

HARP CubeSat – An innovative Hyperangular Imaging Polarimeter for Earth Science Applications

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HARP Organizations

UMBC LACO











GSFC @ Greenbelt and Wallops

Funding: ESTO InVEST Launch: CSLI - ELaNa





HARP Objectives

- Advance Hyperangular, Imaging Polarimetric concepts for the NASA/ACE (Aerosol, Cloud and Ecosystems) Mission
- Prove that CubeSat technology can provide science-quality multi angle imaging data paving the way for lower cost aerosol-cloud instrument developments.
- Student training.

HARP Science Goal

- Demonstrate the ability to characterize the **micro physical properties** of **aerosols and clouds** at the scale of individual moderate-sized clouds for the ultimate purpose of narrowing uncertainties in climate change.
 - Final Instrument: March/2015
 - Full Spacecraft flight-ready: Sept/2015



HARP Science – Clouds and Aerosols



Clouds

precipitating



HARP Science

- Pollution aerosols narrow cloud droplet distributions and postpones rain
- Smaller droplets increase cloud albedo and affect Earth's energy balance
- Polarized rainbow signal provides droplet effective radius and variance measurements
- HARP will measure pollution aerosols and cloud droplets









HARP CubeSat Polarimeter

HARP Pioneering Hyper-Angular Capability will Provide Full Cloudbow Retrievals from Small Area (< 4x4km from space)



Water Droplet Distribution





M

10

30

40 。

D and A produce cloud droplet effective radius and variance



HARP CubeSat Polarimeter

HARP Pioneering Hyper-Angular Capability will Provide Full Cloudbow Retrievals from Small Area (< 4x4km from space)



Same retrieval capability for all individual pixels with < 4x4km resolution





Water Droplet Distribution



 These two cases are undistinguishable from Intensity measurements only (MODIS/VIIRS)

Heritage from PACS ER2 Airborne Polarimeter Selectable Aerosol angles

170° FOL

along track

Multiple simultaneous

pushbroom systems

Current VNIR system

- Ground Resolution = 37m
- 470, 550, 670, 766, 870nm
- 1 K pixel X-track
- 65+ angles for all wavelengths
- 130 view angles for 670nm

SWIR Under construction:

- 1650, 1880, 2130, 2250nm
- 320x256 pixels
- Adjustable FOV



HARP Prism:

Three Polarized Images



Intensity_{0°}



Intensity_{45°}





Intensity_{90°}

$[\mathbf{I} \ \mathbf{Q} \ \mathbf{U}]_{\text{pixel}} = [\mathbf{I}_0 \ \mathbf{I}_{45} \ \mathbf{I}_{90}] \cdot \mathbf{M}$

HARP Scheme for Hyperangular Multi-Wavelength Polarization Images

HARP



Multiple Viewing Angles (>50 angles by airborne PACS)





HARP Instrument & Spacecraft

SDL Spacecraft

UMBC Imaging Polarimeter



Spacecraft Views



Back view

- Thermal Radiators
- Star Camera aperture
- Sun Sensor
- GPS Patch Antenna





Front view

- Deployed Solar Arrays and Antenna
- ADCS Sensors
- Instrument aperture at the bottom



HARP – Full Feature Earth Sciences Satellite



- XACT Blue Canyon ACDS
- Sun Sensor + Star tracker
- Wide FOV hyperangular, polarized imaging payload
- 4 wavelengths
- L3 UHF radio
- Telemetry: 1.43 Gbits/day
- Data Acquisition: up to 8.6Gbits/day
- 2.5km spatial resolution
- 0.66km pointing knowledge/geolocation



HARP Pointing Modes

- Deep Space Dark Reference
- Moon calibration
- Horizon calibration



Nadir Data Collection



Solar panels pointing at the Sun



Body Sun Nadjr:(Centric)

HARP_1

Time Step: 5.00 sec

HARP_1 ICR Axes 4 Jul 2016 19:00:05.000



Bod

Power Acquisition Scenario





UMBC Calibration/Testing Facilities



Polarization Calibrator



Thermo-Vac testing

ESD benchesThermo-Vac testing

Machine shop

• Clean room; etc.



SDL Facilities



- Certified facilities (ESD, etc.)
- Thermo-Vac, shake tables
- Machine shop
- Clean rooms , etc.





80/20 In



Torque Command



Actuator Command

Sun Sensors **Reaction Wheels Torque Coils Mass Properties** Center of mass Calibrate and test Test and • Test, characterize, Moments of inertia and calibrate characterize sun sensor **NOVA LAB** NanoSat **Horizon Sensors Solar Arrays** System Test testing AMO illumination • Flatsat system test Earth/space Helmholtz Cail simulator SIMULINK Simulated Sun Dynamics Simulation Sensor mount Magnetic Field Command \land agi rotates Motor Command FEMAP MATLAB MSC Software SIMULINK Actuator Simulation OLED EDGE

Ground Station Architecture









HARP

Hyper-Angular Rainbow Polarimeter

In-Space Validation of Earth Science Technologies (InVEST)

The HARP payload is a wide FOV imager that splits three spatially identical images into three independent polarizers and detector arrays. This technique achieves simultaneous imagery of three polarization states and is the key innovation to achieve high polarimetric accuracy with no moving parts. The spacecraft consists of a 3U Cubesat with 3-axis stabilization designed to keep the imager pointing nadir. The hyper-angular capability is achieved by acquiring overlapping images at very fast speeds.

OBJECTIVES:

- Space validation of new technology required by the NASA Decadal Survey Aerosol-Cloud-Ecosystem (ACE) mission
- Prove the on-flight capabilities of a highly accurate wide FOV hyper-angle imaging polarimeter for characterizing aerosol and cloud properties
- Prove that cubes at lechnology can provide science-quality Earth Sciences data





Thank you!!!



Space Dynamics

Backup Slides:





Example of hyperangular observations of sunglint from PACS-Aircraft



Intensity RGB



DoLP - Red

Hyperangular Movie of Cloubow from PACS-Aircraft



DoLP - Green 10/16/2013 HA

HARP - Systems Requirement Review - UMBC proprietary



HARP Pioneering Hyper-Angular Capability from Space will **Provide Full Cloudbow Retrievals from Small Area (~4x4km)**



Cloudbow Measurements Possible for highly variable Scenes



D and A parameters allow for measurements of cloud droplet effective radius and variance



Major Program Milestones

Program Milestone	Target Date	Status
Requirements Review	10/2013	Completed
Instrument Single Design Review	2/10/2014	Completed
Preliminary Design Review	2/11/2014	Completed
Mission Critical Design Review Instrument Delta SDR	07/3/2014	Completed
Delivery Functional Instrument Unit #1	1/2015	On schedule
Hot Swap with Flight Unit #2 (Allows for extra calibration on flight unit)	3/2015	On schedule
Observatory Integration	2/2015	On schedule
Launch Readiness	9/2015	On schedule
Observatory Operations	TBD	
Science Observations	TBD	

