Kent Academic Repository Full text document (pdf)

Citation for published version

Robbins, Ed and King, Andy and Schrijvers, Tom (2015) Proof appendix to accompany the paper, "From MinX to MinC: Semantics-Driven Decompilation of Recursive Datatypes". University of Kent

DOI

Link to record in KAR

http://kar.kent.ac.uk/51459/

Document Version

Author's Accepted Manuscript

Copyright & reuse

Content in the Kent Academic Repository is made available for research purposes. Unless otherwise stated all content is protected by copyright and in the absence of an open licence (eg Creative Commons), permissions for further reuse of content should be sought from the publisher, author or other copyright holder.

Versions of research

The version in the Kent Academic Repository may differ from the final published version. Users are advised to check http://kar.kent.ac.uk for the status of the paper. Users should always cite the published version of record.

Enquiries

For any further enquiries regarding the licence status of this document, please contact: **researchsupport@kent.ac.uk**

If you believe this document infringes copyright then please contact the KAR admin team with the take-down information provided at http://kar.kent.ac.uk/contact.html





A. Proof Appendix

A.1 Type Safety

We write $\Sigma; \Psi \vdash \sigma; \pi$ to signify that

 $\forall (a:\theta) \in \Psi . \Sigma; \Psi; \sigma; \pi \vdash a: \theta$

We also write $\Gamma_c; \Sigma; \Psi \vdash \rho$ to signify that

$$\forall (x:\theta) \in \Gamma_c \, . \, \Sigma; \Psi \vdash \rho(x) : \theta * \land \rho(x) \neq 0$$

Moreover, we write Γ_c ; $\Sigma \vdash \lambda_c$ to signify that

 $\forall s \in range(\lambda_c). \ \Gamma_c; \Sigma \vdash s$

Proposition 8 (safety for lvalue evaluation).

1. Progress: if • $\Gamma_c; \Sigma; \Psi \vdash \rho$ • $\Sigma; \Psi \vdash \sigma; \pi$ • $\Gamma_c; \Sigma \vdash \ell : \theta$ then (a) $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \ell \rangle \xrightarrow{\ell} \langle \sigma', \pi', a \rangle$ or (b) $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \ell \rangle \xrightarrow{\ell} \text{err.}$ 2. Preservation: if • $\Gamma_c; \Sigma; \Psi \vdash \rho$ • $\Sigma; \Psi \vdash \sigma; \pi$ • $\Gamma_c; \Sigma \vdash \ell : \theta$ • $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \ell \rangle \xrightarrow{\ell} \langle \sigma', \pi', a \rangle$ then for some $\Psi' \supseteq \Psi$ (a) $\Gamma_c; \Sigma; \Psi' \vdash \rho$ (b) $\Sigma; \Psi' \vdash \sigma'; \pi'$ (c) $\Sigma; \Psi' \vdash a : \theta *$

Proposition 9 (safety for expression evaluation).

1. Progress: if • $\Gamma_c; \Sigma; \Psi \vdash \rho$ • $\Sigma; \Psi \vdash \sigma; \pi$ • $\Gamma_c; \Sigma \vdash e : \theta$ then (a) $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e \rangle \xrightarrow{e} \langle \sigma', \pi', v \rangle$ or (b) $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e \rangle \xrightarrow{e} \text{err.}$ 2. Preservation: if • $\Gamma_c; \Sigma; \Psi \vdash \rho$ • $\Sigma; \Psi \vdash \sigma; \pi$ • $\Gamma_c; \Sigma \vdash e : \theta$ • $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e \rangle \xrightarrow{e} \langle \sigma', \pi', v \rangle$ then for some $\Psi' \supseteq \Psi$ (a) $\Gamma_c; \Sigma; \Psi' \vdash \rho$ (b) $\Sigma; \Psi' \vdash \sigma'; \pi'$ (c) $\Sigma; \Psi' \vdash v : \theta$

Proposition 10 (safety for statement evaluation).

1. Progress: if • $\Gamma_c; \Sigma; \Psi \vdash \rho$ • $\Sigma; \Psi \vdash \sigma; \pi$ • $\Gamma_c; \Sigma \vdash s$ • $\Gamma_c; \Sigma \vdash \lambda_c$ then (a) $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, s \rangle \xrightarrow{s} \langle \sigma', \pi', s' \rangle$ or (b) $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, s \rangle \xrightarrow{s}$ err or (c) s = return. 2. Preservation: if • $\Gamma_c; \Sigma \vdash s$
$$\begin{split} & \Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, s \rangle \xrightarrow{s} \langle \sigma', \pi', s' \rangle \\ & \cdot \Gamma_c; \Sigma; \Psi \vdash \rho \\ & \cdot \Sigma; \Psi \vdash \sigma; \pi \\ & \text{then for some } \Psi' \supseteq \Psi \\ & \text{(a) } \Gamma_c; \Sigma; \Psi' \vdash \rho \\ & \text{(b) } \Sigma; \Psi' \vdash \sigma'; \pi' \\ & \text{(c) } \Gamma_c; \Sigma \vdash s' \end{split}$$

Proposition 11 (safety for function definitions).

1. Progress: if • $\Sigma \vdash f(\overrightarrow{x:\theta})\langle \overrightarrow{y:\theta'}, l, \lambda_c, j \rangle$

• $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \lambda_c(l) \rangle \xrightarrow{s}{\to} \langle \sigma', \pi', \text{return} \rangle$

• $\Gamma_c = \{\overrightarrow{x:\theta}, \overrightarrow{y:\theta'}\}$

• $\Gamma_c; \Sigma; \Psi \vdash \rho$

•
$$\Sigma: \Psi \vdash \sigma: \pi$$

then

- (a) $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \lambda_c(l) \rangle \xrightarrow{s} \langle \sigma', \pi', \text{return} \rangle$ or
- (b) $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \lambda_c(l) \rangle \xrightarrow{s} * err$ (we assume this subsumes divergence).
- 2. Preservation: if

•
$$\Sigma \vdash f(x: \hat{\theta}) \langle y: \theta', l, \lambda_c, j \rangle$$

• $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \lambda_c(l) \rangle \xrightarrow{s} \langle \sigma', \pi', \mathsf{return} \rangle$

- $\Gamma_c = \{ \overrightarrow{x:\theta}, \overrightarrow{y:\theta'} \}$
- $\Gamma_c; \Sigma; \Psi \vdash \rho$
- $\Sigma; \Psi \vdash \sigma; \pi$

then for some $\Psi' \supseteq \Psi$

(a) $\Gamma_c; \Sigma; \Psi' \vdash \rho$

(b) $\Sigma; \Psi' \vdash \sigma'; \pi'$

Proof 1. Propositions 8, 9, 10 and 11 proved together by mutual structural induction on the typing judgements for ℓ , *e*, *s* and *d*_c.

- By case analysis on Γ_c; Σ ⊢ ℓ : θ in Fig. 4. To show 1b or conversely 1a, 2a, 2b and 2c hold for proposition 8. Observe that 2a holds if Ψ' ⊇ Ψ.
 - 1. Let $\ell = x$. By rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \stackrel{\ell}{\longrightarrow} \langle \sigma, \pi, a \rangle$ where $a = \rho(x)$ hence 1a holds. Put $\Psi' = \Psi$. Since $\Gamma_c; \Sigma; \Psi \vdash \rho$ it follows $\Sigma; \Psi' \vdash \rho(x) : \theta^*$ and 2c holds. Moreover $\Sigma; \Psi' \vdash \sigma; \pi$ and 2b holds.
 - 2. Let ℓ : $\theta = *x : \tau$. Since Γ_c ; Σ ; $\Psi \vdash \rho$ it follows $a = \rho(x) \neq 0$. By rule 1-ptr Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, *x \rangle \stackrel{\ell}{\to} \langle \sigma, \pi, \sigma(a) \rangle$ thus 1a holds. Put $\Psi' = \Psi$. By rule t-ptr Γ_c ; $\Sigma \vdash x : \tau *$ and by Γ_c ; Σ ; $\Psi \vdash \rho$ it follows Σ ; $\Psi \vdash a : \tau * *$. By rule vt-addr $(a : \tau *) \in \Psi$ and by Σ ; $\Psi \vdash \sigma; \pi$ it follows Σ ; $\Psi ; \sigma; \pi \vdash a : \tau *$. By rule st-comp Σ ; $\Psi \vdash \sigma(a) : \tau *$ thus Σ ; $\Psi' \vdash \sigma(a) : \tau *$ and 2c holds. Moreover Σ ; $\Psi' \vdash \sigma; \pi$ and 2b holds.
 - 3. Let ℓ : $\theta = x \to c$: θ_c . Since $\Gamma_c; \Sigma; \Psi \vdash \rho$ let $a = \rho(x) \neq 0$ and let $v = \sigma(a) +_{\perp} c$. If $\rho(x) = 0$ or $v \notin \cup \pi$ then 1b holds. Otherwise $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \to c \rangle \xrightarrow{\ell} \langle \sigma, \pi, v \rangle$ and 1a holds. Put $\Psi' = \Psi$. By rule t-fld $\Gamma_c; \Sigma \vdash x : N*$ and by rule t-var $(x : N*) \in \Gamma_c$ and by $\Gamma_c; \Sigma; \Psi \vdash \rho$ it follows $\Sigma; \Psi \vdash \rho(x) : N**$. By rule vt-addr $(\rho(x) : N*) \in \Psi$ and by $\Sigma; \Psi \vdash \sigma; \pi$ it follows $\Sigma; \Psi \vdash \sigma(\rho(x)) : N * *$. By rule st-comp $\Sigma; \Psi \vdash \sigma(\rho(x)) : N*$. By rule vt-addr $(\sigma(\rho(x)) : N) \in \Psi$ and by $\Gamma_c; \Sigma; \Psi \vdash \rho$ it follows $\Sigma; \Psi; \sigma; \pi \vdash \sigma(\rho(x)) : N$ and by rule st-comp $\Sigma; \Psi \vdash \sigma$ if follows $\Sigma; \Psi; \sigma; \pi \vdash \sigma(\rho(x)) : N$ and by rule st-fld $\Sigma; \Psi \vdash \sigma(\sigma(\rho(x)) + c) : \theta_c$. By rule st-comp $\Sigma; \Psi; \sigma; \pi \vdash \sigma(\rho(x)) + c : \theta_c$ and by $\Gamma_c; \Sigma; \Psi \vdash \rho$ it follows $(\sigma(\rho(x)) + c : \theta_c) \in \Psi$ and by rule vt-addr

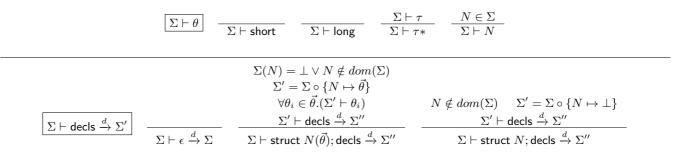


Figure 13: Well-formed type declarations of MINC programs

 $\Sigma; \Psi \vdash \sigma(\rho(x)) + c : \theta_c *$ and 2c holds since $\Psi' = \Psi$. Moreover $\Sigma; \Psi' \vdash \sigma; \pi$ and 2b holds.

- 4. Let $\ell = x[e']$. By rule t-ar Γ_c ; $\Sigma \vdash e' : t$ hence by mutual induction:
 - Either $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e' \rangle \xrightarrow{e}$ err. By rule e-lval-err $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x[e'] \rangle \xrightarrow{e}$ err. Hence 1b.
 - Or $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e' \rangle \xrightarrow{e} \langle \sigma', \pi', v \rangle$. If $\rho(x) = 0$ then 1a holds by rule e-lval-err. Otherwise let $a = \sigma'(\rho(x)) +_{\perp} v$. If $a \notin \cup \pi'$ then 1a holds. Otherwise by rule l-ar $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x[e'] \rangle \xrightarrow{\ell} \langle \sigma', \pi', a \rangle$. Hence 1a holds.

By induction there exists $\Psi' \supseteq \Psi$ such that $\Sigma; \Psi' \vdash \sigma'; \pi'$. By rule t-ar $\Gamma_c; \Sigma \vdash x : \theta[]*$ and by rule t-var $(x : \theta[]*) \in \Gamma_c$ and by $\Gamma_c; \Sigma; \Psi' \vdash \rho$ it follows $\Sigma; \Psi' \vdash \rho(x) : \theta[]**$. By rule vt-addr $(\rho(x) : \theta[]*) \in \Psi'$ and by $\Sigma; \Psi' \vdash \sigma'; \pi'$ it follows $\Sigma; \Psi'; \sigma'; \pi' \vdash \rho(x) : \theta[]*$. By rule st-comp $\Sigma; \Psi' \vdash \sigma'(\rho(x)) : \theta[]*$. By rule vt-addr $(\sigma'(\rho(x)) : \theta[]) \in \Psi'$ and by $\Gamma_c; \Sigma; \Psi' \vdash \rho$ it follows $\Sigma; \Psi'; \sigma'; \pi' \vdash \sigma'(\rho(x)) : \theta[]$ and by rule st-comp $\Sigma; \Psi' \vdash \sigma'(\rho(x)) : \theta[]$ and by rule st-ar $\Sigma; \Psi' \vdash \sigma'(\sigma'(\rho(x)) + v) : \theta$. By rule st-comp $\Sigma; \Psi'; \sigma'; \pi' \vdash \sigma'(\rho(x)) + v : \theta$ and by $\Gamma_c; \Sigma; \Psi' \vdash \rho$ it follows $(\sigma'(\rho(x)) + v : \theta) \in \Psi'$ and by rule vt-addr $\Sigma; \Psi' \vdash \sigma'(\rho(x)) + v : \theta^*$ and by rule vt-addr $\Sigma; \Psi' \vdash \sigma'(\rho(x)) + v : \theta^*$ and 2c holds. Moreover $\Sigma; \Psi' \vdash \sigma; \pi$ and 2b holds.

- By case analysis on Γ_c; Σ ⊢ e : θ in Fig. 4. To show that either 1b or conversely 1a, 2a 2b and 2c of Proposition 9 hold. Observe that 2a holds if Ψ' ⊇ Ψ.
 - 1. Let $e: \theta = \&x: \tau^*$. By rule t-amp $\Gamma_c; \Sigma \vdash x: \tau$ thus $(x:\tau) \in \Gamma_c$ and by $\Gamma_c; \Sigma; \Psi \vdash \rho$ it follows $\Sigma; \Psi \vdash a: \tau^*$ where $a = \rho(x) \neq 0$. By rule e-amp $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \& x \rangle \stackrel{e}{\to} \langle \sigma, \pi, a \rangle$ hence 1a holds. Put $\Psi' = \Psi$ thus $\Sigma; \Psi' \vdash a: \tau^*$ and 2c holds whilst 2b is immediate.
 - 2. Let $e: \theta = c_l$: long. By rule e-const $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, c_l \rangle \xrightarrow{e} \langle \sigma, \pi, c_l \rangle$. Hence 1a. Let $\Psi' = \Psi$. By rule vt-l $\Sigma; \Psi \vdash c_l$: long. Hence 2c. Also
 - 2b. 3. Let $e : \theta = c_s$: short. By rule e-const $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, c_s \rangle \xrightarrow{e} \langle \sigma, \pi, c_s \rangle$. Hence 1a. Let $\Psi' = \Psi$. By rule vt-s $\Sigma; \Psi \vdash c_s$: short. Hence 2c. Also 2b.
 - 4. Let $e: \theta = 0_l : \tau *$. By rule e-const $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, 0_l \rangle \xrightarrow{e} \langle \sigma, \pi, 0_l \rangle$. Hence 1a. Let $\Psi' = \Psi$. By rule vt-null $\Sigma; \Psi \vdash c_s : \tau *$. Hence 2c. Also 2b.
 - 5. Let $e : \theta = \text{new } \tau : \tau *$. By rule e-new $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \text{new } \tau \rangle \xrightarrow{e} \langle \sigma', \pi, a \rangle$ where $\sigma' = \sigma \circ \{a \mapsto \bot\}$. Hence 1a.

Let $\Psi' = \Psi \circ \{a \mapsto \tau\}$. By rule vt-addr $\Sigma; \Psi \vdash a : \tau *$ hence 2c. Also by rule vt-bot $\Sigma; \Psi' \vdash \bot : \tau$ by and rule st-comp $\Sigma; \Psi'; \sigma'; \pi \vdash a : \tau$ hence $\Sigma; \Psi' \vdash \sigma'; \pi$ and 2b holds.

6. Let $e: \theta$ = new struct N: N* and $n = |\Sigma(N)|$. By rule e-str $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \text{new struct } N \rangle \stackrel{e}{\to} \langle \sigma', \pi', a \rangle$ where $\sigma' = \sigma \circ \{a \mapsto \bot, \ldots, a + n - 1 \mapsto \bot\}$ and $\pi' = \pi \cup \{[a, a + n - 1]\}$. Put $\Psi' = \Psi \cup \{a: N, a + 1: \theta_1, \ldots, a + n - 1: \theta_{n-1}\}$. By rule vt-addr $\Sigma; \Psi' \vdash a: N*$ hence 2c holds. Let $i \in [0, n-1]$. Then $\sigma'(a+i) = \bot$ hence $\Sigma; \Psi' \vdash \sigma'(a+i)$

Let $i \in [0, n-1]$. Then $\sigma(a+i) = \bot$ hence $\Sigma; \Psi \vdash \sigma(a+i) : \theta_i$ by rule vt-bot therefore $\Sigma; \Psi'; \sigma'; \pi' \vdash a+i: \theta_i$. By rule st-fld $\Sigma; \Psi'; \sigma'; \pi' \vdash a: N$ hence 2b holds.

- 7. Let $e: \theta = \text{new } \theta[e]: \theta[]*$. By rule t-new-ar $\Gamma_c; \Sigma \vdash e: t$ hence by induction:
 - Either $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e \rangle \xrightarrow{e}$ err. By rule e-ar-err $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \text{new } \theta[e] \rangle \xrightarrow{e}$ err. Hence 1b.
 - Or $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e \rangle \xrightarrow{e} \langle \sigma', \pi', v \rangle$. By rule e-ar $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \text{new } \theta[e] \rangle \xrightarrow{e} \langle \sigma'', \pi'', a \rangle$ where $\sigma'' = \sigma' \circ \{a \mapsto \bot, \dots, a + v 1 \mapsto \bot\}$. Hence 1a. By induction there exists $\Phi' \supseteq \Phi$ such that $\Sigma; \Psi' \vdash \sigma'; \pi'$. Put $\Psi'' = \Psi' \circ \{a \mapsto \theta[], \dots, a + v - 1 \mapsto \theta[]\}$. By rule vt-addr it follows $\Sigma; \Psi'' \vdash a : \theta[]$ hence 2c. By rule vt-bot it follows $\Sigma; \Psi'' \vdash L : \theta[]$ and by st-comp it follows $\Sigma; \Psi'' \vdash a + i : \theta[]$ for all $i \in [0, v - 1]$ hence 2b.
- 8. Let $e : \theta = (e_1 \oplus e_2) : t$. By rule t- $\otimes \Gamma_c$; $\Sigma \vdash e_1 : t$ and Γ_c ; $\Sigma \vdash e_2 : t$. Hence by induction:
 - Either $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e_1 \rangle \xrightarrow{e}$ err. By rule e-op-err₁ $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, (e_1 \oplus e_2) \rangle \xrightarrow{e}$ err. Hence 1b.
 - Or $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma', \pi', e_2 \rangle \xrightarrow{e}$ err. Like previous case.
 - Or $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e_1 \rangle \xrightarrow{e} \langle \sigma', \pi', v_1 \rangle$ and $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma', \pi', e_2 \rangle \xrightarrow{e} \langle \sigma'', \pi'', v_2 \rangle$.
 - Either $v_1 \oplus_{\pi} v_2 = \text{err. By rule e-op-err}_3 \Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, (e_1 \oplus e_2) \rangle \xrightarrow{e} \text{err. Hence 1b.}$
 - Or $v_1 \oplus_{\pi} v_2 = v$. By rule e-op $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, (e_1 \oplus e_2) \rangle \xrightarrow{e} \langle \sigma', \pi, v \rangle$. Hence 1a.
 - By induction $\Sigma; \Psi'' \vdash v_1 : t$ and $\Sigma; \Psi'' \vdash v_2 : t$. If t = short then $v = \bot$ or $v = n_s$ where $n \in [-2^{15}, 2^{15} - 1]$. If $v = \bot$ then $\Sigma; \Psi'' \vdash v$: short. by rule vt-bot. Otherwise if $v = n_s$ then $\Sigma; \Psi'' \vdash v$: short by rule vt-s. An analgous argument holds if t = long hence 2c. Also 2b trivially by induction.
- 9. Let $e: \theta = (e_1 \oplus e_2) : \tau[]*$. Similar to previous case.

- 10. Let $e: \theta = f(\vec{e}): \theta_j$. By rule t-call $\Gamma_c; \Sigma \vdash e_i: \theta'_i$ where $\phi_c(f) = f(\overrightarrow{x:\theta}) \langle \overrightarrow{y:\theta''}, l, \lambda_c, j \rangle$ and $\Sigma \vdash \overrightarrow{\theta'} <: \overrightarrow{\theta}$. With respect to e_i there are two possibilities:
 - Either for some $i: \Sigma; \vec{\rho}; \rho \vdash \langle \sigma_{i-1}, \pi_{i-1}, e_i \rangle \xrightarrow{e}$ err. Then by rule e-call-err it follows that 1b holds.
 - Or for all $i: \Sigma; \vec{\rho}; \rho \vdash \langle \sigma_{i-1}, \pi_{i-1}, e_i \rangle \xrightarrow{e} \langle \sigma_i, \pi_i, v_i \rangle$ and by the inductive hypothesis $\Sigma; \Psi_i \vdash \theta_i : v_i$ and $\Sigma; \Psi_i \vdash \sigma_i; \pi_i$. Let $\Psi' = \Psi_n \cup \{\overrightarrow{a:\theta}, a': \theta'\}$. Then it is easy to verify $\Sigma; \Psi' \vdash \sigma'; \pi_n$ and $\Gamma_c; \Sigma; \Psi' \vdash \rho'$. By the progress induction hypothesis we then have for s:
 - Either $\Sigma; \lambda_c; \vec{\rho}, \rho; \rho' \vdash \langle \sigma', \pi_n, \lambda_c(l) \rangle \xrightarrow{s} \langle \sigma'', \pi', \text{return} \rangle$ **Proof 2.** The proof proceeds by case analysis on the inference
 - Otherwise 1b.

Preservation follows from the induction hyptheses for all e_i and s.

- By case analysis on Γ_c ; $\Sigma \vdash s$ in Fig. 4. To show that either 1b or conversely 1a, 2a, 2b and 2c of Proposition 10 hold. Observe that 2a holds if $\Psi' \supseteq \Psi$.
 - 1. Let Γ_c ; $\Sigma \vdash (\ell := e)$; s. From the induction hypothesis for ℓ , either $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \ell \rangle \xrightarrow{\ell}$ err, and hence 1b, or $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \ell \rangle \xrightarrow{\ell} \langle \sigma', \pi', a \rangle$. In the latter case, we have either $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma', \pi', e \rangle \xrightarrow{e}$ err, and hence 1b, or $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma', \pi', e \rangle \xrightarrow{e} \langle \sigma'', \pi'', v \rangle$. By s-assn we then have $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, (\ell := e); s \rangle \xrightarrow{s} \langle \sigma''', \pi'', s \rangle$ where $\sigma''' = \sigma'' \circ \{a \mapsto v\}$ and hence 1a. We get $\Gamma_c; \Sigma \vdash s$ from t-assn. Hence 2c. From the in-

duction hypotheses for ℓ and e we get type preservations $\Sigma; \Psi'' \vdash a : \theta_1 * \text{ and } \Sigma; \Psi'' \vdash v : \theta_2$ and type consistency $\Sigma; \Psi'' \vdash \sigma''; \pi''$. Hence, through rule vt-addr we know that $(a : \theta_1) \in \Psi''$. From rule t-assn we know $\Sigma \vdash \theta_1$ $\theta_2 \ <: \ \theta_1.$ Hence, through rule vt-subt we have $\Sigma; \Psi^{\prime\prime} \ \vdash$ $v: \theta_1$. Since $\sigma'''(a) = v$ we have hence by rule st-comp $\Sigma; \Psi''; \sigma'''; \pi'' \vdash a: \theta_1$. Hence $\Sigma; \Psi'' \vdash \sigma'''; \pi''$. Thus 2b.

- 2. Let Γ_c ; $\Sigma \vdash$ (if e goto l); s. Then
 - Either $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e \rangle \xrightarrow{e}$ err. Hence 1b.
 - Or $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, e \rangle \xrightarrow{e} \langle \sigma', \pi', v \rangle$. Then
 - Either $v = \bot$. Hence 1b.
 - Or v = 0. Then by rule s-if-false $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash$ $\langle \sigma, \pi, (\text{if } e \text{ goto } l); s \rangle \xrightarrow{s} \langle \sigma', \pi s, \rangle$. Hence 1a. We call this scenario 1.
 - Or $v \neq 0 \land v \neq \bot$. Then
 - Either $l \notin dom(\lambda_c)$. Then 1b.
 - Or $s' = \lambda_c(l)$. Then by rule s-if-true $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash$ $\langle \sigma, \pi, (\text{if } e \text{ goto } l); s \rangle \xrightarrow{s} \langle \sigma', \pi s', \rangle$. Hence 1a. We call this scenario 2.

In scenario 1 we have from t-if Γ_c ; $\Sigma \vdash s$. Hence 2c. In scenario 2 we have that $s' \in range(\lambda_c)$. Hence $\Gamma_c; \Sigma \vdash s'$. Hence 2c. In both scenarios we have from the induction hypthesis for e that $\Sigma; \Psi' \vdash \sigma'; \pi'$. Hence 2b.

3. Let $\Gamma_c; \Sigma \vdash$ goto *l*. Then either $l \notin dom(\lambda_c)$ and thus $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \text{goto } l \rangle \xrightarrow{s} \text{ err. Hence 1b. Alter-}$ natively $\lambda_c(l) = s$. Then by rule s-goto $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash$ $\langle \sigma, \pi, \text{goto } l \rangle \xrightarrow{s} \langle \sigma, \pi, s \rangle$. Hence 1a. From Γ_c ; $\Sigma \vdash \lambda_c$ it follows that Γ_c ; $\Sigma \vdash s$. Hence 2c. Let

 $\Psi' = \Psi$. Then 2b.

- 4. Let Γ_c ; $\Sigma \vdash$ return. Hence 1c. Also vacuously 2c and 2b.
- · Proposition 11 follows by the repeated application of Proposition 10 combining progress and preservation at every step. Besides the givens of Proposition ??, Proposition 10 also requires $\Gamma_c; \Sigma \vdash \lambda_c$. This is given by rule t-def which is the

only possible way that the well-typing of the function definition could have been constructed.

A.2 Well-Typed Decompilation

Proposition 12 (well-typed instruction decompilation). If μ_{Γ} ; Γ_c ; $\Sigma \vdash$ $\iota \stackrel{\iota}{\rightsquigarrow} \ell := e$ then for some θ_1 and θ_2

- 1. $\Gamma_c; \Sigma \vdash \ell : \theta_1$ 2. $\Gamma_c; \Sigma \vdash e : \theta_2$
- 3. $\Sigma \vdash \theta_2 <: \theta_1$

rules of the instruction translation relation.

- 1. Case tr- \oplus -r*₁. Let $\theta_1 = \theta_2 = \theta$ []*. From tr- \oplus -r*₁ we have $(x: \theta[]*) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x: \theta[]*$. Hence 1. From tr- \oplus -r*₁ we have Γ_c ; $\Sigma \vdash m$: long. From tr- \oplus -r*₁ we have $(y : \log) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash y : \log$. From both of these we get by rule t- $\otimes \Gamma_c$; $\Sigma \vdash y * m : long$. From that and the type of x we get through rule t-ptr- $\oplus \Gamma_c$; $\Sigma \vdash$ $x \oplus (y * m) : \theta$ []*. Hence 2. From rule sub-refl 3.
- 2. Case tr- \oplus -r*₂. Let $\theta_1 = \theta_2 = t$. From tr- \oplus -r*₂ we have $(x : t) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x : t$. Hence 1. From tr- \oplus -r^{*}₂ we have Γ_c ; $\Sigma \vdash c : t$. From tr- \oplus -r^{*}₁ we have $(y:t) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash y: t$. From both of these we get by rule t- $\otimes \Gamma_c$; $\Sigma \vdash y * c : t$. From that and the type of x we get through rule t- $\otimes \Gamma_c$; $\Sigma \vdash x \oplus (y * c) : t$. Hence 2. From rule sub-refl 3.
- 3. Case tr- \otimes -rc. Let $\theta_1 = \theta_2 = t$. From tr- \otimes -rc we have $(x:t) \in$ Γ_c . Then by rule t-var Γ_c ; $\Sigma \vdash x : t$. Hence 1. From tr- \otimes -rc we have $\Gamma_c; \Sigma \vdash c : t$. From that and the previous $\Gamma_c; \Sigma \vdash x : t$ we have by rule t- $\otimes \Gamma_c$; $\Sigma \vdash x \otimes c : t$. Hence 2. From rule sub-refl 3.
- 4. Case tr- \otimes -rr. Let $\theta_1 = \theta_2 = t$. From tr- \otimes -rr we have (x : t) $t) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x : t$. Hence 1. From tr- \otimes -rr we have $(y:t) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash y: t$. From that and the previous Γ_c ; $\Sigma \vdash x : t$ we have by rule t- \otimes Γ_c ; $\Sigma \vdash x \otimes y : t$. Hence 2. From rule sub-refl 3.
- 5. Case tr- \oplus -rc. Let $\theta_1 = \theta_2 = \theta$ []*. From tr- \oplus -rc we have $(x : \theta[]*) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x : \theta[]*$. Hence 1. From tr- \oplus -rc we have $\Gamma_c; \Sigma \vdash m : t$. From that and the previous $\Gamma_c; \Sigma \vdash x : \theta$ we have by rule t-ptr- \oplus $\Gamma_c; \Sigma \vdash x \oplus m : \theta[]*$. Hence 2. From rule sub-refl 3.
- 6. Case tr-mov-rc. Let $\theta_1 = \theta_2 = t$. From tr-mov-rc we have $(x:t) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x: t$. Hence 1. From tr-mov-rc we have Γ_c ; $\Sigma \vdash c : t$. Hence 2. From rule sub-refl 3.
- 7. Case tr-mov-r0. Let $\theta_1 = \theta_2 = \tau *$. From tr-mov-r0 we have $(x : \tau^*) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x : \tau^*$. Hence 1. From t-null we have Γ_c ; $\Sigma \vdash 0$: $\tau *$. Hence 2. From rule sub-refl 3.
- 8. Case tr-mov-rr. From tr-mov-rr we have $(x : \theta_1) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : \theta_1$. Hence 1. From tr-mov-rr we have $(y : \theta_2) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash y : \theta_2$. Hence 2. From tr-mov-rr we have $\Sigma \vdash \theta_2 <: \theta_1$. Hence 3.
- 9. Case tr-mov-ri₁. From tr-mov-ri₁ we have $(x : \theta_1) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : \theta_1$. Hence 1. From tr-mov-ri₁ we have $(y: \theta_2 *) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash y: \theta_2 *$. Then by rule t-ptr Γ_c ; $\Sigma \vdash *y : \theta_2$. Hence 2. From tr-mov-ri₁ we have $\Sigma \vdash \theta_2 <: \theta_1$. Hence 3.
- 10. Case tr-mov-ir₁. From tr-mov-ir₁ we have $(x : \theta_1 *) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : \theta_1 *$. Then by rule t-ptr Γ_c ; $\Sigma \vdash$ $*x: \theta_1$. Hence 1. From tr-mov-ir₁ we have $(y: \theta_2) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash y : \theta_2$. Hence 1. From tr-mov-ir₁ we have $\Sigma \vdash \theta_2 <: \theta_1$. Hence 3.

- 11. Case tr-mov-ri₂. From tr-mov-ri₂ we have $(x : \theta_1) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : \theta_1$. Hence 1. From tr-mov-ri₂ we have $(y : \theta_2[]*) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash y : \theta_2[]*$. Also by rule t- Γ_c ; $\Sigma \vdash 0$: long. Then by rule t-ar Γ_c ; $\Sigma \vdash y[0] : \theta_2$. Hence 2. From tr-mov-ri₂ we have $\Sigma \vdash \theta_2 <: \theta_1$. Hence 3.
- 12. Case tr-mov-ir₂. From tr-mov-ir₂ we have $(x : \theta_1[]*) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x : \theta_1[]*$. Also by rule t-l $\Gamma_c; \Sigma \vdash 0$: long. Then by rule t-ar $\Gamma_c; \Sigma \vdash x[0] : \theta_1$. Hence 1. From tr-mov-ir₂ we have $(y : \theta_2) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash y : \theta_2$. Hence 2. From tr-mov-ir₂ we have $\Sigma \vdash \theta_2 <: \theta_1$. Hence 3.
- 13. Case tr-mov-ri₃. From tr-mov-ri₃ we have $(x : \theta) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : \theta$. Hence 1. From tr-mov-ri₃ we have $(y : N*) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash y : N*$. Then by rule t-fld Γ_c ; $\Sigma \vdash y \to 0 : \theta_0$. Hence 2. From tr-mov-ri₃ we have $\Sigma \vdash \theta_0 <: \theta$. Hence 3.
- 14. Case tr-mov-ir₃. From tr-mov-ir₃ we have $(x : N*) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : N*$. Then by rule t-fld Γ_c ; $\Sigma \vdash x \rightarrow 0 : \theta_0$. Hence 1. From tr-mov-ir₃ we have $(y : \theta) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash y : \theta$. Hence 2. From tr-mov-ir₃ we have $\Sigma \vdash \theta <: \theta_0$. Hence 3.
- 15. Case tr-mov-ri+1. From tr-mov-ri+1 we have $(x : \theta_1) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : \theta_1$. Hence 1. From tr-mov-ri+1 we have $(y : \theta_2[]*) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash y : \theta_2[]*$. Also from tr-mov-ri+1 we have Γ_c ; $\Sigma \vdash m : t$. Then by rule t-ar Γ_c ; $\Sigma \vdash y[m] : \theta_2$. Hence 2. From tr-mov-ri+1 we have $\Sigma \vdash \theta_2 <: \theta_1$. Hence 3.
- 16. Case tr-mov-i+r₁. From tr-mov-i+r₁ we have $(x : \theta_1[]*) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x : \theta_1[]*$. Also from tr-mov-i+r₁ we have $\Gamma_c; \Sigma \vdash m : t$. Then by rule t-ar $\Gamma_c; \Sigma \vdash x[m] : \theta_1$. Hence 1. From tr-mov-i+r₁ we have $(y : \theta_2) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash y : \theta_2$. Hence 2. From tr-mov-i+r₁ we have $\Sigma \vdash \theta_2 <: \theta_1$. Hence 3.
- 17. Case tr-mov-ri+2. From tr-mov-ri+2 we have $(x : \theta) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : \theta$. Hence 1. From tr-mov-ri+2 we have $(y : N^*) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash y : N^*$. Then by rule t-fld Γ_c ; $\Sigma \vdash y \to m : \theta_m$. Hence 2. From tr-mov-ri+2 we have $\Sigma \vdash \theta_m <: \theta$. Hence 3.
- 18. Case tr-mov-i+r₂. From tr-mov-i+r₂ we have $(x : N*) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : N*$. Then by rule t-fld Γ_c ; $\Sigma \vdash x \rightarrow m : \theta_m$. Hence 1. From tr-mov-i+r₂ we have $(y : \theta_2) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash y : \theta_2$. Hence 2. From tr-mov-i+r₂ we have $\Sigma \vdash \theta <: \theta_m$. Hence 3.
- 19. Case tr-alloc-r*. From tr-alloc-r* we have (x : θ[]*) ∈ Γ_c. Then by rule t-var Γ_c; Σ ⊢ x : θ[]*. Hence 1. From tr-alloc-r* we have Γ_c; Σ ⊢ m : t. From tr-alloc-r* we have (y : t) ∈ Γ_c. Then by rule t-var Γ_c; Σ ⊢ y : t. From both of these we get by rule t-⊗ Γ_c; Σ ⊢ y * m : t. Then from t-new-ar we get Γ_c; Σ ⊢ new θ[y * m] : θ[]*. Hence 2. From rule sub-refl 3.
- 20. Case tr-alloc-rc₁. From tr-alloc-rc₁ we have $(x : \theta*) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x : \theta*$. Hence 1. From t-new we get $\Gamma_c; \Sigma \vdash$ new $\theta : \theta*$. Hence 2. From rule sub-refl 3.
- 21. Case tr-alloc-rc₂. From tr-alloc-rc₂ we have $(x : N*) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : N*$. Hence 1. From t-new-str we get Γ_c ; $\Sigma \vdash$ new N : N*. Hence 2. From rule sub-refl 3.
- 22. Case tr-alloc-rc₃. From tr-alloc-rc₃ we have $(x : \theta[]*) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash x : \theta[]*$. Hence 1. From tr-alloc-rc₃ we have Γ_c ; $\Sigma \vdash m : t$. Then from rule t-new-ar we have Γ_c ; $\Sigma \vdash \text{new } \theta[m] : \theta[]*$. Hence 2. From rule sub-refl 3.
- 23. Case tr-call. From tr-call we have $(u : \theta_u) \in \Gamma_c$. Then by rule t-var Γ_c ; $\Sigma \vdash u : \theta_u$. Hence 1. We have:

• From tr-call we have
$$\phi_c(f) = f(x: \hat{\theta}) \langle y: \hat{\theta}', l, \lambda_c, j \rangle$$

- From tr-call we have $\overrightarrow{(v:\theta_v)} \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash \vec{v}: \vec{\theta_v}$.
- From tr-call we have $\Sigma \vdash \vec{\theta_v} <: \vec{\theta}$.
- By rule sub-reflwe have $\Sigma \vdash \theta'_j <: \theta'_j$.

Hence by rule t-call we have Γ_c ; $\Sigma \vdash: \theta'_j$. Hence 2. From tr-call we have $\Sigma \vdash \theta'_j <: \theta_u$. Hence 3.

Proposition 13 (well-typed block decompilation). If μ_{λ} ; μ_{Γ} ; Γ_c ; $\Sigma \vdash b \xrightarrow{b} s$ then Γ_c ; $\Sigma \vdash s$.

Proof 3. This proof proceeds by structural induction on the block translation relation.

- 1. Case tr-instr. From tr-instrwe have $\mu_{\Gamma}; \Gamma_c; \Sigma \vdash \iota \stackrel{\iota}{\longrightarrow} \ell := e$. Hence, by Proposition 12 we have $\Gamma_c; \Sigma \vdash \ell : \theta_1, \Gamma_c; \Sigma \vdash e : \theta_2$ and $\Sigma \vdash \theta_2 <: \theta_1$. Also by rule tr-instr we have $\mu_{\lambda}; \mu_{\Gamma}; \Gamma_c; \Sigma \vdash b \stackrel{b}{\rightsquigarrow} s$. Hence by the induction hypothesis we have $\Gamma_c; \Sigma \vdash s$. Then by rule t-assn we have $\Gamma_c; \Sigma \vdash \ell := e; s$
- 2. Case tr-if. From tr-if we have $(x : \theta) \in \Gamma_c$. Then by rule t-var $\Gamma_c; \Sigma \vdash x : \theta_u$. Also from tr-if we have $\mu_\lambda; \mu_\Gamma; \Gamma_c; \Sigma \vdash b \stackrel{b}{\rightsquigarrow} s$. Hence, from the induction hypothesis we have $\Gamma_c; \Sigma \vdash s$ Then the proposition follows from rule t-if.
- 3. Case tr-goto. This follows from rule t-goto.
- 4. Case tr-ret. This follows from rule t-ret.

Proposition 14 (well-typed definition decompilation). If $\Sigma \vdash d_x \rightsquigarrow d_c$ then $\Sigma \vdash d_c$.

Proof 4. We show that the four preconditions to rule t-def are satisfied:

- 1. From rule tr-def we know that $\Gamma_c = \{ \overline{x:\theta}, y: \theta' \}$.
- 2. From rule tr-def we know that $a \in dom(\lambda_c)$ and $l = \mu_{\lambda}(a)$. Hence $l \in range(\mu_{\lambda})$. From the rule we also know that $range(\mu_{\lambda}) = dom(\lambda_c)$. Hence $l \in dom(\lambda_c)$.
- From rule tr-def we know that r_{yj} ∈ r_y. We also know that y_j = μ_Γ(r_{yj}) and that ȳ = μ_Γ(r_y). Hence y_j ∈ ȳ.
 From rule tr-def we know that ∀(a ↦ l) ∈ μ_λ : μ_λ; μ_Γ; Γ_c; Σ ⊢
- 4. From rule tr-def we know that $\forall (a \mapsto l) \in \mu_{\lambda} : \mu_{\lambda}; \mu_{\Gamma}; \Gamma_c; \Sigma \vdash \lambda_x(a) \xrightarrow{b} \lambda_c(l)$. From Proposition 13 we then know that $\forall l \in range(\mu_{\lambda}) : \Gamma_c; \Sigma \vdash \lambda_c(l)$. From rule tr-def we know that $range(\mu_{\lambda}) = dom(\lambda_c)$. Hence $\forall l \in dom(\lambda_c) : \Gamma_c; \Sigma \vdash \lambda_c(l)$.

Hence by rule t-def we conclude $\Sigma \vdash f(\overrightarrow{x:\theta}) \langle \overrightarrow{y:\theta'}, l, \lambda_c, j \rangle$.

A.3 Semantics Preservation

Instructions We prove Propositions 7 and 6 together.

Proof 5. The proof proceeds by case analysis on the derivation of the judgement $\mu_{\Gamma}; \Gamma_c; \Sigma \vdash \iota \stackrel{\iota}{\leadsto} \ell := e.$

1. Case tr- \oplus -r*₁. Then $\iota = (\mathsf{op}_4^{\oplus} r_i, r_j * c), \ \ell = x$ and $e = x \oplus (y * m)$.

(a) This case is not possible. Rule $ex-\oplus -r^*$ always applies.

(b) In this case rules ex- \oplus -r* is used for progress on $\iota: \vec{R} \vdash \langle H, R, \mathsf{op}_4^{\oplus} r_i, r_j * c \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ 4 \{r_i \mapsto \vec{b}_i \oplus 4 (\vec{b}_j * 4 c)\}$ where $\vec{b}_i = R_{0:4}(r_i)$ and $\vec{b}_j = R_{0:4}(r_j)$. Similarly, through rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{\ell} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-op, e-lval, l-var and e-const we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, (x \oplus (y * m)) \rangle \xrightarrow{e} \langle \sigma, \pi, v \rangle$ where $v = v_x \oplus_{\pi} (v_y * \pi m), v_x = \sigma(a), a' = \rho(y)$ and $v_y = \sigma(a')$.

From rule tr- \oplus -r^{*}₁ we know $(r_i : x)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b}_i \iff v_x$. Similarly, we know $\mu_a \vdash \vec{b}_j \iff v_y$. Then from $(x : \theta[]*) \in$ Γ_c and the store typing of σ it follows that $v_x = n_*$ and from the success of the addition, it also follows that $[n_*, n_* \oplus (v_y * m)] \subseteq \in \pi$. Hence, also from the store typing all m values at the addresses in this range have type θ . From the related heaps it then follows with $c/m = sizeof(\theta)$ that $\mu_a \vdash (\vec{b}_i \oplus_4 (\vec{b}_j *_4 c)) \iff (v \oplus_{\pi} (v_y * m))$. Hence, the update registers are still related.

- 2. Case tr- \oplus -r*₂. Then $\iota = (\operatorname{op}_{w}^{\oplus} r_{i}, r_{j} * c), \ \ell = x \text{ and } e = x \oplus (y * c).$
 - (a) This case is not possible. Rule $ex-\oplus -r^*$ always applies.
 - (b) In this case rules ex- \oplus -r* is used for progress on $\iota: \vec{R} \vdash \langle H, R, \mathsf{op}_w^{\oplus} r_i, r_j * c \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_w \{r_i \mapsto \vec{b}_i \oplus_w (\vec{b}_j *_w c)\}$ where $\vec{b}_i = R_{0:w}(r_i)$ and $\vec{b}_j = R_{0:w}(r_j)$. Similarly, through rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{\ell} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-op, e-lval, l-var and e-const we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, (x \oplus (y * m)) \rangle \xrightarrow{e} \langle \sigma, \pi, v \rangle$ where $v = v_x \oplus_\pi (v_y *_\pi m), v_x = \sigma(a), a' = \rho(y)$ and $v_y = \sigma(a')$.

From rule tr- \oplus -r^{*}₂ we know $(r_i: x)_w \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b}_i \iff v_x$. Similarly, we know $\mu_a \vdash \vec{b}_j \iff v_y$. It then follows that $\mu_a \vdash (\vec{b}_i \oplus_w (\vec{b}_j *_w c)) \iff (v \oplus_{\pi} (v_y * c))$. Hence, the update registers are still related.

- Case tr-⊗-rc. Then ι = (op[⊗]_w r_i, c), ℓ = x and e = x ⊗ c.
 (a) This case is not possible. Rule ex-⊗-rc always applies.
 - (a) This case is not possible. Kalle ex-⊗-re always applies.
 (b) In this case rules ex-⊗-rc is used for progress on *ι*: *R* ⊢ ⟨*H*, *R*, op_w[∞] *r_i*, *c*⟩ ^{*i*}→ ⟨*H*, *R*'⟩. Here *R*' = *R* o_w {*r_i* ↦ *b* ⊗_w *c*} where *b* = *R*_{0:w}(*r_i*).
 Similarly, through rule 1-var Σ; *ρ*; *ρ* ⊢ ⟨σ, π, *x*⟩ ^{*l*}→ ⟨σ, π, *a*⟩ with *a* = *ρ*(*x*). Also through rules e-op, e-lval, 1-var and e-const we obtain Σ; *ρ*; *ρ* ⊢ ⟨σ, π, (*x* ⊗ *c*)⟩ ^{*e*}→ ⟨σ, π, *v*'⟩ where *v*' = *v* ⊗_π *c* and *v* = *σ*(*a*). From rule tr-⊗-rc we know (*r_i* : *x*)_w ∈ *μ*_Γ. Hence from the related registers we know *μ_a* ⊢ *b* ↔ *v*. Then from (*x* : *t*) ∈ Γ_c and *w* = *sizeof*(*t*) it follows that *μ_a* ⊢

 $(\vec{k} \otimes w \ c) \iff (v \otimes_{\pi} c)$. Hence, the update registers are still related.

- 4. Case tr-⊕-rc. Then ι = (op[⊕]₄ r_i, c), ℓ = x and e = x ⊕ m.
 (a) This case is not possible. Rule ex-⊗-rc always applies.
 (b) In this case relation ⊕ on its used for proceeding a set not possible.
- (b) In this case rules ex- \otimes -rc is used for progress on $\iota: \vec{R} \vdash$ $\langle H, R, \mathsf{op}_4^\oplus r_i, c \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_4 \{ r_i \mapsto$ $\vec{b} \oplus_4 c$ } where $\vec{b} = R_{0:4}(r_i)$. Similarly, through rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{\ell} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-op, e-lval, l-var and e-const we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, (x \oplus m) \rangle \xrightarrow{e} \langle \sigma, \pi, v' \rangle$ where $v' = v \oplus_{\pi} m$ and $v = \sigma(a)$. From rule tr- \oplus -rc we know $(r_i : x)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b} \iff v$. Then from $(x : \theta[]*) \in \Gamma_c$ and the store typing of σ it follows that $v = n_*$ and from the success of the addition, it also follows that $[n_*, n_* \oplus m] \subseteq \in \pi$. Hence, also from the store typing all m values at the addresses in this range have type θ . From the related heaps it then follows with $c/m = sizeof(\theta)$ that $\mu_a \vdash (\vec{b} \oplus_4 c) \iff (v \oplus_{\pi} m)$. Hence, the update registers are still related. 5. Case tr- \otimes -rr. Then $\iota = (\mathsf{op}_w^{\otimes} r_i, r_j), \ell = x$ and $e = x \otimes y$.
 - (a) This case is not possible. Rule $ex \cdot \otimes$ -rr always applies.
 - (b) In this case rules ex- \otimes -rc is used for progress on ι : $\vec{R} \vdash \langle H, R, \mathsf{op}_w^{\otimes} r_i, r_j \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_w \{r_i \mapsto \vec{b}_i \oplus_w \vec{b}_j\}$ where $\vec{b}_i = R_{0:w}(r_i)$ and $\vec{b}_j = R_{0:w}(r_j)$.

Similarly, through rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{\ell} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-op, e-lval and l-var we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, (x \otimes y) \rangle \xrightarrow{e} \langle \sigma, \pi, v \rangle$ where $v = v_x \otimes_{\pi} v_y, v_x = \sigma(a), a' = \rho(y)$ and $v_y = \sigma(a')$. From rule tr- \otimes -rr we know $(r_i : x)_w \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b}_i \iff v_x$. By similar reasoning we know $\mu_a \vdash \vec{b}_j \iff v_y$. Then from $(x : t) \in \Gamma_c$, $(y : t) \in \Gamma_c$ and w = sizeof(t) it follows that $\mu_a \vdash (\vec{b}_i \otimes_w \vec{b}_j) \iff (v_x \otimes_{\pi} v_y)$. Hence, the update registers are still related.

- 6. Case tr-mov-rc. Then ι = (mov_w r_i, c), l = x and e = c.
 (a) This case is not possible. Rule ex-mov-rc always applies.
 - (b) In this case rules ex-mov-rc is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{mov}_w \ r_i, c \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_w \{r_i \mapsto c\}$.

Similarly, through rule l-var Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, x \rangle \stackrel{\ell}{\to} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rule e-const we obtain Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, c \rangle \stackrel{e}{\to} \langle \sigma, \pi, c \rangle$. We know that $\mu_a \vdash c \iff c$. Hence, the update registers are still related.

- 7. Case tr-mov-r0. Then $\iota = (\text{mov}_4 r_i, 0), \ell = x \text{ and } e = 0.$
 - (a) This case is not possible. Rule ex-mov-rc always applies. \vec{A}
 - (b) In this case rules ex-mov-rc is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{mov}_4 r_i, 0 \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_4 \{ r_i \mapsto 0 \}$. Similarly, through rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{\ell} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rule e-const we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, 0 \rangle \xrightarrow{e} \langle \sigma, \pi, 0 \rangle$. We know that $\mu_a \vdash 0 \iff 0$. Hence, the update registers are still related.
- 8. Case tr-mov-rr. Then $\iota = (mov_w r_i, r_j), \ell = x$ and e = y.

(a) This case is not possible. Rule ex-mov-rr always applies.
(b) In this case rules ex-mov-rr is used for progress on *ι*: *R* ⊢ ⟨*H*, *R*, mov_w r_i, r_j⟩ → ⟨*H*, *R*'⟩. Here *R*' = *R* ∘_w {r_i ↦ *b*} where *b* = *R*_{0:w}(r_j).
Similarly, through rule 1-var Σ; *ρ*; *ρ* ⊢ ⟨σ, π, x⟩ → ⟨σ, π, a⟩ with a = *ρ*(x). Also through rules e-lval and 1-var we obtain Σ; *ρ*; *ρ* ⊢ ⟨σ, π, y⟩ → ⟨σ, π, v⟩ where v = σ(a') and a' = *ρ*(y).

From rule tr-mov-rr we know $(r_j : y)_w \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b} \leftrightarrow v$. Also from rule tr-mov-rr we know $(r_i : x)_w \in \mu_{\Gamma}$. Hence, the registers are related. After the update we can see that they are still related.

- - (b) In this case rules ex-mov-ri is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{mov}_w r_i, [r_j] \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_w \{r_i \mapsto \vec{b}_2\}$ where $\vec{b}_2 = H^w(\vec{b}_1)$ and $\vec{b}_1 = R(r_j)$.

Similarly, through rule 1-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{\ell} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-lval, 1-ptr and 1-var we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, *y \rangle \xrightarrow{e} \langle \sigma, \pi, v_2 \rangle$ where $v_2 = \sigma(v_1), v_1 = \sigma(a')$ and $a' = \rho(y)$.

From rule tr-mov-ri₁ we know $(r_j : y)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b}_1 \iff v_1$. From related stores, we also know $\mu_a \vdash \vec{b}_2 \iff v_2$. Also from rule tr-mov-ri₁ we know $(r_i : x)_w \in \mu_{\Gamma}$. Hence, the registers are related. After the update we can see that they are still related.

- 10. Case tr-mov-ri₂. Then $\iota = (mov_w \ r_i, [r_j]), \ \ell = x$ and e = y[0].
 - (a) This case is possible iff R(r_j) = 0 or R(r_j) = ⊥. Because of the related registers and, from rule tr-mov-ri₂, (r_j : y)₄ ∈ μ_Γ, we have μ_a ⊢ R(r_j) ↔ σ(ρ(y)). In either of the cases for R(r_j) we also have Σ; ρ; ρ ⊢ ⟨σ, π, y⟩ ^e→ err.
 - (b) In this case rules ex-mov-ri is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{mov}_w r_i, [r_j] \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_w \{r_i \mapsto \vec{b}_2\}$ where $\vec{b}_2 = H^w(\vec{b}_1)$ and $\vec{b}_1 = R_(r_j)$.

Similarly, through rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{\ell} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-lval, l-ar and e-const we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, y[0] \rangle \xrightarrow{e} \langle \sigma, \pi, v_2 \rangle$ where $v_2 = \sigma(v_1), v_1 = \sigma(a')$ and $a' = \rho(y)$.

From rule tr-mov-ri₂ we know $(r_j : y)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b_1} \iff v_1$. From related stores, we also know $\mu_a \vdash \vec{b_2} \iff v_2$. Also from rule tr-mov-ri₂ we know $(r_i : x)_w \in \mu_{\Gamma}$. Hence, the registers are related. After the update we can see that they are still related.

- 11. Case tr-mov-ri₃. Then $\iota = (mov_w \ r_i, [r_j]), \ \ell = x \text{ and } e = y \rightarrow 0.$
 - (a) This case is possible iff R(r_j) = 0 or R(r_j) = ⊥. Because of the related registers and, from rule tr-mov-ri₃, (r_j : y)₄ ∈ μ_Γ, we have μ_a ⊢ R(r_j) ↔ σ(ρ(y)). In either of the cases for R(r_j) we also have Σ; ρ; ρ ⊢ ⟨σ, π, y⟩ ^e→ err.
 - (b) In this case rules ex-mov-ri is used for progress on $\iota: \vec{R} \vdash \langle H, R, \mathsf{mov}_w \ r_i, [r_j] \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_w \{r_i \mapsto \vec{b}_2\}$ where $\vec{b}_2 = H^w(\vec{b}_1)$ and $\vec{b}_1 = R(r_j)$.

Similarly, through rule l-var Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{e} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-lval and l-fldwe obtain Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, y \to 0 \rangle \xrightarrow{e} \langle \sigma, \pi, v_2 \rangle$ where $v_2 = \sigma(v_1)$, $v_1 = \sigma(a')$ and $a' = \rho(y)$.

From rule tr-mov-ri₃ we know $(r_j : y)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b_1} \iff v_1$. From related stores, we also know $\mu_a \vdash \vec{b_2} \iff v_2$. Also from rule tr-mov-ri₃ we know $(r_i : x)_w \in \mu_{\Gamma}$. Hence, the registers are related. After the update we can see that they are still related.

- 12. Case tr-mov-ir₁. Then $\iota = (mov_w [r_i], r_j), \ell = *x$ and e = y.
 - (a) This case is possible iff R(r_i) = 0 or R(r_i) = ⊥. Because of the related registers and, from rule tr-mov-ir₁, (r_i : x)₄ ∈ μ_Γ, we have μ_a ⊢ R(r_i) ↔ σ(ρ(x)). In either of the cases for R(r_i) we also have Σ; ρ; ρ ⊢ ⟨σ, π, x⟩ ^ℓ→ err.
 - (b) In this case rules ex-mov-ir is used for progress on ι : $\vec{R} \vdash \langle H, R, \text{mov}_w [r_i], r_j \rangle \xrightarrow{\iota} \langle H', R \rangle$. Here $H' = H \circ \{\vec{b}_1, \dots, \vec{b}_1 + (w-1) \mapsto \vec{b}_2\}$ where $\vec{b}_1 = R(r_i)$ and $\vec{b} = R_{0:w}(r_j)$.

Similarly, through rule l-ptr Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, *x \rangle \xrightarrow{\ell} \langle \sigma, \pi, v_1 \rangle$ with $v_1 = \sigma(a)$ and $a = \rho(x)$. Also through rules e-lval and l-varwe obtain Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, y \rangle \xrightarrow{e} \langle \sigma, \pi, v_2 \rangle$ where $v_2 = \sigma(a')$ and $a' = \rho(y)$.

From rule tr-mov-ir₁ we know $(r_j : y)_w \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b}_2 \iff v_2$. From related stores, we also know $\mu_a \vdash \vec{b}_2 \iff v_2$. Also from rule tr-mov-ir₁ we know $(r_i : x)_w \in \mu_{\Gamma}$. Hence, $\mu_a \vdash \vec{b}_1 \iff$ v_1 . Since $(x : \theta_1 *) \in \Gamma_c$, we know that v_1 is an address. Because of related heaps, we then know that $(\vec{b}_1, v_1)in\mu_a$. After the update we can see that they are still related.

- 13. Case tr-mov-ir₂. Then $\iota = (mov_w [r_i], r_j), \ \ell = x[0]$ and e = y.
 - (a) This case is possible iff R(r_i) = 0 or R(r_i) = ⊥. Because of the related registers and, from rule tr-mov-ir₂, (r_i : x)₄ ∈ μ_Γ, we have μ_a ⊢ R(r_i) ↔ σ(ρ(x)). In either of the cases for R(r_i) we also have Σ; ρ; ρ ⊢ ⟨σ, π, x⟩ ^ℓ→ err.
 - (b) In this case rules ex-mov-ir is used for progress on ι : $\vec{R} \vdash \langle H, R, \text{mov}_w [r_i], r_j \rangle \xrightarrow{\iota} \langle H', R \rangle$. Here $H' = H \circ \{\vec{b}_1, \ldots, \vec{b}_1 + (w - 1) \mapsto \vec{b}_2\}$ where $\vec{b}_1 = R(r_i)$ and $\vec{b} = R_{0:w}(r_j)$.

Similarly, through rule 1-ar and e-const $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x[0] \rangle \stackrel{\ell}{\to} \langle \sigma, \pi, v_1 \rangle$ with $v_1 = \sigma(a)$ and $a = \rho(x)$. Also through rules e-lval and 1-varwe obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, y \rangle \stackrel{e}{\to} \langle \sigma, \pi, v_2 \rangle$ where $v_2 = \sigma(a')$ and $a' = \rho(y)$. From rule tr-mov-ir₂ we know $(r_j : y)_w \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b}_2 \iff v_2$. From related stores, we also know $\mu_a \vdash \vec{b}_2 \iff v_2$. Also from rule tr-mov-ir₂ we know $(r_i : x)_w \in \mu_{\Gamma}$. Hence, $\mu_a \vdash \vec{b}_1 \iff$ v_1 . Since $(x : \theta_1[]*) \in \Gamma_c$, we know that v_1 is an address. Because of related heaps, we then know that $(\vec{b}_1, v_1)in\mu_a$.

- After the update we can see that they are still related. 14. Case tr-mov-ir₃. Then $\iota = (mov_w [r_i], r_j), \ \ell = x \to 0$ and e = y.
 - (a) This case is possible iff R(r_i) = 0 or R(r_i) = ⊥. Because of the related registers and, from rule tr-mov-ir₃, (r_i : x)₄ ∈ μ_Γ, we have μ_a ⊢ R(r_i) ↔ σ(ρ(x)). In either of the cases for R(r_i) we also have Σ; ρ; ρ ⊢ ⟨σ, π, x⟩ ^ℓ→ err.

(b) In this case rules ex-mov-ir is used for progress on ι : $\vec{R} \vdash \langle H, R, \text{mov}_w[r_i], r_j \rangle \xrightarrow{\iota} \langle H', R \rangle$. Here $H' = H \circ \{\vec{b}_1, \ldots, \vec{b}_1 + (w-1) \mapsto \vec{b}_2\}$ where $\vec{b}_1 = R(r_i)$ and $\vec{b} = R_{0:w}(r_j)$.

Similarly, through rule 1-fld $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \to 0 \rangle \xrightarrow{\ell} \langle \sigma, \pi, v_1 \rangle$ with $v_1 = \sigma(a)$ and $a = \rho(x)$. Also through rules e-lval and 1-varwe obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, y \rangle \xrightarrow{e} \langle \sigma, \pi, v_2 \rangle$ where $v_2 = \sigma(a')$ and $a' = \rho(y)$.

From rule tr-mov-ir₃ we know $(r_j : y)_w \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b}_2 \iff v_2$. From related stores, we also know $\mu_a \vdash \vec{b}_2 \iff v_2$. Also from rule tr-mov-ir₃ we know $(r_i : x)_w \in \mu_{\Gamma}$. Hence, $\mu_a \vdash \vec{b}_1 \iff$ v_1 . Since $(x : N^*) \in \Gamma_c$, we know that v_1 is an address. Because of related heaps, we then know that $(\vec{b}_1, v_1)in\mu_a$. After the update we can see that they are still related.

- 15. Case tr-mov-ri+1. Then $\iota = (\text{mov}_w r_i, [r_j + c], \ell = x$ and e = y[m].
 - (a) This case is possible iff R(r_j) = 0, R(r_j) = ⊥ or (R(r_j) + c) ∉ dom(H). Because of the related registers and heaps, and from rule tr-mov-ri+₁(r_j : y)₄ ∈ μ_Γ, we have μ_a ⊢ R(r_j) ↔ σ(ρ(y)). In either of the first two cases for R(r_j) we also have Σ; ρ; ρ ⊢ ⟨σ, π, y[m]⟩ ^ℓ→ err. In the last case, because of related heaps, it also has to be that Σ; ρ; ρ ⊢ ⟨σ, π, y[m]⟩ ^ℓ→ err.
 - (b) In this case rules ex-mov-r+ is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{mov}_w \ r_i, [r_j + c] \rangle \stackrel{\iota}{\to} \langle H, R' \rangle$. Here $R' = R \circ_w \{r_i \mapsto \vec{b}\}$ where $\vec{b} = H^w(\vec{b}')$ and $\vec{b} = R(r_j) + 4c$. Similarly, through rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \stackrel{\ell}{\to} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-lval, l-arand e-const we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, y[m] \rangle \stackrel{e}{\to} \langle \sigma, \pi, v \rangle$ where $v = \sigma(a'' + m), a'' = \sigma(a')$ and $a' = \rho(y)$.

From rule tr-mov-ri+₁ we know $(r_j : y)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b'} \rightsquigarrow a''$. From the translation rule we also have $(y : \theta[]*) \in \Gamma_c$. Because of the progress, it means that $[a'', a'' + m] \subseteq \in \pi$. Because of the related heaps and well-typed store it follows that $\mu_a \vdash \vec{b} \rightsquigarrow v$. Also from rule tr-mov-ri+₁ we know $(r_i : x)_w \in \mu_{\Gamma}$. After the update we can see that they are still related.

- 16. Case tr-mov-ri+2. Then $\iota = (\text{mov}_w r_i, [r_j + c], \ell = x \text{ and } e = y \to m.$
 - (a) This case is possible iff R(r_j) = 0, R(r_j) = ⊥ or (R(r_j)+c) ∉ dom(H). Because of the related registers and heaps, and from rule tr-mov-ri+2(r_j : y)₄ ∈ μ_Γ, we have μ_a ⊢ R(r_j) ↔ σ(ρ(y)). In either of the first two cases for R(r_j) we also have Σ; ρ; ρ ⊢ ⟨σ, π, y[m]⟩ ^ℓ→ err. In the last case, because of related heaps, it also has to be that Σ; ρ; ρ ⊢ ⟨σ, π, y → m⟩ ^ℓ→ err.
 - (b) In this case rules ex-mov-r+ is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{mov}_w \ r_i, [r_j + c] \rangle \xrightarrow{\iota} \langle H, R' \rangle$. Here $R' = R \circ_w \{r_i \mapsto \vec{b}\}$ where $\vec{b} = H^w(\vec{b}')$ and $\vec{b} = R(r_j) +_4 c$.

Similarly, through rule 1-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{e} \langle \sigma, \pi, a \rangle$ with $a = \rho(x)$. Also through rules e-1val and 1-fld we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, y \to m \rangle \xrightarrow{e} \langle \sigma, \pi, v \rangle$ where $v = \sigma(a'' + m), a'' = \sigma(a')$ and $a' = \rho(y)$.

From rule tr-mov-ri+₂ we know $(r_j : y)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash \vec{b'} \iff a''$. From the translation rule we also have $(y : N*) \in \Gamma_c$ and $\Sigma(N) = \langle \theta_0, \ldots, \theta_n \rangle$. Because of the progress, it means that $[a'', a'' + m] \subseteq \in \pi$. Because of the related heaps and well-typed store it follows that $\mu_a \vdash \vec{b} \iff v$. Also from rule tr-mov-ri+₁ we know $(r_i : x)_w \in \mu_{\Gamma}$. After the update we can see that they are still related.

- 17. Case tr-mov-i+r₁. Then $\iota = (mov_w [r_i + c], r_j, \ell = x[m]$ and e = y.
 - (a) This case is possible iff R(r_i) = 0, R(r_i) = ⊥ or (R(r_i) + c) ∉ dom(H). Because of the related registers and heaps, and from rule tr-mov-i+r₁(r_i : x)₄ ∈ μ_Γ, we have μ_a ⊢ R(r_i) ↔ σ(ρ(x)). In either of the first two cases for R(r_i) we also have Σ; ρ; ρ ⊢ ⟨σ, π, x[m]⟩ ^ℓ→ err. In the last case, because of related heaps, it also has to be that Σ; ρ; ρ ⊢ ⟨σ, π, x[m]⟩ ^ℓ→ err.
 - (b) In this case rules ex-mov+r is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{mov}_w \ [r_i + c], r_j \rangle \xrightarrow{\iota} \langle H', R \rangle$. Here $H' = H \circ \{H(R(r_i)) +_4 c +_4 n \mapsto R_{n:n+1}(r_j)\}_{n=0}^{w-1}$.

Similarly, through rule 1-ar $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x[m] \rangle \xrightarrow{\ell} \langle \sigma, \pi, a \rangle$ with a = a' + m and $a' = \rho(x)$. Also through rules e-lval and 1-var we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, y \rangle \xrightarrow{e} \langle \sigma, \pi, v \rangle$ where $v = \sigma(a'')$ and $a'' = \rho(y)$.

From rule tr-mov-i+r₁ we know $(r_i : x)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $\mu_a \vdash R(r_i) \iff a'$. From the translation rule we also have $(x : \theta[]*) \in \Gamma_c$. Because of the progress, it means that $[a', a' + m] \subseteq \in \pi$. Because of the related heaps and well-typed store it follows that $(R(r_i) + c, a' + m) \in \mu_a$. Also from rule tr-mov-ri+₁ we know $(r_j : y)_w \in \mu_{\Gamma}$. Hence, $\mu_a \vdash R_{0:w}(r_j) \iff v$. After the update we can see that $(R(r_i) + c)$ and a' + m are still related.

- 18. Case tr-mov-i+r₂. Then $\iota = (mov_w [r_i + c], r_j, \ell = x \rightarrow m$ and e = y.
 - (a) This case is possible iff R(r_i) = 0, R(r_i) = ⊥ or (R(r_i) + c) ∉ dom(H). Because of the related registers and heaps,

and from rule tr-mov-i+r₂($r_i : x$)₄ $\in \mu_{\Gamma}$, we have $\mu_a \vdash R(r_i) \iff \sigma(\rho(x))$. In either of the first two cases for $R(r_i)$ we also have $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \to m \rangle \xrightarrow{\ell}$ err. In the last case, because of related heaps, it also has to be that $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \to m \rangle \xrightarrow{\ell}$ err.

- (b) In this case rules ex-mov+r is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{mov}_w \ [r_i + c], r_j \rangle \stackrel{\iota}{\to} \langle H', R \rangle$. Here $H' = H \circ \{H(R(r_i)) +_4 c +_4 n \mapsto R_{n:n+1}(r_j)\}_{n=0}^{w-1}$. Similarly, through rule 1-ar $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \to m \rangle \stackrel{\ell}{\to} \langle \sigma, \pi, a \rangle$ with a = a' + m and $a' = \rho(x)$. Also through rules e-lval and 1-var we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, y \rangle \stackrel{e}{\to} \langle \sigma, \pi, v \rangle$ where $v = \sigma(a'')$ and $a'' = \rho(y)$. From rule tr-mov-i+r₂ we know $(r_i : x)_4 \in \mu_{\Gamma}$. Hence from the related registers we know $(r_i : N^*) \in \Gamma_c$. Because of the progress, it means that $[a', a' + m] \subseteq \in \pi$. Because of the related heaps and well-typed store it follows that $(R(r_i) + c, a' + m) \in \mu_a$. Also from rule tr-mov-ri+1 we know $(r_j : y)_w \in \mu_{\Gamma}$. Hence, $\mu_a \vdash R_{0:w}(r_j) \iff v$. After the update we can see that $(R(r_i) + c)$ and a' + m are still related.
- 19. Case tr-alloc-r^{*}. Then $\iota = (\text{alloc } r_i, r_j * c, \ell = x \text{ and } e = \text{new } \theta[y * m].$
 - (a) Rule ex-alloc-* only fails iff R(r_j) = ⊥. Similarly, while rules l-var, e-const and e-op do not fail, rule e-ar fails iff σ(ρ(y)) = ⊥. Since (r_j : y) ∈ μ_Γ, both failures coincide.
 (b) This can be a similar to the doft rules result.
 - (b) This case is similar to that of tr-alloc-rc₂.
- 20. Case tr-alloc-rc₁. Then ι = (alloc r_i, c, ℓ = x and e = new θ.
 (a) Rule ex-alloc cannot fail. Similarly, rules l-var and e-new do not fail.
 - (b) In this case rules ex-alloc is used for progress on *ι*: *R* ⊢ (*H*, *R*, alloc *r_i*, *c*) → (*H'*, *R'*). Here *R'* = *R* ◦₄ *r_i* → *a*. Also *H'* = *H* {*a* + *i* → ⊥}^{*c*-1}_{*i*=0}. Similarly, through rule 1-var Σ; *ρ*; *ρ* ⊢ (*σ*, *π*, *x*) → (*σ*, *π*, *a'*) where *a'* = *ρ*(*x*). Also through rule e-new we obtain Σ; *ρ*; *ρ* ⊢ (*σ*, *π*, new *θ*) → (*σ'*, *π*, *a''*) where *σ'* = *σ* {*a''* → ⊥}. Then choose *µ'_a* = *µ_a* {(*a* : *a''*)_{*c*}}. Since *µ_a* ⊢ ⊥ ↔ ⊥ these fresh addresses are related. Also pick *ν'_a* = *ν_a* {*a* + *i* → (*a*, *c*)}^{*c*-1}.
- 21. Case tr-alloc-rc₂. Then ι = (alloc $r_i, c, \ell = x$ and e = new struct N.
 - (a) Rule ex-alloc cannot fail. Similarly, rules l-var and e-str do not fail.
 - (b) In this case rules ex-alloc is used for progress on $\iota: \vec{R} \vdash \langle H, R, \text{alloc } r_i, c \rangle \stackrel{\iota}{\to} \langle H', R' \rangle$. Here $R' = R \circ_4 r_i \mapsto a$. Also $H' = H \circ \{a + i \mapsto \bot\}_{i=0}^{c-1}$. Similarly, through rule l-var $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, x \rangle \stackrel{\ell}{\to} \langle \sigma, \pi, a' \rangle$ where $a' = \rho(x)$. Also through rule e-str we obtain $\Sigma; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \text{new struct } \theta \rangle \stackrel{e}{\to} \langle \sigma', \pi, a'' \rangle$ where $\sigma' = \sigma \circ \{a'' + i \mapsto \bot\}_{i=0}^{n-1}$ with n is the number of fields in the struct. The new memory relations are straightforward.
- 22. Case tr-alloc-rc₃. Then $\iota = (\text{alloc } r_i, c, \ell = x \text{ and } e = \text{new } \theta[m].$
 - (a) Rule ex-alloc cannot fail. Similarly, rules l-var,e-str and e-const do not fail.
 - (b) In this case rules ex-alloc is used for progress on *ι*: *R* ⊢ ⟨*H*, *R*, alloc *r_i*, *c*⟩ → ⟨*H'*, *R'*⟩. Here *R'* = *R* ◦₄ *r_i* → *a*. Also *H'* = *H* ◦ {*a* + *i* → ⊥}^{*c*-1}_{*i*=0}.

Similarly, through rule l-var Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, x \rangle \xrightarrow{\ell} \langle \sigma, \pi, a' \rangle$ where $a' = \rho(x)$. Also through rule e-ar we obtain Σ ; $\vec{\rho}$; $\rho \vdash \langle \sigma, \pi, \text{new } \theta[m] \rangle \xrightarrow{e} \langle \sigma', \pi, a'' \rangle$ where $\sigma' = \sigma \circ \{a'' + i \mapsto \bot\}_{i=0}^{m-1}$.

The new memory relations are straightforward.

23. Case tr-call. This case follows coinductively.

Basic Blocks The two propositions for basic blocks are the following.

Proposition 15 (Preservation of Progress for Basic Blocks). If

• $\mu_{\lambda}; \mu_{\Gamma}; \Gamma_c; \Sigma \vdash b \stackrel{b}{\rightsquigarrow} s$

•
$$\forall (a:l) \in \mu_{\lambda} : \mu_{\lambda}; \mu_{\Gamma}; \Gamma_c; \Sigma \vdash \lambda_x(a) \stackrel{b}{\rightsquigarrow} \lambda_c(l)$$

- $\Gamma_c; \Sigma; \Psi \vdash \rho$
- $\Sigma; \Psi \vdash \sigma; \pi$
- $\mu_a; \nu_a; \pi; \vec{\rho}, \rho \vdash H \iff \sigma$
- $\mu_a; \vec{\mu_{\Gamma}}, \mu_{\Gamma}; \sigma \vdash \vec{R}, R \iff \vec{\rho}, \rho$
- $\lambda_x; \vec{R} \vdash \langle H, R, b \rangle \xrightarrow{b} \langle H', R', b' \rangle$

then

- $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, s \rangle \xrightarrow{s} \text{ err or }$
- $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, s \rangle \xrightarrow{s} \langle \sigma', \pi', s' \rangle.$

Proposition 16 (Preservation of Related Memory for Basic Blocks). If

• $\mu_{\lambda}; \mu_{\Gamma}; \Gamma_c; \Sigma \vdash b \stackrel{b}{\leadsto} s$

- $\forall (a:l) \in \mu_{\lambda}: \mu_{\lambda}; \mu_{\Gamma}; \Gamma_c; \Sigma \vdash \lambda_x(a) \stackrel{b}{\rightsquigarrow} \lambda_c(l)$
- $\Gamma_c; \Sigma; \Psi \vdash \rho$
- $\Sigma; \Psi \vdash \sigma; \pi$
- $\mu_a; \nu_a; \pi; \vec{\rho}, \rho \vdash H \iff \sigma$
- $\mu_a; \vec{\mu_{\Gamma}}, \mu_{\Gamma}; \sigma \vdash \vec{R}, R \iff \vec{\rho}, \rho$
- $\lambda_x; \vec{R} \vdash \langle H, R, b \rangle \xrightarrow{b} \langle H', R', b' \rangle$
- $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, s \rangle \xrightarrow{s} \langle \sigma', \pi', s' \rangle$

then for some $\mu'_a \supseteq \mu_a$ and $\nu'_a \supseteq \nu_a$:

•
$$\mu'_a; \mu^{\overline{\Gamma}}, \mu_{\Gamma}; \sigma' \vdash \vec{R}, R \iff \vec{\rho}, \rho$$

• $\mu'_a; \nu'_a; \pi'; \vec{\rho}, \rho \vdash H' \iff \sigma'$

Proof 6. The proof is straightforward.

Function Definitions The two propositions for function definitions are the following.

Proposition 17 (Preservation of Progress for Function Definitions). If

$$\begin{split} & \cdot \Sigma \vdash \langle f, \overrightarrow{r_x}, \overrightarrow{r_y}, a, \lambda_x, j \rangle \rightsquigarrow f(\overrightarrow{x:\theta}) \langle \overrightarrow{y:\theta'}, l, \lambda_c, j \rangle \\ & \cdot \mu_{\Gamma} = \{ \overrightarrow{r_x \mapsto x}, \overrightarrow{r_y \mapsto y} \} \\ & \cdot \Gamma_c = \{ \overrightarrow{x:\theta}, \overrightarrow{y:\theta'} \} \\ & \cdot \Gamma_c; \Sigma; \Psi \vdash \rho \\ & \cdot \Sigma; \Psi \vdash \sigma; \pi \\ & \cdot \mu_a; \nu_a; \pi; \overrightarrow{\rho}, \rho \vdash H \iff \sigma \\ & \cdot \mu_a; \overrightarrow{\mu_{\Gamma}}, \mu_{\Gamma}; \sigma \vdash \overrightarrow{R}, R \iff \overrightarrow{\rho}, \rho \\ & \cdot \lambda_x; \overrightarrow{R} \vdash \langle H, R, \lambda_x(a) \rangle \xrightarrow{b} \langle H', R', b' \rangle \end{split}$$

then

• $\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \lambda_c(l) \rangle \xrightarrow{s} \text{err or}$

•
$$\Sigma; \lambda_c; \vec{\rho}; \rho \vdash \langle \sigma, \pi, \lambda(l) \rangle \xrightarrow{s} \langle \sigma', \pi', s' \rangle.$$

Proposition 18 (Preservation of Related Memory for Function Definitions). If

• $\mu_{\lambda}; \mu_{\Gamma}; \Gamma_c; \Sigma \vdash b \stackrel{b}{\rightsquigarrow} s$

$$\begin{split} & \cdot \mu_{\Gamma} = \{\overrightarrow{r_x \mapsto x}, \overrightarrow{r_y \mapsto y}\} \\ & \cdot \Gamma_c = \{\overrightarrow{x:\theta}, \overrightarrow{y:\theta'}\} \\ & \cdot \Gamma_c; \Sigma; \Psi \vdash \rho \\ & \cdot \Sigma; \Psi \vdash \sigma; \pi \\ & \cdot \mu_a; \nu_a; \pi; \overrightarrow{\rho}, \rho \vdash H \nleftrightarrow \sigma \\ & \cdot \mu_a; \mu_{\Gamma}, \mu_{\Gamma}; \sigma \vdash \overrightarrow{R}, R \nleftrightarrow \overrightarrow{\rho}, \rho \\ & \cdot \lambda_x; \overrightarrow{R} \vdash \langle H, R, \lambda_x(a) \rangle \xrightarrow{b} \langle H', R', b' \rangle \\ & \cdot \Sigma; \lambda_c; \overrightarrow{\rho}; \rho \vdash \langle \sigma, \pi, \lambda(l) \rangle \xrightarrow{s} \langle \sigma', \pi', s' \rangle. \end{split}$$

then for some $\mu'_a \supseteq \mu_a$ and $\nu'_a \supseteq \nu_a$:

•
$$\mu'_a; \vec{\mu_{\Gamma}}, \mu_{\Gamma}; \sigma' \vdash \vec{R}, R \iff \vec{\rho}, \rho$$

• $\mu'_a; \nu'_a; \pi'; \vec{\rho}, \rho \vdash H' \iff \sigma'$

Proof 7. The proof is straightforward.