Design of the Local Ionospheric Measurements Satellite

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Overview

- Local lonospheric Measurements Satellite
 - Funded by Nanosat-3 program sponsored by AFOSR/NASA/AIAA
- Scientific goals
 - Explore ram/wake structure via probes as spacecraft spins
 - Obtain ambient measurements of undisturbed ionospheric plasma environment via two probes mounted on deployed booms
 - Correlate ambient to ram/wake measurements
- Engineering goals
 - Test a miniature RF ion thruster system that will augment satellite spin
 - LionSat will use IP communications for return of prime science data and uploading new campaign scenarios
- Educational goals
 - Prepare students at undergraduate and graduate levels for productive careers in technical and nontechnical fields relating to space systems



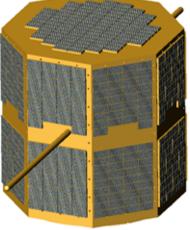




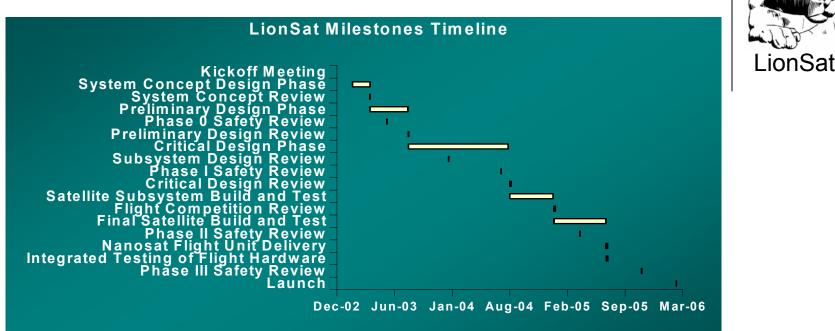








Methodology

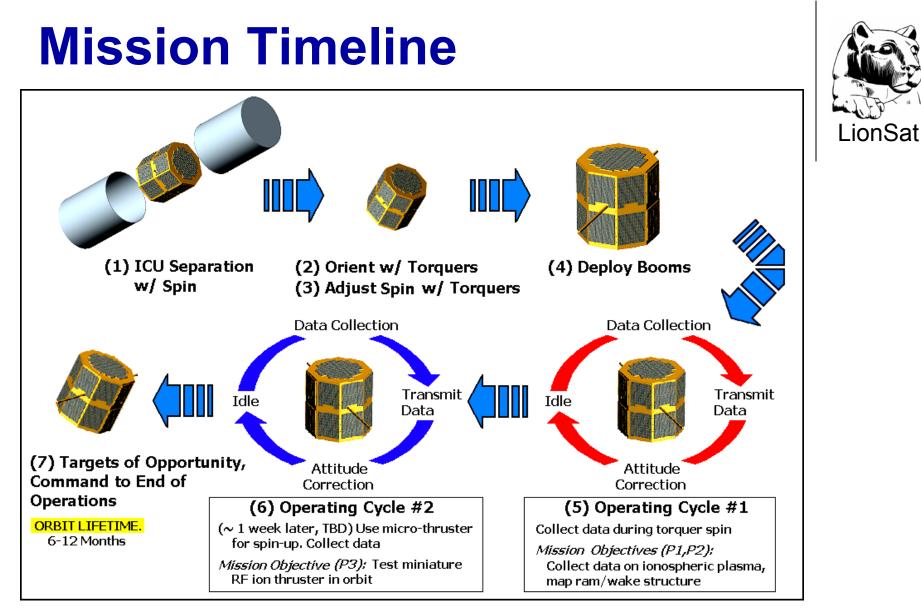


- Top-down approach to design
- 11 subsystems
- Formal documentation process
- Margin of flexibility in design
 - Due to uncertainties (e.g., launch vehicle currently unknown, baseline is Shuttle in CAPE)
- Educational goals are met through public outreach (grades K–12) and integration of LionSat design into design courses

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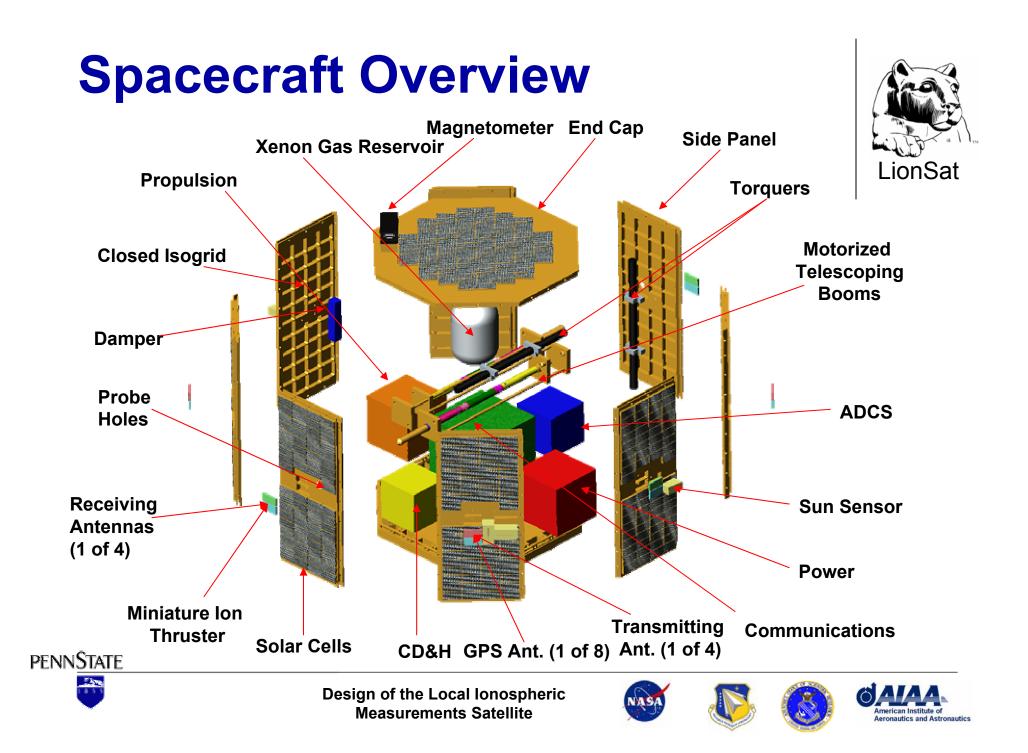




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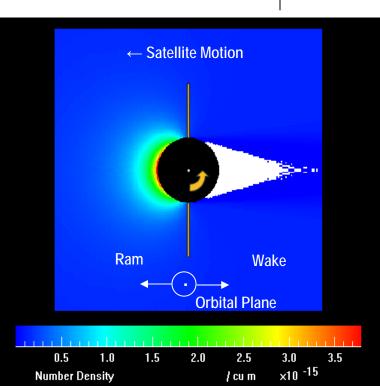
Hybrid Plasma Probe

- Purpose
 - To collect data on ionospheric plasma in perturbed and unperturbed regions within geophysically interesting areas of low earth orbit
 - To demonstrate that combination of several plasma diagnostics is feasible, efficient, and powerful
- Modes of operation
 - Swept Bias Langmuir Probe (SBLP) mode yields electron and ion density, electron temperature, and spacecraft potential
 - Fixed Bias Langmuir Probe (FBLP) mode yields fast relative electron or ion density
 - Plasma Frequency Probe (PFP) mode provides fast absolute electron density measurements
 - Fast Temperature Probe (FTP) mode yields fast, relative electron temperature measurement

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LionSat

Discrete Monte Carlo Simulation of neutral gas density surrounding satellite. Orbital plane coincides with image plane. Booms rotate through ram and wake



Miniature RF Ion Thruster (MRIT)



- MRIT will be tested by increasing s spin rate
- **Functional characteristics:**
 - Thrust: 0.6 mN (calculated)
 - Specific impulse: 3800 s
 - Exhaust velocity: ~38 km/s
- Physical characteristics:
 - Total input power: 15 W
 - Excitation frequency: 13.56 MHz (ir unregulated frequency)
 - Mass: ~1.1 kg (total system mass)
 - Acceleration (grid) voltage: ~1 kV
- Propellant
 - Xenon gas (total stored Xe mass TBD)
 - Propellant contained in sealed container with pressure <100 psia (per requirements)

System diagram of the low-power, miniature RF ion thruster system

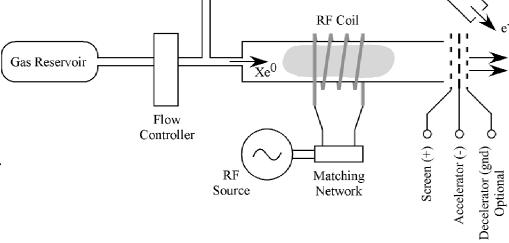


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Neutralizer



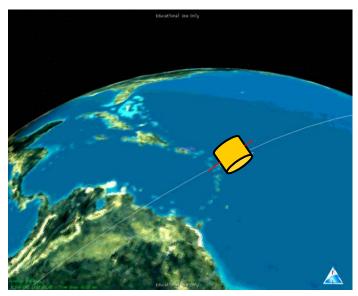
RF

Source

Matching

Network

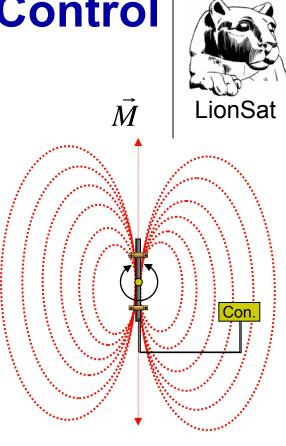
Guidance, Navigation, and Control



Notional LionSat overpass of Arecibo for correlation of plasma density measurement

- Type of control
 - Spin stabilization using geomagnetic field and magnetometer only for attitude determination
 - Passive nutation damping

- Magnetic torque rods
 - Mass depends on size of rods
 - For 10–15 A•m², magnetic moment rods ~0.5 kg
 - Controller decides polarity of rod to change T_{mg}
 - Two magnetic torque rods will be used to maintain desired attitude
- Power consumption
 - 1 W/axis
- Torque
 - 5×10^{−5} N•m (400 km)
- Operational modes
 - Orientation control
 - Spin-rate control
 - Stand-by (idle)



Disturbance	Torques (mN-m)				
Gravity Gradient	0.0072				
Magnetic Field	53.4569				
Solar Radiation	1.7871				
Aerodynamic Drag	0.0156				







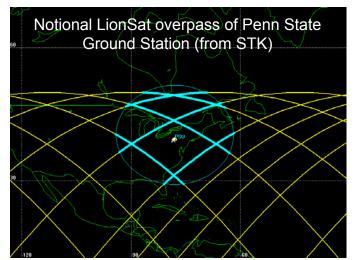


Command and Data Handling

- Main components
 - CPU Intel SA1110 @ 206 MHz (baseline)
- SA1110 Memory
 - Up to 768 MB memory such as SRAM, FLASH
 - Up to 512 MB dynamic memory
- SA1110 subsystems interfaces
 - 28 GPIO lines
 - Multiple serial systems (SPI, UART, USB)
- Ground interface through TCP/IP



- Roll rate of ~10 rpm →14,400 rolls/day
- 12 samples per roll × 4 sensor heads →691,200 samples/day



FO	SBFP	SBLP	PFP	FTP	FBLP	Portion of day	MB/ day
1	5%	10%	40%	10%	35%	15%	11.0
2	100	0	0	0	0	1.5	10.6
3	0	20	40	10	30	15	11.0
4	0	2.5	0	0	97.5	100	10.2

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Communications



- Lionsat will use IP communications for return of science data
 - After mission criteria met, can be used as testbed for testing/verifying relative performance of various protocols
- Why IP?
 - Many popular applications use TCP/IP
 - Allows use of MDP (Multicast Dissemination Protocol), which only requires one-way link
 - Allows secure communications via applications like SSH (Secure Shell) and protocols like IPSec
 - Allows ease of uploading new applications
- CPU: Intel SA1110 (baseline)
- Requirements
 - Downlink frequency = 2.365 GHz
 - Downlink data rate = 200 ksymbol/sec
 - Uplink data rate = 9.6 ksymbol/sec









Conclusions/Summary

- LionSat design at PDR stage
 - Mission concept defined
 - Flow down of requirements performed
 - Preliminary designs for all subsystems (sizings, power, vendors, interfaces, etc.)
 - Significant progress in thermal design, structure, power, etc.
- Educational impacts
 - Involved in several exhibitions (Penn State Engineering Open House, Space Day, engineering camps, etc.)
 - Development of subsystems for fall semester
- Remaining challenges: Ion thruster to be developed, plasma probe, budget, etc.

Next major review: Subsystem design review in January 2004 PENN<u>STATE</u>









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- NASA OMNI group at GSFC

www.psu.edu/dept/aerospace/lionsat/





