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Reflections on Lake Michigan Wind: A Study of Motion Compensated Laser Pulse Technology Using a Mobile Buoy Platform

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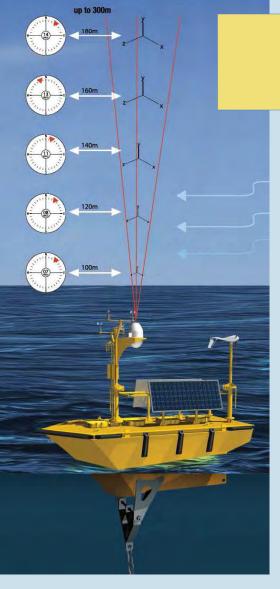
Reflections on Lake Michigan Wind :

A Study of Motion Compensated Laser Pulse Technology Using a Mobile Buoy Platform

> Dave Zeitler Mehmet Sozen Charlie Standridge

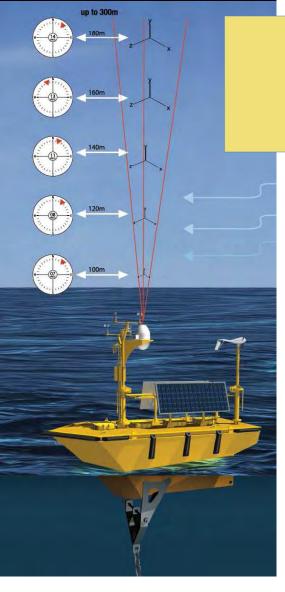
GVSU Big Data Conference April 26, 2013





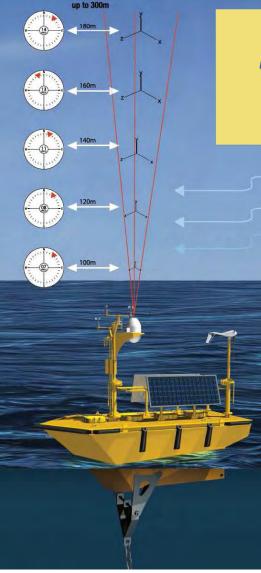
Project Goals

- To collect and analyze wind data essential to the consideration of future wind industry development on the Great Lakes
- To develop real-time / hub-height offshore wind data collection capabilities called for by prior Great Lakes wind assessment studies
- To validate the use of laser pulse technology on a mobile platform as a viable wind assessment technology



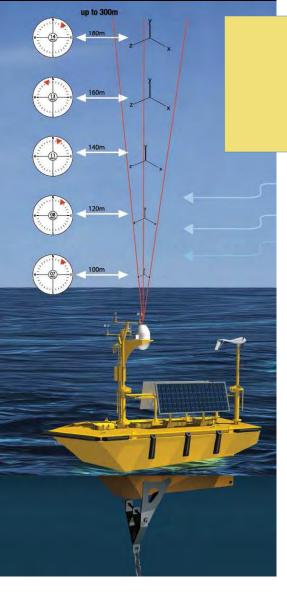
Summer 2012: Mid-Lake Plateau

- May 8 through December 17 224 Days
- Measurements once per second
 - Wind speed and direction
 - 6 range gates and on deck
 - 19,353,600 seconds
- 135,475,200 wind speeds observations



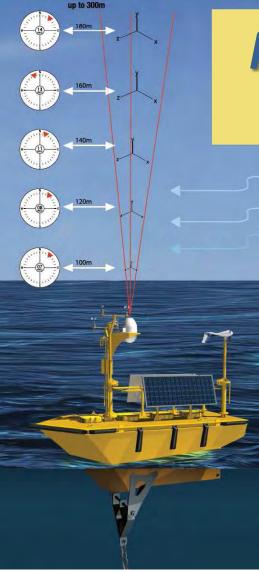
How Effective is the Laser Wind Sensor?

- Noise at one-second requires aggregation of data
 - 10 minutes (traditional)
 - 30 seconds to 10 minutes depending on application
 - Is data valid at all heights (75, 90, 105, 125, 150, 175 m)?



Explaining Variation

- Does wind speed vary by:
 - Height (marine boundary layer)
 - Time of year
 - Location in lake
 - November-December 2011 deployment
 - Summer 2013 deployment

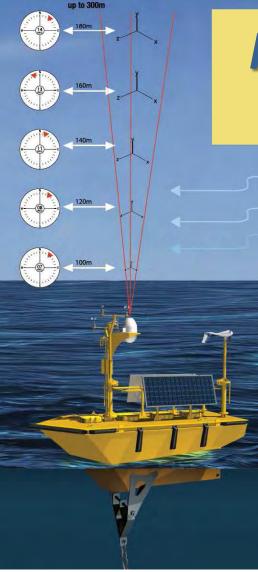


David Zeitler

2011/2012 Yeni Nieves, Biostatistics PSM

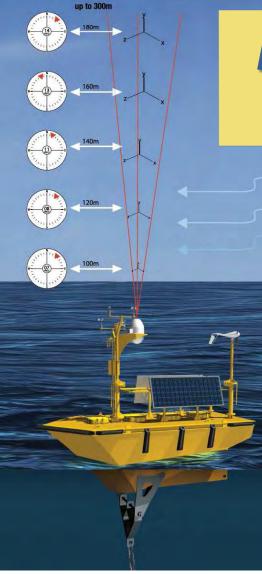
2012/2013 Daniel Hodges, Biostatistics PSM Andrew Borgman, Biostatistics PSM

2013/2014 Tyson Spoelma, Statistics Major Aaron Clark, Biostatistics PSM



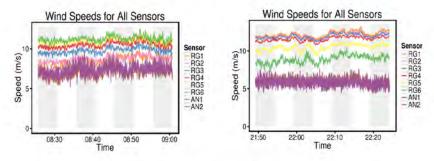
Challenges

- We currently have about 55Gb of data, more coming.
- Data comes from multiple sources (Laser Wind Sensor, Meteorological Package, Water Quality Sensor, NOAA bouy).
- Data rates and recording times vary across sources from 1 second to 1 hour.
- Data has highly variable quality.



Data Quality Issues

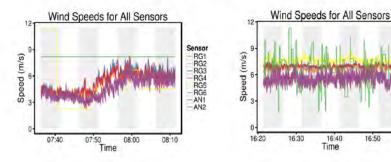
Good Quality Data

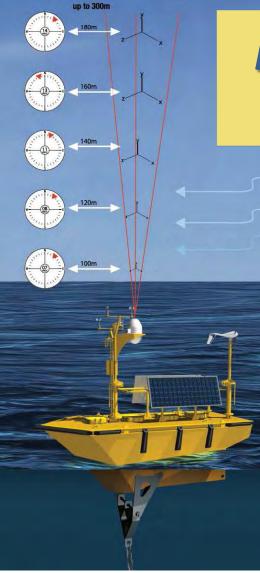


Problematic Data

Sensor RG1 RG2 RG3 RG4 RG5 RG6 AN1 AN2

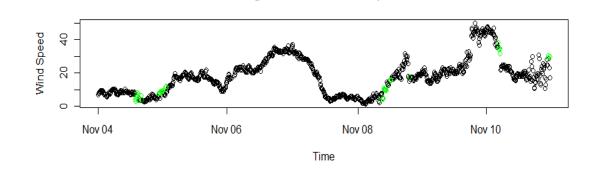
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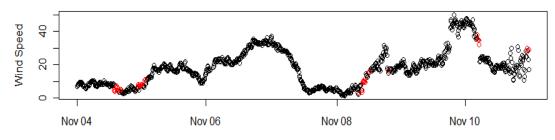


Missing data imputation

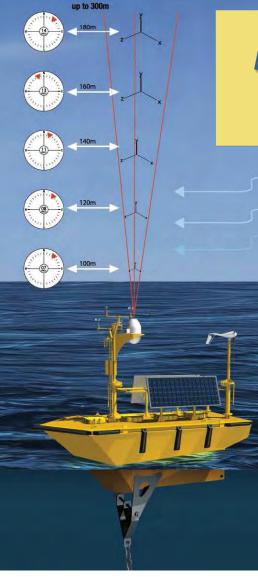
Missingness Filled With Simple Model



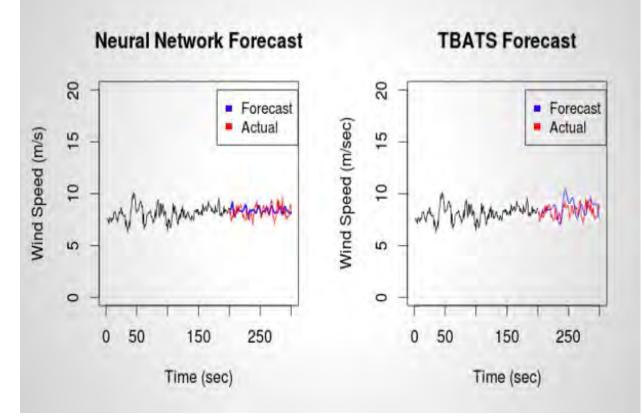


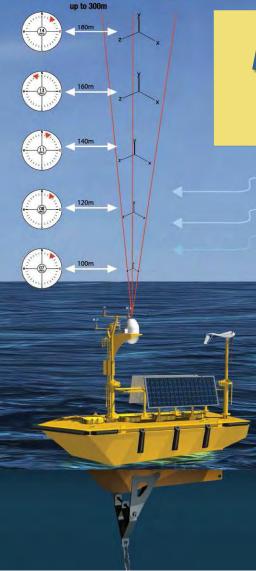


Time

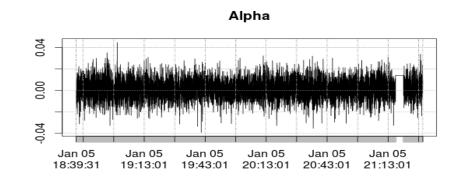


Forecasting



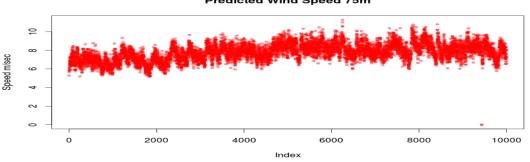


Wind profiling

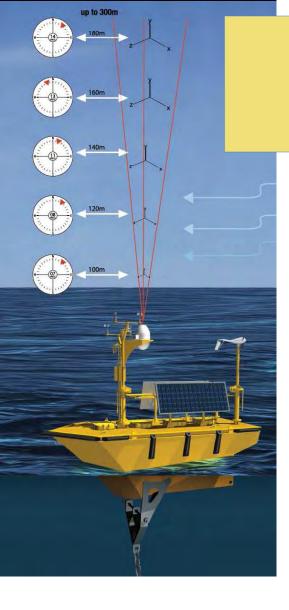


Generalization: $u/u_r = (z/z_r)^{\alpha}$

 $u \rightarrow wind speed @ z$ $u_r \rightarrow wind speed @ z_r$ $z \rightarrow height one$ $z_r \rightarrow height two$ $\alpha \rightarrow exponent$



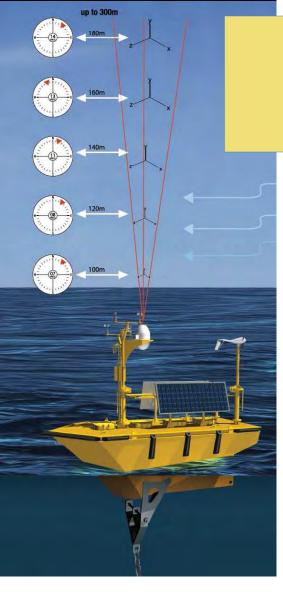
Predicted Wind Speed 75m

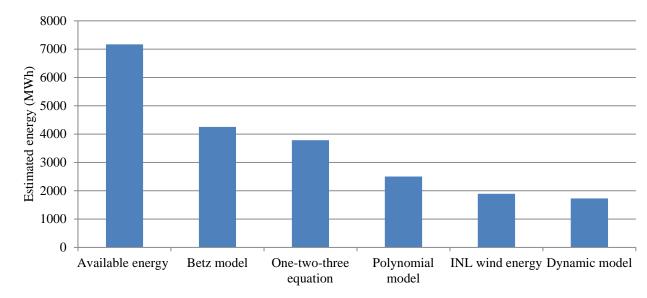


Faculty members: Mehmet Sözen and Azizur Rahman Graduate Assistant: Md Nahid Pervez

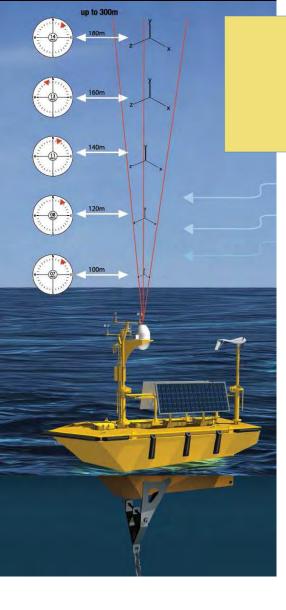
Objectives

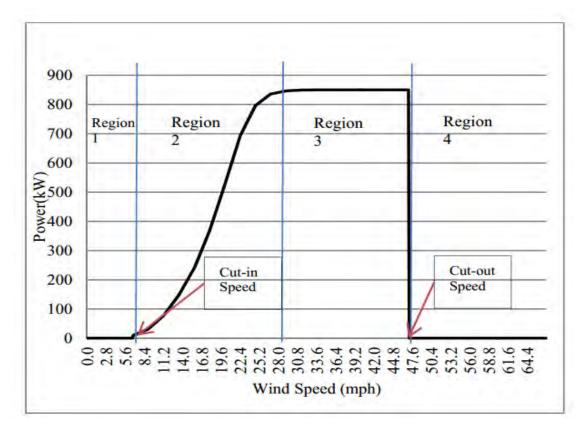
- Accurate power estimation from wind speed and wind direction data
- Integration for estimating total energy generation
- Developing a model for a wind turbine with dynamic yaw control for more accurate energy estimation than traditional models with no yaw control



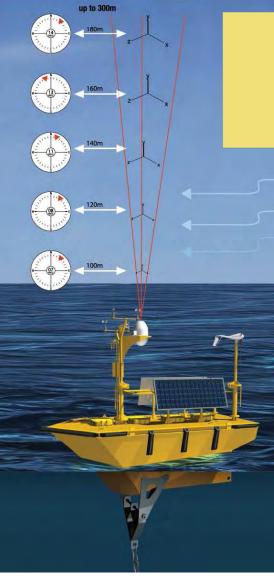


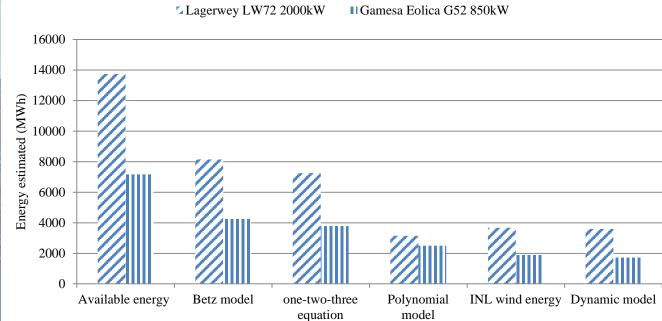
Estimated energy by different models



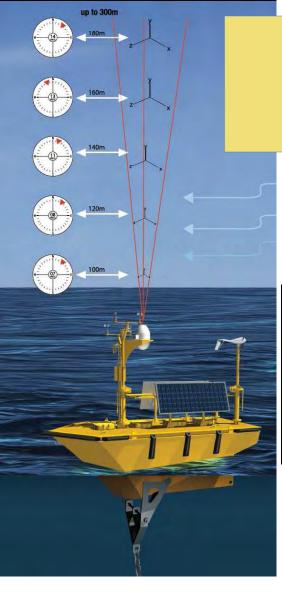


Power curve for Gamesa Eolica G58-850 kW wind turbine

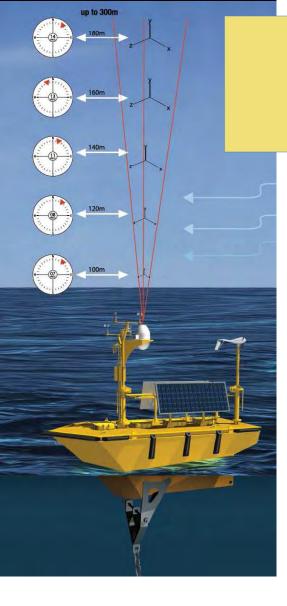


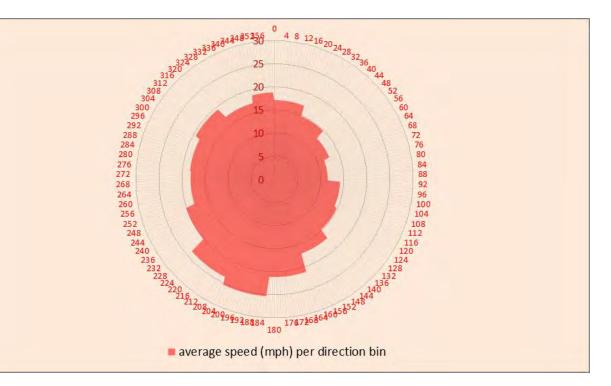


Energy estimated by different wind turbine models

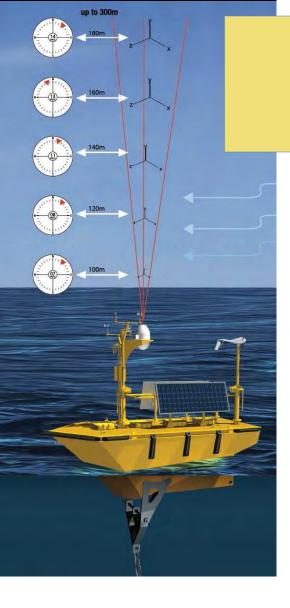


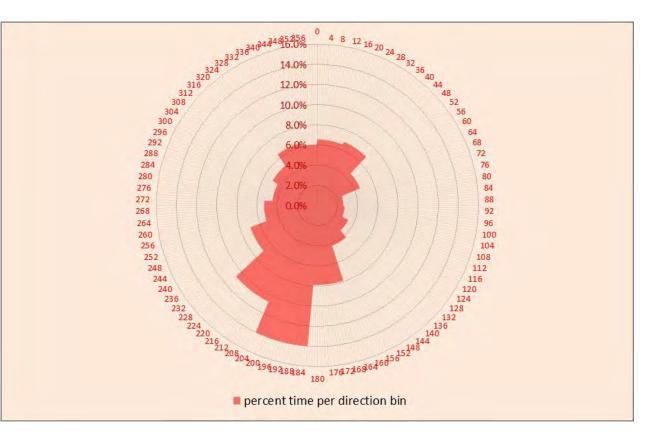
Range Gate	Altitude (m)	Energy output (MWh)	Nameplate capacity (kW)	Capacity factor
RG1	75	1707.732224	850	37.9%
RG2	90	1786.540252	850	39.3%
RG3	105	1805.26632	850	39.7%
RG4	125	1754.083151	850	38.5%



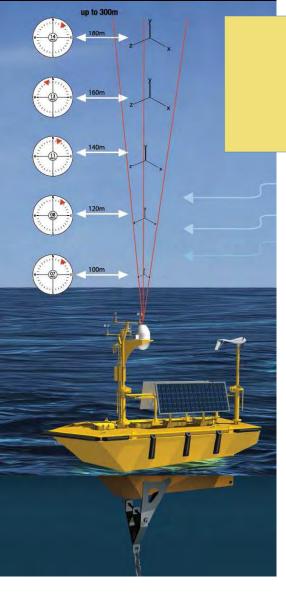


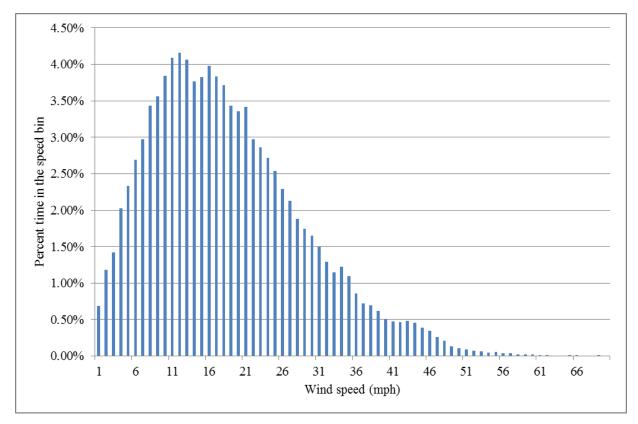
Wind rose of averaged speed per direction bin





Wind rose of fraction time per direction bin





Frequency distribution of RG 1