

Spatial radiative feedbacks from internal variability using multiple regression

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1 **Spatial radiative feedbacks from internal variability using multiple**
2 **regression**

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ABSTRACT

11 The sensitivity of the climate to CO₂ forcing depends on spatially-varying
12 radiative feedbacks which act both locally and nonlocally. We assess whether
13 a method employing multiple regression can be used to estimate local and
14 nonlocal radiative feedbacks from internal variability. We test this method on
15 millennial-length simulations performed with six coupled atmosphere-ocean
16 general circulation models (AOGCMs). Given the spatial pattern of warming,
17 the method does quite well at recreating the top-of-atmosphere flux response
18 for most regions of the Earth, except over the Southern Ocean where it consis-
19 tently overestimates the change, leading to an overestimate of the sensitivity.
20 For five of the six models, the method finds that local feedbacks are posi-
21 tive due to cloud processes, balanced by negative nonlocal shortwave cloud
22 feedbacks associated with regions of tropical convection. For four of these
23 models, the magnitude of both are comparable to the Planck feedback, so that
24 changes in the ratio between them could lead to large changes in climate sen-
25 sitivity. The positive local feedback explains why observational studies that
26 estimate spatial feedbacks using only local regressions predict an unstable cli-
27 mate. The method implies that sensitivity in these AOGCMs increases over
28 time due to a reduction in the share of warming occurring in tropical convect-
29 ing regions and the resulting weakening of associated shortwave cloud and
30 longwave clear-sky feedbacks. Our results provide a step towards an observa-
31 tional estimate of time-varying climate sensitivity by demonstrating that many
32 aspects of spatial feedbacks appear to be the same between internal variability
33 and the forced response.

34 **1. Introduction**

35 Forecasting global warming is one of climate science’s key challenges. As the atmospheric car-
36 bon dioxide concentration increases, the planet’s radiation of energy to space becomes less than its
37 absorption of sunlight (Arrhenius 1896). This energy imbalance, the *radiative forcing*, warms the
38 surface, setting off processes (*radiative feedbacks*) that close the imbalance, restoring the system
39 to a new steady state. We call the global average of the radiative feedbacks the *climate feedback*
40 (also called the climate feedback parameter, Charney et al. (1979), or the thermal damping rate,
41 Dessler (2012)). The total warming in response to a given increase in CO₂ is thus determined by
42 the resulting radiative forcing and the climate feedback (Charney et al. 1979). The rate of warming
43 also involves the thermal inertia of the surface, mostly due to oceanic heat uptake (Gregory et al.
44 2002). Uncertainty in the climate feedback contributes the most to uncertainty in future warming
45 (Otto et al. 2013; Lewis and Curry 2015; Lutsko and Popp 2019), in part because of the inverse
46 relationship between feedback and sensitivity (Roe and Baker 2007).

47 Directly simulating radiative feedbacks is difficult primarily because cloud feedbacks depend
48 on small-scale processes (Wetherald and Manabe 1988). Alternatively, the climate feedback can
49 be inferred from observations, either by solving for it using the observed warming, observed deep
50 ocean heat uptake, and simulated radiative forcing (Gregory et al. 2002; Otto et al. 2013), or by
51 analyzing how the planet’s energy imbalance changes as the surface temperatures varies month-
52 to-month or year-to-year (Forster and Gregory 2006; Murphy et al. 2009; Dessler 2010; Cox et al.
53 2018; Lutsko and Takahashi 2018; Jiménez-de-la Cuesta and Mauritsen 2019; Libardoni et al.
54 2019). These observational methods often assume that the climate feedback is constant, but many
55 studies have shown that it typically changes with time in simulations (e.g., Murphy 1995; Wat-
56 terson 2000; Senior and Mitchell 2000; Armour et al. 2012; Jonko et al. 2012; Andrews et al.

57 2015). While the temperature dependence of feedbacks can cause this to occur under sufficient
58 (and likely strong) warming (Meraner et al. 2013; Bloch-Johnson et al. 2015), the change occurs
59 even after relatively small amounts of warming (e.g., Armour et al. 2012; Andrews et al. 2015;
60 Rugenstein et al. 2016). Since warming in different regions sets off radiative feedbacks of differ-
61 ent strengths, the inconstancy of the climate feedback is likely caused by the change in the spatial
62 pattern of warming with time (Winton et al. 2010; Armour et al. 2012). Since the temperature
63 pattern associated with internal variability differs from the forced response, we should expect the
64 climate feedback associated with each to differ (Dessler 2012; Colman and Hanson 2017), and in
65 fact the climate feedback appears to vary across the historical record (Gregory and Andrews 2016;
66 Fueglistaler 2019). The climate feedback may vary between historical and future warming (Zhou
67 et al. 2016; Armour 2017; Proistosescu and Huybers 2017; Andrews et al. 2018), although the
68 importance of this effect may be modest (Lewis and Curry 2018).

69 Recent modelling work has explored a new framework in which the climate feedback is a linear
70 combination of radiative feedbacks associated with different regions of the surface, weighted by
71 the temperature change in each region (Zhou et al. 2017; Dong et al. 2019). This assumes that
72 the spatial radiative feedbacks themselves are constant, with only the map of surface tempera-
73 ture change evolving. This paper explores a corollary: since internal variability creates an ever-
74 changing pattern of surface temperature and top-of-atmosphere radiative imbalance, a sufficiently
75 long record of this variability should exhibit the behavior of these spatial radiative feedbacks. In
76 this paper, we propose and evaluate a multiple regression (MR) method to estimate the spatial
77 radiative feedbacks of six atmosphere-ocean general circulation models from control simulations,
78 which we compare to existing methods for estimating feedbacks from internal variability (Section
79 2). We do so in spite of the known bias in regression methods related to stochastic variation in
80 top-of-atmosphere fluxes (Spencer and Braswell 2008, 2011; Choi et al. 2014; Proistosescu et al.

81 2018). We test the method by convolving the estimated spatial feedbacks with warming patterns
 82 from forced simulations performed with the respective models (Section 3), assessing the method’s
 83 accuracy in recreating aspects of the forced response. We discuss insights the MR method pro-
 84 vides into climate dynamics, such as the competing nature of local and nonlocal cloud feedbacks
 85 (Section 4) and summarize our findings (Section 5).

86 2. Illustrating the MR method with a conceptual model

87 In this section, we present a method for predicting spatial feedbacks from records of unforced
 88 variability using multiple regression. We first set up a conceptual climate model designed to illus-
 89 trate the method and capture some features of the complex climate models discussed in Section 3.
 90 This conceptual model has two regions of equal area. In each, the change in surface temperature
 91 (T_i) is proportional to the net energy gain of that region, which is the sum of the net downwards
 92 top-of-atmosphere (TOA) radiative flux (N_i), the net gain from horizontal energy transport from
 93 the atmosphere and ocean combined ($-H$ in region 1, H in region 2), and additional random
 94 forcing ($F_{surf,i}$):

$$c_1 \frac{dT_1}{dt} = N_1 - H + F_{surf,1} \quad (1)$$

$$c_2 \frac{dT_2}{dt} = N_2 + H + F_{surf,2} \quad (2)$$

95 where c_i is the surface thermal inertia associated with region i . This model can be re-expressed in
 96 terms of anomalies relative to an initial equilibrium state, so that we consider T'_i , N'_i , H' , and $F'_{surf,i}$
 97 instead of T_i , N_i , H , and $F_{surf,i}$. We assume that heat transport is proportional to the temperature
 98 gradient between the two regions:

$$H' = \gamma(T'_1 - T'_2) \quad (3)$$

99 Changes in a region's top-of-atmosphere radiative fluxes are caused by radiative feedbacks ($\lambda_{i,j}$,
 100 which represents the influence of surface temperature in region j on the net TOA flux in region i),
 101 radiative forcing due to changes in a forcing agent such as an increase in CO₂ ($F_{CO_2,i}$), and radiative
 102 forcing due to random atmospheric fluctuations that occur independently of surface temperature
 103 ($F_{TOA,i}$):

$$N'_1 = \lambda_{1,1}T'_1 + \lambda_{1,2}T'_2 + F_{CO_2,1} + F_{TOA,1} \quad (4)$$

$$N'_2 = \lambda_{2,1}T'_1 + \lambda_{2,2}T'_2 + F_{CO_2,2} + F_{TOA,2} \quad (5)$$

104 $\lambda_{1,1}$ and $\lambda_{2,2}$ are local radiative feedbacks, while $\lambda_{1,2}$ and $\lambda_{2,1}$ are nonlocal radiative feedbacks
 105 (where our sign convention ensures that a negative λ implies a negative, stabilizing feedback).

106 Nonlocal radiative feedbacks (Rugenstein et al. 2016; Zhou et al. 2017; Po-Chedley et al. 2018;
 107 Dong et al. 2019) are changes in a region's top-of-atmosphere flux that occur due to changes in
 108 surface temperature elsewhere, independent of local surface temperature changes. For example, in
 109 Figure 1, regions 1 and 2 represent the convecting and subsiding branches of an overturning cell
 110 respectively. Surface warming in region 1 propagates vertically, warming region 1's free tropo-
 111 sphere, and then horizontally into the free troposphere of region 2, increasing H' . Region 2 now
 112 has a warmer troposphere, which radiates more, decreasing N'_2 . The resulting horizontal advection
 113 may also increase the humidity of region 2's free troposphere, increasing N'_2 . Assuming region 2
 114 has a subsidence-induced boundary layer inversion, its low cloud cover could also increase, caus-
 115 ing a further decrease in N'_2 . All of these changes in N'_2 occur independently of any changes in T'_2 ,
 116 and conspire to make $\lambda_{2,1}$ positive or negative.

117 We note that an increase in H' will also increase T'_2 directly (Eq. 1; Feldl and Roe 2013b). While
 118 this latter effect is connected to nonlocal radiative feedbacks in that both occur due to horizontal
 119 fluxes of heat and moisture, the two effects are different, and can disagree in the sign of the

120 resulting surface warming, as demonstrated by the above example. While the influence of H' on
 121 surface temperature is important for understanding the evolution of the spatial pattern of warming,
 122 in this paper we are focused only on the influence of surface temperature on TOA radiative fluxes,
 123 and so we focus on nonlocal radiative feedbacks.

124 Suppose that region 1 has a weak positive local feedback $\lambda_{1,1} = 0.5 \text{ Wm}^{-2}\text{K}^{-1}$ (red solid line,
 125 Figure 2b), and a stronger negative nonlocal feedback, so that $\lambda_{2,1} = -2 \text{ Wm}^{-2}\text{K}^{-1}$ (light blue
 126 solid line, Figure 2b). We also assume that the surface temperature of the subsiding region 2 has
 127 no net effect on TOA fluxes, so that $\lambda_{1,2} = \lambda_{2,2} = 0 \text{ Wm}^{-2}\text{K}^{-1}$ (orange and gray solid lines in
 128 Figure 2b). We assume that region 2's thermal inertia is much larger than region 1's, representing
 129 more ocean heat uptake in this region (see Appendix for details).

130 We define the global climate feedback λ to be the dependence of the globally averaged net TOA
 131 flux on the globally averaged surface temperature, that is

$$\lambda(t) = \frac{\partial \bar{N}}{\partial \bar{T}}(t) = \sum \left(\Lambda \frac{d\vec{T}}{dt}(t) \right) / \frac{d\bar{T}}{dt}(t) \quad (6)$$

132 where $\vec{T} = \begin{bmatrix} T_1 \\ T_2 \end{bmatrix}$, $\Lambda = \begin{bmatrix} \lambda_{1,1} & \lambda_{2,1} \\ \lambda_{1,2} & \lambda_{2,2} \end{bmatrix}$, and a bar over a vector indicates the global average of that vector.
 133 We do not have to use an anomaly for \bar{N} because \bar{N} is 0 in equilibrium. Note that even though
 134 the spatial feedbacks Λ are constant, the global feedback λ can change with time because of the
 135 evolving spatial pattern of warming $\frac{d\vec{T}}{dt}(t)$.

136 We perform two 5000-year experiments: a “control” experiment, where all variations in
 137 $\vec{T}'_{control}(t)$ and $\vec{N}'_{control}(t)$ are due to random forcing at the surface ($\vec{F}'_{surf}(t) = \begin{bmatrix} F'_{surf,1}(t) \\ F'_{surf,2}(t) \end{bmatrix}$) and TOA
 138 ($\vec{F}'_{TOA}(t) = \begin{bmatrix} F'_{TOA,1}(t) \\ F'_{TOA,2}(t) \end{bmatrix}$), and an “abrupt4x” experiment in which the time series $\vec{T}'_{abrupt4x}(t)$ and
 139 $\vec{N}'_{abrupt4x}(t)$ also respond to an initial step forcing akin to a quadrupling of CO_2 concentration
 140 ($F_{\text{CO}_2,1} = F_{\text{CO}_2,2} = 8 \text{ Wm}^{-2}$).

141 For the abrupt4x simulation, the climate feedback $\lambda = \frac{\partial \bar{N}}{\partial \bar{T}}$ changes significantly around year
 142 20. We therefore define two forced feedbacks, $\lambda_{4x,early}$ and $\lambda_{4x,late}$, which are the slopes of the
 143 linear regressions of $\bar{N}_{abrupt4x}(t)$ against $\bar{T}'_{abrupt4x}(t)$ taken over years 1 to 20 and years 21 to 5000
 144 respectively (Figure 2c). Before these regressions are taken, we average each annual time series
 145 (gray dots) over roughly exponentially increasing time periods (colored dots). $\Delta\lambda_{4x} \equiv \lambda_{4x,late} -$
 146 $\lambda_{4x,early}$ is the change in feedback between the periods.

147 We seek a method to predict $\lambda_{4x,early}$, $\lambda_{4x,late}$, and $\Delta\lambda_{4x}$ given $\bar{T}'_{control}(t)$ and $\bar{N}'_{control}(t)$ (internal
 148 variability), and $\bar{T}'_{abrupt4x}(t)$ (the spatial pattern of warming). The simplest method would be to
 149 regress annual averages of $\bar{N}_{control}(t)$ against $\bar{T}_{control}(t)$ to get the resulting regression slope $\lambda_{control}$
 150 (the slope of the blue line in Figure 2a), and to assume that $\lambda_{4x,early} = \lambda_{4x,late} = \lambda_{control}$ (Forster
 151 and Gregory 2006; Murphy et al. 2009; Dessler 2010). We call this the “global” method because
 152 it uses information about changes in global surface temperature only.

153 The radiative feedbacks associated with temperature change induced by random forcing (i.e.,
 154 \vec{F}_{surf} and \vec{F}_{TOA}) differ from those induced by uniform greenhouse forcing (\vec{F}_{CO_2}) (Dessler 2012;
 155 Colman and Hanson 2017; Proistosescu et al. 2018). Our conceptual model illustrates how this can
 156 arise from spatial variation. Since the thermal inertia in region 2 is larger, most of the temperature
 157 variability occurs in region 1, so that $\lambda_{control}$ is weighted towards the feedbacks associated with
 158 this region ($\lambda_{control} \approx \lambda_{1,1} + \lambda_{2,1}$). The spatial pattern of warming in the forced response is initially
 159 dominated by region 1 as well, once more because it has the lowest thermal inertia. As a result, the
 160 global method predicts $\lambda_{4x,early}$ well (see Figure 2c and d). However, the global method always
 161 predicts $\Delta\lambda_{4x} = 0$, as it assumes a constant λ . Since warming moves to region 2 over time and
 162 $\lambda_{1,2} + \lambda_{2,2} > \lambda_{1,1} + \lambda_{2,1}$, $\Delta\lambda_{4x}$ is positive. As a result, the global method underpredicts the warming
 163 of the abrupt4x simulation by about 1.5 K (Figure 2c). To address this shortcoming, we need a
 164 method that accounts for the spatial variation of feedbacks.

165 The “local” method is a commonly used method (Boer and Yu (2003b), Crook et al. (2011), the
 166 “local” method in Feldl and Roe (2013a), Brown et al. (2015), and Trenberth et al. (2015)) for
 167 estimating spatial feedbacks. In this method, we construct $\vec{\lambda}_{local} = \begin{bmatrix} \lambda_{1,local} \\ \lambda_{2,local} \end{bmatrix}$ where $\lambda_{i,local}$ is the
 168 result of regressing $N'_{i,control}(t)$ against $T'_{i,control}(t)$. Taking the dot product of $\vec{\lambda}_{local}$ with $\vec{T}'_{abrupt4x}(t)$
 169 then provides an estimate of $\vec{N}'_{abrupt4x}(t)$ which we can use to estimate $\lambda_{4x,early}$, $\lambda_{4x,late}$, and $\Delta\lambda_{4x}$.

170 This method assumes all radiative feedbacks are local, while allowing for the nonlocal effects of
 171 heat transport (Feldl and Roe 2013b). However, if there are nonlocal radiative feedbacks, then the
 172 local method can miss or conflate their effects. In region 1, estimates of $\lambda_{1,local}$ tend toward $\lambda_{1,1} =$
 173 $0.5 \text{ Wm}^{-2}\text{K}^{-1}$ (dotted red line, Figure 2b), missing the negative nonlocal feedback $\lambda_{2,1}$. Since
 174 the early period is dominated by warming in region 1, the local method overestimates $\lambda_{4x,early}$
 175 (where “overestimates” implies the estimate of $\lambda_{4x,early}$ is more positive than the true value, even
 176 if both are negative, resulting in an overestimate of the sensitivity). On the other hand, T'_2 tends
 177 to be positively correlated with T'_1 , due to heat transport, while T'_1 tends to be anti-correlated with
 178 N'_2 because $\lambda_{2,1}$ is negative. As a result, the local method predicts that $\lambda_{2,local}$ is negative (dotted
 179 orange line, Figure 2b), even though T'_2 has no net influence on N . Since T'_2 contributes more
 180 to warming over time, the local method incorrectly predicts a more negative feedback (Figure 2c
 181 and d). Similar discrepancies can occur when local feedbacks are used to diagnose feedbacks
 182 in GCMs, which may explain instances when the local method fails to predict feedback changes
 183 properly (Rose et al. 2014). We need a method that includes nonlocal feedbacks while accounting
 184 for correlation between temperature in different regions.

185 We propose a multiple regression (“MR”) method, which estimates the local and nonlocal feed-
 186 backs associated with N'_i (that is, the influence of T'_1 and T'_2 on N'_i) by regressing $N'_{i,control}(t)$ against

187 both regions simultaneously:

$$N'_{i,control}(t) = \lambda_{i,1,MR}T'_{1,control}(t) + \lambda_{i,2,MR}T'_{2,control}(t) + F_{TOA,i} \quad (7)$$

188 In least squares multiple regression, $\lambda_{i,j,MR}$ is the same as the slope of the regression of $N'_{i,control}(t)^*$
 189 against $T'_{j,control}(t)^*$, where the star indicates that each time series is the residual after regressing
 190 against the surface temperatures in all non- j regions (see Appendix). This removes the effect of
 191 correlations between surface temperature in different regions giving spurious feedbacks, as with
 192 $\lambda_{2,local}$ above. Multiple regression has been used to estimate other surface temperature-dependent
 193 feedbacks from internal variability, though not radiative feedbacks (Liu et al. 2008; Li et al. 2012;
 194 Li and Forest 2014; Liu et al. 2018). The dashed lines in Figure 2b show that, given sufficient
 195 time, the MR method predicts the local and nonlocal feedbacks in each region, so that when we
 196 multiply the full matrix of estimated spatial feedbacks $\Lambda_{MR} = \begin{bmatrix} \lambda_{1,1,MR} & \lambda_{1,2,MR} \\ \lambda_{2,1,MR} & \lambda_{2,2,MR} \end{bmatrix}$ by $\vec{T}'_{abrupt,4x}(t)$ to
 197 estimate $\vec{N}_{abrupt4x}(t)$, the resulting estimates $\lambda_{4x,early}$, $\lambda_{4x,late}$, and $\Delta\lambda_{4x}$ are accurate (Figure 2c
 198 and d). Therefore, for this example, the MR method is able to account for the difference in climate
 199 feedback between internal variability and the forced response.

200 Random fluctuations in N influence T via planetary energy gain at the same time that T influ-
 201 ences N via radiative feedbacks. As a result, T will tend to lag N with a positive correlation, while
 202 N will lag T with a negative correlation, so that regressions taken without a lag will be biased to-
 203 wards 0 (Spencer and Braswell 2008, 2011; Choi et al. 2014; Proistosescu et al. 2018). This issue
 204 does not occur for random forcing at the surface, which only affects N indirectly through radiative
 205 feedbacks. Therefore, the more stochastic forcing that occurs at TOA (\vec{F}_{TOA}) as opposed to the
 206 surface (\vec{F}_{surf}), the more the regression of N vs. T will overestimate the true radiative feedback.
 207 For the example in Figure 2, $F_{surf,1}$ and $F_{surf,2}$ are white noise with variance $20 \text{ W}^2\text{m}^{-4}$, while
 208 $F_{TOA,1}$ and $F_{TOA,2}$ are white noise with variance $5 \text{ W}^2\text{m}^{-4}$. Figure S1 shows a case where these

209 variances are 10 and $15 \text{ W}^2\text{m}^{-4}$ respectively, with the result that all three regression methods over-
210 estimate $\lambda_{4x,early}$ and $\lambda_{4x,late}$, while underestimating $\Delta\lambda_{4x}$. In other words, given sufficient random
211 TOA forcing, regression estimates of spatial feedbacks will be biased. We consider this bias in
212 discussing our results in the next section.

213 It should be mentioned that Proistosescu et al. (2018) model ENSO variability as a distinct
214 additional mechanism by which N and T mutually influence each other, which similarly leads
215 to overestimates of λ from regression-based methods. As part of their model, they assume that
216 T influences N with a lag of about three months. Since this is beyond the time scale of most
217 atmospheric processes, we assume that this feedback propagates in part through the ocean, so that
218 the atmospheric component may still operate through the same spatial feedbacks that operate under
219 other forms of variability and under the forced response (e.g., it could occur due to a “tropical
220 atmospheric bridge” mechanism; Klein et al. 1999).

221 **3. Using the MR method on AOGCMs**

222 To test the methods discussed above on atmosphere-ocean general circulation models
223 (AOGCMs), we use simulations from LongRunMIP, an archive of fully coupled millennial-length
224 simulations of complex climate models (Rugenstein et al. 2019). We chose the six models with
225 millennial-length control and abrupt4x simulations for which we have monthly output. Details of
226 these models and simulations are given in Table S1.

227 We alter the three methods from Section 2 to reflect the more complex nature of AOGCMs:

- 228 • CO_2 forcing can lead to atmospheric changes that are independent of surface warming. These
229 “adjustments” to forcing occur mostly within the first year (e.g., Gregory and Webb 2008).

230 We remove this year from our analysis, redefining our early period to be years 2 to 20.

- For AOGCMs, there are more than two regions with distinct behaviors. Dividing our models into n regions, equation 7 becomes

$$N'_i(t) = \lambda_{i,1,MR}T'_{1,control}(t) + \lambda_{i,2,MR}T'_{2,control}(t) + \dots + \lambda_{i,n,MR}T'_{n,control}(t) + F_{TOA,i}, \quad (8)$$

giving a system of n equations

$$\vec{N}'(t) = \Lambda \vec{T}'(t) + \vec{F}_{TOA} \quad (9)$$

where Λ is a matrix of feedbacks $\lambda_{i,j}$. Each equation in this system has $n - 1$ degrees of freedom, so n must be smaller than the length of the control simulation, and preferably much smaller given the significant spatial correlation of surface temperature. For simplicity, we divide the surface equally in latitude and longitude, although this may miss features of the climate system. Since our control simulations last at least 1000 years (Table S1), we use a 15° by 15° grid, giving 288 regions (Figure 3).

- Circulations, and therefore radiative feedbacks, change with season. Thus, we compute feedbacks for each season individually, first by averaging all monthly time series into seasonal time series (where the seasons are DJF, MAM, JJA, SON), and then performing a separate regression for each season (e.g. all DJF values of $\vec{N}'_{control}(t)$ against all DJF values of $\vec{T}'_{control}(t)$) creating a set of four feedbacks. We multiply each month of $\vec{T}'_{4x}(t)$ by the relevant seasonal feedback, and take the annual average to estimate $\vec{N}'_{4x}(t)$. We compare seasonal averages to other approaches in Tables S2 and S3. While seasonal averaging tends to reduce the error in the MR method, the qualitative behavior of the different methods is not affected by the choice of time averaging.

Figures 3 and 4 show \bar{N} vs. \bar{T}' of the control and abrupt4x simulations of the six models respectively. Figure 4 also shows \bar{N} estimated using the three methods, assuming that each estimate starts

251 with the true value of \bar{N} at year 2. The solid lines in Figure 4 are local regressions of \bar{N} against \bar{T}'
252 performed using LOESS (LOcally Estimated Scatterplot Smoothing; Cleveland and Devlin 1988,
253 see Appendix for more detail). We can use the slopes of these lines mapped against the time series
254 of \bar{T} to estimate feedbacks as a function of time (lines in Figure 5).

255 Though there is a range of feedback values between models, all six forced simulations have a
256 feedback that gets less negative with time (black lines), consistent with past results for similar
257 models (Andrews et al. 2015). The MR method (green lines) matches or overestimates the feed-
258 back value, with this error tending to decrease with time. This error can range from $\sim 1 \text{ Wm}^{-2}\text{K}^{-1}$
259 for the early years of CESM104 and GISSE2R (that is, at least half of the feedback strength itself)
260 to roughly 0 for HadCM3L. The MR method correctly predicts that the feedback gets less negative
261 with time, although for some of the models it underestimates the magnitude of the change.

262 The global method (blue) overestimates the early feedback. Since the global method is agnostic
263 about the pattern of surface warming, the predicted feedback is mostly constant except for small
264 differences due to changes in the seasonal distribution of warming and in seasonal feedbacks (e.g.,
265 the early years of HadCM3L). As a result, as the true feedback increases with time, it becomes
266 more positive than the global estimate for half the models. For some models, this allows the global
267 method to more accurately forecast the equilibrium warming than the other methods, albeit due to
268 compensating errors in the early and later periods (i.e., CESM104 and MPIESM12 in Figure 4).

269 The local method (orange) predicts a positive feedback for all models except GISSE2R, implying
270 a climate unstable to external forcing, and does not predict the increase in feedback with time seen
271 in all models.

272 The dots in Figure 5 represent estimates of $\lambda_{4x,early}$ and $\lambda_{4x,late}$ (feedbacks before and after year
273 20; see Appendix for details). We visualize the estimates of these feedbacks and their difference
274 using a scatter plot (black dots in Figure 6), as in Figure 2d. The global and MR methods perform

275 similarly for $\lambda_{4x,early}$ and $\lambda_{4x,late}$, while the MR method gets closer to accurately predicting $\Delta\lambda_{4x}$,
276 consistent with the discussion around Figure 4 and reflected by the root mean square errors in
277 Table 1 (for feedback values for all models and components, see Tables S7 and S8).

278 \vec{N}' and λ can be expressed as the sum of shortwave (SW) and longwave (LW) terms, which can
279 be separated in turn into clear-sky (fluxes recalculated as if no clouds were present) and cloud
280 terms (the residual of total and clear-sky terms; cloud feedbacks defined this way may include
281 changes in cloud masking rather than in clouds themselves (Soden et al. 2004)).

282 Examining these component individually shows that the error in $\lambda_{4x,early}$ in the MR and global
283 methods is due primarily to SW cloud feedbacks (red markers in Figures 6a and b). Both the
284 MR and global methods have smaller errors in $\lambda_{4x,late}$ (Figures 6d and e), but for the MR method
285 this is caused by a reduction in the error in SW cloud, while for the global method this is due
286 to offsetting errors in the SW and LW cloud feedbacks (see also Table 1). Cloud feedbacks are
287 similarly the cause of the local method's large overestimation, while the local method outperforms
288 the other methods at predicting the primarily local SW clear feedback (Table 1). Note that the
289 global method has a relatively small error for the LW clear feedback, consistent with Lutsko and
290 Takahashi (2018). The increase in feedback with time ($\Delta\lambda_{4x}$) and the variation in this increase
291 between models is driven by the SW cloud feedback (Figures 6g, h, and i). The MR method has
292 the smallest error in estimating $\Delta\lambda_{4x}$, with this error tending to be an underestimate. Figures S2-5
293 show feedback time series plots for all component fluxes.

294 All methods examined contain some degree of error. We can find the geographic source of these
295 errors by looking at the true and estimated normalized change in \vec{N}'_{4x} (multi-model mean in Fig-
296 ure 7; errors in the multi-model mean and for individual models in Figures S6-S8), calculated by
297 taking the finite difference in $\vec{N}'_{4x}(t)$ between the first and last part of the indicated time period,
298 where each part contains similar amounts of warming (see Appendix). The difference is normal-

299 ized by the global temperature change, allowing intermodel comparison. For the global method,
300 we make this estimate by regressing $\vec{N}'_{control}(t)$ against $\bar{T}'_{control}(t)$ (the “global” method in Feldl and
301 Roe (2013a) and the “local contribution” in Boer and Yu (2003a,b); Crook et al. (2011); Zelinka
302 et al. (2012); Andrews et al. (2015)) and using this as the predicted normalized change in \vec{N}'_{4x} .

303 The MR method does quite well at recreating the multi-model spatial pattern of TOA flux
304 change, both for net and component fluxes (Figures S9-S12), with the exception of regions south
305 of 30°S and the north Atlantic. The MR method also overestimates the change in these regions in
306 individual models (Figures S6-S8). The error in these regions has contributions from all compo-
307 nent fluxes, foremost the SW cloud feedback (for multi-model mean component flux errors, see
308 Figures S13-17). For all periods, models, and fluxes except for SW clear-sky (which is primarily
309 a local feedback), the MR method outperforms the other two methods when scored by the area-
310 weighted root mean square error (Table 2; for comparison with annual or monthly approaches, see
311 Table S3; for values for individual models, see Table S4; for details on the error metric, see Ap-
312 pendix). Specifically, the global method has large compensating errors, especially in the tropics,
313 and the local method overestimates the change almost everywhere (Figures S6-S8).

314 There are several potential explanations for the MR method’s overestimate for TOA fluxes south
315 of 30°S and over the north Atlantic. These may be regions where there is significantly more
316 stochastic forcing at TOA than at the surface, resulting in a similar overestimation to that discussed
317 in Section 2 and shown in Figure S1. Alternatively, the spatial feedbacks that influence \vec{N}' in these
318 regions may be nonlinear, either in that they change in value as the world warms (e.g., a reduction
319 in the strength of the SW clear feedback once sea ice melts), or the effect of warming in different
320 regions combines nonlinearly, as might occur in response to circulation changes such as a shift in
321 the mid-latitude jet; or surface fluxes may influence \vec{N}' there independently of surface warming.
322 Further research is needed to diagnose this error.

323 In spite of this overestimate, the MR method can be used to explain the multi-model forced
324 TOA flux response for roughly three quarters of the Earth using feedbacks estimated from internal
325 variability (see Table S5 and S6, which show the same error metrics as Tables 1 and 2, using only
326 TOA fluxes north of 30°S). We now discuss the spatial feedbacks estimated by the MR method, as
327 well as some of their implications.

328 4. Discussion

329 We first test if the spatial feedbacks estimated using the MR method exhibit behavior broadly
330 consistent with physically modelled feedbacks. The i^{th} column of Λ represents the change in \vec{N}'
331 from warming in region i . Zhou et al. (2017) performed fixed-SST experiments with the CAM5
332 model where the temperature in region i was perturbed. The top row of Figure 8 shows spatial
333 cloud feedbacks for three representative regions calculated using this approach. The bottom row
334 shows the multi-model and multi-season mean response for warming in similar regions estimated
335 by the MR method. For both approaches, warming in the extratropics or in regions of tropical
336 subsidence produces cloud feedbacks that are mostly local and positive, while warming in tropical
337 convecting regions has significant nonlocal feedbacks which are mostly negative. Since the mod-
338 els, region sizes, and degree of perturbation differ, the details and magnitudes of the feedbacks
339 differ. Further, the fixed-SST method allows land temperatures to evolve freely, so that regions
340 that have significant nonlocal effects, like tropical convecting regions, can cause large changes in
341 TOA fluxes over land (Figure 8b). The MR method is able to estimate land feedbacks directly, so
342 that TOA flux changes due to land warming are not included in these tropical convecting feedbacks
343 (Figure 8e). See also Figure 4 in Dong et al. (2019).

344 The top left panel of Figure 9 shows a map of the multi-model and multi-month mean spatial
345 feedbacks estimated by the MR method: the change in \bar{N} caused by warming in each region di-

346 vided by that region's fractional area (so that smaller, polar regions do not have artificially smaller
347 feedbacks). Spatial feedbacks are strongly negative in regions of tropical convection (e.g., Indone-
348 sia and Central America) and are mostly positive over the tropical oceans in regions of atmospheric
349 subsidence as well as much of the extratropical oceans, in keeping with the examples from Fig-
350 ure 8. These strongly negative feedbacks are robust when feedbacks are recalculated using just
351 the first or second half of the control simulations (Figures S18-22), although outside these regions
352 there is some noise, with the sign of roughly a third of net feedback cells differing between the
353 first and second halves. The variation in the spatial pattern is largely determined by the SW cloud
354 feedback (bottom left panel, Figure 9; for all flux components, see Figures S19-S22).

355 *a. Local and nonlocal feedbacks*

356 The MR method allows us to split spatial feedbacks into local (the diagonal elements of Λ , giving
357 the influence of warming on TOA fluxes directly overhead) and nonlocal components (the off-
358 diagonal elements of Λ), and to calculate the local and nonlocal components of the map of spatial
359 feedbacks (middle and right columns of Figure 9 respectively). We note that the division between
360 local and nonlocal feedbacks depends on grid resolution, with local feedbacks in coarser grids
361 incorporating more nonlocal processes. For the grid considered in this paper, the local feedback
362 is positive almost everywhere, due to cloud feedbacks (Figures S21 and S22): in the tropics and
363 in subtropical subsiding regions, local warming reduces lower tropospheric stability, leading to
364 a loss of low clouds and a positive SW cloud feedback (Klein and Hartmann 1993; Wood and
365 Bretherton 2006; Zhou et al. 2017; Dong et al. 2019). This result holds for each AOGCM except
366 for GISSE2R, which lacks a positive local SW cloud feedback (Figure S24, Table S8). For most
367 models, there is a partially compensating negative local LW cloud feedback in tropical convecting
368 regions, possibly due to an iris effect (Lindzen et al. 2001; Mauritsen and Stevens 2015). Outside

369 of the tropics, there is a positive local LW cloud feedback, possibly associated with an increase in
370 middle and high cloudiness as convection increases (Zelinka et al. 2012).

371 Positive local feedbacks provide an explanation for observational studies that use the local
372 method to predict spatial feedbacks, finding that they are positive over much of the Earth and
373 in the global mean (Brown et al. 2015; Trenberth et al. 2015). For example, the multi-model mean
374 feedbacks estimated using the local method (top middle panel, Figure S23) resemble the feedbacks
375 in the upper right panel of Figure 10 from Trenberth et al. (2015). While local method feedbacks
376 can differ from the local component of MR method feedbacks due to correlation between temper-
377 ature in different regions as discussed in Section 2, the observational studies provide evidence that
378 real world local feedbacks are substantially positive. If we use the MR method to estimate the
379 local components of $\lambda_{4x,early}$ and $\lambda_{4x,late}$ (Table S8), we get positive values for all models except
380 GISSER2R. For these models, the mean estimated local feedback is $3.37 \text{ Wm}^{-2}\text{K}^{-1}$ for the early
381 period and $3.13 \text{ Wm}^{-2}\text{K}^{-1}$ for the late period (Tables S8).

382 The MR method implies that in the absence of negative nonlocal feedbacks, five out of six of
383 these AOGCMs would be unstable to radiative forcing, even accounting for the dominant stabiliz-
384 ing Planck feedback. The MR method predicts that there are strongly negative nonlocal feedbacks
385 coming from regions of tropical convection (upper right panel, Figure 9), largely due to the SW
386 cloud feedback (lower right panel). This is consistent with tropical convecting regions behaving
387 similarly to region 1 of the conceptual model from Section 2: surface warming in the convecting
388 tropics propagates throughout the tropical free troposphere, increasing the temperature aloft while
389 leaving surface temperatures alone. This increases the lower tropospheric stability, and thus low
390 cloud cover (a negative SW cloud feedback), as well as the troposphere's outgoing longwave radi-
391 ation (a negative LW clear feedback) (Rose and Rayborn 2016; Andrews and Webb 2017; Ceppi
392 and Gregory 2017; Klein et al. 2017; Zhou et al. 2017; Dong et al. 2019). Note that incorporating

393 these nonlocal interactions changes both local and total values of the LW clear feedback, giving
394 different values than studies that analyze this feedback purely locally (e.g., Koll and Cronin 2018).

395 For the five models with positive local components, the average nonlocal component of the
396 abrupt4x feedbacks is $-4.21 \text{ Wm}^{-2}\text{K}^{-1}$ for the early period and $-3.69 \text{ Wm}^{-2}\text{K}^{-1}$ for the late
397 period (Table S8). so that the net forced climate feedback is a small residual between competing
398 local and nonlocal feedbacks, with local and nonlocal feedbacks strongly anti-correlated between
399 different models (Table S8; the correlation coefficient for early period non-GISSE2R local vs.
400 nonlocal feedbacks is -0.96 , and for late is -0.98). A modest shift in the relative strength of
401 these feedbacks (for example, due to a shift in circulation) could lead to large changes in cli-
402 mate sensitivity; an increase in the local feedback of only a third would be enough to make these
403 AOGCMs unstable (local and nonlocal feedbacks differ by $\sim 1 \text{ Wm}^{-2}\text{K}^{-1}$, which is on average
404 roughly a third of the magnitude of the local feedback for the non-GISSE2R models). Additional
405 research is needed to understand what mechanisms cause the anti-correlation between local and
406 nonlocal feedback strength, and whether we expect this cancellation to hold in different climate
407 states. Given that the local/nonlocal cancellation does not hold in all contexts – for example, the
408 nonlocal feedback’s seasonal cycle has a larger amplitude and is more latitudinally constrained
409 than the local feedback’s seasonal cycle (Figure S25) – it is unlikely that this cancellation is purely
410 a statistical artifact. Our findings have bearing for exoplanet research, as they suggest that it may
411 be harder to have a cloudy atmosphere with a stable climate than previously thought (Leconte et al.
412 2013), potentially reducing the chance of finding habitable worlds.

413 *b. The cause of the increase in climate feedback over time*

414 For all six models, the change in feedback with time ($\Delta\lambda_{4x}$) is positive, primarily because of the
415 SW cloud feedback, and secondarily the LW clear feedback (Figure 4 and Table S7). The MR

416 method gets the correct sign of $\Delta\lambda_{4x}$ but underestimates this increase for each model, once more
417 primarily due to the SW cloud feedback (Table S8).

418 We can estimate how much the change in the spatial pattern of warming with time (Figure 10a)
419 contributes to $\Delta\lambda_{4x}$ by multiplying this change by the MR estimate of the spatial pattern of feed-
420 backs for each flux component (Figure 9, Figures S18-S22). The resulting maps show the contri-
421 bution of the change in warming pattern to the change in feedback (Figures 10b-f).

422 The MR method identifies two main latitude bands that contribute to the increase in feedback
423 with time: the tropics, whose convecting regions increase the SW cloud and LW clear feedbacks
424 (less warming in these regions reduces the role of the strongly negative nonlocal feedbacks dis-
425 cussed above, consistent with Andrews and Webb 2017; Ceppi and Gregory 2017; Dong et al.
426 2019; Fueglistaler 2019); and the Southern Ocean, which increases the SW clear feedback (due to
427 the delayed warming in this region leading to the delayed melting of sea ice). The MR method
428 estimates that the LW clear sky and SW cloud feedback have offsetting negative contributions in
429 the Southern Ocean. While the LW clear sky offset is consistent with the total change in the LW
430 clear feedback being small, and with the LW clear TOA flux change getting more negative in the
431 Southern Ocean due to a more strongly negative local feedback (zonal figures in the top row of
432 Figure S19), the change in the SW cloud TOA flux is too negative in this region (lower left panel
433 of Figure S17), suggesting that the SW cloud negative contribution is an error, and is likely the
434 reason for the MR method's underestimate of $\Delta\lambda_{4x}$.

435 While the exact evolution of temperature patterns in the tropics in AOGCMs may be incorrect
436 due to cold-tongue biases (Seager et al. 2019), our findings match with Dong et al. (2019), in that
437 as long as the feedbacks in tropical convecting regions are far more negative than anywhere else,
438 the delayed warming in regions of ocean heat uptake will ensure an increase in sensitivity over
439 time. Observational evidence suggests that \bar{N} depends on tropical midtropospheric temperatures

440 (Dessler et al. 2018; Ceppi and Gregory 2019; Fueglistaler 2019), supporting our argument that a
441 reduction in the share of surface warming occurring in the tropical convecting regions which set
442 these temperatures likely influences the Earth’s sensitivity.

443 **5. Conclusions**

444 The global climate feedback, one of the key parameters in determining future climate change,
445 is inconstant in part because radiative feedbacks vary spatially. The MR method estimates these
446 spatial feedbacks from records of its internal variability, and improves upon existing methods for
447 doing so by incorporating both local and nonlocal radiative responses to surface warming. For
448 the six atmosphere-ocean general circulation models studied, the spatial feedbacks estimated by
449 the MR method applied to the pattern of surface warming recreate the spatial pattern of top-of-
450 atmosphere flux response to forcing more accurately than existing methods, as well as providing
451 better estimates of the change in feedback with time. The method consistently overestimates
452 the change in TOA flux over the Southern Ocean and north Atlantic, and so overestimates the
453 sensitivity. The method finds that that there are significant negative nonlocal feedbacks associated
454 with regions of tropical convection, and that the reduction in the share of warming that occurs
455 in these regions over time contributes to an increase in the global feedback with time in these
456 models, consistent with recent studies (Andrews and Webb 2017; Ceppi and Gregory 2017; Dong
457 et al. 2019; Fueglistaler 2019).

458 The MR method finds that five of the six AOGCMs have strongly positive local cloud feedbacks
459 countered by strongly negative nonlocal cloud feedbacks. These positive local feedbacks may
460 explain why studies that use local regressions to estimate spatial feedbacks from observed internal
461 variability find that they are on average positive (Brown et al. 2015; Trenberth et al. 2015). While
462 the AOGCMs exhibit an anti-correlation between local and nonlocal feedbacks, a small relative

463 shift in the balance between these feedbacks could cause large changes in sensitivity, and such
464 shifts may be relevant for paleoclimate or future warming. Given the large magnitudes associated
465 with these local and nonlocal cloud feedbacks, it may be harder for cloudy exoplanets to have
466 stable atmospheres, reducing the chances of finding habitable worlds.

467 Spatial feedbacks estimated from observations could potentially improve warming forecasts and
468 serve as emerging constraints on AOGCMs. The success of the MR method for most fluxes and
469 regions of the Earth (with the important exception of Southern Ocean cloud feedbacks) suggests
470 that many of the spatial feedbacks at work under global warming are observable under internal
471 variability. Challenges remain to applying the MR method to observations. We would need to
472 reduce the information necessary to fit our statistical model to be less than the length of the satellite
473 record; to remove changes in forcing from records of top-of-atmosphere fluxes; and to account for
474 systematic biases in the observations themselves. We would also need to account for regions of the
475 Earth and states of the climate where the MR method is biased, such as for Southern Ocean cloud
476 feedbacks. Furthermore, since spatial feedbacks are just one link in the coupled energy balance
477 of the climate, we would need complementary theory to complete the forecast of future warming,
478 particularly its spatial pattern. Still, our results suggest that the processes that will determine the
479 sensitivity in both the near and far future may be observable today.

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492 APPENDIX

493 **Data and methods**

494 *a. Data/code access*

495 For LongRunMIP data access, visit <http://www.longrunmip.org/>. This paper’s code is
496 available at <https://github.com/jsbj/spatial>.

497 *b. Matrix and vector notation*

498 Note that in the main body of the text, time is treated as continuous, so that time-series are
499 written as functions (e.g., $\vec{T}(t)$ is the evolving spatial pattern of warming). Since the Appendix
500 documents the calculations we have employed, it treats time as discrete, and so time is instead
501 treated as an additional dimension (e.g., \mathbf{T} is the evolving spatial pattern of warming). Therefore,
502 a vector in the main body of the text refers to a spatial pattern, while a vector in the Appendix
503 refers to a time-series of a scalar value (such as a global average).

504 *c. Conceptual model*

505 The conceptual model is a system of stochastic differential equations:

$$\begin{aligned} c_1 \frac{dT'_1}{dt} &= N'_1 - H' + F_{surf,1} \\ c_2 \frac{dT'_2}{dt} &= N'_2 + H' + F_{surf,2} \end{aligned}$$

506 where $H' = \gamma(T'_1 - T'_2)$ and

$$N'_1 = \lambda_{1,1}T'_1 + \lambda_{1,2}T'_2 + F_{CO_2,1} + F_{TOA,1} \quad (A1)$$

$$N'_2 = \lambda_{2,1}T'_1 + \lambda_{2,2}T'_2 + F_{CO_2,2} + F_{TOA,2} \quad (A2)$$

507 The thermal inertia c_i is defined as $m_i\rho c_p$, where ρ and c_p are the density and specific heat of
 508 ocean water respectively, and m_i is an equivalent mixed layer depth; m_1 is 50m, and m_2 is 1000m.
 509 $F_{CO_2,1} = F_{CO_2,2}$ are both 0 Wm^{-2} (8 Wm^{-2}) for the control (abrupt4x) simulation. $\lambda_{1,1} = 0.5$
 510 $\text{Wm}^{-2}\text{K}^{-1}$, $\lambda_{2,1} = -2 \text{ Wm}^{-2}\text{K}^{-1}$, $\lambda_{1,2} = \lambda_{2,2} = 0 \text{ Wm}^{-2}\text{K}^{-1}$, and $\gamma = 2 \text{ Wm}^{-2}\text{K}^{-1}$. The terms
 511 \vec{F}_{surf} and \vec{F}_{TOA} are white noise processes. In the example shown in Figure 2, the variance of $F_{surf,1}$
 512 and $F_{surf,2}$ is 40 Wm^{-2} and the variance of $F_{TOA,1}$ and $F_{TOA,2}$ is 5 Wm^{-2} , while for the example
 513 in Figure S1, the variance of $F_{surf,1}$ and $F_{surf,2}$ is 10 Wm^{-2} and the variance of $F_{TOA,1}$ and $F_{TOA,2}$
 514 is 15 Wm^{-2} .

515 *d. The multiple regression method*

516 Suppose that we have a time series of surface temperatures and TOA radiative fluxes of the
 517 Earth, real or simulated, where the surface of the Earth is regrided into n_{grid} (288) regions, and
 518 where we have n_{time} years of monthly observations. For each season s ($1 \leq s \leq 4$), we can define an
 519 $n_{time} \times n_{grid}$ matrix \mathbf{T}_m , where the element in row i and column j , $T_{i,j,s}$, is the surface temperature

520 in region j during season s of year i . We can also define a matrix of anomalies, \mathbf{T}'_s , where

$$\mathbf{T}'_s = \begin{bmatrix} T_{1,1,s} & T_{1,2,s} & \cdots & T_{1,n_{grid},s} \\ T_{2,1,s} & T_{2,2,s} & \cdots & T_{2,n_{grid},s} \\ \vdots & \vdots & \ddots & \vdots \\ T_{n_{time},1,s} & T_{n_{time},2,s} & \cdots & T_{n_{time},n_{grid},s} \end{bmatrix}$$

$$= \frac{1}{n_{time}} \begin{bmatrix} \sum_{i=1}^{n_{time}} T_{i,1,s} & \sum_{i=1}^{n_{time}} T_{i,2,s} & \cdots & \sum_{i=1}^{n_{time}} T_{i,n_{grid},s} \\ \sum_{i=1}^{n_{time}} T_{i,1,s} & \sum_{i=1}^{n_{time}} T_{i,2,s} & \cdots & \sum_{i=1}^{n_{time}} T_{i,n_{grid},s} \\ \vdots & \vdots & \ddots & \vdots \\ \sum_{i=1}^{n_{time}} T_{i,1,s} & \sum_{i=1}^{n_{time}} T_{i,2,s} & \cdots & \sum_{i=1}^{n_{time}} T_{i,n_{grid},s} \end{bmatrix}$$

521 To estimate the spatial feedbacks associated with a TOA radiative flux of type f (where f is
522 either *net*, *LW clear*, *SW clear*, *LW cloud*, or *SW cloud*) and season s , we first define an $n_{time} \times$
523 n_{grid} matrix of anomalies $\mathbf{R}'_{f,s}$, which is analogous to \mathbf{T}'_s above (N from the main body of the text
524 is R_{net}). We can fit the statistical model defined in Equation 9 using least squares to solve for
525 seasonal spatial feedbacks ($\Lambda_{f,s}$):

$$\Lambda_{f,s} = \begin{bmatrix} \lambda_{f,1,1} & \lambda_{f,1,2} & \cdots & \lambda_{f,1,n_{grid}} \\ \lambda_{f,2,1} & \lambda_{f,2,2} & \cdots & \lambda_{f,2,n_{grid}} \\ \vdots & \vdots & \ddots & \vdots \\ \lambda_{f,n_{grid},1} & \lambda_{f,n_{grid},2} & \cdots & \lambda_{f,n_{grid},n_{grid}} \end{bmatrix} = (\mathbf{T}'_s{}^T \mathbf{T}'_s)^{-1} \mathbf{T}'_s{}^T \mathbf{R}'_{f,s} \quad (\text{A3})$$

526
527 Seasonal feedbacks are used in Section 3, but Section 2 uses an annual version, in which case
528 instead of a set of four seasonal feedback matrices, only one feedback matrix estimated using the
529 above Equation d, with the difference that the time series are annual averages. The “monthly”
530 approach in Section 1.2.1 of the SI is the same as the seasonal approach in Equation d, except

531 instead of a four regressions, twelve are performed, with all time series being monthly averages
 532 sampled every twelve months. The “all months” approach instead performs only one regression,
 533 just like the annual approach, except that monthly average time series are used instead of annual
 534 averages (the logic being that even though months may have different properties, there may be an
 535 advantage in maximizing the data available to fit a regression).

536 *e. Estimating the forced response*

537 1) FORCED FEEDBACKS

538 Suppose that we have a $n_{time,abrupt4x}$ -year long abrupt4x simulation of a GCM for which we
 539 have spatial feedbacks estimated from a control run. We then define an early period (years 2 to 20)
 540 and a late period (years 21 to $n_{time,abrupt4x}$). The true feedbacks $\lambda_{f,p}$ for the abrupt4x simulation
 541 during each period p (where p is *early* or *late*) are defined as the slope of the least squares fit of
 542 the linear regression of the time series of globally averaged TOA flux anomalies of type f from
 543 the abrupt4x simulation ($\vec{R}'_{f,abrupt4x}$), against the globally averaged surface temperature anomalies
 544 from the abrupt4x simulation $\vec{T}'_{abrupt4x}$:

$$\lambda_{abrupt4x,f,p} = \frac{\{\vec{T}'_{abrupt4x}\}_p \cdot \{\vec{R}'_{f,abrupt4x}\}_p}{\|\{\vec{T}'_{abrupt4x}\}_p\|^2} \quad (\text{A4})$$

545 where the curly brackets denote that the time series are averaged over exponentially longer peri-
 546 ods, with annual averages for the first decade increasing to centennial averages by the simulation’s
 547 end, and the p subscript denotes whether values from before or after year 20 are used. $\vec{R}'_{f,abrupt4x}$
 548 and $\vec{T}'_{abrupt4x}$ are vectors with as many entries as years in the abrupt4x simulation (1000 years).

549 We can make estimates of these feedbacks using the MR method by first estimating the abrupt4x
 550 simulation’s TOA radiative flux of type f for each month of the year m by multiplying the surface

551 temperature time series of that abrupt4x simulation for that month, $\mathbf{T}'_{m,abrupt4x}$ (a $n_{time,abrupt4x} \times$
 552 n_{grid} matrix) by the spatial feedbacks for that month's season:

$$\hat{\mathbf{R}}'_{f,m,abrupt4x} = \mathbf{T}'_{m,abrupt4x} \Lambda_{f,s(m)} \quad (\text{A5})$$

553 We use months instead of seasonal averages because our seasons do not start in January, and
 554 this approach allows us to have annual averages that start in January. These monthly time se-
 555 ries $\hat{\mathbf{R}}'_{f,m,abrupt4x}$ can then be turned into annual averages $\hat{\mathbf{R}}'_{f,abrupt4x}$, and then global averages
 556 $\hat{\hat{\mathbf{R}}}'_{f,abrupt4x}$, allowing us to estimate the feedbacks for period p by performing the same least squares
 557 fit as above:

$$\hat{\lambda}_{abrupt4x,f,p} = \frac{\{\vec{T}'_{abrupt4x,p}\} \cdot \{\hat{\hat{\mathbf{R}}}'_{f,abrupt4x,p}\}}{\|\{\vec{T}'_{abrupt4x,p}\}\|^2} \quad (\text{A6})$$

558 2) SPATIAL PATTERNS OF TOA FLUX CHANGE

559 We quantify the normalized spatial pattern of TOA radiative flux change of flux type f across
 560 a period p by taking a finite difference approach, taking the mean value of $\vec{R}'_{f,abrupt4x}$ during two
 561 parts of the period and subtracting the first part from the second (where the divisions for the *early*
 562 period are years 2-6 and 7-20, and the divisions for the *late* period are 21-170 and 171- $n_{time,abrupt4x}$,
 563 with both divisions chosen to allow for substantial warming in each period), and then dividing this
 564 by the average change in the globally averaged surface temperature between these two periods:

$$\Delta \vec{R}'_{f,abrupt4x,p} = \frac{\left(\sum_{i=t_{mid,p}+1}^{t_{end,p}} \begin{bmatrix} R'_{f,abrupt4x,i,1} \\ R'_{f,abrupt4x,i,2} \\ \vdots \\ R'_{f,abrupt4x,n_{grid}} \end{bmatrix} - \sum_{i=t_{start,p}}^{t_{mid,p}} \begin{bmatrix} R'_{f,abrupt4x,i,1} \\ R'_{f,abrupt4x,i,2} \\ \vdots \\ R'_{f,abrupt4x,n_{grid}} \end{bmatrix} \right)}{\left(\sum_{i=t_{mid,p}+1}^{t_{end,p}} T_{abrupt4x,i} - \sum_{i=t_{start,p}}^{t_{mid,p}} T_{abrupt4x,i} \right)} \quad (\text{A7})$$

565 where $t_{start,p}$ and $t_{end,p}$ are the first and last years in period p , respectively, where $t_{mid,p}$ is 6 for
566 the early period and 170 for late period, where $R'_{f,abrupt4x,i,j}$ is the element in the i^{th} row and j^{th}
567 column of $\mathbf{R}'_{f,abrupt4x}$, and where $T_{abrupt4x,i}$ is the i^{th} element in $\vec{T}_{abrupt4x}$. Finite difference is used
568 instead of regressing values against a global average because the presence of local and nonlocal
569 feedbacks causes nonlinear relationships between $N'_i(t)$ and $T'_i(t)$ (or $\vec{T}'(t)$), which would lead to
570 biased estimates of change from a linear regression.

571 *f. Errors*

572 We calculate two types of errors: feedback errors (Tables 1 and S2), and spatial errors (Tables 2
573 and S3). We add a subscript g to our feedbacks and spatial patterns of TOA flux change to signify
574 that they belong to the GCM g , where g is one of CCSM3, CESM104, GISS2R, HadCM3L,
575 IPSLCM5A, and MPIESM12. The feedback error is given by the root mean square error:

$$\mathcal{E}_{feedback,f,p} = \sqrt{\frac{1}{n_{GCMs}} \sum_{g \in GCMs} (\hat{\lambda}_{f,abrupt4x,p,g} - \lambda_{f,abrupt4x,p,g})^2} \quad (\text{A8})$$

576 where n_{GCMs} is 6, the number of AOGCMs. The spatial error is measured by taking the area-
577 weighted root mean square error of the spatial estimate

$$\mathcal{E}_{spatial,f,p} = \sqrt{\frac{\sum_{i=1}^{n_{grid}} (\hat{\Delta \vec{R}}'_{f,abrupt4x,p,i} - \Delta \vec{R}'_{f,abrupt4x,p,i})^2 a_i}{\sum_{i=1}^{n_{grid}} a_i}} \quad (\text{A9})$$

578 where a_i is the area of the i^{th} grid cell. For the spatial errors in the main body of the paper, this is
579 taken on multi-model mean values of $\hat{\Delta \vec{R}}'_{f,abrupt4x,p,i}$ and $\Delta \vec{R}'_{f,abrupt4x,p,i}$. For the same calculation
580 for individual models (Table S4 and Figures S6-S8 in the supplementary materials), values for
581 each model are used instead.

582 *g. Other methods to calculate feedbacks*

583 We consider two other methods for deriving spatial feedbacks, estimating abrupt4x feedbacks,
584 and estimating spatial patterns of TOA flux change:

585 1) THE GLOBAL METHOD

586 The seasonal version of the “global” method used in the main body of the paper is estimated
587 using the least squares fit on this regression:

$$\lambda_{global,f,s} = \frac{\vec{T}'_s \cdot \vec{R}'_{f,s}}{\|\vec{T}'_s\|^2} \quad (\text{A10})$$

588 where \vec{T}'_s and $\vec{R}'_{f,s}$ are globally and seasonally averaged time series of control simulation surface
589 temperature and TOA flux f respectively, sampled every fourth seasonal value so that all elements
590 of the time series are from season s . The four seasonal feedbacks are used to recreate estimates of
591 the global averaged time series $\vec{R}'_{f,abrupt4x}$, which in turn is used, as above, to estimate abrupt4x
592 feedbacks. Once more, different averaging of the control time series and groupings of regression
593 equations can be used to make the annual, monthly, and all months versions of this method featured
594 in Tables S3 and S4.

595 The normalized spatial pattern of TOA flux change can be found by first estimating the “local
596 contribution” (Boer and Yu 2003a,b; Crook et al. 2011; Zelinka et al. 2012; Andrews et al. 2015),
597 using Equation 1, but replacing the time series vector $\vec{R}'_{f,s}$ with the spatial time series matrix
598 $\mathbf{R}'_{f,s}$ from above, and replacing the single feedback $\lambda_{global,f,s}$ with the spatial vector of feedbacks,
599 $\vec{\lambda}_{global,f}$.

600 2) THE LOCAL METHOD

601 The “local” method assumes the statistical model

$$R'_i(t) = \lambda_{local,i} T'_i(t) + \varepsilon(t) \text{ for each region } i \quad (\text{A11})$$

602 Spatial feedbacks are estimated using least squares:

$$\vec{\lambda}_{local,f} = \begin{bmatrix} \lambda_{local,f,1} \\ \lambda_{local,f,2} \\ \vdots \\ \lambda_{local,f,n_{grid}} \end{bmatrix} = \begin{bmatrix} \frac{\vec{T}'_1 \cdot \vec{R}'_{f,1}}{\|\vec{T}'_1\|^2} \\ \frac{\vec{T}'_2 \cdot \vec{R}'_{f,2}}{\|\vec{T}'_2\|^2} \\ \vdots \\ \frac{\vec{T}'_{n_{grid}} \cdot \vec{R}'_{f,n_{grid}}}{\|\vec{T}'_{n_{grid}}\|^2} \end{bmatrix} \quad (\text{A12})$$

603 where \vec{T}'_i and $\vec{R}'_{f,i}$ are the i^{th} rows of \mathbf{T}' and \mathbf{R}'_f respectively. We can then generate estimates of
 604 $\mathbf{R}'_{f,abrupt4x}$ as above. We apply these estimates to Equations A6 and A7 to estimate forced global
 605 feedbacks and spatial patterns of TOA flux change.

606 *h. Local regression*

607 We use LOESS (LOcally Estimated Scatterplot Smoothing; Cleveland and Devlin 1988) to take
 608 local regression of scatterplots of \bar{N} vs \bar{T}' . LOESS uses a weighted regression of a certain number
 609 of nearest neighbors, in our case 30. Full details can be found in the code for this paper listed
 610 above and in the LocallyWeightedRegression.jl Julia package (<https://github.com/juliohm/LocallyWeightedRegression.jl>).

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819 **LIST OF TABLES**

820 **Table 1.** *Feedback errors.* Root mean square errors of estimates of abrupt4x feedbacks
821 ($\lambda_{4x,early}$, $\lambda_{4x,late}$) and their change with time ($\Delta\lambda_{4x}$), for net TOA fluxes and
822 each component flux (in $\text{Wm}^{-2}\text{K}^{-1}$) and for the seasonal versions of the three
823 methods presented in Section 2 (see Appendix for details). For annual and
824 monthly values, see Table S2, and for fluxes north of 30°S , see Table S5. . . . 43

825 **Table 2.** *Spatial errors.* The model-mean area-weighted root mean square error of esti-
826 mates of the warming-normalized change in TOA fluxes during the early and
827 late periods of the abrupt4x simulations, and the change in pattern between
828 these period (see Appendix for details). All values have units of $\text{Wm}^{-2}\text{K}^{-1}$.
829 For annual and monthly versions in addition to seasonal, see Table S2, for in-
830 dividual models see Table S4, and for fluxes north of 30°S , see Table S6. . . . 44

831 TABLE 1. *Feedback errors.* Root mean square errors of estimates of abrupt4x feedbacks ($\lambda_{4x,early}$, $\lambda_{4x,late}$) and
832 their change with time ($\Delta\lambda_{4x}$), for net TOA fluxes and each component flux (in $\text{Wm}^{-2}\text{K}^{-1}$) and for the seasonal
833 versions of the three methods presented in Section 2 (see Appendix for details). For annual and monthly values,
834 see Table S2, and for fluxes north of 30°S , see Table S5.

	<i>net</i>			<i>LW clear</i>			<i>SW clear</i>			<i>LW cloud</i>			<i>SW cloud</i>		
	MR	global	local	MR	global	local	MR	global	local	MR	global	local	MR	global	local
early	0.69	0.74	2.54	0.08	0.12	0.63	0.18	0.48	1.21	0.13	0.23	0.02	0.45	0.55	1.19
late	0.29	0.26	1.87	0.15	0.21	0.47	0.13	0.52	1.09	0.31	0.35	0.17	0.2	0.6	0.65
change	0.44	0.73	0.78	0.12	0.17	0.22	0.08	0.11	0.18	0.19	0.13	0.17	0.39	0.57	0.64

835 TABLE 2. *Spatial errors*. The model-mean area-weighted root mean square error of estimates of the warming-
836 normalized change in TOA fluxes during the early and late periods of the abrupt4x simulations, and the change
837 in pattern between these period (see Appendix for details). All values have units of $\text{Wm}^{-2}\text{K}^{-1}$. For annual and
838 monthly versions in addition to seasonal, see Table S2, for individual models see Table S4, and for fluxes north
839 of 30°S , see Table S6.

	<i>net</i>			<i>LW clear</i>			<i>SW clear</i>			<i>LW cloud</i>			<i>SW cloud</i>		
	MR	global	local	MR	global	local	MR	global	local	MR	global	local	MR	global	local
early	1.02	3.41	2.77	0.33	2.29	1.02	0.7	5.23	2.15	0.82	1.09	0.71	1.05	5.15	2.25
late	0.8	3.08	1.86	0.34	2.27	0.75	0.52	5.13	1.67	1.28	1.21	1.03	1.09	5.1	1.85
change	0.74	1.14	1.26	0.27	0.91	0.42	0.54	0.72	0.83	0.84	0.79	0.79	1.01	1.27	1.37

840 **LIST OF FIGURES**

- 841 **Fig. 1.** A schematic representation of the conceptual model used in Section 2, consisting of an over-
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 843 perature T_1 has nonlocal effects: it increases the horizontal heat transport H , and it changes
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 858 c,d). The MR method, given sufficient years to regress over, correctly estimates all spatial
 859 feedbacks (dashed lines, panel b), accurately predicting the feedbacks and its change with
 860 time (green lines and markers, panels c,d). 48
- 861 **Fig. 3.** Plots of \bar{N} vs. \bar{T}' for control simulations of six coupled atmosphere-ocean general circulation
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 863 the global, local, and MR methods. We regrid simulations to $15^\circ \times 15^\circ$ grids, giving 288
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- 865 **Fig. 4.** \bar{N} vs. \bar{T}' for abrupt4x simulations of the same six GCMs from Figure 3 (black dots). Col-
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- 872 **Fig. 5.** True and estimated abrupt4x feedbacks as a function of time calculated using slopes of
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 874 between the early (2-20 years) and late (21-end) periods. Dots show true and estimated
 875 values of $\lambda_{4x,early}$ and $\lambda_{4x,late}$. Feedbacks get more positive over time for all models. The MR
 876 and global methods initially overestimate feedbacks. The MR estimate increases with time
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 879 the same plot for component fluxes. 51
- 880 **Fig. 6.** True vs. estimated feedbacks for the early (panels a, b, and c) and late (panels d, e, and f)
 881 periods and the change between them (panels g, h, and i). Black dots give values for the net
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 884 (red) feedbacks. The MR estimate of the late period has a small error across all components
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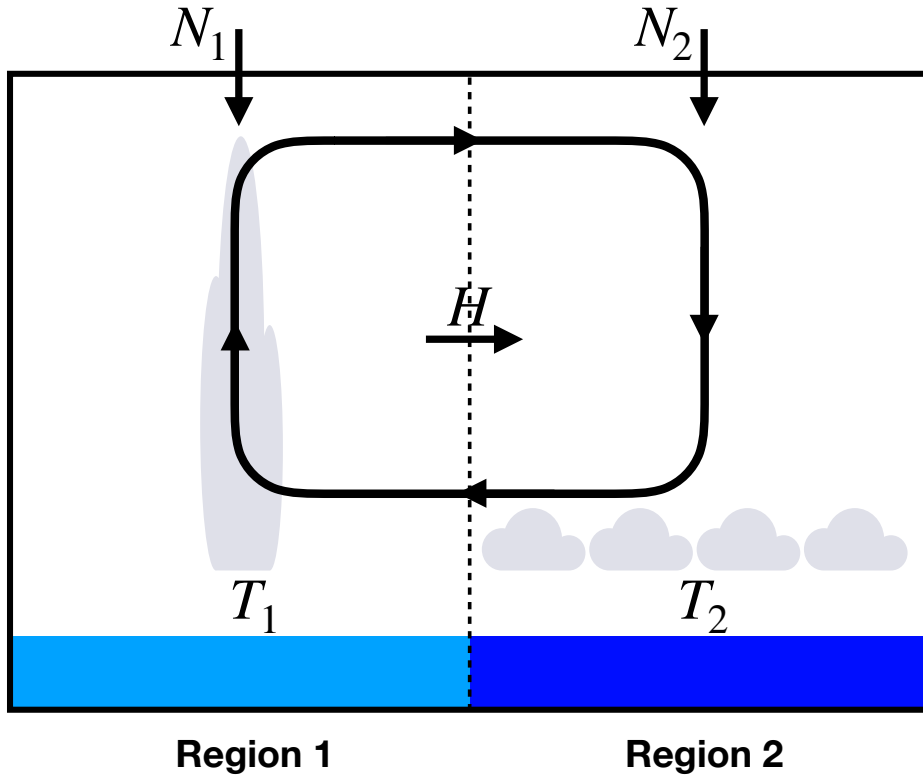
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 888 overestimates the net feedback, primarily due to cloud feedbacks. Numerical values of the
 889 feedbacks are given in Table S7 and S8. 52

890 **Fig. 7.** Multi-model mean spatial pattern of net TOA flux change associated with the early (top
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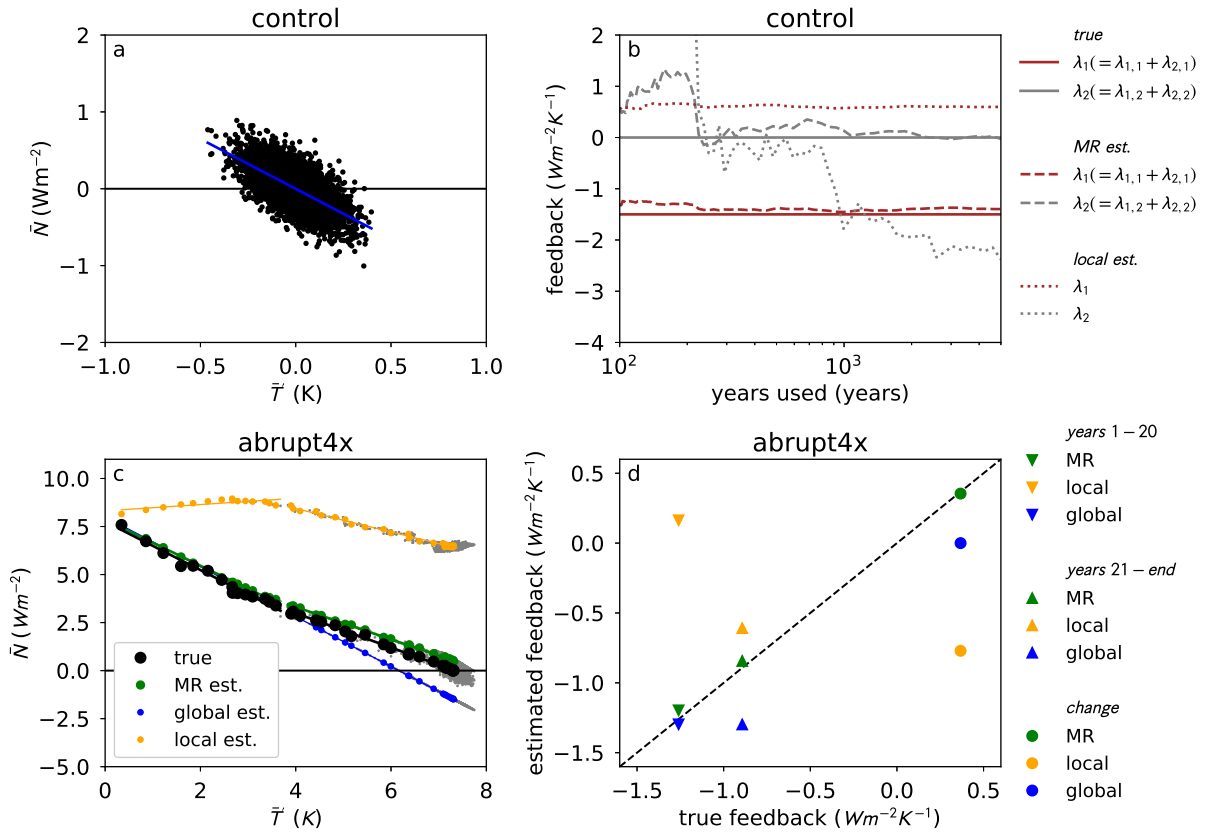
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907 **Fig. 9.** Multi-model and multi-season mean spatial feedbacks estimated by the MR method. Panel
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 913 and assessments of uncertainty, see Figures S18-S22. For spatial feedbacks of all methods,
 914 see Figure S23. Compare with estimates of spatial feedbacks for CAM4 in Figure 5c of
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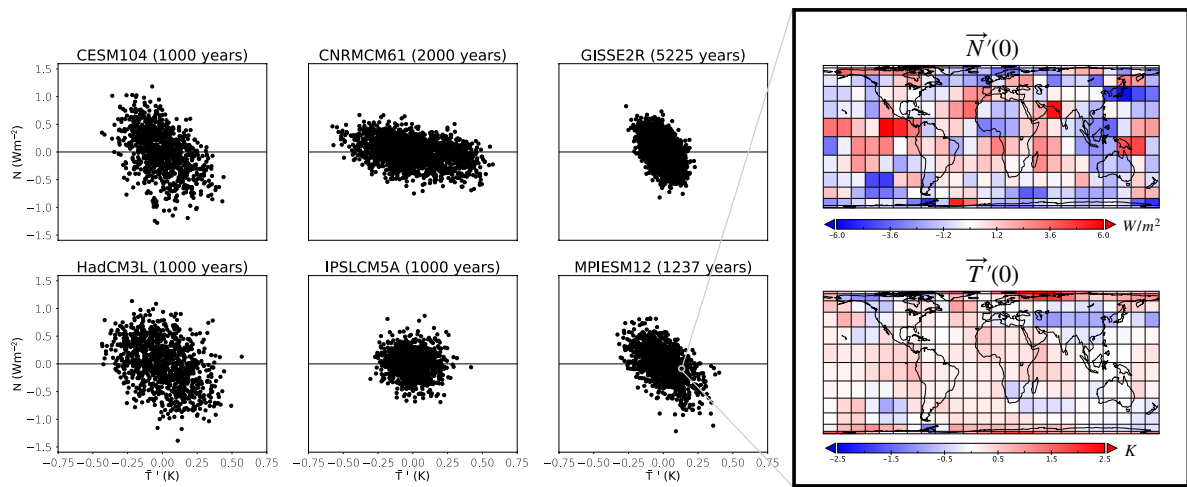
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 918 ing this pattern by MR-estimated spatial feedbacks gives an estimate of each grid cell's
 919 contribution to the change in feedback with time, $\Delta\lambda_{4x}$ (panels b-f). Although the resulting
 920 patterns are patchy, there are positive contributions from tropical convecting regions via the
 921 SW cloud and LW clear feedbacks, and from regions of Southern Ocean sea ice in the SW
 922 clear feedback, as shown by the accompanying zonal averages. The LW clear feedback has a
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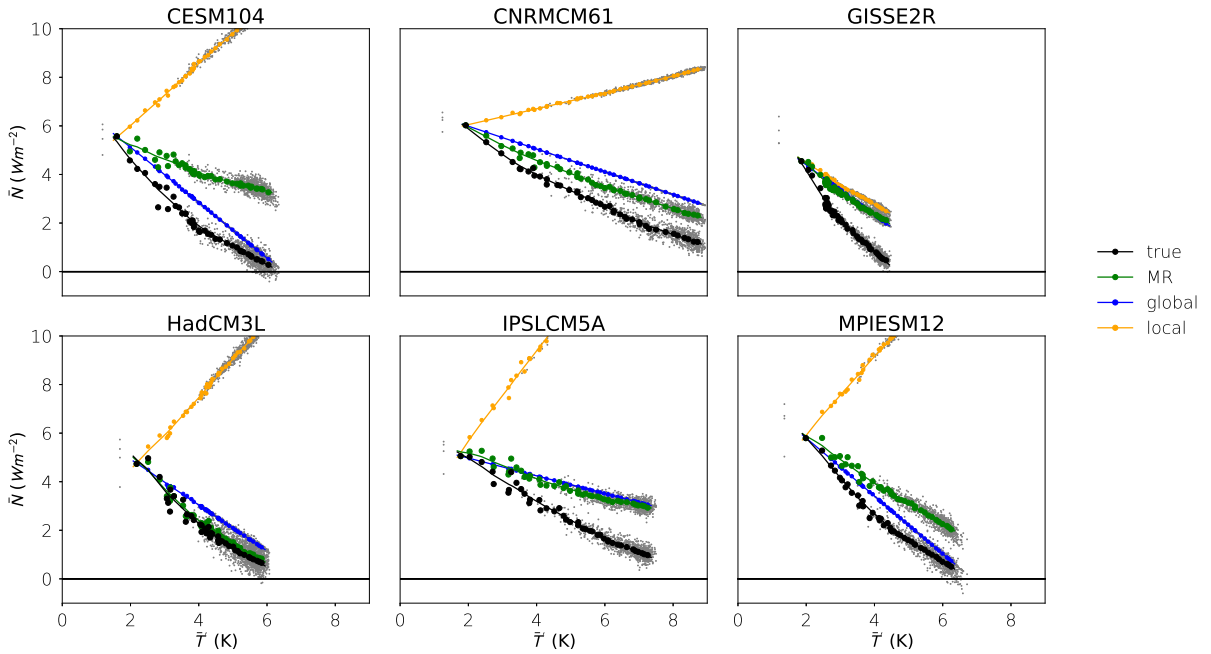
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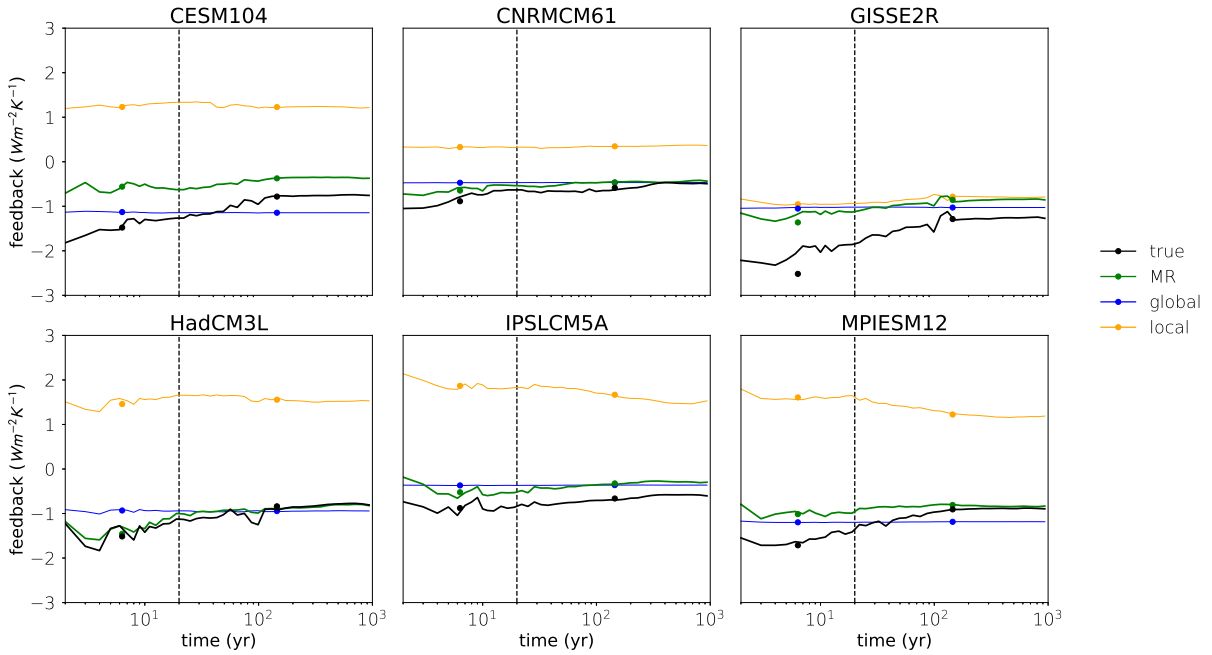
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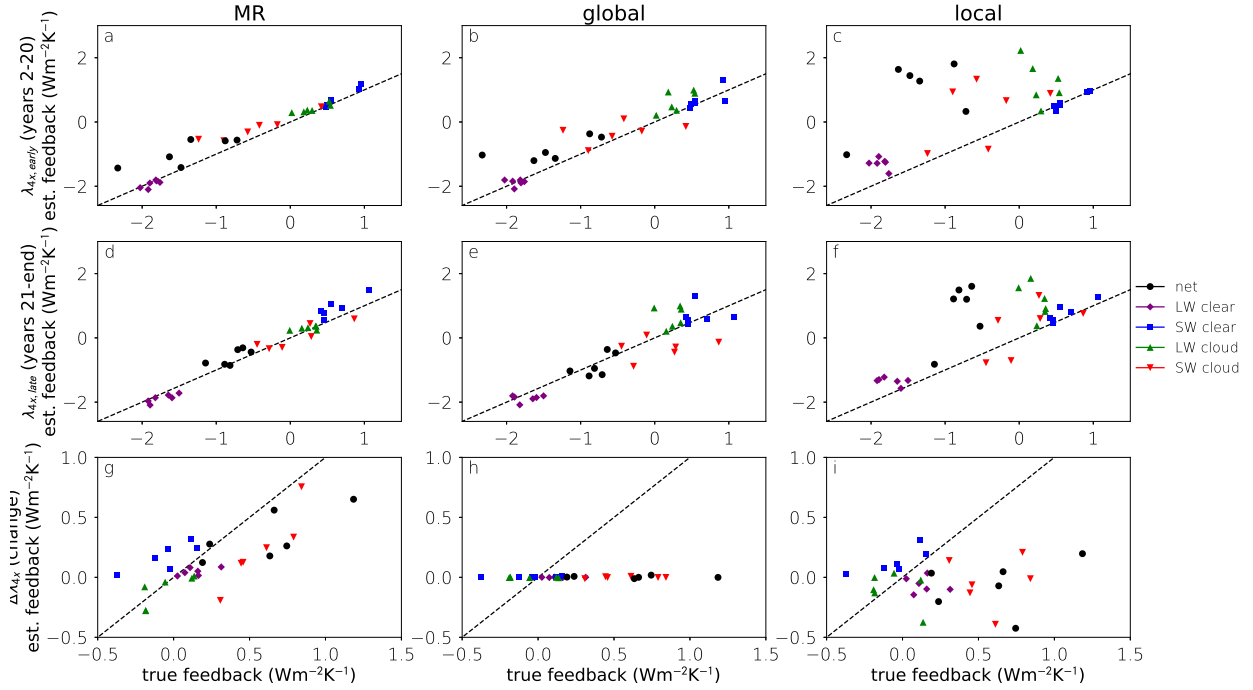
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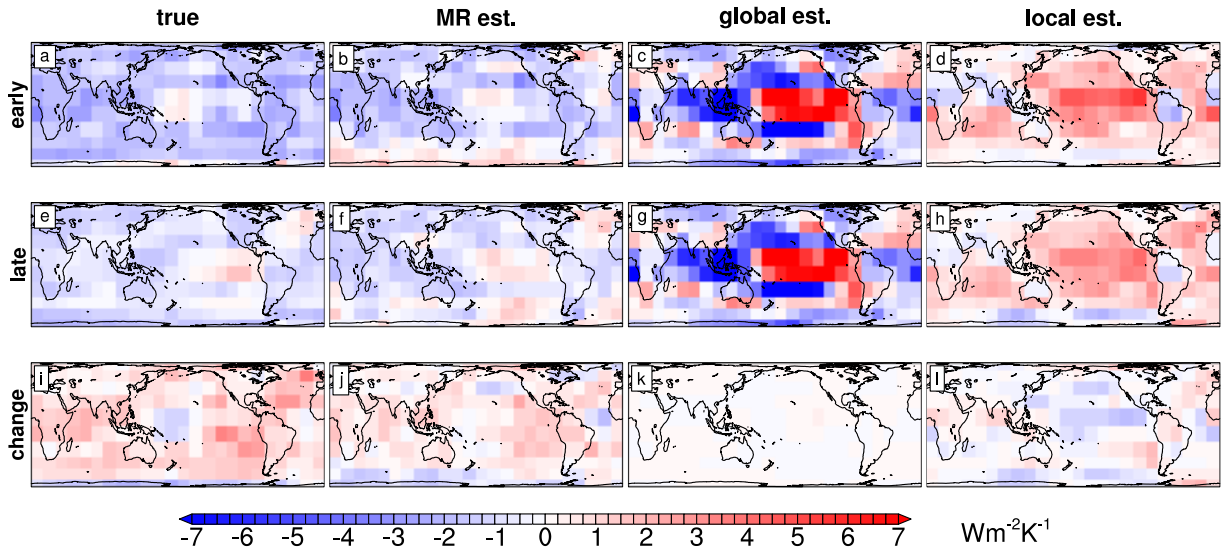
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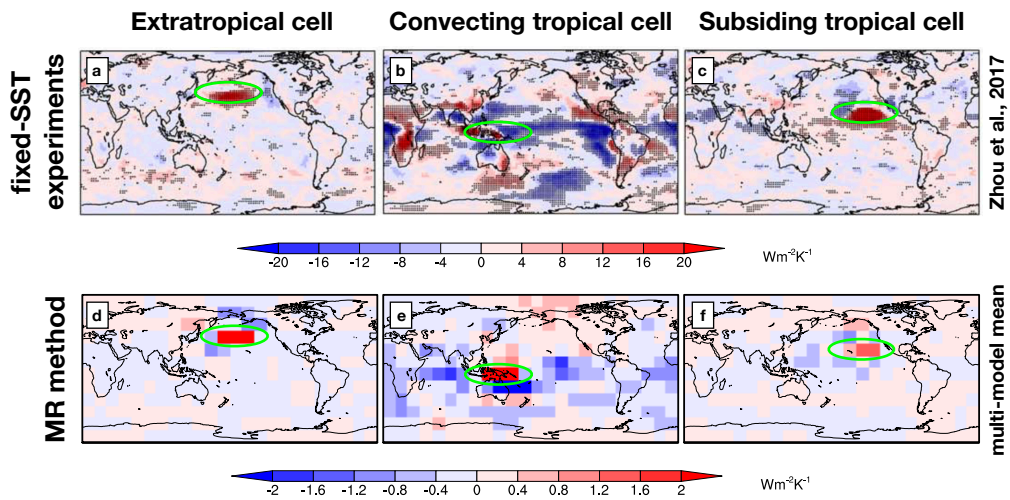
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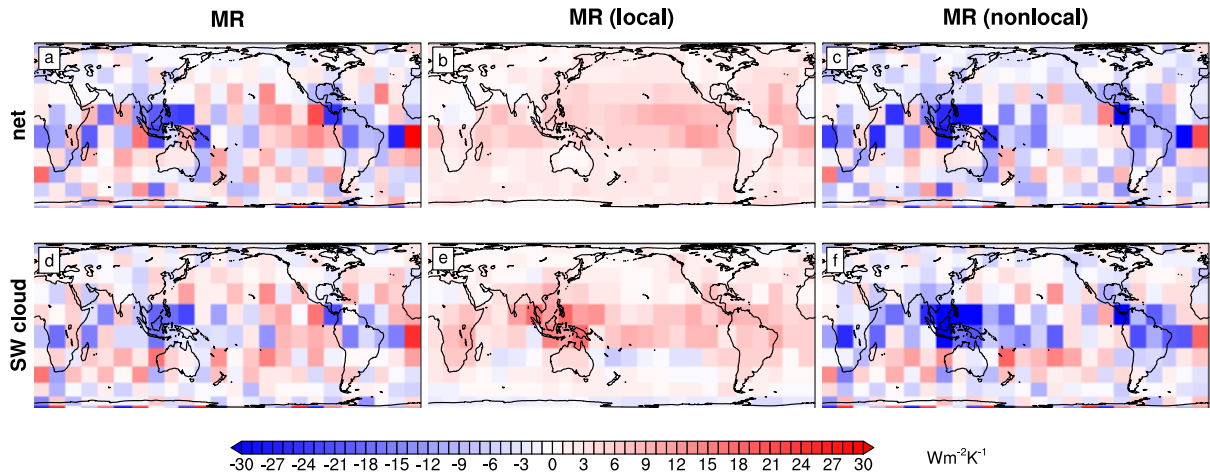
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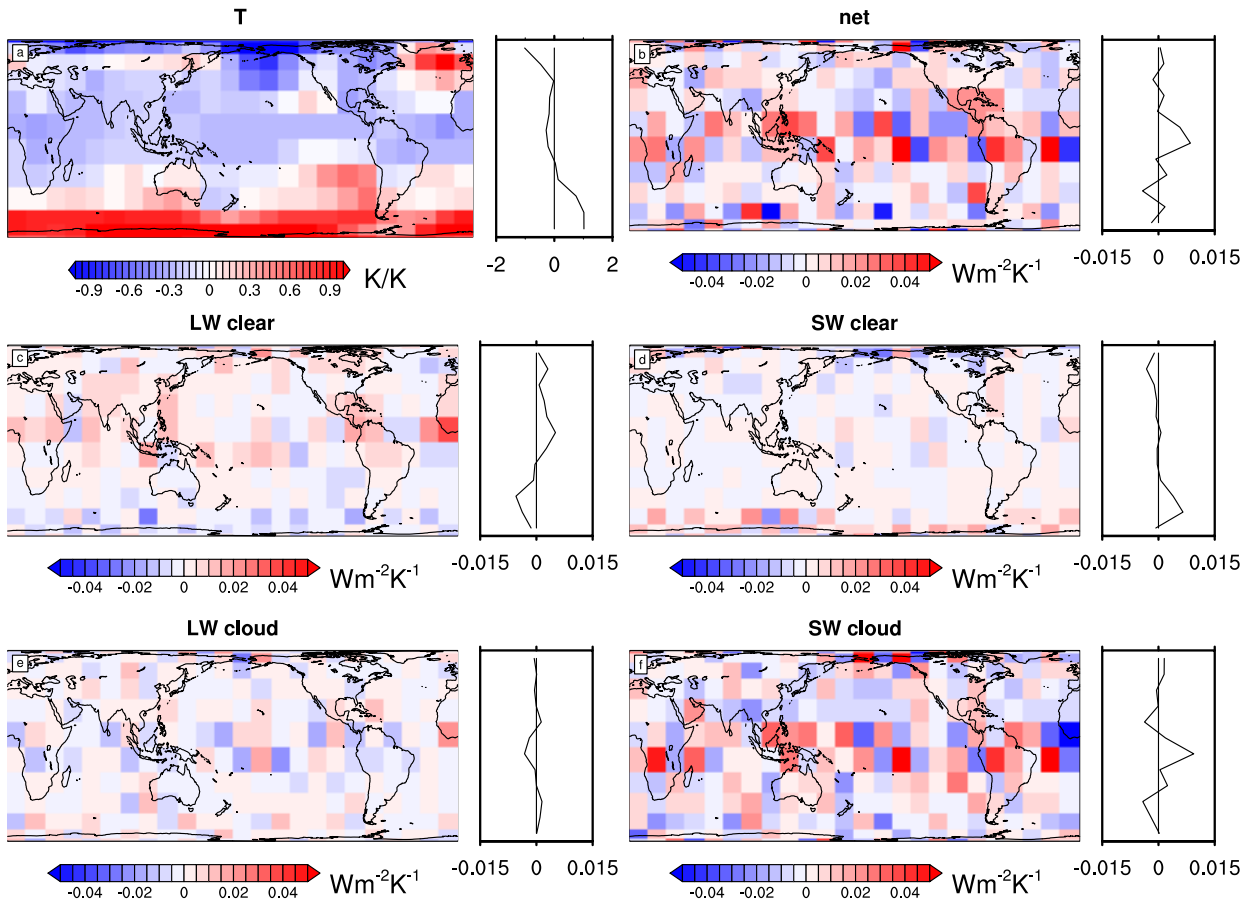
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