

We are IntechOpen, the world's leading publisher of Open Access books Built by scientists, for scientists

4,800

Open access books available

122,000

International authors and editors

135M

Downloads

Our authors are among the

154

Countries delivered to

TOP 1%

most cited scientists

12.2%

Contributors from top 500 universities



WEB OF SCIENCE™

Selection of our books indexed in the Book Citation Index
in Web of Science™ Core Collection (BKCI)

Interested in publishing with us?
Contact book.department@intechopen.com

Numbers displayed above are based on latest data collected.

For more information visit www.intechopen.com



Introductory Chapter: Which Membership Function is Appropriate in Fuzzy System?

Ali Sadollah

Additional information is available at the end of the chapter

<http://dx.doi.org/10.5772/intechopen.79552>

1. Role of membership functions

Fuzzy logic systems are widely used for control, system identification, pattern recognition problems, and many more applications from industry to academia. The membership functions (MFs) play vital role in the overall performance of fuzzy representation. The MFs are the building blocks of fuzzy set theory, that is, fuzziness in a fuzzy set is determined by its MF. Accordingly, the shapes of MFs are important for a particular problem since they effect on a fuzzy inference system. They may have different shapes such as triangular, trapezoidal, Gaussian, and so forth. The only condition a MF must really satisfy is that it must vary between 0 and 1.

2. How to choose an appropriate membership function?

The MFs can be of any shape and form as long as it maps the given data with desirable degree of memberships. As far as choice of MFs is concerned, it is us to decide. This is where fuzzy system offers individual degrees of freedom. With experience, one will come to know which shape of MF is good for the application under consideration.

As there are infinite number of ways to characterize fuzziness, there are infinite number of ways to graphically depict the MFs that describe this fuzziness. The choice of which of the methods to use depends entirely on the problem size and problem type. Instead of choosing the shape of MF, setting the interval and number of MFs are also very important. For instance, to model a temperature control system by fuzzy logic, it is really important to know how

many MFs are needed (e.g., low, med, and high MF) and also choosing the intervals of MFs. These two factors also have a great impact on the outcome of a fuzzy logic system.

In addition, looking at the distribution of the data is a good idea. Although, trial and error method is often used for MF shape, because there is no exact method for choosing the MFs. The shape of MFs depends on how one believes in a given linguistic variable. It is more a question of intuition than criteria. The only condition a MF must really satisfy is that it must vary between 0 and 1. The function itself can be an arbitrary curve whose shape we can define as a function that suits us from the point of view of simplicity, convenience, speed, and efficiency. Therefore, the type of MF does not play a crucial role in shaping how the model performs.

However, the number of MF has greater influence as it determines the computational time. Hence, the optimum model can be determined by varying the number/type of MFs for achieving best system performance. Ref. [1] discusses which shape is best if one uses fuzzy logic as a universal approximator. Also, a constrained interpolations scheme was developed for fitting a MF to a finite number of known membership values [2].

There are many references giving directions of how to choose MF [3–6]. The basic problem with modeling a situation, is to break the 0–1 modeling. This can be done by using triangular MF. However, if the situation is complex and deep, we might need a special type of MF. For instance, if the problem at hand is a quantum mechanics problem, then a special MF is needed. In order to make the best choice, one needs a lot of “experience” with the given situation. This experience will tune up and best fit, the subjective choice of the researcher with the given reality. There is no objective way to do so. Thus, a high fidelity intuition based on sufficient experience will give an acceptable answer.

Generally speaking, triangular MF is one of the most encountered MF in practice. Of highly applied MFs, the triangular MFs are formed using straight lines. These straight line membership functions have the advantage of simplicity. Gaussian MFs are popular methods for specifying fuzzy sets because of their smoothness and concise notation. These curves have the advantage of being smooth and nonzero at all points.

It is advisable to use the symmetric triangular MF with 50% overlap, and then apply tuning procedure during which we can either change the left and/or right spread and/or overlapping. This is to be continued till we get satisfactory results. Same approach can be attempted for other shapes such as trapezoidal, bell-shape, and so forth.

Triangular shapes represent fuzzy numbers, while trapezoid shapes represent fuzzy intervals. These are the simplest shapes. Other different shapes can be obtained from transformations of the triangle induced by linguistic modifiers, truth-functional modifiers, compositions, projections, and other operations.

In fact, the selection of MF shape is problem specific. Based on extensive review on many literatures, it can be concluded that the triangular MF is widely used because of its simplicity. Using various MF for given problems, usually Gaussian and triangular MFs are found to be closely performing well and better than other types of MF. In specific, the triangular MF is found to be better than Gaussian MF. Zhao and Bose [7] compared the response of the system with various MFs and conveyed that the triangular MF is superior to any other MFs.

Indeed, if one has no priority on the shape of MFs, triangular or trapezoidal shapes are simple to implement and fast for computation. However, if one has some priorities on their shapes (e.g., from histograms on sampled data), it may be interested to build MFs with shapes derived from these a priori shapes after some smoothing if needed.

Afterwards, the question is what the optimal values of initial parameters are that we need to be aware of to make a sensible choice of the chosen MF?

In order to maximize their performance, it is often necessary to undertake a design optimization process in which the adjustable parameters defining a particular fuzzy system are tuned to maximize a given performance criterion. Using metaheuristic optimization methods and evolutionary optimization algorithms, fuzzy logic possesses the great flexibility toward its initial parameters regarding MFs [8].

Interested reader can find some useful information about MFs and some procedures (e.g., GA and neural network) to assign memberships to fuzzy variables [4]. There are many articles, which have used optimization algorithms such as particle swarm optimization and genetic algorithm to find the optimal set of parameters for fuzzy models [9–12].

Author details

Ali Sadollah

Address all correspondence to: ali_sadollah@yahoo.com

School of Mechanical Engineering, Sharif University of Technology, Tehran, Iran

References

- [1] Kosko B, Mitaim S. What is the best shape for a fuzzy set in function approximation? Proceedings of the 5th IEEE International Conference on Fuzzy Systems (FUZZ-96); September 1996. pp. 1237-1243
- [2] Chen JE, Otto KN. Constructing membership functions using interpolation and measurement theory. *Fuzzy Sets and Systems*. 1995;**73**(3):313-327
- [3] Wu D. Twelve considerations in choosing between Gaussian and trapezoidal membership functions in interval type-2 fuzzy logic controllers. *IEEE International Conference on Fuzzy Systems (FUZZ-IEEE)*; 2012; Brisbane, QLD, Australia
- [4] Ross TJ. *Fuzzy Logic with Engineering Applications*. 3ed. John Wiley & Sons; 2010
- [5] Rutkowska A. Influence of membership function's shape on portfolio optimization results. 2016;**6** (1):45-54
- [6] Czekalski P. Evolution-fuzzy rule based system with parameterized consequences. *International Journal of Applied Mathematics and Computer Science*. 2006;**16**(3):373-385

- [7] Zhao J, Bose BK. Evaluation of membership functions for fuzzy logic controlled induction motor drive. 28th Annual IEEE Conference of the Industrial Electronics Society 2002; Sevilla; Spain
- [8] El-Zonkoly AM, Khalil AA, Ahmied NM. Optimal tuning of lead-lag and fuzzy logic power system stabilizers using particle swarm optimization. *Expert Systems with Applications*. 2009;**36**(2):2097-2106
- [9] Zhang W, Liu Y. Fuzzy logic controlled particle swarm for reactive power optimization considering voltage stability. *IEEE International Conference on Power Engineering*, Singapore. 2005;**2005**:1-5
- [10] Esmin AAA, Aoki AR, Lambert-Torres G. Particle swarm optimization for fuzzy membership functions optimization. In: *IEEE International Conference on Systems, Man and Cybernetics*, Yasmine Hammamet, Tunisia; Tunisia; 2002
- [11] Arslan A, Kaya M. Determination of fuzzy logic membership functions using genetic algorithms. *Fuzzy Sets and Systems*. 2001;**118**(2):297-306
- [12] Zhang W, Liu Y. Fuzzy logic controlled particle swarm for reactive power optimization considering voltage stability. In: *The 7th International Conference on Power Engineering*; Singapore; January 2005. DOI: 10.1109/IPEC.2005.206969