# New uniqueness results for boundary value problem of fractional differential equation* 

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#### Abstract

In this paper, uniqueness results for boundary value problem of fractional differential equation are obtained. Both the Banach's contraction mapping principle and the theory of linear operator are used, and a comparison between the obtained results is provided.


Keywords: fractional differential equation, uniqueness results, Banach's contraction mapping principle.

## 1 Introduction

In this paper, we consider the uniqueness of solutions of the following boundary value problems for nonlinear fractional differential equation:

$$
\begin{align*}
& D_{0+}^{\alpha} u(t)+f(t, u(t))=0, \quad t \in(0,1), 1<\alpha \leqslant 2 \\
& u(0)=u(1)=0 \tag{1}
\end{align*}
$$

Boundary value problems for nonlinear fractional differential equation have been investigated extensively. The motivation for those works arises from both the development of the theory of fractional calculus itself and the study of models of viscoelasticity, electrochemistry, control, porous media, electromagnetic, etc. (see [5, 7, 8, 16]). In applications, one

[^0]is interested in showing the existence and multiplicity of solution (or positive solution). Consequently, there has been a significant development in the study of boundary value problems of fractional differential equation, see [ $1,3,6,7,9,11,12,15$ ]. In [3], the authors considered the existence and multiplicity of positive solutions of BVP (1) by means of the Krasnosel'skii fixed-point theorem and the Leggett-Williams fixed-point theorem. However, there are few works on the uniqueness for boundary value problems of fractional differential equations [2, 4, 10, 13, 14]. In [13], the authors studied the following multipoint boundary value problems of fractional order:
\[

$$
\begin{align*}
& D_{t}^{\alpha} y(t)=f\left(t, y(t), D_{t}^{\beta} y(t)\right), \quad t \in(0,1) \\
& y(0)=0, \quad D_{t}^{\beta} y(1)-\sum_{i=1}^{m-2} \varsigma_{i} D_{t}^{\beta} y\left(\xi_{i}\right)=y_{0} \tag{2}
\end{align*}
$$
\]

where $1<\alpha \leqslant 2,0<\beta<1,0<\xi_{i}<1(i=1,2, \ldots, m-2), \varsigma_{i} \geqslant 0$ with $\sum_{i=1}^{m-2} \varsigma_{i} \xi_{i}^{\alpha-\beta-1}<1$, and $D_{t}^{\alpha}$ denotes the standard Riemann-Liouville fractional derivative. They proved the uniqueness of solutions to BVP (2) by means of the Banach's contraction mapping principle. Recently, the following nonlinear fractional differential equations with two point boundary conditions was also studied by Cui [4]:

$$
\begin{aligned}
& D^{p} x(t)+p(t) f(t, x(t))+q(t)=0, \quad t \in(0,1) \\
& x(0)=x^{\prime}(0)=0, \quad x(1)=0
\end{aligned}
$$

where $2<p \leqslant 3$ is a real number. By use of $u_{0}$-positive operator, a uniqueness result is proved, provided that $f$ is a Lipschitz continuous function. The novelty of [4] is that the Lipschitz constant is related to the first eigenvalue corresponding to the relevant operator.

Motivated by the results mentioned above, in this paper, we study the uniqueness of solutions for BVP (1) based on the Banach's contraction mapping principle and the theory of linear operator. It should be remarked that the method used in [4] is not suitable for BVP (1).

## 2 Preliminaries and lemmas

For convenience, we present here the necessary definitions from fractional calculus theory. These definitions can be found in the literature.

Definition 1. (See [12].) The Riemann-Liouville fractional integral of order $\alpha>0$ of a function $f:(0, \infty) \rightarrow \mathbb{R}$ is given by

$$
I_{0+}^{\alpha} f(t)=\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} f(s) \mathrm{d} s
$$

provided that the right-hand side is pointwise defined on $(0, \infty)$.

Definition 2. (See [12]) The Riemann-Liouville fractional derivative of order $\alpha>0$ of a continuous function $f:(0, \infty) \rightarrow \mathbb{R}$ is given by

$$
D_{0^{+}}^{\alpha} f(t)=\frac{1}{\Gamma(n-\alpha)}\left(\frac{\mathrm{d}}{\mathrm{~d} t}\right)^{n} \int_{0}^{t} \frac{f(s)}{(t-s)^{\alpha-n+1}} \mathrm{~d} s
$$

where $n-1 \leqslant \alpha<n$, provided that the right-hand side is pointwise defined on $(0, \infty)$.
Let $C[0,1]$ denote the Banach space of real-valued continuous function with norm $\|u\|=\max _{t \in[0,1]}|u(t)|$.
Lemma 1. (See [3].) Given $h \in C[0,1]$ and $1<\alpha \leqslant 2$, the unique solution of

$$
\begin{aligned}
& D_{0+}^{\alpha} u(t)+h(t)=0, \quad t \in(0,1) \\
& u(0)=u(1)=0
\end{aligned}
$$

is

$$
u(t)=\int_{0}^{1} G(t, s) h(s) \mathrm{d} s
$$

where

$$
G(t, s)=\frac{1}{\Gamma(\alpha)} \begin{cases}(t(1-s))^{\alpha-1}-(t-s)^{\alpha-1}, & 0 \leqslant s \leqslant t \leqslant 1 \\ (t(1-s))^{\alpha-1}, & 0 \leqslant t \leqslant s \leqslant 1\end{cases}
$$

By Lemma 1, BVP (1) can be converted into a fixed-point problem $x=A x$, where $A: C[0,1] \rightarrow C[0,1]$ is presented by

$$
(A u)(t)=\int_{0}^{1} G(t, s) f(s, u(s)) \mathrm{d} s
$$

Clearly, BVP (1) has a solution if and only if the associated fixed-point problem $x=A x$ has a fixed point.

Lemma 2. Let $E=\left\{a \in \mathbb{R}: a(1-t) \geqslant 1+t^{\alpha+1}-2 t^{\alpha}, t \in[0,1]\right\}$. Then $E \neq \emptyset$ and $M=\inf E \in[1, \alpha]$.
Proof. By the Lagrange mean value theorem, we have

$$
\begin{aligned}
1+t^{\alpha+1}-2 t^{\alpha} & =1-t^{\alpha}-t^{\alpha}(1-t) \leqslant 1-t^{\alpha}=\alpha \xi^{\alpha-1}(1-t) \\
& \leqslant \alpha(1-t), \quad \xi \in(t, 1) .
\end{aligned}
$$

This implies that $E \neq \emptyset$ and $M \leqslant \alpha$.
On the other hand, substituting the value $t=0$ to the inequality $a(1-t) \geqslant 1+t^{\alpha+1}-$ $2 t^{\alpha}$, we get $a \geqslant 1$ and $M \geqslant 1$. This completes the proof.

## 3 Main results

We first prove a uniqueness result based on the Banach's contraction mapping principle.
Theorem 1. Suppose that $f:[0,1] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function and there exists a constant $L>0$ such that

$$
|f(t, x)-f(t, y)| \leqslant L|x-y|, \quad t \in[0,1], x, y \in \mathbb{R}
$$

If $L<\alpha^{2} \Gamma(\alpha)((\alpha-1) / \alpha)^{1-\alpha}$, then BVP (1) has a unique solution in $C[0,1]$.
Proof. We now show that $A$ is a contraction on $C[0,1]$. To see this, let $u, v \in C[0,1]$ and notice

$$
\begin{align*}
\Gamma(\alpha) \int_{0}^{1} G(t, s) \mathrm{d} s & =\int_{0}^{1}(t(1-s))^{\alpha-1} \mathrm{~d} s-\int_{0}^{t}(t-s)^{\alpha-1} \mathrm{~d} s \\
& =t^{\alpha-1} B(\alpha, 1)-t^{\alpha} \int_{0}^{1}(1-s)^{\alpha-1} \mathrm{~d} s \\
& =t^{\alpha-1} B(\alpha, 1)-t^{\alpha} B(\alpha, 1)=\frac{1}{\alpha}\left(t^{\alpha-1}-t^{\alpha}\right) \\
& \leqslant\left.\frac{1}{\alpha}\left(t^{\alpha-1}-t^{\alpha}\right)\right|_{t=(\alpha-1) / \alpha}=\frac{1}{\alpha^{2}}\left(\frac{\alpha-1}{\alpha}\right)^{\alpha-1} \tag{3}
\end{align*}
$$

Thus, for $t \in[0,1]$,

$$
\begin{aligned}
|(A u)(t)-(A v)(t)| & =\left|\int_{0}^{1} G(t, s)(f(s, u(s))-f(s, v(s))) \mathrm{d} s\right| \\
& \leqslant \int_{0}^{1} G(t, s)|f(s, u(s))-f(s, v(s))| \mathrm{d} s \\
& \leqslant L \int_{0}^{1} G(t, s)|u(s)-v(s)| \mathrm{d} s \leqslant L \int_{0}^{1} G(t, s) \mathrm{d} s\|u-v\| \\
& \leqslant \frac{L}{\Gamma(\alpha) \alpha^{2}}\left(\frac{\alpha-1}{\alpha}\right)^{\alpha-1}\|u-v\|
\end{aligned}
$$

and therefore

$$
\|A u-A v\| \leqslant \frac{L}{\Gamma(\alpha) \alpha^{2}}\left(\frac{\alpha-1}{\alpha}\right)^{\alpha-1}\|u-v\|
$$

Since $L<\Gamma(\alpha) \alpha^{2}((\alpha-1) / \alpha)^{1-\alpha}$, the Banach's contraction mapping principle implies that there is a unique $u$ with $u=A u$, equivalently, BVP (1) has a unique solution $u \in$ $C[0,1]$. The proof is completed.

Next, we prove a uniqueness result by means of the theory of linear operator.
Theorem 2. Suppose that $f:[0,1] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function and there exists a constant $L>0$ such that

$$
|f(t, x)-f(t, y)| \leqslant L|x-y|, \quad t \in[0,1], x, y \in \mathbb{R}
$$

If $L<2 \Gamma(2 \alpha) /(M \Gamma(\alpha))$, then BVP (1) has a unique solution in $C[0,1]$.
Proof. We define an operator $T$ on $C[0,1]$ by

$$
(T u)(t)=\int_{0}^{1} G(t, s) u(s) \mathrm{d} s, \quad u \in C[0,1] .
$$

In the following, we separate the proof into the following four steps.
Step 1. For any given $u \in C[0,1]$ with $u(t) \geqslant 0(t \in[0,1])$, there is a constant $N=N(u)$ such that

$$
(T u)(t) \leqslant N u_{0}(t), \quad t \in[0,1],
$$

where $u_{0}(t)=t^{\alpha-1}(1-t)$. In fact, it follows from (3) that

$$
\begin{aligned}
\Gamma(\alpha) \int_{0}^{1} G(t, s) u(s) \mathrm{d} s & \leqslant\left(\int_{0}^{1}(t(1-s))^{\alpha-1} \mathrm{~d} s-\int_{0}^{t}(t-s)^{\alpha-1} \mathrm{~d} s\right)\|u\| \\
& \leqslant \frac{\|u\|}{\alpha}\left(t^{\alpha-1}-t^{\alpha}\right)=\frac{\|u\|}{\alpha} u_{0}(t), \quad t \in[0,1]
\end{aligned}
$$

Step 2. $\left(T u_{0}\right)(t) \leqslant \beta u_{0}(t)$, where $\beta=M \Gamma(\alpha) /(2 \Gamma(2 \alpha))$. This can be obtained by the following inequality:

$$
\begin{aligned}
& \Gamma(\alpha)\left(T u_{0}\right)(t) \\
& \quad=\Gamma(\alpha) \int_{0}^{1} G(t, s) s^{\alpha-1}(1-s) \mathrm{d} s \\
& \quad=\int_{0}^{1}(t(1-s))^{\alpha-1} s^{\alpha-1}(1-s) \mathrm{d} s-\int_{0}^{t}(t-s)^{\alpha-1} s^{\alpha-1}(1-s) \mathrm{d} s \\
& \quad=t^{\alpha-1} B(\alpha+1, \alpha)-\int_{0}^{t}(t-s)^{\alpha-1} s^{\alpha-1} \mathrm{~d} s+\int_{0}^{t}(t-s)^{\alpha-1} s^{\alpha} \mathrm{d} s \\
& \quad=t^{\alpha-1} B(\alpha+1, \alpha)-t^{2 \alpha-1} \int_{0}^{1}(1-s)^{\alpha-1} s^{\alpha-1} \mathrm{~d} s+t^{2 \alpha} \int_{0}^{1}(1-s)^{\alpha-1} s^{\alpha} \mathrm{d} s
\end{aligned}
$$

$$
\begin{aligned}
& =t^{\alpha-1} B(\alpha+1, \alpha)-t^{2 \alpha-1} B(\alpha, \alpha)+t^{2 \alpha} B(\alpha, \alpha+1) \\
& =t^{\alpha-1} \frac{\Gamma(\alpha+1) \Gamma(\alpha)}{\Gamma(2 \alpha+1)}-t^{2 \alpha-1} \frac{\Gamma(\alpha) \Gamma(\alpha)}{\Gamma(2 \alpha)}+t^{2 \alpha} \frac{\Gamma(\alpha) \Gamma(\alpha+1)}{\Gamma(2 \alpha+1)} \\
& =t^{\alpha-1} \frac{\alpha \Gamma(\alpha) \Gamma(\alpha)}{2 \alpha \Gamma(2 \alpha)}-t^{2 \alpha-1} \frac{\Gamma(\alpha) \Gamma(\alpha)}{\Gamma(2 \alpha)}+t^{2 \alpha} \frac{\alpha \Gamma(\alpha) \Gamma(\alpha)}{2 \alpha \Gamma(2 \alpha)} \\
& =t^{\alpha-1} \frac{B(\alpha, \alpha)}{2}\left(1+t^{\alpha+1}-2 t^{\alpha}\right) \\
& \leqslant \frac{M B(\alpha, \alpha)}{2}(1-t) t^{\alpha-1}=\frac{M \Gamma(\alpha) \Gamma(\alpha)}{2 \Gamma(2 \alpha)} u_{0}(t), \quad t \in[0,1] .
\end{aligned}
$$

Step 3. To show the existence of the solution, select $v_{1} \in C[0,1]$. Let

$$
v_{n+1}=A v_{n}, \quad w_{n}(t)=\left|v_{n+1}(t)-v_{n}(t)\right|, \quad n=1,2, \ldots
$$

Notice for $n \in\{1,2, \ldots\}$ that

$$
\begin{aligned}
w_{n}(t) & =\left|v_{n+1}(t)-v_{n}(t)\right|=\left|\left(A v_{n}\right)(t)-\left(A v_{n-1}\right)(t)\right| \\
& \leqslant \int_{0}^{1} G(t, s)\left|f\left(s, v_{n}(s)\right)-f\left(s, v_{n-1}(s)\right)\right| \mathrm{d} s \\
& \leqslant L \int_{0}^{1} G(t, s)\left|v_{n}(s)-v_{n-1}(s)\right| \mathrm{d} s \\
& =L\left(T w_{n-1}\right)(t), \quad t \in[0,1] .
\end{aligned}
$$

Then by Steps 1 and 2, we have

$$
\begin{aligned}
w_{n}(t) & \leqslant L\left(T w_{n-1}\right)(t) \leqslant \cdots \leqslant L^{n-1}\left(T^{n-1} w_{1}\right)(t) \leqslant N\left(w_{1}\right) L^{n-1}\left(T^{n-2} u_{0}\right)(t) \\
& \leqslant N\left(w_{1}\right) L^{n-1} \beta^{n-2} u_{0}(t), \quad t \in[0,1] .
\end{aligned}
$$

Thus, for $m>n$ where $n \in\{1,2, \ldots\}$,

$$
\begin{aligned}
\left|v_{m}(t)-v_{n}(t)\right| & \leqslant\left|v_{m}(t)-v_{m-1}(t)\right|+\cdots+\left|v_{n+1}(t)-v_{n}(t)\right| \\
& =w_{m-1}(t)+\cdots+w_{n}(t) \\
& \leqslant N\left(w_{1}\right) L^{m-2} \beta^{m-3} u_{0}(t)+\cdots+N\left(w_{1}\right) L^{n-1} \beta^{n-2} u_{0}(t) \\
& \leqslant N\left(w_{1}\right) L^{n-1} \beta^{n-2} u_{0}(t)\left(1+L \beta+(L \beta)^{2}+\cdots\right) \\
& =N\left(w_{1}\right) L^{n-1} \beta^{n-2} u_{0}(t) \frac{1}{1-L \beta}, \quad t \in[0,1] .
\end{aligned}
$$

That is, for $m>n$ where $n \in\{1,2, \ldots\}$,

$$
\begin{equation*}
\left|v_{m}(t)-v_{n}(t)\right| \leqslant N\left(w_{1}\right) L^{n-1} \beta^{n-2} \frac{1}{1-L \beta} . \tag{4}
\end{equation*}
$$

This shows that $\left\{v_{n}\right\}$ is a Cauchy sequence, and since $C[0,1]$ is complete, there exists $v^{*} \in C[0,1]$ with $\lim _{n \rightarrow \infty} v_{n}=v^{*}$. Moreover, the continuity of $A$ yields

$$
v^{*}=\lim _{n \rightarrow \infty} v_{n}=\lim _{n \rightarrow \infty} A\left(v_{n-1}\right)=A v^{*}
$$

therefore, $v^{*}$ is a fixed point of $A$. Finally, letting $m \rightarrow \infty$ in (4) implies

$$
\left\|v^{*}-v_{n}\right\| \leqslant N\left(w_{1}\right) L^{n-1} \beta^{n-2} \frac{1}{1-L \beta}
$$

Step 4. We show the uniqueness of the solution. Suppose that there exist $u, v \in C[0,1]$ with $u=A u$ and $v=A v$. Similarly to the proof of Step 3, we obtain

$$
\begin{aligned}
|u(t)-v(t)| & \leqslant\left|\left(A^{n} u\right)(t)-\left(A^{n} v\right)(t)\right| \\
& \leqslant \int_{0}^{1} G(t, s)\left|f\left(s,\left(A^{n-1} u\right)(s)\right)-f\left(s,\left(A^{n-1} v\right)(s)\right)\right| \mathrm{d} s \\
& \leqslant L \int_{0}^{1} G(t, s)\left|\left(A^{n-1} u\right)(s)-\left(A^{n-1} v\right)(s)\right| \mathrm{d} s \\
& =L T\left(\left|A^{n-1} u-A^{n-1} v\right|\right)(t) \\
& \leqslant \cdots \leqslant L^{n} T^{n}(|u-v|)(t) \leqslant N(|u-v|) L^{n}\left(T^{n-1} u_{0}\right)(t) \\
& \leqslant N(|u-v|) L^{n} \beta^{n-1} u_{0}(t) \quad \forall n \in \mathbb{N} .
\end{aligned}
$$

Therefore, $u=v$. This completes the proof.
From the proof of Theorems 1 and 2 we have

$$
\begin{aligned}
t^{\alpha-1} & \frac{B(\alpha, \alpha)}{2}\left(1+t^{\alpha+1}-2 t^{\alpha}\right) \\
& =\Gamma(\alpha)\left(T u_{0}\right)(t) \leqslant \Gamma(\alpha) \int_{0}^{1} G(t, s) \mathrm{d} s\left\|u_{0}\right\|=\frac{1}{\alpha}\left(t^{\alpha-1}-t^{\alpha}\right)\left\|u_{0}\right\| \\
& =\frac{1}{\alpha}\left(t^{\alpha-1}-t^{\alpha}\right) \frac{1}{\alpha}\left(\frac{\alpha-1}{\alpha}\right)^{\alpha-1}=\frac{1}{\alpha^{2}}\left(\frac{\alpha-1}{\alpha}\right)^{\alpha-1}\left(t^{\alpha-1}-t^{\alpha}\right) .
\end{aligned}
$$

Using this and Lemma 2, we get

$$
\frac{\Gamma(\alpha) M}{2 \Gamma(2 \alpha)} \leqslant \frac{1}{\alpha^{2} \Gamma(\alpha)}\left(\frac{\alpha-1}{\alpha}\right)^{\alpha-1}
$$

that is,

$$
\alpha^{2} \Gamma(\alpha)\left(\frac{\alpha-1}{\alpha}\right)^{1-\alpha} \leqslant \frac{2 \Gamma(2 \alpha)}{\Gamma(\alpha) M}
$$

This implies that Theorem 2 provides the same results with weaker conditions. In order to apply the above results, one needs to compute some of the following three values:

$$
M, \quad \alpha^{2} \Gamma(\alpha)\left(\frac{\alpha-1}{\alpha}\right)^{1-\alpha}, \quad \frac{2 \Gamma(2 \alpha)}{\Gamma(\alpha) M}
$$

When $\alpha=2$, three values are $5 / 4,8$ and $48 / 5$, respectively; if $\alpha=3 / 2$, three values are $M \approx 1.0507,3.454$ and 4.296 , respectively.

Similarly to the proof of Theorem 2, we can obtain the uniqueness result of nonnegative solution for BVP (1).

Theorem 3. Suppose that $f:[0,1] \times \mathbb{R} \rightarrow[0,+\infty)$ is a continuous function and there exists a constant $L>0$ such that

$$
|f(t, x)-f(t, y)| \leqslant L|x-y|, \quad t \in[0,1], x, y \in[0,+\infty)
$$

If $L<2 \Gamma(2 \alpha) /(M \Gamma(\alpha))$, then $B V P(1)$ has a unique nonnegative solution in $C[0,1]$.

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