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BowSaw: inferring higher-order trait interactions associated with complex biological phenotypes

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Abstract

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Machine learning is helping the interpretation of biological complexity by enabling the inference and classification of cellular, organismal and ecological phenotypes based on large datasets, e.g. from genomic, transcriptomic and metagenomic analyses. A number of available algorithms can help search these datasets to uncover patterns associated with specific traits, including disease-related attributes. While, in many instances, treating an algorithm as a black box is sufficient, it is interesting to pursue an enhanced understanding of how system variables end up contributing to a specific output, as an avenue towards new mechanistic insight. Here we address this challenge through a suite of algorithms, named BowSaw, which takes advantage of the structure of a trained random forest algorithm to identify combinations of variables ("rules") frequently used for classification. We first apply BowSaw to a simulated dataset, and show that the algorithm can accurately recover the sets of variables used to generate the phenotypes through complex Boolean rules, even under challenging noise levels. We next apply our method to data from the integrative Human Microbiome Project and find previously unreported high-order combinations of microbial taxa putatively associated with Crohn's disease. By leveraging the structure of trees within a random forest, BowSaw provides a new way of using decision trees to generate testable biological hypotheses.

Introduction

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The production of large biological data sets with high-throughput techniques has increased the utilization of supervised machine learning algorithms to produce predictions of complex phenotypes (e.g. healthy vs. disease) from measurable traits. These algorithms use measurements of relevant traits such as gene variants, the presence/absence of microbial taxa, or metabolic consumption variables as predictors. Categorical prediction of phenotypes is typically the end goal of these applications. However, an additional benefit of these algorithms is the potential to extract explanatory classification rules. In this context, a rule is defined as a Boolean function of a set of traits, such that the value of the function is 1 (true) when the traits are associated with a given phenotype. Identifying the relationships between the traits involved in classification rules may yield key insights into the biological processes associated with important phenotypes [1, 2]. This realization is creating demand for methods that assist in the interpretation of supervised machine learning methods [3–5], especially when the measured traits may be causal agents of disease states, such as genetic variants or microbial taxa [6]. Identifying classification rules associated with a phenotype of interest is valuable because these rules are likely to carry information about the causal mechanisms that generate the phenotype. Algorithms that are particularly valuable in this respect are those involving decision trees, such as random forests, since decision trees are easily interpretable [7]. Decision trees are rule-based classifiers, where rules arise from a series of "yes-no" questions that can efficiently divide the data into categorical groups. In a biological

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context, such rules may arise from sets of genes whose simultaneous modulation could affect a phenotype, or sets of microbial species whose co-occurrence may be associated with a disease state. While in several cases it seems like disease phenotypes are uniquely associated with a single specific pattern (e.g. retinoblastoma [8]), there is increasing evidence for cases in which multiple distinct patterns can be associated with (and potentially causing) the same high-level phenotype [9, 10]. A particular example we will explore in this work is the multiplicity of distinct microbial presence/absence patterns which may be associated with Crohn's disease [11]. Crohn's disease has five clinically defined sub-types [12] but studies of the associated microbiome do not usually indicate which form of Crohn's disease a donor has been diagnosed with. Each sub-type of the disease may be associated with different microbes, each requiring different treatment regimes. Thus, identifying rules associated with sub-populations within a given phenotype label are of great interest due to potential therapeutic implications. The fact that there may be multiple etiologies that generate the same or similar phenotypes complicates the straightforward interpretation of parameter coefficients or variable importance scores [13, 14]. Uncovering the multiple interactions between predictive variables as they relate to phenotypic labels remains a challenging statistical endeavor, but one that is of paramount importance. Identifying the associated rules that a random forest uses to classify a given sample as having a particular disease enables the development of mechanistic hypotheses for follow up-studies. This challenge, and an overview of the key strategy we propose, are illustrated in Figure 1. In figure 1A we depict a toy model where measured variables (traits) have only two possible values (e.g.:

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present/absent), the high-level phenotype (category) is binary (e.g.: no disease/disease), and two distinct Boolean rules can both generate the phenotype. The goal in this case is to identify each of the rules that are associated with the phenotype. The multiple Boolean rules obtained in this manner can be thought of as a consensus decision tree that possesses the most informative branches of the forest with respect to a given class label. In this work, we will show how this can be achieved by in-depth analyses of any given random forest (RF) (Fig. 1B). The random forest algorithm intrinsically takes advantage of non-linear relationships between variables and is widely used in the life sciences [15–17]. RFs, when used to distinguish between disease states known to have multiple causes, often result in excellent classifiers [18, 19]. It has also been reported that RFs capture subtle statistical interactions between variables [13]. Unfortunately, an RF is not straightforwardly interpretable despite its hierarchical structure, and recovering those interactions is notoriously difficult [14] due in large part to the method's reliance on ensembles of trees [20]. The difficulties in interpretation created by these properties has led many to refer to RF as a 'black box' model [21]. Identifying the rules that a RF utilizes in classification tasks is an active area of research, and many strategies have been developed to address this problem. Effective strategies have focused on evaluating how individual variables influence the classification probabilities of specific samples [22, 23], pruning existing decision rules found in the tree ensemble to produce compact models [24], computing conditional importance scores [25], or iteratively enriching the most prevalent variable co-

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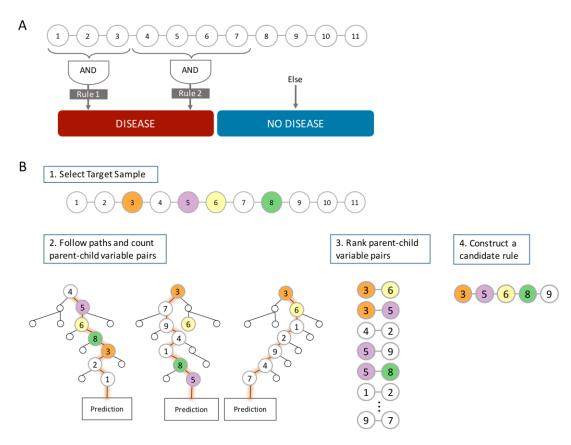
occurrences through regularization [26]. These approaches offer valuable methods for the identification of statistical interactions between variables. However, we and others have observed that while these methods are capable of recovering a true causal rule in simulated data when exactly one such rule is present, the existence of multiple rules associated with one phenotype can confound interpretation efforts [26].

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Here we describe BowSaw, a new set of algorithms that utilizes variable interactions in a trained RF model in order to extract multiple candidate explanatory rules. With BowSaw, we set out to develop a post hoc method intended to aid in the discovery of these rules when the input variables are categorical in nature. The primary approach of BowSaw is to start by approximating a best combination of variables (i.e. a rule) that explain the forest's predictions for individual instances of a given class in the data set and then to curate the collection of best combinations to obtain a concise set of combinations that collectively segregate a class of interest with high precision. For individual instances a rule is identified by systematically quantifying the co-occurrence of specific variable pairs across trees in the forest that attempt to predict the class of the instance (out-of-bag trees) and then using the frequency of co-occurring variable pairs to guide the construction of a rule that precisely identifies the instance as its observed class. For the entire set of instances, we then curate the collection of all rules identified this way in order to produce a small set of rules that are broadly and precisely applicable to instances of the given class label.

We first demonstrate that BowSaw can recover true rules by applying the algorithms to simulated data sets of varying complexity. We then apply BowSaw to a

study on the role of the gut microbiome on Crohn's disease [11], and show that it can find a previously unreported combination of microbial taxa that is broadly and precisely associated with Crohn's disease instances in the data set. In its current implementation BowSaw can be applied to any dataset with categorical or discrete predictors with any number of class labels.



A In a hypothetical dataset there may be two phenotype labels — "Disease" and "No Disease", that we wish to discriminate based on input predictor variables. In this example, there are two distinct high-order patterns that both confer the "Disease" phenotype. Our goal is to identify a potentially diverse set of patterns (or, in this simplified case, all patterns) that are associated with the "Disease" label. B Conceptual pipeline of BowSaw. In (1) we begin by identifying the vector of a target instance that has the target observed label. In this example, the colored nodes indicate a true associated pattern, which is unknown to us. In (2) we follow the path of the instance through each of its out-of-bag trees and record how often the sample encounters sequential pairs of variables. (3) Each ordered pair sequence is sorted in descending order by its observed

frequency. (4) Starting from the top of the list, pair sequences are iteratively evaluated and added to an undirected network of variables (i.e. a candidate rule) until this network is maximally associated with the observed phenotype of the target vector or the list of ordered pairs is exhausted. Each sample with the label of interest yields one such candidate rule. These rules are then aggregated and curated to obtain a concise set of rules that explain class-specific classification decisions that occur in the forest.

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Methods

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Overview of the pipeline

Provided with a trained random forest and a training set, BowSaw goes through three steps in order to generate a candidate rule (variable-value combination) for each observation associated with the phenotype of interest. First, for a specific observation, the Count algorithm counts the frequency of unique ordered pairs of variables encountered along each of its out-of-bag trees in the forest (Figure 1B – step 2). Second, for that observation, the Construct algorithm takes the counts from the first step and generates a list of ordered pairs, ranked by their frequencies, then uses this list as a guide to construct a candidate decision rule (which could consist of two or more variables) that is maximally associated with the observed phenotype (Figure 1B – steps 3 - 4). Finally, the Curate algorithm pools the candidate decision rules from each observation together in order to select a subset of rules that collectively account for all of the samples with the desired phenotype (Figure 1B – step 5). Optionally, the Sub-rule algorithm can be used to generate pruned versions of candidate rules prior to applying the Curate algorithm in order to obtain a more concise, albeit less specific, set of candidate rules. The Count and Curate algorithms generate the candidate rules for individual observations while the

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Curate and Sub-rule algorithms produce a combined set of rules that account for all observations with the chosen phenotype. In the following section, we provide a description of the inputs BowSaw takes and the algorithms that implement these steps along with pseudocode. Inputs BowSaw takes as inputs a dataset, **D**, composed of N observed vectors x_i (together with their respective classes k_i) each of p categorical variables. There are assumed to be K possible class labels for each vector in **D** which for the purposes of this discussion denote different phenotypes. A random forest is assumed to be trained on **D** to distinguish the classes k = 1, ..., K. Additionally, BowSaw takes as input the feature vector x_i of a specific observation for which the goal is to identify a set of simplified rules associated with the phenotype k_i . **Counting stubs** Given an RF machine **M** trained on dataset **D** and a feature vector $\mathbf{x} = (x_1, x_2, ..., x_p) \in$ D, the first sub-routine of our method (the count algorithm) proceeds as follows. It starts by identifying among the set of trees in M, those sub-paths (sequences of successive variable indices) encountered by sample x as it travels through M_x , its set of out-of-bag trees. An out-of-bag tree is a tree for which x was not included in the training set. For a specific path P in M_x the sequence of successive variable indices forms a vector v = $(v_1, ..., v_r)$ (note that each v_i is one of the variables x_i). Each stub (ordered pair of

- sequentially encountered variables $v_i v_{i+1}$ in all out-of-bag along **P** for i = 1, ... r-1 is
- accounted for in a $p \times p$ matrix C^x , where the element C^x_{ij} records the number of stubs
- containing the ordered pair of variables x_i and x_j among all paths of M_x .

Algorithm 1: Count Algorithm Pseudocode

- 178 Initialize C^x as a $p \times p$ matrix of zeros.
- For each path P with feature indices v in M_x do:

180 For
$$i = 1, ..., r - 1$$
,

$$C_{v_i,v_{i+1}}^x = C_{v_i,v_{i+1}}^x + 1$$

- End loop
- 183 End loop

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184 Return *C*^{*x*}.

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- For simplicity, henceforth we will denote $C = C^x$, remembering that C continues to
- depend on the fixed sample x.

Constructing a candidate rule

- 189 A rule for classifying to a test point x will have the form " $x_I = a_I$ implies x is in class
- 190 k". Here I is a designated subcollection of the variable indices i = 1, ..., p, and $x_I =$
- 191 $(x_{i_1}, ..., x_{i_{|I|}})$ is the sub-vector of current vector $\mathbf{x} = (x_1, ..., x_p)$ corresponding just to the
- indices $i_j \in I$. The vector $\mathbf{a}_I = \left(a_{i_1}, \dots, a_{i_{|I|}}\right)$ will denote an assigned set of values to the
- 193 x_i , i.e., so that $x_i = a_i$ for $i \in I$. Thus the condition $x_I = a_I$ means assignment of values

194 to x_i for $i \in I$. The rule is that if training vector x satisfies $x_I = a_I$, we classify x into 195 category k. 196 197 The second sub-routine (the construct algorithm) builds a candidate rule **R**, based 198 (initially) on a fixed training point, say $a \in D$, in class k. This is done by first placing all 199 of the stubs (i, j) with non-zero counts C_{ij} into a list L sorted in descending order by their values in **C**. 200 201 202 We define the candidate rule R (based on a) through the following steps. We initialize using the first stub $L_1 = (i_1, j_1)$ in the list **L**, together with the two fixed values $x_{i_1} =$ 203 a_{i_1} , $x_{j_1} = a_{j_1}$. This is the initialized form of the rule **R**, which requires that for any test 204 205 vector, its values at the above indices i_1 and j_1 match the values 206 of the above fixed training vector $\mathbf{a} \in \mathbf{D}$, so that $x_{i_1} = a_{i_1}$, and $x_{i_2} = a_{i_2}$. For brevity, denote the pair $(i_1, j_1) = I_1$ and the corresponding assigned values as $(a_{i_1}, a_{j_1}) = a_{I_1}$. 207 Then the content of rule **R** will be denoted succinctly as $\mathbf{R}: x_I = a_I \Rightarrow \text{class } k$. Since 208 209 ordering of the indices i_1, j_1 does not matter, (as long as the indices are identified), we 210 will henceforth write $(i_1, i_2) \rightarrow \{i_1, i_2\}$. 211 We then update rule **R** as follows. We find all $x \in D$ that satisfy the initial part of rule **R**, i.e., $x_I = a_I$ i.e., all training points matching the two indices $\{i_1, j_1\}$ of training sample a, 212 213 and store them as a subcollection $D_1 \subset D$ of the training set. We call F the fraction of data points in D_1 that have phenotype k, i.e., match the phenotype of the initial sample 214 215 $a \in D$. If F = 1, we stop and return the current above rule R. If F < 1, we continue by

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If F = 1:

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choosing the second stub $L_2 = \{i_2, j_2\}$ in the above list L, and augment the current rule Rby adding the condition $x_{i_2}=a_{i_2}$, $x_{j_2}=a_{j_2}$ (again written $x_{I_2}=a_{I_2}$) and maintaining the 218 assignment of class k (i.e., the same class as the currently fixed sample $a \in D$). If the second stub L_2 happens to overlap with the initial stub L_1 , this added condition in the rule 219 220 **R** will clearly be consistent, being still based on the fixed sample **a**. We augment the 221 current index list I_1 to a list I_2 , adding to it the two new indices i_2 and j_2 , so that now $I_2 = \{i_1, j_1, i_2, j_2\}$ writing the augmented rule as $R: x_{I_2} = a_{I_2} \Rightarrow \text{class } k$. Again 222 223 defining F to be the fraction of the data subset \mathbf{D}_2 (matching the more restrictive new 224 rule **R**) with phenotype k, we stop the algorithm and use the current rule **R** if F = 1, and 225 otherwise augment rule **R** by adding the indices $L_3 = (i_3, j_3)$ to it, as above, yielding a 226 larger set I_3 of indices and the augmented rule R: $x_{I_3} = a_{I_3} \Rightarrow \text{class } k$, with a more restricted subset $D_3 \subset D$, and a new value for F, now the fraction of D_3 in the class k of 227 228 the fixed $a \in D$. 229 This process continues until the fraction F = 1, i.e., 100% of the samples in **D** match the 230 current set of indices, and also match the class k of the current sample a. Alternatively, 231 the algorithm stops when all stubs in \boldsymbol{L} have been exhausted. 232 233 Algorithm 2: Construct Algorithm Pseudocode 234 Make ranked list *L* of stubs from *C* Initialize fixed $\mathbf{a} \in \mathbf{D}$, $\mathbf{R} = \phi \mathbf{I} = \phi$, $\mathbf{F} = 0$, 235 236 For i = 1: |L|, select stub L_i

238 Exit loop 239 Else: 240 $I' = \{I \cup L_i\}$ $D_{I'} = \{x \in D: x_{I'} = a_{I'}\}$ 241 $F' = \frac{|\{x \in D_{I'}: \operatorname{class} x = k\}|}{|D_{I'}|}$ 242 If F' > F: 243 I = I'244 F = F'245 246 End loop 247 Return I, F, D_I [all corresponding to the fixed $a \in D$]. Return rule \mathbf{R} : $x_I = a_I \Rightarrow \text{class } k$ 248 249 250 **Curating candidate rules:** 251 The *count* and *construct* algorithms are the heart of BowSaw. In our workflow, 252 we apply these algorithms to each observation $a \in D$ that has the desired observed phenotype k. We call the set of these vectors $\mathbf{D}^k \subset \mathbf{D}$. By default, we produce a single 253 candidate rule for each vector in $\mathbf{a} \in \mathbf{D}^k$. We store each candidate rule in list \mathbf{Q} and rank 254 255 them by their respective values of |I|, i.e., the number of indices in the respective rules. 256 Since **Q** may include many redundant rules, we developed another sub-routine (the *curate* 257 algorithm) to generate a concise set of candidate rules that collectively account for all data vectors \mathbf{D}^k in class k. Briefly, we initialize an empty list \mathbf{E} , to which we add the top 258

259 ranked rule from Q (by default this is the rule with the greatest value of |I|), and record 260 the index of samples in D that match any rule in E and also have the desired observed 261 phenotype class k, into a set A. Next, we determine how many samples remain unaccounted for, i.e. are in $U = D^k \sim A$, Then we determine which of the remaining rules 262 263 in Q minimizes |U|, add it to E, and repeat these steps until U is an empty set. 264 265 Algorithm 3: Curate algorithm pseudocode 266 Q = ranked list of all candidate rules for Φ_t $E = Q_{best}$ (user defined, default is maximum M) 267 268 I^* = which **D** match any rule in **E** and $k = K_d$ $A = D^k \cap M^*$ 269 $U = D^k - A$ 270 271 While U is not empty: 272 $\boldsymbol{B} = \{ \}$ 273 For rule i in O: 274 $E*=E+Q_i$ 275 I^* = which **D** match any rule in E^* and $k = K_d$ $A* = D^k \cap I*$ 276 $B_i = |U - A^*|$ 277 278 End loop

best = which min B_i

 $E = E + Q_{best}$

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 M^* = which **D** match any rule in **E** and $k = K_d$

 $A = \mathbf{D}^{k} \cap \mathbf{M}^{*}$

283 U = U - A

284 End while loop

Return **E**

Constructing sub-rules

Since rules are rarely 100% associated with any given phenotype, we devised a strategy for selecting a set of candidate sub-rules that account for all samples with desired observed phenotype class k. Candidate sub-rules are shorter candidate rules derived from larger candidate rules by omitting one or more variables. For each candidate rule in E, we identify sub-rules that meet a user-defined complexity criteria, e.g. only produce sub-rules that are composed of three or four variables and their corresponding values. We place each of the unique sub-rules into a new list E_{sub} . Then the corresponding number of identical matches, I, and proportion of I that have the phenotype K_d , F, are determined. At this stage, we can apply our third sub-routine (the Curate algorithm) to E_{sub} to obtain a parsimonious list of sub-rules that accounts for \mathbf{x}_{all} . In our pipeline, we also choose thresholds based on desired levels of I and/or F in order to eliminate poor candidate sub-rules from consideration. In this study, we decided on the thresholds after visually inspecting a plot of F against I.

Algorithm 4: Sub-rule algorithm pseudocode

303 $E_{sub} = \{ \}$ 304 *Complexity* = {user defined numeric values} 305 For *rule* in *E* 306 For *i* in *Complexity* $Esub = E_{sub} \cup (\frac{rule}{i})$ 307 308 End loop 309 End loop 310 311 The algorithms described above are generalizable to multi-classification tasks but 312 are currently limited to discretized or categorical representations of the feature space. 313 Pseudocode for implementing each of the algorithms described above along with an 314 implementation of the algorithms in R [27] can be found in the supplemental files and on 315 github: https://github.com/ddimucci/BowSaw. 316 317 318 **Results** 319 **Application to simulated Data** 320 To test the capacity of BowSaw to recover multiple decision rules, we applied it 321 to increasingly challenging simulated data sets. These data set consists of binary vectors 322 representing different observations. The phenotype associated with each observation is a 323 function of the corresponding vector. The function consists of a set of multiple mutually 324 distinct Boolean rules, such that if a rule is satisfied, it will cause the observation to have

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ranging involving anywhere from two to five variables, which resulted in unique 50,034

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BowSaw produced 176 unique candidate rules involving between six to thirteen

variables. From this list we generated 68,938 sub-rules and chose an association threshold

of 75% because there are two clusters at $\sim |I| = 125$ that begin to clearly separate in that

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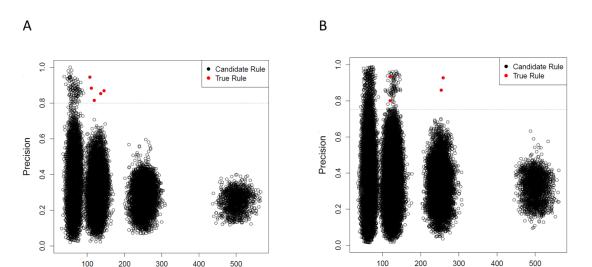
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range and the two outlier points at $\sim |I| = 250$ do not combine to account for all of the phenotype (Figure 3B). Applying the curate algorithm to the rules meeting this threshold produced 20 candidate sub-rules the top four (when ranked by |I|) of which were true rules. The rule of five variables was not recovered. These results show that BowSaw is able to recover strongly associated patters (and in this case, causal patterns) even in the presence of noise, but low prevalence rules can be masked by high prevalence rules. We used the same data generation method to investigate BowSaw's ability to produce candidate rules containing true rules when the underlying parameters change. We applied BowSaw to 20,000 simulated data sets where we randomly altered the number of features, sample size (200 or 2,000 samples), complexity of the rules, number of rules, the likelihood of each rule assigning the phenotype, and the background noise. We identified scenarios where rule recovery with BowSaw performs very well and situations in which it fails to recover any rules at all. Additionally, we found a strong linear relationship between BowSaw's performance measured as the average fraction of rules recovered and the of number of samples, number of features, and two evaluation metrics for RF model – the area under the curve for both the receiver operator characteristic and precision recall curves (Figure S1).



Matching Samples

A Precision of candidate sub-rules against the number of exactly matching samples for the ideal scenario. Each point represents a unique sub-rule. X-axis is the number of samples that exactly match the pattern defined by the rule. Y-axis is the fraction of matching samples with the observed phenotype (i.e. precision of the rule). Each cluster of points corresponds to decreasing rule complexity from 5 variables per rule to 2 on the right most cluster. These clusters appear because the values of each variable is produced by an identical binomial distribution. Dashed line is the precision threshold we set. Only candidate rules with precision above this threshold were considered for the curate algorithm. Red points are the causative sub-rules we defined. BowSaw correctly identified all five red points in this scenario. B Candidate sub-rules generated for the more challenging scenario. We defined 5 causative rules of varying lengths in this scenario and allowed 2% of samples without a causative rule to be assigned the label. BowSaw completely 4 of the causative rules (red points). The longest rule which involved 5 variables was not recovered.

Application to Human Microbiome Data

Matching Samples

Irregular distributions of microbial taxa within the gut are often associated with serious illnesses such as Crohn's disease or ulcerative colitis [28, 29]. Human microbiome studies regularly use 16s sequencing methods and extensive reference databases to report on microbial taxa found in samples as operational taxon units (OTUs). RF classifiers are frequently built using counts of OTUs to accurately discriminate

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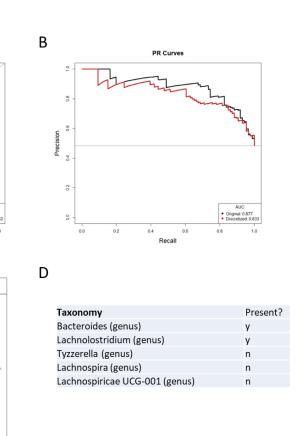


Figure 3

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ROC Curves

A Performance of the random forest classifier as measured by area under the receiver operator curve (ROC-AUC) is not strongly perturbed by simplifying OTU representation to a presence/absence scheme versus the original continuous count. Dashed line indicates the performance of a perfectly random classifier. B The area under the curve of the precision recall curve is similarly not strongly affected by the new representation scheme. Dashed horizontal line is the random performance line. C Each point represents a unique candidate sub-rule. On the x-axis is the number of samples in the data matrix that are subject to that rule. The y-axis represents what fraction of matching samples were diagnosed as Crohn's disease. D The taxon identities of the OTUs that make up the most generally applicable of the sub-rules where all matching samples have the Crohn's disease label.

Table 1 Association rules identified by BowSaw that account for all Crohn's disease samples.

Discussion

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Interpretation of random forest models for classification may be confounded when there are multiple rules (combinations of variables and their specific values) associated with a phenotype of interest. We have developed BowSaw, which is an algorithmic approach for identifying the rules that a trained random forest model uses to make classifications when the values are categorical in nature. By taking advantage of the structure of trees found within a random forest, BowSaw produces a set of multiple decision rules that combine to account for each sample with a given observed phenotype. When the variables are the presumed causal agents, these rules represent plausible mechanistic relationships. Results on simulated data demonstrate that when there are multiple rules associated with a single phenotype label that BowSaw is capable of faithfully identifying them. Application to data from the human microbiome project offers further evidence that BowSaw provides an efficient way of generating plausible hypotheses for high through put metagenomics studies. In particular we identified a rule that utilizes a presence/absence pattern of five microbial taxa (present: bacteroides, lachnoclostridium, absent: lachnospira, lachnospiracea, tyzerrella) that accounts for nearly half of all Crohn's disease samples in the cohort (38/86). This specific pattern of microbial colonization in the guts of Crohn's disease patients is unreported, but each taxon's respective enrichment or depletion status and association with disease status has been reported. If the cohort of patients in the human microbiome study are representative of all people afflicted by Crohn's disease then this rule represents a significantly large sub-set

of those suffering. Inquiries into the relationship of the taxa included in this rule with

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disease status may yield important insights into the mechanisms of the disease and potential therapeutic strategies for this sub-population. Of the five associated taxa, we suspect that the absence of lachnospira, lachnospiracea UCG 001, and tyzzerella are biologically meaningful. We have reason to believe so because it has been reported that the *lachnospiraceae* family is generally suppressed in Crohn's disease [32–34]. Lachnospira has been reported as depleted with respect to Crohn's disease several times [35, 36]. The depletion of tyzzerella has been associated with chronic intestinal inflammation and supplementation suggested as a probiotic for Crohn's disease [37, 38]. While the relationship of *lachnospiracea UCG 001* with Crohn's disease is still unclear, its depletion has been reported in mice displaying symptoms of anhedonia and it was significantly enriched in anhedonia resilient mice [39]. Partly because IBD is frequently accompanied by depression, anhedonia has been suggested as an important symptom in the diagnosis of IBD [40]. The associations of the individual OTUs defined by this rule are consistent with previously reported findings in the existing literature and describe a taxonomic profile that exclusively identifies a large sub-population of Crohn's disease samples within this cohort. The presence of *bacteroides* does not appear to be particularly useful and in this context is probably preserved because it causes a perfect association, although high levels of some species are implicated in the pathology of Crohn's disease [41]. Lachnoclostridium, is differentially distributed across the three classes. Notably it is less frequently detected in ulcerative colitis relative to Crohn's and non-IBD samples, which roughly resemble one another. Increased levels of this genus was detected in rats

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that showed relief of colitis symptoms after treatment with a proposed therapeutic agent [42]. The current implementation of the algorithms are restricted to classification tasks with categorical predictor values, this is a challenge that we will need to address in order to make the approach more generally applicable. Future work will also focus on extending these for the interpretation of regression models. Such additions will greatly increase the number of systems to which we can apply BowSaw. Acknowledgments We are grateful to members of the Segrè lab for helpful discussions and for feedback on the manuscript. DS and DD acknowledge funding from the Defense Advanced Research Projects Agency (Purchase Request No. HR0011515303, Contract No. HR0011-15-C-0091), the U.S. Department of Energy (DE-SC0012627), the NIH (T32GM100842, 5R01DE024468, R01GM121950 and Sub P30DK036836 P&F), the National Science Foundation (1457695), the Human Frontiers Science Program (RGP0020/2016), and the Boston University Interdisciplinary Biomedical Research Office. DD is grateful to Dr. Nisha Rajagopal for her patience in conversations about random forests and her valuable insight.

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