CLUSTERING VERTICAL GROUND REACTION FORCE CURVES PRODUCED DURING COUNTERMOVEMENT JUMPS

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Abstract

The aim of this study is to assess and compare the performance of commonly used hierarchical, partitional (k-means) and Gaussian model-based (Expectation-Maximization algorithm) clustering techniques to appropriately identify subgroup patterns within vertical ground reaction force data, using a continuous waveform analysis. In addition, we also compared the performance across each technique using normalized and non-normalization input scores. Both generated and real data (one hundred-and twenty two vertical jumps) were analyzed. The performance of each cluster technique was measured by assessing the ability to explain variances in jump height using a stepwise regression analysis. Only k-means (normalized scores; 82%) and hierarchical clustering (normalized scores; 85 %) were able to extend the ability to describe variances in jump height beyond that achieved using the group analysis (i.e. one cluster; 78 %). Further, our findings strongly indicate the need to normalize the input data (similarity measure) when clustering. In contrast to the group analysis, the subgroup analysis was able to identify cluster specific phases of variance, which improved the ability to explain variances in jump height, due to the identification of cluster specific predic-

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tor variables. Our findings therefore highlight the benefit of performing a subgroup analysis and may explain, at least in part, the contrasting findings between previous studies that used a single group level of analysis.

Keywords: clustering, vertical ground reaction force, analysis of characterizing phases, countermovement jump

1 1. Introduction

The countermovement jump (CMJ) is an important task in a number 2 of sports (e.g. volleyball, basketball) and its biomechanics have been fre-3 quently studied [16]. However, identified features that relate to the per-4 formance outcome (jump height) are often inconsistent [28]. For example, 5 maximum vertical ground reaction force (vGRF) is reported in some studies 6 as a performance related factor [4, 8, 30], while it is not in others [19, 21, 24]. 7 This makes it difficult to conclude which neuromuscular capacities or movement techniques should be altered to enhance jump height, the criterion 9 performance outcome in CMJs. Recently, we have shown that some of the 10 contrasting findings across studies may be due to the use of discrete point 11 analysis [28]. An alternative to discrete point analysis is a continuous wave-12 form analysis (e.g. functional principal component analysis or analysis of 13 characterizing phases) which has grown in popularity within many disci-14 plines, including biomechanics, and has been reported to provide a better 15 insight than discrete point analysis [6, 7, 9, 11, 20, 26, 28, 29]. 16

An additional reason for the inconsistencies across studies however, may
 be inter-subject variability. Vertical ground reaction curves generated during

a CMJ can differ significantly in shape across subjects (e.g. non-modal, uni-19 modal or bi-modal), which could imply that different movement strategies 20 are being employed, which may in turn have different performance related 21 factors. This might explain some of the contrasting findings, since previous 22 studies generally employed a single group analysis which can mask perfor-23 mance related factors if different shapes have different performance related 24 factors [1, 32, 33]. An alternative to a single group analysis is a subgroup 25 analysis, which classifies similar patterns (curve shapes or movement strate-26 gies) into subgroups; so called clusters. An optimal clustering maximizes the 27 ability to predict the dependent variable (e.g. jump height) of a data set [10]. 28 To the authors' knowledge it appears that none of the previous CMJ studies 29 have used a subgroup analysis, while subgroup analyses have been frequently 30 performed in studies that examine human gait [2, 15, 22, 23, 34, 35, 37]. 31

A challenge in subgroup analysis is that a variety of clustering techniques 32 exists that may result in different clusters [12, 13, 18, 39]. Additionally, while 33 the number of studies that have used continuous waveform analysis in the 34 area of biomechanics is increasing, little is known about the performance of 35 different clustering techniques with continuous waveform analysis in biome-36 chanics. The computed continuous features aim to represent the pattern of a 37 curve over multiple phases of the movement cycle and can be highly collinear, 38 which may influence results of some clustering techniques. Clustering ap-39 proaches differ in their underlying assumptions and can be divided broadly 40 into hierarchical, partitional and probabilistic clustering [12, 18, 39]. The 41

advantage of hierarchical clustering techniques is that they provide a highly 42 interpretable description of the hierarchy within the data (i.e. dendrogram) 43 and do not require the number of clusters to be chosen prior to the analysis. 44 However, the assignment of samples into clusters requires the generation of 45 inter-point distances of the input data (where different approaches can give 46 very different results) and imposes a hierarchical structure within the exam-47 ined data [12, 18, 39]. In contrast, partitional clustering (e.g. k-means) can 48 be performed without calculating inter-point distances, it is commonly used 49 and is usually more suitable for large data sets [18]. However, k-means clus-50 tering also requires the user to choose the number of clusters (prior to anal-51 ysis) and the construction of a dendrogram is computationally prohibitive 52 [12, 13, 18, 39]. In addition, both hierarchical and partitional clustering 53 techniques follow a deterministic process where the generated clusters and 54 their members are somewhat dependent on the ordering of samples [39]. Con-55 sequently, a third method, model-based clustering might be more appropriate 56 for classifying biomechanical data. Model-based clustering techniques assign 57 individuals into clusters based on their fit to a given mathematical model. 58 An often used model is the Gaussian mixture model [10], which assigns sub-59 jects into clusters based on the nature of the statistical inference, might be 60 more appropriate for classifying movement strategies. Due to the variation 61 in clustering approaches, and the relative novelty of classifying continuous 62 biomechanical data / features, it is important to identify which clustering 63 technique has the greatest ability to recognize and appropriately separate 64

⁶⁵ patterns within multiple curves.

The primary aim of this study is to assess and compare the performance 66 of commonly used hierarchical, partitional and probabilistic clustering tech-67 niques to appropriately identify patterns within a sample of self-created 68 curves (manipulated data set) and a sample of vGRF curves captured dur-69 ing countermovement jumps (real data set), using a continuous waveform 70 analysis. A secondary aim is to examine if there are benefits to performing 71 a subgroup analysis compared to the commonly used single group analy-72 sis when identifying vertical ground reaction vGRF factors related to jump 73 height. 74

75 2. Methods

76 2.1. Data Set

Manipulated Data Set A random vGRF curve from the real data set 77 (see below) was selected and used to create a sample of 100 manipulated 78 curves, which contained three clusters to reflect some of the general shapes 79 of the vGRF curve. Curves in the first cluster (n = 41) were manipulated 80 to have a unimodal shape, where the peak value occurred from 25-30 % of 81 the cycle. Curves in the second cluster (n = 9) were manipulated to have a 82 unimodal shape, where the peak value occurred from 70-75 % of the cycle. 83 Curves in the third cluster (n = 50) were manipulated to have a bimodal 84 shape, where the peak value occurred from 75-80 % of the cycle (Figure 1). 85 To generate the manipulated data set the randomly selected curve was trans-86

formed into a function, using seven coefficients and a b-spline basis system 87 [5, 25]. The third (cluster 1 and 3) and fifth (cluster 2 and 3) coefficients 88 were multiplied with a random factor between one and two, while the fourth 89 coefficient (Cluster 3) was multiplied with a random number between minus ar one and zero. After altering the coefficients, manipulated curves were gener-91 ated by solving the altered coefficients to 101 points. Subsequently, the peak 92 position of each curve was shifted randomly in time, using a dynamical time 93 warping approach, within a random range of -2.5 and 2.5 %. The used dis-94 tribution was created *ipso facto* to model a realistic distribution, accounting 95 for low frequent modal shapes. 96

Real Data Set One-hundred-and-twenty-two male athletes (age = 22.4 ± 4.2 years; mass = 71.1 \pm 9.4 kg; height = 1.82 \pm 0.1 m), who were physically active, experienced in performing the countermovement jump (based on the sports they played: Gaelic football, hurling and basketball), and free from lower limb injury participated in this study. The University Ethics Committee approved the study and all participants were informed of any risk and signed an informed consent form before participation.

Prior to data collection, every participant performed a standard warm-up
routine consisting of low intensity jogging, stretching and ten sub-maximal
and five maximal effort countermovement jumps. Each participant performed
15 jumps without an arm swing, standing with each foot on a separate force
platform. Participants rested for 30 seconds between trials. Two force plates

(BP-600900, AMTI, MA, USA) recorded the vGRF (1000Hz). Based on 109 jump height, the best jump performance of each subject was identified and 110 used for analysis¹. Jump height was calculated using the center of mass 111 velocity at takeoff, with take-off determined when the vGRF fell below 5 N 112 [28]. The position of the center of mass was calculated using a motion analysis 113 system (Vicon 512 M, Oxford Metrics Ltd, England) to record the position 114 of twelve reflective markers (250Hz), in combination with anthropometric 115 data [38]. Reflective markers were attached bilaterally, using double sided 116 tape, on the following anatomical landmarks: fifth metatarsal joint, posterior 117 calcaneus (in line with the fifth metatarsal joint), lateral malleolus, lateral 118 femoral epicondyle, greater trochanter and the glenohumeral joint. All curves 119 were normalized to body mass and only the vGRF-time curve during the 120 propulsion phase was analyzed because it holds the information needed to 121 fully describe jump height. The start of the propulsion phase was identified 122 from the power-time curve of the body's centre of mass, when the power 123 became positive. 124

125 2.2. Data Clustering

To generate scores that capture the patterns within the continuous waveforms, an Analysis of Characterizing Phases was performed [28]. Analysis of Characterizing Phases detects phases of variation (key phases) within the

¹The best jump was used because it is a well-defined criterion and avoids taking an average of multiple curves which may have distorted the data.

sample of curves, which are used to generate participants' scores (similarity score). Similarity scores were computed for key phases using the magnitude domain. The number of similarity scores extracted for each waveform is equal to the number of identified key phases. Similarity scores were determined by calculating the area between a participant's curve (p) and the mean curve across the data set (q) for every point (i) within the key phases (Equation 1)².

similarity score =
$$\int p_i - q_i$$
 (1)

Key phases were identified using the information generated by the prin-135 cipal components needed to describe 99.5 % of the variances in the data [27]. 136 To increase the interpretability of the retained principal components a VARI-137 MAX rotation was performed [11, 26]. For further explanation of Analysis 138 of Characterizing Phases the reader is referred to a previous paper by the 139 authors [28]. Given that Analysis of Characterizing Phases generates just 140 a few similarity scores to describe a complex waveform, it was necessary to 141 insure that the generated scores preserve the information needed to cluster 142 curves with similar patterns (shapes). The quality of the preserved infor-143 mation was estimated, for only the manipulated data set, by a subjective 144 visual inspection of the generated similarity scores and was judged sufficient 145

 $^{^{2}}$ The used equation can result in a similarity score close or equal to zero when a subject and the reference signal are opposite or when a signal oscillates above and below the references signal. In the present study, the shape of the reference and subject curve followed a similar pattern within the key phases.

since a clear linear relationship exists for curves within each cluster (Figure 146 2). The reader should note that the calculation of subject score within the 147 present paper differs slightly from Richter et al. [28] to overcome a depen-148 dency of the finding on the reference signal chosen. In Richter et al. [28] 149 the best jump was selected as reference signal because the subject score cal-150 culation used absolute values to measure similarity. This approach assumes 151 that altering a curve towards the reference signal has a positive effect on 152 the dependent variable. However, this might not be true as other movement 153 strategies might represent a better movement solution. The score generation 154 approach used in the present paper overcomes this limitation and findings 155 are not dependent on the reference signal. The overall mean was selected as 156 the reference signal because it is commonly used and easy to relate to when 157 interpreting the findings. 158

To classify the manipulated and real data sets the computed similar-159 ity scores were input into a hierarchical clustering algorithm (hierarchical 160 clustering), a k-means approach (partitional clustering) and an Expectation-161 Maximization algorithm (model-based clustering). Due to the linear relation-162 ship between similarity scores within a cluster, where clusters could overlap 163 in space possibly hampering the ability of the hierarchical and the k-means 164 clustering, the hierarchical and the k-means clustering were also performed 165 using normalized similarity scores (as suggested in Jain et al. [13]). The 166 normalization was performed by transforming the similarity scores into their 167 correlation matrix (Equation 2), to quantify numerically the relationship be-168

tween the similarity scores, which cannot be described by distances of the generated similarity scores. The correlation matrix $(\hat{P}; \hat{P} \in \mathbb{R}^{122x122})$ was created by calculating the Pearson's r-value (*corr*) utilizing the similarity scores (SS) of the curves i (i = 1, 2, ..., number of curves) and j (j = 1, 2, ...,number of curves).

$$[\hat{P}]_{(i,j)} = corr_{(i,j)} = \frac{1}{N-1} \sum_{k=1}^{N} \frac{(SS_{i,k} - \mu_i) * (SS_{j,k} - \mu_j)}{\sigma_i * \sigma_j}$$
(2)

where μ is the average and σ the standard deviation for curve *i* and *j* of their corresponding similarity scores, which were calculated using the identified key phases (k = 1, 2, ..., N, where *N* is the number of identified key phases).

The hierarchical algorithm calculated pairwise distances using Euclidean 178 distance, and created a hierarchical cluster tree using the nearest distance 179 [18]. The quality of the hierarchical clustering was measured by calculating 180 the cophenetic correlation coefficient between the hierarchical cluster tree 181 and the pairwise distances [18, 31]. Hierarchical clustering properties were 182 changed if the cophenetic correlation coefficient was less than 0.7, which 183 indicates a low or medium correlation between the hierarchical cluster tree 184 and the pairwise distances³ [3]. The k-means clustering technique used the 185 squared Euclidean distance as the distance measure and the Expectation-186

 $^{^3\}mathrm{All}$ generated hierarchical cluster trees and the pairwise distances generated a cophenetic correlation coefficient above 0.7

Maximization algorithm was applied using the Gaussian mixture model [18]. 187 For the manipulated data, the performance of each clustering technique 188 was assessed by the percentage of accurately classified curves, assessed by 189 counting how often the assigned membership and the actual membership of 190 a curve matched. To examine the benefits of using a subgroup analysis, key 191 phases were identified using both a single group and a subgroup analysis, 192 and directly compared. The number of clusters in the subgroup analysis was 193 set at three clusters due to the contained number of general shapes (three 194 shapes). 195

For the real data set, the performance of each clustering technique was 196 measured by assessing the ability to explain variances in jump height (de-197 pendent variable) across generated clusters. This approach was based on the 198 assumption that an appropriate grouping of vGRF curve shapes (or similar 199 movement strategies) does not mask performance related factors and hence 200 enhances the ability to describe variances in jump height. To assess the abil-201 ity to explain variances in jump height for a given number of clusters the 202 average r^2 -value of a stepwise regression analysis was computed across these 203 clusters. The clustering technique with x clusters that generated the highest 204 ability to explain variances in jump height was considered the most appro-205 priate clustering technique for the captured vGRF curves. Input variables 206 for the regression model were similarity scores measured solely over the key 207 phases of a cluster. During the clustering process two problems can occur for 208 a given cluster solution: (a) the regression analysis does not identify a predic-209

tor variable and, (b) only one subject is assigned to a cluster. If the stepwise regression analysis was not able to identify any predictor variables, the highest r^2 -value computed during the correlation analysis between the generated similarity scores and jump height was used (irrespective of whether it was statistically significant or not)⁴. If a given cluster solution assigned only one participant to a cluster, the cluster and its member were considered as an outlier and removed from the analysis.

If the stepwise regression analysis was not able to identify any predictor variables within a cluster, the highest r²-value (irrespective of its significance) computed during the correlation analysis (between the generated similarity scores and jump height) was used. If a cluster technique assigned only one participant to a cluster, the cluster was discarded.

To examine the benefits of a subgroup analysis over a single group analysis both the key phases and the predictor variables were compared when calculated for the whole data set (single group) to the key phases the predictor variables selected within each of the generated clusters (subgroup analysis). The number of clusters was set to increase from one to ten clusters. All statistical analyses were performed using MatLab (R2012a, MathWorks Inc., USA).

⁴It should be noted that for the cases where no predictor variable was identified by the regression analysis, the sample size of the corresponding cluster was low and the correlation of an independent variable to the dependent variable was not high enough to reach a significant correlation.

229 3. Results

230 3.1. Manipulated Data Set

For the manipulated data set, the accuracy of the clustering techniques was (from high to low): hierarchical clustering utilizing normalized scores (98 % accuracy), k-means clustering utilizing normalized scores (97 % accuracy), Expectation-Maximization algorithm (95 % accuracy), hierarchical clustering utilizing similarity scores (67 % accuracy) and k-means clustering utilizing similarity scores (61 % accuracy).

Key phases differ between the single group and subgroup analysis. Key phases for the whole group analysis were identified at 20-30 %, 45-57 % and 72-82 % of the movement cycle. The key phases for each cluster, examined using a subgroup analysis were identified at 22-36 % and 82-91 % for cluster 1, 55-67 % and 78-87 % for cluster 2, and 60-68 %, and 81-89 % of the movement cycle for cluster 3.

243 3.2. Real Data Set

For the real data set, predictor variables (similarity scores computed from key phases), identified by the stepwise regression analysis, were able to explain 78 % of the variances in jump height ($r^2 = 0.78$). Hierarchical clustering (normalized scores) best described jump height using four clusters (85 %) and k-means (normalized scores) performed best using four clusters (83 %). The Expectation-Maximization algorithm, hierarchical clustering (similarity scores) and the k-means (similarity scores) were not able to increase the ability to describe jump height over that achieved using the single group
analysis (Figure 3).

Hierarchical (normalized scores) clustering explained most accurately the 253 variances in jump height but generated two clusters with sample sizes less 254 than ten members (Cluster 1 = 7; Cluster 3 = 6). For the clusters with 255 small sample sizes, the regression analysis was not able to identify predictor 256 variables. Hence, k-means (normalized scores) clustering was selected for 257 further analysis, as it had almost the same ability to describe variance in 258 jump height with larger sample sizes and better-balanced cluster sizes. Visual 259 inspection of the mean curves of the generated k-means (normalized scores) 260 clusters indicates four distinct vGRF curve shapes: (cluster 1) unimodal with 261 high initial vGRFs where peak vGRF occurs shortly after the start of the 262 concentric phase, (cluster 2) unimodal with low initial vGRF where peak 263 vGRF occurs at about 70 % of the movement cycle, (cluster 3) bimodal with 264 high initial vGRFs where peak vGRF occurs shortly after the start of the 265 concentric phase, and (cluster 4) bimodal with initial vGRFs similar to both 266 the first and second maxima where peak vGRF could occur either before 15 267 % or around 80 % of the movement cycle (Table 1; Figure 4). No significant 268 difference exists in jump height across the clusters. 269

Key phases and identified predictor variables differed between the single group and subgroup analysis, while the strongest relation to jump height occurred at around 85 % across both subgroup and single group analysis (Figure 5). All predictor variables were identified by the stepwise regression analysis. The reader should note that the subgroup analysis was able to
increase the ability to describe jump height, while using fewer data points (a
smaller percentage) of the movement cycle.

277 4. Discussion

278 4.1. Clustering Technique Comparison

The examined clustering techniques differed in their performance in both 279 the manipulated and real data sets. Using the manipulated data, the hi-280 erarchical clustering utilizing normalized scores, k-means clustering utilizing 281 normalized scores, and Expectation-Maximization algorithm performed best. 282 Using the real data set, only k-means (normalized scores) and hierarchical 283 clustering (normalized scores) extended the ability to describe variances in 284 jump height beyond that achieved using the group analysis (e.g. one clus-285 ter). With respect to the Expectation-Maximization algorithm, it was not 286 able to generate clusters with a higher ability to describe variances in jump 287 height than that achieved at a single group level (i.e. one cluster). While the 288 Expectation-Maximization algorithm was successful for the generated data 289 set, it failed to successfully classify the real data. A possible reason for this 290 contrasting performance lies in the nature of both data sets. The manipu-291 lated data set holds clear distribution patterns where peak vGRF differed 292 across curves within a cluster by only \pm 5 %. The real data set, however, 293 has much more variation and the probability distribution does not differ as 294 clearly across clusters (Figure 6). 295

296 4.1.1. Benefits of Normalizing Data

Normalizing similarity scores (transformation of scores into their corre-297 lation matrix) had a significantly positive effect on the performance of both 298 hierarchical and partitional clustering techniques, indicating that differences 299 in magnitude between similarity scores are not as effective as their quanti-300 fied numerical relationship at maximizing the ability to predict a dependent 301 variable. The same effect is likely to occur when discrete points are used 302 for clustering individuals. To the best of our knowledge, previous studies 303 that aimed to identify movement patterns by clustering discrete kinematic 304 and kinetic variables did not normalize their input variables, which may 305 have reduced their ability to recognize movement patterns [2, 15, 17, 22, 34]. 306 To date, no study has compared clustering approaches using biomechanical 307 waveforms, which makes it difficult to control the effect of normalizing the 308 input data. For this reason we applied k-means clustering to a publicly avail-309 able data set (The Berkeley Growth Data: Tuddenham and Snyder [36]). The 310 Berkeley Growth Data has been used to measure the accuracy of k-means 311 clustering (e.g. Jaques and Preda [14]) and, similar to vGRF curves, the 312 shapes of the sample of curves might hold the information needed to classify 313 the data correctly. Applying k-means to the Berkeley Growth Data using 314 non-normalized and normalized similarity scores resulted in clustering accu-315 racies of 74.2 % and 94.6 %, respectively. In the experiment of Jaques and 316

Preda $[14]^5$, the highest accuracy of k-means was 66.7 %. The increase in 317 accuracy of k-means in the present work is due to the effect of normalization 318 (accounting for ± 20.4 %) and the use of similarity scores (accounting for 319 \pm 7.5 %). The contrasting findings between non-normalized and normalized 320 scores for hierarchical and partitional techniques (for the manipulated, real 321 and Berkeley Growth data) strongly suggest that input variables should be 322 normalized when classifying curves where the curve shape might hold im-323 portant information. It should be noted, however, that other normalization 324 approaches (e.g. Euclidian distance) may lower the ability to recognize shape 325 pattern. 326

327 4.2. Benefits of Subgroup Analysis

With respect to the benefit of performing a subgroup analysis, the sub-328 group analysis alone was able to capture key phases, which reflect specific 329 characteristics of each cluster, resulting in different locations of key phases 330 and predictor variables across clusters. These differences (Figure 5) resulted 331 in a greater ability of the subgroup analysis to describe variances in jump 332 height over a group level analysis (on average +8.3 %). In addition to this 333 increased ability to describe variances in jump height, the subgroups required 334 less information (less % of the data) to predict jump height (on average 17 335 % less of the movement cycle). While previous CMJ studies have not exam-336

⁵Jaques and Preda [14], assessed the ability of k-means using non-normalized data (whole discrete curve, 20 spline coefficients and functional principal component scores)

ined the effectiveness of a subgroup analysis, gait studies have also shown its
appropriateness over a single group analysis [2, 15, 22, 34].

The subgroup analysis was able to identify four distinct vGRF curve 339 shapes. The characteristics of these clusters strengthen the idea that different 340 individuals may have different performance related factors [1, 32, 33]. The 341 combination of the knowledge of general curve shapes and the location of 342 performance related factors gives a further insight into inconsistencies in 343 respect to maximum vGRF reported in some discrete point analysis studies as 344 a performance related factor [4, 8, 30], while not in others [19, 21, 24]. In light 345 of the subgroup findings, maximum vGRF represents different neuromuscular 346 capacities across each cluster. For cluster 1 and 2 (shapes with low initial 347 vGRFs), maximum vGRF represents the ability to generate vGRFs at the 348 end of the movement cycle as the ankle, knee and hip joint extend towards 349 full extension; while it represents the ability to generate vGRFs quickly (1-15 350 %) after the start of the concentric phase for cluster 3 and 4. Consequently, 351 maximum vGRF cannot be compared using a single group analysis because 352 even if an analysis of peak vGRF accounts for different modalities of a vGRF 353 curve, it can fail to examine comparable neuromuscular capacities. The 354 present work indicates that classifying a sample of individuals into multiple 355 clusters can overcome limitations of a group analysis and hence enhances 356 the understanding of the underlying neuromuscular movement's strategies 357 during a movement task. 358

359 5. Conclusion

K-means clustering utilizing normalized subject scores appears to be the 360 most suitable technique for clustering vGRF curves, while hierarchical clus-361 tering also showed a high level of suitability. Further, when clustering curve 362 shapes, it is extremely important to normalize subject scores, by transform-363 ing them into their correlation matrix, before using a clustering technique. 364 The subgroup analysis should be used in preference to a single group anal-365 vsis because it explained greater variances in the dependent variable (jump 366 height), indicating different movement strategies for which some different 367 performance determining factors were evident. These findings may explain, 368 at least in part, the contrasting findings between previous studies that ex-369 amined vGRF during vertical jumping at the single group level of analysis. 370

371 6. Conflict of interest statement

The authors declare that no conflict of interest is associated with the present study.

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