Two-breather solutions for the class I infinitely extended nonlinear Schrödinger equation and their special cases

M. Crabb and N. Akhmediev

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Abstract We derive the two-breather solution of the class I infinitely extended nonlinear Schrödinger equation. We present a general form of this multi-parameter solution that includes infinitely many free parameters of the equation and free parameters of the two-breather components. Particular cases of this solution include rogue wave triplets, and special cases of 'breather to soliton' and 'rogue wave to soliton' transformations. The presence of many parameters in the solution allows one to describe wave propagation problems with higher accuracy than with the use of the basic NLSE.

Keywords Infinitely extended NLSE \cdot breathers \cdot rogue waves

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1 Introduction

The nonlinear Schrödinger equation [1,2] (NLSE) has various applications in describing ocean waves [3,4,5], pulses in optical fibres [6,7,8], Bose-Einstein condensates [9,10,11,12], waves in the atmosphere [13], plasma [14] and many other physical systems [15,16,17,18,19]. Various extensions of the NLSE have been considered [20,21,22] that increase the accuracy of description of nonlinear wave phenomena in these systems by incorporating higher order effects [23,24,26,25]. Higher-order terms in these extensions are responsible for linear dispersion, as well as nonlinear effects such as self-phase modulation, pulse self-steepening, the Raman effect,

M. Crabb

Optical Sciences Group, Research School of Physics and Engineering, The Australian National University, Canberra, ACT, 2600, Australia. E-mail: matthew.crabb@anu.edu.au

and so on [7,27]. These higher-order terms are important in nonlinear optics [28,29], ocean wave dynamics [30,31,32] and especially in modelling high-amplitude rogue wave phenomena [33,34,35].

Adding higher-order terms generally results in the loss of integrability of the resulting equation. This means that exact solutions cannot be written in analytical form, making the treatment more complicated. However, a special choice of the higher-order operators in these extensions allows us to keep the integrability. The power of using these operators consists in the possibility of applying arbitrary real coefficients to each of these operators, thus significantly extending the range of physical problems that can be solved in exact form. It was found that the NLSE can be extended to arbitrarily high orders of these operators [36,37,38], and these operators have been explicitly presented up to eighth order [37]. Using their recurrence relations, they can be calculated to any order, although the explicit form quickly becomes cumbersome. Nevertheless, there are no conceptual difficulties in construction of these equations. Moreover, infinitely many terms can be considered when finding solutions of these equations.

Presently, there are two sets of these operators that can be used for infinite-order extensions of the NLSE. We call them the class I [36,37,38] and class II [39,40] infinite extensions of the NLSE [41]. The presence of two independent extensions enables the more accurate description of physical problems with greater flexibility. Here, we deal exclusively with the class I extension. The class II extension is more involved, and will be left beyond the scope of the present work.

In this paper, we find two-breather solutions of the class I infinitely extended NLSE equation. These are multi-parameter solutions that involve both the free parameters of the equation, and free parameters of the solution, which together control the features of the two breathers, such as their localisation, propagation, and their relative position and frequencies. The presence of an infinite number of free parameters allows us to consider many particular cases, such as breather-soliton conversion, which is exclusive to higher-order extensions of the basic equation.

We also derive several limiting cases, the most important one of which is the general second-order rogue wave solution, a particular case of the two-breather collision. However, only a limited number of special cases can be given in the frame of a single manuscript. We leave others for future work in this direction.

2 The class I infinitely extended NLSE

First, we give a brief exposition of the class I infinitely extended nonlinear Schrödinger equation. It is the integrable equation written in general form [36,37]

$$i\psi_x + F(\psi, \psi^*) = 0, (1)$$

where the operator $F(\psi, \psi^*)$ is defined through

$$F = \sum_{n=1}^{\infty} (\alpha_{2n} K_{2n} - i\alpha_{2n+1} K_{2n+1}), \tag{2}$$

with the operators K_n defined recursively by the integrals of the nonlinear Schrödinger equation [36], and where each coefficient α_n is an arbitrary real number; that is,

$$K_n(\psi, \psi^*) = (-1)^n \frac{\delta}{\delta \psi^*} \int p_{n+1} dt,$$

where p_n is the *n*-th integral of the basic nonlinear Schrödinger equation, and p_{n+1} can be defined recursively as

$$p_{n+1} = \psi \frac{\partial}{\partial t} \left(\frac{p_n}{\psi} \right) + \sum_{r=1}^n p_{n-r} p_r, \ p_1 = |\psi|^2.$$

The four lowest order operators K_n (n = 2, 3, 4, 5) derived in this way are:

$$K_{2}(\psi, \psi^{*}) = \psi_{tt} + 2|\psi|^{2}\psi,$$

$$K_{3}(\psi, \psi^{*}) = \psi_{ttt} + 6|\psi|^{2}\psi_{t},$$

$$K_{4}(\psi, \psi^{*}) = \psi_{tttt} + 8|\psi|^{2}\psi_{tt} + 6|\psi|^{4}\psi + 4\psi|\psi_{t}|^{2} + 6\psi_{t}^{2}\psi^{*} + 2\psi^{2}\psi_{tt}^{*}.$$

$$K_{5}(\psi, \psi^{*}) = \psi_{tttt} + 10|\psi|^{2}\psi_{ttt} + 10(\psi|\psi_{t}|^{2})_{t} + 20\psi^{*}\psi_{t}\psi_{t} + 30|\psi|^{4}\psi_{t}.$$
(3)

A few others can be found in [38]. The operators K_n involve linear terms with derivatives of order n, and nonlinear terms involving t-derivatives of the function

 ψ and its complex conjugate ψ^* .

As already mentioned, the numbers α_n can take any values whatsoever, and do not need to be viewed as representing small perturbations for the equation (1) to be completely integrable. This allows us to find solutions for which any order of dispersion can be taken into account without the need for approximation or numerical techniques. This extension substantially widens the range of applicability of the NLSE for solving nonlinear wave evolution problems.

When only $\alpha_2 \neq 0$, we have the fundamental, or 'basic' nonlinear Schrödinger equation:

$$i\psi_x + \alpha_2 K_2(\psi, \psi^*) = i\psi_x + \alpha_2(\psi_{tt} + 2|\psi|^2\psi) = 0,$$
 (4)

which includes the lowest-order dispersion and self-phase modulation terms. Further, if only α_2 and α_3 are nonzero, we have the integrable Hirota equation [42]:

$$i\psi_x + \alpha_2(\psi_{tt} + 2|\psi|^2\psi) - i\alpha_3(\psi_{ttt} + 6|\psi|^2\psi_t) = 0.$$
 (5)

Adding the fourth-order operator, K_4 , into Eq.(5), gives the Lakshmanan-Porsezian-Daniel (LPD) equation [43, 44], and so on.

Again, the coefficients α_n are finite and arbitrary. However, physical applications, in general, require dispersive effects to decrease rapidly in strength with increasing order n. Convergence will thus not be an issue in practice for series involving α_n , and we will therefore be comfortable leaving the operator F for the whole equation (1), as well as any other associated parameters, in the form of an infinite series when necessary.

While the operators K_n in (3) rapidly become more complicated and the resulting differential equation of order n becomes much harder to solve, exact solutions can be found explicitly by using already known solutions to the NLSE as a guide, and a large class of breather and soliton solutions are already known [37, 38]. In previous works [37,38], we have seen that the effect of nonzero odd order operators is to transform t as $t \mapsto t + vx$ with v being a function of all coefficients α_{2n+1} . The effect of the nonzero even order operators is to transform x as $x \mapsto Bx$, with x being a function of the parameters x

In this work we extend this approach to a general family of second-order solutions, so we introduce parameters B_1 and B_2 , and v_1 and v_2 , to play an analogous role for the two distinct breather components. This enables us to generalise the two-breather to the infinite extension of the NLSE, and we now proceed to the analysis of these solutions.

3 The 2-breather solution

Higher analogues of the Akhmediev breathers can be obtained through iterations of the Darboux transformation [45,46]. After transforming the plane wave solution e^{ix} with a Darboux transformation, with an eigenvalue λ such that $\lambda^2 \neq -1$, and repeating this transformation twice, we get the 2-breather solution to the basic NLSE. This can then be generalised to the 2-breather solution of the extended equation. The general 2-breather solution is of the form

$$\psi(x,t) = \left\{1 + \frac{G(x,t) + iH(x,t)}{D(x,t)}\right\} e^{i\phi x},\tag{6}$$

where

$$G(x,t) = -(\kappa_1^2 - \kappa_2^2) \left\{ \frac{\kappa_1^2 \delta_2}{\kappa_2} \cosh \delta_1 B_1 x \cos \kappa_2 t_2 - \frac{\kappa_2^2 \delta_1}{\kappa_1} \cosh \delta_2 B_2 x \cos \kappa_1 t_1 - \frac{\kappa_1^2 - \kappa_2^2}{\kappa_2^2} \cosh \delta_1 B_1 x \cosh \delta_2 B_2 x \right\},$$
(7)
$$H(x,t) = -2(\kappa_1^2 - \kappa_2^2) \left\{ \frac{\delta_1 \delta_2}{\kappa_2} \sinh \delta_1 B_1 x \cos \kappa_2 t_2 - \frac{\delta_1 \delta_2}{\kappa_1} \sinh \delta_2 B_2 x \cos \kappa_1 t_1 - \delta_1 \sinh \delta_1 B_1 x \cosh \delta_2 B_2 x + \delta_2 \cosh \delta_1 B_1 x \sinh \delta_2 B_2 x \right\},$$
(8)
$$D(x,t) = 2(\kappa_1^2 + \kappa_2^2) \frac{\delta_1 \delta_2}{\kappa_1 \kappa_2} \cos \kappa_1 t_1 \cos \kappa_2 t_2 + 4\delta_1 \delta_2 \times (\sinh \delta_1 B_1 x \sinh \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sinh \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sinh \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sinh \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sinh \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sinh \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sinh \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_1 t_2) - (\sinh \delta_1 B_1 x \sin \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_1 t_2) - (\sinh \delta_1 B_1 x \cos \delta_1 t_1 \cos \delta_2 t_2) - (\sinh \delta_1 B_1 x \cos \delta_1 t_1 \cos \delta_2 t_1 \cos \delta_1 t_1 \cos \delta_1 t_1 \cos \delta_1 t_1 \cos \delta_1 \cos$$

$$D(x,t) = 2(\kappa_1^2 + \kappa_2^2) \frac{1}{\kappa_1 \kappa_2} \cos \kappa_1 t_1 \cos \kappa_2 t_2 + 4\delta_1 \delta_2 \times \\ \times (\sinh \delta_1 B_1 x \sinh \delta_2 B_2 x + \sin \kappa_1 t_1 \sin \kappa_2 t_2) - \\ - (2\kappa_1^2 - \kappa_1^2 \kappa_2^2 + \kappa_2^2) \cosh \delta_1 B_1 x \cosh \delta_2 B_2 x - \\ - 2(\kappa_1^2 - \kappa_2^2) \left\{ \frac{\delta_1}{\kappa_1} \cosh \delta_2 B_2 x \cos \kappa_1 t_1 - \\ - \frac{\delta_2}{\kappa_2} \cosh \delta_1 B_1 x \cos \kappa_2 t_2 \right\},$$
(9)

Here κ_1 and κ_2 are the modulation parameters,

$$\delta_m = \frac{1}{2}\kappa_m \sqrt{4 - \kappa_m^2}$$

is the growth rate of the modulational instability for each breather component, and the shorthand notation t_m indicates $t_m = t + v_m x$ for m = 1, 2. Note that whenever t_m appears, we have ignored a constant of integration, and we have also done the same whenever $\delta_m B_m x$ appears. The most general solution allows for the replacements $t_m \mapsto t_m - T_m$, and $\delta_m B_m x \mapsto \delta_m B_m (x - X_m)$, where T_m and X_m are real constants which determine relative positions along the axes of t and t, respectively, which we might include to incorporate a time delay in one breather component, for instance. For the time being, we set these constants to

be both zero without substantial loss, to address their significance later.

The phase factor ϕ is independent of the modulation, since this part has no physical effect on the modulation when it is real, and here it takes the same real value as it does for the plane wave solution, i.e.

$$\phi = \sum_{n=1}^{\infty} {2n \choose n} \alpha_{2n}. \tag{10}$$

The values B_m determine the modulation frequency of each component, and the parameters v_m , although they cannot be considered velocities in the usual sense, introduce a tilt to $|\psi|$ relative to the axes of x and t. They are given explicitly by

$$B_m = \sum_{n=1}^{\infty} {2n \choose n} nF(1-n,1; \frac{3}{2}; \frac{1}{4}\kappa_m^2) \alpha_{2n},$$
 (11)

$$v_m = \sum_{n=1}^{\infty} {2n \choose n} (2n+1) F(-n,1; \frac{3}{2}; \frac{1}{4} \kappa_m^2) \alpha_{2n+1}, \quad (12)$$

with m=1,2, where F(a,b;c;z) is the Gaussian hypergeometric function. Note that there is a simple relationship between v_m and B_m : the coefficient of α_{2n} in B_m is twice the coefficient of α_{2n-1} in v_m . The first two terms of B_m for the two-breather solution have been previously given in [47]. Our new solution extends these coefficients to arbitrary orders of dispersion and nonlinearity.

Also notice that the parameters are the same functions of κ_m , for both m=1,2. This is at least suggested by symmetry. If two successive Darboux transformations generate a 2-breather solution, then there must be two independent eigenvalues, corresponding to two independent modulation parameters. Physically, we could reason that there should be no way of knowing which breather component is which, so the order in which each component was generated by Darboux transformation should be equally irrelevant. If so, it should then follow that B_1 is the same function of κ_1 as B_2 is of κ_2 , and similar for v_1 and v_2 . It is worth considering whether this property extends to the general n-breather solution: i.e. whether, in general, we can find B_1, \ldots, B_n and v_1, \ldots, v_n which are the same functions of their respective modulation parameters $\kappa_1, \ldots, \kappa_n$, but we do not answer this question here.

The growth rate δ_m in both components will be real when κ_m is real, but the eigenvalues of the Darboux transformation are free to take any complex value at all, although the transformations are trivial when the eigenvalues are real, and thus so are the modulation parameters. Real-valued modulation parameters correspond to Akhmediev breathers, whereas imaginary-valued modulation parameters correspond to Kuznetsov-Ma solitons, the functional form of the breathers being otherwise equivalent. An example which shows the difference between real and imaginary modulation parameters is given in Fig. (2). In Fig. (3) we give an example of the effects of altering the ratio of the modulation of the two components.

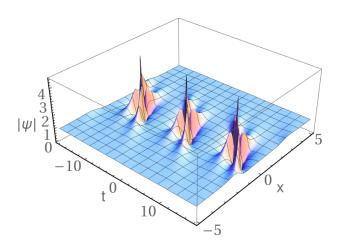


Fig. 1: The 2-breather solution (6) of Eq.(1). The modulation parameters are at a ratio $\kappa_1: \kappa_2 = 1: 2$. Parameters of the equation are: $\alpha_2 = \frac{1}{2}$, $\alpha_3 = \frac{1}{6}$, $\alpha_4 = \frac{1}{24}$, $\alpha_5 = \frac{1}{30}$, $\alpha_6 = \frac{1}{144}$, with all higher $\alpha_n = 0$. The wave profile is tilted in the (x,t)-plane due to the nonzero v_m .

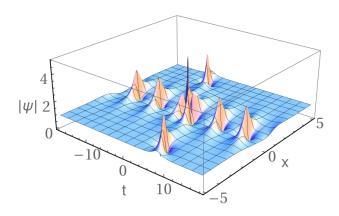


Fig. 2: A collision between an Akhmediev breather and Kuznetsov-Ma soliton, with $\kappa_1 = 1$, and $\kappa_2 = i$. Here $\alpha_n = 1/n!$ up to n = 8, with all higher $\alpha_n = 0$.

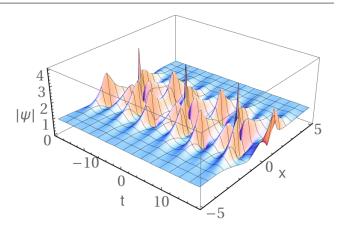


Fig. 3: The 2-breather solution with $\alpha_n = 1/n!$ up to n = 8, with all higher $\alpha_n = 0$, but now with $\kappa_1 = \frac{3}{2}$, and $\kappa_2 = 1$.

4 Breather-to-soliton conversion

If we choose parameters α_n such that $B_m = 0$, the 2-breather solution may then behave in a way which is unique to the extension of the nonlinear Schrödinger equation [47], in the sense that it is only when higher orders of dispersion and nonlinearity are accounted for that it is possible to take $B_m = 0$ without obtaining a trivial or otherwise degenerate solution.

For example, if we choose α_2 such that $B_2=0$ for all κ_2 , then writing $B_1=B$, it is easy to show that B must take the value

$$B = \sum_{n=1}^{\infty} \binom{2n+2}{n+1} (n+1) E\left(-n,1; \frac{3}{2}; \frac{1}{4} \kappa_1^{\ 2} | \frac{1}{4} \kappa_2^{\ 2}\right) \alpha_{2n+2},$$

where we define the function E as the difference of hypergeometric functions:

$$E(a, b; c; z_1|z_2) = F(a, b; c; z_1) - F(a, b; c; z_2).$$

We can then simplify the general 2-breather solution considerably. We obtain

$$G(x,t) = (\kappa_1^2 - \kappa_2^2) \left\{ \frac{\kappa_1^2 \delta_2}{\kappa_2} \cosh \delta_1 Bx \cos \kappa_2 t_2 - \frac{\kappa_2^2 \delta_1}{\kappa_1} \cos \kappa_1 t_1 - (\kappa_1^2 - \kappa_2^2) \cosh \delta_1 Bx \right\},$$

$$H(x,t) = 2\delta_1(\kappa_1^2 - \kappa_2^2) \sinh \delta_1 Bx \left(1 - \frac{\delta_2}{\kappa_2} \cos \kappa_2 t_2\right),$$

$$D(x,t) = 2(\kappa_1^2 + \kappa_2^2) \frac{\delta_1 \delta_2}{\kappa_1 \kappa_2} \cos \kappa_1 t_1 \cos \kappa_2 t_2 + 4\delta_1 \delta_2 \sin \kappa_1 t_1 \sin \kappa_2 t_2 - (2\kappa_1^2 - \kappa_1^2 \kappa_2^2 + \kappa_2^2) \cosh \delta_1 Bx - 2(\kappa_1^2 - \kappa_2^2) \left(\frac{\delta_1}{\kappa_1} \cos \kappa_1 t_1 - \frac{\delta_1}{\kappa_1} \cos \kappa_1 t_1 - \frac{\delta_1}{\kappa_1}$$

$$-\frac{\delta_2}{\kappa_2}\cosh\delta_1 Bx\cos\kappa_2 t_2\bigg). \tag{13}$$

An example of this solution is given in Fig. 4. The difference of this solution from the one shown in Fig. 1 is that the wave profiles at $x \to \pm \infty$ are not plane waves. The periodic set of tails from each breather maximum extends to infinity, reminiscent of periodically repeating solitons. This is the phenomenon that is known as 'breather to soliton conversion' [47]. Clearly, these 'solitons' do not have a separate spectral parameter related to them.

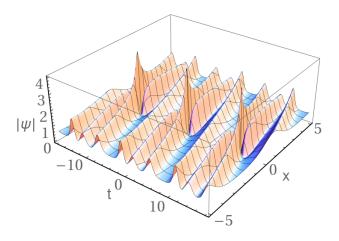


Fig. 4: A wave profile of a 'breather to soliton conversion'. We use the same set of parameters as in Fig. 3, except α_2 is now chosen such that $B_2 = 0$. This choice extends to infinity the tails of the breathers that would otherwise decay.

5 The two-breather solution in the semirational limit

When one of the modulation parameters, say κ_2 , tends to zero, we obtain the semirational limit, i.e. a solution obtained as a combination of polynomials and circular or hyperbolic functions. Then, writing κ for κ_1 , and δ for δ_1 , the functions G, H, and D become

$$G(x,t) = \frac{1}{8}\kappa^2 \{\kappa^2 (1 + 4t_2^2 + 4B_2^2 x^2) - 1\} \cosh \delta B_1 x + \kappa \delta \cos \kappa t_1,$$

$$H(x,t) = 2\kappa B_2 x (\delta \cos \kappa t_1 - \kappa \cosh \delta B_1 x) + \frac{1}{4} \delta \kappa^2 (1 + 4t_2^2 + 4B_2^2 x^2) \sinh \delta B_1 x$$

$$D(x,t) = \frac{\delta}{\kappa} \{ 4 - \frac{1}{4}\kappa^2 (1 + 4t_2^2 + 4B_2^2 x^2) \} \cos \kappa t_1 + 4\delta B_2 x \sinh \delta B_1 x + \delta t_2 \sin \kappa t_1 - \{ 4 + \frac{1}{4}\kappa^2 (1 + 4t_2^2 + 4B_2^2 x^2) \} \cosh \delta B_1 x, (14)$$

and the parameters B_2 and v_2 are reduced to

$$B_2 = \sum_{n=1}^{\infty} {2n \choose n} n\alpha_{2n},\tag{15}$$

$$v_2 = \sum_{n=1}^{\infty} {2n \choose n} (2n+1)\alpha_{2n+1}.$$
 (16)

This semirational 2-breather solution is a superposition of a Peregrine solution with the Akhmediev breather, since taking the limit $\kappa_2 \to 0$ reduces the frequency of one of the breathers to zero, meaning that it is transformed to a Peregrine solution. A plot of this solution is shown in Fig. 5. Here, the central feature is roughly the second order rogue wave while the peaks away from the origin belong to the remaining first-order breather.

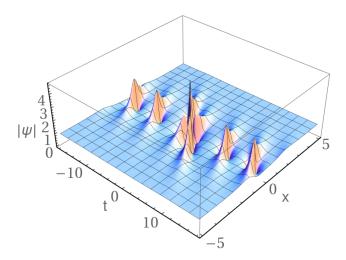


Fig. 5: The 2-breather solution in the semirational limit. Here the nonzero modulation parameter is $\kappa = 1$, with α_n the same as in Fig. (1). It can be considered as a superposition of the Akhmediev breather with the Peregrine solution.

6 The degenerate two-breather limit

If both eigenvalues of the Darboux transformation are taken to be equal, so that both modulation parameters κ_m are also equal, we obtain the case of degenerate breathers. Direct calculations provide no solution. In this case, one modulation parameter should instead be taken as a small perturbation from the other, say $|\kappa_1 - \kappa_2| = \varepsilon$. Then, we take the limit as the perturbation ε becomes arbitrarily small, so that the solution remains

well-defined at all times. Namely, if we put $\kappa_1 = \kappa$, and $\kappa_2 = \kappa + \varepsilon$, we have

$$B_2 = \sum_{n=1}^{\infty} {2n \choose n} nF(1-n,1;\frac{3}{2};\frac{1}{4}(\kappa+\varepsilon)^2)\alpha_{2n},$$

and

$$v_2 = \sum_{n=1}^{\infty} {2n \choose n} (2n+1) F(-n,1; \frac{3}{2}; \frac{1}{4}(\kappa + \varepsilon)^2) \alpha_{2n+1}.$$

Next, recalling the identity

$$\frac{d}{dz}F(a,b;c;z) = \frac{ab}{c}F(a+1,b+1;c+1;z),$$

take the Maclaurin series of the G(x,t), H(x,t), and D(x,t) with respect to ε . In the limit as $\varepsilon \to 0$, the ratio of these series will be a well-defined solution with equal eigenvalues; it is thus sufficient to consider only the lowest-order non-vanishing terms in the series expansion for D(x,t) in ε , which in this case happen to be the coefficients of ε^2 . By this method we obtain the degenerate 2-breather solution in the form (6) with

$$G(x,t) = 2\kappa^2 \left[1 + \cosh 2\delta Bx + \left\{ \left(\kappa B - \frac{2\delta^2}{\kappa} B - \frac{\delta^2 B'}{\kappa} \right) x \sinh \delta Bx - \frac{\kappa}{\delta} \left(1 - \frac{\delta^2}{\kappa^2} \right) \cosh \delta Bx \right\} \cos \kappa (t + vx) - \left\{ t + (v + \kappa v')x \right\} \delta \cosh \delta Bx \sin \kappa (t + vx) \right],$$

$$\begin{split} H(x,t) &= 2\kappa \bigg[\left\{ \left(\frac{2\delta^2}{\kappa^2} - 1 \right) \kappa B + 2\delta^2 B' \right\} x + \\ &+ \frac{1}{2}\delta \bigg\{ \frac{1}{2} \left(\frac{2\delta^2}{\kappa^2} - 1 \right) Bx - \frac{\delta^2}{\kappa} B' \bigg\} x \cosh \delta Bx \times \\ &\times \cos \kappa (t + vx) + \frac{\kappa}{\delta} \left(\frac{2\delta^2}{\kappa^2} - 1 \right) \sinh 2\delta Bx - \\ &- \delta^2 \sinh \delta Bx \{ \cos \kappa (t + vx) + \\ &+ \kappa \sin \kappa (t + vx) \} \{ t + (v + \kappa v')x \} \bigg], \end{split}$$

$$\begin{split} D(x,t) &= \frac{\kappa^2}{32\delta^2} \bigg[-8\kappa^2 \left(1 + \frac{\delta^2}{\kappa^2} \right) - \frac{64\delta^4}{\kappa^2} (t + vx)^2 - \\ &- 64\delta^2 \bigg(1 - \frac{2\delta^2}{\kappa^2} \bigg)^2 B^2 x^2 - 32\cosh 2\delta Bx - \\ &- \frac{128\delta^2}{\kappa} \bigg\{ \bigg(2 - \frac{4\delta^2}{\kappa^2} \bigg) B - \frac{\delta^2}{\kappa} B' \bigg\} x \sinh \delta Bx \times \\ &\times \cos \kappa (t + vx) - 32\delta \bigg\{ \kappa \cos \kappa (t + vx) + \\ &+ \frac{4\delta^2}{\kappa^2} \{ t + (v + \kappa v')x \} \sin \kappa (t + vx) \bigg\} \cosh \delta Bx + \end{split}$$

$$+ \frac{16\delta^{2}}{\kappa^{2}} \left\{ 2\cos 2\kappa (t + vx) + \left(8\left(1 - \frac{2\delta^{2}}{\kappa^{2}}\right) \kappa BB'x - 4\delta^{2}B'^{2} \right) \kappa^{2}x - 4v' \left\{ 2t + (v + \kappa v')x \right\} \right) \right\},$$
 (17)

where $B=B_1$, and we use B' and v' to denote the partial derivatives of B_2 and v_2 with respect to ε evaluated at the point $\varepsilon=0$, i.e. when $\kappa_2\to\kappa$. That is,

$$B' = \frac{1}{3}\kappa \sum_{n=1}^{\infty} {2n \choose n} n(1-n)F(2-n,2;\frac{5}{2};\frac{1}{4}\kappa^2)\alpha_{2n},$$

and

$$v' = -\frac{1}{3}\kappa \sum_{n=1}^{\infty} {2n \choose n} (2n+1)nF(1-n,2;\frac{5}{2};\frac{1}{4}\kappa^2)\alpha_{2n+1},$$

etc. We drop the subscripts due to the fact that as $\varepsilon \to 0$ both modulation parameters take equal values anyway. A plot of this solution is given in Fig.6.

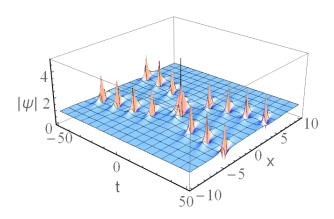


Fig. 6: The degenerate 2-breather solution. We take the set of α_n the same as in Fig. 1, and the modulation parameters $\kappa_1 = \kappa_2 = \frac{1}{2}$. The two breathers collide with the high peak at the origin due to the synchronised phases.

The degenerate breather solution is a one-parameter family of solutions which represents the collision of two breathers with the same modulation parameter κ , or, equivalently, with equal frequencies. It can be considered a generalisation of the known 2-soliton solution for the class I extension of the nonlinear Schrödinger equation [50].

7 Second-order rogue wave solution

When the modulation frequency κ of the degenerate breathers becomes zero, the spacing between the successive peaks in Fig. 6 becomes infinitely large, pushing them out to infinity. What remains at the origin is the second order rogue wave. In order to derive this solution, we take the limit $\kappa \to 0$ in the expressions (17). However, calculations show that this limit cannot be found directly. In order to find it, we apply l'Hôpital's rule to the degenerate breather solution as $\kappa \to 0$. The derivatives of G, H, and D with respect to κ at the point $\kappa = 0$ vanish up to $O(\varepsilon^6)$. The resulting functions G, H, and D become polynomials:

$$G(x,t) = 12\{-3 + 24(3B^2 - BB'' - vv'')x^2 + 80B^4x^4 - 192v''xt + 96B^2x^2(t + vx)^2 + 24(t + vx)^2 + 16(t + vx)^4\},$$
(18)

$$H(x,t) = 576B''x + 2304B''x(t + vx)^2 - 24Bx\{15 - 8(B + 16B'')Bx^2 - 16B^4x^4 + 192v''x(t + vx) - 32B^2x^2(t + vx)^2 + 24(t + vx)^2 - 16(t + vx)^4\},$$
(19)

$$D(x,t) = -9 - 36\{11B^2 - 48BB'' + 64B''^2 - 16(v - v'')v''\}x^2 - 48\{9B^4 - 6B^2v^2 + 16(3v^2 - B^2)BB'' + 16(v^2 - 3B^2)vv''\}x^4 - 64(B^4 + 3B^2v^2 + 3v^4)B^2x^6 + 576v''xt - 768v''xt^3 + 288(B^2 - 8BB'' - 8vv'')x^2t^2 - 192B^2x^2t^4 + 576\{(B - 8B'')Bv + 4(B^2 - v^2)v''\}x^3t - 768B^2vx^3t^3 - 192(B^2 + 6v^2)B^2x^4t^2 - 384(B^2 + 2v^2)B^2vx^5t - 108(t + vx)^2 - 48(t + vx)^4 - 64(t + vx)^6,$$
(20)

where, in the same limit as $\kappa \to 0$,

$$B = \sum_{n=1}^{\infty} {2n \choose n} n\alpha_{2n},$$

$$v = \sum_{n=1}^{\infty} {2n \choose n} (2n+1)\alpha_{2n+1}.$$

The first-order derivatives B' and v' vanish as $\kappa \to 0$, but the second-order derivatives still remain, and in the limit as $\kappa \to 0$ are

$$B'' = -\frac{1}{3} \sum_{n=1}^{\infty} {2n \choose n} n(n-1)\alpha_{2n},$$

$$v'' = -\frac{1}{3} \sum_{n=1}^{\infty} {2n \choose n} (2n+1) n\alpha_{2n+1}.$$

This solution is shown in Fig. 7. It is, naturally, the second-order rogue wave, but slanted and rescaled in the (x,t)-plane relative to the second-order rogue wave of the NLSE [51,52].

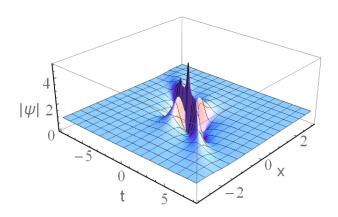


Fig. 7: The second-order rogue wave, Eqs. (18), (19), (20) obtained from the degenerate two-breather solution shown in Fig. 6 in the limit $\kappa \to 0$.

8 Rogue wave triplets

It is well known that the general n-th order rogue wave has the remarkable property of being able to split into $\frac{1}{2}n(n+1)$ first-order components [48]. The second-order rogue wave discussed above is only a particular case of a more general rogue wave structure, where all three first-order components are located at the origin, and have merged into one single peak. In order to obtain the more general solution where the three components are not merged together, known as the rogue wave triplet [49], we re-introduce the constants of integration into the general 2-breather solution, i.e.

$$\delta_m B_m x \mapsto \delta_m (B_m x - \varepsilon X_m),$$

 $t + v_m x \mapsto t - T_m \varepsilon + v_m x,$

where X_m and T_m are arbitrary, and the parameter ε is introduced to make sure that the Taylor series in the degenerate limit still vanishes up to $O(\varepsilon^2)$. The values of X_m and T_m determine the location of the components of the breather components. They add additional free parameters to the solution which we have previously given for the restricted case in which $X_m = T_m = 0$. Notice also that we do not make the replacement $x \mapsto x - X_m \varepsilon$ directly, but, for simplicity's sake, instead define X_m to account for the higher-order terms in B_m .

In order to further simplify parametrisation, we assume that X_m and T_m are functions of the modulation parameter κ , and are of the order $O(\kappa)$. Then, defining free parameters ξ and η independent of κ , such that

$$48\kappa\xi = X_1 - X_2,$$

$$48\kappa\eta = T_1 - T_2,$$

we have in the limit as $\kappa \to 0$ the rogue wave triplet solution in the form

$$\psi(x,t) = \left\{ 1 + \frac{\hat{G}(x,t) + i\hat{H}(x,t)}{\hat{D}(x,t)} \right\} e^{i\phi x},\tag{21}$$

with

$$\hat{G}(x,t) = G(x,t) - 48\xi Bx - 48\eta(t+vx), \tag{22}$$

$$\hat{H}(x,t) = H(x,t) + 12\xi - 48\xi B^2 x^2 - 96\eta Bx(t+vx) + 48\xi(t+vx)^2, \tag{23}$$

$$\hat{D}(x,t) = D(x,t) - (\xi^2 + \eta^2) + 12\{\xi(3B - 4B'') - 4\eta v''\}x + 16\xi B^3 x^3 + 12\eta(1+4B^2 x^2) \times (t+vx) - 48\xi Bx(t+vx)^2$$

 $-16n(t+vx)^3$.

where \hat{G} , \hat{H} and \hat{D} now contain two new free parameters ξ and η that control the separation of the fundamental rogue wave components in the triplet, and where G, H, and D are as given in Eqs. (18)-(20), for the particular case in which $\xi = \eta = 0$. An example of the formation of rogue wave triplets, corresponding to nonzero ξ and η is shown in Fig. 8. When $\xi = 0$ and $\eta = 0$, all three components merge at the origin, as in Fig. 7.

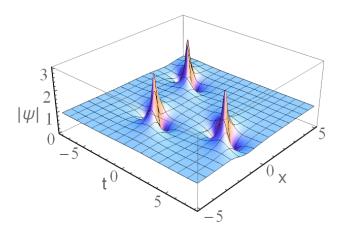


Fig. 8: The second-order rogue wave triplet (21), with separation parameters $\xi = -\eta = 10$, and the extended equation parameters given by $\alpha_2 = \frac{1}{2}$, $\alpha_3 = \frac{1}{27}$, $\alpha_4 = \frac{1}{50}$, $\alpha_5 = \frac{1}{81}$, $\alpha_6 = \frac{1}{200}$, $\alpha_7 = \frac{1}{343}$.

Generally, the coefficient B in Eq. (21) determines the degree of localisation along the x-axis. Larger values of B will correspond to narrower peaks, whereas smaller values of B will correspond to broader peaks, and B =0 to minimal localisation. A point of interest here is that it is again possible to choose a parametrisation for which B is any fixed constant. If we choose, for instance,

$$\alpha_2 = c - \frac{1}{2} \sum_{n=1}^{\infty} {2n+2 \choose n+1} (n+1)\alpha_{2n+2},$$

we end up with B=c, where c is a free parameter. However, now B'' is entirely independent of the choice of c, since the coefficient of α_2 in B'' is zero. As the simplest example, we consider the completely de-localised case, B=0, with B'' remaining arbitrary. The rogue wave solution then reduces to (21) with

$$\hat{G}(x,t) = G_0(x,t) - 48\eta(t+vx),$$

$$\hat{H}(x,t) = H_0(x,t) + 12\xi + 48\xi(t+vx)^2,$$

$$\hat{D}(x,t) = D_0(x,t) - (\xi^2 + \eta^2) - 48(\xi B'' + \eta v'')x + 12\eta(t+vx) - 16\eta(t+vx)^3.$$

where

(24)

$$G_0(x,t) = 12\{-3 - 192v''x(t+vx) + 24(t+vx)^2 + 16(t+vx)^4\},$$

$$H_0(x,t) = 576B''x\{1 + 4(t+vx)^2\},$$

$$D_0(x,t) = -9 - 576\{4B''^2 + v''^2\}x^2 + 576v''x(t+vx) - 768v''x(t+vx)^3 - 108(t+vx)^2 - 48(t+vx)^4 - 64(t+vx)^6.$$

Here, G_0 , H_0 , and D_0 are as given for the case where the components are merged and B=0, and \hat{G} , \hat{H} , \hat{D} incorporate the shifting of the first-order components through ξ and η .

When B=0, the second-order rogue wave acquires soliton-like tails similar to those in Fig.4. When, additionally, $\xi=\eta=0$, rogue waves merge at the origin to form a second-order rogue wave with extended tails. This case is shown in Fig. 9. When ξ or η is not zero, the components split, resulting in the disappearance of the central peak. This case is shown in Fig. 10. Here, the central peak is absent but the tails remain, consisting of maximally de-localised first-order components.

Conclusions

We have derived the general 2-breather solution for the class I infinitely extended nonlinear Schrödinger equation, and given many limiting cases; namely, breather-to-soliton conversions, the semirational limit, the degenerate 2-breather, and, probably most importantly, the general second-order rogue wave solution. These solutions completely describe a large family of second-order solutions to the class I extension of the NLSE, and exhibit rich behaviour.

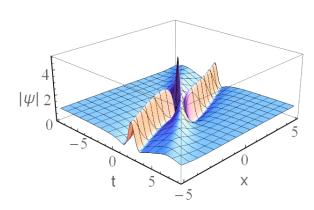


Fig. 9: The second-order rogue wave solution with 'soliton'-like tails when α_2 chosen such that B = 0, and $\xi = \eta = 0$.

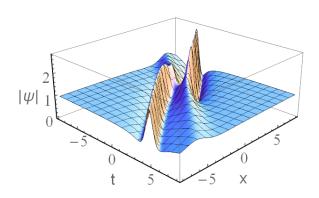


Fig. 10: The second-order rogue wave solution with 'soliton'-like tails when B = 0, but now $\xi = \eta = 1$.

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