

Oscillation of third order impulsive differential equations with delay

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ABSTRACT

This paper deals with the oscillation of third order impulsive differential equations with delay. The results of this paper improve and extend some results for the differential equations without impulses. Some examples are given to illustrate the main results.

Keywords: Oscillation; Third-order; Impulse; Differential equations.

Mathematics Subject Classification 2010: 34A37, 34C10



Council for Innovative Research

Peer Review Research Publishing System

Journal: Journal of Advances in Mathematics

Vol 6, No. 1 editor@cirworld.com <u>www.cirworld.com</u>, member.cirworld.com





1 INTRODUCTION

This paper concerned with the oscillatory and asymptotic behavior of third order impulsive differential equation of the form

$$\begin{cases} \left[a(t)(b(t)(x(t) + p(t)x(t - \tau))')'\right] + q(t)x(t - \sigma) = 0, t \ge t_0 > 0, t \ne t_k; \\ x(t_k^+) = a_k x(t_k), \quad x'(t_k^+) = b_k x'(t_k) \\ x''(t_k^+) = c_k x''(t_k), k = 1, 2, \dots \end{cases}$$
(1.1)

where τ and σ are nonnegative constants with $\sigma > \tau$, $\{t_k\}$ is a sequence of impulsive moments which satisfies $0 \le t_0 < t_1 < \ldots < t_k < \ldots$ with $\lim_{k \to \infty} t_k = \infty$ and $t_{k+1} - t_k > \tau$. Throughout this paper, we will assume that the following assumptions are satisfied:

(H1) a, b and p are positive continuously differentiable functions with $0 \le p(t) \le p < 1$;

(H2) $q \in C([t_0,\infty),[0,\infty))$ and q(t) is not identically zero on any ray of the form $[t^*,\infty)$ for all $t^* \ge t_0$;

(H3) a_k, b_k, c_k are positive constants.

Let $J \subset \mathbb{R}$ be an interval. We define $PC^1(J,\mathbb{R}) = \{x: J \to \mathbb{R}: x(t) \text{ is differentiable for } t \ge 0 \text{ and } t \ne t_k, x'(t_k^-) \text{ and } x'(t_k^+) \text{ exist and } x'(t_k^-) = x'(t_k)\}.$

By a solution of equation (1.1), we mean a real function x(t) such that $x, x', x'' \in PC^1(J, \mathbb{R})$ which satisfies equation (1.1). Our attention is restricted to those solutions x(t) of equation (1.1) which exist on half line $[t_0, \infty)$ and satisfy $\sup\{|x(t)|: t \ge T_x\} > 0$ for all $T_x \ge t_0$. It will be assumed that equation (1.1) has solutions which are nontrivial for large t. Such a solution of equation (1.1) is said to be non-oscillatory if it is eventually positive or eventually negative, otherwise it is oscillatory.

It is well known that there is a drastic difference in the behavior of solutions between differential equations with impulses and those without impulses. Some differential equations are non-oscillatory, but they may become oscillatory if some proper impulse controls are added to them, see [2].

In recent years, the oscillation theory and asymptotic behavior of impulsive differential equations and their applications have been and still receiving intensive attention. But to the best of our knowledge, it seems that little has been done for oscillation of third order impulsive differential equations[10].

Our aim in this paper is to establish some new sufficient conditions which ensure that solutions of equation (1.1) are oscillatory or converge to zero as t tends to ∞ . In particular, we extend the results in [9, 7] to the impulsive differential equation (1.1).

In this paper, we shall study the behavior of solutions of equation (1) under the following three cases:

$$\int_{t_0}^{\infty} \frac{ds}{a(s)} = \infty, \quad \int_{t_0}^{\infty} \frac{ds}{b(s)} = \infty;$$
(1.2)

$$\int_{t_0}^{\infty} \frac{ds}{a(s)} < \infty, \quad \int_{t_0}^{\infty} \frac{ds}{b(s)} = \infty;$$
(1.3)



$$\int_{t_0}^{\infty} \frac{ds}{a(s)} < \infty, \quad \int_{t_0}^{\infty} \frac{ds}{b(s)} < \infty.$$
(1.4)

In the following, all functional inequalities considered are assumed to hold eventually, that is, they are satisfied for all sufficiently large t.

2 Main results

In this section, we present the main results. We write $z(t) = x(t) + p(t)x(t-\tau)$. Furthermore, assume that $a_k \le 1, b_k \ge 1$ and $c_k \le 1$. First we begin with a useful lemma, which is borrowed from [6].

Lemma 2.1 Suppose

- (i) the sequence $\{t_k\}_{k \in \mathbb{N}}$ satisfies $0 \le t_0 < t_1 < \ldots < t_k < \ldots$ with $\lim_{k \to \infty} t_k = \infty$;
- (ii) $m, m': \mathbb{R}_+ \to \mathbb{R}$ are right continuous on $\mathbb{R}_+ \setminus \{t_k : k \in \mathbb{N}\}$, there exist the lateral limits
 - $m(t_k^-), m'(t_k^-), m(t_k^+)$ and $m'(t_k^+)$ with $m(t_k^-) = m(t_k), k = 1, 2, 3...;$
- (iii) for $k = 1, 2, 3, \ldots$ and $t \ge t_0$, we have

$$m'(t) \le p(t)m(t) + q(t), t \ne t_k,$$

$$m(t_k^+) \le \alpha_k m(t_k) + \beta_k$$
(2.1)
(2.2)

where $p, q \in C(\mathbb{R}_+, \mathbb{R}), \alpha_k$ and β_k are real constants with $\alpha_k \ge 0$. Then the following inequality holds

$$m(t) \leq m(t_0) \prod_{t_0 \leq t_k \leq t} \alpha_k \exp\left(\int_{t_0}^t p(s)ds\right) + \int_{t_0}^t \prod_{s \leq t_k \leq t} \alpha_k \exp\left(\int_s^t p(u)du\right) q(s)ds$$
$$+ \sum_{t_0 \leq t_k \leq t} \prod_{t_k \leq t_j \leq t} \alpha_j \exp\left(\int_{t_k}^t p(s)ds\right) \beta_k, t \geq t_0.$$
(2.3)

Theorem 2.1 Assume that (1.2) holds. If there exists a function $\rho \in C^1([t_0,\infty), (0,\infty))$ for all sufficiently large $t \ge t_3 \ge t_2 \ge t_1 \ge t_0$, one has

$$\lim_{t \to \infty} \int_{t_3}^{t} \prod_{s_3 < t_k < s} \frac{1}{b_k} (\rho(s)q(s)(1-p(s-\sigma))) \frac{\int_{t_2}^{s-\sigma} \frac{\int_{t_1}^{v} \frac{1}{a(u)} du}{b(v)} dv}{\int_{t_1}^{s} \frac{1}{a(u)} du} - \frac{a(s)(\rho'(s))^2}{4\rho(s)}) ds = \infty, \quad (2..4)$$

$$\lim_{t \to \infty} \int_{t_3}^t \left[\frac{1}{b(v)} \int_{t_2}^v \prod_{t_1 < t_k < v} b_k \frac{1}{a(u)} \left(\int_{t_1}^u \prod_{t_1 < t_k < s} \frac{1}{b_k} L_1 q(s) ds - L_2 \right) du \right] dv = \infty,$$
(2.5)

where L_1 and L_2 are positive constants, then every solution x(t) of equation (1.1) is either oscillatory or satisfying $\lim_{t\to\infty} x(t) = 0$.



(2.8)

Proof. Let x(t) be a nonoscillatory solution of equation (1.1). Without loss of generality, we may suppose that $x(t) > 0, x(t-\tau) > 0$, and $x(t-\sigma) > 0$ for all $t \ge t_1 \ge t_0$. For $t \ne t_k$ from (1.2), there exists $t \ge t_1 \ge t_0$ such that the following two cases arise:

(1)
$$z(t) > 0, z'(t) > 0, (b(t)z'(t))' > 0, [a(t)(b(t)z'(t))']' \le 0;$$

(2)
$$z(t) > 0, z'(t) < 0, (b(t)z'(t))' > 0, [a(t)(b(t)z'(t))']' \le 0$$

for all $t \ge t_2 \ge t_1$. Assume that case(1) holds. For $t \ne t_k$ define a function ω by

$$\omega(t) = -\rho(t) \frac{a(t)(b(t)z'(t))'}{b(t)z'(t)}, t \ge t_2.$$
(2.6)

Then $\omega(t_k^+) < 0, k = 1, 2, \dots$ and $\omega(t) < 0$, for $t \ge t_2$. Differentiating (2.6), we have

$$\omega'(t) = -\rho'(t)\frac{a(t)(b(t)z'(t))'}{b(t)z'(t)} - \rho(t)\frac{(a(t)(b(t)z'(t))')'}{b(t)z'(t)} + \rho(t)\frac{a(t)(b(t)z'(t))'(b(t)z'(t))'}{(b(t)z'(t))^2}.$$
 (2.7)

Since z'(t) > 0, we have

 $x(t) \ge (1 - p(t))z(t), t \neq t_k, and \ t \ge t_2.$

It follows from equation (1.1), (2.7) and (2.8) that

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$$\omega'(t) \ge -\frac{\rho'(t)}{\rho(t)}\omega(t) + \rho(t)q(t)(1-p(t-\sigma))\frac{z(t-\sigma)}{b(t)z'(t)} + \frac{\omega^2(t)}{\rho(t)a(t)}.$$

or

$$\frac{\omega'(t) \ge -\frac{\rho'(t)}{\rho(t)}\omega(t) + \rho(t)q(t)(1-p(t-\sigma))}{b(t-\sigma)z'(t-\sigma)} \frac{z(t-\sigma)}{b(t-\sigma)z'(t-\sigma)} + \frac{\omega^2(t)}{\rho(t)a(t)}, t \ne t_k, t \ge t_2.$$
(2.9)

Now,

$$b(t)z'(t) \ge \int_{t_1}^t \frac{a(s)(b(s)z'(s))'}{a(s)} ds \ge a(t)(b(t)z'(t))' \int_{t_1}^t \frac{1}{a(s)} ds.$$
(2.10)

Thus

$$(\frac{b(t)z'(t)}{\int_{t_1}^t \frac{1}{a(s)} ds})' \le 0.$$
 (2.11)

Therefore,

$$z(t) = z(t_{2}) + \int_{t_{2}}^{t} \frac{b(s)z'(s)}{\int_{t_{1}}^{s} \frac{1}{a(u)} du} \frac{\int_{t_{1}}^{s} \frac{1}{a(u)} du}{b(s)} ds,$$

$$\geq \frac{b(t)z'(t)}{\int_{t_{1}}^{t} \frac{1}{a(u)} du} \int_{t_{2}}^{t} \frac{\int_{t_{1}}^{s} \frac{1}{a(u)} du}{b(s)} ds, t \ge t_{2} > t_{1}.$$
(2.12)

Using (2.11) and (2.12) in (2.9), we obtain

$$\omega'(t) \ge -\frac{\rho'(t)}{\rho(t)}\omega(t) + \rho(t)q(t)(1-p(t-\sigma))\frac{\int_{t_2}^{t-\sigma} \frac{\int_{t_1}^{s} \frac{1}{a(u)} du}{b(s)} ds}{\int_{t_1}^{t-\sigma} \frac{1}{a(u)} du} - \frac{\int_{t_1}^{t-\sigma} \frac{1}{a(u)} du}{\int_{t_1}^{t} \frac{1}{a(u)} du} + \frac{\omega^2(t)}{\rho(t)a(t)}$$

$$= -\frac{\rho'(t)}{\rho(t)}\omega(t) + \rho(t)q(t)(1-p(t-\sigma))\frac{\int_{t_2}^{t-\sigma}\frac{\int_{t_1}^{s}\frac{1}{a(u)}du}{b(s)}ds}{\int_{t_1}^{t}\frac{1}{a(u)}du} + \frac{\omega^2(t)}{\rho(t)a(t)}$$

or

$$\omega'(t) \ge \rho(t)q(t)(1-p(t-\sigma)) \frac{\int_{t_2}^{t-\sigma} \frac{\int_{t_1}^{s} \frac{1}{a(u)} du}{b(s)} ds}{\int_{t_1}^{t} \frac{1}{a(u)} du} - \frac{a(t)(\rho'(t))^2}{4\rho(t)}, t \ne t_k \text{ and } t_2 \ge t_1.$$
(2.13)

Since $t_{k+1} - t_k > \tau$ for each $k \in \mathbb{N}$, we have

$$t_k < t_{k+1} - \tau < t_{k+1}. \tag{2.14}$$

Since x, x', x'' are continuous on $(t_k, t_{k+1}]$, we have from the inequality (2.14) that

$$z(t_{k}^{+}) = x(t_{k}^{+}) + p(t_{k}^{+})x(t_{k}^{+} - \tau)$$

= $a_{k}x(t_{k}) + p(t_{k})x(t_{k} - \tau)$
 $\leq z(t_{k}), k = 1, 2,$ (2.15)

Now

$$z'(t_{k}^{+}) = x'(t_{k}^{+}) + p'(t_{k}^{+})x(t_{k}^{+} - \tau) + p(t_{k}^{+})x'(t_{k}^{+} - \tau)$$

$$= b_{k}x(t_{k}) + p'(t_{k})x'(t_{k} - \tau) + p(t_{k})x'(t_{k} - \tau)$$

$$\leq b_{k}z'(t_{k}), k = 1, 2,$$
(2.16)

Similarly

$$z''(t_{k}^{+}) = x''(t_{k}^{+}) + p''(t_{k}^{+})x(t_{k}^{+} - \tau) + 2p'(t_{k}^{+})x'(t_{k}^{+} - \tau) + p(t_{k}^{+})x''(t_{k}^{+} - \tau)$$

$$= c_{k}x''(t_{k}) + p''(t_{k})x(t_{k} - \tau) + 2p'(t_{k})x'(t_{k} - \tau) + p(t_{k})x''(t_{k} - \tau)$$

$$\leq z''(t_{k}), k = 1, 2, \dots$$
(2.17)

Now from (2.16) and (2.17), we have

$$\omega(t_k^+) = -\rho(t_k^+)a(t_k^+) \left(\frac{b(t_k^+)z''(t_k^+) + b'(t_k^+)z'(t_k^+)}{b(t_k^+)z'(t_k^+)}\right)$$



$$= -\rho(t_{k}^{+})a(t_{k}^{+})\left(\frac{z''(t_{k}^{+})}{z'(t_{k}^{+})} + \frac{b'(t_{k}^{+})}{b(t_{k}^{+})}\right)$$

$$\geq -\rho(t_{k})a(t_{k})\left(\frac{z''(t_{k})}{b_{k}z'(t_{k})} + \frac{b'(t_{k})}{b(t_{k})}\right)$$

$$\geq \frac{1}{b_{k}}\omega(t_{k}), k = 1, 2, \dots$$
(2.18)

Using Lemma 2.1 in (2.13) and (2.18), we obtain

$$\omega(t) \ge \omega(t_3) \prod_{t_3 \le t_k \le t} \frac{1}{b_k} + \int_{t_3}^t \prod_{s \le t_k \le t} \frac{1}{b_k} \quad (\rho(s)q(s)(1 - p(s - \sigma)))$$
$$\frac{\int_{t_2}^{s - \sigma} \frac{\int_{t_1}^v \frac{1}{a(u)} du}{b(v)} dv}{\int_{t_1}^s \frac{1}{a(u)} du} - \frac{a(s)(\rho'(s))^2}{4\rho(s)}) ds$$

Taking limit as $t \rightarrow \infty$ and using (2.4) we get a contradiction with $\omega(t) < 0$.

Next assume that case (2) holds. Since z(t) is nonincreasing, we have $z(t) \rightarrow L \ge 0$. If L > 0, then for any $\varepsilon > 0$, there exists $t_4 \ge t_3$ such that $L + \varepsilon > z(t) > L$, eventually for $t \ge t_4$. Choose $\varepsilon = \frac{L(1-p)}{2p}$. Then for $t \ne t_k, t \ge t_4$ we have

$$x(t) = z(t) - p(t)x(t - \tau) > L - pz(t - \tau)$$
$$> L - p(L + \varepsilon)$$
$$= \frac{L(1 - p)}{2} = L_1, say.$$

From equation (1.1), we have

$$(a(t)(b(t)(x(t) + p(t)x(t - \tau))')') = -q(t)x(t - \sigma) \le -L_1q(t), t \ne t_k, t \ge t_4.$$
(2.19)

For k = 1, 2, ...

$$z'(t_{k}^{+}) = x'(t_{k}^{+}) + p'(t_{k}^{+})x(t_{k}^{+} - \tau) + p(t_{k}^{+})x'(t_{k}^{+} - \tau)$$

$$= b_{k}x'(t_{k}) + p'(t_{k})x'(t_{k} - \tau) + p(t_{k})x'(t_{k} - \tau)$$

$$\leq b_{k}z'(t_{k}).$$
(2.20)

Also

$$a(t_{k}^{+})(b(t_{k}^{+})z'(t_{k}^{+}))' = a(t_{k}^{+})(b'(t_{k}^{+})z'(t_{k}^{+}) + b(t_{k}^{+})z''(t_{k}^{+}))$$

$$= a(t_{k})(b'(t_{k})b_{k}z'(t_{k}) + b(t_{k})z''(t_{k}))$$

$$\leq b_{k}a(t_{k})(b(t_{k})z'(t_{k}))'.$$
(2.21)

Using Lemma 2.1 in (2.19) and (2.21), we obtain



$$(a(t)(b(t)z'(t))') \leq (a(t_1)(b(t_1)z'(t_1))') \prod_{t_1 \leq t_k \leq t} b_k - L_1 \int_{t_1}^t \prod_{s \leq t_k \leq t} b_k q(s) ds$$
$$(b(t)z'(t))' \leq \frac{L_2}{a(t)} \prod_{t_1 \leq t_k \leq t} b_k - \frac{L_1}{a(t)} \int_{t_1}^t \prod_{s \leq t_k \leq t} b_k q(s) ds$$

where $L_2 = a(t_1)(b(t_1)z'(t_1))' > 0.$

Again using Lemma 2.1 in the last inequality, we have

$$b(t)z'(t) \le b(t_2)z'(t_2) \prod_{t_2 \le t_k \le t} b_k + \int_{t_2}^t \prod_{u \le t_k \le t} b_k [\prod_{t_1 \le t_k \le u} b_k \frac{L_2}{a(u)} - \frac{L_1}{a(u)} \int_{t_1}^u \prod_{s < t_k \le u} b_k q(s) ds] du$$

or

$$z'(t) \le \frac{1}{b(t)} \int_{t_2}^{t} \prod_{t_1 \le t_k \le t} b_k \left[\frac{L_2}{a(u)} - \frac{L_1}{a(u)} \int_{t_1}^{u} \prod_{t_1 \le t_k \le s} \frac{1}{b_k} q(s) ds \right] du.$$
(2.22)

Using Lemma 2.1 in (2.15) and (2.22), we obtain

$$z(t) \leq z(t_3) - \int_{t_3}^t \left[\frac{1}{b(v)} \int_{t_2}^v \prod_{t_1 \leq t_k \leq v} b_k - \frac{1}{a(u)} (L_1 \int_{t_1}^u \prod_{t_1 \leq t_k \leq s} \frac{1}{b_k} q(s) ds - L_2) du \right] dv.$$

Taking limit as $t \to \infty$ in the last inequality we get a contradiction with (2.5). Therefore $\lim_{t \to \infty} z(t) = 0$. Since $x(t) \le z(t)$, we have $\lim_{t \to \infty} x(t) = 0$. This completes the proof.

Theorem 2.2 Assume that (1.3) holds and there exists a function $\rho \in C^1(([t_0,\infty),(0,\infty)))$ such that for all sufficiently large $t \ge t_3 \ge t_2 \ge t_1 \ge t_0$, we have (2.4) and (2.5). If

$$\lim_{t \to \infty} \int_{t_2}^{t} \prod_{t_2 < t_k < s} b_k(\delta(s)q(s)(1-p(s-\sigma))) \int_{t_1}^{s-\sigma} \frac{du}{b(u)} - \frac{1}{4\delta(s)a(s)}) ds = \infty,$$
(2.23)

where

$$\delta(t) := \int_{t}^{\infty} \frac{1}{a(s)} ds, \qquad (2.24)$$

then every solution x(t) of equation (1.1) is either oscillatory or $\lim_{t\to\infty} x(t) = 0$.

Proof. Let x(t) be a nonoscillatory solution of equation (1.1). Without loss of generality, we may suppose that $x(t) > 0, x(t-\tau) > 0$, and $x(t-\sigma) > 0$ for $t \ge t_1 \ge t_0$. For $t \ne t_k, t \ge t_1$ from (1.3), there exist three possible cases (1), (2)(as in Theorem 2.1) and

(3)
$$z(t) > 0, z'(t) > 0, (b(t)z'(t))' < 0, [a(t)(b(t)z'(t))']' \le 0.$$

For the cases (1) and (2), we obtain the conclusion from Theorem 2.1. Now assume that case (3) holds. Since a(t)(b(t)z'(t))' is nonincreasing, we have

$$a(s)(b(s)z'(s))' \le a(t)(b(t)z'(t))', s \ge t \ge t_5 \ge t_4.$$

Dividing the above inequality by a(s) and integrating from t to l, we obtain



$$b(l)z'(l) \le b(t)z'(t) + a(t)(b(t)z'(t))' \int_{t}^{l} \frac{ds}{a(s)}$$

Letting $l \rightarrow \infty$, we have

$$0 \leq b(t)z'(t) + a(t)(b(t)z'(t))' \int_t^\infty \frac{ds}{a(s)}.$$

That is,

$$-\frac{a(t)(b(t)z'(t))'}{b(t)z'(t)}\int_{t}^{\infty}\frac{ds}{a(s)} \le 1.$$
(2.25)

Define a function ϕ by

$$\phi(t) = -\frac{a(t)(b(t)z'(t))'}{b(t)z'(t)}, t \neq t_k, t \ge t_5.$$
(2.26)

Then $\phi(t_k^+) > 0, k = 1, 2, ... and \phi(t) > 0$, for $t \ge t_5$. Hence from (2.25) and (2.26), we obtain

$$\delta(t)\phi(t) \le 1. \tag{2.27}$$

Differentiating (2.26) gives

$$\phi'(t) = -\frac{(a(t)(b(t)z'(t))')'}{b(t)z'(t)} + \frac{a(t)(b(t)z'(t))'(b(t)z'(t))'}{(b(t)z'(t))^2}, t \neq t_k, t \ge t_5.$$

From equation (1.1), (2.8) and (2.26), we obtain

$$\phi'(t) = q(t)(1 - p(t - \sigma))\frac{z(t - \sigma)}{b(t)z'(t)} + \frac{\phi^2(t)}{a(t)}, t \neq t_k, t \ge t_5.$$
(2.28)

From the third inequality in case (3), we see that

$$z(t) \ge b(t) \int_{t_5}^t \frac{ds}{b(s)} z'(t).$$
(2.29)

Hence,

$$\left(\frac{z(t)}{\int_{t_5}^t \frac{ds}{b(s)}}\right)' \le 0, t \ne t_k, t \ge t_5$$

which implies that

$$\frac{z(t-\sigma)}{z(t)} \ge \frac{\int_{t_5}^{t-\sigma} \frac{ds}{b(s)}}{\int_{t_5}^{t} \frac{ds}{b(s)}}.$$
(2.30)

Using (2.28) and (2.29) in (2.30), we have

$$\phi'(t) \ge (t)(1-p(t-\sigma))\int_{t_5}^{t-\sigma} \frac{ds}{b(s)} + \frac{\phi^2(t)}{a(t)}, t \ne t_k.$$

Multiplying the last inequality by $\delta(t)$, we have



$$\delta(t)\phi'(t) \ge \delta(t)q(t)(1-p(t-\sigma))\int_{t_5}^{t-\sigma} \frac{ds}{b(s)} + \frac{\phi^2(t)}{a(t)}\delta(t), t \neq t_k.$$
(2.31)

Now

$$(\delta(t)\phi(t))' = \delta(t)\phi'(t) + \delta'(t)\phi(t)$$

= $\delta(t)\phi'(t) - \frac{1}{a(t)}\phi(t)$
$$\geq \delta(t)q(t)(1-p(t-\sigma))\int_{t_5}^{t-\sigma} \frac{ds}{b(s)} + \frac{\phi^2(t)\delta(t)}{a(t)} - \frac{\phi(t)}{a(t)}.$$
 (2.32)

For k = 1, 2, ... from the definition of $\phi(t)$, we have

$$\phi(t_{k}^{+}) = -a(t_{k}^{+}) \left(\frac{b(t_{k}^{+})z''(t_{k}^{+}) + b'(t_{k}^{+})z'(t_{k}^{+})}{b(t_{k}^{+})z'(t_{k}^{+})} \right)$$

$$= -a(t_{k}^{+}) \left(\frac{z''(t_{k}^{+})}{z'(t_{k}^{+})} + \frac{b'(t_{k}^{+})}{b(t_{k}^{+})} \right)$$

$$\geq -\rho(t_{k})a(t_{k}) \left(\frac{z''(t_{k})}{b_{k}z'(t_{k})} + \frac{b'(t_{k})}{b(t_{k})} \right)$$

$$\geq \frac{1}{b_{k}} \phi(t_{k}), k = 1, 2,$$
(2.33)

Using Lemma 2.1 in (2.32) and (2.33) for all $t_6 \ge t_5$, we obtain

$$\delta(t)\phi(t) \ge \delta(t_6)\phi(t_6) \prod_{t_6 < t_k < t} \frac{1}{b_k} + \int_{t_6}^{t} \prod_{s < t_k < t} \frac{1}{b_k} (\delta(s)q(s)(1 - p(s - \sigma)))$$
$$\int_{t_5}^{s - \sigma} \frac{du}{b(u)} + \frac{\phi^2(s)\delta(s)}{a(s)} - \frac{\phi(s)}{a(s)})ds,$$

or

$$\delta(t)\phi(t) \ge \prod_{t_6 < t_k < t} \frac{1}{b_k} [\delta(t_6)\phi(t_6) + \int_{t_6}^t \prod_{t_6 < t_k < s} b_k(\delta(s)q(s)(1 - p(s - \sigma))) \\ \int_{t_5}^{s - \sigma} \frac{du}{b(u)} - \frac{1}{4\delta(s)a(s)}) ds].$$

Taking limit as $t \to \infty$ in the last inequality, we obtain a contradiction with (2.23) due to (2.27). Now the proof is complete. **Theorem 2.3** Assume that (1.4) holds and and there exists a function $\rho \in C^1(([t_0,\infty), (0,\infty))$ such that for all sufficiently large $t \ge t_3 \ge t_2 \ge t_1 \ge t_0$, we have (2.4) ,(2.5) and (2.23). If

$$\lim_{t \to \infty} \int_{t_1}^{t} \frac{1}{b(v)} \int_{t_1}^{v} \prod_{t_1 \le t_k \le v} b_k \frac{1}{a(u)} \int_{t_1}^{u} \prod_{s < t_k \le u} b_k \eta(s) q(s) \xi(t - \sigma) ds du dv = \infty,$$
(2.34)

where

$$\eta(t) = (1 - p(t - \sigma)) \frac{\xi(t - \tau - \sigma)}{\xi(t - \sigma)} > 0, \quad \xi(t) = \int_{t}^{\infty} \frac{1}{b(s)} ds,$$
(2.35)



then every solution x(t) of equation (1.1) is either oscillatory or $\lim_{t \to \infty} x(t) = 0$.

Proof. Let x(t) be a nonoscillatory solution of equation (1.1). Without loss of generality, we may suppose that $x(t) > 0, x(t-\tau) > 0$, and $x(t-\sigma) > 0$ for $t \ge t_1 \ge t_0$. For $t \ne t_k, t \ge t_1$ from (1.4), there exist four possible cases (1), (2), (3)(as in Theorem 2.2) and

(4)
$$z(t) > 0, z'(t) < 0, (b(t)z'(t))' < 0, [a(t)(b(t)z'(t))']' \le 0,$$

For the cases (1),(2) and (3), we obtain the conclusion from Theorem 2.2. Now assume that case (4) holds. Since b(t)z'(t) is non increasing, we have

$$b(s)z'(s) \le b(t)z'(t), s \ge t \ge t_6 \ge t_5.$$
 (2.36)

Dividing (2.36) by b(s) and then integrating from t to ℓ , and letting $\ell \to \infty$, we have

$$z(t) \ge -b(t)z'(t)\int_{t}^{\infty} \frac{1}{b(s)} ds = -b(t)z'(t)\xi(t) := M\xi(t), t \neq t_{k}.$$
(2.37)

where M = -b(t)z'(t) > 0. Hence

$$\left(\frac{z(t)}{\xi(t)}\right) \ge 0. \tag{2.38}$$

From (2.38), we see that

$$x(t) = z(t) - p(t)x(t-\tau) \ge z(t) - p(t)z(t-\tau)$$
$$\ge \left(1 - p(t)\frac{\xi(t-\tau)}{\xi(t)}\right)z(t), t \ne t_k.$$
(2.39)

From equation (1.1), (2.37) and (2.39), we have

$$(a(t)(b(t)z'(t))')' \le -Mq(t)\eta(t)\xi(t-\sigma).$$
(2.40)

From equation (2.16), we have

$$b(t_k^+)z'(t_k^+) \le b_k b(t_k)z'(t_k).$$
(2.41)

Using (2.41), we have

$$(b(t_{k}^{+})z'(t_{k}^{+}))' = b'(t_{k}^{+})z'(t_{k}^{+}) + b(t_{k}^{+})z''(t_{k}^{+})$$

$$\leq b'(t_{k})b_{k}z'(t_{k}) + b(t_{k})z''(t_{k})$$

$$\leq b_{k}(b(t_{k})z'(t_{k}))'.$$
(2.42)

Using Lemma 2.1 in (2.40) and (2.42) for $t_6 > t_5$, we obtain

$$a(t)(b(t)z'(t))' \le a(t_6)(b(t_6)z'(t_6))' \prod_{t_6 < t_k < t} b_k - M \int_{t_6}^t \prod_{s < t_k < t} b_k q(s)$$

$$\eta(s)\xi(s - \sigma)ds$$

or

$$(b(t)z'(t))' \leq -\frac{M}{a(t)} \int_{t_6}^t \prod_{s < t_k < t} b_k q(s) \eta(s) \xi(s - \sigma) ds.$$

$$(2.43)$$

Again using Lemma 2.1 in (2.41) and (2.43), we obtain



$$b(t)z'(t) \le b(t_6)z'(t_6) \prod_{t_6 < t_k < t} b_k - M \int_{t_6}^t \prod_{u < t_k < t} b_k \frac{1}{a(u)} \int_{t_6 < t_k < u}^u \prod_{s < t_k < u} b_k \frac{1}{q(s)\eta(s)\xi(s-\sigma)dsdu}.$$

Dividing the last inequality by b(t) and using (2.15) in Lemma 2.1, we have

$$z(t) \le z(t_6) - M \int_{t_6}^t \frac{1}{b(v)} \int_{t_6 < t_k < v}^v \prod_{t_6 < t_k < v} b_k (\frac{1}{a(u)} \int_{t_6 < t_k < u}^u b_k q(s) \eta(s) \xi(s - \sigma) ds) du dv.$$

Taking limit as $t \rightarrow \infty$ in the last inequality we get a contradiction with (2.34). This completes the proof.

3 EXAMPLES

In this section we provide two examples to illustrate the main results.

Example 3.1 Consider the following third order impulsive differential equation

$$\begin{cases} [e^{\frac{t}{2}}(x(t) + \frac{1}{2e}x(t-1))'']' + \frac{3}{4}e^{\frac{t}{2}-2}x(t-2) = 0, t \ge 3, t \ne t_k; \\ x(t_k^+) = \left(\frac{1}{k}\right)x(t_k), \quad x'(t_k^+) = \left(\frac{k+1}{k}\right)x'(t_k) \\ x''(t_k^+) = \left(\frac{1}{k}\right)x''(t_k), k = 1, 2, \dots \end{cases}$$
(3.1)

Here $a(t) = e^{\frac{t}{2}}, b(t) = 1, p(t) = \frac{1}{2e}, q(t) = \frac{3}{4}e^{\frac{t}{2}-2}, \tau = 1, \sigma = 2, a_k = c_k = \frac{1}{k}, b_k = \frac{k+1}{k}$. It is easy to see that all

the conditions of Theorem 2.2 are satisfied with $\rho(t) = 1$. Hence any solution of equation (2.34) is either oscillatory or converging to zero.

Example 3.2 Consider the following third order impulsive differential equation

$$\begin{cases} \left[e^{t}(e^{t}(x(t) + \frac{1}{e}x(t-1))')'\right]' + \frac{4}{e^{2}}x(t-2) = 0, t \ge 3, t \ne t_{k}; \\ x(t_{k}^{+}) = \left(\frac{1}{k}\right)x(t_{k}), \quad x'(t_{k}^{+}) = \left(1 + \frac{1}{k}\right)x'(t_{k}) \\ x''(t_{k}^{+}) = x''(t_{k}), k = 1, 2, \dots \end{cases}$$

$$(3.2)$$

Here $a(t) = b(t) = e^t$, $p(t) = \frac{1}{e}$, $q(t) = \frac{4}{e^2}$, $\tau = 1$, $\sigma = 2$, $a_k = \frac{1}{k}$, $b_k = 1 + \frac{1}{k}$, $c_k = 1$. It is easy to see that all the

conditions of Theorem 2.3 are satisfied with $\rho(t) = 1$. Hence any solution of equation (3.1) is either oscillatory or converging to zero.

ACKNOWLEDGEMENT

First author gratefully acknowledges the Research Fellowship granted by the University Grants Commission for Meritorious students in Sciences.

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