

Rational Contractions in b-Metric Spaces

Arben Isufati Department of Mathematics; Faculty of Natural Sciences University of Gjirokastra, Gjirokastra. Albania benisufati@vahoo.com

ABSTRACT

In this paper, we prove fixed point theorems for contractions and generalized weak contractions satisfying rational expressions in complete b-metric spaces. Our results generalize several well-known comparable results in the literature.

Keywords:

Fixed point; rational type; generalized weak contraction; b-metric spaces.

Academic Discipline And Sub-Disciplines

Applied Mathematics.

Mathematics Subject Classification:

47H10, 54H25.



Council for Innovative Research

Peer Review Research Publishing System

Journal: Journal of Advances in Mathematics

Vol 5, No. 3 editor@cirworld.com www.cirworld.com, member.cirworld.com



1. INTRODUCTION

The Banach contraction principle is a very popular tool for solving problems in nonlinear analysis. Generalizations of this principle have been obtained in several directions. The following is an example of such generalizations. Jaggi in [7] proved the following fixed point theorem satisfying a contractive condition of rational type.

Theorem 1.1 Let *T* be a continuous self-map defined on a complete metric space (X, d). Suppose that *T* satisfies the following contractive condition:

$$d(T(x), T(y)) \le \alpha \frac{d(y, T(y))d(x, T(x))}{d(x, y)} + \beta d(x, y), \forall x, y \in X, x \neq y$$
(1.1)

where $\alpha, \beta \in [0,1)$, such that $\alpha + \beta < 1$. Then *T* has a unique fixed point.

Also, in 1975, Dass & Gupta [17] proved that every continuous self-map on the metric spaces (X, d) which satisfies the following contraction conditions:

$$d(T(x), T(y)) \le \alpha \frac{d(y, T(y))[1 + d(x, T(x))]}{1 + d(x, y)} + \beta d(x, y), \forall x, y \in X$$
(1.2)

where $\alpha, \beta \in [0,1)$ and $\alpha + \beta < 1$, have an unique fixed point.

Remark 1.2 By a simple calculation we have that every contraction which satisfies the condition (1.2) satisfies also the condition (1.1).

Another generalization of the contraction principle was suggested by Alber and Guerre-Delabriere [10] in Hilbert spaces. Rhoades [11] has shown that their result is still valid in complete metric spaces.

Definition 1.3 Let (X, d) be a metric space. A mapping $T: X \to X$ is said to be a φ -weak contraction if

$$d(Tx,Ty) \le d(x,y) - \varphi(d(x,y))$$

For all $x, y \in X$, where $\varphi: [0, \infty) \to [0, \infty)$ is a continuous and non-decreasing function with $\varphi(t) = 0$ if and only if t = 0.

Theorem 1.4 [11] Let (X,d) be a complete metric space and T be a φ -weak contraction on X. Then, T has a unique fixed point.

There exists a large number of extensions of Theorem 1.4 in literature.[19,20,21].

The concept of *b*-metric space as a generalization of metric spaces was introduced by Czerwik in [2]. After that, several interesting result about the existence of a fixed point for single-valued and multi-valued operators in b-metric space have been obtained (see [2,3,4,5,6,8,9,12,13,14])

In this paper we prove a fixed point theorems for contractions and generalized weak contractions satisfying rational expressions in complete b-metric spaces.

2. PRELIMINARIES

Definition 2.1 [1,14] Let X be a set and let $s \ge 1$ be given real number. A function $d: X \times X \to \mathbb{R}^+$ is said to be a bmetric if and only if for all $x, y, z \in X$ the following conditions are satisfied:

1. d(x, y) = 0 if and only if x = y;

2. d(x, y) = d(y, x);

3. $d(x,z) \le s[d(x,y) + d(y,z)]$

The pair (X, d) is called a b-metric space with parameter s.

There exists more examples in the literature [1, 2, 3, 17] showing that the class of b-metrics is effectively larger than that of metric spaces, since a b-metric is a metric when s = 1 in the above condition 3.



Example 1.[18] Let (X, d) be a metric space and $\rho(x, y) = (d(x, y))^p$, where p > 1 is a real number. Then ρ is a b-metric with $s = 2^{p-1}$. However, (X, ρ) is not necessarily a metric space.

For example, let X be the set of real numbers and let d(x, y) = |x - y| be the usual Euclidian metric. Then $\rho(x, y) = (x - y)^2$ is a b-metric on \mathbb{R} with s = 2, but is not a metric on \mathbb{R} .

Example 2. [4] The space $l_p (0 ,$

$$l_p = \{(x_n) \subset \mathbb{R} : \sum_{n=1}^{\infty} |x_n|^p < \infty\}$$

together with the function $\, d: l_p \,{ imes} \, l_p \,{ o} \, \mathbb{R}$,

$$d(x, y) = \left(\sum_{n=1}^{\infty} |x_n - y_n|^p\right)^{\frac{1}{p}}$$

where $x = (x_n), y = (y_n) \in l_p$ is a b-metric space with parameter $s = 2^{\overline{p}} > 1$.

Example 3. [4] The space $L_p(0 of all real functions <math>x(t), t \in [0,1]$ such that:

$$\int |x(t)|^p dt < \infty$$

is a b-metric space if we take

$$d(x, y) = (\int_{0}^{1} |x(t) - y(t)|^{p} dt)^{\frac{1}{p}} \text{ for each } x, y \in L_{p}.$$

The parameter $s = 2^p > 1$

We need the following definitions.

Definition 2.2. Let (X, d) be a b-metric space. Then a sequence $(x_n)_{n \in \mathbb{N}}$ is called:

- (a) b-convergent if there exists $x \in X$ such that $d(x_n, x) \to 0$ as $n \to \infty$. In this case, we write $\lim x_n = x$.
- (b) b-Cauchy if $d(x_n, x_m) \rightarrow 0$, as $n, m \rightarrow \infty$.

Proposition 2.3. In a b-metric space (X, d), the following assertions hold:

- (p_1) A b-convergent sequence has a unique limit.
- (p_2) Each b-convergent sequence is b-Cauchy.
- (p_3) In general, a b-metric is not continuous as the following example shows.

Example 4. [see Example 3 in 16] Let $X = \mathbb{N} \cup \{0\}$ and let $d: X \times X \to \mathbb{R}$ be defined by:



$$d(m,n) = \begin{cases} 0 & \text{if } m = n \\ \left| \frac{1}{m} - \frac{1}{n} \right| & \text{if } m \text{ and } n \text{ are even or } mn = \infty \\ 5 & \text{if } m \text{ and } n \text{ are odd } and m \neq n \\ 2 & \text{otherwise} \end{cases}$$

It is easy to see that for all $m, n, p \in X$, we have:

$$d(m,n) \le 3(d(m,p) + d(p,n))$$

Thus, (X, d) is a b-metric space with s = 3.

Let $x_n = 2n$ for each $n \in \mathbb{N}$.

Then

$$d(2n,\infty) = \frac{1}{2n} \to 0 \text{ as } n \to \infty$$

That is, $x_n \to \infty$, but $d(x_n, 1) = 2 \not A d(\infty, 1)$ as $n \to \infty$.

Aghajani et al. [1] proved the following simple lemma about the b-convergent sequences.

Lemma 2.4 [1] Let (X, d) be a b-metric space with $s \ge 1$, and suppose that $(x_n)_{n \in \mathbb{N}}$ and $(y_n)_{n \in \mathbb{N}}$ b-converge to x, y respectively. Then, we have

$$\frac{1}{s^2}d(x, y) \le \liminf_{n \to \infty} d(x_n, y_n) \le \limsup_{n \to \infty} d(x_n, y_n) \le s^2 d(x, y)$$

In particular, if x = y, then, $\lim_{n \to \infty} d(x_n, y_n) = 0$. Moreover, for each $z \in X$ we have

$$\frac{1}{s}d(x, y) \le \liminf_{n \to \infty} d(x_n, z) \le \limsup_{n \to \infty} d(x_n, z) \le sd(x, z)$$

Lemma 2.5 [5] Let (X,d) be a b-metric space with parameter s and $(x_n)_{n\in\mathbb{N}}$ a sequence in X such that:

$$d(x_{n+1}, x_{n+2}) \le q d(x_n, x_{n+1}), \text{ for all } n \in \mathbb{N}$$

where $0 \le q < 1$. Then the sequence $(x_n)_{n \in \mathbb{N}}$ is Cauchy sequence in X provided that sq < 1.

3. MAIN RESULTS

Theorem 3.1 Let (X,d) be a complete b-metric space with parameter *s* and with continuous b-metric in each variable, $T: X \to X$ be a continuous mapping such that:

$$d(T(x),T(y)) \le \alpha \frac{d(y,T(y))d(x,T(x))}{d(x,y)} + \beta d(x,y), \forall x, y \in X, x \neq y$$
(3.1)

where α, β are positive real constants such that $s\beta + \alpha < 1$. Then T has a unique fixed point.

Proof. For a arbitrary point $x_0 \in X$ we construct the sequence $(x_n)_{n \in \mathbb{N}}$ such that $x_{n+1} = f(x_n)$ for all $n \in \mathbb{N}$.

So



$$d(x_1, x_2) = d(Tx_0, Tx_1) \le \alpha \frac{d(x_0, Tx_0)d(x_1, Tx_1)}{d(x_0, x_1)} + \beta d(x_0, x_1)$$
$$= \alpha \frac{d(x_0, x_1)d(x_1, x_2)}{d(x_0, x_1)} + \beta d(x_0, x_1)$$

Equivalently $d(x_1, x_2) \leq \frac{\beta}{1-\alpha} d(x_0, x_1)$ where $\frac{\beta}{1-\alpha} = k < 1$.

Similarly, $d(x_2, x_3) \le k(d(x_1, x_2))$

Inductively:

$$d(x_{n}, x_{n+1}) = d(Tx_{n-1}, Tx_{n}) \le \alpha \frac{d(x_{n-1}, Tx_{n-1})d(x_{n}, Tx_{n})}{d(x_{n-1}, x_{n})} + \beta(d(x_{n-1}, x_{n}))$$

$$\le \frac{\beta}{1-\alpha} d(x_{n-1}, x_{n}) = kd(x_{n-1}, x_{n})$$
(3.2)

By Lemma 2.5 the above sequence is Cauchy in complete b-metric space (X, d).

So there exists a $z \in X$ such that $\lim_{n \to \infty} x_n = z$.

By the continuity of T and d we have:

$$Tz = T(\lim_{n \to \infty} x_n) = \lim_{n \to \infty} Tx_n = \lim_{n \to \infty} x_{n+1} = z$$

and this prove that z is a fixed point.

If there exists another point $w \neq z$ in X such that Tw = w, then

$$d(w,z) = d(Tw,Tz) \le \frac{\alpha d(w,Tw)d(z,Tz)}{d(w,z)} + \beta d(w,z)$$
$$= \beta d(w,z) < d(w,z)$$

which is a contradiction. Hence, the fixed point is unique.

Theorem 3.2 Let (X, d) be a complete b-metric space with parameter *s* and with continuous b-metric in each variable, $T: X \to X$ be a continuous mapping such that:

$$d(F(x), F(y)) \le \alpha \frac{d(y, F(y))[1 + d(x, F(x))]}{1 + d(x, y)} + \beta d(x, y), \forall x, y \in X$$
(3.3)

where α, β are positive real constants such that $s\beta + \alpha < 1$. Then *T* has a unique fixed point.

Proof. The proof of this Theorem follows immediately by Remark 1.2 .

Theorem 3.3 Let (X, d) be a complete *b*-metric space with parameter *s* and with continuous *b*-metric in each variable, $T: X \to X$ be a continuous mapping such that:

$$sd(Tx,Ty) \le M(x,y) - \varphi(M(x,y))$$
, for all $x, y \in X$ (3.4)

where $\varphi:[0,\infty) \rightarrow [0,\infty)$ is continuous and non-decreasing function with $\varphi(t) = 0$ if and only if t = 0 and

$$M(x, y) = \max\{\frac{d(Tx, Tx)d(y, Ty)}{d(x, y)}, d(x, y)\}$$
(3.5)

Then T has a fixed point.

Proof. Let $x_0 \in X$ be such that $x_0 \neq Tx_0$. We construct the sequence $(x_n)_{n \in \mathbb{N}}$ in X as follows

$$x_{n+1} = T(x_n), \qquad n = 0, 1, 2, ...$$

$$d(x_n, x_{n+1}) \le sd(x_n, x_{n+1}) = sd(Tx_{n-1}, Tx_n)$$

$$\le \max\{\frac{d(x_{n-1}, Tx_{n-1})d(x_n, Tx_n)}{d(x_{n-1}, x_n)}, d(x_{n-1}, x_n)\}$$

$$-\varphi(\max\{\frac{d(x_{n-1}, Tx_{n-1})d(x_n, Tx_n)}{d(x_{n-1}, x_n)}, d(x_{n-1}, x_n)\})$$

$$= \max\{d(x_n, x_{n+1}), d(x_{n-1}, x_n)\} - \varphi(\max\{d(x_n, x_{n+1}), d(x_{n-1}, x_n)\})$$

(3.6)

Suppose that there exists n_0 such that $d(x_{n_0}, x_{n_0+1}) > d(x_{n_0-1}, x_{n_0})$.

Then from (3.6)

$$d(x_{n_0}, x_{n_0+1}) \le \max\{d(x_{n_0}, x_{n_0+1}), d(x_{n_0-1}, x_{n_0})\} -\varphi(\max\{d(x_{n_0}, x_{n_0+1}), d(x_{n_0-1}, x_{n_0})\}) = d(x_{n_0}, x_{n_0+1}) - \varphi(d(x_{n_0-1}, x_{n_0})) < d(x_{n_0}, x_{n_0+1})$$

which is a contradiction. Hence, $d(x_n, x_{n+1}) \le d(x_{n-1}, x_n)$ for all $n \ge 1$ and so the $(d(x_n, x_{n+1}))_{n \in \mathbb{N}}$ is a non-increasing sequence of positive real numbers.

Then there exists $r \ge 0$ such that $\lim_{n \to \infty} d(x_n, x_{n+1}) = r$.

Taking the limit as $n \to \infty$ in (3.6) and using the properties of the function φ and the continuity of the distance d we get

$$r \leq r - \varphi(r)$$

Which satisfy if and only if r = 0, that is

$$\lim_{n \to \infty} d(x_n, x_{n+1}) = 0 \tag{3.7}$$

Next, we show that $(x_n)_{n\in\mathbb{N}}$ is a *b*-Cauchy sequence in *X*. Suppose the contrary, that is, $(x_n)_{n\in\mathbb{N}}$ is a not a *b*-Cauchy sequence. Then there exists $\varepsilon > 0$ for which we can find two subsequences (x_{m_k}) and (x_{n_k}) of $(x_n)_{n\in\mathbb{N}}$ such that n_k is smallest index for which

$$n_k > m_k > k, \ d(x_{m_k}, x_{n_k}) \ge \varepsilon.$$
 (3.8)

This means that

$$d(x_{m_{k}}, x_{n_{k}-1}) < \varepsilon \tag{3.9}$$

From (3.8) and (3.9) we have:

$$\varepsilon \leq d(x_{m_k}, x_{n_k}) \leq sd(x_{m_k}, x_{m_{k-1}}) + sd(x_{m_{k-1}}, x_{n_k})$$

$$\leq sd(x_{m_k}, x_{m_{k-1}}) + s^2 d(x_{m_{k-1}}, x_{n_{k-1}}) + s^2 d(x_{n_{k-1}}, x_{n_k})$$
(3.10)

Using (3.7) and taking the upper limit as $k \rightarrow \infty$, we get



$$\frac{\varepsilon}{s^2} \le \limsup_{k \to \infty} d(x_{m_k - 1}, x_{n_k - 1})$$
(3.11)

By triangular inequality, we have

$$d(x_{m_k-1}, x_{n_k-1}) \le sd(x_{m_k-1}, x_{m_k}) + sd(x_{m_k}, x_{n_k-1})$$

Taking the upper limit as $\,k \,{\rightarrow}\,\infty$, we get

$$\limsup_{k \to \infty} d(x_{m_k - 1}, x_{n_k - 1}) \le \varepsilon s \tag{3.12}$$

So, by (3.11) and (3.12) we have

$$\frac{\varepsilon}{s^2} \le \limsup_{k \to \infty} d(x_{m_k - 1}, x_{n_k - 1}) \le \varepsilon s$$
(3.13)

From (3.4) and (3.5), we have

$$sd(x_{m_{k}}, x_{n_{k}}) =$$

$$sd(Tx_{m_{k}-1}, Tx_{n_{k}-1}) \leq \max\{\frac{d(x_{m_{k}-1}, Tx_{m_{k}-1})d(x_{n_{k}-1}, Tx_{n_{k}-1})}{d(x_{m_{k}-1}, x_{n_{k}-1})}, d(x_{m_{k}-1}, x_{n_{k}-1})\}$$

$$-\varphi(\max\{\frac{d(x_{m_{k}-1}, Tx_{m_{k}-1})d(x_{n_{k}-1}, Tx_{n_{k}-1})}{d(x_{m_{k}-1}, x_{n_{k}-1})}, d(x_{m_{k}-1}, x_{n_{k}-1})\})$$

$$=\max\{\frac{d(x_{m_{k}-1}, x_{m_{k}})d(x_{n_{k}-1}, x_{n_{k}})}{d(x_{m_{k}-1}, x_{n_{k}-1})}, d(x_{m_{k}-1}, x_{n_{k}-1})\}$$

$$-\varphi(\max\{\frac{d(x_{m_{k}-1}, x_{m_{k}})d(x_{n_{k}-1}, x_{n_{k}})}{d(x_{m_{k}-1}, x_{n_{k}-1})}, d(x_{m_{k}-1}, x_{n_{k}-1})\}$$

Taking the upper limit as $k \rightarrow \infty$ in (3.14) we get

$$\varepsilon s \leq \varepsilon s - \varphi(\varepsilon s) < \varepsilon$$

which is contradiction. Therefore, $(x_n)_{n \in \mathbb{N}}$ is a *b*-Cauchy sequence in *X*. Since *X* is a *b*-complete metric space, there exists $z \in X$ such that $x_n \to z$ as $n \to \infty$ and

$$z = \lim_{n \to \infty} x_{n+1} = \lim_{n \to \infty} T(x_n)$$

Using the triangular inequality, we get

$$d(z,Tz) \le sd(z,Tx_n) + sd(Tx_n,Tz)$$

Letting $n \rightarrow \infty$, we get

$$d(z,Tz) \le s \lim_{n \to \infty} d(z,Tx_n) + s \lim_{n \to \infty} d(Tx_n,Tz) = 0$$

So, we have Tz = z. Thus, z is a fixed point of T.

Corollary 3.4 Let (X, d) be a complete *b*-metric space with parameter *s* and with continuous *b*-metric in each variable, $T: X \to X$ be a continuous mapping such that:



$$sd(Tx,Ty) \le k \max\{\frac{d(Tx,Tx)d(y,Ty)}{d(x,y)}, d(x,y)\}, \text{ for all } x, y \in X$$
(3.15)

where $k \in (0,1)$. Then *T* has a fixed point.

Proof. In Theorem 3.3, taking $\varphi(t) = (1-k)t$ for all $t \in [0,\infty)$, we get Corollary 3.4.

Remark 3.5 Since a b-metric is a metric when s = 1, so our results can be viewed as a generalization and extension of several other comparable results.

REFERENCES

- [1] Aghajani A, Abbas M, Roshan J.R: 2013. Common fixed point of generalized weak contractive mappings in partially ordered b-metric spaces. Math. Slovaca. In press
- [2] Czerwik, S 1998 Nonlinear set valued contraction mappings in b-metric spaces, Atti Sem Math. Univ. Modena, 46(1998), 263-276.
- [3] S L Singh, B. Prasad, 2008. Some coincidence theorems and stability of iterative procedures, Comput. Math. Appl. 55 (2008), 2512-2520.
- [4] Berinde, V, Generalized contractions in quasimetric spaces, Seminar on fixed pointtheory, Preprint no. 3(1993), 3-9.
- [5] Czerwik, S, Contraction mappings in b-metric spaces. Acta Math. Inform. Univ. Ostraviensis 1 (1993), 5–11.
- [6] S. L. Singh, S. Czerwik, Krzysztof Krol and Abha Singh, Coincidences and Fixed points of hybrid contractions, Tamsui Oxford Journal of Mathematical Sciences 24 (4) (2008) 401-416.
- [7] D. S. Jaggi, Some unique fixed point theorems, Indian Journal of Pure and Applied Mathematics, Vol 8. no. 2, 1977, 223-230.
- [8] M. Akkouchi, A common fixed point Theorem for Expansive Mappings under Strict Implicit Conditions on b-Metric Spaces, Acta Univ. Palacki. Olomuc., Mathematica 50, 1 (2011) 5-15.
- [9] M. Akkouchi, Common Fixed Point Theorems for Two Self-mappings of a b-metric Space under an Implicit Relations, Hacettepe Journal of Mathematics and Statistics, Vol. 40 (6) (2011), 805-810.
- [10] Y. A. Alber, S. Gueer-Delabriere. (1997): Principle of weakly contractive maps in Hilbert space, Oper. Theory. Adv. Appl. 98, Birkhauser, Basel; 7-22.
- [11] B. E. Rhoades, Some theorems on weakly contractive maps, Nonlinear Anal. 47, 2683-2693, (2001).
- [12] M. Boriceanu, M. Bota, A. Petrusel, Multivalued fractals in b-metric spaces, Central European Journal of Mathematics, 8(2), 2010, 367-377.
- [13] V. Berinde, Sequences of operators and fixed points in quasimetric spaces, stud. Univ. "Babes-Bolyai", Math., 16(4)(1996), 23-27.
- [14] I. A. Bakhtin, The contraction mapping principle in almost metric spaces, Funct. Anal. 30(1989), 26-37.
- [15] M. Bota, A. Molnar, C. Varga, On Ekeland's variational principle in b-metric spaces, Fixed Point Theory, 12(2011), No. 2, 21-28.
- [16] Hussain N, Doric D, Kadelburg Z, Radenovic S: Suzuki-type fixed point results in metric spaces. Fixed Point Theory and Applications 2012: 126 (2012).
- [17] B. K. Dass, S. Gupta, An extension of Banach contraction principle through rational expression. Indian J. Pure Appl. Math 6 (1975) 1455-1458.
- [18] J. R. Roshan, V. Parvaneh, s. Sedghi, N. Shobkolaei, W. Shatanawi, Common fixed point of almost generalized $(\psi, \varphi)_s$ -contractive mappings in ordered b-metric spaces, *Fixed Point Theory and Applications* 2013, **2013**:159 doi:10.1186/1687-1812-2013-159.
- [19] D. Doric, Common fixed point for generalized (ψ, ϕ) -weak contractions. Appl. Math. Lett. 22,1896-1900, (2009)
- [20] O. Popescu, Fixed points of φ -weak contractions, Appl. Math. Lett. 24, 1-4, 2011.
- [21] Q. Zhang, Y. Song, Fixed point theory for generalized φ -weak contractions Appl. Math. Lett. 22, 75-78, 2009.



Author' biography



Doc. Dr. Arben isufati (DOB-09.06.1969)

Completed the M.Sc. studies in Mathematics from Tirana University in 2006 and completed the Ph.D. studies from Tirana University in 2012. He has got teaching experience of more than 13 years in the Department of Mathematics, Faculty of Natural Science, University of Gjirokastra. Gjirokastra. Albania.

His subject of teaching is Mathematical Analysis, Topology, Functional Analysis. His research fields are Fixed Point Theory, Fuzzy sets and Fuzzy mappings, Topology etc.

