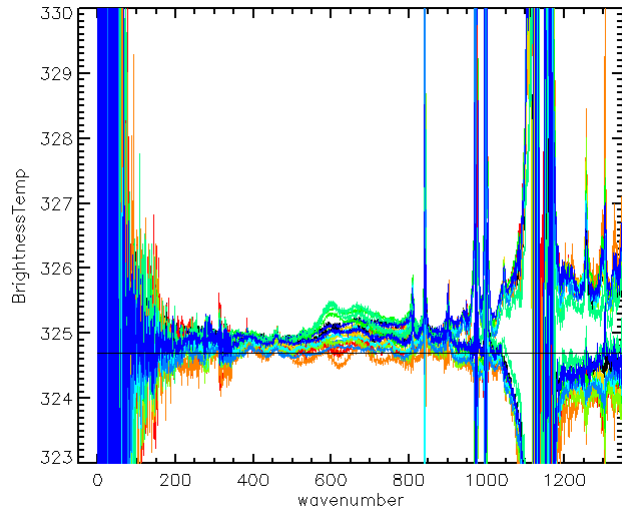
Data from the each scan direction for each detector are the same color



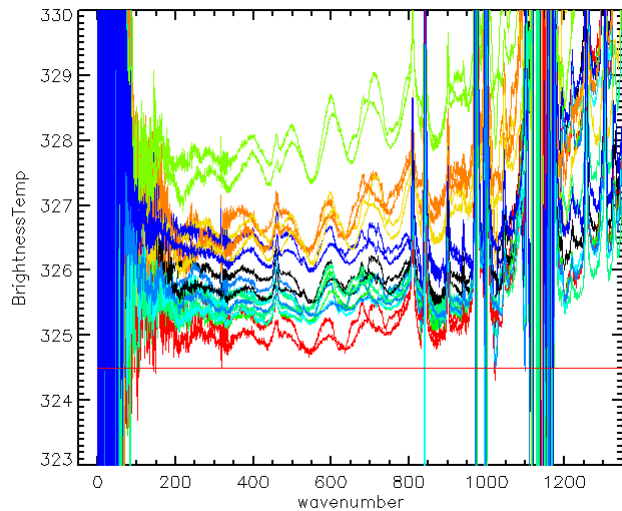
Significant, highly systematic deviations

Detector 2 always within 1 K

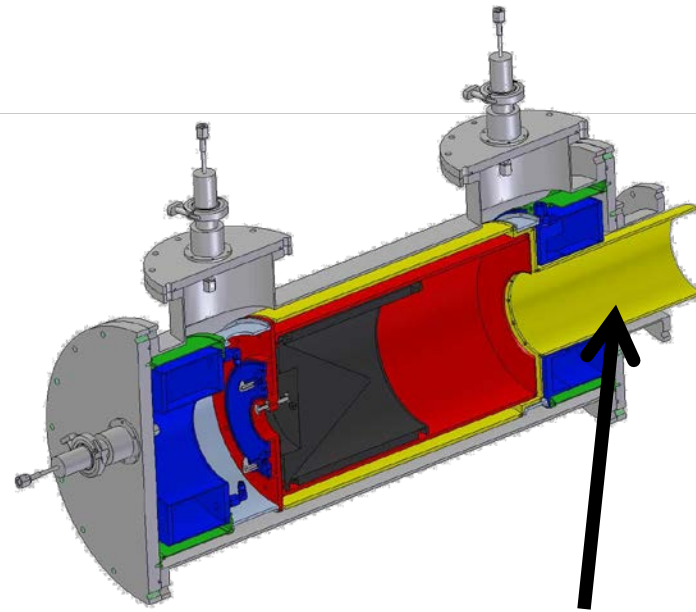
Stray light



LWIRCS 324.66 K
baffle 321.4 K

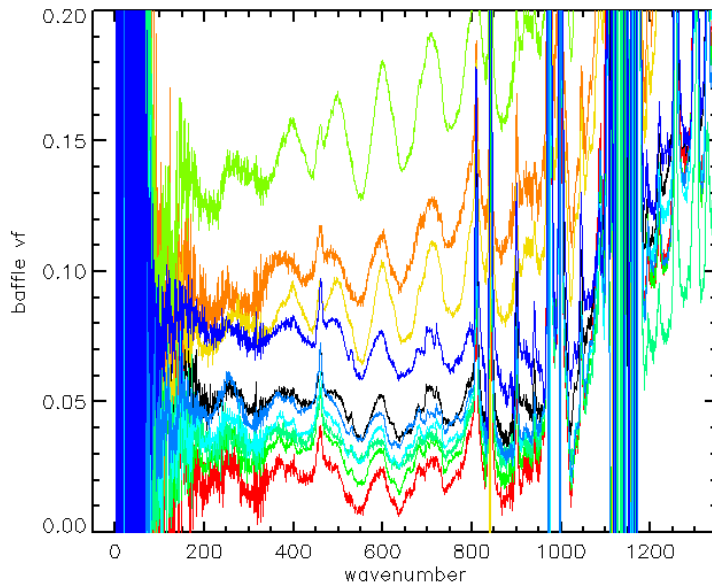


LWIRCS 324.49 K
baffle 341.8 K

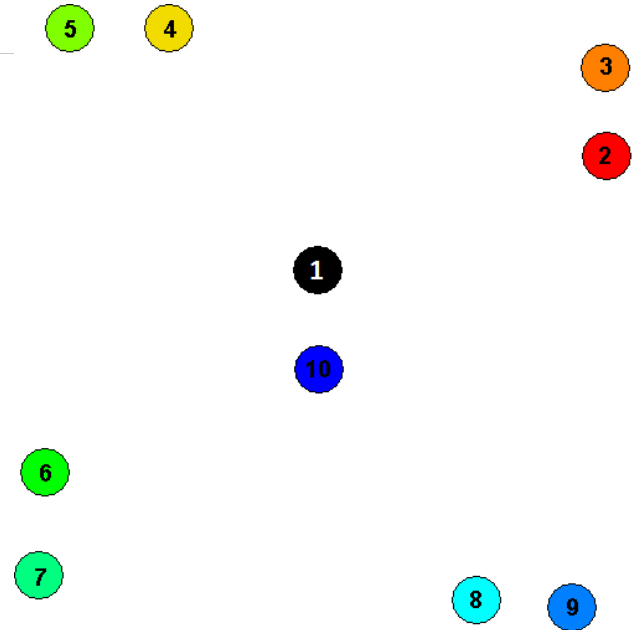


Baffle

Baffle view fraction

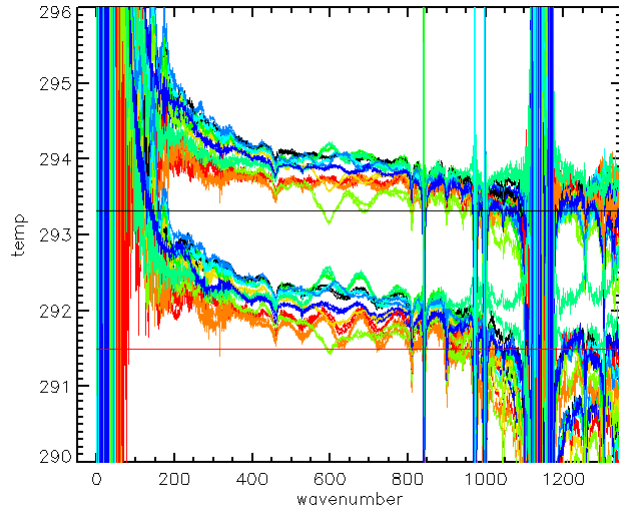


View fraction of baffle by detector

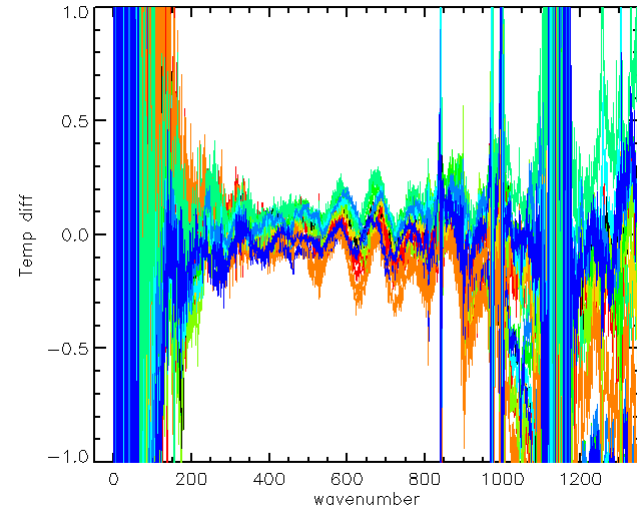


Detector pattern at focal plane

Repeatability



293 K and 292 K data sets
4 days apart



Difference of deviations

Repeatable to 0.2 K
Repeatability always at this level

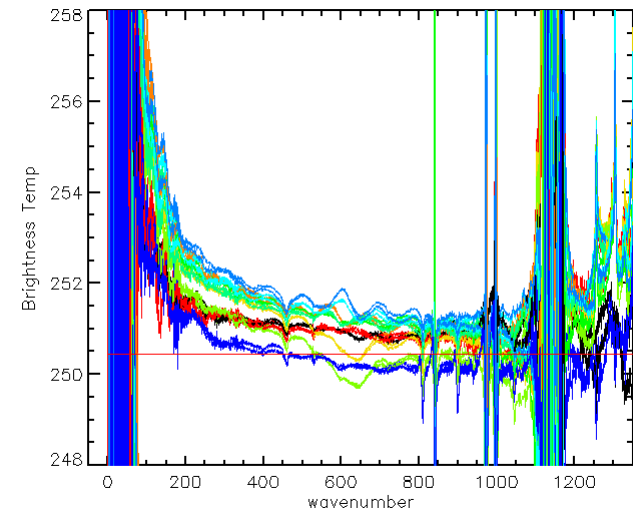
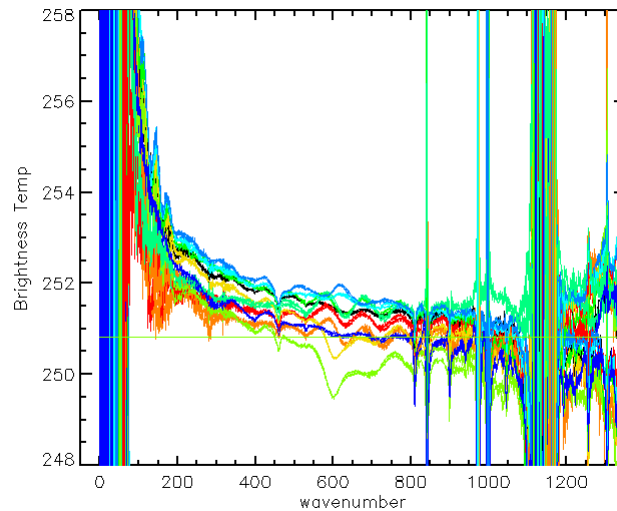
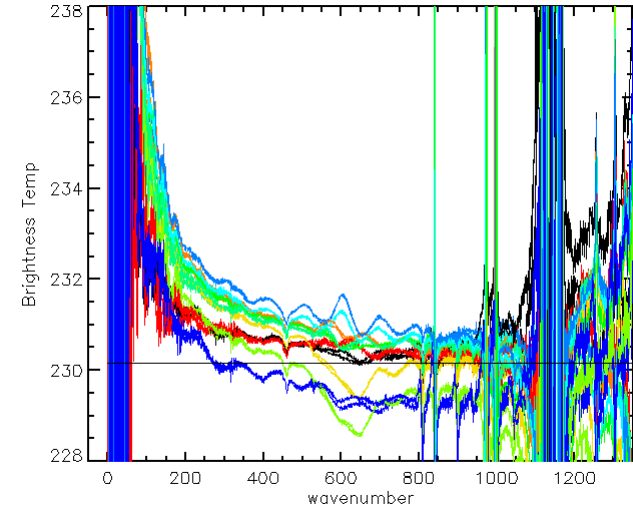
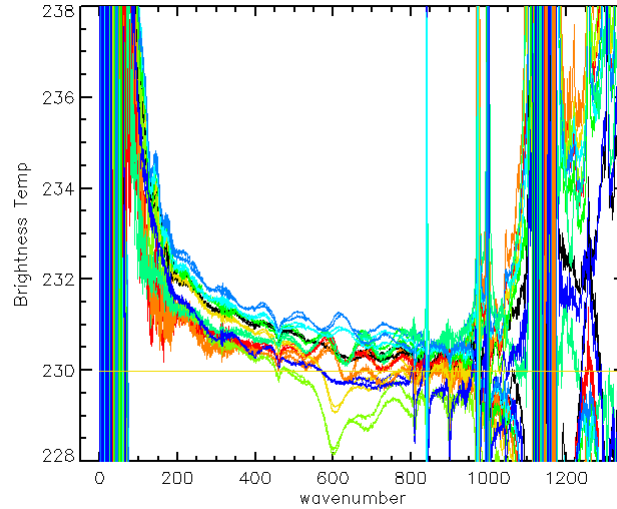
Variation with vacuum cycle confirmed

LWIRCS at
~230, 251 K.

Left: Originals

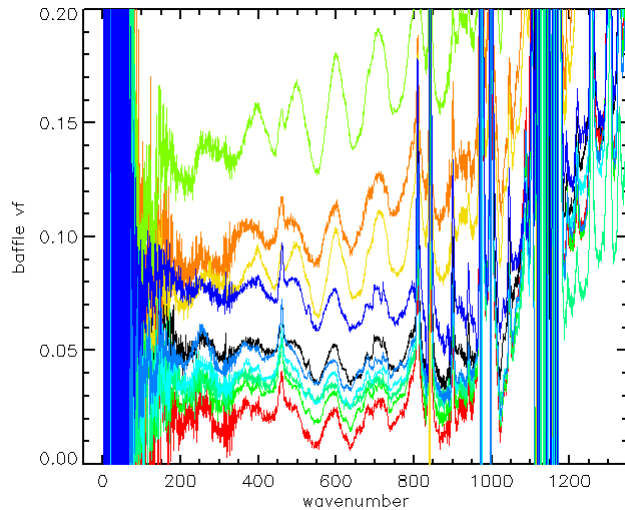
Right: after
FIRST at $\frac{1}{2}$
atmosphere
for 2 days
then re-
pumped

Deviations
change

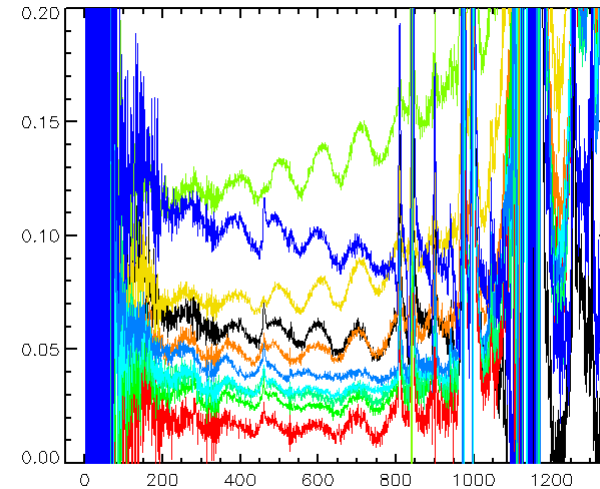


Window effects

- Baffle view fraction changes too



Original from a few slides back



After vacuum cycled

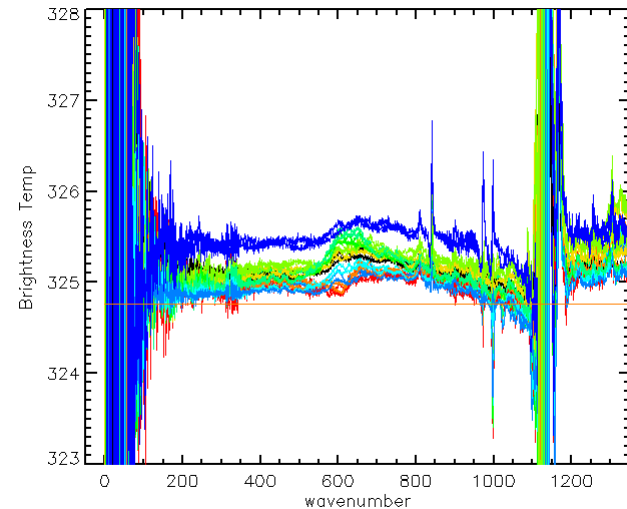
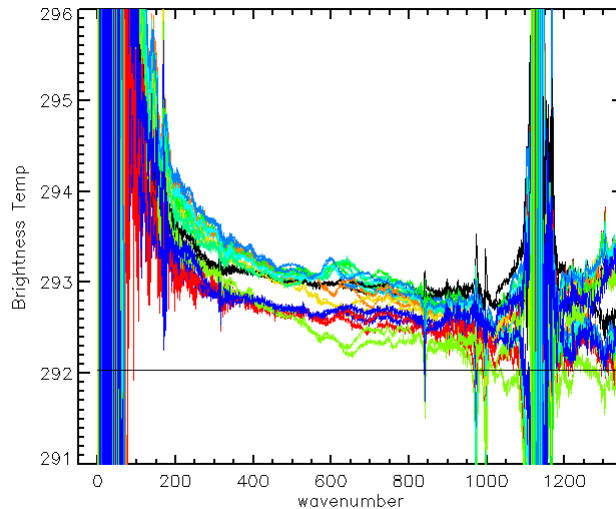
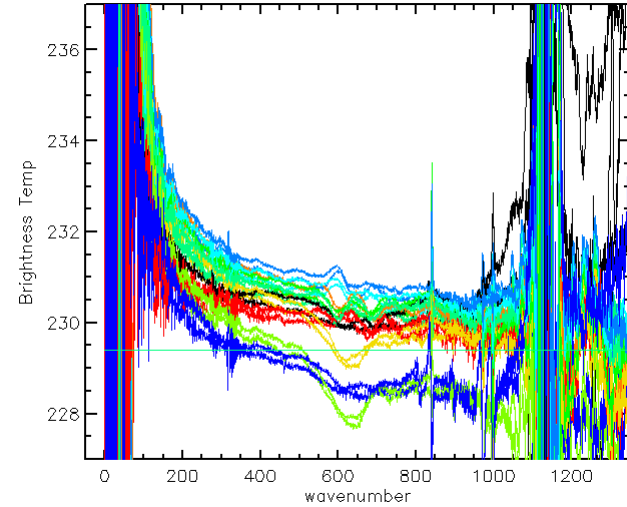
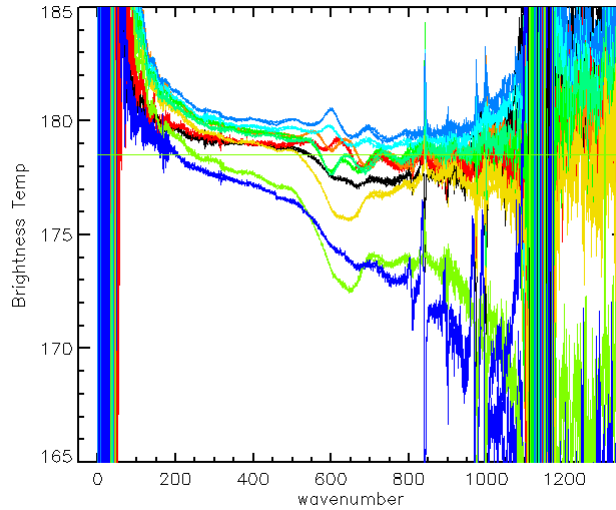
- Window changes shape with each vacuum cycle and window shape directs beam

Windowless data

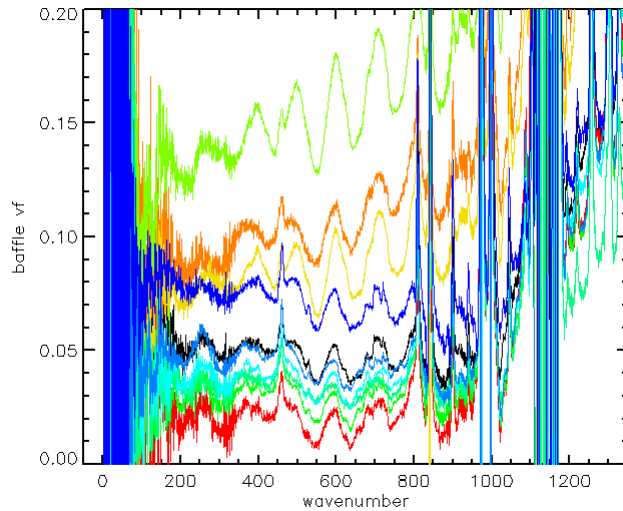
Still have significant systematic deviations

Fewer wiggles

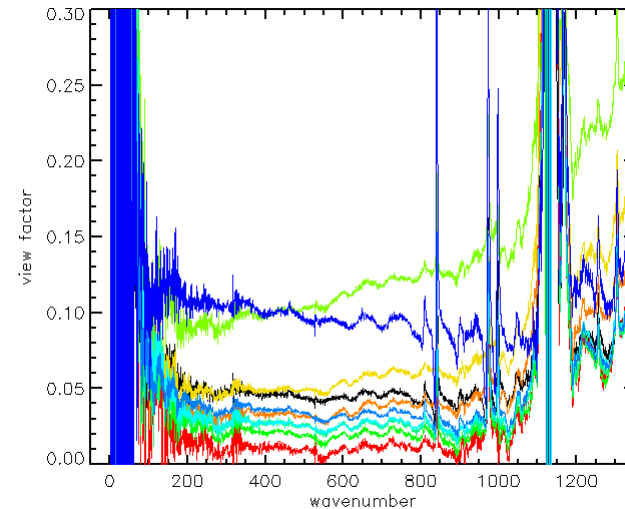
Detector 2 still within 1 K



Windowless baffle view fraction



Original from several slides back



Without window

- ▶ Baffle view fraction improves without window, but still have stray light
- ▶ If FIRST beam can miss LWIRCS, it can also miss WBB, SVS

FIRST cal equation with stray light

Ideal cal equation, P's are BB radiances, S's are measured spectra

$$P_L = \frac{S_L - S_C}{S_W - S_C} (P_W - P_C) + P_C$$

With view factor of f of contaminating radiance, R, for each blackbody

$$(1 - f_L)P_L + f_L R_L = x((1 - f_W)P_W + f_W R_W - (1 - f_C)P_C - f_C R_C) + (1 - f_C)P_C + f_C R_C \quad x \stackrel{\text{def}}{=} \frac{S_L - S_C}{S_W - S_C}$$

Re-arrange

$$P_L = x(P_W - P_C + R_1) + P_C + R_2$$

$$R_1 = \frac{1}{1 - f_L} ((f_L - f_W)P_W + f_W R_W - (f_L - f_C)P_C - f_C R_C) \quad R_2 = \frac{1}{1 - f_L} ((f_L - f_C)P_C + f_C R_C - f_L R_L)$$

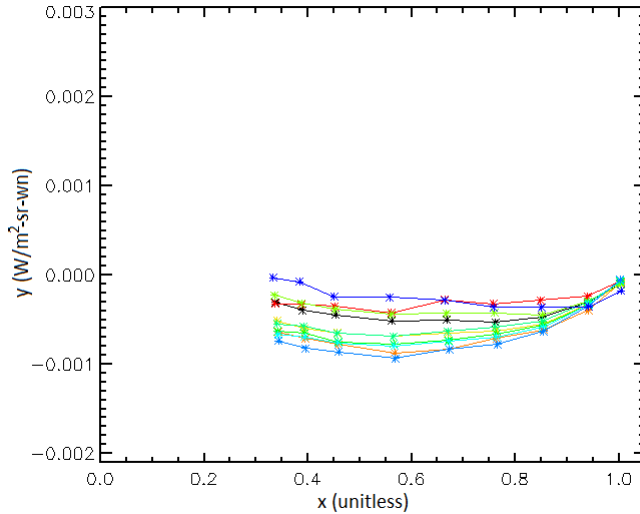
R_1 and R_2 are constant

$$P_L - P_C - x(P_W - P_C) \stackrel{\text{def}}{=} y = xR_1 + R_2$$

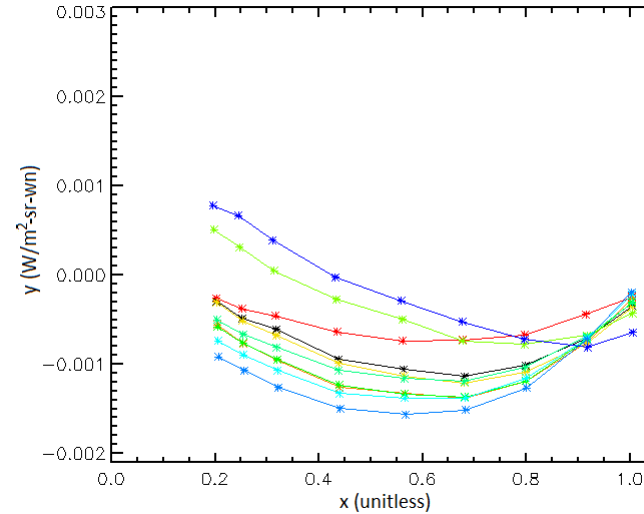
This should be just a line. Can fit for R_1 and R_2 and use to correct data

X vs. Y w/o window

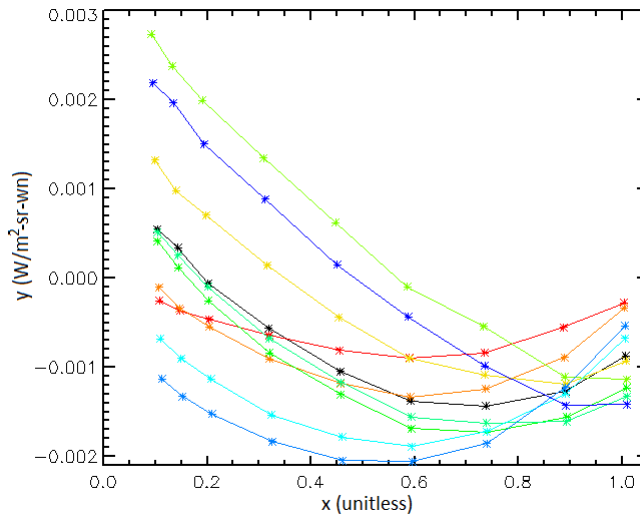
200 cm^{-1}



400 cm^{-1}



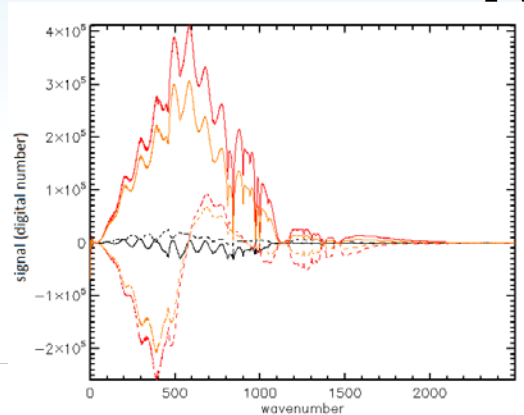
600 cm^{-1}



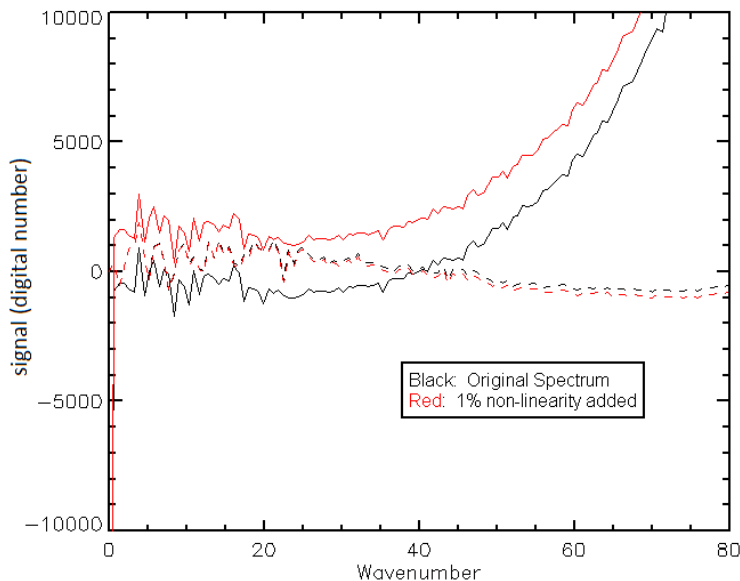
These are not lines

Looks like non-linearity

Non linearity?



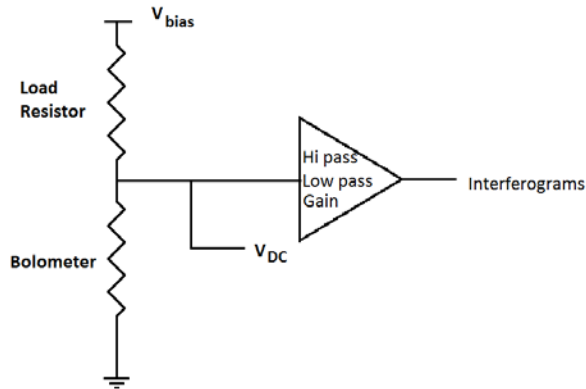
Three example spectra
dashed lines are imaginary
component



Spectra show interferograms are linear
to better than $\sim 0.3\%$ here

To reproduce observed effect requires
several % non linearity

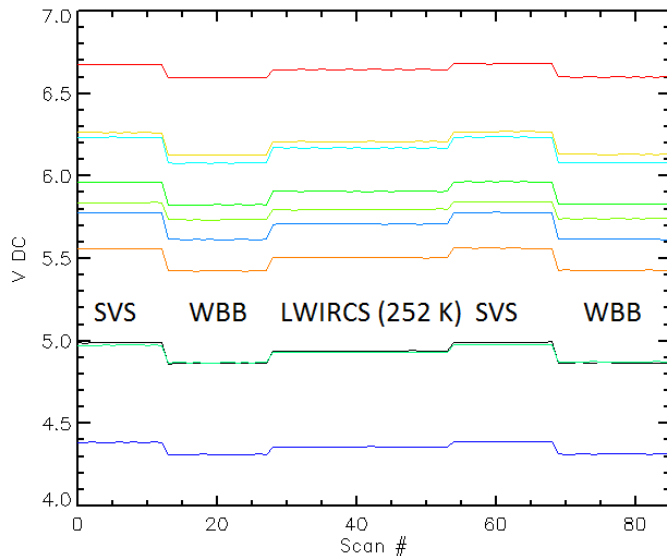
Another type of non-linearity



Detector DC voltage level varies with target

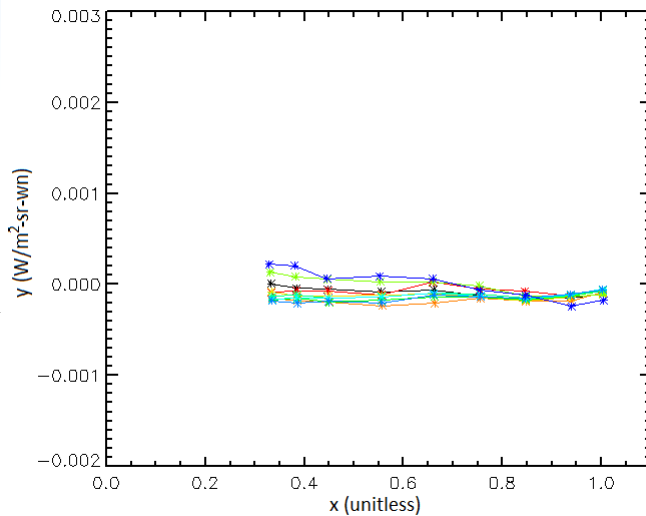
$$\text{Detector Response} \propto R_{\text{Det}} \propto V_{\text{DC}}$$

Another type of non-linearity:
Interferogram linear but $\propto V_{\text{DC}}$

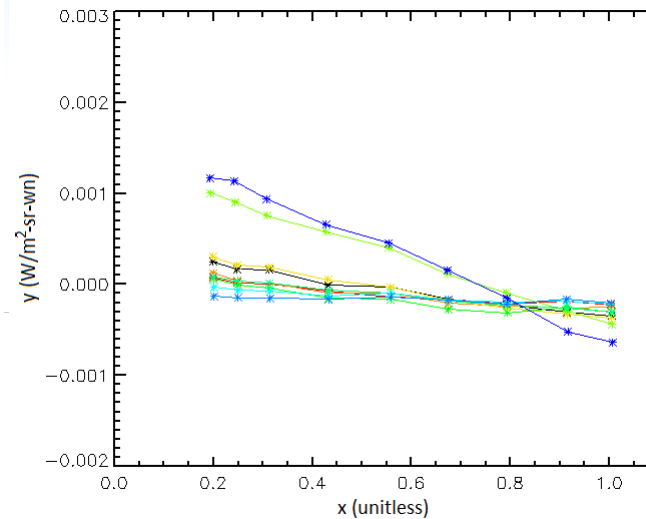


X vs. Y with correction

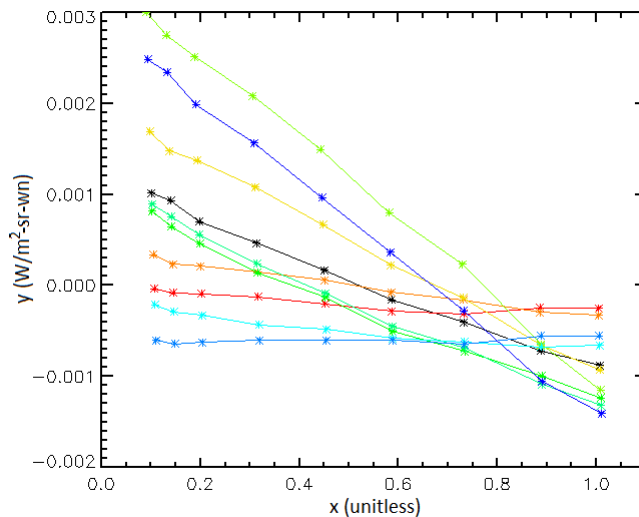
200 cm⁻¹



400 cm⁻¹

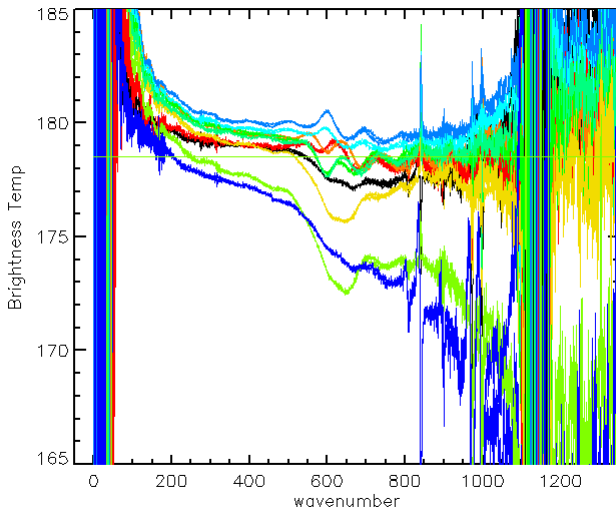


600 cm⁻¹



- Applied correction from response $\propto V_{DC}$
 - No free parameters
- These are lines
 - Near zero for good detectors

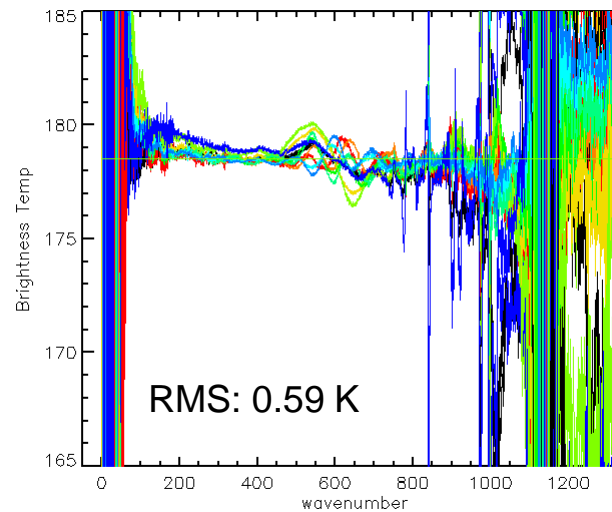
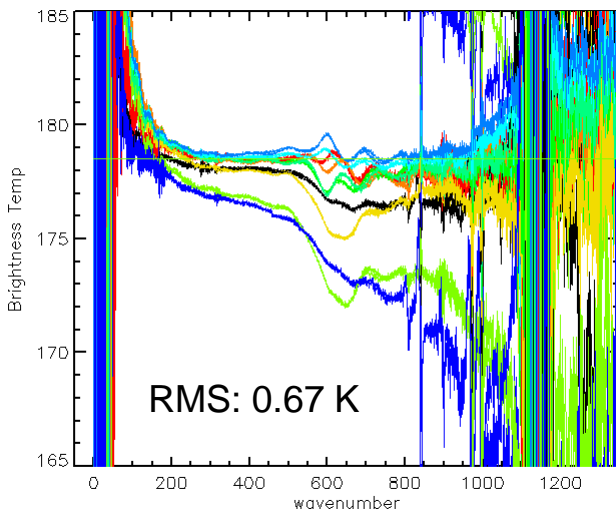
179 K windowless data set



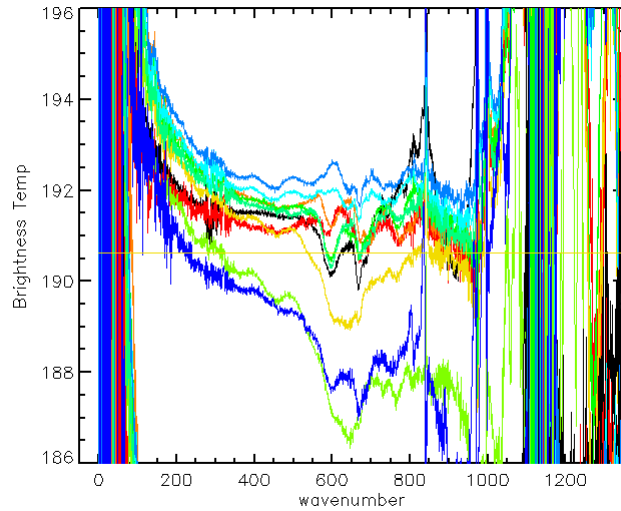
Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too

Linearity correction alone significantly improves deviation

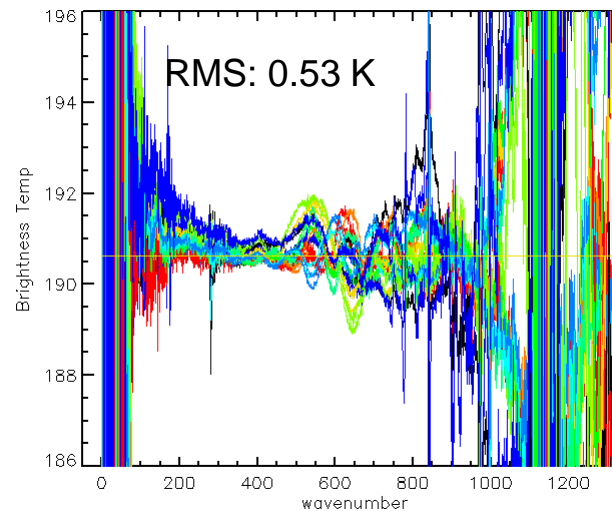
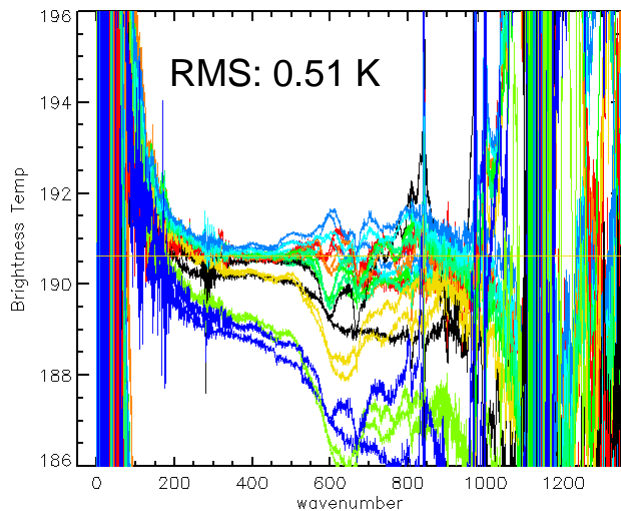
RMS is from 200 to 800 cm⁻¹ for detectors 2,3,6,7,8,9 (left), all but 5 and 10 (right)



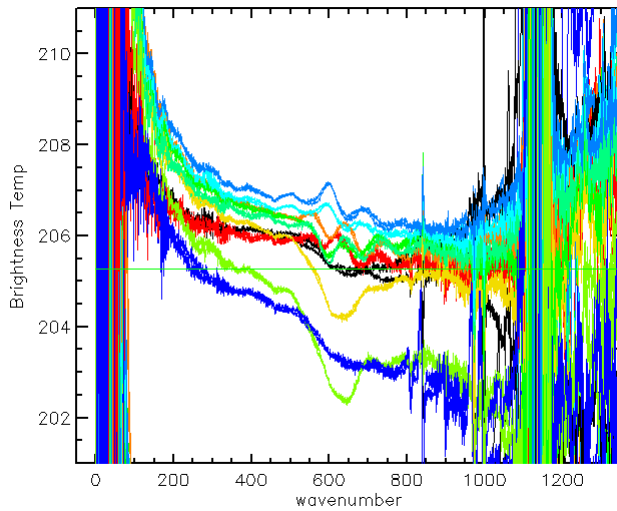
191 K windowless data set



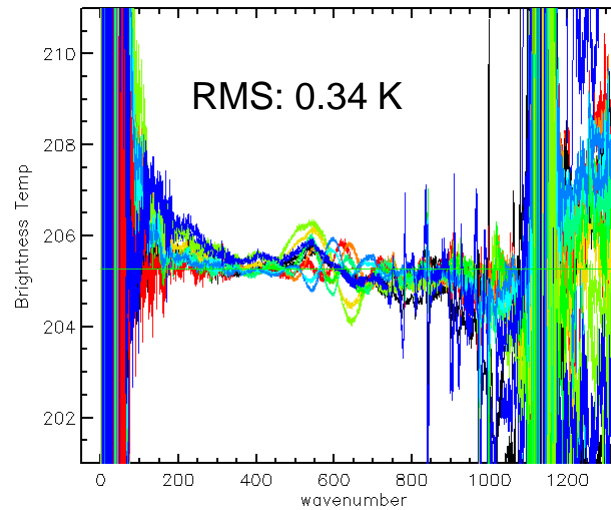
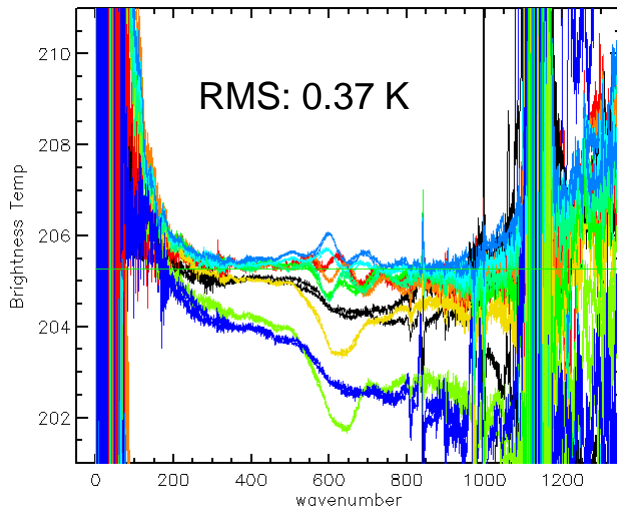
Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too



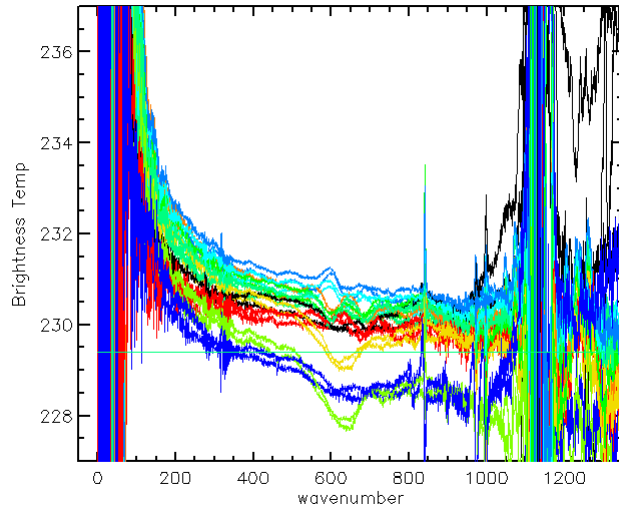
205 K windowless data set



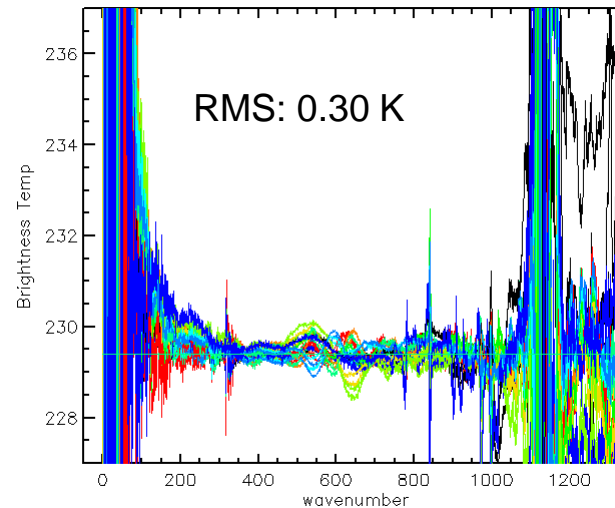
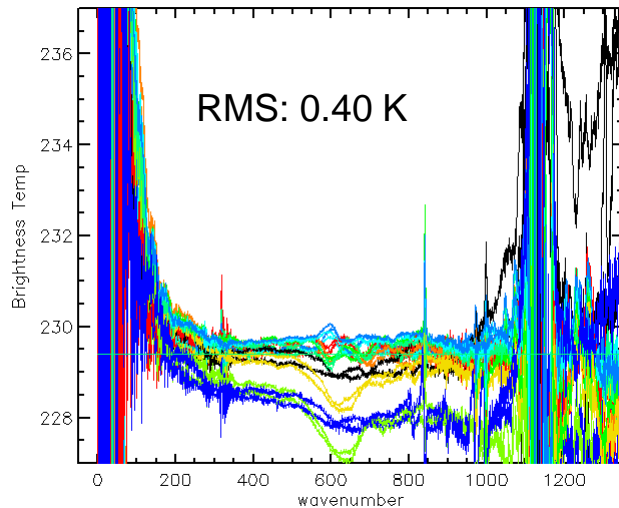
Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too



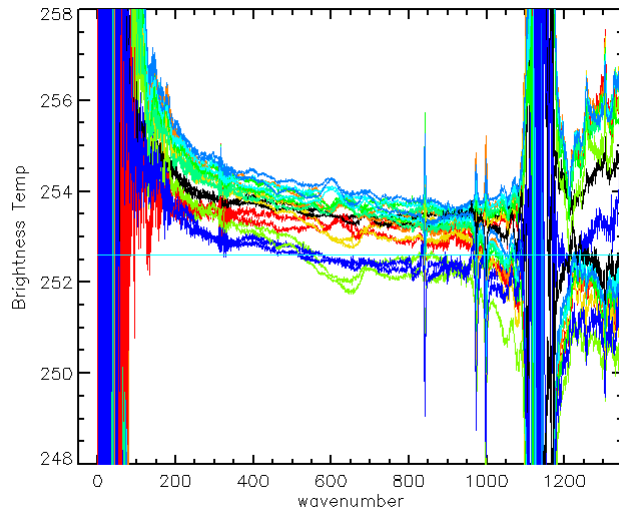
229 K windowless data set



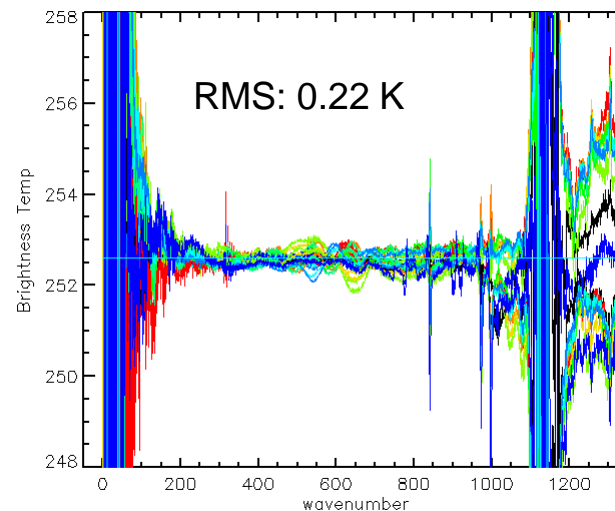
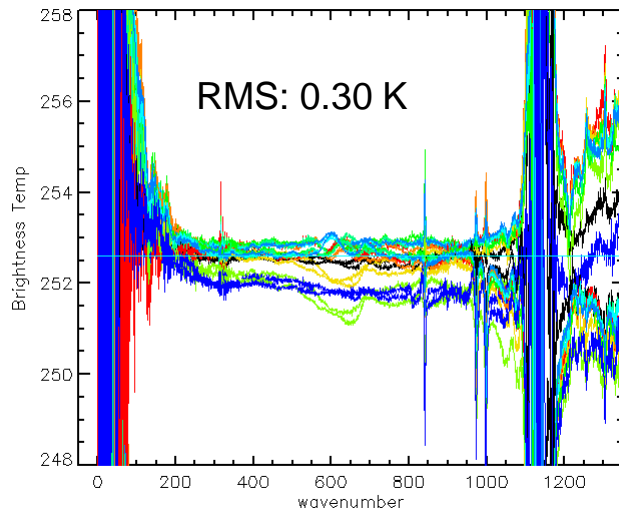
Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too



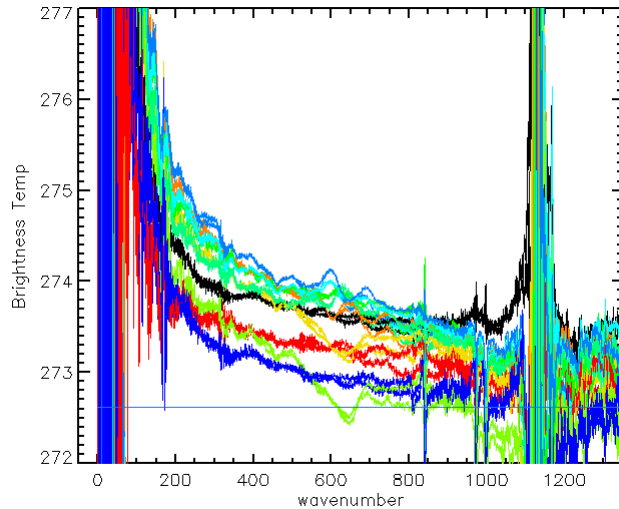
253 K windowless data set



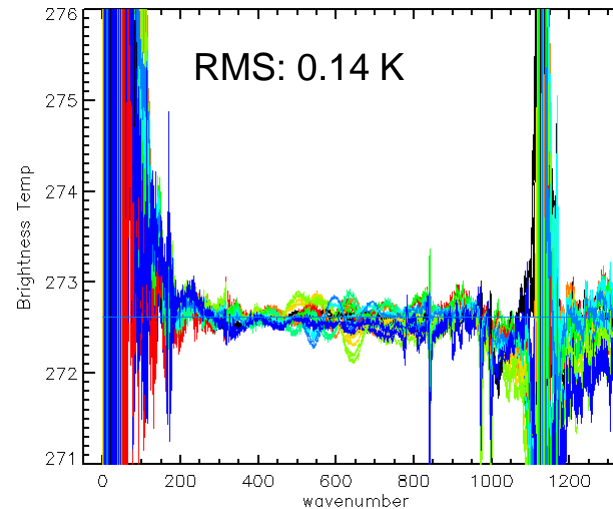
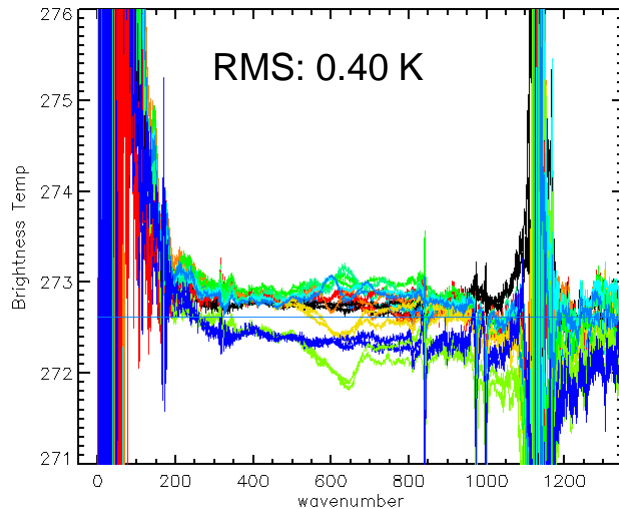
Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too



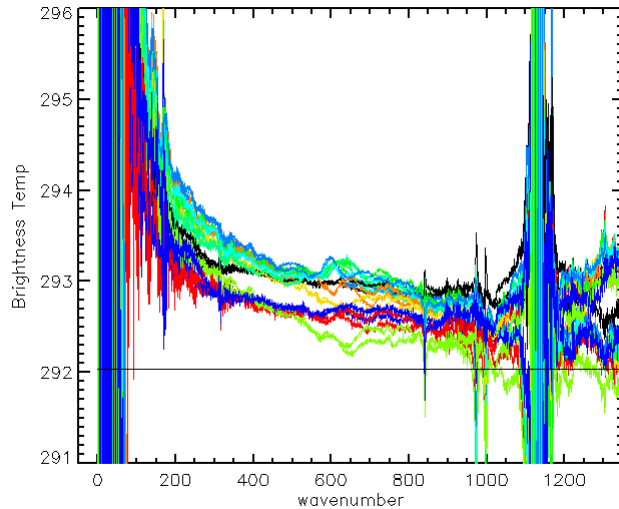
273 K windowless data set



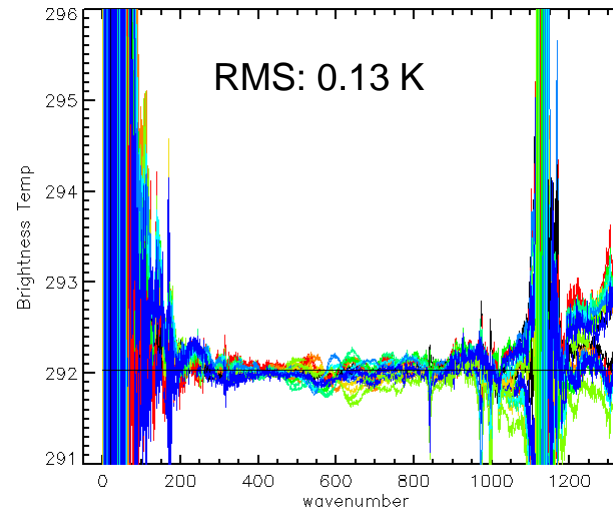
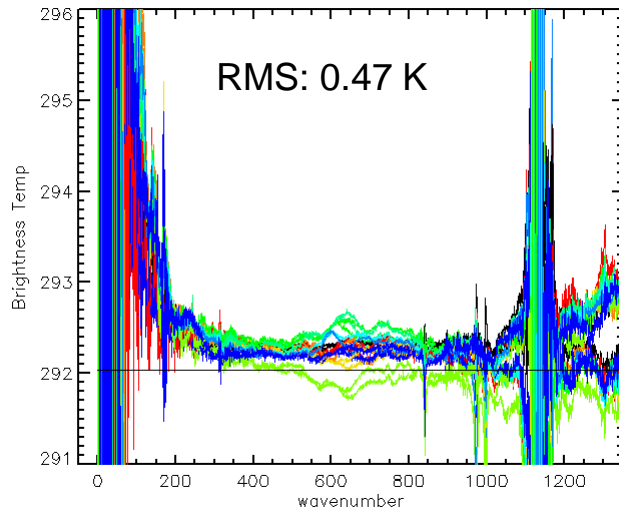
Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too



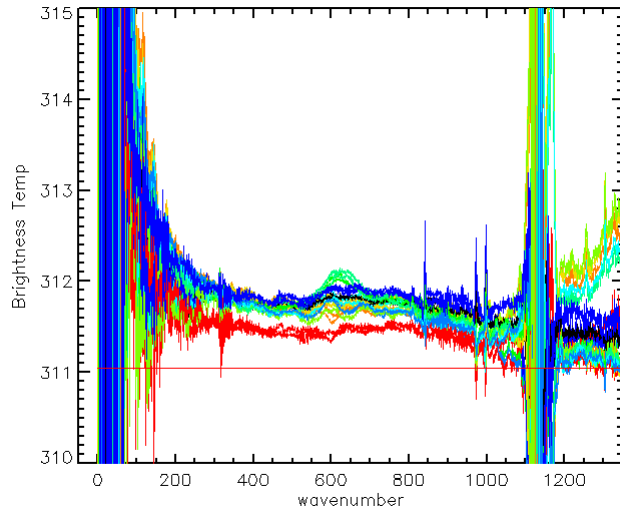
292 K windowless data set



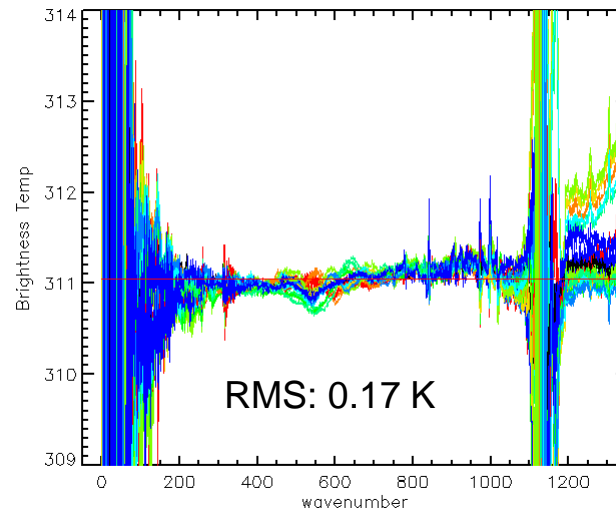
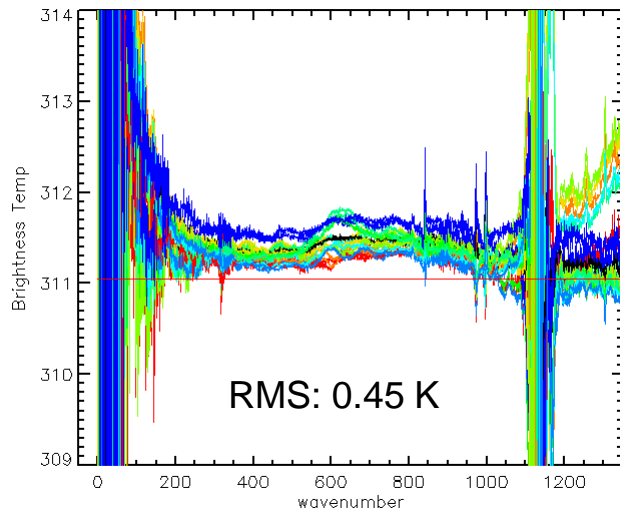
Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too



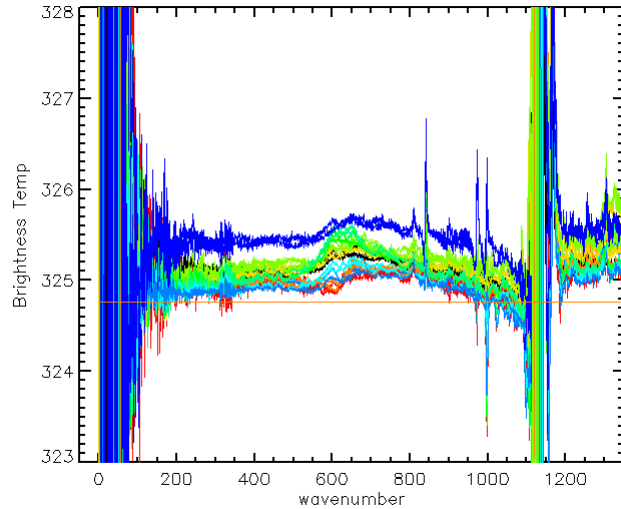
311 K windowless data set



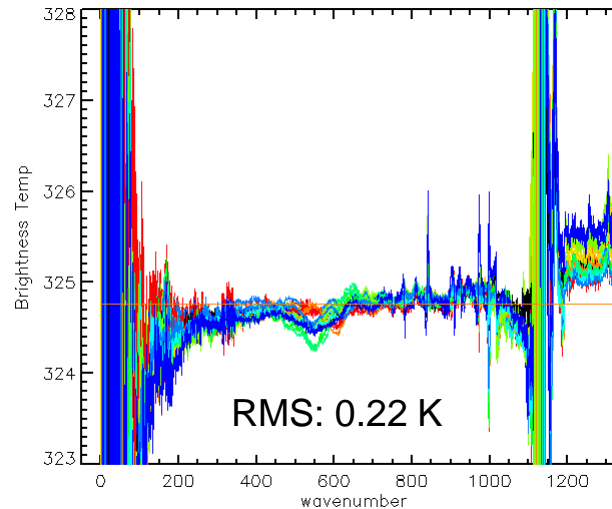
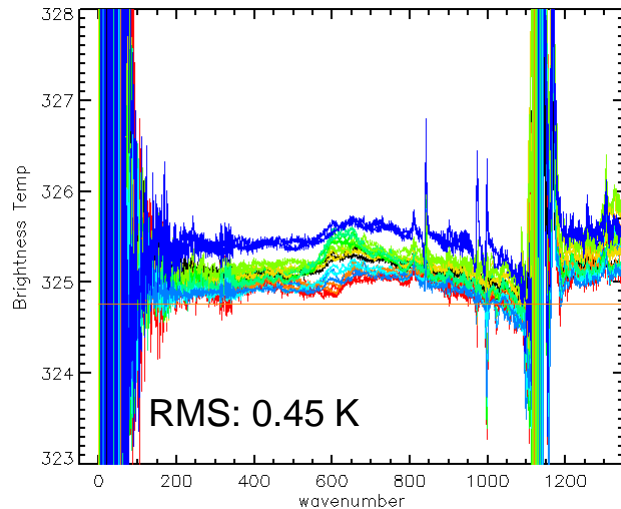
Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too



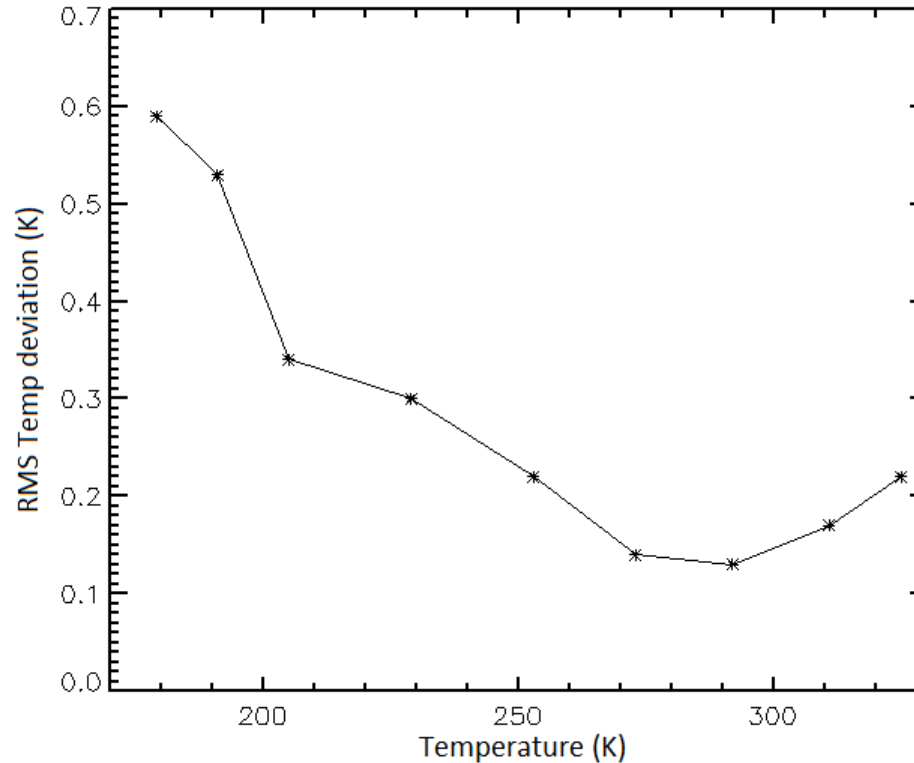
325 K windowless data set



Left: without linearity correction
Bottom left: with non-linearity correction
Bottom right: with stray light correction too



RMS deviation vs. temperature



RMS deviation vs. temperature all detectors except 5 and 10. No window, non-linearity and stray light corrections applied

Conclusions

- ▶ FIRST requires an unusual non-linearity correction
- ▶ FIRST has stray light
 - Windows cause some but not all of it
 - Some detectors worse than others
 - Stray light probably still limits accuracy
- ▶ FIRST is highly accurate
 - Some detectors not affected strongly by stray light
 - Stray light can be fixed